Designing the TMS320C203 DSP Development Board for TMS320C203 Evaluation

APPLICATION BRIEF: SPRA348

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Designing the TMS320C203 DSP Development Board for TMS320C203 Evaluation

Abstract

This application brief describes the design of the TMS320C203 development board (DVB) from both the hardware and software approach. The DVB is a simple stand-alone application board used to evaluate the performance and characteristics of the TMS320C203 digital signal processor (DSP) hardware and software.

The DVB contains the Texas Instruments (TI™) TMS320C203 DSP and provides full-speed verification of TMS320C203 codes. Communication with the host PC is configured through an RS-232 interface via the built-in UART (Universal Asynchronous Receiver and Transmitter) port. The DVB transmits and receives the analog signals via the analog interface circuit (AIC) and operational amplifier (OP Amp, OPA) port. The DVB connects with the XDS-510 (JTAG - Joint Testing Action Group, IEEE1149.1 Standard) and uses the TMS320C2xx (‘C2xx) emulation software as a debugging tool.

This application brief discusses the technologies behind the power system, clock, AIC/OPA, UART, and DSP. We focus on the memory configuration and code development for direct communication between on-chip synchronized/ asynchronized serial port and serial devices AIC/RS-232.

NOTE:

You may see the term DSK in the circuits described in this application report. The DVB was originally named TMS320C203 DSP Starter Kit (DSK), which is a formal name at TI, then renamed DVB on completion of the project.
The authors extend their deep appreciation to Chaucer Kuo, William Chen, Kevin Chang, Gene Lin and Jeffery Lai from the ASP-DSP Application Team; Jerry Chen from the ASP-ASIC Team; Ryan Hsiao from MSLP; and Vivian Shao from the Taiwan CAC Team for their invaluable help in this project.
Product Support

Related Documentation

- **TMS320C203, TMS320C209, TMS320VC203 Digital Signal Processors**, Literature number SPRS025
- **TMS320C1x Evaluation Module Analog Interface Application Report**, Literature number SPRA029
- **TMS320C5x DSP Starter Kit User’s Guide**, Literature number SPRU101
- **TLC320AC02C, TLC320AC02I Single-Supply Analog Interface Circuit Data Manual**, Literature number SLAS084A
- **MOS Memory Commercial and Military Specifications Data Book**, Literature number SMYD095
- **Operational Amplifiers and Comparators Data Book, Volume B**, Literature number SLYD012
- **F Logic (SN54/74F) Data Book**, Literature number SDFD001B
- **ABT Advanced BiCMOS Technology A High Performance Line of 5-V and 3.3-V Products Data Book**, Literature number SCBD002B
- **Data Transmission Circuits Data Book, Volume 1**, Literature number SLLD001A
- **Semiconductor Group Package Outlines Reference Guide**, Literature number SSYU001B
- **UMC UM61256G Series 32Kx8 CMOS SRAM**

World Wide Web

TI’s World Wide Web site at www.ti.com contains the most up-to-date product information, revisions, and additions. New users must register with TI&ME before they can access the data sheet archive. TI&ME allows users to build custom information pages and receive new product updates automatically via email.
Introduction

The TMS320C203 DVB enhances the ability to create your own project by implementing software codes, building daughter boards, and expanding your system as desired. Figure 1 shows the DVB block diagram, which includes the following components:

- TMS320C203 DSP
- TLC320AC01 AIC and TLE2064 operational amplifier for the analog I/O port
- 32K SRAM and 32K EPROM configurable for program and data memory
- UART RS-232 port
- JTAG (Joint Testing Action Group, XDS-510) port
- Power supply for +5 V, -5 V, +12 V, -12 V, analog ground, and digital ground
- 10 MHz oscillator for both the TMS320C203 DSP and TLC320AC01 AIC

Figure 1. TMS320C203 DVB Block Diagram
Hardware Description

The TMS320C2xx generation of the TI TMS320 DSP is fabricated using static CMOS integrated circuit technology. The combination of advanced Harvard architecture, on-chip peripherals, on-chip data memory, and a highly specialized instruction set is the basis for the operational flexibility and speed of this device.

