

High-Speed Interface Layout Guidelines

Embedded Processor Applications

ABSTRACT

As modern bus interface frequencies scale higher, care must be taken in the printed circuit board (PCB) layout phase of a design to ensure a robust solution.

Contents

1	Introduction	3
2	General High-Speed Signal Routing	4
3	High-Speed Differential Signal Routing	10
4	References	18
Appendix A	Device Layout Parameters	19

List of Figures

1	Rotation of the PCB Image	4
2	Routing Angle Rotation	5
3	Zig-Zag Routing	5
4	PCB Fiberglass Style Examples	6
5	Length Matching	6
6	Incorrect Plane Void Routing	7
7	Correct Plane Void Routing	7
8	Incorrect Plane-Split Signal Routing	8
9	Stitching Capacitor Placement	8
10	Overlapped Planes	9
11	Stitching Vias	9
12	USB3/SATA/PCIe/HDMI/SGMII Differential Signal Spacing (mils)	10
13	USB2 Differential Signal Spacing (mils)	10
14	Differential Pair Symmetry	11
15	USB Through-Hole Receptacle Connection	12
16	Via Length (Long Stub)	13
17	Via Length (Short Stub)	13
18	Anti-Pad Diameter	14
19	AC-Coupling Placement	15
20	Reference Plane Voiding of Surface-Mount Devices	16
21	Signal Bending Rules	16
22	Flow-Through Routing	17

List of Tables

1	Critical Signals	3
2	Example PCB Stackups	17
3	AM335x/AM437x/AMIC1xx	19
4	AM57xx/DRA7xx	19

5	KeyStone II - K2K, K2H, K2L, and K2E Devices.....	20
6	KeyStone II - K2G (66AK2G0x/66AK2G1x) Devices	21
7	AM6xx/DRA80xM	21

Trademarks

Texas Instruments is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

1 Introduction

1.1 Scope

This application report can help system designers implement best practices and understand PCB layout options when designing platforms. This document is intended for audiences familiar with PCB manufacturing, layout, and design.

1.2 Critical Signals

A primary concern when designing a system is accommodating and isolating high-speed signals. As high-speed signals are most likely to impact or be impacted by other signals, they must be laid out early (preferably first) in the PCB design process to ensure that prescribed routing rules can be followed.

[Table 1](#) outlines the high-speed interface signals requiring the most attention when laying out a PCB that incorporates a Texas Instruments™ System-on-Chip (SoC).

Table 1. Critical Signals

Signal Name	Description
DP	Universal Serial Bus (USB) 2.0 differential data pair, positive
DM	Universal Serial Bus (USB) 2.0 differential data pair, negative
SSTXP	SuperSpeed Universal Serial Bus (SSUSB) differential data pair, TX, positive
SSTXN	SuperSpeed Universal Serial Bus (SSUSB) differential data pair, TX, negative
SSRXP	SuperSpeed Universal Serial Bus (SSUSB) differential data pair, RX, positive
SSRXN	SuperSpeed Universal Serial Bus (SSUSB) differential data pair, RX, negative
SATA_RXP	Serial ATA (SATA) differential data pair, RX, positive
SATA_RXN	Serial ATA (SATA) differential data pair, RX, negative
SATA_TXP	Serial ATA (SATA) differential data pair, TX, positive
SATA_TXN	Serial ATA (SATA) differential data pair, TX, negative
PCIe_RXP	PCI-Express (PCIe) differential data pair, RX, positive
PCIe_RXN	PCI-Express (PCIe) differential data pair, RX, negative
PCIe_TXP	PCI-Express (PCIe) differential data pair, TX, positive
PCIe_TXN	PCI-Express (PCIe) differential data pair, TX, negative
HDMI_CLOCKx	High-Definition Multimedia Interface (HDMI) differential clock pair, positive or negative
HDMI_CLOCKy	High-Definition Multimedia Interface (HDMI) differential clock pair, positive or negative
HDMI_DATA2x	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
HDMI_DATA2y	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
HDMI_DATA1x	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
HDMI_DATA1y	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
HDMI_DATA0x	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
HDMI_DATA0y	High-Definition Multimedia Interface (HDMI) differential data pair, positive or negative
SGMII_TXP	Serial Gigabit Media Independent Interface (SGMII) differential data pair, TX, positive
SGMII_TXN	Serial Gigabit Media Independent Interface (SGMII) differential data pair, TX, negative
SGMII_RXP	Serial Gigabit Media Independent Interface (SGMII) differential data pair, RX, positive
SGMII_RXN	Serial-Gigabit Media Independent Interface (SGMII) differential data pair, RX, negative

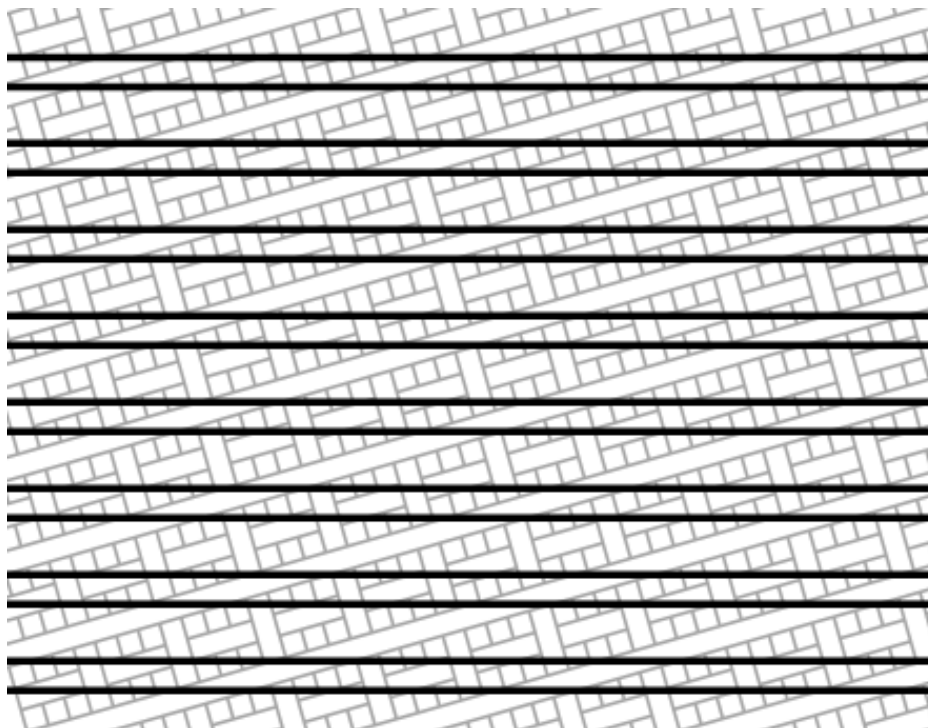
NOTE: Not all referenced interfaces are present on all Texas Instruments SoC devices.

