







DLP550JE

ZHCSN33B - NOVEMBER 2017 - REVISED FEBRUARY 2023

DLP550JE 0.55 XGA 数字微镜器件

1 特性

- 0.55 英寸微镜阵列对角线
 - XGA (1024 × 768)
 - 10.8 微米微镜间距
 - **±12°** 微镜倾斜角 (相对于平面状态)
 - 角落照明
- 2xLVDS 输入数据总线
- DLP550JE 芯片组包括:
 - DLP470TE DMD
 - DLPC4430 控制器
 - DLPA100 控制器电源管理和电机驱动器 IC
 - DLPA200

2 应用

- 数字标牌
- 教育投影仪
- 企业投影仪

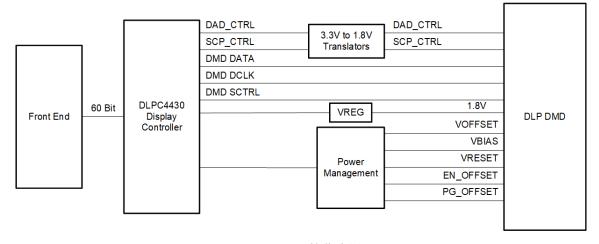
3 说明

TI DLP550JE 数字微镜器件 (DMD) 是一款数控微机电 系统 (MEMS) 空间照明调制器 (SLM),能够实现明 亮、经济实惠的 DLP® 0.55 XGA 显示解决方案。 DLP550JE DMD 通过与 DLPC4430 显示控制器、 DLPA100 电源和电机驱动器及 DLPA200 DMD 微镜驱 动器配合使用,可提供实现高性能系统的能力,是需要 4:3 纵横比、高亮度和系统简单性的显示应用的理想之 选。

器件信息

| 器件型号 | 封装 ⁽¹⁾ | 封装尺寸(标称值) |
|----------|-------------------|---------------------|
| DLP550JE | FYA (149) | 32.20 mm × 22.30 mm |

如需了解所有可用封装,请参阅数据表末尾的可订购产品附 录。



DLP550JE 简化应用



Table of Contents

| 1 特性 1 | 7.2 Feature Description | 19 |
|---|---|------------------|
| 2 应用 | 7.3 Optical Interface and System Image Quality | |
| | Considerations | 19 |
| 4 Revision History2 | 7.4 Micromirror Array Temperature Calculation | 20 |
| 5 Pin Configuration and Functions3 | 7.5 Micromirror Landed-on/Landed-Off Duty Cycle | <mark>21</mark> |
| 6 Specifications6 | 8 Application and Implementation | 24 |
| 6.1 Absolute Maximum Ratings6 | 8.1 Application Information | <mark>2</mark> 4 |
| 6.2 Storage Conditions6 | 8.2 Typical Application | 24 |
| 6.3 ESD Ratings | 9 Power Supply Recommendations | 27 |
| 6.4 Recommended Operating Conditions7 | 9.1 DMD Power-Up and Power-Down Procedures | |
| 6.5 Thermal Information9 | 10 Device and Documentation Support | |
| 6.6 Electrical Characteristics10 | 10.1 Device Support | 28 |
| 6.7 Timing Requirements10 | 10.2 支持资源 | 28 |
| 6.8 Window Characteristics14 | 10.3 接收文档更新通知 | 29 |
| 6.9 System Mounting Interface Loads14 | 10.4 Trademarks | 29 |
| 6.10 Micromirror Array Physical Characteristics15 | 10.5 静电放电警告 | <mark>2</mark> 9 |
| 6.11 Micromirror Array Optical Characteristics 17 | 10.6 术语表 | 29 |
| 6.12 Chipset Component Usage Specification 17 | 11 Mechanical, Packaging, and Orderable | |
| 7 Detailed Description18 | Information | <mark>2</mark> 9 |
| 7.1 Overview | | |
| | | |

4 Revision History 注:以前版本的页码可能与当前版本的页码不同

| Changes from Revision A (September 2022) to Revision B (February 2023) | Page |
|--|------|
| • 将控制器更新为 DLPC4430, 所有芯片组元件均为有效链接 | 1 |
| • 将控制器更新为 DLPC4430,将 DMD 链接到文档 | 1 |
| Updated this section | |
| Updated controller to DLPC4430, updated the application diagram | |
| Updated controller to DLPC4430 | |
| Updated controller to DLPC4430 | 27 |
| Changes from Revision * (November 2017) to Revision A (September 2022) | Page |
| • 更新了整个文档中的表格、图和交叉参考的编号格式 | 1 |
| • 将文档状态从:"预告信息"更改为:量产数据 | 1 |
| • 更新了措辞,将"MOEMS"替换为"MEMS" | 1 |
| Undated wording in "Input Voltages" in # 6.1 | 6 |



5 Pin Configuration and Functions

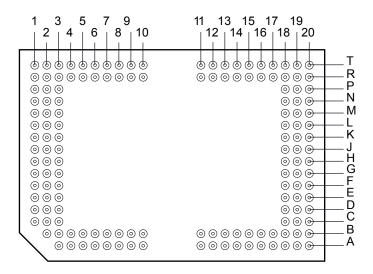


图 5-1. FYA Package 149-Pin Bottom View

表 5-1. Pin Functions

| 衣 5-1. Pili Functions | | | | | | | | | |
|-----------------------|-----|---------|--------|-----------------------------|---------------------------------|--------|---------------------------|-----------------------|--|
| PIN ⁽¹⁾ | | TYPE | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE | |
| NAME | NO. | (I/O/P) | | KAIE | I ERIVI | | | (mils) ⁽⁴⁾ | |
| DATA INPUTS | | | | | | | | | |
| D_AN1 | G20 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.78 | |
| D_AP1 | H20 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.86 | |
| D_AN3 | H19 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.73 | |
| D_AP3 | G19 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.76 | |
| D_AN5 | F18 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.73 | |
| D_AP5 | G18 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.81 | |
| D_AN7 | E18 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.77 | |
| D_AP7 | D18 | Input | LVCMOS | DDR | Differential | DCLK_A | Input data bus A (LVDS) | 760.81 | |
| D_AN9 | C20 | Input | LVCMOS | DDR | Differential | DCLK_A | - Input data bus A (LVDS) | 760.67 | |
| D_AP9 | D20 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.74 | |
| D_AN11 | B18 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.68 | |
| D_AP11 | A18 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.77 | |
| D_AN13 | A20 | Input | LVCMOS | DDR | Differential | DCLK_A | 1 | 760.82 | |
| D_AP13 | B20 | Input | LVCMOS | DDR | Differential | DCLK_A |] | 760.77 | |
| D_AN15 | B19 | Input | LVCMOS | DDR | Differential | DCLK_A |] | 760.79 | |
| D_AP15 | A19 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.75 | |



表 5-1. Pin Functions (continued)

| PIN(1) Type DATA INTERNAL | | | | | | | | |
|---------------------------|-------|-----------------|----------|-----------------------------|---------------------------------|-------------|--|--------------------------------|
| | NO | TYPE (I/O/P) | SIGNAL | DATA RATE ⁽²⁾ | INTERNAL TERM ⁽³⁾ | CLOCK | DESCRIPTION | TRACE (mils) ⁽⁴⁾ |
| NAME | NO. | | 11/01/00 | | | DOLK D | | ` , |
| D_BN1 | K20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.72 |
| D_BP1 | J20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.80 |
| D_BN3 | J19 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.79 |
| D_BP3 | K19 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.82 |
| D_BN5 | L18 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.77 |
| D_BP5 | K18 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.85 |
| D_BN7 | M18 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.78 |
| D_BP7 | N18 | Input | LVCMOS | DDR | Differential | DCLK_B | Input data bus B (LVDS) | 760.81 |
| D_BN9 | P20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.76 |
| D_BP9 | N20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.83 |
| D_BN11 | R18 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.78 |
| D_BP11 | T18 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.80 |
| D_BN13 | T20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.78 |
| D_BP13 | R20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.72 |
| D_BN15 | R19 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.80 |
| D_BP15 | T19 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.77 |
| DCLK_AN | D19 | Input | LVCMOS | _ | Differential | _ | Input data bus A Clock | 760.73 |
| DCLK_AP | E19 | Input | LVCMOS | _ | Differential | _ | (LVDS) | 760.80 |
| DCLK_BN | N19 | Input | LVCMOS | _ | Differential | _ | Input data bus B Clock | 760.72 |
| DCLK_BP | M19 | Input | LVCMOS | _ | Differential | _ | (LVDS) | 760.80 |
| DATA CONTROL IN | NPUTS | | | | | | | |
| SCTRL_AN | F20 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.74 |
| SCTRL AP | E20 | Input | LVCMOS | DDR | Differential | DCLK_A | | 760.70 |
| SCTRL_BN | L20 | Input | LVCMOS | DDR | Differential | DCLK_B | Data Control (LVDS) | 760.83 |
| SCTRL_BP | M20 | Input | LVCMOS | DDR | Differential | DCLK_B | | 760.78 |
| SERIAL COMMUNI | | · . | | | | _ | | |
| SCP_CLK | A8 | Input | LVCMOS | _ | Pulldown | _ | | _ |
| SCP_DO | A9 | Output | LVCMOS | _ | _ | SCP_CLK | | _ |
| SCP_DI | A5 | Input | LVCMOS | _ | Pulldown | SCP_CLK | | _ |
| SCP_EN | B7 | Input | LVCMOS | | Pulldown | SCP_CLK | | _ |
| PWRDN | B9 | Input | LVCMOS | | Pulldown | - OOI _OLIK | | _ |
| MICROMIRROR BI | | | LVOIVIOO | | 1 dildowii | | | |
| MODE A | A4 | Input | LVCMOS | | Pulldown | 1 | | |
| | | · | | | | _ | | _ |
| MBRST0 MBRST1 | C3 | Input | Analog | _ | _ | _ | _ | _ |
| | D2 | Input | Analog | _ | _ | _ | - | _ |
| MBRST2 | D3 | Input | Analog | _ | _ | _ | _ | _ |
| MBRST3 | E2 | Input | Analog | _ | _ | _ | - | _ |
| MBRST4 | G3 | Input | Analog | _ | _ | _ | _ | _ |
| MBRST5 | E1 | Input | Analog | _ | _ | _ | Micromirror Bias | _ |
| MBRST6 | G2 | Input | Analog | _ | _ | _ | Clocking Pulse | _ |
| MBRST7 | G1 | Input | Analog | _ | _ | _ | "MBRST" signals "clock" micromirrors into state of | _ |
| MBRST8 | N3 | Input | Analog | | _ | _ | LVCMOS memory cell | _ |
| MBRST9 | M2 | Input | Analog | _ | _ | _ | associated with each mirror. | _ |
| MBRST10 | M3 | Input | Analog | _ | _ | _ | | _ |
| MBRST11 | L2 | Input | Analog | _ | _ | _ | | _ |
| MBRST12 | J3 | Input | Analog | _ | _ | _ | | _ |
| MBRST13 | L1 | Input | Analog | _ | _ | _ | | _ |
| MBRST14 | J2 | Input | Analog | _ | _ | _ | | _ |
| MBRST15 | J1 | Input | Analog | _ | _ | _ | | _ |
| | | | | | | | | |

