LM4990 Boomer® Audio Power Amplifier Series 2 Watt Audio Power Amplifier with Selectable
Shutdown Logic Level

Check for Samples: LM4990

FEATURES
- Available in Space-Saving Packages: WSON, Exposed-DAP MSOP-PowerPAD, VSSOP, and DSBGA
- Ultra Low Current Shutdown Mode
- Improved Click and Pop Circuitry Eliminates Noise During Turn-On and Turn-Off Transitions
- 2.2 - 5.5V Operation
- No Output Coupling Capacitors, Snubber Networks or Bootstrap Capacitors Required
- Unity-Gain Stable
- External Gain Configuration Capability
- User Selectable Shutdown High or Low Logic Level

APPLICATIONS
- Mobile Phones
- PDAs
- Portable Electronic Devices

KEY SPECIFICATIONS
- Improved PSRR at 217Hz & 1KHz: 62dB
- Power Output at 5.0V, 1% THD+N,
  - 4Ω (NGZ and DGQ only): 2W (Typ)
- Power Output at 5.0V, 1% THD+N, 8Ω: 1.25W (Typ)
- Power Output at 3.0V, 1% THD+N, 4Ω: 600mW (Typ)
- Power Output at 3.0V, 1% THD+N, 8Ω: 425mW (Typ)
- Shutdown Current: 0.1µA (Typ)

DESCRIPTION
The LM4990 is an audio power amplifier primarily designed for demanding applications in mobile phones and other portable communication device applications. It is capable of delivering 1.25 watts of continuous average power to an 8Ω BTL load and 2 watts of continuous average power (NGZ and DGQ only) to a 4Ω BTL load with less than 1% distortion (THD+N+N) from a 5VDC power supply.

Boomer audio power amplifiers were designed specifically to provide high quality output power with a minimal amount of external components. The LM4990 does not require output coupling capacitors or bootstrap capacitors, and therefore is ideally suited for mobile phone and other low voltage applications where minimal power consumption is a primary requirement.

The LM4990 features a low-power consumption shutdown mode. To facilitate this, Shutdown may be enabled by either logic high or low depending on mode selection. Driving the shutdown mode pin either high or low enables the shutdown pin to be driven in a likewise manner to enable shutdown.

The LM4990 contains advanced pop & click circuitry which eliminates noise which would otherwise occur during turn-on and turn-off transitions.

The LM4990 is unity-gain stable and can be configured by external gain-setting resistors.

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Connection Diagram

![Connection Diagram](image)

**Figure 1. VSSOP Package – Top View**
See Package Number DGK

**Figure 2. WSON Package – Top View**
See Package Number NGZ0010B

**Figure 3. Exposed-DAP MSOP-PowerPAD Package – Top View**
See Package Number DGQ

**Figure 4. 9-Bump DSBGA (Top View)**
See Package Number YZR0009

<table>
<thead>
<tr>
<th>Package</th>
<th>NGZ</th>
<th>DGQ</th>
<th>DGK</th>
<th>YZR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Shutdown Mode</td>
<td>Selectable</td>
<td>Selectable</td>
<td>Low</td>
<td>Low</td>
</tr>
<tr>
<td>Typical Power Output at 5V, 1% THD+N</td>
<td>2W ($R_L = 4\Omega$)</td>
<td>2W ($R_L = 4\Omega$)</td>
<td>1.25W ($R_L = 8\Omega$)</td>
<td>1.25W ($R_L = 8\Omega$)</td>
</tr>
</tbody>
</table>
Typical Application

Note: DGK and YZR packaged devices are active low only; Shutdown Mode pin is internally tied to GND.

Figure 5. Typical Audio Amplifier Application Circuit (NGZ and DGQ)

Figure 6. Typical Audio Amplifier Application Circuit (YZR and DGK)
These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### Absolute Maximum Ratings

