

Application Report SWRA577-October 2017

# XWR1xxx Power Management Optimizations – Low Cost LC Filter Solution

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## ABSTRACT

This application report discusses the Power supply ripple and noise specifications, reference solutions and introduces its trade off, an LC filter-based low cost solution.

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## 1 Introduction

XWR1xx is a family of Texas Instrument's mmWave Radar sensor devices with RFCMOS technology. These devices are intended for the automotive and industrial applications. The devices are powered by four voltage rails, namely 3.3 V, 1.2 V, 1.8 V and 1.0 V.

# 2 Power Supply Ripple and Noise Specifications

Out of the four Power supply rails mentioned above, the 1.0 V and the 1.8 V supplies are sensitive to the supply ripple and noise because these supplies feed the critical blocks in the device like PLL, baseband ADC, synthesizer, and so forth. For more details on the power supply rail and the logic that it feeds in the device, see the device-specific data sheet. Table 1 and Table 2 provide the ripple and noise spec for 1.0 V

SI. Number	Frequency (KHz)	XWR1xx Supply Ripple (µVrms)
1	17.1875	
2	34.375	
3	68.75	
4	137.5	
5	275	
6	550	
7	1100	
8	2200	
9	4400	35.48133892
10	6600	

Table 1. XWR1xx Supply Ripple (µVrms)

## Table 2. XWR1xx Noise Spectral Density (µVrms/RtHz)

SI. Number	Frequency (KHz)	XWR1xx Noise Spectral Density (µVrms/RtHz)
1	17.1875	0.01
2	34.375	0.01
3	68.75	0.01
4	137.5	0.015
5	275	0.02
6	550	0.02
7	1100	0.009
8	2200	0.002
9	4400	0.05
10	6600	0.002

Table 3 and Table 4 provide the ripple and noise spec for 1.8 V.

SI Number	Frequency (KHz)	XWR1xxx Supply Ripple (µVrms)
1	17.1875	
2	34.375	
3	68.75	
4	137.5	
5	275	
6	550	
7	1100	
8	2200	
9	4400	35.48133892
10	6600	

## Table 3. XWR1xxx Supply Ripple (µVrms)

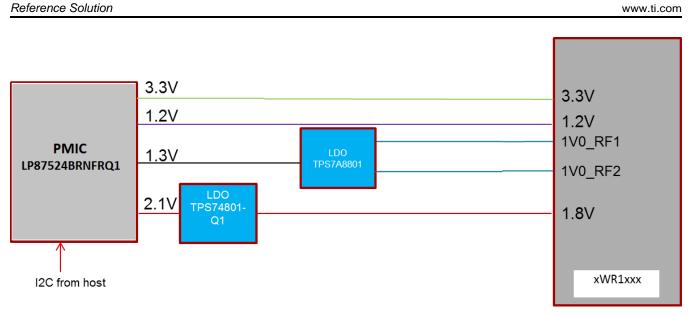
# Table 4. XWR1xxx Noise Spectral Density (µVrms/RtHz)

SI Number	Frequency (KHz)	XWR1xxx Noise Spectral Density (µVrms/RtHz)
1	17.1875	0.08
2	34.375	0.07
3	68.75	0.07
4	137.5	0.07
5	275	0.07
6	550	0.07
7	1100	0.07
8	2200	0.07
9	4400	0.07
10	6600	0.07

## 3 Reference Solution

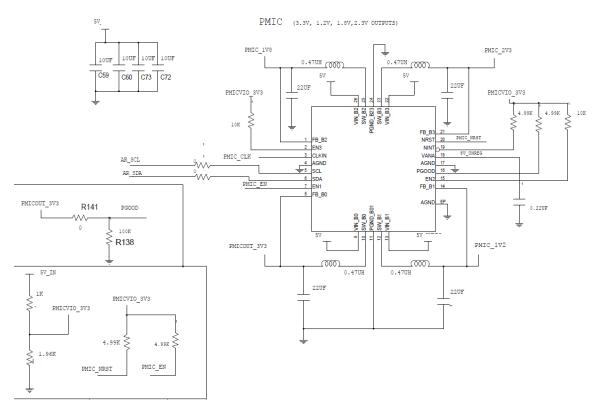
TI recommends the reference solution with the PMIC and the LDOs as shown in Figure 1, which is also incorporated in the XWR1xxx EVMs. The reference solution meets these specifications. The XWR1xx device would expect 1.0 V to be fed on the H5, G5, J5, D2 and C2 pins. The PMIC needs to be reconfigured for the Buck outputs shown in Figure 1 using the Inter-Integrated Circuit (I2C) interface from the host. Initially during the power up, the buck outputs would be 3.3 V, 1.2 V, 1.3 V and 2.1 V. Using I2C interface, the buck outputs needs to be reconfigured as shown in Figure 1 before the nRESET of XWR1xx is released.

