

**TMS470R1VF338, TMS470R1VF348,
TMS470R1VF338A, TMS470R1VF348A,
TMS470R1VF3382A, TMS470R1VF3482A**

TMS470 Microcontrollers

Silicon Errata

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SPNZ122B
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REVISION HISTORY

This silicon errata revision history highlights the technical changes made to the SPNZ122A revision to make it an SPNZ122B revision.

PAGE(S) NO.	ADDITIONS/CHANGES/DELETIONS
	Global TMS470R1VF3382A and TMS470R1VF3482A devices added

Contents

1	Known Design Marginality/Exceptions to Functional Specifications	4
	ADM#5 – BUFEN Bit Required for ADEVT Trigger	4
	ADM#6 – CPU Reads Previous Data	5
	C2SI#27 – After Error Not Waiting for EOF Time	5
	CCM#1 – ICLK Not 50% Duty Cycle	5
	FP#7 – VNV Voltage Adjusted to Set 0xA Step to –7.86V	5
	FW#3 – Configuration Mode Required for Sleep or Standby	5
	FW#13 – Fails Initial Read of 0x0–0x7 in Pipeline Mode	6
	FW#14 – Wait States Must Be Set From Highest to Lowest	6
	FW#17 – Access to Non-Existing Bank Hangs CPU	6
	HET#15 – Auto Read Clear Malfunction	6
	HET#16 – No PWM With MCMP	7
	QUAL#1 – Some Pins Fail Latchup at 125C	7
	RTI#3 – Tap Interrupt When Clearing Counter	7
	RTI#4 – Tap Interrupt When Clearing Counter in Suspend Mode	8
	SCC#4– Delayed Frame Error	8
	SCC#5– Pins are High Impedance in Low Power Mode	8
	SCC#6– CANSRX Must be High During Self-test	9
	SCC#7 – Abort Acknowledge Bit Not Set After Transmission Request Reset	9
	SPI#1 – Slave Baud Rate Setting	10
	SPI#2 – Clearing, Setting SPI EN Bit Does Not Clear Internal Flag	10
	ZPLL#1 – Clock Corruption When Changing Multiplier	10
	ZPLL#2 – High Halt Current	10

1 Known Design Marginality/Exceptions to Functional Specifications

The following is a list of advisories on modules in the K version of silicon. Documentation may differ from the user guide or data sheet. The advisory reference number is shown first (i.e.; ADM#1), followed by a description and any known workarounds. The reference numbers may not always be sequential for this device.

Modules include the following:

- Multi-buffered analog-to-digital converter (ADM)
- Clock control module (CCM)
- Direct memory access controller (DMA)
- Flash pump (FP)
- Flash wrapper (FW)
- High-end timer (HET)
- Device qualification tests (QUAL)
- Real-time interrupt (RTI)
- Standard CAN controller (SCC)
- Serial communication interface (SCI)
- Serial peripheral interface (SPI)
- Zero-pin phase-locked loop (ZPLL)

Advisory ADM#5

BUFEN Bit Required for ADEVT Trigger

Description: The BUFEN bit must be set to have the ADEVT trigger a Group1 conversion.

Workaround: Only use the ADEVT pin to trigger the Event Group conversions in compatibility mode (the same as in x10 devices). Having the ADEVT pin trigger Group1 conversions is actually an enhancement versus the original MibADC specification.

Advisory ADM#6

CPU Reads Previous Data

Description: In compatibility mode, if the ADM and CPU access the data RAM (result registers) in the same cycle, then the CPU will read the previous data with the EMPTY bit cleared.

Workaround: None. The effect of this errata is that the CPU will think it is getting a new sample when it is actually reading the previous sample again. The probability of the CPU and ADM accessing the same result register in the same cycle is quite low.

Advisory C2SI#27*After Error Not Waiting for EOF Time*

Description: After an error, the transmitter goes to idle transmission state and waits for new data to output. If it gets new data AND the bus is HIGH, then it will attempt to output the new data without waiting for the correct EOF time.

Workaround: None

Advisory CCM#1*ICLK Not 50% Duty Cycle*

Description: The ICLK signal output from the CCM is not a 50% duty cycle signal when the SYSCLK to ICLK divide ratio is odd. This affects the SCI and SPI modules and occurs when the divide ratio is 3 or above.

Workaround: None

Advisory FP#7*VNV Voltage Adjusted to Set 0xA Step to -7.86V*

Description: This is to improve yield and reduce erase time. No functional impact or changes to software.