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Absolute Maximum Ratings (1)(2)</td>
<td></td>
</tr>
<tr>
<td>Supply Voltage (3)</td>
<td>6.0V</td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>−65°C to +150°C</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>−0.3V to VDD +0.3V</td>
</tr>
<tr>
<td>Power Dissipation (4)(5)</td>
<td>Internally Limited</td>
</tr>
<tr>
<td>ESD Susceptibility (6)</td>
<td>2000V</td>
</tr>
<tr>
<td>ESD Susceptibility (7)</td>
<td>200V</td>
</tr>
<tr>
<td>Junction Temperature</td>
<td>150°C</td>
</tr>
<tr>
<td>Thermal Resistance</td>
<td></td>
</tr>
<tr>
<td>θJC (VSSOP)</td>
<td>56°C/W</td>
</tr>
<tr>
<td>θJA (VSSOP)</td>
<td>190°C/W</td>
</tr>
<tr>
<td>θJA (9 Bump DSBGA) (8)</td>
<td>180°C/W</td>
</tr>
<tr>
<td>θJA (WSON)</td>
<td>63°C/W (9)</td>
</tr>
<tr>
<td>θIC (WSON)</td>
<td>12°C/W (9)</td>
</tr>
</tbody>
</table>

Soldering Information: See the AN-1187 Application Report

1. Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional but specific performance is not ensured. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.

2. If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

3. If the product is in Shutdown mode and VDD exceeds 6V (to a max of 8V VDD), then most of the excess current will flow through the ESD protection circuits. If the source impedance limits the current to a max of 10mA, then the device will be protected. If the device is enabled when VDD is greater than 5.5V and less than 6.5V, no damage will occur, although operation life will be reduced. Operation above 6.5V with no current limit will result in permanent damage.

4. The maximum power dissipation must be derated at elevated temperatures and is dictated by T_JMAX, θJA, and the ambient temperature T_A. The maximum allowable power dissipation is P_{DMAX} = (T_{JMAX}−T_A)/θJA or the number given in Absolute Maximum Ratings, whichever is lower. For the LM4990, see power derating curves for additional information.

5. Maximum power dissipation in the device (P_{DMAX}) occurs at an output power level significantly below full output power. P_{DMAX} can be calculated using Equation 1 shown in the Application Information section. It may also be obtained from the power dissipation graphs.

6. Human body model, 100pF discharged through a 1.5kΩ resistor.


8. All bumps have the same thermal resistance and contribute equally when used to lower thermal resistance. All bumps must be connected to achieve specified thermal resistance.

9. The Exposed-DAP of the NGZ0010B package should be electrically connected to GND or an electrically isolated copper area. the LM4990LD demo board has the Exposed-DAP connected to GND with a PCB area of 86.7mils x 585mils (2.02mm x 14.86mm) on the copper top layer and 550mils x 710mils (13.97mm x 18.03mm) on the copper bottom layer.

### Operating Ratings

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature Range</td>
<td>T_{MIN} ≤ T_A ≤ T_{MAX}</td>
</tr>
<tr>
<td></td>
<td>−40°C ≤ T_A ≤ 85°C</td>
</tr>
<tr>
<td>Supply Voltage</td>
<td>2.2V ≤ VDD ≤ 5.5V</td>
</tr>
</tbody>
</table>
**Electrical Characteristics $V_{DD} = 5V^{(1)(2)}$**

The following specifications apply for the circuit shown in Figure 1, unless otherwise specified. Limits apply for $T_A = 25^\circ C$.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>LM4990</th>
<th>Units (Limits)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{DD}$</td>
<td>Quiescent Power Supply Current</td>
<td>$V_{IN} = 0V$, $I_{O} = 0A$, No Load</td>
<td>3</td>
<td>mA (max)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$V_{IN} = 0V$, $I_{O} = 0A$, $8\Omega$ Load</td>
<td>4</td>
<td>mA (max)</td>
</tr>
<tr>
<td>$I_{SD}$</td>
<td>Shutdown Current</td>
<td>$V_{SD} = V_{SD\ Mode}^{(6)}$</td>
<td>0.1</td>
<td>$\mu A$ (max)</td>
</tr>
<tr>
<td>$V_{SDH}$</td>
<td>Shutdown Voltage Input High</td>
<td>$V_{SD\ MODE} = V_{DD}$</td>
<td>1.5</td>
<td>V</td>
</tr>
<tr>
<td>$V_{SDLH}$</td>
<td>Shutdown Voltage Input Low</td>
<td>$V_{SD\ MODE} = V_{DD}$</td>
<td>1.3</td>
<td>V</td>
</tr>
<tr>
<td>$V_{SDH}$</td>
<td>Shutdown Voltage Input High</td>
<td>$V_{SD\ MODE} = GND$</td>
<td>1.5</td>
<td>V</td>
</tr>
<tr>
<td>$V_{SDLH}$</td>
<td>Shutdown Voltage Input Low</td>
<td>$V_{SD\ MODE} = GND$</td>
<td>1.3</td>
<td>V</td>
</tr>
<tr>
<td>$V_{OS}$</td>
<td>Output Offset Voltage</td>
<td></td>
<td>7</td>
<td>50 mV (max)</td>
</tr>
<tr>
<td>$R_{OUT}$</td>
<td>Resistor Output to GND$^{(7)}$</td>
<td></td>
<td>8.5</td>
<td>9.7 k$\Omega$ (max)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>7.0 k$\Omega$ (min)</td>
</tr>
<tr>
<td>$P_o$</td>
<td>Output Power</td>
<td>$THD+N = 1%$ (max); $f = 1kHz$</td>
<td>1.25</td>
<td>W (min)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>($4\Omega$)$^{(8)(9)}$</td>
<td>2</td>
<td>W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>($8\Omega$)</td>
<td>0.9</td>
<td>W</td>
</tr>
<tr>
<td>$T_{WU}$</td>
<td>Wake-up time</td>
<td></td>
<td>100</td>
<td>ms</td>
</tr>
<tr>
<td>$THD+N +N$</td>
<td>Total Harmonic Distortion+Noise</td>
<td>$P_o = 0.5W$; $f = 1kHz$</td>
<td>0.2</td>
<td>%</td>
</tr>
<tr>
<td>$PSRR$</td>
<td>Power Supply Rejection Ratio</td>
<td>$V_{ripple} = 200mV$ sine p-p</td>
<td>60 ($f = 217Hz$)</td>
<td>55 dB (min)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Input terminated with 10$\Omega$</td>
<td>64 ($f = 1kHz$)</td>
<td></td>
</tr>
</tbody>
</table>

