SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

- Choice of Memory Organizations
 - SN74V3640 1024 × 36 Bit
 - SN74V3650 2048 \times 36 Bit
 - SN74V3660 4096×36 Bit
 - SN74V3670 8192 \times 36 Bit
 - SN74V3680 16384 \times 36 Bit
 - SN74V3690 32768 × 36 Bit
- 166-MHz Operation (6-ns Read/Write Cycle Time)
- User-Selectable Input- and Output-Port Bus Sizing
 - $\times 36$ in to $\times 36$ out
 - ×36 in to ×18 out
 - $\times 36$ in to $\times 9$ out
 - ×18 in to ×36 out
 - $\times 9$ in to $\times 36$ out
- Big-Endian/Little-Endian User-Selectable Byte Representation
- 5-V-Tolerant Inputs
- Fixed, Low, First-Word Latency
- Zero-Latency Retransmit
- Master Reset Clears Entire FIFO
- Partial Reset Clears Data, But Retains Programmable Settings

- Empty, Full, and Half-Full Flags Signal FIFO Status
- Programmable Almost-Empty and Almost-Full Flags; Each Flag Can Default to One of Eight Preselected Offsets
- Selectable Synchronous/Asynchronous Timing Modes for Almost-Empty and Almost-Full Flags
- Program Programmable Flags by Either Serial or Parallel Means
- Select Standard Timing (Using EF and FF Flags) or First-Word Fall-Through (FWFT) Timing (Using OR and IR Flags)
- Output Enable Puts Data Outputs in High-Impedance State
- Easily Expandable in Depth and Width
- Independent Read and Write Clocks Permit Reading and Writing Simultaneously
- High-Performance Submicron CMOS Technology
- Available in 128-Pin Thin Quad Flat Pack (TQFP)

description

The SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 are exceptionally deep, high-speed CMOS, first-in first-out (FIFO) memories, with clocked read and write controls and a flexible bus-matching ×36/×18/×9 data flow. These FIFOs offer several key user benefits:

- Flexible ×36/×18/×9 bus matching on both read and write ports
- The period required by the retransmit operation is fixed and short.
- The first-word data-latency period, from the time the first word is written to an empty FIFO to the time it can be read, is fixed and short.
- High-density offerings up to 1 Mbit

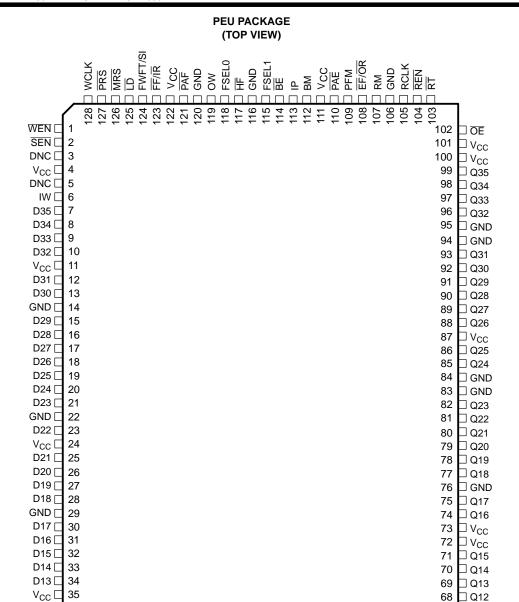
Bus-matching synchronous FIFOs are particularly appropriate for network, video, signal processing, telecommunications, data communications, and other applications that need to buffer large amounts of data and match buses of unequal sizes.

Each FIFO has a data input port (Dn) and a data output port (Qn), both of which can assume 36-bit, 18-bit, or 9-bit width, as determined by the state of external control pins' input width (IW), output width (OW), and bus matching (BM) during the master-reset cycle.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





DNC = Do not connect

D12 ☐ 36

GND [37

D11 🗍 38

description (continued)

The input port is controlled by write-clock (WCLK) and write-enable (WEN) inputs. Data is written into the FIFO on every rising edge of WCLK when WEN is asserted. The output port is controlled by read-clock (RCLK) and read-enable (REN) inputs. Data is read from the FIFO on every rising edge of RCLK when REN is asserted. An output-enable (OE) input is provided for 3-state control of the outputs.

67

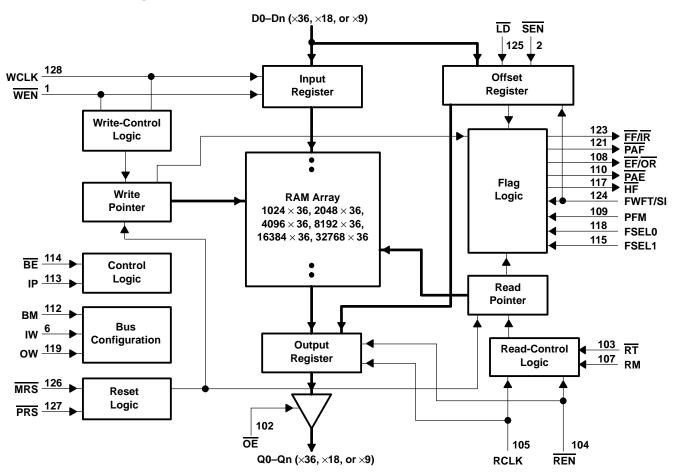
66

☐ Q11

65 Q10



functional block diagram



description (continued)

The frequencies of the RCLK and WCLK signals can vary from 0 to f_{MAX}, with complete independence. There are no restrictions on the frequency of one clock input with respect to the other.

There are two possible timing modes of operation with these devices: first-word fall-through (FWFT) mode and standard mode.

In FWFT mode, the first word written to an empty FIFO is clocked directly to the data output lines after three transitions of the RCLK signal. REN need not be asserted for accessing the first word. However, subsequent words written to the FIFO do require a low on REN for access. The state of the FWFT/SI input during master reset determines the timing mode.

For applications requiring more data-storage capacity than a single FIFO can provide, the FWFT timing mode permits depth expansion by chaining FIFOs in series (i.e., the data outputs of one FIFO are connected to the corresponding data inputs of the next). No external logic is required.

In standard mode, the first word written to an empty FIFO does not appear on the <u>data</u> output lines unless a specific read operation is performed. A read operation, which consists of activating <u>REN</u> and enabling a rising RCLK edge, shifts the word from internal memory to the data output lines.



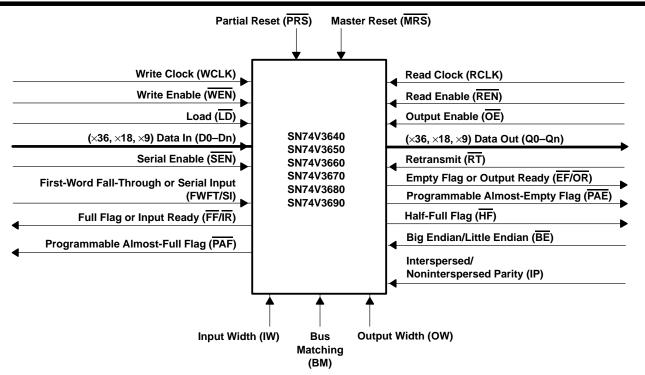


Figure 1. Single-Device-Configuration Signal Flow

description (continued)

These FIFOs have five flag pins: empty flag or output ready ($\overline{\text{FF}/\text{OR}}$), full flag or input ready ($\overline{\text{FF}/\text{IR}}$), half-full flag ($\overline{\text{HF}}$), programmable almost-empty flag ($\overline{\text{PAE}}$), and programmable almost-full flag ($\overline{\text{PAF}}$). The $\overline{\text{EF}}$ and $\overline{\text{FF}}$ functions are selected in standard mode. The $\overline{\text{IR}}$ and $\overline{\text{OR}}$ functions are selected in FWFT mode. $\overline{\text{HF}}$, $\overline{\text{PAE}}$, and $\overline{\text{PAF}}$ always are available for use, regardless of timing mode.

PAE and PAF can be programmed independently to switch at any point in memory. Programmable offsets determine the flag-switching threshold and can be loaded by parallel or serial methods. Eight default offset settings also are provided, so that PAE can be set to switch at a predefined number of locations from the empty boundary. The PAF threshold also can be set at similar predefined values from the full boundary. The default offset values are set during master reset by the state of the FSEL0, FSEL1, and LD.

For serial programming, \overline{SEN} , together with \overline{LD} , loads the offset registers via the serial input (SI) on each rising edge of WCLK. For parallel programming, \overline{WEN} , together with \overline{LD} , loads the offset registers via Dn on each rising edge of WCLK. \overline{REN} , together with \overline{LD} , can read the offsets in parallel from Qn on each rising edge of RCLK, regardless of whether serial parallel offset loading has been selected.

During master reset (MRS), the read and write pointers are set to the first location of the FIFO. The FWFT pin selects standard mode or FWFT mode.

Partial reset (PRS) also sets the read and write pointers to the first location of the memory. However, the timing mode, programmable-flag programming method, and default or programmed offset settings existing before partial reset remain unchanged. The flags are updated according to the timing mode and offsets in effect. PRS is useful for resetting a device in mid-operation, when reprogramming programmable flags would be undesirable.

Also, the timing modes of \overline{PAE} and \overline{PAF} outputs can be selected. Timing modes can be set as either asynchronous or synchronous for \overline{PAE} and \overline{PAF} .



description (continued)

If the asynchronous $\overline{PAE}/\overline{PAF}$ configuration is selected, \overline{PAE} is asserted low on the low-to-high transition of RCLK. \overline{PAE} is reset to high on the low-to-high transition of WCLK. Similarly, \overline{PAF} is asserted low on the low-to-high transition of RCLK.

If the synchronous $\overline{PAE}/\overline{PAF}$ configuration is selected, the \overline{PAE} is asserted and updated on the rising edge of RCLK only, and not WCLK. Similarly, \overline{PAF} is asserted and updated on the rising edge of WCLK only, and not RCLK. The mode desired is configured during master reset by the state of the programmable flag mode (PFM).

The retransmit function allows data to be reread from the FIFO more than once. A low on the retransmit (\overline{RT}) input during a rising RCLK edge initiates a retransmit operation by setting the read pointer to the first location of the memory array. Zero-latency retransmit timing mode can be selected using the retransmit timing mode (RM). During master reset, a low on RM selects zero-latency retransmit. A high on RM during master reset selects normal latency.

If zero-latency retransmit operation is selected, the first data word to be retransmitted is placed on the output register, with respect to the same RCLK edge that initiated the retransmit, if \overline{RT} is low.

See Figures 11 and 12 for normal latency retransmit timing. See Figures 13 and 14 for zero-latency retransmit timing.

The devices can be configured with different input and output bus widths (see Table 1).

WRITE-PORT READ-PORT ow BM IW **WIDTH WIDTH** L L L ×36 ×36 Н L L ×36 ×18 Н Н L ×36 ×9 Н Н L ×18 ×36 Н Н Н $\times 9$ ×36

Table 1. Bus-Matching Configuration Modes†

A big-endian/little-endian data word format is provided. This function is useful when data is written into the FIFO in long-word ($\times 36/\times 18$) format and read out of the FIFO in small-word ($\times 18/\times 9$) format. If big-endian mode is selected, the most-significant byte (MSB) (word) of the long word written into the FIFO is read out of the FIFO first, followed by the least-significant byte (LSB). If little-endian format is selected, the LSB of the long word written into the FIFO is read out first, followed by the MSB. The mode desired is configured during master reset by the state of the big-endian/little-endian ($\overline{\rm BE}$) pin (see Figure 4 for the bus-matching byte arrangement).

The interspersed/noninterspersed parity (IP) bit function allows the user to select the parity bit in the word loaded into the parallel port (D0–Dn) when programming the flag offsets. If interspersed-parity mode is selected, the FIFO assumes that the parity bit is located in bit positions D8, D17, D26, and D35 during the parallel programming of the flag offsets. If noninterspersed-parity mode is selected, D8, D17, and D26 are assumed to be valid bits, and D32, D33, D34, and D35 are ignored. Interspersed parity mode is selected during master reset by the state of the IP input. Interspersed parity control has an effect only during parallel programming of the offset registers. It does not affect data written to and read from the FIFO.

The SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 are fabricated using high-speed submicron CMOS technology, and are characterized for operation from 0°C to 70°C.



