INA1x9 High-Side Measurement Current Shunt Monitor

1 Features
- Complete Unipolar High-Side Current Measurement Circuit
- Wide Supply and Common-Mode Range
  - INA139: 2.7 V to 40 V
  - INA169: 2.7 V to 60 V
- Independent Supply and Input Common-Mode Voltages
- Single Resistor Gain Set
- Low Quiescent Current: 60 µA (Typical)
- 5-Pin, SOT-23 Packages

2 Applications
- Current Shunt Measurement:
  - Automotive, Telephone, Computers
- Portable and Battery-Backup Systems
- Battery Chargers
- Power Management
- Cell Phones
- Precision Current Source

3 Description
The INA139 and INA169 are high-side, unipolar, current shunt monitors. Wide input common-mode voltage range, high-speed, low quiescent current, and tiny SOT-23 packaging enable use in a variety of applications.

Input common-mode and power-supply voltages are independent and can range from 2.7 V to 40 V for the INA139 and 2.7 V to 60 V for the INA169. Quiescent current is only 60 µA, which permits connecting the power supply to either side of the current measurement shunt with minimal error.

The device converts a differential input voltage to a current output. This current is converted back to a voltage with an external load resistor that sets any gain from 1 to over 100. Although designed for current shunt measurement, the circuit invites creative applications in measurement and level shifting.

Both the INA139 and INA169 are available in 5-pin SOT-23 packages. The INA139 device is specified for the –40°C to +125°C temperature range, and the INA169 is specified from –40°C to +85°C.

Device Information

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>INA139</td>
<td>SOT-23 (5)</td>
<td>2.90 mm × 1.60 mm</td>
</tr>
<tr>
<td>INA169</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Application Circuit

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision E (December 2015) to Revision F

Page
• Changed INA139 maximum temperature specification from +85°C to +125°C in Description section .................................................. 1
• Changed INA139 device maximum temperature specification from +85°C to +125°C in Description section ...................... 1
• Updated Typical Application Circuit graphic on front page with 2017 copyright .................................................................................. 1
• Updated pinout diagram in Pin Configurations and Functions section .................................................................................. 3
• Reformatted Recommended Operating Conditions table ...................................................................................................... 4
• Changed common-mode rejection minimum value from 100 dB to 99 dB in the Electrical Characteristics table ......................... 6
• Changed offset voltage maximum value from ±1 mV to ±1.5 mV in the Electrical Characteristics table ......................................... 6
• Changed INA139 nonlinearity error maximum value from ±0.1% to ± 0.13% in the Electrical Characteristics table ............ 6
• Changed maximum value of INA139 temperature range specification from 85°C to 125°C in the Electrical Characteristics table ...................................................................................................... 6
• Added updated copyright statement to Functional Block Diagram .................................................................................. 9

Changes from Revision D (November 2005) to Revision E

Page
• Changed ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section ...................................................................................................... 1
5 Pin Configuration and Functions

![DBV Package 5-Pin SOT-23 Top View](image)

### Pin Functions

<table>
<thead>
<tr>
<th>PIN</th>
<th>I/O</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>GND</td>
<td>2</td>
<td>Ground</td>
</tr>
<tr>
<td>OUT</td>
<td>1</td>
<td>O</td>
</tr>
<tr>
<td>VIN+</td>
<td>3</td>
<td>I</td>
</tr>
<tr>
<td>VIN-</td>
<td>4</td>
<td>I</td>
</tr>
<tr>
<td>V+</td>
<td>5</td>
<td>I</td>
</tr>
</tbody>
</table>

