Application Software (SW) Architecture for
MSP430FR6047-Based Ultrasonic Water Flow Meter

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ABSTRACT
This document explains the software architecture used in the implementation of an ultrasonic water flow meter with MSP430FR6047. It includes a description of the software libraries used by the application as well as the file structure and all relevant source, library, and project files. It describes all resources and peripherals used by the application.

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1 Software Architecture

The MSP430FR6047 ultrasonic water flow meter application is a portable and modular software designed to guide developers in the implementation and customization of their own water meter solutions. Figure 1 shows the software architecture.

Section 1.1 describes the application residing in the top layer in more detail.

Section 1.2 describes the IQMath library, which is used to perform fixed point operations in an effective and efficient way.

Section 1.3 describes the ultrasonic software library (USS SW Library), which is used to implement ultrasonic captures and measurements.

Section 1.4 and Section 1.5 describe the hardware-abstraction layer (HAL) and MSP430™ DriverLib, respectively, which provide a modular and portable implementation.
1.1 Application

The application layer has two main tasks: to perform ultrasonic captures and measurements, and to interface with the user.

Ultrasonic captures and measurements are performed by calling APIs from the USS SW library. The application layer handles all responses from the library including results and errors.

User interaction is implemented in the human-machine interface (HMI) layer. This layer includes support for communication with a graphical user interface (GUI), LCD, push buttons, and LEDs.

Figure 2 shows the flow diagram of the application.

Figure 2. Application Flow Diagram

The application starts by initializing the basic functionality of the system including peripherals, clocks and IOs, followed by the initialization of the HMI peripherals including LCD, GUI communication, buttons and LEDs. Finally, the system performs the initial configuration of the ultrasonic subsystem and its algorithms.

After initialization, the application stays in a continuous loop performing the following actions:

- HMI pre-measurement: Performs user interaction functions before an ultrasonic measurement, such as checking if the GUI has a new configuration to send.
- USS measurement: Performs an ultrasonic measurement. The result of this function is an ADC-sampled waveform.
- HMI post-measurement: Performs user interaction functions after a measurement such as sending the ADC waveform to the GUI if requested.
- USS algorithms: Runs ultrasonic algorithms on the ADC-sampled waveform to calculate data such as the time-of-flight (TOF) and the volume flow rate.
- HMI post-algorithms: Performs user interaction functions after the algorithms are executed. This includes sending the results to the GUI or displaying them in the LCD.
- Delay: The device goes to a low-power state waiting for the next iteration.
1.1.1 Ultrasonic Sensing Design Center

One of the functions of the HMI layer is to interface with a PC GUI known as the Ultrasonic Sensing Design Center (see Figure 3).

This GUI was developed to allow for an easier configuration of the USS subsystem, enabling developers to observe the effect of each parameter in the ADC-sampled waveform or in real-time plots of the time-of-flight and volume flow rate.

For more information about the Ultrasonic Sensing Design Center see the Design Center Graphical User Interface (DCGUI) user guide.

![Ultrasonic Sensing Design Center](image.png)

Figure 3. Ultrasonic Sensing Design Center

1.2 IQMath Library

The MSP IQMath and QMath libraries are collections of highly optimized and high-precision mathematical functions for C programmers to seamlessly port a floating-point algorithm into fixed-point code on MSP430 devices. By using IQMath and QMath libraries, it is possible to achieve execution speeds considerably faster and energy consumption considerably lower than equivalent code written using floating-point math.

Both the application and the USS SW Library make use of the IQMath library to perform fixed point operations in an effective and efficient way.

For more information about IQMath and QMath libraries, see MSP-IQMATHLIB.
1.3 Ultrasonic Software Library (USS SW Library)

The ultrasonic software library is a set of APIs and proprietary algorithms created to configure the ultrasonic subsystem of the MSP430FR6047, perform ultrasonic captures, and process the signal received from the transducers to calculate output information such as the time-of-flight (TOF) and water flow rate.

The library includes an easy-to-implement set of fully documented APIs that hide the complexity behind ultrasonic measurement calculations and allow for a faster implementation of the application.

The library's APIs are grouped in the following categories:

- Measurement APIs: Configure the USS subsystem and perform signal captures.
- Algorithms APIs: Process signal captures and generate output flow information.
- Application debug APIs: Functions to help during the development and debugging stages.
- Calibration APIs: Implement calibration of USS subsystem including modules like the HSPLL or SDHS.
- Configuration update APIs: Reconfigure the USS subsystem if a new configuration is sent by the application layer (for example, from a GUI).
- Interrupt APIs: Registers and handles interrupts used by the application.

A comprehensive list of parameters allows developers to configure the system according to different system and transducer requirements. The configuration and customization of the ultrasonic parameters is explained in Section 3.1.

The ultrasonic software library used by the application is included in CCS and IAR library format.

For more details about the USS SW library, including a comprehensive description of the available APIs, see MSP-USSSWLIB.

1.4 Hardware Abstraction Layer (HAL)

All hardware interactions are implemented in the hardware abstraction layer (HAL) allowing for a more modular and portable solution.

The HAL layer includes the following functionality:

- ADC: implements battery voltage measurement and temperature measurement using the MSP430FR6047's ADC12 module.
- LCD: implements functions to configure and control the LCD_C module in MSP430FR6047.
- System: includes functions to configure and control the watchdog (WDT), clock system (CS), and GPIOs.
- UART: includes functions to configure and communicate using the eUSCI_A module.

1.5 MSP430 Driver Library (DriverLib)

Driver Library (or DriverLib) includes APIs for selected MSP430 device families providing easy-to-use function calls. Each API is thoroughly documented through a user's guide, API guide and code examples.