TMS320C203 Digital Signal Processor

The TMS320C203 DSP, packaged in a 100-pin PZ TQFP, includes the following features:

- T320C2xLP core CPU
- Source code downwardly compatible with the TMS320C1x and TMS320C2x and upwardly compatible with the TMS320C5x
- 544 words of on-chip, dual-access data RAM for B0, B1, and B2 blocks
- Input clock options of x1, x2, x4 or /2
- On-chip 16-bit timer
- 0-7 wait states software programmable to each space
- One synchronous serial port with four-level deep FIFOs
- Full-duplex asynchronous serial port (UART)
- XDS-510 (JTAG) port fully supported

Figure 2 shows the top view of the 100-pin TMS320C203 DSP PZ package. The package includes the following pin groups:

- Parallel data (D0-D15), address bus (A0-A15), and memory control signals
  Used for data transfer between the TMS320C203 DSP and external memory
- Initialization, interrupts, and reset operation control pins
  Provides direct control of the DSP
- Synchronous serial port and asynchronous serial (UART) port signals
  Communicates with the host or other devices having the same kind of the port
- Multiprocessing signals
  Cooperates with other DSPs
- Oscillator, phase-locked loop (PLL), and timer signals
- Power supply pins
- JTAG signals

Defined in the IEEE1149.1 standard and accessed by the emulator.

Appendix A shows circuit schematics designed using these pin definitions.

Figure 2. TMS320C203 DSP PZ Package – Top View

The TMS320C203 is the most cost-effective DSP chip with high MIPS in the fixed-point DSP family. The device is built on the high-performance T320C2xLP core and integrates on-chip peripherals that make it well suited for a variety of applications, including:
- Set-top boxes
- Power line monitors
- Solid state relays
- Hard disk drives
- CD-ROMs
- Feature phones
- Phone-like data modems for LCD phone displays
- Caller ID
- DTMF
- Voice mail
- Centrex modems.

The TMS320C203 DSP is designed so that manufacturers of high-volume applications can reap the benefits of high performance DSPs without paying the higher prices historically associated with them. System code and hardware development for the T320C2xLP core is supported using JTAG scan-based emulation. The serial scan interface to the core is bonded out of the device so that the XDS-510 system emulator can interface with the DSP core. In this way, the system tested and verified using the TMS320C203 DVB can be designed with or without a daughter board.

**TLC320AC01 Analog Interface Circuit**

The TLC320AC01 AIC is an audio-band signal processor that simultaneously provides an analog-to-digital/digital-to-analog input/output interface system on a single, monolithic CMOS chip. The A/D, D/A, and AIC combination is useful to the DSP solution design. The AIC includes the following features:

- Needs only a single 5 V power supply
- Synchronous serial port Interface
- General-purpose, signal-processing analog front end (AFE)
- 14-bit dynamic-range ADC and DAC in 2s-complement data format
- (Sin X)/X compensation supported
- Programmable filter bandwidths (up to 10.8 KHz)
- Programmable output gain
Figure 3 shows the TLC320AC01 AIC functional block diagram.

**Figure 3. TLC320AC01 Functional Block Diagram**

\[
f(\text{LP}) = \frac{\text{FCLK}}{40} = \frac{\text{MCLK}}{\text{A Reg} \times 80}
\]

\[
f(\text{HP}) = \frac{\text{fs}}{200} = \frac{\text{MCLK}}{\text{A Reg} \times \text{B Reg} \times 400}
\]

Use the asynchronous serial port to send information controlling the configuration and performance parameters by eight available data registers. The data in the registers set up the device for a given mode of operation and application. The anti-aliasing input low-pass filter is a switched-capacitor filter with a sixth-order elliptic characteristic, followed by a second-order \((\sin X)/X\) correction filter, followed by a three-pole continuous-time filter to eliminate images of the filter clock signal.

