

Stellaris® LM3S9B92 EVALBOT

Robotic Evaluation Board

User's Manual



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Texas Instruments
108 Wild Basin, Suite 350
Austin, TX 78746
<http://www.ti.com/stellaris>



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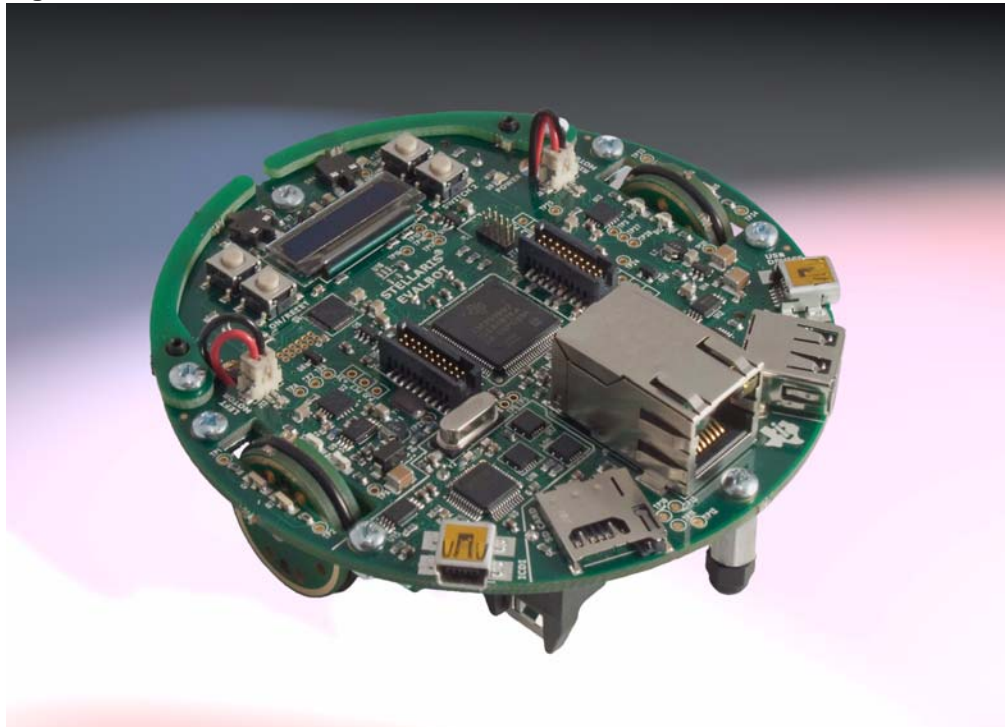
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Board Overview

The Stellaris® LM3S9B92 EVALBOT Robotic Evaluation Board (EVALBOT) is a robotic evaluation platform for the Stellaris LM3S9B92 microcontroller. The board also uses a range of Texas Instruments analog components for motor drive, power supply, and communications functions. The EVALBOT's electronics arrive ready-to-run. The board's robotics capabilities require less than 30 minutes of mechanical assembly. Figure 1-1 shows a photo of the EVALBOT.

Figure 1-1. Stellaris® LM3S9B92 EVALBOT Robotic Evaluation Board



When roaming, three AA batteries supply power to the EVALBOT. The EVALBOT automatically selects USB power when tethered to a PC as a USB device or when debugging. Test points are provided to all key EVALBOT signals. Two 20-pin headers enable future wireless communications using standardized Texas Instruments' low-power embedded radio modules (EM boards). Additional uncommitted microcontroller signals are available on break-out pads arranged in rows adjacent to the microcontroller.

The EVALBOT has factory-installed quickstart software resident in on-chip Flash memory. For software debugging and Flash programming, an integrated In-Circuit Debug Interface (ICDI) requires only a single USB cable for debug and serial port functions.

Features

The EVALBOT board includes the following features:

- Evaluation board with robotic capabilities
- Mechanical components assembled by user

- Stellaris® LM3S9B92-IQC80 microcontroller
- MicroSD card connector
- I²S audio codec with speaker
- USB Host and Device connectors
- RJ45 Ethernet connector
- Bright 96 x 16 Blue OLED display
- On-board In-Circuit Debug Interface (ICDI)
- Battery power (3 AA batteries) or power through ICDI USB cable

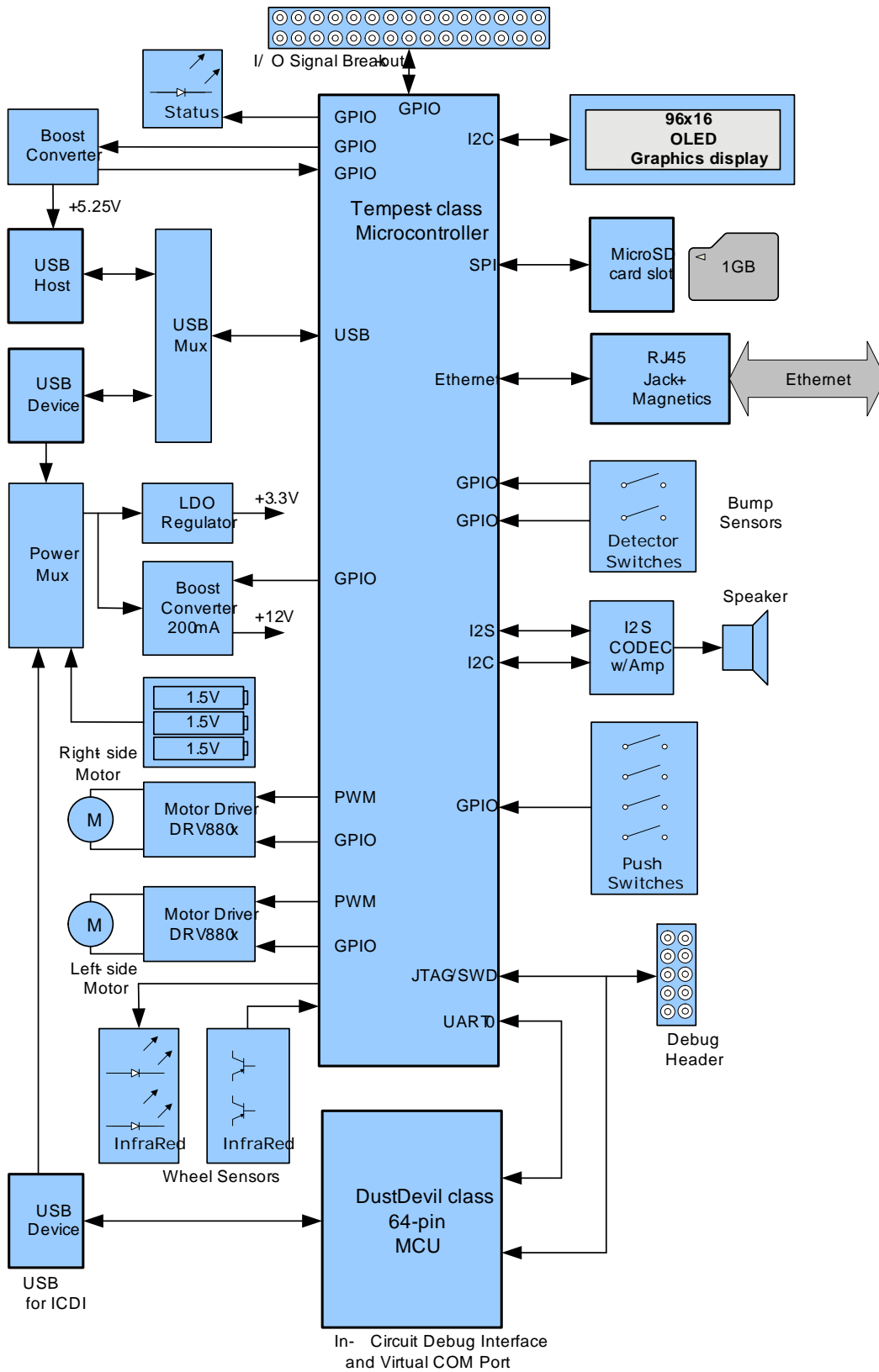
NOTE: EVALBOTs with serial numbers less than 50910-1500 do not support using the ICDI USB connector as a power source. During debugging, either install batteries or connect the USB device connector to a power source.

