ABSTRACT

The SNx5DP159 compensates for ISI loss across a transmission line to provide the optimum DP electrical performance from source to sink. Even though DisplayPort®++ to TMDS applications is the intended target application for the DP159, the DP159 can also be used in a DisplayPort application (like a DisplayPort Monitor). This document is intended to be used to describe how to use the DP159 in a DisplayPort application.
1 Introduction

The SNx5DP159 is a Dual Mode DisplayPort® (DP) to Transition Minimized Differential Signal (TMDS) retimer supporting Digital Video Interface (DVI) and High Definition Multimedia Interface (HDMI). The device supports datarates as high as 6 Gbps (HDMI 2.0).

The DP159 is typically used in DisplayPort++ to TMDS applications but can also be used in DisplayPort applications. With its large amount of equalization gain to clean up inter-symbol interference (ISI), retimer functionality to clean up input high frequency (SJ) and random jitter (RJ), the DP159 can also be used in a DisplayPort application where microcontroller or FPGA can configure and manage the DP159. This document details how to implement a DP159 in a DisplayPort application by putting DP159 in a special mode called X-Mode. In X-Mode, the DP159 can support DisplayPort datarates up to 5.4Gbps (HBR2).

1.1 References

1. SNx5DP159 6 Gbps DP++ to HDMI Retimer (SLLSEJ2)
2. DP159 X-Mode Registers (SLLA359)
3. Total Phase Aardvark I2C/SPI Host Adapter
4. VESA DisplayPort Standard Version 1, Revision 2a. May 23, 2012

2 Local I2C Interface

In a DisplayPort application, the DP159 local I2C interface must be used to configure the DP159 PLL, receivers (IN[3:0]P/N), and transmitters (OUT[3:0]P/N). The DP159 internal registers are accessed through the SCL_CTL pin and SDA_CTL pin. The 7-bit I2C slave address of the DP159 is determined by the HDMI_SEL/A1 and EQ_SEL/A0 pins when the I2C_EN pin is high.

Table 1. DP159 I2C Slave Address Options

<table>
<thead>
<tr>
<th>HDMI_SEL/A1 pin</th>
<th>EQ_SEL/A0 pin</th>
<th>7-bit I2C Slave Address</th>
<th>Read Slave Address</th>
<th>Write Slave Address</th>
</tr>
</thead>
<tbody>
<tr>
<td>Low (VIL)</td>
<td>Low (VIL)</td>
<td>7'b1011110 or 0x5E</td>
<td>0xBD</td>
<td>0xBC</td>
</tr>
<tr>
<td>Low (VIL)</td>
<td>High (VIH)</td>
<td>7'b1011101 or 0x5D</td>
<td>0xBB</td>
<td>0xBA</td>
</tr>
<tr>
<td>High (VIH)</td>
<td>Low (VIL)</td>
<td>7'b1011000 or 0x5C</td>
<td>0x8B</td>
<td>0xB8</td>
</tr>
<tr>
<td>High (VIH)</td>
<td>High (VIH)</td>
<td>7'b1011011 or 0x5B</td>
<td>0xB7</td>
<td>0xB6</td>
</tr>
</tbody>
</table>

Figure 1. Local I2C Example Implementation

The example implementation selects the slave address of 7'b1011110.
### 2.1 HPD Implementation

There are two possible implementations for HPD: HPD routed around DP159 or HDP routed thru DP159. Both options are illustrated Figure 2.

![Figure 2. HPD Implementation](image1)

### 2.2 AUX Implementation

The DP159 AUX interface can be used for one of two purposes: (1) Converting I2C-Over-Aux to DDC. (2) Clock output. The conversion of I2C-Over-AUX is not needed for a displayPort sink. The clock output, available only in 48-pin version of DP159, is a divided down (data rate/20 or data rate/40) version of the clock feeding the OUT[3:0]P/N. For example for a 5.4 Gbps (HBR2) data rate, the clock output can be either 135 MHz (divide by 40) or 270 MHz (divide by 20). The clock output maybe useful for some DisplayPort RX that have difficulty tracking the jitter on the OUT[3:0], and therefore, require a reference clock that contains the same high frequency jitter as the OUT[3:0].