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(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional but specific performance is not ensured. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.

(2) All voltages are measured with respect to the ground pin, unless otherwise specified.

(3) Typicals are measured at 25°C and represent the parametric norm.

(4) Limits are specified to AOQL (Average Outgoing Quality Level).

(5)Datasheet min/max specification limits are specified by design, test, or statistical analysis.

(6) For DSBGA only, shutdown current is measured in a Normal Room Environment. Exposure to direct sunlight will increase $I_{SD}$ by a maximum of 2$\mu A$.

(7) $R_{OUT}$ is measured from the output pin to ground. This value represents the parallel combination of the 10$\Omega$ output resistors and the two 20$\Omega$ resistors.

(8) The Exposed-DAP of the NGZ0010B package should be electrically connected to GND or an electrically isolated copper area. The LM4990LD demo board has the Exposed-DAP connected to GND with a PCB area of 86.7mils x 585mils (2.02mm x 14.86mm) on the copper top layer and 550mils x 710mils (13.97mm x 18.03mm) on the copper bottom layer.

(9) The thermal performance of the WSON and exposed-DAP MSOP-PowerPAD packages when used with the exposed-DAP connected to a thermal plane is sufficient for driving 4$\Omega$ loads. The VSSOP and DSBGA packages do not have the thermal performance necessary for driving 4$\Omega$ loads with a 5V supply and is not recommended for this application.
## Electrical Characteristics \( V_{DD} = 3V^{(1)(2)} \)

The following specifications apply for the circuit shown in Figure 1, unless otherwise specified. Limits apply for \( T_A = 25^\circ C \).

