

🕳 Order

Now







DSLVDS1001

JAJSFV3A – JULY 2018 – REVISED DECEMBER 2018

DSLVDS1001 400Mbps、シングル・チャネルのLVDSドライバ

Technical

Documents

1 特長

- 最大400Mbpsの信号処理速度用に設計
- 単一の3.3V電源(3V~3.6Vの範囲)
- 最大差動スキュー700ps(標準値100ps)
- 最大伝搬遅延1.5ns
- 小さなスイング(±350mV)の差動信号レベルを 駆動
- 電源オフ保護(Tri-Stateで出力)
- フロースルーのピン配置によりPCBレイアウトを 簡素化
- 低消費電力(3.3V時の標準値23mW)
- 5ピンのSOT-23パッケージ
- ANSI TIA/EIA-644-A規格を満たすか上回る
- 工業用動作温度範囲(-40°C~+85°C)

2 アプリケーション

- 基板間通信
- 試験/測定
- モータ・ドライブ
- LEDビデオ・ウォール
- ワイヤレス・インフラ
- 通信インフラ
- 多機能プリンタ
- NICカード
- ラック・サーバー
- 超音波スキャナ

3 概要

🥭 Tools &

Software

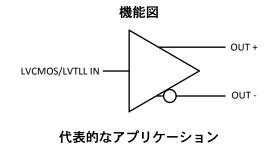
DSLVDS1001デバイスはシングル・チャネルの低電圧差動信号処理(LVDS)ドライバ・デバイスで、低消費電力、低ノイズ、高いデータ・レートを必要とするアプリケーション用に設計されています。さらに、短絡フォルト時の電流も最小化されています。このデバイスは、LVDSテクノロジを使用して、最高400Mbps (200MHz)のデータ・レートをサポートするよう設計されています。

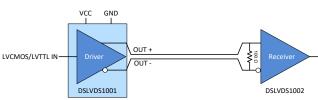
DSLVDS1001は3.3V LVCMOS/LVTTL入力レベルを受け付け、電磁干渉(EMI)の小さい低電圧(標準値± 350mV)の差動信号を出力します。このデバイスは5ピンのSOT-23パッケージで供給され、PCBレイアウトが簡単になるよう設計されています。DSLVDS1001は、コンパニオンのシングル・ライン・レシーバDSLVDS1002、または任意のLVDSレシーバと組み合わせることで、高速なLVDSインターフェイスとなります。

製品情報(1)

型番	パッケージ	本体サイズ(公称)			
DSLVDS1001	SOT-23 (5)	2.90mm×1.60mm			

(1) 提供されているすべてのパッケージについては、データシートの末 尾にある注文情報を参照してください。





1

2

3

4

5

6

7

8

目次

特長1	9	Application and Implementation	9
アプリケーション1	-	9.1 Application Information	
概要		9.2 Typical Application	
改訂履歴		9.3 Design Requirements	
Pin Configuration and Functions		9.4 Detailed Design Procedure	
Specifications		9.5 Application Curve	13
6.1 Absolute Maximum Ratings	10	Power Supply Recommendations	14
6.2 ESD Ratings		10.1 Power Supply Considerations	14
6.3 Recommended Operating Conditions	11	Layout	14
6.4 Thermal Information		11.1 Layout Guidelines	
6.5 Electrical Characteristics		11.2 Layout Example	
6.6 Switching Characteristics	12	デバイスおよびドキュメントのサポート	19
6.7 Typical Characteristics		12.1 ドキュメントのサポート	
Parameter Measurement Information		12.2 ドキュメントの更新通知を受け取る方法	19
Detailed Description		12.3 コミュニティ・リソース	19
8.1 Overview		12.4 商標	19
		12.5 静電気放電に関する注意事項	
8.2 Functional Block Diagram		12.6 Glossary	
8.3 Feature Description	13	メカニカル、パッケージ、および注文情報	
8.4 Device Functional Modes	10	///-//////////////////////////////////	

4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

20	018年7月発行のものから更新	Page)
•	デバイスのステータスを「事前情報」から「量産データ」に変更	1	
•	「ドキュメントのサポート」セクションを追加	19)

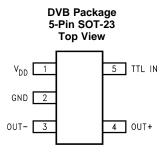


www.ti.com



DSLVDS1001 JAJSFV3A – JULY 2018–REVISED DECEMBER 2018

5 Pin Configuration and Functions



(1) See Package Number DBV (R-PDSO-G5)

Pin Functions

	PIN	1/0	DESCRIPTION
NO.	NAME	1/0	DESCRIPTION
1	V _{DD}	I	Power Supply Pin, +3.3 V ± 0.3 V
2	GND	I	Ground Pin
3	OUT-	0	Inverting Driver Output Pin
4	OUT+	0	Noninverting Driver Output Pin
5	LVCMOS/LVTTL IN	I	LVCMOS/LVTTL Driver Input Pin

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

	MIN	MAX	UNIT
Supply Voltage V _{DD}	-0.3	4	V
LVCMOS input voltage (TTL IN)	-0.3	3.6	V
LVDS output voltage (OUT±)	-0.3	3.9	V
LVDS output short circuit current		24	mA
Lead Temperature – Soldering		260	°C
Maximum Junction Temperature		150	°C
Storage temperature, T _{stg}	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±9000	
V _(ESD)	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 $^{(2)}$	±2000	V

JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Pins listed as ±9000 V may actually have higher performance.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Pins listed as ±2000 V may actually have higher performance.