[†]Logic levels during master reset

Terminal Functions

TERMINAL NAME	1/0	DESCRIPTION
BE†	I	Big endian/little endian. During master reset, a low on BE selects big-endian operation. A high on BE during master reset selects little-endian format.
вм†	I	Bus matching. BM works with IW and OW to select the bus sizes for both write and read ports (see Table 1 for bus-size configuration).
D0-D36	I	Data inputs. Data inputs for a 36-, 18-, or 9-bit bus. When in 18- or 9-bit mode, the unused input pins are in a don't-care state.
EF/OR	0	Empty flag/output ready. In standard mode, the EF function is selected. EF indicates whether the FIFO memory is empty. In FWFT mode, the OR function is selected. OR indicates whether there is valid data available at the outputs.
FF/IR	0	Full flag/input ready. In standard mode, the FF function is selected. FF indicates whether the FIFO memory is full. In FWFT mode, the IR function is selected. IR indicates whether there is space available for writing to the FIFO memory.
FSEL0†	I	Flag-select bit 0. During master reset, FSEL0, along with FSEL1 and LD, selects the default offset values for PAE and PAF. Up to eight possible settings are available.
FSEL1 [†]	I	Flag-select bit 1. During master reset, FSEL1, along with FSEL0 and LD, selects the default offset values for PAE and PAF. Up to eight possible settings are available.
FWFT/SI	ı	First-word fall-through/serial in. During master reset, FWFT/SI selects FWFT or standard mode. After master reset, FWFT/SI functions as a serial input for loading offset registers.
HF	0	Half-full flag. HF indicates whether the FIFO memory is more or less than half full.
IP†	I	Interspersed parity. During master reset, a low on IP selects noninterspersed-parity mode. A high selects interspersed-parity mode. Interspersed-parity control has an effect only during parallel programming of the offset registers. It does not effect data written to and read from the FIFO.
ıw†	I	Input width. IW, along with OW and BM, selects the bus width of the write port (see Table 1 for bus-size configuration).
LD	I	Load. This is a dual-purpose pin. During master reset, the state of $\overline{\text{LD}}$, along with FSEL0 and FSEL1, determines one of eight default offset values for $\overline{\text{PAE}}$ and $\overline{\text{PAF}}$, along with the method by which these offset registers can be programmed, parallel or serial (see Table 2). After master reset, $\overline{\text{LD}}$ enables writing to and reading from the offset registers.
MRS	I	Master reset. MRS initializes the read and write pointers to zero and sets the output register to all zeroes. During master reset, the FIFO is configured for either FWFT or standard mode, bus-matching configurations, one of eight programmable-flag default settings, serial or parallel programming of the offset settings, big-endian/little-endian format, zero-latency timing mode, interspersed parity, and synchronous versus asynchronous programmable-flag timing modes.
OE	I	Output enable. OE controls the output impedance of Qn.
owt	I	Output width. OW, along with IW and BM, selects the bus width of the read port (see Table 1 for bus-size configuration).
PAE	0	Programmable almost-empty flag. PAE goes low if the number of words in the FIFO memory is less than offset n, which is stored in the empty offset register. PAE goes high if the number of words in the FIFO memory is greater than, or equal to, offset n.
PAF	0	Programmable almost-full flag. PAF goes high if the number of free locations in the FIFO memory is more than offset m, which is stored in the full offset register. PAF goes low if the number of free locations in the FIFO memory is less than, or equal to, m.
PFM [†]	I	Programmable-flag mode. During master reset, a low on PFM selects asynchronous programmable-flag timing mode. A high on PFM selects synchronous programmable-flag timing mode.
PRS	I	Partial reset. PRS initializes the read and write pointers to zero and sets the output register to all zeroes. During partial reset, the existing mode (standard or FWFT), programming method (serial or parallel), and programmable-flag settings are all retained.
Q0-Q35	0	Data outputs. Data outputs for a 36-, 18-, or 9-bit bus. When in 18- or 9-bit mode, the unused output pins are in a don't-care state. Outputs are not 5-V tolerant, regardless of the state of $\overline{\sf OE}$.
RCLK	I	Read clock. When enabled by REN, the rising edge of RCLK reads data from the FIFO memory and offsets from the programmable registers.
	<u> </u>	<u> </u>

[†] Inputs should not change state after master reset.



Terminal Functions (Continued)

TERMINAL NAME	1/0	DESCRIPTION
REN	I	Read enable. REN enables RCLK for reading data from the FIFO memory and offset registers.
_{RM} †	-	Retransmit latency mode. During master reset, a low on RM selects zero-latency retransmit timing mode. A high on RM selects normal-latency mode.
RT	I	Retransmit. RT asserted on the rising edge of RCLK initializes the READ pointer to zero, sets the EF flag to low (OR to high in FWFT mode) and does not disturb the write pointer, programming method, existing timing mode, or programmable-flag settings. RT is useful to reread data from the first physical location of the FIFO.
SEN	Ι	Serial enable. SEN enables serial loading of programmable flag offsets.
WCLK	I	Write clock. When enabled by WEN, the rising edge of WCLK writes data into the FIFO and offsets into the programmable registers for parallel programming and, when enabled by SEN, the rising edge of WCLK writes one bit of data into the programmable register for serial programming.
WEN	I	Write enable. WEN enables WCLK for writing data into the FIFO memory and offset registers.

[†] Inputs should not change state after master reset.

detailed description

inputs

data in (D0-Dn)

D0–D35 are data inputs for 36-bit-wide data. D0–D17 are data inputs for 18-bit-wide data. D0–D8 are data inputs for 9-bit-wide data.

controls

master reset (MRS)

A master reset is accomplished when \overline{MRS} is taken low. This operation sets the internal read and write pointers to the first location of the RAM array. \overline{PAE} goes low, \overline{PAF} goes high, and \overline{HF} goes high.

If FWFT/SI is low during master reset, the standard mode, \overline{EF} , and \overline{FF} are selected. \overline{EF} goes low and \overline{FF} goes high. If FWFT/SI is high, the FWFT mode, \overline{IR} , and \overline{OR} are selected. \overline{OR} goes high and \overline{IR} goes low.

All control settings, such as OW, IW, BM, BE, RM, PFM, and IP are defined during the master reset cycle.

During a master reset, the output register is initialized to all zeroes. A master reset is required after power up, before a write operation can take place. MRS is asynchronous.

See Figure 5 for timing information.



SCAS668A - NOVEMBER 2001 - RÉVISED MARCH 2003

partial reset (PRS)

A partial reset is accomplished when the \overline{PRS} input is taken to a low state. As in the case of the master reset, the internal read and write pointers are set to the first location of the RAM array, \overline{PAE} goes low, \overline{PAF} goes high, and \overline{HF} goes high.

Whichever mode is active at the time of partial reset remains selected (standard or FWFT mode). If standard mode is active, FF goes high and FF goes low. If the FWFT mode is active, OR goes high and IR goes low.

Following partial reset, all values held in the offset registers remain unchanged. The programming method (parallel or serial) active at the time of partial reset also is retained. The output register is initialized to all zeroes. PRS is asynchronous.

A partial reset is useful for resetting the device during operation when reprogramming programmable-flag offsets might not be convenient.

See Figure 6 for timing information.

retransmit (RT)

The retransmit operation allows previously read data to be accessed again. There are two modes of retransmit operation: normal latency and zero latency. There are two stages to retransmit. The first stage is a setup procedure that resets the read pointer to the first location of memory. The second stage is the actual retransmit, which consists of reading out the memory contents, starting at the beginning of the memory.

Retransmit setup is initiated by holding \overline{RT} low during a rising RCLK edge. \overline{REN} and \overline{WEN} must be high before bringing \overline{RT} low. When zero latency is utilized, \overline{REN} need not be high before bringing \overline{RT} low.

If standard mode is selected, the FIFO marks the beginning of the retransmit setup by setting \overline{EF} low. The change in level is noticeable only if \overline{EF} was high before setup. During this period, the internal read pointer is initialized to the first location of the RAM array.

When $\overline{\text{EF}}$ goes high, retransmit setup is complete and read operations can begin, starting with the first location in memory. Because standard mode is selected, every word read, including the first word following retransmit setup, requires a low on $\overline{\text{REN}}$ to enable the rising edge of RCLK.

See Figure 11 for timing information.

If FWFT mode is selected, the FIFO marks the beginning of the retransmit setup by setting \overline{OR} high. During this period, the internal read pointer is set to the first location of the RAM array.

When \overline{OR} goes low, retransmit setup is complete. At the same time, the contents of the first location appear on the outputs. Because FWFT mode is selected, the first word appears on the outputs and no low on \overline{REN} is necessary. Reading all subsequent words requires a low on \overline{REN} to enable the rising edge of RCLK.

See Figure 12 for timing information.

In retransmit operation, zero-latency mode can be selected using the retransmit latency mode (RM) pin during a master reset. This can be applied to the standard mode and the FWFT mode.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

first-word fall-through/serial in (FWFT/SI)

FWFT/SI is a dual-purpose pin. During master reset, the state of the FWFT/SI input determines whether the device operates in standard or FWFT mode.

If, at the time of master reset, FWFT/SI is low, standard mode is selected. This mode uses $\overline{\text{EF}}$ to indicate whether any words are present in the FIFO memory. It also uses $\overline{\text{FF}}$ to indicate whether the FIFO memory has free space for writing. In standard mode, every word read from the FIFO, including the first, must be requested using $\overline{\text{REN}}$ and $\overline{\text{RCLK}}$.

If, at the time of master reset, FWFT/SI is high, FWFT mode is selected. This mode uses \overline{OR} to indicate whether there is valid data at the data outputs (Qn). It also uses \overline{IR} to indicate whether the FIFO memory has free space for writing. In the FWFT mode, the first word written to an empty FIFO goes directly to Qn after three RCLK rising edges, therefore, \overline{REN} = low is not necessary. Subsequent words must be accessed using \overline{REN} and RCLK.

After master reset, FWFT/SI acts as a serial input for loading PAE and PAF offsets into the programmable registers. The serial input function can be used only when the serial loading method is selected during master reset. Serial programming using the FWFT/SI pin functions the same way in both standard and FWFT modes.

write clock (WCLK)

A write cycle is initiated on the rising edge of the WCLK input. Data setup and hold times must be met, with respect to the low-to-high transition of the WCLK. It is permissible to stop WCLK. Note that while WCLK is idle, the $\overline{\text{FF/IR}}$, $\overline{\text{PAF}}$, and $\overline{\text{HF}}$ flags are not updated. WCLK is capable only of updating $\overline{\text{HF}}$ flag to low. The write and read clocks can be independent or coincident.

write enable (WEN)

When WEN is low, data may be loaded into the FIFO RAM array on the rising edge of every WCLK cycle if the device is not full. Data is stored in the RAM array sequentially and independently of any ongoing read operation.

When WEN is high, no new data is written in the RAM array on each WCLK cycle.

To prevent data overflow in the standard mode, \overline{FF} goes low, inhibiting further write operations. After completion of a valid read cycle, \overline{FF} goes high, allowing a write to occur. \overline{FF} is updated by two WCLK cycles + t_{sk} after the RCLK cycle.

To prevent data overflow in the FWFT mode, \overline{IR} goes high, inhibiting further write operations. After completion of a valid read cycle, \overline{IR} goes low, allowing a write to occur. The \overline{IR} flag is updated by two WCLK cycles + t_{sk} after the valid RCLK cycle.

WEN is ignored when the FIFO is full in either FWFT or standard mode.

read clock (RCLK)

A read cycle is initiated on the rising edge of the RCLK input. Data can be read on the outputs, on the rising edge of the RCLK input. It is permissible to stop RCLK. While RCLK is idle, the $\overline{\text{EF}/\text{OR}}$, $\overline{\text{PAE}}$, and $\overline{\text{HF}}$ flags are not updated. RCLK is capable only of updating the $\overline{\text{HF}}$ flag to high. The write and read clocks can be independent or coincident.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

read enable (REN)

When REN is low, data is loaded from the RAM array into the output register on the rising edge of every RCLK cycle, if the device is not empty.

When REN is high, the output register holds the previous data and no new data is loaded into the output register. The data outputs Q0–Qn maintain the previous data value.

In standard mode, every word accessed at Qn, including the first word written to an empty FIFO, must be requested using $\overline{\text{REN}}$. When the last word has been read from the FIFO, the empty flag ($\overline{\text{EF}}$) goes low, inhibiting further read operations. $\overline{\text{REN}}$ is ignored when the FIFO is empty. Once a write is performed, $\overline{\text{EF}}$ goes high, allowing a read to occur. The $\overline{\text{EF}}$ flag is updated by two RCLK cycles + t_{sk} after the valid WCLK cycle.

In FWFT mode, the first word written to an empty FIFO automatically goes to the outputs Qn, on the third valid low-to-high transition of RCLK + t_{sk} after the first write. \overline{REN} need not be asserted low. In order to access all other words, a read must be executed using \overline{REN} . The RCLK low-to-high transition after the last word has been read from the FIFO and \overline{OR} goes high with a true read (RCLK with \overline{REN} = low), inhibiting further read operations. \overline{REN} is ignored when the FIFO is empty.

serial enable (SEN)

The $\overline{\text{SEN}}$ input is an enable used only for serial programming of the offset registers. The serial programming method must be selected during master reset. $\overline{\text{SEN}}$ always is used with $\overline{\text{LD}}$. When these lines are both low, data at the SI input can be loaded into the program register, with one bit for each low-to-high transition of WCLK.

When $\overline{\text{SEN}}$ is high, the programmable registers retain the previous settings and no offsets are loaded. $\overline{\text{SEN}}$ functions the same way in standard and FWFT modes.

output enable (\overline{OE})

When output enable is asserted (low), the parallel output buffers receive data from the output register. When $\overline{\text{OE}}$ is high, the output data bus (Qn) goes into the high-impedance state.

load (\overline{LD})

 $\overline{\text{LD}}$ is a dual-purpose pin. During master reset, the state of the $\overline{\text{LD}}$ input, along with FSEL0 and FSEL1, determines one of eight default offset values for the $\overline{\text{PAE}}$ and $\overline{\text{PAF}}$ flags, along with the method by which these offset registers can be programmed, parallel or serial (see Table 2). After master reset, $\overline{\text{LD}}$ enables write operations to, and read operations from, the offset registers. Only the offset loading method currently selected can be used to write to the registers. Offset registers can be read only in parallel.

