ABSTRACT
This application report describes the ways to optimize the design of DC-DC converters (TPS54040-Q1, TPS54060-Q1, TPS54140-Q1, TPS54160-Q1, TPS54240-Q1, TPS54260-Q1, TPS57040-Q1, TPS57060-Q1, TPS57140-Q1, and TPS57160-Q1) in applications with fast transition at the input voltage on the rising and falling edges. First, the issues faced under such a scenario are analyzed. Then, design considerations are provided so that the application circuit operates according to device specifications (see Section 4 for a list of device data sheets).

Contents
1 Application Solution During Fast Rising Input Transient ......................................................... 2
  1.1 Lowering the Converter Switching Frequency ................................................................. 3
  1.2 Increasing the Voltage-Loop Bandwidth ....................................................................... 3
2 Application Issue during fast falling input transient .............................................................. 4
3 Conclusion .......................................................................................................................... 5
4 Related Documentation ........................................................................................................ 5

List of Figures
1 Output Voltage Overshoot (Channel 1) With Fast Input-Voltage Transient (Channel 3) ................. 2
2 Types of Frequency Compensation (TPS57140-Q1) .......................................................... 3
3 Gain and Phase Plots for Power Stage and Error Amplifier .................................................. 4
4 Gain and Phase Plots for Power Stage and Error Amplifier .................................................. 4
5 Disabling the Device With Fast-Falling Input Transient ...................................................... 5
1 Application Solution During Fast Rising Input Transient

The topics covered in this application report apply to any DC-DC converters in the TPS540x0-Q1, TPS541x0-Q1, TPS542x0-Q1, TPS570x0-Q1, and TPS571x0-Q1 family of devices. For the purposes of this report, use the following example: the input voltage transitions from a low level of approximately 5 V to a high voltage level of approximately 40 V which means a rapid transition of approximately 35 V occurs at the input voltage, \( V_I \). The TPS57140-Q1 device has a minimum on-time of 170 ns. The minimum on-time is limited by many factors such as bond wire and PCB parasitics, propagation delay, and others. However, the system design parameters can be selected in a way that the minimum on-time is no longer a restriction for fast input-voltage transients.

If the system design parameters are not carefully selected, then the output voltage can experience an overshoot because of the minimum on-time limitation that can reach the overvoltage-protection (OVP) threshold of the device.

To ensure that device does not reach the OVP threshold during an input voltage transient, the following condition must be satisfied at a given output voltage and switching frequency across the entire \( V_I \) operating range.

\[
\frac{V_O}{V_I} > t_{on(min)} \times f_{SW}
\]

where

- \( V_O \) is the output voltage of the converter.
- \( t_{on(min)} \) is the maximum limit of the minimum on-time listed in the data sheet.
- \( f_{SW} \) is the switching frequency.

Equation 1

Use the following values for this example: \( f_{SW} = 2 \) MHz, \( t_{on(min)} = 170 \) ns, and \( V_O = 3.3 \) V.

Use Equation 2 to calculate the maximum allowed value for \( V_I \).

\[
V_I < \frac{V_O}{t_{on(min)} \times f_{SW}}
\]

Equation 2 results in \( V_I < 9.7 \) V.

In this case, if the \( V_I \) transient goes above 9.7 V, an overshoot occurs at \( V_O \) because of a violation of the specification for the minimum on-time which may cause the converter to reach the OVP threshold.

![Figure 1. Output Voltage Overshoot (Channel 1) With Fast Input-Voltage Transient (Channel 3)](image)

NOTE: \( V_O \) is AC-coupled in this scope capture.

**Figure 1. Output Voltage Overshoot (Channel 1) With Fast Input-Voltage Transient (Channel 3)**

Figure 1 shows the effect when the output voltage (\( V_O \)) experiences an overshoot during the rising transition. This overshoot, if high, could reach the OVP threshold of the device.
To avoid a $V_O$ overshoot during the rising $V_I$ transition, either lower the switching frequency of the converter or increase the bandwidth of the voltage loop.

### 1.1 Lowering the Converter Switching Frequency

One method to avoid a $V_O$ overshoot during the rising $V_I$ transition is lowering the switching frequency of the converter. If the switching frequency is lowered, then the input voltage changes accordingly as shown in **Equation 3**.

$$V_I < \frac{V_O}{t_{on(min)} \times f_{SW}}$$  \hspace{1cm} (3)

For example, when $f_{SW} = 500$ kHz, $t_{on(min)} = 170$ ns, and $V_O = 3.3$ V, the maximum allow $V_I$ value is calculated as 38.8 V. Therefore, if the $V_I$ transient goes above 38.8 V, an overshoot will occur at $V_O$ because the minimum on-time limitation can reach the OVP threshold of the device.