2 General High-Speed Signal Routing

2.1 PCB Fiber Weave Mitigation

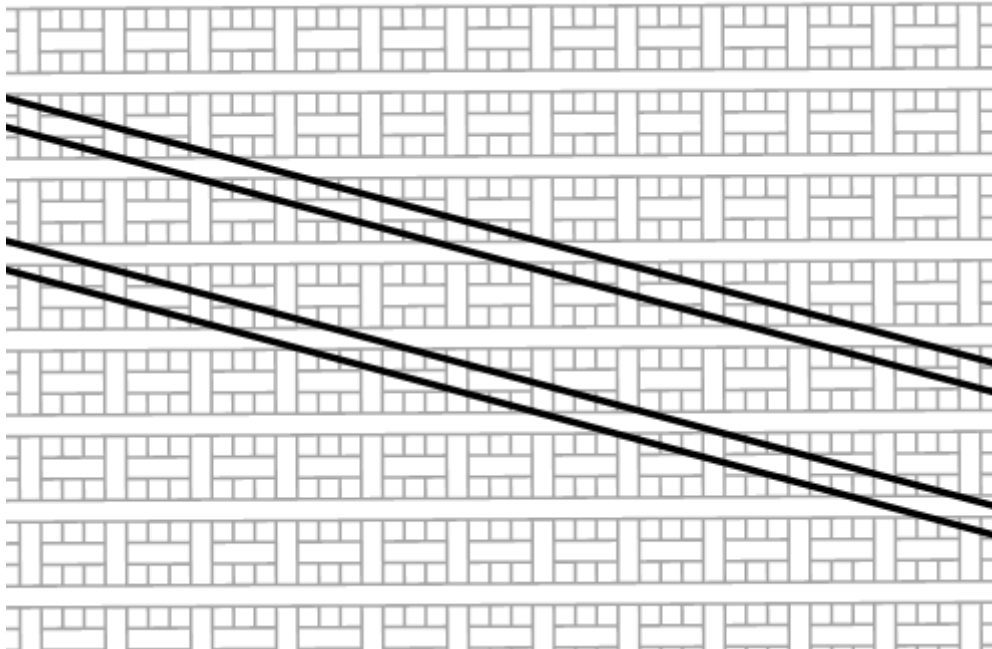
When routing differential signals across common PCB materials, each trace of the pair will experience different dielectric constants and corresponding signal velocities due to the differences in static permittivity (ϵ_r) of the fiberglass weave (ϵ_r is approximately 6) and epoxy (ϵ_r is approximately 3) that comprise a PCB. As signals travel faster when ϵ_r is lower, an interpair skew can develop if a signal in a differential pair travels over a higher ratio of fiberglass or epoxy than does its companion signal. This skew between the differential signals can significantly degrade the differential eye diagram as presented to the receiver, cause significant AC common-mode voltage noise, and cause EMI issues. The extent of this problem will depend on the bus speed, the length of the traces, the trace geometries, the type of fiberglass weave used, and the alignment of the traces to the weave pattern of a PCB. Problems from fiber weave alignment vary from board to board. This variance makes issues difficult to diagnose.

Figure 1, Figure 2, and Figure 3 show the three most common methods to minimize the impact of PCB fiber weave in a board design. The goal of each method is to ensure that both signals of the differential pair will share a relatively common ϵ_r across the length of the pair routing.



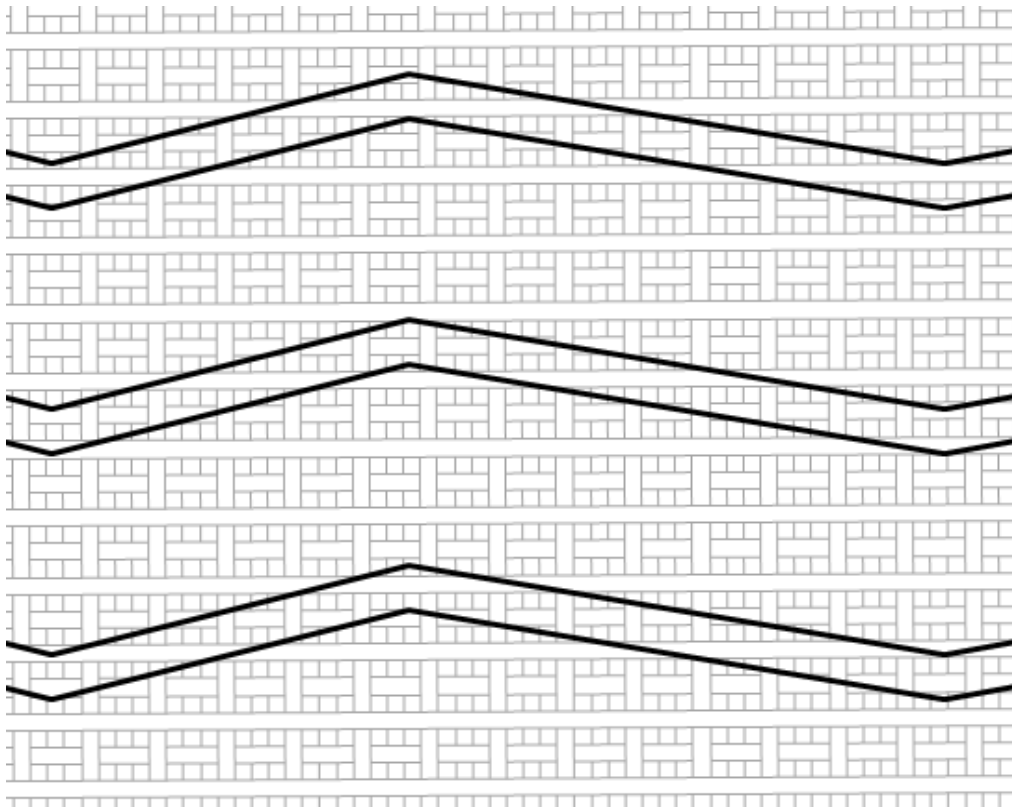
The entirety of the signaling image plane is rotated 10° to 35° in relation to the underlying PCB fiber weave. The PCB manufacturer can effect this rotation without making changes to the PCB layout database.

Figure 1. Rotation of the PCB Image



Only the high-speed differential signals are routed at a 10° to 35° angle in relation to the underlying PCB fiber weave.

Figure 2. Routing Angle Rotation



The high-speed differential signals are routed in a zig-zag fashion across the PCB.

Figure 3. Zig-Zag Routing

Because the ratio of fiberglass to epoxy is the primary contributor to the ϵ_r disparity, choose a PCB style with a tighter weave, less epoxy, and greater ϵ_r uniformity across longer trace lengths. Before sending your design out for fabrication, specify a PCB style that can best accommodate high-speed signals. For examples of common PCB styles, see [Figure 4](#).

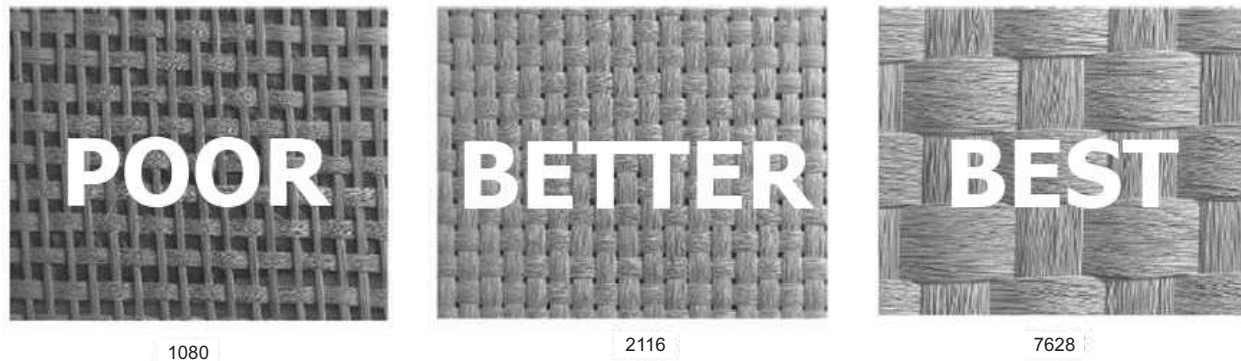


Figure 4. PCB Fiberglass Style Examples

2.2 High-Speed Signal Trace Lengths

As with all high-speed signals, keep total trace length for signal pairs to a minimum. For trace length requirements for each device, see [Appendix A](#).

2.3 High-Speed Signal Trace Length Matching

Match the etch lengths of the relevant differential pair traces of each interface. The etch length of the differential pair groups do not need to match (that is, the length of the transmit pair does not need to match the length of the receive pair). When matching the intrapair length of the high-speed signals, add serpentine routing to match the lengths as close to the mismatched ends as possible. See [Figure 5](#) for more details.