The ultrasonic flow meter application software uses DriverLib to interface with all hardware modules used by the application. This allows for an easier migration to other MSP MCUs and makes the code easier to read and understand by using common language APIs.

All DriverLib files used by this application are included in source code.

More information and documentation about DriverLib is available at MSPDRIVERLIB.
2 File Structure

Figure 4 shows the file structure of the MSP430FR6047 ultrasonic water flow meter application.

![File Structure Diagram]

The most relevant folders are:

- **docs**: Contains documentation of the USS SW library.
- **driverlib**: Source code of MSP DriverLib files supporting MSP430FR6047.
- **examples**: Contains code examples using the USS SW library
  - **common**: files shared by USS applications. They include the HAL layer and files for used for communication with Design Center. These files can be modified to customize the system according to specific hardware or communication requirements. More information available in Section 3.2.
  - **mtr_gui_config**: Includes files to pre-configure the USS subsystem with Design Center to support some sample meters and transducers.
  - **USSLib_GUI_Demo**: Main application folder including source code and IAR and CCS project files for the application described in this document.
    - **CCS**: Project files for CCS.
    - **IAR**: Project files for IAR.
    - **USS_Config**: Includes a header file with definition of the structure passed to the USS SW library and the definition of the default configuration. These files can be modified to set the default configuration of the system. For more information, see Section 3.1.
    - **USSLibGUIApp**: Source code for main functionality of USS water meter application.
  - **USSSWLib_template_example**: Basic template to use the USS SW library. Includes project files for IAR and CCS.
    - **include**: Header files for IQMath and USS SW Library.
    - **lib**: Library files for IQMath and USS SW Library.
2.1 Application Layer Files

2.1.1 main.c

Location
~\examples\USSLib_GUI_Demo\main.c

Description
Main application file. Initializes the system and jumps to the main application loop.

Relevant functions
• void main(void)
  Main function for ultrasonic water meter application.

2.1.2 system_pre_init.c

Location
~\examples\USSLib_GUI_Demo\system_pre_init.c

Description
Function called after reset to initialize time-critical modules in the MSP430 MCU before jumping to the main function. This application is only using this file to initialize the Watchdog.

Relevant functions
• int __system_pre_init(void)
  System initialization for CCS.
• int __low_level_init(void)
  System initialization for IAR.

2.1.3 USS_userConfig.c/h

Location
~\examples\USSLib_GUI_Demo\USS_Config\USS_userConfig.c
~\examples\USSLib_GUI_Demo\USS_Config\USS_userConfig.h

Description
Default initialization of the USS subsystem. Pre-configures all parameters used by the ultrasonic software library, including transducer frequency, algorithm thresholds, or the sampling frequency, among others.

These files should be modified by developers to set the default configuration of the system. See Section 3.1 for more details.

Relevant variables
• __persistent USS_SW_Library_configuration gUssSWConfig
  Structure used to initialize USS SW Library and defining the default configuration of USS subsystem and algorithms.
2.1.4  **USSLibGUIApp.c/h**

**Location**

~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\USSLibGUIApp.c  
~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\USSLibGUIApp.h

**Description**

Integrates the application together with ultrasonic library, HMI and GUI. Calls initialization of the USS library and implements the application's main loop.

**Relevant functions**

- `void USSLibGUIApp_Init(void)`  
  Initialization of USS water meter application.
- `void USSLibGUIApp_Engine(void)`  
  Main loop of USS water meter application calling USS library APIs to get new measurements and execute the algorithms, and calling HMI functions to get and send information to the user.

2.1.5  **masterIncludes.h**

**Location**

~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\masterIncludes.h

**Description**

Common definitions used by application files.

2.1.6  **hmi.c/h**

**Location**

~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\hmiDC\hmi.c  
~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\hmiDC\hmi.h

**Description**

Human-Machine Interface files implementing interactions with user including GUI, LCD, buttons and LEDs. These files can be modified by developers to customize interactions with user.

**Relevant functions**

- `void HMI_Init(void)`  
  Initialization of HMI peripherals.
- `void HMI_updateUSSParameters(void)`  
  Function called when the GUI requests a parameter update. This function reconfigures the USS subsystem and its algorithms.
- `void HMI_reportError_sendErrorMessage(uint16_t error_type, uint16_t error_info)`  
  Handles errors which are reported to the user. These errors are sent to the GUI, but developers can also log them or report them in any other way.
- `void HMI_guiInputValidation(void)`  
  Validates inputs from the GUI. Can be modified by developers to change the values of parameters accepted by the application.
- `void HMI_PreMeasurement_Update(void)`  
  Function called before an ultrasonic measurement to check for a new configuration from the GUI.
- `void HMI_PostMeasurement_Update(void)`  
  Function called after an ultrasonic measurement to send the ADC waveform to the GUI if requested.
void HMI_PostAlgorithm_Update(USS_Algorithms_Results * pt_alg_res)

Function called after the ultrasonic algorithms are executed. Used to send algorithm results to the GUI if requested.

**Relevant variables**
- HMI_App_Config_t HMI_App_Config

Application configuration. Defines the sleep time between ultrasonic captures.

---

### 2.1.7 lcd_statemachinc.c/h

**Location**

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\lcd_statemachincDC\lcd_statemachinc.c`

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\lcd_statemachincDC\lcd_statemachinc.h`

**Description**

Implements the LCD state machine.

**Relevant functions**
- void lcd_statemachinc_stateUpdate(void)
  
  Handles the LCD state machine, checking for button presses and updating the LCD.
- void lcd_statemachinc_stateAction(void)
  
  Function executed after the state machine is updated to perform a corresponding action on the LCD.

**Relevant variables**
- LCD_STATEMACHINE_t g_lcd_statemachinc

State machine of the LCD.

