

# TSW2200EVM: Multi-Output Power Supply Evaluation Module

The TSW2200EVM evaluation module (EVM) provides a multiple output power supply solution for powering other EVMs. This EVM provides fixed and adjustable supplies that can be used as simple on or off supplies or sequenced supplies for power critical EVM setups. This user's guide discusses options available when using the EVM.

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### **1** Hardware Configuration

The TSW2200EVM (Figure 1) provides users with a multiple-output power supply board using a switching regulator and low-dropout (LDO) regulators. With an onboard TUSB3210 integrated circuit (IC) and UCD90120A sequencer, users can configure the EVM to operate in either manual or sequencer mode. Manual operation allows each output to be turned on or off with a jumper setting, whereas the sequencer operation allows precise configurability of turnon time using the Fusion GUI software.

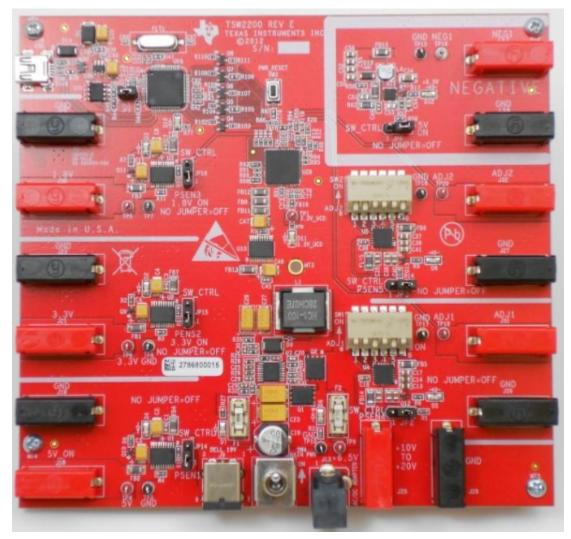


Figure 1. TSW2200EVM Evaluation Module

# 1.1 Input Power Source

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The input supply for the TSW2200 can be a voltage of 10 V to 20 V using banana jacks, a 19-V Dell<sup>™</sup> laptop charger, or a 12 V @ 2 A (AC-to-DC) power module. These input voltages are stepped down to 6.5 V using a switching regulator.

# 1.2 Output Power Regulators

The available power rails are four fixed supplies at 5 V, 3.3 V, 1.8 V and a negative rail of -5 V. Two positive adjustable output regulators are also present supplying voltages from 1.4 V to 6.4 V. All output supplies except for the -5 V output have a rated output current of 1 A. The -5 V output regulator is rated for 0.36 A.



# 1.3 Switches, Jumpers, and LEDs

SW4 controls the main power switch supplying input power to the EVM. After SW4 is enabled, each separate output supply is turned on and off using individual jumpers. Table 1 shows the jumper configurations for each supply. Manually enable or disable the supply, depending on the jumper location. Another option programs the supply with the UCD90120A sequencer. In this mode the UCD90120A is programmed with the Fusion GUI software. This software controls the turnon times of each supply as well as monitoring overvoltage and undervoltage conditions.

Output Supplies	Jumper Setting: Manual ON	Jumper Setting: Manual OFF	Jumper Setting: Sequencer Control
5 V	1-2	Remove jumper	2-3
3.3 V	1-2	Remove jumper	2-3
1.8 V	1-2	Remove jumper	2-3
from 1.4 V to 6.4 V	2-3	Remove jumper	1-2
from 1.4 V to 6.4 V	2-3	Remove jumper	1-2
–5 V	2-3	Remove jumper	1-2

### Table 1. Jumper Settings For Power Output Rails

The LED indication displays which input and output power is enabled or disabled. Table 2 shows which LEDs correspond to specific supplies onboard.

Supply	LED
5-V output	D4
3.3-V output	D2
1.8-V output	D3
from 1.4 V to 6.4 V	D5
from 1.4 V to 6.4 V	D6
–5V output	D12
Input power	D7 and D8
UCD90120A input	D11
TUSB3210 input	D10

# Table 2. LED Indication For Power

# 2 Software Configuration

The Fusion Digital Power Designer software controls the turnon and turnoff of the TSW2200 in sequencer mode. Download the Fusion software from the <u>Digital Power Software</u> page on the TI Web site. This software allows configuration of enable control for turning on and turning off the output supplies at specific time delays. Also available with the Fusion GUI is voltage monitoring of the output. Voltage monitoring reads out conditions of overvoltage, undervoltage, current, and temperature. The following steps demonstrate the set up of the Fusion GUI software.