![Figure 3. DP159 48-pin QFN AUX Channel Implementation](image2)

Do not connect to the DP159’s AUX interface to the sinks AUX interface.
2.3 DisplayPort Input and Output Implementation

The DP159 has DisplayPort++ receivers (IN[3:0]) and TMDS transmitters (OUT[3:0]). Because the DP159 receivers are DisplayPort++, there is nothing special required to connect the DP159's to a DisplayPort source. The DP159 transmitters are TMDS, and therefore, must be terminated to 3.3 V through a 50-Ω resistor. The 50-Ω resistors must be placed as close to the DP159 pins are possible. Because DisplayPort is a AC-coupled interface, 100-nF capacitors must be inserted after the 50-Ω termination but before the DisplayPort sinks input. To confine the impedance discontinuities caused by pads of the resistor and capacitor, it is recommended to place the AC capacitors closer to the resistors.

Figure 4. DisplayPort Main Link Implementation

2.4 Output VOD Control

As previously mentioned, the DP159 outputs are TMDS transmitters, and therefore, not DisplayPort compliant. The DP159 output voltage swing level is determined directly by value of the resistor used on the VSADJ pin and by the VSWING register. The recommend value of 4.62 KΩ produces a typically peak-to-peak voltage swing of around 1400 mV. The value of the resistor can be reduced to produce a larger voltage swing or increased to produce a smaller voltage swing.

Figure 5. VOD vs VSADJ Resistance

NOTE: Note this chart assumes HDMI termination (single 50-Ω to 3.3 V). The external 50-Ω plus the internal FPGA termination reduces the VOD by as much as 40%.
2.5 DP159 48-pin Example Implementation

Figure 6. DP RX Connector
Figure 7. DP159 RGZ (48-Pin QFN)
50-ohm pullups are required for OUT[2:0]P/N and OUT CLKP/N because these lanes at TMDS transmitters should be close to DP159.

Figure 8. Xilinx FPGA
3 Software Implementation

During link training, the DP159 does not monitor the AUX transaction between a DisplayPort source and a DisplayPort sink as a typical DisplayPort retimer would. Because of this, an external microprocessor (within DisplayPort Source or Sink) must configure the DP159 during all aspects of the link training process.

Software Requirements:

1. Configure DP159 after power up or exiting the reset state (OE pin from low to high).
2. Monitor de-assertion of HPD due to loss of DisplayPort Sink (cable removal)
   (a) Reinitialize DP159 PLL settings when sink is no longer detected.
   (b) Disable Rx and Tx lanes.
   (c) Disable Adaptive Equalizer and enable Fixed EQ.
3. Monitor loss of DisplayPort Source when AUXP transitions from low to high
   (a) Reinitialize DP159 PLL settings when source is no longer detected.
   (b) Disable Rx and TX lanes
   (c) Disable Adaptive Equalizer and enable Fixed EQ.
4. Monitor change in Datarate and number of lanes.
   (a) Must reinitialize DP159’s PLL settings when change in datarate occurs.
   (b) Must enable/disable Rx and Tx paths based on number of lanes.
   (c) Disable Adaptive Equalizer and enable Fixed EQ.
5. During Clock Recovery Phase of Link Training
   (a) Set equalizer to Fixed EQ. The Adaptive Equalizer will not adaptive with a clock pattern
   (b) Monitor when DP159’s PLL is locked.
   (c) After PLL is locked, transition PLL operating mode to PD mode
6. During Channel Equalization Phase of Link Training
   (a) Switch from Fixed EQ to adaptive EQ.

Note vast majority of registers mentioned in this section are not found in the SNx5DP159 datasheet, but can found at: DP159 X-Mode Registers (SLLA359).
4 Initial Power-up Configuration