---

### 2.1.8 mathematics.c/h

**Location**

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\mathematicsDC\mathematics.c`

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\mathematicsDC\mathematics.h`

**Description**

Implements calculations used by the HMI and LCD display.

---

### 2.1.9 results.c/h

**Location**

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\resultsDC\results.c`

`~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\resultsDC\results.h`

**Description**

Updates the information displayed on LCD.

**Relevant functions**
- void results_Reset(bool unit)
  
  Clears all the results of data displayed on LCD.
- void results_Update(float dtofData, float volrateData, uint16_t rate)
  
  Updates all results of data displayed on LCD.
Relevant variables

- RESULTS_AVERAGEDATA g_ResultsOfLastMeasurement
  Structure containing the data which is displayed on LCD.

2.1.10 testing.c/h

Location
~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\testingDC\testing.c
~\examples\USSLib_GUI_Demo\USSLibGUIApp\fr6047_USS_app\testingDC\testing.c

Description
File used to configure the ultrasonic subsystem.
Developers are encouraged to use this file to customize the behavior of the system before and after ultrasonic measurements if needed.

Relevant functions

- void Testing_PreMeasurement_Update(void)
  Function called before an ultrasonic measurement. Developers can use this function to configure the USS subsystem before a measurement.
- void Testing_PostMeasurement_Update(void)
  Function called after an ultrasonic measurement. Developers can use this function to configure the USS subsystem after a measurement.
- void Testing_PostAlgorithm_Update(void)
  Function called after running ultrasonic algorithms. Developers can use this function to configure the USS subsystem after the algorithms are executed.
- void Testing_GUIUpdate_PreUSSConfig(void)
  Function called when the GUI requests an update, before the USS Library is reconfigured.
- void Testing_GUIUpdate_PostUSSConfig(void)
  Function called when the GUI requests an update, after the USS Library is reconfigured.
- void Testing_Update_Results(HMI_DesignCenterALG_Results *results)
  Function called after the algorithms are executed and just before the results are sent to the GUI. Can be used to modify the data sent to the GUI if needed.

2.2 Ultrasonic Sensing Design Center Files

2.2.1 ussDCCommandHandlers.c/h

Location
~\examples\common\DesignCenter\ussDC\ussDCCommandHandlers.c
~\examples\common\DesignCenter\ussDC\ussDCCommandHandlers.h

Description
Implements the communication with the design center. Registers and implements the command listeners called when a command is received.

Relevant functions

- void CommandHandler_registerCmdListeners()
  Registers the command listeners which are called when commands are received from GUI.
- void CommandHandler_transmitResults(Packet_t *txPacket, USS_Algorithms_Results* algRes)
  Transmit all algorithm results to Design Center GUI.
2.2.2 comm.c/h

Location
~\examples\common\DesignCenter\comm\comm.c
~\examples\common\DesignCenter\comm\comm.h

Description
Communication module top level API. These are the communication functions that will be called directly by the application.

Relevant functions
- void Comm_setup(void)
  Setup the communication module for operation.
- bool Comm_addCmdListener(uint8_t cmd0, uint8_t cmd1, Listener_handler_t handler)
  Adds command listeners which are called when a command is received from Design Center.

Relevant variables
- const tUARTPort Comm_uartPort
  The UART port definition for the UART driver. Used only when UART is enabled for communication with Design Center.
- const tI2CSlavePort Comm_i2cSlavePort
  The I2C slave port definition for the I2C slave driver. Used only when I2C is enabled for communication with Design Center.

2.2.3 Comm_config.c/h

Location
~\examples\common\DesignCenter\comm\comm_config.c
~\examples\common\DesignCenter\comm\comm_config.h

Description
Communication module configuration file. Can be used to configure the communication interface (UART or I2C) used for communication with Design Center.

2.2.4 drivers\n
Location
~\examples\common\DesignCenter\comm\drivers\*.*

Description
Implementation of lower-level drivers used to communicate with Design Center. These files are not expected to be modified by developers using Design Center.
2.2.5 protocol\n
Location
~\examples\common\DesignCenter\comm\protocol\*.\n
Description
Protocol used for communication with Design Center. These files are not expected to be modified by
developers using Design Center.

2.2.6 utils\n
Location
~\examples\common\DesignCenter\comm\utils\*.\n
Description
Queue and ping-pong buffer implementations used by other design center files. These files are not
expected to be modified by developers using Design Center.

2.3 IQMath Library Files

2.3.1 include\n
Location
~\include\IQmathLib.h
~\include\QmathLib.h

Description
Header files for IQMath (32-bit) and QMath (16-bit) fixed point libraries. Includes all definitions and
function prototypes accessible by the application.
For more information about IQMath and QMath libraries, see MSP-IQMATHLIB.

2.3.2 lib\n
Location
~\lib\IQMathLibrary\libraries\CCS\*.\n~\lib\IQMathLibrary\libraries\IAR\*.\n
Description
Library files for IAR and CCS.
For more information about IQMath and QMath libraries, see MSP-IQMATHLIB.

2.4 Ultrasonic Software Library Files

2.4.1 include\n
Location
~\include\ussSwLib.h

Description
Header files for USS SW Lib. Includes all definitions and function prototypes accessible by the application.
For more details about the USS SW library, see MSP-USSSWLIB.
2.4.2 lib/

Location

~\lib\USS\CCS\*. *
~\lib\USS\IAR\*. *

Description

Library files for IAR and CCS.

For more details about the USS SW library, see MSP-USSSWL.B.

2.5 HAL Files

2.5.1 hal.h

Location

~\examples\common\hal\fr6047EVM\hal.h

Description

Main HAL header file including other HAL files used by the application.