6.3 Recommended Operating Conditions

	MIN	TYP	MAX	UNIT
Supply Voltage (V _{DD})	3	3.3	3.6	V
Temperature (T _A)	-40	+25	+85	°C

6.4 Thermal Information

	THERMAL METRIC ⁽¹⁾	DBV (SOT-23)	UNIT
		5 PINS	
$R_{ heta JA}$	Junction-to-ambient thermal resistance	179.4	°C/W
R _{0JC(top)}	Junction-to-case (top) thermal resistance	88.7	°C/W
R_{\thetaJB}	Junction-to-board thermal resistance	36.2	°C/W
ΨJT	Junction-to-top characterization parameter	4.6	°C/W
Ψјв	Junction-to-board characterization parameter	35.7	°C/W
R _{0JC(bot)}	Junction-to-case (bottom) thermal resistance	N/A	°C/W

 For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report (SPRA953).

6.5 Electrical Characteristics

Over Recommended Supply Voltage and Operating Temperature ranges, unless otherwise specified.⁽¹⁾⁽²⁾

	PARAMETER	TEST COND	DITIONS	MIN	TYP	MAX	UNIT
V _{OD}	Output Differential Voltage	R _L = 100 Ω (⊠ 7) OUT+, OUT− Pins		250	350	450	mV
ΔV_{OD}	V _{OD} Magnitude Change	R _L = 100 Ω (⊠ 8) OUT+, OUT− Pins			3	35	mV
V _{OS}	Offset Voltage	R _L = 100 Ω (図 7) OUT+, OUT− Pins		1.125	1.25	1.375	V
ΔV_{OS}	Offset Magnitude Change	R _L = 100 Ω (⊠ 7) OUT+, OUT− Pins	(図 7)			25	mV
I _{OFF}	Power-off Leakage	V_{OUT} = 3.6 V or GND, V_{DD} = OUT+, OUT- Pins	V_{OUT} = 3.6 V or GND, V_{DD} = 0 V OUT+, OUT- Pins			±15	μΑ
I _{OS}	Output Short Circuit Current ⁽³⁾	V_{OUT+} and $V_{OUT-} = 0 V$ OUT+, OUT- Pins			-5	-20	mA
I _{OSD}	Differential Output Short Circuit Current ⁽³⁾	V _{OD} = 0 V OUT+, OUT– Pins			-5	-12	mA
VIH	Input High Voltage	TTL IN Pin		2		V_{DD}	V
V _{IL}	Input Low Voltage	TTL IN Pin		GND		0.8	V
I _{IH}	Input High Current	V _{IN} = 3.3 V or 2.4 V TTL IN Pin			<u>+2</u>	±15	μA
IIL	Input Low Current	V _{IN} = GND or 0.5 V TTL IN Pin			<u>+2</u>	±15	μA
C _{IN}	Input Capacitance	TTL IN Pin	TTL IN Pin		3		pF
I _{DD}	Power Supply Current	No Load	$V_{IN} = V_{DD}$ or GND		5	8	A
		R _L = 100 Ω	$V_{IN} = V_{DD}$ or GND		7	10	mA

(1) Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except V_{OD}.

(2) All typicals are given for: $V_{DD} = +3.3$ V and $T_A = +25^{\circ}C$.

(3) Output short circuit current (I_{OS}) is specified as magnitude only, minus sign indicates direction only.

6.6 Switching Characteristics

Over Recommended Supply Voltage and Operating Temperature Ranges, unless otherwise specified. (1)(2)(3)(4)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _{PHLD}	Differential Propagation Delay High to Low	$R_L = 100\Omega, C_L = 15 \text{ pF}$	0.5	1	1.5	ns
t _{PLHD}	Differential Propagation Delay Low to High	(🛛 9 and 🖾 10)	0.5	1.1	1.5	ns
t _{SKD1}	Differential Pulse Skew t _{PHLD} - t _{PLHD} ⁽⁵⁾		0	0.1	0.7	ns
t _{SKD4}	Differential Part to Part Skew ⁽⁶⁾		0	0.4	1.2	ns
t _r	Rise Time		0.2	0.5	1	ns
t _f	Fall Time		0.2	0.5	1	ns
f _{MAX}	Maximum Operating Frequency ⁽⁷⁾		200	250		MHz

(1) All typicals are given for: V_{DD} = +3.3 V and T_A = +25°C.