After master reset, \overline{LD} activates the programming process of the flag offset values \overline{PAE} and \overline{PAF} . Pulling \overline{LD} low begins a serial loading, or a parallel load, or a read of these offset values.

bus matching (BM, IW, OW)

BM, IW, and OW define the input and output bus widths. During master reset, the state of these pins is used to configure the device bus sizes (see Table 1 for control settings). All flags operate on the word/byte-size boundary, as defined by the selection of bus width (see Figure 4 for the bus-matching byte arrangement).

big endian/little endian (BE)

During master reset, a low on \overline{BE} selects big-endian operation. A high on \overline{BE} during master reset selects little-endian format. This function is useful when the following input-to-output bus widths are implemented: $\times 36$ to $\times 9$, $\times 18$ to $\times 36$, and $\times 9$ to $\times 36$. If big-endian mode is selected, the MSB (word) of the long word written into the FIFO is read out of the FIFO first, followed by the LSB. If little-endian format is selected, the LSB of the long word written into the FIFO is read out first, followed by the MSB. The desired mode is configured during master reset by the state of \overline{BE} (see Figure 4 for bus-matching byte arrangement).



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

programmable-flag mode (PFM)

During master reset, a low on PFM selects asynchronous programmable-flag timing mode. A high on PFM selects synchronous programmable-flag timing mode. If asynchronous PAF/PAE configuration is selected (PFM low during MRS), PAE is asserted low on the low-to-high transition of RCLK. PAE is reset to high on the low-to-high transition of WCLK, similarly, PAF is asserted low on the low-to-high transition of WCLK, and PAF is reset to high on the low-to-high transition of RCLK.

If synchronous $\overline{PAE}/\overline{PAF}$ configuration is selected (PFM high during \overline{MRS}), \overline{PAE} is asserted and updated on the rising edge of RCLK only, and not WCLK. Similarly, \overline{PAF} is asserted and updated on the rising edge of WCLK only and not RCLK. The mode desired is configured during master reset by the state of the PFM.

interspersed parity (IP)

During master reset, a low on IP selects noninterspersed-parity mode. A high selects interspersed-parity mode. The IP bit function allows the user to select the parity bit in the word loaded into the parallel port (D0–Dn) when programming the flag offsets. If interspersed-parity mode is selected, the FIFO assumes that the parity bits are located in bit positions D8, D17, D26, and D35 during the parallel programming of the flag offsets. If noninterspersed-parity mode is selected, D8, D17, and D28 are assumed to be valid bits and D32, D33, D34, and D35 are ignored. IP mode is selected during master reset by the state of the IP input pin. Interspersed-parity control has an effect only during parallel programming of the offset registers. It does not affect the data written to, and read from, the FIFO.

outputs

full flag/input ready (FF/IR)

 $\overline{FF}/\overline{IR}$ is a dual-purpose pin. In standard mode, the \overline{FF} function is selected. When the FIFO is full, \overline{FF} goes low, inhibiting further write operations. When \overline{FF} is high, the FIFO is not full. If no reads are performed after a reset (either \overline{MRS} or \overline{PRS}), \overline{FF} goes low after D writes to the FIFO (D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690).

See Figure 7 for timing information.

In FWFT mode, the \overline{IR} function is selected. \overline{IR} goes low when memory space is available for writing in data. When there is no longer any free space left, \overline{IR} goes high, inhibiting further write operations. If no reads are performed after a reset (either \overline{MRS} or \overline{PRS}), \overline{IR} goes high after D writes to the FIFO (D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690).

See Figure 9 for timing information.

The $\overline{\mathbb{IR}}$ status not only measures the contents of the FIFO memory, but also counts the presence of a word in the output register. Thus, in FWFT mode, the total number of writes necessary to deassert $\overline{\mathbb{IR}}$ is one greater than needed to assert $\overline{\mathbb{FF}}$ in standard mode.

FF/IR is synchronous and updated on the rising edge of WCLK. FF/IR are double register-buffered outputs.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

empty flag/output ready (EF/OR)

 $\overline{\text{EF}/\text{OR}}$ is a dual-purpose pin. In the standard mode, the $\overline{\text{EF}}$ function is selected. When the FIFO is empty, $\overline{\text{EF}}$ goes low, inhibiting further read operations. When $\overline{\text{EF}}$ is high, the FIFO is not empty.

See Figure 8 for timing information.

In FWFT mode, the \overline{OR} function is selected. \overline{OR} goes low at the same time the first word written to an empty FIFO appears valid on the outputs. \overline{OR} stays low after the RCLK low-to-high transition that shifts the last word from the FIFO memory to the outputs. \overline{OR} goes high only with a true read (RCLK with \overline{REN} = low). The previous data stays at the outputs, indicating the last word was read. Further data reads are inhibited until \overline{OR} goes low again.

See Figure 10 for timing information.

EF/OR is synchronous and updated on the rising edge of RCLK.

In standard mode, $\overline{\mathsf{EF}}$ is a double register-buffered output. In FWFT mode, $\overline{\mathsf{OR}}$ is a triple register-buffered output.

programmable almost-full flag (PAF)

PAF goes low when the FIFO reaches the almost-full condition. In standard mode, if no reads are performed after reset (MRS), PAF goes low after (D – m) words are written to the FIFO. The PAF goes low after (1024 – m) writes for the SN74V3640, (2048 – m) writes for the SN74V3650, (4096 – m) writes for the SN74V3660, (8192 – m) writes for the SN74V3670, (16384 – m) writes for the SN74V3680, and (32768 – m) writes for the SN74V3690. The offset m is the full offset value. The default setting for this value is shown in Table 2.

In FWFT mode, \overline{PAF} goes low after (1025 – m) writes for the SN74V3640, (2049 – m) writes for the SN74V3650, (4097 – m) writes for the SN74V3660, (8193 – m) writes for the SN74V3670, (16385 – m) writes for the SN74V3680, and (32769 – m) writes for the SN74V3690. The offset m is the full offset value. The default setting for this value is shown in Table 2.

See Figure 18 for timing information.

If the asynchronous \overline{PAF} configuration is selected, \overline{PAF} is asserted low on the low-to-high transition of WCLK. \overline{PAF} is reset to high on the low-to-high transition of RCLK. If the synchronous \overline{PAF} configuration is selected, \overline{PAF} is updated on the rising edge of WCLK.

See Figure 20 for timing information.

programmable almost-empty flag (PAE)

PAE goes low when the FIFO reaches the almost-empty condition. In standard mode, PAE goes low when there are n words, or fewer, in the FIFO. The offset n is the empty offset value. The default setting for this value is shown in Table 2.

In FWFT mode, \overline{PAE} goes low when there are n + 1 words, or fewer, in the FIFO. The default setting for this value is shown in Table 2.

See Figure 19 for timing information.

If the asynchronous \overline{PAE} configuration is selected, \overline{PAE} is asserted low on the low-to-high transition of RCLK. \overline{PAE} is reset to high on the low-to-high transition of WCLK. If the synchronous \overline{PAE} configuration is selected, \overline{PAE} is updated on the rising edge of RCLK.

See Figure 21 for timing information.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

half-full flag (HF)

HF indicates a half-full FIFO. The rising WCLK edge that fills the FIFO beyond half-full sets HF low. The flag remains low until the difference between the write and read pointers becomes less than, or equal to, one-half of the total depth of the device. The rising RCLK edge that accomplishes this condition sets HF high.

In standard mode, if no reads are performed after reset (\overline{MRS} or \overline{PRS}), \overline{HF} goes low after (D/2 + 1) writes to the FIFO, where D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690.

In FWFT mode, if no reads are performed after reset (\overline{MRS} or \overline{PRS}), \overline{HF} goes low after [(D - 1)/2] + 2 writes to the FIFO, where D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.

See Figure 22 for timing information. Because $\overline{\text{HF}}$ is updated by both RCLK WCLK, it is considered asynchronous.

data outputs (Q0-Qn)

Q0–Q35 are data outputs for 36-bit-wide data. Q0–Q17 are data outputs for 18-bit-wide data. Q0–Q8 are data outputs for 9-bit-wide data.



SCAS668A - NOVEMBER 2001 - RÉVISED MARCH 2003

absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

recommended operating conditions

		MIN	TYP	MAX	UNIT
Vcc	Supply voltage (see Note 1)	3.15	3.3	3.45	V
GND	Supply voltage	0	0	0	V
VIH	High-level input voltage (see Note 2)	2		5.5	V
V _{IL}	Low-level input voltage (see Note 3)			8.0	V
T _A	Operating free-air temperature	0		70	°C

NOTES: 1. $V_{CC} = 3.3 \text{ V} \pm 0.15 \text{ V}$, JEDEC JESD8-A compliant

2. Outputs are not 5-V tolerant.

3. 1.5-V undershoots are allowed for 10 ns once per cycle.

electrical characteristics over recommended operating conditions, t_{CLK} = 6 ns, 7.5 ns, 10 ns, and 15 ns (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voн	$I_{OH} = -2 \text{ mA}$	2.4			V
V _{OL}	I _{OL} = 8 mA			0.4	V
lį	$V_I = V_{CC}$ to 0.4 V			±1	μΑ
loz	$\overline{OE} \ge V_{IH}$, $V_O = V_{CC}$ to 0.4 V			±10	μΑ
I _{CC1}	See Notes 4, 5, and 6			40	mA
I _{CC2}	See Notes 4 and 7			15	mA
C _{IN}	$V_I = 0$, $T_A = 25$ °C, $f = 1$ MHz			10	pF
COUT	$V_O = 0$, $T_A = 25^{\circ}C$, $f = 1$ MHz, Output deselected ($\overline{OE} \ge V_{IH}$)			10	pF

NOTES: 4. Tested with outputs open (I_{OUT} = 0)

- 5. RCLK and WCLK switch at 20 MHz and data inputs switch at 10 MHz.
- 6. Typical I_{CC1} = 4.2 + 1.4 × f_S + 0.02 × C_L × f_S (in mA), with V_{CC} = 3.3 V, T_A = 25°C, f_S = WCLK frequency = RCLK frequency (in MHz, using TTL levels), data switching at f_S/2, C_L = capacitive load (in pF)
- 7. All inputs = $(V_{CC} 0.2 \text{ V})$ or (GND + 0.2 V), except RCLK and WCLK, $T_A = 25^{\circ}C$, which switch at 20 MHz.



[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

timing requirements over recommended ranges of supply voltage and operating free-air temperature (see Figure 2 through Figure 22) $\!\!\!\!\!^{\dagger}$

		SN74V3 SN74V3 SN74V3 SN74V3 SN74V3	3650-6 3660-6 3670-6 3680-6	SN74V3 SN74V3 SN74V3 SN74V3 SN74V3	650-7 6660-7 6670-7 6680-7	SN74V3 SN74V3 SN74V3 SN74V3 SN74V3 SN74V3	650-10 660-10 670-10 680-10	SN74V3 SN74V3 SN74V3 SN74V3 SN74V3 SN74V3	650-15 660-15 670-15 680-15	UNIT
	,	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
fclock	Clock cycle frequency		166		133.3		100		66.7	MHz
tA	Data access time	2	4.5	2	5	2	6.5	2	10	ns
tCLK	Clock cycle time	6		7.5		10		15		ns
^t CLKH	Clock high time	2.5		3.5		4.5		6		ns
^t CLKL	Clock low time	2.5		3.5		4.5		6		ns
tDS	Data setup time	1.5		2.5		3.5		4		ns
^t DH	Data hold time	0.5		0.5		0.5		1		ns
t _{ENS}	Enable setup time	1.5		2.5		3.5		4		ns
^t ENH	Enable hold time	0.5		0.5		0.5		1		ns
tLDS	Load setup time	2		3.5		3.5		4		ns
^t LDH	Load hold time	0		0.5		0.5		1		ns
tRS	Reset pulse duration [‡]	10		10		10		15		ns
tRSS	Reset setup time	15		15		15		15		ns
tRSR	Reset recovery time	10		10		10		15		ns
tRSF	Reset to flag and output time		15		15		15		15	ns
^t RTS	Retransmit setup time	2		3.5		3.5		4		ns
tOLZ	Output enable to output in low impedance	0		0		0		0		ns
tOE	Output enable to output valid	2	4.5	2	6	2	6	2	8	ns
tOHZ	Output enable to output in high impedance	2	4.5	2	6	2	6	2	8	ns
tWFF	Write clock to FF or IR		4.5		5		6.5		10	ns
^t REF	Read clock to EF or OR		4.5		5		6.5		10	ns
^t PAFA	Clock to asynchronous PAF		8.5		12.5		16		20	ns
^t PAFS	Write clock to synchronous PAF		4.5		5		6.5		10	ns
^t PAEA	Clock to asynchronous PAE		8.5		12.5		16		20	ns
tPAES	Read clock to synchronous PAE		4.5		5		6.5		10	ns
tHF	Clock to HF		9		12.5		16		20	ns
^t sk1	Skew time between read clock and write clock for EF/OR and FF/IR	4.5		5		7		9		ns
t _{sk2}	Skew time between read clock and write clock for PAE and PAF	4.5		7		10		14		ns

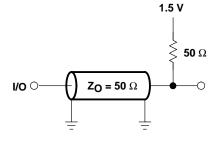
[†] All ac timings apply to standard mode and FWFT mode.



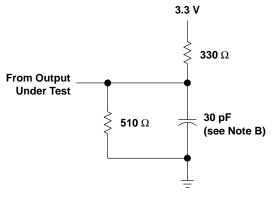
[‡] Pulse durations less than minimum values are not allowed.

