ABSTRACT
This document describes how to use the multichannel buffered serial port (McBSP) in the Texas Instruments (TI) TMS320C6000™ (C6000™) digital signal processors (DSP) to interface to a universal asynchronous receiver/transmitter (UART). Descriptions of the hardware configuration and software routines necessary for proper functionality are included.

The McBSP is not capable of supporting UART standards natively. However, by simple modification of the serial control registers, there are two methods by which the McBSP can be configured to receive and transmit data that is understandable to a UART. The McBSP can be used in either the serial port mode or the general-purpose input/output (GPIO) mode. This application report discusses both methods. In addition, this application report demonstrates the hardware interface between the McBSP and a UART.

Project collateral and source code discussed in this application report can be downloaded from the following URL: http://www-s.ti.com/sc/techlit/spra633.zip

Contents
1 Design Problem ................................................................. 2
2 Overview ........................................................................... 2
3 UART Interface Method 1: McBSP in Serial Port Mode ............... 2
4 UART Interface Method 2: McBSP in GPIO Mode ..................... 7
5 Hardware UART Adapter for the C6000 Processors .................. 10
6 Conclusion ....................................................................... 11
7 References ....................................................................... 11
Appendix A Sample C Code ................................................... 12
Appendix B Sample C/Assembly Code ...................................... 24

List of Figures
1 UART Timing ..................................................................... 2
2 UART Connection - Serial Port Implementation ....................... 3
3 McBSP Transfer in UART 8N1 Mode ................................... 3
4 Pin Control Register (PCR) ............................................... 4
5 Receive Control Register (RCR) ......................................... 5
6 Transmit Control Register (XCR) ....................................... 5
7 Sample Rate Generator Register (SRGR) ............................... 6
8 Block Data Processing of Transmit Buffer ............................ 7
9 UART Connection - GPIO Implementation ............................ 8
10 Serial Port Control Register (SPCR) .................................. 8
11 Pin Control Register (PCR) .............................................. 9
12 UART Auto-Baud Detection ............................................ 9
13 SoftUartInchar UART Data Fetch .................................... 10
14 UART Adapter Board ..................................................... 11

List of Tables
1 Design Problem

How can the McBSP in a TMS320C6000 digital signal processor be used for transmitting data to and receiving data from a UART?

2 Overview

The UART standard is a well-established protocol for the exchange of serial data. Since it is asynchronous, the communications link requires no clock signal to be transmitted. Instead, the receiver and transmitter each have their own serial clocks that run at a preset frequency. The UART transmission protocol includes start and stop bits to help the receiver synchronize to the incoming data. The UART timing specification is shown in Figure 1. A high-to-low transition on the data line signifies the beginning of a transmission. After this Start condition, the data bits are sent serially with the least significant bit (LSB) first. The parity bit is optional, depending on the UART format. Each data frame ends with the Stop bit (logic high).

To interface a UART to the RS-232 port of the computer, the data signal needs to go through a RS-232 level converter to translate from the complementary metal-oxide-semiconductor (CMOS) logic levels to the RS-232 logic levels. The RS-232 logic levels use +3 to +25 V to signify a Space (logic 0) and -3 to -25 V for a Mark (logic 1). Any voltage in between these regions (i.e., between +3 and -3 V) is undefined.

![Figure 1. UART Timing](image)

The McBSPs on the C6000 devices are synchronous serial ports, and are not capable of interfacing to a UART natively. UART functionality can be implemented in software, however. This application report discusses two methods to interface a UART to the McBSP. The first method uses the McBSP in normal serial port mode. The second method uses the McBSP in the GPIO mode.

3 UART Interface Method 1: McBSP in Serial Port Mode

To interface a UART to the McBSP in serial port mode, the UART’s transmit data line is connected to both the data input and the frame synchronization input on the McBSP. This is because the UART serial data line contains both framing and data information. The UART’s receive data line is connected to the data output of the McBSP. Figure 2 illustrates the UART to McBSP connection.

By using the McBSP’s internal sample rate generator to clock itself, the McBSP can be configured to receive and transmit each UART bit as a 16-bit word. Software must expand each bit to be transmitted to a 16-bit word and compress each 16-bit word received to a single bit, as well as handle the necessary framing data.
3.1 McBSP Setup: Serial Port Implementation

The C6000 treats each UART bit as a 16-bit word. The sample rate generator is configured to create an internal serial clock of 16 times the serial baud rate, thus duplicating the UART’s internal timing. Since each UART word starts with a falling edge to indicate the start bit, this edge can be used as the active-low frame sync input. This is why both the data and frame sync inputs are connected to the UART’s output. Notice that to prevent the McBSP from re-triggering, it is set to ignore all frame syncs during the receive packet.

To send a byte to a UART in 8N1 mode (eight data bits, no parity bit and one stop bit) the transfer should be in two phases, one consisting of nine 16-bit words and the other of two 8-bit words. Figure 3 shows the McBSP in 8N1 mode. The first half of the frame corresponds to the start bit and the eight data bits; the second half of the frame is the stop bit. Other UART modes can be accommodated by adjusting the frame word counts. When transmitting single UART bits as 16-bit words, ‘1’ UART bits are encoded as 0xFFFF and ‘0’ UART bits are encoded as 0x0000. The stop bit should be encoded in 8-bit words to allow for easy modification to the 1.5 stop bits setting in other UART modes, if desired.

Several McBSP parameters have to be configured for the UART connection. Figure 4 through Figure 7 show the McBSP registers setup. Table 1 summarizes the McBSP setup.
3.1.1 Pin Control Register (PCR)

- FSXM = 1 and FSXP = 1. This allows the sample rate generator to generate active-low start bits.
- FSRM = 0 and FSRP = 1. The active-low start bit is the frame sync input to the McBSP.
- CLKRM = CLKXM = 1. Internal sample rate generator generates the serial clock.

The pin control register (PCR) is shown in Figure 4 and described in Table 1.

![Figure 4. Pin Control Register (PCR)](image)

<p>| | | | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td>30</td>
<td>29</td>
<td>28</td>
<td>27</td>
<td>26</td>
<td>25</td>
<td>24</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>23</td>
<td>22</td>
<td>21</td>
<td>20</td>
<td>19</td>
<td>18</td>
<td>17</td>
<td>16</td>
</tr>
<tr>
<td>Reserved</td>
<td>XIOEN</td>
<td>RIOEN</td>
<td>FSXM</td>
<td>FSRM</td>
<td>CLKXM</td>
<td>CLKRM</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>14</td>
<td>13</td>
<td>12</td>
<td>11</td>
<td>10</td>
<td>9</td>
<td>8</td>
</tr>
<tr>
<td>Reserved</td>
<td>CLKS_STAT</td>
<td>DX_STAT</td>
<td>DR_STAT</td>
<td>FSXP</td>
<td>FSRP</td>
<td>CLKXP</td>
<td>CLKRP</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

3.1.2 Receive/Transmit Control Registers (RCR/XCR)

- (R/X)PHASE = 1. Enable dual-phase frame mode.
- (R/X)FRLEN1 = 8. Nine elements in the first phase of the frame.
- (R/X)FRLEN2 = 1. Two elements in the second phase of the frame.
- (R/X)WDLEN1 = 2. 16-bit words in the first phase (Start bit, data bits).
- (R/X)WDLEN2 = 0. 8-bit words in the second phase (Stop bits).
- (R/X)COMPAND = 0. No companding.
- (R/X)FIG = 1. For reception, since data line transitions are seen on the FSR pin, unexpected frame sync signals must be ignored. For transmission, since the transmit frame sync signal FSX is generated on every DXR-to-XSR copy (see SRGR setup below), it occurs more frequently than desired for a UART frame. Unexpected frame syncs are ignored.
- XDATDLY = 0. No data delay.
- RDATDLY = 1. 1-bit data delay.

The receive/transmit control registers (RCR/XCR) are shown in Figure 5 and Figure 6 and described in Table 1.
3.1.3 Sample Rate Generator Register (SRGR)

- **FSGM = 0.** The transmit frame sync signal (FSX) is generated on every DXR-to-XSR copy.
- **CLKSM = 0** if the sample rate generator clock is derived from an external clock on the CLKS pin. **CLKSM = 1** if the sample rate generator clock is derived from the internal CPU clock.
- **CLKGDV = (CPU Clock frequency) / (16 * baud rate) -1.** The clock divide ratio must be appropriately set so that the rate generated is 16 times the baud rate. For example, a CPU clock frequency of 200 MHz and a desired baud rate of 115,200 bps would result in an approximate CLKGDV value of 108. Note that when the sample rate generator clock is derived from the internal clock source, you may not be able to get a serial clock that is exactly 16 times the desired baud rate. In addition, the limited size of the CLKGDV field creates a minimum baud rate that the serial port is capable of clocking. If a baud rate slower than the minimum or an exact baud rate is desired, you should use an external clock on the CLKS pin to drive the sample rate generator.
3.2 Receiving/Transmitting UART Data

Once the serial port has been configured to interface to a UART, the software routines that do the necessary data conversions must be implemented. When using the McBSP in serial port mode, there are two possible software implementations. You can either process the UART data word-by-word or in blocks. This application report discusses the more efficient implementation of the two-UART data processing in blocks. With simple modification, the software can handle word-by-word data processing.

---

The sample rate generator register (SRGR) is shown in Figure 7 and described in Table 1.

