FEATuiRES
(Unless Otherwise Noted, Typical Values at $V_S = 2.7V$)

- Renewable Energy Grade
- Ensured 2.7V and 5V Specifications
- Maximum $V_{OS}$ 850μV (Limit)
- Voltage noise
  - $f = 100$ Hz 12.5nV/√Hz
  - $f = 10$ kHz 7.5nV/√Hz
- Rail-to-Rail Output Swing
  - $R_L = 600Ω$ 100mV From Rail
  - $R_L = 2kΩ$ 50mV From Rail
- Open Loop Gain With $R_L = 2kΩ$ 100dB
- $V_{CM}$ 0 to $V^+ - 0.9V$
- Supply Current 550μA
- Gain Bandwidth Product 3.5MHz
- Temperature Range −40°C to 125°C

APPLICATIONS

- Transducer Amplifier
- Instrumentation Amplifier
- Precision Current Sensing
- Data Acquisition Systems
- Active Filters and Buffers
- Sample and Hold
- Portable/battery Powered Electronics
- Automotive

DESCRIPTION

The SM73308 is a single low noise precision operational amplifier intended for use in a wide range of applications. Other important characteristics include: an extended operating temperature range of −40°C to 125°C, the tiny SC70-5 package, and low input bias current.

The extended temperature range of −40°C to 125°C allows the SM73308 to accommodate a broad range of applications. The SM73308 expands TI’s Silicon Dust™ amplifier portfolio offering enhancements in size, speed, and power savings. The SM73308 is ensured to operate over the voltage range of 2.7V to 5.0V and has rail-to-rail output.

The SM73308 is designed for precision, low noise, low voltage, and miniature systems. This amplifier provides rail-to-rail output swing into heavy loads. The maximum input offset is 850 μV at room temperature and the input common mode voltage range includes ground.

The SM73308 is offered in the tiny SC70-5 package.
Instrumentation Amplifier

\[ V_O = -K \left(2a + 1\right) \left(V_1 - V_2\right) \]  

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

**Absolute Maximum Ratings**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>ESD Tolerance</td>
<td>± Supply Voltage</td>
</tr>
<tr>
<td>Machine Model</td>
<td>200V</td>
</tr>
<tr>
<td>Human Body Model</td>
<td>2000V</td>
</tr>
<tr>
<td>Differential Input Voltage</td>
<td>((V^+)) + 0.3V, ((V^-)) – 0.3V</td>
</tr>
<tr>
<td>Voltage at Input Pins</td>
<td>±10 mA</td>
</tr>
<tr>
<td>Current at Input Pins</td>
<td>5.75V</td>
</tr>
<tr>
<td>Supply Voltage ((V^+)–(V^-))</td>
<td>See (4)</td>
</tr>
<tr>
<td>Output Short Circuit to (V^+)</td>
<td>See (5)</td>
</tr>
<tr>
<td>Output Short Circuit to (V^-)</td>
<td></td>
</tr>
<tr>
<td>Mounting Temperature</td>
<td>Infrared or Convection (20 sec)</td>
</tr>
<tr>
<td></td>
<td>Wave Soldering Lead Temp (10 sec)</td>
</tr>
<tr>
<td>Storage Temperature Range</td>
<td>-65°C to 150°C</td>
</tr>
<tr>
<td>Junction Temperature</td>
<td>150°C</td>
</tr>
</tbody>
</table>

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.

(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

(3) Human Body Model is 1.5 kΩ in series with 100 pF, Machine Model is 0Ω in series with 20 pF.

(4) Shorting output to \(V^+\) will adversely affect reliability.

(5) Shorting output to \(V^-\) will adversely affect reliability.

(6) The maximum power dissipation is a function of \(T_{J(MAX)}\) · \(\theta_{JA}\), and \(T_A\). The maximum allowable power dissipation at any ambient temperature is \(P_D = (T_{J(MAX)} - T_A) / \theta_{JA}\). All numbers apply for packages soldered directly into a PC board.