- Wireless communication expansion port
- Robot features
 - Two DC gear-motors provide drive and steering
 - Opto-sensors detect wheel rotation with 45° resolution
 - Sensors for “bump” detection

Block Diagram

The EVALBOT evaluation board uses the Stellaris® LM3S9B92 microcontroller and includes a 10/100 Ethernet port and a USB 2.0 full-speed On-the-Go (OTG) port. The EVALBOT combines all mechanical and electrical components on a single circuit board. Figure 1-2 on page 9 shows a block diagram of the electrical section of the EVALBOT.

Figure 1-2. EVALBOT Block Diagram



Specifications

Table 1-1 shows the specifications for the EVALBOT.

Table 1-1. EVALBOT Specifications

| Parameter | Min | Typical | Max |
|--------------------------------------|-------|-----------------------|--------|
| Battery Supply Voltage | 3.5 V | 4.5 V | 5.0 V |
| USB Supply Voltage | 4.0 V | 5.0 V | 5.25 V |
| Battery current (typical stationary) | – | 100 mA | – |
| Battery current (typical in motion) | – | 200 mA | – |
| Power down supply current | | 0.5 μ A | |
| AA Alkaline Battery Capacity (typ) | – | 2.5 A/Hr ^a | – |
| Reverse Battery Protection | | No | |
| Allowable Battery/USB Current | | | 0.5A |

a. From Energizer E91 data sheet.

Hardware Description

The EVALBOT consists of a 4-inch diameter circuit board populated with a Stellaris LM3S9B92 microcontroller and 14 additional Texas Instruments analog and digital semiconductors.

LM3S9B92 Microcontroller

The Stellaris LM3S9B92 is an ARM® Cortex™-M3-based microcontroller with 256-KB flash memory, 96-KB SRAM, 80-MHz operation, Ethernet MAC/PHY, USB Host/Device/OTG, and a wide range of other peripherals. See the LM3S9B92 microcontroller data sheet (order number DS-LM3S9B92) for complete device details.

Unused microcontroller signals are routed to either the 20-pin EM expansion headers or to 0.1" pitch break-out pads which are labeled with their GPIO reference. An internal multiplexer allows different peripheral functions to be assigned to each of these GPIO pads. When adding external circuitry, consideration should be given to the additional load on the EVALBOT's power rails.

The reference design may include additional components necessary to address silicon errata. For details of those circuit functions, see the LM3S9B92 Errata document.

Clocking

The EVALBOT uses a 16.0-MHz crystal (Y3) to complete the LM3S9B92 microcontroller's main internal clock circuit. An internal PLL, configured in software, multiplies this clock to higher frequencies for core and peripheral timing.

A 25.0 MHz (Y1) crystal provides an accurate timebase for the Ethernet PHY.

Reset

The RESET signal into the LM3S9B92 microcontroller connects to the Reset/On switch (SW6) and to the ICDI circuit for a debugger-controlled reset.

External reset is asserted (active low) under any one of three conditions:

- Power-on reset (filtered by an R-C network)
- Reset/On push switch SW6 held down
- By the ICDI circuit when instructed by the debugger (this capability is optional, and may not be supported by all debuggers).

The OLED Module and Audio CODEC have special Reset timing requirements requiring a dedicated control line from the microcontroller.

Power Supplies

The EVALBOT can be powered either from batteries, the ICDI USB cable, or a USB device cable. The power source is determined by a Texas Instruments TPS2113 Auto Switching Power Mux and two Schottky diodes. Battery power is selected automatically when USB power is not present.

Table 2-1 shows the EVALBOT's power supplies. Each supply is generated directly or indirectly from the main power bus, +VS, using either a linear regulator or boost converter.

Table 2-1. EVALBOT Power Supplies

| Name | Voltage | Max Current | Use |
|-----------|-------------|-------------|--|
| +VS | 3.5 – 5.0 V | 0.5 A | Main power distribution bus to other power rails |
| +3.3V | +3.3 V | 150 mA | Logic power supply for main MCU, digital, and ICDI functions |
| +3.3VA | +3.3 V | 150 mA | Analog and I/O power for audio CODEC |
| +1.8V | +1.8 V | 25 mA | Digital/core power for audio CODEC |
| +5V_HVBUS | +5.25 V | 100 mA | USB Host power supply |
| +12V | +12 V | 100 mA | Motor driver power supply |
| +10V | +10 V | 5 mA | OLED bias power supply |

The board's on/off feature uses two push switches (SW5, SW6) and a simple feedback circuit through the inverter created by MOSFET Q3. An internal 1uA constant current source on the TPS2113's Enable pin (ENn) ensures that the TPS2113 is initially powered on when power is connected. Resistor R47 sets the overcurrent protection to 0.5 A.