- **GND**: Ground
- **OUT**: Output current
- **VIN+**: Positive input voltage
- **VIN-**: Negative input voltage
- **V+**: Power supply voltage
6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage, $V_S$</td>
<td>INA139</td>
<td>–0.3</td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>INA169</td>
<td>–0.3</td>
<td>75</td>
</tr>
<tr>
<td>Analog inputs, INA139</td>
<td>Common-mode (2)</td>
<td>–0.3</td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>Differential ($V_{IN+} - V_{IN-}$)</td>
<td>–40</td>
<td>2</td>
</tr>
<tr>
<td>Analog inputs, INA169</td>
<td>Common-mode (2)</td>
<td>–0.3</td>
<td>75</td>
</tr>
<tr>
<td></td>
<td>Differential ($V_{IN+} - V_{IN-}$)</td>
<td>–40</td>
<td>2</td>
</tr>
<tr>
<td>Analog input, out (2)</td>
<td>–0.3</td>
<td>40</td>
<td>V</td>
</tr>
<tr>
<td>Input current into any pin</td>
<td></td>
<td>10</td>
<td>mA</td>
</tr>
<tr>
<td>Operating temperature, $T_A$</td>
<td></td>
<td>–55</td>
<td>125</td>
</tr>
<tr>
<td>Junction temperature, $T_J$</td>
<td></td>
<td>150</td>
<td></td>
</tr>
<tr>
<td>Storage temperature, $T_{stg}$</td>
<td></td>
<td>–65</td>
<td>125</td>
</tr>
</tbody>
</table>

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The input voltage at any pin may exceed the voltage shown if the current at that pin is limited to 10 mA.

6.2 ESD Ratings

<table>
<thead>
<tr>
<th>$V_{(ESD)}$</th>
<th>Electrostatic discharge</th>
<th>VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)</td>
<td>±1000</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>Charged-device model (CDM), per JEDEC specification JESD22-C101 (2)</td>
<td>±500</td>
<td>V</td>
</tr>
</tbody>
</table>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

<table>
<thead>
<tr>
<th></th>
<th>MIN</th>
<th>NOM</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V+$</td>
<td>INA139</td>
<td>2.7</td>
<td>5</td>
<td>40</td>
</tr>
<tr>
<td></td>
<td>INA169</td>
<td>2.7</td>
<td>5</td>
<td>60</td>
</tr>
<tr>
<td>Common-mode voltage</td>
<td>INA139</td>
<td>2.7</td>
<td>12</td>
<td>40</td>
</tr>
<tr>
<td></td>
<td>INA169</td>
<td>2.7</td>
<td>12</td>
<td>60</td>
</tr>
</tbody>
</table>
6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(^{(1)})</th>
<th>INA1x9</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>(R_{\text{JA}}) Junction-to-ambient thermal resistance</td>
<td>168.3</td>
<td>°C/W</td>
</tr>
<tr>
<td>(R_{\text{JC}\text{{top}}}) Junction-to-case (top) thermal resistance</td>
<td>73.8</td>
<td>°C/W</td>
</tr>
<tr>
<td>(R_{\text{JB}}) Junction-to-board thermal resistance</td>
<td>28.1</td>
<td>°C/W</td>
</tr>
<tr>
<td>(\psi_{\text{JT}}) Junction-to-top characterization parameter</td>
<td>2.5</td>
<td>°C/W</td>
</tr>
<tr>
<td>(\psi_{\text{JB}}) Junction-to-board characterization parameter</td>
<td>27.6</td>
<td>°C/W</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
### 6.5 Electrical Characteristics

**INA139**: all other characteristics at \( T_A = -40^\circ C \) to \(+125^\circ C\), \( V_+ = 5 \) \( V \), \( V_{IN+} = 12 \) \( V \), and \( R_{OUT} = 25 \) \( k\Omega \), unless otherwise noted.