**Figure 7. Sample Rate Generator Register (SRGR)**

<table>
<thead>
<tr>
<th>Register Value</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RCR[31]</td>
<td>RPHASE</td>
<td>Dual Phase Receive</td>
</tr>
<tr>
<td>RCR[30-24]</td>
<td>RFRLEN2</td>
<td>2 Word Receive Frame Length (Phase 2)</td>
</tr>
<tr>
<td>RCR[23-21]</td>
<td>RWDLEN2</td>
<td>8 Bits Receive Word Length (Phase 2)</td>
</tr>
<tr>
<td>RCR[20-19]</td>
<td>RCOMPAND</td>
<td>No Companding</td>
</tr>
<tr>
<td>RCR[18]</td>
<td>RFIG</td>
<td>Unexpected FSR Ignored</td>
</tr>
<tr>
<td>RCR[17-16]</td>
<td>RDATDLY</td>
<td>1-Bit Data Delay</td>
</tr>
<tr>
<td>RCR[14-8]</td>
<td>RFRLEN1</td>
<td>9 Word Receive Frame Length (Phase 1)</td>
</tr>
<tr>
<td>RCR[7-5]</td>
<td>RWDLEN1</td>
<td>16 Bits Receive Word Length (Phase 1)</td>
</tr>
<tr>
<td>PCR[10]</td>
<td>FSRM</td>
<td>FSR is Input Pin</td>
</tr>
<tr>
<td>PCR[8]</td>
<td>CLKRM</td>
<td>CLKR is Output Pin</td>
</tr>
<tr>
<td>PCR[2]</td>
<td>FSRP</td>
<td>Active-Low Frame Sync</td>
</tr>
<tr>
<td>SRGR[29]</td>
<td>CLKSM</td>
<td>SRGR Derived From CPU Clock</td>
</tr>
<tr>
<td>SRGR[7-0]</td>
<td>CLKGDV</td>
<td>Frame Sync is Generated on Every DXR-to-XSR</td>
</tr>
</tbody>
</table>

**Table 1. Field Descriptions for McBSP Registers**

<table>
<thead>
<tr>
<th>Register Value</th>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>XCR[31]</td>
<td>XPHASE</td>
<td>Dual Phase Transmit</td>
</tr>
<tr>
<td>XCR[30-24]</td>
<td>XFRLEN2</td>
<td>2 Word Transmit Frame Length (Phase 2)</td>
</tr>
<tr>
<td>XCR[23-21]</td>
<td>XWDLEN2</td>
<td>8 Bits Transmit Word Length (Phase 2)</td>
</tr>
<tr>
<td>XCR[20-19]</td>
<td>XCOMPAND</td>
<td>No Companding</td>
</tr>
<tr>
<td>XCR[18]</td>
<td>XFIG</td>
<td>Unexpected FSX Ignored</td>
</tr>
<tr>
<td>XCR[17-16]</td>
<td>XDATDLY</td>
<td>No Data Delay</td>
</tr>
<tr>
<td>XCR[14-8]</td>
<td>XFRLEN1</td>
<td>9 Word Transmit Frame Length (Phase 1)</td>
</tr>
<tr>
<td>XCR[7-5]</td>
<td>XWDLEN1</td>
<td>16 Bits Transmit Word Length (Phase 1)</td>
</tr>
<tr>
<td>SRGR[28]</td>
<td>FSGM</td>
<td>FSX Generated on DXR-to-XSR Copy</td>
</tr>
<tr>
<td>PCR[11]</td>
<td>FSXM</td>
<td>FSX is Output pin</td>
</tr>
<tr>
<td>PCR[9]</td>
<td>CLKXM</td>
<td>CLKX is Output pin</td>
</tr>
<tr>
<td>PCR[3]</td>
<td>FSXP</td>
<td>Active-Low Frame Sync</td>
</tr>
</tbody>
</table>
The sample C program in Appendix A shows block UART data processing. In this implementation, the enhanced direct memory access (EDMA) or direct memory access (DMA) services the McBSP by transferring data between the McBSP and the receive/transmit buffers.

For transmits, a transmit conversion subroutine converts a block of data into UART transmission words by expanding each data bit into a 16-bit word. The transmit conversion subroutine places this block of transmission words in a transmit buffer, along with the framing Start (0x0000) and Stop (0xFFFF) bits in the proper locations. Figure 8 shows a sample transmit buffer. Afterward, the EDMA is setup to transfer the data from the transmit buffer to the McBSP. Since the data in the transmit buffer is already in the proper UART format, the McBSP frame sync generator can be used to continuously shift out this data.

**Figure 8. Block Data Processing of Transmit Buffer**

# 4 UART Interface Method 2: McBSP in GPIO Mode

The C6000 DSP can also interface to a UART using its GPIO pins. The McBSP pins CLKX, FSX, DX, CLKR, FSR, DR, and CLKS can be used as GPIO pins when the following two conditions are true:

- The related portion (transmitter or receiver) of the serial port is in reset: (R/X)RST = 0 in the Serial Port Control Register (SPCR).
- The GPIO is enabled for the related portion of the serial port: (R/X)IOEN=1 in the PCR.

Table 2 shows how to setup the McBSP pins as GPIO pins.

**Table 2. Configuration of McBSP Pins as GPIO**

<table>
<thead>
<tr>
<th>Pin</th>
<th>GPIO Enabled When 0</th>
<th>Selected as Output When ...</th>
<th>Output Value Driven From</th>
<th>Selected as Input When ...</th>
<th>Input Value Readable on</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLKX</td>
<td>XRST = 0, XIOEN = 1</td>
<td>CLKX = 1</td>
<td>CLKXP</td>
<td>CLKXM = 0</td>
<td>CLKXP</td>
</tr>
<tr>
<td>FSX</td>
<td>XRST = 0, XIOEN = 1</td>
<td>FSXM = 1</td>
<td>FSXP</td>
<td>FSXM = 0</td>
<td>FSXP</td>
</tr>
<tr>
<td>DX</td>
<td>XRST = 0, XIOEN = 1</td>
<td>Always</td>
<td>DX_STAT</td>
<td>Never</td>
<td>N/A</td>
</tr>
<tr>
<td>CLKR</td>
<td>XRST = 0, RIOEN = 1</td>
<td>CLKRM = 1</td>
<td>CLKRP</td>
<td>CLKRM = 0</td>
<td>CLKRP</td>
</tr>
<tr>
<td>FSR</td>
<td>XRST = 0, RIOEN = 1</td>
<td>FSRM = 1</td>
<td>FSRP</td>
<td>FSRM = 0</td>
<td>FSRP</td>
</tr>
<tr>
<td>DR</td>
<td>XRST = 0, RIOEN = 1</td>
<td>Never</td>
<td>N/A</td>
<td>Always</td>
<td>DR_STAT</td>
</tr>
<tr>
<td>CLKS</td>
<td>XRST = XRST = 0, XIOEN = 1</td>
<td>Never</td>
<td>N/A</td>
<td>Always</td>
<td>CLKS_STAT</td>
</tr>
</tbody>
</table>
4.1 McBSP Setup: GPIO Implementation

Although different GPIO pins on the C6000 DSP can be used as GPIO pins, this application report discusses an example UART implementation when the McBSP DX and DR pin are used as general-purpose output and input pins, respectively. Figure 9 illustrates the McBSP to UART connection. All other McBSP pin connections are don't cares in this example.

Figure 10 and Figure 11 show the SPCR and PCR setup specific to this example. The setups of all other McBSP registers are don't cares because the McBSP is in GPIO mode. The values in shaded bit fields are don't cares and are left at default.

![Figure 9. UART Connection - GPIO Implementation](image)

![Figure 10. Serial Port Control Register (SPCR)](image)

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td>Reserved</td>
</tr>
<tr>
<td>24</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>23</td>
<td>FRST</td>
</tr>
<tr>
<td>22</td>
<td>GRST</td>
</tr>
<tr>
<td>21</td>
<td>XINTM</td>
</tr>
<tr>
<td>20</td>
<td>XSYNCERR</td>
</tr>
<tr>
<td>19</td>
<td>XEMPTY</td>
</tr>
<tr>
<td>18</td>
<td>XRDY</td>
</tr>
<tr>
<td>17</td>
<td>XRST</td>
</tr>
<tr>
<td>16</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>15</td>
<td>DLB</td>
</tr>
<tr>
<td>14</td>
<td>RINTM</td>
</tr>
<tr>
<td>13</td>
<td>RXINTM</td>
</tr>
<tr>
<td>12</td>
<td>XSYNCERR</td>
</tr>
<tr>
<td>11</td>
<td>RFULL</td>
</tr>
<tr>
<td>10</td>
<td>RRST</td>
</tr>
<tr>
<td>8</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>DXENA</td>
</tr>
<tr>
<td>6</td>
<td>Reserved</td>
</tr>
<tr>
<td>5</td>
<td>RINTM</td>
</tr>
<tr>
<td>4</td>
<td>RSYNCERR</td>
</tr>
<tr>
<td>3</td>
<td>RFULL</td>
</tr>
<tr>
<td>2</td>
<td>RRST</td>
</tr>
<tr>
<td>1</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

LEGEND: R/W = Read/Write; R = Read only; - = value after reset
4.2 GPIO UART Software

Appendix B contains three low level routines that can be called by higher level programs to perform UART data transmit and receive. The three functions are:

```c
unsigned int SoftUartSpeedDetect(void);
void SoftUartOutchar(int, char);
char SoftUartInchar(int);
```

Function SoftUartSpeedDetect() sets the McBSP in GPIO mode and detects the UART transmission rate. Function SoftUartOutchar(int, char) transmits UART data from the McBSP to the UART. Function SoftUartInchar(int) receives UART data that comes from the UART to the McBSP. The following sections discuss these functions in detail.