## 2.1 Preprogrammed Configurations

Sequencing is provided by the UCD90120A, included on the EVM. Observe the sequencing capabilities of the board by setting the supplies to SW\_CTRL (settings in Sequencer control column of Table 1), a preloaded delay for each supply occurs when the board is powered on. This delay is seen when powering on by the sequence of LEDs turning on for their respective supplies. The button highlighted in Figure 2 preprograms this delay into the UCD90120A's flash memory, loading a configuration after the board is shut off.

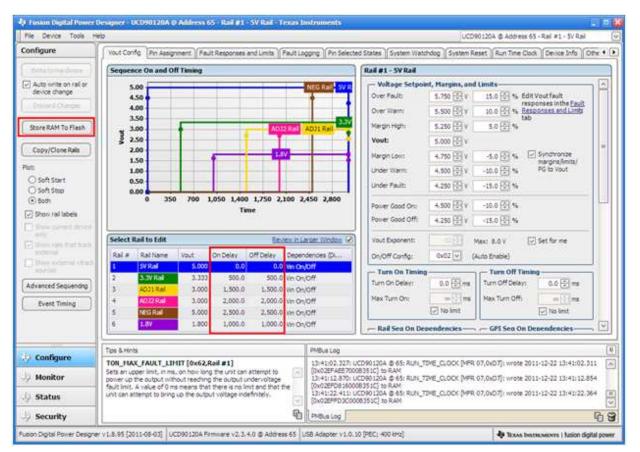


Figure 2. Preprogrammed Delays in Flash Memory

# 2.2 Delay Settings

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Figure 2 highlights the location where the turnon and turnoff delay for each supply is set. Edit the supply value in the *Select Rail to Edit* area for configuration of each rail's delays independently.



# 2.3 Pin Assignment Settings

File Device Tools H	ep						UCD90120A @ Addres	us 65 - Rai #1 - 5V Rai	
Configure	Vout Confg	Pri Aasignment	t Fault Responses	and Limits Fault Logg	ing Pin Selected State	ns System Watchdog	System Reset Run Time	Clock Device Info	094 4
(relations down .)	Rails - Mo	nitors & Enable	ies .			the second s		6 of 12 Assigned	
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Figure 3. Pin Assignments For Supplies, Enables, and Monitoring

Different configurations are possible with the TSW2200, notably changing the enable settings so the EVM powers up with all supplies off or all supplies on. Configuration of active-low or active-high enable settings for each supply as well as the pin assignments for monitoring and enabling are shown in the pin assignment screen, Figure 3.

Pin assignments are made for the rail name using the pin monitors, as seen in the Voltage column in Figure 3. These are preset and must not be changed as this is a permanent pin configuration in the hardware. Because the negative regulator's output is -5 V, the monitor pins of the UCD90120A cannot support a voltage outside the range of 0 V to 2.5 V. In order to eliminate an extra inverter for purposes of converting the -5 V to the required monitor voltage range, no monitoring is provided for the -5V supply.

The enables are also preset in the hardware and must not be changed from the settings shown in Figure 3. All supplies have an enable pin connected and used so that all the supplies can be sequenced. The last customizable pin assignment configuration is under the Configure link highlighted in Figure 3. When selecting *Configure*, the screen shown in Figure 4 appears and allows options for an active-low or active-high enable polarity as well as two types of output mode configurations. The output mode configuration is always actively driven.



Users can set the enable polarity, however, in two configurations, depending on the desired result for the supplies during board power up. Table 3 shows the two configurations available for each supply setting. Mode 1 sets all enable polarities to their appropriate state for turnon. This means that when set in Mode 1, all supplies begin to turn on in the configured sequence as soon as the board is powered up. When *Store RAM to flash* is also pushed when setting in mode 1, the board does not need the USB cable connected or have the Fusion GUI software running, the sequencing simply occurs when the board is powered up or when the PWR\_RESET SW3 is pushed. Note that when sequencing the supplies, do not turn the board on using the main switch to sequence because transient voltage spikes result from the main supply turning on everything for a short time before the UCD90120A takes control. Sequencing from mode 1, the board powers up in a sequence, then the user can press and hold the SW3 button while all connections are made to the output, and when the button is released, the power comes on in sequence.