**Operating Ratings**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage</td>
<td>2.7V to 5.5V</td>
</tr>
<tr>
<td>Temperature Range</td>
<td>-40°C to 125°C</td>
</tr>
<tr>
<td>Thermal Resistance</td>
<td>440 °C/W</td>
</tr>
</tbody>
</table>

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
### 2.7V DC Electrical Characteristics

Unless otherwise specified, all limits are ensured for $T_A = 25°C$, $V^+ = 2.7V$, $V^- = 0V$, $V_{CM} = V^+/2$, $V_O = V^-/2$ and $R_L > 1\text{M}\Omega$. **Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Min(2)</th>
<th>Typ(3)</th>
<th>Max(2)</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{OS}$</td>
<td>Input Offset Voltage</td>
<td></td>
<td>0.3</td>
<td>0.85</td>
<td>1.0</td>
<td>mV</td>
</tr>
<tr>
<td>$TCV_{OS}$</td>
<td>Input Offset Voltage Average Drift</td>
<td>$V_{CM} = 1V$</td>
<td>-0.45</td>
<td></td>
<td></td>
<td>$\mu V/^\circ C$</td>
</tr>
<tr>
<td>$I_B$</td>
<td>Input Bias Current(4)</td>
<td>$V_{CM} = 1V$</td>
<td>-0.1</td>
<td>100</td>
<td>250</td>
<td>pA</td>
</tr>
<tr>
<td>$I_{OS}$</td>
<td>Input Offset Current(4)</td>
<td></td>
<td>0.004</td>
<td>100</td>
<td></td>
<td>pA</td>
</tr>
<tr>
<td>$I_S$</td>
<td>Supply Current</td>
<td></td>
<td>550</td>
<td>900</td>
<td>910</td>
<td>$\mu A$</td>
</tr>
<tr>
<td>CMRR</td>
<td>Common Mode Rejection Ratio</td>
<td>$0.5 \leq V_{CM} \leq 1.2V$</td>
<td>74</td>
<td>72</td>
<td>80</td>
<td>dB</td>
</tr>
<tr>
<td>PSSR</td>
<td>Power Supply Rejection Ratio</td>
<td>$2.7V \leq V^+ \leq 5V$</td>
<td>82</td>
<td>76</td>
<td>90</td>
<td>dB</td>
</tr>
<tr>
<td>$V_{CM}$</td>
<td>Input Common-Mode Voltage Range</td>
<td>For CMRR $\geq 50\text{dB}$</td>
<td>0</td>
<td></td>
<td>1.8</td>
<td>V</td>
</tr>
<tr>
<td>$A_V$</td>
<td>Large Signal Voltage Gain(5)</td>
<td>$R_L = 600\Omega$ to $1.35V$, $V_O = 0.2V$ to $2.5V$</td>
<td>92</td>
<td>80</td>
<td>100</td>
<td>dB</td>
</tr>
<tr>
<td>$R_L = 2k\Omega$ to $1.35V$, $V_O = 0.2V$ to $2.5V$</td>
<td>98</td>
<td>86</td>
<td>100</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_O$</td>
<td>Output Swing</td>
<td>$R_L = 600\Omega$ to $1.35V$, $V_{IN} = 100mV$</td>
<td>0.11</td>
<td>0.084 to 2.59</td>
<td>2.62</td>
<td>V</td>
</tr>
<tr>
<td>$R_L = 2k\Omega$ to $1.35V$, $V_{IN} = 100mV$</td>
<td>0.05</td>
<td>0.026 to 2.68</td>
<td>2.64</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_O$</td>
<td>Output Short Circuit Current</td>
<td>Sourcing, $V_O = 0V$, $V_{IN} = 100mV$</td>
<td>18</td>
<td>11</td>
<td>24</td>
<td>mA</td>
</tr>
<tr>
<td>Sinking, $V_O = 2.7V$, $V_{IN} = -100mV$</td>
<td>18</td>
<td>11</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1. Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$.
2. All limits are ensured by testing or statistical analysis.
3. Typical values represent the most likely parametric norm.
4. Limits ensured by design.
5. $R_L$ is connected to mid-supply. The output voltage is set at 200mV from the rails. $V_O = GND + 0.2V$ and $V_O = V^- - 0.2V$.