表 5-1 Pin Functions (continued)

| 表 5-1. Pin Functions (continued) | | | | | | | | |
|----------------------------------|---|--------------|--------|---------------------|---------------------|-------|--------------------------------------|-----------------------|
| PIN ⁽¹⁾ | | TYPE | SIGNAL | DATA | INTERNAL | CLOCK | DESCRIPTION | TRACE |
| NAME | NO. | (I/O/P) | SIGNAL | RATE ⁽²⁾ | TERM ⁽³⁾ | CLOCK | DESCRIPTION | (mils) ⁽⁴⁾ |
| POWER | | | | | | | | |
| V _{CC} | B11, B12, B13, B16, R12, R13, R16, R17 | Power | Analog | _ | _ | _ | Power for LVCMOS Logic | _ |
| V _{CCI} | A12, A14, A16, T12, T14, T16 | Power | Analog | _ | _ | _ | Power supply for LVDS Interface | _ |
| V _{OFFSET} | C1, D1, M1, N1 | Power | Analog | _ | _ | _ | Power for High Voltage CMOS Logic | _ |
| V _{SS} | A6, A11, A13, A15, A17, B4, B5, B8, B14, B15, B17, C2, C18, C19, F1, F2, F19, H1, H2, H3, H18, J18, K1, K2, L19, N2, P18, P19, R4, R9, R14, R15, T7, T13, T15, T17 | Power | Analog | _ | _ | _ | Common return for all power inputs | _ |
| RESERVED SIGNA | LS (Not for | use in syste | | | | | | |
| RESERVED_FC | R7 | Input | LVCMOS | _ | Pulldown | _ | | _ |
| RESERVED_FD | R8 | Input | LVCMOS | _ | Pulldown | _ | Pins should be | _ |
| RESERVED_PFE | T8 | Input | LVCMOS | _ | Pulldown | _ | connected to V _{SS} . | _ |
| RESERVED_STM | В6 | Input | LVCMOS | _ | Pulldown | _ | | _ |
| NO_CONNECT | A3, A7, A10, B2, B3, B10, E3, F3, K3, L3, P1, P2, P3, R1, R2, R3, R5, R6, R10, R11, T1, T2, T3, T4, T5, T6, T9, T10, | _ | _ | _ | _ | _ | Do not connect. | _ |

- The following power supplies are required to operate the DMD: V_{CC} , V_{CCI} , V_{OFFSET} . V_{SS} must also be connected. DDR = Double Data Rate. SDR = Single Data Rate. Refer to the *Timing Requirements* for specifications and relationships.
- (3) Refer to *Electrical Characteristics* for differential termination specification.
- Internal Trace Length (mils) refers to the Package electrical trace length. See the DLP 0.55 XGA Chip-Set Data Manual for details regarding signal integrity considerations for end-equipment designs.



6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted).(7)

| | | MIN | MAX | UNIT |
|--|---|-------|-----------------------|------|
| SUPPLY VOLTAGES | | | | |
| V _{CC} | Supply voltage for LVCMOS core logic ⁽¹⁾ | - 0.5 | 4 | V |
| V _{CCI} | Supply voltage for LVDS Interface ⁽¹⁾ | - 0.5 | 4 | V |
| V _{OFFSET} | Micromirror Electrode and HVCMOS voltage ⁽¹⁾ (2) | - 0.5 | 9 | V |
| V _{MBRST} | Voltage applied to MBRST[0:15] Input Pins | - 28 | 28 | V |
| V _{CC} - V _{CCI} | Supply voltage change ⁽³⁾ | | 0.3 | V |
| INPUT VOLTAGES | | | | |
| | Input voltage for all other input pins ⁽¹⁾ | - 0.5 | V _{CC} + 0.3 | V |
| V _{ID} | Input differential voltage (absolute value) (4) | | 700 | mV |
| CLOCKS | | | - | |
| $f_{\sf clock}$ | Clock frequency for LVDS interface, DCLK_A | | 400 | MHz |
| $f_{\sf clock}$ | Clock frequency for LVDS interface, DCLK_B | | 400 | MHz |
| ENVIRONMENTAL | | | | |
| T _{ARRAY} and T _{WINDOW} | Temperature, operating ⁽⁵⁾ | 0 | 90 | °C |
| | Temperature, non-operating ⁽⁵⁾ | - 40 | 90 | °C |
| T _{DELTA} | Absolute Temperature delta between any point on the window edge and the ceramic test point TP1 ⁽⁶⁾ | | 30 | °C |
| T_DP | Dew Point Temperature, operating and non-operating (non-condensing) | | 81 | °C |

- All voltages are referenced to common ground V_{SS}. Voltages V_{CC}, V_{CCI}, and V_{OFFSET} are required for proper DMD operation. V_{SS} must also be connected.
- (2) V_{OFFSET} supply transients must fall within specified voltages.
- (3) Exceeding the recommended allowable absolute voltage difference between V_{CC} and V_{CCI} may result in excess current draw.
- (4) This maximum LVDS input voltage rating applies when each input of a differential pair is at the same voltage potential.
- (5) The highest temperature of the active array (as calculated by the † 7.4) or of any point along the Window Edge as defined in § 7-1.

 The locations of thermal test points TP2, TP3, TP4, and TP5 in § 7-1 are intended to measure the highest window edge temperature. If a particular application causes another point on the window edge to be at a higher temperature, that point should be used.
- (6) Temperature delta is the highest difference between the ceramic test point 1 (TP1) and anywhere on the window edge as shown in 图 7-1. The window test points TP2, TP3, TP4, and TP5 shown in 图 7-1 are intended to result in the worst-case delta. If a particular application causes another point on the window edge to result in a larger delta temperature, that point should be used.
- (7) Stresses beyond those listed under 节 6.1 may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under 节 6.4. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 Storage Conditions

Applicable for the DMD as a component or non-operational in a system.

| | | MIN | MAX | UNIT |
|---------------------|--|------|-----|--------|
| T _{DMD} | DMD storage temperature | - 40 | 80 | °C |
| T _{DP-AVG} | Average dew point temperature (non-condensing) ⁽¹⁾ | | 28 | °C |
| T _{DP-ELR} | Elevated dew point temperature range (non-condensing) ⁽²⁾ | 28 | 36 | °C |
| CT _{ELR} | Cumulative time in elevated dew point temperature range | | 24 | Months |

- (1) The average over time (including storage and operating) that the device is not in the elevated dew point temperature range.
- (2) Exposure to dew point temperatures in the elevated range during storage and operation should be limited to less than a total cumulative time of CT_{FLR}.

Submit Document Feedback



6.3 ESD Ratings

| | | | | VALUE | UNIT |
|--------------------|-----------|---|-----------------------------|-------|------|
| V/ | | Trainan body model (Tibin), per 7 itoli | All pins except MBRST(15:0) | ±2000 | V |
| V _(ESD) | discharge | ESDA/JEDEC JS-001 ⁽¹⁾ | Pins MBRST(15:0) | <250 | |

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.4 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted). The functional performance of the device specified in this data sheet is achieved when operating the device within the limits defined by this table. No level of performance is implied when operating the device above or below these limits.

