







BQ25713, BQ25713B JAJSFQ9C - JUNE 2018 - REVISED MAY 2023

# BQ25713、BQ25713B I<sup>2</sup>C Narrow VDC システム電力監視およびプロセッサ・ホ ット監視付き、昇降圧バッテリ充電コントローラ

# 1 特長

TEXAS

INSTRUMENTS

- BQ25703A とピン互換およびソフトウェア互換
- 1S~4S バッテリを広範囲の入力電源から充電
  - 3.5V~24Vの入力動作電圧範囲
  - USB2.0, USB 3.0, USB 3.1 (Type C), USB Power Delivery (USB-PD) 入力電流設定に対応
  - 降圧、昇降圧、および昇圧動作間のシームレスな 移行
  - ソース過負荷に対する入力電流および電圧のレギ ュレーション (IDPM および VDPM)
- 電力 / 電流モニタによる CPU スロットル処理
  - 包括的な PROCHOT プロファイル、IMVP8/ IMVP9 準拠
  - 入力およびバッテリ電流モニタ
  - システム電力モニタ、IMVP8/IMVP9 準拠
- Narrow VDC (NVDC) パワー・パス・マネージメント機 ٠ 能
  - バッテリなしまたは消耗したバッテリでの即時オン
  - アダプタの過負荷時にバッテリでシステムを補完
  - 補完モードでのバッテリ MOSFET の理想ダイオー ド動作
- バッテリから USB ポートへ電源供給 (USB OTG)
  - 分解能 8mV の 3V~ 20.8V OTG
  - 一 分解能 50mA の最大 6.4A の出力電流制限
- システムの電力効率向上とバッテリの高速充電に向け た、テキサス・インスツルメンツによる特許申請中のパ ス・スルー・モード (PTM)
- バッテリのみをシステム電源とする場合は、Vmin アク ティブ・プロテクション (VAP) モードにより、システムの ピーク電力スパイク時に入力コンデンサでバッテリを補 完
- 入力電流最適化 (ICO) により最大入力電力を抽出
- 2.2µH または 1.0µH インダクタの 800kHz または 1.2MHz にプログラム可能なスイッチング周波数
- ホスト制御インターフェイスによる柔軟なシステム構成
  - I<sup>2</sup>C ポートにより、最適なシステム性能とステータス・ レポートを実現
  - EC 制御なしでハードウェア・ピンにより入力電流制 限を設定
- 内蔵された ADC により電圧、電流、電力を監視
- 高精度のレギュレーションと監視
  - ±0.5% の充電電圧レギュレーション
  - ±2%の入力/充電電流レギュレーション
  - ±2%の入力/充電電流監視
  - ±4%の電力監視
- 安全

- サーマル・シャットダウン
- 入力、システム、バッテリの過電圧保護
- 入力、MOSFET、インダクタの過電流保護
- 安全性関連の認定
  - IEC 62368-1 CB 認定
- 小さいバッテリ静止電流
- パッケージ:32 ピン 4 × 4 WQFN

# 2 アプリケーション

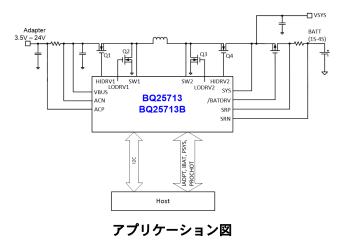
- ドローン、Bluetooth スピーカー、IP カメラ、脱着可能 PC、タブレット PC、パワー・バンク
- 産業用および医療用機器
- 充電式バッテリ搭載の携帯機器

# 3 概要

このデバイスは同期整流 NVDC 昇降圧バッテリ充電コン トローラであり、スペースに制約がある 1S~4S バッテリ充 電機器に適した、部品数の少ない高効率のソリューション です。

製品情報						
部品番号	パッケージ <sup>(1)</sup>	本体サイズ (公称)				
BQ25713、BQ25713B	WQFN (32)	4.00mm × 4.00mm				

(1) 利用可能なすべてのパッケージについては、このデータシートの 末尾にある注文情報を参照してください。



英語版のTI製品についての情報を翻訳したこの資料は、製品の概要を確認する目的で便宜的に提供しているものです。該当する正式な英語版の最新情報は、 🐼 www.ti.com で閲覧でき、その内容が常に優先されます。 TI では翻訳の正確性および妥当性につきましては一切保証いたしません。 実際の設計などの前には、必ず 最新版の英語版をご参照くださいますようお願いいたします。





# **Table of Contents**

1	特長	1
2	アプリケーション	.1
3	概要	1
4	Revision History	2
5	概要 (続き)	.4
6	Device Comparison Table	.5
	Pin Configuration and Functions	
8	Specifications	9
	8.1 Absolute Maximum Ratings	9
	8.2 ESD Ratings	9
	8.3 Recommended Operating Conditions	
	8.4 Thermal Information1	0
	8.5 Electrical Characteristics1	
	8.6 Timing Requirements1	
	8.7 Typical Characteristics	20
9	Detailed Description	22
	9.1 Overview	22
	9.2 Functional Block Diagram2	
	9.3 Feature Description	
	9.4 Device Functional Modes	31

9.5 Programming	<mark>32</mark>
9.6 Register Map	
10 Application and Implementation	
10.1 Application Information	
10.2 Typical Application	73
11 Power Supply Recommendations	
12 Layout	82
12.1 Layout Guidelines	82
12.2 Layout Example	<mark>83</mark>
13 Device and Documentation Support	<mark>84</mark>
13.1 Device Support	<mark>84</mark>
13.2 Documentation Support	84
13.3ドキュメントの更新通知を受け取る方法	84
13.4 サポート・リソース	<mark>84</mark>
13.5 Trademarks	84
13.6 静電気放電に関する注意事項	84
13.7 用語集	84
14 Mechanical, Packaging, and Orderable	
Information	<mark>85</mark>

# **4 Revision History**

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

С	hanges from Revision B (February 2021) to Revision C (May 2023)	Page
•	Changed IVBUS in 🗵 9-1	27
	Changed EN_PROCHOT_LPWR 01b and 10b in ChargeOption1 Register	
•	Changed ICRIT_DEG 01b, 10b, and 11b and INOM_DEG 0b and 1b in ProchotOption0 Register	46
	Changed IDCHG_DEG and PROCHOT_PROFILE_VDPM in ProchotOption1 Register	
	Changed PROCHOT_WIDTH 11b in ProchotStatus Register	
	Updated Typical Application Diagram	

С	hanges from Revision A (July 2018) to Revision B (February 2021)	Page
•	安全関連認証を追加:「特長」に IEC 62368-1 CB 認証を追加	1
•	Changed units of measure for several parameters in Electrical Characteristics	10
•	Changed in Timing Requirements	
•	Added bullet 2 in Power-Up from DC Source	24
•	Changed 3.25A in Input Voltage and Current Limit Setup	25
•	Changed in USB On-The-Go (OTG)	
•	Added in System Short Hiccup Mode	31
•	Changed in I <sup>2</sup> C Serial Interface	
•	Changed in ChargeOption0 Register	
•	Changed in ChargeOption2 Register	42
•	Changed in ProchotOption0 Register	
•	Changed in ProchotStatus Register	
•	Changed in Input Current Registers	61
•	Changed in IIN_DPM Register With 10-mΩ Sense Resistor	63
•	Changed in ADCIINCMPIN Register	70
•	Updated Typical Application Diagram	
•	Updated ACP-ACN Input Filter Diagram	
•	Updated Input Capacitor	



•

#### BQ25713, BQ25713B JAJSFQ9C – JUNE 2018 – REVISED MAY 2023

С	hanges from Revision * (June 2018) to Revision A (July 2018)	Page
	Added detailed layout reference in Layout Example	
•	Changed in Layout Guidelines	82
•	Updated Output Capacitor	75



# 5 概要 (続き)

NVDC構成により、システムをバッテリの電圧にレギュレートしながら、システムの最低電圧を下回らないように維持できます。バッテリが完全に放電した場合や取り外された場合でも、システムは動作を続けられます。負荷電力が入力電源の定格を超過すると、バッテリは補完モードに移行し、システムの故障を防止します。

BQ25713/BQ25713B は、USB アダプタ、高電圧 USB PD ソース、従来型のアダプタなど、広範な入力電源からバッテ リを充電します。

電源投入時に、充電器は入力電源およびバッテリの状況に基づいてコンバータを降圧、昇圧、昇降圧型のいずれかの構成に設定します。充電器はホストの制御なしに、降圧、昇圧、昇降圧型の構成間を自動的に遷移します。

入力電源が存在しない場合、BQ25713/BQ25713B は 1~4 セル・バッテリからの USB On-the-Go (OTG) 機能をサポートするため、8mV の分解能で VBUS に 3V~20.8V の可変電圧を出力できます。OTG の出力過渡電圧スルーレートは設定可能であり、USB PD 3.0 PPS 仕様に準拠しています。

バッテリのみをシステム電源とし、USB OTG ポートに外部負荷を接続していない場合、BQ25713/BQ25713B は Vmin アクティブ・プロテクション (VAP)機能をサポートするため、バッテリから VBUS 電圧を充電して、入力デカップリング・コン デンサに蓄電できます。システムのピーク電力スパイク時には、バッテリから大電流が引き出されるため、バッテリからシス テムへのインピーダンスによる電圧降下が大きくなります。入力コンデンサに蓄えられた電力がシステムを補完することに より、システムの電圧が最低値を下回り、システムが故障するのを防止できます。この Vmin アクティブ・プロテクション (VAP) は、SOC の高電力要求周期においてシステムのピーク電力を吸収するように設計されているため、インテルは 1S ~2S バッテリ搭載プラットフォームに強く推奨しています。

BQ25713/BQ25713B はアダプタの電流、バッテリの電流、システムの電力を監視します。柔軟にプログラムされる PROCHOT 出力は、必要に応じてスロットル・バックのため CPU へ直接接続されます。

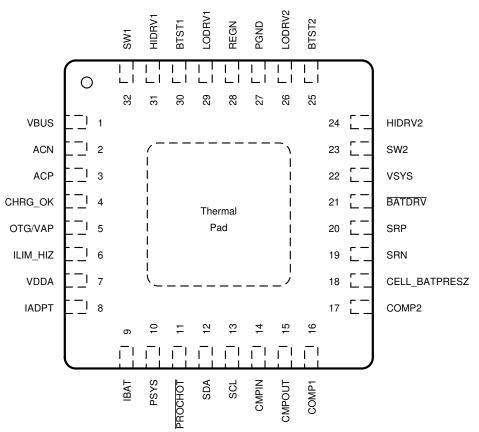


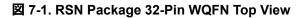
# 6 Device Comparison Table

	BQ25700A	BQ25703A	BQ25708	BQ25710	BQ25718	BQ25713	BQ25713B
Interface	SMBus	I2C	SMBus	SMBus	SMBus	I2C	I2C
Device Address	09h	6Bh	09h	09h	09h	6Bh	6Ah
VAP for IMVP9	No	No	No	Yes	Yes	Yes	Yes
Pass Through Mode	No	No	No	Yes	Yes	Yes	Yes
OTG Mode	Yes	Yes	No	Yes	No	Yes	Yes
OTG Voltage Range	4.48V-20.8V	4.48V-20.8V	N/A	3.0V-20.8V	N/A	3.0V-20.8V	3.0V-20.8V
OTG Voltage Resolution	64mV	64mV	N/A	8mV	N/A	8mV	8mV
Charging Voltage Resolution	16mV	16mV	16mV	8mV	8mV	8mV	8mV



# 7 Pin Configuration and Functions





#### 表 7-1. Pin Functions

PIN NAME NO.		I/O	DESCRIPTION		
ACN 2		PWR	Input current sense resistor negative input. The leakage on ACP and ACN are matched. A R-C low-pass filter is required to be placed between the sense resistor and the ACN pin to suppress the high frequency noise in the input current signal. Refer to セクション 10 for ACP/ACN filter design.		
ACP	3	PWR	Input current sense resistor positive input. The leakage on ACP and ACN are matched. A R-C low-pass filter is required to be placed between the sense resistor and the ACP pin to suppress the high frequency noise in the input current signal. Refer to セクション 10 for ACP/ACN filter design.		
BATDRV	21	0	P-channel battery FET (BATFET) gate driver output. It is shorted to VSYS to turn off the BATFET. It goes 10 V below VSYS to fully turn on BATFET. BATFET is in linear mode to regulate VSYS at minimum system voltage when battery is depleted. BATFET is fully on during fast charge and works as an ideal-diode in supplement mode.		
BTST1	30	PWR	Buck mode high side power MOSFET driver power supply. Connect a 0.047-µF capacitor between SW1 and BTST1. The bootstrap diode between REGN and BTST1 is integrated.		
BTST2	25	PWR	Boost mode high side power MOSFET driver power supply. Connect a 0.047-µF capacitor between SW2 and BTST2. The bootstrap diode between REGN and BTST2 is integrated.		
CELL_BATPRESZ 18		I	Battery cell selection pin for 1–4 cell battery setting. CELL_BATPRESZ pin is biased from VDDA. CELL_BATPRESZ pin also sets SYSOVP thresholds to 5 V for 1-cell, 12 V for 2-cell, and 19.5 V for 3-cell/4-cell. CELL_BATPRESZ pin is pulled below $V_{CELL}$ BATPRESZ FALL to indicate battery removal. The device exits LEARN mode, and disables charge. The charge voltage register REG0x05/04() goes back to default.		



# 表 7-1. Pin Functions (continued)

PIN NAME NO.					
		I/O	DESCRIPTION		
CHRG_OK	4	0	Open drain active high indicator to inform the system good power source is connected to the charger input. Connect to the pullup rail via 10-k $\Omega$ resistor. When VBUS rises above 3.5V or falls below 24.5V, CHRG_OK is HIGH after 50ms deglitch time. When VBUS falls below 3.2 V or rises above 26 V, CHRG_OK is LOW. When any fault occurs, CHRG_OK is asserted LOW.		
CMPIN	14	I	Input of independent comparator. The independent comparator compares the voltage sensed on CMPIN pin with internal reference, and its output is on CMPOUT pin. Internal reference, output polarity and deglitch time is selectable by the I <sup>2</sup> C host. With polarity HIGH (REG0x30[6] = 1), place a resistor between CMPIN and CMPOUT to program hysteresis. With polarity LOW (REG0x30[6] = 0), the internal hysteresis is 100 mV. If the independent comparator is not in use, tie CMPIN to ground.		
CMPOUT	15	0	Open-drain output of independent comparator. Place pullup resistor from CMPOUT to pullup supply rail. Internal reference, output polarity and deglitch time are selectable by the I <sup>2</sup> C host.		
COMP2	17	I	Buck boost converter compensation pin 2. Refer to BQ2571X EVM schematic for COMP2 pin RC network.		
COMP1	16	I	Buck boost converter compensation pin 1. Refer to BQ2571X EVM schematic for COMP1 pin RC network.		
OTG/VAP	5	I	Active HIGH to enable OTG or VAP modes. When REG0x34[5]=1, pulling high OTG/VAP pin and setting REG0x35[4]=1 can enable OTG mode. When REG0x34[5]=0, pulling high OTG/VAP pin is to enable VAP mode.		
HIDRV1	31	0	Buck mode high side power MOSFET (Q1) driver. Connect to high side n-channel MOSFET gate.		
HIDRV2	24	0	Boost mode high side power MOSFET(Q4) driver. Connect to high side n-channel MOSFET gate.		
IADPT	8	0	The adapter current monitoring output pin. $V_{(IADPT)} = 20 \text{ or } 40 \times (V_{(ACP)} - V_{(ACN)})$ with r selectable in REG0x00[4]. Place a resistor from the IADPT pin to ground corresponding the inductance in use. For a 2.2 µH inductance, the resistor is 137 kΩ. Place a 100-pF less ceramic decoupling capacitor from IADPT pin to ground. IADPT output voltage is clamped below 3.3 V.		
IBAT	9	0	The battery current monitoring output pin. $V_{(IBAT)} = 8$ or $16 \times (V_{(SRP)} - V_{(SRN)})$ for charge current, or $V_{(IBAT)} = 8$ or $16 \times (V_{(SRN)} - V_{(SRP)})$ for discharge current, with ratio selectable in REG0x00[3]. Place a 100-pF or less ceramic decoupling capacitor from IBAT pin to ground. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V.		
ILIM_HIZ	6	I	Input current limit setting pin. Program ILIM_HIZ voltage by connecting a resistor divider from supply rail to ILIM_HIZ pin to ground. The pin voltage is calculated as: $V_{(ILIM_HIZ)} = 1 V + 40 \times IDPM \times RAC$ , in which IDPM is the target input current. The input current limit used by the charger is the lower setting of ILIM_HIZ pin and REG0x0F/0E(). When the pin voltage is below 0.4 V, the device enters Hi-Z mode with low quiescent current. When the pin voltage is above 0.8 V, the device is out of Hi-Z mode.		
LODRV1	29	0	Buck mode low side power MOSFET (Q2) driver. Connect to low side n-channel MOSFET gate.		
LODRV2	26	0	Boost mode low side power MOSFET (Q3) driver. Connect to low side n-channel MOSFET gate.		
PGND	27	GND	Device power ground.		
PROCHOT	11	0	Active low open drain output of processor hot indicator. It monitors adapter input current, battery discharge current, and system voltage. After any event in the PROCHOT profile is triggered, a pulse is asserted. The minimum pulse width is adjustable in REG0x23[6:3].		
PSYS	10	0	Current mode system power monitor. The output current is proportional to the total power from the adapter and the battery. The gain is selectable through I <sup>2</sup> C. Place a resistor from PSYS to ground to generate output voltage. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V. Place a capacitor in parallel with the resistor for filtering.		
REGN	28	PWR	6-V linear regulator output supplied from VBUS or VSYS. The LDO is active when VBUS above V <sub>VBUS_CONVEN</sub> . Connect a 2.2- or 3.3- $\mu$ F ceramic capacitor from REGN to power ground. REGN pin output is for power stage gate drive.		

BQ25713, BQ25713B JAJSFQ9C – JUNE 2018 – REVISED MAY 2023



# 表 7-1. Pin Functions (continued)

PIN NAME NO.		1/0	DESCRIPTION		
SCL	13	I	$I^2C$ clock input. Connect to clock line from the host controller or smart battery. Connect a 10- k $\Omega$ pullup resistor according to I <sup>2</sup> C specifications.		
SDA	12	I/O	$I^2C$ open-drain data I/O. Connect to data line from the host controller or smart battery. Connect a 10-kΩ pullup resistor according to $I^2C$ specifications.		
SRN	19	PWR	Charge current sense resistor negative input. SRN pin is for battery voltage sensing as well. Connect SRN pin with optional 0.1- $\mu$ F ceramic capacitor to GND for common-mode filtering. Connect a 0.1- $\mu$ F ceramic capacitor from SRP to SRN to provide differential mode filtering. The leakage current on SRP and SRN are matched.		
SRP	20	PWR	Charge current sense resistor positive input. Connect SRP pin with optional 0.1-uF ceramic capacitor to GND for common-mode filtering. Connect a 0.1-µF ceramic capacitor from SRP to SRN to provide differential mode filtering. The leakage current on SRP and SRN are matched.		
SW1	32	PWR	Buck mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.		
SW2	23	PWR	Boost mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.		
VBUS	1	PWR	Charger input voltage. An input low pass filter of $1\Omega$ and 0.47 $\mu F$ (minimum) is recommended.		
VDDA	7	PWR	Internal reference bias pin. Connect a $10-\Omega$ resistor from REGN to VDDA and a $1-\mu$ F ceramic capacitor from VDDA to power ground.		
VSYS	22	PWR	Charger system voltage sensing. The system voltage regulation limit is programmed in REG0x05/04() and REG0X0D/0C().		
Thermal pad	-	-	Exposed pad beneath the IC. Always solder thermal pad to the board, and have vias on the thermal pad plane connecting to power ground planes. It serves as a thermal pad to dissipate the heat.		



# 8 Specifications

# 8.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

		MIN	MAX	UNIT
	SRN, SRP, ACN, ACP, VBUS, VSYS	-0.3	30	
	SW1, SW2	-2	30	
	BTST1, BTST2, HIDRV1, HIDRV2, /BATDRV	-0.3	36	
	LODRV1, LODRV2 (25nS)	-4	7	
	HIDRV1, HIDRV2 (25nS)	-4	36	
Voltage	SW1, SW2 (25nS)	-4	30	V
	SDA, SCL, REGN, PSYS, CHRG_OK, OTG/VAP, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT	-0.3	7	
	/PROCHOT	-0.3	5.5	
	IADPT, IBAT, PSYS	-0.3	3.6	
Differential	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	-0.3	7	V
Voltage	SRP-SRN, ACP-ACN	-0.5	0.5	v
Temperature	Junction temperature range, T <sub>J</sub>	-40	155	°C
Temperature	Storage temperature, T <sub>stg</sub>	-40	155	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages are with respect to GND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages.