### 2.7V AC Electrical Characteristics

Unless otherwise specified, all limits are ensured for $T_A = 25°C$, $V^+ = 5.0V$, $V^- = 0V$, $V_{CM} = V^+/2$, $V_O = V^-/2$ and $R_L > 1\text{M}\Omega$. **Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Min(2)</th>
<th>Typ(3)</th>
<th>Max(2)</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR</td>
<td>Slew Rate(4)</td>
<td>$A_V = +1$, $R_L = 10 \text{k}\Omega$</td>
<td>1.4</td>
<td></td>
<td></td>
<td>$V/\mu s$</td>
</tr>
<tr>
<td>GBW</td>
<td>Gain-Bandwidth Product</td>
<td></td>
<td>3.5</td>
<td></td>
<td></td>
<td>$\text{MHz}$</td>
</tr>
<tr>
<td>$\Phi_m$</td>
<td>Phase Margin</td>
<td></td>
<td>79</td>
<td></td>
<td></td>
<td>Deg</td>
</tr>
<tr>
<td>$G_m$</td>
<td>Gain Margin</td>
<td></td>
<td>-15</td>
<td></td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td>$e_n$</td>
<td>Input-Refereed Voltage Noise (Flatband)</td>
<td>$f = 10\text{kHz}$</td>
<td>7.5</td>
<td></td>
<td></td>
<td>$nV/\sqrt{Hz}$</td>
</tr>
<tr>
<td>$e_{in}$</td>
<td>Input-Refereed Voltage Noise (i/f)</td>
<td>$f = 100\text{Hz}$</td>
<td>12.5</td>
<td></td>
<td></td>
<td>$nV/\sqrt{Hz}$</td>
</tr>
<tr>
<td>$I_n$</td>
<td>Input-Refereed Current Noise</td>
<td>$f = 1\text{kHz}$</td>
<td>0.001</td>
<td></td>
<td></td>
<td>$pA/\sqrt{Hz}$</td>
</tr>
<tr>
<td>THD</td>
<td>Total Harmonic Distortion</td>
<td>$f = 1\text{kHz}$, $A_V = +1$, $R_L = 600\Omega$, $V_{IN} = 1V_{PP}$</td>
<td></td>
<td>0.007</td>
<td></td>
<td>%</td>
</tr>
</tbody>
</table>

1. Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$.
2. All limits are ensured by testing or statistical analysis.
3. Typical values represent the most likely parametric norm.
4. The number specified is the slower of positive and negative slew rates.
5.0V DC Electrical Characteristics (1)

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ C$, $V^+ = 5.0V$, $V^- = 0V$, $V_{CM} = V^+/2$, $V_O = V^-/2$ and $R_L > 1\, \Omega$.

**Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Min(2)</th>
<th>Typ(3)</th>
<th>Max(2)</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{OS}$</td>
<td>Input Offset Voltage</td>
<td></td>
<td>0.25</td>
<td>0.85</td>
<td>1.0</td>
<td>mV</td>
</tr>
<tr>
<td>TCV$_{OS}$</td>
<td>Input Offset Voltage Average Drift</td>
<td>$V_{CM} = 1$V</td>
<td>-0.35</td>
<td></td>
<td></td>
<td>µV/°C</td>
</tr>
<tr>
<td>$I_B$</td>
<td>Input Bias Current(4)</td>
<td>$V_{CM} = 1V$</td>
<td>-0.23</td>
<td>100</td>
<td>250</td>
<td>pA</td>
</tr>
<tr>
<td>$I_{OS}$</td>
<td>Input Offset Current(4)</td>
<td></td>
<td>0.017</td>
<td>100</td>
<td></td>
<td>pA</td>
</tr>
<tr>
<td>$I_S$</td>
<td>Supply Current</td>
<td></td>
<td>600</td>
<td>950</td>
<td>960</td>
<td>µA</td>
</tr>
<tr>
<td>CMRR</td>
<td>Common Mode Rejection Ratio</td>
<td>$0.5 \leq V_{CM} \leq 3.5V$</td>
<td>80</td>
<td>79</td>
<td>90</td>
<td>dB</td>
</tr>
<tr>
<td>PSRR</td>
<td>Power Supply Rejection Ratio</td>
<td>$2.7V \leq V^+ \leq 5V$</td>
<td>82</td>
<td>76</td>
<td>90</td>
<td>dB</td>
</tr>
<tr>
<td>$V_{CM}$</td>
<td>Input Common-Mode Voltage Range</td>
<td>For CMRR &gt; 50dB</td>
<td>0</td>
<td></td>
<td>4.1</td>
<td>V</td>
</tr>
<tr>
<td>$A_V$</td>
<td>Large Signal Voltage Gain(5)</td>
<td>$R_L = 600\Omega$ to 2.5V, $V_O = 0.2V$ to 4.8V</td>
<td>92</td>
<td>89</td>
<td>100</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$R_L = 2k\Omega$ to 2.5V, $V_O = 0.2V$ to 4.8V</td>
<td>98</td>
<td>95</td>
<td>100</td>
<td>dB</td>
</tr>
<tr>
<td>$V_O$</td>
<td>Output Swing</td>
<td>$R_L = 600\Omega$ to 2.5V, $V_{IN} = \pm 100$mV</td>
<td>0.15</td>
<td>0.112 to 4.9</td>
<td>4.85</td>
<td>4.77</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$R_L = 2k\Omega$ to 2.5V, $V_{IN} = \pm 100$mV</td>
<td>0.06</td>
<td>0.035 to 4.97</td>
<td>4.94</td>
<td>4.93</td>
</tr>
<tr>
<td>$I_O$</td>
<td>Output Short Circuit Current(4)(6)</td>
<td>Sourcing, $V_O = 0$V</td>
<td>35</td>
<td>35</td>
<td>75</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Sinking, $V_O = 2.7$V</td>
<td>35</td>
<td>35</td>
<td>66</td>
<td>mA</td>
</tr>
</tbody>
</table>