| | | MIN | NOM | MAX | UNIT |
|------------------------------------|---|-------|------|--------------------------|-----------------------|
| VOLTAGE SUPPLY | Y | | | | |
| V _{CC} | Supply voltage for LVCMOS core logic ⁽¹⁾ | 3.0 | 3.3 | 3.6 | V |
| V _{CCI} | Supply voltage for LVDS receivers ⁽¹⁾ | 3.0 | 3.3 | 3.6 | V |
| V _{OFFSET} | Mirror Electrode and HVCMOS voltage ⁽¹⁾ (2) | 8.25 | 8.5 | 8.75 | V |
| V _{MBRST} | Micromirror clocking pulse voltages ⁽¹⁾ | - 27 | | 26.5 | V |
| V _{CCI} - V _{CC} | Supply voltage delta (absolute value) ⁽³⁾ | | | 0.3 | V |
| LVCMOS INTERFA | ACE | | | | |
| V _{IH} | High level input voltage | 1.7 | 2.5 | VCC + 0.3 | V |
| V _{IL} | Low level input voltage | - 0.3 | | 0.7 | V |
| I _{OH} | High level output current at V _{OH} = 2.4 V | | | - 20 | mA |
| I _{OL} | Low level output current at V _{OL} = 0.4 V | | | 15 | mA |
| t _{PWRDNZ} | PWRDNZ pulse width ⁽⁴⁾ | 10 | | | ns |
| SCP INTERFACE | | | | | |
| f _{SCPCLK} | SCP clock frequency ⁽⁵⁾ | 50 | | 500 | kHz |
| t _{SCP_PD} | Propagation delay, clock to Q, from rising-edge of SCPCLK to valid SCPDO ⁽⁶⁾ | 0 | | 900 | ns |
| t _{SCP DS} | SCPDI clock setup time (before SCPCLK falling-edge) ⁽⁶⁾ | 800 | | | ns |
| t _{SCP DH} | SCPDI hold time (after SCPCLK falling-edge) ⁽⁶⁾ | 900 | | | |
| t _{SCP_NEG_ENZ} | Time between falling-edge of SCPENZ and the first rising-edge of SCPCLK | 1 | | | us |
| t _{SCP_POS_ENZ} | Time between falling-edge of SCPCLK and the rising-edge of SCPENZ | 1 | | | us |
| t _{SCP_PW_ENZ} | SCPENZ inactive pulse width (high level) | 1 | | | 1/f _{SCPCLK} |
| t _{r_SCP} | Rise time for SCP signals | | | 200 | ns |
| t _{fP} | Fall time for SCP signals | | | 200 | ns |
| LVDS INTERFACE | | | | | |
| f _{CLOCK} | Clock frequency for LVDS interface (all channels), DCLK ⁽⁷⁾ | | 320 | 330 | MHz |
| V _{ID} | Input differential voltage (absolute difference) ⁽⁸⁾ | 100 | 400 | 600 | mV |
| V _{CM} | Common mode voltage ⁽⁸⁾ | | 1200 | | mV |
| V _{LVDS} | LVDS voltage ⁽⁸⁾ | 0 | | 2000 | mV |
| t _r | Rise time (20% to 80%) | 100 | | 400 | ps |
| t _r | Fall time (80% to 20%) | 100 | - | 400 | ps |
| t _{LVDS_RSTZ} | Time required for LVDS receivers to recover from PWRDNZ | | | 10 | ns |
| Z _{IN} | Internal differential termination resistance | 95 | | 105 | Ω |
| ENVIRONMENTAL | • | | | | |
| T | Array temperature, long-term operational ⁽⁹⁾ (10) (11) | 10 | | 40 to 70 ⁽¹²⁾ | °C |
| T _{ARRAY} | Array temperature, short-term operational ⁽¹⁰⁾ (13) | 0 | | 10 | °C |

6.4 Recommended Operating Conditions (continued)

Over operating free-air temperature range (unless otherwise noted). The functional performance of the device specified in this data sheet is achieved when operating the device within the limits defined by this table. No level of performance is implied when operating the device above or below these limits.

| | | MIN | NOM | MAX | UNIT |
|-----------------------|---|-----|-----------------|------|--------------------|
| T _{WINDOW} | Window temperature - operational ⁽¹⁴⁾ | | | 85 | °C |
| T _{IDELTA I} | Absolute temperature delta between any point on the window edge and the ceramic test point ${\sf TP1}^{(15)}$ | | | 26 | °C |
| T _{DP-AVG} | Average dew point temperature (non-condensing) ⁽¹⁶⁾ | | | 28 | °C |
| T _{DP-ELR} | Elevated dew point temperature range (non-condensing) ⁽¹⁷⁾ | 28 | | 36 | °C |
| CT _{ELR} | Cumulative time in elevated dew point temperature range | | | 24 | Months |
| ILL _{UV} | Illumination wavelengths < 395 nm ⁽⁹⁾ | | 0.68 | 2.00 | mW/cm ² |
| ILL _{VIS} | Illumination wavelengths between 395 nm and 800 nm | Th | ermally limited | | mW/cm ² |
| ILL _{IR} | Illumination wavelengths > 800 nm | | | 10 | mW/cm ² |

- (1) All voltages are referenced to common ground V_{SS}. V_{BIAS}, V_{CC}, V_{OFFSET}, and V_{RESET} power supplies are all required for proper DMD operation. V_{SS} must also be connected.
- (2) V_{OFFSET} supply transients must fall within specified max voltages.
- (3) To prevent excess current, the supply voltage delta $|V_{CCI} V_{CC}|$ must be less than specified limit. See \ddagger 9.
- (4) PWRDNZ input pin resets the SCP and disables the LVDS receivers. PWRDNZ input pin overrides SCPENZ input pin and tristates the SCPDO output pin.
- (5) The SCP clock is a gated clock. Duty cycle shall be 50% ± 10%. SCP parameter is related to the frequency of DCLK.
- (6) See \(\bar{8} \) 6-2.
- (7) See LVDS Timing Requirements in 节 6.7 and 图 6-5.
- (8) Refer to 图 6-7, 图 6-8, and 图 6-9.
- (9) Simultaneous exposure of the DMD to the maximum 节 6.4 for temperature and UV illumination reduces device lifetime.
- (10) The array temperature cannot be measured directly and must be computed analytically from the temperature measured at test point 1 (TP1) shown in 图 7-1 and the package 节 6.5 using the calculation in 节 7.4
- (11) Long-term is defined as the average over the usable life.
- (12) Per 图 6-1, the maximum operational array temperature should be derated based on the micromirror landed duty cycle that the DMD experiences in the end application. See 节 7.5 for a definition of micromirror landed duty cycle.
- (13) Array temperatures beyond those specified as long-term are recommended for short-term conditions only (for example, power-up). Short-term is defined as cumulative time over the usable life of the device and is less than 500 hours.
- (15) Temperature delta is the highest difference between the ceramic test point 1 (TP1) and anywhere on the window edge as shown in [8] 7-1. The window test points TP2, TP3, TP4, and TP5 shown in [8] 7-1 are intended to result in the worst-case delta temperature. If a particular application causes another point on the window edge to result in a larger delta in temperature, that point should be used.
- (16) The average over time (including storage and operating) that the device is not in the "elevated dew point temperature range."
- (17) Exposure to dew point temperatures in the elevated range during storage and operation should be limited to less than a total cumulative time of CT_{ELR}.

Submit Document Feedback

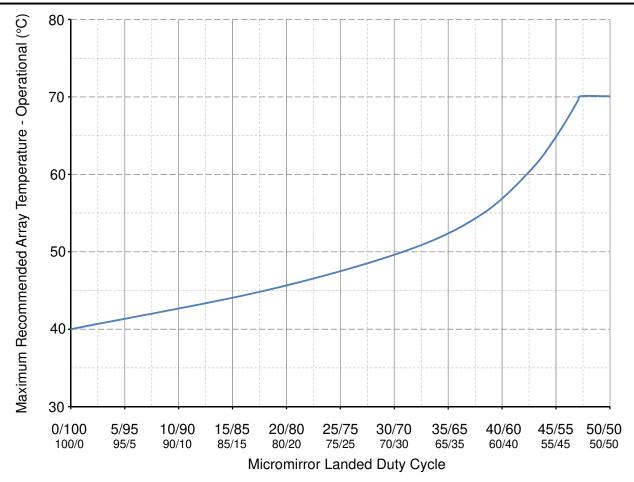


图 6-1. Maximum Recommended DMD Temperature—Derating Curve

6.5 Thermal Information

| | DLP550JE | |
|---|-------------|------|
| THERMAL METRIC | FYA PACKAGE | UNIT |
| | 149 PINS | |
| Thermal resistance, active array to test point 1 (TP1) ⁽¹⁾ | 0.60 | °C/W |

⁽¹⁾ The DMD is designed to conduct absorbed and dissipated heat to the back of the package. The cooling system must be capable of maintaining the package within the temperature range specified in the 节 6.4.

The total heat load on the DMD is largely driven by the incident light absorbed by the active area; although other contributions include light energy absorbed by the window aperture and electrical power dissipation of the array.

Optical systems should be designed to minimize the light energy falling outside the window clear aperture since any additional thermal load in this area can significantly degrade the reliability of the device.

6.6 Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted).

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|---|---|-----|-----|------|------|
| V _{OH} | High-level output voltage | $V_{CC} = 3.0 \text{ V}, I_{OH} = -20 \text{ mA}$ | 2.4 | | | V |
| V _{OL} | Low-level output voltage | V _{CC} = 3.6 V, I _{OL} = 15 mA | | | 0.4 | V |
| I _{OZ} | High impedance output current | V _{CC} = 3.6 V | | | 10 | μΑ |
| I _{IL} | Low-level input current | V _{CC} = 3.6 V, V _I = 0 V | | | - 60 | μΑ |
| I _{IH} | High-level input current ⁽¹⁾ | $V_{CC} = 3.6 \text{ V}, V_{I} = V_{CC}$ | | | 200 | μA |
| I _{CC} | Current into V _{CC} pin | V _{CC} = 3.6 V | | | 531 | mA |
| I _{CCI} | Current into V _{CC1} pin ⁽²⁾ | V _{CCI} = 3.6 V | | | 374 | mA |
| I _{OFFSET} | Current into V _{OFFSET} pin ⁽³⁾ | V _{OFFSET} = 8.75 V | | - | 25 | mA |
| Z _{IN} | Internal Differential Impedance | | 95 | | 105 | Ω |
| Z _{LINE} | Line Differential Impedance (PWB or Trace) | | 90 | 100 | 110 | Ω |
| Cı | Input capacitance ⁽¹⁾ | f = 1 MHz | | | 10 | pF |
| Co | Output capacitance ⁽¹⁾ | f = 1 MHz | | | 10 | pF |
| C _{IM} | Input capacitance for MBRST[0:15] pins | f = 1 MHz | 160 | | 210 | pF |

- (1) Applies to LVCMOS pins only. Excludes LVDS pins and test pad pins
- (2) To prevent excess current, the supply voltage change |V_{CCI} V_{CC}| must be less than specified limits listed in the 节 6.4.
- (3) To prevent excess current, the supply voltage delta $|V_{BIAS} V_{OFFSET}|$ must be less than the specified limit in \ddagger 6.4.