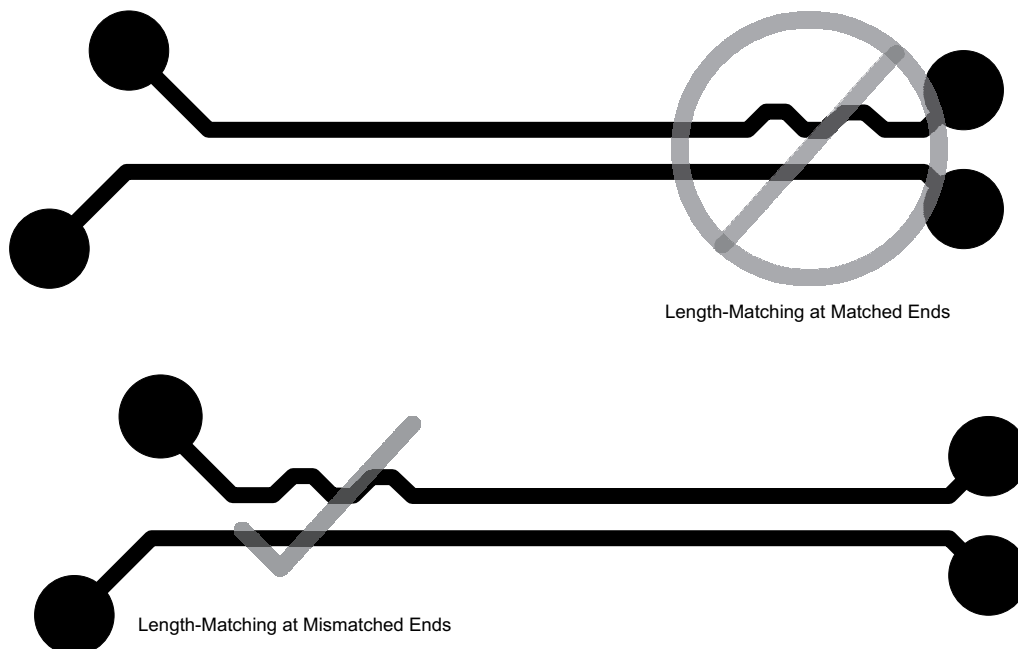


Figure 5. Length Matching

2.4 High-Speed Signal Reference Planes

High-speed signals should be routed over a solid GND reference plane and not across a plane split or a void in the reference plane unless absolutely necessary. TI does not recommend high-speed signal references to power planes.

Routing across a plane split or a void in the reference plane forces return high-frequency current to flow around the split or void. This can result in the following conditions:

- Excess radiated emissions from an unbalanced current flow
- Delays in signal propagation delays due to increased series inductance
- Interference with adjacent signals
- Degraded signal integrity (that is, more jitter and reduced signal amplitude)

For examples of correct and incorrect plane void routing, see [Figure 6](#) and [Figure 7](#).

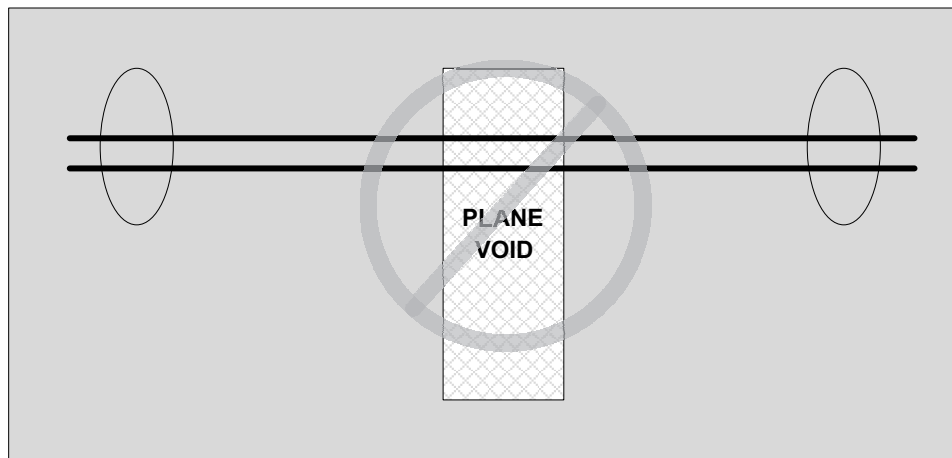


Figure 6. Incorrect Plane Void Routing

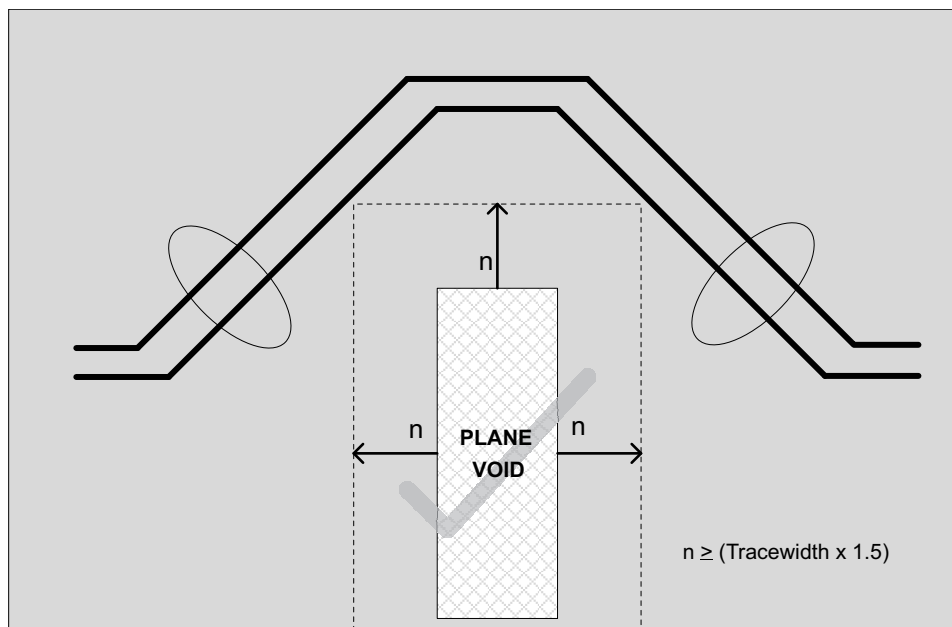


Figure 7. Correct Plane Void Routing

If routing over a plane-split is completely unavoidable, place stitching capacitors across the split to provide a return path for the high-frequency current. These stitching capacitors minimize the current loop area and any impedance discontinuity created by crossing the split. These capacitors should be $1\ \mu\text{F}$ or lower and placed as close as possible to the plane crossing. For examples of incorrect plane-split routing and correct stitch capacitor placement, see [Figure 8](#) and [Figure 9](#).

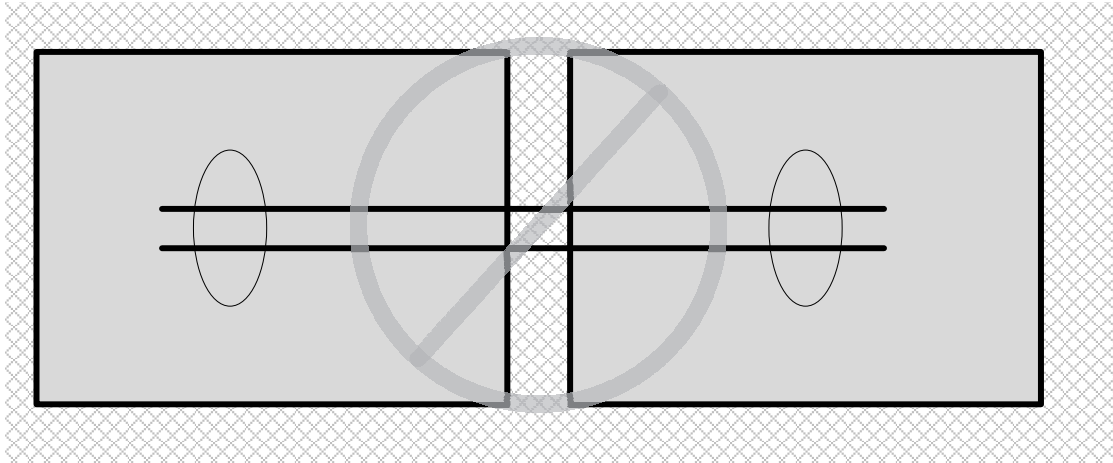


Figure 8. Incorrect Plane-Split Signal Routing

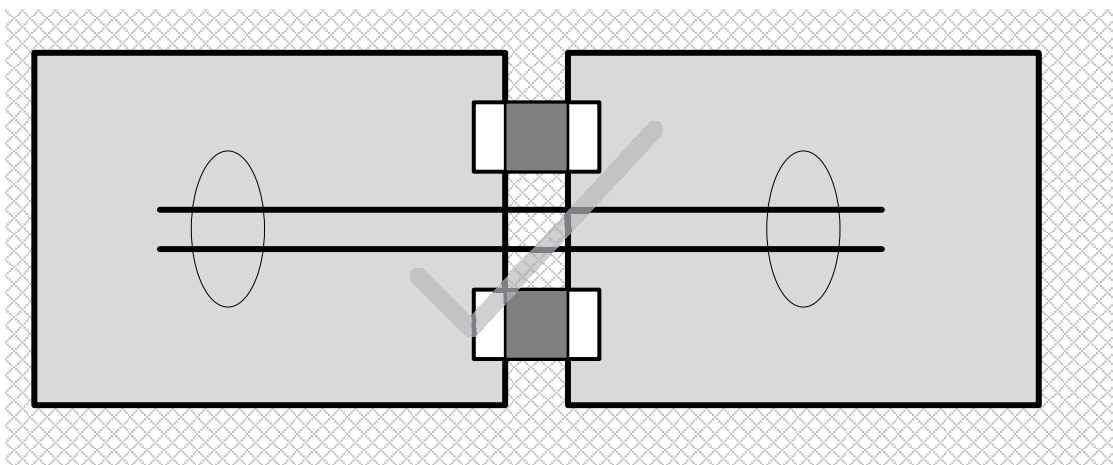


Figure 9. Stitching Capacitor Placement

When planning a PCB stackup, ensure that planes that do not reference each other are not overlapped because this produces unwanted capacitance between the overlapping areas. To see an example of how this capacitance could pass RF emissions from one plane to the other, see [Figure 10](#).