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>LM4990</th>
<th>Units (Limits)</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_{DD} )</td>
<td>Quiescent Power Supply Current</td>
<td>( V_{IN} = 0V, I_o = 0A, ) No Load</td>
<td>2</td>
<td>7</td>
</tr>
<tr>
<td>( I_{DD} )</td>
<td></td>
<td>( V_{IN} = 0V, I_o = 0A, 8\Omega ) Load</td>
<td>3</td>
<td>9</td>
</tr>
<tr>
<td>( I_{SD} )</td>
<td>Shutdown Current</td>
<td>( V_{SD} = V_{SD \ Mode}^{(6)} )</td>
<td>0.1</td>
<td>2.0</td>
</tr>
<tr>
<td>( V_{SDIH} )</td>
<td>Shutdown Voltage Input High</td>
<td>( V_{SD \ MODE} = V_{DD} )</td>
<td>1.1</td>
<td>( V )</td>
</tr>
<tr>
<td>( V_{SDIL} )</td>
<td>Shutdown Voltage Input Low</td>
<td>( V_{SD \ MODE} = V_{DD} )</td>
<td>0.9</td>
<td>( V )</td>
</tr>
<tr>
<td>( V_{SDIH} )</td>
<td>Shutdown Voltage Input High</td>
<td>( V_{SD \ MODE} = GND )</td>
<td>1.3</td>
<td>( V )</td>
</tr>
<tr>
<td>( V_{SDIL} )</td>
<td>Shutdown Voltage Input Low</td>
<td>( V_{SD \ MODE} = GND )</td>
<td>1.0</td>
<td>( V )</td>
</tr>
<tr>
<td>( V_{OS} )</td>
<td>Output Offset Voltage</td>
<td></td>
<td>7</td>
<td>50</td>
</tr>
<tr>
<td>( R_{OUT} )</td>
<td>Resistor Output to GND(7)</td>
<td></td>
<td>8.5</td>
<td>9.7</td>
</tr>
<tr>
<td>( P_o )</td>
<td>Output Power</td>
<td>(8( \Omega ))</td>
<td>425</td>
<td>( mW )</td>
</tr>
<tr>
<td>( P_o )</td>
<td></td>
<td>(4( \Omega ))</td>
<td>600</td>
<td>( mW )</td>
</tr>
<tr>
<td>( T_{WU} )</td>
<td>Wake-up time</td>
<td></td>
<td>75</td>
<td>ms</td>
</tr>
<tr>
<td>( THD+N )</td>
<td>Total Harmonic Distortion+Noise</td>
<td>( P_o = 0.25W ) rms; ( f = 1kHz )</td>
<td>0.1</td>
<td>%</td>
</tr>
<tr>
<td>PSRR</td>
<td>Power Supply Rejection Ratio</td>
<td>( V_{ripple} = 200mV ) sine p-p Input terminated with 10( \Omega )</td>
<td>62 ( f = 217Hz )</td>
<td>55</td>
</tr>
<tr>
<td>&amp;</td>
<td></td>
<td>68 ( f = 1kHz )</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional but specific performance is not ensured. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.

(2) All voltages are measured with respect to the ground pin, unless otherwise specified.

(3) Typicals are measured at 25\( ^\circ C \) and represent the parametric norm.

(4) Limits are specified to AOQL (Average Outgoing Quality Level).

(5) Datasheet min/max specification limits are specified by design, test, or statistical analysis.

(6) For DSBGA only, shutdown current is measured in a Normal Room Environment. Exposure to direct sunlight will increase \( I_{SD} \) by a maximum of 2\( \mu A \).

(7) \( R_{OUT} \) is measured from the output pin to ground. This value represents the parallel combination of the 10k\( \Omega \) output resistors and the two 20k\( \Omega \) resistors.
Electrical Characteristics $V_{DD} = 2.6V^{(1)(2)}$

The following specifications apply for the circuit shown in Figure 1, unless otherwise specified. Limits apply for $T_A = 25^\circ C$.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Conditions</th>
<th>LM4990</th>
<th>Units (Limits)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{DD}$</td>
<td>Quiescent Power Supply Current</td>
<td>$V_N = 0V$, $I_o = 0A$, No Load</td>
<td>2.0</td>
<td>mA</td>
</tr>
<tr>
<td>$I_{SDH}$</td>
<td>Shutdown Current</td>
<td>$V_{SD} = V_{SD Mode}^{(6)}$</td>
<td>0.1</td>
<td>$\mu A$</td>
</tr>
<tr>
<td>$V_{DDH}$</td>
<td>Shutdown Voltage Input High</td>
<td>$V_{SD MODE} = V_{DD}$</td>
<td>1.0</td>
<td>V</td>
</tr>
<tr>
<td>$V_{DDL}$</td>
<td>Shutdown Voltage Input Low</td>
<td>$V_{SD MODE} = V_{DD}$</td>
<td>0.9</td>
<td>V</td>
</tr>
<tr>
<td>$V_{SDH}$</td>
<td>Shutdown Voltage Input High</td>
<td>$V_{SD MODE} = GND$</td>
<td>1.2</td>
<td>V</td>
</tr>
<tr>
<td>$V_{SDL}$</td>
<td>Shutdown Voltage Input Low</td>
<td>$V_{SD MODE} = GND$</td>
<td>1.0</td>
<td>V</td>
</tr>
<tr>
<td>$V_{OS}$</td>
<td>Output Offset Voltage</td>
<td></td>
<td>5</td>
<td>50 mV (max)</td>
</tr>
<tr>
<td>$R_{OUT}$</td>
<td>Resistor Output to GND$^{(7)}$</td>
<td></td>
<td>8.5</td>
<td>9.7 k$\Omega$ (max)</td>
</tr>
<tr>
<td>$P_o$</td>
<td>Output Power</td>
<td>(8$\Omega$)</td>
<td>THD+N = 1% (max); $f = 1kHz$</td>
<td>300</td>
</tr>
<tr>
<td>$T_{WU}$</td>
<td>Wake-up time</td>
<td>(4$\Omega$)</td>
<td>THD+N = 1% (max); $f = 1kHz$</td>
<td>400</td>
</tr>
<tr>
<td>THD+N+N</td>
<td>Total Harmonic Distortion+Noise</td>
<td>$P_o = 0.15Wrms$; $f = 1kHz$</td>
<td>0.1</td>
<td>%</td>
</tr>
<tr>
<td>PSRR</td>
<td>Power Supply Rejection Ratio</td>
<td>$V_{ripple} = 200mV$ sine p-p</td>
<td>51 ($f = 217Hz$) 51 ($f = 1kHz$)</td>
<td>dB</td>
</tr>
</tbody>
</table>