6.7 Timing Requirements

Over operating free-air temperature range (unless otherwise noted).

| | | MIN | NOM | MAX | UNIT |
|-------------------|--|----------|------|------|------|
| LVDS (1) | | <u>'</u> | | | |
| t _c | Clock Cycle for DLCK_A | 3.03 | | | ns |
| t _c | Clock Cycle for DCLKC_B | 3.03 | | | ns |
| t _w | Pulse Duration DCLK_A | 1.36 | 1.52 | | ns |
| t _w | Pulse Duration for DCLK_B | 1.36 | 1.52 | | ns |
| t _{SU} | Setup Time, D_A[0:15] before DCLK_A | 0.35 | | | ns |
| t _{SU} | Setup Time, D_B[0:15] before DCLK_B | 0.35 | | | ns |
| t _{SU} | Setup Time, SCTRL_A before DCLK_A | 0.35 | | | ns |
| t _{SU} | Setup Time, SCTRL_B before DCLK_B | 0.35 | | | ns |
| t _H | Hold Time, D_A[0:15] after DCLK_A | 0.35 | | | ns |
| t _H | Hold Time, D_B[0:15] after DCLK_B | 0.35 | | | ns |
| t _H | Hold Time, SCTRL_A after DCLK_A | 0.35 | | | ns |
| t _H | Hold Time, SCTRL_B after DCLK_B | 0.35 | | | ns |
| t _{skew} | Channel B relative to Channel A ⁽²⁾ (3) | - 1.51 | | 1.51 | ns |

- (1) See 8 6-5 for timing requirements for LVDS.
- (2) Channel A (Bus A) includes the following LVDS pairs: DCLK_AN and DCLK_AP, SCTRL_AN and SCTRL_AP, D_AN(15:0) and D_AP(15:0).
- (3) Channel B (Bus B) includes the following LVDS pairs: DCLK_BN and DCLK_BP, SCTRL_BN and SCTRL_BP, D_BN(15:0) and D_BP(15:0).

Submit Document Feedback

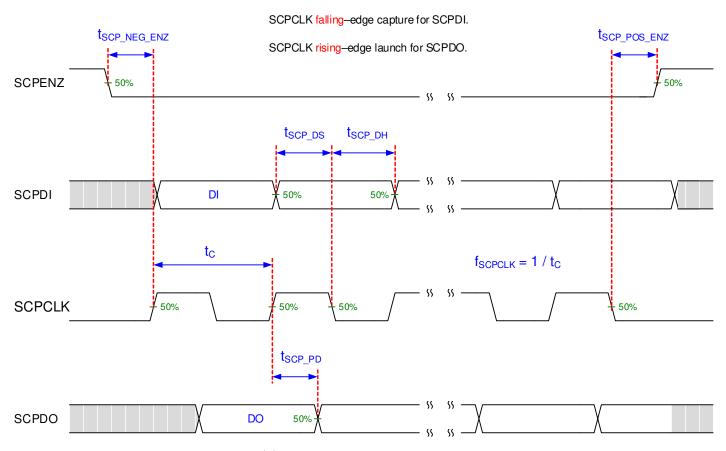
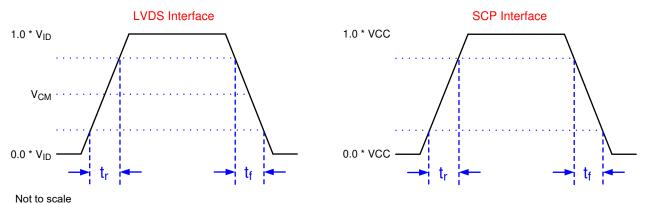


图 6-2. SCP Timing Parameters



Refer to 节 6.7.

Refer to \$ 5 for list of LVDS pins and SCP pins.

图 6-3. Rise Time and Fall Time

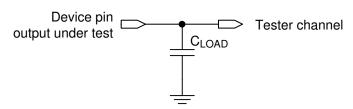


图 6-4. Test Load Circuit for Output Propagation Measurement

For output timing analysis, the tester pin electronics and its transmission line effects must be taken into account. System design should use IBIS or other simulation tools to correlate the timing reference load to a system environment. See 8 6-4.

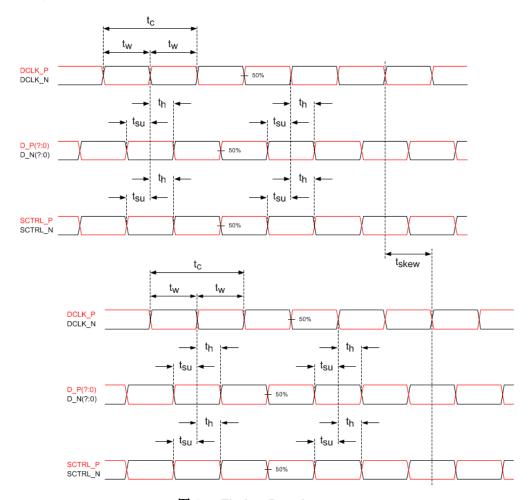


图 6-5. Timing Requirements

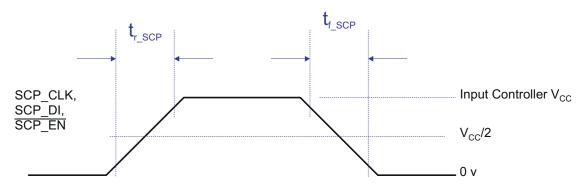
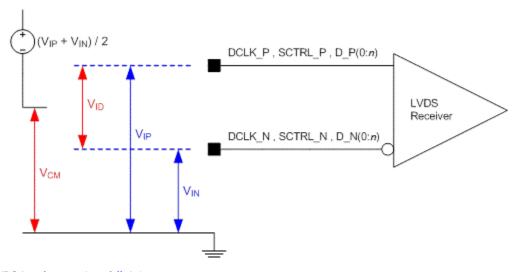


图 6-6. Serial Communications Bus Waveform Requirements

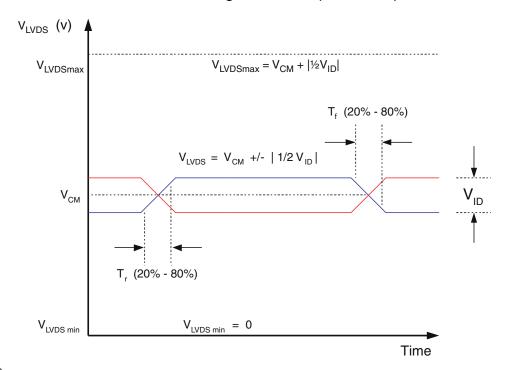




Refer to LVDS Interface section of 76.4.

Refer to 节 5 for list of LVDS pins.

图 6-7. LVDS Voltage Definitions (References)

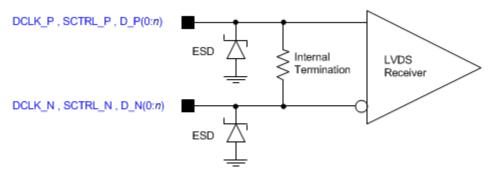


Not to scale

Refer to LVDS Interface section of the # 6.4.

图 6-8. LVDS Voltage Parameter





Refer to LVDS Interface section of the % 6.4.

Refer to $\footnote{1}{7}\footnote{1}{5}$ for list of LVDS pins.

图 6-9. LVDS Equivalent Input Circuit

6.8 Window Characteristics

| PARAMETER | MIN | NOM |
|---|-----|---------------------|
| Window material | | Corning Eagle XG |
| Window refractive index at wavelength 546.1 nm | | 1.5119 |
| Window Transmittance, minimum within the wavelength range 420 - 680 nm. Applies to all angles 0° - 30° AOI. (1) (2) | 97% | |
| Window Transmittance, average over the wavelength range 420 - 680 nm. Applies to all angles 30° - 45° AOI. (1) (2) | 97% | |

- (1) Single-pass through both surfaces and glass.
- (2) Angle of incidence (AOI) is the angle between an incident ray and the normal to a reflecting or refracting surface.

6.9 System Mounting Interface Loads

| PARAMETER | MIN | NOM | MAX | UNIT |
|--|-----|-----|------|------|
| Condition 1: | | | | |
| Thermal Interface area ⁽¹⁾ | | | 11.3 | kg |
| Electrical Interface area ⁽¹⁾ | | | 11.3 | kg |
| Condition 2: | | | | |
| Thermal Interface area ⁽¹⁾ | | | 0 | kg |
| Electrical Interface area ⁽¹⁾ | | | 22.6 | kg |

(1) Uniformly distributed within the area shown in 图 6-10

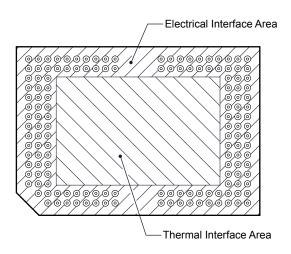


图 6-10. System Interface Loads

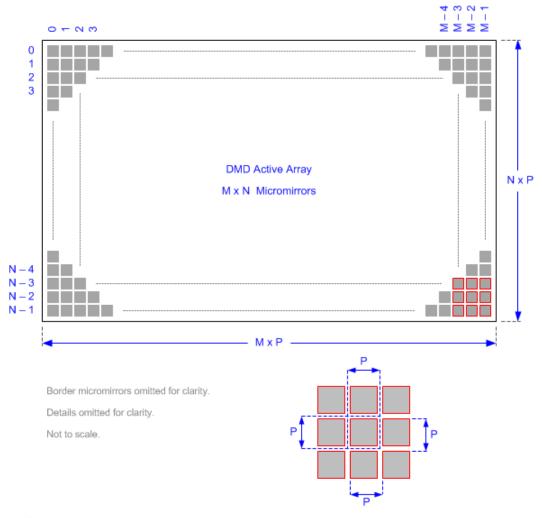
6.10 Micromirror Array Physical Characteristics

| PARAMETER | | | UNIT |
|--|--|--------|-------------------|
| Number of active columns ⁽¹⁾ | M | 1024 | micromirrors |
| Number of active rows ⁽¹⁾ | N | 768 | THICIOITHITOIS |
| Micromirror (pixel) pitch ⁽¹⁾ | Р | 10.8 | μm |
| Micromirror active array width ⁽¹⁾ | Micromirror pitch × number of active columns | 11.059 | mm |
| Micromirror active array height (1) | Micromirror pitch × number of active columns | 8.294 | mm |
| Micromirror active array border ⁽²⁾ | Pond of Micromirror (POM) | 10 | micromirrors/side |

⁽¹⁾ (2) See 图 6-11.

