1 Features

- 3-W Output into 8 $\Omega$ at 5 V With THD+N = 1%
- Selectable Spread Spectrum Mode Reduces EMI
- 80% Efficiency
- Independent Regulator and Amplifier Shutdown Controls
- Dynamically Selectable Regulator Output Voltages
- Filterless Class D
- 3-V to 5.5-V Operation
- Low Shutdown Current
- Click and Pop Suppression

Key Specifications
- Quiescent Power Supply Current
  - $V_{DD} = 3$ V 9 mA (Typical)
  - $V_{DD} = 5$ V 13.5 mA (Typical)
- $P_O$ at $V_{DD} = 5$ V, $PV_1 = 7.8$ V, $R_L = 8$ $\Omega$, THD+N = 1% 3 W (Typical)
- $P_O$ at $V_{DD} = 3$ V, $PV_1 = 4.8$ V, $R_L = 8$ $\Omega$, THD+N = 1% 1 W (Typical)
- $P_O$ at $V_{DD} = 5$ V, $PV_1 = 7.8$ V, $R_L = 4$ $\Omega$, THD+N = 1% 5.4 W (Typical)
- Shutdown Current at $V_{DD} = 3$ V, 0.01 $\mu$A (Typical)

2 Applications

- GPS
- Portable media
- Cameras
- Mobile Phones
- Handheld games

3 Description

The LM48511 device integrates a boost converter with a high-efficiency Class D audio power amplifier to provide 3-W continuous power into an 8-$\Omega$ speaker when operating from a 5-V power supply. When operating from a 3-V to 4-V power supply, the LM48511 can be configured to drive 1 to 2.5 W into an 8-$\Omega$ load with less than 1% distortion (THD+N).

The Class D amplifier features a low-noise PWM architecture that eliminates the output filter, reducing external component count, board area consumption, system cost, and simplifying design. A selectable spread spectrum modulation scheme suppresses RF emissions, further reducing the need for output filters.

The switching regulator of the LM48511 is a current-mode boost converter operating at a fixed frequency of 1 MHz. Two selectable feedback networks allow the LM48511 regulator to dynamically switch between two different output voltages, improving efficiency by optimizing the amplifier’s supply voltage based on battery voltage and output power requirements.

The LM48511 is designed for use in portable devices, such as GPS, mobile phones, and MP3 players. The high, 80% efficiency at 5 V, extends battery life when compared to Boosted Class AB amplifiers. Independent regulator and amplifier shutdown controls optimize power savings by disabling the regulator when high-output power is not required.

The gain of the LM48511 is set by external resistors, which allows independent gain control from multiple sources by summing the signals. Output short circuit and thermal overload protection prevent the device from damage during fault conditions. Superior click and pop suppression eliminates audible transients during power-up and shutdown.

Device Information(1)

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>LM48511</td>
<td>WQFN (24)</td>
<td>5.00 mm × 4.00 mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.

EMI Graph: LM48511 RF Emissions — 3-Inch Cable

![EMI Graph](image-url)
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7 Detailed Description ................................................ 12
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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision G (May 2013) to Revision H 
Page 
- Added Pin Configuration and Functions section, ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section ....................... 1

Changes from Revision F (October 2012) to Revision G 
Page 
- Changed layout of National Data Sheet to TI format ................................................................. 19

Changes from Revision D (February 2012) to Revision E 
Page 
- Deleted the Typical limits (Vih and Vil) EC table ........................................................................... 5

Changes from Revision C (November 2007) to Revision D 
Page 
- Deleted the “Build of Materials” (BOM) table ............................................................................. 19

Changes from Revision B (September 2007) to Revision C 
Page 
- Edited the Notes section and added another $P_o (@V_{DD} = 5\,V, R_L = 4\,\Omega)$ section in the Key Specification division ........ 1

Changes from Revision A (July 2007) to Revision B 
Page 
- Changed the Amplifier Voltage (Operating Ratings section) from 5 V to 4.8 V .......................................................... 4

Changes from Original (July 2007) to Revision A 
Page 
- Input some text edits .................................................................................................................. 1
5 Pin Configuration and Functions

Pin Functions

<table>
<thead>
<tr>
<th>PIN</th>
<th>I/O</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>NAME</td>
<td>NO.</td>
<td>DESCRIPTION</td>
</tr>
<tr>
<td>DAP</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>FB</td>
<td>19</td>
<td>Regulator feedback input Connect FB to an external resistive voltage divider to set the boost output voltage.</td>
</tr>
<tr>
<td>FB_GND0</td>
<td>21</td>
<td>Ground return for R3, R1 resistor divider</td>
</tr>
<tr>
<td>FB_GND1</td>
<td>20</td>
<td>Ground return for R3, R2 resistor divider</td>
</tr>
<tr>
<td>FB_SEL</td>
<td>1</td>
<td>Regulator feedback select Connect to VDD to select feedback network connected to FB_GND1. Connect to GND to select feedback network connected to FB_GND0.</td>
</tr>
<tr>
<td>GND</td>
<td>7</td>
<td>Signal ground</td>
</tr>
<tr>
<td>IN–</td>
<td>15</td>
<td>Amplifier inverting input</td>
</tr>
<tr>
<td>IN+</td>
<td>16</td>
<td>Amplifier noninverting input</td>
</tr>
<tr>
<td>LS+</td>
<td>8</td>
<td>Amplifier noninverting output</td>
</tr>
<tr>
<td>LS–</td>
<td>12</td>
<td>Amplifier inverting output</td>
</tr>
<tr>
<td>LSGND</td>
<td>9, 11</td>
<td>Amplifier H-Bridge ground</td>
</tr>
<tr>
<td>PV1</td>
<td>10</td>
<td>Amplifier H-Bridge power supply Connect to V1.</td>
</tr>
<tr>
<td>REGGND</td>
<td>22, 23</td>
<td>Power ground (booster)</td>
</tr>
<tr>
<td>SD_AMP</td>
<td>5</td>
<td>Amplifier active-low shutdown Connect to VDD for normal operation. Connect to GND to disable amplifier.</td>
</tr>
<tr>
<td>SD_BOOST</td>
<td>24</td>
<td>Regulator active-low shutdown. Connect to VDD for normal operation. Connect to GND to disable regulator.</td>
</tr>
<tr>
<td>SOFT-START</td>
<td>4</td>
<td>Soft-start capacitor</td>
</tr>
<tr>
<td>SS/FF</td>
<td>6</td>
<td>Modulation mode select Connect to VDD for spread spectrum mode (SS). Connect to GND for fixed frequency mode (FF).</td>
</tr>
<tr>
<td>SW</td>
<td>2, 3</td>
<td>Drain of the internal FET switch</td>
</tr>
<tr>
<td>V1</td>
<td>13</td>
<td>Amplifier supply voltage Connect to PV1</td>
</tr>
<tr>
<td>VDD</td>
<td>18</td>
<td>Power supply</td>
</tr>
<tr>
<td>VG0+</td>
<td>14</td>
<td>Amplifier noninverting gain output</td>
</tr>
<tr>
<td>VG0–</td>
<td>17</td>
<td>Amplifier inverting gain output</td>
</tr>
</tbody>
</table>
6 Specifications