×	12							
Rail #1 Voltage Monitor Type								
Voltage monitor type:								
<ul> <li>Standard</li> </ul>								
O Hardware comparator								
The response time to an over/under voltage fault is faster with the hardware comparator. The hardware comparator option is only available with up to six monitored voltages. There is no glitch filtering when using the hardware comparator.								
You can not use either of the "continue to operate" voltage fault responses (VOUT_OV_FAULT_RESPONSE and VOUT_UV_FAULT_RESPONSE) with a hardware comparator Voltage monitor.								
Rail #1 Enable Pin Configuration								
Polarity: Output Mode:								
Active Low	<ul> <li>Actively Driven</li> </ul>							
O Active High	Open-Drain							

Figure 4. Enable Polarity and Output Mode Type

Output Supplies	Mode 1 – Enable Polarities	Mode 2 – Enable Polarities
5 V	Active low	Active high
3.3 V	Active low	Active high
1.8 V	Active low	Active high
ADJ1	Active high	Active low
ADJ2	Active high	Active low
NEG	Active high	Active low

### Table 3. Enable Polarity Modes For Desired Turnon or Turnoff Conditions

Table 3 shows the second mode possible for each supply. Mode 2 sets the supplies to the enable polarity keeping supplies off when the board powers on. In this mode, the Fusion GUI software and a USB cable connected to the board are required. When operating in this mode and once all the desired delay settings are set, a write to the hardware is possible. This write to hardware is in real time and sets all supplies to the appropriate delays. Once the configuration for turnon is set, then all enable polarities for each supply



under Configure in Figure 3 are changed to Mode 1 settings. Another write to hardware is done, and then all supplies are sequenced without turning the board off and on. When all boards need to be sequenced off by a specified delay setting, then all enable polarities can be reset to Mode 2 and a write to the hardware can be repeated. This then sequences all supplies off, based on the specified time for each supply.

# 2.4 Voltage Monitoring

The last Fusion GUI readout beneficial for maintaining correct output voltage levels is the voltage monitoring function. This portion of the software allows real-time voltage monitoring of each output voltage rail. In Figure 5, the output voltage readings appear in the top left. Each voltage reads out the correct output voltage of each supply. The monitoring is preprogrammed based on the hardware and software specifications. The voltage reading for Vout #6 – NEG Rail is not valid because the monitor pin was not connected for this rail. This is because the output of the negative regulator is -5 V and cannot be divided appropriately to a voltage within the 0V to 2.5V requirement.

When monitoring voltage it is important whether the voltage exhibits undervoltage or overvoltage conditions. Measure this data within the Status Registers/Lines box or the graphical readout for the respective output voltage to the right of the Readings box. These two boxes indicate if the output voltage is OK, as well as what condition the voltage is in with respect to the overvoltage and undervoltage limit conditions. This data ensures the power supply board is operating correctly.

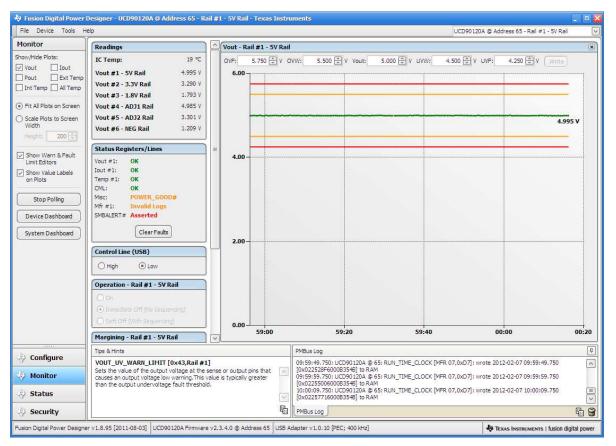


Figure 5. Voltage Monitoring Readouts For Each Output Voltage Rail

# 3 Turnon Sequencing Example

To verify the sequencing of two of the supplies turning on, perform the following steps for setting up the TSW2200 and the Fusion GUI software. For this setup, the 5V rail does not have a turn on delay, whereas the 3.3V rail has a 20ms delay.



Turnon Sequencing Example

www.ti.com

# 3.1 Hardware Setup

Prepare the TSW2200 for software programming with the following steps:

- 1. Plug in the input power as described in Section 1.1.
- 2. Connect the TSW2200 to the computer with a USB cable.
- 3. Turn on the EVM with SW4. Do not connect the output voltages to the loads.



# 3.2 Software Setup

Configure the sequencer delay settings with the following steps:

- 1. Start the Fusion GUI software.
- 2. Configure the delay settings for the 5V and 3.3V rails as shown in Figure 6.
- 3. Set the enable polarities as listed in Mode 2 from Table 3 (accessible in Configure menu as shown in Figure 3).
- 4. Click Write to Hardware (all rails must be turned off; verify by appropriate LEDs in Table 2 being off).
- 5. Change jumpers for all other rails, besides 5 V and 3.3 V, to the settings in Table 1 under Manual OFF.
- 6. Connect a scope probe to the 5V rail and another to the 3.3V rail.
- 7. Change the enable polarities to the settings listed for Mode 1 from Table 3.
- 8. Click Write to Hardware (5V and 3.3V rails turn on; verify by LEDs).
- 9. Figure 7 shows the oscilloscope capture of the 5V and 3.3V rails sequencing with a delay of 10 ms.

