1 Features

- Digital Unipolar-Switch Hall Sensor
- Superior Temperature Stability
  - Sensitivity ±10% Over Temperature
- Multiple Sensitivity Options \(B_{\text{OP}} / B_{\text{RP}}\):
  - 3.5 / 2 mT (FA, see Figure 24)
  - 6.9 / 3.2 mT (AJ, see Figure 24)
  - 14.5 / 6 mT (BI, see Figure 24)
- Supports a Wide Voltage Range
  - 2.5 to 38 V
  - No External Regulator Required
- Wide Operating Temperature Range
  - \(T_A = -40\) to 125°C (Q, see Figure 24)
- Open Drain Output (30-mA Sink)
- Fast 35-µs Power-On Time
- Small Package and Footprint
  - Surface Mount 3-Pin SOT-23 (DBZ)
    - 2.92 mm × 2.37 mm
  - Through-Hole 3-Pin TO-92 (LPG)
    - 4.00 mm × 3.15 mm
- Protection Features
  - Reverse Supply Protection (up to –22 V)
  - Supports up to 40-V Load Dump
  - Output Short-Circuit Protection
  - Output Current Limitation

2 Applications

- Docking Detection
- Door Open and Close Detection
- Proximity Sensing
- Valve Positioning
- Pulse Counting

3 Description

The DRV5023 device is a chopper-stabilized Hall Effect Sensor that offers a magnetic sensing solution with superior sensitivity stability over temperature and integrated protection features.

When the applied magnetic flux density exceeds the \(B_{\text{OP}}\) threshold, the DRV5023 open-drain output goes low. The output stays low until the field decreases to less than \(B_{\text{RP}}\), and then the output goes to high impedance. The output current sink capability is 30 mA. A wide operating voltage range from 2.5 to 38 V with reverse polarity protection up to –22 V makes the device suitable for a wide range of industrial applications.

Internal protection functions are provided for reverse supply conditions, load dump, and output short circuit or over current.

Device Information

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>DRV5023</td>
<td>SOT-23 (3)</td>
<td>2.92 mm × 1.30 mm</td>
</tr>
<tr>
<td></td>
<td>TO-92 (3)</td>
<td>4.00 mm × 3.15 mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.
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2 Applications .......................................................... 1
3 Description ............................................................ 1
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   6.2 ESD Ratings .......................................................... 5
   6.3 Recommended Operating Conditions ................... 5
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4 Revision History
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision F (May 2016) to Revision G Page
• Changed the power-on time for the FA version in the Electrical Characteristics table .................................................... 6
• Added the Layout section .................................................. 19
• Added the Receiving Notification of Documentation Updates section ................................................................................... 21

Changes from Revision E (February 2016) to Revision F Page
• Revised preliminary limits for the FA version ................................................. 6

Changes from Revision D (December 2015) to Revision E Page
• Added the FA device option ........................................................................ 1
• Added the typical bandwidth value to the Magnetic Characteristics table ................................................................................... 6

Changes from Revision C (May 2015) to Revision D Page
• Corrected body size of SOT-23 package and SIP package name to TO-92 .......................................................... 1
• Added BMAX to Absolute Maximum Ratings .................................................. 5
• Removed table note from junction temperature ................................................................................................................ 5
• Updated package tape and reel options for M and blank ................................................. 20
• Added Community Resources ........................................................................... 21

Changes from Revision B (September 2014) to Revision C Page
• Updated device status to production data ........................................................ 1
Changes from Revision A (August 2014) to Revision B

<table>
<thead>
<tr>
<th>Change</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Updated High Sensitivity Options to +6.9 / +3.2 mT (AJ) and +14.5 / +6 mT (BI)</td>
<td>1</td>
</tr>
<tr>
<td>Added typical rise and fall time and removed maximum value</td>
<td>6</td>
</tr>
<tr>
<td>Updated the device values and typical values in Magnetic Characteristics</td>
<td>6</td>
</tr>
<tr>
<td>Updated all Typical Characteristics graphs</td>
<td>7</td>
</tr>
<tr>
<td>Updated Equation 4</td>
<td>17</td>
</tr>
<tr>
<td>Updated Figure 24</td>
<td>20</td>
</tr>
</tbody>
</table>