The high-pass filter is a single-pole filter that preserves low-frequency response as the low-pass filter cutoff is adjusted by the parameters in the related register (see Figure 3). Since the TLC320AC01 is a one-frame, synchronous signal only, we should connect the 'C203/FSR and 'C203/FSX with the 'AC01/FS pin. The transmit and receive clock are of the same design.

Two packages are available with the TLC320AC01 AIC (Figure 4 shows the top views of both packages):

- 28-pin FN PLCC
- 64-pin PM TQFP

The TMS320C203 DVB uses the 28-pin FN PLCC.
TLE2064 Operational Amplifier

The AIC uses differential input and output and thus requires an operational amplifier (OP Amp, OPA). Because the AIC uses a single 5 V power supply only, we should take care of the middle point voltage \(V_{\text{MID}}\). Figure 5 and Figure 6 show the differential input with \(V_{\text{MID}}\) and differential output designs.

Figure 5. Differential Input
The TLE2064 is an audio band operational amplifier. Both 5~15 V and -5~15 V should be offered to this chip, and 12 V and -12 V are chosen for the DVB. The TLE2064 combines outstanding output drive capability with low power consumption, excellent DC precision, and wide bandwidth. In addition to maintaining traditional JFET advantages of fast slew rates, low input bias, and offset currents, the TI Excalibur process offers outstanding parametric stability over time and temperature. The result is a precision device that remains precise, even with changes in temperature and long time in use.

Figure 6. Differential Output

To enlarge the input and the output signals, semi-variable resistors are used as input resistors of the operational amplifiers. Unfortunately, because the DC signals are enlarged along with the AC signals, the operational amplifiers are easily saturated. For this reason, two capacitors are cascaded between the operational amplifiers and the I/O connectors as the AC couplers. Only AC signals that are large enough can be received and transmitted.

External Memory

The TMS320C203 DVB 64K words of external memory are split into SRAM and EPROM. You can configure the SRAM and EPROM as the upper 32K words and the lower 32K words by themselves, or vise versa.

Figure 7 shows the block diagram of the external memory system. These areas can be used as either program or data memory, as defined by the assembly code. The priority of usage in internal, on-chip data memory is higher than that for external data memory, so regardless which memory you select, the B0, B1, and B2 data memory areas are always used in the internal dual access RAM.
The 32K-word SRAM is combined by two 32K x 8 bits memory devices. The allowable memory access time must be under 15 ns because the TMS320C203 operates at such high speed. We use these two chips of SRAM in parallel, which means that one chip is the upper byte and the other is the lower byte.

The other 32K-word EPROM uses a 64K-word chip with a tri-state buffer made by Advanced Bipolar Technology for faster response. Since SRAM is much faster than EPROM, the tri-state buffer separates these two kinds of memory to avoid bus conflict problems (see Figure 8).
The TMS320C203 DSP can start the program only from program address 0000h and thus cannot be designed as the EPROM or the SRAM area in the fixed addressing position for the stand alone demo board design.

If you locate the SRAM in address 0000h-7FFFh and the EPROM in address 8000h-FFFFh, you can use the DVB connected with the XDS-510 (JTAG) as an emulation tool.

If you locate the EPROM in address 0000h-7FFFh and the SRAM in address 8000h-FFFFh, you can use the DVB as a stand-alone demonstration board.

Asynchronous Serial (UART, RS-232) Port

The TMS320C203 DVB provides communication with the PC host or other serial device via the UART/RS-232 port. Two problems must be resolved in the DVB’s asynchronous serial port design:

- Voltage caused by the 9 V signals required for the RS-232
- No handshaking pin in the TMS320C203 DSP

Both the SN75188 and SN75189 chips deal with the first problem. Both chips function as the data buffer for the voltage transfer from 5 V to 9 V and 9 V to 5 V requested by the RS-232 specification. The SN75188 and SN75189 chips invert the signals between the development board and the RS-232 serial port of the PC host.