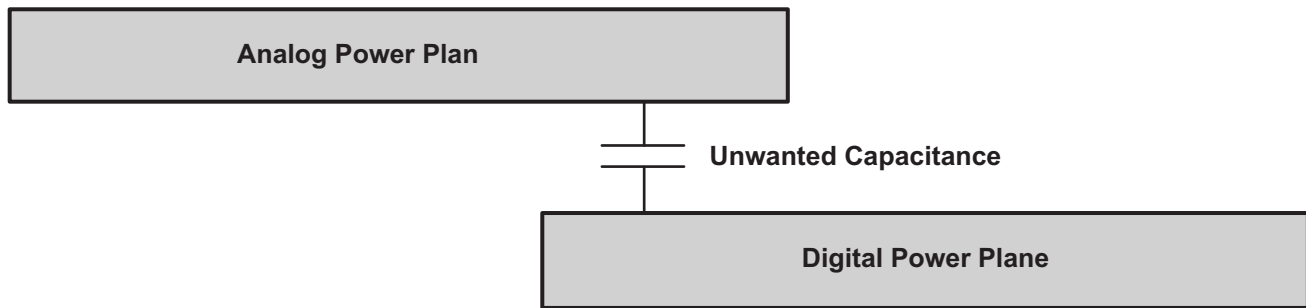


Figure 10. Overlapped Planes

The entirety of any high-speed signal trace should maintain the same GND reference from origination to termination. If unable to maintain the same GND reference, via-stitch both GND planes together to ensure continuous grounding and uniform impedance. Place these stitching vias symmetrically within 200 mils (center-to-center, closer is better) of the signal transition vias. For an example of stitching vias, see [Figure 11](#).

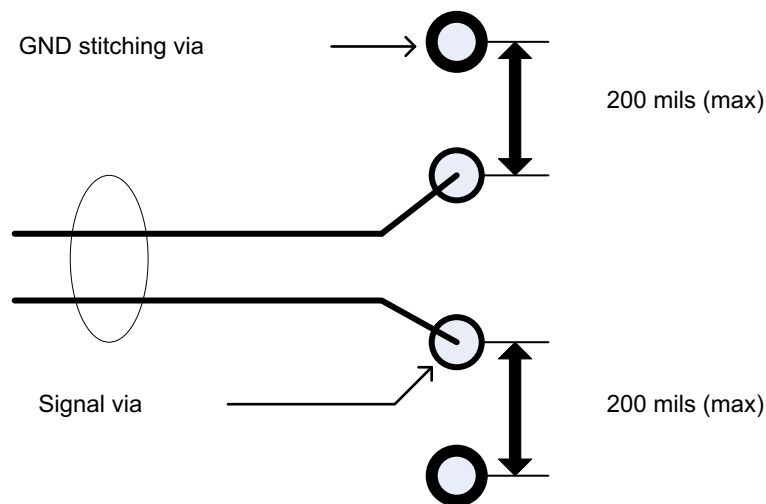


Figure 11. Stitching Vias

3 High-Speed Differential Signal Routing

3.1 Differential Signal Spacing

To minimize crosstalk in high-speed interface implementations, the spacing between the signal pairs must be a minimum of 5 times the width of the trace. This spacing is referred to as the 5W rule. A PCB design with a calculated trace width of 6 mils requires a minimum of 30 mils spacing between high-speed differential pairs. Also, maintain a minimum keep-out area of 30 mils to any other signal throughout the length of the trace. Where the high-speed differential pairs about a clock or a periodic signal, increase this keep-out to a minimum of 50 mils to ensure proper isolation. For examples of high-speed differential signal spacing, see [Figure 12](#) and [Figure 13](#).

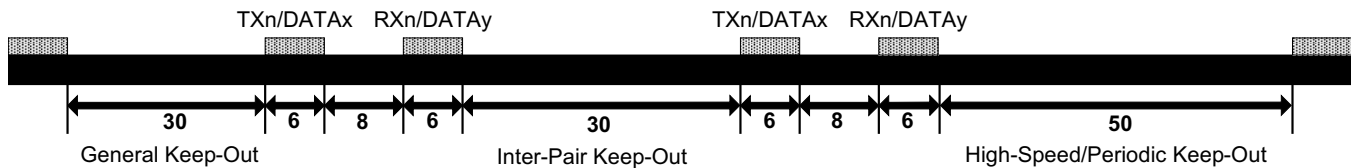


Figure 12. USB3/SATA/PCIe/HDMI/SGMII Differential Signal Spacing (mils)

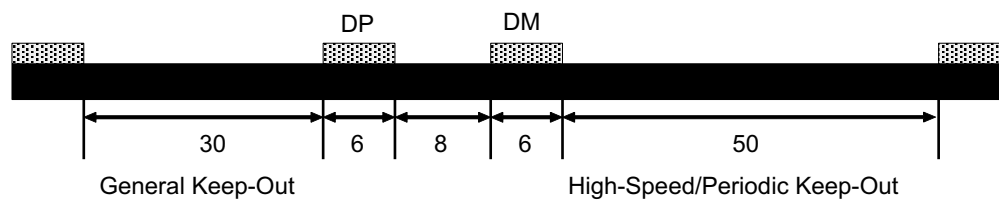


Figure 13. USB2 Differential Signal Spacing (mils)

3.2 High-Speed Differential Signal Rules

- Do not place probe or test points on any high-speed differential signal.
- Do not route high-speed traces under or near crystals, oscillators, clock signal generators, switching power regulators, mounting holes, magnetic devices, or ICs that use or duplicate clock signals.
- After BGA breakout, keep high-speed differential signals clear of the SoC because high current transients produced during internal state transitions can be difficult to filter out.
- When possible, route high-speed differential pair signals on the top or bottom layer of the PCB with an adjacent GND layer. TI does not recommend stripline routing of the high-speed differential signals.
- Ensure that high-speed differential signals are routed ≥ 90 mils from the edge of the reference plane.
- Ensure that high-speed differential signals are routed at least $1.5W$ (calculated trace-width $\times 1.5$) away from voids in the reference plane. This rule does not apply where SMD pads on high-speed differential signals are voided.
- Maintain constant trace width after the SoC BGA escape to avoid impedance mismatches in the transmission lines.
- Maximize differential pair-to-pair spacing when possible.

3.3 Symmetry in the Differential Pairs

Route all high-speed differential pairs together symmetrically and parallel to each other. Deviating from this requirement occurs naturally during package escape and when routing to connector pins. These deviations must be as short as possible and package break-out must occur within 0.25 inches of the package.