Organic LED Display

The user interface consists of a 96 x 16 OLED display and two push switches. The OLED display has an integrated controller IC with a parallel, SPI, and I²C interfaces. In this design, the I²C interface is used. The OLED display is limited to 'write-only' in this mode, so pixel data cannot be read back from the display.

microSD CARD

EVALBOT includes a microSD card interface, which interfaces to the MCU using a SPI interface. Because power to the SD card is not controlled removing or inserting the card while power is applied is not recommended.

Audio

A Texas Instruments TLV320AIC3107 CODEC adds a high performance audio stage to the EVALBOT. An integrated mono class-D amplifier drives an on-board speaker, with other audio inputs and outputs available on break-out header pads. An I2S interface carries the output (and input) audio data streams, while an I²C interface configures the CODEC. Most unused audio pins are available on nearby pads (0.05"pitch).

Ethernet

With its fully integrated 10/100 Ethernet MAC and PHY, the LM3S9B92 requires only a standard Jack with integrated magnetics and a few passive components. The TX and RX signals are routed to the jack as a differential pair. The PHY incorporates MDI/MDI-X cross-over, so the function of the TX and RX pairs can be swapped in software.

USB

The LM3S9B92 microcontroller has Host, Device, and OTG USB capabilities. EVALBOT supports USB Host and Device with dedicated connectors and a Texas Instruments T3USB30E high-speed USB multiplexer to select between them.

Robotic Features

Two 12-V gear motors provide locomotion to the EVALBOT. A Texas Instruments' DRV8801 Full-Bridge motor driver IC controls each motor; providing direction control, over-current and short-circuit protection, dead-time insertion and several switching schemes.

Each EVALBOT wheel has two infra-red optical sensors which generate a quadrature signal as the wheel rotates. The IR emitters (D2, D3, D11, and D12) each connect to a GPIO signal so that the MCU can turn off the LEDs for power saving when not in motion. The GPIO outputs should be configured for 8 mA drive-strength to ensure the IR emitters have sufficient intensity.

Left and right-side bumpers detect collisions using simple detector switches. The GPIO inputs should have internal pull-up resistors enabled and may optionally be configured to generate an interrupt when a collision occurs.

Expansion

The EM port on EVALBOT enables RF connectivity using a range of Low-Power RF Evaluation Modules (EM boards) from Texas Instruments. EM boards cover both Sub 1-GHz and 2.4GHz bands and are supported by a several different protocol stacks.

The EM port can also be used for general purpose expansion. SPI, UART, and GPIO signals are available. Table 2-2 lists the connector part numbers. Two identical connectors should be installed on a 1.20" pitch.

Table 2-2. Connector Part Numbers

| Supplier | Part Number | Description | Use |
|----------|----------------|--------------------------------|-----------------|
| Samtec | TFM-110-02-S-D | SMT Header 20-pos 0.050" pitch | EVALBOT EM port |
| Samtec | SFM-110-02-S-D | SMT Socket 20-pos 0.050" pitch | EM board |

In addition to the EM port, EVALBOT also has 9 GPIO (PJ0..7, PE7), Power and GND connections on a 0.1" grid.

Debugging

EVALBOT includes an integrated In-Circuit Debug Interface (ICDI) for debugging, serial communication and power over a single USB cable. Based on an FTDI FT2232 USB controller, the ICDI supports all major Cortex-M3 development environments.

Stellaris microcontrollers support programming and debugging using either JTAG or SWD. JTAG uses the signals TCK, TMS, TDI, and TDO. SWD requires fewer signals (SWCLK, SWDIO, and, optionally, SWO for trace). The debugger determines which debug protocol is used.

An external debug interface can be used with EVALBOT if connector J4 is installed by the user.

JTAG/SWD

The FT2232 is factory-configured by Texas Instruments to implement a JTAG/SWD port (synchronous serial) on channel A and a Virtual COM Port (VCP) on channel B. This feature

allows two simultaneous communications links between the host computer and the target device using a single USB cable. Separate Windows drivers for each function are provided on the Documentation and Software CD.

The In-Circuit Debug Interface USB capabilities are completely independent from the LM3S9B92's on-chip USB functionality.

A small serial EEPROM holds the FT2232 configuration data. The EEPROM is not accessible by the LM3S9B92 microcontroller. For full details on FT2232 operation, go to www.ftdichip.com.

The FT2232 USB device performs JTAG/SWD serial operations under the control of the debugger. A simple logic circuit multiplexes SWD and JTAG functions and, when working in SWD mode, provides direction control for the bidirectional data line.

Virtual COM Port

The Virtual COM Port (VCP) allows Windows applications (such as HyperTerminal) to communicate with UART0 on the LM3S9B92 over USB. Once the FT2232 VCP driver is installed, Windows assigns a COM port number to the VCP channel.

Serial Wire Out

EVALBOT also supports the Cortex-M3 Serial-Wire Output (SWO) trace capabilities. Under debugger control, on-board logic can route the SWO data stream to the VCP transmit channel. The debugger software can then decode and interpret the trace information received from the Virtual Com Port. The normal VCP connection to UART0 is interrupted when using SWO. Not all debuggers support SWO.

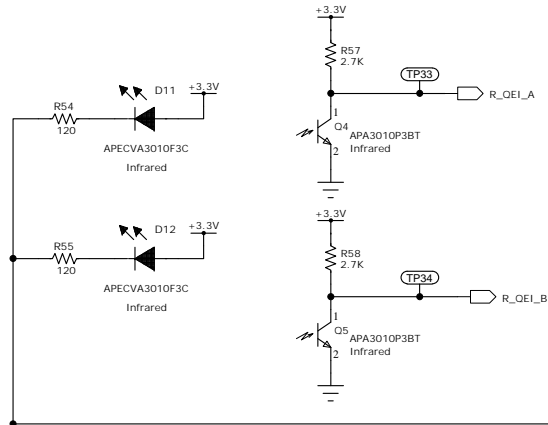
See the *Stellaris LM3S9B92 Microcontroller Data Sheet* for additional information on the Trace Port Interface Unit (TPIU).

