



Now







ADS5474

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ADS5474 14-Bit, 400-MSPS Analog-to-Digital Converter

Features

- 400-MSPS Sample Rate
- 14-Bit Resolution, 11.2-Bits ENOB
- 1.4-GHz Input Bandwidth
- 80-dBc SFDR at 230 MHz and 400 MSPS
- 69.8-dBFS SNR at 230 MHz and 400 MSPS
- 2.2-V_{PP} Differential Input Voltage
- LVDS-Compatible Outputs
- 2.5-W Total Power Dissipation
- 50-mW Power-Down Mode
- Offset Binary Output Format
- Output Data Transitions on the Rising and Falling Edges of a Half-Rate Output Clock
- On-Chip Analog Buffer, Track-and-Hold, and Reference Circuit
- HTQFP-80 PowerPAD[™] Package (14-mm × 14-mm Footprint)
- Industrial Temperature Range: -40°C to +85°C
- Pin-Similar, -Compatible With 12-, 13-, and 14-Bit • Family: ADS5463, ADS5440, ADS5444

2 Applications

- **Test and Measurement Instrumentation**
- Software-Defined Radio
- Data Acquisition
- **Power Amplifier Linearization**
- Communication Instrumentation
- Radar

3 Description

The ADS5474 device is a 14-bit, 400-MSPS analogto-digital converter (ADC) that operates from both a 5-V supply and 3.3-V supply while providing LVDScompatible digital outputs. This ADC is one of a family of 12-, 13-, and 14-bit ADCs that operate from 210 MSPS to 500 MSPS. The ADS5474 device has an input buffer that isolates the internal switching of the onboard track and hold (T&H) from disturbing the signal source while providing a high-impedance input. An internal reference generator is also provided to simplify the system design.

Designed with a 1.4-GHz input bandwidth for the conversion of wide-bandwidth signals that exceed 400 MHz of input frequency at 400 MSPS, the has device ADS5474 outstanding low-noise performance and spurious-free dynamic range over a large input frequency range.

The ADS5474 device is available in an TQFP-80 PowerPAD package. The device is built on Texas Instruments complementary bipolar process (BiCom3) and is specified over the full industrial temperature range (-40° C to $+85^{\circ}$ C).

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
ADS5474	HTQFP (80)	12.00 mm x 12.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

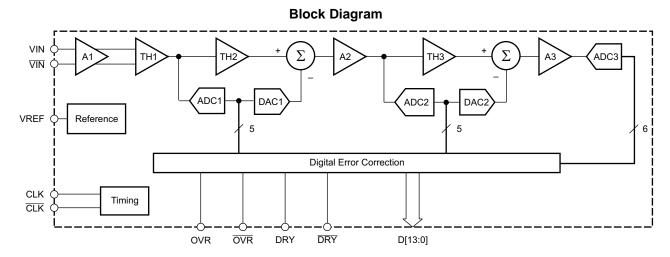




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4 Revision History

Changes from Revision C (January 2016) to Revision D	Page
Changed CLK input sample rate (sine wave) parameter maximum specification from	n 400 MSPS to 404 MSPS 6
Changed max sample rate from 400 MHz to 404 MHz in Detailed Design Procedure	e section 25
Changes from Revision B (February 2012) to Revision C	Page

•	Added ESD Ratings table, Feature Description section, Device Functional Modessection, Application and
	Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation
	Support section, and Mechanical, Packaging, and Orderable Information section

C	Changes from Revision A (August 2008) to Revision B	
•	Changed 1.6pF to 2.3pF TYP Input capacitance in ELECTRICAL CHARACTERISTICS	7
•	Changed (where DRY equals the CLK frequency) to (where DRY equals ½ the CLK frequency) in Digital Outputs section	21

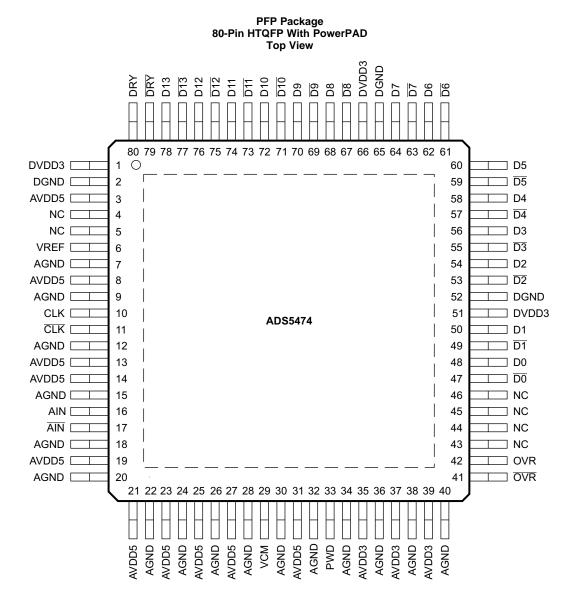
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5 Pin Configuration and Functions



(1) NC - No internal connection.

P0027-03

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NSTRUMENTS

Texas

	PIN		Pin Functions	
NAME	NO.	TYPE	DESCRIPTION	
AIN	16		Differential input signal (positive)	
	17	1	Differential input signal (peditve)	
/	3	•		
	8	-		
	13	_		
	14	-		
	19	-		
AVDD5	21		Analog power supply (5 V)	
	23	-		
	25			
	27			
	31			
	35		Δr_{2}	
AVDD3	37	Appleg power supply (2.2 V) (suggestion for < 250 MSPS; leave option to compa		
	39			
	1			
DVDD3	51		Digital and output driver power supply (3.3 V)	
	66			
	7	_		
	9	_		
	12	_		
	15	_		
	18	_		
	20	_		
	22	_		
AGND	24	-	Analog Ground	
	26	_		
	28 30	_		
	30	-		
	34	-		
	36	-		
	38	1		
	40	1		
	2			
DGND	52	1	Digital Ground	
	65	1		
CLK	10	I	Differential input clock (positive). Conversion is initiated on rising edge, digital outputs on falling edge.	
CLK	11	I	Differential input clock (negative)	
D0	48			
D0	47	0	LVDS digital output pair, least significant bit (LSB)	



Pin Functions (continued)

PIN			DECODUCTION (
NAME	NO.	TYPE	DESCRIPTION				
D1	50						
D1	49						
D2	54						
D2	53						
D3	56						
D3	55						
D4	58						
D4	57						
D5	60						
D5	59						
D6	62						
D6	61	0	LVDS digital output pairs				
D7	64	Ū					
D7	63						
D8	68						
D8	67						
D9	70						
D9	69						
D10	72						
D10	71						
D11	74						
D11	73						
D12	76						
D12	75						
D13	78	0	LVDS digital output pair, most significant bit (MSB)				
D13	77						
DRY	80	0	Data ready LVDS output pair				
DRY	79						
	4	-	No connection (pins 4 and 5 should be left floating)				
	5 43						
NC	43						
	44	-	No connection (pins 43 to 46 are possible future bit additions for this pinout and therefore can be connected to a digital bus or left floating)				
	45						
OVR	40						
OVR	42	0	Overrange indicator LVDS output. A logic high signals an analog input in excess of the full- scale range.				
VCM	29	0	Common-mode voltage output (3.1 V nominal). Commonly used in DC-coupled applications to set the input signal to the correct common-mode voltage. A 0.1-μF capacitor from VCM to AGND is recommended, but not required. (This pin is not used on the ADS5440, ADS5444, and ADS5463)				
PWD	33		Power-down (active high). Device is in sleep mode when PWD pin is logic HIGH. ADC converter is awake when PWD is logic LOW (grounded). (This pin is not used on the ADS5440, ADS5444, and ADS5463)				
VREF	6		Reference voltage input/output (2.4 V nominal). A 0.1- μ F capacitor from VREF to AGND is recommended, but not required.				
(Power Pad)	(not numbered)		Power Pad for thermal relief, also Analog Ground				

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6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range, unless otherwise noted.⁽¹⁾

		MIN	MAX	UNIT
	AVDD5 to GND		6	
Supply voltage	AVDD3 to GND		5	V
	DVDD3 to GND		5	
Analog input to GND	Valid when supplies are on and within normal ranges. See additional information in the Power Supplies portion of the applications information	-0.3	(AVDD5 + 0.3)	V
Clock input to GND	in the back of the datasheet regarding Clock and Analog Inputs when the supplies are off.	-0.3	-0.3 (AVDD5 + 0.3)	V
CLK to CLK		-2.5	2.5	V
Digital data outp	ut to GND	-0.3	(DVDD3 + 0.3)	V
Operating tempe	erature range	-40	85	°C
Maximum junction	on temperature		+150	°C
Storage tempera	ature range	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	2000	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

