

# AN-1690 LM20154 Evaluation Board

## 1 Introduction

The LM20154 is a full featured buck switching regulator capable of driving up to 4A of load current. The nominal 1MHz switching frequency of the LM20154 reduces the size of the power stage components while still allowing for highly efficient operation. The LM20154 is capable of converting an input voltage between 2.95 V and 5.5 V down to an output voltage as low as 0.8 V. Fault protection features include cycle-by-cycle current limit, output power good, and output over-voltage protection. The dual function soft-start/tracking pin can be used to control the startup response of the LM20154, and the precision enable pin can be used to easily sequence the LM20154 in applications with sequencing requirements. The LM20154 features an open drain SYNCOUT pin that provides a signal that is 180 degrees out of phase with the internal oscillator. The LM20154 is available in a 16-pin HTSSOP package with an exposed pad for enhanced thermal performance.

The LM20154 evaluation board has been designed to balance overall solution size with the efficiency of the regulator. The evaluation board measures just under 1.3" x 1.1" on a two layer PCB, with all components placed on the top layer. The power stage and compensation components of the LM20154 evaluation board have been optimized for an input voltage of 5 V, but for testing purposes, the input can be varied across the entire operating range. The output voltage of the evaluation board is nominally 1.2 V, but this voltage can be easily changed by replacing one of the feedback resistors (R<sub>FB1</sub> or R<sub>FB2</sub>). The control loop compensation of the LM20154 evaluation board has been designed to provide a stable solution over the entire input and output voltage range with a reasonable transient response. The EN pin must be above 1.18 V (typ) on the board to initiate switching. If the EN function is not necessary, the EN pin should be externally tied to  $V_{IN}$ .

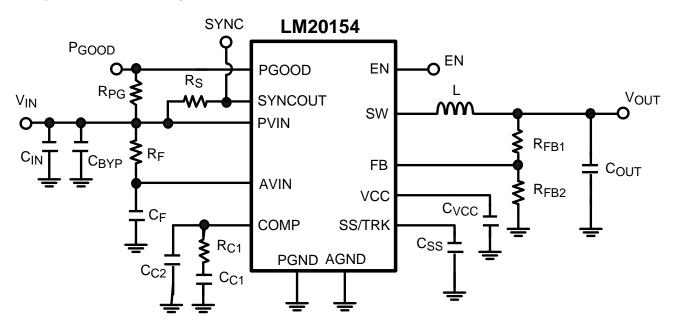


Figure 1. Evaluation Board Schematic

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# 2 Bill of Materials (BOM)

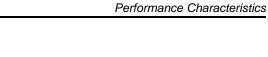
Designator	Description	Part Number	Qty	Manufacturer
U1	Synchronous Buck Regulator	LM20154	1	Texas Instruments
C <sub>IN</sub>	100 µF, 1210, X5R, 6.3 V	GRM32ER60J107ME20	1	Murata
C <sub>BYP</sub>	1 μF, 0603, X5R, 6.3 V	GRM188R60J105KA01	1	Murata
C <sub>OUT</sub>	100 µF, 1210, X5R, 6.3 V	GRM32ER60J107ME20	1	Murata
L	1 μH, 6 mΩ	MSS1038-102NL	1	Coilcraft
R <sub>F</sub>	1Ω, 0603	CRCW06031R0J-e3	1	Vishay-Dale
C <sub>F</sub>	100 nF, 0603, X7R, 16 V	GRM188R71C104KA01	1	Murata
CV <sub>cc</sub>	1 μF, 0603, X5R, 6.3 V	GRM188R60J105KA01	1	Murata
R <sub>PG</sub>	10 kΩ, 0603	CRCW06031002F-e3	1	Vishay-Dale
R <sub>C1</sub>	3.65 kΩ, 0603	CRCW06033651F-e3	1	Vishay-Dale
C <sub>C1</sub>	3.3 nF, 0603, X7R, 25 V	VJ0603Y332KXXA	1	Vishay-Vitramon
C <sub>C2</sub>	OPEN	OPEN	0	N/A
C <sub>ss</sub>	33 nF, 0603, X7R, 25 V	VJ0603Y333KXXA	1	Vishay-Vitramon
R <sub>FB1</sub>	4.99 kΩ, 0603	CRCW06034991F-e3	1	Vishay-Dale
R <sub>FB2</sub>	10 kΩ, 0603	CRCW06031002F-e3	1	Vishay-Dale
Rs	4.99 kΩ, 0603	CRCW06034991F-e3	1	Vishay-Dale
Test Points	Test Points	160-1026-02-01-00	8	Cambion