6.1 Absolute Maximum Ratings
over operating free-air temperature range (unless otherwise noted)(1)(2).

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage (V_{DD}, PV1, V_{I})</td>
<td>9</td>
<td>V</td>
</tr>
<tr>
<td>Input voltage</td>
<td>-0.3 V_{DD} + 0.3</td>
<td>V</td>
</tr>
<tr>
<td>Power dissipation(3)</td>
<td>Internally limited</td>
<td></td>
</tr>
<tr>
<td>Junction temperature</td>
<td>150</td>
<td>°C</td>
</tr>
<tr>
<td>Storage temperature</td>
<td>-65</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied. The Recommended Operating Conditions indicate conditions at which the device is functional and the device must not be operated beyond such conditions. All voltages are measured with respect to the ground pin, unless otherwise specified.

(2) If Military/Aerospace specified devices are required, please contact the TI Sales Office/ Distributors for availability and specifications.

(3) The maximum power dissipation must be derated at elevated temperatures and is dictated by \( T_{JMAX}, \theta_{JA}, \) and the ambient temperature, \( T_A \). The maximum allowable power dissipation is \( P_{DMAX} = (T_{JMAX} - T_A) / \theta_{JA} \) or the number given in Absolute Maximum Ratings, whichever is lower. For the LM48511, see Figure 20 for additional information.

6.2 ESD Ratings

<table>
<thead>
<tr>
<th>VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Human body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)</td>
<td>2000 V</td>
</tr>
<tr>
<td>Machine model(2)</td>
<td>200 V</td>
</tr>
</tbody>
</table>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) Machine model, applicable std. JESD22-A115-A.

6.3 Recommended Operating Conditions

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature range ( T_{MIN} \leq T_A \leq T_{MAX} )</td>
<td>-40</td>
<td>85 °C</td>
</tr>
<tr>
<td>Supply voltage (V_{DD})</td>
<td>3</td>
<td>5.5 V</td>
</tr>
<tr>
<td>Amplifier voltage (PV1, V_{I})</td>
<td>4.8</td>
<td>8 V</td>
</tr>
</tbody>
</table>

6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(1)</th>
<th>LM48511</th>
</tr>
</thead>
<tbody>
<tr>
<td>( R_{JUA} ) Junction-to-ambient thermal resistance</td>
<td>32.8 °C/W</td>
</tr>
<tr>
<td>( R_{JUC(top)} ) Junction-to-case (top) thermal resistance</td>
<td>3.8 °C/W</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.
### 6.5 Electrical Characteristics $V_{DD} = 5\, V$

The following specifications apply for $V_{DD} = 5\, V$, $PV_1 = 7.8\, V$ (continuous mode), $AV = 2\, V/V$, $R_3 = 25.5\, k\Omega$, $R_{LS} = 4.87\, k\Omega$, $R_L = 8\, \Omega$, $f = 1\, kHz$, $SS/FF = GND$, unless otherwise specified. Limits apply for $T_A = 25^\circ C$.\(^{(1)}\)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP(^{(2)})</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{DD}$ Quiescent Power Supply</td>
<td>$V_{IN} = 0$, $R_{LOAD} = \infty$</td>
<td></td>
<td>Fixed Frequency Mode (FF)</td>
<td>13.5</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Spread Spectrum Mode (SS)</td>
<td>14.5</td>
<td>mA</td>
</tr>
<tr>
<td>$I_{SD}$ Shutdown Current(^{(3)})</td>
<td>$V_{SS}^{BOOST} = V_{SS}^{AMP} = SS = FB_SEL = GND$</td>
<td>0.11</td>
<td>1</td>
<td>$\mu A$</td>
<td></td>
</tr>
<tr>
<td>$V_{IH}$ Logic Voltage Input High</td>
<td></td>
<td>1.4</td>
<td>$V$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{IL}$ Logic Voltage Input Low</td>
<td></td>
<td>0.4</td>
<td>$V$</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$T_{WU}$ Wake-up Time</td>
<td>$C_{SS} = 0.1, \mu F$</td>
<td>49</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{OS}$ Output Offset Voltage</td>
<td>See (^{(4)})</td>
<td>0.01</td>
<td>3</td>
<td>$mV$</td>
<td></td>
</tr>
</tbody>
</table>

### Output Power

<table>
<thead>
<tr>
<th>$P_O$</th>
<th>Output Power</th>
<th>$R_L = 8, \Omega$, $BW = 22, kHz$, $THD+N = 1%$</th>
<th>FF</th>
<th>3</th>
<th>W</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>$f = 1, kHz$, $BW = 22, kHz$, $THD+N = 10%$</td>
<td>SS</td>
<td>2.6</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$R_L = 4, \Omega$, $BW = 22, kHz$</td>
<td>FF</td>
<td>3.8</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$f = 1, kHz$, $BW = 22, kHz$, $THD+N = 1%$</td>
<td>SS</td>
<td>3.8</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$R_L = 4, \Omega$, $BW = 22, kHz$</td>
<td>FF</td>
<td>5.4</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$f = 1, kHz$, $BW = 22, kHz$, $THD+N = 10%$</td>
<td>SS</td>
<td>5.4</td>
<td>W</td>
</tr>
</tbody>
</table>

### Total Harmonic Distortion + Noise

| $P_O = 2\, W$, $f = 1\, kHz$, $R_L = 8\, \Omega$ | FF | 0.03% |
| $P_O = 3\, W$, $f = 1\, kHz$, $R_L = 4\, \Omega$ | FF | 0.04% |

### Output Noise

| $f = 20\, Hz$ to $20\, kHz$, Inputs to AC GND, No weighting | FF | 32 $\mu V_{RMS}$ |
| $f = 20\, Hz$ to $20\, kHz$, Inputs to AC GND, A weighted | SS | 32 $\mu V_{RMS}$ |

### Power Supply Rejection Ratio (Input Referred)

| $V_{RIPPLE} = 200\, mV_{P-P}$, Sine, $f_{RIPPLE} = 217\, Hz$ | FF | 88 $dB$ |
| $V_{RIPPLE} = 200\, mV_{P-P}$, Sine, $f_{RIPPLE} = 1\, kHz$ | SS | 87 $dB$ |
| $V_{RIPPLE} = 200\, mV_{P-P}$, Sine, $f_{RIPPLE} = 10\, kHz$ | FF | 88 $dB$ |

### Common-Mode Rejection Ratio (Input Referred)

| $V_{RIPPLE} = 1\, V_{P-P}$, $f_{RIPPLE} = 217\, Hz$ | FF | 73 $dB$ |

### Efficiency

| $f = 1\, kHz$, $R_L = 8\, \Omega$, $P_O = 1\, W$ | 80% |

### Feedback Pin Reference Voltage\(^{(5)}\)

| $\eta$ | 1.23 | $V$ |

---

\(^{(1)}\) $R_L$ is a resistive load in series with two inductors to simulate an actual speaker load for $R_L = 8\, \Omega$, the load is $15\, \mu H + 8\, \Omega + 15\, \mu H$. For $R_L = 4\, \Omega$, the load is $15\, \mu H + 4\, \Omega + 15\, \mu H$.