Only two pins provide TX and RX for the asynchronous serial port in the TMS320C203 DSP. In the communications system, not only is the data transmission used but the handshaking signals also have to be controlled. To build up the handshaking signals, the following four general I/O pins are also supported on the TMS320C203 DSP:

- IO0 for DTR (Data Terminal Ready)
- IO1 for DSR (Data Set Ready)
- IO2 for RTS (Request to Send)
- IO3 for CTS (Clear to Send)

Connecting these pins along with the power supply pins are designed for asynchronous serial port to the DB9 connector, as shown in Figure 9 (see Appendix A for circuit schematics).
Figure 9. RS-232 9-Pin Connector (DB9)

1. DCD - Data Carrier Detector
2. RXD - Received Data
3. TXD - Transmitted Data
4. DTR - Data Terminal Ready
5. GND - Signal Ground
6. DSR - Data Set Ready
7. RTS - Request to Send
8. CTS - Clear to Send
9. RI - Ring Indicator

JTAG (XDS-510)

To perform emulation with the XDS-510 following the IEEE 1149.1 specification, the target system must have a 14-pin header (two 7-pin rows, 0.025” x 0.235") with connections shown in Figure 10. Seven pins on the TMS320C203 DSP chip are used for the JTAG. These pins, as well as the power supply pins, are mapped to the 14-pin header.

Pin 11 on the JTAG pod is the Test Clock (10 MHz output) signal, which is generated from the emulator pod. I have an experience to parallel a diode in the inverse mode for the impedance compatibility problem solving. The TMS320C2xx emulation system may not connect properly if the TMS320C203 DSP (Batch Number 5349653) is used on the DVB.

Figure 10. JTAG Cable Header and Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TRST - Test Reset</td>
</tr>
<tr>
<td>2</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>3</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>4</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>5</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>6</td>
<td>No Pin (Key)</td>
</tr>
<tr>
<td>7</td>
<td>TCK_RET - Test Clock Return</td>
</tr>
<tr>
<td>8</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>9</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>10</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>11</td>
<td>TCK - Test Clock</td>
</tr>
<tr>
<td>12</td>
<td>GND - Ground</td>
</tr>
<tr>
<td>13</td>
<td>EMU0 - Emulation Pin 0</td>
</tr>
<tr>
<td>14</td>
<td>EMU1 - Emulation Pin 1</td>
</tr>
</tbody>
</table>

CAUTION:
Cut the No Pin (pin 6) to avoid plugging the connector in the wrong direction and thus connecting the Presence pin (5) with Ground and the Ground pin (10) with VCC (5 V).
This would connect the Presence pin and VCC with possibly serious results.

Power System

The power system design of the TMS320C203 DVB is a formal design similar to that of the TMS320C50 DSK design. The DVB includes more capacitors for noise bypass and an LED as a power indicator. The AC-9V adapter used with the TMS320C50 DSK can be used with the DVB as well.

The most important design consideration for the DVB power system is that digital ground connects to analog ground via a ferrite bead (a kind of core, 800 ohm/100 MHz = 1.27 μH). The resistance of the inductor in the frequency domain $Z(f) = j2\pi fL$

Where

\[ j = \text{the image value} \]
\[ f = \text{the frequency value} \]
\[ L = \text{the inductor value} \]

Thus, the high frequency of the noise generated from the digital ground cannot interfere with the analog ground. Analog devices, such as the AIC and OPA, will work more stable than before. In addition, this approach avoids EMI (electromagnetic interference) problems, because the analog devices are used always as the front-end components.

*Figure 11. Ground System*
Layout Issues

Because of the high frequencies of the signals running on the data and address buses between the TMS320C203 DSP and SRAMs, these two components must be placed as close as possible to each other. For the same reason, much noise is generated around these buses, which is why a four-layer board is implemented.

The TMS320C203 DVB offers the flexibility DSP application engineers require in an evaluation or development tool. A variety of component packages can be used:

- Either DIP or SMD LED package
- Either 1206 or 0805 resistors and capacitors
- Either full- or half-size oscillator
- Any one of three kinds of semi-variable resistor packages

Several connectors for the extension board are reserved; thus, you can make your own design based using the DVB.
Software Description

Memory Configuration

The memory configuration is the most important consideration when writing assembly code (see Figure 12). As mentioned above, the priority of usage to internal data memory is higher than it is for external data memory (see External Memory). Regardless which memory you select, the B0, B1, and B2 data memory is always used in the internal RAM (for a discussion of registers, see the TI TMS320C2xx User’s Guide).

