



Design Consideration in Selecting the Switching Frequency of Power Controllers

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Agenda

- Introduction
- Case Study
- Concepts and analysis
 - Minimum On Time
 - Minimum duty cycle capability
 - Effects of pulse skipping
 - Size
 - Filter selections
 - Filter comparisons
 - Efficiency
 - Power loss and thermal roadblocks
 - Efficiency comparisons
 - Performance
 - Bode Plots
 - Transient response
 - Ripple
- Competition
- TI Power Management devices > 1MHz
- Summary



Industry Trends

- Board space is becoming more valuable as density requirements increase
- Performance DSP and FPGA core voltage are dropping $<1V$
- Suppliers are aggressively marketing faster DC/DC Converters that claim to save space
 - How much space is really saved?
 - What are the trade offs and pitfalls?



Three Designs Compared

Design Example:

- Input Voltage: 5V
- Output voltage: 1.8V
- Output Current: 3A
- Output voltage Ripple: 20mV
- Inductor Ripple Current: 1A peak to peak

Switching Frequencies

- 350kHz
- 700kHz
- 1.6MHz

TPS54317 Selected

- Supports up to 1.6MHz
- Marketed as small sized design for high-density DSP & FPGA applications



TPS54317

1.6MHz, 3-6Vin, 3-A Step Down Converter

Features

- Adjustable / synchronized switching frequency to 1.6MHz
- Supported by free SWIFT™ Software tool
- Two integrated MOSFETs provide synchronous rectification
- Output voltage adjustable down to 0.9V
- Power Good, Enable, Adj. Slow-start, Current Limit, Thermal Shutdown, & 1% accuracy
- 4x5mm 24pin thermal QFN package

Applications

- 3.3/5V Intermediate Bus for high density point of load power systems
- Broadband, networking, and optical communications
- Point of Load Regulation for DSPs, FPGAs, & ASICs

EVM

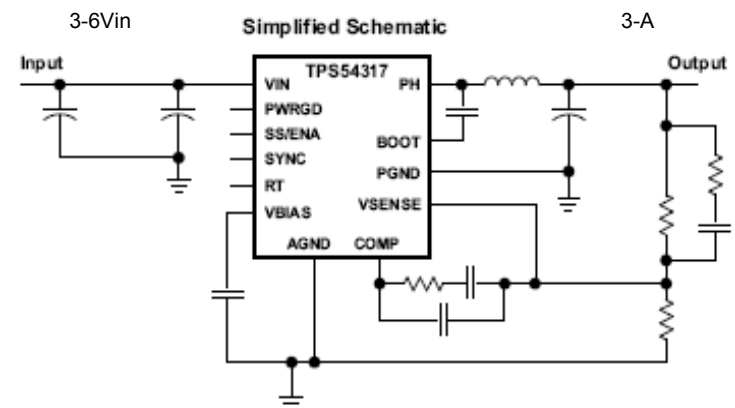


TPS54317EVM-159

\$2.50 @1K

Benefits

- High frequency allows a smaller inductor and capacitor to save board space
- Fast and easy design in minutes
- High efficiency greater than 90%; regulates at no load
- Ideal for DSP/FPGA power
- Many integrated protection and performance features to protect the system when powering advanced processors
- High current density saves board space





Inductor Selection

Know $V = L * di/dt$

$$L = V * \Delta I / \Delta t$$

$L \geq V_{out} * (1-D)/(\Delta I * F_s)$; with $\Delta I = 1A$ peak to peak

- 350kHz $L \geq 3.3 \mu H$ → Choose $3.5 \mu H$
- 700kHz $L \geq 1.7 \mu H$ → Choose $2.2 \mu H$
- 1.6MHz $L \geq 0.7 \mu H$ → Choose $1.0 \mu H$



Capacitor Selection

Know: $R = V/I$

→ $ESR \leq \Delta V / \Delta I$; use 0 mΩ for ceramic

$I = C * dv/dt$

→ $C \geq \Delta I / (8 * F_s * \Delta V)$

Total $\Delta V = \Delta I / (8 * C * F_s) * 2$ (to account for DC bias)