2.5.2 hal_adc.c/h

Location

~\examples\common\hal\fr6047EVM\hal_adc.c
~\examples\common\hal\fr6047EVM\hal_adc.h

Description

HAL files for ADC implementing temperature sensor and supply voltage measurements using the internal ADC12 in MSP430FR6047.

Relevant functions

- void hal_adc_init(void)
  
  Initializes the ADC12 in MSP430FR6047 to read the internal temperature sensor and supply voltage.

- float hal_adc_tempsensor_readCelsius(void)
  
  Reads the internal temperature and returns the value in Celsius degrees.

- uint16_t hal_adc_voltagesupply_readmV(void)
  
  Reads the supply voltage and returns the value in millivolts.
2.5.3 hal_lcd.c/h

Location
~\examples\common\hal\fr6047EVM\hal_lcd.c
~\examples\common\hal\fr6047EVM\hal_lcd.h

Description
HAL files supporting the FH-1138P segmented LCD using the LCD_C module on MSP430FR6047.

Relevant functions
• void hal_lcd_Init(void)
  Initializes the LCDC_C in MSP430FR6047 including I/Os, voltage reference, and charge pump.
• void hal_lcd_turnonLCD(void)
  Turn on LCD.
• void hal_lcd_turnoffLCD(void)
  Turn off LCD.

2.5.4 hal_system.c/h

Location
~\examples\common\hal\fr6047EVM\hal_system.c
~\examples\common\hal\fr6047EVM\hal_system.h

Description
HAL file for system modules including the clock system (CS), watchdog (WDT), and GPIOs.

Relevant functions
• void hal_system_Init(void)
  Initializes the system, including GPIOs, clock system, watchdog, LCD and ADC.
• void hal_system_WatchdogInit(void)
  Initializes the watchdog.

2.5.5 hal_uart.c/h

Location
~\examples\common\hal\fr6047EVM\hal_uart.c
~\examples\common\hal\fr6047EVM\hal_uart.h

Description
HAL file for UART communication module. The application is not using the UART module but it can be used to communicate with PC using the ezFET backchannel UART available in the MSP430FR6047 EVM.

2.6 DriverLib Files

Location
~\driverlib\MSP430FR5xx_6xx

Description
DriverLib source and header files supporting the MSP430FR6047.
For more details about DriverLib, see MSPDRIVERLIB.
2.7 IDE Files

2.7.1 CCS Project File

Location
~\examples\USSLib_GUI_Demo\CCS\USSLib_GUI_Demo.projectspec

Description
This file can be imported into CCS, creating a copy of the USS water meter project in the user's workspace. See the CCS documentation for more information on how to import and build projects.

The project contains three configurations:
• LPM
  Default configuration. Uses USS_startLowPowerUltrasonicCapture to perform USS captures while going to the lowest-power mode possible between upstream and downstream. The device also goes to LPM3 between measurements.
• Disable_LPM
  Uses USS_startUltrasonicMeasurement to perform USS captures and stays in LPM0 between upstream and downstream. The device also goes to LPM0 between measurements.
• LPM_LEARAM
  In addition to the same functionality as the LPM configuration, the device executes LEA functions from RAM.

2.7.2 CCS Linker File

Location
~\examples\USSLib_GUI_Demo\CCS\lnk_msp430fr6047.cmd

Description
Linker file used by CCS project. This file can be modified by developers to change the memory layout used by the application.

A copy of this file is made by CCS when importing the project to the user's workspace.

2.7.3 IAR Project Files

Location
~\examples\USSLib_GUI_Demo\IAR\USSLib_GUI_Demo.*

Description
IAR workspace and project files.

Developers can import the project file (USSLib_GUI_Demo.ewp) to their workspace, or they can open the provided workspace (USSLib_Workspace.eww). See the IAR documentation for more information on how to import and build projects.

The project contains two configurations:
• LPM
  Default configuration. Uses USS_startLowPowerUltrasonicCapture to perform USS captures while going to the lowest-power mode possible between upstream and downstream. The device also goes to LPM3 between measurements.
• Disable_LPM
  Uses USS_startUltrasonicMeasurement to perform USS captures and stays in LPM0 between upstream and downstream. The device also goes to LPM0 between measurements.
2.7.4 IAR Linker File

**Location**

`~\examples\USSLib_GUI_Demo\IAR\lnk430fr6047.xcl`

**Description**

Linker file used by IAR project. This file can be modified by developers to change the memory layout used by the application.

3 Customizing the Application

The ultrasonic water flow meter application described in this document is provided in source code, allowing developers to customize it according to their needs. Although developers can customize the functionality and behavior of the application as needed, some of the most relevant customizations include: changing the default configuration of the USS SW library, making hardware modifications, and modifying algorithms and processing of data.

3.1 Changing the Default USS Configuration

The Ultrasonic Sensing Design Center GUI can be used to modify the configuration of the system without any software changes; however, developers have the option to customize the default configuration of the system without using the GUI.

The default USS configuration is defined in the following files:

```
Root>examples>USSLib_GUI_Demo>USS_Config>USS_userConfig.c
Root>examples>USSLib_GUI_Demo>USS_Config>USS_userConfig.h
```

These files contain the following global structure which sets the default configuration of the system:

```
__persistent USS_SW_Library_configuration gUssSWConfig
```

As observed, `gUssSWConfig` is defined as a persistent structure, meaning that it can be modified as a RAM variable but it resides in FRAM and retains its contents after a power cycle.

`gUssSWConfig` contains pointers to the structures listed in Table 1.