**Figure 12. Memory Configuration**
Echo Program

The Echo program enables the synchronous serial port to communicate with the TLC320AC01 AIC. Before the analog signal from the audio input is converted to digital data and then received by the DSP, the TLE2064 operational amplifier enlarges it.

After the AIC passes the digitized data to the DSP via the synchronous serial port, the DSP receives the data and sends it back directly via the synchronous serial port. If the function generator is used as the signal source and the oscilloscope is used as the observer, the same wave shape will be seen on the screen. The hardware signal communication paths are shown in Figure 13.

Figure 13. Signal Communication Path

The TMS320C203 synchronous serial port, which is controlled differently than the TMS320C50 DSP, offers the following features:

- Two four-word-deep FIFO buffers
- Interrupts generated by the FIFO buffers
- Maximum transmission rate of CLKOUT1/2
- Wide range of operating speeds
- Burst and continuous modes of operation

The synchronous serial port requires three kinds of signals:

- Clock signal
  Controls timing during the transfer and can be generated by an internal or external source.
- **Frame sync signal**
  Synchronizes transmit and receive operations at the start of a transfer and can be generated by an internal or external source.

- **Data signal**
  Carries the actual data transferred in the transmit/receive operation. The data signal transmit pin (DX) of one device should be connected to the data signal receive (DR) pin of another device.

The synchronous serial port also uses two on-chip, I/O-mapped registers as the synchronous serial port control register (SSPCR, FFF1h@IO) and the synchronous serial port transmit/receive register (SDTR, FFF0h@IO). Figure 14 shows how to connect the synchronous serial port with other devices.

**Figure 14. Connecting the Synchronous Serial Port with Other Devices**

Transmitting a word through the synchronous serial port is a four-step process as follows:

**Step 1:** Your software writes up to four words to the transmit FIFO buffer through the SDTR.

**Step 2:** The transmit FIFO buffer copies the first-written word to the transmit shift register (XSR) when the XSR is empty.

**Step 3:** The XSR shifts the data bit by bit (MSB first) to the DX pin.

**Step 4:** The XSR lets the FIFO buffer know when it is empty.

  a) If the FIFO buffer is full, the process repeats starting at Step 2.

  b) If the FIFO buffer is empty, it sends a transmit interrupt (XINT) to request more data and transmission stops.
Receiving a word from the synchronous serial port is a four-step process as follows:

**Step 1:** Data from the DR pin is shifted bit by bit (MSB first) into the receive shift register (RSR).

**Step 2:** When the RSR is full, the RSR copies the data to the receive FIFO buffer.

**Step 3:** One of two actions occur, depending on the state of the receive FIFO buffer.
   a) If the receive FIFO buffer is not full, the process starts over at Step 1.
   b) If the receive FIFO buffer is full, it sends a receive interrupt (RINT) to the processor to request servicing.

**Step 4:** The processor reads the received data from the receive FIFO buffer through the SDTR.

*Figure 15. Synchronous Serial Port Block Diagram*

For more information regarding the synchronous serial port, see the TI *TMS320C2xx User's Guide*.

Example 1 and Example 2 show the Echo.Asm and AIC_Table.Inc files. The polling mode is used in this program in addition to the interrupt mode.

A single-layer FIFO buffer is set up to avoid two problems not discussed in the *TMS320C2xx User’s Guide*:

- If the transmit FIFO buffer is not full or empty, the status will be unknown.
If the FIFO buffer is not full, the receive FIFO buffer will not generate the RINT.

At the beginning of the Echo.Asm program, the interrupt vector table should be defined in program address from 0000h to 0040h, and the I/O wait-state and synchronous serial port should be initialized (see Example 1).

Afterward, the AIC can be programmed through the synchronous serial port by the AIC setup table, shown in Example 2. The data can be transmitted and received successfully by RINT, since the CLKX and CLKR are connected together, and the RINT is in a higher priority.

