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70-V Fault-Protected RS-485 Transceiver With Cable Invert

Check for Samples: SN65HVD1794, SN65HVD1795, SN65HVD1796

FEATURES

- Bus-Pin Fault Protection to > ±70 V
- Cable Invert Function Allows Correction for Reversed Bus Pins
- Common-Mode Voltage Range (-20 V to 25 V)
 More Than Doubles TIA/EIA 485 Requirement
- Bus I/O Protection
 - ±16 kV JEDEC HBM Protection
- Reduced Unit Load for Up to 256 Nodes

- Failsafe Receiver for Open-Circuit, Short-Circuit and Idle-Bus Conditions
- Low Power Consumption
 - I_{CC} 5 mA Quiescent During Operation
- Power-Up, Power-Down Glitch-Free Operation

APPLICATIONS

Designed for RS-485 and RS-422 Networks

DESCRIPTION

These devices are designed to survive overvoltage faults such as direct shorts to power supplies, mis-wiring faults, connector failures, cable crushes, and tool mis-applications. They are also robust to ESD events, with high levels of protection to human-body model specifications.

These devices combine a differential driver and a differential receiver, which operate from a single power supply. The driver differential outputs and the receiver differential inputs are connected internally to for a bus port suitable for half-duplex (two-wire bus) communication. A cable invert pin (INV) allows active correction of miswires that may occur during installation. Upon detecting communication errors, the user can apply a logic HIGH to the INV pin, effectively inverting the polarity of the differential bus port, thereby correcting for the reversed bus wires.

These devices feature a wide common-mode voltage range, making them suitable for multi-point applications over long cable runs. These devices are characterized from -40°C to 105°C.

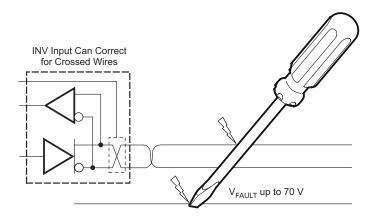


Table 1. PRODUCT SELECTION GUIDE

| PART NUMBER | DUPLEX | SIGNALING RATE | NODES | CABLE LENGTH | |
|---------------------|--------|----------------|-----------|--------------|--|
| SN65HVD1794 | Half | 115 kbps | Up to 256 | 1500 m | |
| SN65HVD1795 PREVIEW | Half | 1 Mbps | Up to 256 | 150 m | |
| SN65HVD1796 PREVIEW | Half | 10 Mbps | Up to 64 | 50 m | |

For similar features with 3.3 V supply operation, see the SN65HVD1781 (SLLS877).



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

DEVICE INFORMATION

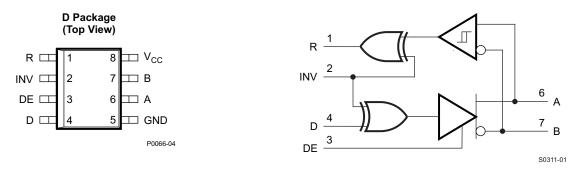


Figure 1. SN65HVD17xx With Inverting Feature to Correct for Miswired Cables

DRIVER FUNCTION TABLE

| INPUT | ENABLE | INVERT | OUT | PUTS | |
|-------|--------|--------|-----|------|---|
| D | DE | INV | Α | В | |
| Н | Н | L | Н | L | Actively drive normal bus High |
| L | Н | L | L | Н | Actively drive normal bus Low |
| Н | Н | Н | L | Н | Actively drive inverted bus High (drive normal bus Low) |
| L | П | Н | Н | L | Actively drive inverted bus Low (drive normal bus High) |
| Х | L | Х | Z | Z | Driver disabled |
| Х | OPEN | Х | Z | Z | Driver disabled by default |
| OPEN | Н | L | Н | L | Actively drive bus High by default |
| OPEN | Н | Н | L | Н | Actively drive bus Low by default (inverted cable) |

