

Technical documentation



Support & training



REF2025, REF2030, REF2033, REF2041 SBOS600E - JULY 2018 - REVISED FEBRUARY 2022

REF20xx Low-Drift, Low-Power, Dual-Output, V<sub>REF</sub> and V<sub>REF</sub> / 2 Voltage References

## 1 Features

- Two outputs,  $V_{REF}$  and  $V_{REF}$  / 2, for convenient use in single-supply systems
- Excellent temperature drift performance:
- 8 ppm/°C (maximum) from –40°C to 125°C
- High initial accuracy: ±0.05% (maximum)
  - V<sub>REF</sub> and V<sub>BIAS</sub> tracking overtemperature: 6 ppm/°C (maximum) from –40°C to 85°C
  - 7 ppm/°C (maximum) from –40°C to 125°C
- Microsize package: SOT23-5 ٠
- Low dropout voltage: 10 mV
- High output current: ±20 mA
- Low quiescent current: 360 µA
- Line regulation: 3 ppm/V •
- Load regulation: 8 ppm/mA
- Matte-Sn version (REF2025AISDDCR) for improved corrosion resistance in the Battelle Class III and similar harsh environments

# 2 Applications

- **Electricity meter** ٠
- Analog input module
- Analog output module
- Servo drive control module
- Circuit breaker (ACB, MCCB, VCB)
- Clinical digital thermometer
- Lab & field instrumentation
- Battery test

# **3 Description**

Applications with only a positive supply voltage often require additional stable voltage in the middle of the analog-to-digital converter (ADC) input range to bias input bipolar signals. The REF20xx provides a reference voltage ( $V_{REF}$ ) for the ADC and a second highly-accurate voltage (V<sub>BIAS</sub>) that can be used to bias the input bipolar signals.

The REF20xx offers excellent temperature drift

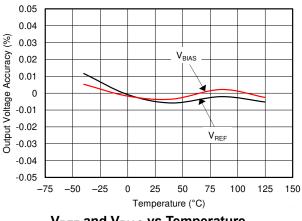
(8 ppm/°C, maximum) and initial accuracy (0.05%) on both the  $V_{REF}$  and  $V_{BIAS}$  outputs while operating at a quiescent current less than 430 µA. In addition, the  $V_{REF}$  and  $V_{BIAS}$  outputs track each other with a precision of 6 ppm/°C (maximum) across the temperature range of -40°C to 125°C. All these features increase the precision of the signal chain and decrease board space, while reducing the cost of the system as compared to a discrete solution. Extremely low dropout voltage of only 10 mV allows operation from very low input voltages, which can be very useful in battery-operated systems.

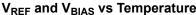
Both the  $V_{\mathsf{REF}}$  and  $V_{\mathsf{BIAS}}$  voltages have the same excellent specifications and can sink and source current equally well. Very good long-term stability and low noise levels make these devices ideally-suited for high-precision industrial applications.

|--|

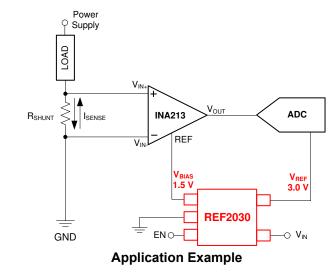
PART NAME	PACKAGE (1) BODY SIZE (N	
REF20xx	SOT-23 (5)	2.90 mm × 1.60 mm

For all available packages, see the orderable addendum at (1)the end of the datasheet.





An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.





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# **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision D (May 2018) to Revision E (January 2022)	Page
•	Updated Applications section	1
	Updated the numbering format for tables, figures, and cross-references throughout the document	
•	Changed ESD Rating table: changed HBM rating from ±4000 V to ±2500 V	4
•	Updated Long-term stability value	<mark>5</mark>
	Added Long-Term Stability sub-section under Parameter Measurement Information section	

CI	nanges from Revision C (January 2017) to Revision D (May 2018)	Page
•	Changed application information to include corrosion resistance advantages.	

С	Changes from Revision B (July 2014) to Revision C (January 2017)	Page
•	Added I/O column to Pin Functions table	
•	Added Storage temperature parameter to Absolute Maximum Ratings table (moved from ESD I	• /
•	Changed ESD Rating table: changed title, updated table format	
С	Changes from Revision A (June 2014) to Revision B (July 2014)	Page
<u>с</u>		
•	Changed device status to Production Data from Mixed Status Deleted footnote 2 from Device Information table	

## Changes from Revision \* (May 2014) to Revision A (June 2014)

Made changes to product preview data sheet.....1

Page



# **5** Device Comparison Table

PRODUCT	V <sub>REF</sub>	V <sub>BIAS</sub>
REF2025	2.5 V	1.25 V
REF2030	3.0 V	1.5 V
REF2033	3.3 V	1.65 V
REF2041	4.096 V	2.048 V

# **6** Pin Configuration and Functions

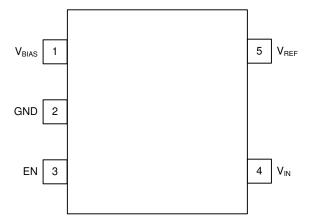


Figure 6-1. DDC Package SOT23-5 (Top View)

## **Pin Functions**

PIN		I/O	DESCRIPTION	
NO.	NAME	10	DESCRIPTION	
1	V <sub>BIAS</sub>	Output	Bias voltage output (V <sub>REF</sub> / 2)	
2	GND	_	Ground	
3	EN	Input	Enable (EN $\ge$ V <sub>IN</sub> – 0.7 V, device enabled)	
4	V <sub>IN</sub>	Input	Input supply voltage	
5	V <sub>REF</sub>	Output	Reference voltage output (V <sub>REF</sub> )	



# 7 Specifications

# 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Input voltage	V <sub>IN</sub>	-0.3	6	V
	EN	-0.3	V <sub>IN</sub> + 0.3	v
	Operating	-55	150	
Temperature	Junction, T <sub>j</sub>		150	°C
	Storage, T <sub>stg</sub>	-65	170	

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 7.2 ESD Ratings

				UNIT
V <sub>(ESD)</sub> Electrostatic discharge		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2500	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±1500	- V	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM MAX	UNIT	
$V_{IN}$ Supply input voltage range (I <sub>L</sub> = 0 mA, T <sub>A</sub> = 25°C)	V <sub>REF</sub> + 0.02 <sup>(1)</sup>	5.5	V	

(1) See Figure 7-28 in Section 7.6 for minimum input voltage at different load currents and temperature

## 7.4 Thermal Information

		REF20xx	
	THERMAL METRIC <sup>(1)</sup>	DDC (SOT23)	UNIT
		5 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	193.6	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	40.2	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	34.5	°C/W
ΨJT	Junction-to-top characterization parameter	0.9	°C/W
Ψјв	Junction-to-board characterization parameter	34.3	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.



## 7.5 Electrical Characteristics

At $T_A = 25^{\circ}$ C, $I_L = 0$ mA, and $V_{IN} = 5$ V	unless otherwise noted Both \	/per and Vouse have the	same specifications
$A_{L} I_{A} = 25 \text{ C}, I_{L} = 0 \text{ III}A, and V_{IN} = 5 \text{ V}$	, unicas ounciwise noteu. Dour v	VREF and VBIAS have the	same specifications.