**Example 1. Echo.Asm File**

```assembly
.title "Echo Program"

TMVER .equ 0

.MMregs
.include "AIC_TBLE.INC"

SDTR .set 0FFF0h
SSPCR .set 0FFF1h
WSGR .set 0FFFCh
RFNE .set 15 - 12
TCOMP .set 15 - 13

.sect "vectors"
B BEGIN
.space 2 * 16
.space 2 * 16
.space 2 * 16
B R_ISR
B X_ISR
.space 2 * 16

.r_port .set PORT
.x_port .set r_port + 1
.ctrl .set x_port + 1

.text
BEGIN:
SETC INTM
LDP #PORT

.SETC INTM
```

**Example 2. AIC Setup Table**

```assembly

Set the AIC configuration and control registers:

1. Set SDTR (Synchronous Data Transmit/Receiver) register to 0FFF0h.
2. Set SSPCR (Synchronous Serial Port Control Reg.) register to 0FFF1h.
3. Set WSGR (Wait-State Generator) register to 0FFFCh.
4. Set RFNE (Receive FIFO Not Empty Bit) to 15 - 12.
5. Set TCOMP (Transmit Complete Bit) to 15 - 13.

Disable the interrupt:

```
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SPLK #0000h, ctrl ;; 0-Wait State Set
OUT ctrl, WSGR

;; Init Serial Port Control Register, User’s Guide 9-7
SPLK #0000000000000010b, ctrl ;; Write the Value with Reset
OUT ctrl, SSPCR
SPLK #0000000000110010b, ctrl ;; Go!
OUT ctrl, SSPCR

;; AIC initialization Routine
LACL #(AICTBL) ;; Load Address to AIC Control Table
LAR AR1, #AICTBL_LENGTH - 1
MAR *, AR1

AIC_LOOP:
TBLR x_port ;; Load Data from AIC Control Table|
OUT x_port, SDTR

AIC_WAIT:
IN ctrl, SSPCR ;; Waiting for Transmit Complete Bit
BIT ctrl, TCOMP
BCND AIC_WAIT, NTC
ADD #1 ;; To Next One
BANZ AIC_LOOP, *-

;; Enable RINT and XINT
LDP #0
SPLK #0000000000011000b, IMR ;; Set RINT, XINT
CLRC INTM ;; Enable Interrupt

LOOP:
NOP ;; Waiting for Interrupt
B LOOP

;; Interrupt Service Routines
R_ISR:
SETC INTM ;; Receive Interrupt Service Routine
LDP #0 ;; Disable Interrupt
IFDEF TMVER = 1 ;; TMP Chip Version
LACL #00018h ;; Clear the RINT and XINT Flag
ENDIF
IFDEF TMVER = 0 ;; TMX Chip Version
LACC IFR ;; Clear the RINT and XINT Flag
ENDIF
AND #0FFE7h
SACL IFR

LDP #PORT ;; Get the Data from FIFO
IN r_port, SDTR
CALL PROCESS ;; Process

LDP #PORT
OUT x_port, SDTR ;;
CLRC INTM ;; Enable Interrupt
RET

X_ISR:
SETC INTM ;; Disable Interrupt
LDP #0
.IF TMVER = 1 ;; TMP Chip Version
LACL #00018H ;; Clear the RINT and XINT Flag
.ENDIF
.IF TMVER = 0 ;; TMX Chip Version
LACC IFR ;; Clear the RINT and XINT Flag
AND #0FFE7H ;;
.ENDIF
SACL IFR ;;
CLRC INTM ;; Enable Interrupt
RET