4.2.1 SoftUartSpeedDetect - Subroutine for Auto-Baud Detection

The subroutine SoftUartSpeedDetect sets the McBSP in GPIO mode with the SPCR and PCR registers. It performs auto-baud detection by measuring the length of the Start bit, plus the length of the first data bit (logic high) in the character <cr> (carriage return). You need to ensure (in software) that the first character sent is <cr> because the first data bit has to be a logical one. This is shown as `T' in Figure 12.

![Figure 12. UART Auto-Baud Detection](image)

The time T is determined by a software counter incremented by one until the second transition from high to low is detected by reading the DRSTAT bit in the PCR register. T represents twice the time of a bit length.

This measurement is required because the RX signal from UART is not always very clean. Simply measuring the length of the Start bit to determine the baud rate is not accurate enough.

The time reference value UartSpeed = T >>1 (i.e., T/2) is returned from SoftUartSpeedDetect() and used in the character input detection and character output send routines, SoftUartInchar and SoftUartOutchar.

This software UART is a basic emulation and can be customized in several ways by using timers and interrupts.
Current implementations of software UART are used for debugging purpose or application monitoring in places where a VT100 or an ANSI terminal is mandatory.

4.2.2 SoftUartInchar - Subroutine for UART Data Receive

Subroutine SoftUartInchar takes the input argument UartSpeed - the UART speed output returned from function SoftUartSpeedDetect.

This subroutine parses bit-by-bit the UART data on the DR line. It detects the Start bit by polling for the first DR line transition from inactive (logic 1) to active (logic 0) state. The eight data bits are transmitted by the UART device immediately after the Start bit. The best time to fetch the right value of each data bit is in the middle of the data bit waveform. Figure 13 shows how subroutine SoftUartInchar achieves this. It waits for half of the UartSpeed time value (P/2 in) during the Start bit. Then for each of the eight valid data bits, it samples the DR line status (DR_STAT bit in the PCR) in the middle of the data bit waveform. The subroutine shifts each binary bit result into a single register value to retrieve the original 8-bit character. All the delays are generated with polling loops to minimize the use of resources in the DSP.

![Figure 13. SoftUartInchar UART Data Fetch](image)

4.2.3 SoftUartOutchar - Subroutine for UART Data Transmit

Subroutine SoftUartOutchar is based on the same mechanism as the SoftUartInchar subroutine. It takes the input argument UartSpeed - the UART speed output returned from function SoftUartSpeedDetect.

This subroutine drives the transmit data on the DX line through writing the DX_STAT bit in the PCR. At the beginning of a transfer, SoftUartOutchar writes a `0' to the DX line (Start bit). Subsequently, it transmits each data bit on the DX line. The time spent on each bit is derived from the UartSpeed input, processed by a polling loop.

The transmit character is first placed into the least significant eight bits in a register padded with three Stop bits (0x00000700). For example, the character `A' (ASCII character 0x41) is placed in the padded register to become 0x00000741. Each time through the loop, the LSB of the padded register is driven on the DX line, and is right-shifted to be ready for the next bit transmit. In the character `A' example, after the first bit `1' is driven on the DX line, the padded register is right-shifted by one to 0x00003A0.

5 Hardware UART Adapter for the C6000 Processors

The hardware adapter for the software UART support consists of a single SN75LV4737A multichannel RS232 line driver/receiver which transmit/receives the binary stream from/to the McBSP lines.

The SN75LV4737A consists of three line drivers, five line receivers, and a charge-pump circuit. It provides the electrical interface between an asynchronous communication controller and the serial port connector and meets the requirements of EIA/TIA-232-E. This combination of drivers and receivers matches those needed for the typical serial port used in an IBM PC/AT or compatibles.

The device has flexible control options for power management when the serial port is inactive. A common disable for all of the drivers and receivers is provided with the active-high STBY input. The active-low EN input is an enable for one receiver to implement a wake-up feature for the serial port. All the logic inputs can accept signals from controllers operating from a 5 V supply even though the SN75LV4737A is operating from 3.3 V.

Figure 14 presents an adapter board for the C6000 DSP. The connection in this figure demonstrates the GPIO mode implementation. For serial port mode implementation described in this application report, pin DR0 needs to be tied to pin FSR0.
6 Conclusion

The McBSP on the TMS320C6000 DSP is not natively capable of interfacing to a UART; however, with software control, communication between a McBSP and a UART is possible. The McBSP is easy to configure, and the compression/expansion software routines are straightforward for this purpose.

7 References

- TMS320C6201 Digital Signal Processor (SPRS051)
- TMS320C6000 DSP Peripherals Overview Reference Guide (SPRU190)
- TMS320C6x Peripheral Support Library Programmer's Reference (SPRU273)
- TMS320C6000 CPU and Instruction Set Reference Guide (SPRU189)
- 3.3-V/5-V Multichannel RS-232 Line Driver/Receiver (SLLS178)
Appendix A Sample C Code

A.1 Serial Port Mode

```
/* This code describes how to initialize the C6000 McBSP to */
/* communicate with a UART. By modifying the CHIP definition, */
/* this code can be used to run on 6x1x/6x0x/64x. #if statements */
/* are included in this code which allow flexibility in different */
/* devices. */
/* */
/* On 6x0x devices, DMA channels 1 and 2 are used to service */
/* McBSP 1 transmit and receive operations, respectively. On */
/* 6x1x/64x devices, EDMA channels 14 and 15 are used to service */
/* McBSP 1 transmit and receive operations, respectively. */
/* */
/* For this example, a data string is being transmitted from McBSP */
/* transmit (DX) to McBSP receive (DR). Each bit of the 8-bit */
/* ASCII character is expanded into 16-bit UART transmission word. */
/* Once being received, the 16-bit UART transmission words are */
/* compressed back to binary bits and ASCII form. */
/* */
/* For the code to work, DX, DR, and FSR of McBSP1 are shorted */
/* together. */
/* */
/* This code has been verified for functionality on 6711, 6202, */
/* and 6203 devices. */
/* */
/* This program is based on CSL 2.0. Please refer to the */
/* TMS320C6000 Chip Support Library API User's Guide for further */
/* information. */
/* ************************************************************************/ */

/* Chip definition - Please change this accordingly */
#define CHIP_6711 1

/* Include files */
#include <cs1.h>
#include <cs1_mcbsp.h>
#include <cs1_edma.h>
#include <cs1_dma.h>
#include <cs1_irq.h>
#include <stdio.h>

/* Create buffers and aligning them on an L2 cache line boundary. */
#pragma DATA_SECTION(xmitbuf,"xmit_buf");
unsigned short xmitbuf[0x0400];
#pragma DATA_SECTION(recebbuf,"recb_buf");
unsigned short recvbuf[0x0400];

/* Definitions */
#define BUFFER_SIZE 27 /* total number of UART data words*/
#define TRUE 1
#define FALSE 0

/* Declare CSL objects */
MCBSP_Handle hMcbsp1; /* handle for McBSP1 */
#if (EDMA_SUPPORT)
   EDMA_Handle hEdma14; /* handle for EDMA 14 */
   EDMA_Handle hEdma15; /* handle for EDMA 15 */
#else
#endif
#if (DMA_SUPPORT)
   DMA_Handle hDma1; /* handle for DMA 1 */
   DMA_Handle hDma2; /* handle for DMA 2 */
#endif
```
#endif

/* Global Variables */
volatile int receive_done = FALSE;
volatile int transmit_done = TRUE;
char xmit_msg[BUFFER_SIZE] = "McBSP does UART on C6000!
";
char recv_msg[BUFFER_SIZE] = "Transmission didn't work!
";

/**
 * Include the vector table to call the IRQ ISRs hook up
 */
extern void ConfigMcBSP(void);

/** Prototypes */
void ConfigEDMA(void);
void ConfigDMA(void);
void ProcessTransmitData(void);
void ProcessReceiveData(void);
short VoteLogic(unsigned short);
int CheckTestCase(void);
interrupt void c_int11(void);
interrupt void c_int09(void);
interrupt void c_int08(void);

/**********************************************************
* void main(void)
***********************************************************/

void main(void)
{
    int waittime = 0;
    int works = FALSE;

    /* initialize the CSL library */
    CSL_init();
    /* enable NMI and GI */
    IRQ_nmiEnable();
    IRQ_globalEnable();

    /* point to the IRQ vector table */
    IRQ_setVecs(vectors);
    #if (EDMA_SUPPORT)
        /* disable and clear the event interrupt */
        IRQ_reset(IRQ_EVT_EDMAINT);
        /* clear Parameter RAM of EDMA */
        EDMA_clearPram(0x00000000);
    #endif

    #if (DMA_SUPPORT)
        DMA_reset(INV);
    #endif

    /**************
    * process transmit data *
    */
    printf("Processing Transmit string...\n");
    ProcessTransmitData();
    printf("String transmitted: %s \n", xmit_msg);
    #if (EDMA_SUPPORT)
        /* Open the EDMA channels - EDMA 14 for transmit, */
        /* EDMA 15 for receive */
        hEdma14 = EDMA_open(EDMA_CHA_XEVT1, EDMA_OPEN_RESET);
        hEdma15 = EDMA_open(EDMA_CHA_REVT1, EDMA_OPEN_RESET);
    #endif