**Table 1. Contents of gUssSWConfig Structure**

<table>
<thead>
<tr>
<th>Structure</th>
<th>Description</th>
<th>Example Members</th>
</tr>
</thead>
<tbody>
<tr>
<td>USS_System_Configuration</td>
<td>Configuration of system parameters</td>
<td>.mCLKFrequency .LFXTFrequency .timerBaseAddress</td>
</tr>
<tr>
<td>.systemConfig</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_Meter_Configuration</td>
<td>Configuration of the meter and transducer</td>
<td>.volumeScaleFactor .acousticLength .transducerFreq</td>
</tr>
<tr>
<td>.meterConfig</td>
<td>characteristics</td>
<td></td>
</tr>
<tr>
<td>USS_Measurement_Configuration</td>
<td>Configuration of ultrasonic measurements</td>
<td>.numOfExcitationPulses .startPPGCount .startADCsamplingCount</td>
</tr>
<tr>
<td>.measurementConfig</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_HSPLL_Configuration</td>
<td>Configuration of PLL</td>
<td>.pllXtalFreq_inKHz .pllOutputFreq .hspllTolerance</td>
</tr>
<tr>
<td>.pllConfiguration</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_Capture_Configuration</td>
<td>Configuration of capture of ultrasonic waveform</td>
<td>.overSampleRate .gainRange .sampleSize</td>
</tr>
<tr>
<td>.captureConfig</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_Trigger_Configuration</td>
<td>Configuration of USS trigger</td>
<td>.triggerConfig</td>
</tr>
<tr>
<td>.triggerConfig</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_INTERRUPT_Configuration</td>
<td>Configuration of PLL</td>
<td>.enableUUPSPREQIInterrupt .enableSAPHIPingTransmitDoneInterrupt</td>
</tr>
<tr>
<td>.interruptConfig</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USS_Algorithms_User_Configuration</td>
<td>Configuration of USS algorithms</td>
<td>.absTOFInterval .dcOffset .enableWindowing</td>
</tr>
<tr>
<td>.algorithmsConfig</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
USS_userConfig.c contains the definition of this structure; however, all the parameters are initialized with a default value defined in USS_userConfig.h.

For example, the number of excitation pulses sent to the transducer is defined as follows:

```
USS_userConfig.c:
__persistent USS_Measurement_Configuration ussMeasurementConfig = {
    .ch0DriveStrength = USS_CH0_DRIVE_STRENGTH,
    .ch1DriveStrength = USS_CH1_DRIVE_STRENGTH,
    .pauseState = USS_PAUSE_STATE,
    .pulsePolarity = USS_PULSE_POLARITY,
    .pulseHighPhasePeriod = USS_PULSE_HIGH_PHASE_PERIOD,
    .pulseLowPhasePeriod = USS_PULSE_LOW_PHASE_PERIOD,
    .pPGPrescalerMode = USS_PPGPRESCALER_MODE,
    .numOfExcitationPulses = USS_NUM_OF_EXCITATION_PULSES,
    .numOfStopPulses = USS_NUM_OF_STOP_PULSES,
    .sequenceSelection = USSSEQUENCE_SELECTION,
    .eofSequenceState = USS_EOFSEQUENCE_SELECTION,
    .startPPGCount = USSSTART_PPG_COUNT,
    .turnOnADCCount = USS_TURN_ON_ADC_COUNT,
    .startPGAandINBiasCount = USS_PSA_IN_BIAS_COUNT,
    .startADCsamplingCount = USS_ADC_SAMP_COUNT,
    .restartCaptureCount = USS_RESTART_CAP_COUNT,
    .captureTimeOutCount = USS_TIME_OUT_COUNT
};
```

USS_userConfig.h:
```
#define USS_PPGPRESCALER_MODE USS_measurement_prescaler_disabled
#define USS_NUM_OF_EXCITATION_PULSES 20
#define USS_NUM_OF_STOP_PULSES 0
```

### 3.2 Customizing the Hardware

The application example was developed and tested using the MSP430FR6047 EVM; however, developers can customize the software to their own hardware.

As explained in Section 1.4, hardware interaction is implemented in the HAL layer. Table 2 lists the most relevant HAL functions and their corresponding source files.

<table>
<thead>
<tr>
<th>Function</th>
<th>File</th>
<th>Description</th>
<th>Possible Uses</th>
</tr>
</thead>
<tbody>
<tr>
<td>hal_system_Init</td>
<td>hal_system.c</td>
<td>Initializes the system.</td>
<td>• Change the order of initialization of the system</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Add initialization of additional peripherals</td>
</tr>
<tr>
<td>hal_system_GPIOInit</td>
<td>hal_system.c</td>
<td>Defines the default configuration and state of GPIOs.</td>
<td>• Change the pins used for communication purposes, LEDs, buttons, and so on.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Set default state of all pins to avoid floating inputs.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Add functionality to other pins not used by the application.</td>
</tr>
<tr>
<td>hal_system_ClockInit</td>
<td>hal_system.c</td>
<td>Defines the default configuration of the system clocks including the low-frequency crystal.</td>
<td>• Change the ACLK, MCLK, SMCLK frequencies (for CPU or peripherals)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Change the configuration of the low frequency crystal (LFXT)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Enable a high-frequency crystal (HFXT)</td>
</tr>
<tr>
<td>hal_system_WatchdogInit</td>
<td>hal_system.c</td>
<td>Sets default configuration of watchdog.</td>
<td>• Change watchdog time-out</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Disable or enable watchdog by default</td>
</tr>
</tbody>
</table>
3.3 Customizing Data Processing

The USS SW Library includes proprietary algorithms which can be used to process captured ADC waveforms and obtain flow rate information. While developers are encouraged to use the algorithms implemented in the library, it is also possible to implement custom algorithms to add any proprietary IP or to optimize and improve the performance of the system.