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional but specific performance is not ensured. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which ensure specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.

(2) All voltages are measured with respect to the ground pin, unless otherwise specified.

(3) Typicals are measured at 25$^\circ$C and represent the parametric norm.

(4) Limits are specified to AOQL (Average Outgoing Quality Level).

(5) Datasheet min/max specification limits are specified by design, test, or statistical analysis.

(6) For DSBGA only, shutdown current is measured in a Normal Room Environment. Exposure to direct sunlight will increase $I_{SD}$ by a maximum of 2$\mu A$.

(7) $R_{OUT}$ is measured from the output pin to ground. This value represents the parallel combination of the 10k$\Omega$ output resistors and the two 20k$\Omega$ resistors.

External Components Description

See (Figure 5)
Typical Performance Characteristics
NGZ and DGQ Specific Characteristics

**THD+N+N vs Frequency**

-\[ V_{DD} = 5V, R_L = 4\Omega, \text{ and } P_O = 1W \]

**THD+N+N vs Output Power**

-\[ V_{DD} = 5V, R_L = 4\Omega, \text{ and } f = 1 \text{ kHz} \]

*Figure 7.*

*Figure 8.*
Typical Performance Characteristics

THD+N+N vs Frequency

- $V_{DD} = 5\text{V}$, $R_L = 8\Omega$, and $P_O = 500\text{mW}$
- $V_{DD} = 3\text{V}$, $R_L = 4\Omega$, and $P_O = 500\text{mW}$
- $V_{DD} = 3\text{V}$, $R_L = 8\Omega$, and $P_O = 250\text{mW}$
- $V_{DD} = 2.6\text{V}$, $R_L = 4\Omega$, and $P_O = 150\text{mW}$
- $V_{DD} = 2.6\text{V}$, $R_L = 8\Omega$, and $f = 1\text{kHz}$

Figure 9.  
Figure 10.  
Figure 11.  
Figure 12.  
Figure 13.  
Figure 14.
Typical Performance Characteristics (continued)

**THD+N+N vs Output Power**

- **$V_{DD} = 3V$, $R_L = 4\Omega$, and $f = 1kHz$**

- **$V_{DD} = 3V$, $R_L = 8\Omega$, and $f = 1kHz$**

**Power Supply Rejection Ratio (PSRR) vs Frequency**

- **$V_{DD} = 5V$, $R_L = 8\Omega$, input 10\Omega terminated**

- **$V_{DD} = 5V$, $R_L = 8\Omega$, input floating**
Typical Performance Characteristics (continued)

Power Supply Rejection Ratio (PSRR) vs Frequency

*V_{DD} = 3V, R_{L} = 8Ω, Input 10Ω terminated*

Figure 21.

Power Supply Rejection Ratio (PSRR) vs Frequency

*V_{DD} = 3V, R_{L} = 8Ω, Input floating*

Figure 22.

Power Supply Rejection Ratio (PSRR) vs Frequency

*V_{DD} = 2.6V, R_{L} = 8Ω, Input 10Ω terminated*

Figure 23.

Power Supply Rejection Ratio (PSRR) vs Frequency

*V_{DD} = 2.6V, R_{L} = 8Ω, Input floating*

Figure 24.

Open Loop Frequency Response, 5V

80kHz Bandwidth, Input to GND

Figure 25.