		MIN	NOM	MAX	UNIT
SUPPLIE	S			·	
AVDD5	Analog supply voltage	4.75	5	5.25	V
AVDD3	Analog supply voltage	3.1	3.3	3.6	V
DVDD3	Output driver supply voltage	3	3.3	3.6	V
ANALOG	INPUT				
	Differential input range		2.2		V _{PP}
VCM	Input common mode		3.1		V
DIGITAL	OUTPUT (DRY, DATA, OVR)			3.1	
	Maximum differential output load		10		pF
CLOCK I	NPUT (CLK)				
	CLK input sample rate (sine wave)	20		404	MSPS
	Clock amplitude, differential sine wave (see Figure 37)	0.5		5	V _{PP}
	Clock duty cycle (see Figure 31)	40%	50%	60%	
T _A	Operating free-air temperature	-40		+85	°C

6.4 Thermal Information

		ADS5474	
	THERMAL METRIC ⁽¹⁾	PFP (HTQFP)	UNIT
		80 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	25.9	°C/W
R _{0JC(top)}	Junction-to-case (top) thermal resistance	7.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	9.8	°C/W
ΨJT	Junction-to-top characterization parameter	0.2	°C/W
Ψјв	Junction-to-board characterization parameter	9.7	°C/W
R _{0JC(bot)}	Junction-to-case (bottom) thermal resistance	0.2	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

6.5 Electrical Characteristics

Typical values at $T_A = 25^{\circ}$ C: minimum and maximum values over full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3-V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
Resolutio	on			14		Bits
ANALOG	G INPUTS					
	Differential input range			2.2		V _{PP}
	Analog input common-mode voltage	Self-biased; see VCM specification below		3.1		V
	Input resistance (dc)	Each input to VCM		500		Ω
	Input capacitance	Each input to GND		2.3		pF
	Analog input bandwidth (-3dB)			1.44		GHz
CMRR	Common-mode rejection ratio	Common-mode signal < 50 MHz (see Figure 27)		100		dB
INTERNA	AL REFERENCE VOLTAGE					
VREF	Reference voltage			2.4		V
VCM	Analog input common-mode voltage reference output	With internal VREF. Provided as an output via the VCM pin for dc-coupled applications. If an external VREF is used, the VCM pin tracks as illustrated in Figure 42	2.9	3.1	3.3	V
	VCM temperature coefficient			-0.8		mV/°C
DYNAM	C ACCURACY				,	
	No missing codes			Assured		
DNL	Differential linearity error	f _{IN} = 70 MHz	-0.99	±0.7	1.5	LSB
INL	Integral linearity error	f _{IN} = 70 MHz	-3	±1	3	LSB
	Offset error		-11		11	mV
	Offset temperature coefficient			0.02		mV/°C
	Gain error		-5		5	%FS
	Gain temperature coefficient			-0.02		%FS/°C
POWER	SUPPLY					
I _{AVDD5}	5-V analog supply current	V_{IN} = full-scale, f_{IN} = 70 MHz, f_{S} = 400 MSPS		338	372	mA
I _{AVDD3}	3.3-V analog supply current	V_{IN} = full-scale, f_{IN} = 70 MHz, f_{S} = 400 MSPS		185	201	mA
I _{DVDD3}	3.3-V digital supply current (includes LVDS)	V_{IN} = full-scale, f_{IN} = 70 MHz, f_{S} = 400 MSPS		75	83	mA
	Total power dissipation			2.5	2.797	W
	Power-up time	From turn-on of AVDD5		50		μS



Electrical Characteristics (continued)

Typical values at $T_A = 25^{\circ}$ C: minimum and maximum values over full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3-V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Wake-up time	From PWD pin switched from HIGH (PWD active) to LOW (ADC awake) (see Figure 28)		5		μS
	Power-down power dissipation	PWD pin = logic HIGH		50	350	mW
PSRR	Power-supply rejection ratio, AVDD5 supply	Without 0.1- μ F board supply capacitors, with < 1-MHz supply noise (see Figure 46)		75		dB
PSRR	Power-supply rejection ratio, AVDD3 supply	Without 0.1- μ F board supply capacitors, with < 1-MHz supply noise (see Figure 46)		90		dB
PSRR	Power-supply rejection ratio, DVDD3 supply	Without 0.1- μ F board supply capacitors, with < 1-MHz supply noise (see Figure 46)		110		dB
DYNAM	IC AC CHARACTERISTICS					
		f _{IN} = 30 MHz		70.3		
		f _{IN} = 70 MHz	68.3	70.2		
		f _{IN} = 130 MHz		70.1		
		f _{IN} = 230 MHz	68	69.8		
SNR	Signal-to-noise ratio	f _{IN} = 351 MHz		69.1		dBFS
		f _{IN} = 451 MHz		68.4		
		f _{IN} = 651 MHz		67.5		
		f _{IN} = 751 MHz		66.6		
		f _{IN} = 999 MHz		64.7		
		f _{IN} = 30 MHz		88		
		f _{IN} = 70 MHz	74	86		
		f _{IN} = 130 MHz		80		
		f _{IN} = 230 MHz	71	80		
SFDR	Spurious-free dynamic range	f _{IN} = 351 MHz		76		dBc
		f _{IN} = 451 MHz		71		
		f _{IN} = 651 MHz		60		
		f _{IN} = 751 MHz		55		
		f _{IN} = 999 MHz		46		
		f _{IN} = 30 MHz		89		
		f _{IN} = 70 MHz		87		
		f _{IN} = 130 MHz		90		
		f _{IN} = 230 MHz		84		
HD2 S	Second-harmonic	f _{IN} = 351 MHz		76		dBc
		f _{IN} = 451 MHz		71		
		f _{IN} = 651 MHz		74		
		f _{IN} = 751 MHz		70		
		f _{IN} = 999 MHz		55		



Electrical Characteristics (continued)

Typical values at $T_A = 25^{\circ}$ C: minimum and maximum values over full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3-V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT				
		f _{IN} = 30 MHz	93					
		f _{IN} = 70 MHz	86					
		f _{IN} = 130 MHz	80					
		f _{IN} = 230 MHz	80					
HD3	Third-harmonic	f _{IN} = 351 MHz	85	dBc				
		f _{IN} = 451 MHz	71					
		f _{IN} = 651 MHz	60					
		f _{IN} = 751 MHz	55					
		f _{IN} = 999 MHz	46					
		f _{IN} = 30 MHz	95					
		f _{IN} = 70 MHz	93					
		f _{IN} = 130 MHz	85					
		f _{IN} = 230 MHz	85					
	Worst harmonic, spur	f _{IN} = 351 MHz	87	dBc				
	(other than HD2 and HD3)	f _{IN} = 451 MHz	87	_				
		$f_{\rm IN} = 451 \text{ MHz}$ 90						
		IN 651 MHZ 90 f _{IN} = 751 MHz 87						
		80	_					
		f _{IN} = 999 MHz f _{IN} = 30 MHz	86					
		$f_{\rm IN} = 70 \text{ MHz}$	83	_				
		$f_{\rm IN} = 130 \text{ MHz}$	78	_				
THD Total harmonic distortion		$f_{\rm IN} = 230 \text{ MHz}$	77	_				
	$f_{\rm IN} = 351 \text{ MHz}$	75	dBc					
IIID	HD I otal harmonic distortion	$\frac{f_{\rm IN} = 651 \text{ MHz}}{f_{\rm IN} = 651 \text{ MHz}} = 1000000000000000000000000000000000000$						
		$f_{\rm IN} = 751 \text{ MHz}$	55	_				
		$f_{\rm IN} = 999 \text{ MHz}$	45	_				
		$f_{\rm IN} = 30 \text{ MHz}$	69.2					
				_				
		f _{IN} = 70 MHz	67 68.9	_				
		$f_{IN} = 130 \text{ MHz}$	68.5	_				
		$f_{IN} = 230 \text{ MHz}$	65.5 68.2					
SINAD	Signal-to-noise and distortion	$f_{IN} = 351 \text{ MHz}$	67.3	dBc				
		$f_{IN} = 451 \text{ MHz}$	64.8	_				
		$f_{IN} = 651 \text{ MHz}$	58.5	_				
		f _{IN} = 751 MHz	54	_				
		f _{IN} = 999 MHz	45.4					
		$f_{IN1} = 69 \text{ MHz}, f_{IN2} = 70 \text{ MHz},$ each tone at -7 dBFS	93					
		$f_{IN1} = 69 \text{ MHz}, f_{IN2} = 70 \text{ MHz},$ each tone at -16 dBFS	95	dBFS				
Two-tone SFDR	f_{IN1} = 297.5 MHz, f_{IN2} = 302.5 MHz, each tone at –7 dBFS	85	UDF3					
		$f_{\rm IN1}$ = 297.5 MHz, $f_{\rm IN2}$ = 302.5 MHz, each tone at –16 dBFS	83					
		f _{IN} = 70 MHz	10.8 11.2					
ENOB	Effective number of bits	f _{IN} = 230 MHz	10.6 10.9	Bits				

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Electrical Characteristics (continued)

