TPS62770 Multi-Rail DC/DC Converter For Wearable Applications

1 Features

- VIN Range 2.5 V to 5.5 V
- 370 nA Iq Step-Down Converter
  - 8 Selectable Output Voltages (1.0V to 3.0V)
  - 300 mA Output Current
  - Output Discharge Function
- Slew Rate Controlled Load Switch with Discharge Function
- Dual Mode Step-Up Converter
  - Load Disconnect
  - Constant Output Voltage Adjustable up to 15 V (V_{FB} 0.8 V) / 12 V Fixed
  - LED Current Driver with PWM to Current Conversion (max V_{FB} Voltage 200 mV @ D = 100%)
- Tiny 16pin 1.58 x 1.58mm WCSP Package 0.4mm pitch

2 Applications

- Wearable and Personal Electronics
- Fitness Accessories
- Health Monitoring and Medical Accessories

3 Description

The TPS62770 is a tiny power solution for wearable applications including a 370nA ultra low Iq step-down converter, a slew rate controlled load switch and a dual mode step-up converter. The output voltage of the step-down converter can be selected with three VSEL pins between 1.0 V, 1.05 V, 1.1 V, 1.2 V, 1.8 V, 1.9 V, 2.0 V and 3.0 V. The output voltage can be changed during operation. In shutdown mode, the output of the step-down converter is pulled to GND. The integrated load switch is internally connected to the output of the step-down converter and features slew rate control during turn on phase. Once turned off, its output is connected to GND.

The dual mode step-up converter can generate a constant output voltage up to 15 V, such as PMOLED supply; or, a constant output current, such as LED back light supply. The output voltage can be adjusted up to 15 V with external resistors, or set to fixed 12 V by connecting the FB pin to VIN. The device features an internal over voltage protection of 17.7 V in case the FB node is left open or tight to GND. It includes an internal rectifier and load disconnect function. When used as constant output current driver, the device offers a PWM to analog converter to scale down the reference voltage according to the duty cycle of the PWM signal.

The device is available in a small 16pin 0.4mm pitch WCSP package.

Device Information

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>PACKAGE</th>
<th>BODY SIZE (NOM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>TPS62770</td>
<td>DSBGA (16)</td>
<td>1.58mm x 1.58mm</td>
</tr>
</tbody>
</table>

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Application Schematic
# Table of Contents

1 Features .......................................................... 1  
2 Applications .................................................. 1  
3 Description ..................................................... 1  
4 Revision History ................................................ 2  
5 Pin Configuration and Functions .......................... 3  
6 Specifications .................................................. 4  
   6.1 Absolute Maximum Ratings .............................. 4  
   6.2 ESD Ratings .................................................. 4  
   6.3 Recommended Operating Conditions ................. 5  
   6.4 Thermal Information ....................................... 5  
   6.5 Electrical Characteristics ................................ 5  
   6.6 Typical Characteristics .................................. 8  
7 Detailed Description .......................................... 9  
   7.1 Overview .................................................... 9  
   7.2 Functional Block Diagram ............................... 9  
   7.3 Feature Description ....................................... 10  
6.4 Device Functional Modes ................................ 13  
8 Application and Implementation ......................... 17  
   8.1 Application Information .................................. 17  
   8.2 Typical Applications ...................................... 18  
9 Power Supply Recommendations ......................... 32  
10 Layout .......................................................... 32  
   10.1 Layout Guidelines ........................................ 32  
   10.2 Layout Example .......................................... 33  
11 Device and Documentation Support ..................... 34  
   11.1 Device Support ............................................ 34  
   11.2 Documentation Support ................................ 34  
   11.3 Trademarks.................................................. 34  
   11.4 Electrostatic Discharge Caution .................... 34  
   11.5 Glossary .................................................... 34  
12 Mechanical, Packaging, and Orderable Information 34  

## 4 Revision History

### Changes from Revision A (March 2016) to Revision B  
- Changed Application and Implementation section organization for clarity ........................................... 17

### Changes from Original (February 2016) to Revision A  
- Changed device status to Production Data and released the full data sheet ........................................... 1
5 Pin Configuration and Functions

Table 1. Pin Functions

<table>
<thead>
<tr>
<th>PIN</th>
<th>I/O</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>EN2/PWM</td>
<td>B3</td>
<td>IN</td>
</tr>
<tr>
<td>GND2</td>
<td>A1</td>
<td>PWR</td>
</tr>
<tr>
<td>SW2</td>
<td>A2</td>
<td>IN</td>
</tr>
<tr>
<td>VO2</td>
<td>A3</td>
<td>OUT</td>
</tr>
<tr>
<td>BM</td>
<td>B1</td>
<td>IN</td>
</tr>
<tr>
<td>FB</td>
<td>B4</td>
<td>IN</td>
</tr>
<tr>
<td>EN1</td>
<td>C2</td>
<td>IN</td>
</tr>
<tr>
<td>VSEL1</td>
<td>C3</td>
<td>IN</td>
</tr>
<tr>
<td>VSEL2</td>
<td>B2</td>
<td>IN</td>
</tr>
<tr>
<td>VSEL3</td>
<td>A4</td>
<td>IN</td>
</tr>
<tr>
<td>CTRL</td>
<td>C4</td>
<td>IN</td>
</tr>
<tr>
<td>VIN</td>
<td>D1</td>
<td>PWR</td>
</tr>
<tr>
<td>GND1</td>
<td>D2</td>
<td>PWR</td>
</tr>
<tr>
<td>SW1</td>
<td>C1</td>
<td>OUT</td>
</tr>
<tr>
<td>VO1</td>
<td>D3</td>
<td>OUT</td>
</tr>
<tr>
<td>LOAD</td>
<td>D4</td>
<td>OUT</td>
</tr>
</tbody>
</table>
Table 2. Output Voltage Setting Step-Down Converter

<table>
<thead>
<tr>
<th>VO1 [V]</th>
<th>VSEL3</th>
<th>VSEL2</th>
<th>VSEL1</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1.05</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1.1</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1.2</td>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>1.8</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1.9</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>2.0</td>
<td>1</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>3.0</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

<table>
<thead>
<tr>
<th>Pin voltage(2)</th>
<th>MIN</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>VIN, FB</td>
<td>–0.3</td>
<td>6</td>
<td>V</td>
</tr>
<tr>
<td>SW1</td>
<td>–0.3</td>
<td>V&lt;sub&gt;IN&lt;/sub&gt; +0.3V</td>
<td>V</td>
</tr>
<tr>
<td>EN1, EN2/PWM, CTRL, BM, VSEL1-3</td>
<td>–0.3</td>
<td>V&lt;sub&gt;IN&lt;/sub&gt; +0.3V</td>
<td>V</td>
</tr>
<tr>
<td>SW2, VO2</td>
<td>–0.3</td>
<td>32</td>
<td>V</td>
</tr>
<tr>
<td>VO1, LOAD</td>
<td>–0.3</td>
<td>3.7</td>
<td>V</td>
</tr>
<tr>
<td>T&lt;sub&gt;J&lt;/sub&gt;</td>
<td>–40</td>
<td>125</td>
<td>°C</td>
</tr>
<tr>
<td>T&lt;sub&gt;stg&lt;/sub&gt;</td>
<td>–65</td>
<td>150</td>
<td>°C</td>
</tr>
</tbody>
</table>

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal GND.