    #if (DMA_SUPPORT)
        /* Open the DMA channels - DMA 1 for transmit, */
        /* DMA 2 for receive */
    #endif
}
hDma1 = DMA_open(DMA_CHAN1, DMA_OPEN_RESET);
hDma2 = DMA_open(DMA_CHAN2, DMA_OPEN_RESET);

#endif

/* Open the McBSP channel 1 */
hMcbsp1 = McBSP_open(MCBSP_DEV1, MCBSP_OPEN_RESET);
#if (EDMA_SUPPORT)
    /* Configure the EDMA channels */
    ConfigEDMA();

    /* enable EDMA-CPU interrupt tied to McBSP */
    IRQ_enable(IRQ_EVT_EDMAINT);

    /* enable EDMA channel interrupt to CPU */
    EDMA_intEnable(14);
    EDMA_intEnable(15);

    /* Enable EDMA channels */
    EDMA_enableChannel(hEdma14);
    EDMA_enableChannel(hEdma15);
#endif

#if (DMA_SUPPORT)
    /* Configure the DMA channels */
    ConfigDMA();

    IRQ_disable(IRQ_EVT_DMAINT1);
    IRQ_disable(IRQ_EVT_DMAINT2);

    IRQ_clear(IRQ_EVT_DMAINT1);
    IRQ_clear(IRQ_EVT_DMAINT2);

    IRQ_enable(IRQ_EVT_DMAINT1);
    IRQ_enable(IRQ_EVT_DMAINT2);

    DMA_start(hDma1);    /* start DMA channel 1*/
    DMA_start(hDma2);    /* start DMA channel 2*/
#endif

/* Setup for McBSP */
ConfigMcBSP();

/* Start Sample Rate Generator: set /GRST = 1 */
MCBSP_enableSrgr(hMcbsp1);

/* inserted wait time for McBSP to get ready */
for (waittime=0; waittime<0xF; waittime++);

/* Wake up the McBSP as transmitter and receiver */
MCBSP_enableRcv(hMcbsp1);
MCBSP_enableXmt(hMcbsp1);

/* Enable Frame Sync Generator for McBSP 1: set /FRST = 1 */
MCBSP_enableFsync(hMcbsp1);

/* To flag an interrupt to the CPU when EDMA transfer/receive is done */
while (!receive_done || !transmit_done);

/* Check to make sure the test case works */
works = CheckTestCase();
if (works != 0) printf("Transmission Error....\n\n");
else printf("Received data matched transmitted data!\n\n");

/* process received data */
printf("Processing Receive string...\n");
ProcessReceiveData();
printf("String received: %s \n", recv_msg);
```c
#if (EDMA_SUPPORT)
  IRQ_disable(IRQ_EVT_EDMAINT);
  EDMA_RSET(CIER, 0x0);
#endif

#if (DMA_SUPPORT)
  IRQ_disable(IRQ_EVT_DMAINT1);
  IRQ_disable(IRQ_EVT_DMAINT2);
#endif

MCBSP_close(hMcbsp1);  /* close McBSP 1 */

#if (EDMA_SUPPORT)
  EDMA_close(hEdma14);  /* close EDMA 14 */
  EDMA_close(hEdma15);  /* close EDMA 15 */
#endif

#if (DMA_SUPPORT)
  DMA_close(hDma1);  /* close DMA 1 */
  DMA_close(hDma2);  /* close DMA 2 */
#endif

}  /* End of main() */

/****************************************************************************
/* void ConfigEDMA(void): set up EDMA channel 14/15 for UART Xmit */
/****************************************************************************
#if (EDMA_SUPPORT)
void ConfigEDMA(void)
{
  EDMA_configArgs(hEdma14,
  /* OPT Setup */
  #if (C64_SUPPORT)
   EDMA_OPT_RMK{
    EDMA_OPT_PRI_HIGH,  /* 1 */
    EDMA_OPT_ESIZE_16BIT,  /* 01 */
    EDMA_OPT_2DS_NO,  /* 0 */
    EDMA_OPT_SUM_INC,  /* 01 */
    EDMA_OPT_2DD_NO,  /* 0 */
    EDMA_OPT_DUM_NONE,  /* 00 */
    EDMA_OPT_TCIINT_YES,  /* 01 */
    EDMA_OPT_TCCM_OF(14),  /* 14 */
    EDMA_OPT_ATCC_DEFAULT,  /* 0 */
    EDMA_OPT_ATCC_DEFAULT,  /* 0 */
    EDMA_OPT_PDTS_DEFAULT,  /* 0 */
    EDMA_OPT_PDTD_DEFAULT,  /* 0 */
    EDMA_OPT_LINK_NO,  /* 0 */
    EDMA_OPT_FS_NO  /* 0 */
   },
  #else
   EDMA_OPT_RMK{
    EDMA_OPT_PRI_HIGH,  /* 1 */
    EDMA_OPT_ESIZE_16BIT,  /* 01 */
    EDMA_OPT_2DS_NO,  /* 0 */
    EDMA_OPT_SUM_INC,  /* 01 */
    EDMA_OPT_2DD_NO,  /* 0 */
    EDMA_OPT_DUM_NONE,  /* 00 */
    EDMA_OPT_TCIINT_YES,  /* 1 */
    EDMA_OPT_TCCM_OF(14),  /* 14 */
    EDMA_OPT_ATCC_DEFAULT,  /* 0 */
    EDMA_OPT_ATCC_DEFAULT,  /* 0 */
    EDMA_OPT_PDTS_DEFAULT,  /* 0 */
    EDMA_OPT_PDTD_DEFAULT,  /* 0 */
    EDMA_OPT_LINK_NO,  /* 0 */
    EDMA_OPT_FS_NO  /* 0 */
   },
  #endif
```
```c
EDMA_SRC_RMK((Uint32)xmitbuf),  /**<xmitbuf address*/

/* CNT Setup */
EDMA_CNT_RMK(
    EDMA_CNT_RMCNT_DEFAULT,
    EDMA_CNT_ELECNT_OF((BUFFER_SIZE*11))
),

/* DST Setup */
EDMA_DST_RMK(MCBSP_getXmtAddr(hMcbsp1)),

/* IDX Setup */
EDMA_IDX_RMK(0,0),

/* RLD Setup */
EDMA_RLD_RMK(0,0)
);

EDMA_configArgs(hEdma15,

/* OPT Setup */
#if (C64_SUPPORT)
EDMA_OPT_RMK(
    EDMA_OPT_PRI_HIGH,  /**< 1 */
    EDMA_OPT_ESIZE_16BIT,  /**< 01 */
    EDMA_OPT_2DS_NO,  /**< 0 */
    EDMA_OPT_SUM_NONE,  /**< 00 */
    EDMA_OPT_2DD_NO,  /**< 0 */
    EDMA_OPT_DUM_INC,  /**< 01 */
    EDMA_OPT_TCINT_YES,  /**< 1 */
    EDMA_OPT_TCC_OF(15),  /**< 15 */
    EDMA_OPT_TCCM_DEFAULT,  /**< 0 */
    EDMA_OPT_ATCC_DEFAULT,  /**< 0 */
    EDMA_OPT_ATCINT_DEFAULT,  /**< 0 */
    EDMA_OPT_PDTS_DEFAULT,  /**< 0 */
    EDMA_OPT_PDTD_DEFAULT,  /**< 0 */
    EDMA_OPT_LINK_NO,  /**< 0 */
    EDMA_OPT_FS_NO  /**< 0 */
),
#else
EDMA_OPT_RMK(
    EDMA_OPT_PRI_HIGH,  /**< 1 */
    EDMA_OPT_ESIZE_16BIT,  /**< 01 */
    EDMA_OPT_2DS_NO,  /**< 0 */
    EDMA_OPT_SUM_NONE,  /**< 00 */
    EDMA_OPT_2DD_NO,  /**< 0 */
    EDMA_OPT_DUM_INC,  /**< 01 */
    EDMA_OPT_TCINT_YES,  /**< 1 */
    EDMA_OPT_TCC_OF(15),  /**< 15 */
    EDMA_OPT_TCCM_DEFAULT,  /**< 0 */
    EDMA_OPT_ATCC_DEFAULT,  /**< 0 */
    EDMA_OPT_ATCINT_DEFAULT,  /**< 0 */
    EDMA_OPT_PDTS_DEFAULT,  /**< 0 */
    EDMA_OPT_PDTD_DEFAULT,  /**< 0 */
    EDMA_OPT_LINK_NO,  /**< 0 */
    EDMA_OPT_FS_NO  /**< 0 */
),
#endif

/* SRC Setup */
EDMA_SRC_RMK(MCBSP_getRcvAddr(hMcbsp1)),

/* CNT Setup */
EDMA_CNT_RMK(0, (BUFFER_SIZE * 11)),

/* DST Setup */
EDMA_DST_RMK((Uint32)recvbuf),  /**<recvbuf address*/

/* IDX Setup */
EDMA_IDX_RMK(0,0),

/* RLD Setup */
EDMA_RLD_RMK(0,0)
);

} /* End of ConfigEDMA() */
#endif
```
void ConfigDMA(void)
{
    DMA_configArgs(hDma1,
        /* PRICTL Setup */
        DMA_PRICTL_RMK(
            DMA_PRICTL_DSTRLD_NONE,
            DMA_PRICTL_SRCRLD_NONE,
            DMA_PRICTL_EMOD_HALT,
            DMA_PRICTL_FS_DISABLE,
            DMA_PRICTL_TCINT_ENABLE,
            DMA_PRICTL_PRI_DMA,
            DMA_PRICTL_WSYNC_XEV1,
            DMA_PRICTL_RSXNC_RL_NONE,
            DMA_PRICTL_INDEX_NA,
            DMA_PRICTL_CNTLD_NA,
            DMA_PRICTL_SPLIT_DISABLE,
            DMA_PRICTL_ESIZE_16BIT,
            DMA_PRICTL_DSTDIR_NONE,
            DMA_PRICTL_SRCDIR_INC,
            DMA_PRICTL_START_STOP
        ),
        /* SECCTL Setup */
        DMA_SECCTL_RMK(
            DMA_SECCTL_WSPOL_ACTIVEHIGH,
            DMA_SECCTL_RSPOL_ACTIVEHIGH,
            DMA_SECCTL_FSIG_NORMAL,
            DMA_SECCTL_DMACEN_FRAMECOND,
            DMA_SECCTL_WSYNCCLR_NOTHING,
            DMA_SECCTL_RSYNCCLR_NOTHING,
            DMA_SECCTL_WDROPIE_DISABLE,
            DMA_SECCTL_WDROPCOND_CLEAR,
            DMA_SECCTL_RDROPIE_DISABLE,
            DMA_SECCTL_RDROPCOND_CLEAR,
            DMA_SECCTL_BLOCKIE_ENABLE,
            DMA_SECCTL_BLOCKCOND_CLEAR,
            DMA_SECCTL_LASTIE_DISABLE,
            DMA_SECCTL_LASTCOND_CLEAR,
            DMA_SECCTL_FRAMEIE_DISABLE,
            DMA_SECCTL_FRAMECOND_CLEAR,
            DMA_SECCTL_SXIE_DISABLE,
            DMA_SECCTL_SXCOND_CLEAR
        ),
        /* SRC Setup */
        DMA_SRC_RMK((Uint32)xmitbuf),
        /* DST Setup */
        DMA_DST_RMK(MCBSP_getXmtAddr(hMcbsp1)),
    );
    DMA_configArgs(hDma2,
        /* PRICTL Setup */
        DMA_PRICTL_RMK(
            DMA_PRICTL_DSTRLD_NONE,
            DMA_PRICTL_SRCRLD_NONE,
            DMA_PRICTL_EMOD_HALT,
            DMA_PRICTL_FS_DISABLE,
            DMA_PRICTL_TCINT_ENABLE,
            DMA_PRICTL_PRI_DMA,
        ));
DMA_PRICTL_WSVec NONE,
DMA_PRICTL_RSYNC_REVTI,
DMA_PRICTL_INDEX_NA,
DMA_PRICTL_CNTRLD_NA,
DMA_PRICTL_SPLIT_DISABLE,
DMA_PRICTL_ESIZE_16BIT,
DMA_PRICTL_DSSTD_IR_INC,
DMA_PRICTL_SRCDIR_NONE,
DMA_PRICTL_START_STOP
);