RECEIVER FUNCTION TABLE

| DIFFERENTIAL INPUT | INVERT | OUTPUT | |
|------------------------------|-----------|--------|---------------------------|
| $V_{ID} = V_A - V_B$ | INV | R | |
| V 4V | L or OPEN | Н | Receive valid bus High |
| $V_{IT+} < V_{ID}$ | Н | L | Receive inverted bus Low |
| $V_{IT-} < V_{ID} < V_{IT+}$ | X | ? | Indeterminate bus state |
| V -4V | L or OPEN | L | Receive valid bus Low |
| $V_{ID} < V_{IT-}$ | Н | Н | Receive inverted bus High |
| On an aircuit hua | L or OPEN | Н | Fail-safe high output |
| Open-circuit bus | Н | L | Failsafe inverted output |
| Short-circuit bus | L or OPEN | Н | Fail-safe high output |
| Short-circuit bus | Н | L | Failsafe inverted output |
| Idla (tarminated) bug | L or OPEN | Н | Fail-safe high output |
| Idle (terminated) bus | Н | L | Failsafe inverted output |

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ABSOLUTE MAXIMUM RATINGS(1)

| | | VALUE | UNIT |
|-----------------|---|------------------------------|------|
| V _{CC} | Supply voltage | -0.5 to 7 | V |
| | Voltage range at A and B pins with respect to GND | -70 to 70 | V |
| | Voltage range across A and B pins (differential) | -70 to 70 | V |
| | Input voltage range at any logic pin | -0.3 to $V_{CC} + 0.3$ | V |
| | Voltage input range, transient pulse, A and B, through 100 Ω | -100 to 100 | V |
| | Receiver output current | -24 to 24 | mA |
| ΓJ | Junction temperature | 170 | °C |
| | Continuous total power dissipation | See Dissipation Rating Table | |
| | IEC 60749-26 ESD (human-body model), bus terminals and GND | ±16 | kV |
| | JEDEC Standard 22, Test Method A114 (human-body model), bus terminals and GND | ±16 | kV |
| | JEDEC Standard 22, Test Method A114 (human-body model), all pins | ±4 | kV |
| | JEDEC Standard 22, Test Method C101 (charged-device model), all pins | ±2 | kV |
| | JEDEC Standard 22, Test Method A115 (machine model), all pins | ±400 | V |

⁽¹⁾ Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

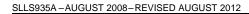
PACKAGE DISSIPATION RATINGS

| PACKAGE | JEDEC THERMAL MODEL | T _A < 25°C RATING | DERATING FACTOR ABOVE T _A = 25°C | T _A = 85°C RATING | T _A = 105°C RATING |
|----------------|---------------------|---------------------------------|--|---------------------------------|----------------------------------|
| COIC (D) 0 min | High-K | 905 mW | 7.25 mW/°C | 470 mW | 325 mW |
| SOIC (D) 8-pin | Low-K | 516 mW | 4.1 mW/°C | 268 mW | 186 mW |
| DDID (D) 0 nin | High-K | 2119 mW | 16.9 mW/°C | 1100 mW | 763 mW |
| PDIP (P) 8-pin | Low-K | 976 mW | 7.8 mW/°C | 508 mW | 352 mW |

RECOMMENDED OPERATING CONDITIONS

| | | | MIN | NOM | MAX | UNIT | |
|-------------------|----------------------------|--|-----|-----|-----------------|------|--|
| V_{CC} | Supply voltage | | 4.5 | 5 | 5.5 | V | |
| VI | Input voltage at | any bus terminal (separately or common mode) ⁽¹⁾ | -20 | | 25 | V | |
| V _{IH} | High-level input | voltage (driver, driver enable, and invert inputs) | 2 | | V _{CC} | V | |
| V_{IL} | Low-level input | voltage (driver, driver enable, and invert inputs) | 0 | | 8.0 | V | |
| V_{ID} | Differential input voltage | | -25 | | 25 | V | |
| | Output current, | driver | -60 | | 60 | mA | |
| IO | Output current, | receiver | -8 | | 8 | mA | |
| R_L | Differential load | resistance | 54 | 60 | | Ω | |
| C_L | Differential load | capacitance | | 50 | | pF | |
| | | HVD1794 | | | 115 | kbps | |
| 1/t _{UI} | Signaling rate | HVD1795 | | | 1 | Mana | |
| | | HVD1796 | | | 10 | Mbps | |
| T _A | Operating free-a | ir temperature (See application section for thermal information) | -40 | | 105 | °C | |
| TJ | Junction temper | ature | -40 | | 150 | °C | |

⁽¹⁾ By convention, the least positive (most negative) limit is designated as minimum in this data sheet.





ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | | MIN | TYP | MAX | UNIT |
|---------------------|--|--|-----------------------|-----------------------|------|--------------------------|-----|------|
| | | RS-485 with | T _A ≤ 85° | С | 1.5 | | | |
| V _{OD} | Driver differential output voltage magnitude | common-mode load, $V_{CC} > 4.75 \text{ V}$, see Figure 2 | T _A ≤ 105 | 5°C | 1.4 | | | V |
| | | $R_L = 54 \Omega, 4.75 V \le V$ | _{CC} ≤ 5.25 | V | 1.5 | 2 | | |
| | | $R_L = 100 \Omega, 4.75 V \le 100$ | V _{CC} ≤ 5.2 | 5 V | 2 | 2.5 | | |
| $\Delta V_{OD} $ | Change in magnitude of driver differential output voltage | R _L = 54 Ω | | | -0.2 | 0 | 0.2 | V |
| V _{OC(SS)} | Steady-state common-mode output voltage | | | | 1 | V _{CC} /2 | 3 | V |
| ΔV_{OC} | Change in differential driver output common- mode voltage | | | | -100 | 0 | 100 | mV |
| V _{OC(PP)} | Peak-to-peak driver common-mode output voltage | Center of two 27-Ω los Figure 3 | ad resistor | s, See | | 500 | | mV |
| C _{OD} | Differential output capacitance | | | | | 23 | | pF |
| V_{IT+} | Positive-going receiver differential input voltage threshold | | | | | -100 | -10 | mV |
| V_{IT-} | Negative-going receiver differential input voltage threshold | V _{CM} = -20 V to 25 V | | | -200 | -150 | | mV |
| V_{HYS} | Receiver differential input voltage threshold hysteresis $(V_{\text{IT+}} - V_{\text{IT-}})$ | | | | 30 | 50 | | mV |
| V_{OH} | Receiver high-level output voltage | $I_{OH} = -8 \text{ mA}$ | | | 2.4 | V _{CC} - 0.3 | | V |
| V | Receiver low-level output voltage | I _{OL} = 8 mA | $T_A \le 85^\circ$ | С | | 0.2 | 0.4 | V |
| V _{OL} | Receiver low-level output voltage | IOL = 0 IIIA | T _A ≤ 105 | 5°C | | 0.2 | 0.5 | V |
| I | Driver input, driver enable, and invert input current | | | | -100 | | 100 | μΑ |
| I _{OS} | Driver short-circuit output current | | | | -250 | | 250 | mA |
| | | | 94, 95 | V _I = 12 V | | 75 | 125 | |
| I _I | Bus input current (disabled driver) | $V_{CC} = 4.5 \text{ to } 5.5 \text{ V or}$ | 94, 93 | $V_I = -7 V$ | -100 | -40 | | μA |
| ij Dus ii iş | bus input current (disabled differ) | $V_{CC} = 0 \text{ V}, DE \text{ at } 0 \text{ V}$ | 96 | V _I = 12 V | | | 500 | μΛ |
| | | | 30 | $V_I = -7 V$ | -400 | | | |
| loo | Supply current (quiescent) | Driver enabled | DE = 5V | DE = 5V | | 4 | 6 | mA |
| I _{CC} | ouppry ourreint (quiescerit) | Driver disabled | ver disabled DE = GND | | | 2 | 4 | |
| | Supply current (dynamic) | See TYPICAL CHARA | ACTERIST | TCS section | | | | |



SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

| PARAMETER | | TEST CONDITION | TEST CONDITIONS | | TYP | MAX | UNIT |
|-------------------------------------|---|--|--|-----|-----|-----|------|
| DRIVER (H) | /D1794) | | | | | , | |
| t _r , t _f | Driver differential output rise/fall time | | | 0.4 | 1.7 | 2.6 | μs |
| t _{PHL} , t _{PLH} | Driver propagation delay | $R_1 = 54 \Omega$, $C_1 = 50 pF$, See Figure 4 | | | 0.8 | 2 | μs |
| t _{SK(P)} | Driver differential output pulse skew, tpHL - tpLH | Ν = 34 Ω, Ο = 30 ρι , σεε ι | iguic 4 | | 20 | 250 | ns |
| t _{PHZ} , t _{PLZ} | Driver disable time | See Figure 5 and Figure 6 | | | 0.1 | 5 | μs |
| t _{PZH} , t _{PZL} | Driver enable time | | | | 0.2 | 3 | μs |
| DRIVER (HV | /D1795) | | | | | • | |
| t _r , t _f | Driver differential output rise/fall time | | | 50 | | 300 | ns |
| t _{PHL} , t _{PLH} | Driver propagation delay | R 54 O. C 50 pF. See | Figure 4 | | | 200 | ns |
| t _{SK(P)} | Driver differential output pulse skew, t _{PHL} - t _{PLH} | Ν[– 34 Ω, Θ[– 30 μ] , σεε Ι | $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 4 | | | 25 | ns |
| t _{PHZ} , t _{PLZ} | Driver disable time | See Figure 5 and Figure 6 | See Figure 5 and Figure 6 | | | 3 | μs |
| t _{PZH} , t _{PZL} | Driver enable time | | | | 500 | ns | |
| DRIVER (H) | /D1796) | | | | | , | |
| t _r , t _f | Driver differential output rise/fall time | | | 3 | | 30 | ns |
| t _{PHL} , t _{PLH} | Driver propagation delay | $R_1 = 54 \Omega, C_1 = 50 pF, See F$ | Figure 4 | | | 50 | ns |
| t _{SK(P)} | Driver differential output pulse skew, tpHL - tpLH | Λ[= 54 Ω, δ[= 50 μ , δεε τ | iguic 4 | | | 10 | ns |
| t _{PHZ} , t _{PLZ} | Driver disable time | See Figure 5 and Figure 6 | | | | 3 | μs |
| t _{PZH} , t _{PZL} | Driver enable time | | | | | 500 | ns |
| RECEIVER | (ALL DEVICES UNLESS OTHERWISE NOT | ED) | | | | , | |
| t _r , t _f | Receiver output rise/fall time | | | | 4 | 15 | ns |
| | B : " !! " | | 94, 95 | | 100 | 200 | |
| t _{PHL} , t _{PLH} | Receiver propagation delay time | C _L = 15 pF, See Figure 7 | 96 | | | 70 | ns |
| | Receiver output pulse skew, | | 94, 95 | | 6 | 20 | |
| t _{SK(P)} | tphl - tplh | | 96 | | | 5 | ns |



THERMAL INFORMATION

| PARAMETER | | TEST CONDITIONS | VALUE | UNIT | |
|--|--------|---|-------|-------|--|
| | SOIC-8 | JEDEC high-K model | 138 | | |
| D. Lunction to ambient thermal resistance (no cirfleur) | SOIC-8 | JEDIC low-K model | 242 | °C/W | |
| R _{0JA} Junction-to-ambient thermal resistance (no airflow) | DIP-8 | JEDEC high-K model | 59 | *C/VV | |
| | DIP-6 | JEDIC low-K model | 128 | | |
| D. Lunction to board thormal registeres | SOIC-8 | | 62 | °C/W | |
| R _{BJB} Junction-to-board thermal resistance | DIP-8 | | 39 | *C/VV | |
| R _{BJC} Junction-to-case thermal resistance | SOIC-8 | | 61 | °C/W | |
| | DIP-8 | | 61 | *C/VV | |
| | 94 | $V_{CC} = 5.5 \text{ V}, T_J = 150^{\circ}\text{C}, R_L = 300 \ \Omega,$ $C_L = 50 \text{ pF (driver)}, C_L = 15 \text{ pF (receiver)}$ 5-V supply, unterminated ⁽¹⁾ | 290 | | |
| | 94 | $V_{CC} = 5.5 \text{ V}, T_J = 150^{\circ}\text{C}, R_L = 100 \Omega,$ | | | |
| P _D Power dissipation | 95 | $C_L = 50 \text{ pF (driver)}, C_L = 15 \text{ pF (receiver)}$ 5-V supply, RS-422 load ⁽¹⁾ | 320 | mW | |
| T b T ower discipation | 96 | 0 1 Supply, 110 122 15dd | | | |
| | 94 | $V_{CC} = 5.5 \text{ V}, T_J = 150^{\circ}\text{C}, R_L = 54 \Omega,$ | 400 | | |
| | 95 | C _L = 50 pF (driver), C _L = 15 pF (receiver) 5-V supply, RS-485 load ⁽¹⁾ | | | |
| | 96 | | | | |
| T _{SD} Thermal-shutdown junction temperature | | | 170 | °C | |