	PARAMETER	TEST CONDITION	IS	MIN	TYP	MAX	UNIT			
ACCURA	CY AND DRIFT									
	Output voltage accuracy				-0.05%		0.05%			
	Output voltage temperature co	efficient <sup>(1)</sup>	–40°C ≤ T <sub>A</sub> ≤ 125°C			±3	±8	ppm/°C		
			–40°C ≤ T <sub>A</sub> ≤ 85°C			±1.5	±6			
	$V_{\text{REF}}$ and $V_{\text{BIAS}}$ tracking over te	-40°C ≤ T <sub>A</sub> ≤ 125°C			±7	ppm/°C				
LINE ANI	D LOAD REGULATION							<u>I</u>		
ΔV <sub>O(ΔVI)</sub>	Line regulation		V <sub>REF</sub> + 0.02 V ≤ V <sub>IN</sub> ≤ 5.5 V			3	35	ppm/V		
•••		Sourcing	0 mA $\leq$ I <sub>L</sub> $\leq$ 20 mA , V <sub>REF</sub> + 0.6 V $\leq$ V <sub>IN</sub> $\leq$ 5.5 V			8	20			
ΔV <sub>O(ΔIL)</sub>	Load regulation	Sinking	$0 \text{ mA} \le I_L \le -20 \text{ mA},$ $V_{REF} + 0.02 \text{ V} \le V_{IN} \le 5.5 \text{ V}$	0 mA ≤ I <sub>L</sub> ≤ –20 mA,		8	20	- ppm/mA		
POWER	SUPPLY									
		Active mode				360	430			
		Active mode	$-40^{\circ}C \le T_A \le 125^{\circ}C$				460			
ICC	Supply current	Chutdours mode				3.3	5	_		
		Shutdown mode	$-40^{\circ}C \le T_A \le 125^{\circ}C$				9			
	Enable voltage		Device in shutdown mode (EN	Device in shutdown mode (EN = 0)			0.7	v		
	Enable voltage		Device in active mode (EN = 1	V <sub>IN</sub> – 0.7		V <sub>IN</sub>	v			
						10	20	mV		
	Dropout voltage		I <sub>L</sub> = 20 mA			600				
I <sub>SC</sub>	Short-circuit current					50		mA		
t <sub>on</sub>	Turn-on time		0.1% settling, $C_L = 1 \ \mu F$			500		μs		
NOISE										
	Low-frequency noise <sup>(3)</sup>		0.1 Hz ≤ f ≤ 10 Hz			12		ppm <sub>PP</sub>		
	Output voltage noise density		f = 100 Hz		0.			ppm/√ Hz		
CAPACIT	TIVE LOAD									
Stable output capacitor range			0				10	μF		
HYSTER	ESIS AND LONG TERM STABIL	ITY								
	Long-term stability <sup>(4)</sup>	0 to 1000 hours			25		ppm			
	Output voltage hysteresis <sup>(5)</sup>		25°C, –40°C, 125°C, 25°C	Cycle 1		60				
	Output voltage hysteresis(o)		25 0, -40 0, 125 0, 25 0	Cycle 2		35		ppm		

(1) Temperature drift is specified according to the box method. See the Section 9.3 section for more details.

(2) The V<sub>REF</sub> and V<sub>BIAS</sub> tracking over temperature specification is explained in more detail in the Section 9.3 section.

(3) The peak-to-peak noise measurement procedure is explained in more detail in the Section 8.4 section.

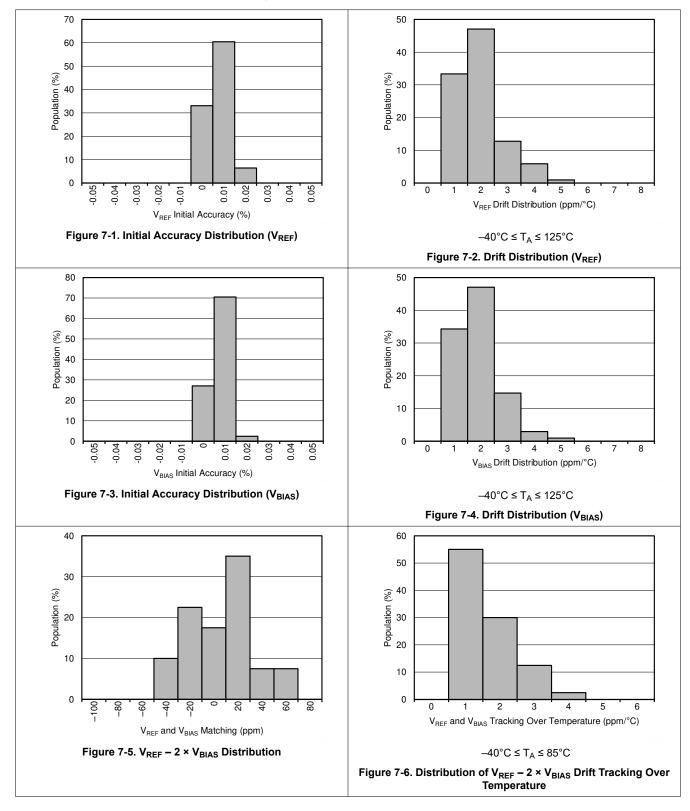
(4) Long-term stability measurement procedure is explained in more in detail in the Section 8.2 section.

(5) The thermal hysteresis measurement procedure is explained in more detail in the Section 8.3 section.



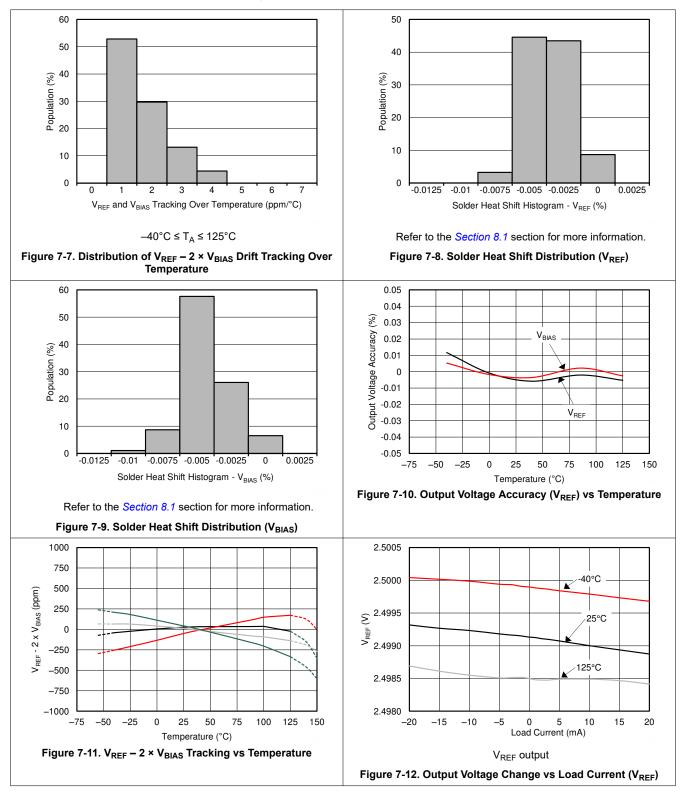
## 7.6 Typical Characteristics

At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0$  µF, and 2.5-V output, unless otherwise noted.