Figure 26.
Typical Performance Characteristics (continued)

Power Dissipation vs Output Power, \( V_{DD} = 5V \)

Power Dissipation vs Output Power, \( V_{DD} = 3V \)

Figure 27.

Figure 28.

Power Dissipation vs Output Power, \( V_{DD} = 2.6V \)

Figure 29.

Shutdown Hysteresis Voltage

\( V_{DD} = 5V, SD\ Mode = V_{DD} \)

\( V_{DD} = 3V, SD\ Mode = V_{DD} \)

Figure 30.

Figure 31.

Figure 32.
Typical Performance Characteristics (continued)

Output Power vs Supply Voltage, \( R_L = 32\Omega \)

Figure 39.

Frequency Response vs Input Capacitor Size

Figure 40.
APPLICATION INFORMATION

BRIDGE CONFIGURATION EXPLANATION

As shown in Figure 5, the LM4990 has two internal operational amplifiers. The first amplifier's gain is externally configurable, while the second amplifier is internally fixed in a unity-gain, inverting configuration. The closed-loop gain of the first amplifier is set by selecting the ratio of $R_f$ to $R_i$ while the second amplifier's gain is fixed by the two internal 20kΩ resistors. Figure 5 shows that the output of amplifier one serves as the input to amplifier two which results in both amplifiers producing signals identical in magnitude, but out of phase by 180°. Consequently, the differential gain for the IC is

$$A_{VD} = 2 \times \frac{R_f}{R_i} \quad (1)$$

By driving the load differentially through outputs Vo1 and Vo2, an amplifier configuration commonly referred to as “bridged mode” is established. Bridged mode operation is different from the classical single-ended amplifier configuration where one side of the load is connected to ground.

A bridge amplifier design has a few distinct advantages over the single-ended configuration, as it provides differential drive to the load, thus doubling output swing for a specified supply voltage. Four times the output power is possible as compared to a single-ended amplifier under the same conditions. This increase in attainable output power assumes that the amplifier is not current limited or clipped. In order to choose an amplifier’s closed-loop gain without causing excessive clipping, please refer to the AUDIO POWER AMPLIFIER DESIGN section.

A bridge configuration, such as the one used in LM4990, also creates a second advantage over single-ended amplifiers. Since the differential outputs, Vo1 and Vo2, are biased at half-supply, no net DC voltage exists across the load. This eliminates the need for an output coupling capacitor which is required in a single supply, single-ended amplifier configuration. Without an output coupling capacitor, the half-supply bias across the load would result in both increased internal IC power dissipation and also possible loudspeaker damage.

POWER DISSIPATION

Power dissipation is a major concern when designing a successful amplifier, whether the amplifier is bridged or single-ended. A direct consequence of the increased power delivered to the load by a bridge amplifier is an increase in internal power dissipation. Since the LM4990 has two operational amplifiers in one package, the maximum internal power dissipation is 4 times that of a single-ended amplifier. The maximum power dissipation for a given application can be derived from the power dissipation graphs or from Equation 2.

$$P_{DMAX} = 4 \times \left(\frac{V_{DD}}{2}\right)^2/(2\pi^2 R_L) \quad (2)$$

It is critical that the maximum junction temperature $T_{JMAX}$ of 150°C is not exceeded. $T_{JMAX}$ can be determined from the power derating curves by using $P_{DMAX}$ and the PC board foil area. By adding copper foil, the thermal resistance of the application can be reduced from the free air value of $\theta_{JA}$, resulting in higher $P_{DMAX}$ values without thermal shutdown protection circuitry being activated. Additional copper foil can be added to any of the leads connected to the LM4990. It is especially effective when connected to $V_{DD}$, GND, and the output pins. Refer to the application information on the LM4990 reference design board for an example of good heat sinking. If $T_{JMAX}$ still exceeds 150°C, then additional changes must be made. These changes can include reduced supply voltage, higher load impedance, or reduced ambient temperature. Internal power dissipation is a function of output power. Refer to the Typical Performance Characteristics curves for power dissipation information for different output powers and output loading.