\(^{(2)}\) Typical values represent most likely parametric norms at $T_A = +25^\circ C$, and at the Recommended Operation Conditions at the time of product characterization and are not specified.

\(^{(3)}\) Shutdown current is measured with components R1 and R2 removed.

\(^{(4)}\) Offset voltage is determined by: $(I_{DD} \text{ (with load)} - I_{DD} \text{ (no load)}) \times R_L$.

\(^{(5)}\) Feedback pin reference voltage is measured with the Audio Amplifier disconnected from the Boost converter (the Boost converter is unloaded).
6.6 Electrical Characteristics V\textsubscript{DD} = 3.6 V

The following specifications apply for V\textsubscript{DD} = 3.6 V, PV1 = 7 V (continuous mode), AV = 2 V/V, R\textsubscript{3} = 25.5 k\Omega, R\textsubscript{L} = 8 \Omega, f = 1 kHz, SS/FF = GND, unless otherwise specified. Limits apply for T\textsubscript{A} = 25ºC.\(^{(1)}\)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP(^{(2)})</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>I\textsubscript{DD} (1)</td>
<td>Quiescent Power Supply Current</td>
<td>V\textsubscript{IN} = 0, R\textsubscript{LOAD} = \infty</td>
<td>Fixed Frequency Mode (FF)</td>
<td>16</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Spread Spectrum Mode (SS)</td>
<td>17.5</td>
<td>26.6</td>
</tr>
<tr>
<td>I\textsubscript{SD} (3)</td>
<td>Shutdown Current</td>
<td>V\textsubscript{SD_BOOST} = V\textsubscript{SD_AMP} = SS = FB_SEL = GND</td>
<td>0.03</td>
<td>1</td>
<td>\mu A</td>
</tr>
<tr>
<td>V\textsubscript{IH}</td>
<td>Logic Voltage Input High</td>
<td></td>
<td>1.4</td>
<td>0.96</td>
<td>V</td>
</tr>
<tr>
<td>V\textsubscript{IL}</td>
<td>Logic Voltage Input Low</td>
<td></td>
<td>0.4</td>
<td>0.84</td>
<td>V</td>
</tr>
<tr>
<td>T\textsubscript{WU}</td>
<td>Wake-up Time</td>
<td>C\textsubscript{SS} = 0.1 \mu F</td>
<td>See (^{(4)})</td>
<td>50</td>
<td>ms</td>
</tr>
<tr>
<td>V\textsubscript{OS}</td>
<td>Output Offset Voltage</td>
<td>See (^{(4)})</td>
<td>0.04</td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>P\textsubscript{O} (4)</td>
<td>Output Power</td>
<td>R\textsubscript{L} = 8 \Omega, f = 1 kHz, BW = 22 kHz, THD+N = 1%</td>
<td>FF</td>
<td>2.5</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>2.5</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FF</td>
<td>3</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FF</td>
<td>4.3</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>4.2</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>FF</td>
<td>5.4</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>5.3</td>
<td></td>
</tr>
<tr>
<td>THD+N (3)</td>
<td>Total Harmonic Distortion + Noise</td>
<td>P\textsubscript{O} = 1.5 W, f = 1 kHz, R\textsubscript{L} = 8 \Omega</td>
<td>FF</td>
<td>0.03%</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>0.03%</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>P\textsubscript{O} = 3 W, f = 1 kHz, R\textsubscript{L} = 4 \Omega</td>
<td>FF</td>
<td>0.04%</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>0.05%</td>
<td></td>
</tr>
<tr>
<td>\varepsilon\textsubscript{OS}</td>
<td>Output Noise</td>
<td>f = 20 Hz to 20 kHz Inputs to AC GND, No weighting</td>
<td>FF</td>
<td>35</td>
<td>\mu V\textsubscript{RMS}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>36</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>f = 20 Hz to 20 kHz Inputs to AC GND, A weighted</td>
<td>FF</td>
<td>25</td>
<td>\mu V\textsubscript{RMS}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>26</td>
<td></td>
</tr>
<tr>
<td>PSRR (5)</td>
<td>Power Supply Rejection Ratio (Input Referred)</td>
<td>V\textsubscript{RIPPLE} = 200 mV\textsubscript{P-P} Sine, f\textsubscript{RIPPLE} = 217 Hz</td>
<td>FF</td>
<td>85</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>86</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>V\textsubscript{RIPPLE} = 200 mV\textsubscript{P-P} Sine, f\textsubscript{RIPPLE} = 1 kHz</td>
<td>FF</td>
<td>87</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>86</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>V\textsubscript{RIPPLE} = 200 mV\textsubscript{P-P} Sine, f\textsubscript{RIPPLE} = 10 kHz</td>
<td>FF</td>
<td>78</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>77</td>
<td></td>
</tr>
<tr>
<td>CMRR (6)</td>
<td>Common-Mode Rejection Ratio (Input Referred)</td>
<td>V\textsubscript{RIPPLE} = 1 V\textsubscript{P-P}, f\textsubscript{RIPPLE} = 217 Hz</td>
<td>FF</td>
<td>73</td>
<td>dB</td>
</tr>
<tr>
<td>\eta</td>
<td>Efficiency</td>
<td>f = 1 kHz, R\textsubscript{L} = 8 \Omega, P\textsubscript{O} = 1 W</td>
<td></td>
<td>77%</td>
<td></td>
</tr>
<tr>
<td>V\textsubscript{FB}</td>
<td>Feedback Pin Reference Voltage</td>
<td></td>
<td>1.23</td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>

\(^{(1)}\) R\textsubscript{L} is a resistive load in series with two inductors to simulate an actual speaker load for R\textsubscript{L} = 8\Omega, the load is 15\mu H+8\Omega+15\mu H. For R\textsubscript{L} = 4 \Omega, the load is 15 \mu H + 4 \Omega + 15 \mu H.

\(^{(2)}\) Typical values represent most likely parametric norms at T\textsubscript{A} = +25ºC, and at the Recommended Operation Conditions at the time of product characterization and are not specified.

\(^{(3)}\) Shutdown current is measured with components R1 and R2 removed.

\(^{(4)}\) Offset voltage is determined by: (I\textsubscript{DD \text{with load}} − I\textsubscript{DD \text{no load}}) x R\textsubscript{L}.