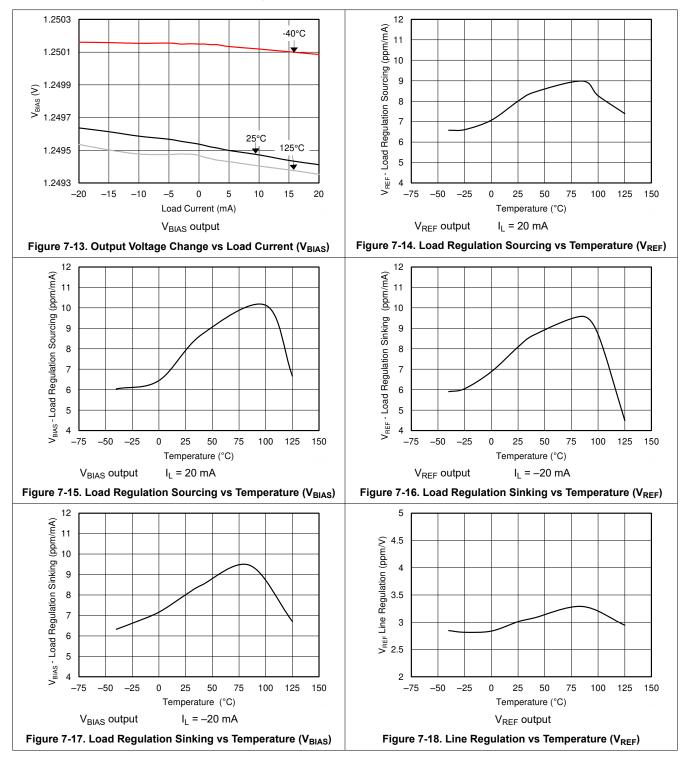


At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0 \mu$ F, and 2.5-V output, unless otherwise noted.



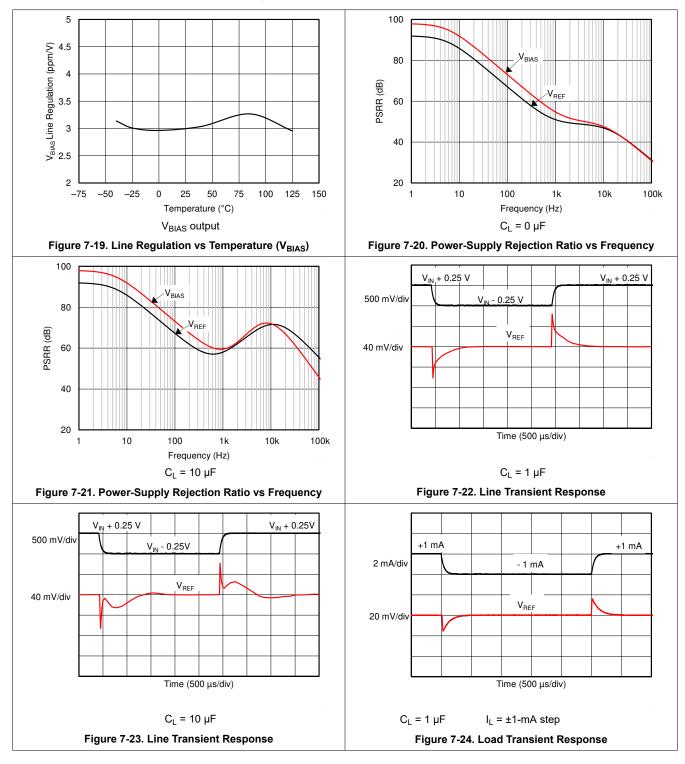


At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0$  µF, and 2.5-V output, unless otherwise noted.



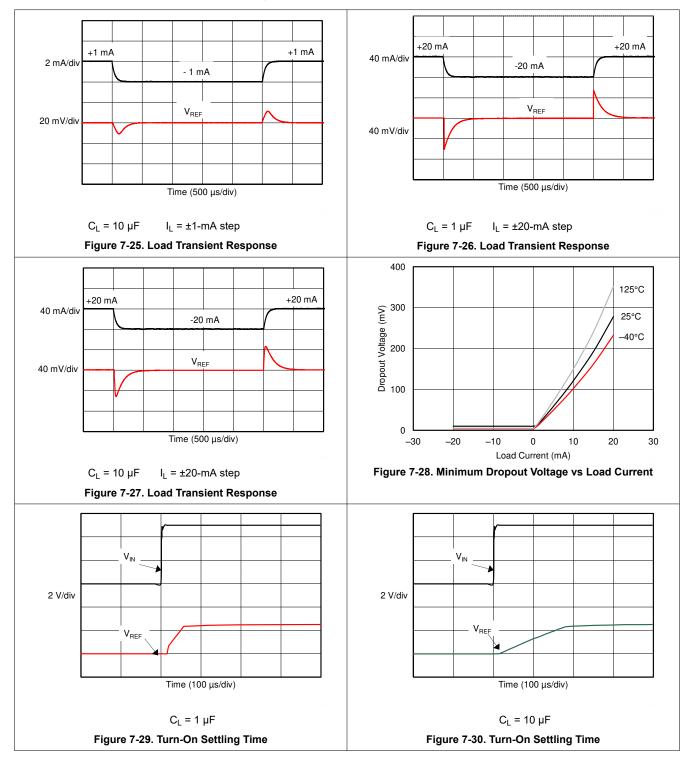


At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0 \mu$ F, and 2.5-V output, unless otherwise noted.



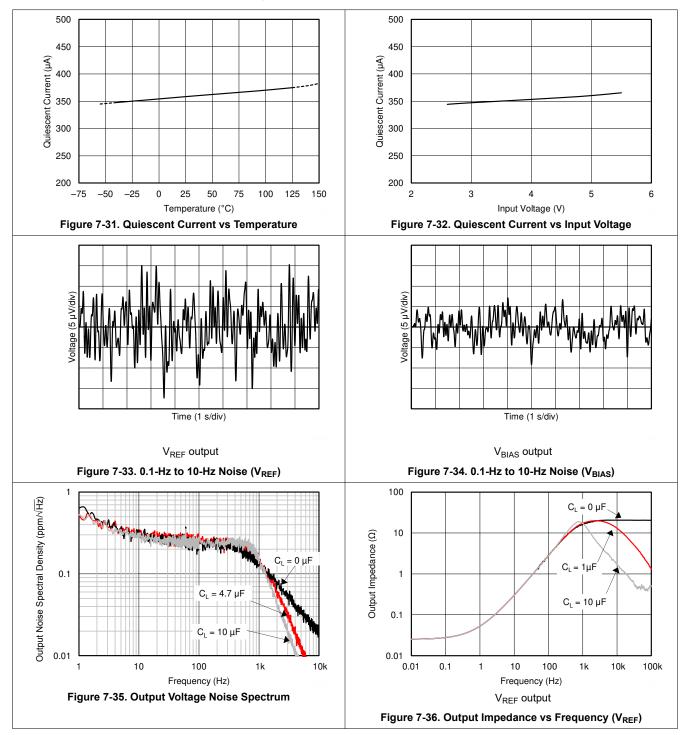


At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0$  µF, and 2.5-V output, unless otherwise noted.