POWER SUPPLY BYPASSING

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both the bypass and power supply pins should be as close to the device as possible. Typical applications employ a 5V regulator with 10µF tantalum or electrolytic capacitor and a ceramic bypass capacitor which aid in supply stability. This does not eliminate the need for bypassing the supply nodes of the LM4990. The selection of a bypass capacitor, especially $C_B$, is dependent upon PSRR requirements, click and pop performance (as explained in the section, PROPER SELECTION OF EXTERNAL COMPONENTS), system cost, and size constraints.
SHUTDOWN FUNCTION

In order to reduce power consumption while not in use, the LM4990 contains shutdown circuitry that is used to turn off the amplifier's bias circuitry. In addition, the LM4990 contains a Shutdown Mode pin (NGZ and DGQ packages only), allowing the designer to designate whether the part will be driven into shutdown with a high level logic signal or a low level logic signal. This allows the designer maximum flexibility in device use, as the Shutdown Mode pin may simply be tied permanently to either \( V_{DD} \) or GND to set the LM4990 as either a “shutdown-high” device or a “shutdown-low” device, respectively. The device may then be placed into shutdown mode by toggling the Shutdown pin to the same state as the Shutdown Mode pin. For simplicity's sake, this is called “shutdown same”, as the LM4990 enters shutdown mode whenever the two pins are in the same logic state. The DGK package lacks this Shutdown Mode feature, and is permanently fixed as a ‘shutdown-low’ device. The trigger point for either shutdown high or shutdown low is shown as a typical value in the Supply Current vs Shutdown Voltage graphs in the Typical Performance Characteristics section. It is best to switch between ground and supply for maximum performance. While the device may be disabled with shutdown voltages in between ground and supply, the idle current may be greater than the typical value of 0.1µA. In either case, the shutdown pin should be tied to a definite voltage to avoid unwanted state changes.

In many applications, a microcontroller or microprocessor output is used to control the shutdown circuitry, which provides a quick, smooth transition to shutdown. Another solution is to use a single-throw switch in conjunction with an external pull-up resistor (or pull-down, depending on shutdown high or low application). This scheme ensures that the shutdown pin will not float, thus preventing unwanted state changes.

PROPER SELECTION OF EXTERNAL COMPONENTS

Proper selection of external components in applications using integrated power amplifiers is critical to optimize device and system performance. While the LM4990 is tolerant of external component combinations, consideration to component values must be used to maximize overall system quality.

The LM4990 is unity-gain stable which gives the designer maximum system flexibility. The LM4990 should be used in low gain configurations to minimize THD+N+N values, and maximize the signal to noise ratio. Low gain configurations require large input signals to obtain a given output power. Input signals equal to or greater than 1Vrms are available from sources such as audio codecs. Please refer to the section, AUDIO POWER AMPLIFIER DESIGN, for a more complete explanation of proper gain selection.

Besides gain, one of the major considerations is the closed-loop bandwidth of the amplifier. To a large extent, the bandwidth is dictated by the choice of external components shown in Figure 5. The input coupling capacitor, \( C_i \), forms a first order high pass filter which limits low frequency response. This value should be chosen based on needed frequency response for a few distinct reasons.

Selection of Input Capacitor Size

Large input capacitors are both expensive and space hungry for portable designs. Clearly, a certain sized capacitor is needed to couple in low frequencies without severe attenuation. But in many cases the speakers used in portable systems, whether internal or external, have little ability to reproduce signals below 100Hz to 150Hz. Thus, using a large input capacitor may not increase actual system performance.

In addition to system cost and size, click and pop performance is effected by the size of the input coupling capacitor, \( C_i \). A larger input coupling capacitor requires more charge to reach its quiescent DC voltage (nominally 1/2 \( V_{DD} \)). This charge comes from the output via the feedback and is apt to create pops upon device enable. Thus, by minimizing the capacitor size based on necessary low frequency response, turn-on pops can be minimized.

Besides minimizing the input capacitor size, careful consideration should be paid to the bypass capacitor value. Bypass capacitor, \( C_B \), is the most critical component to minimize turn-on pops since it determines how fast the LM4990 turns on. The slower the LM4990’s outputs ramp to their quiescent DC voltage (nominally 1/2 \( V_{DD} \)), the smaller the turn-on pop. Choosing \( C_B \) equal to 1.0µF along with a small value of \( C_i \) (in the range of 0.1µF to 0.39µF), should produce a virtually clickless and popless shutdown function. While the device will function properly, (no oscillations or motorboating), with \( C_B \) equal to 0.1µF, the device will be much more susceptible to turn-on clicks and pops. Thus, a value of \( C_B \) equal to 1.0µF is recommended in all but the most cost sensitive designs.
A designer must first determine the minimum supply rail to obtain the specified output power. By extrapolating from the Output Power vs Supply Voltage graphs in the Typical Performance Characteristics section, the supply rail can be easily found.