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$.

(2) All limits are ensured by testing or statistical analysis.

(3) Typical values represent the most likely parametric norm.

(4) Limits ensured by design.

(5) $R_L$ is connected to mid-supply. The output voltage is set at 200mV from the rails. $V_O = GND + 0.2V$ and $V_O = V^- - 0.2V$

(6) Continuous operation of the device with an output short circuit current larger than 35mA may cause permanent damage to the device.

5.0V AC Electrical Characteristics (1)

Unless otherwise specified, all limits are ensured for $T_A = 25^\circ C$, $V^+ = 5.0V$, $V^- = 0V$, $V_{CM} = V^+/2$, $V_O = V^-/2$ and $R_L > 1\, \Omega$.

**Boldface** limits apply at the temperature extremes.

<table>
<thead>
<tr>
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<th>Max(2)</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>SR</td>
<td>Slew Rate(4)</td>
<td>$A_V = +1, R_L = 10, \Omega$</td>
<td>1.4</td>
<td></td>
<td></td>
<td>V/µs</td>
</tr>
<tr>
<td>GBW</td>
<td>Gain-Bandwidth Product</td>
<td></td>
<td>3.5</td>
<td></td>
<td></td>
<td>MHz</td>
</tr>
<tr>
<td>$\Phi_m$</td>
<td>Phase Margin</td>
<td></td>
<td>79</td>
<td></td>
<td></td>
<td>Deg</td>
</tr>
<tr>
<td>$G_m$</td>
<td>Gain Margin</td>
<td></td>
<td>-15</td>
<td></td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td>$e_n$</td>
<td>Input-Reflected Voltage Noise (Flatband)</td>
<td>$f = 10kHz$</td>
<td>6.5</td>
<td></td>
<td></td>
<td>nV/√Hz</td>
</tr>
<tr>
<td>$e_{in}$</td>
<td>Input-Reflected Voltage Noise (l/f)</td>
<td>$f = 100Hz$</td>
<td>12</td>
<td></td>
<td></td>
<td>nV/√Hz</td>
</tr>
<tr>
<td>$I_n$</td>
<td>Input-Reflected Current Noise</td>
<td>$f = 1kHz$</td>
<td>0.001</td>
<td></td>
<td></td>
<td>pA/√Hz</td>
</tr>
<tr>
<td>THD</td>
<td>Total Harmonic Distortion</td>
<td>$f = 1kHz$, $A_V = +1$ $R_L = 600\Omega$, $V_{IN} = 1P$</td>
<td>0.007</td>
<td></td>
<td></td>
<td>%</td>
</tr>
</tbody>
</table>

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$.

(2) All limits are ensured by testing or statistical analysis.

(3) Typical values represent the most likely parametric norm.

(4) The number specified is the slower of positive and negative slew rates.
Typical Performance Characteristics

**Figure 2.**

V<sub>OS</sub> vs. V<sub>CM</sub> Over Temperature

**Figure 3.**

V<sub>OS</sub> vs. V<sub>CM</sub> Over Temperature

**Figure 4.**

Output Swing vs. V<sub>S</sub>

**Figure 5.**

Output Swing vs. V<sub>S</sub>

**Figure 6.**

Output Swing vs. V<sub>S</sub>

**Figure 7.**

I<sub>S</sub> vs. V<sub>S</sub> Over Temperature
Typical Performance Characteristics (continued)

\[ V_{IN} \text{ vs. } V_{OUT} \]

![Graph showing \( V_{IN} \text{ vs. } V_{OUT} \) for different temperature conditions.]

\[ V_{S} = 2.7V, \ TA = 25°C \]

\[ R_{L} = 2kΩ, \ R_{L} = 600Ω \]

\( V_{S} = ±2.5V, \ TA = 25°C \)

\( R_{L} = 2kΩ, \ R_{L} = 600Ω \)

Figure 8.