// SECCTL Setup */
DMA_SECCTL_RMK(

DMa_SECCTL_WSPol_ACTIVEHIGH,
DMA_SECCTL_RSPOlACTIVEHIGH,
DMA_SECCTL_FSIG_NORMAL,
DMA_SECCTL_DETACEN_FRAMECOND,
DMA_SECCTL_WSYNClR NOTHING,
DMA_SECCTL_WSYNCRSTAT_CLEAR,
DMA_SECCTL_RSYNCCLR NOTHING,
DMA_SECCTL_RSYNCSTAT_CLEAR,
DMA_SECCTL_WS_BADIE_DISABLE,
DMA_SECCTL_WDROFCOND_CLEAR,
DMA_SECCTL_RTROFCOND_CLEAR,
DMA_SECCTL_BLOClE_ENABLE,
DMA_SECCTL_BLOCKCOND_CLEAR,
DMA_SECCTL_LASTIE_DISABLE,
DMA_SECCTL_LASTCOND_CLEAR,
DMA_SECCTL_FRAMEIE_DISABLE,
DMA_SECCTL_FRAMECOND_CLEAR,
DMA_SECCTL_RXIE_DISABLE,
DMA_SECCTL_RXCOND_CLEAR
);

// SRC Setup */
DMA_SRC_RMK(MCBSP_getRcvAddr(hMcbsp1)), /*McBSP DRR */

// DST Setup */
DMA_DST_RMK((Uint32)recvbuf), /*recvbuf*/

// XFRCNT Setup */
DMA_XFRCNT_RMK(

DMA_XFRCNT_FRMCNT_OF(1),
DMA_XFRCNT_ELEMCNT_OF(BUFFER_SIZE*11)
);

}/* End of ConfigDMA() */
#endif

/**************************************************************************/

void ConfigMcBSP(void):
Setup for McBSP Configuration
**************************************************************************/

/* void ConfigMcBSP(void): Setup for McBSP Configuration */
/**************************************************************************/
void ConfigMcBSP(void)
{

MCBSP_Config mcbspCfg1 = {

/* SPCR Setup */
#if (DMA_SUPPORT)

MCBSP_SPCR_RMK{

MCBSP_SPCR_FRST_DEFAULT, /* 0 */
MCBSP_SPCR_GRST_DEFAULT, /* 0 */
MCBSP_SPCR_XINTM_XRDY, /* 0 */
MCBSP_SPCR_XSYNCERR_DEFAULT, /* 0 */
MCBSP_SPCR_XRST_DEFAULT, /* 0 */
MCBSP_SPCR_DLB_OFF, /* 0 */
MCBSP_SPCR_RJJUST_RZF, /* 0 */
MCBSP_SPCR_CLKSTP_DISABLE, /* 0 */
MCBSP_SPCR_RINTM_RRDY, /* 0 */
MCBSP_SPCR_RSYNCERR_DEFAULT, /* 0 */
MCBSP_SPCR_RRST_DEFAULT, /* 0 */

```
Serial Port Mode