\(^{(5)}\) Feedback pin reference voltage is measured with the Audio Amplifier disconnected from the Boost converter (the Boost converter is unloaded).
6.7 Electrical Characteristics \( V_{DD} = 3 \) V

The following specifications apply for \( V_{DD} = 3 \) V, \( PV1 = 4.8 \) V (continuos mode), \( AV = 2 \) V/V, \( R_3 = 25.5 \) k\( \Omega \), \( R_{LS} = 9.31 \) k\( \Omega \), \( R_L = 8 \) \( \Omega \), \( f = 1 \) kHz, \( SS/FF = \) GND, unless otherwise specified. Limits apply for \( T_A = 25^\circ \)C. \(^{(1)}\)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP(^{(2)})</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_{DD} )</td>
<td>Quiescent Power Supply Current</td>
<td>( V_{IN} = 0, R_{LOAD} = \infty )</td>
<td>Fixed Frequency Mode (FF)</td>
<td>9</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Spread Spectrum Mode (SS)</td>
<td>9.5</td>
<td>mA</td>
</tr>
<tr>
<td>( I_{SD} )</td>
<td>Shutdown Current (^{(3)})</td>
<td>( V_{SD_BOOST} = V_{SD_AMP} = SS = FB_SEL = ) GND</td>
<td>0.01</td>
<td>1</td>
<td>( \mu )A</td>
</tr>
<tr>
<td>( V_{IH} )</td>
<td>Logic Voltage Input High</td>
<td></td>
<td></td>
<td>0.91</td>
<td>V</td>
</tr>
<tr>
<td>( V_{IL} )</td>
<td>Logic Voltage Input Low</td>
<td></td>
<td></td>
<td>0.79</td>
<td>V</td>
</tr>
<tr>
<td>( T_{WU} )</td>
<td>Wake-up Time</td>
<td>( C_{SS} = 0.1 \mu F )</td>
<td>49</td>
<td>ms</td>
<td></td>
</tr>
<tr>
<td>( V_{OS} )</td>
<td>Output Offset Voltage (^{(4)})</td>
<td></td>
<td></td>
<td>0.04</td>
<td>mV</td>
</tr>
<tr>
<td>( P_O )</td>
<td>Output Power</td>
<td>( R_L = 8 ) ( \Omega ), ( f = 1 ) kHz, ( BW = 22 ) kHz, ( THD+N = 1% )</td>
<td>FF</td>
<td>1</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>0.84</td>
<td>1</td>
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<td></td>
<td></td>
<td></td>
<td>( R_L = 4 ) ( \Omega ), ( f = 1 ) kHz, ( BW = 22 ) kHz, ( THD+N = 1% )</td>
<td>FF</td>
<td>2.2</td>
</tr>
<tr>
<td>( THD+N )</td>
<td>Total Harmonic Distortion + Noise</td>
<td>( P_O = 500 ) mW, ( f = 1 ) kHz, ( R_L = 8 ) ( \Omega )</td>
<td>FF</td>
<td>0.02%</td>
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<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>0.03%</td>
<td></td>
</tr>
<tr>
<td>( \varepsilon_{OS} )</td>
<td>Output Noise</td>
<td>( f = 20 ) Hz to 20kHz, inputs to AC GND, No weighting</td>
<td>FF</td>
<td>35</td>
<td>( \mu )V RMS</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>35</td>
<td>( \mu )V RMS</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( f = 20 ) Hz to 20kHz, inputs to AC GND, A weighted</td>
<td>FF</td>
<td>25</td>
<td>( \mu )V RMS</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>25</td>
<td>( \mu )V RMS</td>
</tr>
<tr>
<td>( PSRR )</td>
<td>Power Supply Rejection Ratio (Input Referred)</td>
<td>( V_{RIPPLE} = 200 ) mV, ( f_{RIPPLE} = 217 ) Hz</td>
<td>FF</td>
<td>89</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>89</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>( V_{RIPPLE} = 200 ) mV, ( f_{RIPPLE} = 1 ) kHz</td>
<td>FF</td>
<td>88</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>88</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>( V_{RIPPLE} = 200 ) mV, ( f_{RIPPLE} = 10 ) kHz</td>
<td>FF</td>
<td>78</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SS</td>
<td>78</td>
<td>dB</td>
</tr>
<tr>
<td>( CMRR )</td>
<td>Common-Mode Rejection Ratio (Input Referred)</td>
<td>( V_{RIPPLE} = 1 ) V, ( f_{RIPPLE} = 217 ) Hz</td>
<td>71</td>
<td>dB</td>
<td></td>
</tr>
<tr>
<td>( \eta )</td>
<td>Efficiency</td>
<td>( f = 1 ) kHz, ( R_L = 8 ) ( \Omega ), ( P_O = 1 ) W</td>
<td>75%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( V_{FB} )</td>
<td>Feedback Pin Reference Voltage (^{(5)})</td>
<td></td>
<td></td>
<td>1.23</td>
<td>V</td>
</tr>
</tbody>
</table>

\(^{(1)}\) \( R_L \) is a resistive load in series with two inductors to simulate an actual speaker load for \( R_L = 8 \) \( \Omega \), the load is 15\( \mu \)H+8\( \Omega \)+15\( \mu \)H. For \( R_L = 4 \) \( \Omega \), the load is 15\( \mu \)H+4\( \Omega \)+15\( \mu \)H.

\(^{(2)}\) Typical values represent most likely parametric norms at \( T_A = +25^\circ \)C, and at the Recommended Operation Conditions at the time of product characterization and are not specified.

\(^{(3)}\) Shutdown current is measured with components R1 and R2 removed.

\(^{(4)}\) Offset voltage is determined by: \( I_{DD} \) (with load) - \( I_{DD} \) (no load) \times \( R_L \).

\(^{(5)}\) Feedback pin reference voltage is measured with the Audio Amplifier disconnected from the Boost converter (the Boost converter is unloaded).

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6.8 Typical Characteristics

Figure 1. THD+N vs Frequency
\[ V_{DD} = 5 \text{ V}, R_L = 8 \Omega \]
\[ P_O = 2 \text{ W}, \text{Filter} = 22 \text{ kHz}, PV_1 = 7.8 \text{ V} \]

Figure 2. THD+N vs Frequency
\[ V_{DD} = 3.6 \text{ V}, R_L = 8 \Omega \]
\[ P_O = 500 \text{ mW}, \text{Filter} = 22 \text{ kHz}, PV_1 = 4.8 \text{ V} \]

Figure 3. THD+N vs Frequency
\[ V_{DD} = 3 \text{ V}, R_L = 8 \Omega \]
\[ P_O = 1.5 \text{ W}, \text{Filter} = 22 \text{ kHz}, PV_1 = 7 \text{ V} \]

Figure 4. THD+N vs Output Power
\[ V_{DD} = 5 \text{ V}, R_L = 8 \Omega \]
\[ P_O = 1.5 \text{ W}, f = 1 \text{ kHz}, \text{Filter} = 22 \text{ kHz}, PV_1 = 7.8 \text{ V} \]