;; Process

PROCESS:
LDP #PORT
LACC r_port ;; Let Transmit = Receive Port
SACL x_port ;;
RET

;; End of Echo.Asm

Example 2. AIC_Table.Inc File

;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;; Header File: AIC_Table.Inc
;; Description TLC320AC01/02 AIC Initialization Data
;; 1. Master Clock (MCLK) = 10.0 MHz
;; 2. Frame Sync Clock (FCLK) = MCLK / (2 * A) = 142.857 kHz.
;; 3. Sample Rate = FCLK / B = MCLK / (2 * A * B) = 9.524 kHz.
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
.data
AICTBL .word 0000h ;; Silent Padding
.word 0000h ;; Silent Padding
.word 0000000000000011b ;; Control Request
.word 0000000100100011b ;; A = 0x23 = 35
.word 0000000000000011b ;; Control Request
.word 0000001000001111b ;; B = 0x0F = 15
.word 0000h ;; Silent Padding
.word 0000h ;; Silent Padding
.word 0000h ;; Silent Padding
AICTBL_LENGTH .equ $ - AICTBL
AIC_END

;; End of AIC_Table.Inc

UART Program

Two types of signals are used in asynchronous serial port operations:

- Data signal
- Handshake signals
The data signal carries data from the transmitter to the receiver. One-way serial port transmission requires one data signal; two-way transmission requires two data signals.

In the TMS320C203 DSP, no handshake pins are supported; hence, IO0-IO3 are used as handshake signals. The signals allow the transmitter and receiver to control the time to transfer data.

Figure 16 shows the block diagram for the asynchronous serial port.