# 8.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/ JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
V <sub>(ESD)</sub>	Electrostatic discharge	Charged device model (CDM), per JEDEC specificationJESD22-C101, all pins <sup>(2)</sup>	±500	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 8.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
	ACN, ACP, VBUS	0	24	
Voltage       SRN, SRP, VSYS         SW1, SW2         BTST1, BTST2, HIDRV1, HIDRV2, /BATDRV         SDA, SCL, REGN, PSYS, CHRG_OK, OTG/VAP, CELL_BATPRESZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT	SRN, SRP, VSYS	0	19.2	
	SW1, SW2	-2	24	
	BTST1, BTST2, HIDRV1, HIDRV2, /BATDRV	0	30	V
	SDA, SCL, REGN, PSYS, CHRG_OK, OTG/VAP, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT	0	6.5	
	/PROCHOT	0	5.3	
	IADPT, IBAT, PSYS	0	3.3	
Differential	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	0	6.5	V
Voltage	SRP-SRN, ACP-ACN	-0.5	0.5	v
Junction tem	perature range, T <sub>J</sub>	-20	125	°C

Copyright © 2023 Texas Instruments Incorporated



# 8.3 Recommended Operating Conditions (continued)

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Operating free-air temperature range, $T_J$	-40	85	°C

# 8.4 Thermal Information

		BQ25713/BQ25713B	
	THERMAL METRIC <sup>(1)</sup>	RSN (WQFN)	UNIT
		32 PINS	_
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	37.2	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	26.1	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	7.8	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	0.3	°C/W
Y <sub>JB</sub>	Junction-to-board characterization parameter	7.8	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	2.3	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

# **8.5 Electrical Characteristics**

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>INPUT_OP</sub>	Input voltage operating range		3.5		26	V
REGULATION ACCUR	ACY					
MAX SYSTEM VOLTA	GE REGULATION					
Vsysmax_rng	System Voltage Regulation, measured on V <sub>SYS</sub> (charge disabled)		1.024		19.2	V
		REG0x05/04() = 0x41A0H (16.800 V)	N	/ <sub>SRN</sub> + 160 mV		V
			-2%		2%	
		REG0x05/04() = 0x3138H (12.600 V) REG0x05/04() = 0x20D0H (8.400 V)	N	/ <sub>SRN</sub> + 160 mV		V
. <i>.</i>	System voltage regulation		-2%		2%	
V <sub>SYSMAX_ACC</sub>	accuracy (charge disabled)		١	/ <sub>SRN</sub> + 160 mV		V
			-3%		3%	
		REG0x05/04() = 0x1068H (4.200 V)	N	/ <sub>SRN</sub> + 160 mV		V
			-3%		3%	
MINIMUM SYSTEM VC	DLTAGE REGULATION					
V <sub>SYSMIN_RNG</sub>	System Voltage Regulation, measured on V <sub>SYS</sub>		1.024		19.2	V



	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		REG0x0D/0C() = 0x3000H		12.288		V
			-2%		2%	
		REG0x0D/0C() = 0x2400H		9.216		V
N/	Minimum System Voltage		-2%		2%	
Vsysmin_reg_acc	Regulation Accuracy (VBAT below REG0x0D/0C() setting)	REG0x0D/0C() = 0x1800H		6.144		V
	() ()		-3%		3%	
		REG0x0D/0C() = 0x0E00H		3.584		V
			-3%		3%	
CHARGE VOLTAGE REG	ULATION	1				
V <sub>BAT_RNG</sub>	Battery voltage regulation		1.024		19.2	V
		REG0x05/04() = 0x41A0H		16.8		V
VBAT_REG_ACC	Battery voltage regulation		-0.5%		0.5%	
		REG0x05/04() = 0x3138H		12.6		V
			-0.5%		0.5%	
	accuracy (charge enable) (0°C to 85°C)	REG0x05/04() = 0x20D0H		8.4		V
			-0.6%		0.6%	
		REG0x05/04() = 0x1068H		4.2		V
			-1.1%		1.2%	
CHARGE CURRENT REG	ULATION IN FAST CHARGE					
V <sub>IREG_CHG_RNG</sub>	Charge current regulation differential voltage range	V <sub>IREG_CHG</sub> = V <sub>SRP</sub> - <sub>VSRN</sub>	0		81.28	mV
				4096		mA
		REG0x03/02() = 0x1000H	-3%		2%	
	Charge surrent regulation			2048		mA
1	Charge current regulation accuracy 10-mΩ sensing resistor,	REG0x03/02() = 0x0800H	-4%		3%	
CHRG_REG_ACC	VBAT above REG0x0D/0C()			1024		mA
	setting (0°C to 85°C)	REG0x03/02() = 0x0400H	-5%		6%	
		BEC0x02/02/1 = 0x020011		512		mA
		REG0x03/02() = 0x0200H	-12%		12%	
CHARGE CURRENT REG	ULATION IN LDO MODE					
		CELL 2s-4s		384		mA
	Precharge current clamp	CELL 1 s, VSRN < 3 V		384		mA
ICLAMP	r recharge current clamp	CELL 1 s, 3 V < VSRN < VSYSMIN		2		А



PARA	METER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		REG0x03/02() = 0x0180H		384		mA
		2S-4S	-15%		15%	
		1S	-25%		25%	
		REG0x03/02() = 0x0100H		256		mA
	Precharge current regulation accuracy with 10-mΩ SRP/SRN	2S-4S	-20%		20%	
PRECHRG REG ACC	series resistor, VBAT below	1S	-35%		35%	
	REG0x0D/0C() setting (0°C to 85°C)	REG0x03/02() = 0x00C0H		192		mA
	85 C)	2S-4S	-25%		25%	
		1S	-50%		50%	
		REG0x03/02() = 0x0080H		128		mA
		2S-4S	-30%		30%	
ILEAK_SRP_SRN	SRP, SRN leakage current mismatch (0°C to 85°C)		-12		10	μA
INPUT CURRENT REGULATION	. ,					
Vireg_dpm_rng	Input current regulation differential voltage range	$V_{IREG_{DPM}} = V_{ACP} - V_{ACN}$	0.5		64	mV
	<u>5</u>	REG0x0F/0E() = 0x5000H	3800	3900	4000	mA
	Input current regulation accuracy (-40°C to $105^{\circ}$ C) with $10$ -m $\Omega$ ACP/ACN series resistor	REG0x0F/0E() = 0x3C00H	2800	2900	3000	mA
IDPM_REG_ACC		REG0x0F/0E() = 0x1E00H	1300	1400	1500	mA
		REG0x0F/0E() = 0x0A00H	300	400	500	mA
ILEAK_ACP_ACN	ACP, ACN leakage current mismatch (-40°C to 105°C)		-16		10	μA
VIREG_DPM_RNG_ILIM	Voltage range for input current regulation (ILIM_HIZ Pin)		1.15		4	V
	Input Current Regulation Accuracy on ILIM_HIZ pin $V_{ILIM_HIZ} = 1 V + 40 \times I_{DPM} \times R_{AC}$ , with 10-m $\Omega$ ACP/ACN series resistor	V <sub>ILIM_HIZ</sub> = 2.6 V	3800	4000	4200	mA
		V <sub>ILIM_HIZ</sub> = 2.2 V	2800	3000	3200	mA
DPM_REG_ACC_ILIM		V <sub>ILIM_HIZ</sub> = 1.6 V	1300	1500	1700	mA
		V <sub>ILIM_HIZ</sub> = 1.2 V	300	500	700	mA
	ILIM_HIZ pin leakage current		-1		1	μA
INPUT VOLTAGE REGULATION						
VIREG_DPM_RNG	Input voltage regulation range	Voltage on VBUS	3.2		19.52	V
		REG0x0B/0A()=0x3C80H		18688		mV
			-3%		2%	
. ,		REG0x0B/0A()=0x1E00H	-	10880		mV
V <sub>DPM_REG_ACC</sub>	Input voltage regulation accuracy		-4%		2.5%	
		REG0x0B/0A()=0x0500H		4480		mV
			-5%		5%	
OTG CURRENT REGULATION		1				
VIOTG_REG_RNG	OTG output current regulation differential voltage range	$V_{IOTG\_REG} = V_{ACP} - V_{AC}N$	0		81.28	mV
	OTG output current regulation	REG0x09/08() = 0x3C00H	2800	3000	3200	mA
Іотд асс	accuracy with 50-mA LSB and	REG0x09/08() = 0x1E00H	1300	1500	1700	mA
	10-mΩ ACP/ACN series resistor	REG0x09/08() = 0x0A00H	300	500	700	mA
OTG VOLTAGE REGULATION		V				
V <sub>OTG_REG_RNG</sub>	OTG voltage regulation range	Voltage on VBUS	3		20.8	V



over  $T_{1}$  = -40°C to 125°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNI
		REG0x07/06() = 0x23F8H REG0x34[2] = 0		20.002		V
			-2%		2%	
V <sub>OTG_REG_ACC</sub>	OTG voltage regulation accuracy	REG0x07/06() = 0x1710H REG0x34[2] = 1		12.004		V
			-2%		2%	
		REG0x07/06() = 0x099CH REG0x34[2] = 1		5.002		V
			-3%		3%	
REFERENCE AND BUFFE	R					
REGN REGULATOR						
V <sub>REGN_REG</sub>	REGN regulator voltage (0 mA – 60 mA)	V <sub>VBUS</sub> = 10 V	5.7	6	6.3	V
VDROPOUT	REGN voltage in drop out mode	V <sub>VBUS</sub> = 5 V, I <sub>LOAD</sub> = 20 mA	3.8	4.3	4.6	V
REGN_LIM_Charging	REGN current limit when converter is enabled	$V_{VBUS}$ = 10 V, force $V_{REGN}$ =4 V	50	65		mA
C <sub>REGN</sub>	REGN output capacitor required for stability	$I_{LOAD}$ = 100 µA to 50 mA	2.2			μF
C <sub>VDDA</sub>	REGN output capacitor required for stability	$I_{LOAD}$ = 100 µA to 50 mA	1			μF
QUIESCENT CURRENT		1 1				
	System powered by battery. BATFET on. I <sub>SRN</sub> + I <sub>SRP</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub> + I <sub>SW1</sub> + I <sub>BTST1</sub> + I <sub>ACP</sub> + I <sub>ACN</sub> + I <sub>VBUS</sub> + I <sub>VSYS</sub>	VBAT = 18 V, REG0x01[7] = 1, in low power mode		22	45	μA
		VBAT = 18 V, REG0x01[7] = 1, REG0x31[5] = 1, REGN off		125	195	μA
BAT_BATFET_ON		VBAT = 18 V, REG0x01[7] = 0, REG0x31[4] = 0, REGN on, DIS_PSYS		880	1170	μA
		VBAT = 18 V, REG0x01[7] = 0, REG0x31[4] = 1, REGN on, EN_PSYS		980	1270	μA
AC_SW_LIGHT_buck	Input current during PFM in buck mode, no load, I <sub>VBUS</sub> + I <sub>ACP</sub> + I <sub>ACN</sub> + I <sub>VSYS</sub> + I <sub>SRP</sub> + I <sub>SRN</sub> + I <sub>SW1</sub> + I <sub>BTST</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub>	VIN = 20 V, VBAT = 12.6 V, 3s, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.2		mA
IAC_SW_LIGHT_boost	Input current during PFM in boost mode, no load, I <sub>VBUS</sub> + I <sub>ACP</sub> + I <sub>ACN</sub> + I <sub>VSYS</sub> + I <sub>SRP</sub> + I <sub>SRN</sub> + I <sub>SW1</sub> + I <sub>BTST2</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub>	VIN = 5 V, VBAT = 8.4 V, 2s, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.7		mA
IAC_SW_LIGHT_buckboost	Input current during PFM in buck boost mode, no load, I <sub>VBUS</sub> + I <sub>ACP</sub> + I <sub>ACN</sub> + I <sub>VSYS</sub> + I <sub>SRP</sub> + I <sub>SRN</sub> + I <sub>SW1</sub> + I <sub>BTST1</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub>	VIN = 12 V, VBAT = 12 V, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.4		mA
		VBAT = 8.4 V, VBUS = 5 V, 800 kHz switching frequency, MOSFET Qg = 4nC		3		mA
Iotg_standby	Ivsys + Isrp + Isrn + Isw1 + Ibtst2 + I <sub>SW2</sub> + I <sub>BTST2</sub>	VBAT = 8.4 V, VBUS = 12 V, 800 kHz switching frequency, MOSFET Qg = 4nC		4.2		mA
		VBAT = 8.4 V, VBUS = 20 V, 800 kHz switching frequency, MOSFET Qg = 4nC		6.2		mA



	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>ACP/N_OP</sub>	Input common mode range	Voltage on ACP/ACN	3.8		26	V
VIADPT_CLAMP	I <sub>ADPT</sub> output clamp voltage		3.1	3.2	3.3	V
IIADPT	I <sub>ADPT</sub> output current				1	mA
A		$ V_{(\text{IADPT})} / V_{(\text{ACP-ACN})}, \text{REG0x00[4]} $ = 0		20		V/V
A <sub>IADPT</sub>	Input current sensing gain	V <sub>(IADPT)</sub> / V <sub>(ACP-ACN)</sub> , REG0x00[4] = 1		40		V/V
		V <sub>(ACP-ACN)</sub> = 40.96 mV	-2%		2%	
N		V <sub>(ACP-ACN)</sub> = 20.48 mV	-3%		3%	
VIADPT_ACC	Input current monitor accuracy	V <sub>(ACP-ACN)</sub> =10.24 mV	-6%		6%	
		V <sub>(ACP-ACN)</sub> = 5.12 mV	-10%		10%	
C <sub>IADPT_MAX</sub>	Maximum capacitance at IADPT Pin				100	pF
V <sub>SRP/N_OP</sub>	Battery common mode range	Voltage on SRP/SRN	2.5		18	V
V <sub>IBAT_CLAMP</sub>	IBAT output clamp voltage		3.05	3.2	3.3	V
I <sub>IBAT</sub>	IBAT output current				1	mA
٨	Charge and discharge current	V <sub>(IBAT)</sub> / V <sub>(SRN-SRP)</sub> , REG0x00[3] = 0,		8		V/V
A <sub>IBAT</sub>	sensing gain on IBAT pin	V <sub>(IBAT)</sub> / V <sub>(SRN-SRP)</sub> , REG0x00[3] = 1,		16		V/V
		V <sub>(SRN-SRP)</sub> = 40.96 mV	-2%		2%	
IBAT_CHG_ACC	Charge and discharge current	V <sub>(SRN-SRP)</sub> = 20.48 mV	-4%		4%	
	monitor accuracy on IBAT pin	V <sub>(SRN-SRP)</sub> =10.24 mV	-7%		7%	
		V <sub>(SRN-SRP)</sub> = 5.12 mV	-15%		15%	
C <sub>IBAT_MAX</sub>	Maximum capacitance at IBAT Pin				100	pF
SYSTEM POWER SENSE	E AMPLIFIER					
V <sub>PSYS</sub>	PSYS output voltage range		0		3.3	V
I <sub>PSYS</sub>	PSYS output current		0		160	μA
A <sub>PSYS</sub>	PSYS system gain	V <sub>(PSYS)</sub> / (P <sub>(IN)</sub> +P <sub>(BAT)</sub> ), REG0x31[1] = 1		1		µA/W
V <sub>PSYS_ACC</sub>	PSYS gain accuracy (REG0x31[1] = 1)	Adapter only with system power = 19.5 V / 45 W, TA = -40°C to 85°C	-4%		4%	
	(REG0331[1] - 1)	Battery only with system power = 11 V / 44 W, TA = -40°C to 85°C	-3%		3%	
V <sub>PSYS_CLAMP</sub>	PSYS clamp voltage		3		3.3	V
COMPARATOR						
VBUS UNDER VOLTAGE	LOCKOUT COMPARATOR					
V <sub>VBUS_UVLOZ</sub>	VBUS undervoltage rising threshold	VBUS rising	2.30	2.55	2.80	V
V <sub>VBUS_UVLO</sub>	VBUS undervoltage falling threshold	VBUS falling	2.18	2.40	2.62	V
V <sub>VBUS_UVLO_HYST</sub>	VBUS undervoltage hysteresis			150		mV
V <sub>VBUS_CONVEN</sub>	VBUS converter enable rising threshold	VBUS rising	3.2	3.5	3.9	V
Vvbus_convenz	VBUS converter enable falling threshold	VBUS falling	2.9	3.2	3.5	V



over  $T_J = -40^{\circ}C$  to 125°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>VBUS_CONVEN_HYST</sub>	VBUS converter enable hysteresis			400		mV
BATTERY UNDER VOLTA	GE LOCKOUT COMPARATOR					
V <sub>VBAT_UVLOZ</sub>	VBAT undervoltage rising threshold	VSRN rising	2.35	2.55	2.75	V
V <sub>VBAT_UVLO</sub>	VBAT undervoltage falling threshold	VSRN falling	2.2	2.4	2.6	V
V <sub>VBAT_UVLO_HYST</sub>	VBAT undervoltage hysteresis			150		mV
V <sub>VBAT_OTGEN</sub>	VBAT OTG enable rising threshold	VSRN rising	3.25	3.55	3.85	V
V <sub>VBAT_OTGENZ</sub>	VBAT OTG enable falling threshold	VSRN falling	2.2	2.4	2.6	V
V <sub>VBAT_OTGEN_HYST</sub>	VBAT OTG enable hysteresis			1100		mV
VBUS UNDER VOLTAGE	COMPARATOR (OTG MODE)					
V <sub>VBUS_OTG_UV</sub>	VBUS undervoltage falling threshold	As percentage of REG0x07/06()		85		%
t <sub>VBUS_OTG_UV</sub>	VBUS time undervoltage deglitch			7		ms
VBUS OVER VOLTAGE CO	OMPARATOR (OTG MODE)					
V <sub>VBUS_OTG_OV</sub>	VBUS overvoltage rising threshold	As percentage of REG0x07/06()		110		%
t <sub>VBUS_OTG_OV</sub>	VBUS Time Over-Voltage Deglitch			10		ms
PRECHARGE to FAST CH	ARGE TRANSITION					
VBAT_SYSMIN_RISE	LDO mode to fast charge mode threshold, VSRN rising	as percentage of 0x0D/0C()	98	100	102	%
VBAT_SYSMIN_FALL	LDO mode to fast charge mode threshold, VSRN falling	as percentage of 0x0D/0C()		97.5		%
VBAT_SYSMIN_HYST	Fast charge mode to LDO mode threshold hysteresis	as percentage of 0x0D/0C()		2.5		%
BATTERY LOWV COMPAN	RATOR (Precharge to Fast Charge Three	shold for 1S)				
V <sub>BATLV_FALL</sub>	BATLOWV falling threshold	1 s		2.8		V
V <sub>BATLV_RISE</sub>	BATLOWV rising threshold			3		V
V <sub>BATLV_RHYST</sub>	BATLOWV hysteresis			200		mV
INPUT OVER-VOLTAGE C	OMPARATOR (ACOVP)					
V <sub>ACOV_RISE</sub>	VBUS overvoltage rising threshold	VBUS rising	25	26	27	V
V <sub>ACOV_FALL</sub>	VBUS overvoltage falling threshold	VBUS falling	23.5	24.5	25	V
V <sub>ACOV_HYST</sub>	VBUS overvoltage hysteresis			1.5		V
t <sub>ACOV_RISE_DEG</sub>	VBUS deglitch overvoltage rising	VBUS converter rising to stop converter		100		μs
tacov_fall_deg	VBUS deglitch overvoltage falling	VBUS converter falling to start converter		1		ms
INPUT OVER CURRENT C	COMPARATOR (ACOC)	,				
V <sub>ACOC</sub>	ACP to ACN rising threshold, w.r.t. ILIM2 in REG0x37[7:4]	Voltage across input sense resistor rising, REG0x32[2] = 1	1.8	2	2.2	
V <sub>ACOC_FLOOR</sub>	Measure between ACP and ACN	Set IDPM to minimum	44	50	56	mV
V <sub>ACOC_CEILING</sub>	Measure between ACP and ACN	Set IDPM to maximum	172	180	188	mV
t <sub>ACOC</sub> DEG RISE	Rising deglitch time	Deglitch time to trigger ACOC		250		μs

Copyright © 2023 Texas Instruments Incorporated



PARA	AMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>ACOC_RELAX</sub>	Relax time	Relax time before converter starts again		250		ms
SYSTEM OVER-VOLTAGE COM	IPARATOR (SYSOVP)				•	
		1 s	4.85	5	5.1	V
V <sub>SYSOVP_RISE</sub>	System overvoltage rising threshold to turn off converter	2 s	11.7	12	12.2	V
		3 s, 4 s	19	19.5	20	V
		1 s		4.8		V
V <sub>SYSOVP_FALL</sub>	System overvoltage falling threshold	2 s		11.5		V
		3 s, 4 s		19		V
I <sub>SYSOVP</sub>	Discharge current when SYSOVP stop switching was triggered	on SYS		20		mA
BAT OVER-VOLTAGE COMPAR	ATOR (BATOVP)	I				
V <sub>BATOVP_RISE</sub>	Overvoltage rising threshold as percentage of VBAT_REG in REG0x05/04()	1 s, 4.2 V	102.5	104	106	%
		2 s - 4 s	102.5	104	105	%
VBATOVP_FALL	Overvoltage falling threshold as percentage of VBAT_REG in REG0x05/04()	1 s	100	102	104	%
		2 s - 4 s	100	102	103	%
V <sub>BATOVP_HYST</sub>	Overvoltage hysteresis as percentage of VBAT_REG in REG0x05/04()	1 s		2		%
		2 s - 4 s		2		%
IBATOVP	Discharge current during BATOVP	on VSYS pin		20		mA
t <sub>BATOVP_RISE</sub>	Overvoltage rising deglitch to turn off BATDRV to disable charge			20		ms
CONVERTER OVER-CURRENT	COMPARATOR (Q2)					
VOCD limit 02	Converter Over-Current Limit	REG0x32[5]=1		150		mV
VOCP_limit_Q2	Converter Over-Current Limit	REG0x32[5]=0		210		mV
VOCD IIIIII OVOCUODT OD	Custom Chart on CDN 4.2.4.V	REG0x32[5]=1		45		mV
VOCP_limit_SYSSHORT_Q2	System Short or SRN < 2.4 V	REG0x32[5]=0		60		mV
CONVERTER OVER-CURRENT	COMPARATOR (ACX)					
	Opensional and Opensional Line 11	REG0x32[4]=1		150		mV
VOCP_limit_ACX	Converter Over-Current Limit	REG0x32[4]=0		280		mV
		REG0x32[4]=1		90		mV
VOCP_limit_SYSSHORT_ACX	System Short or SRN < 2.4 V	REG0x32[4]=0		150		mV
THERMAL SHUTDOWN COMP	ARATOR	1				
T <sub>SHUT_RISE</sub>	Thermal shutdown rising temperature	Temperature increasing		155		°C
T <sub>SHUTF_FALL</sub>	Thermal shutdown falling temperature	Temperature reducing		135		°C
T <sub>SHUT_HYS</sub>	Thermal shutdown hysteresis			20		°C
t <sub>SHUT_RDEG</sub>	Thermal deglitch shutdown rising			100		μs
t <sub>SHUT_FHYS</sub>	Thermal deglitch shutdown falling			12		ms
VSYS PROCHOT COMPARATO	R					



P	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VSYS TH1	VSYS_TH1 comparator falling	REG0x36[7:4] = 0111, 2-4 s		6.6		V
voro_m	threshold	REG0x36[7:4] = 0100, 1 s		3.5		V
	VSYS_TH2 comparator falling	REG0x36[3:2] = 10, 2-4 s		6.5		V
VSYS_TH2	threshold	REG0x36[3:2] = 10, 1 s		3.5		V
t <sub>SYS_PRO_falling_DEG</sub>	$V_{SYS}$ falling deglitch for throttling			4		μs
ICRIT PROCHOT COMPAR	ATOR					
V <sub>ICRIT_PRO</sub>	Input current rising threshold for throttling as 10% above ILIM2 (REG0x37[7:3])	Only when ILIM2 setting is higher than 2A	105	110	117	%
INOM PROCHOT COMPARA	ATOR					
V <sub>INOM_PRO</sub>	INOM rising threshold as 10% above IIN (REG0x0F/0E())		105	110	116	%
IDCHG PROCHOT COMPA	RATOR					
	IDCHG threshold for throttling for			6272		mA
VIDCHG_PRO	IDSCHG of 6 A	REG0x39[7:2] = 001100	95		103	%
INDEPENDENT COMPARA	TOR					
	Independent comparator	REG0x30[7] = 1, CMPIN falling	1.17	1.2	1.23	V
VINDEP_CMP	threshold	REG0x30[7] = 0, CMPIN falling	2.27	2.3	2.33	V
VINDEP_CMP_HYS	Independent comparator hysteresis	REG0x30[7] = 0, CMPIN falling		100		mV
POWER MOSFET DRIVER						
PWM OSCILLATOR AND R	АМР					
F <sub>SW</sub>	PWM switching frequency	REG0x01[1] = 0	1020	1200	1380	kHz
		REG0x01[1] = 1	680	800	920	kHz
BATFET GATE DRIVER (BA	ATDRV)					
V <sub>BATDRV_ON</sub>	Gate drive voltage on BATFET		8.5	10	11.5	V
VBATDRV_DIODE	Drain-source voltage on BATFET during ideal diode operation			30		mV
R <sub>BATDRV_ON</sub>	Measured by sourcing 10 µA current to BATDRV		2.5	4	6	kΩ
R <sub>BATDRV_OFF</sub>	Measured by sinking 10 µA current from BATDRV			1.2	2.1	kΩ
PWM HIGH SIDE DRIVER (I	HIDRV Q1)	1 1			I	
R <sub>DS_HI_ON_Q1</sub>	High side driver (HSD) turn on resistance	V <sub>BTST1</sub> - V <sub>SW1</sub> = 5 V		6		Ω
R <sub>DS_HI_OFF_Q1</sub>	High side driver turn off resistance	V <sub>BTST1</sub> - V <sub>SW1</sub> = 5 V		1.3	2.2	Ω
V <sub>BTST1_REFRESH</sub>	Bootstrap refresh comparator falling threshold voltage	V <sub>BTST1</sub> - V <sub>SW1</sub> when low side refresh pulse is requested	3.2	3.7	4.6	V
PWM HIGH SIDE DRIVER (I	HIDRV Q4)					
R <sub>DS_HI_ON_Q4</sub>	High side driver (HSD) turn on resistance	V <sub>BTST2</sub> - V <sub>SW2</sub> = 5 V		6		Ω
R <sub>DS_HI_OFF_Q4</sub>	High side driver turn off resistance	V <sub>BTST2</sub> - V <sub>SW2</sub> = 5 V		1.5	2.4	Ω