The structure and qualities of the border around the active array includes a band of partially functional micromirrors referred to as the Pond Of Mirrors (POM). These micromirrors are structurally and/or electrically prevented from tilting toward the bright or ON state, but still require an electrical bias to tilt toward OFF.





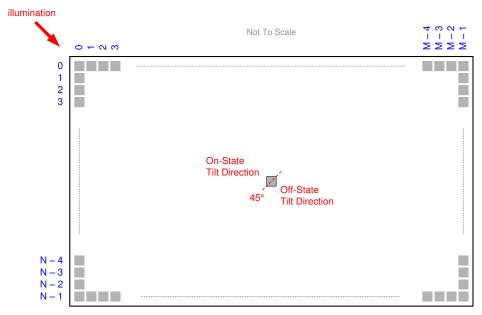
Refer to the #6.10 for M, N, and P specifications.

图 6-11. Micromirror Array Physical Characteristics

6.11 Micromirror Array Optical Characteristics

| PARAMETER | | MIN | NOM | MAX | UNIT |
|--|---------------------------|-----|-----|-----|--------------|
| Micromirror tilt angle, variation device to device (1) (2) (3) (4) | | 11 | 12 | 13 | degrees |
| | Adjacent micromirrors | | | 0 | |
| Number of out-of-specification micromirrors (5) | Non-adjacent micromirrors | | | 10 | micromirrors |

- (1) Measured relative to the plane formed by the overall micromirror array.
- (2) Variation can occur between any two individual micromirrors located on the same device or located on different devices.
- (3) Additional variation exists between the micromirror array and the package datums. See package drawing.
- (4) See \(\bigsize 6-12.
- (5) An out-of-specification micromirror is defined as a micromirror that is unable to transition between the two landed states.



Refer to section #6.10 table for M, N, and P specifications.

图 6-12. Micromirror Landed Orientation and Tilt

6.12 Chipset Component Usage Specification

Reliable function and operation of the DLP550JE DMD requires that it be used in conjunction with the other components of the applicable DLP chipset, including those components that contain or implement TI DMD control technology. TI DMD control technology consists of the TI technology and devices used for operating or controlling a DLP DMD.



7 Detailed Description

7.1 Overview

The DLP550JE is a 0.55 inch diagonal spatial light modulator which consists of an array of highly reflective aluminum micromirrors. Pixel array size and square grid pixel arrangement are shown in 8 6-11.

The DMD is an electrical input, optical output micro-electrical-mechanical system (MEMS). The electrical interface is Low Voltage Differential Signaling (LVDS), Double Data Rate (DDR).

The DLP550JE DMD consists of a two-dimensional array of 1-bit CMOS memory cells. The array is organized in a grid of *M* memory cell columns by *N* memory cell rows.

The positive or negative deflection angle of the micromirrors can be individually controlled by changing the address voltage of underlying CMOS addressing circuitry and micromirror reset signals (MBRST).

Each cell of the $M \times N$ memory array drives its true and complement ('Q' and 'QB') data to two electrodes underlying one micromirror, one electrode on each side of the diagonal axis of rotation. The micromirrors are electrically tied to the micromirror reset signals (MBRST) and the micromirror array is divided into reset groups.

Electrostatic potentials between a micromirror and its memory data electrodes cause the micromirror to tilt toward the illumination source in a DLP projection system or away from it, thus reflecting its incident light into or out of an optical collection aperture. The positive (+) tilt angle state corresponds to an 'on' pixel, and the negative (-) tilt angle state corresponds to an 'off' pixel.

Refer to # 6.11 for the \pm tilt angle specifications. Refer to the # 5 for more information on micromirror clocking pulse (reset) control.

Submit Document Feedback

7.2 Feature Description

7.2.1 Power Interface

The DMD requires 3 DC voltages: DMD_P3P3V, V_{OFFSET} , and MBRST. DMD_P3P3V is created by the DLPA100 power and motor driver and the DLPA200 DMD micromirror driver. Both the DLPA100 and DLPA200 create the main DMD voltages, as well as powering various peripherals (TMP411, I^2C , and TI level translators). DMD_P3P3V provides the V_{CC} voltage required by the DMD. V_{OFFSET} (8.5V) and MBRST are made by the DLPA200 and are supplied to the DMD to control the micromirrors.

7.2.2 Timing

The data sheet provides timing analysis as measured at the device pin. For output timing analysis, the tester pin electronics and its transmission line effects must be considered. (2) 6-4 shows an equivalent test load circuit for the output under test. Timing reference loads are not intended as a precise representation of any particular system environment or depiction of the actual load presented by a production test. TI suggests that system designers use IBIS or other simulation tools to correlate the timing reference load to a system environment. The load capacitance value stated is only for characterization and measurement of AC timing signals. This load capacitance value does not indicate the maximum load the device is capable of driving.

7.3 Optical Interface and System Image Quality Considerations

TI assumes no responsibility for end-equipment optical performance. Achieving the desired end-equipment optical performance involves making trade-offs between numerous component and system design parameters. System optical performance and image quality strongly relate to optical system design parameter trade offs. Although it is not possible to anticipate every conceivable application, projector image quality and optical performance is contingent on compliance to the optical system operating conditions described in the following sections.

7.3.1 Numerical Aperture and Stray Light Control

The angle defined by the numerical aperture of the illumination and projection optics at the DMD optical area should be the same. This angle should not exceed the nominal device mirror tilt angle unless appropriate apertures are added in the illumination and/or projection pupils to block out flat-state and stray light from the projection lens. The mirror tilt angle defines DMD capability to separate the "ON" optical path from any other light path, including undesirable flat-state specular reflections from the DMD window, DMD border structures, or other system surfaces near the DMD such as prism or lens surfaces. If the numerical aperture exceeds the mirror tilt angle, or if the projection numerical aperture angle is more than two degrees larger than the illumination numerical aperture angle (and vice versa), contrast degradation, and objectionable artifacts in the display's border and/or active area could occur.

7.3.2 Pupil Match

TI's optical and image quality specifications assume that the exit pupil of the illumination optics is nominally centered within 2° of the entrance pupil of the projection optics. Misalignment of pupils can create objectionable artifacts in the display's border and/or active area, which may require additional system apertures to control, especially if the numerical aperture of the system exceeds the pixel tilt angle.

7.3.3 Illumination Overfill

The active area of the device is surrounded by an aperture on the inside DMD window surface that masks structures of the DMD chip assembly from normal view, and is sized to anticipate several optical operating conditions. Overfill light illuminating the window aperture can create artifacts from the edge of the window aperture opening and other surface anomalies that may be visible on the screen. The illumination optical system should be designed to limit light flux incident anywhere on the window aperture from exceeding approximately 10% of the average flux level in the active area. Depending on the particular system's optical architecture, overfill light may have to be further reduced below the suggested 10% level in order to be acceptable.

Copyright © 2023 Texas Instruments Incorporated

Submit Document Feedback



7.4 Micromirror Array Temperature Calculation

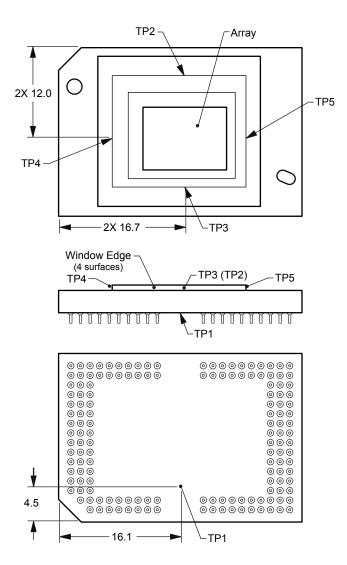


图 7-1. Thermal Test Point Location

7.4.1 Micromirror Array Temperature Calculation

$$T_{ARRAY} = T_{CERAMIC} + (Q_{ARRAY} \times R_{ARRAY - TO - CERAMIC})$$

$$Q_{ARRAY} = Q_{ELECTRICAL} + Q_{ILLUMINATION}$$

$$Q_{ILLUMINATION} = (C_{L2W} \times SL)$$

where

- T_{ARRAY} = Computed array temperature (°C)
- T_{CERAMIC} = Measured ceramic temperature (°C), TP1 location in 图 7-1

Submit Document Feedback

www.ti.com.cn

- R_{ARRAY TO CERAMIC} = Thermal resistance of package (specified in #6.5) from array to ceramic TP1(°C/ Watts).
- Q_{ARRAY} = Total DMD Power (electrical + absorbed) on array (Watts).
- Q_{ELECTRICAL} = Nominal electrical power
- C_{I 2W} = Conversion constant for screen lumens to absorbed optical power on the DMD (W/lm) specified below
- SL = Measured ANSI screen lumens (Im)

The electrical power dissipation of the DMD is variable and depends on the voltages, data rates and operating frequencies. A nominal electrical power dissipation to use when calculating array temperature is 1.4 W. The absorbed optical power from the illumination source is variable and depends on the operating state of the micromirrors and the intensity of the light source. The equations shown above are valid for a 1-chip DMD system with total projection efficiency through the projection lens from DMD to the screen of 87%.

The conversion constant C_{I 2W} is based on the DMD micromirror array characteristics. It assumes a spectral efficiency of 300 lm/W for the projected light and illumination distribution of 83.7% on the DMD active array, and 16.3% on the DMD array border and window aperture. The conversion constant is calculated to be 0.00274 W/lm.

Sample calculations:

T_{CERAMIC} = 55°C

SL = 3000 Im

Q_{ELECTRICAL} = 1.4 W

 $C_{1.2W} = 0.00274 \text{ W/Im}$

 $Q_{ARRAY} = 1.4 W + (0.00274 \times 3000) = 9.62 W$

 $T_{ARRAY} = 55^{\circ}C + (9.62 \text{ W} \times 0.6 \text{ C/W}) = 60.8^{\circ}C$

7.5 Micromirror Landed-on/Landed-Off Duty Cycle

7.5.1 Definition of Micromirror Landed-On/Landed-Off Duty Cycle

The micromirror landed-on/landed-off duty cycle (landed duty cycle) denotes the amount of time (as a percentage) that an individual micromirror is landed in the On - state versus the amount of time the same micromirror is landed in the Off - state.

