The DS90C401 is a dual driver device optimized for high data rate and low power applications. This device along with the DS90C402 provides a pair chip solution for a dual high speed point-to-point interface. The DS90C401 is a current mode driver allowing power dissipation to remain low even at high frequency. In addition, the short circuit fault current is also minimized. The device is in a 8 lead small outline package. The differential driver outputs provides low EMI with its low output swings typically 340 mV.

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.
### Absolute Maximum Ratings

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage (V\text{CC})</td>
<td>−0.3V</td>
<td>+6V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Voltage (D\text{IN})</td>
<td>−0.3V</td>
<td>(V\text{CC} + 0.3V)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Voltage (D\text{OUT+}, D\text{OUT−})</td>
<td>−0.3V</td>
<td>(V\text{CC} + 0.3V)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Short Circuit Duration (D\text{OUT+}, D\text{OUT−})</td>
<td>Continuous</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Maximum Package Power Dissipation @ +25°C
- D Package: 1068 mW

Derate D Package: 8.5 mW/°C above +25°C

Storage Temperature Range: −65°C to +150°C

Lead Temperature Range:
- Soldering (4 sec.): +260°C

Maximum Junction Temperature: +150°C

ESD Rating (3)
- HBM (1.5 kΩ, 100 pF): ≥3,500V
- EIAJ (0Ω, 200 pF): ≥250V

Recommended Operating Conditions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage (V\text{CC})</td>
<td>+4.5</td>
<td>+5.0</td>
<td>+5.5</td>
<td>V</td>
</tr>
<tr>
<td>Operating Free Air Temperature (T\text{A})</td>
<td>−40</td>
<td>+25</td>
<td>+85</td>
<td>°C</td>
</tr>
</tbody>
</table>

Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Pin</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>\text{VOD1}</td>
<td>Differential Output Voltage</td>
<td>R\text{L} = 100Ω (Figure 1)</td>
<td>D\text{OUT+}, D\text{OUT−}</td>
<td>250</td>
<td>340</td>
<td>450</td>
<td>mV</td>
</tr>
<tr>
<td>\Delta\text{VOD1}</td>
<td>Change in Magnitude of \text{VOD1}</td>
<td>for Complementary Output States</td>
<td>D\text{OUT+}, D\text{OUT−}</td>
<td>4</td>
<td>35</td>
<td></td>
<td>[mV]</td>
</tr>
<tr>
<td>\text{VOS}</td>
<td>Offset Voltage</td>
<td></td>
<td></td>
<td>1.125</td>
<td>1.25</td>
<td>1.375</td>
<td>V</td>
</tr>
<tr>
<td>\Delta\text{VOS}</td>
<td>Change in Magnitude of \text{VOS}</td>
<td>for Complementary Output States</td>
<td></td>
<td>5</td>
<td>25</td>
<td></td>
<td>[mV]</td>
</tr>
<tr>
<td>\text{VOL}</td>
<td>Output Voltage Low</td>
<td>R\text{L} = 100Ω</td>
<td></td>
<td>0.90</td>
<td>1.07</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>\text{IO}</td>
<td>Output Short Circuit Current</td>
<td>V\text{OUT} = 0V(3)</td>
<td>D\text{IN}</td>
<td>−3.5</td>
<td>−5.0</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>\text{VIN}</td>
<td>Input Voltage High</td>
<td></td>
<td>D\text{IN}</td>
<td>2.0</td>
<td>VCC</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>\text{VL}</td>
<td>Input Voltage Low</td>
<td></td>
<td>D\text{IN}</td>
<td>0.8</td>
<td>GND</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>\text{Ii}</td>
<td>Input Current</td>
<td>V\text{IN} = V\text{CC}, GND, 2.5V or 0.4V</td>
<td>I\text{CL} = −18 mA</td>
<td>−10</td>
<td>±1</td>
<td>+10</td>
<td>µA</td>
</tr>
<tr>
<td>\text{VCL}</td>
<td>Input Clamp Voltage</td>
<td></td>
<td>D\text{IN}</td>
<td>−1.5</td>
<td>−0.8</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>\text{I\text{CC}}</td>
<td>No Load Supply Current</td>
<td>D\text{IN} = V\text{CC} or GND</td>
<td>V\text{CC}</td>
<td>1.7</td>
<td>3.0</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>D\text{IN} = 2.5V or 0.4V</td>
<td></td>
<td>3.5</td>
<td>5.5</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>\text{I\text{CCl}}</td>
<td>Loaded Supply Current</td>
<td>R\text{L} = 100Ω All Channels</td>
<td>V\text{IN} = V\text{CC} or GND (all inputs)</td>
<td>8</td>
<td>14.0</td>
<td></td>
<td>mA</td>
</tr>
</tbody>
</table>