	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
R <sub>DS_LO_ON_Q2</sub>	Low side driver (LSD) turn on resistance	V <sub>BTST1</sub> - V <sub>SW1</sub> = 5.5 V		6		Ω
R <sub>DS_LO_OFF_Q2</sub>	Low side driver turn off resistance	V <sub>BTST1</sub> - V <sub>SW1</sub> = 5.5 V		1.7	2.6	Ω
PWM LOW SIDE DRIVER	(LODRV Q3)	•				
R <sub>DS_LO_ON_Q3</sub>	Low side driver (LSD) turn on resistance	V <sub>BTST2</sub> - V <sub>SW2</sub> = 5.5 V		7.6		Ω
R <sub>DS_LO_OFF_Q3</sub>	Low side driver turn off resistance	V <sub>BTST2</sub> - V <sub>SW2</sub> = 5.5 V		2.9	4.6	Ω
INTERNAL SOFT START	During Charge Enable					
SSSTEP_DAC	Soft Start Step Size			64		mA
SSSTEP_DAC	Soft Start Step Time			8		μs
INTEGRATED BTST DIOD	DE (D1)					
V <sub>F_D1</sub>	Forward bias voltage	IF = 20 mA at 25°C		0.8		V
V <sub>R_D1</sub>	Reverse breakdown voltage	IR = 2 µA at 25°C			20	V
INTEGRATED BTST DIOL	DE (D2)				I	
V <sub>F_D2</sub>	Forward bias voltage	IF = 20 mA at 25°C		0.8		V
 V <sub>R_D2</sub>	Reverse breakdown voltage	IR = 2 μA at 25°C			20	V
INTERFACE					I	
LOGIC INPUT (SDA, SCL	., OTG/VAP)					
V <sub>IN_LO</sub>	Input low threshold	12C			0.4	V
V <sub>IN_HI</sub>	Input high threshold	12C	1.3			V
	RAIN (SDA, CHRG_OK, CMPOUT)					
V <sub>OUT_LO</sub>	Output saturation voltage	5 mA drain current			0.4	V
V <sub>OUT_LEAK</sub>	Leakage current	V = 7 V	-1		1	μA
LOGIC OUTPUT OPEN D	RAIN SDA					
V <sub>OUT_LO_SDA</sub>	Output Saturation Voltage	5 mA drain current			0.4	V
V <sub>OUT_LEAK_SDA</sub>	Leakage Current	V = 7V	-1		1	μA
LOGIC OUTPUT OPEN D	RAIN CHRG_OK				I	
V <sub>OUT_LO_CHRG_OK</sub>	Output Saturation Voltage	5 mA drain current			0.4	V
V <sub>OUT_LEAK_CHRG_OK</sub>	Leakage Current	V = 7V	-1		1	μA
LOGIC OUTPUT OPEN D	RAIN CMPOUT					
V <sub>OUT_LO_CMPOUT</sub>	Output Saturation Voltage	5 mA drain current			0.4	V
V <sub>OUT LEAK CMPOUT</sub>	Leakage Current	V = 7V	-1		1	μA
LOGIC OUTPUT OPEN D	RAIN (PROCHOT)				1	
V <sub>OUT_LO_PROCHOT</sub>	Output saturation voltage	50 Ω pullup to 1.05 V / 5-mA			300	mV
V <sub>OUT_LEAK_PROCHOT</sub>	Leakage current	V = 5.5 V			1	μA
ANALOG INPUT (ILIM_HI	IZ)	1				-
V <sub>HIZ_LO</sub>	Voltage to get out of HIZ mode	ILIM_HIZ pin rising	0.8			V
V <sub>HIZ_HIGH</sub>	Voltage to enable HIZ mode	ILIM_HIZ pin falling			0.4	V
ANALOG INPUT (CELL_E	BATPRESZ)					
V <sub>CELL_4S</sub>	4S	REGN of REGN = 6 V, as percentage	68.4	75		%
V <sub>CELL_3S</sub>	3S	REGN of REGN = 6 V, as percentage	51.7	55	65	%
V <sub>CELL_2S</sub>	28	REGN of REGN = 6 V, as percentage	35	40	49.1	%



over  $T_J = -40^{\circ}C$  to  $125^{\circ}C$  (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>CELL_1S</sub>	18	REGN of REGN = 6 V, as percentage	18.4	25	31.6	%
V <sub>CELL_BATPRESZ_RISE</sub>	Battery is present	CELL_BATPRESZ rising	18			%
V <sub>CELL_BATPRESZ_FALL</sub>	Battery is removed	CELL_BATPRESZ falling			15	%

# 8.6 Timing Requirements

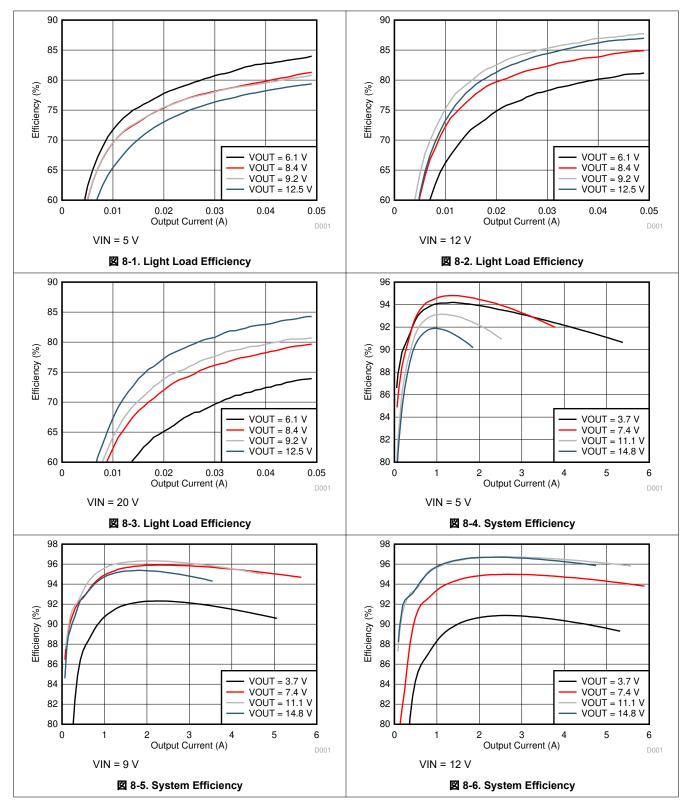
		MIN	NOM	MAX	UNIT
I2C TIMIN	IG CHARACTERISTICS	I		I	
t <sub>r</sub>	SCLK/SDATA rise time			300	ns
t <sub>f</sub>	SCLK/SDATA fall time			300	ns
t <sub>W(H)</sub>	SCLK pulse width high	0.6		50	μs
t <sub>W(L)</sub>	SCLK Pulse Width Low	1.3			μs
t <sub>SU(STA)</sub>	Setup time for START condition	0.6			μs
t <sub>H(STA)</sub>	START condition hold time after which first clock pulse is generated	0.6			μs
t <sub>SU(DAT)</sub>	Data setup time	100			ns
t <sub>H(DAT)</sub>	Data hold time	300			ns
t <sub>SU(STOP)</sub>	Setup time for STOP condition	0.6			μs
t <sub>(BUF)</sub>	Bus free time between START and STOP condition	1.3			μs
F <sub>S(CL)</sub>	Clock Frequency	10		400	kHz
	DMMUNICATION FAILURE				
t <sub>timeout</sub>	I2C bus release timeout <sup>(1)</sup>	25		35	ms
t <sub>Deg_WD</sub>	Deglitch for watchdog reset signal	10			ms
	Watchdog timeout period, ChargeOption() bit [14:13] = 01 <sup>(2)</sup>	4	5.5	7	S
t <sub>WDI</sub>	Watchdog timeout period, ChargeOption() bit bit [14:13] = 10 <sup>(2)</sup>	70	88	105	S
	Watchdog timeout period, ChargeOption() bit bit [14:13] = 11 <sup>(2)</sup>	140	175	210	S

(1) Devices participating in a transfer will timeout when any clock low exceeds the 25ms minimum timeout period. Devices that have detected a timeout condition must reset the communication no later than the 35 ms maximum timeout period. Both a master and a slave must adhere to the maximum value specified as it incorporates the cumulative stretch limit for both a master (10 ms) and a slave (25 ms).

(2) User can adjust threshold via I2C ChargeOption() REG0x01/00().

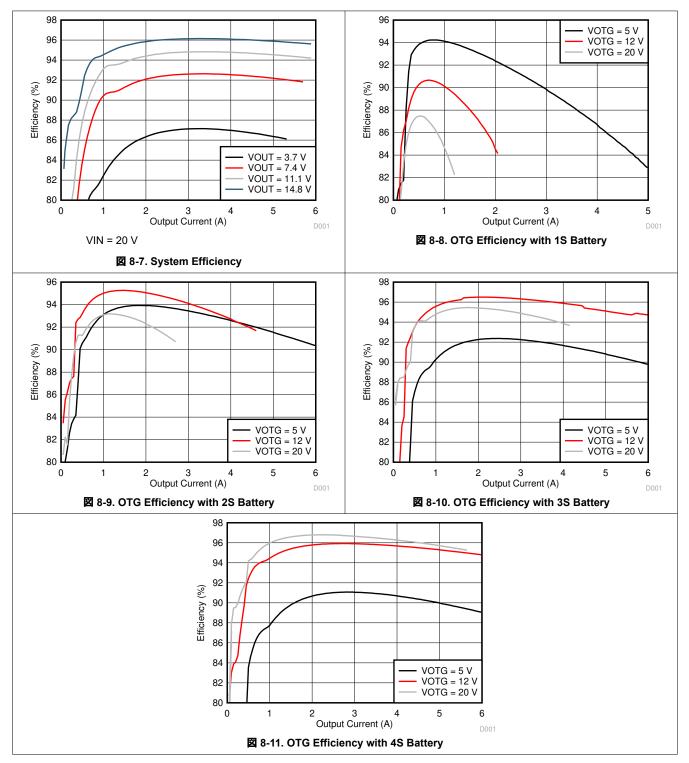


# 8.7 Typical Characteristics





# 8.7 Typical Characteristics (continued)





# 9 Detailed Description

# 9.1 Overview

The BQ25713/BQ25713B is a Narrow VDC buck-boost charger controller for portable electronics such as notebook, detachable, ultrabook, tablet and other mobile devices with rechargeable batteries. It provides seamless transition among different converter operation modes (buck, boost, or buck boost), fast transient response, and high light load efficiency.

BQ25713/BQ25713B supports wide range of power sources, including USB PD ports, legacy USB ports, traditional ACDC adapters, etc. It takes input voltage from 3.5 V to 24 V, and charges battery of 1-4 series. In the absence of an input source, BQ25713/BQ25713B supports USB On-the-Go (OTG) function from 1-4 cell battery to generate adjustable 3 V ~ 20.8 V at USB port with 8mV resolution. The OTG output voltage transition slew rate can be configurable, which complies with the USB Power Delivery 3.0 PPS specifications.

When only the battery powers the system and no external load is connected to the USB OTG port, BQ25713/ BQ25713B provides the Vmin Active Protection (VAP) feature. In the VAP operation, BQ25713/BQ25713B first charges up the voltage of the input decoupling capacitors at VBUS to store a certain amount of energy. During the system peak power spike, the huge current drawn from the battery introduces a larger voltage drop across the impedance from the battery to the system. Then the energy stored in the input capacitors will supplement the system, to prevent the system voltage from drooping below the minimum system voltage and leading the system to black screen. This VAP is designed to absorb system power peaks during the periods of high demand to improve the system turbo performance, which is highly recommended by Intel for the platforms with 1S~2S battery.

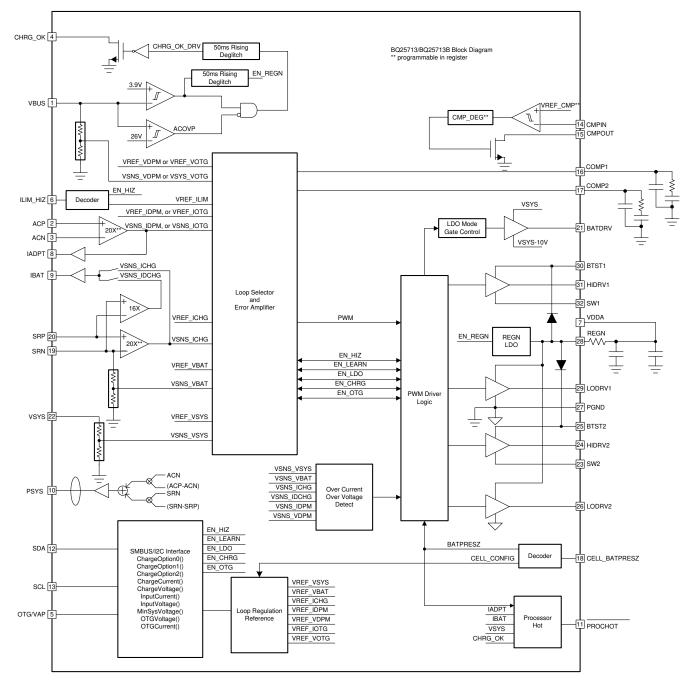
BQ25713/BQ25713B features Dynamic Power Management (DPM) to limit the input power and avoid AC adapter overloading. During battery charging, as the system power increases, the charging current will reduce to maintain total input current below adapter rating. If system power demand temporarily exceeds adapter rating, BQ25713/BQ25713B supports NVDC architecture to allow battery discharge energy to supplement system power. For details, refer to セクション 9.6.5.1.

In order to be compliant with an Intel IMVP8 / IMVP9 compliant system, BQ25713/BQ25713B includes PSYS function to monitor the total platform power from adapter and battery. Besides PSYS, it provides both an independent input current buffer (IADPT) and a battery current buffer (IBAT) with highly accurate current sense amplifiers. If the platform power exceeds the available power from adapter and battery, a PROCHOT signal is asserted to CPU so that the CPU optimizes its performance to the power available to the system.

The I<sup>2</sup>C controls input current, charge current and charge voltage registers with high resolution, high accuracy regulation limits. It also sets the PROCHOT timing and threshold profile to meet system requirements.



# 9.2 Functional Block Diagram





# 9.3 Feature Description

# 9.3.1 Power-Up from Battery Without DC Source

If only battery is present and the voltage is above  $V_{VBAT_UVLOZ}$ , the BATFET turns on and connects battery to system. By default, the charger is in low power mode (REG0x01[7] = 1) with lowest quiescent current. The LDO stays off. When device moves to performance mode (REG0x01[7] = 0), The host can enable IBAT buffer through I<sup>2</sup>C to monitor discharge current. The PSYS, PROCHOT or independent comparator also can be enabled by the host through the I<sup>2</sup>C commands. In performance mode, the REGN LDO is always available to provide an accurate reference for the other features.

# 9.3.2 Vmin Active Protection (VAP) when Battery only Mode

In VAP mode operation, the buck-boost charger delivers the energy from the battery to charge the voltage of the input decoupling capacitors (VBUS) as high as possible (like 20V). The system peak power pulse for a 2S1P or 1S2P system can be as high as 100W if the SoC and motherboard systems spikes coincide. These spikes are expected to be very rare, but possible. During these high power spikes, the charger is expected to supplement the battery (drawing the power from the charger's input decoupling capacitors) to prevent the system voltage from drooping. VAP allows the SoC to set much higher peak power levels to the SoC, thus provides for much better Turbo performance.

Follows the steps below to enter VAP operation.:

- 1. Set the voltage limit to charge VBUS in REG0x07/06().
- 2. Set the current limit to charge VBUS in REG0x09/08() and REG0x39[7:2].
- 3. Set the system voltage regulation point in REG0x0D[5:0], when the input cap supplements battery, the VSYS\_MIN regulation loop will maintain VSYS at this regulation point.
- 4. Set the PROCHOT\_VSYS\_TH1 threshold to trigger the VAP discharging VBUS in REG0x36[7:4].
- 5. Set the PROCHOT\_VSYS\_TH2 threshold to assert /PROCHOT active low signal to throttle SoC in REG0x36[3:2].
- 6. Enable the VAP mode by setting REG0x34[5] = 0, REG0x35[4] = 0, and pulling the OTG/VAP pin to high.

To exit VAP mode, the host should write either REG0x34[5] = 1 or pull low the OTG/VAP pin to low.

Any regular fault conditions of the charger in VAP mode will reset REG0x34[5] = 1, and the charger will exit VAP mode automatically.

# 9.3.3 Power-Up From DC Source

When an input source plugs in, the charger checks the input source voltage to turn on LDO and all the bias circuits. It sets the input current limit before the converter starts.

The power-up sequence from DC source is as follows:

- 1. 50 ms after VBUS above V<sub>VBUS CONVEN</sub>, enable 6 V LDO and CHRG\_OK goes HIGH
- 2. VBUS qualification is executed  $\overline{50}$  ms after VBUS first rises above V<sub>VBUS UVLOZ</sub>. If

 $V_{VBUS}_{UVLOZ}$  < VBUS <  $V_{VBUS}_{CONVEN}$  then charger fails VBUS qualification, and the charger will re-qualify VBUS every 2s.

- 3. Input voltage and current limit setup
- 4. Battery CELL configuration
- 5. 150 ms after VBUS above  $V_{VBUS\_CONVEN}$ , converter powers up.

# 9.3.3.1 CHRG\_OK Indicator

CHRG\_OK is an active HIGH open drain indicator. It indicates the charger is in normal operation when the following conditions are valid:

- VBUS is above V<sub>VBUS\_CONVEN</sub>
- VBUS is below V<sub>ACOV</sub>
- No MOSFET/inductor, or over-voltage, over-current, thermal shutdown fault



#### 9.3.3.2 Input Voltage and Current Limit Setup

After CHRG\_OK goes HIGH, the charger sets default input current limit in REG0x0F/0E() to 3.25 A. The actual input current limit being adopted by the device is the lower setting of REG0x0F/0E() and ILIM\_HIZ pin.

Charger initiates a VBUS voltage measurement without any load (VBUS at no load) right before the converter is enabled. The default VINDPM threshold is VBUS at no load – 1.28 V.

After input current and voltage limits are set, the charger device is ready to power up. The host can always program the input current and voltage limit after the charger being powered up, based on the input source type.

#### 9.3.3.3 Battery Cell Configuration

CELL\_BATPRESZ pin is biased with a resistor divider from REGN to CELL\_BATPRESZ to GND. After VDDA LDO is activated, the device detects the battery configuration through CELL\_BATPRESZ pin bias voltage. Refer to 表 9-1 for cell setting thresholds.

CELL COUNT	PIN VOLTAGE w.r.t. VDDA	BATTERY VOLTAGE (REG0x05/04)	SYSOVP			
4S	75%	16.800 V	19.5 V			
3S	55%	12.592 V	19.5 V			
2S	40%	8.400 V	12 V			
1S	25%	4.192 V	5 V			

#### 表 9-1. Battery Cell Configuration

#### 9.3.3.4 Device Hi-Z State

The charger enters Hi-Z mode when ILIM\_HIZ pin voltage is below 0.4 V or REG0x35[7] is set to 1. During Hi-Z mode, the input source is present, and the charger is in the low quiescent current mode with REGN LDO enabled.

#### 9.3.4 USB On-The-Go (OTG)

The device supports USB OTG operation to deliver power from the battery to other portable devices through USB port. The OTG mode output voltage is set in REG0x07/06(). The OTG mode output current is set in REG0x09/08(). The OTG operation can be enabled if the conditions are valid:

- Valid battery voltage is set REG0x05/04(), the battery voltage should not trip the BATOVP threshold, otherwise, the converter will stop switching.
- OTG output voltage is set in REG0x07/06() and REG0x34[2], if REG0x34[2] = 0, the VOTG digital DAC is
  offset by 1.28V to achieve higher range from 4.28V~20.8V, if REG0x34[2] = 1, the VOTG digital DAC is from
  3V to 19.52V.
- OTG output current is set in REG0x09/08().
- EN\_OTG pin is HIGH, REG0x35[4] = 1 and REG0x34[5] = 1.
- VBUS is below V<sub>VBUS CONVENZ</sub>.
- 10 ms after the above conditions are valid, converter starts and VBUS ramps up to target voltage. CHRG\_OK pin goes HIGH if REG0x01[3] = 1.

#### 9.3.5 Converter Operation

The charger employs a synchronous buck-boost converter that allows charging from a standard 5-V or a high-voltage power source. The charger operates in buck, buck-boost and boost mode. The buck-boost can operate uninterruptedly and continuously across the three operation modes.

MODE	BUCK	BUCK-BOOST	BOOST
Q1	Switching	Switching	ON
Q2	Switching	Switching	OFF
Q3	OFF	Switching	Switching

#### 表 9-2. MOSFET Operation

Copyright © 2023 Texas Instruments Incorporated



#### 表 9-2. MOSFET Operation (continued)

		( )	
MODE	BUCK	BUCK-BOOST	BOOST
Q4	ON	Switching	Switching

#### 9.3.5.1 Inductance Detection Through IADPT Pin

The charger reads the inductance value through the resistance tied to IADPT pin before the converter starts up. The resistances recommended for 1uH, 2.2uH and 3.3uH inductance are  $93k\Omega$ ,  $137k\Omega$  and  $169k\Omega$ , respectively. A surface mount chip resistor with ±3% or better tolerance must to be used for an accurate inductance detection.

表 5-3. Inductor Detection Through IADFT Resistance				
INDUCTOR IN USE RESISTOR ON IADPT PIN				
1 µH	93 kΩ			
2.2 µH	137 κΩ			
3.3 µH	169 kΩ			

#### 表 9-3. Inductor Detection Through IADPT Resistance

#### 9.3.5.2 Continuous Conduction Mode (CCM)

With sufficient charge or system current, the inductor current does not cross 0 A, which is defined as CCM. The controller starts a new cycle with ramp coming up from 200 mV. As long as the error amplifier output voltage is above the ramp voltage, the high-side MOSFET (HSFET) stays on. When the ramp voltage exceeds error amplifier output voltage, HSFET turns off and low-side MOSFET (LSFET) turns on. At the end of the cycle, ramp gets reset and LSFET turns off, ready for the next cycle. There is always break-before-make logic during transition to prevent cross-conduction and shoot-through. During the dead time when both MOSFETs are off, the body-diode of the low-side power MOSFET conducts the inductor current.

During CCM, the inductor current always flows and creates a fixed two-pole system. Having the LSFET turn-on when the HSFET is off keeps the power dissipation low and allows safe charging at high currents.

#### 9.3.5.3 Pulse Frequency Modulation (PFM)

In order to improve converter light-load efficiency, BQ25713/BQ25713B switches to PFM operation at light load. The effective switching frequency will decrease accordingly when system load decreases. The minimum frequency can be limit to 25 kHz when the OOA feature is enabled (ChargeOption0() bit[10]=1).