6.2 ESD Ratings

<table>
<thead>
<tr>
<th>V&lt;sub&gt;(ESD)&lt;/sub&gt;</th>
<th>ELECTROSTATIC DISCHARGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins&lt;sup&gt;(1)&lt;/sup&gt;</td>
<td>±2000</td>
</tr>
<tr>
<td>Charged device model (CDM), per JEDEC specification JESD22-C101, all pins&lt;sup&gt;(2)&lt;/sup&gt;</td>
<td>±500</td>
</tr>
</tbody>
</table>

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. The human body model is a 100-pF capacitor discharged through a 1.5-kΩ resistor into each pin.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.
6.3 Recommended Operating Conditions

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Test Conditions</th>
<th>MIN</th>
<th>NOM</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>V_{IN}</strong></td>
<td>Input voltage range at VIN pin</td>
<td>2.5</td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td><strong>I_{OUT1}</strong></td>
<td>DC/DC 1 Step down converter output current, L1 = 2.2\mu H, C_{OUT1} = 10 \mu F</td>
<td>300</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>I_{OUT2}</strong></td>
<td>DC/DC 2 Step up converter output current, 2.5V &lt; VIN &lt; 5.5V, VOUT2 = 12V, C_{OUT2} = 10 \mu F, L = 10 \mu H</td>
<td>30</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>2.5V &lt; VIN &lt; 5.5V, VOUT2 = 12V, C_{OUT2} = 2x 10 \mu F, L = 10 \mu H</td>
<td>100</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3V &lt; VIN &lt; 5.5V, VOUT2 = 5V, C_{OUT2} = 2x 10 \mu F, L = 4.7 \mu H</td>
<td>200</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>I_{LOAD}</strong></td>
<td>Load current (current from LOAD pin)</td>
<td>100</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>T_J</strong></td>
<td>Operating junction temperature range</td>
<td>-40</td>
<td>125</td>
<td>°C</td>
<td></td>
</tr>
<tr>
<td><strong>T_A</strong></td>
<td>Ambient temperature range</td>
<td>-40</td>
<td>85</td>
<td>°C</td>
<td></td>
</tr>
</tbody>
</table>

6.4 Thermal Information

<table>
<thead>
<tr>
<th>THERMAL METRIC(1)</th>
<th>TPS62770</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>R_{JA}</td>
<td>Junction-to-ambient thermal resistance</td>
<td>90.6</td>
</tr>
<tr>
<td>R_{JC,Top}</td>
<td>Junction-to-case (top) thermal resistance</td>
<td>0.6</td>
</tr>
<tr>
<td>R_{JB}</td>
<td>Junction-to-board thermal resistance</td>
<td>13.8</td>
</tr>
<tr>
<td>\psi_{JT}</td>
<td>Junction-to-top characterization parameter</td>
<td>2.8</td>
</tr>
<tr>
<td>\psi_{JB}</td>
<td>Junction-to-board characterization parameter</td>
<td>13.7</td>
</tr>
<tr>
<td>R_{JC,bot}</td>
<td>Junction-to-case (bottom) thermal resistance</td>
<td>n/a</td>
</tr>
</tbody>
</table>

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

6.5 Electrical Characteristics

V_{IN} = 3.6V, T_A = -40°C to 85°C typical values are at T_A = 25°C (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SUPPLY</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I_{SD}</td>
<td>Shutdown current into V_{IN}</td>
<td>EN1 = EN2/PWM = GND, CTRL GND, BM = GND,</td>
<td>0.1</td>
<td>1850</td>
<td>nA</td>
</tr>
<tr>
<td>V_{TH, UVLO+}</td>
<td>Undervoltage lockout threshold</td>
<td>Rising V_{IN}</td>
<td>2.1</td>
<td>2.22</td>
<td>V</td>
</tr>
<tr>
<td>V_{TH, UVLO-}</td>
<td></td>
<td>Falling V_{IN}</td>
<td>1.9</td>
<td>2</td>
<td>V</td>
</tr>
<tr>
<td><strong>INPUTS EN1, EN2/PWM, BM, CTRL, VSEL 1-3</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>V_{H, TH}</td>
<td>High level input threshold</td>
<td>EN1 = EN2/PWM = GND, BM = GND,</td>
<td>1.2</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>V_{L, TH}</td>
<td>Low level input threshold</td>
<td>EN1 = EN2/PWM = GND, BM = GND,</td>
<td>0.4</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>I_{IN}</td>
<td>Input bias Current</td>
<td>T_J = 25°C</td>
<td>10</td>
<td></td>
<td>nA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>T_J = -40°C to 85°C</td>
<td>25</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Electrical Characteristics (continued)

\( V_{IN} = 3.6 \text{V}, \ T_A = -40^\circ \text{C} \text{ to } 85^\circ \text{C} \text{ typical values are at } T_A = 25^\circ \text{C} \) (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_Q )</td>
<td>Operating quiescent current</td>
<td>EN1 = ( V_{IN} ), EN2/PWM = GND, CTRL = GND, ( I_{OUT} = 0 \mu \text{A}, \ V_{OUT} = 1.8 \text{V} ), device not switching, EN1 = ( V_{IN} ), EN2/PWM = GND, ( I_{OUT} = 0 \mu \text{A}, \ CTRL = \text{GND}, \ V_{OUT} = 1.8 \text{V} ), device switching</td>
<td>370</td>
<td>1850</td>
<td>nA</td>
</tr>
<tr>
<td>( V_{OUT} )</td>
<td>Output voltage range</td>
<td>1.0</td>
<td>3.0</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Output voltage accuracy</td>
<td>PFM mode</td>
<td>-2.5</td>
<td>0</td>
<td>2.5 %</td>
</tr>
<tr>
<td></td>
<td>DC output voltage load regulation</td>
<td>PWM mode</td>
<td>-2</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>DC output voltage line regulation</td>
<td>( V_{OUT} = 1.8 \text{V} ), ( I_{OUT} = 10 \mu \text{A}, 2.5 \text{V} \leq V_{IN} \leq 5.5 \text{V} )</td>
<td></td>
<td>0</td>
<td>%/mA</td>
</tr>
<tr>
<td>( R_{D(ON)} )</td>
<td>High side MOSFET on-resistance</td>
<td>( I_{OUT} = 50 \mu \text{A} )</td>
<td></td>
<td>0.45</td>
<td>\Omega</td>
</tr>
<tr>
<td></td>
<td>Low Side MOSFET on-resistance</td>
<td></td>
<td></td>
<td>0.22</td>
<td>\Omega</td>
</tr>
<tr>
<td>( I_{LIMF} )</td>
<td>High side MOSFET switch current limit</td>
<td></td>
<td></td>
<td>480</td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td>Low side MOSFET switch current limit</td>
<td></td>
<td></td>
<td>600</td>
<td>mA</td>
</tr>
<tr>
<td>( R_{DISCH_VO1} )</td>
<td>Discharge switch on-resistance</td>
<td>EN = GND, ( I_{VO1} = -10 \mu \text{A} ) into VO1 pin</td>
<td></td>
<td>20</td>
<td>65</td>
</tr>
<tr>
<td>( I_{IN_VO1} )</td>
<td>Bias current into VO1 pin</td>
<td>EN = ( V_{IN} ), ( V_{OUT} = 1.8 \text{V} )</td>
<td>( T_J = 25^\circ \text{C} )</td>
<td>40</td>
<td>100</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>( T_J = -40^\circ \text{C} \text{ to } 85^\circ \text{C} )</td>
<td></td>
<td>1010</td>
</tr>
<tr>
<td>( V_{TH,100+} )</td>
<td>Auto 100% Mode leave detection threshold (1)</td>
<td>Rising ( V_{IN} ), 100% Mode is left with ( V_{IN} = V_{OUT} + V_{TH,100+} ), max value at ( T_J = 85^\circ \text{C} )</td>
<td></td>
<td>150</td>
<td>250</td>
</tr>
<tr>
<td>( V_{TH,100-} )</td>
<td>Auto 100% Mode enter detection threshold (1)</td>
<td>Falling ( V_{IN} ), 100% Mode is entered with ( V_{IN} = V_{OUT} + V_{TH,100-} ), max value at ( T_J = 85^\circ \text{C} )</td>
<td></td>
<td>85</td>
<td>200</td>
</tr>
<tr>
<td>( t_{ONmin} )</td>
<td>Minimum ON time</td>
<td>( V_{OUT} = 2.0 \text{V}, \ I_{OUT} = 0 \mu \text{A} )</td>
<td></td>
<td>225</td>
<td>ns</td>
</tr>
<tr>
<td>( t_{OFFmin} )</td>
<td>Minimum OFF time</td>
<td></td>
<td></td>
<td>50</td>
<td>ns</td>
</tr>
<tr>
<td>( t_{SUDDelay} )</td>
<td>Regulator start up delay time</td>
<td>From transition EN1 = low to high until device starts switching</td>
<td></td>
<td>1</td>
<td>5</td>
</tr>
<tr>
<td>( I_{SOFTS} )</td>
<td>Softstart time with reduced switch current limit</td>
<td></td>
<td></td>
<td>700</td>
<td>1200</td>
</tr>
<tr>
<td>( I_{LIM_{SOFTS}} )</td>
<td>High side MOSFET switch current limit</td>
<td>Reduced switch current limit during softstart</td>
<td></td>
<td>80</td>
<td>150</td>
</tr>
<tr>
<td></td>
<td>Low side MOSFET switch current limit</td>
<td></td>
<td></td>
<td>150</td>
<td></td>
</tr>
</tbody>
</table>