Schematics

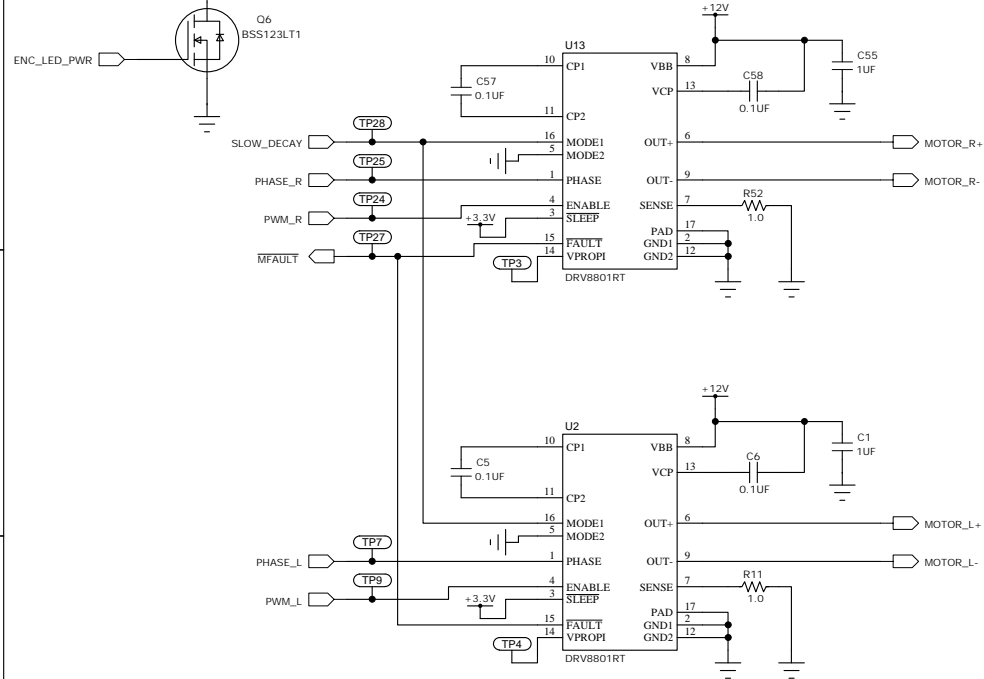
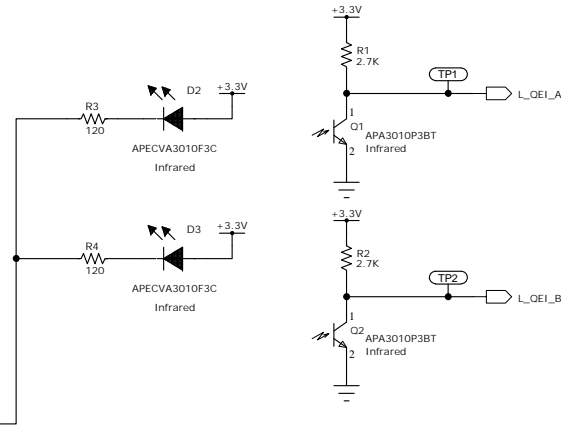
Schematics for the EVALBOT board follow.

- Microcontroller, Ethernet, and USB on page 16
- Wheel Encoders, Motor Drivers, and Bumper Switches on page 17
- User Interface, Audio, SD Card on page 18
- Power Supplies on page 19
- In-Circuit Debug Interface on page 20

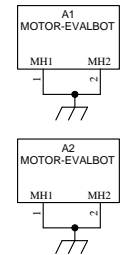
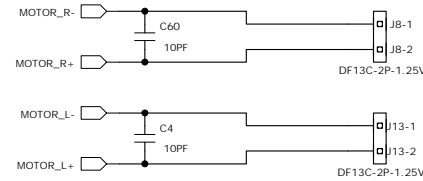
RIGHT-WHEEL ENCODER



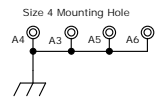
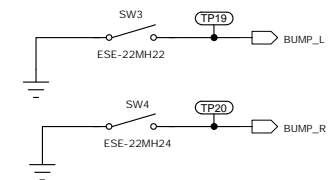
LEFT-WHEEL ENCODER



MOTOR TERMINALS

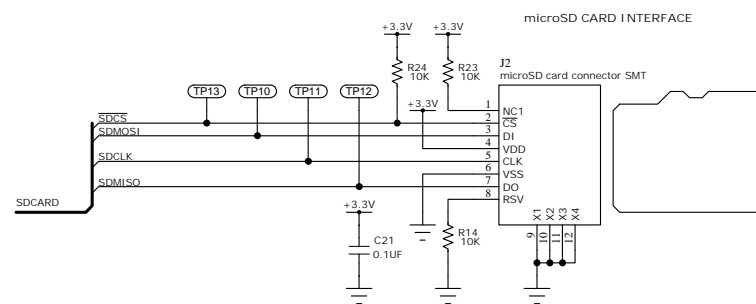
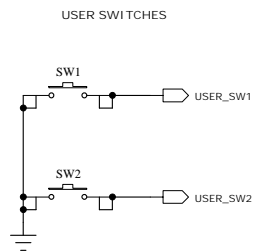
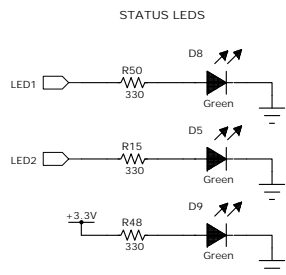
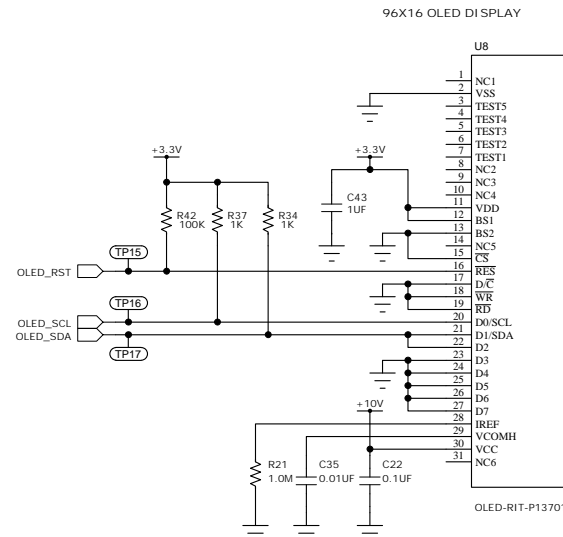
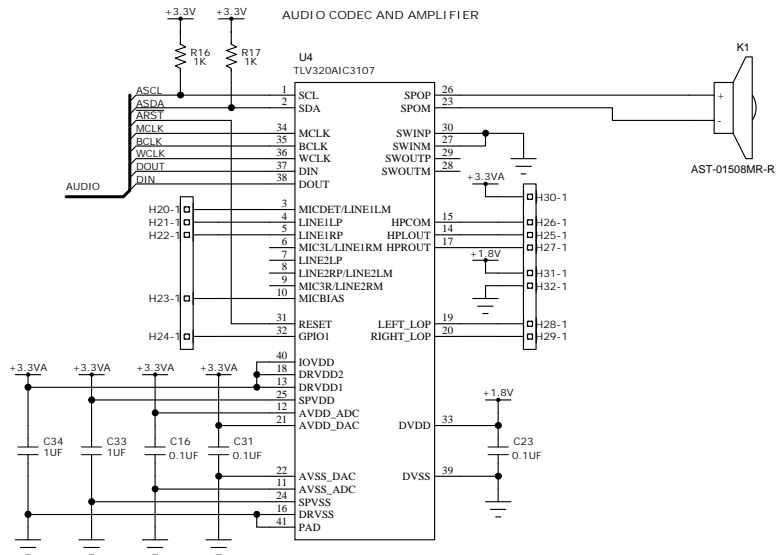