#### 9.3.6 Current and Power Monitor

# 9.3.6.1 High-Accuracy Current Sense Amplifier (IADPT and IBAT)

As an industry standard, a high-accuracy current sense amplifier (CSA) is used to monitor the charger input current during forward charging mode, or output current during OTG mode (IADPT) and the battery charge/ discharge current (IBAT). IADPT voltage is 20× or 40× the differential voltage across ACP and ACN. IBAT voltage is 8x/16× (during charging), or 8×/16× (during discharging) of the differential across SRP and SRN. After input voltage or battery voltage is above UVLO, IADPT output becomes valid. To lower the voltage on current monitoring, a resistor divider from CSA output to GND can be used and accuracy over temperature can still be achieved.

- V<sub>(IADPT)</sub> = 20 or 40 × (V<sub>(ACP)</sub> V<sub>(ACN)</sub>) during forward mode, or 20 or 40 × (V<sub>(ACN)</sub> V<sub>(ACP)</sub>) during reverse OTG mode.
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRP)} V_{(SRN)})$  for battery charging current.
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRN)} V_{(SRP)})$  for battery discharging current.

A maximum 100-pF capacitor is recommended to connect on the output for decoupling high-frequency noise. An additional RC filter is optional, if additional filtering is desired. Note that adding filtering also adds additional response delay. The CSA output voltage is clamped at 3.3 V.

# 9.3.6.2 High-Accuracy Power Sense Amplifier (PSYS)

The charger monitors total system power. During forward mode, the input adapter powers system. During reverse OTG mode, the battery powers the system and VBUS output. The ratio of PSYS pin output current and



total system power, K<sub>PSYS</sub>, can be programmed in REG0x31[1] with default 1 µA/W. The input and charge sense resistors (RAC and RSR) are selected in REG0x31[3:2]. PSYS voltage can be calculated with  $\neq$  1, where I<sub>IN</sub>>0 I<sub>BAT</sub><0 when the charger is in forward charging with an adapter connected, and I<sub>BAT</sub>>0 when the battery is in discharging mode.

$$V_{PSYS} = R_{PSYS} \times K_{PSYS} (V_{ACP} \times I_{IN} + V_{BAT} \times I_{BAT})$$
<sup>(1)</sup>

For proper PSYS functionality, RAC and RSR values are limited to 10 m $\Omega$  and 20 m $\Omega$ .

To minimize the quiescent current, the PSYS function is disabled by default. It can be enabled by setting REG0x31[4] = 1.

#### 9.3.7 Input Source Dynamic Power Manage

#### Refer to セクション 9.6.6.

#### 9.3.8 Two-Level Adapter Current Limit (Peak Power Mode)

Usually adapter can supply current higher than DC rating for a few milliseconds to tens of milliseconds. The charger employs two-level input current limit, or peak power mode, to fully utilize the overloading capability and minimize battery discharge during CPU turbo mode. Peak power mode is enabled in REG0x33[5:4]. The DC current limit, or  $I_{LIM1}$ , is the same as adapter DC current, set in REG0x0F/0E(). The overloading current, or  $I_{LIM2}$ , is set in REG0x37[7:3], as a percentage of  $I_{LIM1}$ .

When the charger detects input current surge and battery discharge due to load transient (both the adapter and battery support the system together), or when the charger detects the system voltage starts to drop due to load transient (only the adapter supports the system), the charger will first apply  $I_{LIM2}$  for  $T_{OVLD}$  in REG0x33[7:6], and then  $I_{LIM1}$  for up to  $T_{MAX} - T_{OVLD}$  time.  $T_{MAX}$  is programmed in REG0x33[1:0]. After  $T_{MAX}$ , if the load is still high, another peak power cycle starts. Charging is disabled during  $T_{MAX}$ ; once  $T_{MAX}$ , expires, charging continues. If  $T_{OVLD}$  is programmed to be equal to  $T_{MAX}$ , then peak power mode is always on.

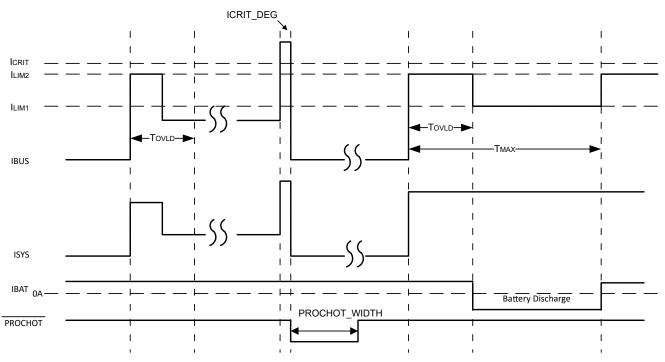


図 9-1. Two-Level Adapter Current Limit Timing Diagram



## 9.3.9 Processor Hot Indication

When CPU is running turbo mode, the system peak power may exceed available power from adapter and battery together. The adapter current and battery discharge peak current, or system voltage drop is an indication that system power is too high. The charger processor hot function monitors these events, and **PROCHOT** pulse is asserted if the system power is too high. Once CPU receives **PROCHOT** pulse from charger, it slows down to reduce system power. The events monitored by the processor hot function includes:

- ICRIT: adapter peak current, as 110% of ILIM2
- INOM: adapter average current (110% of input current limit)
- · IDCHG: battery discharge current
- VSYS: system voltage on VSYS
- Adapter Removal: upon adapter removal (CHRG OK pin HIGH to LOW)
- Battery Removal: upon battery removal (CELL\_BATPRESZ pin goes LOW)
- CMPOUT: Independent comparator output (CMPOUT pin HIGH to LOW)
- VDPM: VBUS lower than 80%/90%/100% of VINDPM threshold.
- EXIT VAP: Every time when the charger exits VAP mode.

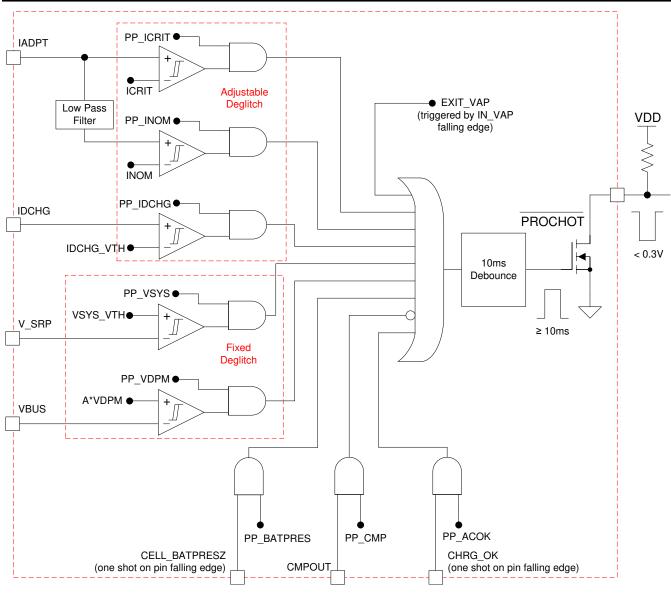
The threshold of ICRIT, IDCHG, VSYS or VDPM, and the deglitch time of ICRIT, INOM, IDCHG or CMPOUT are programmable through I<sup>2</sup>C. Except the PROCHOT\_EXIT\_VAP is always enabled, the other triggering events can be individually enabled in REG0x38[7:0]. When any enabled event in PROCHOT profile is triggered, PROCHOT is asserted low for a single pulse with minimal width programmable in REG0x23[5:4]. At the end of the single pulse, if the PROCHOT event is still active, the pulse gets extended until the event is removed.

If the PROCHOT pulse extension mode is enabled by setting REG0x23[6] = 1, the PROCHOT pin will be kept as low until host writes REG0x23[3]21[11] = 0, even if the triggering event has been removed.

If the PROCHOT\_VDPM or PROCHOT\_EXIT\_VAP is triggered, PROCHOT pin will always stay low until the host clears it, no matter the PROCHOT is in one pulse mod or in extended mode.



BQ25713, BQ25713B JAJSFQ9C – JUNE 2018 – REVISED MAY 2023



# 3 9-2. PROCHOT Profile

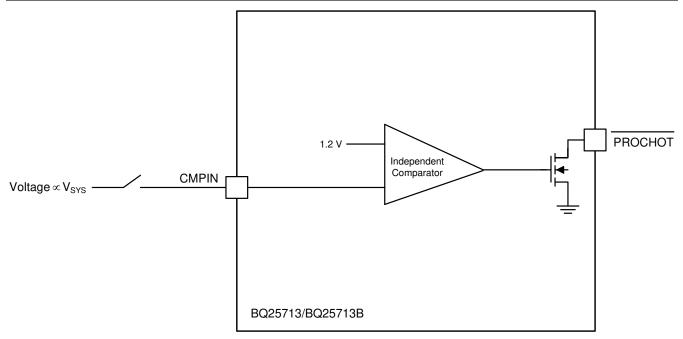
# 9.3.9.1 PROCHOT During Low Power Mode

During low power mode (REG0x01[7] = 1), the charger offers a low power  $\overrightarrow{PROCHOT}$  function with very low quiescent current consumption (~150uA), which uses the independent comparator to monitor the system voltage, and assert  $\overrightarrow{PROCHOT}$  to CPU if the system power is too high.

Below lists the register setting to enable **PROCHOT** monitoring system voltage in low power mode.

- REG0x01[7] = 1 to enable charger low power mode.
- REG0x38[7:0] = 00h
- REG0x30[6:4] = 100
- Independent comparator threshold is always 1.2 V
- When REG0x31[5] = 1, charger monitors system voltage. Connect CMPIN to voltage proportional to system.
   PROCHOT triggers from HIGH to LOW when CMPIN voltage rises above 1.2 V.





**2** 9-3. **PROCHOT** Low Power Mode Implementation

# 9.3.9.2 PROCHOT Status

REG0x22[7:0] and REG0x23[0] reports which event in the profile triggers **PROCHOT** if the corresponding bit is set to 1. The status bit can be reset back to 0 after it is read by host, when the current **PROCHOT** event is not active any more.

Assume there are two **PROCHOT** events, event A and event B. Event A triggers **PROCHOT** first, but event B is also active. Both status bits will be HIGH. At the end of the 10 ms **PROCHOT** pulse, if any of the **PROCHOT** event is still active (either A or B), the **PROCHOT** pulse is extended.

# 9.3.10 Device Protection

# 9.3.10.1 Watchdog Timer

The charger includes watchdog timer to terminate charging if the charger does not receive a write MaxChargeVoltage() or write ChargeCurrent() command within 175 s (adjustable via REG0x01[6:5]). When watchdog timeout occurs, all register values are kept unchanged except ChargeCurrent() resets to zero. Battery charging is suspended. Write MaxChargeVoltage() or write ChargeCurrent() commands must be re-sent to reset watchdog timer and resume charging. Writing REG0x01[6:5] = 00 to disable watchdog timer also resumes charging.

# 9.3.10.2 Input Overvoltage Protection (ACOV)

The charger has fixed ACOV voltage. When VBUS pin voltage is higher than ACOV, it is considered as adapter over voltage. CHRG\_OK will be pulled low, and converter will be disabled. As system falls below battery voltage, BATFET will be turned on. When VBUS pin voltage falls below ACOV, it is considered as adapter voltage returns back to normal voltage. CHRG\_OK is pulled high by external pull up resistor. The converter resumes if enable conditions are valid.

# 9.3.10.3 Input Overcurrent Protection (ACOC)

If the input current exceeds the 1.33× or 2× (REG0x32[2]) of  $I_{LIM2\_VTH}$  (REG0x37[7:3]) set point, converter stops switching. After 300 ms, converter starts switching again.



## 9.3.10.4 System Overvoltage Protection (SYSOVP)

When the converter starts up, BQ25713/BQ25713B reads CELL pin configuration and sets MaxChargeVoltage() and SYSOVP threshold (1s - 5 V, 2s - 12 V, 3s/4s - 19.5 V). Before REGx05/04() is written by the host, the battery configuration will change with CELL pin voltage. When SYSOVP happens, the device latches off the converter. REG0x20[4] is set to 1. The user can clear latch-off by either writing 0 to the SYSOVP bit or removing and plugging in the adapter again. After latch-off is cleared, the converter starts again.

#### 9.3.10.5 Battery Overvoltage Protection (BATOVP)

Battery over-voltage may happen when battery is removed during charging or the user plugs in a wrong battery. The BATOVP threshold is 104% (1 s) or 102% (2 s to 4 s) of regulation voltage set in REG0x05/04().

#### 9.3.10.6 Battery Short

If BAT voltage falls below SYSMIN during charging, the maximum current is limited to 384 mA.

#### 9.3.10.7 System Short Hiccup Mode

VSYS pin is monitoring the system voltage, when Vsys is lower than 2.4V, after 2ms deglitch time, the charger will be shut down for 500ms. The charger will restart for 10ms and measure Vsys again, if it is still lower than 2.4V, the charger will be shut down again. This hiccup mode will be tried continuously, if the charger restart is failed for 7 times in 90 second, the charger will be latched off. REG0x20[3] will be set to 1 to report a system short fault. The charger only can be enabled again once the host writes REG0x20[3]= 0.

The charger system short hiccup mode can be disabled by writing REG0x00[6]= 1.

#### 9.3.10.8 Thermal Shutdown (TSHUT)

The WQFN package has low thermal impedance, which provides good thermal conduction from the silicon to the ambient, to keep junction temperatures low. As added level of protection, the charger converter turns off for self-protection whenever the junction temperature exceeds the 155°C. The charger stays off until the junction temperature falls below 135°C. During thermal shut down, the LDO current limit is reduced to 16 mA and REGN LDO stays off. When the temperature falls below 135°C, charge can be resumed with soft start.

#### 9.4 Device Functional Modes

#### 9.4.1 Forward Mode

When input source is connected to VBUS, BQ25713/BQ25713B is in forward mode to regulate system and charge battery.

#### 9.4.1.1 System Voltage Regulation with Narrow VDC Architecture

BQ25713/BQ25713B employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by MinSystemVoltage(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode).

As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

The BATDRV pin is only able to drive a battery MOSFET with Ciss lower than 5nF. The Ciss in the range of 1nF~3nF is recommended.

See 2222 9.6.5.1 for details on system voltage regulation and register programming.

## 9.4.1.2 Battery Charging

BQ25713/BQ25713B charges 1-4 cell battery in constant current (CC), and constant voltage (CV) mode. Based on CELL\_BATPREZ pin setting, the charger sets default battery voltage 4.2V/cell to ChargeVoltage(), or REG0x05/04(). According to battery capacity, the host programs appropriate charge current to ChargeCurrent(),

Copyright © 2023 Texas Instruments Incorporated



or REG0x03/02(). When battery is full or battery is not in good condition to charge, host terminates charge by setting REG0x00[0] to 1, or setting ChargeCurrent() to zero.

See セクション 9.3 for details on register programming.

## 9.4.2 USB On-The-Go

BQ25713/BQ25713B supports USB OTG functionality to deliver power from the battery to other portable devices through USB port (reverse mode). The OTG output voltage is compliant with USB PD specification, including 5 V, 9 V, 15 V, and 20 V. The output current regulation is compliant with USB type C specification, including 500 mA, 1.5 A, 3 A and 5 A.

Similar to forward operation, the device switches from PWM operation to PFM operation at light load to improve efficiency.

#### 9.4.3 Pass Through Mode (PTM)

When the system is in the sleep mode or light load condition, the charger can be operated in the pass through mode to improve the light load efficiency. In TI patented pass through mode (PTM), the Buck and Boost high side FETs are both turned on, while the Buck and Boost low side FETs are both turned off. The input power is directly passed through the charger to the system. The switching losses of MOSFETs and the inductor core loss are saved.

Device will be transition from normal Buck-Boost operation to PTM operation by:

- Set REG0x32[7] = 0, to disable the EN\_EXITILIM.
- Set REG0x31[0] = 1.
- Set REG0x30[2] = 1.
- Ground ILIM\_HIZ pin.

Device will transition out of PTM mode with host control by:

- Set REG0x30[2] = 0.
- Pull ILIM\_HIZ pin to high.
- Device exits PTM to buck-boost operation if tripping VINDPM.
- · Device exits PTM to buck-boost operation under fault conditions

# 9.5 Programming

The charger supports battery-charger commands that use either Write-Word or Read-Word protocols, as summarized in  $\frac{1}{2}2 = 2$  9.5.1. The I2C address is D6h. The ManufacturerID and DeviceID registers are assigned identify the charger device. The ManufacturerID register command always returns 40h.

#### 9.5.1 I<sup>2</sup>C Serial Interface

The BQ25713/BQ25713B uses I<sup>2</sup>C compatible interface for flexible charging parameter programming and instantaneous device status reporting. I<sup>2</sup>C is a bi-directional 2-wire serial interface. Only two bus lines are required: a serial data line (SDA) and a serial clock line (SCL). Devices can be considered as masters or slaves when performing data transfers. A master is the device which initiates a data transfer on the bus and generates the clock signals to permit that transfer. At that time, any device addressed is considered a slave.

The device operates as a slave device with address D6h, receiving control inputs from the master device like micro controller or a digital signal processor through REG00-REG3A. The I<sup>2</sup>C interface supports both standard mode (up to 100 kbits), and fast mode (up to 400 kbits). connecting to the positive supply voltage via a current source or pull-up resistor. When the bus is free, both lines are HIGH. The SDA and SCL pins are open drain.

#### 9.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock. The HIGH or LOW state of the data line can only change when the clock signal on the SCL line is LOW. One clock pulse is generated for each data bit transferred.



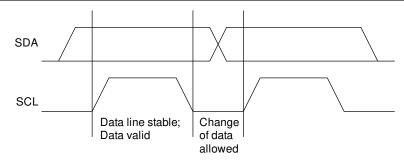
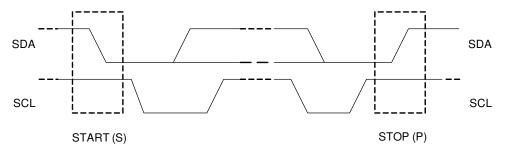


図 9-4. Bit Transfer on the I<sup>2</sup>C Bus

# 9.5.1.2 START and STOP Conditions

All transactions begin with a START (S) and can be terminated by a STOP (P). A HIGH to LOW transition on the SDA line while SCL is HIGH defines a START condition. A LOW to HIGH transition on the SDA line when the SCL is HIGH defines a STOP condition.

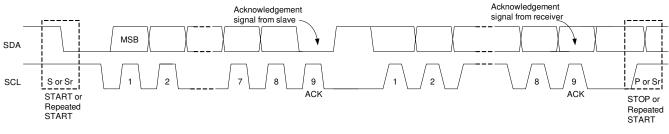
START and STOP conditions are always generated by the master. The bus is considered busy after the START condition, and free after the STOP condition.

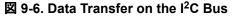


**図** 9-5. START and STOP Conditions

#### 9.5.1.3 Byte Format

Every byte on the SDA line must be 8 bits long. The number of bytes to be transmitted per transfer is unrestricted. Each byte has to be followed by an Acknowledge bit. Data is transferred with the Most Significant Bit (MSB) first. If a slave cannot receive or transmit another complete byte of data until it has performed some other function, it can hold the clock line SCL low to force the master into a wait state (clock stretching). Data transfer then continues when the slave is ready for another byte of data and release the clock line SCL.





# 9.5.1.4 Acknowledge (ACK) and Not Acknowledge (NACK)

The acknowledge takes place after every byte. The acknowledge bit allows the receiver to signal the transmitter that the byte was successfully received and another byte may be sent. All clock pulses, including the acknowledge 9th clock pulse, are generated by the master.

The transmitter releases the SDA line during the acknowledge clock pulse so the receiver can pull the SDA line LOW and it remains stable LOW during the HIGH period of this clock pulse.

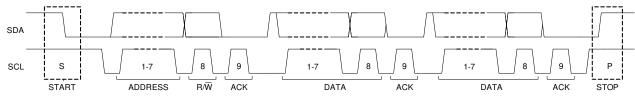
Copyright © 2023 Texas Instruments Incorporated



When SDA remains HIGH during the 9th clock pulse, this is the Not Acknowledge signal. The master can then generate either a STOP to abort the transfer or a repeated START to start a new transfer.

#### 9.5.1.5 Slave Address and Data Direction Bit

After the START, a slave address is sent. This address is 7 bits long followed by the eighth bit as a data direction bit (bit R/W). A zero indicates a transmission (WRITE) and a one indicates a request for data (READ).

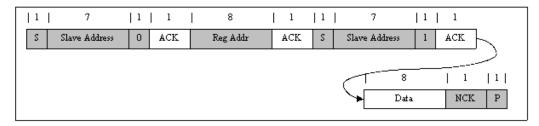


9-7. Complete Data Transfer

# 9.5.1.6 Single Read and Write



# 2 9-8. Single Write

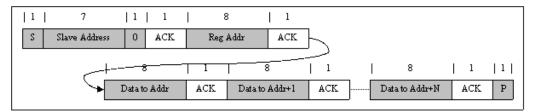


# 図 9-9. Single Read

If the register address is not defined, the charger IC send back NACK and go back to the idle state.

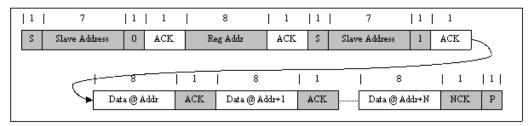
# 9.5.1.7 Multi-Read and Multi-Write

The charger device supports multi-read and multi-write.



#### 図 9-10. Multi Write





🛛 9-11. Multi Read

# 9.5.1.8 Write 2-Byte I<sup>2</sup>C Commands

A few I<sup>2</sup>C commands combine two 8-bit registers together to form a complete value. These commands include:

- ChargeCurrent()
- MaxChargeVoltage()
- IIN\_DPM()
- OTGVoltage()
- InputVoltage()

Host has to write LSB command followed by MSB command. No other command can be inserted in between these two writes. The charger waits for the complete write to the two registers to decide whether to accept or ignore the new value.

After the completion of LSB and MSB bytes, the two bytes will be updated at the same time. If host writes MSB byte first, the command will be ignored. If the time between write of LSB and MSB bytes exceeds watchdog timer, both the LSB and MSB commands will be ignored.