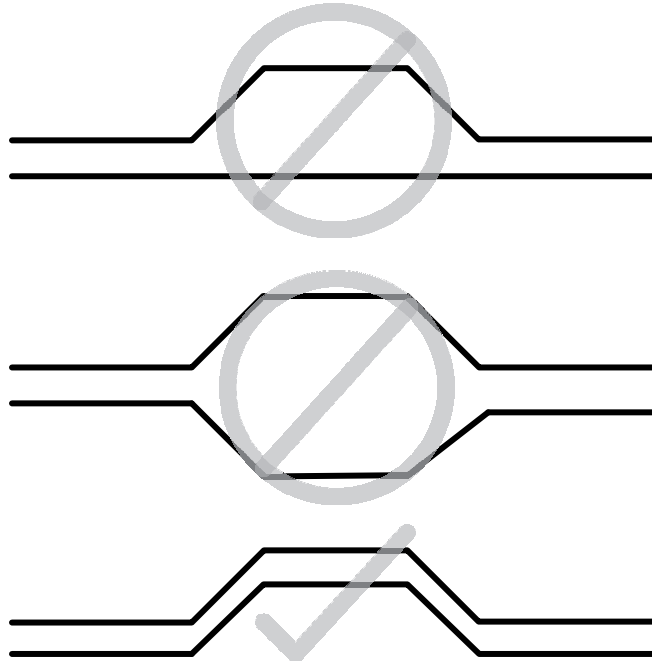


Figure 14. Differential Pair Symmetry

3.4 Crosstalk Between the Differential Signal Pairs

In devices that include multiple high-speed interfaces, avoiding crosstalk between these interfaces is important. To avoid crosstalk, ensure that each differential pair is not routed within 30 mils of another differential pair after package escape and before connector termination.

3.5 Connectors and Receptacles

When implementing a through-hole receptacle (like a USB Standard-A), TI recommends making high-speed differential signal connections to the receptacle on the bottom layer of the PCB. Making these connections on the bottom layer of the PCB prevents the through-hole pin from acting as a stub in the transmission path. For surface-mount receptacles such as USB Micro-B and Micro-AB, make high-speed differential signal connections on the top layer. Making these connections on the top layer eliminates the need for vias in the transmission path. For examples of USB through-hole receptacle connections, see [Figure 15](#).

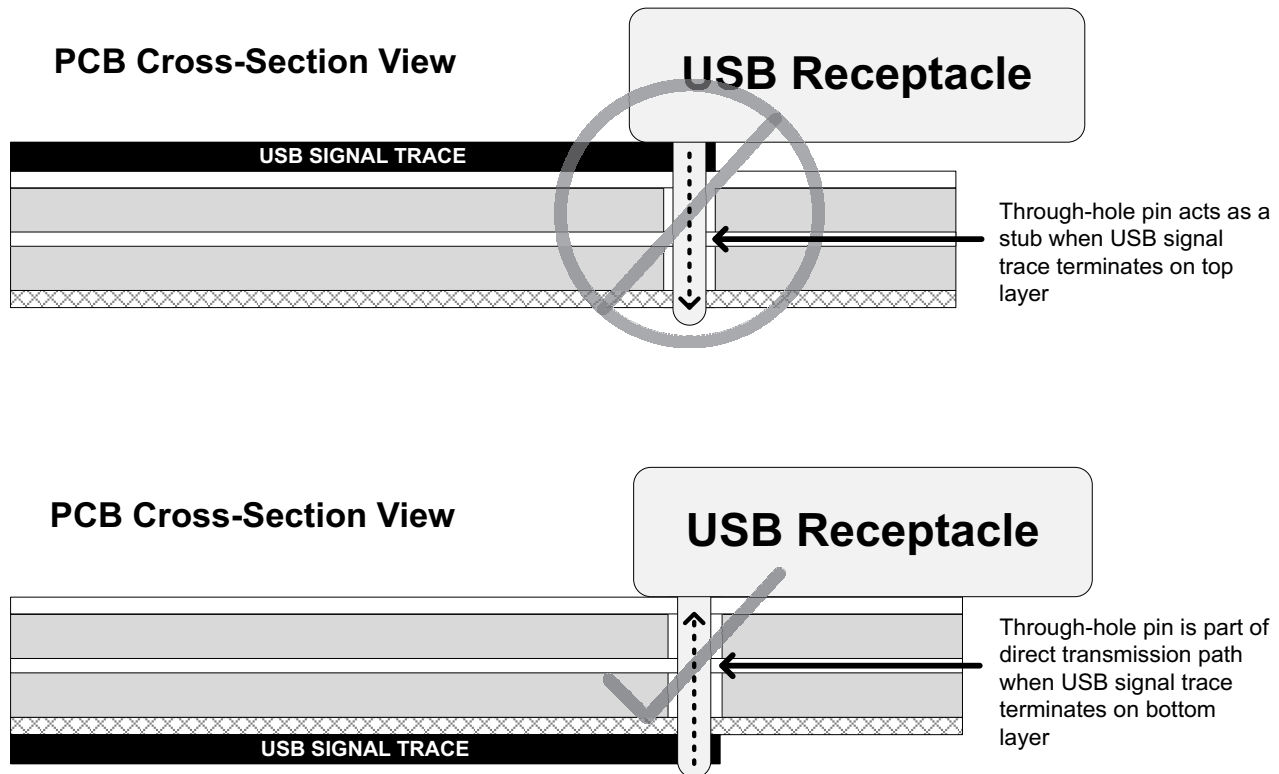


Figure 15. USB Through-Hole Receptacle Connection

3.6 Via Discontinuity Mitigation

A via presents a short section of change in geometry to a trace and can appear as a capacitive and/or an inductive discontinuity. These discontinuities result in reflections and some degradation of a signal as it travels through the via. Reduce the overall via stub length to minimize the negative impacts of vias (and associated via stubs).

Because longer via stubs resonate at lower frequencies and increase insertion loss, keep these stubs as short as possible. In most cases, the stub portion of the via present significantly more signal degradation than the signal portion of the via. TI recommends keeping via stubs to less than 15 mils. Longer stubs must be back-drilled.

For examples of short and long via lengths, see [Figure 16](#) and [Figure 17](#).

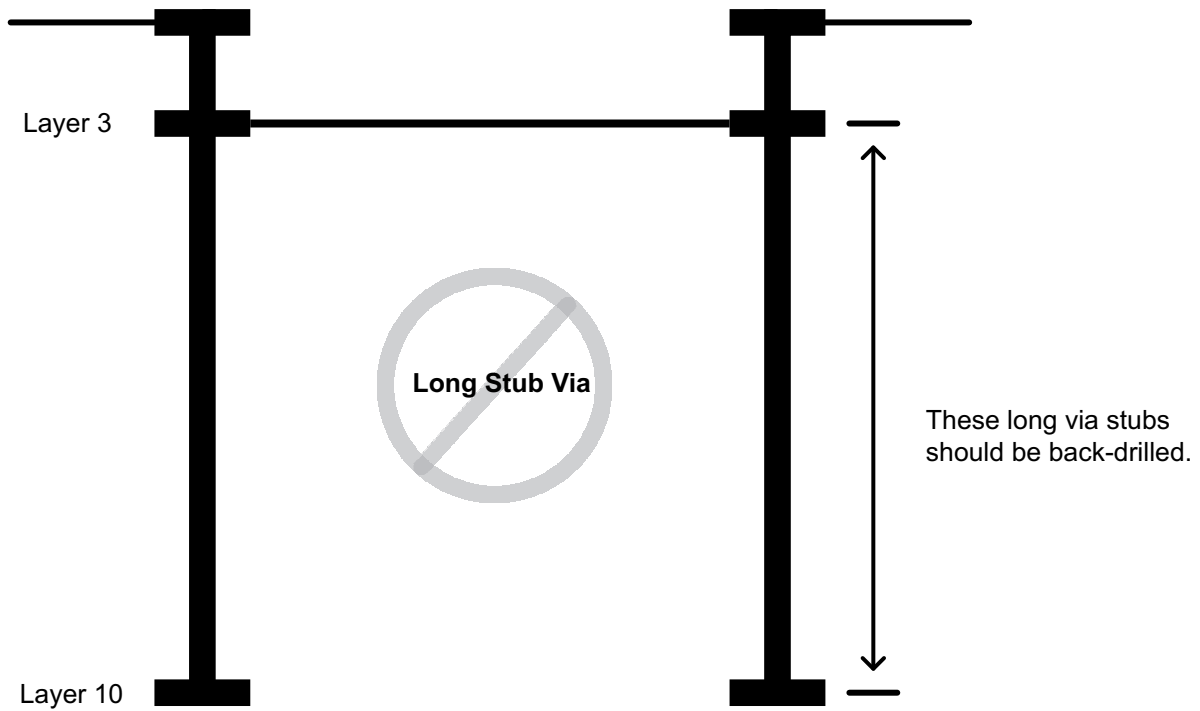


Figure 16. Via Length (Long Stub)