BUMPER SWITCHES




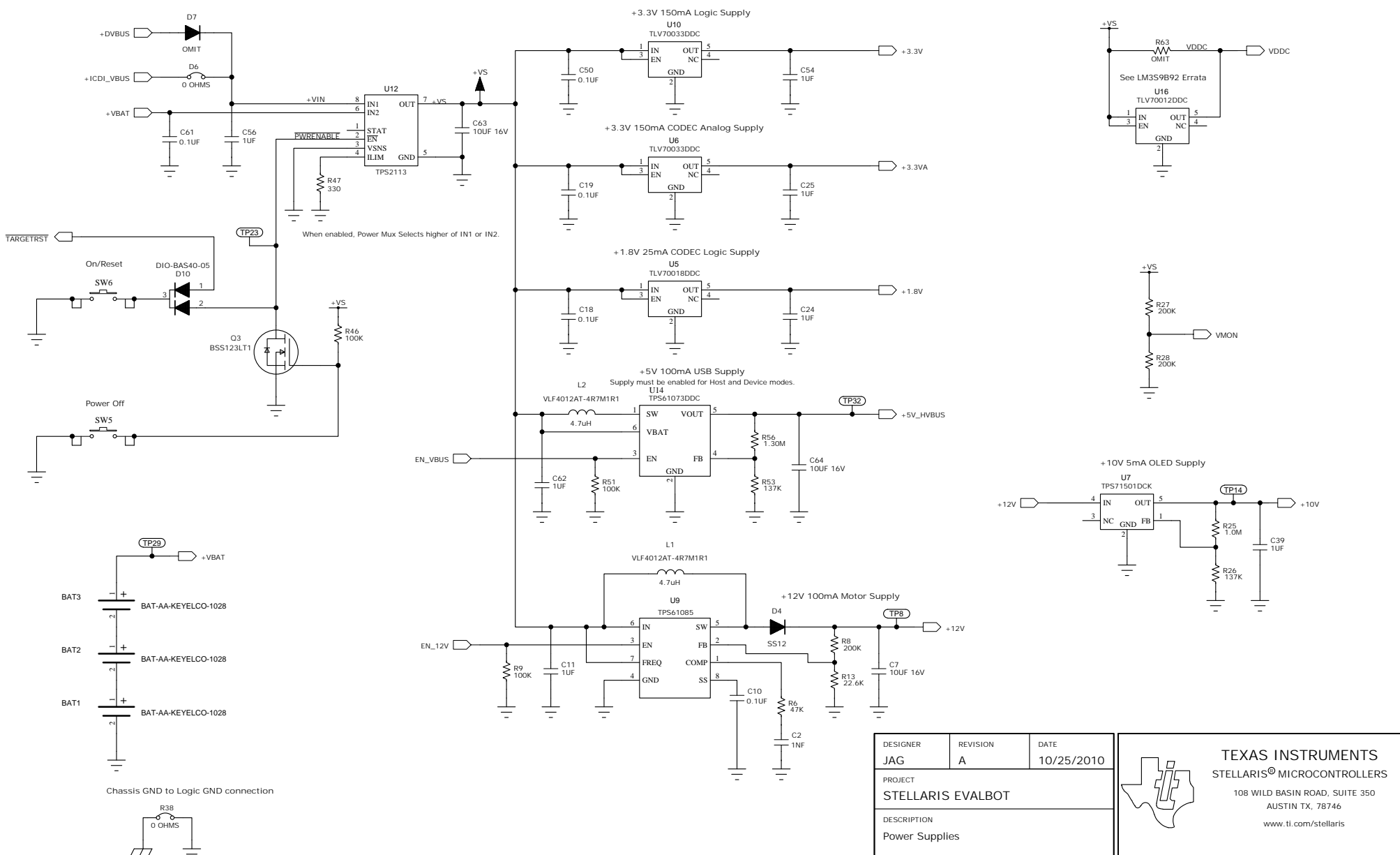
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| ?DESC2? | | |
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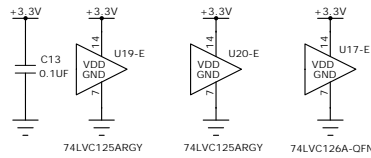
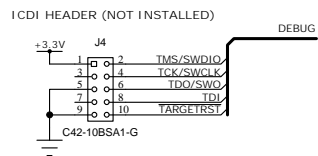
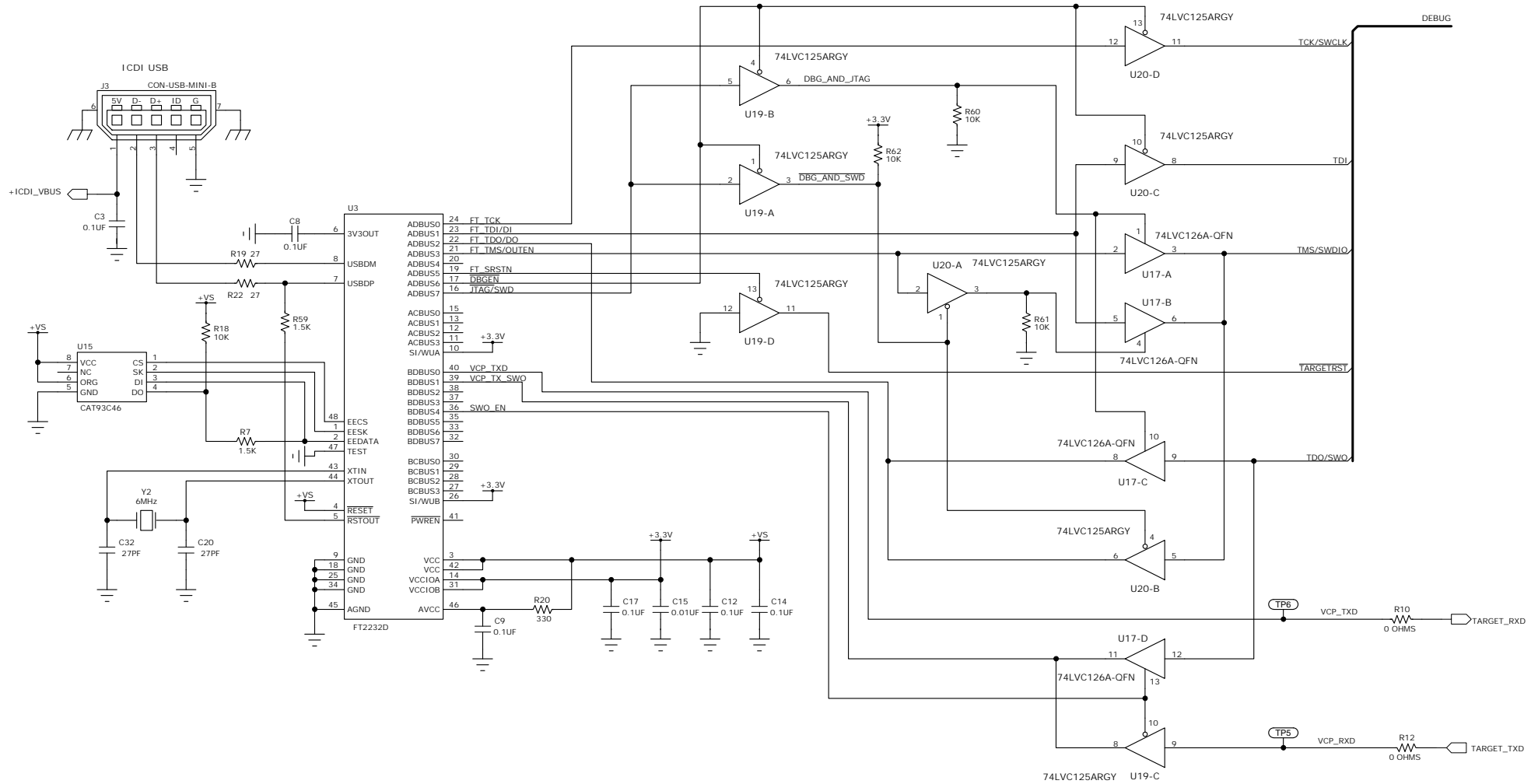
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| DESIGNER | REVISION | DATE |
| JAG | A | 10/25/2010 |
| PROJECT | | |
| STELLARIS EVALBOT | | |
| DESCRIPTION | | |
| USER INTERFACE, AUDIO, SD CARD | | |
| FILENAME | EvalBot Rev A.sch | |