Workaround: None

Advisory FW#3*Configuration Mode Required for Sleep or Standby*

Description: The configuration mode must be set to enter sleep or standby modes.

Workaround: The documentation will be updated to reflect this requirement. (SPNU213, 12/2002)

Advisory FW#13*Fails Initial Read of 0x0–0x7 in Pipeline Mode*

Description: Immediately after entering pipeline mode, a data read of location 0x04 immediately following a data read of location 0x0 will cause 0x04 to read as all 0's.

Workaround: Do a dummy data read of any location other than zero or four immediately after entering pipeline mode. The documentation will be updated to reflect this requirement. (SPNU213, 12/2002)

Advisory FW#14*Wait States Must Be Set From Highest to Lowest*

Description: Wait states must be set by bank from highest to lowest wait states. Otherwise, if the higher number of wait states is written last, this value will apply to all banks.

Workaround: Set the wait states in each bank by writing to the bank requiring the most wait states first and proceeding to the bank requiring the least wait states last. The documentation will be updated to reflect this requirement. (SPNU213, 12/2002)

Advisory FW#17*Access to Non-Existing Bank Hangs CPU*

Description: If all banks are in sleep or standby mode and an access to a non-existing bank is performed, the CPU will hang.

Workaround: Make sure the decoder MFBAH/L0 and MFBAH/L1 registers are set properly so that an access to a non-existing memory bank will generate an illegal access exception. The documentation will be updated to reflect this requirement. (SPNU213, 12/2002)

Advisory HET#15*Auto Read Clear Malfunction*

Description: The HET Auto Read Clear feature does not always work properly. Specifically, the data field of instruction X is NOT cleared if the following conditions a) and b) are true at the same time:

a) The 64-bit CPU read access happens exactly in the two HET time slots PRECEDING the time slot Y in which instruction X is executed.

b) Instruction X just changes its data field (in time slot Y). (Example: Instruction X is an ECNT instruction, which just detected an edge). The malfunction does NOT occur if the data field of instruction X does not change, since then b) is not true.

Workaround: See above.

Advisory HET#16*No PWM With MCMP*

- Description:** MCMP causes a constant signal instead of a PWM, if both of the following conditions are met:
1. Consecutive compare match in every LRP for order=reg_ge_data (only when [data=0]).
 2. The high resolution delay (in number of SYSCLK cycles) is equal to the time slot the MCM is executed.
- Workaround:** Replace each MCMP with a two instruction sequence: ECMP and MOV32

Advisory QUAL#1*Some Pins Fail Latchup at 125C*

- Description:** Pins that are used in the parallel memory test and have the SW0145 buffer fail latchup at 125C, but pass at 95C.
- Workaround:** None. The following pins are affected on this device:

SPI1CLK 5
 SPI1ENA 1
 SPI1SCS 2
 SPI1SIMO 3
 SPI1SOMI 4
 SCI1CLK 89
 SCI1RX 91
 SCI1TX 90
 GIOA[1] 40
 GIOA[4]/INT4 36
 GIOA[5]/INT5 35
 GIOA[6]/INT6 34
 GIOA[7]/INT7 33
 SCI2RX 43
 SCI2TX 44
 HET[16] 23

Advisory RTI#3*Tap Interrupt When Clearing Counter*

- Description:** Write accesses to the RTICNTR register will clear the CNTR (21 bit counter), which causes a Tap interrupt if the corresponding bit switches from a "1" to a "0".
- Workaround:** Disable the RTI prior to changing the RTICNTR value.

Advisory RTI#4*Tap Interrupt When Clearing Counter in Suspend Mode*

Description: Write accesses to the RTICNTR register will clear the CNTR (21 bit counter), which causes a Tap interrupt if the corresponding bit switches from a “1” to a “0” when the suspend signal is asserted.

Workaround: This is the same problem as RTI#3, however, on the initial fix of RTI#3, the case where the suspend signal is asserted because of an emulator breakpoint was not considered. This problem occurs when the emulator has set a breakpoint on one of the instructions closely following the instruction which writes to the counter.

Advisory SCC#4*Delayed Frame Error*

Description: Due to the proposed update of the ISO-WD-16485 CAN Test specification (2001–05–31), the SCC on this device has a non-conformance to the Bosch CAN Specification and the ISO-11898 Standard as described below.

If the following conditions are met, the CAN does not perform a re-synchronization as it is expected.