```
},
#endif
#if (EDMA_SUPPORT)
MCBSP_SPCR_RMK(
    MCBSP_SPCR_FREE_YES, /* 1 */
    MCBSP_SPCR_SOFT_DEFAULT, /* 0 */
    MCBSP_SPCR_FIRST_DEFAULT, /* 0 */
    MCBSP_SPCR_GRST_DEFAULT, /* 0 */
    MCBSP_SPCR_XINTM_XRDY, /* 0 */
    MCBSP_SPCR_XSYNCERR_DEFAULT, /* 0 */
    MCBSP_SPCR_XRST_DEFAULT, /* 0 */
    MCBSP_SPCR_DLB_OFF, /* 0 */
    MCBSP_SPCR_RINTM_RRDY, /* 00 */
    MCBSP_SPCR_RSYNCERR_DEFAULT, /* 0 */
    MCBSP_SPCR_RRST_DEFAULT /* 0 */
),
#endif
	/* RCR Setup */
#if (DMA_SUPPORT)
MCBSP_RCR_RMK(
    MCBSP_RCR_RPHASE_DUAL, /* 1 */
    MCBSP_RCR_RFRLEN2_OF(1), /* 0010 */
    MCBSP_RCR_RWDLEN2_8BIT, /* 00 */
    MCBSP_RCR_RCOMPAND_MSB, /* 0 */
    MCBSP_RCR_RFIG_YES, /* 1 */
    MCBSP_RCR_RDATDLY_1BIT, /* 01 */
    MCBSP_RCR_RFRLEN1_OF(8), /* 01000 */
    MCBSP_RCR_RWDLEN1_16BIT /* 010 */
),
#endif
#if (EDMA_SUPPORT)
MCBSP_RCR_RMK(
    MCBSP_RCR_RPHASE_DUAL, /* 1 */
    MCBSP_RCR_RFRLEN2_OF(1), /* 0010 */
    MCBSP_RCR_RWDLEN2_8BIT, /* 00 */
    MCBSP_RCR_RCOMPAND_MSB, /* 0 */
    MCBSP_RCR_RFIG_YES, /* 1 */
    MCBSP_RCR_RDATDLY_1BIT, /* 01 */
    MCBSP_RCR_RFRLEN1_OF(8), /* 01000 */
    MCBSP_RCR_RWDLEN1_16BIT /* 010 */
),
#endif
#if (DMA_SUPPORT)
MCBSP_XCR_RMK(
    MCBSP_XCR_XPHASE_DUAL, /* 1 */
    MCBSP_XCR_XFRLEN2_OF(1), /* 0010 */
    MCBSP_XCR_XWDLEN2_8BIT, /* 00 */
    MCBSP_XCR_XCOMPAND_MSB, /* 0 */
    MCBSP_XCR_XFIG_YES, /* 1 */
    MCBSP_XCR_XDATDLY_0BIT, /* 00 */
    MCBSP_XCR_XFRLEN1_OF(8), /* 01000 */
    MCBSP_XCR_XWDLEN1_16BIT /* 010 */
),
#endif
#if (EDMA_SUPPORT)
MCBSP_XCR_RMK(
    MCBSP_XCR_XPHASE_DUAL, /* 1 */
    MCBSP_XCR_XFRLEN2_OF(1), /* 0010 */
    MCBSP_XCR_XWDLEN2_8BIT, /* 00 */
    MCBSP_XCR_XCOMPAND_MSB, /* 0 */
    MCBSP_XCR_XFIG_YES, /* 1 */
    MCBSP_XCR_XDATDLY_0BIT, /* 00 */
    MCBSP_XCR_XFRLEN1_OF(8), /* 01000 */
    MCBSP_XCR_XWDLEN1_16BIT /* 010 */
),
#endif
	/* XCR Setup */
#if (DMA_SUPPORT)
MCBSP_XCR_RMK(
    MCBSP_XCR_XPHASE_DUAL, /* 1 */
    MCBSP_XCR_XFRLEN2_OF(1), /* 0010 */
    MCBSP_XCR_XWDLEN2_8BIT, /* 00 */
    MCBSP_XCR_XCOMPAND_MSB, /* 0 */
    MCBSP_XCR_XFIG_YES, /* 1 */
    MCBSP_XCR_XDATDLY_0BIT, /* 00 */
    MCBSP_XCR_XFRLEN1_OF(8), /* 01000 */
    MCBSP_XCR_XWDLEN1_16BIT /* 010 */
),
#endif
```
/ * SRGR Setup */
      
      MCBSP_SRGR_RMK({
      MCBSP_SRGR_GSYNC_FREE, /* 0 */
      MCBSP_SRGR_CLKSP_RISING, /* 0 */
      MCBSP_SRGR_CLKSM_INTERNAL, /* 1 */
      MCBSP_SRGR_FSGM_DXRS2XR, /* 0 */
      MCBSP_SRGR_FPER_DEFAULT, /* 0 */
      MCBSP_SRGR_FWID_DEFAULT, /* 0 */
      MCBSP_SRGR_CLKGDV_OF(108) /* CLKGDV */
      }),

      /* MCR Setup */
      MCBSP_MCR_DEFAULT,

      /* RCER Setup */
      #if (C64_SUPPORT)
      MCBSP_RCERE0_DEFAULT, /* default values */
      MCBSP_RCERE1_DEFAULT, /* default values */
      MCBSP_RCERE2_DEFAULT, /* default values */
      MCBSP_RCERE3_DEFAULT, /* default values */
      #else
      MCBSP_RCER_DEFAULT, /* default values */
      #endif

      /* XCER Setup */
      #if (C64_SUPPORT)
      MCBSP_XCERE0_DEFAULT, /* default values */
      MCBSP_XCERE1_DEFAULT, /* default values */
      MCBSP_XCERE2_DEFAULT, /* default values */
      MCBSP_XCERE3_DEFAULT, /* default values */
      #else
      MCBSP_XCER_DEFAULT, /* default values */
      #endif

      /* PCR Setup */
      MCBSP_PCR_RMK({
      MCBSP_PCR_XIOEN_SP, /* 0 */
      MCBSP_PCR_RIOEN_SP, /* 0 */
      MCBSP_PCR_FSXM_INTERNAL, /* 1 */
      MCBSP_PCR_FSRM_EXTERNAL, /* 0 */
      MCBSP_PCR_CLKSM_OUTPUT, /* 1 */
      MCBSP_PCR_CLKRM_OUTPUT, /* 1 */
      MCBSP_PCR_CLKSSTAT_0, /* 0 */
      MCBSP_PCR_DXSTAT_0, /* 0 */
      MCBSP_PCR_FSXP_ACTIVELOW, /* 1 */
      MCBSP_PCR_FSRP_ACTIVELOW, /* 1 */
      MCBSP_PCR_CLKXP_RISING, /* 0 */
      MCBSP_PCR_CLKRP_FALLING /* 0 */
      });

      MCBSP_config(hMcbsp1, &mcbspCfg1);
    } /* end of Config_McBSP(void) */

    /*******************************************************************************/
    /* void ProcessTransmitData(void) */
    /*******************************************************************************/
    void ProcessTransmitData(void)
    {
      Int i;
      Short cnt = 1;
      unsigned char xmit_char;
      unsigned short *xmitbufptr;
    }
/* point to Transmit Buffer */
xbmitbufptr = (unsigned short *)xmitbuf;

for (i=0; i<sizeof(xmitbuf)/sizeof(unsigned int); i++)
{
    xmitbufptr[i] = 0x0000; /* zero fill buffer */
}

/* Process data BYTES in xmit_msg[] and put in xmit buffer */
for (i = 0; i < BUFFER_SIZE; i++)
{
    /* Get transmit character (one byte) from xmit_msg[] */
    xmit_char = xmit_msg[i];

    /* Process each BYTE of transmit character */
    for (cnt = -1; cnt < 10; cnt++)
    {
        if (cnt == -1)
            *xmitbufptr++ = 0x0000;
        else if (cnt == 8 || cnt == 9)
            *xmitbufptr++ = 0xFFFF;
        else if (xmit_char & (1 << cnt))
            *xmitbufptr++ = 0xFFFF;
        else
            *xmitbufptr++ = 0x0000;
    }
}
/* end ProcessTransmitData */

/***************************************************************************/

void ProcessReceiveData(void)
{
    Int i;
    unsigned short recvchar = 0;
    short cnt = -1;
    short recv_val;
    unsigned short raw_data;
    unsigned short *recvbufptr; /* receive buffer pointer */

    /* Point to the receive buffer */
    Recvbufptr = (unsigned short *)recvbuf;

    /* Process all data in the Receive buffer */
    for (i = 0; i < BUFFER_SIZE; i++)
    {
        recv_char = 0;

        /* Process each UART frame */
        for (cnt = -1; cnt < 10; cnt++)
        {
            if (cnt == -1 || cnt == 8 || cnt == 9)
            {
                /* Ignore Start and Stop bits */
                *recvbufptr++;
            }
            else
            {

            }
        }
    }

/******************************************************************************/

// ProcessReceiveData(void)

// This function decodes the data in the receive buffer, "recvbuf" */
// and strips the framing start (0x0000) and stop (0xFFFF) words. */
// It calls the subroutine VoteLogic() to determine each bit of */
// the ASCII character. It then puts the result in recv_msg. */
//***************************************************************************/

void ProcessReceiveData(void)
{
    Int i;
    unsigned char recv_char = 0;
    short cnt = -1;
    short recv_val;
    unsigned short raw_data;
    unsigned short *recvbufptr; /* receive buffer pointer */

    /* Point to the receive buffer */
    Recvbufptr = (unsigned short *)recvbuf;

    /* Process all data in the Receive buffer */
    for (i = 0; i < BUFFER_SIZE; i++)
    {
        recv_char = 0;

        /* Process each UART frame */
        for (cnt = -1; cnt < 10; cnt++)
        {
            if (cnt == -1 || cnt == 8 || cnt == 9)
            {
                /* Ignore Start and Stop bits */
                *recvbufptr++;
            }
            else
            {

            }
        }
    }

/******************************************************************************/

// ProcessReceiveData(void)

// This function decodes the data in the receive buffer, "recvbuf" */
// and strips the framing start (0x0000) and stop (0xFFFF) words. */
// It calls the subroutine VoteLogic() to determine each bit of */
// the ASCII character. It then puts the result in recv_msg. */
//***************************************************************************/

/* The functions in UART21.c contain the code for the UART21 */
/* microcontroller. It sets up the McBSP to support */
/* the UART21 */

SPRA633C--September 2008
Submit Documentation Feedback

TMS320C620x/C642x McBSP: UART 21
/* Get 16-bit data from receive buffer */
raw_data = *recvbufptr;
recvbufptr++;

/* get the value of the majority of the bits */
recv_val = VoteLogic(raw_data);

put received bit into proper place */
recv_char += recv_val << cnt;
} /* end for cnt */

/* A full BYTE is decoded. Put in result: recv_msg[i] */
recv_msg[i] = recv_char;
} /* end for I */
} /* end ProcessReceiveData() function */

/**************************************************************************/
/* void CheckTestCase(void) */
/**************************************************************************/
int CheckTestCase(void)
{
    unsigned short *source;
    unsigned short *result;
    unsigned int i = 0;
    short cnt = -1;
    int error = 0;

    source = (unsigned short *) xmitbuf;
    result = (unsigned short *) recvbuf;

    for (i = 0; i < BUFFER_SIZE ; i++)
    {
        for (cnt = -1; cnt < 10; cnt++)
        {
            /* Ignore the start and stop bits */
            if((cnt == -1 || cnt == 8 || cnt ==9))
            {
                source++;
                result++;
            }
            else
            {
                if (*source != *result)
                {
                    error = i + 1;
                    break;
                }
                source++;
                result++;
            }
        }
        return(error);
    }
} /* end CheckTestCase() function */

/**************************************************************************/
/* short VoteLogic(unsigned short) */
/**************************************************************************/
short VoteLogic(unsigned short value)
{
    short returnvalue;

    switch ((value >> 6) & 0x0F)
```c
{  
  Case 0:  
  Case 1:  
  Case 2:  
  Case 3:  
  Case 4:  
  Case 5:  
  Case 6:  
  Case 8:  
  Case 9:  
  Case 10:  
    returnvalue = 0;  
    break;  
  case 7:  
  case 11:  
  case 12:  
  case 13:  
  case 14:  
  case 15:  
    returnvalue = 1;  
    break;  
}  
/* end switch */

return (returnvalue);  
}  
/* end VoteLogic() function */

/******************************************************************************
/* EDMA Data Transfer Completion ISRs */
******************************************************************************/

interrupt void c_int11(void) /* DMA 2 */  
{  
  #if (DMA_SUPPORT)
  transmit_done = TRUE;  
  printf("Transmit Completed\n");  
  #endif

}

interrupt void c_int09(void) /* DMA 1 */  
{  
  #if (DMA_SUPPORT)
  receive_done = TRUE;  
  printf("Receive Completed\n");  
  #endif

}

interrupt void c_int08(void)  
{  
  #if (EDMA_SUPPORT)
  if (EDMA_intTest(14))  
  {  
    EDMA_intClear(14);  
    transmit_done = TRUE;  
    printf("Transmit Completed\n");  
  }  
  if (EDMA_intTest(15))  
  {  
    EDMA_intClear(15);  
    receive_done = TRUE;  
    printf("Receive Completed\n");  
  }  
  #endif