**INA169**: all other characteristics at \( T_A = -40^\circ C \) to \(+85^\circ C\), \( V_+ = 5 \) \( V \), \( V_{IN+} = 12 \) \( V \), and \( R_{OUT} = 25 \) \( k\Omega \), unless otherwise noted.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>INPUT</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Full-scale sense voltage</td>
<td>( V_{SENSE} = V_{IN+} - V_{IN-} )</td>
<td>100</td>
<td>500</td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>Common-mode input range</td>
<td><strong>INA139</strong></td>
<td>2.7</td>
<td>40</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong></td>
<td>2.7</td>
<td>60</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Common-mode rejection</td>
<td><strong>INA139</strong>: ( V_{IN+} = 2.7 ) ( V ) to ( 40 ) ( V ), ( V_{SENSE} = 50 ) ( mV )</td>
<td>99</td>
<td>115</td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong>: ( V_{IN+} = 2.7 ) ( V ) to ( 60 ) ( V ), ( V_{SENSE} = 50 ) ( mV )</td>
<td>100</td>
<td>120</td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td>Offset voltage (1) <strong>RTI</strong></td>
<td><strong>INA139</strong></td>
<td>±0.2</td>
<td>±1.5</td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong></td>
<td>±0.2</td>
<td>±1</td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>vs. temperature</td>
<td>( T_{MIN} ) to ( T_{MAX} )</td>
<td>1</td>
<td></td>
<td></td>
<td>µV/°C</td>
</tr>
<tr>
<td>vs power supply (( V_+ ))</td>
<td><strong>INA139</strong>: ( V_+ = 2.7 ) ( V ) to ( 40 ) ( V ), ( V_{SENSE} = 50 ) ( mV )</td>
<td>0.5</td>
<td>10</td>
<td></td>
<td>µV/V</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong>: ( V_+ = 2.7 ) ( V ) to ( 60 ) ( V ), ( V_{SENSE} = 50 ) ( mV )</td>
<td>0.1</td>
<td>10</td>
<td></td>
<td>µV/V</td>
</tr>
<tr>
<td>Input bias current</td>
<td></td>
<td>10</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td><strong>OUTPUT</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Transconductance vs temperature</td>
<td>( V_{SENSE} = 10 ) ( mV ) – ( 150 ) ( mV )</td>
<td>990</td>
<td>1000</td>
<td>1010</td>
<td>µA/V</td>
</tr>
<tr>
<td></td>
<td>( V_{SENSE} = 10 ) ( mV )</td>
<td>10</td>
<td></td>
<td></td>
<td>nA/°C</td>
</tr>
<tr>
<td>Nonlinearity error</td>
<td>( V_{SENSE} = 10 ) ( mV ) to ( 150 ) ( mV )</td>
<td><strong>INA139</strong>: ±0.01% ±0.13%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong>:</td>
<td>±0.01% ±0.1%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Total output error</td>
<td>( V_{SENSE} = 100 ) ( mV )</td>
<td>±0.5%</td>
<td>±2%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output impedance</td>
<td>1</td>
<td></td>
<td>5</td>
<td>GΩ</td>
<td></td>
</tr>
<tr>
<td>Voltage output</td>
<td>Swing to power supply, ( V_+ )</td>
<td>(( V_+ ) – 0.9)</td>
<td>(( V_+ ) – 1.2)</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Swing to common-mode, ( V_{CM} )</td>
<td>( V_{CM} ) – 0.6</td>
<td>( V_{CM} ) – 1</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>FREQUENCY RESPONSE</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bandwidth</td>
<td>( R_{OUT} = 10 ) ( k\Omega )</td>
<td>440</td>
<td></td>
<td></td>
<td>kHz</td>
</tr>
<tr>
<td></td>
<td>( R_{OUT} = 20 ) ( k\Omega )</td>
<td>220</td>
<td></td>
<td></td>
<td>kHz</td>
</tr>
<tr>
<td>Settling time (0.1%)</td>
<td>5-V step, ( R_{OUT} = 10 ) ( k\Omega )</td>
<td>2.5</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td></td>
<td>5-V step, ( R_{OUT} = 20 ) ( k\Omega )</td>
<td>5</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
<tr>
<td><strong>NOISE</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output-current noise density</td>
<td></td>
<td>20</td>
<td></td>
<td></td>
<td>pA/√Hz</td>
</tr>
<tr>
<td>Total output-current noise</td>
<td>( BW = 100 ) ( kHz )</td>
<td>7</td>
<td></td>
<td></td>
<td>nA RMS</td>
</tr>
<tr>
<td><strong>POWER SUPPLY</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operating range, ( V_+ )</td>
<td><strong>INA139</strong></td>
<td>2.7</td>
<td>40</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong></td>
<td>2.7</td>
<td>60</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Quiescent current</td>
<td>( V_{SENSE} = 0 ), ( I_O = 0 )</td>
<td>60</td>
<td>125</td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td><strong>TEMPERATURE RANGE</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Specification, ( T_{MIN} ) to ( T_{MAX} )</td>
<td><strong>INA139</strong></td>
<td>−40</td>
<td>125</td>
<td></td>
<td>°C</td>
</tr>
<tr>
<td></td>
<td><strong>INA169</strong></td>
<td>−40</td>
<td>85</td>
<td></td>
<td>°C</td>
</tr>
<tr>
<td>Operating</td>
<td></td>
<td>−55</td>
<td>125</td>
<td></td>
<td>°C</td>
</tr>
<tr>
<td>Storage</td>
<td></td>
<td>−65</td>
<td>150</td>
<td></td>
<td>°C</td>
</tr>
<tr>
<td>Thermal resistance, ( \theta_J )</td>
<td></td>
<td>200</td>
<td></td>
<td></td>
<td>°C/W</td>
</tr>
</tbody>
</table>