Sourcing Current \( V_{S} \text{ vs. } V_{OUT}^{(1)} \)

![Graph showing sourcing current vs. output voltage for different temperatures.]

\( V_{S} = 2.7V \)

\( 25°C, 85°C, 125°C, -40°C \)

\( V_{S} = 5V \)

Figure 9.

Sinking Current \( V_{S} \text{ vs. } V_{OUT}^{(1)} \)

![Graph showing sinking current vs. output voltage for different temperatures.]

\( V_{S} = 2.7V \)

\( -40°C, 25°C, 85°C, 125°C \)

\( V_{S} = 5V \)

Figure 10.

Sinking Current \( V_{S} \text{ vs. } V_{OUT}^{(1)} \)

![Graph showing sinking current vs. output voltage for different temperatures.]

\( V_{S} = 2.7V \)

\( -40°C, 25°C, 85°C, 125°C \)

\( V_{S} = 5V \)

Figure 11.

(1) Continuous operation of the device with an output short circuit current larger than 35mA may cause permanent damage to the device.

(1) Continuous operation of the device with an output short circuit current larger than 35mA may cause permanent damage to the device.

Product Folder Links: SM73308
Typical Performance Characteristics (continued)

Input Voltage Noise vs. Frequency

Figure 14.

Input Bias Current Over Temperature

Figure 15.

Input Bias Current Over Temperature

Figure 16.

Input Bias Current Over Temperature

Figure 17.

THD+N vs. Frequency

Figure 18.

THD+N vs. VOUT

Figure 19.
Typical Performance Characteristics (continued)

Slew Rate vs. Supply Voltage

Open Loop Frequency Response Over Temperature

Open Loop Frequency Response

Open Loop Gain & Phase with Cap. Loading

Figure 20.

Figure 21.

Figure 22.

Figure 23.

Figure 24.

Figure 25.
Typical Performance Characteristics (continued)

Non-Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = -40^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 26.

Non-Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = -40^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 27.

Non-Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 25^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 28.

Non-Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 25^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 29.

Non-Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 125^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 30.

Non-Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 125^\circ C \]
\[ R_L = 2k\Omega \]

TIME (10 \mu s/div)

Figure 31.
Typical Performance Characteristics (continued)

Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = -40^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 32.

Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = -40^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 33.

Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 25^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 34.

Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 25^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 35.

Inverting Small Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 125^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 36.

Inverting Large Signal Pulse Response

\[ V_S = \pm 2.5V \]
\[ T_A = 125^\circ C \]
\[ R_L = 2k\Omega \]

Time (10 \( \mu \)s/div)

Figure 37.
Typical Performance Characteristics (continued)

Stability vs. $V_{CM}$

Figure 38.

PSRR vs. Frequency

Figure 40.

CMRR vs. Frequency

Figure 41.
SM73308

The SM73308 is a precision amplifier with very low noise and ultra low offset voltage. SM73308's extended temperature range of −40 °C to 125 °C enables the user to design a variety of applications including automotive.

The SM73308 has a maximum offset voltage of 1mV over the extended temperature range. This makes the SM73308 ideal for applications where precision is important.

INSTRUMENTATION AMPLIFIER

Measurement of very small signals with an amplifier requires close attention to the input impedance of the amplifier, gain of the overall signal on the inputs, and the gain on each input since we are only interested in the difference of the two inputs and the common signal is considered noise. A classic solution is an instrumentation amplifier. Instrumentation amplifiers have a finite, accurate, and stable gain. Also they have extremely high input impedances and very low output impedances. Finally they have an extremely high CMRR so that the amplifier can only respond to the differential signal. A typical instrumentation amplifier is shown in Figure 42.

![Figure 42. Instrumentation Amplifier](image)

There are two stages in this amplifier. The last stage, output stage, is a differential amplifier. In an ideal case the two amplifiers of the first stage, input stage, would be set up as buffers to isolate the inputs. However they cannot be connected as followers because of real amplifier's mismatch. That is why there is a balancing resistor between the two. The product of the two stages of gain will give the gain of the instrumentation amplifier. Ideally, the CMRR should be infinite. However the output stage has a small non-zero common mode gain which results from resistor mismatch.