LOAD SWITCH

| \( R_{LOAD} \) | MOSFET on-resistance | \( I_{LOAD} = 50 \mu \text{A}, \ CTRL = V_{IN}, \ V_{OUT} = 1.8 \text{V} \) | | 0.6 | 1.27 | \Omega |
| \( t_{LOADrise} \) | \( V_{LOAD} \) rise time | Starting with CTRL low to high transition, time to ramp \( V_{LOAD} \) from 95%, \( V_{LOAD} = 1.8 \text{V}, \ I_{LOAD} = 20 \mu \text{A} \) | | 315 | 800 | \mu s |
| \( R_{OCHRG} \) | MOSFET on-resistance | | | 20 | 65 | \Omega |

(1) \( V_{IN} \) is compared to the programmed output voltage (\( V_{OUT} \)). When \( V_{IN} - V_{OUT} \) falls below \( V_{TH,100-} \), the device enters 100% Mode by turning the high side MOSFET on. The 100% Mode is exited when \( V_{IN} - V_{OUT} \) exceeds \( V_{TH,100+} \), and the device starts switching. The hysteresis for the 100% Mode detection threshold \( V_{TH,100-} - V_{TH,100+} \) will always be positive and will be approximately 50 mV (typ.)
### Electrical Characteristics (continued)

\( V_{IN} = 3.6\ V, \ T_A = -40^\circ C \) to 85°C typical values are at \( T_A = 25^\circ C \) (unless otherwise noted)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>( I_{Q,\text{VIN}} )</td>
<td>Quiescent current into VIN pin</td>
<td>EN2/PWM = VIN, BM = GND, EN1 = GND, no load, no switching, ( V_{OUT} = 12 \ V )</td>
<td>110</td>
<td>200</td>
<td>( \mu A )</td>
</tr>
<tr>
<td>( V_{OUT} )</td>
<td>Output voltage range</td>
<td>EN2/PWM = VIN, BM = GND</td>
<td>4.5</td>
<td>15</td>
<td>V</td>
</tr>
<tr>
<td>( V_{OUT,12V} )</td>
<td>12-V output voltage accuracy</td>
<td>FB pin connected to VIN pin, EN2/PWM = VIN, BM = GND</td>
<td>11.7</td>
<td>12</td>
<td>12.3</td>
</tr>
<tr>
<td>( V_{FB} )</td>
<td>Feedback voltage</td>
<td>PWM mode, BM = GND, EN2/PWM = VIN</td>
<td>0.775</td>
<td>0.795</td>
<td>0.814</td>
</tr>
<tr>
<td></td>
<td></td>
<td>PFM mode, BM = GND, EN2/PWM = VIN</td>
<td>0.803</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Feedback regulation voltage under brightness control</td>
<td>EN2/PWM = VIN, BM = VIN, VFB ( = 50mV ), BM = VIN, D(PWM) @ EN2/PWM = 25%,</td>
<td>189</td>
<td>200</td>
<td>206</td>
</tr>
<tr>
<td></td>
<td></td>
<td>VFB ( = 20mV ), BM = VIN, D(PWM) @ EN2/PWM = 10%</td>
<td>40</td>
<td>50</td>
<td>60</td>
</tr>
<tr>
<td></td>
<td></td>
<td>189</td>
<td>200</td>
<td>206</td>
<td>mV</td>
</tr>
<tr>
<td>( t_{\text{Dim,Off}} )</td>
<td>Dimming signal on pin EN2/PWM</td>
<td></td>
<td>270</td>
<td>160</td>
<td>( \mu s )</td>
</tr>
<tr>
<td>( t_{\text{Dim,On}} )</td>
<td>Dimming signal on</td>
<td></td>
<td>1</td>
<td>( \mu s )</td>
<td></td>
</tr>
<tr>
<td>( V_{DV,\text{HYS}} )</td>
<td>Output overvoltage protection threshold</td>
<td>17</td>
<td>17.7</td>
<td>18.4</td>
<td>V</td>
</tr>
<tr>
<td>( R_{DS(on)} )</td>
<td>Isolation MOSFET on resistance</td>
<td>( V_{OUT} = 12 \ V )</td>
<td>850</td>
<td>mΩ</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Low-side MOSFET on resistance</td>
<td>( V_{OUT} = 12 \ V )</td>
<td>450</td>
<td></td>
</tr>
<tr>
<td>( f_{SW} )</td>
<td>Switching frequency</td>
<td>( V_{OUT} = 12 \ V, \text{PWM mode} )</td>
<td>850</td>
<td>1050</td>
<td>1250</td>
</tr>
<tr>
<td>( I_{ON,\text{min}} )</td>
<td>Minimal switch on time</td>
<td></td>
<td>150</td>
<td>250</td>
<td>ns</td>
</tr>
<tr>
<td>( I_{\text{LIM,SW}} )</td>
<td>Peak switch current limit</td>
<td>( V_{OUT} = 12 \ V )</td>
<td>730</td>
<td>970</td>
<td>1230</td>
</tr>
<tr>
<td>( I_{\text{LIM,CHG}} )</td>
<td>Pre-charge current</td>
<td>( V_{OUT} = 0 \ V )</td>
<td>30</td>
<td>55</td>
<td>mA</td>
</tr>
<tr>
<td>( I_{\text{OUT,sw}} )</td>
<td>Pre-charge time</td>
<td>BM = GND, EN2/PWM from low to high until device starts switching, ( I_{\text{OUT,CHG}} = 0 \text{mA, } C_{\text{OUT,eff}} = 10\mu F )</td>
<td>6</td>
<td></td>
<td>ms</td>
</tr>
<tr>
<td></td>
<td>Startup time</td>
<td>( V_{OUT} ) from ( V_{IN} ) to 12 ( V ), ( C_{\text{OUT,eff}} = 2.2 \text{ } \mu F, \text{ } I_{\text{OUT}} = 0 \text{mA} )</td>
<td>6</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Copyright © 2016, Texas Instruments Incorporated
6.6 Typical Characteristics