Figure 5. THD+N vs Output Power
\[ V_{DD} = 3.6 \text{ V}, R_L = 8 \Omega \]
\[ f = 1 \text{ kHz}, \text{Filter} = 22 \text{ kHz}, PV_1 = 7 \text{ V} \]

Figure 6. THD+N vs Output Power
\[ V_{DD} = 3 \text{ V}, R_L = 8 \Omega \]
\[ f = 1 \text{ kHz}, \text{Filter} = 22 \text{ kHz}, PV_1 = 4.8 \text{ V} \]
Typical Characteristics (continued)

Figure 7. THD+N vs Output Power

\( V_{DD} = 3 \text{ V}, 3.6 \text{ V}, 5 \text{ V}, R_L = 8 \Omega \)
\( f = 1 \text{ kHz}, \text{ Filter} = 22 \text{ kHz}, R_1 = 4.87 \text{ k}\Omega, \text{ FF} \)

Figure 8. THD+N vs Output Power

\( V_{DD} = 3.6 \text{ V}, R_L = 8 \Omega \)
\( \text{ Filter} = 22 \text{ kHz}, PV_1 = 7.8 \text{ V}, PV_1 = 7 \text{ V}, PV_1 = 4.8 \text{ V}, \text{ FF} \)

Figure 9. Boost Amplifier vs Output Power

\( V_{DD} = 5 \text{ V}, R_L = 8 \Omega \)
\( f = 1 \text{ kHz}, PV_1 = 7.8 \text{ V} \)

Figure 10. Boost Amplifier vs Output Power

\( V_{DD} = 3.6 \text{ V}, R_L = 8 \Omega \)
\( f = 1 \text{ kHz}, PV_1 = 7 \text{ V} \)

Figure 11. Boost Amplifier vs Output Power

\( V_{DD} = 3 \text{ V}, R_L = 8 \Omega \)
\( f = 1 \text{ kHz}, PV_1 = 4.8 \text{ V} \)

Figure 12. PSRR vs Frequency

\( V_{DD} = 5 \text{ V}, R_L = 8 \Omega \)
\( V_{RIPPLE} = 200 \text{ mV}_{PP}, PV_1 = 7.8 \text{ V} \)
Typical Characteristics (continued)

Figure 13. PSRR vs Frequency

\[ V_{DD} = 3.6 \, \text{V}, \quad R_L = 8 \, \Omega \]
\[ V_{RIPPLE} = 200 \, \text{mV}_{pp}, \quad PV_1 = 7 \, \text{V} \]

Figure 14. PSRR vs Frequency

\[ V_{DD} = 3 \, \text{V}, \quad R_L = 8 \, \Omega \]
\[ V_{RIPPLE} = 200 \, \text{mV}_{pp}, \quad PV_1 = 4.8 \, \text{V} \]

Figure 15. Supply Current vs Supply Voltage

\[ PV_1 = 7.8 \, \text{V} \]

Figure 16. Supply Current vs Supply Voltage

\[ PV_1 = 7 \, \text{V} \]

Figure 17. Supply Current vs Supply Voltage

\[ PV_1 = 4.8 \, \text{V} \]

Figure 18. Power Dissipation vs Output Power

\[ V_{DD} = 5 \, \text{V}, \quad R_L = 8 \, \Omega \]
\[ PV_1 = 7.8 \, \text{V}, \quad \text{FF} \]
Typical Characteristics (continued)

**Figure 19. Power Dissipation vs Output Power**

\[ V_{DD} = 3.6 \, \text{V}, \, R_L = 8 \, \Omega \]
\[ PV_1 = 7 \, \text{V}, \, FF \]

**Figure 20. Power Dissipation vs Output Power**

\[ V_{DD} = 3 \, \text{V}, \, R_L = 8 \, \Omega \]
\[ PV_1 = 4.8 \, \text{V}, \, FF \]

**Figure 21. Boost Converter Efficiency vs I_{LOAD(DC)}**

\[ V_{DD} = 5 \, \text{V}, \, PV_1 = 7.8 \, \text{V} \]

**Figure 22. Boost Converter Efficiency vs I_{LOAD(DC)}**

\[ V_{DD} = 3 \, \text{V}, \, PV_1 = 7 \, \text{V} \]

**Figure 23. Boost Converter Efficiency vs I_{LOAD(DC)}**

\[ V_{DD} = 3.6 \, \text{V}, \, PV_1 = 4.8 \, \text{V} \]
7 Detailed Description

7.1 Overview

The LM48511 integrates a boost converter with a high-efficiency Class D audio power amplifier, which features a low-noise PWM architecture that eliminates the output filter, reducing external component count, board area consumption, system cost, and simplifying design. A selectable spread spectrum modulation scheme suppresses RF emissions, further reducing the need for output filters. Two selectable feedback networks allow the LM48511 regulator to dynamically switch between two different output voltages, improving efficiency by optimizing the amplifier’s supply voltage based on battery voltage and output power requirements. The gain of the LM48511 is set by external resistors, which allows independent gain control from multiple sources by summing the signals. Output short circuit and thermal overload protection prevent the device from damage during fault conditions.

7.2 Functional Block Diagram
7.3 Feature Description

7.3.1 General Amplifier Function

The LM48511 features a Class D audio power amplifier that uses a filterless modulation scheme, reducing external component count, conserving board space and reducing system cost. The outputs of the device transition from PV1 to GND with a 300-kHz switching frequency. With no signal applied, the outputs (V_{LS+} and V_{LS-}) switch with a 50% duty cycle, in phase, causing the two outputs to cancel. This cancellation results in no net voltage across the speaker, thus there is no current to the load in the idle state.

With the input signal applied, the duty cycle (pulse width) of the LM48511 outputs changes. For increasing output voltage, the duty cycle of V_{LS+} increases, while the duty cycle of V_{LS-} decreases. For decreasing output voltages, the converse occurs. The difference between the two pulse widths yields the differential output voltage.

7.3.2 Differential Amplifier Explanation

The LM48511 includes fully differential amplifier that features differential input and output stages. A differential amplifier amplifies the difference between the two input signals. Traditional audio power amplifiers have typically offered only single-ended inputs resulting in a 6dB reduction in signal to noise ratio relative to differential inputs. The LM48511 also offers the possibility of DC input coupling which eliminates the two external AC coupling, DC blocking capacitors. The LM48511 can be used, however, as a single-ended input amplifier while still retaining the fully differential benefits of the device. In fact, completely unrelated signals may be placed on the input pins. The LM48511 simply amplifies the difference between the signals. A major benefit of a differential amplifier is the improved common-mode rejection ratio (CMRR) over single input amplifiers. The common-mode rejection characteristic of the differential amplifier reduces sensitivity to ground offset related noise injection, especially important in high noise applications.

7.3.3 Audio Amplifier Power Dissipation and Efficiency

The major benefit of a Class D amplifier is increased efficiency versus a Class AB. The efficiency of the LM48511 is attributed to the region of operation of the transistors in the output stage. The Class D output stage acts as current steering switches, consuming negligible amounts of power compared to their Class AB counterparts. Most of the power loss associated with the output stage is due to the IR loss of the MOSFET ON-resistance, along with switching losses due to gate charge.