Design #1: 350kHz

- $C \geq 36 \mu F$

→ Choose 47μF 1206 ceramic

Design #2: 700kHz

- $C \geq 18 \mu F$

→ Choose 22μF 0805 ceramic

Design #3: 1.6MHz

- $C \geq 7.9 \mu F$

→ Choose 10μF 0603 ceramic



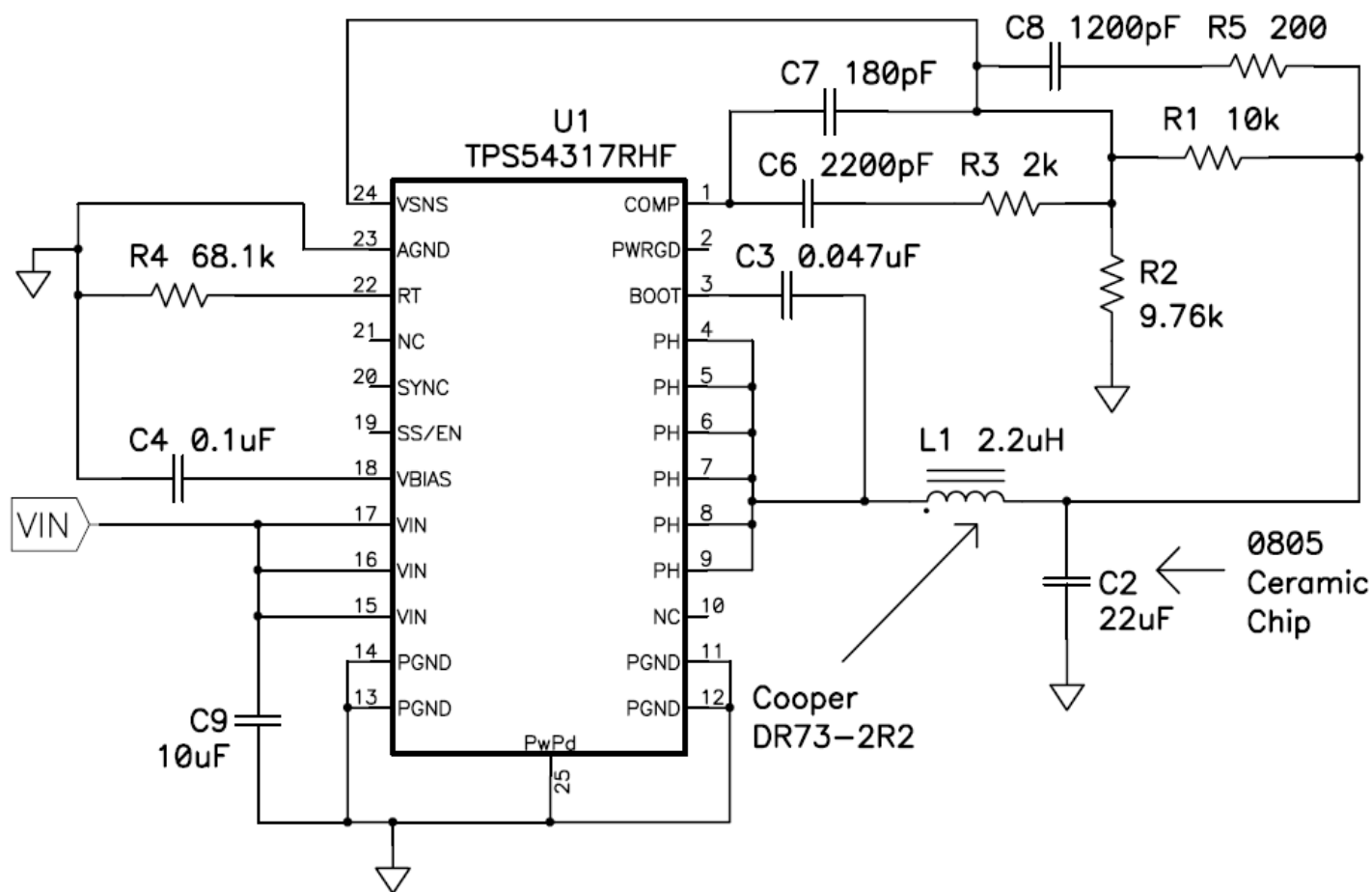
- Sumida
- $3.5\mu\text{H}$
- $19\text{ m}\Omega$

Capacitor:

- $47\mu\text{F}$
- 1206



Design Example #2



700kHz

Inductor:

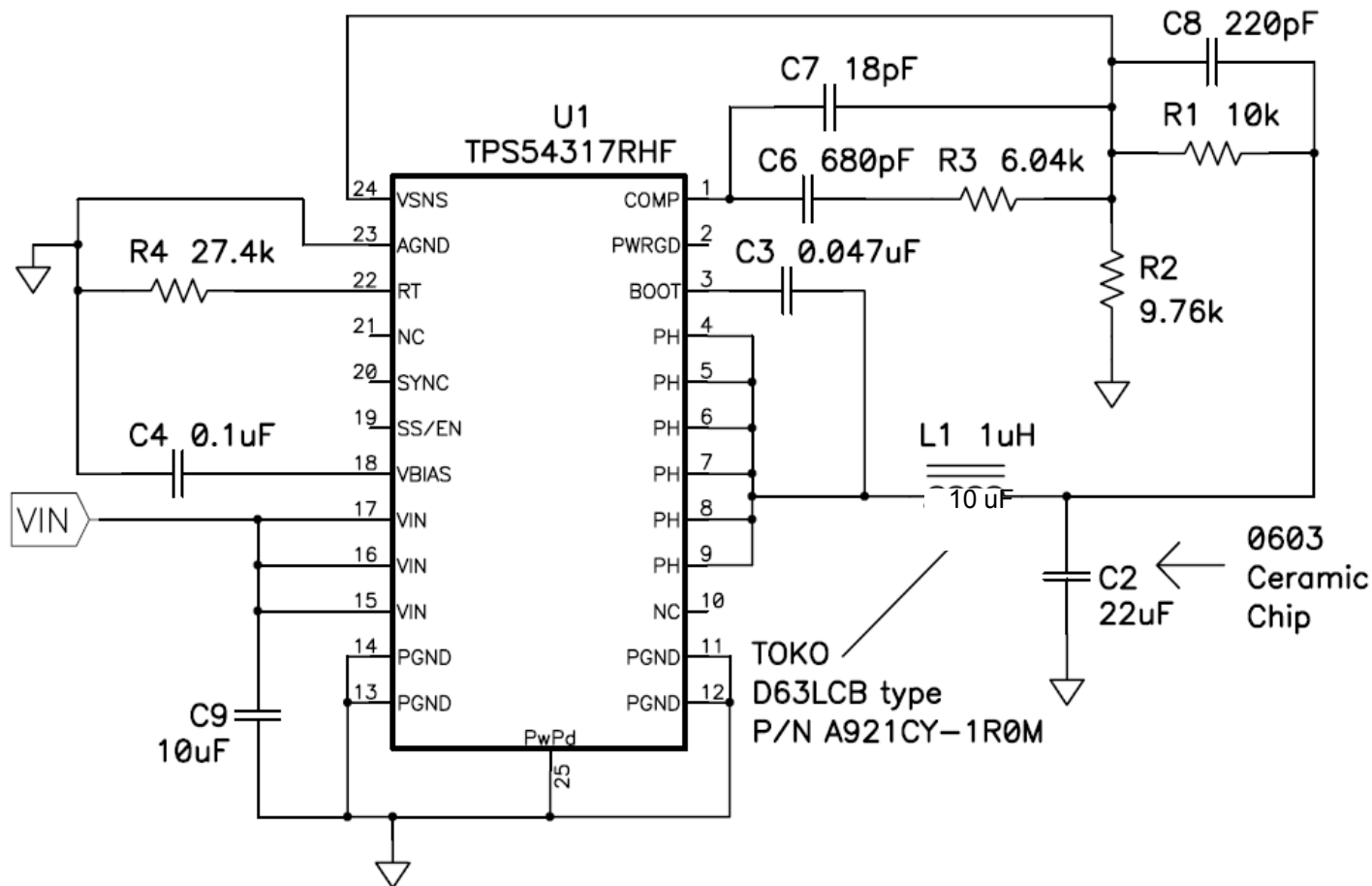
- Cooper
- 2.2µH
- 16.5 mΩ

Capacitor:

- 22µF
- 0805



Design Example #3



1.6MHz

Inductor:

- Toko
- 1 μ H
- 11 m Ω

Capacitor:

- 10 μ F
- 0603



Minimum *Controllable* On-Time

DC/DC Converters won't always work over a wide Vout/Vin Range.