In the input stage of the circuit, current is the same across all resistors. This is due to the high input impedance and low input bias current of the SM73308. With the node equations we have:

\[ R_1 = R_{11} \]  

\[ V_{O1} - V_{O2} = (2R_1 + R_{11})I_{R_{11}} \]

\[ = (2a + 1)R_{11} \]

\[ = (2a + 1)V_{R_{11}} \]

However:

\[ V_{R_{11}} = V_1 - V_2 \]

So we have:

\[ \text{GIVEN: } I_{R_1} = I_{R_{11}} \]  

\[ \text{By Ohm's Law: } \]

\[ V_{O1} - V_{O2} = (2R_1 + R_{11})I_{R_{11}} \]

\[ = (2a + 1)R_{11} \]

\[ = (2a + 1)V_{R_{11}} \]  

\[ \text{However: } \]

\[ V_{R_{11}} = V_1 - V_2 \]  

\[ \text{So we have: } \]
Now looking at the output of the instrumentation amplifier:

\[
V_O = \frac{KR_2}{R_2} (V_{O2} - V_{O1})
\]

\[
= -K (V_{O1} - V_{O2})
\]

Substituting from Equation 5:

\[
V_O = -K (2a + 1) (V_1 - V_2)
\]

This shows the gain of the instrumentation amplifier to be:

\[
-K(2a+1)
\]

Typical values for this circuit can be obtained by setting: \(a = 12\) and \(K = 4\). This results in an overall gain of \(-100\).

Figure 43 shows typical CMRR characteristics of this Instrumentation amplifier over frequency. Three SM73308 amplifiers are used along with 1% resistors to minimize resistor mismatch. Resistors used to build the circuit are: \(R_1 = 21.6k\Omega\), \(R_{11} = 1.8k\Omega\), \(R_2 = 2.5k\Omega\) with \(K = 40\) and \(a = 12\). This results in an overall gain of \(-1000\), \(-K(2a+1) = -1000\).

Figure 43. CMRR vs. Frequency

ACTIVE FILTER

Active filters are circuits with amplifiers, resistors, and capacitors. The use of amplifiers instead of inductors, which are used in passive filters, enhances the circuit performance while reducing the size and complexity of the filter.

The simplest active filters are designed using an inverting op amp configuration where at least one reactive element has been added to the configuration. This means that the op amp will provide "frequency-dependent" amplification, since reactive elements are frequency dependent devices.

LOW PASS FILTER

The following shows a very simple low pass filter.
The transfer function can be expressed as follows:

By KCL:

\[
\frac{-V_i}{R_1} + \frac{V_O}{\frac{1}{j\omega C}} + \frac{V_O}{R_2} = O
\]

Simplifying this further results in:

\[
V_O = -\frac{R_2}{R_1} \left[ \frac{1}{j\omega C R_2 + 1} \right] V_i
\]

or

\[
\frac{V_O}{V_i} = -\frac{R_2}{R_1} \left[ \frac{1}{j\omega C R_2 + 1} \right]
\]

Now, substituting \(\omega = 2\pi f\), so that the calculations are in \(f(\text{Hz})\) and not \(\omega(\text{rad/s})\), and setting the DC gain \(H_O = -\frac{R_2}{R_1}\) and \(H = \frac{V_O}{V_i}\),

\[
H = H_O \left[ \frac{1}{j2\pi f R_2 + 1} \right]
\]

Set: \(f_o = 1/(2\pi R_1 C)\)

\[
H = H_O \left[ \frac{1}{1 + j(2\pi f/f_o)} \right]
\]

Low pass filters are known as lossy integrators because they only behave as an integrator at higher frequencies. Just by looking at the transfer function one can predict the general form of the bode plot. When the \(f/f_o\) ratio is small, the capacitor is in effect an open circuit and the amplifier behaves at a set DC gain. Starting at \(f_o\), a 3dB corner, the capacitor will have the dominant impedance and hence the circuit will behave as an integrator and the signal will be attenuated and eventually cut. The bode plot for this filter is shown in the following picture:
HIGH PASS FILTER

In a similar approach, one can derive the transfer function of a high pass filter. A typical first order high pass filter is shown below:

Figure 46. Highpass Filter

Writing the KCL for this circuit:

\[
\frac{V_1}{V_i} = \frac{1}{jwC}
\]

\[
\frac{V + V_1}{R_1} = \frac{V + V_O}{R_2}
\]

