FIFO Mailbox-Bypass Registers: Using Bypass Registers to Initialize DMA Control

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Introduction

This application report describes the operation of FIFO mailbox-bypass registers and shows their application in an example that implements the direct memory access (DMA) control of a digital signal processor (DSP). All Texas Instruments (TI) 32- and 36-bit FIFOs contain mailbox-bypass registers that transmit priority data from one FIFO port to the other, either from port A to port B or port B to port A, without storing the data in the FIFO SRAM buffer. The SN74ACT3641, a unidirectional, clocked-DSP, application-specific FIFO (1K x 36), is used as the example for our discussion. In the following scenario, this device connects to a DMA controller that may be viewed as an integral part of any generic processing element. This discussion focuses on the DMA controller that is resident on board the TMS320C31 DSP.

Mailbox-Bypass Register Operation

The operation of the FIFO mailbox-bypass register is straightforward. Each FIFO that features the mailbox option has two 32- or 36-bit bypass registers (Mail1 and Mail2) to pass command and control information between both ports without queuing the information in the FIFO SRAM buffer. The functional block diagram of the SN74ACT3641 is shown in Figure 1. The associated timing of the Mail1 register in the FIFO functional block diagram is shown in Figure 2.
Figure 1. SN74ACT3641 FIFO Functional Block Diagram
Operation of the SN74ACT3641 mailbox-bypass registers is summarized below and shown in Figure 2. The mailbox-select inputs (MBA and MBB) are used to choose between a mail register and the FIFO SRAM for a port data transfer operation. A low-to-high transition on CLKA writes the data on A0–A35 to the Mail1 register when a port-A write is selected by CSA, W/R A, and ENA while MBA is high. Likewise, a low-to-high transition on CLKB writes the data on B0–B35 to the Mail2 register when a port-B write is selected by CSB, W/RB, and ENB while MBB is high. Writing data to a mail register sets its corresponding status flag (MBF1 or MBF2) low. Attempted writes to a mail register are ignored while the mail flag is low.

When the port-B data outputs (B0–B35) are active and the mailbox-select input (MBB) is low, data on the bus comes from the FIFO output register. When the port-B data outputs are active and the port-B mailbox-select input is high, data on the bus comes from the mailbox register (Mail1). The Mail2 register data is always present on the port-A data outputs (A0–A35) when they are active. The Mail1 register flag (MBF1) is set high by a low-to-high transition on CLKB when MBB is high and a port-B read is selected by CSB, W/RB, and ENB. The Mail2 register flag (MBF2) is set high by a low-to-high transition on CLKA when MBA is high and a port-A read is selected by CSA, W/R A, and ENA. Data in a mail register remains intact after it is read and changes only when new data is written to the register.

The mailbox-bypass registers can be easily mapped to a location within a DSP that is separate from the location assigned to the FIFO SRAM within the same memory map. This is made possible by virtue of the mailbox-register control terminals and timing similarities between the mailbox-register read/write operation and the FIFO SRAM read/write operation. An example of assigning the mailbox register and FIFO to the memory map of the TMS320C31 is shown in Figure 3.
DMA Controller Description

The TMS320C31 DSP contains an on-board direct-memory-access (DMA) controller that minimizes the requirement for the CPU to perform input/output operations. The TMS320C31 DSP block diagram is shown in Figure 4. Because of the DMA controller, the TMS320C31 can operate with slow external memories, peripherals, or analog-to-digital converters, for example, without slowing the computational throughput of the CPU.

Address and data buses are specifically dedicated to the DMA. As a result, there exists minimal conflict between the CPU and DMA controller. Using its address generators, source and destination registers, and transfer counter, the DMA controller can react to interrupts much like the CPU. Performing data transfers based upon interrupts received enables the DMA to execute input/output transfers that are typically the task of the CPU. While the DMA is receiving and transmitting data, the CPU is permitted to continue processing data.