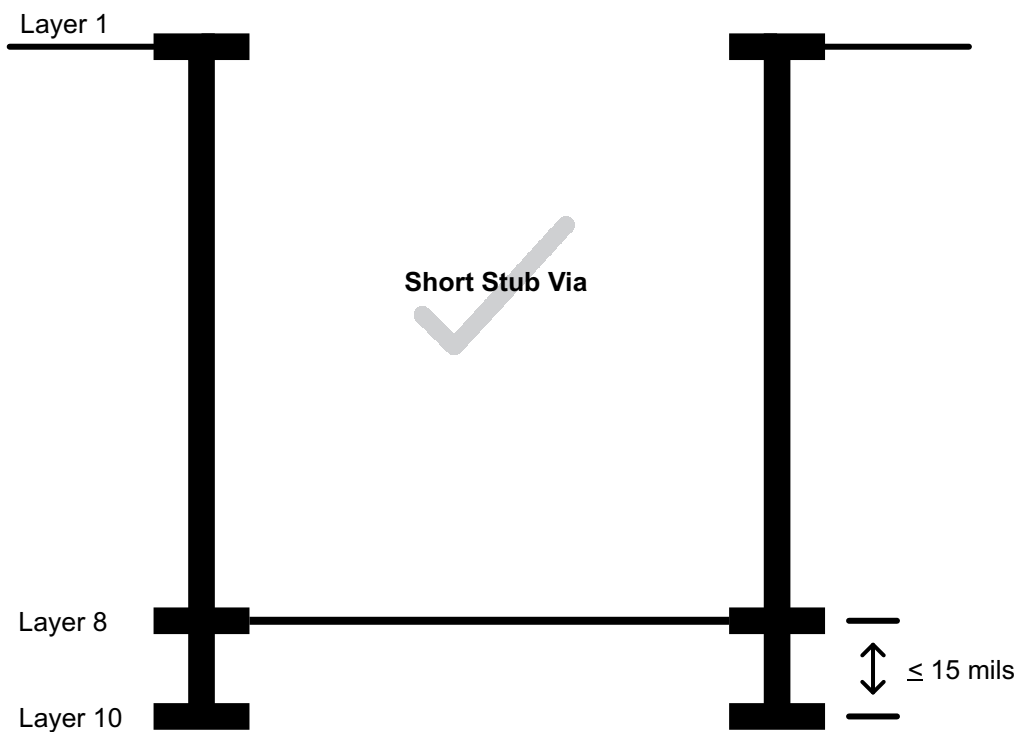


Figure 17. Via Length (Short Stub)

3.7 Back-Drill Stubs

Back-drilling is a PCB manufacturing process in which the undesired conductive plating in the stub section of a via is removed. To back-drill, use a drill bit slightly larger in diameter than the drill bit used to create the original via hole. When via transitions result in stubs longer than 15 mils, back-drill the resulting stubs to reduce insertion losses and to ensure that they do not resonate.

3.8 Increase Via Anti-Pad Diameter

Increasing the via anti-pad diameter reduces the capacitive effects of the via and the overall insertion loss. Ensure that anti-pad diameter for vias on any high-speed signal are as large as possible (30 mils provides significant benefits without imposing undue implementation hardship). The copper clearance, indicated by this anti-pad, must be met on all layers where the via exists, including both routing layer and plane layers. The traces connecting to the via barrel contain the only copper allowed in this area; non-functional or unconnected via pads are not permitted. For an example of a via anti-pad diameter, see [Figure 18](#).

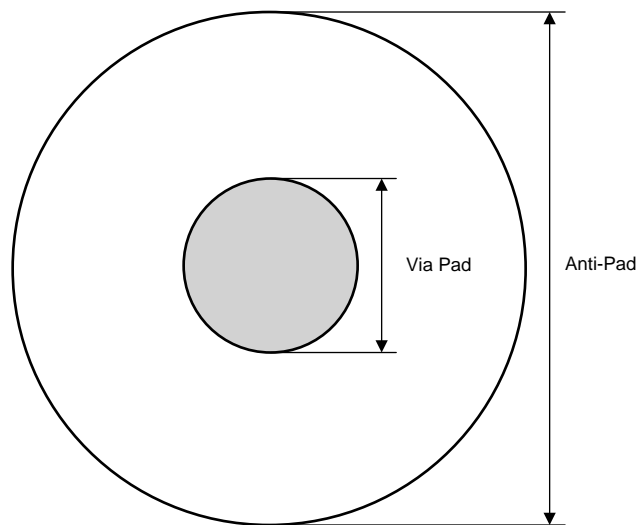


Figure 18. Anti-Pad Diameter

3.9 Equalize Via Count

If using vias is necessary on a high-speed differential signal trace, ensure that the via count on each member of the differential pair is equal and that the vias are as equally spaced as possible. TI recommends placing vias as close as possible to the SoC.

3.10 Surface-Mount Device Pad Discontinuity Mitigation

Avoid including surface-mount devices (SMDs) on high-speed signal traces because these devices introduce discontinuities that can negatively affect signal quality. When SMDs are required on the signal traces (for example, the USB SuperSpeed transmit AC coupling capacitors) the maximum permitted component size is 0603. TI strongly recommends using 0402 or smaller. Place these components symmetrically during the layout process to ensure optimum signal quality and to minimize reflection. For examples of correct and incorrect AC coupling capacitor placement, see [Figure 19](#).

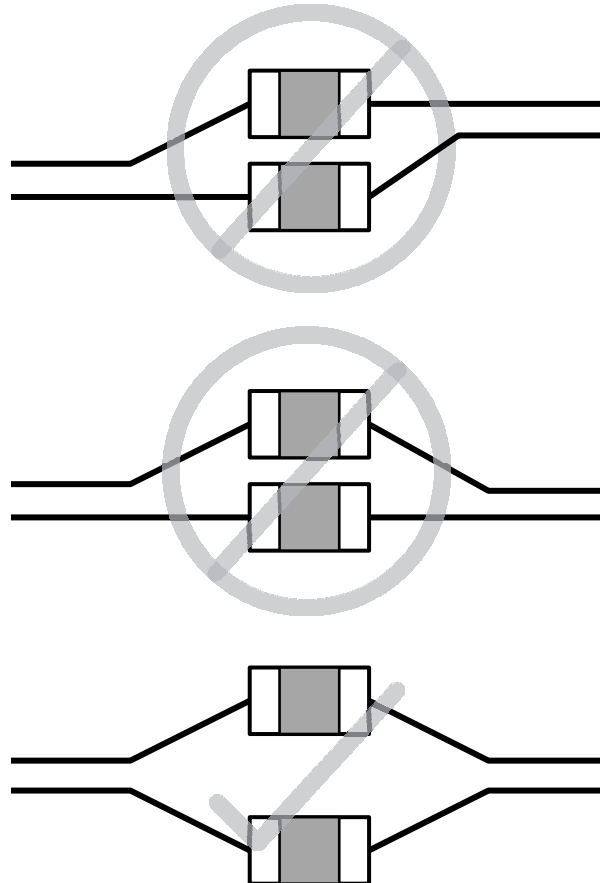


Figure 19. AC-Coupling Placement

To minimize the discontinuities associated with the placement of these components on the differential signal traces, TI recommends voiding the SMD mounting pads of the reference plane by 100%. This void should be at least two PCB layers deep. For an example of a reference plane voiding of surface mount devices, see [Figure 20](#).