Changes from Original (May 2014) to Revision A

<table>
<thead>
<tr>
<th>Change</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed High Sensitivity Options: +6.9 / +2.3 mT (AJ) to +6.9 / +3.3 mT (AJ)</td>
<td>1</td>
</tr>
<tr>
<td>Changed the maximum $T_J$ value from 175°C to 150°C</td>
<td>5</td>
</tr>
<tr>
<td>Changed MIN value for $I_{OCP}$ from 20 to 15</td>
<td>6</td>
</tr>
<tr>
<td>Changed Max value for $I_{OCP}$ from 40 to 45</td>
<td>6</td>
</tr>
<tr>
<td>Updated Magnetic Characteristics table.</td>
<td>6</td>
</tr>
</tbody>
</table>
5 Pin Configuration and Functions

For additional configuration information, see Device Markings and Mechanical, Packaging, and Orderable Information.

### Pin Functions

<table>
<thead>
<tr>
<th>PIN</th>
<th>TYPE</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>GND</td>
<td>GND</td>
<td>Ground pin</td>
</tr>
<tr>
<td>OUT</td>
<td>Output</td>
<td>Hall sensor open-drain output. The open drain requires a resistor pullup.</td>
</tr>
<tr>
<td>VCC</td>
<td>Power</td>
<td>2.5 to 38 V power supply. Bypass this pin to the GND pin with a 0.01-μF (minimum) ceramic capacitor rated for VCC.</td>
</tr>
</tbody>
</table>
6 Specifications

6.1 Absolute Maximum Ratings
over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power supply voltage $V_{CC}$</td>
<td>$-22$</td>
<td>$40$</td>
<td>V</td>
</tr>
<tr>
<td>Voltage ramp rate ($V_{CC}$), $V_{CC} &lt; 5$ V</td>
<td>Unlimited</td>
<td></td>
<td>V/µs</td>
</tr>
<tr>
<td>Voltage ramp rate ($V_{CC}$), $V_{CC} &gt; 5$ V</td>
<td>0</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>Output pin voltage</td>
<td>$-0.5$</td>
<td>40</td>
<td>V</td>
</tr>
<tr>
<td>Output pin reverse current during reverse supply condition</td>
<td>0</td>
<td>100 mA</td>
<td></td>
</tr>
<tr>
<td>Magnetic flux density, $B_{MAX}$</td>
<td>Unlimited</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operating junction temperature, $T_J$</td>
<td>$-40$</td>
<td>150</td>
<td>°C</td>
</tr>
<tr>
<td>Storage temperature, $T_{stg}$</td>
<td>$-65$</td>
<td>150</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) Ensured by design. Only tested to $-20$ V.

6.2 ESD Ratings

<table>
<thead>
<tr>
<th>V(ESD)</th>
<th>VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Electrostatic discharge</td>
<td>±2500</td>
<td>V</td>
</tr>
</tbody>
</table>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions
over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CC}$ Power supply voltage</td>
<td>2.5</td>
<td>38</td>
<td>V</td>
</tr>
<tr>
<td>$V_O$ Output pin voltage (OUT)</td>
<td>0</td>
<td>38</td>
<td>V</td>
</tr>
<tr>
<td>$I_{SINK}$ Output pin current sink (OUT)</td>
<td>0</td>
<td>30 mA</td>
<td></td>
</tr>
<tr>
<td>$T_A$ Operating ambient temperature</td>
<td>$-40$</td>
<td>125</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Power dissipation and thermal limits must be observed.