9.6 Register Map	
------------------	--

# 表 9-4. Charger Command Summary

I <sup>2</sup> C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
01/00h	ChargeOption0()	R/W	Charge Option 0	Go
03/02h	ChargeCurrent()	R/W	7-bit charge current setting LSB 64 mA, Range 0 mA – 8128 mA	Go
05/04h	MaxChargeVoltage()	R/W	12-bit charge voltage setting LSB 8 mV, Default: 1S-4200mV, 2S-8400mV, 3S-12600mV, 4S-16800mV	Go
31/30h	ChargeOption1()	R/W	Charge Option 1	Go
33/32h	ChargeOption2()	R/W	Charge Option 2	Go
35/34h	ChargeOption3()	R/W	Charge Option 3	Go
37/36h	ProchotOption0()	R/W	PROCHOT Option 0	Go
39/38h	ProchotOption1()	R/W	PROCHOT Option 1	Go
3B/3Ah	ADCOption()	R/W	ADC Option	Go
21/20h	ChargerStatus()	R	Charger Status	Go
23/22h	ProchotStatus()	R	Prochot Status	Go
25/24h	IIN_DPM()	R	7-bit input current limit in use LSB: 50 mA, Range: 50 mA - 6400 mA	Go
27/26h	ADCVBUS/PSYS()	R	8-bit digital output of input voltage, 8-bit digital output of system power PSYS: Full range: 3.06 V, LSB: 12 mV VBUS: Full range: 3.2 V - 19.52 V, LSB 64 mV	Go
29/28h	ADCIBAT()	R	8-bit digital output of battery charge current, 8-bit digital output of battery discharge current ICHG: Full range 8.128 A, LSB 64 mA IDCHG: Full range: 32.512 A, LSB: 256 mA	Go

Copyright © 2023 Texas Instruments Incorporated



I <sup>2</sup> C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
2B/2Ah	ADCIINCMPIN()	R	8-bit digital output of input current, 8-bit digital output of CMPIN voltage POR State - IIN: Full range: 12.75 A, LSB 50 mA CMPIN: Full range 3.06 V, LSB: 12 mV	Go
2D/2Ch	ADCVSYSVBAT()	R	8-bit digital output of system voltage, 8-bit digital output of battery voltage VSYS: Full range: 2.88 V - 19.2 V, LSB: 64 mV VBAT: Full range : 2.88 V - 19.2 V, LSB 64 mV	Go
07/06h	OTGVoltage()	R/W	12-bit OTG voltage setting LSB 8 mV, Range: 3000 mV – 20800 mV	Go
09/08h	OTGCurrent()	R/W	7-bit OTG output current setting LSB 50 mA, Range: 0 A – 6350 mA	Go
0B/0Ah	InputVoltage()	R/W	8-bit input voltage setting LSB 64 mV, Range: 3200 mV – 19520 mV	Go
0D/0Ch	MinSystemVoltage()	R/W	6-Bit minimum system voltage setting LSB: 256 mV, Range: 1024 mV - 16182 mV Default: 1S-3.584V, 2S-6.144V, 3S-9.216V, 4S-12.288V	Go
0F/0Eh	IIN_HOST()	R/W	6-bit Input current limit set by host LSB: 50-mA, Range: 50 mA - 6400 mA	Go
2Eh	ManufacturerID()	R	Manufacturer ID - 0x0040H	Go
2Fh	DeviceID()	R	Device ID	Go

## 表 9-4. Charger Command Summary (continued)

# 9.6.1 Setting Charge and PROCHOT Options

# 9.6.1.1 ChargeOption0 Register (I<sup>2</sup>C address = 01/00h) [reset = E70Eh]

# 図 9-12. ChargeOption0 Register (I<sup>2</sup>C address = 01/00h) [reset = E70Eh]

7	6	5	4	3	2	1	0
EN_LWPWR	WDTMR_ADJ		IDPM_AUTO_ DISABLE	OTG_ON_ CHRGOK	EN_OOA	PWM_FREQ	PTM_LL_EFF
R/W	R/	W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Reserved	SYS_SHORT DISABLE	EN_LEARN	IADPT_GAIN	IBAT_GAIN	EN_LDO	EN_IDPM	CHRG_INHIBIT
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-5. ChargeOption0 Register (I<sup>2</sup>C address = 01h) Field Descriptions

l <sup>2</sup> C 01h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_LWPWR	R/W	1b	Low Power Mode Enable Ob: Disable Low Power Mode. Device in performance mode with battery only. The PROCHOT, current/power monitor buffer and comparator follow register setting. 1b: Enable Low Power Mode. Device in low power mode with battery only for lowest quiescent current. The LDO is off. The PROCHOT, discharge current monitor buffer, power monitor buffer and independent comparator are disabled. ADC is not available in Low Power Mode.Independent comparator can be enabled by setting either REG0X31()[6] or [5] to 1. <default at="" por=""></default>
6-5	WDTMR_ADJ	R/W	11b	WATCHDOG Timer Adjust Set maximum delay between consecutive I <sup>2</sup> C write of charge voltage or charge current command. If device does not receive a write on the REG0x05/04() or the REG0x03/02() within the watchdog time period, the charger will be suspended by setting the REG0x03/02() to 0 mA. After expiration, the timer will resume upon the write of REG0x03/02(), REG0x05/04() or REG0x01[6:5]. The charger will resume if the values are valid. 00b: Disable Watchdog Timer 01b: Enabled, 5 sec 10b: Enabled, 88 sec 11b: Enable Watchdog Timer, 175 sec <default at="" por=""></default>
4	IDPM_AUTO_ DISABLE	R/W	ОЬ	IDPM Auto Disable When CELL_BATPRESZ pin is LOW, the charger automatically disables the IDPM function by setting EN_IDPM (REG0x00[1]) to 0. The host can enable IDPM function later by writing EN_IDPM bit (REG0x00[1]) to 1. 0b: Disable this function. IDPM is not disabled when CELL_BATPRESZ goes LOW. <default at="" por=""> 1b: Enable this function. IDPM is disabled when CELL_BATPRESZ goes LOW.</default>
3	OTG_ON_ CHRGOK	R/W	Ob	Add OTG to CHRG_OK Drive CHRG_OK to HIGH when the device is in OTG mode. 0b: Disable <default at="" por=""> 1b: Enable</default>



# 表 9-5. ChargeOption0 Register (I<sup>2</sup>C address = 01h) Field Descriptions (continued)

l <sup>2</sup> C 01h	FIELD	TYPE	RESET	DESCRIPTION
2	EN_OOA	R/W	1b	Out-of-Audio Enable 0b: No limit of PFM burst frequency 1b: Set minimum PFM burst frequency to above 25 kHz to avoid audio noise <default at="" por=""></default>
1	PWM_FREQ	R/W	1b	Switching Frequency Two converter switching frequencies. One for small inductor and the other for big inductor. Recommend 800 kHz with 2.2 µH or 3.3 µH, and 1.2 MHz with 1 µH or 1.5 µH. Host has to set the right PWM frequency after device POR. 0b: 1200 kHz 1b: 800 kHz <default at="" por=""></default>
0	LOW_PTM_ RIPPLE	R/W	1b	PTM mode input voltage and current ripple reduction 0b: Disable 1b: Enable <default at="" por=""></default>

# 表 9-6. ChargeOption0 Register (I<sup>2</sup>C address = 00h) Field Descriptions

l <sup>2</sup> C 00h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Reserved	R/W	0b	Reserved
6	SYS_SHORT_DISABLE	R/W	ОЬ	To disable the hiccup mode during the system short protection. 0b: When VSYS is short to lower than 2.4V, the charger enters hiccup mode <default at="" por=""> 1b: The charger hiccup mode is disabled during system short fault</default>
5	EN_LEARN	R/W	Ob	LEARN function allows the battery to discharge while the adapter is present. It calibrates the battery gas gauge over a complete discharge/charge cycle. When the battery voltage is below battery depletion threshold, the system switches back to adapter input by the host. When CELL_BATPRESZ pin is LOW, the device exits LEARN mode and this bit is set back to 0. 0b: Disable LEARN Mode <default at="" por=""> 1b: Enable LEARN Mode</default>
4	IADPT_GAIN	R/W	ОЬ	IADPT Amplifier Ratio The ratio of voltage on IADPT and voltage across ACP and ACN. 0b: 20× <default at="" por=""> 1b: 40×</default>
3	IBAT_GAIN	R/W	1b	IBAT Amplifier Ratio The ratio of voltage on IBAT and voltage across SRP and SRN 0b: 8× 1b: 16× <default at="" por=""></default>
2	EN_LDO	R/W	1b	LDO Mode Enable When battery voltage is below minimum system voltage (REG0x0D/0C()), the charger is in precharge with LDO mode enabled. 0b: Disable LDO mode, BATFET fully ON. Precharge current is set by battery pack internal resistor. The system is regulated by the MaxChargeVoltage register. 1b: Enable LDO mode, Precharge current is set by the ChargeCurrent register and clamped below 384 mA (2 cell – 4 cell) or 2A (1 cell). The system is regulated by the MinSystemVoltage register. <a href="https://www.default.com">default</a> at POR>



## 表 9-6. ChargeOption0 Register (I<sup>2</sup>C address = 00h) Field Descriptions (continued)

l <sup>2</sup> C 00h	FIELD	TYPE	RESET	DESCRIPTION
1	EN_IDPM	R/W	1b	IDPM Enable Host writes this bit to enable IDPM regulation loop. When the IDPM is disabled by the charger (refer to IDPM_AUTO_DISABLE), this bit goes LOW. 0b: IDPM disabled 1b: IDPM enabled <default at="" por=""></default>
0	CHRG_INHIBIT	R/W	0b	Charge Inhibit When this bit is 0, battery charging will start with valid values in the MaxChargeVoltage register and the ChargeCurrent register. 0b: Enable Charge <default at="" por=""> 1b: Inhibit Charge</default>



# 9.6.1.2 ChargeOption1 Register (I<sup>2</sup>C address = 31/30h) [reset = 0211h]

g 9-13. ChargeOption1 Register (I <sup>2</sup> C address = 31/30n) [reset = 0211n]									
7	6	5	4	3	2	1	0		
EN_IBAT	EN_PROCH	HOT_LPWR	EN_PSYS	RSNS_RAC	RSNS_RSR	PSYS_RATIO	PTM_PINSEL		
R/W	R/	V R/W		R/W	R/W	R/W	R/W		
7	6	5	4	3	2	1	0		
CMP_REF	CMP_POL	CMP_	_DEG	FORCE_ LATCHOFF	EN_PTM	EN_SHIP_ DCHG	AUTO_ WAKEUP_EN		
R/W	R/W	R/	W	R/W	R/W	R/W	R/W		

# 図 9-13. ChargeOption1 Register (I<sup>2</sup>C address = 31/30h) [reset = 0211h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-7. ChargeOption1 Register (I<sup>2</sup>C address = 31h) Field Descriptions

l <sup>2</sup> C 31h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_IBAT	R/W	Ob	IBAT Enable Enable the IBAT output buffer. In low power mode (REG0x01[7] = 1), IBAT buffer is always disabled regardless of this bit value. 0b Turn off IBAT buffer to minimize Iq <default at="" por=""> 1b: Turn on IBAT buffer</default>
6-5	EN_PROCHOT _LPWR	R/W	00Ь	Enable PROCHOT during battery only low power mode With battery only, enable VSYS in PROCHOT with low power consumption. Do not enable this function with adapter present. Refer to セクション 9.3.9.1 for more details. 00b: Disable low power PROCHOT <default at="" por=""> 01b: Enable VSYS low power PROCHOT 10b: Reserved 11b: Reserved</default>
4	EN_PSYS	R/W	ОЬ	PSYS Enable Enable PSYS sensing circuit and output buffer (whole PSYS circuit). In low power mode (REG0x01[7] = 1), PSYS sensing and buffer are always disabled regardless of this bit value. 0b: Turn off PSYS buffer to minimize Iq <default at="" por=""> 1b: Turn on PSYS buffer</default>
3	RSNS_RAC	R/W	Ob	Input sense resistor RAC 0b: 10 m $\Omega$ <default at="" por=""> 1b: 20 m<math>\Omega</math></default>
2	RSNS_RSR	R/W	Ob	Charge sense resistor RSR 0b: 10 mΩ <default at="" por=""> 1b: 20 mΩ</default>
1	PSYS_RATIO	R/W	1b	PSYS Gain Ratio of PSYS output current vs total input and battery power with 10-mΩ sense resistor. 0b: 0.25 μA/W 1b: 1 μA/W <default at="" por=""></default>
0	PTM_PINSEL	R/W	Ob	Select the ILIM_HIZ pin function 0b: charger enters HIZ mode when pull low the ILIM_HIZ pin. <default at="" por=""> 1b: charger enters PTM when pull low the ILIM_HIZ pin.</default>



120	$\overline{\mathbf{x}}$ 9-8. ChargeOption1 Register (I <sup>2</sup> C address = 30h) Field Descriptions							
l <sup>2</sup> C 30h	FIELD	TYPE	RESET	DESCRIPTION				
7	CMP_REF	R/W	0b	Independent Comparator Internal Reference. 0b: 2.3 V <default at="" por=""> 1b: 1.2 V</default>				
6	CMP_POL	R/W	Ob	Independent Comparator Output Polarity 0b: When CMPIN is above internal threshold, CMPOUT is LOW (internal hysteresis) <default at="" por=""> 1b: When CMPIN is below internal threshold, CMPOUT is LOW (external hysteresis)</default>				
5-4	CMP_DEG	R/W	01b	Independent Comparator Deglitch Time, only applied to the falling edge of CMPOUT (HIGH $\rightarrow$ LOW). 00b: Independent comparator is disabled 01b: Independent comparator is enabled with output deglitch time 1 µs <default at POR&gt; 10b: Independent comparator is enabled with output deglitch time of 2 ms 11b: Independent comparator is enabled with output deglitch time of 5 sec</default 				
3	FORCE_LATCHOFF	R/W	Ob	Force Power Path Off When independent comparator triggers, charger turns off Q1 and Q4 (same as disable converter) so that the system is disconnected from the input source. At the same time, CHRG_OK signal goes to LOW to notify the system. 0b: Disable this function <default at="" por=""> 1b: Enable this function</default>				
2	EN_PTM	R/W	0b	PTM enable register bit 0b: disable PTM. <default at="" por=""> 1b: enable PTM.</default>				
1	EN_SHIP_DCHG	R/W	Ob	Discharge SRN for Shipping Mode When this bit is 1, discharge SRN pin down below 3.8 V in 140 ms. When 140 ms is over, this bit is reset to 0. 0b: Disable shipping mode <default at="" por=""> 1b: Enable shipping mode</default>				
0	AUTO_WAKEUP_EN	R/W	1b	Auto Wakeup Enable When this bit is HIGH, if the battery is below minimum system voltage (REG0x0D/0C()), the device will automatically enable 128 mA charging current for 30 mins. When the battery is charged up above minimum system voltage, charge will terminate and the bit is reset to LOW. 0b: Disable 1b: Enable <default at="" por=""></default>				

# 表 9-8. ChargeOption1 Register (I<sup>2</sup>C address = 30h) Field Descriptions

# 9.6.1.3 ChargeOption2 Register (I<sup>2</sup>C address = 33/32h) [reset = 02B7h]

	<b>–</b> • • • • •					•==•••	
7	6	5	4	3	2	1	0
PKPWR_TOVLD_DEG		EN_PKPWR_ IDPM	EN_PKPWR_ VSYS	PKPWR_ OVLD_STAT	PKPWR_ RELAX_STAT	PKPWR_	TMAX[1:0]
R/W		R/W	R/W	R/W	R/W	R	W
7	6	5	4	3	2	1	0
EN_EXTILIM	EN_ICHG _IDCHG	Q2_OCP	ACX_OCP	EN_ACOC	ACOC_VTH	EN_	_VTH
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

## 図 9-14. ChargeOption2 Register (I<sup>2</sup>C address = 33/32h) [reset = 02B7h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-9. ChargeOption2 Register (I<sup>2</sup>C address = 33h) Field Descriptions

l <sup>2</sup> C 33h	FIELD	TYPE	RESET	DESCRIPTION
7-6	PKPWR_ TOVLD_DEG	R/W	00Ь	Input Overload time in Peak Power Mode 00b: 1 ms <default at="" por=""> 01b: 2 ms 10b: 10 ms 11b: 20 ms</default>
5	EN_PKPWR_IDPM	R/W	Ob	Enable Peak Power Mode triggered by input current overshoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapter removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by input current overshoot <default at="" por=""> 1b: Enable peak power mode triggered by input current overshoot.</default>
4	EN_PKPWR_VSYS	R/W	Ob	Enable Peak Power Mode triggered by system voltage under-shoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapter removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by system voltage under-shoot <default at="" por=""> 1b: Enable peak power mode triggered by system voltage under-shoot.</default>
3	PKPWR_ OVLD_STAT	R/W	Ob	Indicator that the device is in overloading cycle. Write 0 to get out of overloading cycle. 0b: Not in peak power mode. <default at="" por=""> 1b: In peak power mode.</default>
2	PKPWR_ RELAX_STAT	R/W	Ob	Indicator that the device is in relaxation cycle. Write 0 to get out of relaxation cycle. 0b: Not in relaxation cycle. <default at="" por=""> 1b: In relaxation mode.</default>
1-0	PKPWR_ TMAX[1:0]	R/W	10ь	Peak power mode overload and relax cycle time. When REG0x33[7:6] is programmed longer than REG0x33[1:0], there is no relax time. 00b: 5 ms 01b: 10 ms 10b: 20 ms <default at="" por=""> 11b: 40 ms</default>



# 表 9-10. ChargeOption2 Register (I<sup>2</sup>C address = 32h) Field Descriptions

l <sup>2</sup> C 32h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	EN_EXTILIM	R/W	1b	Enable ILIM_HIZ pin to set input current limit 0b: Input current limit is set by REG0x0F/0E. 1b: Input current limit is set by the lower value of ILIM_HIZ pin and REG0x0F/0E. <default at="" por=""></default>
6	EN_ICHG _IDCHG	R/W	0b	0b: IBAT pin as discharge current. <default at="" por=""> 1b: IBAT pin as charge current.</default>
5	Q2_OCP	R/W	1b	Q2 OCP threshold by sensing Q2 VDS 0b: 210 mV 1b: 150 mV <default at="" por=""></default>
4	ACX_OCP	R/W	1b	Input current OCP threshold by sensing ACP-ACN. 0b: 280 mV 1b: 150 mV <default at="" por=""></default>
3	EN_ACOC	R/W	ОЬ	ACOC Enable Input overcurrent (ACOC) protection by sensing the voltage across ACP and ACN. Upon ACOC (after 100-µs blank-out time), converter is disabled. 0b: Disable ACOC <default at="" por=""> 1b: ACOC threshold 133% or 200% ILIM2</default>
2	ACOC_VTH	R/W	1b	ACOC Limit Set MOSFET OCP threshold as percentage of IDPM with current sensed from R <sub>AC.</sub> 0b: 133% of ILIM2 1b: 200% of ILIM2 <default at="" por=""></default>
1	EN_BATOC	R/W	1b	BATOC Enable Battery discharge overcurrent (BATOC) protection by sensing the voltage across SRN and SRP. Upon BATOC, converter is disabled. 0b: Disable BATOC 1b: BATOC threshold 133% or 200% PROCHOT IDCHG <default at<br="">POR&gt;</default>
0	BATOC_VTH	R/W	1b	Set battery discharge overcurrent threshold as percentage of PROCHOT battery discharge current limit. 0b: 133% of PROCHOT IDCHG 1b: 200% of PROCHOT IDCHG <default at="" por=""></default>

# 9.6.1.4 ChargeOption3 Register (I<sup>2</sup>C address = 35/34h) [reset = 0030h]

		sindi gooption		e uuui ooo						
7	6	5	4	3	2	1	0			
EN_HIZ	RESET_REG	RESET_ VINDPM	EN_OTG	EN_ICO MODE		Reserved				
R/W	R/W	R/W	R/W	R/W		R/W				
7	6	5	4	3	2	1	0			
Reserved	EN_CONS VAP	OTG_VAP _MODE	IL_AVG		OTG_RANGE _LOW	BATFETOFF_ HIZ	PSYS_OTG_ IDCHG			
R/W	R/W	R/W	R	/W	R/W	R/W	R/W			

## 図 9-15. ChargeOption3 Register (I<sup>2</sup>C address = 35/34h) [reset = 0030h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-11. ChargeOption3 Register (I<sup>2</sup>C address = 35h) Field Descriptions

l <sup>2</sup> C 35h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_HIZ	R/W	Ob	Device Hi-Z Mode Enable When the charger is in Hi-Z mode, the device draws minimal quiescent current. With VBUS above UVLO. REGN LDO stays on, and system powers from battery. 0b: Device not in Hi-Z mode <default at="" por=""> 1b: Device in Hi-Z mode</default>
6	RESET_REG	R/W	Ob	Reset Registers         All the registers go back to the default setting except the VINDPM register.         VSYS_MIN will always go back to 1S default setting (3.584V), and the charging voltage goes back to the default values according to the cell pin setting.         0b: Idle <default at="" por="">         1b: Reset all the registers to default values. After reset, this bit goes back to 0.         When the battery voltage is lower than minimal system voltage, or the battery is removed, it is NOT recommended to use this bit to reset the registers to default values.</default>
5	RESET_VINDPM	R/W	0b	Reset VINDPM Threshold 0b: Idle 1b: Converter is disabled to measure VINDPM threshold. After VINDPM measurement is done, this bit goes back to 0 and converter starts.
4	EN_OTG	R/W	Ob	OTG Mode Enable Enable device in OTG mode when EN_OTG pin is HIGH. 0b: Disable OTG <default at="" por=""> 1b: Enable OTG mode to supply VBUS from battery.</default>
3	EN_ICO_MODE	R/W	Ob	Enable ICO Algorithm 0b: Disable ICO algorithm. <default at="" por=""> 1b: Enable ICO algorithm.</default>
2-0	Reserved	R/W	0b	Reserved

### 表 9-12. ChargeOption3 Register (I<sup>2</sup>C address = 34h) Field Descriptions

l <sup>2</sup> C 34h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Reserved	R/W	0b	Reserved

# 表 9-12. ChargeOption3 Register (I<sup>2</sup>C address = 34h) Field Descriptions (continued)

l <sup>2</sup> C 34h	FIELD	ТҮРЕ	RESET	DESCRIPTION
6	EN_CON_VAP	R/W	Ob	Enable the conservative VAP mode. 0b: Disabled <default at="" por=""> 1b: Enabled</default>
5	OTG_VAP_MODE	R/W	1b       The selection of the external OTG/VAP pin control.         0b: the external OTG/VAP pin controls the EN/DIS VAP mode         1b: the external OTG/VAP pin controls the EN/DIS OTG mode <de< td="">         POR&gt;</de<>	
4-3	IL_AVG	R/W	10b	4 levels inductor average current clamp. 00b: 6A 01b: 10A 10b: 15A <default at="" por=""> 11b: Disabled</default>
2	OTG_RANGE_LOW	R/W	Ob	Selection of the different OTG output voltage range. 0b: VOTG high range 4.28 V - 20.8 V <default at="" por=""> 1b: VOTG low range 3 V - 19.52 V</default>
1	BATFETOFF_ HIZ	R/W	Ob	Control BATFET during HIZ mode. 0b: BATFET on during Hi-Z <default at="" por=""> 1b: BATFET off during Hi-Z</default>
0	PSYS_OTG_ IDCHG	R/W	Ob	PSYS function during OTG mode. 0b: PSYS as battery discharge power minus OTG output power <default at POR&gt; 1b: PSYS as battery discharge power only</default 

# 9.6.1.5 ProchotOption0 Register (I<sup>2</sup>C address = 37/36h) [reset = 4A65h]

## 図 9-16. ProchotOption0 Register (I<sup>2</sup>C address = 37/36h) [reset = 4A65h]

		<i>.</i>	
7-3	2-1	0	
ILIM2_VTH	ICRIT_DEG	PROCHOT_ VDPM_80_90	
R/W	R/W	R/W	
7-4	3-2	1	0
VSYS_TH1	VSYS_TH2	INOM_DE	EG LOWER_ PROCHOT _VDPM
R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-13. ProchotOption0 Register (I<sup>2</sup>C address = 37h) Field Descriptions

l <sup>2</sup> C 37h	FIELD	TYPE	RESET	DESCRIPTION
7-3	ILIM2_VTH	R/W	01001b	I <sub>LIM2</sub> Threshold 5 bits, percentage of IDPM in 0x0F/0EH. Measure current between ACP and ACN. Trigger when the current is above this threshold: 00001b - 11001b: 110% - 230%, step 5% 11010b - 11110b: 250% - 450%, step 50% 11111b: Out of Range (Ignored) Default 150%, or 01001
2-1	ICRIT_DEG	R/W	01b	ICRIT Deglitch time ICRIT is set to be 110% of <sub>ILIM2</sub> . Typical ICRIT deglitch time to trigger PROCHOT. 00b: 15 μs 01b: 120 μs <default at="" por=""> 10b: 500 μs 11b: 1 ms</default>
0	PROCHOT_ VDPM_80_90	R/W	Ob	Lower threshold of the PROCHOT_VDPM comparator When REG0x36[0]=1, the threshold of the PROCHOT_VDPM comparator is determined by this bit setting. 0b: 80% of VinDPM threshold <default at="" por="">. 1b: 90% of VinDPM threshold</default>

## 表 9-14. ProchotOption0 Register (I<sup>2</sup>C address = 36h) Field Descriptions

l <sup>2</sup> C 36h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-4	VSYS_TH1	R/W	0110b	VSYS Threshold to trigger discharging VBUS in VAP mode. Measure on VSYS with fixed 5-µs deglitch time. Trigger when SYS pin voltage is below the thresholds. 2S - 4S battery 0000b - 1111b: 5.9 V - 7.4V with 0.1 V step size. 1S battery 0000b - 0111b: 3.1 V - 3.8 V with 0.1 V step size. 1000b - 1111b: 3.1 V - 3.8 V with 0.1 V step size.