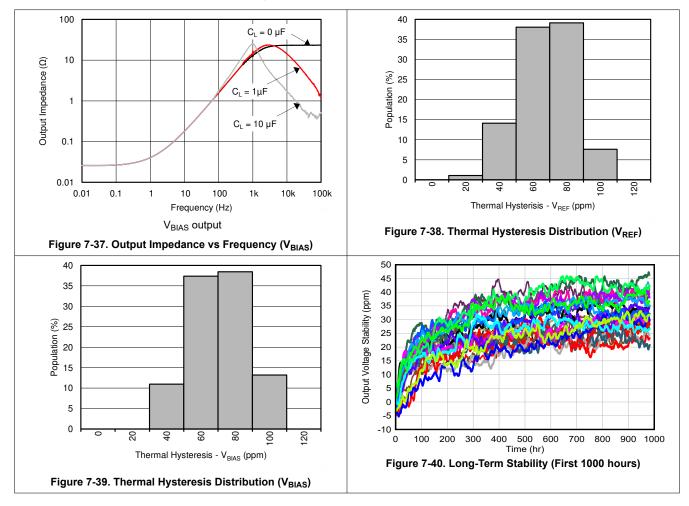


At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0 \mu$ F, and 2.5-V output, unless otherwise noted.





At  $T_A = 25^{\circ}$ C,  $I_L = 0$  mA,  $V_{IN} = 5$ -V power supply,  $C_L = 0 \mu$ F, and 2.5-V output, unless otherwise noted.





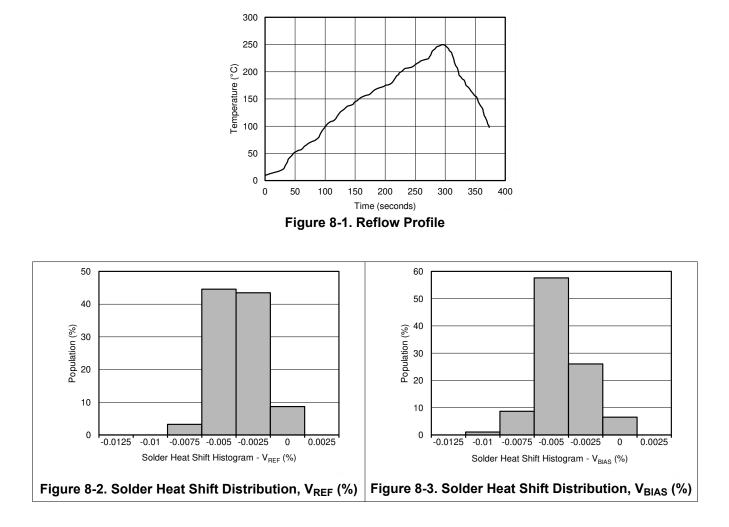
# 8 Parameter Measurement Information

## 8.1 Solder Heat Shift

The materials used in the manufacture of the REF20xx have differing coefficients of thermal expansion, resulting in stress on the device die when the part is heated. Mechanical and thermal stress on the device die can cause the output voltages to shift, degrading the initial accuracy specifications of the product. Reflow soldering is a common cause of this error.

In order to illustrate this effect, a total of 92 devices were soldered on four printed circuit boards [23 devices on each printed circuit board (PCB)] using lead-free solder paste and the paste manufacturer suggested reflow profile. The reflow profile is as shown in Figure 8-1. The printed circuit board is comprised of FR4 material. The board thickness is 1.57 mm and the area is 171.54 mm × 165.1 mm.

The reference and bias output voltages are measured before and after the reflow process; the typical shift is displayed in Figure 8-2 and Figure 8-3. Although all tested units exhibit very low shifts (< 0.01%), higher shifts are also possible depending on the size, thickness, and material of the printed circuit board. An important note is that the histograms display the typical shift for exposure to a single reflow profile. Exposure to multiple reflows, as is common on PCBs with surface-mount components on both sides, causes additional shifts in the output bias voltage. If the PCB is exposed to multiple reflows, the device should be soldered in the second pass to minimize its exposure to thermal stress.





## 8.2 Long-Term Stability

The long term stability of the REF20xx was collected on 32 parts that were soldered onto Printed Circuit Boards without any slots or special layout considerations. The boards were then placed into an oven with air temperature maintained at  $T_A = 35$ °C. The V<sub>REF</sub> output of the 32 parts was measured regularly. Typical long term stability is as shown in Figure 8-4.

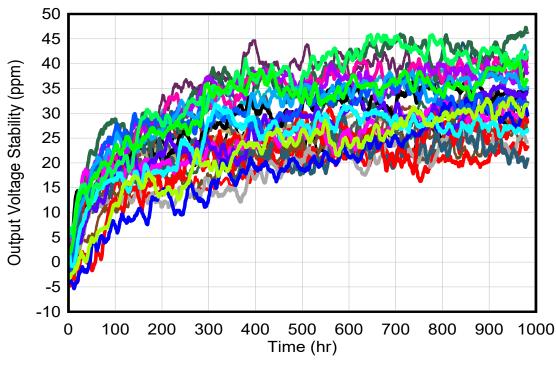


Figure 8-4. Long Term Stability – 1000 hours (V<sub>REF</sub>)



## 8.3 Thermal Hysteresis

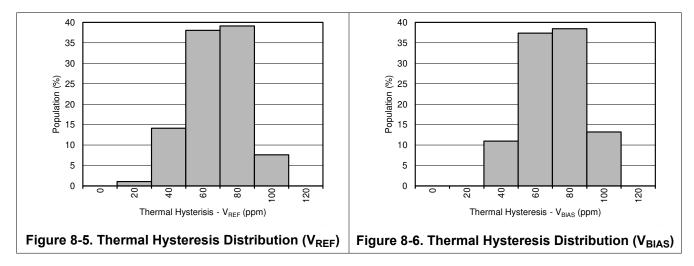
Thermal hysteresis is measured with the REF20xx soldered to a PCB, similar to a real-world application. Thermal hysteresis for the device is defined as the change in output voltage after operating the device at 25°C, cycling the device through the specified temperature range, and returning to 25°C. Hysteresis can be expressed by Equation 1:

$$V_{HYST} = \left(\frac{\left|V_{PRE} - V_{POST}\right|}{V_{NOM}}\right) \bullet 10^{6} \quad (ppm)$$
(1)

where

- V<sub>HYST</sub> = thermal hysteresis (in units of ppm),
- V<sub>NOM</sub> = the specified output voltage,
- V<sub>PRE</sub> = output voltage measured at 25°C pre-temperature cycling, and
- V<sub>POST</sub> = output voltage measured after the device has cycled from 25°C through the specified temperature range of -40°C to 125°C and returns to 25°C.

Typical thermal hysteresis distribution is as shown in Figure 8-5 and Figure 8-6.