6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(1)</th>
<th>DRV5023</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R_{JA}$ Junction-to-ambient thermal resistance</td>
<td>333.2</td>
<td>180 °C/W</td>
</tr>
<tr>
<td>$R_{JC(top)}$ Junction-to-case (top) thermal resistance</td>
<td>99.9</td>
<td>98.6 °C/W</td>
</tr>
<tr>
<td>$R_{JB}$ Junction-to-board thermal resistance</td>
<td>66.9</td>
<td>154.9 °C/W</td>
</tr>
<tr>
<td>$\psi_{JT}$ Junction-to-top characterization parameter</td>
<td>4.9</td>
<td>40 °C/W</td>
</tr>
<tr>
<td>$\psi_{JB}$ Junction-to-board characterization parameter</td>
<td>65.2</td>
<td>154.9 °C/W</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.
### 6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>POWER SUPPLIES (V(_{CC}))</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>V(_{CC})</td>
<td>V(_{CC}) operating voltage</td>
<td>2.5</td>
<td>38</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>I(_{CC})</td>
<td>Operating supply current</td>
<td>V(<em>{CC}) = 2.5 to 38 V, T(</em>{A}) = 25°C</td>
<td>2.7</td>
<td>3.5</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>V(<em>{CC}) = 2.5 to 38 V, T(</em>{A}) = 125°C</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>t(_{on})</td>
<td>Power-on time</td>
<td>AJ, BI versions</td>
<td>35</td>
<td>50</td>
<td>µs</td>
</tr>
<tr>
<td></td>
<td>FA version</td>
<td></td>
<td>35</td>
<td>70</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>OPEN DRAIN OUTPUT (OUT)</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>t(_{d})</td>
<td>Output delay time</td>
<td>B = B(<em>{RP}) – 10 mT to B(</em>{OP}) + 10 mT in 1 µs</td>
<td>13</td>
<td>25</td>
<td>µs</td>
</tr>
<tr>
<td>t(_{r})</td>
<td>Output rise time (10% to 90%)</td>
<td>R1 = 1 kΩ, C(<em>{O}) = 50 pF, V(</em>{CC}) = 3.3 V</td>
<td>200</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>t(_{f})</td>
<td>Output fall time (90% to 10%)</td>
<td>R1 = 1 kΩ, C(<em>{O}) = 50 pF, V(</em>{CC}) = 3.3 V</td>
<td>31</td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>

### 6.6 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>OPEN DRAIN OUTPUT (OUT)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>t(_{d})</td>
<td>Output delay time</td>
<td>B = B(<em>{RP}) – 10 mT to B(</em>{OP}) + 10 mT in 1 µs</td>
<td>13</td>
<td>25</td>
<td>µs</td>
</tr>
<tr>
<td>t(_{r})</td>
<td>Output rise time (10% to 90%)</td>
<td>R1 = 1 kΩ, C(<em>{O}) = 50 pF, V(</em>{CC}) = 3.3 V</td>
<td>200</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>t(_{f})</td>
<td>Output fall time (90% to 10%)</td>
<td>R1 = 1 kΩ, C(<em>{O}) = 50 pF, V(</em>{CC}) = 3.3 V</td>
<td>31</td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>

### 6.7 Magnetic Characteristics

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT(^{(1)})</th>
</tr>
</thead>
<tbody>
<tr>
<td>f(_{BW})</td>
<td>Bandwidth(^{(2)})</td>
<td>20</td>
<td>30</td>
<td></td>
<td>kHz</td>
</tr>
</tbody>
</table>

**DRV5023FA: 3.5 / 2 mT**

| B\(_{OP}\) | Operate point (see Figure 12) | T\(_{A}\) = –40°C to 125°C | 1.8 | 3.5 | 6.8 | mT |
| B\(_{RP}\) | Release point (see Figure 12)  | T\(_{A}\) = –40°C to 125°C | 0.5 | 2   | 4.2 | mT |
| B\(_{hys}\) | Hysteresis; B\(_{hys}\) = (B\(_{OP}\) – B\(_{RP}\)) | 1.5 |     |     | mT |
| B\(_{O}\)  | Magnetic offset, B\(_{O}\) = (B\(_{OP}\) + B\(_{RP}\)) / 2 | 2.8 |     |     | mT |