Driver enabled, 50% duty cycle square-wave signal at signaling rate: 115 kbps for HVD1794, 1 Mbps for HVD1795, 10 Mbps for HVD1796

PARAMETER MEASUREMENT INFORMATION

Input generator rate is 100 kbps, 50% duty cycle, rise and fall times less than 6 nsec, output impedance 50 Ω .

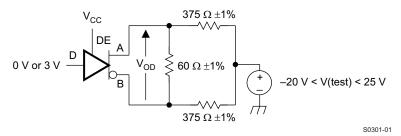


Figure 2. Measurement of Driver Differential Output Voltage With Common-Mode Load

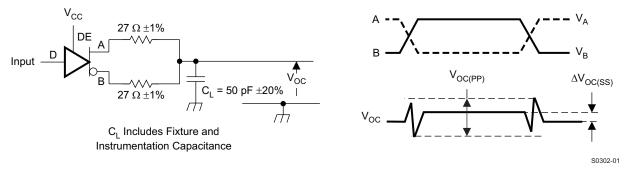


Figure 3. Measurement of Driver Differential and Common-Mode Output With RS-485 Load



PARAMETER MEASUREMENT INFORMATION (continued)

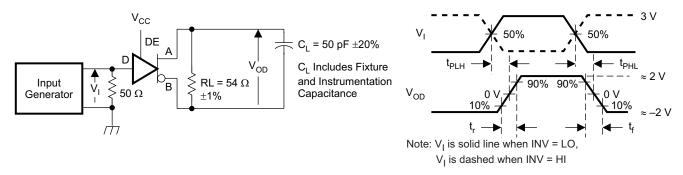
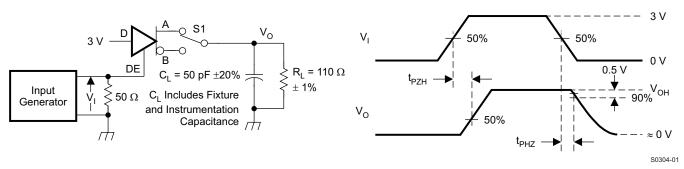
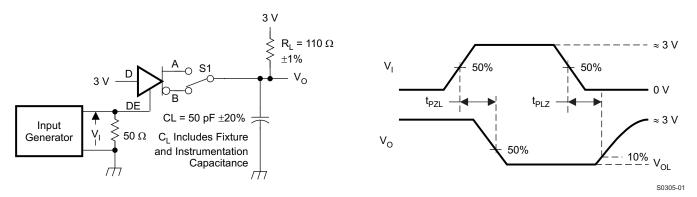


Figure 4. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays



NOTE: D at 3 V to test non-inverting output, D at 0 V to test inverting output.

Figure 5. Measurement of Driver Enable and Disable Times With Active High Output and Pulldown Load



NOTE: D at 0 V to test non-inverting output, D at 3 V to test inverting output.