## 8.4 Noise Performance

Typical 0.1-Hz to 10-Hz voltage noise can be seen in Figure 8-7 and Figure 8-8. Device noise increases with output voltage and operating temperature. Additional filtering can be used to improve output noise levels, although care should be taken to ensure the output impedance does not degrade ac performance. Peak-to-peak noise measurement setup is shown in Figure 8-9.

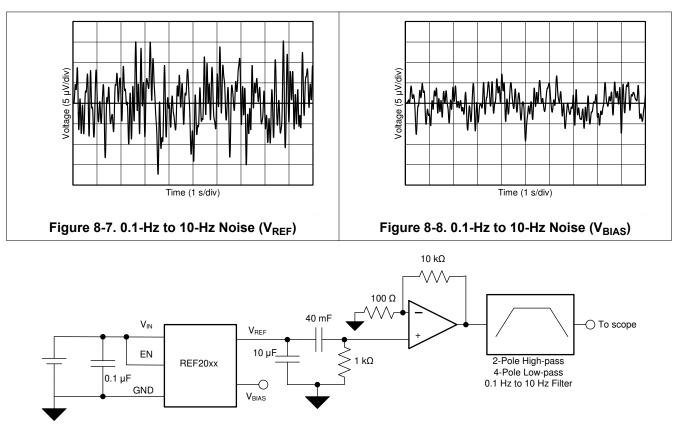


Figure 8-9. 0.1-Hz to 10-Hz Noise Measurement Setup



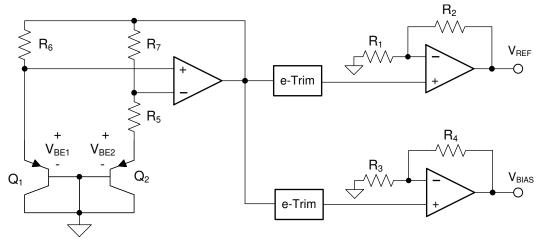
# 9 Detailed Description

## 9.1 Overview

The REF20xx are a family of dual-output,  $V_{REF}$  and  $V_{BIAS}$  ( $V_{REF}$  / 2) band-gap voltage references. The Section 9.2 section provides a block diagram of the basic band-gap topology and the two buffers used to derive the  $V_{REF}$  and  $V_{BIAS}$  outputs. Transistors  $Q_1$  and  $Q_2$  are biased such that the current density of  $Q_1$  is greater than that of  $Q_2$ . The difference of the two base emitter voltages ( $V_{BE1} - V_{BE2}$ ) has a positive temperature coefficient and is forced across resistor  $R_5$ . The voltage is amplified and added to the base emitter voltage of  $Q_2$ , which has a negative temperature coefficient. The resulting band-gap output voltage is almost independent of temperature. Two independent buffers are used to generate  $V_{REF}$  and  $V_{BIAS}$  from the band-gap voltage. The resistors  $R_1$ ,  $R_2$  and  $R_3$ ,  $R_4$  are sized such that  $V_{BIAS} = V_{REF}$  / 2.

e-Trim<sup>™</sup> is a method of package-level trim for the initial accuracy and temperature coefficient of V<sub>REF</sub> and V<sub>BIAS</sub>, implemented during the final steps of manufacturing after the plastic molding process. This method minimizes the influence of inherent transistor mismatch, as well as errors induced during package molding. e-Trim is implemented in the REF20xx to minimize the temperature drift and maximize the initial accuracy of both the V<sub>REF</sub> and V<sub>BIAS</sub>, and V<sub>BIAS</sub>, outputs.

## 9.2 Functional Block Diagram



# 9.3 Feature Description

## 9.3.1 $V_{\text{REF}}$ and $V_{\text{BIAS}}$ Tracking

Most single-supply systems require an additional stable voltage in the middle of the analog-to-digital converter (ADC) input range to bias input bipolar signals. The V<sub>REF</sub> and V<sub>BIAS</sub> outputs of the REF20xx are generated from the same band-gap voltage as shown in the *Section 9.2* section. Hence, both outputs track each other over the full temperature range of  $-40^{\circ}$ C to  $125^{\circ}$ C with an accuracy of 7 ppm/°C (maximum). The tracking accuracy increases to 6 ppm/°C (maximum) when the temperature range is limited to  $-40^{\circ}$ C to  $85^{\circ}$ C. The tracking error is calculated using the box method, as described by Equation 2:

Tracking Error = 
$$\left(\frac{V_{\text{DIFF}(MAX)} - V_{\text{DIFF}(MIN)}}{V_{\text{REF}} \bullet \text{Temperature Range}}\right) \bullet 10^6 \text{ (ppm)}$$
 (2)

where

•  $V_{\text{DIFF}} = V_{\text{REF}} - 2 \cdot V_{\text{BIAS}}$ 



The tracking accuracy is as shown in Figure 9-1.

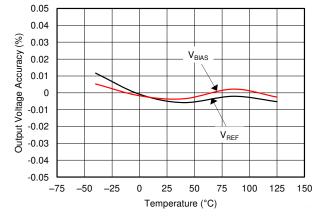


Figure 9-1.  $V_{\text{REF}}$  and  $V_{\text{BIAS}}$  Tracking vs Temperature

## 9.3.2 Low Temperature Drift

The REF20xx is designed for minimal drift error, which is defined as the change in output voltage over temperature. The drift is calculated using the box method, as described by Equation 3:

$$Drift = \left(\frac{V_{REF(MAX)} - V_{REF(MIN)}}{V_{REF} \bullet Temperature Range}\right) \bullet 10^{6} \quad (ppm)$$
(3)

## 9.3.3 Load Current

The REF20xx family is specified to deliver a current load of  $\pm 20$  mA per output. Both the V<sub>REF</sub> and V<sub>BIAS</sub> outputs of the device are protected from short circuits by limiting the output short-circuit current to 50 mA. The device temperature increases according to Equation 4:

$$\mathsf{T}_{\mathsf{J}} = \mathsf{T}_{\mathsf{A}} + \mathsf{P}_{\mathsf{D}} \bullet \mathsf{R}_{\mathsf{\theta}\mathsf{J}\mathsf{A}} \tag{4}$$

where

- $T_J$  = junction temperature (°C),
- T<sub>A</sub> = ambient temperature (°C),
- P<sub>D</sub> = power dissipated (W), and
- $R_{\theta JA}$  = junction-to-ambient thermal resistance (°C/W)

The REF20xx maximum junction temperature must not exceed the absolute maximum rating of 150°C.

## 9.4 Device Functional Modes

When the EN pin of the REF20xx is pulled high, the device is in active mode. The device should be in active mode for normal operation. The REF20xx can be placed in a low-power mode by pulling the ENABLE pin low. When in shutdown mode, the output of the device becomes high impedance and the quiescent current of the device reduces to 5  $\mu$ A in shutdown mode. See the *Section 7.5* for logic high and logic low voltage levels.



## **10** Applications and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## **10.1 Application Information**

The low-drift, bidirectional, single-supply, low-side, current-sensing solution, described in this section, can accurately detect load currents from –2.5 A to 2.5 A. The linear range of the output is from 250 mV to 2.75 V. Positive current is represented by output voltages from 1.5 V to 2.75 V, whereas negative current is represented by output voltages from 250 mV to 1.5 V. The difference amplifier is the INA213 current-shunt monitor, whose supply and reference voltages are supplied by the low-drift REF2030.