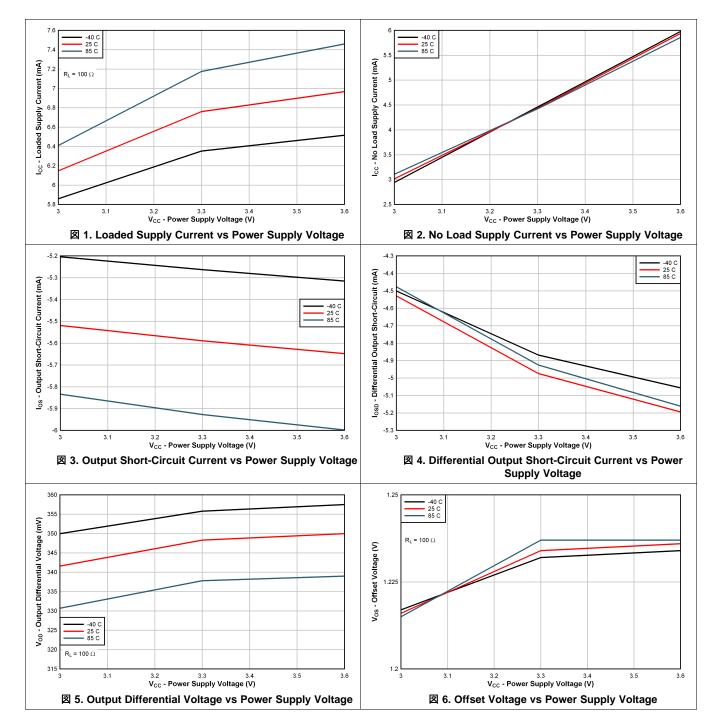
- (2) These parameters are specified by design, and not tested in production. The limits are based on statistical analysis of the device performance over PVT (process, voltage, temperature) ranges.
- (3) C_L includes probe and fixture capacitance.
- (4) Generator waveform for all tests unless otherwise specified: f = 1 MHz, $Z_0 = 50 \Omega$, $t_f \le 1 \text{ ns}$, $t_f \le 1 \text{ ns}$ (10%-90%).
- (5) t_{SKD1}, |t_{PHLD} t_{PLHD}|, is the magnitude difference in differential propagation delay time between the positive going edge and the negative going edge of the same channel.
- (6) t_{SKD2}, part to part skew, is the differential channel to channel skew of any event between devices. This specification applies to devices over recommended operating temperature and voltage ranges, and across process distribution. t_{SKD4} is defined as |Max Min| differential propagation delay.
- (7) f_{MAX} generator input conditions: t_r = t_f < 1 ns (0% to 100%), 50% duty cycle, 0V to 3V. Output criteria: duty cycle = 45%/55%, V_{OD} > 250 mV. The parameter is specified by design. The limit is based on the statistical analysis of the device over the PVT range by the transitions times (t_{TLH} and t_{THL}).

DSLVDS1001 JAJSFV3A – JULY 2018 – REVISED DECEMBER 2018



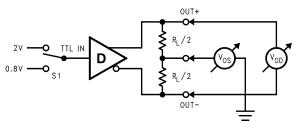
www.tij.co.jp

6.7 Typical Characteristics





7 Parameter Measurement Information



☑ 7. Differential Driver DC Test Circuit

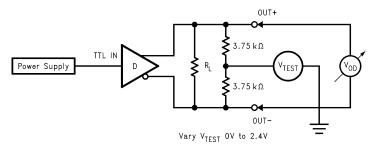


図 8. Differential Driver Full Load DC Test Circuit

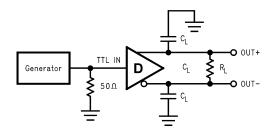
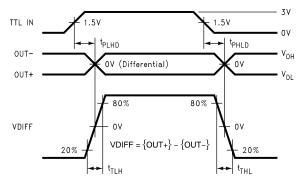


図 9. Differential Driver Propagation Delay and Transition Time Test Circuit





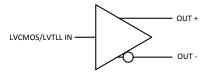


8 Detailed Description

8.1 Overview

The DSLVDS1001 device is a single-channel, low-voltage differential signaling (LVDS) line driver. It operates from a single supply that is nominally 3.3-V, but can be as low as 3-V and as high as 3.6-V. The input signal to the DSLVDS1001 is an LVCMOS/LVTTL signal. The output of the device is a differential signal complying with the LVDS standard (TIA/EIA-644). The differential output signal operates with a signal level of 350 mV, nominally, at a common-mode voltage of 1.2 V. This low differential output voltage results in low emmsions durning electromagnetic compatability (EMC) testing. The differential nature of the output provides immunity to common-mode coupled signals that the driven signal may experience. The DSLVDS1001 device is intended to drive a 100- Ω transmission line. This transmission line may be a printed-circuit board (PCB) or cabled interconnect. With transmission lines, the optimum signal quality and power delivery is reached when the transmission line is terminated with a load equal to the characteristic impedance of the interconnect. Likewise, the driven 100- Ω transmission line should be terminated with a matched resistance.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 DSLVDS1001 Driver Functionality

As can be seen in 表 1, the driver single-ended input to differential output relationship is defined. When the driver input is left open, the differential output is undefined.