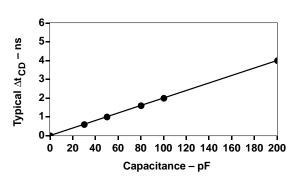
PARAMETER MEASUREMENT INFORMATION

AC TEST CONDITIONS Input Pulse Levels Input Rise/Fall Times Input Timing Reference Levels Output Reference Levels Output Load for t_{CLK} = 10 ns, 15 ns Output Load for t_{CLK} = 6 ns, 7.5 ns AC TEST CONDITIONS GND to 3.0 V 3 ns (see Note A) 1.5 V 1.5 V See B See A and C



A. AC TEST LOAD FOR 6-ns AND 7.5-ns SPEED GRADES





B. OUTPUT LOAD CIRCUIT FOR 10-ns AND 15-ns SPEED GRADES

C. LUMPED CAPACITIVE LOAD, TYPICAL DERATING

NOTES: A. For 133-MHz operation, input rise/fall times are 1.5 ns.

B. Includes probe and jig capacitance

Figure 2. Load Circuits

functional description

timing modes: FWFT mode vs standard mode

The SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 support two different timing modes of operation: standard mode or FWFT mode. The mode is selected during master reset by the state of the FWFT/SI input.

If, at the time of master reset, FWFT/SI is low, standard mode is selected. This mode uses $\overline{\text{EF}}$ to indicate whether any words are present in the FIFO. It also uses $\overline{\text{FF}}$ to indicate whether the FIFO has any free space for writing. In standard mode, every word read from the FIFO, including the first word, must be requested using $\overline{\text{REN}}$ and RCLK.

If, at the time of master reset, FWFT/SI is high, FWFT mode is selected. This mode uses \overline{OR} to indicate whether valid data is at the data outputs (Qn). It also uses \overline{IR} to indicate whether the FIFO has any free space for writing. In the FWFT mode, the first word written to an empty FIFO goes directly to Qn after three RCLK rising edges; \overline{REN} = low is not necessary. Subsequent words must be accessed using \overline{REN} and RCLK.

Various signals (both input and output) operate differently, depending on which timing mode is in effect.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

FWFT mode

In FWFT mode, status flags IR, PAF, HF, PAE, and OR operate as outlined in Table 4. To write data into the FIFO, WEN must be low. Data presented to the DATA IN lines is clocked into the FIFO on subsequent transitions of WCLK. After the first write is performed, the OR flag goes low. Subsequent writes continue to fill the FIFO. PAE goes high after n + 2 words have been loaded into the FIFO, where n is the empty offset value. The default settings for these values are shown in Table 2, and are user programmable.

If one continues to write data into the FIFO and assumes no read operations are taking place, $\overline{\text{HF}}$ switches to low once the 514th word for the SN74V3640, 1026th word for the SN74V3650, 2050th word for the SN74V3660, 4098th word for the SN74V3670, 8194th word for the SN74V3680, and 16386th word for the SN74V3690, are written into the FIFO. Continuing to write data into the FIFO causes $\overline{\text{PAF}}$ to go low. If no reads are performed, $\overline{\text{PAF}}$ goes low after (1025 – m) writes for the SN74V3640, (2049 – m) writes for the SN74V3650, (4097 – m) writes for the SN74V3660, (8193 – m) writes for the SN74V3670, (16385 – m) writes for the SN74V3680, and (32769 – m) writes for the SN74V3690, where m is the full offset value. The default setting for these values is shown in Table 2.

When the FIFO is full, the $\overline{\text{IR}}$ flag goes high, inhibiting further write operations. If no reads are performed after a reset, $\overline{\text{IR}}$ goes high after D writes to the FIFO. D = 1025 writes for the SN74V3640, D = 2049 writes for the SN74V3650, D = 4097 writes for the SN74V3660, D = 8193 writes for the SN74V3670, D = 16385 writes for the SN74V3680, and D = 32769 writes for the SN74V3690. Note that the additional word in FWFT mode is due to the capacity of the memory plus output register.

If the FIFO is full, the first read operation causes the $\overline{\text{IR}}$ flag to go low. Subsequent read operations cause $\overline{\text{PAF}}$ and $\overline{\text{HF}}$ to go high at the conditions described in Table 4. If further read operations occur without write operations, $\overline{\text{PAE}}$ goes low when there are n + 1 words in the FIFO, where n is the empty offset value. Continuing read operations causes the FIFO to become empty. When the last word has been read from the FIFO, $\overline{\text{OR}}$ goes high, inhibiting further read operations. $\overline{\text{REN}}$ is ignored when the FIFO is empty.

When configured in FWFT mode, the \overline{OR} flag output is triple register buffered, and the \overline{IR} flag output is double register buffered.

See Figures 9, 10, 12, and 14 for timing information.

standard mode

In standard mode, status flags FF, PAF, HF, PAE, and EF operate as outlined in Table 3. To write data into the FIFO, WEN must be low. Data presented to the DATA IN lines is clocked into the FIFO on subsequent transitions of WCLK. After the first write is performed, EF goes high. Subsequent writes continue to fill the FIFO. PAE goes high after n + 1 words have been loaded into the FIFO, where n is the empty offset value. The default setting for these values is shown in Table 2. This parameter is also user programmable.

If one continues to write data into the FIFO and assumes no read operations are taking place, $\overline{\text{HF}}$ switches to low after the 513rd word for SN74V3640, 1025th word for SN74V3650, 2049th word for SN74V3660, 4097th word for SN74V3670, 8193th word for the SN74V3680, and 16385th word for the SN74V3690 are written into the FIFO. Continuing to write data into the FIFO causes $\overline{\text{PAF}}$ to go low. If no reads are performed, $\overline{\text{PAF}}$ goes low after (1024 – m) writes for the SN74V3640, (2048 – m) writes for the SN74V3650, (4096 – m) writes for the SN74V3660, (8192 – m) writes for the SN74V3670, (16384 – m) writes for the SN74V3680, and (32768 – m) writes for the SN74V3690. Offset m is the full offset value. The default setting for these values is in the footnote of Table 2. This parameter is also user programmable.

When the FIFO is full, \overline{FF} goes low, inhibiting further write operations. If no reads are performed after a reset, \overline{FF} goes low after D writes to the FIFO. D = 1024 writes for the SN74V3640, D = 2048 writes for the SN74V3650, D = 4096 writes for the SN74V3660, D = 8192 writes for the SN74V3670, D = 16384 writes for the SN74V3680, and D = 32768 writes for the SN74V3690.



standard mode (continued)

If the FIFO is full, the first read operation causes \overline{FF} to go high. Subsequent read operations cause \overline{PAF} and \overline{HF} to go high at the conditions described in Table 3. If further read operations occur without write operations, \overline{PAE} goes low when there are n words in the FIFO, where n is the empty offset value. Continuing read operations causes the FIFO to become empty. When the last word has been read from the FIFO, \overline{EF} goes low, inhibiting further read operations. \overline{REN} is ignored when the FIFO is empty.

When configured in standard mode, the EF and FF outputs are register-buffered outputs.

See Figures 7, 8, 11, and 13 for timing information.

Table 2. Default Programmable Flag Offsets

	SN	74V3640,	SN74V3650	SN74V	3660, SN	74V3670, \$	SN74V3680, SN74V3690
LD	FSEL1	FSEL0	OFFSETS (n, m)†	LD	FSEL1	FSEL0	OFFSETS (n, m) [†]
L	Н	L	511	Н	L	L	1,023
L	L	Н	255	L	Н	L	511
L	L	L	127	L	L	Н	255
L	Н	Н	63	L	L	L	127
Н	L	L	31	L	Н	Н	63
Н	Н	L	15	Н	Н	L	31
Н	L	Н	7	Н	L	Н	15
Н	Н	Н	3	Н	Н	Н	7
			PROGRAM MODE				PROGRAM MODE
Н	Х	Х	Serial [‡]	Н	Х	Х	Serial [‡]
L	Х	Х	Parallel [§]	L	Х	Х	Parallel§

 $[\]uparrow$ n = empty offset for \overline{PAE} , m = full offset for \overline{PAF}

programming flag offsets

Full and empty flag offset values are user programmable. The SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 have internal registers for these offsets. Eight default offset values are selectable during master reset. These offset values are shown in Table 2. Offset values can also be programmed into the FIFO by serial or parallel loading. The loading method is selected using \overline{LD} . During master reset, the state of the \overline{LD} input determines whether serial or parallel flag offset programming is enabled. A high on \overline{LD} during master reset selects serial loading of offset values. A low on \overline{LD} during master reset selects parallel loading of offset values.

In addition to loading offset values into the FIFO, it is also possible to read the current offset values. Offset values can be read via the parallel output port Q0–Qn, regardless of the programming mode selected (serial or parallel). It is not possible to read the offset values in serial fashion.

Figure 3 summarizes the control pins and sequence for both serial and parallel programming modes. A more detailed description is given in the following paragraphs.

The offset registers may be programmed (and reprogrammed) any time after master reset, regardless of whether serial or parallel programming has been selected. Valid programming ranges are from 0 to D-1.



[‡] As well as selecting serial programming mode, one of the default values also is loaded, depending on the state of FSEL0 and FSEL1.

[§] As well as selecting parallel programming mode, one of the default values also is loaded, depending on the state of FSEL0 and FSEL1.

synchronous vs asynchronous programmable flag timing selection

The SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 $\underline{\text{can}}$ be configured during the master reset cycle, with either synchronous or asynchronous timing for $\overline{\text{PAF}}$ and $\overline{\text{PAE}}$, by use of the PFM pin.

If synchronous $\overline{PAF}/\overline{PAE}$ configuration is selected (PFM high during \overline{MRS}), \overline{PAF} is asserted and updated on the rising edge of WCLK only and not RCLK. Similarly, \overline{PAE} is asserted and updated on the rising edge of RCLK only, and not WCLK (see Figure 17 for synchronous \overline{PAF} timing and Figure 18 for synchronous \overline{PAE} timing).

If asynchronous $\overline{PAF}/\overline{PAE}$ configuration is selected (PFM low during \overline{MRS}), \overline{PAF} is asserted low on the low-to-high transition of WCLK, and \overline{PAF} is reset to high on the low-to-high transition of RCLK. Similarly, \overline{PAE} is asserted low on the low-to-high transition of WCLK.

See Figure 19 for asynchronous PAF timing and Figure 20 for asynchronous PAE timing.

Table 3. Status Flags for Standard Mode

	SN74V3640	SN74V3650	SN74V3660	SN74V3670	FF	PAF	HF	PAE	EF
	0	0	0	0	Н	Н	Н	L	L
Number of	1 to n	1 to n	1 to n	1 to n	Н	Н	Н	L	Н
Words in	(n + 1) to 512	(n + 1) to 1024	(n + 1) to 2048	(n + 1) to 4096	Н	Н	Н	Н	Н
FIFO (see Note 8)	513 to [1024 – (m + 1)]	1025 to [2048 – (m + 1)]	2049 to [4096 – (m + 1)]	4097 to [8192 – (m + 1)]	Н	Н	L	Н	Н
	(1024 – m) to 1023	(2048 – m) to 2047	(4096 - m) to 4095	(8192 – m) to 8191	Н	L	L	Н	Н
	1024	2048	4096	8192	L	L	L	Н	Н

	SN74V3680	SN74V3690	FF	PAF	HF	PAE	EF
	0	0	Н	Н	Н	L	L
Number of	1 to n	1 to n	Н	Н	Η	L	Н
Words in FIFO (see	(n + 1) to 8192	(n + 1) to 16384	Η	Н	Η	Н	Н
Note 8)	8193 to [16384 – (m + 1)]	16385 to [32768 – (m + 1)]	Н	Η	L	Н	Н
	(16384 - m) to 16383	(32768 - m) to 32767	Н	┙	┙	Н	Н
	16384	32768	L	L	L	Н	Н

NOTE 8: See Table 2 for values for n. m.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

Table 4. Status Flags for FWFT Mode

	SN74V3640	SN74V3650	SN74V3660	SN74V3670	ĪR	PAF	HF	PAE	OR
	0	0	0	0	L	Н	Н	L	Н
Number of	1 to (n + 1)	1 to (n + 1)	1 to (n + 1)	1 to (n + 1)	L	Н	Н	L	L
Words in	(n + 2) to 513	(n + 2) to 1025	(n + 2) to 2049	(n + 2) to 4097	L	Н	Н	Н	L
FIFO (see Note 8)	514 to [1025 – (m + 1)]	1026 to [2049 – (m + 1)]	2050 to [4097 – (m + 1)]	4098 to [8193 – (m + 1)]	L	Н	L	Н	L
	(1025 – m) to 1024	(2049 - m) to 2048	(4097 – m) to 4096	(8193 – m) to 8192	L	L	L	Н	L
	1025	2049	4097	8193	Н	L	L	Н	L

	SN74V3680	SN74V3690	ĪR	PAF	HF	PAE	OR
	0	0	L	Н	Η	L	Н
Number of	1 to (n + 1)	1 to (n + 1)	L	Н	Η	L	L
Words in	(n + 2) to 8193	(n + 2) to 16385	L	Н	Ι	Н	L
FIFO (see Note 8)	8194 to [16385 – (m + 1)]	16386 to [32769 – (m + 1)]	L	Н	L	П	L
	(16385 – m) to 16384	(32769 - m) to 32768	L	L	L	Н	L
	16385	32769	Н	L	Ĺ	Н	Ĺ

NOTE 8: See Table 2 for values for n, m.

LD	WEN	REN	SEN	WCLK	RCLK	SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, SN74V3690
0	0	1	1	↑	х	Parallel write to registers: Empty offset (LSB) Empty offset (MSB) Full offset (LSB) Full offset (MSB)
0	1	0	1	х	↑	Parallel read from registers: Empty offset (LSB) Empty offset (MSB) Full offset (LSB) Full offset (MSB)
0	1	1	0	↑	X	Serial shift into registers: 20 bits for the SN74V3640 22 bits for the SN74V3650 24 bits for the SN74V3660 26 bits for the SN74V3670 28 bits for the SN74V3680 30 bits for the SN74V3690 1 bit for each rising WCLK edge, starting with empty offset (LSB) ending with full offset (MSB)
Х	1	1	1	Х	Х	No operation
1	0	Х	Х	1	Х	Write memory
1	Х	0	Χ	Х	↑	Read memory
1	1	1	Х	Х	Х	No operation

NOTES: A. The programming method can be selected only at master reset.