As an example, a landed duty cycle of 100/0 indicates that the referenced pixel is in the On-state 100% of the time (and in the Off-state 0% of the time); whereas 0/100 would indicate that the pixel is in the Off-state 100% of the time. Likewise, 50/50 indicates that the pixel is On 50% of the time and Off 50% of the time.

Note that when assessing landed duty cycle, the time spent switching from one state (ON or OFF) to the other state (OFF or ON) is considered negligible and is thus ignored.

Since a micromirror can only be landed in one state or the other (On or Off), the two numbers (percentages) always add to 100.

7.5.2 Landed Duty Cycle and Useful Life of the DMD

Knowing the long-term average landed duty cycle (of the end product or application) is important because subjecting all (or a portion) of the DMD' s micromirror array (also called the active array) to an asymmetric landed duty cycle for a prolonged period of time can reduce the DMD's usable life.

Note that it is the symmetry/asymmetry of the landed duty cycle that is of relevance. The symmetry of the landed duty cycle is determined by how close the two numbers (percentages) are to being equal. For example, a landed duty cycle of 50/50 is perfectly symmetrical whereas a landed duty cycle of 100/0 or 0/100 is perfectly asymmetrical.

7.5.3 Landed Duty Cycle and Operational DMD Temperature

Operational DMD Temperature and Landed Duty Cycle interact to affect the DMD's usable life, and this interaction can be exploited to reduce the impact that an asymmetrical Landed Duty Cycle has on the DMD's usable life. This is quantified in the de-rating curve shown in 86-1. The importance of this curve is that:

- · All points along this curve represent the same usable life.
- All points above this curve represent lower usable life (and the further away from the curve, the lower the usable life).
- All points below this curve represent higher usable life (and the further away from the curve, the higher the usable life).

In practice, this curve specifies the maximum operating DMD Temperature at a given long-term average Landed Duty Cycle.

7.5.4 Estimating the Long-Term Average Landed Duty Cycle of a Product or Application

During a given period of time, the Landed Duty Cycle of a given pixel follows from the image content being displayed by that pixel.

For example, in the simplest case, when displaying pure-white on a given pixel for a given time period, that pixel will experience a 100/0 Landed Duty Cycle during that time period. Likewise, when displaying pure-black, the pixel will experience a 0/100 Landed Duty Cycle.

Between the two extremes (ignoring for the moment color and any image processing that may be applied to an incoming image), the Landed Duty Cycle tracks one-to-one with the gray scale value, as shown in \gtrsim 7-1.

表 7-1. Grayscale Value and Landed Duty Cycle

| GRAYSCALE VALUE | LANDED DUTY CYCLE |
|-----------------|-------------------|
| 0% | 0/100 |
| 10% | 10/90 |
| 20% | 20/80 |
| 30% | 30/70 |
| 40% | 40/60 |
| 50% | 50/50 |
| 60% | 60/40 |
| 70% | 70/30 |
| 80% | 80/20 |
| 90% | 90/10 |
| 100% | 100/0 |

Submit Document Feedback

Accounting for color rendition (but still ignoring image processing) requires knowing both the color intensity (from 0% to 100%) for each constituent primary color (red, green, and/or blue) for the given pixel as well as the color cycle time for each primary color, where "color cycle time" is the total percentage of the frame time that a given primary must be displayed in order to achieve the desired white point.

During a given period of time, the landed duty cycle of a given pixel can be calculated as follows:

Landed Duty Cycle = (Red_Cycle_% × Red_Scale_Value) + (Green_Cycle_% × Green_Scale_Value) + (Blue_Cycle_% (1) × Blue_Scale_Value)

where

• Red_Cycle_%, Green_Cycle_%, and Blue_Cycle_%, represent the percentage of the frame time that Red, Green, and Blue are displayed (respectively) to achieve the desired white point.

For example, assume that the red, green, and blue color cycle times are 50%, 20%, and 30% respectively (in order to achieve the desired white point), then the Landed Duty Cycle for various combinations of red, green, and blue color intensities would be as shown in $\frac{1}{2}$ 7-2.

表 7-2. Example Landed Duty Cycle for Full-Color

| | · pc · _ : | - u., -, | |
|--------------------------|----------------------------|---------------------------|-------------------|
| Red Cycle Percentage 50% | Green Cycle Percentage 20% | Blue Cycle Percentage 30% | Landed Duty Cycle |
| Red Scale Value | Green Scale Value | Blue Scale Value | |
| 0% | 0% | 0% | 0/100 |
| 100% | 0% | 0% | 50/50 |
| 0% | 100% | 0% | 20/80 |
| 0% | 0% | 100% | 30/70 |
| 12% | 0% | 0% | 6/94 |
| 0% | 35% | 0% | 7/93 |
| 0% | 0% | 60% | 18/82 |
| 100% | 100% | 0% | 70/30 |
| 0% | 100% | 100% | 50/50 |
| 100% | 0% | 100% | 80/20 |
| 12% | 35% | 0% | 13/87 |
| 0% | 35% | 60% | 25/75 |
| 12% | 0% | 60% | 24/76 |
| 100% | 100% | 100% | 100/0 |
| | | | |

Copyright © 2023 Texas Instruments Incorporated

Submit Document Feedback

8 Application and Implementation

备注

以下应用部分中的信息不属于 TI 器件规格的范围, TI 不担保其准确性和完整性。TI 的客户应负责确定器件是否适用于其应用。客户应验证并测试其设计,以确保系统功能。

8.1 Application Information

Texas Instruments DLP technology is a micro-electromechanical system (MEMS) technology that modulates light using a digital micromirror device (DMD). The DMD is a spatial light modulator, which reflects incoming light from an illumination source to one of two directions, either towards the projection optics or the collection optics. The large micromirror array size and ceramic package provides great thermal performance for bright display applications. Typical applications using the DLP550JE include digital signage, educational projector, and business projector.

The following orderables have been replaced by the DLP650JE:

Device Information

| PART NUMBER | PACKAGE | BODY SIZE (NOM) | MECHANICAL ICD |
|-------------|-----------|---------------------|----------------|
| DLP550JET | FYA (149) | 32.20 mm × 22.30 mm | 2512194 |
| 1076-6434B | FYA (149) | 32.20 mm × 22.30 mm | 2512194 |
| 1076-6438B | FYA (149) | 32.20 mm × 22.30 mm | 2512194 |
| 1076-6439B | FYA (149) | 32.20 mm × 22.30 mm | 2512194 |
| 1076-643AB | FYA (149) | 32.20 mm × 22.30 mm | 2512194 |

8.2 Typical Application

The DLP550JE digital micromirror device (DMD), combined with a DLPC4430 digital controller and a DLPA100 power management or a DLPA200 power management device, provides XGA resolution for bright, colorful display applications. A typical display system using the DLP550JE and additional system components is shown in Typical DLPC4430 Application (LED Top, LPCW Bottom).

Product Folder Links: DLP550JE



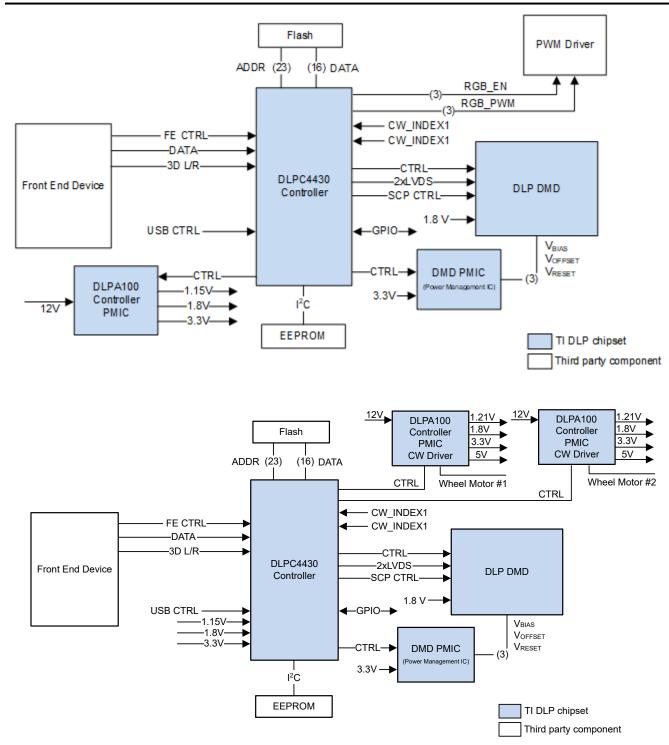


图 8-1. Typical DLPC4430 Application (LED Top, LPCW Bottom)

8.2.1 Design Requirements

The DLP550JE projection system is created by using the DMD chipset, including the DLP550JE, DLPC4430, DLPA100, and the DLPA200. The DLP550JE is used as the core imaging device in the display system and contains a 0.55-inch array of micromirrors. The DLPC4430 controller is the digital interface between the DMD and the rest of the system, taking digital input from front end receiver that converts the data from the source and using the converted data for driving the DMD over a high speed interface. The DLPA100 power management



device provides voltage regulators for the controller and illumination functionality. The DLPA200 provides the power and sequencing to drive the DLP550JE.

Other core components of the display system include an illumination source, an optical engine for the illumination and projection optics, other electrical and mechanical components, and software. The illumination source options include a lamp, LED, laser, or laser phosphor. The type of illumination used and desired brightness will have a major effect on the overall system design and size.

8.2.2 Detailed Design Procedure

For connecting the DLPC4430 display controller and the DLP550JE DMD, see the reference design schematic. For a complete DLP system, an optical module or light engine is required that contains the DLP550JE DMD, associated illumination sources, optical elements, and necessary mechanical components. The optical module is typically supplied by an OMM (optical module manufacturer) who specializes in designing optics for DLP projectors.

To ensure reliable operation, the DLP550JE DMD must always be used with the DLPC4430 display controller, a DLPA100 PMIC driver, and a DLPA200 DMD micromirror driver.