		•	
INPUT	OUTPUTS		
LVCMOS/LVTTL IN	OUT +	OUT -	
Н	Н	L	
L	L	Н	
Open	?	?	

表 1. DSLVDS1001 Driver Functionality

8.3.2 Driver Output Voltage and Power-On Reset

The DSLVDS1001 driver operates and meets all the specified performance requirements for supply voltages in the range of 3 V to 3.6 V. When the supply voltage drops below 1.5-V (or is turning on and has not yet reached 1.5-V), power-on reset circuitry set the driver output to a high-impedance state.

8.3.3 Driver Offset

An LVDS-compliant driver is required to maintain the common-mode output voltage at 1.2 V (±75 mV). The DSLVDS1001 incorporates sense circuitry and a control loop to source common-mode current and keep the output signal within specified values. Further, the device maintains the output common-mode voltage at this set point over the full 3-V to 3.6-V supply range.

8.4 Device Functional Modes

The device has one mode of operation that applies when operated within the *Recommended Operating Conditions*.



9 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The DSLVDS1001 device is a single-channel LVDS driver. The functionality of this device is simple, yet extremely flexible, leading to its use in designs ranging from wireless base stations to desktop computers. The varied class of potential applications share features and applications discussed in the paragraphs below.

9.2 Typical Application

9.2.1 Point-to-Point Communications

The most basic application for LVDS buffers, as found in this data sheet, is for point-to-point communications of digital data, as shown in 🛛 11.

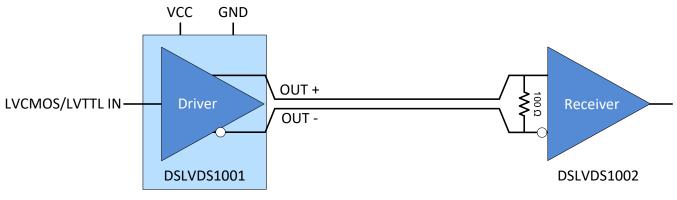


図 11. Typical Application

A point-to-point communications channel has a single transmitter (driver) and a single receiver. This communications topology is often referred to as simplex. In 🛛 11, the driver receives a single-ended input signal and the receiver outputs a single-ended recovered signal. The LVDS driver converts the single-ended input to a differential signal for transmission over a balanced interconnecting media of $100-\Omega$ characteristic impedance. The conversion from a single-ended signal to an LVDS signal retains the digital data payload while translating to a signal whose features are more appropriate for communication over extended distances or in a noisy environment.

9.3 Design Requirements

表 2 shows the design parameters for this example.

DESIGN PARAMETERS	EXAMPLE VALUE			
Driver Supply Voltage (V _{CC})	3 to 3.6 V			
Driver Input Voltage	0 to 3.6 V			
Driver Signaling Rate	DC to 400 Mbps			
Interconnect Characteristic Impedance	100 Ω			
Termination Resistance	100 Ω			
Number of Receiver Nodes	1			
Ground shift between driver and receiver	±1 V			

表 2. Design Parameters

Copyright © 2018, Texas Instruments Incorporated



9.4 Detailed Design Procedure

9.4.1 Driver Supply Voltage

The DSLVDS1001 driver is operated from a single supply. The device can support operation with a supply as low as 3 V and as high as 3.6 V. The driver output voltage is dependent upon the chosen supply voltage. The minimum output voltage stays within the specified LVDS limits (247 mV to 450 mV) for a 3.3 V supply. If the supply range is between 3 V and 3.6 V, the minimum output voltage may be as low as 150 mV. If a communication link is designed to operate with a supply within this lower range, the channel noise margin must be looked at carefully to ensure error-free operation.

9.4.2 Driver Bypass Capacitance

Bypass capacitors play a key role in power distribution circuitry. Specifically, they create low-impedance paths between power and ground. At low frequencies, a good digital power supply offers very low-impedance paths between its terminals. However, as higher frequency currents propagate through power traces, the source is quite often incapable of maintaining a low-impedance path to ground. Bypass capacitors are used to address this shortcoming. Usually, large bypass capacitors (10 μ F to 1000 μ F) at the board-level do a good job up into the kHz range. Due to their size and length of their leads, they tend to have large inductance values at the switching frequencies of modern digital circuitry. To solve this problem, one must resort to the use of smaller capacitors (nF to μ F range) installed locally next to the integrated circuit.

Multilayer ceramic chip or surface-mount capacitors (size 0603 or 0805) minimize lead inductances of bypass capacitors in high-speed environments, because their lead inductance is about 1 nH. For comparison purposes, a typical capacitor with leads has a lead inductance around 5 nH.