**DRV5023AJ: 6.9 / 3.2 mT**

| B\(_{OP}\) | Operate point (see Figure 12) | T\(_{A}\) = –40°C to 125°C | 3   | 6.9 | 12  | mT |
| B\(_{RP}\) | Release point (see Figure 12)  | T\(_{A}\) = –40°C to 125°C | 1   | 3.2 | 5   | mT |
| B\(_{hys}\) | Hysteresis; B\(_{hys}\) = (B\(_{OP}\) – B\(_{RP}\)) | 3.7 |     |     | mT |
| B\(_{O}\)  | Magnetic offset, B\(_{O}\) = (B\(_{OP}\) + B\(_{RP}\)) / 2 | 5   |     |     | mT |

**DRV5023BI: 14.5 / 6 mT**

| B\(_{OP}\) | Operate point (see Figure 12) | T\(_{A}\) = –40°C to 125°C | 6   | 14.5 | 24  | mT |
| B\(_{RP}\) | Release point (see Figure 12)  | T\(_{A}\) = –40°C to 125°C | 3   | 6   | 9   | mT |
| B\(_{hys}\) | Hysteresis; B\(_{hys}\) = (B\(_{OP}\) – B\(_{RP}\))\(^{(3)}\) | 8.5 |     |     | mT |
| B\(_{O}\)  | Magnetic offset, B\(_{O}\) = (B\(_{OP}\) + B\(_{RP}\)) / 2 | 10.3|     |     | mT |

1. 1 mT = 10 Gauss
2. Bandwidth describes the fastest changing magnetic field that can be detected and translated to the output.
3. |B\(_{OP}\)| is always greater than |B\(_{RP}\)|.
6.8 Typical Characteristics

Figure 1. $I_{CC}$ vs $V_{CC}$

Figure 2. $I_{CC}$ vs Temperature

Figure 3. $B_{OP}$ vs $V_{CC}$

Figure 4. $B_{OP}$ vs Temperature

Figure 5. $B_{RP}$ vs $V_{CC}$

Figure 6. $B_{RP}$ vs Temperature
Typical Characteristics (continued)

Figure 7. Hysteresis vs $V_{CC}$

Figure 8. Hysteresis vs Temperature

Figure 9. Offset vs $V_{CC}$

Figure 10. Offset vs Temperature
7 Detailed Description

7.1 Overview

The DRV5023 device is a chopper-stabilized Hall sensor with a digital output for magnetic sensing applications. The DRV5023 device can be powered with a supply voltage between 2.5 and 38 V, and will survive –22 V reverse-battery conditions. The DRV5023 device does not operate when –22 to 2.4 V is applied to the \( V_{CC} \) pin (with respect to GND pin). In addition, the device can withstand supply voltages up to 40 V for transient durations.

The field polarity is defined as follows: a south pole near the marked side of the package is a positive magnetic field. A north pole near the marked side of the package is a negative magnetic field.

The output state is dependent on the magnetic field perpendicular to the package. A strong south pole near the marked side of the package causes the output to pull low (operate point, BOP), and a weak south pole causes the output to release (release point, BRP). Hysteresis is included in between the operate point and the release point therefore magnetic-field noise does not accidentally trip the output.

An external pullup resistor is required on the OUT pin. The OUT pin can be pulled up to \( V_{CC} \), or to a different voltage supply. This allows for easier interfacing with controller circuits.

7.2 Functional Block Diagram
7.3 Feature Description

7.3.1 Field Direction Definition

A positive magnetic field is defined as a south pole near the marked side of the package as shown in Figure 11.