- Check the minimum controllable on time in the datasheet, not the maximum oscillator frequency.

TPS54317 datasheet

	Min	typ	max	
Frequency range, SYNC	330		1600	kHz
Ramp valley ⁽¹⁾		0.75		V
Ramp amplitude (peak-to-peak) ⁽¹⁾		1		V
Minimum controllable on time			150	ns
Maximum duty cycle	90%			

- Check if the Vout/Vin (duty cycle) combination will work when the switching frequency and the minimum controllable on time are known.

$$\text{Min. Duty Cycle} = \text{Min. On time} * \text{Switching Frequency}$$

For 5Vin, 1.8Vout, 150ns min. on-time examples:

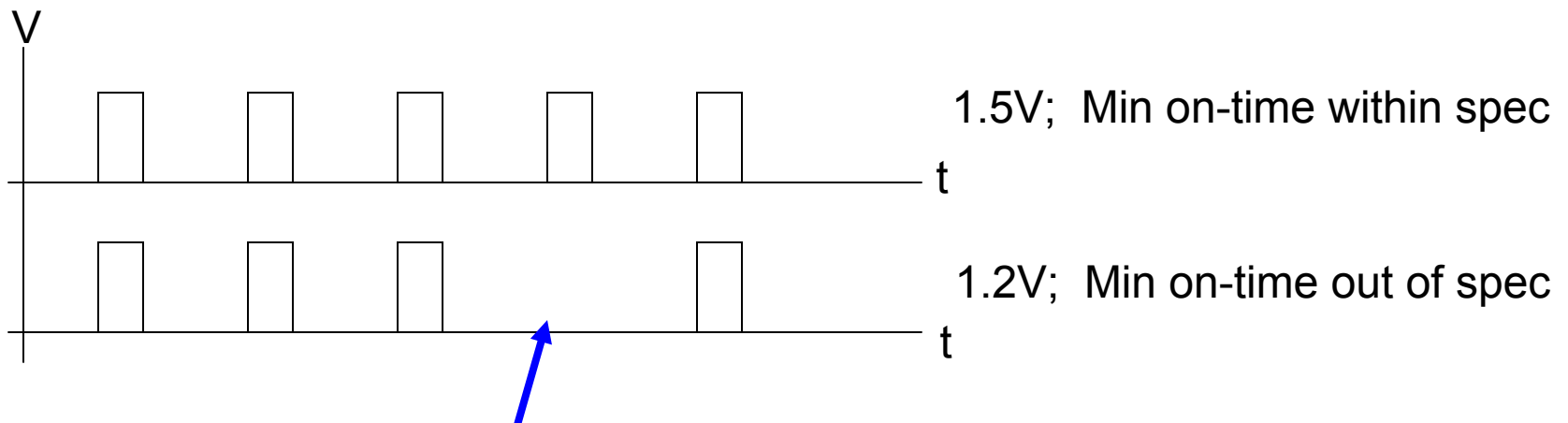
<u>Frequency</u>	<u>Min. Duty Cycle</u>	<u>Minimum Vout</u>
350 kHz	0.0525	→ OK - below Vout minimum of IC
700 kHz	0.12	→ OK - below Vout minimum of IC
1.6 MHz	0.24	→ OK 1.2V
3MHz	0.45	→ 2.3V (pulse skipping)



Minimum On-Time Issues

Pulse skipping happens when the DC/DC converter cannot extinguish the gate drive pulses fast enough to maintain the desired duty cycle. The power supply will still regulate the output voltage, but...

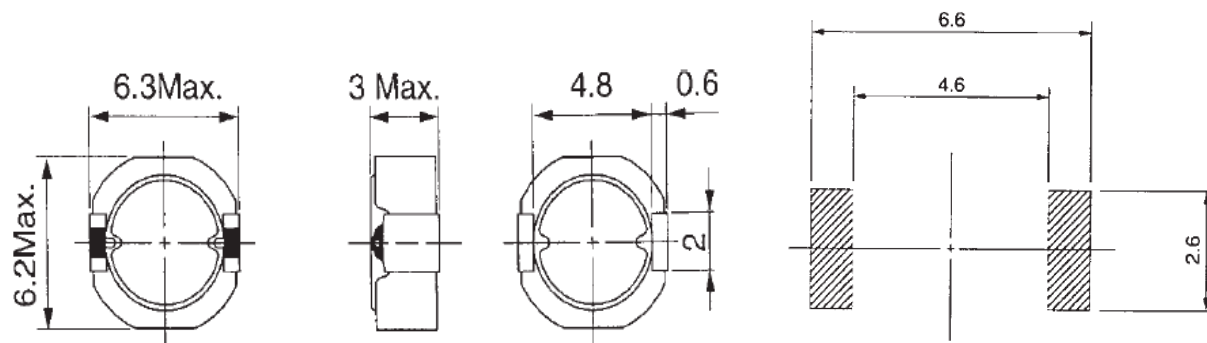
- Ripple voltage increases due to the pulses being further apart
- Frequency is no longer fixed
- Current limit may no longer work since the IC cannot respond in time
- Control loop may be unstable. Transient response is also affected



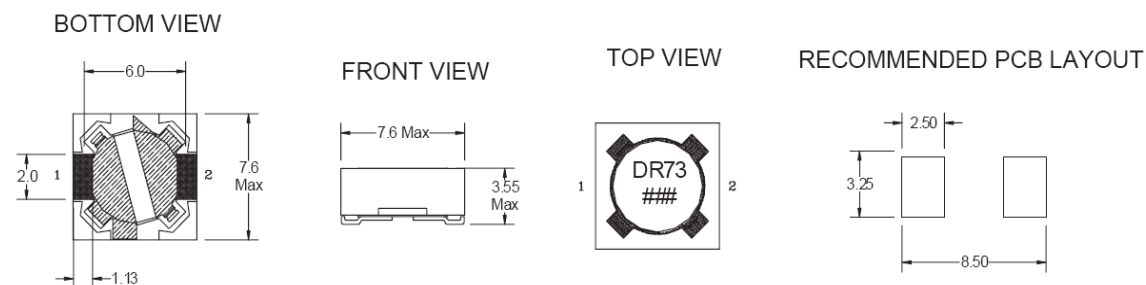
Controller misses a pulse to maintain desired regulation. Drop the V_{in} .