Conditions:

1. The node must be transmitter
2. The node must transmit a dominant bit
3. The dominant bit must be sampled back as recessive
4. A recessive to dominant edge must be detected after the sample point

But since the recessive sampling of the bit transmitted as dominant is an error anyway, an error frame will be transmitted at the beginning of the following bit.

Therefore, the effect of the non-conformance is a delay of this error frame. The maximum for this delay is five ($\max(\text{SJW}) + 1 T_q$) time quanta.

Workaround: This non-conformance is classified as non-serious and does not have any impact on proper communication and inter-operability with other nodes. See above description.

Advisory SCC#5*Pins Are High Impedance in Low Power Mode*

Description: Regardless of how the CANSTX or CANSRX pins are configured, they become general purpose inputs when entering low power mode.

Workaround: If the pin is not driven externally, which is usually the case with the CANSTX pin, an external pull-up or pull-down resistor should be added to avoid consuming extra current in low power mode.

Advisory SCC#6*CANSRX Must be High During Self-test*

Description: The CANSRX pin must be high during self-test.

Workaround: The CANSRX pin is usually driven high by the bus transceiver. As long as there is no bus activity during the self-test, this is not a problem. If there is nothing driving the CANSRX pin, it can be configured as a digital output and set high during the self-test.

Advisory SCC#7*Abort Acknowledge Bit Not Set After Transmission Request Reset*

Description: After aborting a message using the Transmission Request Reset (TRR) register bit, there are some rare instances where the TRR bit will clear without setting the Abort Acknowledge (AA) bit.

In order for this rare condition to occur all the following three conditions must happen:

1. The current message has a message error or lost arbitration. This message does not need to have the same mailbox number as the following TRR bit mailbox.
2. The TRS bit of the same mailbox as the TRR mailbox must be set from either this current message, prior to the current message and still pending, or just set.
3. The TRR bit must be set in the exact ICLK cycle were the wrapper state machine is in IDLE for one cycle. (One ICLK before or after and the condition will not occur). This IDLE state can occur just after the current message. It can also occur just a few ICLKs after setting the TRS bit of any mailbox after the current message (point 1 above).

If these conditions occur then the TRR and TRS bits for the mailbox will clear t_{clr} ICLKs after the TRR bit is set where:

$$t_{clr} = ((16 - \text{mailbox_number}) * 2) + 3 \quad \text{ICLK cycles}$$

The TA and AA bits will not be set if this condition occurs. Normally, either the TA or AA bit sets after TRR bit goes to zero.

Workaround: When this problem occurs, the TRR and TRS bits will clear within t_{clr} ICLK cycles. To check for this condition, first disable the interrupts. Check the TRR bits' t_{clr} ICLK cycles after setting the TRR bits to make sure that they are still set. A set TRR bit indicates the problem did not occur. If TRR is cleared, then maybe it was the normal end of a message and the TA or AA bits are set. Check both the TA and AA bits. If they are both zero, then the conditions did occur. Handle the condition like the interrupt service routine would, except that the AA bit does not need clearing now. If the TA or AA bit is set, then the normal interrupt routine will happen when the interrupt is re-enabled.

Advisory SPI#1*Slave Baud Rate Setting*

Description: When the SPI is operated in slave mode, the SPI clock must be configured to a baud rate as close to the master's baud rate as possible. If the baud rate is too slow, the enable signal will not be generated in time to keep the master from sending additional data. If the baud rate is too fast, the slave will capture the data before the last bit is shifted in.

Workaround: The documentation will be updated to reflect this requirement. (SPNU195C, 7/2003)

Advisory SPI#2*Clearing, Setting SPI EN Bit Does Not Clear Internal Flag*

Description: Clearing and then setting the SPI EN bit does not clear an internal flag that indicates there is valid data in the SPI data register. This could lead to an inadvertent overrun error. The software should do a dummy read of SPIBUF after setting the SPIEN bit to clear the internal flag.

Workaround: The documentation will be update to reflect this requirement. (SPNU195C, 7/2003)

Advisory ZPLL#1*Clock Corruption When Changing Multiplier*

Description: All interrupt requests coming to the CIM module must be disabled when changing between multiply-by-4 and multiply-by-8.

Workaround: Disable the interrupt request at the peripheral source if possible.

Advisory ZPLL#2*High Halt Current*

Description: High IDDQ current consumption due to an incorrect tie-off of internal unused signals.

Workaround: None

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