# 表 9-14. ProchotOption0 Register (I<sup>2</sup>C address = 36h) Field Descriptions (continued)

l <sup>2</sup> C 36h	FIELD	TYPE	RESET	DESCRIPTION
3-2	VSYS_TH2	R/W	01Ь	VSYS Threshold to assert /PROCHOT_VSYS. Measure on VSYS with fixed 5-µs deglitch time. Trigger when SYS pin voltage is below the thresholds. 2S - 4S battery 00b: 5.9V; 01b: 6.2V <default at="" por="">; 10b: 6.5V; 11b: 6.8V. 1S battery 00b: 3.1V; 01b: 3.3V <default at="" por="">; 10b: 3.5V; 11b: 3.7V.</default></default>
1	INOM_DEG	R/W	Ob	INOM Deglitch Time INOM is always 10% above IDPM in 0x0F/0EH. Measure current between ACP and ACN. Trigger when the current is above this threshold. 0b: 1 ms <default at="" por=""> 1b: 50 ms</default>
0	LOWER_ PROCHOT _VDPM	R/W	1b	Enable the lower threshold of the PROCHOT_VDPM comparator 0b: the threshold of the PROCHOT_VDPM comparator follows the same VinDPM REG0x0A/0B() setting. 1b: the threshold of the PROCHOT_VDPM comparator is lower and determined by REG0x37[0] setting. <default at="" por=""></default>

## 9.6.1.6 ProchotOption1 Register (I<sup>2</sup>C address = 39/38h) [reset = 81A0h]

# ☑ 9-17. ProchotOption1 Register (I<sup>2</sup>C address = 39/38h) [reset = 81A0h]

						-	
		1-0					
		IDCHG_DEG					
		R/	W				
7	6	5	4	3	2	1	0
PP_VDPM	PROCHOT_PR OFILE_IC	PP_ICRIT	PP_INOM	PP_IDCHG	PP_VSYS	PP_BATPRES	PP_ACOK
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

When the REG0x38[7:0] are set to be disabled, the PROCHOT event associated with that bit will not be reported in the PROCHOT status register REG0x22[7:0] any more, and the PROCHOT pin will not be pulled low any more if the event happens.

表 9-15. ProchotOption1 Register (I<sup>2</sup>C address = 39h) Field Descriptions

l <sup>2</sup> C 39h	FIELD	TYPE	RESET	DESCRIPTION
7-2	IDCHG_VTH	R/W	100000Ь	IDCHG Threshold 6 bit, range, range 0 A to 32256 mA, step 512 mA. There is a 128 mA offset. Measure current between SRN and SRP. Trigger when the discharge current is above the threshold. If the value is programmed to 000000b, PROCHOT is always triggered. Default: 16384 mA or 100000b
1-0	IDCHG_DEG	R/W	01b	Typical IDCHG Deglitch Time 00b: 2 ms 01b: 130 μs <default at="" por=""> 10b: 8 ms 11b: 16 ms</default>

#### 表 9-16. ProchotOption1 Register (I<sup>2</sup>C address = 38h) Field Descriptions

l <sup>2</sup> C 38h	FIELD	TYPE	RESET	DESCRIPTION
7	PROCHOT _PROFILE_VDPM	R/W	1b	PROCHOT Profile         When all the REG0x38[7:0] bits are 0, PROCHOT function is disabled.         Bit7 PP_VDPM detects VBUS voltage         0b: disable         1b: enable <default at="" por=""></default>
6	PROCHOT _PROFILE_COMP	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>
5	PROCHOT _PROFILE_ICRIT	R/W	1b	0b: disable 1b: enable <default at="" por=""></default>
4	PROCHOT _PROFILE_INOM	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>
3	PROCHOT _PROFILE_IDCHG	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>
2	PROCHOT _PROFILE_VSYS	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>



# 表 9-16. ProchotOption1 Register (I<sup>2</sup>C address = 38h) Field Descriptions (continued)

l <sup>2</sup> C 38h	FIELD	TYPE	RESET	DESCRIPTION
1	PROCHOT _PROFILE_BATPRES	R/W	Ob	0b: disable <default at="" por=""> 1b: enable (one-shot falling edge triggered) If BATPRES is enabled in PROCHOT after the battery is removed, it will immediately send out one-shot PROCHOT pulse.</default>
0	PROCHOT _PROFILE_ACOK	R/W	Ob	0b: disable <default at="" por=""> 1b: enable ChargeOption0[15] = 0 to assert PROCHOT pulse after adapter removal. If PROCHOT_PROFILE_ACOK is enabled in PROCHOT after the adapter is removed, it will be pulled low.</default>

## 9.6.1.7 ADCOption Register (*I*<sup>2</sup>C address = 3B/3Ah) [reset = 2000h]

7	6	5			4-0		
ADC_CONV	ADC_START	ADC_ FULLSCALE			Reserved		
R/W	R/W	R/W			R/W		
7	6	5	4	3	2	1	0
EN_ADC_ CMPIN	EN_ADC_ VBUS	EN_ADC_ PSYS	EN_ADC_ IIN	EN_ADC_ IDCHG	EN_ADC_ ICHG	EN_ADC_ VSYS	EN_ADC_ VBAT
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

The ADC registers are read in the following order: VBAT, VSYS, ICHG, IDCHG, IIN, PSYS, VBUS, CMPIN. ADC is disabled in low power mode. When enabling ADC, the device exit low power mode at battery only.

l <sup>2</sup> C 3Bh	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	ADC_CONV	R/W	Ob	Typical ADC conversion time is 10 ms. 0b: One-shot update. Do one set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() after ADC_START = 1. 1b: Continuous update. Do a set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() every 1 sec.
6	ADC_START	R/W	Ob	0b: No ADC conversion 1b: Start ADC conversion. After the one-shot update is complete, this bit automatically resets to zero
5	ADC_ FULLSCALE	R/W	1b	ADC input voltage range. When input voltage is below 5 V, or battery is 1S, full scale 2.04 V is recommended. 0b: 2.04 V 1b: 3.06 V <default at="" por=""></default>
4-0	Reserved	R/W	00000b	Reserved

## 表 9-17. ADCOption Register (I<sup>2</sup>C address = 3Bh) Field Descriptions

表 9-18. ADCOption Register (I <sup>2</sup> C address = 3Ah) Field Descriptions	s
	•

l <sup>2</sup> C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
7	EN_ADC_CMPIN	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
6	EN_ADC_VBUS	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
5	EN_ADC_PSYS	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
4	EN_ADC_IIN	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
3	EN_ADC_IDCHG	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
2	EN_ADC_ICHG	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>



# 表 9-18. ADCOption Register (I<sup>2</sup>C address = 3Ah) Field Descriptions (continued)

l <sup>2</sup> C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
1	EN_ADC_VSYS	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
0	EN_ADC_VBAT	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>



## 9.6.2 Charge and PROCHOT Status

# 9.6.2.1 ChargerStatus Register (I<sup>2</sup>C address = 21/20h) [reset = 0000h]

#### 図 9-19. ChargerStatus Register (I<sup>2</sup>C address = 21/20h) [reset = 0000h]

7	6	5	4	3	2	1	0
AC_STAT	ICO_DONE	IN_VAP	IN_VINDPM	IN_IINDPM	IN_FCHRG	IN_PCHRG	IN_OTG
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Fault ACOV	Fault BATOC	Fault ACOC	SYSOVP _STAT	Fault SYS _SHORT	Fault Latchoff	Fault_OTG _OVP	Fault_OTG _OCP
R	R	R	R/W	R/W	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-19. ChargerStatus Register (I<sup>2</sup>C address = 21h) Field Descriptions

l <sup>2</sup> C 21h	FIELD	TYPE	RESET	DESCRIPTION
7	AC_STAT	R	Ob	Input source status, same as CHRG_OK bit 0b: Input not present 1b: Input is present
6	ICO_DONE	R	Ob	After the ICO routine is successfully executed, the bit goes 1. 0b: ICO is not complete 1b: ICO is complete
5	IN_VAP	R	0b	0b: Charger is not operated in VAP mode 1b: Charger is operated in VAP mode
4	IN_VINDPM	R	Ob	0b: Charger is not in VINDPM during forward mode, or voltage regulation during OTG mode 1b: Charger is in VINDPM during forward mode, or voltage regulation during OTG mode
3	IN_IINDPM	R	0b	0b: Charger is not in IINDPM 1b: Charger is in IINDPM
2	IN_FCHRG	R	0b	0b: Charger is not in fast charge 1b: Charger is in fast charger
1	IN_PCHRG	R	0b	0b: Charger is not in precharge 1b: Charger is in precharge
0	IN_OTG	R	0b	0b: Charger is not in OTG 1b: Charge is in OTG

# 表 9-20. ChargerStatus Register (I<sup>2</sup>C address = 20h) Field Descriptions

l <sup>2</sup> C 20h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Fault ACOV	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: ACOV
6	Fault BATOC	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: BATOC
5	Fault ACOC	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: ACOC



# 表 9-20. ChargerStatus Register (I<sup>2</sup>C address = 20h) Field Descriptions (continued)

l <sup>2</sup> C 20h	FIELD	ТҮРЕ	RESET	DESCRIPTION
4	SYSOVP_STAT	R/W	0b	SYSOVP Status and Clear When the SYSOVP occurs, this bit is HIGH. During the SYSOVP, the converter is disabled. After the SYSOVP is removed, the user must write a 0 to this bit or unplug the adapter to clear the SYSOVP condition to enable the converter again. 0b: Not in SYSOVP <default at="" por=""> 1b: In SYSOVP. When SYSOVP is removed, write 0 to clear the SYSOVP latch.</default>
3	Fault SYS_SHORT	R/W	Ob	The fault is latched until a clear from host by writing this bit to 0. 0b: No fault <default at="" por=""> 1b: When SYS is lower than 2.4V, then 7 times restart tries are failed.</default>
2	Fault Latchoff	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: Latch off (REG0x30[3])
1	Fault_OTG_OVP	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: OTG OVP
0	Fault_OTG_UVP	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: OTG UVP



# 9.6.2.2 ProchotStatus Register (I<sup>2</sup>C address = 23/22h) [reset = A800h]

# 図 9-20. ProchotStatus Register (I<sup>2</sup>C address = 23/22h) [reset = A800h]

			<b>U</b> (		/ <b>-</b>	-	
7	6	5	4	3	2	1	0
Reserved	EN_PROCHOT _EXIT	PROCHOT_WIDTH		PROCHOT _CLEAR	Reserved	STAT_VAP _FAIL	STAT_EXIT _VAP
R	R/W	R/W		R/W	R	R/W	R/W
7	6	5	4	3	2	1	0
STAT_VDPM	STAT_COMP	STAT_ICRIT	STAT_INOM	STAT_IDCHG	STAT_VSYS	STAT_BAT _Removal	STAT_ADPT _Removal
R/W	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-21. ProchotStatus Register (I<sup>2</sup>C address = 23h) Field Descriptions

l <sup>2</sup> C 23h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Reserved	R	1b	Reserved
6	EN_PROCHOT_EXIT	R/W	Ob	PROCHOT Pulse Extension Enable. When pulse extension isenabled, keep the PROCHOT pin voltage LOW until host writesREG0x23[3] = 0.0b: Disable pulse extension <default at="" por="">1b: Enable pulse extension</default>
5-4	PROCHOT _WIDTH	R/W	10Ь	PROCHOT Pulse Width. Minimum PROCHOT pulse width when REG0x23[6] = 0 00b: 100 us 01b: 1 ms 10b: 10 ms <default at="" por=""> 11b: 5 ms</default>
3	PROCHOT_CLEAR	R/W	1b	PROCHOT Pulse Clear. Clear PROCHOT pulse when 0x23[6] = 1. 0b: Clear PROCHOT pulse and drive PROCHOT pin HIGH 1b: Idle <default at="" por=""></default>
2	Reserved	R	0b	Reserved
1	STAT_VAP_FAIL	R/W	Ob	This status bit reports a failure to load VBUS 7 consecutive times in VAP mode, which indicates the battery voltage might be not high enough to enter VAP mode, or the VAP loading current settings are too high. 0b: Not is VAP failure <default at="" por=""> 1b: In VAP failure, the charger exits VAP mode, and latches off until the host writes this bit to 0.</default>
0	STAT_EXIT_VAP	R/W	Ob	When the charger is operated in VAP mode, it can exit VAP by either being disabled through host, or there is any charger faults. 0b: PROCHOT_EXIT_VAP is not active <default at="" por=""> 1b: PROCHOT_EXIT_VAP is active, PROCHOT pin is low until host writes this status bit to 0.</default>

# 表 9-22. ProchotStatus Register (I<sup>2</sup>C address = 22h) Field Descriptions

l <sup>2</sup> C 22h	FIELD	TYPE	RESET	DESCRIPTION
7	STAT_VDPM	R/W	0b	0b: Not triggered 1b: Triggered

# 表 9-22. ProchotStatus Register (I<sup>2</sup>C address = 22h) Field Descriptions (continued)

l <sup>2</sup> C 22h	FIELD	ТҮРЕ	RESET	DESCRIPTION
6	STAT_COMP	R	0b	0b: Not triggered 1b: Triggered
5	STAT_ICRIT	R	0b	0b: Not triggered 1b: Triggered
4	STAT_INOM	R	0b	0b: Not triggered 1b: Triggered
3	STAT_IDCHG	R	0b	0b: Not triggered 1b: Triggered
2	STAT_VSYS	R	0b	0b: Not triggered 1b: Triggered
1	STAT_Battery_Removal	R	0b	0b: Not triggered 1b: Triggered
0	STAT_Adapter_Removal	R	0b	0b: Not triggered 1b: Triggered



## 9.6.3 ChargeCurrent Register (I<sup>2</sup>C address = 03/02h) [reset = 0000h]

To set the charge current, write a 16-bit ChargeCurrent() command (REG0x03/02h()) using the data format listed in  $\boxtimes$  9-21,  $\cancel{5}$  9-23, and  $\cancel{5}$  9-24.

With  $10-m\Omega$  sense resistor, the charger provides charge current range of 64 mA to 8.128 A, with a 64-mA step resolution. Upon POR, when auto wakeup is not active, ChargeCurrent() is 0 A. Any conditions for CHRG\_OK low except ACOV will reset ChargeCurrent() to zero. CELL\_BATPRESZ going LOW (battery removal) will reset the ChargeCurrent() register to 0 A.

Charge current is not reset in ACOC, TSHUT, power path latch off (REG0x30[1]), and SYSOVP.

A 0.1- $\mu$ F capacitor between SRP and SRN for differential mode filtering is recommended; an optional 0.1- $\mu$ F capacitor between SRN and ground, and an optional 0.1- $\mu$ F capacitor between SRP and ground for common mode filtering. Meanwhile, the capacitance on SRP should not be higher than 0.1  $\mu$ F in order to properly sense the voltage across SRP and SRN for cycle-by-cycle current detection.

The SRP and SRN pins are used to sense voltage drop across RSR with default value of 10 m $\Omega$ . However, resistors of other values can also be used. For a larger sense resistor, a larger sense voltage is given, and a higher regulation accuracy; but, at the expense of higher conduction loss. A current sensing resistor value no more than 20 m $\Omega$  is suggested.

#### **Ξ** 9-21. ChargeCurrent Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 03/02h) [reset = 0h]

7	6	5	4	3	2	1	0	
	Reserved		Charge Current, bit 6	Charge Current, bit 5	Charge Current, bit 4	Charge Current, bit 3	Charge Current, bit 2	
	R/W		R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0	
Charge Current, bit 1	Charge Current, bit 0	Reserved	Reserved					
R/W	R/W	R/W			R/W			

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-23. Charge Current Register (14h) With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 03h) Field Descriptions

l <sup>2</sup> C 03h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-5	Reserved	R/W	000b	Not used. 1 = invalid write.
4	Charge Current, bit 6	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 4096 mA of charger current.
3	Charge Current, bit 5	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 2048 mA of charger current.
2	Charge Current, bit 4	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 1024 mA of charger current.
1	Charge Current, bit 3	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 512 mA of charger current.
0	Charge Current, bit 2	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 256 mA of charger current.

#### 表 9-24. Charge Current Register (14h) With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 02h) Field Descriptions

l <sup>2</sup> C 02h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Charge Current, bit 1	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 128 mA of charger current.



# 表 9-24. Charge Current Register (14h) With 10-m $\Omega$ Sense Resistor (I<sup>2</sup>C address = 02h) Field Descriptions (continued)

l <sup>2</sup> C 02h	FIELD	ТҮРЕ	RESET	DESCRIPTION
6	Charge Current, bit 0	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 64 mA of charger current.
5-0	Reserved	R/W	00000b	Not used. Value Ignored.

## 9.6.3.1 Battery Precharge Current Clamp

During precharge, BATFET works in linear mode or LDO mode (default REG0x00[2] = 1). For 2-4 cell battery, the system is regulated at minimum system voltage in REG0x0D/0C() and the precharge current is clamped at 384 mA. For 1 cell battery, the precharge to fast charge threshold is 3 V, and the precharge current is clamped at 384 mA. However, the BATFET stays in LDO mode operation until battery voltage is above minimum system voltage (~3.6 V). During battery voltage from 3 V to 3.6 V, the fast charge current is clamped at 2 A.



# 9.6.4 MaxChargeVoltage Register (I<sup>2</sup>C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]

To set the output charge voltage, write a 16-bit ChargeVoltage register command (REG0x05/04()) using the data format listed in  $\boxtimes$  9-22,  $\ddagger$  9-25, and  $\ddagger$  9-26. The charger provides charge voltage range from 1.024 V to 19.200 V, with 8-mV step resolution. Any write below 1.024 V or above 19.200 V is ignored.

Upon POR, REG0x05/04() is by default set as 4200 mV for 1 s, 8400 mV for 2 s, 12600 mV for 3 s or 16800 mV for 4 s. After CHRG\_OK goes high, the charge will start when the host writes the charging current to REG0x03/02(), the default charging voltage is used if REG0x05/04() is not programmed. If the battery is different from 4.2 V/cell, the host has to write to REG0x05/04() before REG0x03/02() for correct battery voltage setting. Writing REG0x05/04() to 0 will set REG0x05/04() to the default value based on CELL\_BATPRESZ pin, and force REG0x03/02() to zero to disable charge.

The SRN pin senses the battery voltage for voltage regulation and should be connected as close to the battery as possible, and directly place a decoupling capacitor (0.1  $\mu$ F recommended) as close to the device as possible to decouple high frequency noise.

# 図 9-22. MaxChargeVoltage Register (I<sup>2</sup>C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]

7	6	5	4	3	2	1	0		
Reserved	Max Charge Voltage, bit 11	Max Charge Voltage, bit 10	Max Charge Voltage, bit 9	Max Charge Voltage, bit 8	Max Charge Voltage, bit 7	Max Charge Voltage, bit 6	Max Charge Voltage, bit 5		
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W		
7	6	5	4	3	2	1	0		
Max Charge Voltage, bit 4	Max Charge Voltage, bit 3	Max Charge Voltage, bit 2	Max Charge Voltage, bit 1	Max Charge Voltage, bit 1	Reserved				
R/W	R/W	R/W	R/W	R/W	•	R/W			

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-25. MaxChargeVoltage Register (I<sup>2</sup>C address = 05h) Field Descriptions

l <sup>2</sup> C 05h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Max Charge Voltage, bit 11	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 16384 mV of charger voltage.
5	Max Charge Voltage, bit 10	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 8192 mV of charger voltage
4	Max Charge Voltage, bit 9	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 4096 mV of charger voltage.
3	Max Charge Voltage, bit 8	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 2048 mV of charger voltage.
2	Max Charge Voltage, bit 7	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 1024 mV of charger voltage.
1	Max Charge Voltage, bit 6	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 512 mV of charger voltage.
0	Max Charge Voltage, bit 5	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 256 mV of charger voltage.



# 表 9-26. MaxChargeVoltage Register (I<sup>2</sup>C address = 04h) Field Descriptions

l <sup>2</sup> C 04h	FIELD	TYPE	RESET	DESCRIPTION			
7	Max Charge Voltage, bit 4	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 128 mV of charger voltage.			
6	Max Charge Voltage, bit 3	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 64 mV of charger voltage.			
5	Max Charge Voltage, bit 2	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 32 mV of charger voltage.			
4	Max Charge Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 16 mV of charger voltage.			
3	Max Charge Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 8 mV of charger voltage.			
2-0	Reserved	R/W	000b	Not used. Value Ignored.			



# 9.6.5 MinSystemVoltage Register (I<sup>2</sup>C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]

To set the minimum system voltage, write a 16-bit MinSystemVoltage register command (REG0x0D/0C()) using the data format listed in  $\boxtimes$  9-23, 表 9-27, and 表 9-28. The charger provides minimum system voltage range from 1.024 V to 16.128 V, with 256-mV step resolution. Any write below 1.024 V or above 16.128 V is ignored. Upon POR, the MinSystemVoltage register is 3.584 V for 1 S, 6.144 V for 2 S and 9.216 V for 3 S, and 12.288 V for 4 S.

# 図 9-23. MinSystemVoltage Register (I<sup>2</sup>C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]

7	6	5	4	3	2	1	0			
Rese	rved	Min System Voltage, bit 5	Min System Voltage, bit 4	Min System Voltage, bit 3	Min System Voltage, bit 2	Min System Voltage, bit 1	Min System Voltage, bit 0			
R/	W	R/W	R/W	R/W	R/W	R/W	R/W			
7	7 6		4	3	2	1	0			
	Reserved									
	R/W									

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-27. MinSystemVoltage Register (I<sup>2</sup>C address = 0Dh) Field Descriptions

l <sup>2</sup> C 0Dh	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Min System Voltage, bit 5	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 8192 mV of system voltage.
4	Min System Voltage, bit 4	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 4096mV of system voltage.
3	Min System Voltage, bit 3	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 2048 mV of system voltage.
2	Min System Voltage, bit 2	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 1024 mV of system voltage.
1	Min System Voltage, bit 1	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 512 mV of system voltage.
0	Min System Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of system voltage. 1 = Adds 256 mV of system voltage.