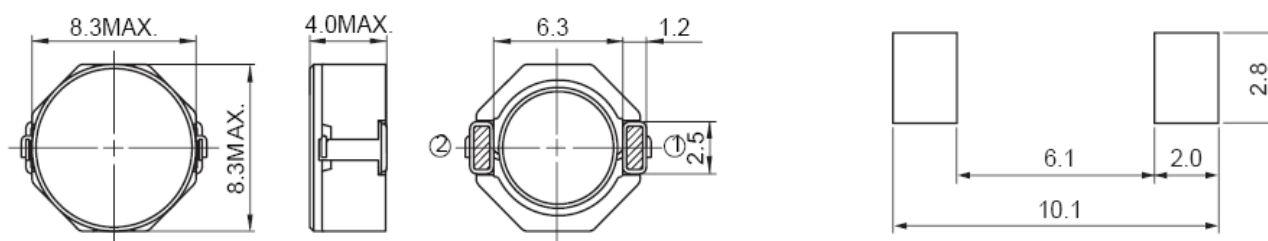
Inductor Size Comparison



TOKO
1.6MHz
1.0 μ H
11m Ω



COOPER
700kHz
2.2 μ H
16.5m Ω



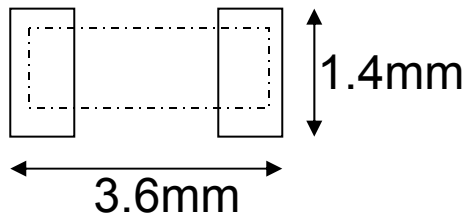
SUMIDA
350kHz
3.5 μ H
19m Ω



Capacitor Size Comparison

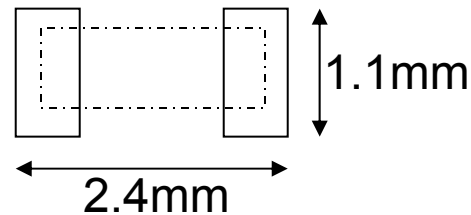
350 kHz Design

47 μ F



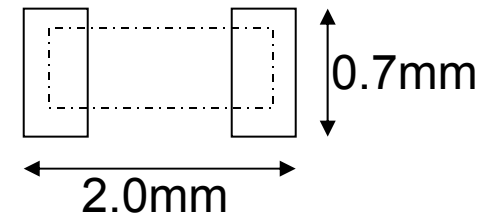
700 kHz Design

22 μ F



1.6 MHz Design

10 μ F



Frequency	Capacitor Land-pad size	Inductor Size	Filter Area (w/o spacing)	Total area (with spacing)
350kHz	5mm ²	84mm ²	89mm ²	260mm ²
700kHz	2.6mm ²	65mm ²	67.6mm ²	216mm ²
1.6MHz	1.4mm ²	41mm ²	42.4mm ²	163mm ²



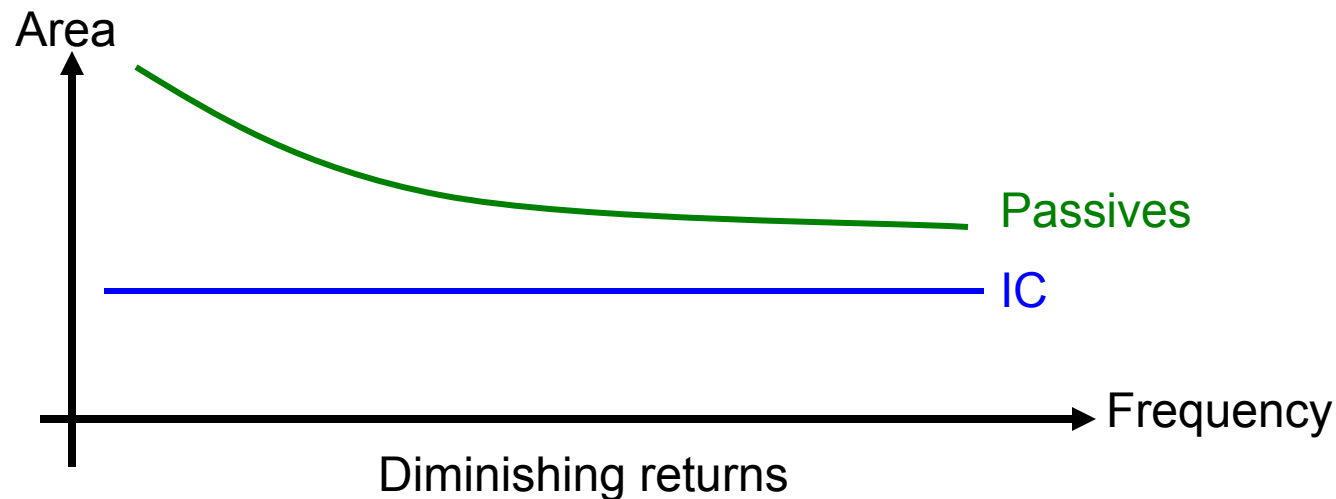
Filter Size Comparison

Consider Capacitor Package:

- Capacitors are available in fixed sizes
- ESR must be maintained as the case size is reduced

Consider Inductor Volume:

- Taller inductors may take up less board area, but pose a height issue
- Inductor Volume = $L * i^2 / 5 \times 10^{-3}$