- B. Parallel reading of the offset registers is always permitted, regardless of which programming method has been selected.
- C. The programming sequence applies to FWFT and standard modes.

Figure 3. Programmable Flag Offset Programming Sequence



1st Parallel Offset Write/Read Cycle

Data Inputs/Outputs

	D/Q0								D/Q8						5	D/Q1	[35	D/Q
						ONS	CATIO	LOC) BIT	(PAE	TER	EGIS	ET R	FFS	TY (EMF						
Noninterspersed Parity	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	Χ	Χ	Χ	Χ	Х		Х
Interspersed Parity	1	2	3	4	5	6	7	8	Χ	9	10	11	12	13	14	15	Χ	Х	Χ	Х		Х

2nd Parallel Offset Write/Read Cycle

Data Inputs/Outputs

D/Q35 D/Q17						D/Q8											D/Q0						
							FU	LL O	FFSE	TRE	GIS	ΓER (PAF)	BIT	LOC	ATIO	NS						
	Х		Х	Х	Х	Х	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	Nonintersp
	Х		Х	Х	Х	16	15	14	13	12	11	10	9	Х	8	7	6	5	4	3	2	1	Intersperse

Noninterspersed Parity Interspersed Parity

×36 Bus Width

1st Parallel Offset Write/Read Cycle

D/Q17	D/Q15 Data Inputs/Outputs															D/Q0		
				EMP	TY O	FFSE	T (LS	B) RE	GISTE	R (PA	E) BI	T LOC	CATIC	NS				
X	Х	Х	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
	Х	15	14	13	12	11	10	9	Х	8	7	6	5	4	3	2	1]

Noninterspersed Parity Interspersed Parity

D/Q8

2nd Parallel Offset Write/Read Cycle

_	D/Q17	D/Q15 Data Inputs/Outputs											D/Q0					
I			FULL OFFSET (LSB) REGISTER (PAF) BIT LOCATIONS															
l	Х	Х	Х	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
l		Х	15	14	13	12	11	10	9	Х	8	7	6	5	4	3	2	1

Noninterspersed Parity Interspersed Parity

D/Q8

×18 Bus Width

Number of bits used:

10 bits for the SN74V364011 bits for the SN74V3650

12 bits for the SN74V3660 13 bits for the SN74V3670

14 bits for the SN74V3680

15 bits for the SN74V3690

Note: All unused bits of the

LSB and MSB are don't care.

Figure 3. Programmable Flag Offset Programming Sequence (Continued)



		Offset \	Wille/F	cau o	<i>y</i> 0.0					
D/Q8								D/Q0		
EM	PTY O	FFSET	REGI	STER (PAE) E	BIT LO	CATIO	NS		
Х	8	7	6	5	4	3	2	1		
2nd Parallel Offset Write/Read Cycle D/Q8 D/Q0										
EM	PTY O	FFSET	REGI	STER (PAE) E	BIT LO	CATIO	NS		
Х	16	15	14	13	12	11	10	9		
3rd Parallel Offset Write/Read Cycle D/Q8 D/Q0										
				_						
FU	JLL OF	FSET	REGIS	TER (F	PAF) B	IT LOC	OITA	IS		
X	JLL OF	FSET 7	REGIS 6	TER (F	PAF) B 4	IT LOC	2	IS		
Х		7	6	5	4					
X 4th Pa D/Q8	8	7 Offset	6 Write/F	5 Read C	4 cycle	3	2	1 D/Q0		
X 4th Pa D/Q8	8 arallel C	7 Offset	6 Write/F	5 Read C	4 cycle	3	2	1 D/Q0		

×9 Bus Width

Number of bits used: 10 bits for the SN74V3640 11 bits for the SN74V3650 12 bits for the SN74V3660 13 bits for the SN74V3670 14 bits for the SN74V3680 15 bits for the SN74V3690 Note: All unused bits of the LSB and MSB are don't care.

Figure 3. Programmable Flag Offset Programming Sequence (Continued)

serial programming mode

If the serial programming mode has been selected as described previously, programming of \overline{PAE} and \overline{PAF} values can be achieved by using a combination of the \overline{LD} , \overline{SEN} , WCLK, and SI inputs. Programming \overline{PAE} and \overline{PAF} proceeds as follows. When \overline{LD} and \overline{SEN} are set low, data on the SI input are written, one bit for each WCLK rising edge, starting with the empty offset LSB and ending with the full offset MSB. This makes a total of 20 bits for the SN74V3640, 22 bits for the SN74V3650, 24 bits for the SN74V3660, 26 bits for the SN74V3670, 28 bits for the SN74V3680, and 30 bits for the SN74V3690.

See Figure 15 for the timing information.

Using the serial method, individual registers cannot be programmed selectively. \overline{PAE} and \overline{PAF} can show a valid status only after the complete set of bits (for all offset registers) has been entered. The registers can be reprogrammed, as long as the complete set of new offset bits is entered. When \overline{LD} is low and \overline{SEN} is high, no serial write to the registers can occur.



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

serial programming mode (continued)

Write operations to the FIFO are allowed before and during the serial programming sequence. In this case, the programming of all offset bits need not occur at once. A select number of bits can be written to the SI input and then, by bringing \overline{LD} and \overline{SEN} high, data can be written to FIFO memory via Dn by switching \overline{WEN} . When \overline{WEN} is brought high with \overline{LD} and \overline{SEN} restored to a low, the next offset bit in sequence is written to the registers via SI. If an interruption of serial programming is desired, it is sufficient either to set \overline{LD} low and deactivate \overline{SEN} , or to set \overline{SEN} low and deactivate \overline{LD} . When \overline{LD} and \overline{SEN} are restored to a low level, serial offset programming continues.

From the time serial programming begins, neither programmable flag is valid until the full set of bits required to fill all the offset registers is written. Measuring from the rising WCLK edge that achieves the previous criteria, \overline{PAF} is valid after two more rising WCLK edges + t_{PAF} . \overline{PAE} is valid after the next two rising RCLK edges + t_{PAF} + t_{Sk2} .

Flag offset values can be read only via parallel output port Qn.

parallel programming mode

If the parallel programming mode has been selected as described previously, programming of \overline{PAE} and \overline{PAF} values can be achieved by using a combination of the \overline{LD} , WCLK, \overline{WEN} and Dn inputs. Programming \overline{PAE} and \overline{PAF} proceeds as follows. \overline{LD} and \overline{WEN} must be set low. For $\times 36$ -bit input bus width, data on the inputs Dn are written into the Empty Offset register on the first low-to-high transition of WCLK. On the second low-to-high transition of WCLK, data are written into the Full Offset register. The third transition of WCLK writes, once again, to the Empty Offset register. For $\times 18$ -bit input bus width, data on the inputs Dn are written into the Empty Offset register (LSB) on the first low-to-high transition of WCLK. On the second low-to-high transition of WCLK, data are written into the Empty Offset (MSB) register. The third transition of WCLK writes to the Full Offset register (LSB). The fourth transition of WCLK writes to the Full Offset register (MSB). The fifth transition of WCLK writes, once again, to the Empty Offset register (LSB). A total of four writes to the offset registers is required to load values using a $\times 18$ input bus width. For an input bus width of $\times 9$ bits, a total of six write cycles to the offset registers is required to load values.

See Figures 3 and 16 for timing information.

Writing offsets in parallel employs a dedicated Write Offset register pointer. Reading offsets employs a dedicated Read Offset register pointer. The two pointers operate independently; however, a read and a write should not be performed simultaneously to the offset registers. A master reset initializes both pointers to the Empty Offset register (LSB). A partial reset has no effect on the position of these pointers.

Write operations to the FIFO are allowed before and during the parallel programming sequence. In this case, the programming of all offset registers need not occur at one time. One, two, or more offset registers can be written to and then, by bringing \overline{LD} high, write operations can be redirected to the FIFO memory. When \overline{LD} is set low again and \overline{WEN} is low, the next offset register in sequence is written to. As an alternative to holding \overline{WEN} low and switching \overline{LD} , parallel programming can also be interrupted by setting \overline{LD} low and switching \overline{WEN} .

Note that the status of a programmable-flag (\overline{PAE} or \overline{PAF}) output is invalid during the programming process. From the time parallel programming has begun, a programmable-flag output is not valid until the appropriate offset word has been written to the register(s) pertaining to that flag. Measuring from the rising WCLK edge that achieves the previous criteria, \overline{PAF} is valid after two more rising WCLK edges + t_{PAF} . \overline{PAE} is valid after the next two rising RCLK edges + t_{PAF} + t_{Sk2} .

Reading the offset registers employs a dedicated read offset register pointer. The contents of the offset registers can be read on the Q0–Qn pins when \overline{LD} is set low and \overline{REN} is set low. For $\times 36$ output bus width, data are read via Qn from the Empty Offset register on the first low-to-high transition of RCLK. On the second low-to-high transition of RCLK, data are read from the Full Offset register. The third transition of RCLK reads, once again, from the Empty Offset register. For $\times 18$ output bus width, a total of four read cycles is required to obtain the values of the offset registers, starting with the Empty Offset register (LSB) and finishing with the Full Offset register (MSB). For $\times 9$ output bus width, a total of six read cycles must be performed on the offset registers.



SCAS668A - NOVEMBER 2001 - RÉVISED MARCH 2003

parallel programming mode (continued)

See Figures 3 and 17 for timing information.

It is permissible to interrupt the offset register read sequence with reads or writes to the FIFO. The interruption is accomplished by deasserting \overline{REN} , \overline{LD} , or both together. When \overline{REN} and \overline{LD} are restored to a low level, reading of the offset registers continues where it left off. It should be noted (and care should be taken from the fact) that when a parallel read of the flag offsets is performed, the data word that was present on output lines Qn is overwritten.

Parallel reading of the offset registers always is permitted, regardless of which timing mode (Standard or FWFT modes) has been selected.

retransmit operation

The retransmit operation allows data that has been read to be accessed again. There are two modes of retransmit operation: normal latency and zero latency. There are two stages to retransmit. The first stage is a setup procedure that resets the read pointer to the first location of memory. The second stage is the actual retransmit, which consists of reading out the memory contents, starting at the beginning of memory.

Retransmit setup is initiated by holding \overline{RT} low during a rising RCLK edge. \overline{REN} and \overline{WEN} must be high before bringing \overline{RT} low. When zero latency is utilized, \overline{REN} need not be high before bringing \overline{RT} low. At least two words, but no more than D – 2 words should have been written into the FIFO, and read from the FIFO, between reset (master or partial) and the time of retransmit setup, D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690. In FWFT mode, D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.

If standard mode is selected, the FIFO marks the beginning of the retransmit setup by setting \overline{EF} low. The change in level is noticeable only if \overline{EF} was high before setup. During this period, the internal read pointer is initialized to the first location of the RAM array.

When $\overline{\mathsf{EF}}$ goes high, retransmit setup is complete and read operations can begin, starting with the first location in memory. Because standard mode is selected, every word read, including the first word following retransmit setup, requires a low on $\overline{\mathsf{REN}}$ to enable the rising edge of RCLK.

See Figure 11 for timing information.

If FWFT mode is selected, the FIFO marks the beginning of the retransmit setup by setting \overline{OR} high. During this period, the internal read pointer is set to the first location of the RAM array.

When \overline{OR} goes low, retransmit setup is complete. At the same time, the contents of the first location appear on the outputs. Because FWFT mode is selected, the first word appears on the outputs and no low on \overline{REN} is necessary. Reading all subsequent words requires a low on \overline{REN} to enable the rising edge of RCLK.

See Figure 12 for timing information.

For either standard mode or FWFT mode, updating of \overline{PAE} , \overline{HF} , and \overline{PAF} begins with the rising edge of RCLK that \overline{RT} is set up on. \overline{PAE} is synchronized to RCLK, thus, on the second rising edge of RCLK after \overline{RT} is set up, \overline{PAE} is updated. \overline{HF} is asynchronous, thus, the rising edge of RCLK that \overline{RT} is set up on updates \overline{HF} . \overline{PAF} is synchronized to WCLK, thus, the second rising edge of WCLK that occurs t_{SK} after the rising edge of RCLK that \overline{RT} is set up on updates \overline{PAF} . \overline{RT} is synchronized to RCLK.

The retransmit function has the option of two modes of operation, either normal latency or zero latency. Figures 11 and 12 show normal latency. Figures 13 and 14 show the zero-latency retransmit operation. Zero latency means, basically, that the first data word to be retransmitted is placed in the output register, with respect to the RCLK pulse that initiated the retransmit.



