Nano-Power Transimpedance Amplifier (TIA)

Design Goals

<table>
<thead>
<tr>
<th>OVER CURRENT LEVELS</th>
<th>Signal Path Requirement</th>
<th>SUPPLY</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_S ) (min)</td>
<td>( I_S ) (max)</td>
<td>CL Bandwidth</td>
</tr>
<tr>
<td>50 nA</td>
<td>25 µA</td>
<td>&gt; 1Hz</td>
</tr>
</tbody>
</table>

Design Description

The basic transimpedance circuit for amplifying and filtering the output current of a sensor is shown below. The transimpedance amplifier configuration converts the current of the sensor \( I_S \) to a voltage with a gain set by the feedback resistor \( R_F \). The combination of \( R_F \) and \( C_F \) controls the closed loop bandwidth of the circuit by limiting the transimpedance gain at elevated frequencies, while the combination of current source \( I_S \) and capacitor \( C_S \) represents a simplified model for the sensor to be monitored. Typical sensor model values for \( C_S \) are in the mF range. \( R_L \) is a manufacturer recommended load resistance for the sensor and the value ranges from 10 to 100 Ω. In addition to filtering noise, a minimum value for \( C_F \) is required for circuit stability.

An electrochemical gas sensor is a good example of a sensor that requires a transimpedance amplifier. The sensor transduces gas concentration levels (for example carbon monoxide (CO)) into current. The output current ranges from the 10's of nA's to 10's of µA's. Because electrochemical gas sensors are noisy, a low-pass filtering function is necessary to limit the noise bandwidth of the system before driving the input to a comparator and/or an analog-to-digital converter (ADC). Gas sensors typically have response times in the seconds range. So setting the circuit bandwidth to greater than 1Hz is appropriate.

Due to gas sensors’ slow response to changes in gas concentration, a high bandwidth signal path is not required. Therefore, a precision, nano-power, low-bandwidth operational amplifier such as the LPV821 is selected. Another key aspect for this application is low input offset voltage on the operational amplifier to reduce dead-band in the amplifier output. Dead-band equates to the time when the sensor output is not recognized at the amplifier output. Voltage offset is bipolar in nature, with some devices having positive offset while others have negative. In the case of negative offset, changes in sensor output current can not be reliably seen until the negative offset voltage is overcome. Likewise, low offset voltage limits voltage shifts due to the internal resistance of the gas sensor. Lastly, low input bias current is important to minimize sensor measurement errors when measuring low gas concentration levels. The LPV821 is a zero-drift amplifier with 650 nA of quiescent current, µV's of input offset, nV's of offset drift over temperature, and pA's of input bias current.
Design Notes

1. Select gain resistor $R_F$ such that the amplifier output remains within the linear range as specified by the amplifier open-gain (AOL) specification. For the LPV821, $V_{OUT}$ must be limited to $V_{OUT} \leq (V+) - 0.1$ V.

2. Calculate the minimum $C_F$ value where stability of the transimpedance amplifier circuit is ensured.

3. Select $C_F$ such that the amplifier closed loop bandwidth is greater than 1Hz. For gas sensors, the response time of the sensor is typically 10 seconds, so choosing a bandwidth 10x faster will accommodate the sensor speed appropriately while still limiting sensor noise.

Design Steps

1. Select gain resistor $R_F$ such that the max sensor current output of 25 µA does not cause the amplifier output ($V_{OUT}$) to exceed 3.2 V ($(V+) - 0.1$)

   \[
   R_F < \frac{V_{OUT}(\text{max})}{I_S(\text{max})}
   \]

\[
R_F < \frac{3.2 - 0.1}{25 \mu} = 128 \text{ k\Omega}
\]

   select $R_F = 127 \text{ k\Omega}$
   
   (closest real world value)

2. Calculate the minimum $C_F$ for circuit stability using $R_F = 127 \text{ k\Omega}$, $C_S = 1 \text{ mF}$, and LPV821 GBW = 8 kHz.