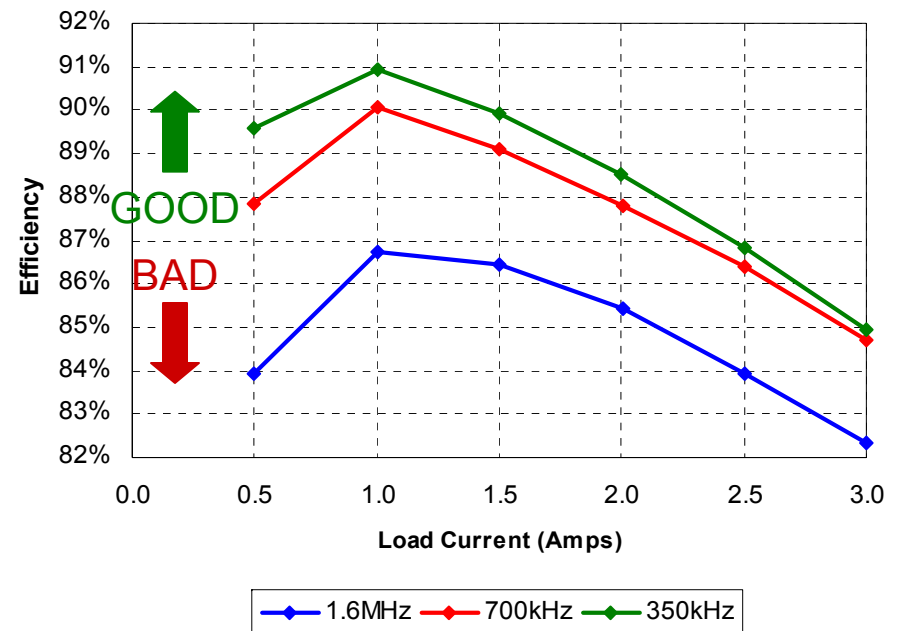
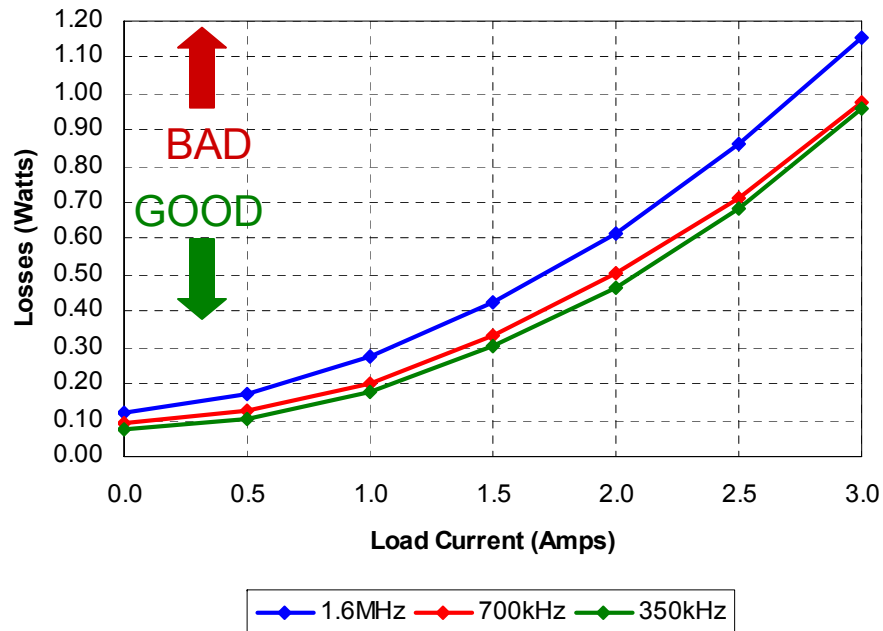
Efficiency

Power dissipation comes from several places including:

- FET driving loss ($Q_g * V * F$):
 - FET drive loss is proportional to the switching frequency
- FET switching loss function of V_{in} , I_{out} , $T_{on/off}$, F
 - Switching loss is proportional to the switching frequency
- FET resistance ($I^2 * R_{ds(on)}$)
 - Same FET – little variance in these examples
- Inductor loss ($I^2 * DCR + \text{Core losses}$):
 - DCR losses may be reduced when Inductance is smaller
 - AC losses are proportional to the frequency
- Capacitor loss ($I_{RMS}^2 * ESR$):
 - Capacitor loss is negligible
- IC loss (I_q):
 - Same IC – no variance in these design examples



Efficiency Results



Dissipated power turns into heat:

Frequency

350kHz

700kHz

1.6MHz

IC temperature

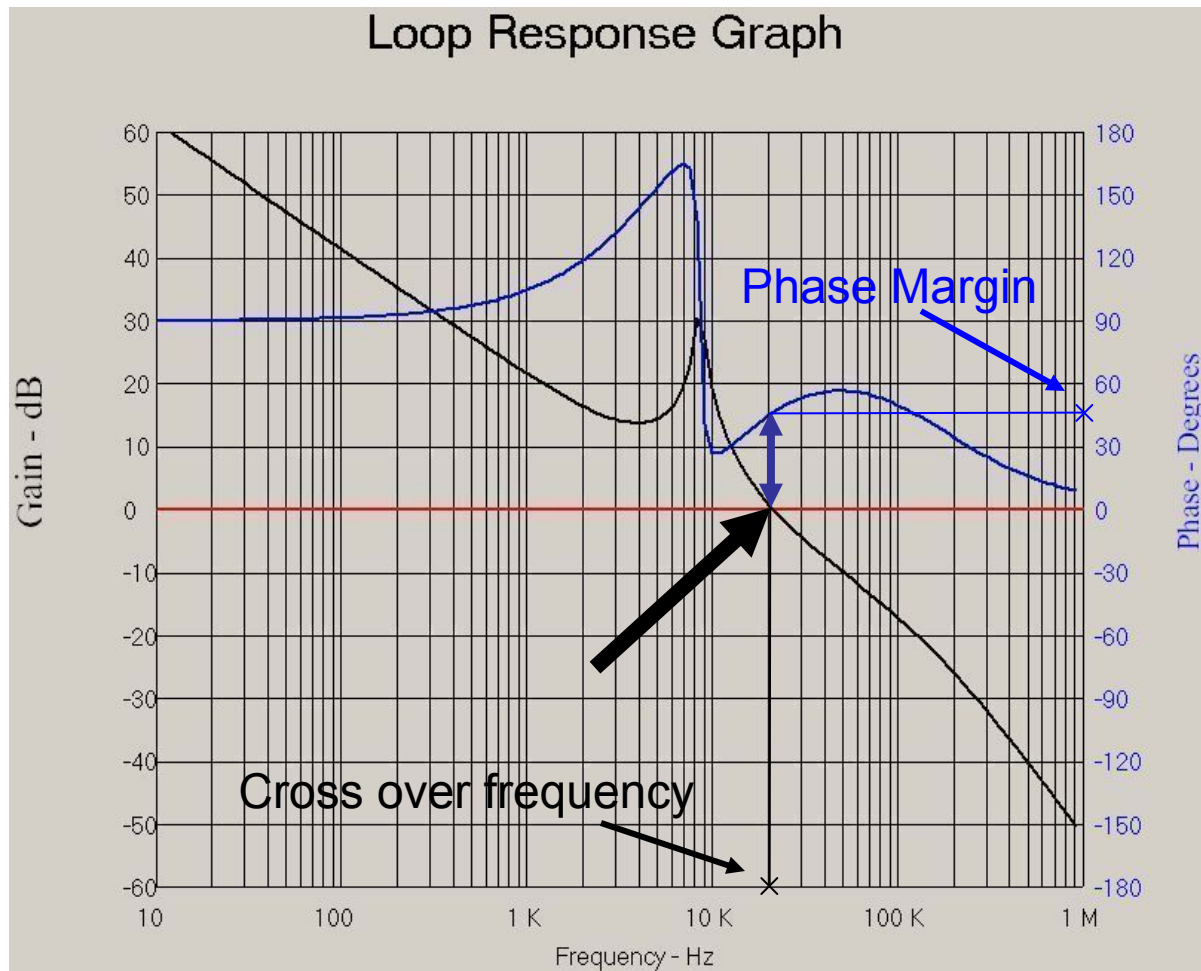
45° C

48° C

52° C



Basic Stability Criterion

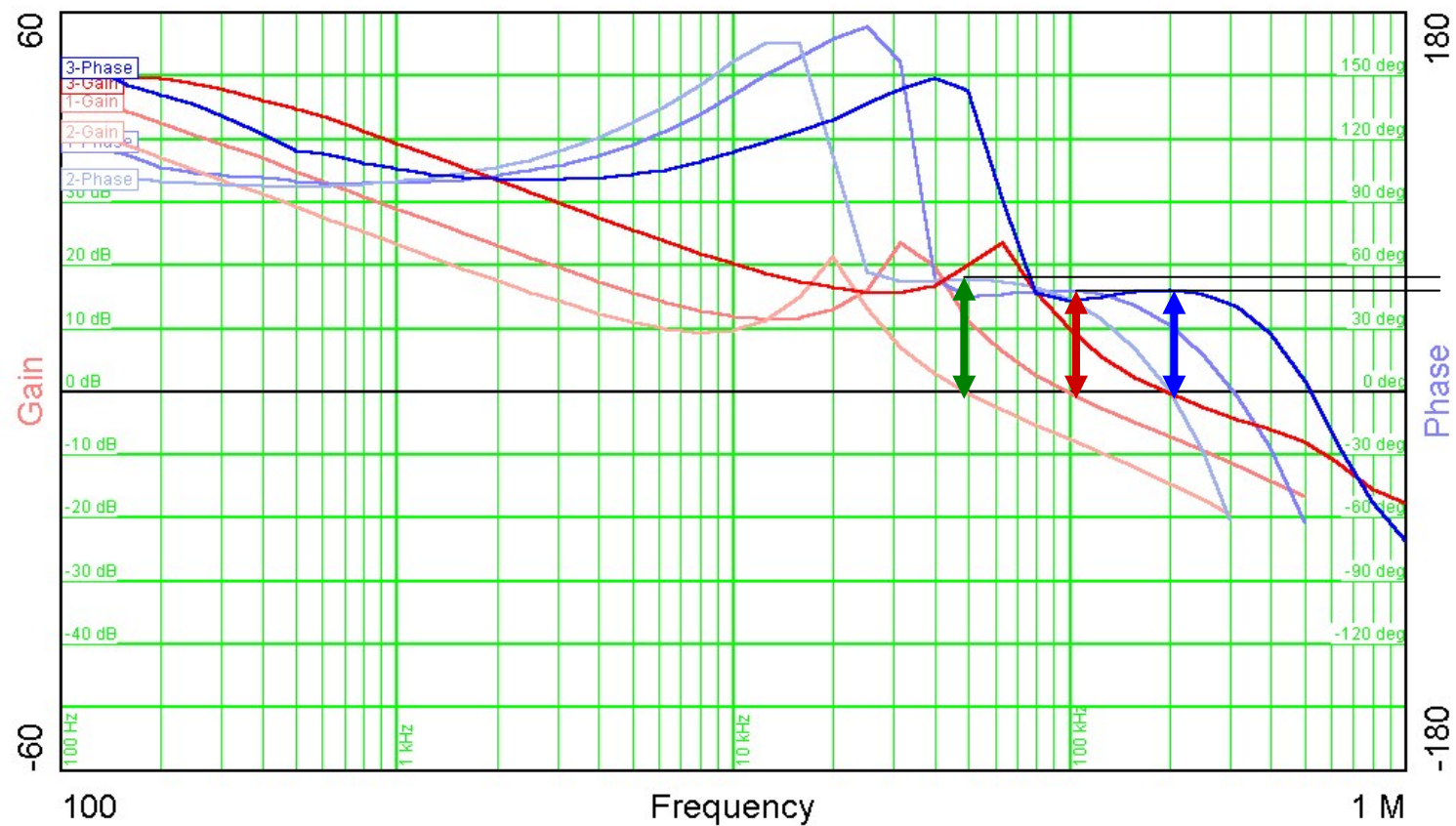


Reading Bode Plot

- 1) Find Cross Over Frequency at 0dB
 - 21 kHz Cross Over
- 2) Find Phase Margin at the Cross Over Frequency
 - 45° at 21kHz
- 3) Goal is to have Phase Margin between 45° and 90° to maintain a well-damped transient response