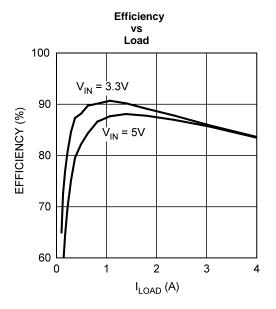
# 3 Connection Descriptions

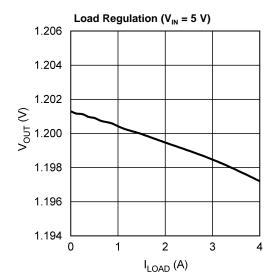
Terminal Silkscreen	Description		
V <sub>IN</sub>	This terminal is the input voltage to the device. The device will operation over the input voltage range of 2.95 V to 5.5 V. The absolute maximum voltage rating for this pin is 6 V.		
GND	This terminal is the ground connection to the device. There are two different GND connections on the PCB. One should be used for the input supply and the other for the load.		
V <sub>OUT</sub>	This terminal connects to the output voltage of the power supply and should be connected to the load.		
EN	This terminal connects to the enable pin of the device. This terminal should be connected to $V_{IN}$ or driven externally. If driven externally, a voltage typically greater than 1.18 V will enable the device. The operating voltage for this pin should not exceed 5.5 V. The absolute maximum voltage rating on this pin is 6 V.		
SS/TRACK	This terminal provides access to the SS/TRK pin of the device. Connections to this terminal are not needed for most applications. The feedback pin of the device will track the voltage on the SS/TRK pin if it is driven with an external voltage source that is below the 0.8 V reference. The voltage on this pin should not exceed 5.5 V during normal operation. The absolute maximum voltage rating on this pin is 6 V.		
PGOOD	This terminal connects to the power good output of the device. There is a 10 k $\Omega$ pull-up resistor from this pin to the input voltage. The voltage on this pin should not exceed 5.5 V during normal operation and has an absolute maximum voltage rating of 6 V.		
SYNC	This terminal connects to the SYNCOUT pin of the device. This open drain output has a 4.99 k $\Omega$ pull-up resistor from this pin to the input voltage. The voltage on this pin should not exceed 5.5 V during normal operation and has an absolute maximum voltage rating of 6 V.		

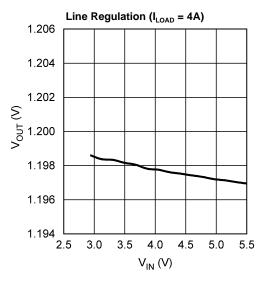


## 4 Performance Characteristics

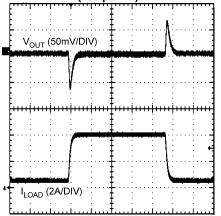


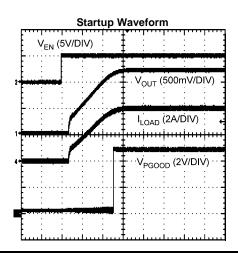






0.5A to 4A Load Transient Response (200 µs/DIV)







(1)

(3)

#### 5 Component Selection

This section provides a walk-through of the design process of the LM20154 evaluation board. Unless otherwise indicated, all equations assume units of Amps (A) for current, Farads (F) for capacitance, Henries (H) for inductance, and Volts (V) for voltages.

#### 5.1 Input Capacitor

The required RMS current rating of the input capacitor for a buck regulator can be estimated by Equation 1:

 $I_{CIN(RMS)} = I_{OUT} \sqrt{D(1 - D)}$ 

The variable D refers to the duty cycle, and can be approximated by:

$$D = \frac{V_{OUT}}{V_{IN}}$$
(2)

From Equation 3, it follows that the maximum  $I_{CIN(RMS)}$  requirement will occur at a full 4A load current with the system operating at 50% duty cycle. Under this condition, the maximum  $I_{CIN(RMS)}$  is given by:

 $I_{CIN(RMS)} = 4A \sqrt{0.5 \times 0.5} = 2.0A$ 

Ceramic capacitors feature a very large  $I_{\text{RMS}}$  rating in a small footprint, making a ceramic capacitor ideal for this application. A 100  $\mu$ F X5R ceramic capacitor from Murata with a 5.4A  $I_{\text{RMS}}$  rating provides the necessary input capacitance for the evaluation board. For improved bypassing, a small 1  $\mu$ F high frequency capacitor is placed in parallel with the 100  $\mu$ F bulk capacitor to filter high frequency noise pulses on the supply.