**Figure 1. Quiescent Current $I_Q$ Step-Down converter**

**Figure 2. Quiescent Current $I_Q$ Step-Up converter**

**Figure 3. Shutdown Current $I_{SDN}$**
7 Detailed Description

7.1 Overview

The TPS62770 is a tiny power solution for wearable applications including a 370nA ultra low Iq step-down converter, a slew rate controlled load switch and a dual mode step-up converter. The output voltage of the step-down converter can be selected with three VSEL pins between 1.0 V, 1.05 V, 1.1 V, 1.2 V, 1.8 V, 1.9 V, 2.0 V and 3.0 V.

The dual mode step-up converter can generate a constant output voltage up to 15 V, such as PMOLED supply or, a constant output current, such as LED back light supply.

7.2 Functional Block Diagram
7.3 Feature Description

7.3.1 Step-Down Converter Device

**Figure 4. Block Diagram Step-Down Converter with Load Switch**

7.3.1.1 DCS-Control™

TI's DCS-Control™ (Direct Control with Seamless Transition into Power Save Mode) is an advanced regulation topology, which combines the advantages of hysteretic and voltage mode control. Characteristics of DCS-Control™ are excellent AC load regulation and transient response, low output ripple voltage and a seamless transition between PFM and PWM mode operation. DCS-Control™ includes an AC loop which senses the output voltage (VO1 pin) and directly feeds the information to a fast comparator stage. This comparator sets the switching frequency, which is constant for steady state operating conditions, and provides immediate response to dynamic load changes. In order to achieve accurate DC load regulation, a voltage feedback loop is used. The internally compensated regulation network achieves fast and stable operation with small external components and low ESR capacitors. The DCS-Control™ topology supports PWM (Pulse Width Modulation) mode for medium and high load conditions and a Power Save Mode at light loads. Since DCS-Control™ supports both operation modes within one single building block, the transition from PWM to Power Save Mode is seamless with minimum output voltage ripple. The step-down converter offers both excellent DC voltage and superior load transient regulation, combined with low output voltage ripple, minimizing interference with RF circuits.

7.3.1.2 Output Voltage Selection with pins VSEL1-VSEL3

The step-down converter doesn’t require an external resistor divider network to program the output voltage. The device integrates a high impedance feedback resistor divider network that is programmed by the pins VSEL1-3. It supports an output voltage range from 1.0 V to 3.0 V. The output voltage is programmed according to Table 2. The output voltage can be changed during operation. This can be used for simple dynamic output voltage scaling.
Feature Description (continued)

7.3.1.3 CTRL / Output Load

With the CTRL pin set to high, the integrated load switch is activated and connects the LOAD pin to the VO1 pin to power up an additional sub-system. The load switch is slew rate controlled to support soft switching and not to impact the regulated output VO1. If CTRL pin is pulled to GND, the LOAD pin is disconnected from the VO1 pin and internally connected to GND by an internal discharge switch. The CTRL pin can be controlled by a microcontroller.

7.3.1.4 Output Discharge At Pins VO1 And LOAD

Both the VO1 pin and the LOAD pin feature a discharge circuit to connect each rail to GND, once they are disabled. This feature prevents residual charge voltages on capacitors connected to these pins, which may impact proper power up of the main- and sub-system. With CTRL pin pulled to low, the discharge circuit at the LOAD pin becomes active. With the EN pin pulled to low, the discharge circuits at both pins VO1 and Load are active. The discharge circuits of both rails VO1 and LOAD are associated with the UVLO comparator as well. Both discharge circuits become active once the input voltage VIN has dropped below the UVLO comparator threshold VTH_UVLO- and the UVLO comparator triggers.

7.3.1.5 Undervoltage Lockout UVLO

The UVLO circuit shuts down the device if the input voltage $V_{IN}$ drops to typical 1.9 V. The device starts up at an input voltage of typically 2.1 V.

7.3.1.6 Short Circuit Protection

The step-down converter integrates a current limit on the high side, as well on the low side MOSFETs to protect the device against overload or short circuit conditions. The peak current in the switches is monitored cycle by cycle. If the high side MOSFET current limit is reached, the high side MOSFET is turned off and the low side MOSFET is turned on until the switch current decreases below the low side MOSFET current limit. Once the low side MOSFET current limit trips, the low side MOSFET is turned off and the high side MOSFET turns on again.
Feature Description (continued)

7.3.2 Step-Up Converter Device

The step-up converter is designed for applications requiring voltages up to 15 V from an Li-Ion battery and tiny solution size such as PMOLED displays or LED back light for small size LCD displays. The step-up converter operates in two different modes, either as constant output voltage step-up converter operating with 0.8 V internal reference or as a constant output current step-up converter operating with a reduced internal reference voltage of 200mV. The block integrates power switch, input/output isolation switch, and power diode.

7.3.2.1 Under-Voltage Lockout

See section Undervoltage Lockout UVLO description for the Step-Down Converter.

7.3.2.2 Output Disconnect

One common issue with conventional step-up regulators is the conduction path from input to output even when the device is disabled. It creates three problems, which are inrush current during start-up, output leakage current during shutdown and excessive over load current. The step-up converter has an integrated isolation (load disconnect) switch, which is turned off under shutdown mode and over load conditions, thereby opening the current path to the output VO2. Thus the device can truly disconnect the load from the input voltage and minimize the leakage current during shutdown mode.
Feature Description (continued)

7.3.2.3 12 V Fixed Output Voltage
The step-up converter features an internal default 12-V output voltage setting by connecting the FB pin to the VIN pin. Therefore no external resistor divider network is required minimizing the total solution size.

7.3.2.4 Mode Selection With Pin BM
The step-up converter can operate in two different modes. With pin BM = low the device regulates to a constant output voltage; with BM = high, the device can regulate a constant output current. Further details are in section Constant-Current Step-Up Mode Operation and section Constant-Voltage Step-Up Mode Operation. The operation mode needs to be selected before the device is enabled. Pin BM may not be changed during operation.

7.3.2.5 Output Overvoltage Protection
When the output voltage exceeds the OVP threshold of 17.7 V, the device stops switching. Once the output voltage falls 0.8 V below the OVP threshold, the device resumes operation again.

7.3.2.6 Output Short Circuit Protection
The step-up converter starts to limit the output current whenever the output voltage drops below 4 V. When the VOUT pin is shorted to ground, the output current is limited. This function protects the device from being damaged when the output is shorted to ground.

7.3.2.7 PWM to Analog Converter AT PIN EN2/PWM
In constant current step-up mode operation two control functions are associated with the pin EN2/PWM:
   a) Enable/ disable of the step-up converter
   b) PWM to analog conversion to scale the internal reference voltage.