(1) “Absolute Maximum Ratings” are those values beyond which the safety of the device cannot be ensured. They are not meant to imply that the devices should be operated at these limits. Electrical Characteristics specifies conditions of device operation.

(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

(3) ESD Ratings:
- HBM (1.5 kΩ, 100 pF): ≥3,500V
- EIAJ (0Ω, 200 pF): ≥250V

Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except: \text{VOD1} and \Delta\text{VOD1}.

All typicals are given for: V\text{CC} = +5.0V, T\text{A} = +25°C.

Output short circuit current (I\text{OS}) is specified as magnitude only, minus sign indicates direction only.
Switching Characteristics

$V_{CC} = +5.0\, \text{V} \pm 10\%, \quad T_A = -40^\circ \text{C} \text{ to } +85^\circ \text{C}$(1)(2)(3)(4)(5)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_{PHLD}$</td>
<td>Differential Propagation Delay High to Low</td>
<td>$R_L = 100, \Omega, \ C_L = 5, \text{pF}$ (Figure 2 and Figure 3)</td>
<td>0.5</td>
<td>2.0</td>
<td>3.5</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{PLHD}$</td>
<td>Differential Propagation Delay Low to High</td>
<td></td>
<td>0.5</td>
<td>2.1</td>
<td>3.5</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{SKD}$</td>
<td>Differential Skew $</td>
<td>t_{PHLD} - t_{PLHD}</td>
<td>$</td>
<td></td>
<td>0</td>
<td>80</td>
</tr>
<tr>
<td>$t_{SK1}$</td>
<td>Channel-to-Channel Skew$^{(2)}$</td>
<td></td>
<td>0</td>
<td>0.3</td>
<td>1.0</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{SK2}$</td>
<td>Chip to Chip Skew$^{(3)}$</td>
<td></td>
<td></td>
<td></td>
<td>3.0</td>
<td>ns</td>
</tr>
<tr>
<td>$t_{THL}$</td>
<td>Rise Time</td>
<td></td>
<td>0.35</td>
<td>2.0</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$t_{TLH}$</td>
<td>Fall Time</td>
<td></td>
<td>0.35</td>
<td>2.0</td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>

(1) All typicals are given for: $V_{CC} = +5.0\, \text{V}, \ T_A = +25^\circ \text{C}$.
(2) Channel-to-Channel Skew is defined as the difference between the propagation delay of the channel and the other channels in the same chip with an event on the inputs.
(3) Chip to Chip Skew is defined as the difference between the minimum and maximum specified differential propagation delays.
(4) Generator waveform for all tests unless otherwise specified: $f = 1 \, \text{MHz}, \ Z_O = 50\, \Omega, \ t_r \leq 6\, \text{ns}, \ \text{and} \ t_f \leq 6\, \text{ns}$.
(5) $C_L$ includes probe and jig capacitance.