#### 5.2 AV<sub>IN</sub> Filter

An RC filter should be added to prevent any switching noise on  $PV_{IN}$  from interfering with the internal analog circuitry connected to  $AV_{IN}$ . These can be seen on the schematic as components  $R_F$  and  $C_F$ . There is a practical limit to the size of the resistor  $R_F$  as the  $AV_{IN}$  pin will draw a short 60mA burst of current during startup, and if  $R_F$  is too large the resulting voltage drop can trigger the UVLO comparator. For the demo board a 1  $\Omega$  resistor is used for  $R_F$  ensuring that UVLO will not be triggered after the part is enabled. A recommended 1  $\mu$ F  $C_F$  capacitor coupled with the 1  $\Omega$  resistor provides roughly 16dB of attenuation at the 1 MHz switching frequency.

#### 5.3 Inductor

As per the device-specific data sheet recommendations, the inductor value should initially be chosen to give a peak-to-peak ripple current equal to roughly 30% of the maximum output current. The peak-to-peak inductor ripple current can be calculated by Equation 4:

$$\Delta I_{P-P} = \frac{(V_{IN} - V_{OUT}) \times D}{L \times f_{SW}}$$

(4)

Rearranging this equation and solving for the inductance reveals that for this application, ( $V_{IN} = 5$  V,  $V_{OUT} = 1.2$  V,  $f_{SW} = 1$  MHz, and  $I_{OUT} = 4$ A) the nominal inductance value is roughly 0.76 µH. Rounding up to the nearest standard inductor value, a final inductance of 1 µH is selected. This results in a peak-to-peak ripple current of 912 mA and 1.122A when the converter is operating from 5 V and 3.3 V, respectively. Once an inductance value is calculated, an actual inductor needs to be selected based on a tradeoff between physical size, efficiency, and current carrying capability. For the LM20154 evaluation board, a Coilcraft MSS1038-102NL inductor offers a good balance between efficiency (6 m $\Omega$  DCR), size, and saturation current rating (9A I<sub>SAT</sub> rating).



#### 5.4 Output Capacitor

The value of the output capacitor in a buck regulator influences the voltage ripple that will be present on the output voltage, as well as the large signal output voltage response to a load transient. Given the peak-to-peak inductor current ripple ( $\Delta I_{P,P}$ ) the output voltage ripple can be approximated by Equation 5:

$$\Delta V_{OUT} = \Delta I_{P-P} \times \left[ R_{ESR} + \frac{1}{8 \times f_{SW} \times C_{OUT}} \right]$$

(5)

Component Selection

The variable  $R_{ESR}$  above refers to the ESR of the output capacitor. As can be seen in Equation 5, the ripple voltage on the output can be divided into two parts, one of which is attributed to the AC ripple current flowing through the ESR of the output capacitor and another due to the AC ripple current actually charging and discharging the output capacitor. The output capacitor also has an effect on the amount of droop that is seen on the output voltage in response to a load transient event.

For the evaluation board, a Murata 100  $\mu$ F ceramic capacitor is selected for the output capacitor to provide good transient and DC performance in a relatively small package. From the technical specifications of this capacitor, the ESR is roughly 2 m $\Omega$ , and the effective in-circuit capacitance is approximately 55  $\mu$ F (reduced from 100  $\mu$ F due to the 1.2 V DC bias). With these values, the peak-to-peak voltage ripple on the output when operating from a 5 V input can be calculated to be 3.9 mV.

#### 5.5 C<sub>SS</sub>

A soft-start capacitor can be used to control the startup time of the LM20154 voltage regulator. The startup time of the regulator when using a soft-start capacitor can be estimated by Equation 6:

$$t_{SS} = \frac{0.8V \times C_{SS}}{I_{SS}}$$
(6)

For the LM20154,  $I_{ss}$  is nominally 5  $\mu$ A. For the evaluation board, the soft-start time has been designed to be roughly 5 ms, resulting in a C<sub>ss</sub> capacitor value of 33 nF.

## 5.6 C<sub>VCC</sub>

The C<sub>VCC</sub> capacitor is necessary to bypass an internal 2.7 V sub-regulator. This capacitor should be sized equal to or greater than 1  $\mu$ F, but less than 10  $\mu$ F. A value of 1  $\mu$ F is sufficient for most applications.