}  
```
Appendix B  Sample C/Assembly Code

B.1 GPIO Mode

******************************************************************************
*TEXAS INSTRUMENTS, INC.                                                      *
*SOFTWARE UART EMULATION FOR TMS320C6000                                    *
*Revision Date: 18/5/99                                                       *
*Author: Philippe Malleth                                                   *
******************************************************************************

**USAGE**

These routines are C-callable and can be called as:

- `unsigned int SoftUartSpeedDetect(void);`
- `void SoftUartOutchar(int, char);`
- `char SoftUartInchar(int);`

If the routine is not to be used as a C-callable function, then all instructions relating to the stack should be removed.

See comments of individual instructions to determine if they are related to the stack. You also need to initialize all passed parameters since these are assumed to be in registers as defined by the calling convention of the compiler, (See the C compiler reference guide.)

**DESCRIPTION**

These routines are used to emulate the RX/TX behavior of a RS232 UART.

The RX and TX waveforms are generated with the McBSP pins put in GPIO mode. See the Application report for further details.

**C CODE**

This is the C equivalent of the assembly code without restrictions:

Note that the assembly code is hand optimized and restrictions may apply.

Calling convention:

This is a very basic example that first gets the right baudrate from subroutine SoftUartSpeedDetect(), then forever waits for a character and send it out as soon as received.

```c
main()
{
  unsigned int UartSpeed;
  char c;

  UartSpeed = SoftUartSpeedDetect();
  for(i=0; i<10; i++)
  {
    c = SoftUartInchar(UartSpeed);
    SoftUartOutchar(UartSpeed, c);
  }
}
```

Subroutine details:

- `volatile unsigned int speedcounter, i;`
- `MCBSP_IO_ENABLE(1);`
- `speedcounter = 0;`
- `while((int)MCBSP_DRSTAT(1));`
- `while(((int)MCBSP_DRSTAT(1)){ /* counts START bit */`
  `speedcounter++;`
- `while((int)MCBSP_DRSTAT(1)){ /* counts DR high (from <cr>) */`
```
/* speedcounter++; */
/* */
/* MCBSP_DX_IO_H(1); */
/* for(i=11*speedcounter;i>0;i--); /* wait long enough for one char */
/* speedcounter >>= 2; /* speedcounter divide by 2 */
/* */
/* return(speedcounter); */
/* */
/* */
/* char SoftUartInchar(int speedcnt) */
/* { */
/* volatile unsigned int incomingChar,speedcounter,tmpcounter; */
/* * volatile unsigned int tmpreg,dxstat; */
/* unsigned int lsb; */
/* */
/* incomingChar=0; */
/* * speedcounter = speedcnt; */
/* * tmpcounter = speedcounter>>1; */
/* * while((int)MCBSP_DRSTAT(1)); */
/* * while(--tmpcounter != 0) */
/* * tmpreg = (unsigned int)MCBSP_DRSTAT(1); /* counts half bit time */
/* * for(tmpreg = 9;tmpreg!=0;--tmpreg) */
/* * tmpcounter = speedcounter; */
/* * while(--tmpcounter != 0) */
/* * dxstat = (unsigned int)MCBSP_DRSTAT(1); /* counts bit time */
/* * if(dxstat==1) incomingChar++; */
/* * lsb = incomingChar&1; */
/* * incomingChar >>=1; */
/* * if (lsb) incomingChar+=0x80000000; */
/* } */
/* incomingChar >>=23; */
/* return((char)incomingChar); */
/* } */
/* */
/* * void SoftUartOutchar(int speedcnt, char outgoingChar) */
/* { */
/* unsigned int c,carry; */
/* volatile unsigned int paddedChar,bitcounter,tmpcounter; */
/* */
/* MCBSP_DX_IO_L(1); */
/* carry = 0; */
/* * paddedChar = ((unsigned int)outgoingChar) | 0x00000700; */
/* * for(bitcounter=11;bitcounter>0;bitcounter--) { */
/* * tmpcounter = speedcnt; */
/* * while(--tmpcounter != 0) (int)MCBSP_DRSTAT(1); */
/* * c = carry; */
/* * carry = paddedChar&1; */
/* * paddedChar >>=1; */
/* * if (cary) MCBSP_DX_IO_H(1); */
/* * else MCBSP_DX_IO_L(1); */
/* */
/* * MCBSP_DX_IO_H(1); */
/* * } */
/* */
/* } */
/* */
/* */
/* .global _SoftUartSpeedDetect */
/* .global _SoftUartInchar */
/* .global _SoftUartOutchar */
/* .sect *.text* */
/* */
/* */
/* FUNCTION NAME: _SoftUartSpeedDetect */
/* */
/* USAGE */
/* This routines are C-callable and can be called as: */
/* unsigned int SoftUartSpeedDetect(void); */
/* */
/* The McBSP1 at address 0x1900000 is used here. */
/* Argument 1 : None. */
/* Return Value : ASCII coded character read from a terminal. */
/* */
/* */
** preserve "save-on-call" registers

SUB .D2 B15, 4, A0
STW .D1 A10, *B15--[2] ; f
STW .D2 A11, *B15--[2] ; f
STW .D1 B11, *A0--[2] ; f
STW .D2 B12, *A0--[2] ; f
STW .D2 A13, *B15--[2] ; f
STW .D1 B13, *A0--[2] ; f
MVC .S2 CSR, B13 ; f
STW .D2 A14, *B15--[2] ; f
STW .D1 B14, *A0--[2] ; f
AND .L2 -2, B13, B13 ; f
STW .D2 A15, *B15--[2] ; f
STW .D1 B3, *A0--[2] ; f
MVC .S2 B13, CSR ; f disable global interrupts

** ---------------------------------------*

MVK .S1 0x8, A0 ; set offset to SPCR register
MVKH .S1 0x1900000, A0 ; takes McBSP1 port address
LDW .DIT1 *A0, A3 ; load SPCR register
NOP 4
CLR .S1 A3, 0x10, 0x10, A3 ;
AND .L1 0xffffffff, A3, A3 ;
STW .DIT1 A3, *A0 ; store new SPCR config value
|
MVK .S1 0x24, A0 ; set offset for PCR register
MVKH .S1 0x1900000, A0 ; takes McBSP1 port address
LDW .DIT1 *A0, A3 ; load PCR register
NOP 4
SET .S1 A3, 0xc, 0xd, A3 ; set bit 12&13 for I/O mode
STW .DIT1 A3, *A0 ; store new PCR config value
NOP 5
LDW .DIT1 *A0, A3 ;
NOP 4
EXTU .S1 A3, 0x1b, 0x1f, A1 ; wait while DRSTAT is high

** ---------------------------------------*

.align 32
L1: [A1] B .S2 L1 ;
  | [ A1] LDW .DIT1 *A0, A3 ;
  | [ A1] EXTU .S1 A3, 0x1b, 0x1f, A1 ; wait while DRSTAT is high
  | ![A1] ZERO .L2 B4 ; initialize counter
  | [A1] NOP 5 ; for StartBit measurement

** ---------------------------------------*

.align 32
L3: [A1] B .S2 L3 ;
  | [ A1] LDW .DIT1 *A0, A3 ;
  | [ A1] EXTU .S1 A3, 0x1b, 0x1f, A1 ;
  | ![A1] ADD .L2 0x1, B4, B4 ; increment counter while
  | [A1] NOP 5 ; DRSTAT bit is low

** ---------------------------------------*

.align 32
L31B: [A1] B .S2 L31B ;
  | [ A1] LDW .DIT1 *A0, A3 ;
  | [ A1] EXTU .S1 A3, 0x1b, 0x1f, A1 ;
  | [ A1] ADD .L2 0x1, B4, B4 ; increment counter while
  | [A1] NOP 5 ; DRSTAT bit is low

** ---------------------------------------*

.align 32
SHRU .S2 B4, 0x1, B4 ;
MVK .S2 0x0b, B0 ;
SET .S1 A3, 0x5, 0x5, A3 ; set DXSTAT bit to 1
|
MV .LIX B0, A4 ;
MPYLUH .M1X A4, B4, A3 ;
|
STW .DIT1 A3, *A0 ; store new PCR config value
MPYU .M2 B0, B4, B0 ;
SHL .S1 A3, 0x10, A3 ;
ADD .L2X B0, A3, B0 ;