This can be achieved in several ways, including:

1. Processing raw ADC waveform:
   The USS subsystem uses the Sigma Delta High Speed ADC (SDHS) to sample the signal coming from the ultrasonic transducers on two directions (upstream and downstream). These raw signals are used by the USS algorithms to calculate the absolute and differential time-of-flight but developers can process the data using custom algorithms.
   
   The functions `USS_startLowPowerUltrasonicCapture` or `USS_startUltrasonicMeasurement` perform a capture according to the predefined USS configuration and will generate upstream and downstream ADC waveforms as a result.
   
   These waveforms have a size of:
   ```
gUssSWConfig.captureConfig.sampleSize
```

   The upstream waveform will be stored in:
   ```
gUssSWConfig.captureConfig.pCapturesBuffer[ 0: gUssSWConfig.captureConfig.sampleSize-1 ]
```

   The downstream waveform will be stored in:
   ```
gUssSWConfig.captureConfig.pCapturesBuffer[ gUssSWConfig.captureConfig.sampleSize: gUssSWConfig.captureConfig.sampleSize+ gUssSWConfig.captureConfig.sampleSize-1 ]
```

   By having direct access to the ADC sampled waveforms, developers can implement their own algorithms to process the data as desired.

2. Perform custom calculation of flow rate:
   While the USS algorithms can calculate the flow rate, developers have the flexibility to perform their own calculation to compensate for things like noise or temperature.

   This is achieved by using the output generated by the function `USS_runAlgorithms`. This function uses the upstream and downstream ADC waveforms as an input and it calculates the following information:
   - Differential time-of-flight in seconds:
     ```
     USS_Algorithms_Results.deltaTOF
     ```
   - Absolute time-of-flight of upstream signal in seconds:
     ```
     USS_Algorithms_Results.totalTOF_UPS
     ```
   - Absolute time-of-flight of downstream signal in seconds:
     ```
     USS_Algorithms_Results.totalTOF_DNS
     ```
   - Volume flow rate (in units defined by meter constant):
     ```
     USS_Algorithms_Results.volumeFlowRate
     ```

### Table 2. HAL Functions (continued)

<table>
<thead>
<tr>
<th>Function</th>
<th>File</th>
<th>Description</th>
<th>Possible Uses</th>
</tr>
</thead>
<tbody>
<tr>
<td>hal_adc_init</td>
<td>hal_adc.c</td>
<td>Preconfigures ADC to take temperature and voltage supply measurements.</td>
<td>• Change ADC channel used for voltage supply measurement</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Enable ADC to read other channels</td>
</tr>
<tr>
<td>hal_lcd_Init</td>
<td>hal_lcd.c</td>
<td>Defines the default configuration of the LCD</td>
<td>• Enable or disable the LCD charge pump</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Change the I/Os used for LCD</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Enable or disable the external resistor ladder for contrast control</td>
</tr>
</tbody>
</table>
The volume flow rate is calculated using Equation 1.

\[ v = \frac{L}{2} \times \left( \frac{\Delta t}{T_{12} - T_{21}} \right) \]

where
- \( v \) = Volume flow rate
- \( L \) = Propagation length of pipe. Defines the meter constant.
- \( \Delta t \) = Differential time-of-flight (TOF)
- \( T_{12} \) = Upstream absolute TOF
- \( T_{21} \) = Downstream absolute TOF

By having direct access to the data shown above, developers can implement their own algorithms to compensate for other factors and calculate the flow rate.

4 Resources Used by the Application

4.1 I/Os

Table 3 lists the device I/Os that are used in the application.

Table 3. I/Os Used by the Application

<table>
<thead>
<tr>
<th>Port</th>
<th>I/O</th>
<th>Initialization</th>
<th>Use by application</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>P1.0</td>
<td>Output low</td>
<td>LED1</td>
</tr>
<tr>
<td>P1</td>
<td>P1.1</td>
<td>Output low</td>
<td>LED2</td>
</tr>
<tr>
<td>P1</td>
<td>P1.2</td>
<td>Output low</td>
<td>Not used. Can be used as TXD for communication using back-channel UART.</td>
</tr>
<tr>
<td>P1</td>
<td>P1.3</td>
<td>Output low</td>
<td>Not used. Can be used as RXD for communication using back-channel UART.</td>
</tr>
<tr>
<td>P1</td>
<td>P1.4</td>
<td>Output low</td>
<td>LED3</td>
</tr>
<tr>
<td>P1</td>
<td>P1.5</td>
<td>Input</td>
<td>IRQ for communication with Design Center.</td>
</tr>
<tr>
<td>P1</td>
<td>P1.6</td>
<td>I2C SDA</td>
<td>I²C communication with Design Center.</td>
</tr>
<tr>
<td>P1</td>
<td>P1.7</td>
<td>I2C SCL</td>
<td>I²C communication with Design Center.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.0</td>
<td>Output low</td>
<td>Not used. Can be used as TXD for UART communication with design center.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.1</td>
<td>Output low</td>
<td>Not used. Can be used as RXD for UART communication with design center.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.2</td>
<td>Input</td>
<td>Enables measurement of VCC when set as output low.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.3</td>
<td>Analog Input</td>
<td>Used to measure external VCC using voltage divider.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.4</td>
<td>Output low</td>
<td>Not used.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.5</td>
<td>Input with pullup</td>
<td>Left button.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.6</td>
<td>Input with pullup</td>
<td>Up button.</td>
</tr>
<tr>
<td>P2</td>
<td>P2.7</td>
<td>LCD</td>
<td>LCD segment 21</td>
</tr>
<tr>
<td>P3</td>
<td>P3.0</td>
<td>Input with pullup</td>
<td>Down button</td>
</tr>
<tr>
<td>P3</td>
<td>P3.1</td>
<td>Input with pullup</td>
<td>Select button</td>
</tr>
<tr>
<td>P3</td>
<td>P3.2</td>
<td>Input with pullup</td>
<td>Right button</td>
</tr>
<tr>
<td>P3</td>
<td>P3.3</td>
<td>LCD</td>
<td>LCD segment 26</td>
</tr>
<tr>
<td>P3</td>
<td>P3.4</td>
<td>LCD</td>
<td>LCD segment 25</td>
</tr>
<tr>
<td>P3</td>
<td>P3.5</td>
<td>LCD</td>
<td>LCD segment 24</td>
</tr>
<tr>
<td>P3</td>
<td>P3.6</td>
<td>LCD</td>
<td>LCD segment 23</td>
</tr>
<tr>
<td>P3</td>
<td>P3.7</td>
<td>LCD</td>
<td>LCD segment 22</td>
</tr>
</tbody>
</table>
### Table 3. I/Os Used by the Application (continued)