Figure 6. Measurement of Driver Enable and Disable Times With Active-Low Output and Pullup Load



PARAMETER MEASUREMENT INFORMATION (continued)

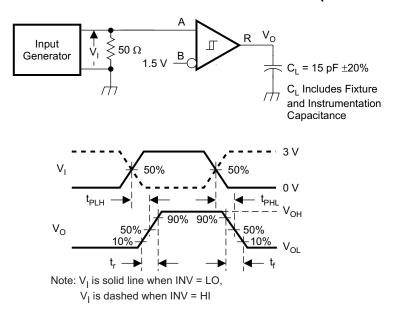
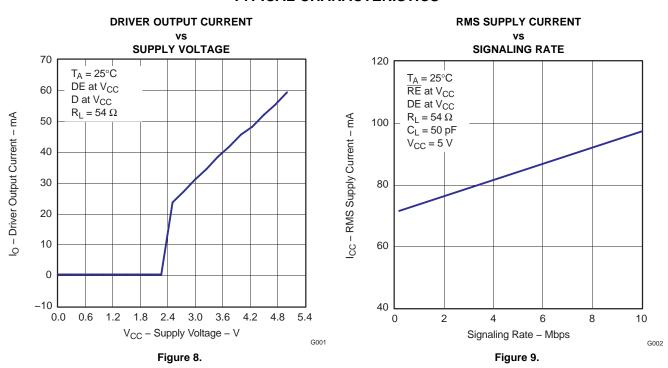


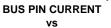
Figure 7. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

TYPICAL CHARACTERISTICS





TYPICAL CHARACTERISTICS (continued)



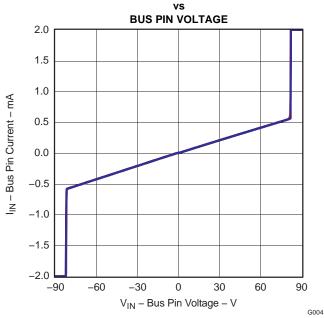


Figure 10.

DIFFERENTIAL OUTPUT VOLTAGE

VS

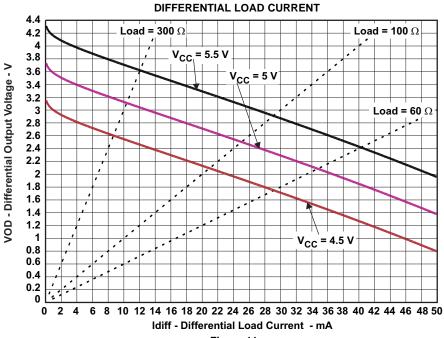


Figure 11.



ADDITIONAL OPTIONS

The SN65HVD17xx family also has options for J1708 applications, for always-enabled full-duplex versions (industry-standard SN65LBC179 footprint) and for inverting-polarity versions, which allow users to correct a reversal of the bus wires without re-wiring. Contact your local Texas Instruments representative for information on these options.

| PART NUMBER | SN65HVD17xx | | | | |
|---|-------------|--------|------|--|--|
| FOOTPRINT/FUNCTION | SLOW | MEDIUM | FAST | | |
| Half-duplex (176 pinout) | 85 | 86 | 87 | | |
| Full-duplex no enables (179 pinout) | 88 | 89 | 90 | | |
| Full-duplex with enables (180 pinout) | 91 | 92 | 93 | | |
| Half-duplex with cable invert | 94 | 95 | 96 | | |
| Full-duplex with cable invert and enables | 97 | 98 | 99 | | |
| J1708 | 08 | 09 | 10 | | |



Figure 12. SN65HVD1708E Transceiver for J1708 Applications



Figure 13. SN65HVD17xx Always-Enabled Driver Receiver



APPLICATION INFORMATION

Hot-Plugging

These devices are designed to operate in "hot swap" or "hot pluggable" applications. Key features for hot-pluggable applications are power-up, power-down glitch free operation, default disabled input/output pins, and receiver failsafe. As shown in Figure 8, an internal Power-On Reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device will reliably operate. This ensures that no spurious transitions (glitches) will occur on the bus pin outputs as the power supply turns on or turns off.

As shown in the device **FUNCTION TABLE**, the *ENABLE* inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device will neither drive the bus nor report data on the R pin until the associated controller actively drives the enable pins.

Likewise, the receiver output is "failsafe" to open-circuit, short-circuit, or idle (terminated only) bus conditions. This eliminates false transitions on the receiver output until a valid RS-485 signal is applied to the receiver input pins.