** ---------------------------------------*

.waitcnt: [B0] B .S1 waitcnt ;
  | [B0] SUB .L2 B0, 0x1, B0 ;
  | [B0] LDW .DIT1 *A0, A3 ; Dummy load
```assembly
NOP 5 ; BRANCH OCCURS ;
/** ------------------------------------------ function epilog ---------------------------------------------*
/** restore preserved by call registers
SUB    B15, 4, A0
LDW .D1 ++A0[2], B3 ; f
LDW .D2 ++B15[2], A15 ; f
MVC .S2 CSR, B13 ; f
LDW .D1 ++A0[2], B14 ; f
LDW .D2 ++B15[2], A14 ; f
OR .L2 B13, 1, B13 ; f
LDW .D1 ++A0[2], B13 ; f
LDW .D2 ++B15[2], A13 ; f
MVC .S2 B13,CSR ; f enable global interrupts
LDW .D1 ++A0[2], B12 ; f
LDW .D2 ++B15[2], A12 ; f
LDW .D1 ++A0[2], B11 ; f
LDW .D2 ++B15[2], A11 ; f
B .S2 B3 ; f return();
MV .LIX B4,A4 ;
LDW .D2 ++B15[2], A10 ; f
LDW .D1 ++A0[2], B10 ; f
NOP 4 ; f
/** -------------------------------------------------------------------------------------------*
/** ------------------------------------------ function prolog ------------------------------------------*
/** preserve *save-on-call* registers
SUB    B15, 4, A0
STW .D1 B10, *A0[2] ; f
STW .D1 B11, *A0[2] ; f
STW .D1 B12, *A0[2] ; f
STW .D1 B13, *A0[2] ; f
MVC .S2 CSR,B13 ; f
temp = McBSP1 address 0x1900000 is used here.
LDW .D1 B14, *A0[2] ; f
AND .L2 -2,B13,B13 ; f
STW .D1 B3, *A0[2] ; f
MVC .S2 B13,CSR ; f disable global interrupts
/** -------------------------------------------------------------------------------------------*
MVK .S2 0x24,B4 ; set offset to SPCR register
MV .L1 A4,A0 ;
MVKH .S2 0x1900000,B4 ; takes McBSP1 port address
SHRU .S1 A0,0x2,A1 ;
ZERO .L1 A4 ;
LDW .D2 T2 *B4,B5 ;
NOP 4
EXTU .S2 B5,0x1b,0xf,0 ; wait while DRSTAT bit is high
/** -------------------------------------------------------------------------------------------*
LP: [ B0] B .S1 L2 ;
[ B0] LDW .D2 T2 *B4,B5 ;
EXTU .S2 B5,0x1b,0xf,0 ; wait while DRSTAT bit is high
NOP 5 ; BRANCH OCCURS ; |16|
/** -------------------------------------------------------------------------------------------*```
L4:[ A1] B .S1 L4 ;
[ A1] SUB .L1 A1,0x1,A1 ; while (--tmpcounter != 0 )
[ A1] LDW .D2T2 *B4,B0 ; dummy load
NOP 5
MVK .S2 0x8,B1 ;
MV .L1 A0,A1 ;
/* ------------------------------------------------------------------------*

L8:[ A1] B .S1 L8 ;
[ A1] SUB .L1 A1,0x1,A1 ; while (--tmpcounter != 0 )
[ A1] LDW .D2T2 *B4,B0 ; do read DRSTAT bit
EXTU .S2 B0,0x1b,0x1f,B0 ;
NOP 5 ; BRANCH OCCURS ; |33|
/* ------------------------------------------------------------------------*

L4:
[ B1] B .S1 L8 ;
[ B0] ADD .L1 0x1,A4,A4 ;
AND .L1 0x1,A4,A4 ; lsb = incomingChar & 1
|| SHRU .S1 A4,0x1,A4 ; incomingChar >>= 1
|| SET .S1 A4,0xf,0xf,A4 ; if (lsb) incomingChar
|| =0x80000000
|| MV .L1 A0,A1 ;
|| SUB .L2 B1,0x1,B1 ;
NOP 3 ; BRANCH OCCURS ; |42|
/* ------------------------------------ function epilog ----------------------*
/* restore preserved by call registers
SUB B15, 4, A0
|| LDW .D1 ***A0[2], B3 ; f
LDW .D2 ***B15[2], A15 ; f
MVC .S2 CSR, B13 ; f
LDW .D1 ***A0[2], B14 ; f
LDW .D2 ***B15[2], A14 ; f
OR .L2 B13, l, B13 ; f
LDW .D1 ***A0[2], B13 ; f
LDW .D2 ***B15[2], A13 ; f
MVC .S2 B13,CSR ; f enable global interrupts
LDW .D1 ***A0[2], B12 ; f
LDW .D2 ***B15[2], A12 ; f
LDW .D1 ***A0[2], B11 ; f
LDW .D2 ***B15[2], A11 ; f
B .S2 B3 ; f return();
SHRU .S1 A4,0x17,A4 ; incomingChar >>= 23
LDW .D2 ***B15[2], A10 ; f
LDW .D1 ***A0[2], B10 ; f
NOP 4 ; f
/* ------------------------------------------------------------------------*

/*************************************************************/
/* FUNCTION NAME: _SoftUartOutchar */
/* */
/* USAGE */
/* * This routine are C-callable and can be called as: */
/* */
/* void SoftUartOutchar(int speedcnt, char rl); */
/* */
/* The McBSP1 at address 0x19000000 is used here. */
/* Argument 1 : Speed counter value returned by SoftUartSpeedDetect(). */
/* Argument 2 : ASCII coded character to be send out to a terminal. */
/* Return Value : None */
/* */
/*************************************************************/
_SoftUartOutchar:
/---------- function prolog ------------------------------*/
/* preserve "save-on-call" registers */
SUB B15, 4, A0
STW .D2 A10, *B15--[2] ; f
STW .D1 B10, *A0--[2] ; f
STW .D2 A11, *B15--[2] ; f
STW .D1 B11, *A0--[2] ; f
STW .D2 A12, *B15--[2] ; f
STW .D1 B12, *A0--[2] ; f
STW .D2 A13, *B15--[2] ; f
STW .D1 B13, *A0--[2] ; f
MVC .S2 CSR,B13 ; f
STW .D2 A14, *B15--[2] ; f
STW .D1 B14, *A0--[2] ; f
AND .L2 -2,B13,B13 ; f
STW .D2 A15, *B15--[2] ; f
STW .D1 B3, *A0--[2] ; f
MVC .S2 B13,CSR ; f disable global interrupts

**

MKV .S1 0x24,A0
MKKH .S1 0x1000000,A0 ; takes McBSP1 port address
LDW .DIT1 *A0,A3 ;
ZERO .L2 B1 ; carry = 0
MVK .S2 0xb,B2 ; bitcounter = 11 bit
| (1st,8dt,2stp)
SET .S2 B4,0x8,0xA,B4 ; paddedChar = outgoingChar
MV .L2X A4,B0 ;
CLR .S1 A3,0x5,0x6,A3 ; set DXSTAT bit to 0
STW .DIT1 A3,*A0 ; store new PCR config value

** ---------------------------------------*

loopcnt4: [B0] B .S1 loopcnt4 ;

[ B0] LDW .DIT1 *A0,A3 ; Dummy load
MV .L1X B1,A1 ; c = carry
[ B0] SUB .L2 B0,0x1,B0 ; while (--tmpcounter !=0 )
NOP 5

** ---------------------------------------*

[ B2] B .S1 loopcnt4 ; wait 11 bits released
AND .L2 0x1,B4,B1 ; carry = paddedChar*1
NOP 2
[ B2] SUB .L2 B2,0x1,B2 ; bitcounter--
SHRU .S2 B4,0x1,B4 ; paddedChar >>= 1
[ B1] SET .S1 A3,0x5,0x6,A3 ; set DXSTAT bit to 1
[!B1] CLR .S1 A3,0x5,0x6,A3 ; set DXSTAT bit to 0
MV .L2X A4,B0 ;
STW .DIT1 A3,*A0 ; store new PCR config value
; BRANCH OCCURS ;

** ---------------------------------------*

LDW .DIT1 *A0,A3 ;
NOP 4
SET .S1 A3,0x5,0x6,A3 ; set DXSTAT bit to 1
STW .DIT1 A3,*A0 ; store new PCR config value

** ---------------------------------------*

;** restore preserved by call registers
SUB .L2 B15, 4, A0
LDW .D1 ++++B15[2], B3 ; f
LDW .D2 ++++B15[2], A15 ; f
MVC .S2 CSR, B13 ; f
LDW .D1 ++++B15[2], B14 ; f
LDW .D2 ++++B15[2], A14 ; f
OR .L2 B13, 1, B13 ; f
LDW .D1 ++++B15[2], B13 ; f
LDW .D2 ++++B15[2], A13 ; f
MVC .S2 B13,CSR ; f enable global interrupts
LDW .D1 ++++B15[2], B12 ; f
LDW .D2 ++++B15[2], A12 ; f
LDW .D1 ++++B15[2], B11 ; f
LDW .D2 ++++B15[2], A11 ; f
B .S2 B3 ; f return();
LDW .D2 ++++B15[2], A10 ; f
LDW .D1 ++++B15[2], B10 ; f
NOP 4 ; f

** ---------------------------------------*
**IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death. Users represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory, and safety-related requirements concerning their products and any use of TI products in such safety-critical applications. TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or “enhanced plastic.” Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer’s risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

<table>
<thead>
<tr>
<th>Products</th>
<th>Applications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Amplifiers</td>
<td>Audio</td>
</tr>
<tr>
<td>Data Converters</td>
<td>Automotive</td>
</tr>
<tr>
<td>DSP</td>
<td>Broadband</td>
</tr>
<tr>
<td>Clocks and Timers</td>
<td>Digital Control</td>
</tr>
<tr>
<td>Interface</td>
<td>Medical</td>
</tr>
<tr>
<td>Logic</td>
<td>Military</td>
</tr>
<tr>
<td>Power Mgmt</td>
<td>Optical Networking</td>
</tr>
<tr>
<td>Microcontrollers</td>
<td>Security</td>
</tr>
<tr>
<td>RFID</td>
<td>Telephony</td>
</tr>
<tr>
<td>RF/I and ZigBee® Solutions</td>
<td>Video &amp; Imaging</td>
</tr>
<tr>
<td></td>
<td>Wireless</td>
</tr>
</tbody>
</table>

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2008, Texas Instruments Incorporated