The value of the bypass capacitors used locally with LVDS chips can be determined by the following formula according to Johnson⁽¹⁾, equations 8.18 to 8.21. A conservative rise time of 200 ps and a worst-case change in supply current of 1 A covers the whole range of LVDS devices offered by Texas Instruments. In this example, the maximum power supply noise tolerated is 200 mV. This figure varies, however, depending on the noise budget available in the design. ⁽¹⁾

$$C_{chip} = \left(\frac{\Delta I_{Maximum Step Change Supply Current}}{\Delta V_{Maximum Power Supply Noise}}\right) \times T_{Rise Time}$$
(1)
$$C_{LVDS} = \left(\frac{1A}{0.2V}\right) \times 200 \text{ ps} = 0.001 \,\mu\text{F}$$
(2)

 \boxtimes 12 lowers lead inductance and covers intermediate frequencies between the board-level capacitor (>10 μ F) and the value of capacitance found above (0.001 μ F). Place the smallest value of capacitance as close to the chip as possible.





9.4.3 Driver Input Voltage

The DSLVDS1001 input is designed to support a wide input voltage range. The input stage can accept signals as high as 3.6 V.

9.4.4 Driver Output Voltage

The DSLVDS1001 driver output is a 1.2-V common-mode voltage, with a nominal differential output signal of 350 mV. This 350 mV is the absolute value of the differential swing ($V_{OD} = |V^+ - V^-|$). The peak-to-peak differential voltage is twice this value, or 700 mV.

(1) Howard Johnson & Martin Graham.1993. High Speed Digital Design – A Handbook of Black Magic. Prentice Hall PRT. ISBN number 013395724.



Detailed Design Procedure (continued)

In this example, the LVDS receiver thresholds are ±100 mV. With these receiver decision thresholds, it is clear that the disadvantage of operating the driver with a lower supply will be noise margin. With fully-compliant LVDS drivers and receivers, TI expects a minimum noise margin of approximately 150 mV (247-mV minimum output voltage – 100-mV maximum input requirement). If the DSLVDS1001 operates within the 3 V to 3.6 V supply range, the minimum noise margin will drop to 150 mV.

9.4.5 Interconnecting Media

The physical communication channel between the driver and the receiver may be any balanced paired metal conductors meeting the requirements of the LVDS standard, with the key points included here. This media may be a twisted pair, a twinax cable, a flat ribbon cable, or PCB traces.

The nominal characteristic impedance of the interconnect should be between 100 Ω and 120 Ω with a variation no more than 10% (90 Ω to 132 Ω).

9.4.6 PCB Transmission Lines

As per the *LVDS Owner's Manual Design Guide, 4th Edition* (SNLA187), 🛛 13 depicts several transmission line structures commonly used in printed-circuit boards (PCBs). Each structure has a signal line and a return path with a uniform cross-section along its length. A microstrip is a signal trace on the top (or bottom) layer, separated by a dielectric layer from its return path in a ground or power plane. A stripline is a signal trace in the inner layer, with a dielectric layer in between a ground plane above and below the signal trace. The dimensions of the structure and the dielectric material properties determine the characteristic impedance of the transmission line (also called controlled-impedance transmission line).

When two signal lines are placed close by, they form a pair of coupled transmission lines. 🛛 13 shows examples of edge-coupled microstrip lines, and edge-coupled or broad-side-coupled striplines. When excited by differential signals, the coupled transmission line is referred to as a differential pair. The characteristic impedance of each line is called odd-mode impedance. The sum of the odd-mode impedances of each line is the differential pair. In addition to the trace dimensions and dielectric material properties, the spacing between the two traces determines the mutual coupling and impacts the differential pair is called a tightly-coupled differential pair. To maintain constant differential impedance along the length, it is important to keep the trace width and spacing uniform along the length, as well as maintain good symmetry between the two lines.

Detailed Design Procedure (continued)

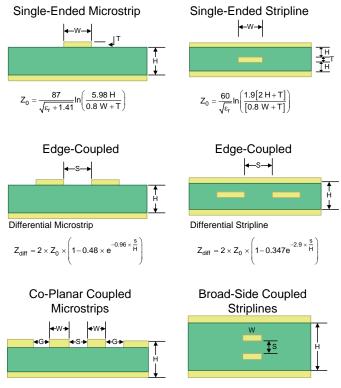


図 13. Controlled-Impedance Transmission Lines

9.4.7 Termination Resistor

As shown earlier, an LVDS communication channel employs a current source driving a transmission line that is terminated with a resistive load. This load serves to convert the transmitted current into a voltage at the receiver input. To ensure incident wave switching (which is necessary to operate the channel at the highest signaling rate), the termination resistance should be matched to the characteristic impedance of the transmission line. The designer should ensure that the termination resistance is within 10% of the nominal media characteristic impedance. If the transmission line is targeted for 100- Ω impedance, the termination resistance should be between 90 Ω and 110 Ω .

The line termination resistance should be placed as close to the receiver as possible to minimize the stub length from the resistor to the receiver.

Remember to only place line termination resistors at the end(s) of the transmission line in these multidrop topologies.