# **5.7 C**<sub>C1</sub>

The capacitor  $C_{C1}$  is used to set the crossover frequency of the LM20154 control loop. Since this board was optimized to work well over the full input and output voltage range, the value of  $C_{C1}$  was selected to be 3.3 nF. Once the operating conditions for the device are known, the transient response can be optimized by reducing the value of  $C_{C1}$  and calculating the value for  $R_{C1}$  as outlined in Section 5.8.

# 5.8 **R**<sub>C1</sub>

Once the value of  $C_{C1}$  is known, resistor  $R_{C1}$  is used to place a zero in the control loop to cancel the output filter pole. This resistor can be sized according to Equation 7:

$$R_{C1} = \left[\frac{C_{C1}}{C_{OUT}} \times \left[\frac{I_{OUT}}{V_{OUT}} + \frac{1 - D}{f_{SW} \times L} + \frac{18 \times D}{V_{IN}}\right]\right]^{-1}$$

(7)

For stability purposes the device should be compensated for the maximum output current expected in the application.

6

#### **Component Selection**

#### 5.9 **C**<sub>C2</sub>

A second compensation capacitor C<sub>C2</sub> can be used in some designs to provide a high frequency pole, useful for cancelling a possible zero introduced by the ESR of the output capacitor. For the LM20154 evaluation board, the C<sub>c2</sub> footprint is unpopulated, as the low ESR ceramic capacitor used on the output does not contribute a zero to the control loop before the crossover frequency. If the ceramic capacitor on the evaluation board is replaced with a different capacitor having significant ESR, the required value of the capacitor  $C_{C2}$  can be estimated by Equation 8:

5.10 R<sub>s</sub>

 $C_{C2} = \frac{C_{OUT} \times R_{ESR}}{R_{C1}}$ 

The resistor R<sub>s</sub> is used to pull the open drain output of the SYNCOUT pin to the input voltage. The value of  $R_s$  was selected to be 4.99 k $\Omega$  which should work for most applications. However, keep in mind capacitive loading on the SYNC terminal can create additional phase lag in the SYNCOUT signal. When driving capacitive loads, a sharper SYNC edge can be optained by reducing the value of Rs.

## 5.11 $R_{FB1}$ and $R_{FB2}$

The resistors labeled R<sub>FB1</sub> and R<sub>FB2</sub> create a voltage divider from V<sub>OUT</sub> to the feedback pin that is used to set the output of the voltage regulator. Nominally, the output of the LM20154 evaluation board is set to 1.2 V, giving resistor values of  $R_{FB1} = 4.99 \text{ k}\Omega$  and  $R_{FB2} = 10 \text{ k}\Omega$ . If a different output voltage is required, the value of  $R_{FB1}$  can be adjusted according to Equation 9:

$$R_{FB1} = \left(\frac{V_{OUT}}{0.8} - 1\right) x R_{FB2}$$
(9)

 $R_{FB2}$  does not need to be changed from its value of 10 k $\Omega$ .



(8)

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6 PCB Layout

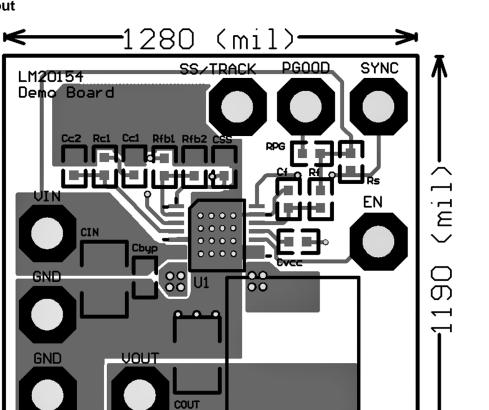


Figure 2. Top Layer

7

PCB Layout



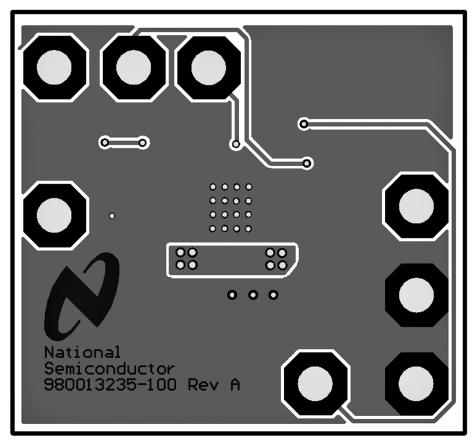


Figure 3. Bottom Layer

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