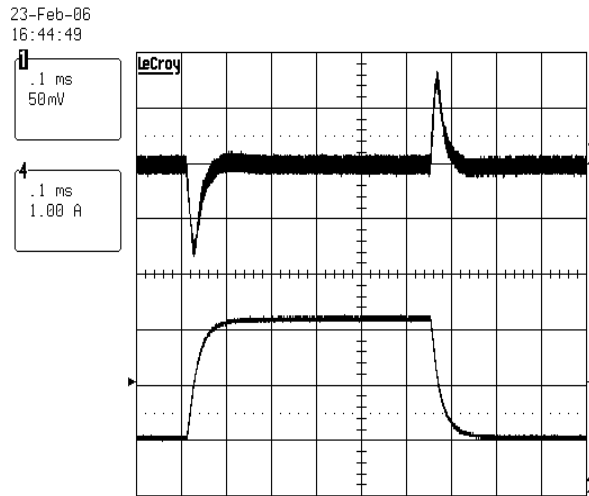
Bode Comparison



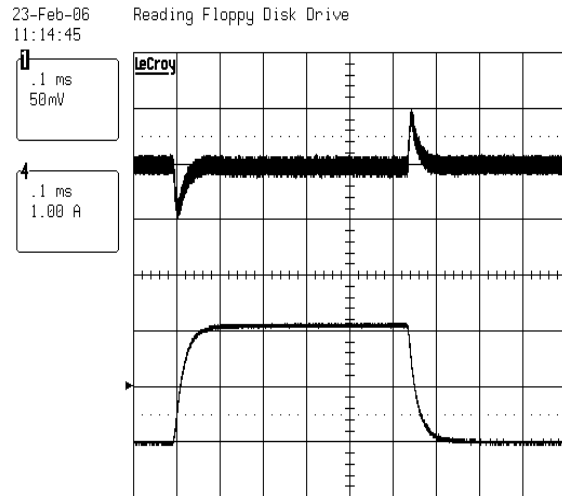


Transient Response

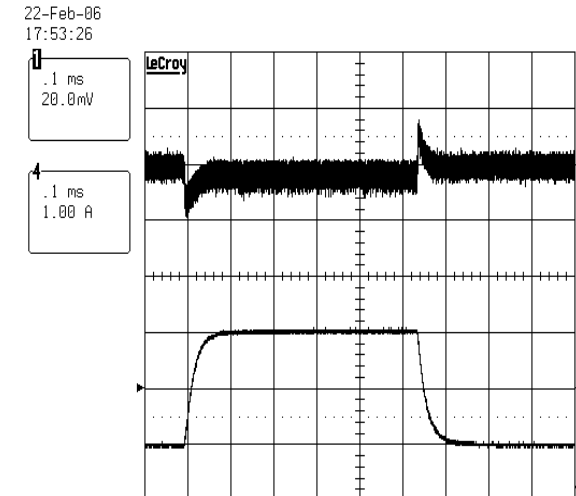
350 kHz



700 kHz



1.6 MHz



	Cross Over	Phase Margin	Response time	Voltage peak
350kHz	50kHz	52°	80us	80mV
700kHz	95kHz	45°	70us	50mV
1.6MHz	200kHz	45°	60us	20mV

Higher cross-over frequency yields slightly faster transient response

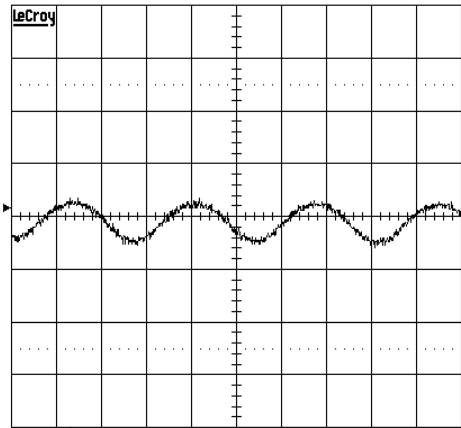


Ripple Comparison

23-Feb-06
16:39:54

Reading Floppy Disk Drive

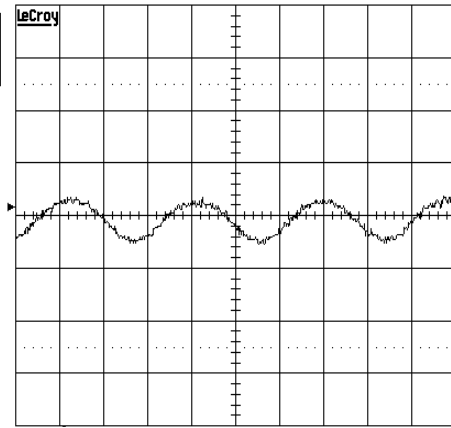
1 μ s
20.0mV



350 kHz
18mV ripple

23-Feb-06
11:12:24

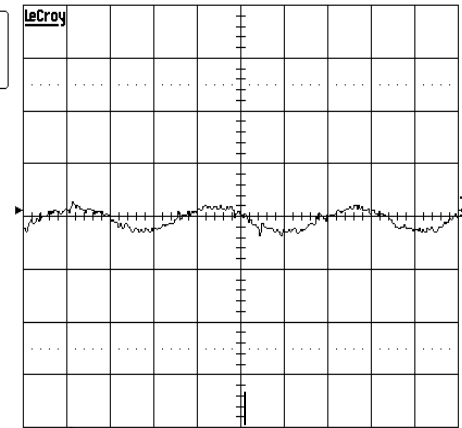
.5 μ s
20.0mV



700 kHz
17mV ripple

22-Feb-06
17:54:21

.2 μ s
20.0mV



1.6 MHz
12mV ripple

Higher switching frequency yields slightly lower output voltage ripple



Competition (>1MHz, >2A)