9.5 Application Curve

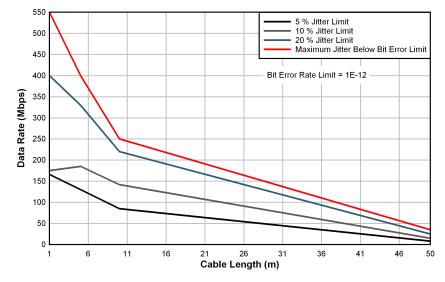


図 14. DSLVDS1001 Performance: Data Rate vs Cable Length

Single-Ended

(2)

10 Power Supply Recommendations

10.1 Power Supply Considerations

The DSLVDS1001 driver is designed to operate from a single power supply with supply voltage in the range of 3 V to 3.6 V. In a typical application, a driver and a receiver may be on separate boards, or even separate equipment. In these cases, separate supplies would be used at each location. The expected ground potential difference between the driver power supply and the receiver power supply would be less than |±1 V|. Board level and local device level bypass capacitance should be used.

Layout 11

11.1 Layout Guidelines

Microstrip vs. Stripline Topologies 11.1.1

As per the LVDS Application and Data Handbook (SLLD009), printed-circuit boards usually offer designers two transmission line options: microstrip and stripline. Microstrips are traces on the outer layer of a PCB, as shown in 図 15.

図 15. Microstrip Topology

Ground Plane

Balanced Pai

On the other hand, striplines are traces between two ground planes. Striplines are less prone to emissions and susceptibility problems because the reference planes effectively shield the embedded traces. However, from the standpoint of high-speed transmission, juxtaposing two planes creates additional capacitance. TI recommends routing LVDS signals on microstrip transmission lines, if possible. The PCB traces allow designers to specify the necessary tolerances for Z_o based on the overall noise budget and reflection allowances. Footnotes 1⁽²⁾, 2⁽³⁾, and $3^{(4)}$ provide formulas for Z_0 and t_{PD} for differential and single-ended traces. ^{(2) (3) (4)}

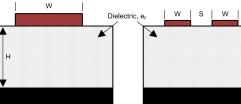
Ground Plane Ground Plane W Reference Plane Reference Plane Single-Ended Balanced Pair

図 16. Stripline Topology

Howard Johnson & Martin Graham. 1993. High Speed Digital Design – A Handbook of Black Magic. Prentice Hall PRT. ISBN number



FXAS ISTRUMENTS



www.tij.co.jp

^{013395724.} Mark I. Montrose. 1996. Printed Circuit Board Design Techniques for EMC Compliance. IEEE Press. ISBN number 0780311310.

Clyde F. Coombs, Jr. Ed, Printed Circuits Handbook, McGraw Hill, ISBN number 0070127549.



Layout Guidelines (continued)

11.1.2 Dielectric Type and Board Construction

The speeds at which signals travel across the board dictates the choice of dielectric. FR-4, or equivalent, usually provides adequate performance for use with LVDS signals. If rise or fall times of LVCMOS/LVTTL signals are less than 500 ps, empirical results indicate that a material with a dielectric constant near 3.4, such as Rogers[™] 4350 or Nelco N4000-13 is better suited. When the designer chooses the dielectric, there are several parameters pertaining to the board construction that can affect performance. The following set of guidelines were developed experimentally through several designs involving LVDS devices:

- Copper weight: 15 g or 1/2 oz start, plated to 30 g or 1 oz
- All exposed circuitry should be solder-plated (60/40) to 7.62 μ m or 0.0003 in (minimum).
- Copper plating should be 25.4 μm or 0.001 in (minimum) in plated-through-holes.
- · Solder mask over bare copper with solder hot-air leveling

11.1.3 Recommended Stack Layout

Following the choice of dielectrics and design specifications, the designer must decide how many levels to use in the stack. To reduce the LVCMOS/LVTTL to LVDS crosstalk, it is a good practice to have at least two separate signal planes as shown in 🛛 17.

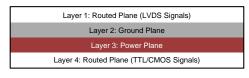


図 17. Four-Layer PCB

注

The separation between layers 2 and 3 should be 127 μ m (0.005 in). By keeping the power and ground planes tightly coupled, the increased capacitance acts as a bypass for transients.

One of the most common stack configurations is the six-layer board, as shown in $\boxed{2}$ 18.

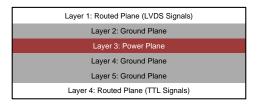


図 18. Six-Layer PCB

In this particular configuration, it is possible to isolate each signal layer from the power plane by at least one ground plane. The result is improved signal integrity, but fabrication is more expensive. Using the 6-layer board is preferable, because it offers the layout designer more flexibility in varying the distance between signal layers and referenced planes, in addition to ensuring reference to a ground plane for signal layers 1 and 6.

11.1.4 Separation Between Traces

The separation between traces can depend on several factors, but the amount of coupling that can be tolerated usually dictates the actual separation. Low-noise coupling requires close coupling between the differential pair of an LVDS link to benefit from the electromagnetic field cancellation. The traces should be $100-\Omega$ differential and thus coupled in the manner that best fits this requirement. In addition, differential pairs should have the same electrical length to ensure that they are balanced, thus minimizing problems with skew and signal reflection.