Figure 11. Field Direction Definition

7.3.2 Device Output

If the device is powered on with a magnetic field strength between $B_{RP}$ and $B_{OP}$, then the device output is indeterminate and can either be Hi-Z or Low. For the FA, AJ, and BI device versions, if the field strength is greater than $B_{OP}$, then the output is pulled low; if the field strength is less than $B_{RP}$, then the output is released. For the FI device version, if the field strength is greater than $B_{OP}$, then the output is Hi-Z; if the field strength is less than $B_{RP}$, then the output is pulled Low.
7.3.3 Power-On Time

After applying $V_{CC}$ to the DRV5023 device, $t_{on}$ must elapse before the OUT pin is valid. During the power-up sequence, the output is Hi-Z. A pulse as shown in Figure 13 and Figure 14 occurs at the end of $t_{on}$. This pulse can allow the host processor to determine when the DRV5023 output is valid after startup. In Case 1 (Figure 13) and Case 2 (Figure 14), the output is defined assuming a constant magnetic field $B > B_{OP}$ and $B < B_{RP}$.

![Figure 13. Case 1: Power On When $B > B_{OP}$](image1)

![Figure 14. Case 2: Power On When $B < B_{RP}$](image2)
Feature Description (continued)

If the device is powered on with the magnetic field strength $B_{RP} < B < B_{OP}$, then the device output is indeterminate and can either be Hi-Z or pulled low. During the power-up sequence, the output is held Hi-Z until $t_{on}$ has elapsed. At the end of $t_{on}$, a pulse is given on the OUT pin to indicate that $t_{on}$ has elapsed. After $t_{on}$, if the magnetic field changes such that $B_{OP} < B$, the output is released. Case 3 (Figure 15) and Case 4 (Figure 16) show examples of this behavior.

![Diagram showing magnetic field strength and output behavior over time](image-url)

**Figure 15. Case 3: Power On When $B_{RP} < B < B_{OP}$, Followed by $B > B_{OP}$**
Feature Description (continued)

Figure 16. Case 4: Power On When $B_{RP} < B < B_{OP}$, Followed by $B < B_{RP}$
Feature Description (continued)

7.3.4 Output Stage

The DRV5023 output stage uses an open-drain NMOS, and it is rated to sink up to 30 mA of current. For proper operation, calculate the value of the pullup resistor R1 using Equation 1.

\[
\frac{V_{\text{ref max}}}{30 \, \text{mA}} \leq R1 \leq \frac{V_{\text{ref min}}}{100 \, \mu\text{A}}
\]

The size of R1 is a tradeoff between the OUT rise time and the current when OUT is pulled low. A lower current is generally better, however faster transitions and bandwidth require a smaller resistor for faster switching.

In addition, ensure that the value of \( R1 > 500 \, \Omega \) to ensure the output driver can pull the OUT pin close to GND.

**NOTE**

\( V_{\text{ref}} \) is not restricted to \( V_{\text{CC}} \). The allowable voltage range of this pin is specified in the *Absolute Maximum Ratings*.

Select a value for C2 based on the system bandwidth specifications as shown in Equation 2.

\[
2 \times f_{\text{BW}} \, (\text{Hz}) < \frac{1}{2\pi \times R1 \times C2}
\]

Most applications do not require this C2 filtering capacitor.
Feature Description (continued)

7.3.5 Protection Circuits

The DRV5023 device is fully protected against overcurrent and reverse-supply conditions.

7.3.5.1 Overcurrent Protection (OCP)

An analog current-limit circuit limits the current through the FET. The driver current is clamped to $I_{\text{OCP}}$. During this clamping, the $r_{\text{DS(on)}}$ of the output FET is increased from the nominal value.

7.3.5.2 Load Dump Protection

The DRV5023 device operates at DC $V_{\text{CC}}$ conditions up to 38 V nominally, and can additionally withstand $V_{\text{CC}} = 40$ V. No current-limiting series resistor is required for this protection.