Part	TPS54317	MAX1536	EL7532	MIC2207	LTC3412A
Current	3-A (4 peak)	3.6-A (4 peak)	2-A	3-A (3.5 peak)	2.5-A (4.5 peak)
Voltage	3 - 6V	3 – 5.5V	2.5-5.5	2.7 - 5.5V	2.7 – 5.5V
Frequency	1.6MHz	1.4 MHz	1.5MHz	2MHz	4MHz
Minimum on time	150ns	300ns	?	?	?
RDS ON	59mΩ	54mΩ	80mΩ	95mΩ	77mΩ
Accuracy	1%	1%	2%	1%	2%
Adj. Soft Start	✓				✓
Enable	✓	✓	✓	✓	✓
Sync Pin	✓				✓
Power Good Pin	✓	✓	✓	✓	✓
Tools Support	✓		✓		✓
Package	4x5/24QFN	5x5/28QFN	10 Pin MSOP	3x3/12SON	4x4/16QFN



TI Power Devices >1MHz

Part Number	Max. Freq.	I _{out}	Topology	V _{in} (min)	V _{in} (max)	Description
TPS62300	3000	0.5	Buck	2.7	6	Adjustable, 500-mA, 3-MHz Step-Down Converter in QFN or Chip-Scale
TPS62320	3000	0.5	Buck	2.7	6	Adjustable, 500-mA, 3-MHz Step-Down Converter in QFN or Chip-Scale
TPS62102	2000	0.5	Buck	2.5	9	Multimode 1MHz Synchronous Buck Converter with Adjustable Output
TPS62220	1850	0.4	Buck	2.5	6	Adjustable, 400-mA, 95% Efficient Step-Down Converter, 15uA, ThinSOT-23
TPS54317	1600	3	Buck	3	6	1.6MHz, 3-6Vin, Synchronous Step Down Converter
TPS62020	1500	0.6	Buck	2.5	6	Adjustable, 600-mA, 95% Efficient Step-Down Converter, 18uA, MSOP-10
TPS62040	1500	1.2	Buck	2.5	6	Adjustable, 1.2-A, 95% Efficient Step-Down Converter, 18uA, MSOP-10
TPS62200	1500	0.3	Buck	2.5	6	Adjustable, 300-mA, 95% Efficient Step-Down Converter in SOT-23
TPS65010	1500	1	Buck	2.5	6	Multi-Channel 1-cell Li-Ion Power Mgmt IC: USB/AC Charger, 2DC/DC, 2 LDOs, I2C interface in QFN-48
TPS40222	1250	1.6	Buck	4.5	8	1.6A, 1.25-MHz Buck Converter in a 3 mm SON Package
TPS60500	1200	0.25	Buck	1.8	6.5	250-mA Adjustable (0.8V-3.3V) High-Efficiency Step-Down Charge Pump



TI Power Devices >1MHz

Part Number	Max. Freq.	I _{out}	Topology	V _{in} (min)	V _{in} (max)	Description
TPS40140	1000	-	Sync. Buck	4.5	15	Dual Channel, Stackable DC/DC Controller
TPS65120	4000		Boost	2.5	5.5	Single-Inductor, Quad-Output Supply for Small Form Factor TFT Display in QFN-16, 3.3-V LDO, Auto-Seg
TPS65140	2100	0.02	Boost, Inverter	2.7	5.5	Triple-Channel, 2.1-A Switch Boost Converter for large LCD displays w/ Power Good in QFN-24
UCC2880x	2000	-	Buck, Boost, Flyback, Forward			High Speed Voltage Mode Pulse Width Modulator
UCC29421	2000	1	Boost, Flyback, SEPIC	1.5	8	High Frequency, Multimode Synchronous Controller
UCC29422	2000	1	Boost, Flyback, SEPIC	1.5	8	High Frequency, Multimode Synchronous Controller
TPS43000	2000	1.25	Boost, Buck, Flyback, SEPIC	1.8	9	Multi-Topology (buck, boost, sepic) High Frequency DC/DC Controller
TPS65130	1500		Boost, Inverter	2.7	5.5	Adjustable, Dual Output, Positive & Negative 800-mA Switch Boost DC/DC 4x4 QFN-24 for OLED,TFT,CCD
TPS65100	1500	0.35	Boost, Inverter	2.7	6	Triple Output TFT LCD Supply w/VCOM Buffer
TPS65105	1500	0.35	Boost, Inverter	2.7	6	TPS65100, TPS65105 - (TFT) LCD Supply with Vcom Buffer
TPS61070	1440	0.15	Boost	0.9	5.5	Adjustable, 600-mA Switch, 90% Efficient PFM/PWM Boost Converter in ThinSOT-23
TPS63700	1380	0.36	Inverter	2.7	5.5	Adjustable, -15V Output Inverting DC/DC Converter in 3x3 QFN
TPS60230	1250	0.125	Boost	2.7	6.5	5-Channel, Current-regulated 125-mA Charge Pump for White LED Backlight in 3x3 QFN



Summary

Minimum on time:

- Vout is limited by the controllable on time and frequency
- Take the input voltage and switching frequency tolerances into consideration
- Check to see if the current limit circuit will respond fast enough

Size

- Switching frequency from 350kHz to 1.6 MHz
 - 50% reduction in filter size, saving only 45mm²
- Switching frequency from 350kHz to 700kHz
 - 25% reduction in filter size, saving only 21mm²
- Switching frequency from 350kHz to 1.6MHz
 - Board area from 260mm² to 100mm², 35% saving on board area
- More heat in a smaller area



Summary

Efficiency

- Efficiency decreases as switching frequency increases mainly due to FET switching losses
- More copper, board area or additional heat-sinking may be needed

Performance

- Higher switching frequency allows for a higher cross over frequency and a faster transient response. Is this necessary?
- High frequency devices are more expensive. Make sure you really need the benefits and can handle the trade offs (heat and efficiency)



Summary

Noise - EMI

- Sometimes an application specific frequency band must be avoided (AM band, ADSL, IF, etc...)
- Alternative - Synchronize the frequency in an area of the band that is not so sensitive
- This topic will be reserved for future study



Jedi Mind Tricks



You must use a higher switching frequency to save space! This new 4MHz part is the ultimate power in the universe – I suggest you use it.

Your sorcerous ways have failed to conjure up the minimum on-time specification in the datasheet. I may save some board space, but there is more heat in that smaller area. The efficiency hit is unacceptable. The transient response is impressive, but not necessary.





***Thanks For Considering
Texas Instruments!!***