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| | | 3 OF 5 |



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|-------------------|-------------------|------------|
| DESIGNER | REVISION | DATE |
| JAG | A | 10/25/2010 |
| PROJECT | | |
| STELLARIS EVALBOT | | |
| DESCRIPTION | | |
| Power Supplies | | |
| FILENAME | EvalBot Rev A.sch | |

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| | PART NO. | EK-EVALBOT-A |
| | SHEET | 4 OF 5 |



| | | |
|---|---------------|--------------------|
| DESIGNER JAG | REVISION A | DATE 10/25/2010 |
| PROJECT STELLARIS EVALBOT | | |
| DESCRIPTION In-Circuit Debug Interface | | |
| FILENAME EvalBot Rev A.sch | | |

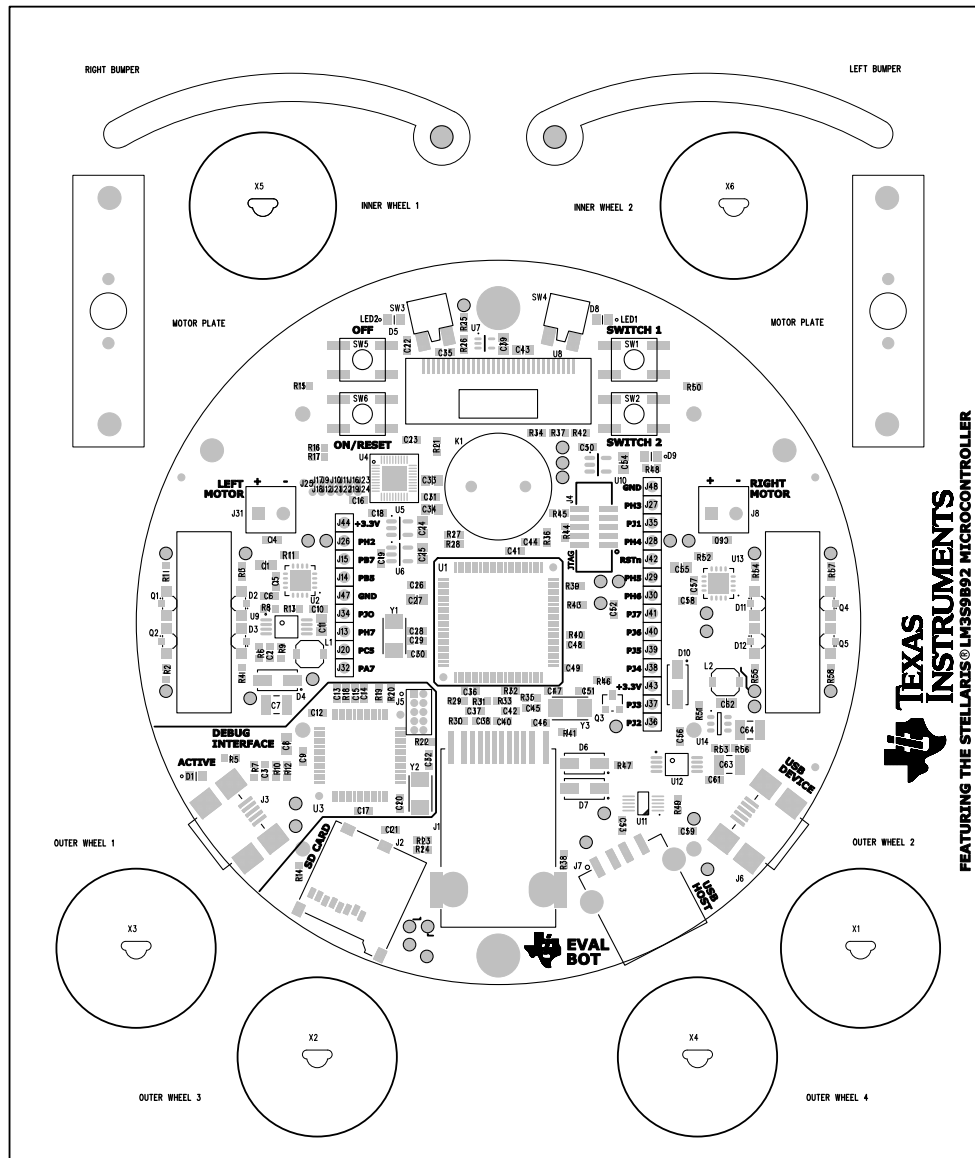
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| | PART NO. EK-EVALBOT-A | SHEET 5 OF 5 |