**Figure 16. Asynchronous Serial Port Block Diagram**

```
Configuring the asynchronous serial port requires two steps.

**Step 1:** You must select the configuration you want to use.

**Step 2:** The information must be written to the serial port control register.

In addition, you must set the baud rate by writing to the baud rate divisor register. Apply the equation

\[
\text{baud rate} = \frac{\text{CLKOUT1 frequency}}{16 \times \text{BRD register}}
\]

to calculate the value for the baud rate divisor. (This item is a correction to the *TMS320C2xx User’s Guide.*)

The UART.Asm program shown in Example 3 was written by Jeffrey Lai, a summer student from Stanford University, and modified by Art Chen. The function of the UART.Asm is to transmit the characters (from A to Z) to the PC host.

As is required for the Echo.ASM file, the interrupt vector table should be defined in program address from 0000h to 0040h, and the I/O wait-state and asynchronous serial port should be initialized. Then the data can be prepared for transmitting.
Example 3. UART.Asm

Program Name: UART.Asm
Description: C203 UART Program without Auto Baud Rate Detecting
Author: Jeffrey Lai, a Summer Student from Stanford University
Modifier: Art Chen in TI-Asia/DSP

.title "UART Program"

TMVER .equ 0

.mmregs

ADTR .set 0FFF4H ;; Asynchronous Data Transmit/Receiver
ASPCR .set 0FFF5H ;; Asynchronous SerialPort Control Reg.
IOSR .set 0FFF6H ;; I/O Status Reg.
BRD .set 0FFF7H ;; Baud Rate Divisor
WSGR .set 0FFFCH ;; Wait-State Generator
IO0 .set 15 - 0 ;; General IO Port 1st in IOSR
IO1 .set 15 - 1 ;; General IO Port 2nd in IOSR
IO2 .set 15 - 2 ;; General IO Port 3rd in IOSR
IO3 .set 15 - 3 ;; General IO Port 4th in IOSR
DR .set 15 - 8 ;; Data Ready Indicator in IOSR
TEMT .set 15 - 12 ;; Transmit Empty Indicator in IOSR
DTR .set IO0 ;; Data Terminal Ready
DSR .set IO1 ;; Data Set Ready
RTS .set IO2 ;; Request To Send
CTS .set IO3 ;; Clear To Send

.sect "vectors"
B BEGIN
.space 2 * 16 ;; HOLD/INT1
.space 2 * 16 ;; INT2/INT3
.space 2 * 16 ;; Timer Interrupt ISR
.space 2 * 16 ;; SyncSerPort Receive ISR
.space 2 * 16 ;; SyncSerPort Transmit ISR
B TXRX_ISR
.space 2 * 16 ;; AsyncSerPort Transmit/Receive ISR

.bss TEMP_DATA, 4
temp .set TEMP_DATA
test .set temp + 1
counter .set test + 2

.text
BEGIN:

SETC INTM ;; Disable Interrupt
LDP #TEMP_DATA

;; Set Wait State
SPLK #0E00h, temp ;; 7-Wait State Set
OUT temp, WSGR

;; Set Baud Rate Divisor
SPLK #130, temp ;; BRD = 130 = CLKOUT1(20Mhz) / 16 *
OUT temp, BRD

B

END


SPLK #001000110001010b, temp ; Config IO0,1,2,3 and Disable
OUT temp, ASPCR ; TX RX Mask, Reset, 1 StopBit

IN temp, IOSR ; Set CTS, DSR to 0
LACC temp ; and Clear ADC Bit
AND #1011111111110101b ;
SACL temp ;
OUT temp, IOSR ;

SPLK #64, counter ; Initialize Data, counter = 64

WAIT_FOR_PC_READY:
  IN test, IOSR ; Wait for PC Ready
  BIT test, DTR ;
  BCND WAIT_FOR_PC_READY, TC ;
  BIT test, RTS ;
  BCND WAIT_FOR_PC_READY, TC ;
LDP #0
LACC #IMR ; Enable the TXRXINT in IMR
OR #20H ;
SACL IMR ;
CLRC INTM

LOOP: ; Waiting for Interrupt
  NOP ;
  B LOOP ;
  LOOP:
TXRX_ISR:
  SETC INTM ; Disable Interrupt
  LDP #0
  .IF TMVER = 1 ; If TMP Chip is used
    LACL #00020H ; Clear the TXRXINT Flag
  .ENDIF
  .IF TMVER = 0 ; If TMX Chip is used
    LACC #IFR ; Clear the TXRXINT Flag
    AND #0FFDFH ;
  .ENDIF
  SACL IFR ;
  LDP #TEMP_DATA
  IN test, IOSR ; If Data is Ready?
  BIT test, DR ; To Receive Data
  BCND RX_DATA, TC ; If Transmit is Empty?
  BIT test, TEMT ; To Transmit Data
  BCND TX_DATA, TC ; Enable Interrupt
  CLRC INTM ; Nothing Held
  RET

TX_DATA:
  LACC counter ; counter ++ as the Data
  ADD # 1 ;
  SACL counter ;
  OUT counter, ADTR ; Transmit Data
  SUB #90 ; If(counter > 90)
  BCND TX_RET, LT ; count = 64
  SPLK #64, counter ;

TX_RET:
  CLRC INTM ; Enable Interrupt
  RET

RX_DATA:
CLRC  INTM
RET

;; Enable Interrupt

;; End of UART.Asm
Appendix A. TMS320C203 Development Board Schematics

TMS320C203 DSP and Clock
Designing the TMS320C203 DSP Development Board for TMS320C203 Evaluation
TMS320C203 Development Board External Memory System

MS28562: AccessTime 12 - 18ns, OperatingCurrent 70mA, StandbyCurrent 150mA
MS27C21A-10: AccessTime 150ns, OperatingCurrent 50mA, StandbyCurrent 100mA

Note: Propagation Delay Time is 1 to 6ns
TMS320C203 Development Board JTAG Connector
TMS320C203 Development Board RS-232 Connector
TMS320C203 Development Board I/O Connectors
## Appendix B. Bill of Materials

<table>
<thead>
<tr>
<th>Item</th>
<th>Quantity</th>
<th>Reference</th>
<th>Part</th>
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<td>1</td>
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<td>CB1, C1, CB2, CB3, CB4, C4, CB5, C5, CB6, CB7, C7, CB8, C8, C10, C11, C12, C13, C14, C15, C16, C17, C18</td>
<td>0.1 µF</td>
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<td>2</td>
<td>C2, C3</td>
<td>1000 µF</td>
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<td>2</td>
<td>C9, C6, C19, C20</td>
<td>4.7 µF</td>
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<td>1</td>
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<td>1</td>
<td>D4</td>
<td>MLED71</td>
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<td>JP1, JP2, JP6, JP7</td>
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<td>1</td>
<td>JP3</td>
<td>HEADER 7x2</td>
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