Typical values at $T_A = 25^{\circ}$ C: minimum and maximum values over full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3-V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	RMS idle-channel noise	Inputs tied to common-mode		1.8		LSB
DIGITA	L OUTPUTS				Ľ	
V _{OD}	Differential output voltage (±)		247	350	454	mV
V _{OC}	Common-mode output voltage		1.125		1.375	V
DIGITA	L INPUTS		•			
V _{IH}	High level input voltage	PWD (pin 33)	2			V
VIL	Low level input voltage	PWD (pin 33)			0.8	V
I _{IH}	High level input current	PWD (pin 33)			1	μA
IIL	Low level input current	PWD (pin 33)	-1			μA
	Input capacitance	PWD (pin 33)		2		pF

6.6 Timing Characteristics

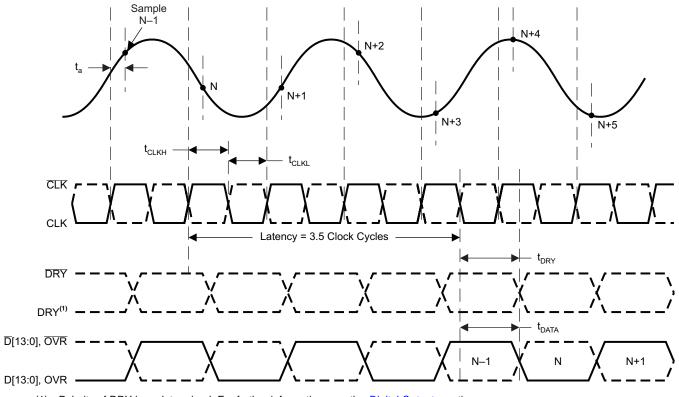
Typical values at $T_A = 25^{\circ}$ C: minimum and maximum values over full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, and $3 - V_{PP}$ differential clock, unless otherwise noted.⁽¹⁾

		TEST CONDITIONS	MIN	NOM	MAX	UNIT
ta	Aperture delay			200		ps
	Aperture jitter, rms	Internal jitter of the ADC		103		fs
	Latency			3.5		cycles
t _{CLK}	Clock period		2.5		50	ns
t _{CLKH}	Clock pulse duration, high		1			ns
t _{CLKL}	Clock pulse duration, low		1			ns
t _{DRY}	CLK to DRY delay ⁽²⁾	Zero crossing, 10-pF parasitic loading to GND on each output pin	1000	1400	1800	ps
t _{DATA}	CLK to DATA/OVR delay ⁽²⁾	Zero crossing, 10-pF parasitic loading to GND on each output pin	800	1400	2000	ps
t _{SKEW}	DATA to DRY skew	$t_{\text{DATA}} - t_{\text{DRY}}, 10\text{-}p\text{F}$ parasitic loading to GND on each output pin	-500	0	500	ps
t _{RISE}	DRY/DATA/OVR rise time	10-pF parasitic loading to GND on each output pin		500		ps
t _{FALL}	DRY/DATA/OVR fall time	10-pF parasitic loading to GND on each output pin		500		ps

(1) Timing parameters are ensured by design or characterization, but not production tested.

(2) DRY, DATA, and OVR are updated on the falling edge of CLK. The latency must be added to t_{DATA} to determine the overall propagation delay.





(1) Polarity of DRY is undetermined. For further information, see the *Digital Outputs* section.

Figure 1. Timing Diagram

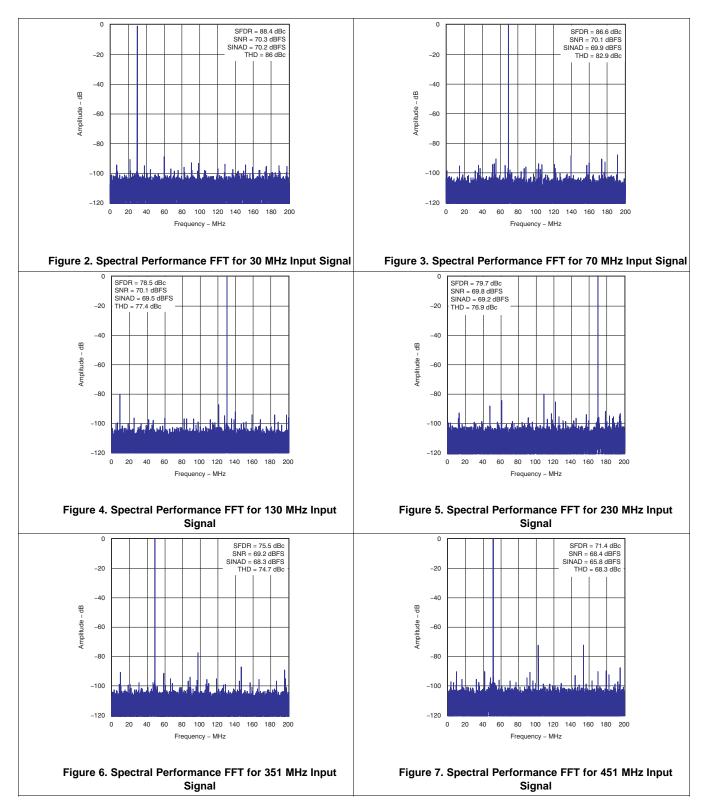
INSTRUMENTS

Texas

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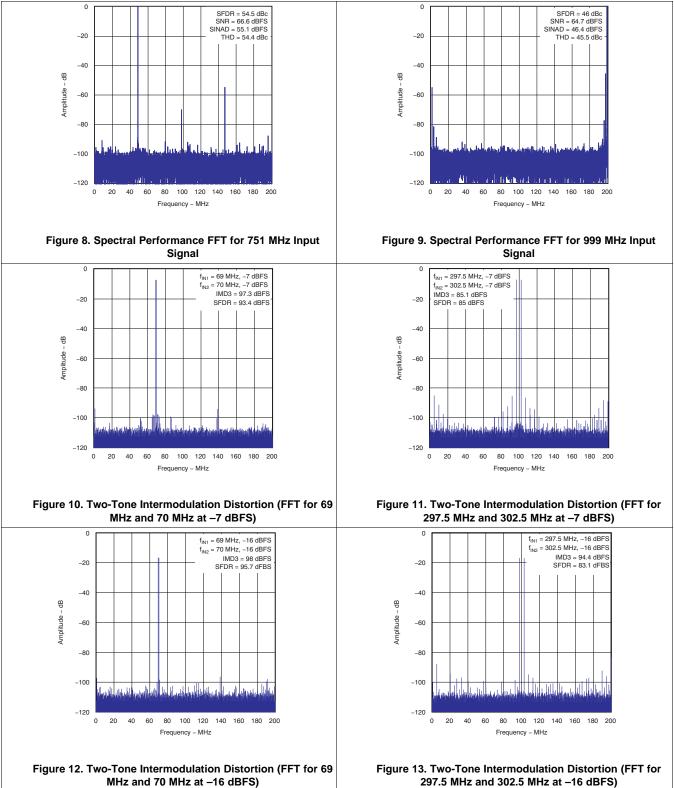
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6.7 Typical Characteristics



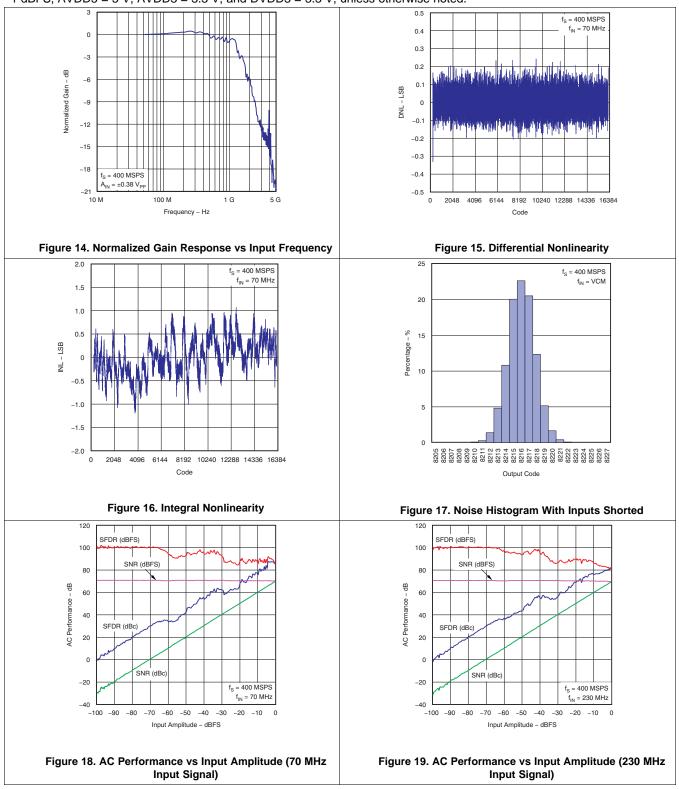


Typical Characteristics (continued)