APPENDIX B

Component Locations

Plots of the top-side and bottom-side component locations are shown in Figure B-1. Complete Gerber (RS274X) and PCB (Mentor PADS) files for the four-layer PCB layout are included in the EVALBOT Board Hardware Package.

Figure B-1. EVALBOT Component Locations



A P P E N D I X C

Bill of Materials (BOM)

Table C-1 shows the Bill of Materials for the EVALBOT board design.

Table C-1. EVALBOT Bill of Materials (BOM)

| Item | Reference | Qty | Part Number | Description | Mfg |
|------|--|-----|--|--|---------------------|
| 1 | BAT1-3 | 3 | 1028 | Compact AA Battery holder, through-hole | Keystone |
| 2 | C1 C11 C24-25 C27 C33-34 C39 C43 C54 C55 C56 C62 | 13 | C2012X5R1E105K | Capacitor, 1.0uF 25V 10% X5R 0805 | TDK |
| 3 | C15 C35 C41 C44 C48 | 5 | C0603C103J5RACTU | Capacitor, 0.01uF 50V 5% 0603 X7R | Kemet |
| 4 | C2 | 1 | C0603C102J5RACTU | Capacitor , 0.001uF 50V 5% 0603 X7R | Kemet |
| 5 | C3 C5-6 C8-10 C12-14 C16-19 C21-23 C26 C30-31 C36-37 C46 C49-50 C52-53 C57-59 C61 C65 | 31 | GRM188R71H104KA 93D | Capacitor, 0.1uF 50V 10% 0603 X7R | TDK |
| 6 | C4 C28-29 C38 C40 C42 C45 C47 C51 C60 | 10 | C0603C100J5GACTU | Capacitor 10pF 50V 5% Ceramic NPO/COG 0603 | Kemet |
| 7 | C20 C32 | 2 | C0603C270J5GACTU | Capacitor 27pF 50V 5% Ceramic NPO/COG 0603 | Kemet |
| 8 | C7 C63-64 | 3 | C3225X5R1C106M | Capacitor, 10uF 16V 20% X5R 1210 | TDK |
| 9 | D5 D8-9 | 3 | LTST-C171GKT | LED, 0805 SMT Green | LiteOn |
| 10 | D2-3 D11-12 | 4 | APECVA3010F3C | LED, Infrared, Right Angle in 3.0 x 1.0mm SMT | Kingbright |
| 11 | D4 D6-7 | 4 | SS12 | Diode, Schottky 20V 1A SMA | Taiwan Semi |
| 12 | D10 | 1 | BAS40-05-7-F | Diode, Schottky 40V 100mA SOT23 | Diodes |
| 13 | J1 | 1 | HR961160C J3011G21DNL J3011G21DNLT | Connector, RJ45 with 10/100 magnetics, shielded SMT | Hanrun Pulse |
| 14 | J2 | 1 | 2908-05WB-MG | Connector, Micro SD card, push-push SMT | 3M |
| 15 | J3 J6 | 2 | 54819-0572 | Connector, USB Mini-B SMT 5pin | Molex |
| 16 | J7 | 1 | AU-Y1006-R 154-UAR42-E | Connector, USB Type A | Assmann Kobiconn |

Table C-1. EVALBOT Bill of Materials (BOM) (Continued)

| Item | Reference | Qty | Part Number | Description | Mfg |
|------|--|-----|-----------------------|---|--------------------|
| 17 | J8 J13 | 2 | DF13C-2P-1.25V(20) | Connector, Header 2 pos, 1.25mm SMD Tin | Hirose |
| 18 | K1 | 1 | AST-01508MR-R | Speaker, 8 ohm 0.3W 15mm PCB mount | Projects Unlimited |
| 19 | L1-2 | 2 | VLF4012AT-4R7M1R 1 | Inductor 3.7x3.5 SMT 1.1A | TDK |
| 20 | Q1-2 Q4-5 | 4 | APA3010P3BT | Phototransistor, Infrared, Right Angle in 3.0 x 1.0mm SMT | Kingbright |
| 21 | Q3 Q6 | 2 | BSS123LT1 | MOSFET, N-Channel 100V 170mA SOT-23 | On Semi |
| 22 | R11 R52 | 2 | | Resistor 1 ohms 1% 0603 | Generic |
| 23 | R19, R22 | 2 | | Resistor 27 ohms 5% 0603 | Generic |
| 24 | R1-2 R57-58 | 4 | | Resistor 4.7K 5% 0603 | Generic |
| 25 | R13 | 1 | | Resistor 22.6K 1% 0603 | Generic |
| 26 | R14 R18 R23-24 R36 R40 R44-45 R49 R60-62 | 12 | | Resistor 10K 5% 0606 | Generic |
| 27 | R39 | 1 | | Resistor 9.10K 1% 0603 | Generic |
| 28 | R21 R25 | 2 | | Resistor 1.0M 1% 0603 | Generic |
| 29 | R26 R53 | 2 | | Resistor 137K 1% 0603 | Generic |
| 30 | R29 | 1 | | Resistor 12.4K 1% 0603 | Generic |
| 31 | R5, R64 | 2 | | Resistor, 10 ohms 5% 0603 | Generic |
| 32 | R31-33 R35 R43 | 5 | | Resistor 49.9 ohms 1% 0603 | Generic |
| 33 | R3-4 R54-55 | 4 | | Resistor 120 ohms 1% 0603 | Generic |
| 34 | R10, R12, R38 | 3 | | Resistor 0 ohms 0603 | Generic |
| 35 | R16-17 R34 R37 R47 R63 | 6 | | Resistor 1K 5% 0603 | Generic |
| 36 | R7, R59 | 2 | | Resistor 1.5K 5% 0603 | Generic |
| 37 | R15 R20 R30 R41 R48 R50 | 6 | | Resistor 330 ohms 5% 0603 | Generic |
| 38 | R56 | 1 | | Resistor 1.30M 1% 0603 | Generic |
| 39 | R6 | 1 | | Resistor 47K 5% 0603 | Generic |
| 40 | R8 R27-28 | 3 | | Resistor 200K 1% 0603 | Generic |
| 41 | R9 R42 R46 R51 | 4 | | Resistor 100K 1% 0603 | Generic |
| 42 | SW3 | 1 | ESE-22MH22 | Switch, Detector-style Horizontal - Right/top actuation | Panasonic |