Industrial applications with electronics in corrosive environments are susceptible to corrosive damage due to the exposure to heat, moisture, and corrosive gases. The combination of the following conditions in a given system lead to higher risk of corrosive damage:

- 1. Ventilated enclosures exposing underlying PCB.
- 2. PCBs not conformally coated.
- 3. Exposed-lead components with plating susceptible to corrosion.
- 4. Changes in plating techniques for RoHS compliance (e.g. removal of Pb (lead) and certain types of plating).

To improve resistance to corrosion in harsh environments, the REF2025AISDDCR uses Matte-Sn plating with improved assembly process to reduce exposed Cu, leading to improved corrosion resistance in the Battelle Class III and similar harsh environments. The "S" in the part number identifies this special plating option. REF2025 versions that do not have the "S" will continue to be available in industry standard NiPdAu processing technique.



# **10.2 Typical Application**

10.2.1 Low-Side, Current-Sensing Application

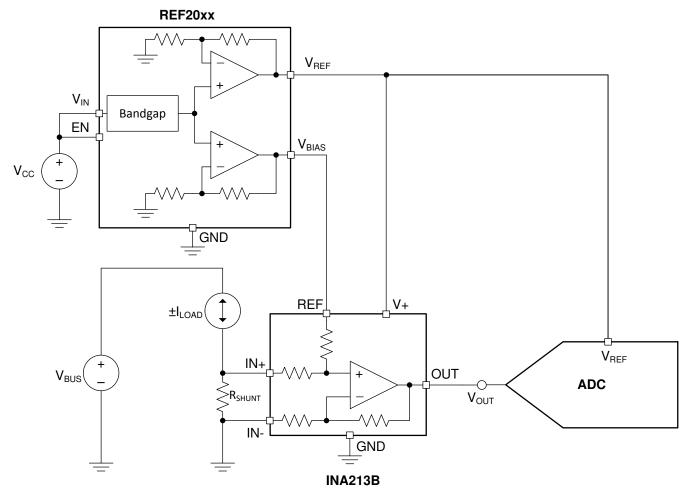


Figure 10-1. Low-Side, Current-Sensing Application



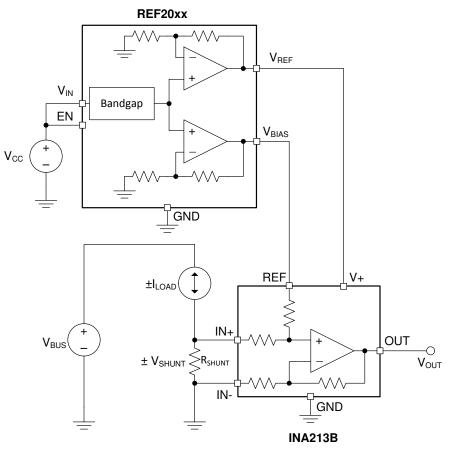
#### 10.2.1.1 Design Requirements

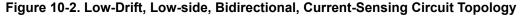
The design requirements are as follows:

- 1. Supply voltage: 5.0 V
- 2. Load current: ±2.5 A
- 3. Output: 250 mV to 2.75 V
- 4. Maximum shunt voltage: ±25 mV

#### 10.2.1.2 Detailed Design Procedure

Low-side current sensing is desirable because the common-mode voltage is near ground. Therefore, the currentsensing solution is independent of the bus voltage,  $V_{BUS}$ . When sensing bidirectional currents, use a differential amplifier with a reference pin. This procedure allows for the differentiation between positive and negative currents by biasing the output stage such that it can respond to negative input voltages. There are a variety of methods for supplying power (V+) and the reference voltage ( $V_{REF}$ , or  $V_{BIAS}$ ) to the differential amplifier. For a low-drift solution, use a monolithic reference that supplies both power and the reference voltage. Figure 10-2 shows the general circuit topology for a low-drift, low-side, bidirectional, current-sensing solution. This topology is particularly useful when interfacing with an ADC; see Figure 10-1. Not only do  $V_{REF}$  and  $V_{BIAS}$  track over temperature, but their matching is much better than alternate topologies. For a more detailed version of the design procedure, refer to TIDU357.





The transfer function for the circuit given in Figure 10-2 is as shown in Equation 5:

$$V_{OUT} = G \bullet (\pm V_{SHUNT}) + V_{BIAS}$$
$$= G \bullet (\pm I_{LOAD} \bullet R_{SHUNT}) + V_{BIAS}$$

(5)



#### 10.2.1.2.1 Shunt Resistor

As illustrated in Figure 10-2, the value of  $V_{SHUNT}$  is the ground potential for the system load. If the value of  $V_{SHUNT}$  is too large, issues may arise when interfacing with systems whose ground potential is actually 0 V. Also, a value of  $V_{SHUNT}$  that is too negative may violate the input common-mode voltage of the differential amplifier in addition to potential interfacing issues. Therefore, limiting the voltage across the shunt resistor is important. Equation 6 can be used to calculate the maximum value of  $R_{SHUNT}$ .

$$R_{SHUNT(max)} = \frac{V_{SHUNT(max)}}{I_{LOAD(max)}}$$

(6)

Given that the maximum shunt voltage is  $\pm 25$  mV and the load current range is  $\pm 2.5$  A, the maximum shunt resistance is calculated as shown in Equation 7.

$$R_{SHUNT (max)} = \frac{V_{SHUNT (max)}}{I_{LOAD (max)}} = \frac{25mV}{2.5A} = 10m\Omega$$
(7)

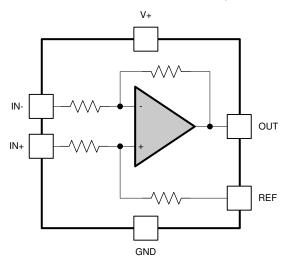
To minimize errors over temperature, select a low-drift shunt resistor. To minimize offset error, select a shunt resistor with the lowest tolerance. For this design, the Y14870R01000B9W resistor is used.

#### 10.2.1.2.2 Differential Amplifier

The differential amplifier used for this design should have the following features:

- 1. Single-supply (3 V),
- 2. Reference voltage input,
- 3. Low initial input offset voltage (V<sub>OS</sub>),
- 4. Low-drift,
- 5. Fixed gain, and
- 6. Low-side sensing (input common-mode range below ground).

For this design, a current-shunt monitor (INA213) is used. The INA21x family topology is shown in Figure 10-3. The INA213B specifications can be found in the INA213 product data sheet.



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#### Figure 10-3. INA21x Current-Shunt Monitor Topology

The INA213B is an excellent choice for this application because all the required features are included. In general, instrumentation amplifiers (INAs) do not have the input common-mode swing to ground that is essential for this application. In addition, INAs require external resistors to set their gain, which is not desirable for low-drift applications. Difference amplifiers typically have larger input bias currents, which reduce solution accuracy at



small load currents. Difference amplifiers typically have a gain of 1 V/V. When the gain is adjustable, these amplifiers use external resistors that are not conducive to low-drift applications.