BYTE ORDER ON INPUT PORT:	D35-D27	D26-D18	D17-D9	D8-D0 Write to FIFO
BYTE ORDER ON OUTPUT PORT: BE	Q35-Q27	Q26-Q18	Q17-Q9	Q8-Q0 D Read from FIFO
		(a) ×36 INPUT T	O ×36 OUTPUT	
BE BM IW OW L H L L	Q35-Q27 X Q35-Q27 X	Q26-Q18 X Q26-Q18 X	Q17-Q9 A Q17-Q9 C	Q8-Q0 B 1st: Read from FIFO Q8-Q0 D 2nd: Read from FIFO
	(b) ×36	INPUT TO ×18 C	OUTPUT – BIG EN	IDIAN
BE BM IW OW H H L L	Q35-Q27 X Q35-Q27 X	Q26-Q18 X Q26-Q18 X	Q17-Q9 C Q17-Q9 A	Q8-Q0 D 1st: Read from FIFO Q8-Q0 B 2nd: Read from FIFO
	(c) ×36 II	NPUT TO ×18 OU	JTPUT – LITTLE E	ENDIAN
BE BM IW OW L H L H	Q35-Q27 X Q35-Q27 X Q35-Q27 X Q35-Q27 X	Q26-Q18 X Q26-Q18 X Q26-Q18 X Q26-Q18 X	Q17-Q9 X Q17-Q9 X Q17-Q9 X Q17-Q9 X	Q8-Q0 A 1st: Read from FIFO Q8-Q0 B 2nd: Read from FIFO Q8-Q0 C 3rd: Read from FIFO Q8-Q0 D 4th: Read from FIFO
	(d) >36	SINPLIT TO V9 O	UTPUT – BIG EN	DIAN
	(u) ×30) IIII 01 10 ×3 0	OTI OT - BIG EN	DIAN
BE BM IW OW H H L H	Q35-Q27 X Q35-Q27 X Q35-Q27 X Q35-Q27 X	Q26-Q18 X Q26-Q18 X Q26-Q18 X Q26-Q18 X Q26-Q18 X	Q17-Q9 X Q17-Q9 X Q17-Q9 X Q17-Q9 X	Q8-Q0 D 1st: Read from FIFO Q8-Q0 C 2nd: Read from FIFO Q8-Q0 B 3rd: Read from FIFO Q8-Q0 A 4th: Read from FIFO

Figure 4. Bus-Matching Byte Arrangement

(e) ×36 INPUT TO ×9 OUTPUT – LITTLE ENDIAN



BYTE ORDER ON OUTPUT PORT: BE	D35-D27 X Q35-Q27 X Q35-Q27 A	D26-D18 X Q26-Q18 X Q26-Q18 B SINPUT TO ×36 O	D17-D9 A Q17-Q9 C Q17-Q9 C	D8-D0 B
BE BM IW OW H H H L	Q35-Q27 C	Q26-Q18 D NPUT TO ×36 OL	Q17-Q9 A	Q8-Q0 B Read from FIFO
BYTE ORDER ON INPUT PORT:	Q35-Q27 X Q35-Q27 X Q35-Q27 X Q35-Q27 X	Q26-Q18 X Q26-Q18 X Q26-Q18 X Q26-Q18 X	Q17-Q9 X Q17-Q9 X Q17-Q9 X Q17-Q9 X	Q8-Q0 A 1st: Write to FIFO Q8-Q0 B 2nd: Write to FIFO Q8-Q0 C 3rd: Write to FIFO Q8-Q0 D 4th: Write to FIFO
BYTE ORDER ON OUTPUT PORT: BE	Q35-Q27 A (a) ×9	Q26-Q18 B INPUT TO ×36 O	Q17-Q9 C UTPUT – BIG EI	Q8-Q0 D Read from FIFO
BE BM IW OW H H H H	Q35-Q27	Q26-Q18	Q17-Q9	Q8-Q0 A Read from FIFO

(b) \times 9 INPUT TO \times 36 OUTPUT – LITTLE ENDIAN

Figure 1. Bus-Matching Byte Arrangement (Continued)

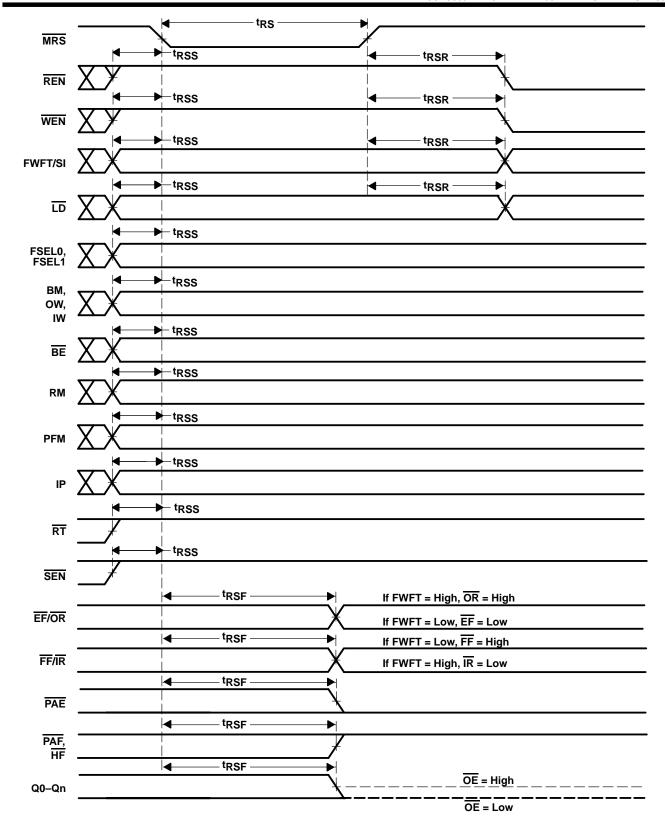


Figure 2. Master Reset Timing



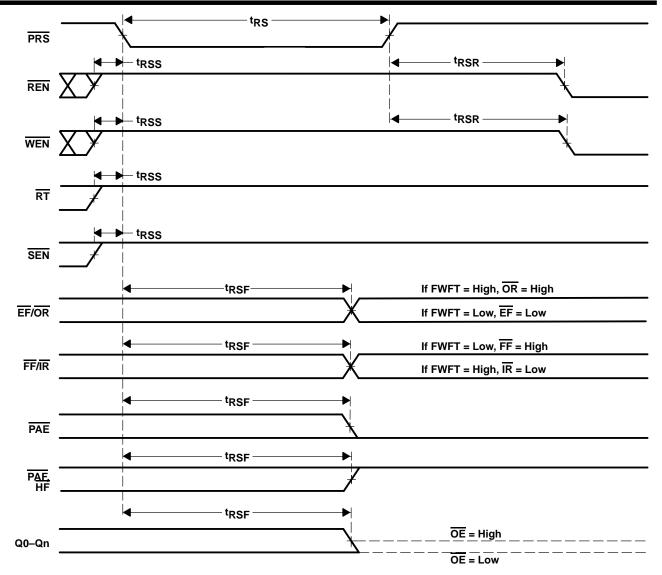
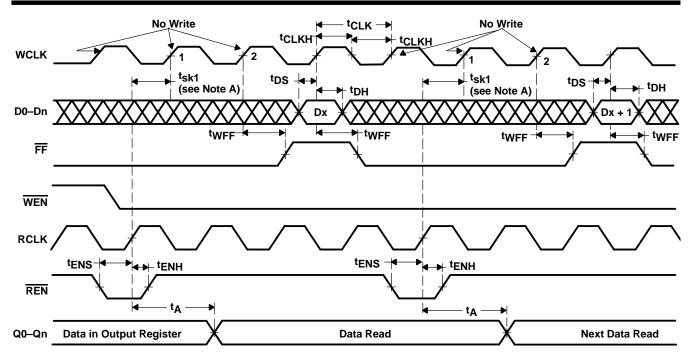


Figure 3. Partial Reset Timing

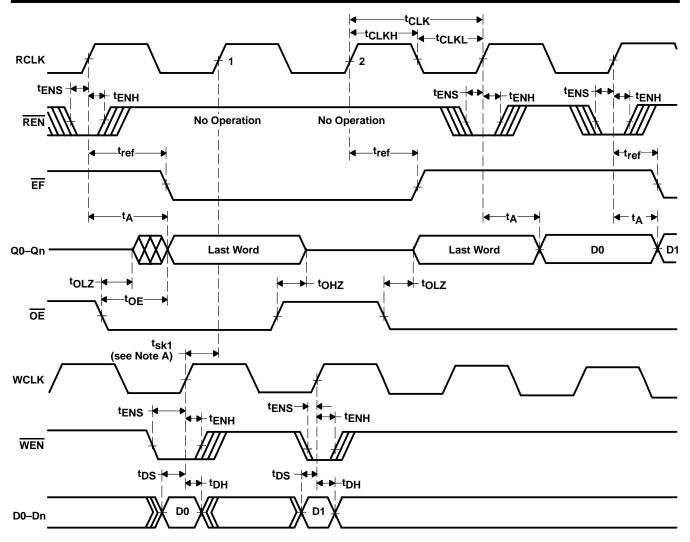


NOTES: A. t_{sk1} is the minimum time between a rising RCLK edge and a rising WCLK edge to ensure that $\overline{\text{FF}}$ goes high (after one WCLK cycle + t_{WFF}). If the time between the rising edge of the RCLK and the rising edge of the WCLK is less than t_{sk1}, $\overline{\text{FF}}$ deassertion can be delayed one additional WCLK cycle.

B. $\overline{LD} = \text{high}, \overline{OE} = \text{low}, \overline{EF} = \text{high}$

Figure 4. Write Cycle and Full Flag Timing (Standard Mode)



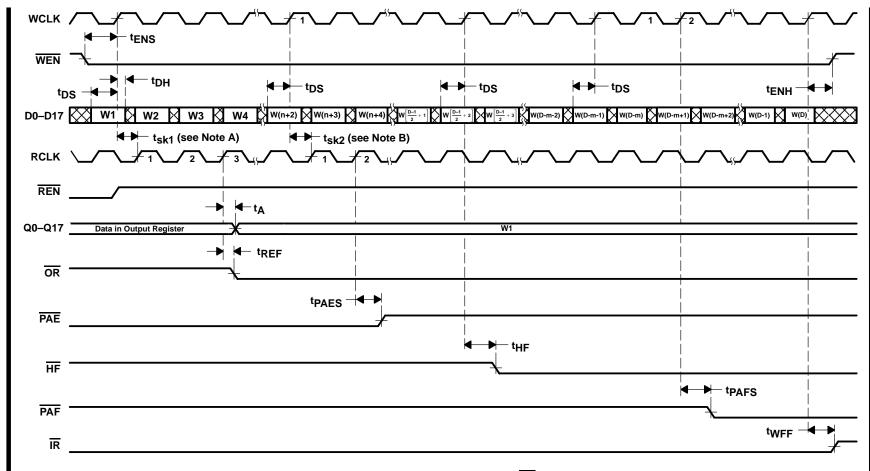


NOTES: A. t_{sk1} is the minimum time between a rising WCLK edge and a rising RCLK edge to ensure that $\overline{\text{EF}}$ goes high (after one RCLK cycle + t_{ref}). If the time between the rising edge of WCLK and the rising edge of RCLK is less than t_{sk1}, $\overline{\text{EF}}$ deassertion can be delayed one additional RCLK cycle.

- B. $\overline{LD} = high$
- C. First-data-word latency: t_{Sk1} + 1T_{RCLK} + t_{REF}

Figure 5. Read Cycle, Empty Flag, and First-Data-Word Latency Timing (Standard Mode)

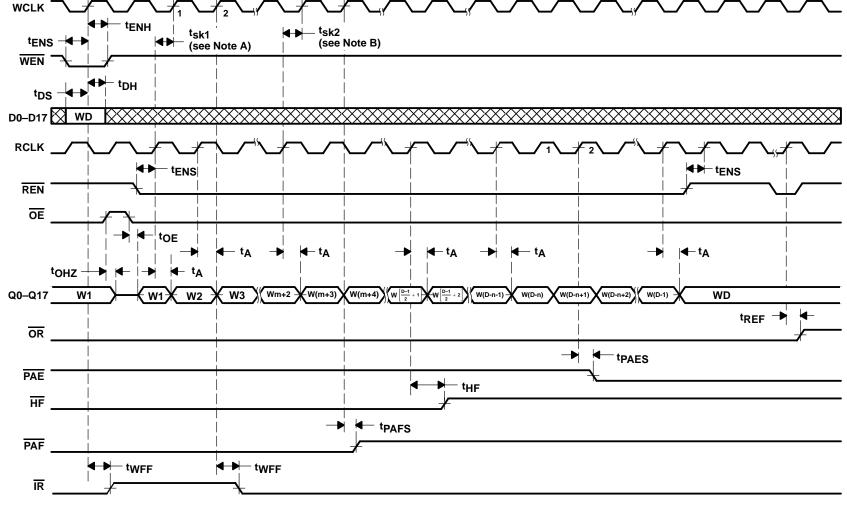




NOTES: A. t_{sk1} is the minimum time between a rising WCLK edge and a rising RCLK edge to ensure that $\overline{\text{OR}}$ goes low after two RCLK cycles + t_{REF}. If the time between the rising edge of WLCK and the rising edge of RCLK is less than t_{sk1}, $\overline{\text{OR}}$ assertion can be delayed one additional RCLK cycle.

