CC1111/CC2511 USB HW
User’s Guide

swru082b
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1 Introduction
Thank you for purchasing a development kit for Low Power RF System-on-Chips from Texas Instruments.

2 About this Manual
This manual covers the CC1111 USB Dongle or the CC2511 USB Dongle found in the CC1110-CC1111DK/CC2510-CC2511DK development kits. Both these USB dongles are also available separately as the CC1111EMK868-915 and CC2511EMK evaluation module kits.


3 Acronyms

<table>
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<tr>
<th>Acronym</th>
<th>Description</th>
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<tr>
<td>CDC</td>
<td>Communications Device Class</td>
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<tr>
<td>DK</td>
<td>Development Kit</td>
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<tr>
<td>EB</td>
<td>Evaluation Board</td>
</tr>
<tr>
<td>EM</td>
<td>Evaluation Module</td>
</tr>
<tr>
<td>HID</td>
<td>Human Interface Device</td>
</tr>
<tr>
<td>IC</td>
<td>Integrated Circuit</td>
</tr>
<tr>
<td>ICE</td>
<td>In Circuit Emulator</td>
</tr>
<tr>
<td>KB</td>
<td>Kilo Byte (1024 byte)</td>
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<tr>
<td>LED</td>
<td>Light Emitting Diode</td>
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<tr>
<td>LPRF</td>
<td>Low Power RF</td>
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<td>MCU</td>
<td>Micro Controller</td>
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<td>NC</td>
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<td>RF</td>
<td>Radio Frequency</td>
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<td>RX</td>
<td>Receive</td>
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<tr>
<td>SoC</td>
<td>System on Chip</td>
</tr>
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<td>Texas Instruments</td>
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<tr>
<td>TX</td>
<td>Transmit</td>
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<tr>
<td>UART</td>
<td>Universal Asynchronous Receive Transmit</td>
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<td>USB</td>
<td>Universal Serial Bus</td>
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4 Definitions

<table>
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<th>SmartRF04EB</th>
<th>CC1110EM/CC2510EM</th>
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<tr>
<td>Evaluation Board. Main board in the development kits, USB interface, LCD, LEDs, pot-meter etc. Development platform for the Evaluation Modules (EM).</td>
<td>CC1110 and CC2510 Evaluation Module are small modules for the CC1110 and CC2510 devices. These can be plugged into the SmartRF04EB and they should be used as the reference design for antenna and RF layout.</td>
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<table>
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<th>CC1111/CC2511 USB Dongle</th>
<th>System-on-Chip Debug Plug-in Board</th>
</tr>
</thead>
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<tr>
<td>A reference design for a CC1111/CC2511 based full-speed USB dongle with RF interface. Should be used as reference design for antenna and RF layout.</td>
<td>The System-on-Chip Debug Plug-In Board. It provides an additional physical debug/programming interface for the SmartRF04EB. Referred to as SOC_DEM in this document.</td>
</tr>
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Figure 1. Kit Hardware Component Overview

<table>
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<th>Definition</th>
<th>Description</th>
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<tr>
<td>SoC</td>
<td>System on Chip. A collective term used to refer to Texas Instruments ICs with on-chip MCU and RF transceiver. Used in this document to reference the CC1111/CC2511 and the CC1110/CC2510.</td>
</tr>
<tr>
<td>ICE</td>
<td>In Circuit Emulator. ICE functionality is built into the SmartRF04EB.</td>
</tr>
<tr>
<td>USB Software Application Examples</td>
<td>Application examples using the CC1111/CC2511 USB Dongle together with a CC1110/CC2510EM.</td>
</tr>
<tr>
<td>USB Firmware Library</td>
<td>A library of low level USB firmware which is used by all the USB software examples.</td>
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</table>

Table 1. Key Definitions

See Figure 1 for an overview of the hardware components contained in the CC1110-CC1111DK/CC2510-CC2511DK development kits. Table 1 explains some of the key definitions/abbreviations used in this document.
5 Getting Started

Make sure to install SmartRF Studio before connecting the SmartRF04EB to a PC. By installing it, the required Windows drivers will be provided when connecting the SmartRF04EB.

The USB dongle is not delivered with pre-programmed firmware so an external ICE is needed for initial programming of the device. The SmartRF04EB or the CC-Debugger can be used to program the USB dongle. The CC1111/CC2511 has a 2 wire debug interface that is used for chip programming and debugging. When connecting this interface to the SmartRF04EB, the CC1111/CC2511 can be programmed from the SmartRF Flash Programmer software [4] and debugged from IAR Embedded Workbench. To connect the CC1111/CC2511 USB Dongle to the SmartRF04EB, follow these 7 steps:

1. Turn off the SmartRF04EB power by moving the power switch shown in Figure 4 to the left position.
2. Remove any evaluation modules (EMs) attached to the SmartRF04EB.
3. Connect the SmartRF04EB to a PC with the supplied USB cable.
4. Connect the System-on-Chip Debug Plug-In Board (SOC_DEM) to the EM connectors (P1 and P2) on the SmartRF04EB.
5. Connect the USB Dongle to the SOC_DEM with the supplied 10 pin cable. The cable should be mounted between the “Debug” connector on the dongle and the P3 connector on the SOC_DEM. Make sure pin 1 on the dongle is connected to pin 1 on the SOC_DEM (truncated corner). This cable connects the debug interface and GND between the two devices; however the USB Dongle is not powered through this cable.
6. Power the CC1111/CC2511 USB Dongle. To power the dongle there are two options:
   - **Powered with a USB Cable**
     Use the supplied USB extension cable to connect the USB Dongle to the PC (see Figure 2).
   - **Powered from the SmartRF04EB**
     Connect pin 9 on the “Test pin” connector on USB Dongle to pin 3 (labelled “3.3 V”) on the “I/O B” connector on SmartRF04EB to power the dongle from the EB (see Figure 3).

The CC1111/CC2511 USB Dongle should only be powered by one of the two sources at a time. Do not connect the USB cable to the USB Dongle while it is powered from the SmartRF04EB. The SOC_DEM has a voltage level converter on the P3 connector, so the SmartRF04EB and the USB Dongle may have a different power supply voltage.
7. Turn on the power on the SmartRF04EB (see Figure 4).
The CC1111/CC2511 can now be programmed with the SmartRF Flash Programmer software. The firmware on the CC1111/CC2511 can also be debugged using the IAR Embedded Workbench debugger. Please see the SmartRF Flash Programmer [2] user manual for more details.

Please see the “CC1110DK/CC2510DK Development Kit User Manual” [1] for more information on the SmartRF04EB and how to use the CC1110/CC2510EMs.
6 Using SmartRF04EB as an In-Circuit Emulator (ICE)

The debug interface on the SmartRF04EB is controlled by the USB MCU. This allows both programming and an emulator interface over USB, which makes the SmartRF04EB usable as an In-Circuit Emulator (ICE) for the CC1111/CC2511.

To use the SmartRF04EB as ICE, the IAR Embedded Workbench software for 8051 architecture (EW8051) must be installed. The Embedded Workbench is an integrated development environment with a complete tool-chain such as C Compiler, Simulator, and ICE debugger. Please see [1] for instructions on how to set up the ICE debugger for use as an ICE.

When the SmartRF04EB with a SoC is connected to a PC with the USB port, the debugger in IAR EW8051 will connect to it when started. If several SmartRF04EBs are connected to USB ports simultaneously, a selection window will display the connected evaluation boards, and the user can select which device to load.

6.1 The Debug Interface

For custom PCB’s with e.g. the CC2511 SoC, it is recommended to include a pin header or test points to allow in-circuit emulation or programming using a SmartRF04EB or other 3rd party programming tools. The USB Dongle can be used as a reference. Please see the CC1110/CC2510/CC1111/CC2511 section of the TI web site for an updated list of 3rd party programming tools.

VDD note: The SmartRF04EB includes a voltage converter to support programming and debugging of external systems with different voltage than the SmartRF04EB. The debug connector includes two VDD connections on pin 2 and pin 9. The function is different for these connections.

Pin 2 VDD supplies voltage from the external target to the voltage converter. If the target application is self powered pin 2 should be connected to VDD to assure that the correct supply voltage is used for the voltage converter. This pin must always be connected to VDD.

Pin 9 VDD supplies VDD (3.3 V) from the SmartRF04EB. If the target application is powered from the SmartRF04EB supply during programming and debugging this pin can be connected to VDD. If the target voltage differs from 3.3V, this pin should not be connected.

On the USB Dongle this pin is not connected. Hence the USB Dongle must be powered from either a separate USB cable or a separate cable connecting pin 9 on P4 / “test pins” on the dongle to VDD on the SmartRF04EB. When using SmartRF04EB as emulator for external target debugging any evaluation module (EM) must be removed.

Figure 5 shows the required signal for a minimum connector layout on external target.

![Figure 5. Minimum Debug Connector Pinout (top view)](image-url)
7 USB Dongle Hardware Description

Figure 6. CC2511 USB Dongle, (top view)

Figure 7. CC2511 USB Dongle, (back view)

Figure 8. CC1111 USB Dongle, (top view)

Figure 9. CC1111 USB Dongle, (back view)
7.1 User Interface

The CC1111/CC2511 USB Dongle has one button and one LED that can be used to interact with the user. The LED is connected to pin P1_1. Setting P1_1 high (to logic 1) will turn the LED on. The button is connected to pin P1_2 and GND. The pin P1_2 must be configured as an input with pull-up for the button to operate as intended. When the button is pushed, P1_2 is pulled low (to logic 0).