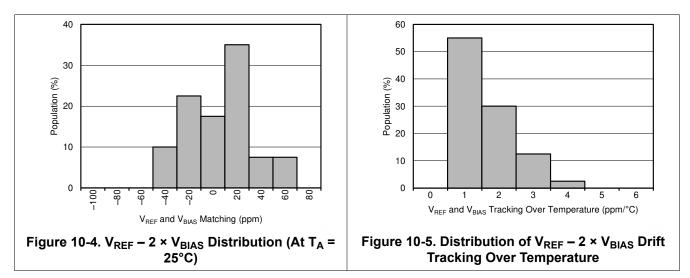
#### 10.2.1.2.3 Voltage Reference

The voltage reference for this application should have the following features:

- 1. Dual output (3.0 V and 1.5 V),
- 2. Low drift, and
- 3. Low tracking errors between the two outputs.

For this design, the REF2030 is used. The REF20xx topology is as shown in the Section 9.2 section.

The REF2030 is an excellent choice for this application because of its dual output. The temperature drift of 8 ppm/°C and initial accuracy of 0.05% make the errors resulting from the voltage reference minimal in this application. In addition, there is minimal mismatch between the two outputs and both outputs track very well across temperature, as shown in Figure 10-4 and Figure 10-5.



#### 10.2.1.2.4 Results

Table 10-1 summarizes the measured results.

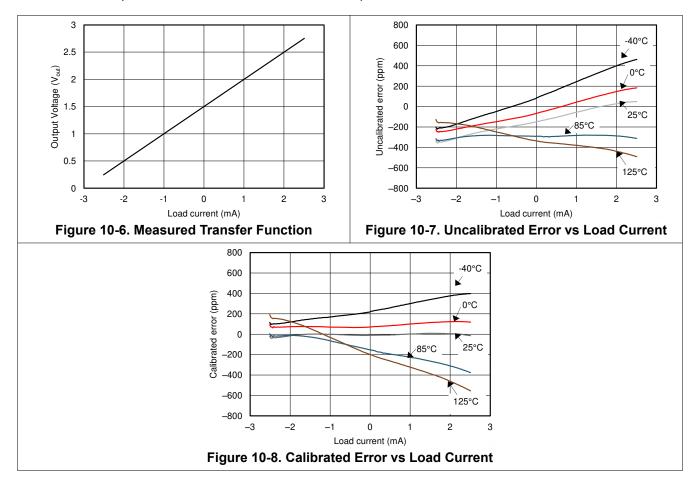
#### Table 10-1. Measured Results

ERROR	UNCALIBRATED (%)	CALIBRATED (%)
Error across the full load current range (25°C)	±0.0355	±0.004
Error across the full load current range (-40°C to 125°C)	±0.0522	±0.0606



### 10.2.1.3 Application Curves

Performing a two-point calibration at 25°C removes the errors associated with offset voltage, gain error, and so forth. Figure 10-6 to Figure 10-8 show the measured error at different conditions. For a more detailed description on measurement procedure, calibration, and calculations, please refer to TIDU357.





# 11 Power-Supply Recommendations

The REF20xx family of references feature an extremely low-dropout voltage. These references can be operated with a supply of only 20 mV above the output voltage. For loaded reference conditions, a typical dropout voltage versus load is shown in Figure 11-1. A supply bypass capacitor ranging between 0.1  $\mu$ F to 10  $\mu$ F is recommended.

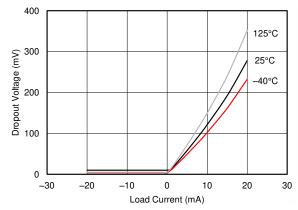


Figure 11-1. Dropout Voltage vs Load Current



# 12 Layout

# 12.1 Layout Guidelines

Figure 12-1 shows an example of a PCB layout for a data acquisition system using the REF2030. Some key considerations are:

- Connect low-ESR, 0.1-μF ceramic bypass capacitors at V<sub>IN</sub>, V<sub>REF</sub>, and V<sub>BIAS</sub> of the REF2030.
- Decouple other active devices in the system per the device specifications.
- Using a solid ground plane helps distribute heat and reduces electromagnetic interference (EMI) noise pickup.
- Place the external components as close to the device as possible. This configuration prevents parasitic errors (such as the Seebeck effect) from occurring.
- Minimize trace length between the reference and bias connections to the INA and ADC to reduce noise pickup.
- Do not run sensitive analog traces in parallel with digital traces. Avoid crossing digital and analog traces if possible, and only make perpendicular crossings when absolutely necessary.

## 12.2 Layout Example

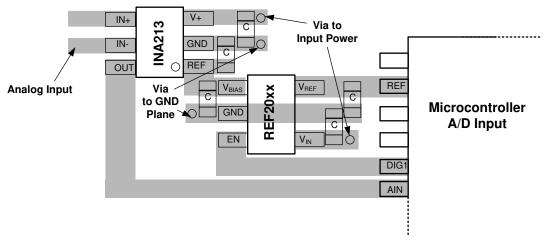


Figure 12-1. Layout Example



## 13 Device and Documentation Support

## **13.1 Documentation Support**

## 13.1.1 Related Documentation

For related documentation see the following:

- INA21x Voltage Output, Low- or High-Side Measurement, Bidirectional, Zero-Drift Series, Current-Shunt Monitors (SBOS437)
- Low-Drift Bidirectional Single-Supply Low-Side Current Sensing Reference Design (TIDU357)

## **13.2 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## **13.3 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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TI E2E<sup>™</sup> is a trademark of Texas Instruments.

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#### **13.5 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 13.6 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



9-Mar-2021

# PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		aly	(2)	(6)	(3)		(4/5)	
REF2025AIDDCR	ACTIVE	SOT-23-THIN	DDC	5	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GACM	Samples
REF2025AIDDCT	ACTIVE	SOT-23-THIN	DDC	5	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GACM	Samples
REF2025AISDDCR	ACTIVE	SOT-23-THIN	DDC	5	3000	RoHS & Green	Call TI	Level-2-260C-1 YEAR	-40 to 125	1M98	Samples
REF2030AIDDCR	ACTIVE	SOT-23-THIN	DDC	5	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GADM	Samples
REF2030AIDDCT	ACTIVE	SOT-23-THIN	DDC	5	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GADM	Samples
REF2033AIDDCR	ACTIVE	SOT-23-THIN	DDC	5	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GAEM	Samples
REF2033AIDDCT	ACTIVE	SOT-23-THIN	DDC	5	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GAEM	Samples
REF2041AIDDCR	ACTIVE	SOT-23-THIN	DDC	5	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GAFM	Samples
REF2041AIDDCT	ACTIVE	SOT-23-THIN	DDC	5	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	GAFM	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.