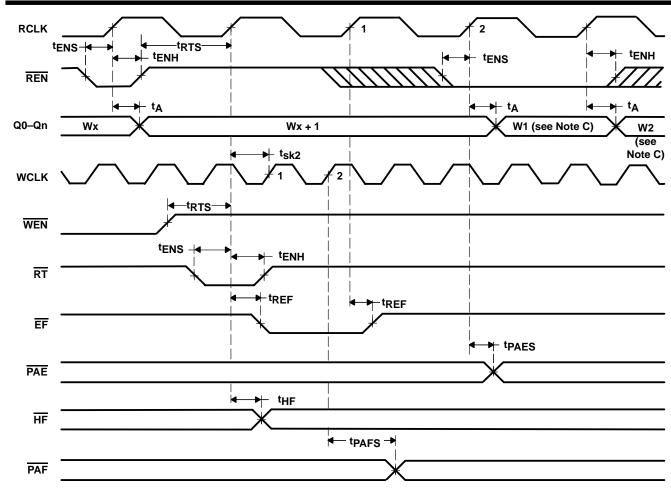
- B. t_{sk2} is the minimum time between a rising WCLK edge and a rising RCLK edge to ensure that PAE goes high after one RCLK cycle + t_{PAES}. If the time between the rising edge of WCLK and the rising edge of RCLK is less than t_{sk2}, PAE deassertion can be delayed one additional RCLK cycle.
- C. $\overline{LD} = \text{high}, \overline{OE} = \text{low}$
- D. $n = \overline{PAE}$ offset, $m = \overline{PAF}$ offset, D = maximum FIFO depth
- E. D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690
- F. First-data-word latency: t_{Sk1} + 2t_{RCLK} + t_{REF}

Figure 6. Write Timing (FWFT Mode)



- NOTES: A. t_{sk1} is the minimum time between a rising RCLK edge and a rising WCLK edge to ensure that \overline{IR} goes low after one WCLK cycle + t_{WFF} . If the time between the rising edge of RLCK and the rising edge of WCLK is less than t_{sk1} , \overline{IR} assertion may be delayed an additional WCLK cycle.
 - B. t_{sk2} is the minimum time between a rising RCLK edge and a rising WCLK edge to ensure that \overline{PAF} to goes high after one WCLK cycle + t_{PAFS} . If the time between the rising edge of RCLK and the rising edge of WCLK is less than t_{sk2} , \overline{PAF} deassertion may be delayed an additional WCLK cycle.
 - C. $\overline{LD} = high$
 - D. $n = \overline{PAE}$ offset, $m = \overline{PAF}$ offset, D = maximum FIFO depth
 - E. D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690

Figure 7. Read Timing (FWFT Mode)



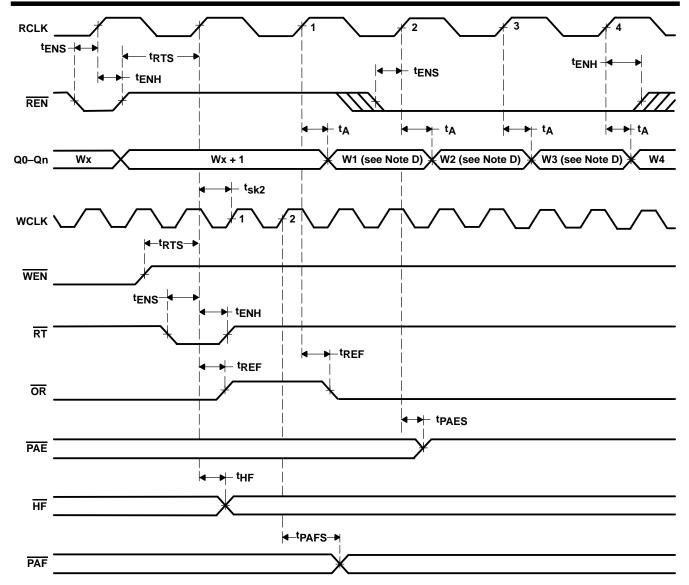
NOTES: A. Retransmit setup is complete after EF returns high; only then can a read operation begin.

- B. $\overline{OE} = low$
- C. W1 = first word written to the FIFO after master reset, W2 = second word written to the FIFO after master reset
- D. No more than (D 2) words may be written to the FIFO between reset (master or partial) and retransmit setup. Therefore, FF is high throughout the retransmit setup procedure.

 D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690.
- E. There must be at least two words written to and two words read from the FIFO before a retransmit operation can be invoked.
- F. RM is set high during \overline{MRS} .

Figure 8. Retransmit Timing (Standard Mode)

SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

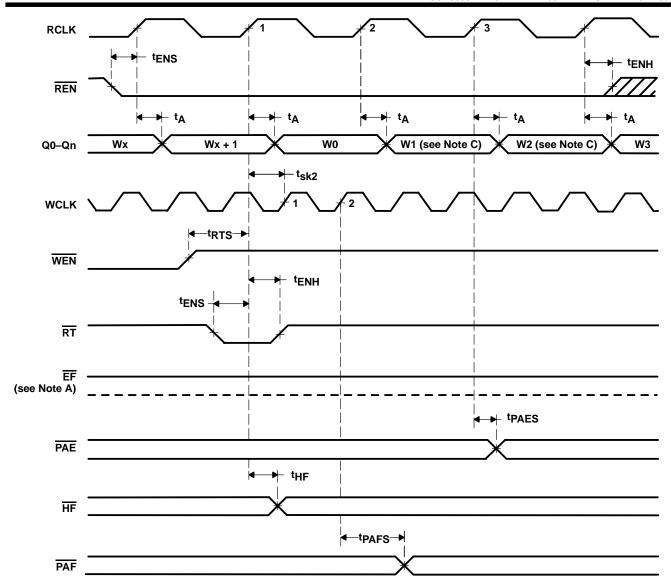


NOTES: A. Retransmit setup is complete after OR returns low.

- B. No more than (D − 2) words can be written to the FIFO between reset (master or partial) and retransmit setup. Therefore, is low throughout the retransmit setup procedure.
 D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.
- C. $\overline{OE} = low$
- D. W1, W2, W3 = first, second, and third words written to the FIFO after master reset
- E. There must be at least two words written to the FIFO before a retransmit operation can be invoked.
- F. RM is set high during \overline{MRS} .

Figure 9. Retransmit Timing (FWFT Mode)



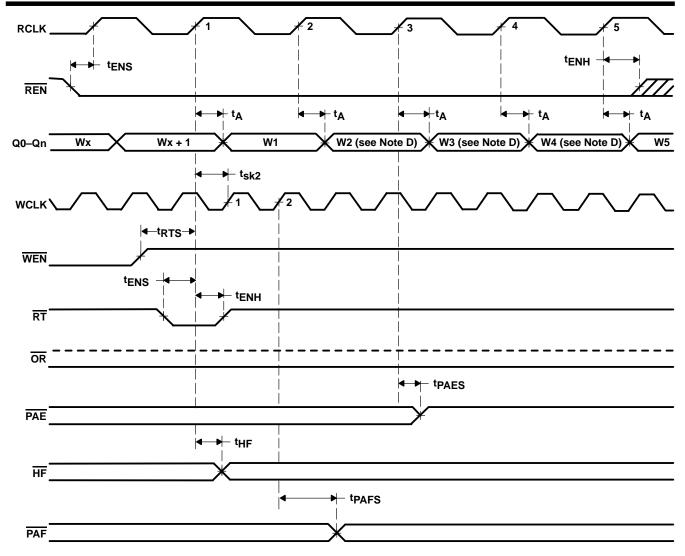


- NOTES: A. If the FIFO is empty at the point of retransmit, $\overline{\mathsf{EF}}$ is updated, based on RCLK (retransmit clock cycle). Valid data appears on the output.
 - B. \overline{OE} = low, enables data to be read on outputs Q0–Qn
 - C. W1 = first word written to the FIFO after master reset, W2 = second word written to the FIFO after master reset
 - D. No more than (D 2) words may be written to the FIFO between reset (master or partial) and retransmit setup. Therefore, FF is high throughout the retransmit setup procedure.
 - D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, D = 32768 for the SN74V3690.
 - E. At least two words must be written to and read from the FIFO before a retransmit operation can be invoked.
 - F. RM is set low during MRS.

Figure 10. Zero-Latency Retransmit Timing (Standard Mode)



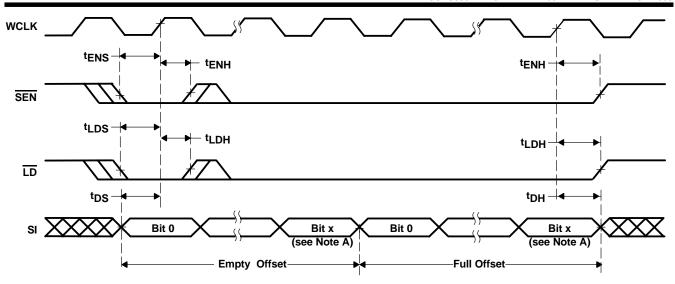
SCAS668A - NOVEMBER 2001 - RÉVISED MARCH 2003



- NOTES: A. If the FIFO is empty at the point of retransmit, $\overline{\mathsf{OR}}$ is updated, based on RCLK (retransmit clock cycle). Valid data also appears on the output.
 - B. No more than (D 2) words may be written to the FIFO between reset (master or partial) and retransmit setup. Therefore, \overline{IR} is low throughout the retransmit setup procedure.
 - D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, and D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.
 - C. $\overline{OE} = low$
 - D. W1, W2, W3 = first, second, and third words written to the FIFO after master reset.
 - E. There must be at least two words written to the FIFO before a retransmit operation can be invoked.
 - F. RM is set low during \overline{MRS} .

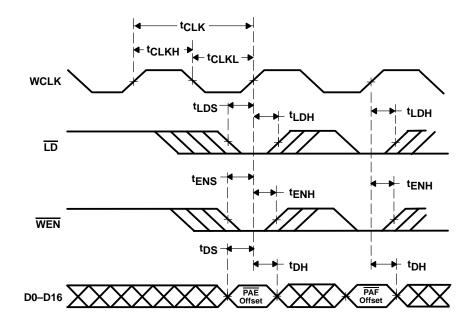
Figure 11. Zero-Latency Retransmit Timing (FWFT Mode)





NOTE A: x = 9 for the SN74V3640, x = 10 for the SN74V3650, x = 11 for the SN74V3660, x = 12 for the SN74V3670, x = 13 for the SN74V3690.

Figure 12. Serial Loading of Programmable Flag Registers (FWFT Mode)

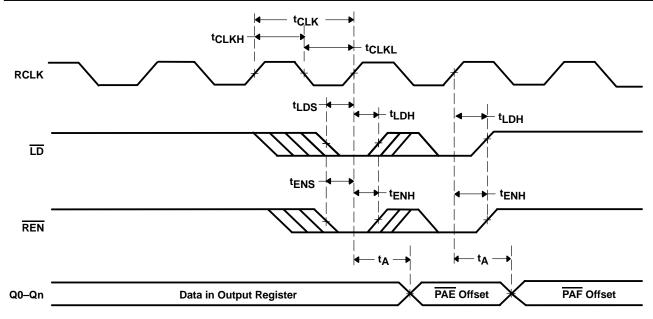


NOTE A: This diagram shows programming with an input bus width of 36 bits.

Figure 13. Parallel Loading of Programmable Flag Registers (Standard and FWFT Modes)



SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

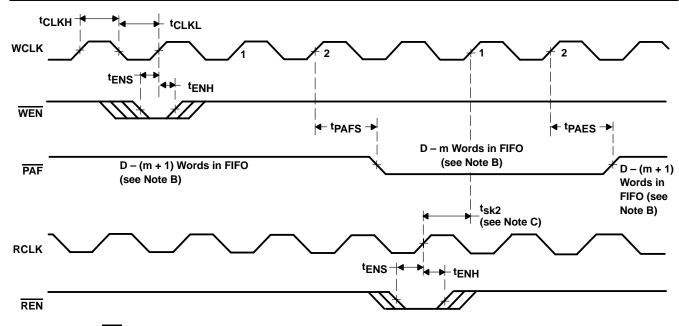


NOTES: A. OE = low

B. This diagram shows reading of offset registers with an output bus width of 36 bits.

Figure 14. Parallel Read of Programmable Flag Registers (Standard and FWFT Modes)



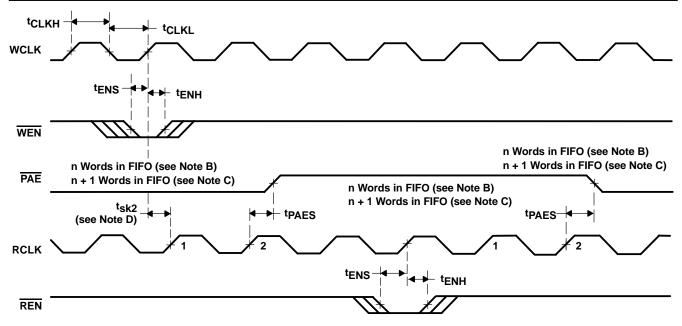


NOTES: A. $m = \overline{PAF}$ offset

- B. D = maximum FIFO depth
 In FWFT mode: D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, and D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.
 In standard mode: D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, D = 32768 for the SN74V3690.
- C. t_{sk2} is the minimum time between a rising RCLK edge and a rising WCLK edge to ensure that PAF goes high (after one WCLK cycle + tpAFs). If the time between the rising edge of RCLK and the rising edge of WCLK is less than t_{sk2}, PAF deassertion time may be delayed one additional WCLK cycle.
- D. PAF is asserted and updated on the rising edge of WCLK only.
- E. Select this mode by setting PFM high during master reset.