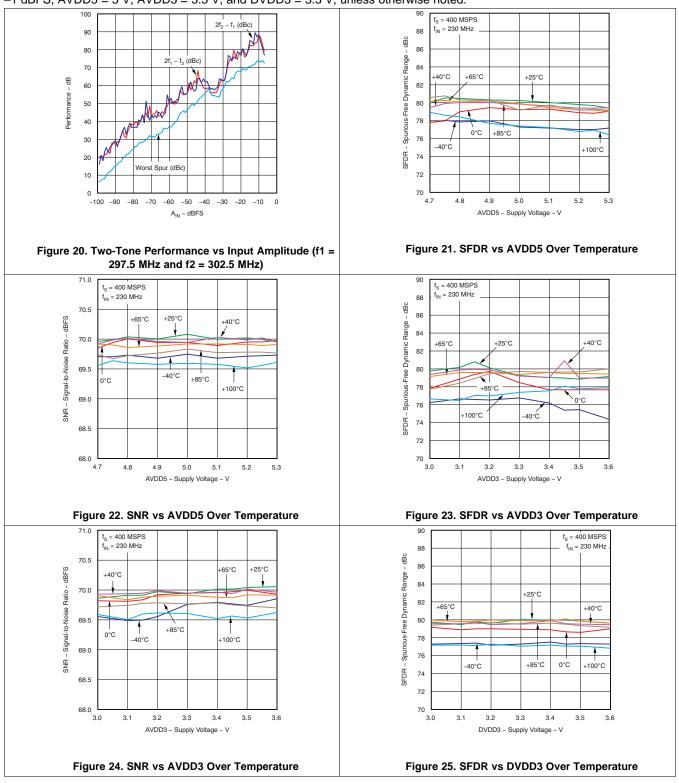


Typical Characteristics (continued)



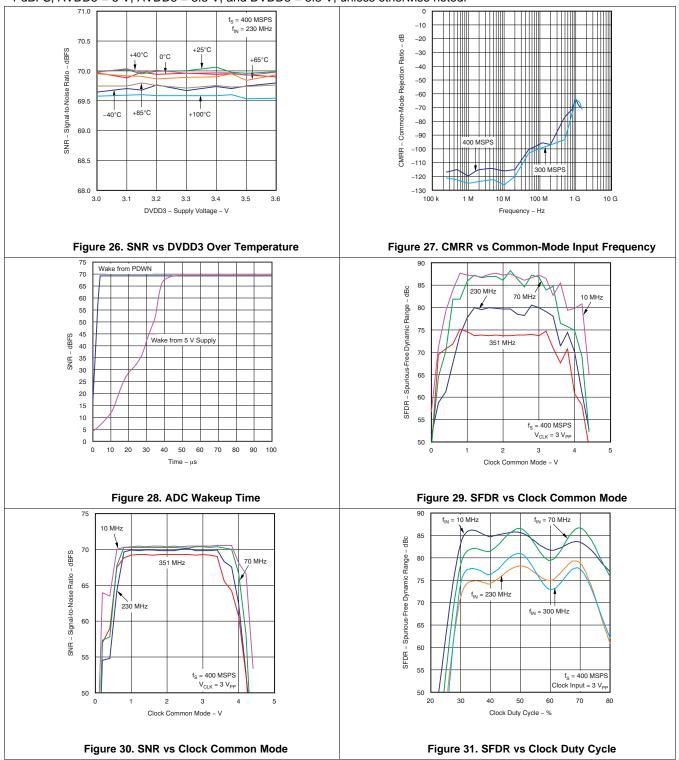


Typical Characteristics (continued)



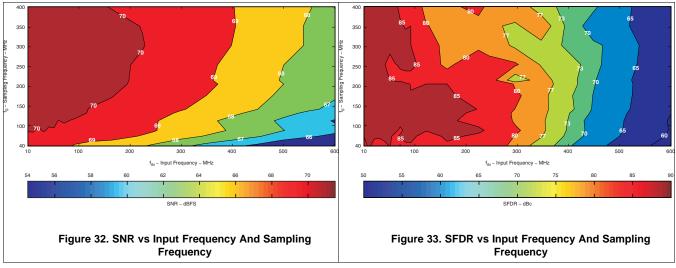


Typical Characteristics (continued)





Typical Characteristics (continued)



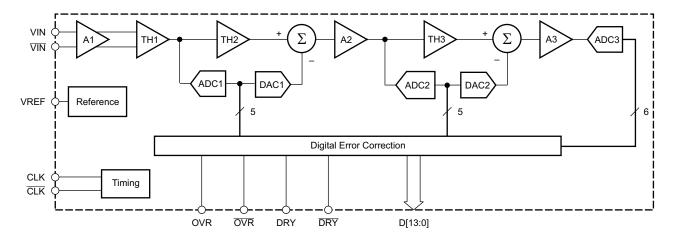


7 Detailed Description

7.1 Overview

The ADS5474 device is a 14-bit, 400-MSPS, monolithic pipeline ADC. The bipolar analog core operates from 5-V and 3.3-V supplies, while the output uses a 3.3-V supply to provide LVDS-compatible outputs. The conversion process is initiated by the rising edge of the external input clock. At that instant, the differential input signal is captured by the input track-and-hold (T&H), and the input sample is converted sequentially by a series of lower resolution stages, with the outputs combined in a digital correction logic block. Both the rising and the falling clock edges are used to propagate the sample through the pipeline every half clock cycle. This process results in a data latency of 3.5 clock cycles, after which the output data are available as a 14-bit parallel word, coded in offset binary format.

7.2 Functional Block Diagram



7.3 Feature Description

The analog input for the ADS5474 device consists of an analog pseudo-differential buffer followed by a bipolar transistor T&H. The analog buffer isolates the source driving the input of the ADC from any internal switching and presents a high impedance that is easy to drive at high input frequencies, compared to an ADC without a buffered input. The input common-mode is set internally through a 500- Ω resistor connected from 3.1 V to each of the inputs (common-mode is approximately 2.4 V on 12-bit and 13-bit members of this family). This configuration results in a differential input impedance of 1 k Ω .



Feature Description (continued)

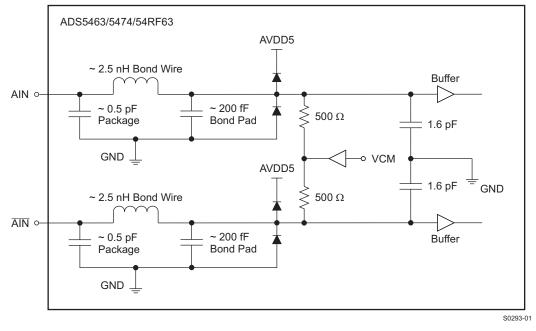


Figure 34. Analog Input Equivalent Circuit

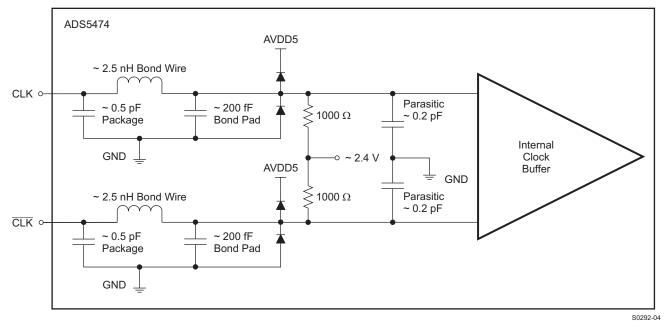
For a full-scale differential input, each of the differential lines of the input signal (pins 16 and 17) swings symmetrically between (3.1 V + 0.55 V) and (3.1 V – 0.55 V). This range means that each input has a maximum signal swing of 1.1 V_{PP} for a total differential input signal swing of 2.2 V_{PP}. Operation below 2.2 V_{PP} is allowable, with the characteristics of performance versus input amplitude demonstrated in Figure 18 and Figure 19. For instance, for performance at 1.1 V_{PP} rather than 2.2 V_{PP}, refer to the SNR and SFDR at –6 dBFS (0 dBFS = 2.2 V_{PP}). The maximum swing is determined by the internal reference voltage generator, eliminating the need for any external circuitry for this purpose.

7.3.1 Clock Inputs

The ADS5474 device clock input can be driven with either a differential clock signal or a single-ended clock input. The characterization of the ADS5474 device is typically performed with a $3-V_{PP}$ differential clock, but the ADC performs well with a differential clock amplitude down to approximately $0.5 V_{PP}$, as shown in Figure 37. The clock amplitude becomes more of a factor in performance as the analog input frequency increases. In low-input-frequency applications, where jitter may not be a big concern, the use of a single-ended clock could save cost and board space without much performance tradeoff. When clocked with this configuration, it is best to connect CLK to ground with a $0.01-\mu$ F capacitor, while CLK is ac-coupled with a $0.01-\mu$ F capacitor to the clock source, as shown in Figure 36.