Parameter Measurement Information

![Figure 1. Driver $V_{OD}$ and $V_{OS}$ Test Circuit](image1)

![Figure 2. Driver Propagation Delay and Transition Time Test Circuit](image2)
Figure 3. Driver Propagation Delay and Transition Time Waveforms
Applications Information

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in Figure 4. This configuration provides a clean signaling environment for the quick edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic impedance of the media is in the range of 100Ω. A termination resistor of 100Ω should be selected to match the media, and is located as close to the receiver input pins as possible. The termination resistor converts the current sourced by the driver into a voltage that is detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be taken into account.

The DS90C401 differential line driver is a balanced current source design. A current mode driver, generally speaking has a high output impedance and supplies a constant current for a range of loads (a voltage mode driver on the other hand supplies a constant voltage for a range of loads). Current is switched through the load in one direction to produce a logic state and in the other direction to produce the other logic state. The typical output current is mere 3.4 mA, a minimum of 2.5 mA, and a maximum of 4.5 mA. The current mode requires (as discussed above) that a resistive termination be employed to terminate the signal and to complete the loop as shown in Figure 4. AC or unterminated configurations are not allowed. The 3.4 mA loop current will develop a differential voltage of 340 mV across the 100Ω termination resistor which the receiver detects with a 240 mV minimum differential noise margin neglecting resistive line losses (driven signal minus receiver threshold (340 mV – 100 mV = 240 mV)). The signal is centered around +1.2V (Driver Offset, V\_OS) with respect to ground as shown in Figure 5. Note that the steady-state voltage (V\_SS) peak-to-peak swing is twice the differential voltage (V\_OD) and is typically 680 mV.

The current mode driver provides substantial benefits over voltage mode drivers, such as an RS-422 driver. Its quiescent current remains relatively flat versus switching frequency. Whereas the RS-422 voltage mode driver increases exponentially in most case between 20 MHz–50 MHz. This is due to the overlap current that flows between the rails of the device when the internal gates switch. Whereas the current mode driver switches a fixed current between its output without any substantial overlap current. This is similar to some ECL and PECL devices, but without the heavy static I\_CC requirements of the ECL/PECL designs. LVDS requires > 80% less current than similar PECL devices. AC specifications for the driver are a tenfold improvement over other existing RS-422 drivers.
## PIN DESCRIPTIONS

<table>
<thead>
<tr>
<th>Pin No.</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4, 8</td>
<td>(D_{\text{IN}})</td>
<td>TTL/CMOS driver input pins</td>
</tr>
<tr>
<td>3, 7</td>
<td>(D_{\text{OUT}+})</td>
<td>Non-inverting driver output pin</td>
</tr>
<tr>
<td>2, 6</td>
<td>(D_{\text{OUT}-})</td>
<td>Inverting driver output pin</td>
</tr>
<tr>
<td>5</td>
<td>GND</td>
<td>Ground pin</td>
</tr>
<tr>
<td>1</td>
<td>(V_{\text{CC}})</td>
<td>Positive power supply pin, (+5.0\text{V} \pm 10%)</td>
</tr>
</tbody>
</table>

### Truth Table\(^{(1)}\)

<table>
<thead>
<tr>
<th>(D_{\text{IN}})</th>
<th>(D_{\text{OUT}+})</th>
<th>(D_{\text{OUT}-})</th>
</tr>
</thead>
<tbody>
<tr>
<td>L</td>
<td>L</td>
<td>H</td>
</tr>
<tr>
<td>H</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>(D_{\text{IN}} &gt; 0.8\text{V and } D_{\text{IN}} &lt; 2.0\text{V})</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

\(^{(1)}\) H = Logic high level  
L = Logic low level  
X = Indeterminant state
Typical Performance Characteristics

Power Supply Current vs Power Supply Voltage

Figure 6.

Power Supply Current vs Power Supply Voltage

Figure 8.

Output Short Circuit Current vs Power Supply Voltage

Figure 10.

Power Supply Current vs Temperature

Figure 7.

Power Supply Current vs Temperature

Figure 9.