DSLVDS1001

JAJSFV3A – JULY 2018 – REVISED DECEMBER 2018



Layout Guidelines (continued)

In the case of two adjacent single-ended traces, one should use the 3-W rule: the distance between two traces must be greater than two times the width of a single trace, or three times its width measured from trace center to trace center. This increased separation effectively reduces the potential for crosstalk. The same rule should be applied to the separation between adjacent LVDS differential pairs, whether the traces are edge-coupled or broad-side-coupled.

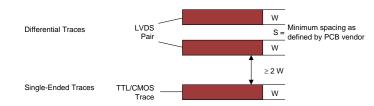


図 19. 3-W Rule for Single-Ended and Differential Traces (Top View)

注 Exercise caution when using autorouters, because they do not always account for all factors affecting crosstalk and signal reflection. For instance, it is best to avoid sharp 90° turns to prevent discontinuities in the signal path. Using successive 45° turns tends to minimize reflections.

11.1.5 Crosstalk and Ground Bounce Minimization

To reduce crosstalk, it is important to provide a return path to high-frequency currents that is as close as possible to its originating trace. A ground plane usually achieves this. Because the returning currents always choose the path of lowest inductance, they are most likely to return directly under the original trace, thus minimizing crosstalk. Lowering the area of the current loop lowers the potential for crosstalk. Traces kept as short as possible with an uninterrupted ground plane running beneath them emit the minimum amount of electromagnetic field strength. Discontinuities in the ground plane increase the return path inductance and should be avoided.

11.1.6 Decoupling

Each power or ground lead of a high-speed device should be connected to the PCB through a low inductance path. For best results, one or more vias are used to connect a power or ground pin to the nearby plane. Ideally, via placement is immediately adjacent to the pin to avoid adding trace inductance. Placing a power plane closer to the top of the board reduces the effective via length and its associated inductance.

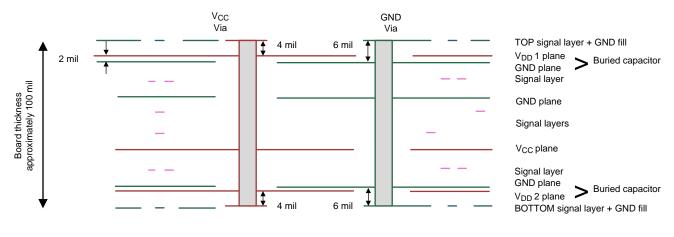




図 20. Low-Inductance, High-Capacitance Power Connection



Layout Guidelines (continued)

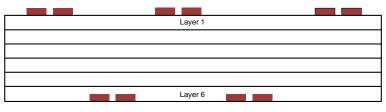
Bypass capacitors should be placed close to V_{DD} pins. They can be placed conveniently near the corners or underneath the package to minimize the loop area. This extends the useful frequency range of the added capacitance. Small-physical-size capacitors, such as 0402 or even 0201, or X7R surface-mount capacitors should be used to minimize body inductance of capacitors. Each bypass capacitor is connected to the power and ground plane through vias tangent to the pads of the capacitor as shown in \mathbb{Z} 21(a).

An X7R surface-mount capacitor of size 0402 has about 0.5-nH body inductance. At frequencies above 30 MHz or so, X7R capacitors behave as low-impedance inductors. To extend the operating frequency range to a few hundred MHz, an array of different capacitor values like 100 pF, 1 nF, 0.03 µF, and 0.1 µF are commonly used in parallel. The most effective bypass capacitor can be built using sandwiched layers of power and ground at a separation of 2 to 3 mils. With a 2-mil FR4 dielectric, there is approximately 500 pF per square inch of PCB. Refer back to 🗵 13 for some examples. Many high-speed devices provide a low-inductance GND connection on the backside of the package. This center dap must be connected to a ground plane through an array of vias. The via array reduces the effective inductance to ground and enhances the thermal performance of the small Surface Mount Technology (SMT) package. Placing vias around the perimeter of the dap connection ensures proper heat spreading and the lowest possible die temperature. Placing high-performance devices on opposing sides of the PCB using two GND planes (as shown in 🗵 13) creates multiple paths for heat transfer. Often thermal PCB issues are the result of one device adding heat to another, resulting in a very high local temperature. Multiple paths for heat transfer minimize this possibility. In many cases, the GND dap that is so important for heat dissipation makes the optimal decoupling layout impossible to achieve due to insufficient pad-to-dap spacing as shown in 21(b). When this occurs, placing the decoupling capacitor on the backside of the board keeps the extra inductance to a minimum. It is important to place the V_{DD} via as close to the device pin as possible while still allowing for sufficient solder mask coverage. If the via is left open, solder may flow from the pad and into the via barrel. This will result in a poor solder connection.



21. Typical Decoupling Capacitor Layouts

At least two or three times the width of an individual trace should separate single-ended traces and differential pairs to minimize the potential for crosstalk. Single-ended traces that run in parallel for less than the wavelength of the rise or fall times usually have negligible crosstalk. Increase the spacing between signal paths for long parallel runs to reduce crosstalk. Boards with limited real estate can benefit from the staggered trace layout, as shown in 🛛 22.