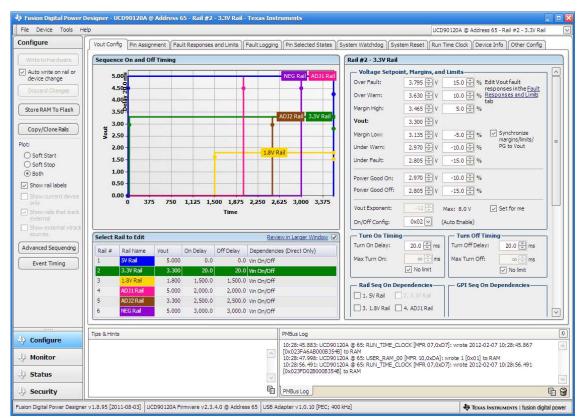


Figure 6. 5V and 3.3V Rails With 20ms Delay

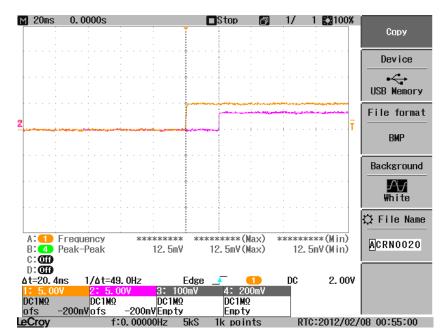


Figure 7. 5V and 3.3V Rails With 20ms Delay Capture

# 4 Reference

For more information on Fusion GUI software functionality, refer to the supplementary <u>Fusion Tools</u> <u>Documentation</u>.

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#### General Statement for EVMs including a radio

User Power/Frequency Use Obligations: This radio is intended for development/professional use only in legally allocated frequency and power limits. Any use of radio frequencies and/or power availability of this EVM and its development application(s) must comply with local laws governing radio spectrum allocation and power limits for this evaluation module. It is the user's sole responsibility to only operate this radio in legally acceptable frequency space and within legally mandated power limitations. Any exceptions to this are strictly prohibited and unauthorized by Texas Instruments unless user has obtained appropriate experimental/development licenses from local regulatory authorities, which is responsibility of user including its acceptable authorization.

### For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant

#### Caution

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

#### FCC Interference Statement for Class A EVM devices

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

#### FCC Interference Statement for Class B EVM devices

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- · Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

#### For EVMs annotated as IC – INDUSTRY CANADA Compliant

This Class A or B digital apparatus complies with Canadian ICES-003.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

#### Concerning EVMs including radio transmitters

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

#### Concerning EVMs including detachable antennas

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Cet appareil numérique de la classe A ou B est conforme à la norme NMB-003 du Canada.

Les changements ou les modifications pas expressément approuvés par la partie responsable de la conformité ont pu vider l'autorité de l'utilisateur pour actionner l'équipement.

#### Concernant les EVMs avec appareils radio

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

#### Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

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### This development kit is NOT certified as Confirming to Technical Regulations of Radio Law of Japan

If you use this product in Japan, you are required by Radio Law of Japan to follow the instructions below with respect to this product:

- Use this product in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
- 2. Use this product only after you obtained the license of Test Radio Station as provided in Radio Law of Japan with respect to this product, or
- 3. Use of this product only after you obtained the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to this product. Also, please do not transfer this product, unless you give the same notice above to the transferee. Please note that if you could not follow the instructions above, you will be subject to penalties of Radio Law of Japan.

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For Feasibility Evaluation Only, in Laboratory/Development Environments. Unless otherwise indicated, this EVM is not a finished electrical equipment and not intended for consumer use. It is intended solely for use for preliminary feasibility evaluation in laboratory/development environments by technically qualified electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems and subsystems. It should not be used as all or part of a finished end product.

Your Sole Responsibility and Risk. You acknowledge, represent and agree that:

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- 2. You have full and exclusive responsibility to assure the safety and compliance of your products with all such laws and other applicable regulatory requirements, and also to assure the safety of any activities to be conducted by you and/or your employees, affiliates, contractors or designees, using the EVM. Further, you are responsible to assure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard.
- 3. You will employ reasonable safeguards to ensure that your use of the EVM will not result in any property damage, injury or death, even if the EVM should fail to perform as described or expected.
- 4. You will take care of proper disposal and recycling of the EVM's electronic components and packing materials.

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