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# PACKAGE OPTION ADDENDUM

9-Mar-2021

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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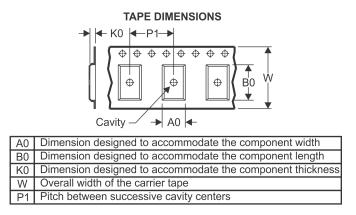
# PACKAGE MATERIALS INFORMATION

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# TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
REF2025AIDDCR	SOT- 23-THIN	DDC	5	3000	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2025AIDDCT	SOT- 23-THIN	DDC	5	250	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2025AISDDCR	SOT- 23-THIN	DDC	5	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2030AIDDCR	SOT- 23-THIN	DDC	5	3000	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2030AIDDCT	SOT- 23-THIN	DDC	5	250	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2033AIDDCR	SOT- 23-THIN	DDC	5	3000	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2033AIDDCT	SOT- 23-THIN	DDC	5	250	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2041AIDDCR	SOT- 23-THIN	DDC	5	3000	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
REF2041AIDDCT	SOT- 23-THIN	DDC	5	250	179.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

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# PACKAGE MATERIALS INFORMATION

10-Mar-2021



*All dimensions are nominal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
REF2025AIDDCR	SOT-23-THIN	DDC	5	3000	213.0	191.0	35.0
REF2025AIDDCT	SOT-23-THIN	DDC	5	250	213.0	191.0	35.0
REF2025AISDDCR	SOT-23-THIN	DDC	5	3000	213.0	191.0	35.0
REF2030AIDDCR	SOT-23-THIN	DDC	5	3000	213.0	191.0	35.0
REF2030AIDDCT	SOT-23-THIN	DDC	5	250	213.0	191.0	35.0
REF2033AIDDCR	SOT-23-THIN	DDC	5	3000	213.0	191.0	35.0
REF2033AIDDCT	SOT-23-THIN	DDC	5	250	213.0	191.0	35.0
REF2041AIDDCR	SOT-23-THIN	DDC	5	3000	213.0	191.0	35.0
REF2041AIDDCT	SOT-23-THIN	DDC	5	250	213.0	191.0	35.0

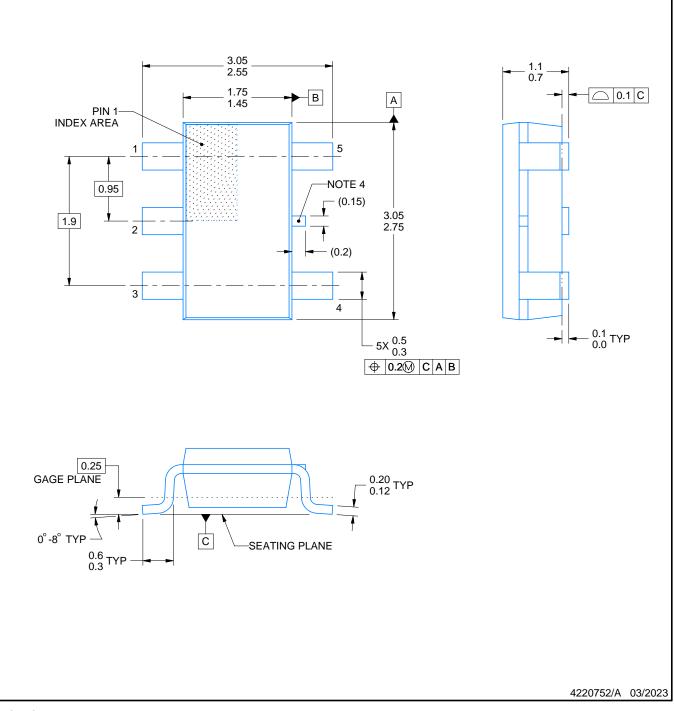
# **DDC0005A**



# **PACKAGE OUTLINE**

# SOT-23 - 1.1 max height

SMALL OUTLINE TRANSISTOR



NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
   This drawing is subject to change without notice.
   Reference JEDEC MO-193.

- 4. Support pin may differ or may not be present.

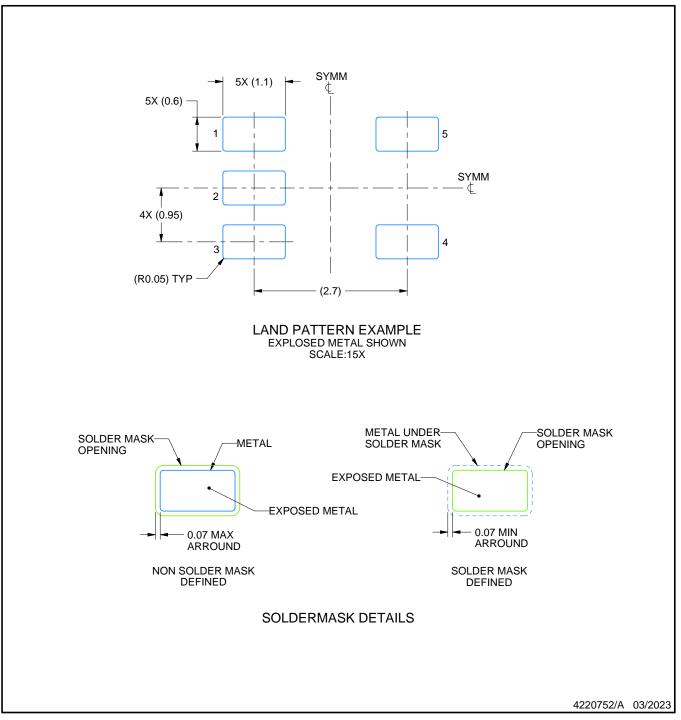


# DDC0005A

# **EXAMPLE BOARD LAYOUT**

# SOT-23 - 1.1 max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

4. Publication IPC-7351 may have alternate designs.

5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

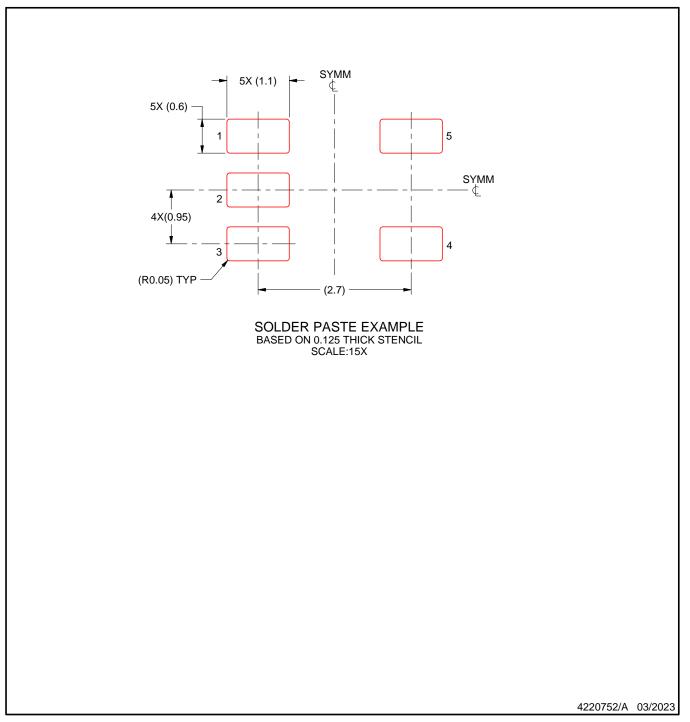


# **DDC0005A**

# **EXAMPLE STENCIL DESIGN**

# SOT-23 - 1.1 max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)



<sup>6.</sup> Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations. 7. Board assembly site may have different recommendations for stencil design.

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