(1) Defined as the amount of voltage (\( V_{SENSE} \)) to drive the output to zero.
6.6 Typical Characteristics

at $T_A = 25^\circ C$, $V_+ = 5\, V$, $V_{IN+} = 12\, V$, and $R_L = 125\, k\Omega$, unless otherwise noted.

Output error is essentially independent both of $V_+$ supply voltage and input common-mode voltage.

Figure 1. Gain vs Frequency

Figure 2. Common-Mode Rejection vs Frequency

Figure 3. Power-Supply Rejection vs Frequency

Figure 4. Total Output Error vs $V_{IN}$

Figure 5. Total Output Error vs Power-Supply Voltage

Figure 6. Quiescent Current vs Power-Supply Voltage
Typical Characteristics (continued)

at $T_A = 25^\circ C$, $V_+ = 5$ V, $V_{\text{IN}+} = 12$ V, and $R_L = 125$ k$\Omega$, unless otherwise noted.

Figure 7. Step Response

Figure 8. Step Response
7 Detailed Description

7.1 Overview
The INA139 and INA169 devices are comprised of a high voltage, precision operational amplifier, precision thin film resistors trimmed in production to an absolute tolerance and a low noise output transistor. The INA139 and INA169 devices can be powered from a single power supply and their input voltages can exceed the power supply voltage. The INA139 and INA169 devices are ideal for measuring small differential voltages, such as those generated across a shunt resistor in the presence of large, common-mode voltages. See the Functional Block Diagram, which illustrates the functional components within both the INA139 and INA169 devices.

7.2 Functional Block Diagram

7.3 Feature Description

7.3.1 Output Voltage Range
The output of the INA139 is a current, which is converted to a voltage by the load resistor \(R_L\). The output current remains accurate within the compliance voltage range of the output circuitry. The shunt voltage and the input common-mode and power-supply voltages limit the maximum possible output swing. The maximum output voltage compliance is limited by the lower of Equation 1 and Equation 2.

\[ V_{\text{OUTMAX}} = (V^+) - 0.7\ V - (V_{\text{IN+}} - V_{\text{IN-}}) \]  

or whichever is lower

\[ V_{\text{OUTMAX}} = V_{\text{IN-}} - 0.5\ V \]
Feature Description (continued)

7.3.2 Bandwidth

Measurement bandwidth is affected by the value of the load resistor ($R_L$). High gain produced by high values of $R_L$ yield a narrower measurement bandwidth (see the Typical Characteristics graphs). For widest possible bandwidth, keep the capacitive load on the output to a minimum. Reduction in bandwidth due to capacitive load is shown in the Typical Characteristics graphs.

If bandwidth limiting (filtering) is desired, a capacitor can be added to the output (see Figure 12). This does not cause instability.