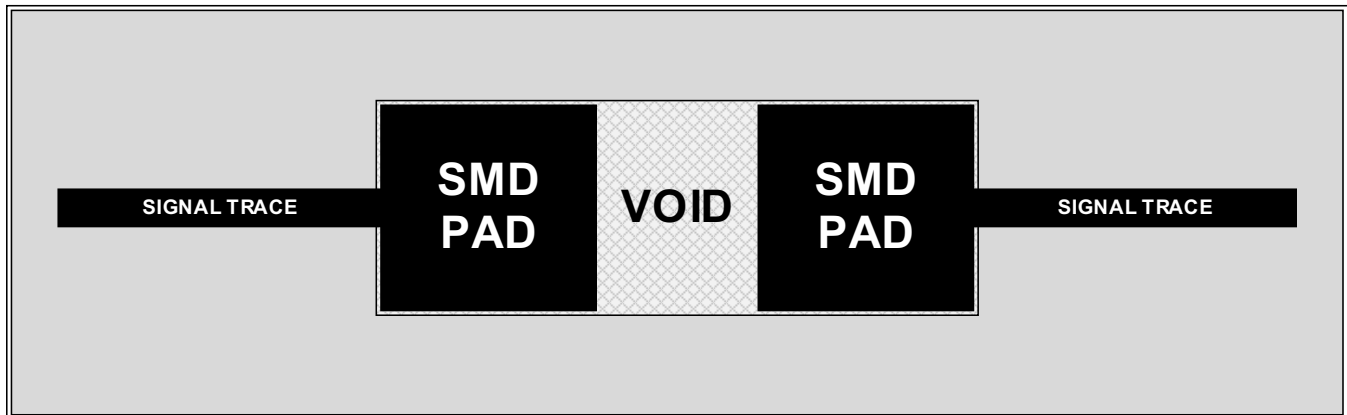


Figure 20. Reference Plane Voiding of Surface-Mount Devices

3.11 Signal Bending

Avoid the introduction of bends into high-speed differential signals. When bending is required, maintain a bend angle greater than 135° to ensure that the bend is as loose as a possible. For an example of high-speed signal bending rules, see [Figure 21](#).

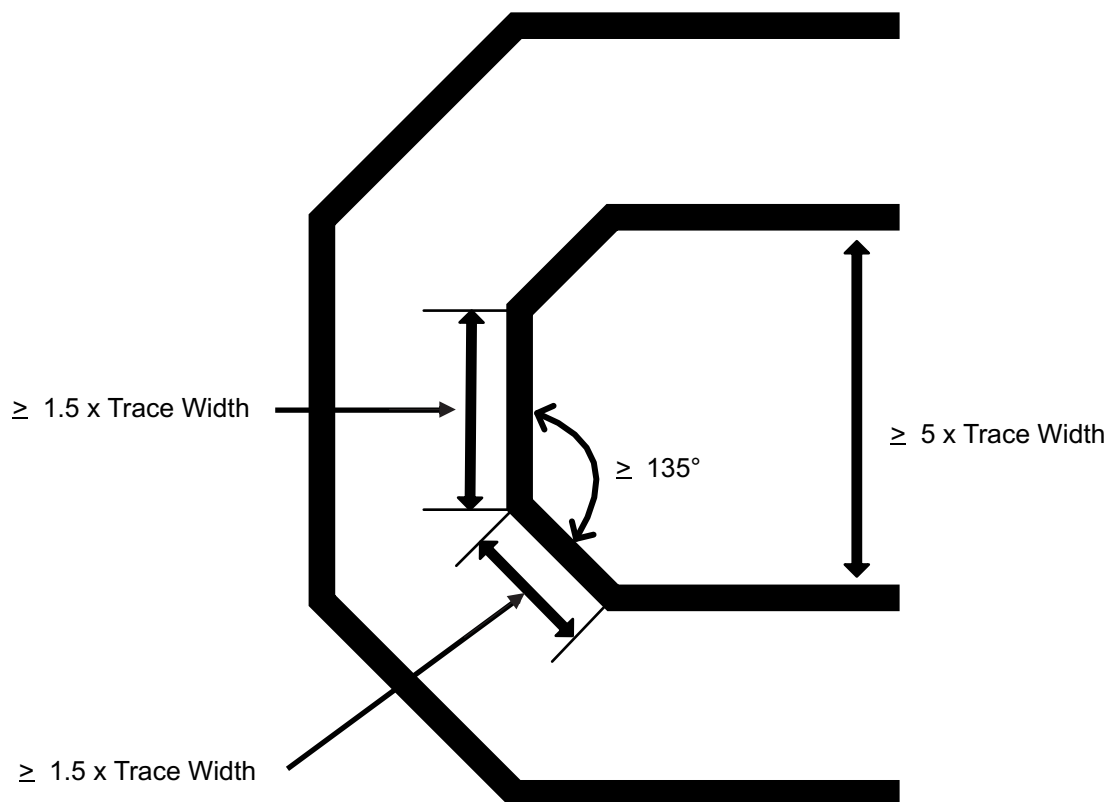


Figure 21. Signal Bending Rules

3.12 Suggested PCB Stackups

TI recommends a PCB of at least six layers. [Table 2](#) provides example PCB stackups.

Table 2. Example PCB Stackups

6-LAYER	8-LAYER	10-LAYER
SIGNAL	SIGNAL	SIGNAL
GROUND	GROUND	GROUND
SIGNAL ⁽¹⁾	SIGNAL	SIGNAL ⁽¹⁾
SIGNAL ⁽¹⁾	SIGNAL	SIGNAL ⁽¹⁾
POWER/GROUND ⁽²⁾	POWER/GROUND ⁽²⁾	POWER
SIGNAL	SIGNAL	POWER/GROUND ⁽²⁾
	GROUND	SIGNAL ⁽¹⁾
	SIGNAL	SIGNAL ⁽¹⁾
		GROUND
		SIGNAL

⁽¹⁾ Route directly adjacent signal layers at a 90° offset to each other

⁽²⁾ Plane may be split depending on specific board considerations. Ensure that traces on adjacent planes do not cross splits.

3.13 ESD/EMI Considerations

When choosing ESD/EMI components, TI recommends selecting devices that permit flow-through routing of the USB differential signal pair because they provide the cleanest routing. For example, the TI TPD4EUSB30 can be combined with the TI TPD2EUSB30 to provide flow-through ESD protection for both USB2 and USB3 differential signals without the need for bends in the signal pairs. For an example of flow-through routing, see [Figure 22](#).

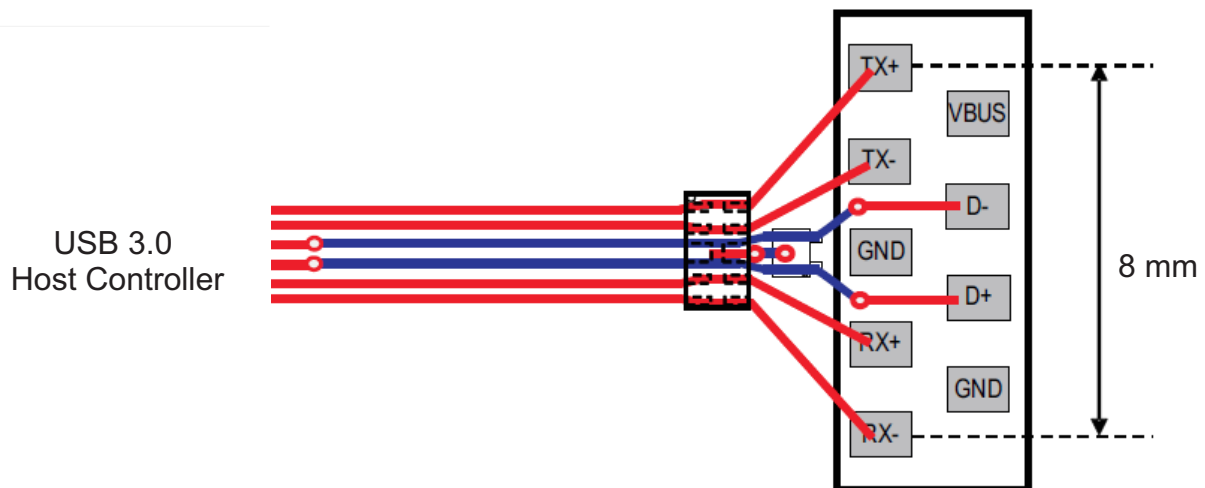


Figure 22. Flow-Through Routing

3.14 ESD/EMI Layout Rules

- Place ESD and EMI protection devices as close as possible to the connector.
- Keep any unprotected traces away from protected traces to minimize EMI coupling.
- Incorporate 60% voids under the ESD/EMI component signal pads to reduce losses.
- Use 0402 0- Ω resistors for common-mode filter (CMF) no-stuff options because larger components will typically introduce more loss than the CMF itself.
- Place any required signal pair AC coupling capacitors on the protected side of the CMF and as close as possible to the CMF.
- If vias are needed to transition to the CMF layer, ensure that the vias are as close as possible to the CMF.
- Keep the overall routing of AC coupling capacitors + CMF + ESD protection as short and as close as possible to the connector.