The internal reference voltage scales proportional with the duty cycle of the PWM signal applied at the pin EN2/PWM. More details in section Constant-Current Step-Up Mode Operation.

7.4 Device Functional Modes

7.4.1 Step-Down Converter

7.4.1.1 Enable and Shutdown
The step-down converter is turned on with EN1 = high. With EN1 = low the step-down converter is turned off. This pin must be terminated.

7.4.1.2 Power Save Mode Operation
At light loads, the device operates in Power Save Mode. The switching frequency varies linearly with the load current. In Power Save Mode the device operates in PFM (Pulse Frequency Modulation) that generates a single switching pulse to ramp up the inductor current and recharges the output capacitor, followed by a sleep period where most of the internal circuits are shutdown to achieve lowest operating quiescent current. During this time, the load current is supported by the output capacitor. The duration of the sleep period depends on the load current and the inductor peak current. During the sleep periods, the current consumption is reduced to 360 nA. This low quiescent current consumption is achieved by an ultra low power voltage reference, an integrated high impedance feedback divider network and an optimized Power Save Mode operation.

7.4.1.3 PWM Mode Operation
At moderate to heavy load currents, the device operates in PWM mode with continuous conduction. The switching frequency is up to 1.6 MHz with a controlled frequency variation depending on the input voltage and load current. If the load current decreases, the converter seamlessly enters Power Save Mode to maintain high efficiency down to very light loads.
Device Functional Modes (continued)

7.4.1.4 Device Start-up and Soft Start

The step-down converter has an internal soft start to minimize inrush current and input voltage drop during start-up. Once the device is enabled the device starts switching after a typical delay time of 1 ms. Then the soft start time of typical 700 μs begins with a reduced current limit of typical 150mA. When this time expires the device enters full current limit operation.

7.4.1.5 Automatic Transition Into 100% Mode

Once the input voltage comes close to the output voltage, the DC/DC converter stops switching and enters 100% duty cycle operation. It connects the output V\text{OUT} via the inductor and the internal high side MOSFET switch to the input V\text{IN}, once the input voltage V\text{IN} falls below the 100% mode enter threshold, V\text{TH}_{100-}. The DC/DC regulator is turned off, switching stops and therefore no output voltage ripple is generated. Because the output is connected to the input, the output voltage follows the input voltage minus the voltage drop across the internal high side switch and the inductor. Once the input voltage increases and trips the 100% mode exit threshold, V\text{TH}_{100+}, the DC/DC regulator turns on and starts switching again.

7.4.2 Step-Up Converter

7.4.2.1 Enable and Shutdown

The device is turned on with EN2/PWM = high. With EN2/PWM = low the device enters shutdown mode. In constant current step-up mode (BM = high) the pin EN2/PWM has to be pulled to low level for longer than t\text{Dim.Off} max to enter shutdown mode. This pin must be terminated.

7.4.2.2 Soft Start

The step-up converter begins soft start when the EN2/PWM pin is pulled high. At the beginning of the soft start period, the isolation FET is turned on slowly to charge the output capacitor with 30-mA current for about 6 ms. This is called the pre-charge phase. The output is charged up to the level of the input voltage V\text{IN}. After the pre-charge phase, the device starts switching and the output voltage ramps up. This is called switching soft start phase. An internal soft start circuit limits the peak inductor current.

7.4.2.3 Power Save Mode

The step-up converter integrates a power save mode with pulse frequency modulation (PFM) to improve efficiency at light load. When the load current decreases, the inductor peak current set by the output of the error amplifier declines to regulate the output voltage. When the inductor peak current hits the low limit of 240 mA, the output voltage will exceed the set voltage as the load current decreases further. The device enters power save mode once the FB voltage exceeds the PFM mode threshold, which is 1% above the nominal output voltage. It stops switching, the load is supplied by the output capacitor and the output voltage begins to decline. When the FB voltage falls below the PFM mode threshold voltage, the device starts switching again to ramp up the output voltage.
Device Functional Modes (continued)

![Graph showing Output Voltage in PFM and PWM Mode](image)

**Figure 6. Output Voltage in PFM and PWM Mode**

### 7.4.2.4 PWM Mode

The step-up converter uses a quasi-constant 1.0-MHz frequency pulse width modulation (PWM) at moderate to heavy load current. Based on the input voltage to output voltage ratio, a circuit predicts the required off-time. At the beginning of the switching cycle, the NMOS switching FET is turned on. The input voltage is applied across the inductor and the inductor current ramps up. In this phase, the output capacitor is discharged by the load current. When the inductor current hits the current threshold that is set by the output of the error amplifier, the PWM switch is turned off, and the power diode is forward-biased. The inductor transfers its stored energy to charge the output capacitor and supply the load. When the off-time is expired, the next switching cycle starts again. The error amplifier compares the FB pin voltage with an internal reference voltage, and its output determines the inductor peak current.

### 7.4.2.5 Constant-Current Step-Up Mode Operation

With pin BM = high the converter can regulate to a constant output current. The internal reference voltage is therefore reduced to 200mV. In order to regulate a constant output current, a sense resistor has to be connected between pin FB and GND, see Figure 7. The device features in this operation mode a PWM to analog converter at pin EN2/PWM. The internal reference voltage is scaled according to the duty cycle of the PWM signal applied to pin EN2/PWM, see Figure 8. When the pin EN2/PWM is pulled low longer than $t_{\text{Dim\_OFF}}$ max, the step-up converter enters shutdown mode. The constant output current $I_{\text{OUT2}}$ can be calculated according equations Equation 1 and Equation 2.
Device Functional Modes (continued)

Figure 7. Step-Up Converter in Constant-Current Operation Mode

Figure 8. EN2/PWM Pin Function

\[ I_{OUT2} = \frac{V_{FB}}{R_{Sense}} \]  

\[ I_{OUT2} = D_{PWM} \times \frac{200 \text{ mV}}{R_{Sense}} \]
Device Functional Modes (continued)

7.4.2.6 Constant-Voltage Step-Up Mode Operation

With pin BM = low the converter operates as a constant output voltage step-up converter. The internal reference voltage is set to 795 mV. A feedback resistor divider need to be connected between VOUT, FB and GND with its tap point connected to FB pin. The device provides a fixed set 12 V output voltage if the FB pin is connected to VIN. In this case no external resistor divider network is needed.

8 Application and Implementation

---

**NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

---

8.1 Application Information

The TPS62770 is a tiny power solution for wearable applications including a 370 nA ultra low Iq step-down converter, a slew-rate controlled load switch and a dual-mode step-up converter. The output voltage of the step-down converter can be selected between 1.0 V and 3.0 V. The output voltage can be changed during operation. In shutdown mode, the output of the step-down converter is pulled to GND. The integrated load switch is internally connected to the output of the step-down converter and features slew rate control during turn on phase. Once turned off, its output is connected to GND. In order to achieve better supply voltage decoupling / noise reduction a capacitor can be connected on the LOAD output. The $R_{DSON}$ of the load switch and the connected capacitor form a RC filter.

The dual mode step-up converter can generate a constant output voltage up to 15V, e.g. for PMOLED supply, or a constant output current, e.g. for LED back light supply. The output voltage can be adjusted up to 15 V with external resistors, or set to fixed 12 V by connecting the FB pin to VIN. The device features an internal over voltage protection of 17 V in case the FB node is left open or tight to GND. It includes an internal rectifier and load disconnect function. When used as constant output current driver, the device offers a PWM to analog converter to scale down the reference voltage according to the duty cycle of the PWM signal.