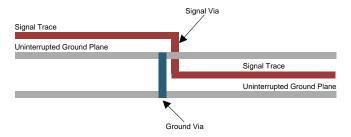


22. Staggered Trace Layout

This configuration lays out alternating signal traces on different layers. Thus, the horizontal separation between traces can be less than 2 or 3 times the width of individual traces. To ensure continuity in the ground signal path, TI recommends that the designer have an adjacent ground via for every signal via, as shown in \boxtimes 23. Note that vias create additional capacitance. For example, a typical via has a lumped capacitance effect of 1/2 pF to 1 pF in FR4.



Layout Guidelines (continued)



23. Ground Via Location (Side View)

Short and low-impedance connection of the device ground pins to the PCB ground plane reduces ground bounce. Holes and cutouts in the ground planes can adversely affect current return paths if they create discontinuities that increase returning current loop areas.

To minimize EMI problems, TI recommends avoiding discontinuities below a trace (for example, holes, slits, and so on) and keeping traces as short as possible. Zoning the board wisely by placing all similar functions in the same area, as opposed to mixing them together, helps reduce susceptibility issues.

11.2 Layout Example

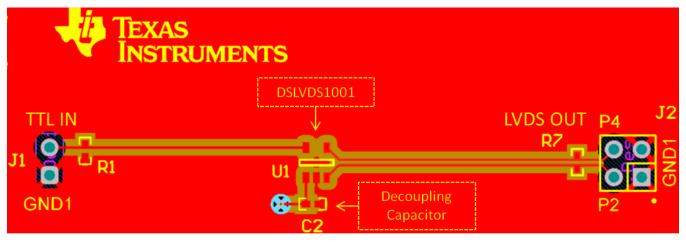


図 24. Layout Example



12 デバイスおよびドキュメントのサポート

12.1 ドキュメントのサポート

12.1.1 関連資料

関連資料については、以下を参照してください。

- 『AN-1194、LVDSインターフェイスのフェイルセーフ・バイアス法』(SNLA051)
- 『LVDSオーナー・マニュアル・デザイン・ガイド、第4版』(SNLA187)
- 『LVDSアプリケーションおよびデータ・ハンドブック』(SLLD009)

12.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。右上の隅にある「通 知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の 詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

12.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™オンライン・コミュニティ *TIのE2E(Engineer-to-Engineer)コミュニティ。*エンジニア間の共同作 業を促進するために開設されたものです。e2e.ti.comでは、他のエンジニアに質問し、知識を共有 し、アイディアを検討して、問題解決に役立てることができます。

設計サポート TIの設計サポート 役に立つE2Eフォーラムや、設計サポート・ツールをすばやく見つけることが できます。技術サポート用の連絡先情報も参照できます。

12.4 商標

E2E is a trademark of Texas Instruments. Rogers is a trademark of Rogers Corporation. All other trademarks are the property of their respective owners.

12.5 静電気放電に関する注意事項



すべての集積回路は、適切なESD保護方法を用いて、取扱いと保存を行うようにして下さい。

静電気放電はわずかな性能の低下から完全なデバイスの故障に至るまで、様々な損傷を与えます。高精度の集積回路は、損傷に対して敏感 であり、極めてわずかなパラメータの変化により、デバイスに規定された仕様に適合しなくなる場合があります。

12.6 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

13 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスに ついて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もありま す。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。



PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
							(6)				
DSLVDS1001DBVR	LIFEBUY	SOT-23	DBV	5	1000	Non-RoHS & Green	Call TI	Level-1-260C-UNLIM	-40 to 85	1TBX	
DSLVDS1001DBVT	LIFEBUY	SOT-23	DBV	5	250	Non-RoHS & Green	Call TI	Level-1-260C-UNLIM	-40 to 85	1TBX	

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



PACKAGE OPTION ADDENDUM

12-Apr-2024



Texas

www.ti.com

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	-	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DSLVDS1001DBVR	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
DSLVDS1001DBVT	SOT-23	DBV	5	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3



PACKAGE MATERIALS INFORMATION

9-Aug-2022



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DSLVDS1001DBVR	SOT-23	DBV	5	1000	210.0	185.0	35.0
DSLVDS1001DBVT	SOT-23	DBV	5	250	210.0	185.0	35.0

DBV0005A



PACKAGE OUTLINE

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 This drawing is subject to change without notice.
 Reference JEDEC MO-178.

- 4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
- 5. Support pin may differ or may not be present.



DBV0005A

EXAMPLE BOARD LAYOUT

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



DBV0005A

EXAMPLE STENCIL DESIGN

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



重要なお知らせと免責事項

TIは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス・デザインを含みます)、アプリケーションや 設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供してお り、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的に かかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあら ゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプ リケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載す ることは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを 自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TIの製品は、TIの販売条件、または ti.com やかかる TI 製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供され ています。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありま せん。

お客様がいかなる追加条項または代替条項を提案した場合でも、TIはそれらに異議を唱え、拒否します。

郵送先住所:Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2024, Texas Instruments Incorporated