#### 表 9-28. MinSystemVoltage Register (I<sup>2</sup>C address = 0Ch) Field Descriptions

l <sup>2</sup> C 0Ch	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-0	Reserved	R/W	00000000 b	Not used. Value Ignored.

#### 9.6.5.1 System Voltage Regulation

The device employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by REG0x0D/0C(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage with BATFET.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode), and the system is regulated above the minimum system voltage setting. As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference



between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

When BATFET is removed, the system node VSYS is shorted to SRP. Before the converter starts operation, LDO mode needs to be disabled. The following sequence is required to configure charger without BATFET.

- 1. Before adapter plugs in, put the charger into HIZ mode. (either pull pin 6 ILIM\_HIZ to ground, or set REG0x35[7] to 1)
- 2. Set 0x00[2] to 0 to disable LDO mode.
- 3. Set 0x30[0] to 0 to disable auto-wakeup mode.
- 4. Check if battery voltage is properly programmed (REG0x05/04)
- 5. Set precharge/charge current (REG0x03/02)
- 6. Put the device out of HIZ mode. (Release ILIM\_HIZ from ground and set REG0x35[7]=0).

In order to prevent any accidental SW mistakes, the host sets low input current limit (a few hundred milliamps) when device is out of HIZ.

## 9.6.6 Input Current and Input Voltage Registers for Dynamic Power Management

The charger supports Dynamic Power Management (DPM). Normally, the input power source provides power for the system load or to charge the battery. When the input current exceeds the input current setting, or the input voltage falls below the input voltage setting, the charger decreases the charge current to provide priority to the system load. As the system current rises, the available charge current drops accordingly towards zero. If the system load keeps increasing after the charge current drops down to zero, the system voltage starts to drop. As the system voltage drops below the battery voltage, the battery will discharge to supply the heavy system load.

## 9.6.6.1 Input Current Registers

To set the maximum input current limit, write a 16-bit IIN\_HOST register command (REG0x0F/0E()) using the data format listed in  $\frac{1}{2}$  9-29 and  $\frac{1}{2}$  9-30. When using a 10-m $\Omega$  sense resistor, the charger provides an inputcurrent limit range of 50 mA to 6400 mA, with 50-mA resolution. The default current limit is 3.25 A. Due to the USB current setting requirement, the register setting specifies the maximum current instead of the typical current. Upon adapter removal, the input current limit is reset to the default value of 3.25 A. With code 0, the input current limit is 50 mA.

The ACP and ACN pins are used to sense  $R_{AC}$  with the default value of 10 m $\Omega$ . For a 20-m $\Omega$  sense resistor, a larger sense voltage is given and a higher regulation accuracy, but at the expense of higher conduction loss.

Instead of using the internal DPM loop, the user can build up an external input current regulation loop and have the feedback signal on the ILIM\_HIZ pin.

$$V_{\text{ILIM}_{\text{HIZ}}} = 1V + 40 \times (V_{\text{ACP}} - V_{\text{ACN}}) = 1 + 40 \times I_{\text{DPM}} \times R_{\text{AC}}$$
<sup>(2)</sup>

In order to disable ILIM\_HIZ pin, the host can write to 0x32[7] to disable ILIM\_HIZ pin, or pull ILIM\_HIZ pin above 4.0 V.



#### 9.6.6.1.1 IIN\_HOST Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 0F/0Eh) [reset = 4100h]

With code 0, the input current limit readback is 50 mA.

#### 図 9-24. IIN\_HOST Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 0F/0Eh) [reset = 4100h]

	_	0				/ 6	-			
7	6	5	4	3	2	1	0			
Reserved	Input Current set by host, bit 6	Input Current set by host, bit 5	Input Current set by host, bit 4	Input Current set by host, bit 3	Input Current set by host, bit 2	Input Current set by host, bit 1	Input Current set by host, bit 0			
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W			
7	6	5	4	3	2	1	0			
	Reserved									
	R									

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-29. IIN\_HOST Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 0Fh) Field Descriptions

l <sup>2</sup> C 0Fh	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Input Current set by host, bit 6	R/W	1b	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current set by host, bit 5	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current set by host, bit 4	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 800 mA of input current.
3	Input Current set by host, bit 3	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current set by host, bit 2	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current set by host, bit 1	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current set by host, bit 0	R/W	1b	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current.

# 表 9-30. IIN\_HOST Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 0Eh) Field Descriptions

l <sup>2</sup> C 0Eh	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R	00000000 b	Not used. Value Ignored.



#### 9.6.6.1.2 IIN\_DPM Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 25/24h) [reset = 4100h]

IIN\_DPM register reflects the actual input current limit programmed in the register, either from host or from ICO.

After ICO, the current limit used by DPM regulation may differ from the IIN\_HOST register settings. The actual DPM limit is reported in REG0x25/24(). With code 0, the input current limit read-back is 50 mA.

## 2 9-25. IIN\_DPM Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 25/24h) [reset = 4100h]

	_	J		•		/			
7	6	5	4	3	2	1	0		
Reserved	Input Current in DPM, bit 6	Input Current in DPM, bit 5	Input Current in DPM, bit 4	Input Current in DPM, bit 3	Input Current in DPM, bit 2	Input Current in DPM, bit 1	Input Current in DPM, bit 0		
R	R	R	R	R	R	R	R		
7	6	5	4	3	2	1	0		
	Reserved								
	R								

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-31. IIN\_DPM Register With 10-mΩ Sense Resistor (I<sup>2</sup>C address = 25h) Field Descriptions

l <sup>2</sup> C 25h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R	0b	Not used. 1 = invalid write.
6	Input Current in DPM, bit 6	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current in DPM, bit 5	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current in DPM, bit 4	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 800mA of input current
3	Input Current in DPM, bit 3	R	0b	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current in DPM, bit 2	R	0b	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current in DPM, bit 1	R	0b	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current in DPM, bit 0	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current.

## 表 9-32. IIN\_DPM Register With 10-m $\Omega$ Sense Resistor (I<sup>2</sup>C address = 24h) Field Descriptions

l <sup>2</sup> C 24h	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R	0000000b	Not used. Value Ignored.



#### 9.6.6.1.3 InputVoltage Register (I<sup>2</sup>C address = 0B/0Ah) [reset = VBUS-1.28V]

To set the input voltage limit, write a 16-bit InputVoltage register command (REG0x0B/0A()) using the data format listed in  $\boxtimes$  9-26,  $\cancel{E}$  9-33, and  $\cancel{E}$  9-34.

If the input voltage drops more than the InputVoltage register allows, the device enters DPM and reduces the charge current. The default offset voltage is 1.28 V below the no-load VBUS voltage. The DC offset is 3.2 V (0000000).

## 図 9-26. InputVoltage Register (I<sup>2</sup>C address = 0B/0Ah) [reset = VBUS-1.28V]

7	6	5	4	3	2	1	0
Rese	erved	Input Voltage, bit 7	Input Voltage, bit 6	Input Voltage, bit 5	Input Voltage, bit 4	Input Voltage, bit 3	Input Voltage, bit 2
R/	W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Input Voltage, bit 1	Input Voltage, bit 0	Reserved					
R/W	R/W		R/W				

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-33. InputVoltage Register (I<sup>2</sup>C address = 0Bh) Field Descriptions

l <sup>2</sup> C 0Bh	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Input Voltage, bit 7	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 8192 mV of input voltage.
4	Input Voltage, bit 6	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 4096mV of input voltage.
3	Input Voltage, bit 5	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 2048 mV of input voltage.
2	Input Voltage, bit 4	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 1024 mV of input voltage.
1	Input Voltage, bit 3	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 512 mV of input voltage.
0	Input Voltage, bit 2	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 256 mV of input voltage.

#### 表 9-34. InputVoltage Register (I<sup>2</sup>C address = 0Ah) Field Descriptions

l <sup>2</sup> C 0Ah	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	Input Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 128 mV of input voltage.
6	Input Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 64 mV of input voltage
5-0	Reserved	R/W	00000b	Not used. Value Ignored.



#### 9.6.7 OTGVoltage Register (I<sup>2</sup>C address = 07/06h) [reset = 0000h]

To set the OTG output voltage limit, write to REG0x07/06() using the data format listed in  $\boxtimes$  9-27,  $\cancel{5}$  9-35, and  $\cancel{5}$  9-36.

The DAC is clamped in digital core at minimal 3V and maximum 20.8V. Any register writing lower than the minimal or higher than the maximum will be ignored. When REG0x34[2] = 1, there is no DAC offset. When REG0x34[2] = 0 the DAC is offset by 1.28V

	즈 3-2/	. Or Gvollage	Register (I-C	auuress – ur	/uon) [reset –	uuuunj	
7	6	5	4	3	2	1	0
Rese	erved	OTG Voltage, bit 11	OTG Voltage, bit 10	OTG Voltage, bit 9	OTG Voltage, bit 8	OTG Voltage, bit 7	OTG Voltage, bit 6
R/	W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
OTG Voltage, bit 5	OTG Voltage, bit 4	OTG Voltage, bit 3	OTG Voltage, bit 2	OTG Voltage, bit 1	OTG Voltage, bit 0	Rese	erved
R/W	R/W	R/W	R/W	R/W	R/W	R	W

# 図 9-27. OTGVoltage Register (I<sup>2</sup>C address = 07/06h) [reset = 0000h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-35. OTGVoltage Register (I<sup>2</sup>C address = 07h) Field Descriptions

l <sup>2</sup> C 07h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	OTG Voltage, bit 11	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 16656 mV of OTG voltage.
4	OTG Voltage, bit 10	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 8328 mV of OTG voltage.
3	OTG Voltage, bit 9	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 4164 mV of OTG voltage.
2	OTG Voltage, bit 8	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 2082 mV of OTG voltage.
1	OTG Voltage, bit 7	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 1041 mV of OTG voltage.
0	OTG Voltage, bit 6	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 521 mV of OTG voltage.

## 表 9-36. OTGVoltage Register (I<sup>2</sup>C address = 06h) Field Descriptions

l <sup>2</sup> C 06h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7	OTG Voltage, bit 5	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 260 mV of OTG voltage.
6	OTG Voltage, bit 4	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 130 mV of OTG voltage.
5	OTG Voltage, bit 3	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 65 mV of OTG voltage.
4	OTG Voltage, bit 2	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 33 mV of OTG voltage.
3	OTG Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 16 mV of OTG voltage.

Copyright © 2023 Texas Instruments Incorporated



# 表 9-36. OTGVoltage Register (I<sup>2</sup>C address = 06h) Field Descriptions (continued)

l <sup>2</sup> 0 06		FIELD	ТҮРЕ	RESET	DESCRIPTION
2		OTG Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 8.1 mV of OTG voltage.
1-(	C	Reserved	R/W	00b	Not used. Value Ignored.



#### 9.6.8 OTGCurrent Register (I<sup>2</sup>C address = 09/08h) [reset = 0000h]

To set the OTG output current limit, write to REG0x09/08() using the data format listed in 図 9-28, 表 9-37, and 表 9-38.

	図 9-28. OTGCurrent Register (I <sup>2</sup> C address = 09/08h) [reset = 0000h]										
7	6	5	4	3	2	1	0				
Reserved	OTG Current set by host, bit 6	OTG Current set by host, bit 5	OTG Current set by host, bit 4	OTG Current set by host, bit 3	OTG Current set by host, bit 2	OTG Current set by host, bit 1	OTG Current set by host, bit 0				
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W				
7	6	5	4	3	2	1	0				
Reserved											
			R/	W							

# 図 9-28. OTGCurrent Register (I<sup>2</sup>C address = 09/08h) [reset = 0000h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-37. OTGCurrent Register (I<sup>2</sup>C address = 09h) Field Descriptions

l <sup>2</sup> C 09h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	OTG Current set by host, bit 6	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 3200 mA of OTG current.
5	OTG Current set by host, bit 5	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 1600mA of OTG current.
4	OTG Current set by host, bit 4	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 800 mA of OTG current.
3	OTG Current set by host, bit 3	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 400 mA of OTG current.
2	OTG Current set by host, bit 2	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 200 mA of OTG current.
1	OTG Current set by host, bit 1	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 100 mA of OTG current.
0	OTG Current set by host, bit 0	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 50 mA of OTG current.

# 表 9-38. OTGCurrent Register (I<sup>2</sup>C address = 08h) Field Descriptions

l <sup>2</sup> C 08h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-0	Reserved	R/W	0000000b	Not used. Value Ignored.

# 9.6.9 ADCVBUS/PSYS Register (I<sup>2</sup>C address = 27/26h)

- PSYS: Full range: 3.06 V, LSB: 12 mV
- VBUS: Full range: 3200 mV to 19520 mV, LSB: 64 mV

## 図 9-29. ADCVBUS/PSYS Register (I<sup>2</sup>C address = 27/26h)

7	6	5	4	3	2	1	0
R	R	R	R	R R		R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-39. ADCVBUS/PSYS Register (I<sup>2</sup>C address = 27h) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of Input Voltage

#### 表 9-40. ADCVBUS/PSYS Register (I<sup>2</sup>C address = 26h) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of System Power



## 9.6.10 ADCIBAT Register (I<sup>2</sup>C address = 29/28h)

- ICHG: Full range: 8.128 A, LSB: 64 mA
- IDCHG: Full range: 32.512 A, LSB: 256 mA

## 図 9-30. ADCIBAT Register (I<sup>2</sup>C address = 29/28h)

7	6	5	4	3	2	1	0
Reserved	R	R	R	R R		R	R
7	6	5	4	3	2	1	0
Reserved	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 9-41. ADCIBAT Register (I<sup>2</sup>C address = 29h) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R		Not used. Value ignored.
6-0		R		7-bit Digital Output of Battery Charge Current

# 表 9-42. ADCIBAT Register (I<sup>2</sup>C address = 28h) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R		Not used. Value ignored.
6-0		R		7-bit Digital Output of Battery Discharge Current



## 9.6.11 ADCIINCMPIN Register (I<sup>2</sup>C address = 2B/2Ah)

- IIN: Full range: 12.75 A, LSB: 50 mA. For  $10m\Omega$  sense resistor, IIN full range = 6.4A
- CMPIN: Full range: 3.06 V, LSB: 12 mV

# 図 9-31. ADCIINCMPIN Register (I<sup>2</sup>C address = 2B/2Ah)

7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-43. ADCIINCMPIN Register (I<sup>2</sup>C address = 2Bh) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of Input Current

#### 表 9-44. ADCIINCMPIN Register (I<sup>2</sup>C address = 2Ah) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of CMPIN voltage



## 9.6.12 ADCVSYSVBAT Register (I<sup>2</sup>C address = 2D/2Ch)

- VSYS: Full range: 2.88 V to 19.2 V, LSB: 64 mV
- VBAT: Full range: 2.88 V to 19.2 V, LSB: 64 mV

## 図 9-32. ADCVSYSVBAT Register (I<sup>2</sup>C address = 2D/2Ch)

7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## 表 9-45. ADCVSYSVBAT Register (I<sup>2</sup>C address = 2Dh) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of System Voltage

#### 表 9-46. ADCVSYSVBAT Register (I<sup>2</sup>C address = 2Ch) Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
7-0		R		8-bit Digital Output of Battery Voltage



## 9.6.13 ID Registers

#### 9.6.13.1 ManufactureID Register (I<sup>2</sup>C address = 2Eh) [reset = 0040h]

## 図 9-33. ManufactureID Register (I<sup>2</sup>C address = 2Eh) [reset = 0040h]

7-0	
MANUFACTURE_ID	
R	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-47. ManufactureID Register Field Descriptions

l2C 2Eh	FIELD	TYPE	RESET	DESCRIPTION (READ ONLY)
7-0	MANUFACTURE_ID	R		40h

#### 9.6.13.2 Device ID (DeviceAddress) Register (I<sup>2</sup>C address = 2Fh) [reset = 0h]

## 図 9-34. Device ID (DeviceAddress) Register (I<sup>2</sup>C address = 2Fh) [reset = 0h]

7-0
DEVICE_ID
R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### 表 9-48. Device ID (DeviceAddress) Register Field Descriptions

l2C 2Fh	FIELD	TYPE	RESET	DESCRIPTION (READ ONLY)
7-0	DEVICE_ID	R	0b	I2C: 88h (BQ25713); 8Ah (BQ25713B)



## **10 Application and Implementation**

注

以下のアプリケーション情報は、TIの製品仕様に含まれるものではなく、TIではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

## **10.1 Application Information**

The BQ2571xEVM-017 evaluation module (EVM) is a complete charger module for evaluating the BQ25713/ BQ25713B. The application curves were taken using the BQ2571xEVM-017. Refer to the EVM User's Guide for EVM information.

## **10.2 Typical Application**

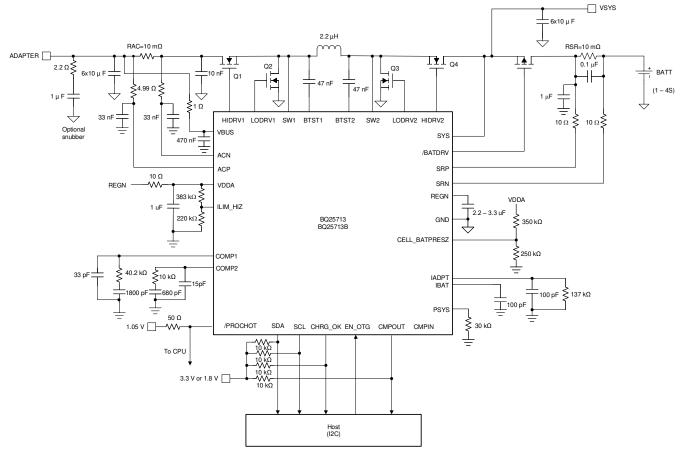


図 10-1. Application Diagram

#### **10.2.1 Design Requirements**

DESIGN PARAMETER	EXAMPLE VALUE				
Input Voltage <sup>(2)</sup>	3.5 V < Adapter Voltage < 24 V				
Input Current Limit <sup>(2)</sup>	3.2 A for 65 W adapter				
Battery Charge Voltage <sup>(1)</sup>	8400 mV for 2s battery				
Battery Charge Current <sup>(1)</sup>	3072 mA for 2s battery				



DESIGN PARAMETER	EXAMPLE VALUE
Minimum System Voltage <sup>(1)</sup>	6144 mV for 2s battery

(1) Refer to battery specification for settings.

(2) Refer to adapter specification for settings for Input Voltage and Input Current Limit.

#### 10.2.2 Detailed Design Procedure

The parameters are configurable using the evaluation software. The simplified application circuit (see  $\boxtimes$  10-1, as the application diagram) shows the minimum component requirements. Inductor, capacitor, and MOSFET selection are explained in the rest of this section. Refer to the EVM User's Guide for the complete application schematic.

#### 10.2.2.1 ACP-ACN Input Filter

The BQ25713/BQ25713B has average current mode control. The input current sensing through ACP/ACN is critical to recover inductor current ripple. Parasitic inductance on board will generate high frequency ringing on ACP-ACN which overwhelms converter sensed inductor current information, so it is difficult to manage parasitic inductance created based on different PCB layout. Bigger parasitic inductance will generate bigger sense current ringing which will cause the average current control loop to go into oscillation.

For real system board condition, we suggest to use below circuit design to get best result and filter noise induced from different PCB parasitic factor. With time constant of filter from 47 nsec to 200 nsec, the filtering on ringing is effective and in the meantime, the delay of on the sensed signal is small and therefore poses no concern for average current mode control.

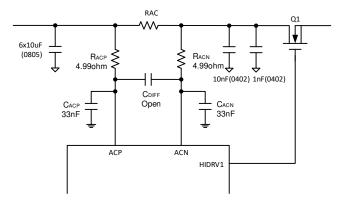


図 10-2. ACN-ACP Input Filter

#### 10.2.2.2 Inductor Selection

The BQ25713/BQ25713B has two selectable fixed switching frequency. Higher switching frequency allows the use of smaller inductor and capacitor values. Inductor saturation current should be higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPLE}$ ):

$$I_{SAT} \ge I_{CHG} + (1/2) I_{RIPPLE}$$
(3)

The inductor ripple current in buck operation depends on input voltage ( $V_{IN}$ ), duty cycle ( $D_{BUCK} = V_{OUT}/V_{IN}$ ), switching frequency ( $f_S$ ) and inductance (L):

$$I_{\text{RIPPLE}\_BUCK} = \frac{V_{\text{IN}} \times D \times (1 - D)}{f_{\text{S}} \times L}$$
(4)

During boost operation, the duty cycle is:

$$D_{BOOST} = 1 - (V_{IN}/V_{BAT})$$

and the ripple current is:



### $I_{RIPPLE BOOST} = (VIN \times D_{BOOST}) / (f_S \times L)$

The maximum inductor ripple current happens with D = 0.5 or close to 0.5. For example, the battery charging voltage range is from 9 V to 12.6 V for 3-cell battery pack. For 20-V adapter voltage, 10-V battery voltage gives the maximum inductor ripple current. Another example is 4-cell battery, the battery voltage range is from 12 V to 16.8 V, and 12-V battery voltage gives the maximum inductor ripple current.

Usually inductor ripple is designed in the range of (20 - 40%) maximum charging current as a trade-off between inductor size and efficiency for a practical design.

#### 10.2.2.3 Input Capacitor

Input capacitor should have enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current (plus system current there is any system load) when duty cycle is 0.5 in buck mode. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current occurs where the duty cycle is closest to 50% and can be estimated by  $\neq 5$ :

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1 - D)}$$
(5)

Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed in front of  $R_{AC}$  current sensing and as close as possible to the power stage half bridge MOSFETs. Capacitance after  $R_{AC}$  before power stage half bridge should be limited to 10 nF + 1 nF referring to  $\boxtimes$  10-2. Because too large capacitance after  $R_{AC}$  could filter out  $R_{AC}$  current sensing ripple information. Voltage rating of the capacitor must be higher than normal input voltage level, 25-V rating or higher capacitor is preferred for 19-V to 20-V input voltage. The minimum input effective capacitance recommendation is shown in  $\gtrsim$  10-1.

Ceramic capacitors (MLCC) show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the input capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high input voltages and small capacitor packages. See the manufacturer's datasheet about the derating performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required effective capacitance value at the operating point. Considering the 25 V 0603 package MLCC capacitance derating under 19-V to 20-V input voltage, the recommended practical capacitors configuration can also be found in  $\gtrsim$  10-1. Tantalum capacitors (POSCAP) can avoid dc-bias effect and temperature variation effect which is recommended for 90 W to 130 W higher power application.

INPUT CAPACITORS VS TOTAL INPUT POWER	65W	90W	130W
Minimum effective input capacitance	4 μF	6 μF	13 µF
Minimum practical input capacitors configuration	4*10 μF (0603 25 V MLCC)	6*10 μF (0603 25 V MLCC)	3*10 μF (0603 25 V MLCC) 1* 10 μF (25 V to 35 V POSCAP)

#### 表 10-1. Minimum Input Capacitance Requirement

#### 10.2.2.4 Output Capacitor

Output capacitor also should have enough ripple current rating to absorb output switching ripple current. To get good loop stability, the resonant frequency of the output inductor and output capacitor should be designed between 10 kHz and 20 kHz. The preferred ceramic capacitor is 25-V X7R or X5R for output capacitor. Minimum 7 pcs of 10- $\mu$ F 0603 package capacitor is suggested to be placed as close as possible to Q3&Q4 half bridge (between Q4 drain and Q3 source terminal). Total minimum output effective capacitance along VSYS distribution line is 50  $\mu$ F refers to  $\gtrsim$  10-2. Recommend to place minimum 20- $\mu$ F MLCC capacitors after the charge current sense resistor for best stability.