The following registers must be programmed immediately after power-up or whenever OE transitions from de-asserted (low) to asserted (high).

```c
struct DP159InitT
{
    unsigned short regAddr; //DP159’s register address
    unsigned short regValue; //Data written
};

struct DP159InitT RBR_HBR_HBR2_Common_Init[] = {
    //Page 0
    {0xFF, 0x00}, //Select Page 0
    {0x09, 0x36}, //Enable X-Mode
    {0x0A, 0x7B}, //Disable HPD_SNK pass thru to HPD_SRC.
    {0x0D, 0x80}, //Enable clock on AUX. Select 1/20 mode.
    {0x06, 0x6D}, //Set TX Swing to Max
    {0x10, 0x00}, //Turn off pattern verifier
    {0x16, 0xF1}, //Disable char-alignment on all lanes.
    {0xFF, 0x01}, // Select Page 1

    //CONFIGURE PLL BLOCK
    {0x00, 0x02}, //Enable Bandgap.
    {0x04, 0x80}, //PLL_FBDIV[7:0]
    {0x05, 0x00}, //PLL_FBDIV[10:8]
    {0x08, 0x00},
    {0x0D, 0x02}, //Select LN0 for clock.
    {0x08, 0x03}, //CDR_CONFIG[4:0]. FIXED, LN0.
    {0x01, 0x01}, //CP_EN is PLL mode
    {0x02, 0x3F}, //CP_CURRENT is high.
    {0x08, 0x33}, //Loop Filter to 8K.
    {0xA1, 0x02}, //Allows for Override of PLL settings.
    {0xA4, 0x02}, //Allows for Override of PLL settings.

    //CONFIGURE TX BLOCK
    {0x10, 0xF0}, //ENTX for all four lanes (disable)
    {0x11, 0x30}, //TX_RATE is Full Rate, TX_TERM = 75 to 150 , TX_INVPAIR = None
    {0x14, 0x00}, //HDMI_TWPST1 is 0dB pre-emphasis
    {0x12, 0x03}, //SLEW_CTRL is Normal, SWING is 600mV.
    {0x13, 0xFF}, //FIR_UPD. Load TX settings
    {0x13, 0x00},

    //CONFIGURE RX BLOCK
    {0x30, 0xE0}, //Disable Receivers except lane 0
    {0x32, 0x00}, //PD_RXINT
    {0x31, 0x00}, //RX_RATE is Full
    {0x40, 0x08}, //EQFCTC = 0 and EQLEV = 8
    {0x4C, 0x01}, //Enable Fixed EQ
    {0x34, 0x01}, //Enable Offset correction
    {0x32, 0xF0}, //Load RX settings.
    {0x32, 0x00},
    {0x33, 0xF0}, //Load EQ settings.
    {0xFF, 0x00}, //Select Page 0
    {0x0A, 0x3B}, //Enable HPD_SNK pass thru to HPD_SRC. Retimer
    {0xFF, 0x01}, //Select Page 1
};
```
### 4.1 Reinitialize PLL, RX, and TX Settings

The DP159 PLL, RX, and TX settings must be reinitialized anytime there is a change in datarate, lane count, HPD de-asserted (sink removal), or DisplayPort Source no longer detected.

All registers below are located in DP159 Page 1.

```c
struct DP159InitT
{
    unsigned short regAddr; //DP159's register address
    unsigned short regValue; //Data written
};

struct DP159InitT Disconnect_Event[] = {
    {0x00, 0x02}, //Disable PLL and clear A_LOCK_OVR
    {0x34, 0x01}, //Enable Offset Correction
    {0x02, 0x3F}, //CP_Current is High BW.
    {0x01, 0x01}, //CP_EN is PLL mode
    {0x0B, 0x33}, //PLL Loop filter 8K
    {0x4D, 0x08}, //EQFTC = 0 and EQLEV = 8
    {0x4C, 0x01}, //Set to Fixed EQ
    {0x33, 0xF0}, //Load EQ settings
    {0x10, 0xF0}, //Disable all Tx Lanes
    {0x30, 0xE0}, //Enable Rx Lane 0 only
};
```

### 4.2 Bandwidth and Number of Lanes

Before the beginning of link training, the GPU must inform the sink of the link bandwidth (LINK_BW_SET) and number of lanes (LANE_COUNT_SET). It is at this stage software must to program the DP159’s PLL enable and number of Rx lanes. The TX lanes will be disabled in this step.

```c
#define LBW_HBR2 0x14 // 0x14 = 20 -> 20 * 270 Mbps = 5.40 Gbps
#define LBW_HBR 0x0A // 0x0A = 10 -> 10 * 270 Mbps = 2.70 Gbps
#define LBW_RBR 0x06 // 0x06 = 6 -> 6 * 270 Mbps = 1.62 Gbps

void BW_handler (void) {
    u8 rtxen, eqreg, tsten;
    u16 eq_lev = 8;

    rtxen = (link_lanecnt == 1) ? 0xE1 : (link_lanecnt == 2) ? 0xC3 : 0x0F;
    eqreg = ((link_bw == LBW_HBR2) ? 0x0 : (link_bw == LBW_HBR ) ? 0x1 : 0x2 )<< 4 | (eq_lev & 0x0F);
    tsten = (link_lanecnt == 1) ? 0x11 : (link_lanecnt == 2) ? 0x31 : 0xF1;

    write_csr (0x10, 0xF0); // Disable TX lanes
    write_csr (0x00, 0x02); // Enable Bandgap, Disable PLL, clear A_LOCK_OVR
    write_csr (0x01, 0x01); // CP_EN = PLL (reference) mode
    write_csr (0x0B, 0x33); // Set PLL loop filter
    write_csr (0x02, 0x3F); // Set CP_CURRENT
    write_csr (0x30, rtxen); // Enable RX lanes
    write_csr (0x00, 0x03); // Enable Bandgap, Enable PLL, clear A_LOCK_OVR

    write_csr (0x4C, 0x01); // Enable fixed EQ (use fixed when RX disabled)
    write_csr (0x4D, eqreg); // Set EQFTC and EQLEV (fixed EQ)
}
```