Feature Description (continued)





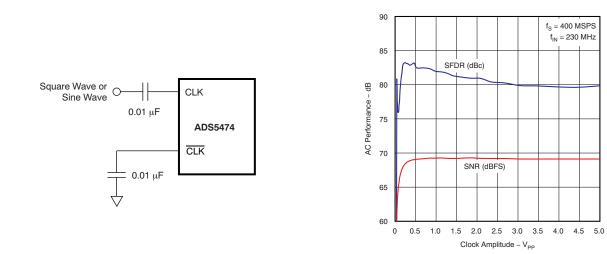




Figure 37. AC Performance vs Clock Level

7.3.2 Digital Outputs

The ADC provides 14 LVDS-compatible, offset binary data outputs (D13 to D0; D13 is the MSB and D0 is the LSB), a data-ready signal (DRY), and an over-range indicator (OVR). TI recommends using the DRY signal to capture the output data of the ADS5474 device. DRY is source-synchronous to the DATA/OVR outputs and operates at the same frequency, creating a half-rate DDR interface that updates data on both the rising and falling edges of DRY. It is recommended that the capacitive loading on the digital outputs be minimized. Higher capacitance shortens the data-valid timing window. The values given for timing (see Figure 1) were obtained with



Feature Description (continued)

a measured 10-pF parasitic board capacitance to ground on each LVDS line (or 5-pF differential parasitic capacitance). When setting the time relationship between DRY and DATA at the receiving device, it is generally recommended that setup time be maximized, but this partially depends on the setup and hold times of the device receiving the digital data (like an FPGA or Field Programmable Field Array). Since DRY and DATA are coincident, it will likely be necessary to delay either DRY or DATA such that setup time is maximized.

Referencing Figure 1, the polarity of DRY with respect to the sample N data output transition is undetermined because of the unknown startup logic level of the clock divider that generates the DRY signal (DRY is a frequency divide-by-two of CLK). Either the rising or the falling edge of DRY will be coincident with sample N and the polarity of DRY could invert when power is cycled off, on or when the power-down pin is cycled. Data capture from the transition and not the polarity of DRY is recommended, but not required. If the synchronization of multiple ADS5474 devices is required, it might be necessary to use a form of the CLKIN signal rather than DRY to capture the data.

The DRY frequency is identical on the ADS5474 and ADS5463 devices (where DRY equals $\frac{1}{2}$ the CLK frequency), but different on the pin-similar ADS5444 and ADS5440 devices (where DRY equals the CLK frequency). The LVDS outputs all require an external 100- Ω load between each output pair in order to meet the expected LVDS voltage levels. For long trace lengths, it may be necessary to place a 100- Ω load on each digital output as close to the ADS5474 device as possible and another 100- Ω differential load at the end of the LVDS transmission line to provide matched impedance and avoid signal reflections. The effective load in this case reduces the LVDS voltage levels by half.

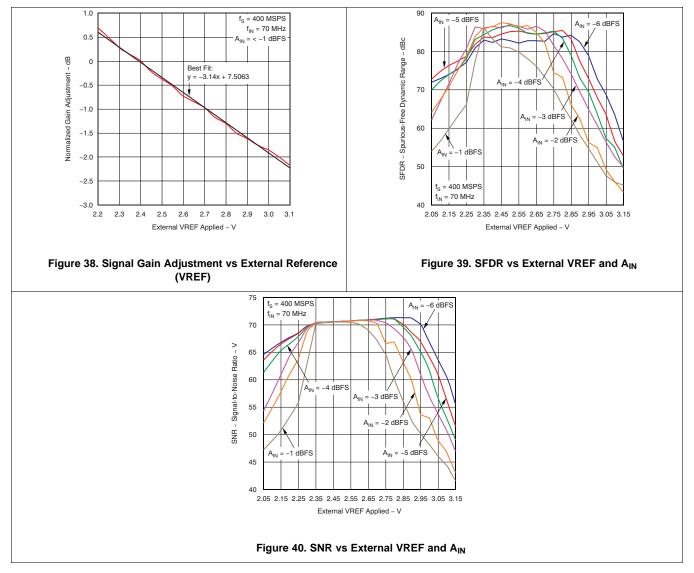
The OVR output equals a logic high when the 14-bit output word attempts to exceed either all 0s or all 1s. This flag is provided as an indicator that the analog input signal exceeded the full-scale input limit of approximately 2.2 V_{PP} (± gain error). The OVR indicator is provided for systems that use gain control to keep the analog input signal within acceptable limits.

7.4 Device Functional Modes

7.4.1 External Voltage Reference

For systems that require the analog signal gain to be adjusted or calibrated, this can be performed by using an external reference. The dependency on the signal amplitude to the value of the external reference voltage is characterized typically by Figure 38 (VREF = 2.4 V is normalized to 0 dB as this is the internal reference voltage). As can be seen in the linear fit, this equates to approximately –0.3 dB of signal adjustment per 100 mV of reference adjustment. The range of allowable variation depends on the analog input amplitude that is applied to the inputs and the desired spectral performance, as can be seen in the performance versus external reference graphs in Figure 39 and Figure 40. As the applied analog signal amplitude is reduced, more variation in the reference voltage is allowed in the positive direction (which equates to a reduction in signal amplitude), whereas an adjustment in reference voltage below the nominal 2.4 V (which equates to an increase in signal amplitude) is not recommended below approximately 2.35 V. The power consumption versus reference voltage and operating temperature should also be considered, especially at high ambient temperatures, because the lifetime of the device is affected by internal junction temperature (see Figure 48).

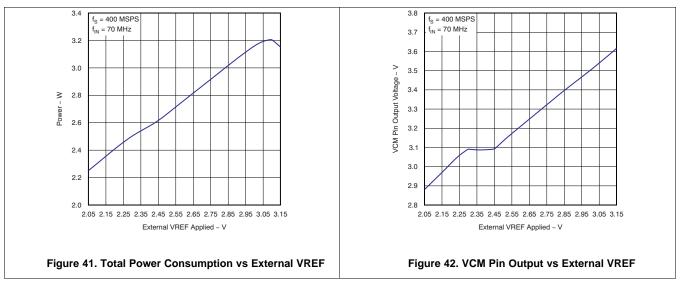
Device Functional Modes (continued)



For dc-coupled applications that use the VCM pin of the ADS5474 device as the common mode of the signal in the analog signal gain path prior to the ADC inputs, the information in Figure 42 is useful to consider versus the allowable common-mode range of the device that is receiving the VCM voltage, such as an operational amplifier. Because it is pin-compatible, it is important to note that the ADS5463 does not have a VCM pin and primarily uses the VREF pin to provide the common-mode voltage in dc-coupled applications. The ADS5463 (VCM = 2.4 V) and ADS5474 (VCM = 3.1 V) devices do not have the same common-mode voltage. To create a board layout that may accommodate both devices in dc-coupled applications, route VCM and VREF both to a common point that can be selected via a switch, jumper, or a $0-\Omega$ resistor.



Device Functional Modes (continued)



TEXAS INSTRUMENTS

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8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

In the design of any application involving a high-speed data converter, particular attention should be paid to the design of the analog input, the clocking solution, and careful layout of the clock and analog signals. The ADS5474 evaluation module (EVM) is one practical example of the design of the analog input circuit and clocking solution, as well as a practical example of good circuit board layout practices around the ADC.

8.2 Typical Applications

The analog inputs of the ADS5474 must be fully differential and biased to an appropriate common mode voltage, VCM. It is rare that the end equipment will have a signal that already meets the requisite amplitude and common mode and is fully differential. Therefore, there will be a signal conditioning circuit for the analog input. If the amplitude of the input circuit is such that no gain is needed to make full use of the full-scale range of the ADC, then a transformer coupled circuit as used on the EVM may be used with good results. The transformer coupling is inherently low-noise, and inherently AC-coupled so that the signal may be biased to VCM after the transformer coupling.

If signal gain is required, or the input bandwidth is to include the spectrum all the way down to DC such that AC coupling is not possible, then an amplifier-based signal conditioning circuit would be required. Figure 43 shows LMH3401 interfaced with ADS5474. LMH3401 is configured to have to Single-Ended input with a differential outputs follow by 1st Nyquist based low pass filter with 375-MHz bandwidth. Power supply recommendations for the amplifier are also shown in the figure below.

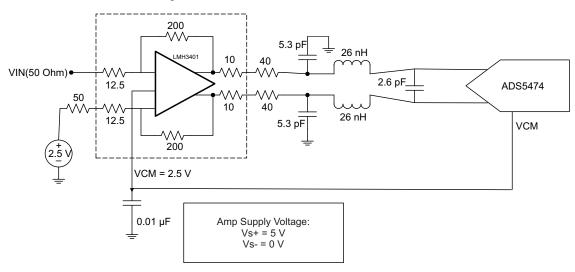


Figure 43. Application Diagram

Clocking a High Speed ADC such as the ADS5474 requires a fully differential clock signal from a clean, low-jitter clock source and driven by an appropriate clock buffer, often with LVPECL or LVDS signaling levels. The sample clock is internally biased to the desired level if the sample clock is AC coupled to the ADS5474. Figure 44 shows the typical AC coupling and termination circuit used for an AC coupled clock source.