7.3.5.3 Reverse Supply Protection

The DRV5023 device is protected in the event that the $V_{\text{CC}}$ pin and the GND pin are reversed (up to $-22$ V).

NOTE

In a reverse supply condition, the OUT pin reverse-current must not exceed the ratings specified in the Absolute Maximum Ratings.

<table>
<thead>
<tr>
<th>FAULT</th>
<th>CONDITION</th>
<th>DEVICE</th>
<th>DESCRIPTION</th>
<th>RECOVERY</th>
</tr>
</thead>
<tbody>
<tr>
<td>FET overload (OCP)</td>
<td>$I_{\text{Sink}} \geq I_{\text{OCP}}$</td>
<td>Operating</td>
<td>Output current is clamped to $I_{\text{OCP}}$</td>
<td>$I_{O} &lt; I_{\text{OCP}}$</td>
</tr>
<tr>
<td>Load dump</td>
<td>$38 \text{ V} &lt; V_{\text{CC}} &lt; 40 \text{ V}$</td>
<td>Operating</td>
<td>Device will operate for a transient duration</td>
<td>$V_{\text{CC}} \leq 38 \text{ V}$</td>
</tr>
<tr>
<td>Reverse supply</td>
<td>$-22 \text{ V} &lt; V_{\text{CC}} &lt; 0 \text{ V}$</td>
<td>Disabled</td>
<td>Device will survive this condition</td>
<td>$V_{\text{CC}} \geq 2.5 \text{ V}$</td>
</tr>
</tbody>
</table>

7.4 Device Functional Modes

The DRV5023 device is active only when $V_{\text{CC}}$ is between 2.5 and 38 V.

When a reverse supply condition exists, the device is inactive.
8 Application and Implementation

NOTE
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information
The DRV5023 device is used in magnetic-field sensing applications.

8.2 Typical Applications

8.2.1 Standard Circuit

![Typical Application Circuit Diagram]

Figure 18. Typical Application Circuit

8.2.1.1 Design Requirements
For this design example, use the parameters listed in Table 2 as the input parameters.

Table 2. Design Parameters

<table>
<thead>
<tr>
<th>DESIGN PARAMETER</th>
<th>REFERENCE</th>
<th>EXAMPLE VALUE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage</td>
<td>( V_{CC} )</td>
<td>3.2 to 3.4 V</td>
</tr>
<tr>
<td>System bandwidth</td>
<td>( f_{BW} )</td>
<td>10 kHz</td>
</tr>
</tbody>
</table>

8.2.1.2 Detailed Design Procedure

Table 3. External Components

<table>
<thead>
<tr>
<th>COMPONENT</th>
<th>PIN 1</th>
<th>PIN 2</th>
<th>RECOMMENDED</th>
</tr>
</thead>
<tbody>
<tr>
<td>C1</td>
<td>( V_{CC} )</td>
<td>GND</td>
<td>A 0.01-µF (minimum) ceramic capacitor rated for ( V_{CC} )</td>
</tr>
<tr>
<td>C2</td>
<td>OUT</td>
<td>GND</td>
<td>Optional: Place a ceramic capacitor to GND</td>
</tr>
<tr>
<td>R1</td>
<td>OUT</td>
<td>REF(1)</td>
<td>Requires a resistor pullup</td>
</tr>
</tbody>
</table>

(1) REF is not a pin on the DRV5023 device, but a REF supply-voltage pullup is required for the OUT pin; the OUT pin may be pulled up to \( V_{CC} \).
8.2.1.2.1 Configuration Example

In a 3.3-V system, $3.2 \leq V_{\text{ref}} \leq 3.4$ V. Use Equation 3 to calculate the allowable range for $R_1$.

$$\frac{V_{\text{ref \ max}}}{30 \text{ mA}} \leq R_1 \leq \frac{V_{\text{ref \ min}}}{100 \text{ µA}}$$

(3)

For this design example, use Equation 4 to calculate the allowable range of $R_1$.

$$\frac{3.4 \text{ V}}{30 \text{ mA}} \leq R_1 \leq \frac{3.2 \text{ V}}{100 \text{ µA}}$$

(4)

Therefore:

$$113 \ \Omega \leq R_1 \leq 32 \ \text{k}\Omega$$

(5)

After finding the allowable range of $R_1$ (Equation 5), select a value between 500 $\Omega$ and 32 k$\Omega$ for $R_1$.