Differential Output Voltage vs Power Supply Voltage

Figure 11.
Typical Performance Characteristics (continued)

Differential Output Voltage vs Ambient Temperature

\[ V_{CC} = 5\text{V} \]
\[ \text{Load} = 100\Omega \]

\[ V_{OH} - \text{Output Voltage High (mV)} \]
\[ V_{OL} - \text{Output Voltage Low (mV)} \]

\[ T_A - \text{Ambient Temperature (°C)} \]

Figure 12.

Output Voltage High vs Power Supply Voltage

\[ T_A = 25\text{°C} \]
\[ \text{Load} = 100\Omega \]

\[ V_{OH} - \text{Output Voltage High (V)} \]

\[ V_{CC} - \text{Power Supply Voltage (V)} \]

Figure 13.

Output Voltage Low vs Ambient Temperature

\[ V_{CC} = 5\text{V} \]
\[ \text{Load} = 100\Omega \]

\[ V_{OL} - \text{Output Voltage Low (V)} \]

\[ T_A - \text{Ambient Temperature (°C)} \]

Figure 14.

Offset Voltage vs Power Supply Voltage

\[ T_A = 25\text{°C} \]
\[ \text{Load} = 100\Omega \]

\[ V_{OS} - \text{Offset Voltage (V)} \]

\[ V_{CC} - \text{Power Supply Voltage (V)} \]

Figure 17.
Typical Performance Characteristics (continued)

Offset Voltage vs Ambient Temperature

\[ V_{OS} = \text{Offset Voltage (V)} \]

\[ V_{CC} = 5\, \text{V} \]
\[ \text{Load} = 100\, \Omega \]

\[ T_A = \text{Ambient Temperature (°C)} \]

Figure 18.

Power Supply Current vs Frequency

\[ I_{CC} = \text{Power Supply Current (mA)} \]

\[ T_A = 25^\circ\, \text{C} \]
\[ V_{CC} = 5\, \text{V} \]

All Drivers Switching
\[ \text{Load} = 100\, \Omega \]

1 dr load
No loads

\[ F_Q = \text{Frequency (MHz)} \]

Figure 19.

Differential Output Voltage vs Load Resistor

\[ V_{DD} = \text{Differential Output Voltage (mV)} \]

\[ T_A = 25^\circ\, \text{C} \]
\[ V_{CC} = 5\, \text{V} \]

\[ R_L = \text{Load Resistor (Ω)} \]

Figure 20.

Differential Propagation Delay vs Power Supply Voltage

\[ t_{PD} = \text{Differential Propagation Delay (ns)} \]

\[ T_A = 25^\circ\, \text{C} \]
\[ V_{CC} = 5\, \text{V} \]
\[ \text{Freq} = 65\, \text{MHz} \]
\[ \text{Load} = 100\, \Omega \]

\[ t_{PHLH} \quad t_{PLH} \]

\[ t_{PHLH} \quad t_{PLH} \]

\[ V_{CC} = \text{Power Supply Voltage (V)} \]

Figure 21.

Differential Propagation Delay vs Ambient Temperature

\[ t_{PD} = \text{Differential Propagation Delay (ns)} \]

\[ V_{CC} = 5\, \text{V} \]
\[ \text{Freq} = 65\, \text{MHz} \]
\[ \text{Load} = 100\, \Omega \]

\[ T_A = \text{Ambient Temperature (°C)} \]

\[ t_{PHLH} \quad t_{PLH} \]

\[ t_{PHLH} \quad t_{PLH} \]

Figure 22.

Differential Skew vs Power Supply Voltage

\[ t_{SK} = \text{Differential Skew (ns)} \]

\[ T_A = 25^\circ\, \text{C} \]
\[ V_{CC} = 5\, \text{V} \]
\[ \text{Freq} = 65\, \text{MHz} \]
\[ \text{Load} = 100\, \Omega \]

\[ V_{CC} = \text{Power Supply Voltage (V)} \]

Figure 23.
Typical Performance Characteristics (continued)

Differential Skew vs Ambient Temperature

![Graph showing differential skew vs ambient temperature](image)

Figure 24.