7.4 Device Functional Modes

For proper operation the INA139 and INA169 devices must operate within their specified limits. Operating either device outside of their specified power supply voltage range or their specified common-mode range results in unexpected behavior and is not recommended. Additionally operating the output beyond their specified limits with respect to power supply voltage and input common-mode voltage will also produce unexpected results. See the Electrical Characteristics table for device specifications.
8 Application and Implementation

8.1 Application Information

8.1.1 Operation

Figure 9 illustrates the basic circuit diagram for both the INA139 and INA169. Load current \( I_S \) is drawn from supply \( V_S \) through shunt resistor \( R_S \). The voltage drop in shunt resistor \( V_S \) is forced across \( R_{Q1} \) by the internal operational amplifier, causing current to flow into the collector of Q1. The external resistor \( R_L \) converts the output current to a voltage, \( V_{OUT} \), at the OUT pin.

The transfer function for the INA139 is given by Equation 3:

\[
I_O = g_m \left( V_{IN+} - V_{IN-} \right)
\]

where

\[
g_m = 1000 \; \mu A / V
\]  

(3)

In the circuit of Figure 9, the input voltage \( (V_{IN+} - V_{IN-}) \) is equal to \( I_S \times R_S \) and the output voltage \( V_{OUT} \) is equal to \( I_O \times R_L \). The transconductance \( g_m \) of the INA139 is 1000 \( \mu A / V \). The complete transfer function for the current measurement amplifier in this application is given by Equation 4:

\[
V_{OUT} = \left( I_S \right) \left( R_S \right) \left( 1000 \; \mu A / V \right) \left( R_L \right)
\]

(4)

The maximum differential input voltage for accurate measurements is 0.5 V, which produces a 500-\( \mu \)A output current. A differential input voltage of up to 2 V will not cause damage. Differential measurements (pins 3 and 4) must be unipolar with a more-positive voltage applied to pin 3. If a more-negative voltage is applied to pin 3, the output current, \( I_O \), is zero, but it will not cause damage.
Application Information (continued)

8.2 Typical Applications

The INA139 is designed for current shunt measurement circuits, as shown in Figure 9, but its basic function is useful in a wide range of circuitry. A creative engineer will find many unforeseen uses in measurement and level shifting circuits. A few ideas are illustrated in Figure 14 through Figure 18.

8.2.1 Buffering Output to Drive an ADC

Figure 10. Buffering Output to Drive the A/D Converter

8.2.1.1 Design Requirements

Digitize the output of the INA139 or INA169 devices using a 1-MSPS analog-to-digital converter (ADC).
Typical Applications (continued)

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Selecting $R_S$ and $R_L$

In Figure 9 the value selected for the shunt resistor ($R_S$) depends on the application and is a compromise between small-signal accuracy and maximum permissible voltage loss in the measurement line. High values of $R_S$ provide better accuracy at lower currents by minimizing the effects of offset, while low values of $R_S$ minimize voltage loss in the supply line. For most applications, best performance is attained with an $R_S$ value that provides a full-scale shunt voltage of 50 mV to 100 mV; maximum input voltage for accurate measurements is 500 mV.

$R_L$ is selected to provide the desired full-scale output voltage. The output impedance of the INA139 and INA169 OUT terminal is very high, which permits using values of $R_L$ up to 100 kΩ with excellent accuracy. The input impedance of any additional circuitry at the output must be much higher than the value of $R_L$ to avoid degrading accuracy.

Some analog-to-digital converters (ADCs) have input impedances that significantly affect measurement gain. The input impedance of the ADC can be included as part of the effective $R_L$ if the input can be modeled as a resistor to ground. Alternatively, an operational amplifier can be used to buffer the ADC input, as shown in Figure 10. The INA139 and INA169 are current output devices, and have an inherently large output impedance. The output currents from the amplifier are converted to an output voltage through the load resistor ($R_L$) connected from the amplifier output to ground. The ratio of the load resistor value to that of the internal resistor value determines the voltage gain of the system.