Assuming a system bandwidth of 10 kHz, use Equation 6 to calculate the value of $C_2$.

$$2 \times f_{\text{BW}} \text{ (Hz)} < \frac{1}{2\pi \times R_1 \times C_2}$$

(6)

For this design example, use Equation 7 to calculate the value of $C_2$.

$$2 \times 10 \ \text{kHz} < \frac{1}{2\pi \times R_1 \times C_2}$$

(7)

An $R_1$ value of 10 k$\Omega$ and a $C_2$ value less than 820 pF satisfy the requirement for a 10-kHz system bandwidth. A selection of $R_1 = 10$ k$\Omega$ and $C_2 = 680$ pF would cause a low-pass filter with a corner frequency of 23.4 kHz.

8.2.1.3 Application Curves

![Figure 19. 10-kHz Switching Magnetic Field](image1)

![Figure 20. 10-kHz Switching Magnetic Field](image2)

![Figure 21. Low-Pass Filtering](image3)
8.2.2 Alternative Two-Wire Application

For systems that require minimal wire count, the device output can be connected to \( V_{CC} \) through a resistor, and the total supplied current can be sensed near the controller.

![2-Wire Application Diagram](image)

Current can be sensed using a shunt resistor or other circuitry.

### 8.2.2.1 Design Requirements

Table 4 lists the related design parameters.

<table>
<thead>
<tr>
<th>DESIGN PARAMETER</th>
<th>REFERENCE</th>
<th>EXAMPLE VALUE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage</td>
<td>( V_{CC} )</td>
<td>12 V</td>
</tr>
<tr>
<td>OUT resistor</td>
<td>( R_1 )</td>
<td>1 kΩ</td>
</tr>
<tr>
<td>Bypass capacitor</td>
<td>( C_1 )</td>
<td>0.1 µF</td>
</tr>
<tr>
<td>Current when ( B &lt; B_{RP} )</td>
<td>( i_{\text{RELEASE}} )</td>
<td>About 3 mA</td>
</tr>
<tr>
<td>Current when ( B &gt; B_{OP} )</td>
<td>( i_{\text{OPERATE}} )</td>
<td>About 15 mA</td>
</tr>
</tbody>
</table>

### 8.2.2.2 Detailed Design Procedure

When the open-drain output of the device is high-impedance, current through the path equals the \( I_{CC} \) of the device (approximately 3 mA).

When the output pulls low, a parallel current path is added, equal to \( V_{CC} / (R_1 + r_{D\text{S(on)}}) \). Using 12 V and 1 kΩ, the parallel current is approximately 12 mA, making the total current approximately 15 mA.

The local bypass capacitor \( C_1 \) should be at least 0.1 µF, and a larger value if there is high inductance in the power line interconnect.

### 9 Power Supply Recommendations

The DRV5023 device is designed to operate from an input voltage supply (VM) range between 2.5 and 38 V. A 0.01-µF (minimum) ceramic capacitor rated for \( V_{CC} \) must be placed as close to the DRV5023 device as possible.
10 Layout

10.1 Layout Guidelines

The bypass capacitor should be placed near the DRV5023 device for efficient power delivery with minimal inductance. The external pullup resistor should be placed near the microcontroller input to provide the most stable voltage at the input; alternatively, an integrated pullup resistor within the GPIO of the microcontroller can be used.

Generally, using PCB copper planes underneath the DRV5023 device has no effect on magnetic flux, and does not interfere with device performance. This is because copper is not a ferromagnetic material. However, if nearby system components contain iron or nickel, they may redirect magnetic flux in unpredictable ways.