4 References

- Hall, Stephen H., and Garrett W. Hall. *High Speed Digital System Design: A Handbook of Interconnect Theory and Design Practices*. New York: Wiley, 2000.
- Johnson, Howard W., and Martin Graham. *High-speed Signal Propagation: Advanced Black Magic*. Upper Saddle River, NJ: Prentice Hall/PTR, 2003.
- Hall, Stephen H., and Howard L. Heck. *Advanced Signal Integrity for High-speed Digital Designs*. Hoboken, N.J.: Wiley, 2009.
- Heck, Howard. *USB 3.1 Electrical Design*. USB 3.1 Developer Days, 2014.
- Stephen C. Thierauf. *High-Speed Circuit Board Signal Integrity*. ISBN-13: 978-1580531313.

Device Layout Parameters

Table 3. AM335x/AM437x/AMIC1xx

Parameter	MIN	TYP	MAX	Unit
USB2.0 Tracelength (total)		4000	12000	Mils
Skew within any USB2.0 differential pair			50	Mils
USB2.0 DP/DM pair differential impedance	81	90	99	Ω
USB2.0 DP/DM pair common-mode impedance	40.5	45	49.5	Ω
Number of stubs allowed on any USB differential pair trace (total)			0	Stubs
Number of vias allowed on each USB2.0 differential trace (total)			4	Vias
Number of test points permitted on any USB differential pair trace (total)			0	Test Points
USB differential pair to clock or high-speed periodic signal trace spacing	50			Mils
USB differential pair to any other signal trace spacing	30			Mils

Table 4. AM57xx/DRA7xx

Parameter	MIN	TYP	MAX	Unit
USB3.0 (SuperSpeed) Tracelength (Total)			3500	Mils
Serial-ATA (SATA) Tracelength (Total)			3500	Mils
PCI-Express (PCIe) Tracelength (Total)			4700	Mils
SuperSpeed Insertion Loss at 2.5GHz (device to connector)	Refer to USB Specification			dB
USB2.0 Tracelength (Total)		4000	12000	Mils
HDMI Tracelength (Total)			4000	Mils
Skew within any USB3/SATA/PCIe/HDMI differential pair			5	Mils
Skew between all PCIe RX pairs (Total)			550	Mils
Skew between all PCIe TX pairs (Total)			550	Mils
Skew within any USB2.0 differential pair			50	Mils
USB2.0 DP or DM pair differential impedance	81	90	99	Ω
USB2.0 DP or DM pair single-ended impedance	40.5	45	49.5	Ω
SuperSpeed SSRX or SSTX pair differential impedance	83.7	90	96.3	Ω
PCI-Express RX or TX pair differential impedance	90	100	110	Ω
PCI-Express RX or TX trace single-ended impedance	51	60	69	Ω
Serial-ATA RX or TX pair differential impedance	85	100	115	Ω
HDMI TMDS differential impedance	90	100	110	Ω
Number of stubs allowed on any differential pair trace (Total)			0	Stubs
Number of vias allowed on any USB3 differential trace (Total)			2	Vias
Number of vias allowed on any PCIe/SATA differential trace (Total)			0	Vias
Number of vias allowed on each USB2.0 differential trace (Total)			4	Vias
Number of vias allowed on each TMDS differential trace (HDMI)(Total)			0	Vias
Number of test points permitted on any differential pair trace (Total)			0	Test Points
Differential pair to clock or high-speed periodic signal trace spacing	50			Mils
Differential pair to any other signal trace spacing	30			Mils

Table 5. KeyStone II - K2K, K2H, K2L, and K2E Devices

Parameter	MIN	TYP	MAX	UNIT
USB3.0 (SuperSpeed) Tracelength (Total)			5500	Mils
Serial-ATA (SATA) Tracelength (Total)			5500	Mils
PCI-Express (PCIe) Tracelength (Total)			5500	Mils
SuperSpeed Insertion Loss at 2.5 GHz (device to connector)	Refer to USB Specification			dB
USB2.0 Tracelength (Total)		4000	12000	Mils
Skew within any USB3/SATA/PCIe differential pair			5	Mils
Skew between all PCIe RX pairs (Total)			550	Mils
Skew between all PCIe TX pairs (Total)			550	Mils
Skew within any USB2.0 differential pair			50	Mils
USB2.0 DP or DM pair differential impedance	81	90	99	Ω
USB2.0 DP or DM pair common mode impedance	40.5	45	49.5	Ω
SuperSpeed SSRX or SSTX pair differential impedance	83.7	90	96.3	Ω
PCI-Express RX or TX pair differential impedance	90	100	110	Ω
PCI-Express RX or TX trace single-ended impedance	51	60	69	Ω
Serial-ATA RX or TX pair differential impedance	85	100	115	Ω
Number of stubs allowed on any differential pair trace (Total)			0	Stubs
Number of vias allowed on USB3 differential trace (Total)			2	Vias
Number of vias allowed on any PCIe/SATA differential trace (Total)			0	Vias
Number of vias allowed on each USB2.0 differential trace (Total)			4	Vias
Number of test points permitted on any differential pair trace (Total)			0	Test Points
Differential pair to clock or high-speed periodic signal trace spacing	50			Mils
Differential pair to any other signal trace spacing	30			Mils

Table 6. KeyStone II - K2G (66AK2G0x/66AK2G1x) Devices

Parameter	MIN	TYP	MAX	Unit
PCI-Express (PCIe) Tracelength (Total)			5500	Mils
USB2.0 Tracelength (Total)		4000	12000	Mils
Skew within any PCIe differential pair			5	Mils
Skew between all PCIe RX pairs (Total)			550	Mils
Skew between all PCIe TX pairs (Total)			550	Mils
Skew within any USB2.0 differential pair			50	Mils
USB2.0 DP or DM pair differential impedance	81	90	99	Ω
USB2.0 DP or DM pair single-ended impedance	40.5	45	49.5	Ω
PCI-Express RX or TX pair differential impedance	90	100	110	Ω
PCI-Express RX or TX trace single-ended impedance	51	60	69	Ω
Number of stubs allowed on any differential pair trace (Total)			0	Stubs
Number of vias allowed on any PCIe differential trace (Total)			0	Vias
Number of vias allowed on each USB2.0 differential trace (Total)			4	Vias
Number of test points permitted on any differential pair trace (Total)			0	Test Points
Differential pair to clock or high-speed periodic signal trace spacing	50			Mils
Differential pair to any other signal trace spacing	30			Mils

Table 7. AM6xxx/DRA80xM ⁽¹⁾

Parameter	MIN	TYP	MAX	Unit
USB3.1 GEN1 Tracelength (Total)			4000	Mils
PCI-Express (PCIe) Tracelength (Total)			4000	Mils
Serial Gigabit Media Independent Interface (SGMII) Tracelength (Total)			7500	Mils
USB2.0 Tracelength (Total)		4000	12000	Mils
SuperSpeed Insertion Loss at 2.5GHz (device to connector)	Refer to USB Specification			dB
Skew within any USB3/PCIe/SGMII differential pair			5	Mils
Skew between all PCIe RX pairs (Total)			6	ns
Skew between all PCIe TX pairs (Total)			1.5	ns
Skew within any USB2.0 differential pair			50	Mils
USB2.0 DP or DM pair differential impedance	81	90	99	Ω
SuperSpeed SSRX or SSTX pair differential impedance	90.25	95	99.75	Ω
PCI-Express RX or TX pair differential impedance	90.25	95	99.75	Ω
SGMII RX/TX/RXCLK/TXCLK pair differential impedance	90.25	95	99.75	Ω
Number of stubs allowed on any differential pair trace (Total)			0	Stubs
Number of vias allowed on any USB3/PCIe/SGMII differential trace (Total)			2	Vias
Number of vias allowed on each USB2.0 differential trace (Total)			4	Vias
Number of test points permitted on any differential pair trace (Total)			0	Test Points
Differential pair to clock or high-speed periodic signal trace spacing	50			Mils
Differential pair to any other signal trace spacing	30			Mils

(1) Data provided in this table is advance information and subject to change without notice. For more information, see the device-specific data sheet.

Revision History

Changes from G Revision (July 2017) to H Revision	Page
• Update was made in Section 1.2	3
• Added new Table 7	21

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale (www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2018, Texas Instruments Incorporated