5V is a standard voltage in most applications, it is chosen for the supply rail. Extra supply voltage creates headroom that allows the LM4990 to reproduce peaks in excess of 1W without producing audible distortion. At this time, the designer must make sure that the power supply choice along with the output impedance does not violate the conditions explained in the POWER DISSIPATION section.

Once the power dissipation equations have been addressed, the required differential gain can be determined from Equation 3.

\[ A_{VD} \geq \sqrt{\frac{P_{OL}}{V_{rms}^2/V_{in rms}}} \]  
\[ R_f/R_i = A_{VD}/2 \]  

From Equation 3, the minimum \( A_{VD} \) is 2.83; use \( A_{VD} = 3 \).

Since the desired input impedance was 20kΩ, and with an \( A_{VD} \) impedance of 2, a ratio of 1.5:1 of \( R_i \) to \( R_f \) results in an allocation of \( R_i = 20kΩ \) and \( R_f = 30kΩ \). The final design step is to address the bandwidth requirements which must be stated as a pair of −3dB frequency points. Five times away from a −3dB point is 0.17dB down from passband response which is better than the required ±0.25dB specified.

\[ f_L = 100Hz/5 = 20Hz \]  
\[ f_H = 20kHz * 5 = 100kHz \]  

As stated in the External Components Description section, \( R_i \) in conjunction with \( C_i \) create a highpass filter.

\[ C_i \geq \frac{1}{(2\pi*20kΩ*20Hz)} = 0.397 \mu F; \text{ use } 0.39 \mu F \]  

The high frequency pole is determined by the product of the desired frequency pole, \( f_H \), and the differential gain, \( A_{VD} \). With a \( A_{VD} = 3 \) and \( f_H = 100kHz \), the resulting GBWP = 300kHz which is much smaller than the LM4990 GBWP of 2.5MHz. This figure displays that if a designer has a need to design an amplifier with a higher differential gain, the LM4990 can still be used without running into bandwidth limitations.
Figure 41. HIGHER GAIN AUDIO AMPLIFIER

The LM4990 is unity-gain stable and requires no external components besides gain-setting resistors, an input coupling capacitor, and proper supply bypassing in the typical application. However, if a closed-loop differential gain of greater than 10 is required, a feedback capacitor (C4) may be needed as shown in Figure 2 to bandwidth limit the amplifier. This feedback capacitor creates a low pass filter that eliminates possible high frequency oscillations. Care should be taken when calculating the -3dB frequency in that an incorrect combination of R3 and C4 will cause rolloff before 20kHz. A typical combination of feedback resistor and capacitor that will not produce audio band high frequency rolloff is R3 = 20kΩ and C4 = 25pf. These components result in a -3dB point of approximately 320kHz.
Figure 42. DIFFERENTIAL AMPLIFIER CONFIGURATION FOR LM4990

Figure 43. REFERENCE DESIGN BOARD SCHEMATIC

* Not specified
## REVISION HISTORY

Changes from Revision D (May 2013) to Revision E

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- Changed layout of National Data Sheet to TI format
## PACKAGING INFORMATION

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<th>Package Type</th>
<th>Package Drawing</th>
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<th>Lead/Ball Finish (6)</th>
<th>MSL Peak Temp (3)</th>
<th>Op Temp (°C)</th>
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(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBsolete:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# TAPE AND REEL INFORMATION

## TAPE DIMENSIONS

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<td>Dimension designed to accommodate the component length</td>
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<td>K0</td>
<td>Dimension designed to accommodate the component thickness</td>
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<td>Overall width of the carrier tape</td>
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<td>P1</td>
<td>Pitch between successive cavity centers</td>
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## REEL DIMENSIONS

![Reel Dimensions Diagram](image)

- **Reel Diameter**
- **Reel Width (W1)**

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

![Quadrant Assignments Diagram](image)

- **Sprocket Holes**
- **User Direction of Feed**

## PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal.*
### TAPE AND REEL BOX DIMENSIONS

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*All dimensions are nominal*
DGK (S-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE

NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
D. Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
E. Falls within JEDEC MO-187 variation AA, except interlead flash.
NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.
NOTES:  
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.  
B. This drawing is subject to change without notice.

D: Max = 1.502 mm, Min = 1.441 mm

E: Max = 1.502 mm, Min = 1.441 mm
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