10.2 Layout Example

![DRV5023 Layout Example](image-url)
11 Device and Documentation Support

11.1 Device Support

11.1.1 Device Nomenclature

Figure 24 shows a legend for reading the complete device name for and DRV5023 device.

Prefix
DRV5023: Digital switch Hall sensor

BOP/BRP
FA: 3.5/2 mT
AJ: 6.9/3.2 mT
BI: 14.5/6 mT

AEC-Q100
Q1: Automotive qualification
Blank: Non-auto

Tape and Reel
R: 3000 pcs/reel
T: 250 pcs/reel
M: 3000 pcs/box (ammo)
Blank: 1000 pcs/bag (bulk)

Package
DBZ: 3-pin SOT-23
LPG: 3-pin TO-92

Temperature Range
Q: ±40 to 125°C
E: ±40 to 150°C

Figure 24. Device Nomenclature

11.1.2 Device Markings

Marked Side
1 2 3

Marked Side Front
1 2 3

Marked Side
(Bottom view)

Figure 25. SOT-23 (DBZ) Package

Figure 26. TO-92 (LPG) Package

indicates the Hall effect sensor (not to scale). The Hall element is located in the center of the package with a tolerance of ±100 µm. The height of the Hall element from the bottom of the package is 0.7 mm ±50 µm in the DBZ package and 0.987 mm ±50 µm in the LPG package.
11.2 Receiving Notification of Documentation Updates
To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on Alert me to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Community Resources
The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.4 Trademarks
E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution

⚠️ These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.6 Glossary

**SLYZ022 — Ti Glossary.**
This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information
The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
### PACKAGING INFORMATION

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status (1)</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan (2)</th>
<th>Lead/Ball Finish</th>
<th>MSL Peak Temp (3)</th>
<th>Op Temp (°C)</th>
<th>Device Marking</th>
<th>Samples</th>
</tr>
</thead>
<tbody>
<tr>
<td>DRV5023AJQDBZR</td>
<td>ACTIVE</td>
<td>SOT-23</td>
<td>DBZ</td>
<td>3</td>
<td>3000</td>
<td>Green (RoHS &amp; no Sb/Br)</td>
<td>NIPDAUAG</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 125</td>
<td>(+PLAJ, 1J22)</td>
<td>Samples</td>
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<tr>
<td>DRV5023AJQDBZT</td>
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<td>3</td>
<td>250</td>
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<td>(+PLBI, 1J32)</td>
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<td>Samples</td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:
- **ACTIVE**: Product device recommended for new designs.
- **LIFEBUY**: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND**: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE**: TI has discontinued the production of the device.

(2) **RoHS**: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
- **RoHS Exempt**: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
- **Green**: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp**: The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF DRV5023:
- Automotive: DRV5023-Q1

NOTE: Qualified Version Definitions:
- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects
TAPE AND REEL INFORMATION

<table>
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<tr>
<th>Device</th>
<th>Package Type</th>
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<th>Reel Diameter (mm)</th>
<th>Reel Width W1 (mm)</th>
<th>A0 (mm)</th>
<th>B0 (mm)</th>
<th>K0 (mm)</th>
<th>P1 (mm)</th>
<th>W (mm)</th>
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<td>2.77</td>
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*All dimensions are nominal.*
**TAPE AND REEL BOX DIMENSIONS**

*All dimensions are nominal*

<table>
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<tr>
<th>Device</th>
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</table>
NOTES:
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
EXAMPLE BOARD LAYOUT

TO-92 - 5.05 mm max height

LPG0003A

TRANSISTOR OUTLINE

LAND PATTERN EXAMPLE
NON-SOLDER MASK DEFINED
SCALE: 20X
Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC registration TO-236, except minimum foot length.
NOTES: (continued)

4. Publication IPC-7351 may have alternate designs.
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
7. Board assembly site may have different recommendations for stencil design.
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