A DMA transfer consists of two operations: reading from a memory location and writing to a memory location. These read and write operations can be as a block or a single word. The DMA controller can read from and write to any location in the TMS320C31 memory map, including all memory-mapped peripherals.
FIFO memories, such as the SN74ACT3641, typically channel data between a generic local or backplane bus and a TMS320C31 DSP. The FIFO collects incoming information from the bus and develops packets or vectors of data for transfer to the DSP via the DMA controller (see Figure 5). The packet size of the stored data is easily defined by using the FIFO programmable almost-empty or almost-full flags and, if necessary, its empty and full flags. Data transfers via the DMA controller are performed block by block from the FIFO to the DSP or to off-chip memory such as RAM. The DMA-controlled transfer is preferred for moving large blocks of data. Instead of using the DSP’s CPU for each single-word transfer, investing in a small amount of setup overhead allows the DMA to initialize the transfer of several words. In this case, the DMA controller becomes the bus master and performs the block transfer while the CPU is not using the external bus. The CPU is free to accomplish its primary task of performing mathematical operations.
Generally, the DMA controller requires the following information for data-block transfers: location of the data, destination of the data, and size of the data block to be transferred. The DMA controller is initialized by using the FIFO mailbox-bypass registers. This concept is shown in Figure 6. As previously, mailbox-bypass registers are useful in separating a control word from the data in a FIFO queue. In the example shown in Figure 6, the bypass registers of the SN74ACT3641 FIFO provide the DMA controller with the block-length initialization before performing the block transfer. At the same time, the mailbox-register status flags alert the DMA controller that the FIFO data is ready for transfer. In other instances, the mailbox register can also store a destination address in the DSP memory for incoming data.

In the earlier discussion, data flow through the mailbox register has been assumed to be in the bus-to-DSP direction. However, because of the bidirectional nature of the mailbox feature, the Mail2 register (see Figure 5) can also be used for transferring data in the DSP-to-bus direction. Many bus architectures support burst writes or have virtual addresses that can use the mailbox-bypass register for initialization.
Figure 6. Using Mailbox-Bypass Registers to Initialize DMA Control
Conclusion

Mailbox-bypass registers are very useful in performing block-data transfers from a bus to a processing element or vice versa. Integrating the 32- or 36-bit mailbox registers on board the FIFO chip significantly reduces the device count per system. Likewise, implementing on-board mailbox registers with access timing similar to the FIFO SRAM also reduces the requirement for control logic.

TI’s DSP application-specific FIFOs, in addition to the other application-specific FIFOs with mailbox-bypass registers, are summarized in Table 1.

Table 1. FIFOs Featuring Mailbox-Bypass Registers

<table>
<thead>
<tr>
<th>DEVICE</th>
<th>ORGANIZATION</th>
<th>SPEED SORTS</th>
<th>MAX FREQ</th>
<th>MAX ACCESS</th>
<th>APPLICATION</th>
</tr>
</thead>
<tbody>
<tr>
<td>SN74ACT3622</td>
<td>256 × 36 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3621</td>
<td>512 × 36</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3632</td>
<td>512 × 36 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3638</td>
<td>512 × 32 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3641</td>
<td>1K × 36</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3642</td>
<td>1K × 36 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ACT3651</td>
<td>2K × 36</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>11</td>
<td>DSP</td>
</tr>
<tr>
<td>SN74ABT3611</td>
<td>64 × 36</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>10</td>
<td>High Bandwidth</td>
</tr>
<tr>
<td>SN74ABT3612</td>
<td>64 × 36 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>10</td>
<td>High Bandwidth</td>
</tr>
<tr>
<td>SN74ABT3613</td>
<td>64 × 36</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>10</td>
<td>Internetworking</td>
</tr>
<tr>
<td>SN74ABT3614</td>
<td>64 × 36 × 2</td>
<td>−15, −20, −30</td>
<td>67</td>
<td>10</td>
<td>Internetworking</td>
</tr>
</tbody>
</table>