7.3.4 Regulator Power Dissipation

At higher duty cycles, the increased ON-time of the switch FET means the maximum output current will be determined by power dissipation within the LM48511 FET switch. The switch power dissipation from ON-time conduction is calculated by:

\[
P_{\text{DI(SWITCH)}} = \text{DC} \times (\text{I}_{\text{INDUCTOR(AVE)}})^2 \times R_{\text{DS(ON)}} \ (W)
\]

where

- \(\text{DC}\) is the duty cycle. \(\text{(1)}\)

7.3.5 Shutdown Function

The LM48511 features independent amplifier and regulator shutdown controls, allowing each portion of the device to be disabled or enabled independently. SD_AMP controls the Class D amplifiers, while SD_BOOST controls the regulator. Driving either inputs low disables the corresponding portion of the device, and reducing supply current.

When the regulator is disabled, both FB_GND switches open, further reducing shutdown current by eliminating the current path to GND through the regulator feedback network. Without the GND switches, the feedback resistors as shown in Figure 1 would consume an additional 165 \(\mu\)A from a 5-V supply. With the regulator disabled, there is still a current path from \(V_{DD}\), through the inductor and diode, to the amplifier power supply. This allows the amplifier to operate even when the regulator is disabled. The voltage at PV1 and V1 will be:

\[(V_{DD} - [V_D + (I_L \times DCR)])\]

Where

- \(V_D\) is the forward voltage of the Schottky diode
- \(V_D\) is the forward voltage of the Schottky diode
- \(I_L\) is the current through the inductor
Feature Description (continued)

- DCR is the DC resistance of the inductor

Additionally, when the regulator is disabled, an external voltage from 5 V to 8 V can be applied directly to PV1 and V1 to power the amplifier.

It is best to switch between ground and V_{DD} for minimum current consumption while in shutdown. The LM48511 may be disabled with shutdown voltages in between GND and V_{DD}; the idle current will be greater than the typical 0.1-µA value. Increased THD+N may also be observed when a voltage of less than V_{DD} is applied to SD_AMP.

7.3.6 Regulator Feedback Select

The LM45811 regulator features two feedback paths as shown in Figure 1, which allow the regulator to easily switch between two different output voltages. The voltage divider consists of the high side resistor, R3, and the low side resistors (R_{LS}), R1 and R2. R3 is connected to the output of the boost regulator, the mid-point of each divider is connected to FB, and the low side resistors are connected to either FB_{GND1} or FB_{GND0}. FB_SEL determines which FB_{GND} switch is closed, which in turn determines which feedback path is used. For example if FB_SEL = V_{DD}, the FB_{GND} switch is closed, while the FB_{GND0} switch remains open, creating a current path through the resistors connected to FB_{GND1}. Conversely, if FB_SEL = GND, the FB_{GND0} switch is closed, while the FB_{GND1} switch remains open, creating a current path through the resistors connected to FB_{GND0}.

FB_SEL can be susceptible to noise interference. To prevent an accidental state change, either bypass FB_SEL with a 0.1µF capacitor to GND, or connect the higher voltage feedback network to FB_{GND0}, and the lower voltage feedback network to FB_{GND1}. Because the higher output voltage configuration typically generates more noise on V_{DD}, this configuration minimizes the V_{DD} noise exposure of FB_SEL, as FB_SEL = GND for FB_{GND0} (high voltage output) and FB_SEL = V_{DD} for FB_{GND1} (low voltage output).

The selectable feedback networks maximize efficiency in two ways. In applications where the system power supply voltage changes, such as a mobile GPS receiver, that transitions from battery power, to AC line, to a car power adapter, the LM48511 can be configured to generate a lower voltage when the system power supply voltages is lower, and conversely, generate a higher voltage when the system power supply is higher. See the Setting the Regulator Output Voltage (PV1) section.

In applications where the same speaker/amplifier combination is used for different purposes with different audio power requirements, such as a cell phone ear piece/speaker phone speaker, the ability to quickly switch between two different voltages allows for optimization of the amplifier power supply, increasing overall system efficiency. When audio power demands are low (ear piece mode) the regulator output voltage can be set lower, reducing quiescent current consumption. When audio power demands increase (speaker phone mode), a higher voltage increases the amplifier headroom, increasing the audio power delivered to the speaker.

7.4 Device Functional Modes

The LM48511 features two modulations schemes, a fixed frequency mode (FF) and a spread spectrum mode (SS).

7.4.1 Fixed Frequency

Select the fixed frequency mode by setting SS/FF = GND. In fixed frequency mode, the amplifier outputs switch at a constant 300 kHz. In fixed frequency mode, the output spectrum consists of the fundamental and its associated harmonics (see Typical Characteristics).

7.4.2 Spread Spectrum Mode

Set SS/FF = VDD for spread spectrum mode. The logic selectable spread spectrum mode eliminates the need for output filters, ferrite beads or chokes. In spread spectrum mode, the switching frequency varies randomly by 10% about a 330-kHz center frequency, reducing the wideband spectral contend, improving EMI emissions radiated by the speaker and associated cables and traces. Where a fixed frequency class D exhibits large amounts of spectral energy at multiples of the switching frequency, the spread spectrum architecture of the LM48511 spreads that energy over a larger bandwidth (see Typical Characteristics). The cycle-to-cycle variation of the switching period does not affect the audio reproduction, efficiency, or PSRR.
8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LM48511 integrates a boost converter with a high-efficiency Class D audio power amplifier, which uses a filterless modulation scheme, reducing external component count, board area consumption and system cost. The major benefit of a Class D amplifier is increased efficiency versus a Class AB. The LM48511 regulator has two selectable feedback paths, which allow the regulator to dynamically switch between two different output voltages easily. In addition, the LM48511 regulator features two different switching modes, improving light load efficiency by minimizing losses due to MOSFET gate charge. The amplifier gain of the LM48511 is set by four external resistors. Careful matching of those resistor pairs is required for optimum performance.

8.2 Typical Application

Typical LM48511 Audio Amplifier Application Circuit
Typical Application (continued)

8.2.1 Design Requirements

Table 1 lists the design parameters for this example.

Table 1. Design Parameters

<table>
<thead>
<tr>
<th>PARAMETERS</th>
<th>VALUES</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage range</td>
<td>3.0 V to 5.5 V</td>
</tr>
<tr>
<td>Amplifier range</td>
<td>4.8 V to 8 V</td>
</tr>
<tr>
<td>Temperature range</td>
<td>–40°C to 85°C</td>
</tr>
</tbody>
</table>

8.2.2 Detailed Design Procedure

8.2.2.1 Proper Selection of External Components

Proper selection of external components in applications using integrated power amplifiers, and switching DC-DC converters, is critical for optimizing device and system performance. Consideration to component values must be used to maximize overall system quality. The best capacitors for use with the switching converter portion of the LM48511 are multi-layer ceramic capacitors. They have the lowest ESR (equivalent series resistance) and highest resonance frequency, which makes them optimum for high-frequency switching converters. When selecting a ceramic capacitor, only X5R and X7R dielectric types must be used. Other types such as Z5U and Y5F have such severe loss of capacitance due to effects of temperature variation and applied voltage, they may provide as little as 20% of rated capacitance in many typical applications. Always consult capacitor manufacturer’s data curves before selecting a capacitor. High-quality ceramic capacitors can be obtained from Taiyo-Yuden and Murata.