<table>
<thead>
<tr>
<th>Port</th>
<th>I/O</th>
<th>Initialization</th>
<th>Use by application</th>
</tr>
</thead>
<tbody>
<tr>
<td>P4</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P4.0</td>
<td>LCD</td>
<td>LCD segment 16</td>
<td></td>
</tr>
<tr>
<td>P4.1</td>
<td>LCD</td>
<td>LCD segment 15</td>
<td></td>
</tr>
<tr>
<td>P4.2</td>
<td>LCD</td>
<td>LCD segment 14</td>
<td></td>
</tr>
<tr>
<td>P4.3</td>
<td>LCD</td>
<td>LCD segment 13</td>
<td></td>
</tr>
<tr>
<td>P4.4</td>
<td>LCD</td>
<td>LCD segment 12</td>
<td></td>
</tr>
<tr>
<td>P4.5</td>
<td>LCD</td>
<td>LCD segment 11</td>
<td></td>
</tr>
<tr>
<td>P4.6</td>
<td>LCD</td>
<td>LCD segment 10</td>
<td></td>
</tr>
<tr>
<td>P4.7</td>
<td>LCD</td>
<td>LCD segment 9</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P5</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P5.0</td>
<td>LCD</td>
<td>LCD segment 8</td>
<td></td>
</tr>
<tr>
<td>P5.1</td>
<td>LCD</td>
<td>LCD segment 7</td>
<td></td>
</tr>
<tr>
<td>P5.2</td>
<td>LCD</td>
<td>LCD segment 6</td>
<td></td>
</tr>
<tr>
<td>P5.3</td>
<td>LCD</td>
<td>LCD segment 5</td>
<td></td>
</tr>
<tr>
<td>P5.4</td>
<td>LCD</td>
<td>LCD segment 4</td>
<td></td>
</tr>
<tr>
<td>P5.5</td>
<td>LCD</td>
<td>LCD segment 3</td>
<td></td>
</tr>
<tr>
<td>P5.6</td>
<td>LCD</td>
<td>LCD segment 2</td>
<td></td>
</tr>
<tr>
<td>P5.7</td>
<td>LCD</td>
<td>LCD segment 1</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P6</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P6.0</td>
<td>LCD</td>
<td>LCD segment 0</td>
<td></td>
</tr>
<tr>
<td>P6.1</td>
<td>LCD</td>
<td>LCD resistor ladder R03</td>
<td></td>
</tr>
<tr>
<td>P6.2</td>
<td>LCD</td>
<td>LCD resistor ladder R13</td>
<td></td>
</tr>
<tr>
<td>P6.3</td>
<td>LCD</td>
<td>LCD resistor ladder R23</td>
<td></td>
</tr>
<tr>
<td>P6.4</td>
<td>LCD</td>
<td>LCD common 0</td>
<td></td>
</tr>
<tr>
<td>P6.5</td>
<td>LCD</td>
<td>LCD common 1</td>
<td></td>
</tr>
<tr>
<td>P6.6</td>
<td>LCD</td>
<td>LCD common 2</td>
<td></td>
</tr>
<tr>
<td>P6.7</td>
<td>LCD</td>
<td>LCD common 3</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P7</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P7.0</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.2</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.3</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.4</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.5</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.6</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P7.7</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P8</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P8.0</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P8.2</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P8.4</td>
<td>Output low</td>
<td>Not used. Accessible using TP3 testpoint.</td>
<td></td>
</tr>
<tr>
<td>P8.5</td>
<td>Output low</td>
<td>Not used. Accessible using TP2 testpoint.</td>
<td></td>
</tr>
<tr>
<td>P8.6</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td>P8.7</td>
<td>Output low</td>
<td>Not used. Accessible using J5/J6 connectors.</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P9</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P9.0</td>
<td>LCD</td>
<td>LCD segment 20</td>
<td></td>
</tr>
<tr>
<td>P9.1</td>
<td>LCD</td>
<td>LCD segment 19</td>
<td></td>
</tr>
<tr>
<td>P9.2</td>
<td>LCD</td>
<td>LCD segment 18</td>
<td></td>
</tr>
<tr>
<td>P9.3</td>
<td>LCD</td>
<td>LCD segment 17</td>
<td></td>
</tr>
</tbody>
</table>
Table 3. I/Os Used by the Application (continued)

<table>
<thead>
<tr>
<th>Port</th>
<th>I/O</th>
<th>Initialization</th>
<th>Use by application</th>
</tr>
</thead>
<tbody>
<tr>
<td>PJ</td>
<td>PJ.0</td>
<td>Output low</td>
<td>Not used. Can be used by JTAG.</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.1</td>
<td>Output low</td>
<td>Not used. Can be used by JTAG.</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.2</td>
<td>Output low</td>
<td>Not used. Can be used by JTAG.</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.3</td>
<td>Output low</td>
<td>Not used. Can be used by JTAG.</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.4</td>
<td>LFXT</td>
<td>Low-frequency crystal input</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.5</td>
<td>LFXT</td>
<td>Low-frequency crystal output</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.6</td>
<td>Output low</td>
<td>Not used. Can be used for HFXT.</td>
</tr>
<tr>
<td>PJ</td>
<td>PJ.7</td>
<td>Output low</td>
<td>Not used. Can be used for HFXT.</td>
</tr>
</tbody>
</table>