Product Folder Links: DLP550JE



9 Power Supply Recommendations

9.1 DMD Power-Up and Power-Down Procedures

The DLP550JE power-up and power-down procedures are defined by the DLPC4430 data sheet. The power supply guidelines are defined in the *DLPA200 DMD Micromirror Driver Data Sheet*. These procedures must be followed to ensure reliable operation of the device.

CAUTION

For reliable operation of the DMD, the following power supply sequencing requirements must be followed. Failure to adhere to the prescribed power-up and power-down procedures may affect device reliability. V_{CC} , V_{CCI} , V_{OFFSET} , and V_{MBRST} power supplies have to be coordinated during power-up and power-down operations. V_{SS} must also be connected. Failure to meet any of these requirements results in a significant reduction in the DMD's reliability and lifetime.

10 Device and Documentation Support

10.1 Device Support

10.1.1 第三方产品免责声明

TI 发布的与第三方产品或服务有关的信息,不能构成与此类产品或服务或保修的适用性有关的认可,不能构成此类产品或服务单独或与任何 TI 产品或服务一起的表示或认可。

10.1.2 Device Nomenclature



图 10-1. Device Number Description

10.1.3 Device Markings

The device marking includes both human-readable information and a 2-dimensional matrix code. The human readable information is described in [8] 10-2. The 2-dimensional matrix code is an alpha-numeric character string that contains the DMD part number, Part 1 of Serial Number, and Part 2 of Serial Number. The first character of the DMD Serial Number (part 1) is the manufacturing year. The second character of the DMD Serial Number (part 2) is the bias voltage bin letter.

Example: *1076-643AB GHXXXXX LLLLLLM

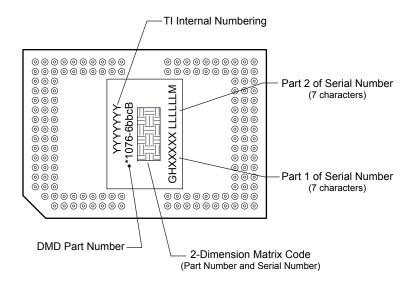


图 10-2. DMD Marking (Device Top View)

10.2 支持资源

TI E2E™ 支持论坛是工程师的重要参考资料,可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

Submit Document Feedback

www.ti.com.cn

链接的内容由各个贡献者"按原样"提供。这些内容并不构成 TI 技术规范,并且不一定反映 TI 的观点;请参阅 TI的《使用条款》。

10.2.1 Related Documentation

The following documents contain additional information related to the chipset components used with the DLP470NE.

- DLPC4430 Display Controller Data Sheet
- DLPA100 Power and Motor Driver Data Sheet

10.3 接收文档更新通知

要接收文档更新通知,请导航至 ti.com 上的器件产品文件夹。点击 订阅更新 进行注册,即可每周接收产品信息更 改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

10.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

DLP® is a registered trademark of TI.

所有商标均为其各自所有者的财产。

10.5 静电放电警告



静电放电 (ESD) 会损坏这个集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理 和安装程序,可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级,大至整个器件故障。精密的集成电路可能更容易受到损坏,这是因为非常细微的参 数更改都可能会导致器件与其发布的规格不相符。

10.6 术语表

TI 术语表 本术语表列出并解释了术语、首字母缩略词和定义。

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



www.ti.com 14-May-2023

PACKAGING INFORMATION

| Orderable Device | Status | Package Type | Package Drawing | Pins | Package Qty | Eco Plan | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|--------|--------------|--------------------|------|----------------|--------------|-------------------------------|--------------------|--------------|----------------------|---------|
| | | | | | | | (6) | | | | |
| DLP550JEFYA | ACTIVE | CPGA | FYA | 149 | 33 | RoHS & Green | NI-AU | N / A for Pkg Type | 0 to 70 | | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

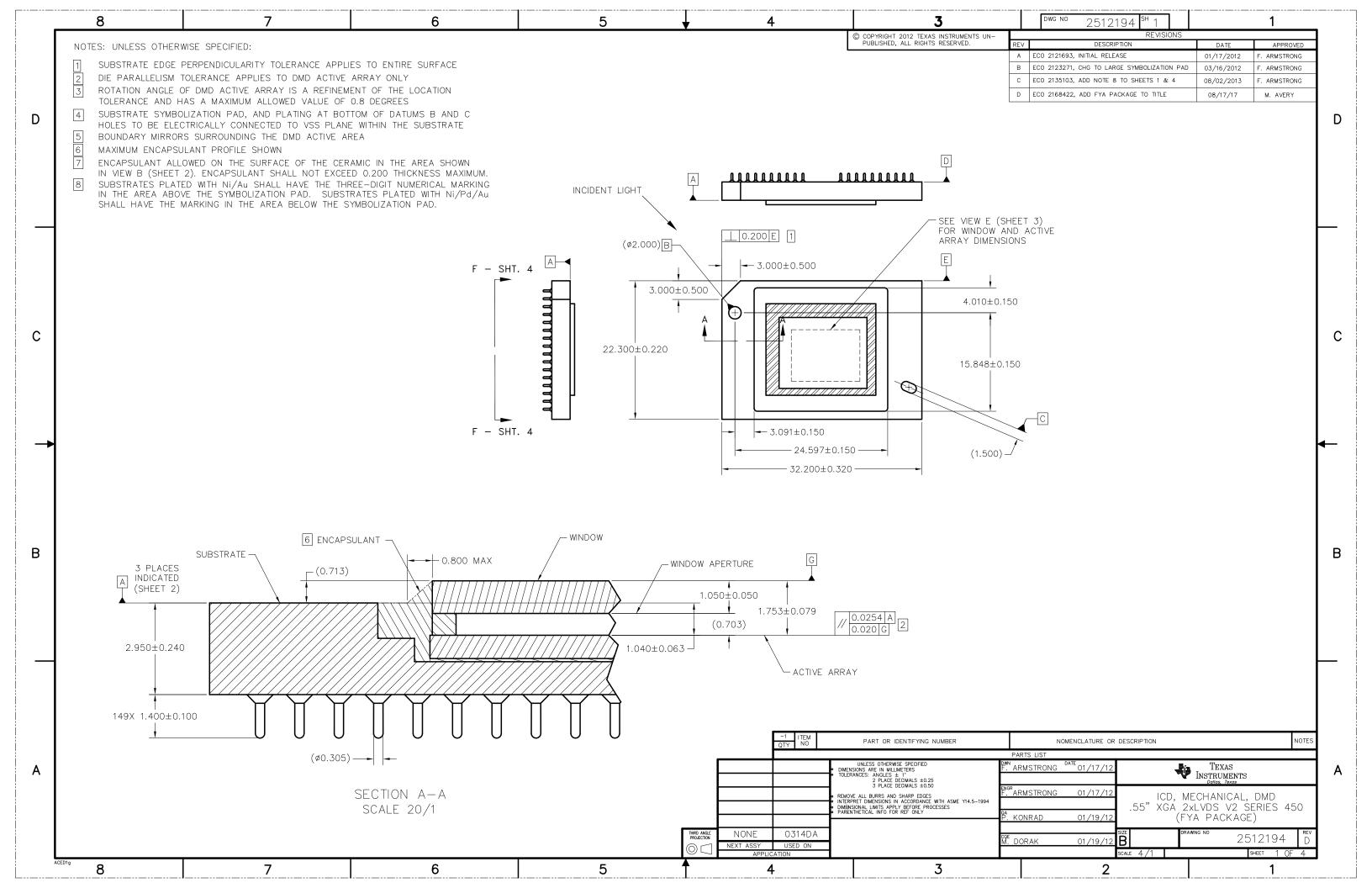
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

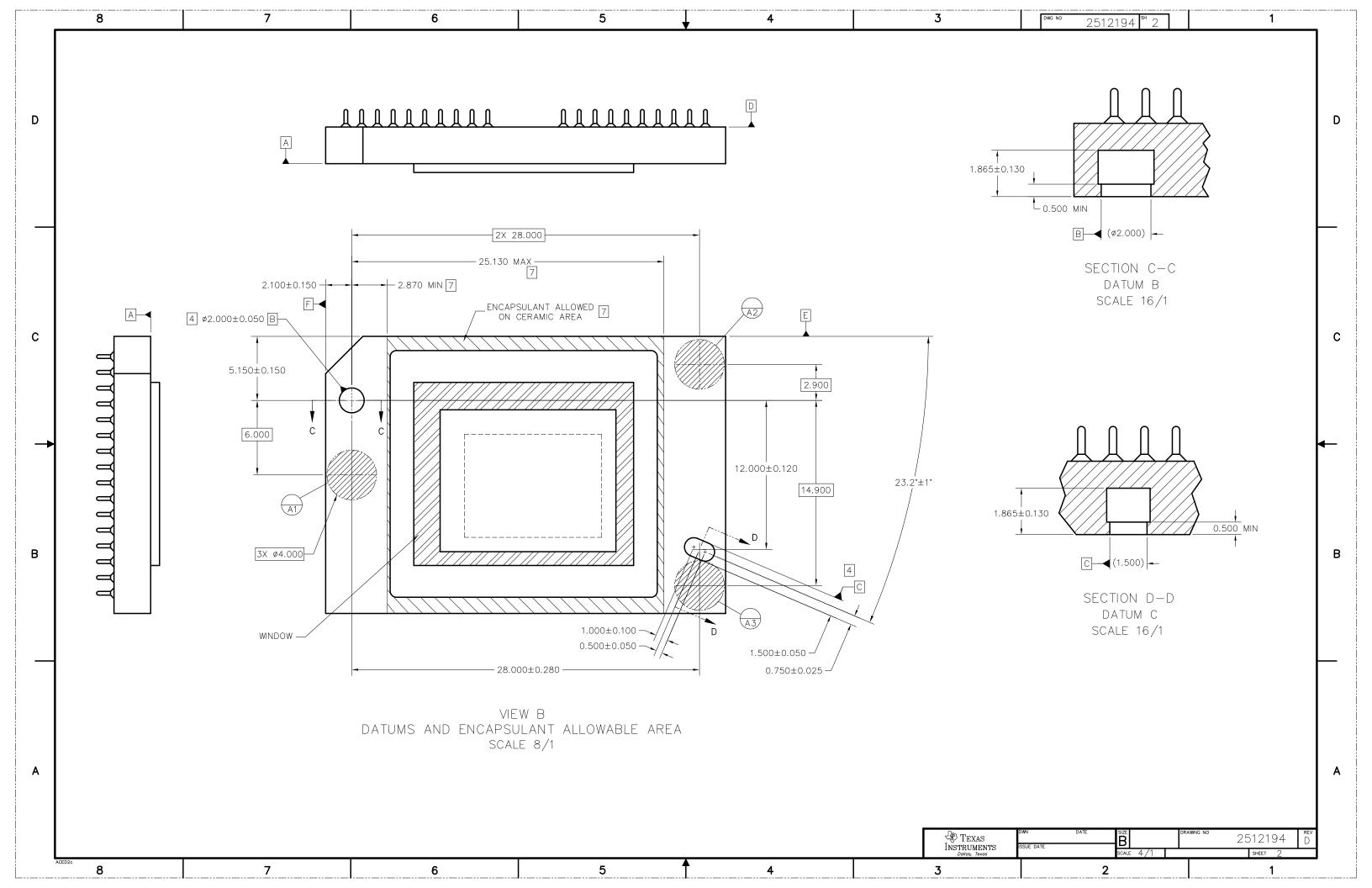
Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