   \[
   C_F > \frac{1}{4\pi R_F \text{GBW}} \times (1 + \sqrt{8\pi R_F C_S \text{GBW}})
   \]

\[
C_F > \frac{1}{4\pi(127k)(8k)} \times (1 + \sqrt{8\pi(127k)(1m)(8k)})
\]

   $C_F > 400 \text{ nF}$
   
   select $C_F = 1 \mu F$
   
   (guarantee circuit stability)

3. Test low-pass frequency pole value ($f_p$) using $R_F = 127 k$ and $C_F = 1 \mu F$ to make sure it is greater than 1 Hz. If $f_p$ is lower than 1 Hz, reduce the value of $C_F$ to the minimum allowable $C_F$ value from Equation 2. However, if the minimum $C_F$ value does not meet the target circuit bandwidth, the gain setting $R_F$ value will need to be reduced or an amplifier with higher GBW will need to be selected.

\[
\frac{1}{2\pi R_F C_F}
\]

\[
f_p = \frac{1}{2\pi (127k)(1\mu)} = 1.25 \text{ Hz}
\]
Design Simulations

DC Simulation Results

![DC Simulation Graph]

Transient Step Response Simulation Results

![Transient Response Graph]
AC Simulation Results

![AC Simulation Graph]

Noise Simulation Results

![Noise Simulation Graph]
TI Design, Tech Note, and Blog References

See Always-on Low-power Gas Sensing with 10+ Year Coin Cell Battery Life Reference Design TIDA-00756.

See Micropower Electrochemical Gas Sensor Amplifier Reference Design TIDA-00854.

See Extend Battery Life and Simplify Calibration in Gas Sensing Applications SBAA240A.

See Advantages of Using Nanopower Zero Drift Amp for Mobile Phone Battery Monitoring SNOA977.

See GPIO Pins Power Signal Chain in Personal Electronics Running on Li-Ion Batteries SNOA983.


Design Featured Op Amp

<table>
<thead>
<tr>
<th>LPV821</th>
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</tr>
</thead>
<tbody>
<tr>
<td>$V_S$</td>
<td>1.7 V to 3.6 V</td>
</tr>
<tr>
<td>Input $V_{CM}$</td>
<td>Rail-to-rail</td>
</tr>
<tr>
<td>$V_{out}$</td>
<td>Rail-to-rail</td>
</tr>
<tr>
<td>$V_{os}$</td>
<td>1.5 µV</td>
</tr>
<tr>
<td>$V_{os}$ Drift</td>
<td>20 nV/°C</td>
</tr>
<tr>
<td>$I_q$</td>
<td>650 nA/Ch</td>
</tr>
<tr>
<td>$I_b$</td>
<td>7 pA</td>
</tr>
<tr>
<td>UGBW</td>
<td>8 kHz</td>
</tr>
<tr>
<td>#Channels</td>
<td>1</td>
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Design Alternate Op Amp

<table>
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<th>LPV811</th>
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<tbody>
<tr>
<td>$V_S$</td>
<td>1.6 V to 5.5 V</td>
</tr>
<tr>
<td>Input $V_{CM}$</td>
<td>(V-) only</td>
</tr>
<tr>
<td>$V_{out}$</td>
<td>Rail-to-rail</td>
</tr>
<tr>
<td>$V_{os}$</td>
<td>60 µV</td>
</tr>
<tr>
<td>$V_{os}$ Drift</td>
<td>1 µV/°C</td>
</tr>
<tr>
<td>$I_q$</td>
<td>450 nA/Ch</td>
</tr>
<tr>
<td>$I_b$</td>
<td>100 fA</td>
</tr>
<tr>
<td>UGBW</td>
<td>8 kHz</td>
</tr>
<tr>
<td>#Channels</td>
<td>1, 2</td>
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