Figure 15. Synchronous Programmable Almost-Full Flag Timing (Standard and FWFT Modes)

SCAS668A – NOVEMBER 2001 – REVISED MARCH 2003

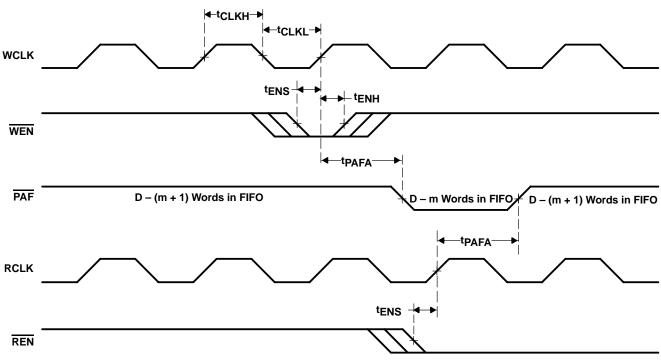


NOTES: A. $n = \overline{PAE}$ offset

- B. For standard mode
- C. For FWFT mode
- D. t_{sk2} is the minimum time between a rising WCLK edge and a rising RCLK edge to ensure that $\overline{\text{PAE}}$ goes high (after one RCLK cycle + tpAEs). If the time between the rising edge of WCLK and the rising edge of RCLK is less than t_{sk2}, $\overline{\text{PAE}}$ deassertion can be delayed one additional RCLK cycle.
- E. PAE is asserted and updated on the rising edge of WCLK only.
- F. Select this mode by setting PFM high during master reset.

Figure 16. Synchronous Programmable Almost-Empty Flag Timing (Standard and FWFT Modes)



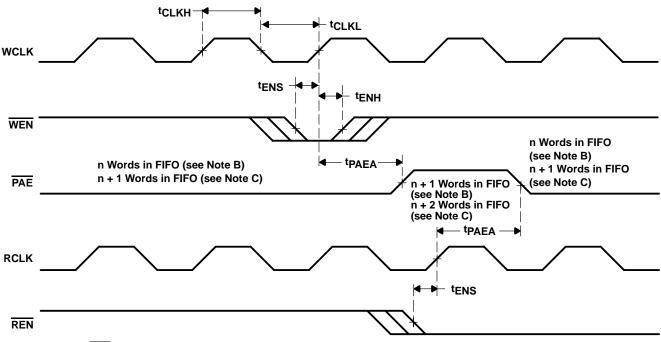


NOTES: A. $m = \overline{PAF}$ offset

- B. D = maximum FIFO depth
 In FWFT mode: D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.
 In standard mode: D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690.
- C. PAF is asserted to low on WCLK transition and reset to high on RCLK transition.
- $\label{eq:decomposition} \textbf{D.} \quad \textbf{Select this mode by setting PFM low during master reset.}$

Figure 17. Asynchronous Programmable Almost-Full Flag Timing (Standard and FWFT Modes)

SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

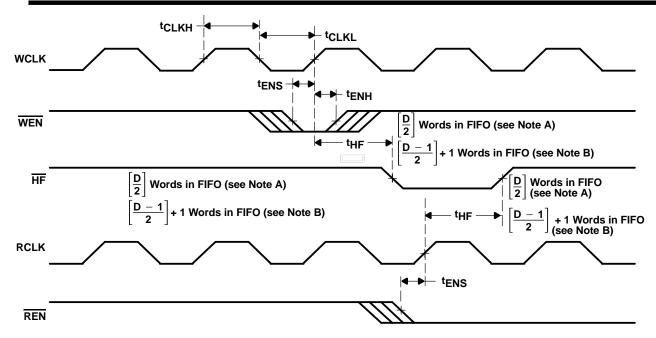


NOTES: A. $n = \overline{PAE}$ offset

- B. For standard mode
- C. For FWFT mode
- D. PAE is asserted low on RCLK transition and reset to high on WCLK transition.
- E. Select this mode by setting PFM low during master reset.

Figure 18. Asynchronous Programmable Almost-Empty Flag Timing (Standard and FWFT Modes)





- NOTES: A. In standard mode: D = maximum FIFO depth. D = 1024 for the SN74V3640, D = 2048 for the SN74V3650, D = 4096 for the SN74V3660, D = 8192 for the SN74V3670, D = 16384 for the SN74V3680, and D = 32768 for the SN74V3690.
 - B. In FWFT mode: D = maximum FIFO depth. D = 1025 for the SN74V3640, D = 2049 for the SN74V3650, D = 4097 for the SN74V3660, D = 8193 for the SN74V3670, D = 16385 for the SN74V3680, and D = 32769 for the SN74V3690.

Figure 19. Half-Full Flag Timing (Standard and FWFT Modes)

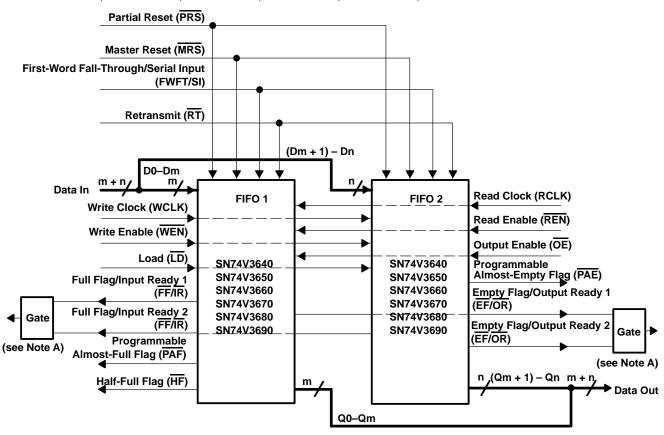
SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

operating configurations

width-expansion configuration

Word width can be increased by connecting the control signals of multiple devices together. Status flags can be detected from any one device. The exceptions are the $\overline{\text{EF}}$ and $\overline{\text{FF}}$ functions in standard mode and the $\overline{\text{IR}}$ and $\overline{\text{OR}}$ functions in FWFT mode. Because of variations in skew between RCLK and WCLK, it is possible for $\overline{\text{EF}}/\overline{\text{FF}}$ deassertion and $\overline{\text{IR}}/\overline{\text{OR}}$ assertion to vary by one cycle between FIFOs. In standard mode, such problems can be avoided by creating composite flags, that is, ANDing $\overline{\text{EF}}$ of every FIFO and separately ANDing $\overline{\text{FF}}$ of every FIFO. In FWFT mode, composite flags can be created by ORing $\overline{\text{OR}}$ of every FIFO and separately ORing $\overline{\text{IR}}$ of every FIFO.

Figure 23 demonstrates a width expansion using two SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 devices. D0–D35 from each device form a 72-bit-wide input bus and Q0–Q35 from each device form a 72-bit-wide output bus. Any word width can be attained by adding additional SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 devices.



- NOTES: A. Use an OR gate in FWFT mode and an AND gate in standard mode.
 - B. Do not connect any output control signals together directly.
 - C. FIFO 1 and FIFO 2 must be the same depth, but can be different word widths.

Figure 20. 1024 \times 72, 2048 \times 72, 4096 \times 72, 8192 \times 72, 16384 \times 72, 32768 \times 72 Width-Expansion Block Diagram



depth-expansion configuration (FWFT mode only)

The SN74V3640 easily can be adapted to applications requiring depths greater than 1024 for the SN74V3640, 2048 for the SN74V3650, 4096 for the SN74V3660, 8192 for the SN74V3670, 16384 for the SN74V3680, and 32768 for the SN74V3690, with an 18-bit bus width. In FWFT mode, the FIFOs can be connected in series (the data outputs of one FIFO connected to the data inputs of the next), with no external logic necessary. The resulting configuration provides a total depth equivalent to the sum of the depths associated with each single FIFO. Figure 24 shows a depth expansion using two SN74V3640, SN74V3650, SN74V3660, SN74V3670, SN74V3680, and SN74V3690 devices.

Care should be taken to select FWFT mode during master reset for all FIFOs in the depth-expansion configuration. The first word written to an empty configuration passes from one FIFO to the next (ripple down) until it finally appears at the outputs of the last FIFO in the chain. No read operation is necessary, but the RCLK of each FIFO must be free running. Each time the data word appears at the outputs of one FIFO, that device's \overline{OR} line goes low, enabling a write to the next FIFO in line.

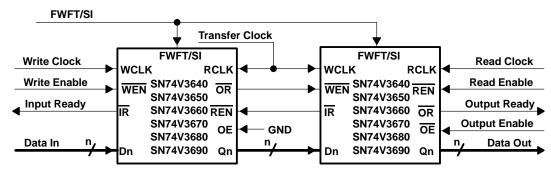


Figure 21. 2048 \times 36, 4096 \times 36, 8192 \times 36, 16384 \times 36, 32768 \times 36, 65536 \times 36 Depth-Expansion Block Diagram

For an empty-expansion configuration, the amount of time it takes for $\overline{\mathsf{OR}}$ of the last FIFO in the chain to go low (i.e., valid data to appear on the last FIFO's outputs) after a word has been written to the first FIFO is the sum of the delays for each FIFO:

$$(n-1) \times (4 \times \text{transfer clock}) + 3t_{RCLK}$$
 (1)

Where:

n = number of FIFOs in the expansion $t_{RCLK} = RCLK$ period

Note that extra cycles should be added for the possibility that the t_{sk1} specification is not met between WCLK and the transfer clock, or RCLK and the transfer clock, for the \overline{OR} flag.

The ripple-down delay is noticeable only for the first word written to an empty-depth-expansion configuration. There will be no delay evident for subsequent words written to the configuration.

The first free location created by reading from a full-depth-expansion configuration will bubble up from the last FIFO to the previous one until, finally, it moves into the first FIFO of the chain. Each time a free location is created in one FIFO of the chain, that FIFO's \overline{IR} line goes low, enabling the preceding FIFO to write a word to fill it.

SCAS668A - NOVEMBER 2001 - REVISED MARCH 2003

depth-expansion configuration (FWFT mode only) (continued)

For a full expansion configuration, the amount of time it takes for \overline{IR} of the first FIFO in the chain to go low after a word has been read from the last FIFO is the sum of the delays for each individual FIFO:

$$(n-1) \times (3 \times \text{transfer clock}) + 2t_{\text{WCLK}}$$
 (2)

Where:

 $\begin{array}{ll} n & = number \ of \ FIFOs \ in \ the \ expansion \\ t_{WCLK} & = WCLK \ period \end{array}$

Note that extra cycles should be added for the possibility that the t_{sk1} specification is not met between RCLK and the transfer clock, or WCLK and the transfer clock, for the \overline{IR} flag.

The transfer-clock line should be tied to either WCLK or RCLK, whichever is faster. Both these actions result in data moving as quickly as possible to the end of the chain and moving free locations to the beginning of the chain.



www.ti.com 11-Nov-2025

PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
SN74V3680-15PEU	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	V3680-15
SN74V3680-15PEU.A	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	V3680-15
SN74V3680-6PEU	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	V3680-6
SN74V3680-6PEU.A	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	V3680-6
SN74V3690-6PEU	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-220C-168 HR	0 to 70	V3690-6
SN74V3690-6PEU.A	Active	Production	LQFP (PEU) 128	72 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-220C-168 HR	0 to 70	V3690-6

⁽¹⁾ Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



PACKAGE OPTION ADDENDUM

www.ti.com 11-Nov-2025

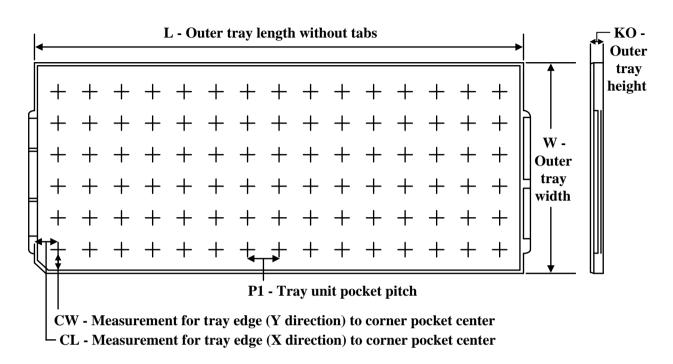
Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



www.ti.com 23-May-2025

TRAY



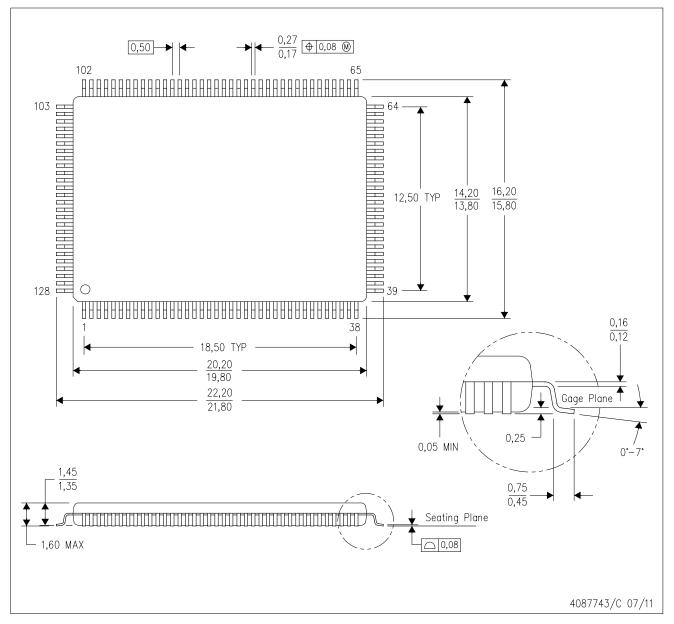
Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	Κ0 (μm)	P1 (mm)	CL (mm)	CW (mm)
SN74V3680-15PEU	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45
SN74V3680-15PEU.A	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45
SN74V3680-6PEU	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45
SN74V3680-6PEU.A	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45
SN74V3690-6PEU	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45
SN74V3690-6PEU.A	PEU	LQFP	128	72	6X12	150	315	135.9	7620	25.4	17.8	15.45

PEU (R-PQFP-G128)

PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale, TI's General Quality Guidelines, or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Copyright © 2025, Texas Instruments Incorporated

Last updated 10/2025