Not general purpose

<table>
<thead>
<tr>
<th>I/O</th>
<th>Initialization</th>
<th>Use by application</th>
</tr>
</thead>
<tbody>
<tr>
<td>TEST/SBTWCK</td>
<td>–</td>
<td>Can be used by JTAG/SBW.</td>
</tr>
<tr>
<td>RST/NMI/</td>
<td>–</td>
<td>Reset. Can be used by JTAG/SBW.</td>
</tr>
<tr>
<td>SBWTDIO</td>
<td>–</td>
<td>LCD resistor ladder R33</td>
</tr>
<tr>
<td>USSXTIN</td>
<td>–</td>
<td>USS crystal input</td>
</tr>
<tr>
<td>USSXTOUT</td>
<td>–</td>
<td>USS crystal output</td>
</tr>
<tr>
<td>CH0_IN</td>
<td>–</td>
<td>Input from transducer 1</td>
</tr>
<tr>
<td>CH0_OUT</td>
<td>–</td>
<td>Output to transducer 1</td>
</tr>
<tr>
<td>CH1_IN</td>
<td>–</td>
<td>Input from transducer 2</td>
</tr>
<tr>
<td>CH1_OUT</td>
<td>–</td>
<td>Output to transducer 2</td>
</tr>
</tbody>
</table>

4.2 Peripherals and Modules

Table 4 summarizes the device modules used by the application.

Table 4. Peripherals and Modules Used by the Application

<table>
<thead>
<tr>
<th>Module</th>
<th>Initialization</th>
<th>Use by application</th>
</tr>
</thead>
<tbody>
<tr>
<td>USS</td>
<td>Used and initialized by USS SW Library</td>
<td>The application uses and initializes the six USS submodules (UUPS, HSPLL, ASQ, PPG, PGA, SDHS) to implement an efficient measurement of ultrasonic signals.</td>
</tr>
<tr>
<td>UCS</td>
<td>LFXT enabled at 32.768 kHz. Enable DCO at 8 MHz. ACLK = LFXT SMCLK = DCO MCLK = DCO</td>
<td>Configure clocks used by application</td>
</tr>
<tr>
<td>WDT</td>
<td>Watchdog enabled using VLO (approximately 10 kHz) with a time-out of approximately 3.2 seconds</td>
<td>Configure and feed watchdog</td>
</tr>
<tr>
<td>ADC12</td>
<td>Initialized to read temperature sensor and external voltage. Uses internal MODOSC.</td>
<td>Read internal temperature sensor and external supply voltage</td>
</tr>
<tr>
<td>LCD_C</td>
<td>Using 4-MUX mode. Internal charge pump disabled. External resistor ladder enabled for contrast control.</td>
<td>Display information to the user</td>
</tr>
<tr>
<td>eUSCI_B0</td>
<td>I^2C slave with address 0x0A</td>
<td>Communication with Design Center</td>
</tr>
<tr>
<td>TA4</td>
<td>Used and initialized by USS SW Library</td>
<td>Delays used by USS SW library</td>
</tr>
<tr>
<td>LEA</td>
<td>Used and initialized by USS SW Library</td>
<td>Efficient implementation of algorithms</td>
</tr>
</tbody>
</table>
4.3 Memory Footprint

Table 5 summarizes the memory footprint of the application.

<table>
<thead>
<tr>
<th>Memory Area</th>
<th>Description</th>
<th>CCS (1)</th>
<th>IAR (2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Code</td>
<td>Total code used by application</td>
<td>38.9KB</td>
<td>34.6KB</td>
</tr>
<tr>
<td>Const</td>
<td>Nonvolatile constants and persistent variables used by application</td>
<td>3.5KB</td>
<td>3.4KB</td>
</tr>
<tr>
<td>Data</td>
<td>Volatile variables used by the application</td>
<td>5.8KB</td>
<td>5.6KB</td>
</tr>
</tbody>
</table>

(1) Using "LPM" configuration with CCS 6.2.0 with optimization level 3
(2) Using "LPM" configuration with IAR 6.50.2 with optimization level Medium

Table 6 shows the RAM usage of the application.

<table>
<thead>
<tr>
<th>Memory Area (1)</th>
<th>Description</th>
<th>Available on MSP430FR6047</th>
<th>Used by Application</th>
</tr>
</thead>
<tbody>
<tr>
<td>RAM (4)</td>
<td>RAM not shared with LEA</td>
<td>4KB</td>
<td>3672 bytes</td>
</tr>
<tr>
<td>LEA RAM</td>
<td>RAM shared with LEA</td>
<td>4KB</td>
<td>2604 bytes</td>
</tr>
</tbody>
</table>

(1) The MSP430FR6047 has 8KB of total RAM. 4KB are shared with LEA
(2) Using "LPM" configuration with CCS 6.2.0 with optimization level 3
(3) Using "LPM" configuration with IAR 6.50.2 with optimization level Medium
(4) Developers can also place variables in FRAM if needed

5 References
1. MSP430FR6047 Ultrasonic Sensing Design Center Quick Start Guide
2. Quick Start Guide for MSP430FR6047-Based Ultrasonic Water Flow Meter
3. EVM430-FR6047 Hardware Guide
4. MSP430FR6047 and Ultrasonic Software Based Water Flow Meter Measurement Results
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