Typical Applications (continued)

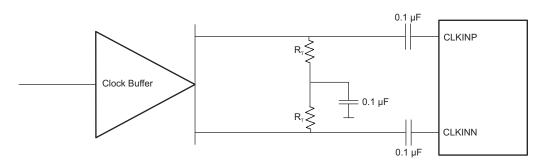


Figure 44. Recommended Differential Clock Driving Circuit

8.2.1 Design Requirements

The ADS5474 requires a fully differential analog input with a full-scale range not to exceed 2.2-V peak to peak differential, biased to a common mode voltage of 3.1 V. In addition the input circuit must provide proper transmission line termination (or proper load resistors in an amplifier-based solution) so the input of the impedance of the ADC analog inputs should be considered as well.

The ADS5474 is capable of a typical SNR of 70.1 dBFS for input frequencies of about 130 MHz, which is well under the Nyquist limit for this ADC operating at 400 Msps. The amplifier and clocking solution will have a direct impact on performance in terms of SNR, so the amplifier and clocking solution should be selected such that the SNR performance of at least 69 dBFS is preserved.

8.2.2 Detailed Design Procedure

The ADS5474 has a max sample rate of 404 MHz and an input bandwidth of approximately 1440 MHz, but an application involving the first Nyquist zone is being considered, therefore limit the frequency bandwidth here to be under 200 MHz.

8.2.2.1 Clocking Source for ADC5474

The signal to noise ratio of the ADC is limited by three different factors: the quantization noise, the thermal noise, and the total jitter of the sample clock. Quantization noise is driven by the resolution of the ADC, which is 14 bits for the ADS5474. Thermal noise is typically not noticeable in high speed pipelined converters such as the ADS5474, but may be estimated by looking at the signal to noise ratio of the ADC with very low input frequencies and using Equation 1 to solve for thermal noise. (For this estimation, we will look to the ADS5474 datasheet and take the specified SNR for the lowest frequency listed. The lowest input frequency listed for the ADS5474 is at 30 MHz, and the SNR at that frequency is 70.3 dB, so we will use 70.3 dB as our SNR limit due to thermal noise. This is just an approximation, and the lower the input frequency that has an SNR specification the better this approximation would be.) The thermal noise limits the SNR at low input frequencies while the clock jitter sets the SNR for higher input frequencies.

Quantization noise is also a limiting factor for SNR, as the theoretical maximum achievable SNR as a function of the number of bits of resolution is set by Equation 1.

$$SNR_{MAX} = 1.76 + (6.02 \times N)$$

where

• N = number of bits resolution

(1)

(3)

For a 14-bit ADC, the maximum $SNR = 1.76 + (6.02 \times 14) = 86.04 \text{ dB}$. This is the number that we shall enter into Equation 2 for guantization noise as we solve for total SNR for different amounts of clock jitter using Equation 2.

$$SNR_{ADC}[dBc] = -20 \times \log \sqrt{(10 - \frac{SNR_{Quantization_Noise}}{20})^2 + (10 - \frac{SNR_{ThermalNoise}}{20})^2 + (10 - \frac{SNR_{Jitter}}{20})^2}$$
(2)

The SNR limitation due to sample clock jitter can be calculated using Equation 3: $SNR_{Jitter}[dBc] = -20 \times \log(2p \times f_{IN} \times t_{Jitter})$

Typical Applications (continued)

The clock jitter in Equation 3 is the total amount of clock jitter, whether the jitter source is internal to the ADC itself or external due to the clocking source. The total clock jitter (t_{Jitter}) has two components - the internal aperture jitter (103 fs for ADS5474) which is set by the noise of the clock input buffer, and the external clock jitter from the clocking source and all associated buffering of the clock signal. Total clock jitter can be calculated from the aperture jitter and the external clock jitter as in Equation 4.

$$T_{Jitter} = \sqrt{\left(T_{Jitter, Ext.CLock _ Input}\right)^2 + \left(T_{Aperture _ ADC}\right)^2} \tag{4}$$

External clock jitter can be minimized by using high quality clock sources and jitter cleaners as well as bandpass filters at the clock input while a faster clock slew rate may at times also improve the ADC aperture jitter slightly.

The ADS5474 has an internal aperture jitter of 103 fs, which is largely fixed. The SNR depending on the amount of external jitter for different input frequencies is shown in Figure 45. Often the design requirements will list a target SNR for a system, and Equation 1 through Equation 3 are then used to calculate the external clock jitter needed from the clocking solution to meet the system objectives.

Figure 45 shows that with an external clock jitter of 100 fs rms, the expected SNR of the ADS5474 would be greater than 69 dBFS at an input tone of 200 MHz, which is the Nyquist limit. Having less external clock jitter such as 35 fs rms or even 50 fs rms would result in an SNR that would exceed our design target, but at possibly the expense of a more costly clocking solution. Having external clock jitter of 150 fs rms or more would fail to meet the design target.

8.2.2.2 Amplifier Selection

The amplifier and any input filtering will have its own SNR performance, and the SNR performance of the amplifier front end will combine with the SNR of the ADC itself to yield a system SNR that is less than that of the ADC itself. System SNR can be calculated from the SNR of the amplifier conditioning circuit and the overall ADC SNR as in Equation 5. In Equation 5, the SNR of the ADC would be the value derived from the datasheet specifications and the clocking derivation presented in the previous section.

$$SNR_{System} = -20 \times \log \sqrt{\left(10^{\frac{-SNR_{ADC}}{20}}\right)^2 + \left(10^{\frac{-SNR_{AMP+Filter}}{20}}\right)^2}$$
(5)

The signal-to-noise ratio (SNR) of the amplifier and filter can be calculated from the noise specifications in the datasheet for the amplifier, the amplitude of the signal, and the bandwidth of the filter. The noise from the amplifier is band-limited by the filter and the rolloff of the filter will depend on the order of the filter, therefore the user should replace the filter rolloff with an equivalent brick-wall filter bandwidth. For example, a first order filter may be approximated by a brick-wall filter with bandwidth of 1.57 times the bandwidth of the first order filter. We will assume a first order filter for this design. The amplifier and filter noise can be calculated using Equation 6:

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Typical Applications (continued)

$$SNR_{AMP+Filter} = 10 \times \log(\frac{V_o^2}{E_{FILTEROUT}^2}) = 20 \times \log(\frac{V_o}{E_{FILTEROUT}})$$

where

- $E_{FILTEROUT} = E_{NAMPOUT} \times \sqrt{ENB}$
- $E_{NAMPOUT}$ = the output noise density of the LMH3401 (3.4 nV / \sqrt{Hz})
- ENB = the brick-wall equivalent noise bandwidth of the filter
- VO = the amplifier output signal. (which will be full scale input of the ADC expressed in rms)

(6)

In Equation 6, the parameters of the equation can be seen to be in terms of signal amplitude in the numerator and amplifier noise in the denominator, or SNR. For the numerator, use the full scale voltage specification of the ADS5474, or 2.2 V peal to peak differential. Because Equation 6 requires the signal voltage to be in rms, convert 2.2 V p-p to 0.7766 V rms.

The noise specification for the LMH3401 is listed as 3.4 (nV/ \sqrt{Hz}), so we will use this value to integrate the noise component from DC out to the filter cutoff, using the equivalent brick wall filter of 200 MHz × 1.57, or 314 MHz. 3.4 (nV/ \sqrt{Hz}) × 314 MHz yields 60248 nV, or 60.25 μ V.

Using 0.7766 V rms for V_O and 60.25 μ V for E_{filterout}, the SNR of the amplifier and filter as given by Equation 6 is approximately 82.2 dB.

Taking the SNR of the ADC as 69.2 dB from Figure 45, and SNR of the amplifier and filter as 82.2 dB, Equation 5 predicts the system SNR to be 68.99 dB. In other words, the SNR of the ADC and the SNR of the front end combine as the square root of the sum of squares, and since the SNR of the amplifier front end is seen to be much greater than the SNR of the ADC in this example, the SNR of the ADC dominates Equation 5 and the system SNR is seen to be nearly the SNR of the ADC itself. We assumed our design requirement to be 69 dB, and after a clocking solution was chosen and an amplifier, filter solution was chosen we have a predicted SNR of 68.99 dB. If we deem 68.99 dB to not be close enough, or wish to have some margin in the design, then either improving the clock jitter from 100 fs to 50 fs, or replacing the first order filter with a second order filter would get the predicted system SNR above the 69-dB design requirement.

8.2.3 Application Curves

Figure 45 shows the SNR of the ADC as a function of clock jitter and input frequency for the ADS5474. This plot of curves take into account the aperture jitter of the ADC, the number of bits of resolution, and the thermal noise estimation so that the figure may be used to predict SNR for a given input frequency and external clock jitter. This figure then may be used to set the jitter requirement for the clocking solution for a given input bandwidth and given design goal for SNR.