7.2 USB Interface

The USB Dongle has a standard USB connector. The dongle is powered through this connector. On the D+ line there is a pull-up used to identify the dongle as a full-speed USB device on the USB bus. The pull-up can be controlled from the firmware, using P1_0. This enables the dongle to be connected to the USB bus without signalling its presence to the USB hub.

7.3 Debug Connector

The USB Dongle has debug connector (P3) that is compatible with the SoC debug connector on the SmartRF04EB (P14) and on the System-on-Chip Debug Plug-In board (SOC_DEM) (P3). This enables the USB Dongle to be programmed and debugged via the SmartRF04EB. The pin-out of the debug connector (P3) is given in Table 2.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>GND</td>
</tr>
<tr>
<td>2</td>
<td>VDD</td>
</tr>
<tr>
<td>3</td>
<td>P2_2 / debug clock</td>
</tr>
<tr>
<td>4</td>
<td>P2_1 / debug data</td>
</tr>
<tr>
<td>5</td>
<td>P1_4</td>
</tr>
<tr>
<td>6</td>
<td>P1_5</td>
</tr>
<tr>
<td>7</td>
<td>RESET_N</td>
</tr>
<tr>
<td>8</td>
<td>P1_6</td>
</tr>
<tr>
<td>9</td>
<td>Not connected (VDD by mounting R6, 0 Ohm)</td>
</tr>
<tr>
<td>10</td>
<td>P1_7</td>
</tr>
</tbody>
</table>

Table 2. Debug Connector (P3) Pin-Out

7.4 General Purpose I/O Connectors

All GPIO pins on the CC1111/CC2511 SoC that are not used on the USB Dongle are routed to the P4 “Test pins” pin-row. They can be used for debugging or to connect external devices to the CC1111/CC2511. The pin-out is given in Table 3.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>P2_0</td>
</tr>
<tr>
<td>2</td>
<td>GND</td>
</tr>
<tr>
<td>3</td>
<td>P0_5</td>
</tr>
<tr>
<td>4</td>
<td>P0_4</td>
</tr>
<tr>
<td>5</td>
<td>P0_3</td>
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<td>6</td>
<td>P0_2</td>
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<tr>
<td>7</td>
<td>P0_1</td>
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<tr>
<td>8</td>
<td>P0_0</td>
</tr>
<tr>
<td>9</td>
<td>VDD</td>
</tr>
<tr>
<td>10</td>
<td>P1_3</td>
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Table 3. Test Pins (P4) Pin-Out
7.5 Cutaway Section
On the USB Dongle the debug connector and the GPIO test-pin connector is mounted on a section of the dongle that may be removed to minimize the dongle's size. This cutaway section is marked with a white line, see Figure 8. If this section is removed from the dongle, the CC1111/CC2511 can still be programmed and debugged using the alternative debug connector found on the back of the USB Dongle, see Figure 7.

7.6 RF Performance of Antenna
While the CC2511 USB Dongle has a PCB antenna designed as a meandered inverted F antenna, the CC1111 USB Dongle has a chip antenna with a PCB track added for tuning of the resonant frequency.

The performance of the PCB antenna on the USB Dongle will be affected by its nearby surroundings. Therefore, when plugged into different computers or a USB extension cable differences in the RF performance must be expected. Also, if the USB Dongle is put inside a casing, the material and design of the enclosure will influence the antenna's performance. For the CC2511 USB Dongle the maximum antenna gain measured is 5.3 dBi. This means that duty cycling or reduction of output power might be needed to ensure compliance with regulatory limits. Please see [7] for more information about SRD regulations in the 2.4 GHz ISM band. The performance of the antenna of the CC2511 USB Dongle is further described in [8].

8 USB Dongle Reference Design and Schematics
Please see [9] and [10] for the schematics of the CC1111/CC2511 USB Dongle. Both schematics and layout files are available as a part of the reference designs.

9 SOC_DEM schematics

![SOC_DEM schematics](image-url)
10 References

[2] SmartRF Flash Programmer (swrc044)
[3] SmartRF Packet Sniffer (swrc045)
[4] SmartRF Studio (swrc046)
[5] CC USB Firmware Library and Examples (swrc088)
[7] AN032 – SRD Regulation for License-Free Transceiver Operation in the 2.4 GHz Band (swra060)
[8] AN043 – Small Size 2.4 GHz PCB Antenna (swra117)
[9] CC1111 USB Dongle Reference Design (swrr049)
[10] CC2511 USB-Dongle Reference Design (swrc062)
### 11 General Information

#### 11.1 Document History

<table>
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<tr>
<th>Revision</th>
<th>Date</th>
<th>Description/Changes</th>
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<tr>
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<td>2009.07.31</td>
<td>Updated hardware pictures and corrected a few typos</td>
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<td>SWRU082A</td>
<td>2009.05.08</td>
<td>Renamed. Moved software sections to swru222.pdf</td>
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<tr>
<td>SWRU082</td>
<td>2006.07.06</td>
<td>Initial release</td>
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