Table C-1. EVALBOT Bill of Materials (BOM) (Continued)

| Item | Reference | Qty | Part Number | Description | Mfg |
|------|-------------|-----|--|---|----------------|
| 43 | SW4 | 1 | ESE-22MH24 | Switch, Detector-style Horizontal - Left/top actuation | Panasonic |
| 44 | SW1-2 SW5-6 | 2 | EVQ-Q2B02W | Switch, Tact 6mm SMT, 50gf | Panasonic |
| 45 | U3 | 1 | FT2232D | IC, USB to Serial Interface TQFP48 | Ftdi |
| 46 | U15 | 1 | CAT93C46YI-G / AT93C46A-10TU-2.7 | IC, Serial Eeprom 1Kbit TSSOP8 | Catalyst Atmel |
| 47 | Y1 | 1 | NX5032GA-25.00000 0MHZ 8B48-25.000MHZ TR | Crystal, 25.00MHz 5.0x3.2mm SMT | NDK Suntsu |
| 48 | Y2 | 1 | FOXSDLF/060-20 | Crystal, 6.00MHz HC49US SMT | Fox |
| 49 | Y3 | 1 | NX5032GA- 16.000000MHZ | Crystal, 16.00MHz 5.0x3.2mm SMT | tbd |
| 50 | J5 J33 | 2 | TFM-110-02-S-D-K-A | Connector, 20 pos 1.27mm pitch, SMT | Samtec |
| 51 | U1 | 1 | LM3S9B92-IQC80 | IC, ARM Cortex-M3 Microcontroller TQFP100 | TI |
| 52 | U2 U13 | 2 | DRV8801RTY | IC, Full-Bridge Motor Driver | TI |
| 53 | U4 | 1 | TLV320AIC3107IRSB R | IC, Audio CODEC with class D amplifier WQFN | TI |
| 54 | U5 | 1 | TLV70018DDCT | IC, 1.8V 200mA Low-dropout voltage regulator | TI |
| 55 | U6 U10 | 2 | TLV70033DDCT | IC, 3.3V 200mA Low-dropout voltage regulator | TI |
| 56 | U7 | 1 | TPS71501DCKR | IC, Adjustable 50mA Low-dropout voltage regulator, SC70 | TI |
| 57 | U8 | 1 | RGS08096016BW00 1 | OLED display, 96x16 Blue 13701 | RiT |
| 58 | U9 | 1 | TPS61085PWR | IC, Step-up DC-DC Converter | TI |
| 59 | U11 | 1 | TS3USB30EDGSR | IC, High Speed USB 2.0 1:2 Mux/Demux Switch SSOP | TI |
| 60 | U12 | 1 | TPS2113PW | IC, 2-Ch Auto-switching power mux | TI |
| 61 | U14 | 1 | TPS61073DDC | IC, Synchronous Boost Converter with 600-mA switch | TI |
| 62 | U17 | 1 | SN74LVC126ARGY | IC, Quad tri-state line driver act lo TSSOP14 | TI |
| 63 | U19 U20 | 2 | SN74LVC125ARGY | IC, Quad tri-state line driver act hi TSSOP14 | TI |
| 64 | PCB1 | 1 | PCB-EVALBOT-A | PCB, 4-layer 5.200x6.850" | |
| 65 | LABEL1 | 1 | LABEL-EVALBOT | Label, 2.90" x 0.50" 'Learn more at www.ti.com/EVALBOT '. Place on robot underside. | |

References

In addition to this document, the following references are available for download at www.ti.com.

- *Stellaris LM3S9B92 Microcontroller Data Sheet*
- *Stellaris LM3S5632 Microcontroller Data Sheet*
- *DMOS Full-Bridge Motor Drivers Data Sheet (DRV8801RTY)*
- *Low-Power Stereo CODEC with Integrated Mono Class-D Amplifier Data Sheet (TLV320AIC3107)*
- *200mA, Low IQ, Low Dropout Regulator for Portables Data Sheet (TLV70018)*
- *200mA, Low IQ, Low Dropout Regulator for Portables Data Sheet (TLV70033)*
- *50mA, 24V, 3.2- μ A Supply Current, Low-Dropout Linear Regulator in SC70 Package Data Sheet (TPS71501)*
- *650 kHz/1.2MHz Step-Up DC-DC Converter w/ Forced PWM Mode Data Sheet (TPS61085)*
- *High-Speed USB 2.0 (480 Mbps) 1:2 Multiplexer/Demultiplexer Switch With Single Enable Data Sheet (TS3USB30)*
- *Dual In/Single Out Autoswitching Power MUX Data Sheet (TPS2113)*
- *Adjustable, 600-mA Switch, 90% Efficient PFM/PWM Boost Converter in ThinSOT Data Sheet (TPS61073)*
- The following data sheets can be obtained from the manufacturer:
- *P13701 OLED Display Data Sheet from RiT Display Corporation*
- *SSD1300 OLED Controller Data Sheet from Solomon Systech Limited*

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