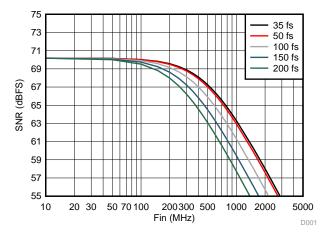


Figure 45. SNR vs Input Frequency and External Clock Jitter



9 Power Supply Recommendations

9.1 Power Supplies

The ADS5474 device uses three power supplies. For the analog portion of the design, a 5-V and 3.3-V supply (AVDD5 and AVDD3) are used, while the digital portion uses a 3.3-V supply (DVDD3). Using low-noise power supplies with adequate decoupling is recommended. Linear supplies are preferred to switched supplies, as switched supplies tend to generate more noise components that can be coupled to the ADS5474 device. However, the PSRR value and the plot shown in Figure 46 were obtained without bulk supply decoupling capacitors. When bulk (0.1- μ F) decoupling capacitors are used, the board-level PSRR is much higher than the stated value for the ADC. The user may be able to supply power to the device with a less-than-ideal supply and still achieve good performance. It is not possible to make a single recommendation for every type of supply and level of decoupling for all systems. If the noise characteristics of the available supplies are understood, a study of the PSRR data for the ADS5474 device may provide the user with enough information to select noisy supplies if the performance is still acceptable within the frequency range of interest. The power consumption of the ADS5474 device does not change substantially over clock rate or input frequency as a result of the architecture and process. The DVDD3 PSRR is superior to both the AVDD5 and AVDD3, and therefore was not graphed.

Because there are two diodes connected in reverse between AVDD3 and DVDD3 internally, a power-up sequence is recommended. When there is a delay in power up between these two supplies, the one that lags could have current sinking through an internal diode before it powers up. The sink current can be large or small depending on the impedance of the external supply and could damage the device or affect the supply source. The best power up sequence is one of the following options (regardless of when AVDD5 powers up):

1) Power up both AVDD3 and DVDD3 at the same time (best scenario), OR

2) Keep the voltage difference less than 0.8 V between AVDD3 and DVDD3 during the power up (0.8 V is not a hard specification - a smaller delta between supplies is safer).

If the above sequences are not practical then the sink current from the supply must be controlled or protection added externally. The max transient current (on the order of µsec) for DVDD3 or AVDD3 pin is 500 mA to avoid potential damage to the device or reduce its lifetime.

Values for analog and clock input given in the *Absolute Maximum Ratings* are valid when the supplies are on. When the power supplies are off and the clock or analog inputs are still alive, the input voltage and current must be limited to avoid device damage. If the ADC supplies are off, the max, min continuous DC voltage is ±0.95 V and max DC current is 20 mA for each input pin (clock or analog), relative to ground.

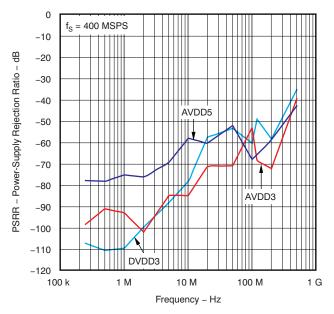


Figure 46. PSRR vs Supply Injected Frequency



10 Layout

10.1 Layout Guidelines

The evaluation board represents a good model of how to lay out the printed circuit board (PCB) to obtain the maximum performance from the ADS5474 device. Follow general design rules such as the use of multilayer boards, a single ground plane for ADC ground connections, and local decoupling ceramic chip capacitors. The analog input traces should be isolated from any external source of interference or noise, including the digital outputs as well as the clock traces. The clock signal traces should also be isolated from other signals, especially in applications such as high IF sampling where low jitter is required. Besides performance-oriented rules, care must be taken when considering the heat dissipation of the device. The thermal heatsink included on the bottom of the package should be soldered to the board as described in the *PowerPad Package* section. See the *ADS5474 EVM User Guide* (SLAU194) on the TI web site for the evaluation board schematic.

10.1.1 PowerPAD Package

The PowerPAD package is a thermally-enhanced, standard-size IC package designed to eliminate the use of bulky heatsinks and slugs traditionally used in thermal packages. This package can be easily mounted using standard PCB assembly techniques, and can be removed and replaced using standard repair procedures.

The PowerPAD package is designed so that the leadframe die pad (or thermal pad) is exposed on the bottom of the IC. This pad design provides an extremely low thermal resistance path between the die and the exterior of the package. The thermal pad on the bottom of the IC can then be soldered directly to the PCB, using the PCB as a heatsink.

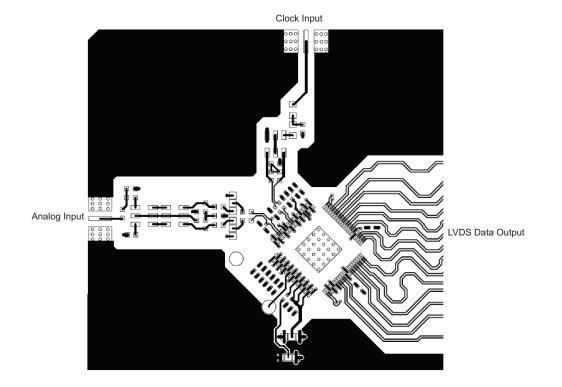
10.1.1.1 Assembly Process

- 1. Prepare the PCB top-side etch pattern including etch for the leads as well as the thermal pad as illustrated in the Mechanical Data section (at the end of this data sheet).
- 2. Place a 6 × 6 array of thermal vias in the thermal pad area. These holes should be 13 mils (0.013 in or 0.3302 mm) in diameter. The small size prevents wicking of the solder through the holes.
- 3. It is recommended to place a small number of 25-mil (0.025-in or 0.635-mm) diameter holes under the package, but outside the thermal pad area, to provide an additional heat path.
- 4. Connect all holes (both those inside and outside the thermal pad area) to an internal copper plane (such as a ground plane).
- 5. Do not use the typical web or spoke via-connection pattern when connecting the thermal vias to the ground plane. The spoke pattern increases the thermal resistance to the ground plane.
- 6. The top-side solder mask should leave exposed the terminals of the package and the thermal pad area.
- 7. Cover the entire bottom side of the PowerPAD vias to prevent solder wicking.
- 8. Apply solder paste to the exposed thermal pad area and all of the package terminals.

For more detailed information regarding the PowerPAD package and its thermal properties, see either the *PowerPAD Made Easy* application brief (SLMA004) or the *PowerPAD Thermally Enhanced Package* application report (SLMA002), both available for download at www.ti.com.



10.2 Layout Example



*Solid Black is top layer ground fill



10.3 Thermal Considerations

It is important for applications that anticipate running continuously for long periods of time near the maximumrated ambient temperature of 85°C to consider the data shown in Figure 48. Referring to the *Thermal Information* table, the worst-case operating condition with no airflow has a thermal rise of 23.7° C/W. At approximately 2.5 W of normal power dissipation, at a maximum ambient of 85°C with no airflow, the junction temperature of the ADS5474 device reaches approximately 85°C + (23.7°C/W × 2.5 W) = +144°C. Being even more conservative and accounting for the maximum possible power dissipation that is ensured (2.797 W), the junction temperature becomes nearly 150°C. As Figure 48 shows, this performance limits the expected lifetime of the ADS5474 device. Operation at 85°C continuously can require airflow or an additional heatsink in order to decrease the internal junction temperature and increase the expected lifetime (because of electromigration failures). An airflow of 250 LFM (linear feet per minute) reduces the thermal resistance to 16.4°C/W and, therefore, the maximum junction temperature to 131°C, assuming a worst-case of 2.797 W and 85°C ambient.

The ADS5474 device performance over temperature is quite good and can be seen starting in Figure 21. Though the typical plots show good performance at 100°C, the device is only rated from –40°C to 85°C. For continuous operation at temperatures near or above the maximum, the expected primary negative effect is a shorter device lifetime because of the electromigration failures at high junction temperatures. The maximum recommended continuous junction temperature is 150°C.



Thermal Considerations (continued)

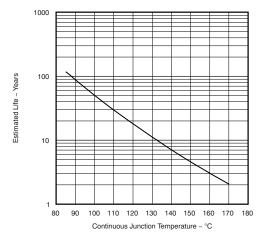


Figure 48. Operating Life Derating Chart, Electromigration Fail Mode



11 Device and Documentation Support

11.1 Device Support

11.1.1 Device Nomenclature

- Analog Bandwidth The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low-frequency value.
- Aperture Delay The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

Aperture Uncertainty (Jitter) The sample-to-sample variation in aperture delay.