The design guideline provides a component selection to operate the device within the recommended operating conditions.
8.2 Typical Applications

8.2.1 TPS62770 Step-Down Converter + Load Switch

Figure 9. Simplified Schematic – TPS62770 Step-Down Converter Set to 1.8-V Output

8.2.1.1 Design Requirements

The LC output filter should meet the values shown in Table 3.

Table 3. Recommended LC Output Filter Combinations for the Step-Down Converter

<table>
<thead>
<tr>
<th>INDUCTOR VALUE [µH] (1)</th>
<th>OUTPUT CAPACITOR VALUE [µF] (2)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>10 µF</td>
</tr>
<tr>
<td>2.2</td>
<td>√</td>
</tr>
</tbody>
</table>

(1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by 20% and -30%.
(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by 20% and -50%.
(3) This LC combination is the standard value and recommended for most applications.

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Setting The Output Voltage Of The Step-Down Converter

The output voltage is set with the VSEL1-3 pins according to Table 2. No further external components are required.

8.2.1.2.2 Inductor Selection Step-Down Converter

The inductor value affects its peak-to-peak ripple current, the PWM-to-PFM transition point, the output voltage ripple and the efficiency. The selected inductor has to be rated for its DC resistance and saturation current. The inductor ripple current (ΔIL) decreases with higher inductance and increases with higher VIN or VOUT and can be estimated according to Equation 3.
Equation 4 calculates the maximum inductor current under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current, as calculated with Equation 4. This is recommended because during a heavy load transient the inductor current rises above the calculated value. A more conservative way is to select the inductor saturation current above the high-side MOSFET switch current limit, $I_{LIMF}$.

\[
\Delta I_L = V_{out} \times \frac{1 - \frac{V_{out}}{V_{in}}}{L \times f} \\
I_{Lmax} = I_{outmax} + \frac{\Delta I_L}{2}
\]

With:
- $f$ = Switching Frequency
- $L$ = Inductor Value
- $\Delta I_L$ = Peak to Peak inductor ripple current
- $I_{Lmax}$ = Maximum Inductor current

In DC/DC converter applications, the efficiency is essentially affected by the inductor AC resistance (i.e. quality factor) and by the inductor DCR value. Increasing the inductor value produces lower RMS currents, but degrades transient response. For a given physical inductor size, increased inductance usually results in an inductor with lower saturation current.

The total losses of the coil consist of both the losses in the DC resistance ($R_{DC}$) and the following frequency-dependent components:
- The losses in the core material (magnetic hysteresis loss, especially at high switching frequencies)
- Additional losses in the conductor from the skin effect (current displacement at high frequencies)
- Magnetic field losses of the neighboring windings (proximity effect)
- Radiation losses

**8.2.1.2.3 Input and Output Capacitor Selection**

Ceramic capacitors with low ESR values have the lowest output voltage ripple and are recommended. The output capacitor requires either an X7R or X5R dielectric. Y5V and Z5U dielectric capacitors, aside from their wide variation in capacitance over temperature, become resistive at high frequencies. At light load currents, the converter operates in Power Save Mode and the output voltage ripple is dependent on the output capacitor value and the PFM peak inductor current. A 10 µF ceramic capacitor is recommended as input capacitor.

Table 4 shows a list of tested input/output capacitors.

<table>
<thead>
<tr>
<th>REFERENCE</th>
<th>DESCRIPTION</th>
<th>VALUE</th>
<th>PACKAGE CODE / SIZE [mm x mm x mm]</th>
<th>MANUFACTURER(1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIN</td>
<td>Ceramic capacitor X5R 6.3V, GRM155R60J106ME11</td>
<td>10 µF</td>
<td>0402 / 1.0 x 0.5 x 0.5</td>
<td>Murata</td>
</tr>
<tr>
<td>COUT1</td>
<td>Ceramic capacitor X5R 6.3V, GRM155R60J106ME11</td>
<td>10 µF</td>
<td>0402 / 1.0 x 0.5 x 0.5</td>
<td>Murata</td>
</tr>
<tr>
<td>L1</td>
<td>Inductor DFE201610C</td>
<td>2.2 µH</td>
<td>2.0 x 1.6 x 1.0</td>
<td>Toko</td>
</tr>
</tbody>
</table>

(1) See Third-party Products Disclaimer
8.2.1.3 Application Curves – TPS62770 Step-Down Converter + Load Switch

Figure 10. Efficiency vs. IOUT, VOUT1 = 1.0 V

Figure 11. Efficiency vs. IOUT, VOUT1 = 1.2 V

Figure 12. Efficiency vs. IOUT, VOUT1 = 1.8 V

Figure 13. Efficiency vs. IOUT, VOUT1 = 3.0 V

Figure 14. $F_{SW}$ vs. IOUT1, VOUT1 = 1.1 V

Figure 15. VOUT1 = 1.8 V vs IOUT1
VIN = 3.6 V
VOUT = 1.2 V
IOUT = 50 µA

Figure 16. Typical Operation in Power Save Mode

VIN = 3.6 V
VOUT = 1.2 V
IOUT = 1 mA

Figure 17. Typical Operation in Power Save Mode

VIN = 3.6 V
VOUT = 1.2 V
IOUT = 50 mA

Figure 18. Typical Operation in Power Save Mode

VIN = 3.6 V
VOUT = 1.2 V
IOUT = 200 mA

Figure 19. Typical Operation in PWM Mode

VIN = 3.6 V
VOUT = 1.2 V
IOUT = 5 mA to 200 mA
1 µs Rise/Fall Time

Figure 20. Load Transient Performance

VIN = 3.6 V
VOUT = 1.2 V
IOUT = 5 mA to 200 mA
Sinusoidal IOUT Sweep

Figure 21. AC Load Regulation Performance
**Figure 22. Startup After EN High**

- $V_{IN} = 3.6 \text{ V}$
- $V_{OUT} = 1.8 \text{ V}$
- $I_{OUT} = 0 \text{ mA}$

**Figure 23. VOUT Ramp Up**

- $V_{IN} = 3.6 \text{ V}$
- $V_{OUT} = 1.8 \text{ V}$
- $I_{OUT} = 0 \text{ mA}$
- EN Altered from Low to High

**Figure 24. VIN Ramp Up/Down**

- $V_{IN}$ from 0 V to 3.6 V in 100 µs
- $V_{OUT} = 1.8 \text{ V}$
- $I_{OUT} = 0 \text{ mA}$

**Figure 25. Output Discharge**

- $V_{IN} = 3.6 \text{ V}$
- $V_{OUT} = 1.8 \text{ V}$
- $I_{OUT} = 0 \text{ mA}$

**Figure 26. Output Load Enable/Disable**

- $V_{IN} = 3.6 \text{ V}$
- $V_{OUT} = 1.8 \text{ V}$
- $I_{OUT1} = 5 \text{ mA}$
- $R_{LOAD} = 150 \Omega$
8.2.2 TPS62770 Step-Up Converter with Adjustable Output Voltage (9 V to 15 V)

The LC output filter should meet the values shown in Table 5.