Ceramic capacitors show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the output capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high output voltages and small capacitor packages. See the



(6)

manufacturer's data sheet about the derating performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required capacitance value at the operating point. Considering the 25-V 0603 package MLCC capacitance derating under 21-V to 23-V output voltage, the recommended practical capacitors configuration at VSYS output terminal can also be found in 表 10-2. Tantalum capacitors (POSCAP) can avoid dc-bias effect and temperature variation effect which are recommended to be used along VSYS output distribution line to meet total minimum effective output capacitance requirement.

OUTPUT CAPACITORS VS TOTAL INPUT POWER	65W	65W 90W				
Minimum Effective Output Capacitance	50 µF	50 µF	50 µF			
Minimum output capacitors at charger VSYS output terminal	7*10 µF (0603 25 V MLCC)	9*10 µF (0603 25 V MLCC)	9*10 µF (0603 25 V MLCC)			
Additional output capacitors along VSYS distribution line	2*22 µF (25 V~35 V POSCAP)	2*22 µF (25 V~35 V POSCAP)	2*22 μF (25 V~35 V POSCAP)			

#### 表 10-2. Minimum Output Capacitance Requirement

#### 10.2.2.5 Power MOSFETs Selection

Four external N-channel MOSFETs are used for a synchronous switching battery charger. The gate drivers are internally integrated into the IC with 6 V of gate drive voltage. 30 V or higher voltage rating MOSFETs are preferred for 19 V - 20 V input voltage.

Figure-of-merit (FOM) is usually used for selecting proper MOSFET based on a tradeoff between the conduction loss and switching loss. For the top side MOSFET, FOM is defined as the product of a MOSFET's on-resistance,  $R_{DS(ON)}$ , and the gate-to-drain charge,  $Q_{GD}$ . For the bottom side MOSFET, FOM is defined as the product of the MOSFET's on-resistance,  $R_{DS(ON)}$ , and the total gate charge,  $Q_{G}$ .

$$FOM_{top} = R_{DS(on)} \times Q_{GD}$$
;  $FOM_{bottom} = R_{DS(on)} \times Q_{G}$ 

The lower the FOM value, the lower the total power loss. Usually lower  $R_{DS(ON)}$  has higher cost with the same package size.

The top-side MOSFET loss includes conduction loss and switching loss. It is a function of duty cycle (D=V<sub>OUT</sub>/  $V_{IN}$ ), charging current (I<sub>CHG</sub>), MOSFET's on-resistance (R<sub>DS(ON)</sub>), input voltage (V<sub>IN</sub>), switching frequency (f<sub>S</sub>), turn on time (t<sub>on</sub>) and turn off time (t<sub>off</sub>):

$$P_{top} = D \times I_{CHG}^{2} \times R_{DS(on)} + \frac{1}{2} \times V_{IN} \times I_{CHG} \times (t_{on} + t_{off}) \times f_{s}$$
(7)

The first item represents the conduction loss. Usually MOSFET  $R_{DS(ON)}$  increases by 50% with 100°C junction temperature rise. The second term represents the switching loss. The MOSFET turn-on and turn-off times are given by:

$$t_{on} = \frac{Q_{SW}}{I_{on}}, \quad t_{off} = \frac{Q_{SW}}{I_{off}}$$
(8)

where  $Q_{sw}$  is the switching charge,  $I_{on}$  is the turn-on gate driving current and  $I_{off}$  is the turn-off gate driving current. If the switching charge is not given in MOSFET datasheet, it can be estimated by gate-to-drain charge ( $Q_{GD}$ ) and gate-to-source charge ( $Q_{GS}$ ):

$$Q_{SW} = Q_{GD} + \frac{1}{2} \times Q_{GS}$$
<sup>(9)</sup>

Gate driving current can be estimated by REGN voltage ( $V_{REGN}$ ), MOSFET plateau voltage ( $V_{plt}$ ), total turn-on gate resistance ( $R_{on}$ ) and turn-off gate resistance ( $R_{off}$ ) of the gate driver:



$$I_{on} = \frac{V_{REGN} - V_{plt}}{R_{on}}, \quad I_{off} = \frac{V_{plt}}{R_{off}}$$
(10)

The conduction loss of the bottom-side MOSFET is calculated with the following equation when it operates in synchronous continuous conduction mode:

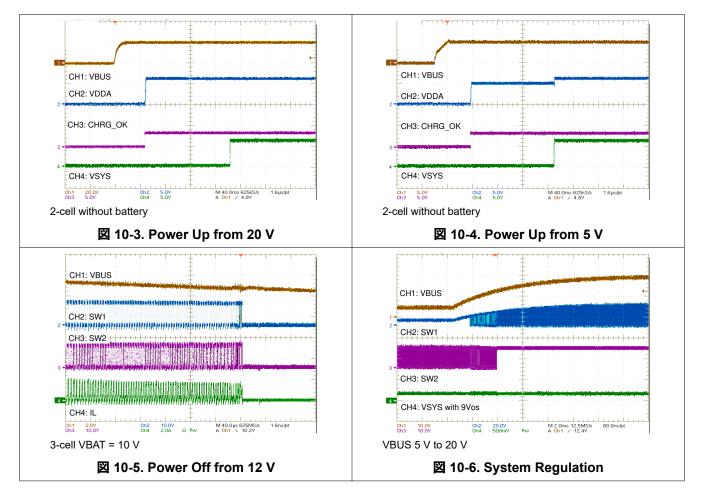
$$P_{bottom} = (1 - D) \times I_{CHG}^{2} \times R_{DS(on)}$$
(11)

When charger operates in non-synchronous mode, the bottom-side MOSFET is off. As a result all the freewheeling current goes through the body-diode of the bottom-side MOSFET. The body diode power loss depends on its forward voltage drop ( $V_F$ ), non-synchronous mode charging current ( $I_{NONSYNC}$ ), and duty cycle (D).

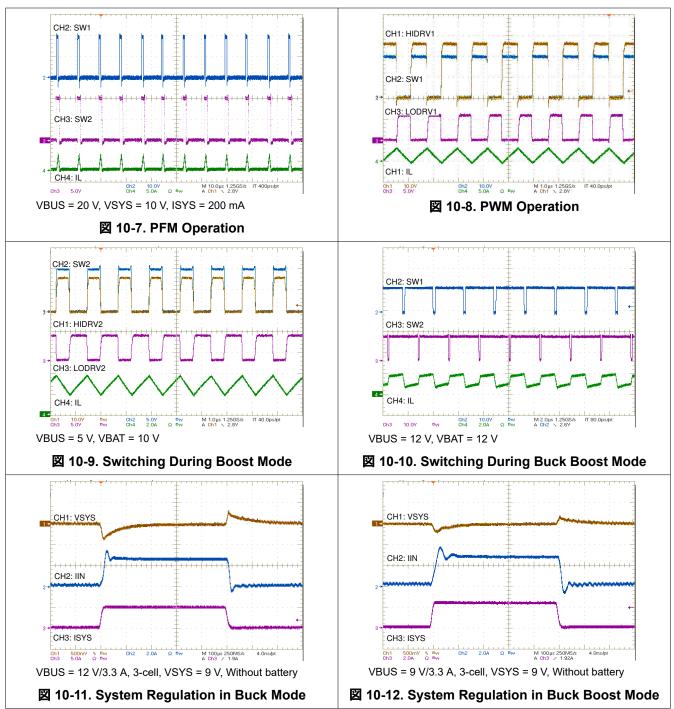
$$P_{\rm D} = V_{\rm F} \times I_{\rm NONSYNC} \times (1 - {\rm D})$$
<sup>(12)</sup>

The maximum charging current in non-synchronous mode can be up to 0.25 A for a  $10-m\Omega$  charging current sensing resistor or 0.5 A if battery voltage is below 2.5 V. The minimum duty cycle happens at lowest battery voltage. Choose the bottom-side MOSFET with either an internal Schottky or body diode capable of carrying the maximum non-synchronous mode charging current.

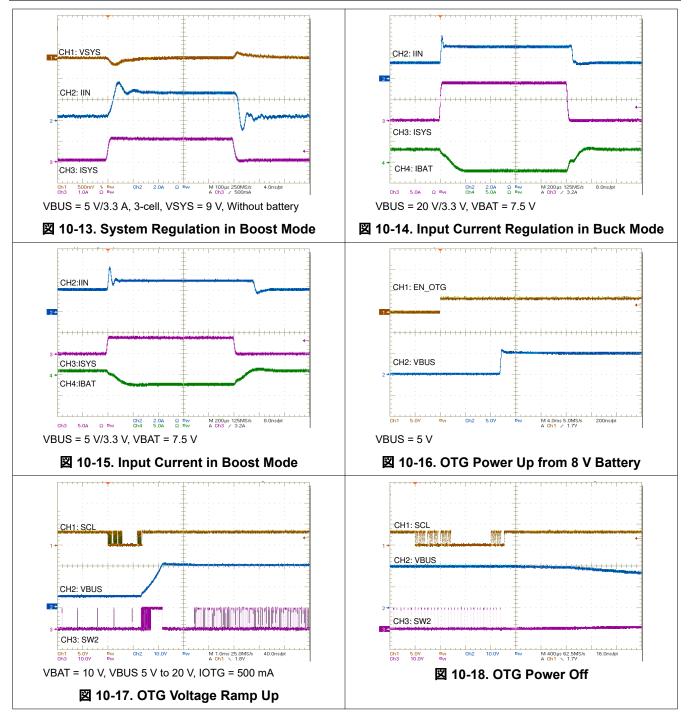
## **10.2.3 Application Curves**



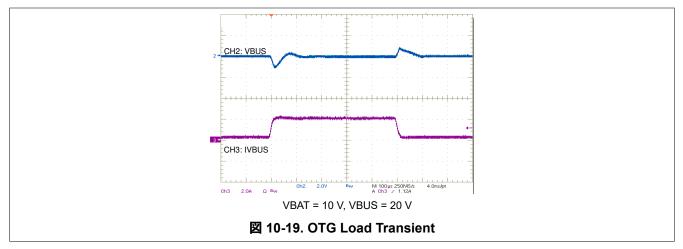














## **11 Power Supply Recommendations**

The valid adapter range is from 3.5 V (V<sub>VBUS\_CONVEN</sub>) to 24 V (ACOV) with at least 500-mA current rating. When CHRG\_OK goes HIGH, the system is powered from adapter through the charger. When adapter is removed, the system is connected to battery through BATFET. Typically the battery depletion threshold should be greater than the minimum system voltage so that the battery capacity can be fully utilized for maximum battery life.



# 12 Layout

## **12.1 Layout Guidelines**

Proper layout of the components to minimize high frequency current path loop (see  $2/2 \ge 12.2$ ) is important to prevent electrical and magnetic field radiation and high frequency resonant problems. Here is a PCB layout priority list for proper layout.

RULES	COMPONENTS	FUNCTION	IMPACT	GUIDELINES
1		PCB layer stack up	Thermal, efficiency, signal integrity	Multi- layer PCB is suggested. Allocate at least one ground layer. The BQ257XXEVM uses a 4-layer PCB (top layer, ground layer, signal layer and bottom layer).
2	CBUS, RAC, Q1, Q2	Input loop	High frequency noise, ripple	VBUS capacitors, RAC, Q1 and Q2 form a small loop 1. It is best to put them on the same side. Connect them with large copper to reduce the parasitic resistance. Move part of CBUS to the other side of PCB for high density design. After RAC before Q1 and Q2 power stage recommend to put 10 nF + 1 nF (0402 package) decoupling capacitors as close as possible to IC to decoupling switching loop high frequency noise.
3	R <sub>AC</sub> , Q1, L1, Q4	Current path	Efficiency	The current path from VBUS to VSYS, through $R_{AC}$ , Q1, L1, Q4, has low impedance. Pay attention to via resistance if they are not on the same side. The number of vias can be estimated as 1 to 2A/via for a 10-mil via with 1 oz. copper thickness.
4	CSYS, Q3, Q4	Output loop	High frequency noise, ripple	VSYS capacitors, Q3 and Q4 form a small loop 2. It is best to put them on the same side. Connect them with large copper to reduce the parasitic resistance. Move part of CSYS to the other side of PCB for high density design.
5	QBAT, R <sub>SR</sub>	Current path	Efficiency, battery voltage detection	Place QBAT and $R_{SR}$ near the battery terminal. The current path from VBAT to VSYS, through $R_{SR}$ and QBAT, has low impedance. Pay attention to via resistance if they are not on the same side. The device detects the battery voltage through SRN near battery terminal.
6	Q1, Q2, L1, Q3, Q4	Power stage	Thermal, efficiency	Place Q1, Q2, L1, Q3 and Q4 next to each other. Allow enough copper area for thermal dissipation. The copper area is suggested to be 2x to 4x of the pad size. Multiple thermal vias can be used to connect more copper layers together and dissipate more heat.
7	R <sub>AC</sub> , R <sub>SR</sub>	Current sense	Regulation accuracy	Use Kelvin-sensing technique for $R_{AC}$ and $R_{SR}$ current sense resistors. Connect the current sense traces to the center of the pads, and run current sense traces as differential pairs.
8	Small capacitors	IC bypass caps	Noise, jittering, ripple	Place VBUS cap, VCC cap, REGN caps near IC.
9	BST capacitors	HS gate drive	High frequency noise, ripple	Place HS MOSFET boost strap circuit capacitor close to IC and on the same side of PCB board. Capacitors SW1/2 nodes are recommended to use wide copper polygon to connect to power stage and capacitors BST1/2 node are recommended to use at least 8mil trace to connected to IC BST1/2 pins.
10		Ground partition	Measurement accuracy, regulation accuracy, jitters, ripple	Separate analog ground(AGND) and power grounds(PGND) is preferred. PGND should be used for all power stage related ground net. AGND should be used for all sensing, compensation and control network ground for example ACP/ACN/COMP1/ COMP2/CMPIN/CMPOUT/IADPT/IBAT/PSYS. Connect all analog grounds to a dedicated low-impedance copper plane, which is tied to the power ground underneath the IC exposed pad. If possible, use dedicated COMP1, COMP2 AGND traces. Connect analog ground and power ground together using power pad as the single ground connection point.

表 12-1.	PCB L	ayout (	Guidelines
---------	-------	---------	------------



## 12.2 Layout Example

### 12.2.1 Layout Example Reference Top View

Based on the above layout guidelines, the buck-boost charger layout example top view is shown below including all the key power components.

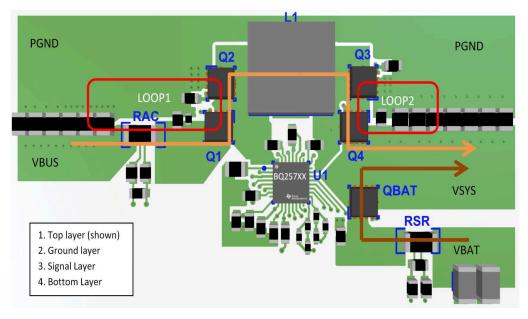
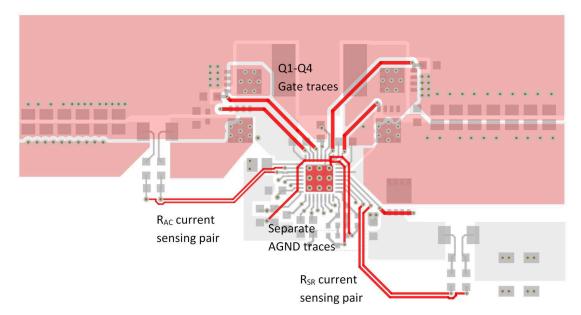


図 12-1. Buck-Boost Charger Layout Reference Example Top View

#### 12.2.2 Inner Layer Layout and Routing Example

For both input sensing resistor and charging current sensing resistor, differential sensing and routing method are suggested and highlighted in below figure. Use wide trace for gate drive traces, minimum 15 mil trace width. Connect all analog grounds to a dedicated low-impedance copper plane, which is tied to the power ground underneath the IC exposed pad. Suggest using dedicated COMP1, COMP2 analog ground traces shown in below figure.







# **13 Device and Documentation Support**

## **13.1 Device Support**

## 13.1.1 サード・パーティ製品に関する免責事項

サード・パーティ製品またはサービスに関するテキサス・インスツルメンツの出版物は、単独またはテキサス・インスツルメンツの製品、サービスと一緒に提供される場合に関係なく、サード・パーティ製品またはサービスの適合性に関する是認、サード・パーティ製品またはサービスの是認の表明を意味するものではありません。

## **13.2 Documentation Support**

#### 13.2.1 Related Documentation

For related documentation see the following:

- Semiconductor and IC Package Thermal Metrics Application Report
- BQ2571x Evaluation Module User's Guide
- QFN/SON PCB Attachment Application Report

## 13.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

## 13.4 サポート・リソース

TI E2E<sup>™</sup> サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接 得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計で必要な支援を迅速に得るこ とができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の使用条件を参照してください。

## 13.5 Trademarks

TI E2E<sup>™</sup> is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

## 13.6 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずか に変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

## 13.7 用語集

テキサス・インスツルメンツ用語集

この用語集には、用語や略語の一覧および定義が記載されています。



## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable Device	Status	Package Type	•	Pins	•	Eco Plan	Lead finish/	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	Ball material	(3)		(4/5)	
							(6)				
BQ25713BRSNR	ACTIVE	QFN	RSN	32	3000	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 85	BQ 25713B	Samples
BQ25713BRSNT	ACTIVE	QFN	RSN	32	250	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 85	BQ 25713B	Samples
BQ25713RSNR	ACTIVE	QFN	RSN	32	3000	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 85	BQ25713	Samples
BQ25713RSNT	ACTIVE	QFN	RSN	32	250	RoHS & Green	NIPDAU   NIPDAUAG	Level-2-260C-1 YEAR	-40 to 85	BQ25713	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and



www.ti.com

# PACKAGE OPTION ADDENDUM

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



Texas

\*All dimensions are nominal

STRUMENTS

## TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	-	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ25713BRSNR	QFN	RSN	32	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ25713BRSNT	QFN	RSN	32	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ25713RSNR	QFN	RSN	32	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ25713RSNT	QFN	RSN	32	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2



www.ti.com

# PACKAGE MATERIALS INFORMATION

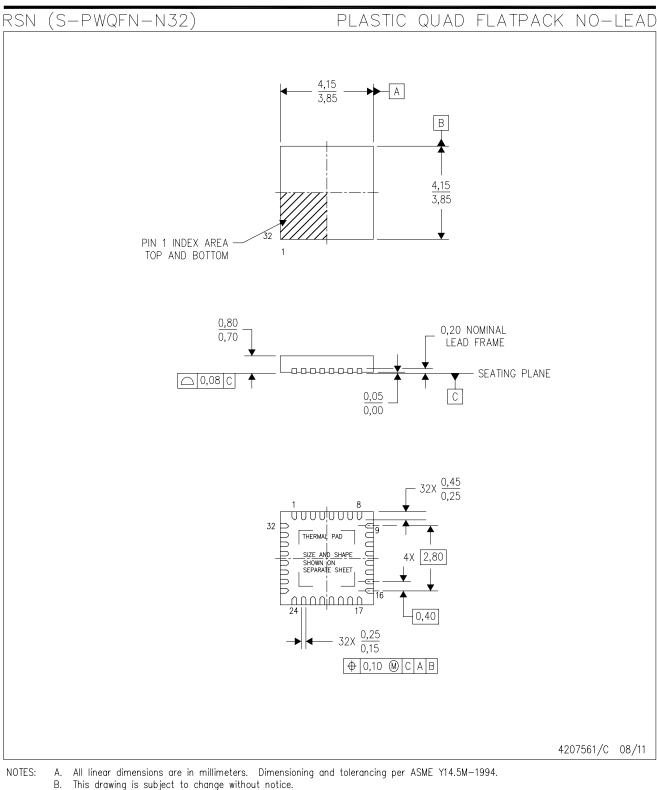
5-Dec-2023



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ25713BRSNR	QFN	RSN	32	3000	367.0	367.0	35.0
BQ25713BRSNT	QFN	RSN	32	250	210.0	185.0	35.0
BQ25713RSNR	QFN	RSN	32	3000	367.0	367.0	35.0
BQ25713RSNT	QFN	RSN	32	250	210.0	185.0	35.0

# **MECHANICAL DATA**



- C. QFN (Quad Flatpack No-Lead) Package configuration.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



# RSN (S-PWQFN-N32)

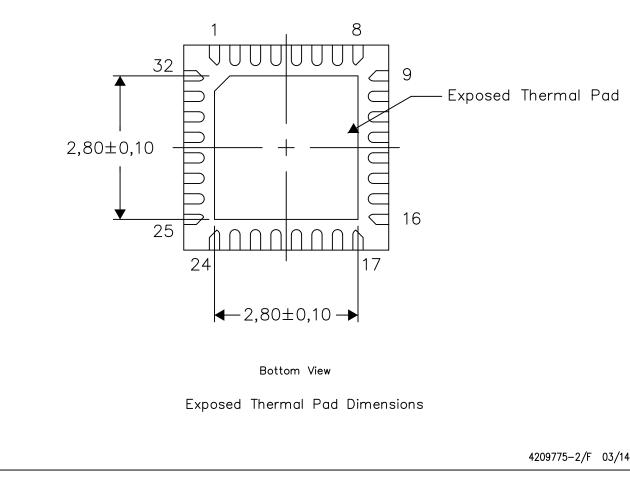
# PLASTIC QUAD FLATPACK NO-LEAD

### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

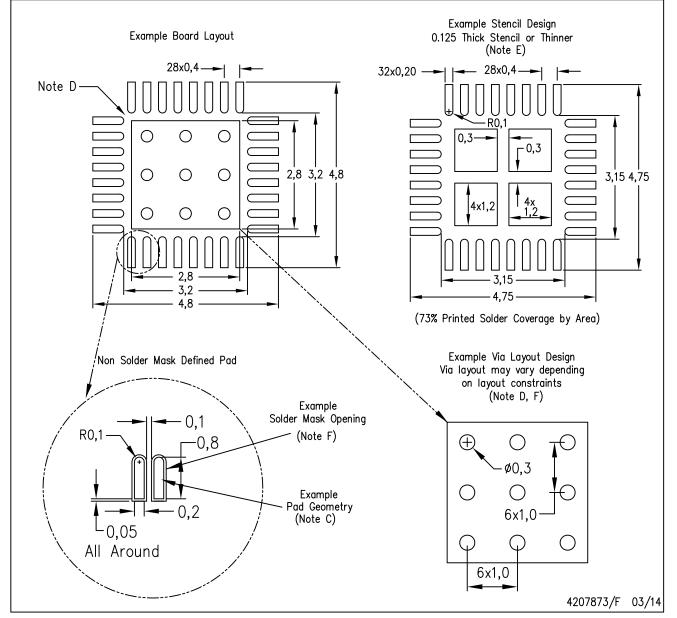


#### NOTE: All linear dimensions are in millimeters



RSN (S-PWQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



#### 重要なお知らせと免責事項

TIは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス・デザインを含みます)、アプリケーションや 設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供してお り、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的に かかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあら ゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプ リケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載す ることは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを 自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TIの製品は、TIの販売条件、または ti.com やかかる TI 製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供され ています。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありま せん。

お客様がいかなる追加条項または代替条項を提案した場合でも、TIはそれらに異議を唱え、拒否します。

郵送先住所:Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2024, Texas Instruments Incorporated