In many applications, digitizing the output of the INA139 or INA169 devices is required. This is accomplished by connecting the output of the amplifier to an ADC. It is very common for an ADC to have a dynamic input impedance. If the INA139 or INA169 output is connected directly to an ADC input, the input impedance of the ADC is effectively connected in parallel with the gain setting resistor ($R_L$). This parallel impedance combination affects the gain of the system and the impact on the gain is difficult to estimate accurately. A simple solution that eliminates the paralleling of impedances, simplifying the gain of the circuit is to place a buffer amplifier (such as the OPA340) between the output of the INA139 or INA169 devices and the input to the ADC.

Figure 10 illustrates this concept. A low-pass filter can be placed between the OPA340 output and the input to the ADC. The filter capacitor is required to provide any instantaneous demand for current required by the input stage of the ADC. The filter resistor is required to isolate the OPA340 output from the filter capacitor to maintain circuit stability. The values for the filter components vary according to the operational amplifier used for the buffer and the particular ADC selected. For more information regarding the design of the low-pass filter, see the 16-bit 1-MSPS Data Acquisition Reference Design for Single-Ended Multiplexed Applications TI Precision Design.

Figure 11 shows the expected results when driving an analog-to-digital converter at 1 MSPS with and without buffering the INA139 or INA169 output. Without the buffer, the high impedance of the INA139 or INA169 reacts with the input capacitance and sample and hold (S/H) capacitance of the analog-to-digital converter and does not allow the S/H to reach the correct final value before the S/H resets and the next conversion starts. Adding the buffer amplifier significantly reduces the output impedance driving the S/H and allows for higher conversion rates than can be achieved without adding the buffer.
Typical Applications (continued)

8.2.1.3 Application Curve

![Application Curve Diagram]

Figure 11. Driving an ADC With and Without a Buffer

8.2.2 Output Filter

8.2.2.1 Design Requirements

Filter the output of the INA139 or INA169 devices.

8.2.2.2 Detailed Design Procedure

A low-pass filter can be formed at the output of the INA139 or INA169 devices simply by placing a capacitor of the desired value in parallel with the load resistor. First, determine the value of the load resistor required to achieve the desired gain. See the table in Figure 9. Next, determine the capacitor value that results in the desired cutoff frequency according to the equation shown in Figure 12. Figure 13 illustrates various combinations of gain settings (determined by R_L) and filter capacitors.
Typical Applications (continued)

8.2.2.3 Application Curve

![Gain vs Frequency Graph](image)

Figure 13. Gain vs Frequency

8.2.3 Offsetting the Output Voltage

For many applications using only a single power supply, it may be required to level shift the output voltage away from ground when there is no load current flowing in the shunt resistor. Level shifting the output of the INA139 or INA169 devices is easily accomplished by one of two simple methods shown in Figure 14. The method on the left hand side of Figure 14 illustrates a simple voltage divider method. This method is useful for applications that require the output of the INA139 or INA169 devices to remain centered with respect to the power supply at zero load current through the shunt resistor. Using this method the gain is determined by the parallel combination of $R_1$ and $R_2$, while the output offset is determined by the voltage divider ratio $R_1$ and $R_2$. For applications that may require a fixed value of output offset independent of the power supply voltage, TI recommends using the current source method shown on the right hand side of Figure 14. With this method, a REF200 constant current source is used to generate a constant output offset. Using this method, the gain is determined by $R_L$ and the offset is determined by the product of the value of the current source and $R_L$.

![Offsetting the Output Voltage Diagrams](image)

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1. Gain set by $R_1 || R_2$. Output offset = $(V_R) \times R_2 / (R_1 + R_2)$ using resistor divider.
2. Gain set by $R_L$. Output offset = $100 \mu A \times R_L$ (independent of $V+$) using current source.