### 1.2 Increasing the Voltage-Loop Bandwidth

Another method to avoid a $V_O$ overshoot during the rising $V_I$ transition is increasing the bandwidth of the voltage loop. Increasing the bandwidth of the voltage loop allows the converter to respond quickly to the sudden change in the input voltage. As soon as the converter receives this information, the power FET quickly turns off and stops charging the output capacitor.

For example, when $V_I = 35$ V (5- to 40-V change), $V_O = 3.3$ V, inductance ($L$) = 10 µH, and $t_{on(min)} = 170$ ns,

$$\Delta L = \frac{V_I - V_O}{L} t_{on}$$  \hspace{1cm} (4)

This inductor ripple current charges the output capacitor ($C_{OUT}$) and leads to an overshoot at the output voltage. Use **Equation 5** to calculate the change in the output voltage ($\Delta V_O$).

$$\Delta V_O = \Delta L \frac{\text{charge time}}{C_{OUT}}$$  \hspace{1cm} (5)

**Figure 2. Types of Frequency Compensation (TPS57140-Q1)**

If the required change in the output voltage must be within ±4% (0.04 × 3.3 V = 0.132 V), the charging time can be calculated as 9.94 µs (with $C_{OUT} = 47$ µF).

The loop response, if lower than 9.94 µs in this example, can help compensate for the overshoot in the output voltage. Using the standard bandwidth versus response time, use **Equation 6** to calculate the bandwidth which, for this example, results in 35.2 kHz.

$$BW = \frac{0.35}{t_{res}}$$  \hspace{1cm} (6)

where

- $BW$ is the bandwidth.
- $t_{res}$ is the response time.
If values of the compensation network are changed to achieve a bandwidth of 35.2 kHz, the overshoot can be controlled to be within ±4% of \( V_O \). Use the design calculator tool (www.ti.com/tool/tps54-57xx0-calc) for the TPS54xx0-Q1 and TPS57xx0-Q1 to calculate the crossover frequency for the selected R3 and C1 values.

With the following values, \( R_3 = 100 \, \Omega \) and \( C_1 = 2.2 \, \text{nF} \), the crossover frequency is calculated as 14.45 kHz (see Figure 3).

By changing the value of \( R_3 \) to 243 \( \Omega \) and \( C_1 \) to 6.8 nF, the crossover frequency can be increased to approximately 35 kHz (see Figure 4). Increasing the crossover frequency helps limit the overshoot voltage at the output.

Equation 7 shows the basic equation to calculate PSRR.

\[
\text{PSRR} = 20 \log \frac{V_{I(rip)}}{V_{O(rip)}}
\]

where

- \( V_{I(rip)} \) is the input voltage ripple
- \( V_{O(rip)} \) is the output voltage ripple

The fast transition corresponds to higher frequencies. The bandgap noise that is internal to the LDO regulator becomes a limiting factor in the rejection of high frequency components. Using the TPS57140-Q1 design simulation and bench test measurement, the resulting slew-rate value was 1.2 V/µs. If the slew rate is higher than this value, the device is disabled and regenerates a soft start. Higher ESR of the input capacitor negatively affects the slew rate of the input voltage and the duration of this rate because of high current transient across the ESR according to \( \text{ESR} \times C \times \frac{dV}{dt} \). Therefore, the use of a low-ESR ceramic capacitor is recommended.
3 Conclusion

In conclusion, a fast-rising input transient can be avoided by either increasing the voltage-loop bandwidth or reducing the switching frequency of the converter. A fast-falling input transient can be avoided by selecting a low-ESR ceramic input capacitor.

4 Related Documentation

For related documentation, see the following:

- TPS54040-Q1 0.5-A 42-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™, SLVSA26
- TPS54060-Q1 0.5-A 60-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™, SLVSA25
- TPS54140-Q1 1.5-A 42-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™ CONTROL, SLVSA24
- TPS54160-Q1 1.5-A 60-V STEP-DOWN SWIFT™ DC-DC CONVERTER WITH Eco-mode™ CONTROL, SLVS922
- TPS54240-Q1 3.5-V to 42-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™ CONTROL SCHEME, SLVSAQ4
- TPS54260-Q1 3.5-V to 60-V Step-Down Converter With Eco-Mode™, SLVSAH8
- TPS57040-Q1 0.5-A 42-V Step-Down SWIFT™ DC-DC Converter With Eco-mode™, SLVSAP4
- TPS57060-Q1 0.5-A 60-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™, SLVSAP2
- TPS57140-Q1 1.5-A 42-V STEP-DOWN SWIFT™ DC-DC CONVERTER WITH Eco-mode™ CONTROL, SLVSAP3
- TPS57160-Q1 1.5-A 60-V Step-Down SWIFT™ DC-DC Converter With Eco-mode™ Control, SLVSAP1
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