### 4.3 Link Training Clock Recovery phase

While in the clock recovery phase of link training phase, the DisplayPort source is required to transmit a TPS1 pattern. The TPS1 pattern consists of a repetition of D10.2 symbols (without scrambling). This pattern results in a clock at ½ the datarate (2.7 GHz for HBR2, 1.35 GHz for HBR, and 810 MHz for RBR).
4.3.1 Determine PLL Locked

While the DP159 is receiving the TPS1 pattern, software must monitor the DP159’s PLL LOCK_COMPLETE status. The PLL is considered locked when address 0x00 bit 6 in Page 1 is set. Note that depending on the quality of signal being received, the DP159 may not acquire PLL lock until VOD reaches level 1 or Level 2. Because of this, the lock_wait interval must be set to a value large enough to allow the DP159 to acquire lock.

```c
u16 lock_wait = 256; //Approx 300us with 400KHz I2C.

ReadBuffer[0] = 0;
while (ReadBuffer[0] == 0 && lock_cnt < lock_wait) {
    read_csr (0x00);
    ReadBuffer[0] = ReadBuffer[0] & 0x40; // 0x80;
    lock_cnt++;
}
```

4.3.2 Change PLL Mode

Once PLL lock has been achieved, software must immediately transition the PLL mode of operation from PLL_MODE to PD_MODE. The actual PLL setting will be different based on the datarate. It is important to note that A_LOCK_OVR (Page 1 address 0x00 bit 6) must be set to a 1'b1 before transitioning the PLL mode. The following code shows what values based on datarate need to be programmed and the order to program them. It is also important to enable the TX lanes in this stage so that DP sink can start performing clock recovery.

```c
struct DP159InitT
{
    unsigned short regAddr; //DP159’s register address
    unsigned short regValue; //Data written
};

rtxen = (link_lanecnt == 1) ? 0xE1 : (link_lanecnt == 2) ? 0xC3 : 0x0F;

struct DP159InitT RBR_CRDONE[] = {
    {0x10, rtxen} , //Enable TX lanes
    {0x00, 0x23} , //Enable PLL and Bandgap and A_LOCK_OVR
    {0x02, 0x1F} , //CP_CURRENT for RBR.
    {0x0B, 0x30} , //PLL Loop filter 1K.
    {0x01, 0x02} , //CP_EN is PD mode
};

struct DP159InitT HBR_CRDONE[] = {
    {0x10, rtxen} , //Enable TX lanes
    {0x00, 0x23} , //Enable PLL and Bandgap and A_LOCK_OVR
    {0x02, 0x27} , //CP_CURRENT for HBR
    {0x0B, 0x30} , //PLL Loop filter 1K.
    {0x01, 0x02} , //CP_EN is PD mode
};

struct DP159InitT HBR2_CRDONE[] = {
    {0x10, rtxen} , //Enable TX lanes
    {0x00, 0x23} , //Enable PLL and Bandgap and A_LOCK_OVR
    {0x02, 0x5F} , //CP_CURRENT for HBR2.
    {0x0B, 0x30} , //PLL Loop filter 1K.
    {0x01, 0x02} , //CP_EN is PD mode
};
```

4.4 Link Training Channel Equalization Phase

After completing the clock recovery phase of link training, the source will transition to the channel equalization phase. Once in the channel equalization phase, software should enable DP159 adaptive equalizer.

```c
write_csr (0x4C, 0x03); // Enable Adaptive EQ
```
4.5 **REFCLK_OUT**

As mentioned in Section 2.2, the AUX_P and AUX_N can function as a clock output. In order to enable the clock on these pins the following conditions must be true:

- The AUX_CFG bit (Page 0 offset 0Dh bit 7) must be set to a 1'b1.
- The AUX_BRG_EN bit (Page 0 offset 0Ah bit 3) must be set to a 1'b1.
- LOCK_COMPLETE bit (Page 1 offset 00h bit 6) must be set to a 1'b1.
- TX Lane 0 must be enabled (Page 1 offset 10h bit 0 is 1'b1 and Page 1 offset 10h bit 4 is 1'b0).