Figure 14. Offsetting the Output Voltage
Typical Applications (continued)

8.2.4 Bipolar Current Measurement

The INA139 or INA169 devices can be configured as shown in Figure 15 in applications where measuring current bi-directionally is required. Two INA devices are required connecting their inputs across the shunt resistor as shown in Figure 15. A comparator, such as the TLV3201, is used to detect the polarity of the load current. The magnitude of the load current is monitored across the resistor connected between ground and the connection labeled Output. In this example the 20-kΩ resistor results in a gain of 20 V/V. The 10-kΩ resistors connected in series with the INA139 or INA169 output current are used to develop a voltage across the comparator inputs. Two diodes are required to prevent current flow into the INA139 or INA169 output, as only one device at a time is providing current to the Output connection of the circuit. The circuit functionality is illustrated in Figure 16.

![Figure 15. Bipolar Current Measurement](image-url)
Typical Applications (continued)

8.2.4.1 Application Curve

![Application Curve](image)

Figure 16. Bipolar Current Measurement Results (Arbitrary Scale)

8.2.5 Bipolar Current Measurement Using a Differential Input of the A/D Converter

The INA139 or INA169 devices can be used with an ADC such as the ADS7870 programmed for differential mode operation. Figure 17 illustrates this configuration. In this configuration, the use of two devices allows for bidirectional current measurement. Depending upon the polarity of the current, one of the devices provides an output voltage while the other output is zero. In this way, the ADC reads the polarity of current directly, without requiring additional circuitry.

![Bipolar Current Measurement Using a Differential Input of the A/D Converter](image)

The A/D converter is programmed for differential input. Depending on the polarity of the current, one INA139 provides an output voltage whereas the output of the other is zero.

Figure 17. Bipolar Current Measurement Using a Differential Input of the A/D Converter
Typical Applications (continued)

8.2.6 Multiplexed Measurement Using Logic Signal for Power

Multiple loads can be measured as illustrated in Figure 18. In this configuration, each INA139 or INA169 device is powered by the digital I/O from the ADS7870. Multiplex each device by switching the desired I/O on or off.

Digital I/O on the ADS7870 provides power to select the desired INA169. Diodes prevent output current of an on INA169 from flowing into an off INA169.

![Figure 18. Multiplexed Measurement Using Logic Signal for Power](image)

9 Power Supply Recommendations

The input circuitry of the INA139 can accurately measure beyond the power-supply voltage (V+). For example, the V+ power supply can be 5 V, whereas the load power supply voltage is up to 40 V (or 60 V with the INA169). However, the output voltage range of the OUT terminal is limited by the lesser of the two voltages (see the Output Voltage Range section). TI recommends placing a 0.1-µF capacitor near the V+ pin on the INA139 or INA169. Additional capacitance may be required for applications with noisy supply voltages.
10 Layout

10.1 Layout Guidelines

Figure 19 shows the basic connection of the INA139. The input pins (\(V_{\text{IN}+}\) and \(V_{\text{IN}-}\)) must be connected as closely as possible to the shunt resistor to minimize any resistance in series with the shunt resistance. The output resistor, \(R_L\), is shown connected between pin 1 and ground. Best accuracy is achieved with the output voltage measured directly across \(R_L\). This is especially important in high-current systems where load current could flow in the ground connections, affecting the measurement accuracy.

No power-supply bypass capacitors are required for stability of the INA139. However, applications with noisy or high-impedance power supplies may require decoupling capacitors to reject power-supply noise; connect the bypass capacitors close to the device pins.

10.2 Layout Example

Figure 19. Typical Layout Example
11 Device and Documentation Support

11.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

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11.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

**TI E2E™ Online Community** [TI's Engineer-to-Engineer (E2E) Community](https://e2e.ti.com). Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** [TI's Design Support](https://www.ti.com/tool/DesignSupport) Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.3 Trademarks

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

11.4 Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.5 Glossary

[SLYZ022 — TI Glossary](https://www.ti.com/tool/Glossary). This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
## PACKAGING INFORMATION

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(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBsolete: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF INA139, INA169:
• Automotive: INA139-Q1, INA169-Q1

NOTE: Qualified Version Definitions:
• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects
TAPE AND REEL INFORMATION

*All dimensions are nominal.

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## TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal*

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NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Refer to JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

8. Board assembly site may have different recommendations for stencil design.
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