Table 5. Recommended LC Output Filter Combinations for Step-Up Converter

<table>
<thead>
<tr>
<th>INDUCTOR VALUE [µH] (^{(1)})</th>
<th>VOUT</th>
<th>IOUT</th>
<th>OUTPUT CAPACITOR VALUE [µF] (^{(2)})</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>9 V –15 V</td>
<td>(IOUT ≤ 30 mA)</td>
<td>10 µF</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(IOUT ≤ 100 mA)</td>
<td></td>
</tr>
</tbody>
</table>

(1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by 20% and -30%.
(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by 20% and -50%.
(3) This LC combination is the standard value and recommended for most applications.

8.2.2.2 Detailed Design Procedure

8.2.2.2.1 Programming the Output Voltage Of The Step-Up Converter

There are two ways to set the output voltage of the step-up converter. When the FB pin is connected to the input voltage, the output voltage is fixed to 12 V. This function reduces the external components to minimize the solution size. The second way is to use an external resistor divider to set the desired output voltage.
By selecting the external resistor divider R1 and R2, as shown in Equation 5, the output voltage is programmed to the desired value. When the output voltage is regulated, the typical voltage at the FB pin is $V_{REF}$ of 795 mV.

$$R_1 = \left( \frac{V_{OUT}}{V_{REF}} - 1 \right) \times R_2$$  \hspace{1cm} (5)

Where:
- $V_{OUT}$ is the desired output voltage
- $V_{REF}$ is the internal reference voltage at the FB pin

8.2.2.2 Inductor Selection for TPS62770 Step-Up Converter

The step-up converter is optimized to work with an inductor values of 10 $\mu$H. Follow Equation 6 to Equation 8 to calculate the inductor’s peak current for the application. To calculate the current in the worst case, use the minimum input voltage, maximum output voltage, and maximum load current of the application. To have enough design margin, choose the inductor value with -30% tolerance, and a low power-conversion efficiency for the calculation.

In a step-up regulator, the inductor dc current can be calculated with Equation 6.

$$I_{L(DC)} = \frac{V_{OUT} \times I_{OUT}}{V_{IN} \times \eta}$$  \hspace{1cm} (6)

Where:
- $V_{OUT}$ = output voltage
- $I_{OUT}$ = output current
- $V_{IN}$ = input voltage
- $\eta$ = power conversion efficiency, use 80% for most applications

The inductor ripple current is calculated with the Equation 7 for an asynchronous step-up converter in continuous conduction mode (CCM).

$$\Delta I_{L(P-P)} = \frac{V_{IN} \times (V_{OUT} + 0.8V - V_{IN})}{L \times f_{SW} \times (V_{OUT} + 0.8V)}$$  \hspace{1cm} (7)

Where:
- $\Delta I_{L(P-P)}$ = inductor ripple current
- $L$ = inductor value
- $f_{SW}$ = switching frequency
- $V_{OUT}$ = output voltage
- $V_{IN}$ = input voltage

Therefore, the inductor peak current is calculated with Equation 8.

$$I_{L(P)} = I_{L(DC)} + \frac{\Delta I_{L(P-P)}}{2}$$  \hspace{1cm} (8)

The following inductor series from different suppliers have been used:

<table>
<thead>
<tr>
<th>Table 6. List Of Inductors</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONVERTER</td>
</tr>
<tr>
<td>-----------</td>
</tr>
<tr>
<td>Step-up</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>

(1) See Third-party Products Disclaimer
8.2.2.2.2.1 Example Step-Up Converter with 12-V Fixed Output

Figure 28. Schematic for a Step-Up Converter with Fixed 12-V Output

Table 7. Components for Application Curves for Step-Up Converter

<table>
<thead>
<tr>
<th>REFERENCE</th>
<th>DESCRIPTION</th>
<th>VALUE</th>
<th>PACKAGE CODE / SIZE [mm x mm x mm]</th>
<th>MANUFACTURER(1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIN</td>
<td>Ceramic capacitor X5R 6.3V, GRM155R60J106ME11</td>
<td>10 µF</td>
<td>0402 / 1.0 x 0.5 x 0.5</td>
<td>Murata</td>
</tr>
<tr>
<td>COUT2</td>
<td>Ceramic capacitor X5R 25V, GRM188R61E106MA73</td>
<td>2 x 10 uF</td>
<td>0603 / 1.6 x 0.8 x 0.8</td>
<td>Murata</td>
</tr>
<tr>
<td>L2</td>
<td>Inductor VLS302515</td>
<td>10 µH</td>
<td>3.0 x 2.5 x 1.5</td>
<td>TDK</td>
</tr>
</tbody>
</table>

(1) See Third-party Products Disclaimer
8.2.2.3 Application Curves for Step-Up Converter

![Efficiency vs. IOUT, VOUT = 15 V](image)

![Efficiency vs. IOUT, VOUT = 12 V](image)

![VOUT2 = 12 V vs IOUT2](image)

![Maximum Output Current vs VIN for Typical I_LIMSW](image)

![Typical Operation PFM Mode](image)

![Typical Operation PWM Mode](image)
**Figure 35. AC Load Regulation Performance**

\[ V_{IN} = 3.6 \text{ V} \]
\[ V_{OUT} = 12 \text{ V} \]
\[ I_{OUT2} = 0 \text{ mA to } 20 \text{ mA} \]
\[ L = 10 \mu\text{H} \]

**Figure 36. Startup after EN High**

\[ V_{IN} = 3.6 \text{ V} \]
\[ V_{OUT} = 12 \text{ V} \]
\[ R_{LOAD} = 1 \text{ k}\Omega \]
\[ L = 10 \mu\text{H} \]
### 8.2.3 Step-Up Converter with Constant 5-V Output Voltage

**Figure 37. Step-Up Converter Providing 5V \( V_{OUT2} \)**

#### 8.2.3.1 Design Requirements

The LC output filter should meet the values shown in Table 8. For 5V Output voltage an inductor value of 4.7µH should be used for loop stability.

<table>
<thead>
<tr>
<th>INDUCTOR VALUE ([\mu H]^{(1)})</th>
<th>VOUT</th>
<th>IOUT (\leq 200\text{ mA})</th>
<th>OUTPUT CAPACITOR VALUE ([\mu F]^{(2)})</th>
</tr>
</thead>
<tbody>
<tr>
<td>4.7</td>
<td>5 V</td>
<td>10 µF</td>
<td>2 x 10 µF</td>
</tr>
</tbody>
</table>

(1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by 20% and -30%.

(2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by 20% and -50%.

(3) This LC combination is the standard value and recommended for most applications.
### 8.2.3.2 Detailed Design Procedure

For setting the output voltage, see *Programming the Output Voltage Of The Step-Up Converter*

Table 9. Components for *Application Performance Curves*

<table>
<thead>
<tr>
<th>REFERENCE</th>
<th>DESCRIPTION</th>
<th>VALUE</th>
<th>PACKAGE CODE / SIZE [mm x mm x mm]</th>
<th>MANUFACTURER(1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIN</td>
<td>Ceramic capacitor X5R 6.3V, GRM155R60J106ME11</td>
<td>10 µF</td>
<td>0402 / 1.0 x 0.5 x 0.5</td>
<td>Murata</td>
</tr>
<tr>
<td>COUT2 (2x)</td>
<td>Ceramic capacitor X5R 6.3V, GRM188R60J106ME84</td>
<td>10uF</td>
<td>0603 / 1.6 x 0.8 x 0.8</td>
<td>Murata</td>
</tr>
<tr>
<td>L2</td>
<td>Inductor VLS302515</td>
<td>4.7 µH</td>
<td>3.0 x 2.5 x 1.5</td>
<td>TDK</td>
</tr>
</tbody>
</table>

(1) See *Third-party Products Disclaimer*

### 8.2.3.3 Application Performance Curves

**Figure 38. Efficiency vs. IOUT, VOUT = 5.0 V**

**Figure 39. Transient Response VOUT2 = 5 V**
8.2.4 Typical Step Up Converter with Constant Output Current

Figure 40. Step-Up Converter with Constant Output Current

8.2.4.1 Design Requirements

The step-up converter is configured to operate as a constant current driver e.g. to power 3 to 4 white LED's in a string. The maximum current through the string is set by the sense resistor $R_{\text{Sense}}$ as shown in Figure 40. To minimize the losses in the sense resistor, the device features a 200mV internal reference, which is enabled by connecting the BM pin to high level. This section describes an application delivering 10mA through an LED string with 4 LED's which is suitable for small display used in wearable applications. See also TPS62770 Step-Up Converter with Adjustable Output Voltage (9 V to 15 V) section Design Requirements.