<table>
<thead>
<tr>
<th>DisplayPort RATE</th>
<th>TX_CLK_TST REGISTER</th>
<th>REFCLK_OUT FREQUENCY (MHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0 = 1/20</td>
<td>1 = 1/40</td>
</tr>
<tr>
<td>RBR (1.62 Gbps)</td>
<td>0</td>
<td>81</td>
</tr>
<tr>
<td>HBR (2.7 Gbps)</td>
<td>1</td>
<td>40.5</td>
</tr>
<tr>
<td>HBR2 (5.4 Gbps)</td>
<td>0</td>
<td>135</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>67.5</td>
</tr>
<tr>
<td></td>
<td>0</td>
<td>270</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>135</td>
</tr>
</tbody>
</table>

5 **DisplayPort Sink Link Training Suggestions**

This section provides suggestions for sink manufacturer on how to communicate with a DisplayPort 1.2 source with a DP159 in the middle.

5.1 **Adjust AUX Read Interval**

The DisplayPort 1.2a standard defines a DPCD register, called TRAINING_AUX_RD_INTERVAL, within the sink that adjusts the timing of the aux read of DPCD link status registers (DPCD address 00202h thru 00204h) and adjust request registers (DPCD address 00206h and 00207h). Typically, a sink defaults this register to 00h. Changing the default to 01h or 02h allows more time for the I^2C writes to the DP159’s DCPD registers to complete.

<table>
<thead>
<tr>
<th>DPCD Address</th>
<th>Definition</th>
<th>Read/Write over AUX Ch</th>
</tr>
</thead>
</table>
| 0000Eh       | TRAINING_AUX_RD_INTERVAL  
Link status/Adjust request read interval during main link training  
00h: 100 µs for main link clock recovery phase and 400 µs for main link channel equalization phase  
01h: 4 ms all  
02h: 8 ms all  
03h: 12 ms all  
04h: 16 ms all  
Other values are reserved | Read-Only             |
5.2 Link Training Clock Recovery (CR) Phase

During link training, a DisplayPort 1.2 compliant source will follow the CR phase of link training detailed in Figure 9. It is important the DisplayPort sink take full advantage of the source behavior. The state diagram shows that CR phase will continue as long as the same VOD level is not used 5 times or a max VOD level is never used. Because of this, the sink CR phase algorithm should never use the same voltage swing level five times or the max voltage swing. Depending on the source, the max voltage swing level can be either Level 2 or Level 3. Typically, a sink algorithm starts at level 0 and progress to level 3. It is suggested to try level 0 two times, level 1 four times, level 2 four times, and level 3 once. Keep in mind source support for level 3 is not required. For the case in which level 3 is not support by the source, level 2 will happen once.

Figure 9. DisplayPort 1.2a Link Training CR Phase State Diagram
5.3 Link Training Channel Equalization (EQ) Phase

During link training, a DisplayPort 1.2 compliant source will follow the channel EQ phase of link training detailed in Figure 10. It is important the DisplayPort sink take full advantage of the source behavior. In the EQ phase of link training, the sink typically requests an increase in pre-emphasis level starting at level 0 and ending at level 3. The channel between DP159 and sink is fixed, and therefore, should be programmed to a fixed voltage swing and pre-emphasis level through the DP159 local I2C interface. The EQ increase requested by the sink not cause the DP159 to increase its output pre-emphasis level. As Figure 10 indicates, a loop count greater than 5 causes EQ phase to end. In order to help ensure a successful EQ phase, the sink channel EQ algorithm should request pre-emphasis level 0 two times, level 1 two times, and level 2 once. The sink is welcome to try other combinations but needs to keep in mind that once is loop count requirement is meet the source ends channel equalization phase of link training.

Figure 10. DisplayPort 1.2a Link Training Channel Equalization Link Phase State Diagram
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