8.2.2.2 Power Supply Bypassing

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both PV1, V1 and V_DD pins must be as close to the device as possible.

8.2.2.3 Audio Amplifier Gain Setting Resistor Selection

The amplifier gain of the LM48511 is set by four external resistors, the input resistors, R5 and R7, and the feedback resistors R6 and R8. The amplifier gain is given by:

\[ A_{VD} = 2 \times R_F / R_IN \]  
(3)

Careful matching of the resistor pairs, R6 and R8, and R5 and R7, is required for optimum performance. Any mismatch between the resistors results in a differential gain error that leads to an increase in THD+N, decrease in PSRR and CMRR, as well as an increase in output offset voltage. Resistors with a tolerance of 1% or better are recommended.

The gain setting resistors must be placed as close to the device as possible. Keeping the input traces close together and of the same length increases noise rejection in noisy environments. Noise coupled onto the input traces which are physically close to each other will be common mode and easily rejected.

8.2.2.4 Audio Amplifier Input Capacitor Selection

Input capacitors may be required for some applications, or when the audio source is single-ended. Input capacitors block the DC component of the audio signal, eliminating any conflict between the DC component of the audio source and the bias voltage of the LM48511. The input capacitors create a highpass filter with the input resistors R_IN. The -3dB point of the highpass filter is found by:

\[ f = 1 / 2\pi R_IN C_IN \]  
(4)

In single-ended configurations, the input capacitor value affects click-and-pop performance. The LM48511 features a 50-mg turnon delay. Choose the input capacitor / input resistor values such that the capacitor is charged before the 50-ms turnon delay expires. A capacitor value of 0.18 μF and a 20-kΩ input resistor are recommended. In differential applications, the charging of the input capacitor does not affect click-and-pop significantly.
The input capacitors can also be used to remove low-frequency content from the audio signal. Highpass filtering the audio signal helps protect speakers that can not reproduce or may be damaged by low frequencies. When the LM48511 is using a single-ended source, power supply noise on the ground is seen as an input signal. Setting the highpass filter point above the power supply noise frequencies, 217 Hz in a GSM phone, for example, filters out the noise such that it is not amplified and heard on the output. Capacitors with a tolerance of 10% or better are recommended for impedance matching and improved CMRR and PSRR.

8.2.2.5 Selecting Regulator Output Capacitor

A single 100-µF low ESR tantalum capacitor provides sufficient output capacitance for most applications. Higher capacitor values improve line regulation and transient response. Typical electrolytic capacitors are not suitable for switching converters that operate above 500 kHz because of significant ringing and temperature rise due to self-heating from ripple current. An output capacitor with excessive ESR reduces phase margin and causes instability.

8.2.2.6 Selecting Regulating Bypass Capacitor

A supply bypass capacitor is required to serve as an energy reservoir for the current which must flow into the coil each time the switch turns on. This capacitor must have extremely low ESR, so ceramic capacitors are the best choice. A nominal value of 10 µF is recommended, but larger values can be used. Because this capacitor reduces the amount of voltage ripple seen at the input pin, it also reduces the amount of EMI passed back along that line to other circuitry.

8.2.2.7 Selecting the Soft-Start (C_{SS}) Capacitor

The soft-start function charges the boost converter reference voltage slowly. This allows the output of the boost converter to ramp up slowly thus limiting the transient current at start-up. Selecting a soft-start capacitor (C_{SS}) value presents a trade off between the wake-up time and the start-up transient current. Using a larger capacitor value will increase wake-up time and decrease start-up transient current while the opposite effect happens with a smaller capacitor value. A general guideline is to use a capacitor value 1000 times smaller than the output capacitance of the boost converter (C2). A 0.1-uF soft-start capacitor is recommended for a typical application.

Table 2 shows the relationship between C_{SS} start-up time and surge current.

<table>
<thead>
<tr>
<th>C_{SS} (µF)</th>
<th>BOOST SET-UP TIME (ms)</th>
<th>INPUT SURGE CURRENT (mA)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>5.1</td>
<td>330</td>
</tr>
<tr>
<td>0.22</td>
<td>10.5</td>
<td>255</td>
</tr>
<tr>
<td>0.47</td>
<td>21.7</td>
<td>220</td>
</tr>
</tbody>
</table>

(1) V_{DD} = 5 V, PV1 = 7.8 V (continuous mode)

8.2.2.8 Selecting Diode (D1)

Use a Schottkey diode, as shown in Figure 1. A 30-V diode such as the DFLS230LH from Diodes Incorporated is recommended. The DFLS230LH diodes are designed to handle a maximum average current of 2 A.

8.2.2.9 Duty Cycle

The maximum duty cycle of the boost converter determines the maximum boost ratio of output-to-input voltage that the converter can attain in continuous mode of operation. The duty cycle for a given boost application is defined by:

\[
\text{Duty Cycle} = \frac{(PV1 + V_D - V_{DD})}{(PV1 + V_D - V_{SW})}
\]

This applies for continuous mode operation.
8.2.2.10 Selecting Inductor Value

Inductor value involves trade-offs in performance. Larger inductors reduce inductor ripple current, which typically means less output voltage ripple (for a given size of output capacitor). Larger inductors also mean more load power can be delivered because the energy stored during each switching cycle is:

\[ E = \frac{L}{2} \times (I_p)^2 \]

Where

- \( I_p \) is the peak inductor current

The LM48511 will limit its switch current based on peak current. With \( I_p \) fixed, increasing \( L \) will increase the maximum amount of power available to the load. Conversely, using too little inductance may limit the amount of load current which can be drawn from the output. Best performance is usually obtained when the converter is operated in “continuous” mode at the load current range of interest, typically giving better load regulation and less output ripple. Continuous operation is defined as not allowing the inductor current to drop to zero during the cycle. Boost converters shift over to discontinuous operation if the load is reduced far enough, but a larger inductor stays continuous over a wider load current range.

8.2.2.11 Inductor Supplies

The recommended inductor for the LM48511 is the IHLP-2525CZ-01 from Vishay Dale. When selecting an inductor, the continuous current rating must be high enough to avoid saturation at peak currents. A suitable core type must be used to minimize switching losses, and DCR losses must be considered when selecting the current rating. Use shielded inductors in systems that are susceptible to RF interference.