8.2.4.2 Detailed Design Procedure

8.2.4.2.1 Setting the Output Current

The Sense resistor to set the maximum output current can be calculated according to Equation 9. The output current $I_{\text{OUT2}}$ can be reduced by applying a PWM signal at pin EN2/PWM according to Equation 10.

$$R_{\text{Sense}} = \frac{200 \text{ mV}}{I_{\text{OUT2}}} \quad (9)$$

$$I_{\text{OUT2}} = D_{\text{PWM}} \times \frac{200 \text{ mV}}{R_{\text{Sense}}} \quad (10)$$

Where:

- $R_{\text{Sense}}$ = sense resistor in [Ω]
- $I_{\text{OUT2}}$ = output current in [mA]
- $D_{\text{PWM}}$ = Duty cycle of the PWM singal at pin EN2/PWM

8.2.4.2.2 Inductor Selection

See Inductor Selection for TPS62770 Step-Up Converter
### Table 10. Components for Application Curves

<table>
<thead>
<tr>
<th>REFERENCE</th>
<th>DESCRIPTION</th>
<th>VALUE</th>
<th>PACKAGE CODE / SIZE [mm x mm x mm]</th>
<th>MANUFACTURER(1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIN</td>
<td>Ceramic capacitor X5R 6.3V, GRM155R60J106ME11</td>
<td>10 µF</td>
<td>0402 / 1.0 x 0.5 x 0.5</td>
<td>Murata</td>
</tr>
<tr>
<td>COUT2</td>
<td>Ceramic capacitor X5R 25V, GRM188R61E106MA73</td>
<td>10 µF</td>
<td>0603 / 1.6 x 0.8 x 0.8</td>
<td>Murata</td>
</tr>
<tr>
<td>L2</td>
<td>Inductor VLS302515</td>
<td>10 µH</td>
<td>3.0 x 2.5 x 1.5</td>
<td>TDK</td>
</tr>
<tr>
<td>R\text{Sense}</td>
<td>Resistor 1%</td>
<td>20 Ω</td>
<td>0402/ 1.0 x 0.5 x 0.5</td>
<td>Vishay</td>
</tr>
<tr>
<td>D1-D4</td>
<td>LED LTW-E670DS</td>
<td>n/a</td>
<td></td>
<td>Lite ON</td>
</tr>
</tbody>
</table>

(1) See Third-party Products Disclaimer

#### 8.2.4.3 Application Curves

![Graph 41](image1.png)  
**Figure 41.** Constant Current Operation with EN2/PWM = 100% D

\[
V_{\text{IN}} = 3.6 \text{ V} \quad R_{\text{Sense}} = 20 \Omega \quad 4 \text{ LEDs in Series} \\
D = 100\%, \; I_{\text{LED}} = 10 \text{ mA} \quad L = 10 \mu\text{H}
\]

![Graph 42](image2.png)  
**Figure 42.** Constant Current with EN2/PWM = 50% D

\[
V_{\text{IN}} = 3.6 \text{ V} \quad R_{\text{Sense}} = 20 \Omega \quad 4 \text{ LEDs in Series} \\
D = 50\%, \; T_{\text{Dim}} = 140 \mu\text{s}, \; I_{\text{LED}} = 5 \text{ mA} \quad L = 10 \mu\text{H}
\]
9 Power Supply Recommendations

The power supply must provide a current rating according to the supply voltage, output voltage and output current of the TPS62770.

10 Layout

10.1 Layout Guidelines

• As for all switching power supplies, the layout is an important step in the design. Care must be taken in board layout to get the specified performance.

• If the layout is not carefully done, the regulator could show poor line and/or load regulation, stability issues as well as EMI problems and interference with RF circuits.

• It is critical to provide a low inductance, impedance ground path. Therefore, use wide and short traces for the main current paths.

• The input capacitor should be placed as close as possible to the IC pins VIN and GND. The output capacitors should be placed close between VO1/2 and GND pins.

• The VO1/2 line should be connected to the output capacitor and routed away from noisy components and traces (e.g. SW line) or other noise sources.

• See Figure 45 and Figure 46 for the recommended PCB layout.
10.2 Layout Example

Figure 45. Recommended PCB Layout with 12 V Fixed VOUT2

Figure 46. Recommended PCB Layout with Adjustable VOUT2
11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer
TI's publication of information regarding third-party products or services does not constitute an endorsement regarding the suitability of such products or services or a warranty, representation or endorsement of such products or services, either alone or in combination with any TI product or service.

11.2 Documentation Support

11.2.1 Related Documentation

11.3 Trademarks
DCS-Control is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.4 Electrostatic Discharge Caution
These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.5 Glossary
SLYZ022 — TI Glossary.
This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information
The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.
## Packaging Information

<table>
<thead>
<tr>
<th>Orderable Device</th>
<th>Status</th>
<th>Package Type</th>
<th>Package Drawing</th>
<th>Pins</th>
<th>Package Qty</th>
<th>Eco Plan</th>
<th>Lead/Ball Finish</th>
<th>MSL Peak Temp</th>
<th>Op Temp (°C)</th>
<th>Device Marking</th>
<th>Samples</th>
</tr>
</thead>
<tbody>
<tr>
<td>TPS62770YFPR</td>
<td>ACTIVE</td>
<td>DSBGA</td>
<td>YFP</td>
<td>16</td>
<td>3000</td>
<td>Green</td>
<td>SNAGCU</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 85</td>
<td>62770</td>
<td>Samples</td>
</tr>
<tr>
<td>TPS62770YFPT</td>
<td>ACTIVE</td>
<td>DSBGA</td>
<td>YFP</td>
<td>16</td>
<td>250</td>
<td>Green</td>
<td>SNAGCU</td>
<td>Level-1-260C-UNLIM</td>
<td>-40 to 85</td>
<td>62770</td>
<td>Samples</td>
</tr>
</tbody>
</table>

(1) The marketing status values are defined as follows:
- **ACTIVE:** Product device recommended for new designs.
- **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
- **NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
- **PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
- **OBSOLETE:** TI has discontinued the production of the device.

(2) **Eco Plan** - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check [http://www.ti.com/productcontent](http://www.ti.com/productcontent) for the latest availability information and additional product content details.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) **Lead/Ball Finish** - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.
In no event shall TI’s liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.
NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. NanoFree™ package configuration.

NanoFree is a trademark of Texas Instruments

Texas Instruments
www.ti.com