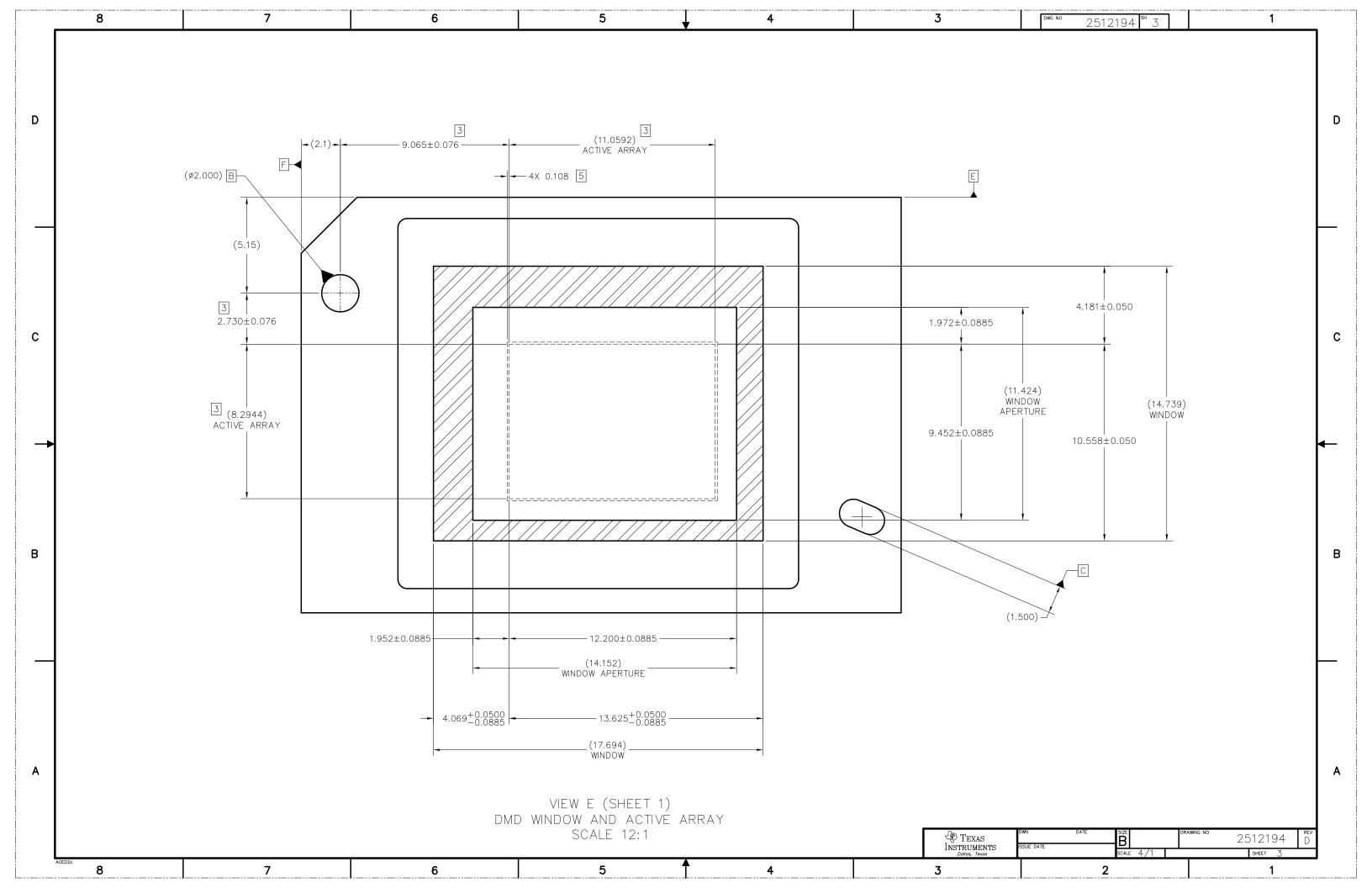
- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

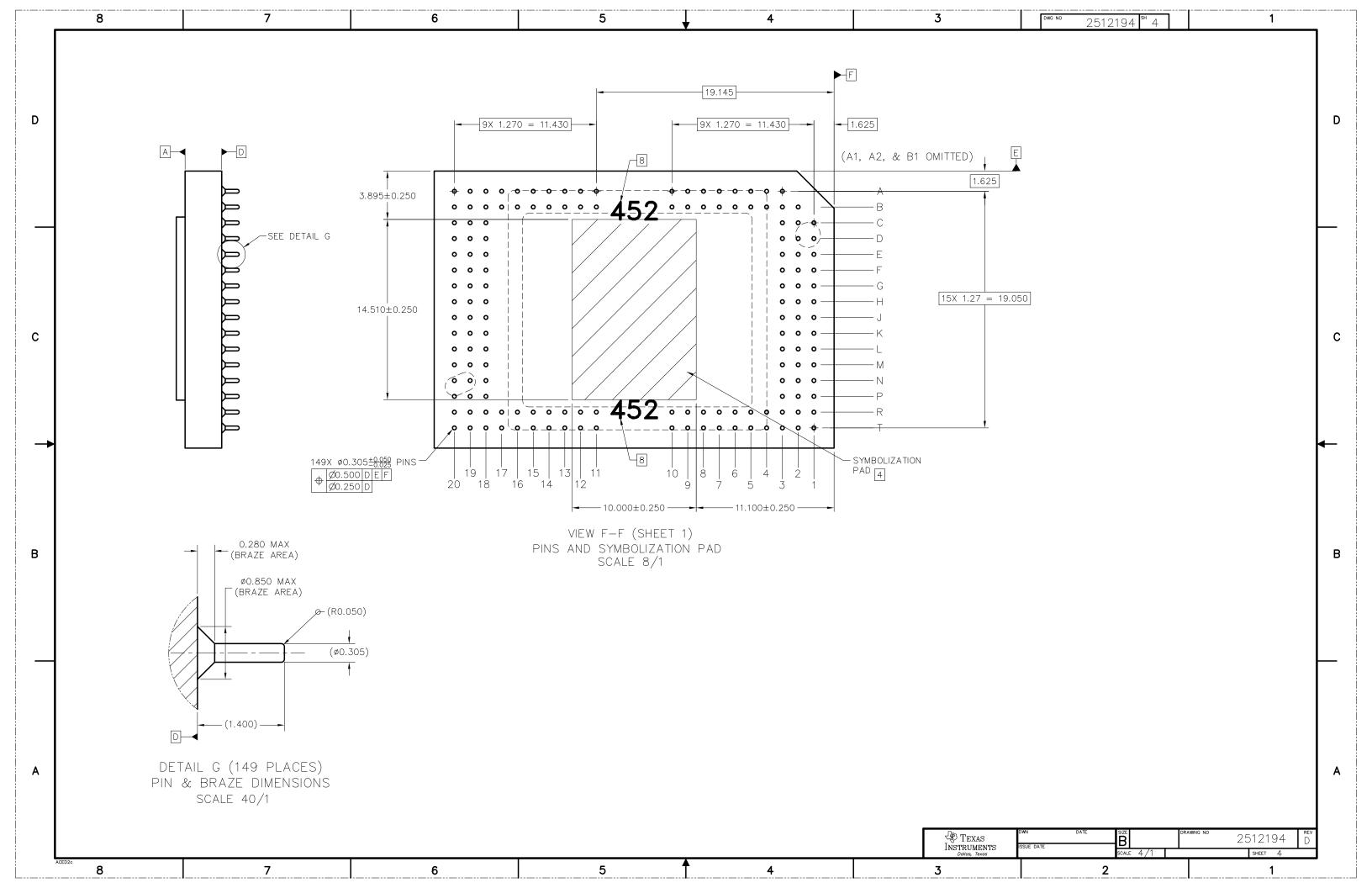
Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.









重要声明和免责声明

TI"按原样"提供技术和可靠性数据(包括数据表)、设计资源(包括参考设计)、应用或其他设计建议、网络工具、安全信息和其他资源,不保证没有瑕疵且不做出任何明示或暗示的担保,包括但不限于对适销性、某特定用途方面的适用性或不侵犯任何第三方知识产权的暗示担保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任:(1) 针对您的应用选择合适的 TI 产品,(2) 设计、验证并测试您的应用,(3) 确保您的应用满足相应标准以及任何其他功能安全、信息安全、监管或其他要求。

这些资源如有变更,恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的应用。严禁对这些资源进行其他复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。您应全额赔偿因在这些资源的使用中对 TI 及其代表造成的任何索赔、损害、成本、损失和债务,TI 对此概不负责。

TI 提供的产品受 TI 的销售条款或 ti.com 上其他适用条款/TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

邮寄地址: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023,德州仪器 (TI) 公司