8.2.2.12 Setting the Regulator Output Voltage (PV1)

The output voltage of the regulator is set through one of two external resistive voltage-dividers (R3 in combination with either R1 or R2) connected to FB (Figure 1). The resistor, R4 is only for compensation purposes and does not affect the regulator output voltage. The regulator output voltage is set by the following equation:

\[ PV1 = V_{FB} \times \left[ 1 + \frac{R3}{R_{LS}} \right] \]

Where

- \( V_{FB} \) is 1.23 V, and \( R_{LS} \) is the low side resistor (R1 or R2)

To simplify resistor selection:

\[ R_{LS} = \frac{R3 \times V_{FB}}{PV1 - V_{FB}} \]

A value of approximately 25.5 kΩ is recommended for R3.

The quiescent current of the boost regulator is directly related to the difference between its input and output voltages, the larger the difference, the higher the quiescent current. For improved power consumption the following regulator input/output voltage combinations are recommended:

<table>
<thead>
<tr>
<th>( V_{DD} ) (V)</th>
<th>PV1 (V)</th>
<th>R3 (kΩ)</th>
<th>R_{LS} (kΩ)</th>
<th>P_{OUT} \text{ into } 8 \Omega (W)</th>
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</thead>
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<tr>
<td>3.0</td>
<td>4.8</td>
<td>25.5</td>
<td>9.31</td>
<td>1</td>
</tr>
<tr>
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<td>7.1</td>
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<td>5.35</td>
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<tr>
<td>5</td>
<td>7.8</td>
<td>25.5</td>
<td>4.87</td>
<td>3</td>
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</tbody>
</table>

(1) The values of PV1 are for continuous mode operation.

For feedback path selection, see Regulator Feedback Select.

8.2.2.13 Discontinuous and Continuous Operation

The LM48511 regulator features two different switching modes. Under light-load conditions, the regulator operates in a variable frequency, discontinuous, pulse-skipping mode, that improves light load efficiency by minimizing losses due to MOSFET gate charge. Under heavy loads, the LM48511 regulator automatically switches to a continuous, fixed-frequency PWM mode, improving load regulation. In discontinuous mode, the regulator output voltage is typically 400 mV higher than the expected (calculated) voltage in continuous mode.
8.2.2.14  $I_{SW}$ Feed-Forward Compensation for Boost Converter

Although the LM48511 regulator is internally compensated, an external feed-forward capacitor, (C1) may be required for stability. The compensation capacitor places a zero in regulator loop response. The recommended frequency of the zero ($f_z$) is 22.2 kHz. The value of C1 is given by:

$$ C_1 = \frac{1}{2\pi R_3 f_z} \quad (9) $$

In addition to C1, a compensation resistor, R4 is required to cancel the zero contributed by the ESR of the regulator output capacitor. Calculate the zero frequency of the output capacitor by:

$$ f_{CO} = \frac{1}{2\pi R_{CO} C_O} \quad (10) $$

where

• $R_{CO}$ is the ESR of the output capacitor

The value of $R_{FB3}$ is given by:

$$ R_4 = \frac{1}{2\pi f_{CO} C_1} \quad (11) $$

8.2.2.15 Calculating Regulator Output Current

The load current of the boost converter is related to the average inductor current by the relation:

$$ I_{AMP} = I_{INDUCTOR(AVE)} \times (1 – DC) \quad (A) $$

where

• DC is the duty cycle of the application

The switch current can be found by:

$$ I_{SW} = I_{INDUCTOR(AVE)} + \frac{1}{2} (I_{RIPPLE}) \quad (A) $$

Inductor ripple current is dependent on inductance, duty cycle, supply voltage and frequency:

$$ I_{RIPPLE} = DC \times (V_{DD} – V_{SW}) / (f \times L) \quad (A) $$

where

• $f$ = switching frequency = 1MHz

Combining all terms, we can develop an expression which allows the maximum available load current to be calculated:

$$ I_{AMP(max)} = (1–DC) \times \frac{[I_{SW(max)}– DC (V – V_{SW})]}{2fL} \quad (A) \quad (15) $$

The equation shown to calculate maximum load current takes into account the losses in the inductor or turnoff switching losses of the FET and diode.

8.2.2.16 Design Parameters $V_{SW}$ and $I_{SW}$

The value of the FET "ON" voltage (referred to as $V_{SW}$ in Equation 9 thru Equation 12) is dependent on load current. A good approximation can be obtained by multiplying the ON-resistance ($R_{DS(ON)}$) of the FET times the average inductor current. The maximum peak switch current the device can deliver is dependent on duty cycle.
8.2.3 Application Curve

Figure 24. $V_{DD}$ vs $P_{OUT}$, $I_{DD}$, and Efficiency With 4-Ω Load
9 Power Supply Recommendations

The devices are designed to operate from an input supply voltage (VDD) operating range from 3 V to 5.5 V, but the absolute maximum rating is 9 V.

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both PV1, V1 and VDD pins must be as close to the device as possible.

10 Layout

10.1 Layout Guidelines

This section provides general practical guidelines for PCB layouts that use various power and ground traces. Designers must note that these are only rule-of-thumb recommendations and the actual results are predicated on the final layout.

10.1.1 Power and Ground Circuits

Star trace routing techniques can have a major positive impact on low-level signal performance. Star trace routing refers to using individual traces that radiate from a signal point to feed power and ground to each circuit or even device.

10.1.2 Layout Helpful Hints

- Avoid routing traces under the inductor.
- Use three separate grounds that eventually connect to one point:
  - Signal or quiet ground (GND)
  - Ground for the LM48511 device (LSGND)
  - SW (REGGND) (switch ground). This trace for the switch ground carries the heaviest current (3 A) and therefore is the noisiest. Make this trace as wide and short as possible and keep at a distance from the quiet ground and device ground. Give distance priority to the quiet ground.

10.2 Layout Example

![Figure 25. Layout Example](image-url)
11 Device and Documentation Support

11.1 Community Resources
The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.2 Trademarks
E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.3 Electrostatic Discharge Caution
These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.4 Glossary
**SLYZ022 — TI Glossary.**
This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information
The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
## PACKAGING INFORMATION

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<th>Orderable Device</th>
<th>Status</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan</th>
<th>Lead/Ball Finish</th>
<th>MSL Peak Temp</th>
<th>Op Temp (°C)</th>
<th>Device Marking</th>
<th>Samples</th>
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<td>WQFN</td>
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<td>1000</td>
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<td>Level-1-260C-UNLIM</td>
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<td>-40 to 85</td>
<td>48511SQ</td>
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(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check [http://www.ti.com/productcontent](http://www.ti.com/productcontent) for the latest availability information and additional product content details.
- **TBD:** The Pb-Free/Green conversion plan has not been defined.
- **Pb-Free (RoHS):** TI terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
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- **Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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<th>B0 (mm)</th>
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*All dimensions are nominal.*
### TAPE AND REEL BOX DIMENSIONS

*All dimensions are nominal*

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<th>Package Type</th>
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