Solving these two equations to find the transfer function and using:

\[
H_O = \frac{R_2}{R_1}
\]

\[
H = \frac{V_O}{V_i}
\]

Which results:

\[
H = H_O \times \frac{j(f/f_o)}{1 + j(f/f_o)}
\]

Looking at the transfer function, it is clear that when \(f/f_o\) is small, the capacitor is open and hence no signal is getting in to the amplifier. As the frequency increases the amplifier starts operating. At \(f = f_o\) the capacitor behaves like a short circuit and the amplifier will have a constant, high frequency, gain of \(H_O\). Figure 47 shows the transfer function of this high pass filter:
Combining a low pass filter and a high pass filter will generate a band pass filter. In this network the input impedance forms the high pass filter while the feedback impedance forms the low pass filter. Choosing the corner frequencies so that \( f_1 < f_2 \), then all the frequencies in between, \( f_1 \leq f \leq f_2 \), will pass through the filter while frequencies below \( f_1 \) and above \( f_2 \) will be cut off.

The transfer function can be easily calculated using the same methodology as before.

\[
H = H_0 \frac{j (\theta f_1)}{[1 + j (\theta f_1)] [1 + j (\theta f_2)]}
\]

where

\[
f_1 = \frac{1}{2\pi R_1 C_1}
\]

\[
f_2 = \frac{1}{2\pi R_2 C_2}
\]

\[
H_0 = \frac{R_2}{R_1}
\]

The transfer function is presented in the following figure.
STATE VARIABLE ACTIVE FILTER

State variable active filters are circuits that can simultaneously represent high pass, band pass, and low pass filters. The state variable active filter uses three separate amplifiers to achieve this task. A typical state variable active filter is shown in Figure 50. The first amplifier in the circuit is connected as a gain stage. The second and third amplifiers are connected as integrators, which means they behave as low pass filters. The feedback path from the output of the third amplifier to the first amplifier enables this low frequency signal to be fed back with a finite and fairly low closed loop gain. This is while the high frequency signal on the input is still gained up by the open loop gain of the 1st amplifier. This makes the first amplifier a high pass filter. The high pass signal is then fed into a low pass filter. The outcome is a band pass signal, meaning the second amplifier is a band pass filter. This signal is then fed into the third amplifiers input and so, the third amplifier behaves as a simple low pass filter.

Figure 50. State Variable Active Filter

The transfer function of each filter needs to be calculated. The derivations will be more trivial if each stage of the filter is shown on its own.

The three components are:
For A₁ the relationship between input and output is:

\[ V_{O1} = \frac{-R_4}{R_1} V_0 + \left[ \frac{R_6}{R_5 + R_6} \right] \frac{R_1 + R_4}{R_1} V_{IN} + \left[ \frac{R_5}{R_5 + R_6} \right] \frac{R_1 + R_4}{R_1} V_{O2} \]  

(19)

This relationship depends on the output of all the filters. The input-output relationship for A₂ can be expressed as:

\[ V_{O2} = \frac{-1}{sC_2R_2} V_{O1} \]  

(20)

And finally this relationship for A₃ is as follows:

\[ V_O = \frac{-1}{sC_3R_3} V_{O2} \]  

(21)

Re-arranging these equations, one can find the relationship between \( V_O \) and \( V_{IN} \) (transfer function of the lowpass filter), \( V_{O1} \) and \( V_{IN} \) (transfer function of the highpass filter), and \( V_{O2} \) and \( V_{IN} \) (transfer function of the bandpass filter). These relationships are as follows:

**Lowpass Filter**

\[
\frac{V_O}{V_{IN}} = \frac{\frac{1}{s^2} + \frac{1}{sC_2R_2} \left[ \frac{R_1 + R_4}{R_1} \right] \left[ \frac{R_6}{R_5 + R_6} \right] + \frac{1}{C_2C_3R_2R_3}}{\frac{R_5}{R_5 + R_6} \left[ \frac{R_1 + R_4}{R_1} \right] + \frac{1}{C_2C_3R_2R_3}}
\]  

(22)

**Highpass Filter**

\[
\frac{V_{O1}}{V_{IN}} = \frac{\frac{s^2}{s^2} + \frac{1}{sC_2R_2} \left[ \frac{R_1 + R_4}{R_1} \right] \left[ \frac{R_6}{R_5 + R_6} \right] + \frac{1}{C_2C_3R_2R_3}}{\frac{R_5}{R_5 + R_6} \left[ \frac{R_1 + R_4}{R_1} \right] + \frac{1}{C_2C_3R_2R_3}}
\]  