Cable Invert

For many RS-485 applications, wiring of data cables takes place during equipment installation, and the possibility of miss-wiring is a significant issue. When the twisted-pair wires are reversed due to installation mistakes, normal RS-485 communication is not possible. The Cable Invert (INV) pin allows designers to compensate for this installation mistake. Under normal circumstances, the INV pin can be set to logic LOW, and the transceiver operates with normal polarity. If, after initial network start-up, a node cannot communicate properly, the local controller can set the INV pin high, which will invert the polarity of the A and B differential bus pins. This will compensate for a reversal of the bus wires, allowing proper communication.

Receiver Failsafe

The differential receiver is "failsafe" to invalid bus states caused by open bus conditions such as a disconnected connector, shorted bus conditions such as cable damage shorting the twisted-pair together or idle bus conditions that occur when no driver is actively driving a valid RS-485 bus state on the network. In any of these cases, the differential receiver outputs a failsafe state, so that small noise signals do not cause spurious transitions at the receiver output. When INV is logic Low or Open (normal operation), the receiver output will be failsafe High. When INV is logic High to correct for a twisted-pair reversal, the receiver output will be failsafe Low under those fault conditions.

SN65HVD1794, SN65HVD1795 SN65HVD1796



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| Changes from Original (August 2008) to Revision A | | | | | |
|---|--|---|--|--|--|
| • | Added Voltage range across A and B pins (differential) in Absolute Maximum Ratings table | 3 | | | |

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PACKAGING INFORMATION

| Orderable part number | Status | Material type | Package Pins | Package qty Carrier | RoHS | Lead finish/ | MSL rating/ | Op temp (°C) | Part marking |
|-----------------------|--------|---------------|----------------|-----------------------|------|---------------|--------------------|--------------|--------------|
| | (1) | (2) | | | (3) | Ball material | Peak reflow | Peak reflow | |
| | | | | | | (4) | (5) | | |
| SN65HVD1794D | Active | Production | SOIC (D) 8 | 75 TUBE | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |
| SN65HVD1794D.A | Active | Production | SOIC (D) 8 | 75 TUBE | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |
| SN65HVD1794D.B | Active | Production | SOIC (D) 8 | 75 TUBE | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |
| SN65HVD1794DR | Active | Production | SOIC (D) 8 | 2500 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |
| SN65HVD1794DR.A | Active | Production | SOIC (D) 8 | 2500 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |
| SN65HVD1794DR.B | Active | Production | SOIC (D) 8 | 2500 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 105 | VP1794 |

⁽¹⁾ Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



PACKAGE OPTION ADDENDUM

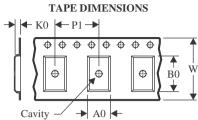
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PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width |
|----|---|
| В0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

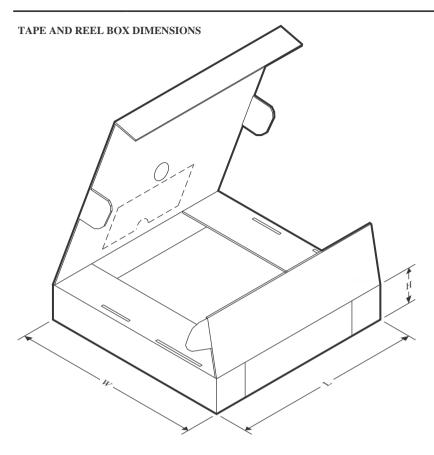


*All dimensions are nominal

| Device | | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|---------------|------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| SN65HVD1794DR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |

PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

| | Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---|---------------|--------------|-----------------|------|------|-------------|------------|-------------|
| 5 | SN65HVD1794DR | SOIC | D | 8 | 2500 | 353.0 | 353.0 | 32.0 |

PACKAGE MATERIALS INFORMATION

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TUBE



*All dimensions are nominal

| Device | Package Name | Package Type | Pins | SPQ | L (mm) | W (mm) | T (µm) | B (mm) |
|----------------|--------------|--------------|------|-----|--------|--------|--------|--------|
| SN65HVD1794D | D | SOIC | 8 | 75 | 506.6 | 8 | 3940 | 4.32 |
| SN65HVD1794D.A | D | SOIC | 8 | 75 | 506.6 | 8 | 3940 | 4.32 |
| SN65HVD1794D.B | D | SOIC | 8 | 75 | 506.6 | 8 | 3940 | 4.32 |



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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