- Clock Pulse Duration/Duty Cycle The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse duration) to the period of the clock signal, expressed as a percentage.
- **Differential Nonlinearity (DNL)** An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. DNL is the deviation of any single step from this ideal value, measured in units of LSB.
- **Common-Mode Rejection Ratio (CMRR)** CMRR measures the ability to reject signals that are presented to both analog inputs simultaneously. The injected common-mode frequency level is translated into dBFS, the spur in the output FFT is measured in dBFS, and the difference is the CMRR in dB.
- Effective Number of Bits (ENOB) ENOB is a measure in units of bits of converter performance as compared to the theoretical limit based on quantization noise:

$$ENOB = (SINAD - 1.76)/6.02$$

(7)

- **Gain Error** Gain error is the deviation of the ADC actual input full-scale range from its ideal value, given as a percentage of the ideal input full-scale range.
- Integral Nonlinearity (INL) INL is the deviation of the ADC transfer function from a best-fit line determined by a least-squares curve fit of that transfer function. The INL at each analog input value is the difference between the actual transfer function and this best-fit line, measured in units of LSB.
- Offset Error Offset error is the deviation of output code from mid-code when both inputs are tied to commonmode.
- **Power-Supply Rejection Ratio (PSRR)** PSRR is a measure of the ability to reject frequencies present on the power supply. The injected frequency level is translated into dBFS, the spur in the output FFT is measured in dBFS, and the difference is the PSRR in dB. The measurement calibrates out the benefit of the board supply decoupling capacitors.
- Signal-to-Noise Ratio (SNR) SNR is the ratio of the power of the fundamental (P_S) to the noise floor power (P_N), excluding the power at dc and in the first five harmonics. SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

$$SNR = 10\log_{10} \frac{P_S}{P_N}$$

(8)

Signal-to-Noise and Distortion (SINAD) SINAD is the ratio of the power of the fundamental (P_S) to the power of all the other spectral components including noise (P_N) and distortion (P_D), but excluding dc. SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

$$SINAD = 10\log_{10} \frac{P_S}{P_N + P_D}$$

(9)

Temperature Drift Temperature drift (with respect to gain error and offset error) specifies the change from the value at the nominal temperature to the value at T_{MIN} or T_{MAX} . It is computed as the maximum variation the parameters over the whole temperature range divided by $T_{MIN} - T_{MAX}$.

Total Harmonic Distortion (THD) THD is the ratio of the power of the fundamental (P_S) to the power of the first

Product Folder Links: ADS5474



Device Support (continued)

five harmonics (P_D).THD is typically given in units of dBc (dB to carrier).

$$THD = 10\log_{10} \frac{P_S}{P_D}$$

(10)

ADS5474

SLAS525D - JULY 2007 - REVISED DECEMBER 2017

Two-Tone Intermodulation Distortion (IMD3) IMD3 is the ratio of the power of the fundamental (at frequencies f_1 , f_2) to the power of the worst spectral component at either frequency $2f_1 - f_2$ or $2f_2 - f_1$). IMD3 is given in units of either dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

- Clocking High Speed Data Converters
- PowerPAD Thermally Enhanced Package
- PowerPAD Made Easy
- ADS5474 EVM User Guide
- ADS5463 12-bit, 500 MSPS Analog-to-Digital Converter with Buffered Input
- ADS5440 13-Bit 210 MSPS Analog-to-Digital Converter
- ADS5444 13-Bit 250 MSPS Analog-to-Digital Converter
- LMK04808 IBIS Model
- LMH3401 7-GHz, Ultra-Wideband, Fixed-Gain, Fully-Differential Amplifier

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E[™] Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.5 Trademarks

PowerPAD, E2E are trademarks of Texas Instruments. All other trademarks are the property of their respective owners.

11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



11.7 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS5474IPFP	ACTIVE	HTQFP	PFP	80	96	RoHS & Green	NIPDAU	Level-4-260C-72 HR	-40 to 85	ADS5474I	Samples
ADS5474IPFPR	ACTIVE	HTQFP	PFP	80	1000	RoHS & Green	NIPDAU	Level-4-260C-72 HR	-40 to 85	ADS5474I	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF ADS5474 :

• Space : ADS5474-SP

NOTE: Qualified Version Definitions:

• Space - Radiation tolerant, ceramic packaging and qualified for use in Space-based application

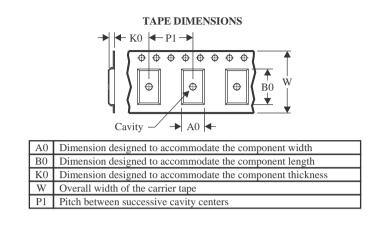


Texas

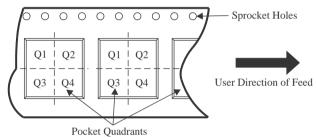
STRUMENTS

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS5474IPFPR	HTQFP	PFP	80	1000	330.0	24.4	15.0	15.0	1.5	20.0	24.0	Q2



PACKAGE MATERIALS INFORMATION

5-Oct-2022



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS5474IPFPR	HTQFP	PFP	80	1000	350.0	350.0	43.0

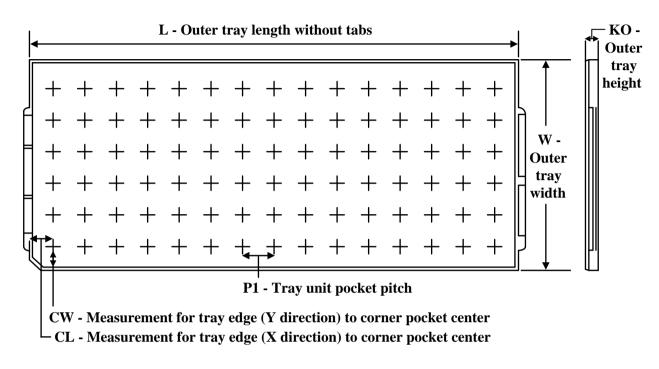
Texas Instruments

www.ti.com

TRAY



5-Oct-2022



Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	K0 (µm)	P1 (mm)	CL (mm)	CW (mm)
ADS5474IPFP	PFP	HTQFP	80	96	6 x 16	150	315	135.9	7620	18.7	17.25	18.3

PFP (S-PQFP-G80)

PowerPAD™ PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com http://www.ti.com.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

F. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.



THERMAL PAD MECHANICAL DATA

PFP (S-PQFP-G80)

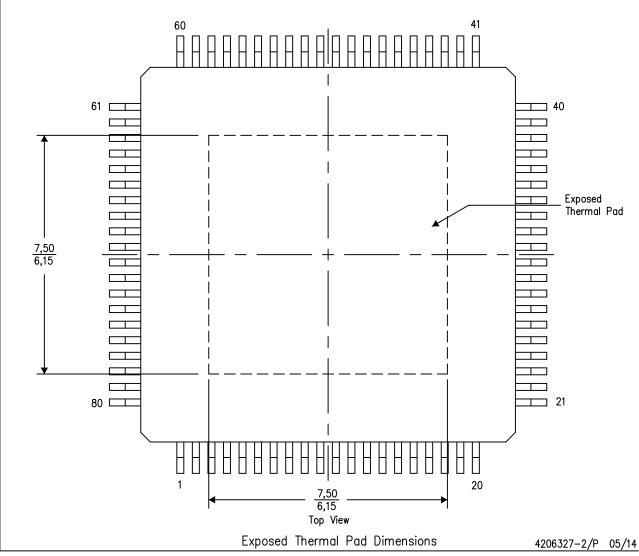
PowerPAD[™] PLASTIC QUAD FLATPACK

THERMAL INFORMATION

This PowerPAD[™] package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

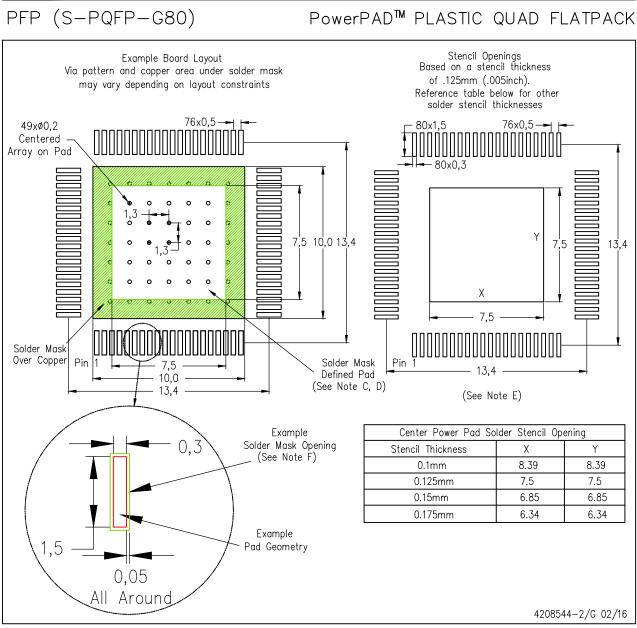
The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: A. All linear dimensions are in millimeters

PowerPAD is a trademark of Texas Instruments





NOTES:

Α.

PowerPAD is a trademark of Texas Instruments.

All linear dimensions are in millimeters. Β. This drawing is subject to change without notice.

- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations. F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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