Differential Transition Time vs Ambient Temperature

![Graph showing differential transition time vs ambient temperature](image)

Figure 26.

Differential Transition Time vs Power Supply Voltage

![Graph showing differential transition time vs power supply voltage](image)

Figure 25.
## REVISION HISTORY

### Changes from Revision B (April 2013) to Revision C

<table>
<thead>
<tr>
<th>Change Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Changed layout of National Data Sheet to TI format</td>
<td>9</td>
</tr>
</tbody>
</table>
## Packaging Information

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan</th>
<th>Lead/Ball Finish</th>
<th>MSL Peak Temp</th>
<th>Op Temp (°C)</th>
<th>Device Marking</th>
<th>Samples</th>
</tr>
</thead>
<tbody>
<tr>
<td>DS90C401M</td>
<td>NRND</td>
<td>SOIC</td>
<td>D</td>
<td>8</td>
<td>95</td>
<td>TBD</td>
<td>Call TI</td>
<td>Call TI</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DS90C401M/NOPB</td>
<td>ACTIVE</td>
<td>SOIC</td>
<td>D</td>
<td>8</td>
<td>95</td>
<td>Green (RoHS &amp; no Sb/Br)</td>
<td>CU SN</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 85</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DS90C401MX/NOPB</td>
<td>ACTIVE</td>
<td>SOIC</td>
<td>D</td>
<td>8</td>
<td>2500</td>
<td>Green (RoHS &amp; no Sb/Br)</td>
<td>CU SN</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 85</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** Ti has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but Ti does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE:** Ti has discontinued the production of the device.

(2) **RoHS:** Ti defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. Ti may reference these types of products as "Pb-Free".
- **RoHS Exempt:** Ti defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
- **Green:** Ti defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.
## TAPE AND REEL INFORMATION

<table>
<thead>
<tr>
<th>Device</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>SPQ</th>
<th>Reel Diameter (mm)</th>
<th>Reel Width W1 (mm)</th>
<th>A0 (mm)</th>
<th>B0 (mm)</th>
<th>K0 (mm)</th>
<th>P1 (mm)</th>
<th>W (mm)</th>
<th>Pin1 Quadrant</th>
</tr>
</thead>
<tbody>
<tr>
<td>DS90C401MX/NOPB</td>
<td>SOIC</td>
<td>D</td>
<td>8</td>
<td>2500</td>
<td>330.0</td>
<td>12.4</td>
<td>6.5</td>
<td>5.4</td>
<td>2.0</td>
<td>8.0</td>
<td>12.0</td>
<td>Q1</td>
</tr>
</tbody>
</table>

*All dimensions are nominal.

### TAPE DIMENSIONS

- **A0**: Dimension designed to accommodate the component width
- **B0**: Dimension designed to accommodate the component length
- **K0**: Dimension designed to accommodate the component thickness
- **W**: Overall width of the carrier tape
- **P1**: Pitch between successive cavity centers

### REEL DIMENSIONS

- **Reel Diameter**
- **Reel Width (W1)**

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

- **Pocket Quadrants**
- **Sprocket Holes**
- **User Direction of Feed**

*www.ti.com 15-Sep-2018*
### TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal*

<table>
<thead>
<tr>
<th>Device</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>SPQ</th>
<th>Length (mm)</th>
<th>Width (mm)</th>
<th>Height (mm)</th>
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<tbody>
<tr>
<td>DS90C401MX/NOPB</td>
<td>SOIC</td>
<td>D</td>
<td>8</td>
<td>2500</td>
<td>367.0</td>
<td>367.0</td>
<td>35.0</td>
</tr>
</tbody>
</table>
NOTES:
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.

⚠️ Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0.15) each side.

⚠️ Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0.43) each side.
E. Reference JEDEC MS-012 variation AA.

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