(23)

**Bandpass Filter**

\[
\frac{V_{O2}}{V_{IN}} = \frac{s^2 + \frac{1}{sC_2R_2} \left[ \frac{R_1 + R_4}{R_1} \right] \left[ \frac{R_6}{R_5 + R_6} \right] + \frac{1}{C_2C_3R_2R_3}}{\frac{R_5}{R_5 + R_6} \left[ \frac{R_1 + R_4}{R_1} \right] + \frac{1}{C_2C_3R_2R_3}}
\]  

(24)
The center frequency and Quality Factor for all of these filters is the same. The values can be calculated in the following manner:

\[ \omega_c = \sqrt{\frac{1}{C_2C_3R_2R_3}} \]

and

\[ Q = \sqrt{\frac{C_2R_2}{C_3R_3} \left( \frac{R_5 + R_6}{R_6} \right) \frac{R_1}{R_1 + R_4}} \]

(25)

A design example is shown here:

Designing a bandpass filter with center frequency of 10kHz and Quality Factor of 5.5

To do this, first consider the Quality Factor. It is best to pick convenient values for the capacitors. \( C_2 = C_3 = 1000\text{pF} \). Also, choose \( R_1 = R_4 = 30\text{k}\Omega \). Now values of \( R_5 \) and \( R_6 \) need to be calculated. With the chosen values for the capacitors and resistors, \( Q \) reduces to:

\[ Q = \frac{11}{2} = \frac{1}{2} \left( \frac{R_5 + R_6}{R_6} \right) \]

(26)

or

\[ R_5 = 10R_6 \]

\[ R_6 = 1.5k \Omega \]

\[ R_5 = 15k \Omega \]

(27)

Also, for \( f = 10\text{kHz} \), the center frequency is \( \omega_c = 2\pi f = 62.8\text{kHz} \).

Using the expressions above, the appropriate resistor values will be \( R_2 = R_3 = 16k \Omega \).

The following graphs show the transfer function of each of the filters. The DC gain of this circuit is:

\[ \text{DC GAIN} = \frac{R_1 + R_4}{R_1} \left( \frac{R_5 + R_6}{R_5 + R_6} \right) = -14.8 \text{ dB} \]

(28)
# REVISION HISTORY

<table>
<thead>
<tr>
<th>Changes from Revision A (April 2013) to Revision B</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>• Changed layout of National Data Sheet to TI format</td>
<td>19</td>
</tr>
</tbody>
</table>

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Product Folder Links: **SM73308**
## PACKAGING INFORMATION

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status (1)</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan (2)</th>
<th>Lead/Ball Finish</th>
<th>MSL Peak Temp (3)</th>
<th>Op Temp (°C)</th>
<th>Top-Side Markings (4)</th>
<th>Samples</th>
</tr>
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<tbody>
<tr>
<td>SM73308MG/NOPB</td>
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<td>DCK</td>
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<td>1000</td>
<td>Green (RoHS &amp; no Sb/Br)</td>
<td>CU SN</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
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<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
<td>S08</td>
<td>Samples</td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan:
- The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check [http://www.ti.com/productcontent](http://www.ti.com/productcontent) for the latest availability information and additional product content details.
- **TBD:** The Pb-Free/Green conversion plan has not been defined.
- **Pb-Free (RoHS):** TI’s terms “Lead-Free” or “Pb-Free” mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
- **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.
- **Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. – The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a “~” will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

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## TAPE AND REEL INFORMATION

**REEL DIMENSIONS**

![Reel Dimensions Diagram]

**TAPE DIMENSIONS**

![Tape Dimensions Diagram]

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**

![Quadrant Assignments Diagram]

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*All dimensions are nominal.

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### TAPE AND REEL BOX DIMENSIONS

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</tr>
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</table>

*All dimensions are nominal*
DCK (R-PDSO-G5)  PLASTIC SMALL-OUTLINE PACKAGE

NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
D. Falls within JEDEC MO-203 variation AA.
LAND PATTERN DATA

DCK (R-PDSO-G5)  PLASTIC SMALL OUTLINE

Example Board Layout

Stencil Openings
Based on a stencil thickness of .127mm (.005 inch).

NOTES:  
A. All linear dimensions are in millimeters.  
B. This drawing is subject to change without notice.  
C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.  
D. Publication IPC-7351 is recommended for alternate designs.  
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7526 for other stencil recommendations.
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