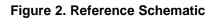






The above reference solution consists of the LP87524BRNFRQ1 PMIC with the switching frequency localized at 4 MHz, so that the fundamental and the harmonics could easily be filtered out during RADAR data post processing. The reference schematic is shown in Figure 2.







## 4 Low Cost LC Filter Solution

For the cost sensitive use cases, a low cost LC filter (Ferrite bead + Device Decoupling capacitor) based solution could be used, which would effectively replace the LDOs on the 1.8 V and 1.0 V rails. This approach would have performance and the system level trade-off.

Figure 3 shows the Power management scheme.

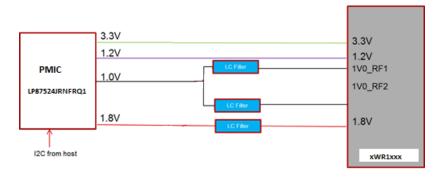


Figure 3. Power Management Scheme With LC filter

NOTE: The capacitors shown above in the LC filter are the device decoupling capacitors.

The recommended Ferrite bead components are shown in Table 5.

LC Filter	Inductor Value (µH)	DC Resistance (mΩ)	Impedance @ 100 MHz (Ω)	Size (inches)	Pole Frequencies w.r.t. 1V Rail Decaps/1.8V Rail Decaps (KHz)	DC Current (A)	Theoretical Rejection Offered by the Filter (dB)	Manufacture r Part Number
Ferrite Bead	0.1909	25	120	0603	113.9	3	64	BLM18KG12 1TH1

# 4.1 LDO vs LC Filter Scheme Comparison

#### 4.1.1 Waveguide Loopback Tests

provides the summary of comparison between LDO based and LC filter based implementation. Two consecutive chirps have been analyzed with 10  $\mu$ Sec and 100  $\mu$ Sec of idle time and the below chirp configuration.

Table 6 provides the sensor configuration for the below tests.

#### Table 6. Sensor Configuration

Parameter	Value
Start frequency (GHz)	77
Frequency slope (MHz)	35.003
Tx start time (µsec)	0
ADC start time (µsec)	5
ADC samples	1024
Sample rate (Kbps)	10000
Ramp end time (µsec)	110
Rx gain	33

XWR1xxx Power Management Optimizations - Low Cost LC Filter Solution



Low Cost LC Filter Solution

#### 4.1.2 Spur/Noise Floor Level

The measurements shown in Table 7 are done with TX to RX loopback with Tx Back-Off=0 and Complex Rx gain=33dB.

## Table 7. Spur/Noise Level Measurements With Tx to Rx Waveguide Loopback

PM Scheme	Idle Channel Noise Floor (Rx-alone) at the ADC Output (dBFs/Hz)	Amplitude Level of PMIC Ripple Frequency Spur (4.05M-4.17M) Seen at the ADC Output (dBFs)	(Tx+Rx) SNR dBc/Hz	Amplitude Level of PMIC Ripple Frequency Spur (4.05M-4.17M) Seen at the ADC Output (dBFs)		
	Additive (Rx1 - alone)		Loop back (Tx2-Rx1)			
LDO Scheme	-138.80	Not seen	-118.74	Not seen (less than noise floor)		
LC Filter Scheme	-138.27	Not seen	-120.6	-104		



# 4.1.3 Voltage Transient Behavior

		Vo	oltage Setting Pa	rameters on Chir	p 1	Volta	age Setting Paran	neters on Chirp 2	2	Steady State DC	Calculated IR Drop (mV)
PM Scheme	XWR1xx Supply Rail		oot Voltage nV)		oot Period ıs)	Undershoot (mV)			oot Period Is)	Value (mV) at the Input of XWR1642 Rail	(difference between steady state DC and actual input voltage)
	Idle time (µs)	10	100	10	100	10	100	10	100	10	10/100
	RF1_1V0	55.6	79.0	4.4	6.7	67.0	214.5	5.0	10.0	982.0	17
LDO	RF2_1V0	33.9	34.6	7.2	11.1	42.0	208.3	5.6	12.2	982.0	17
	CLK_1V8	20.0	20.0	1.6	2.5	24.0	20.0	2.4	2.6	1760.0	35
	RF1_1V0	59.0	51.2	6.2	6.1	59.0	51.2	4.4	5.0	949.5	49.5
LC Filter	RF2_1V0	44.1	47.0	5.9	5.5	44.1	41.1	4.3	5.7	944.6	54.4
	CLK_1V8	30.5	17.9	3.1	4.0	30.5	17.9	3.5	3.5	1737.0	58

# Table 8. Voltage Transient Behavior

## 4.2 System Tests

# 4.2.1 Sensor Configuration

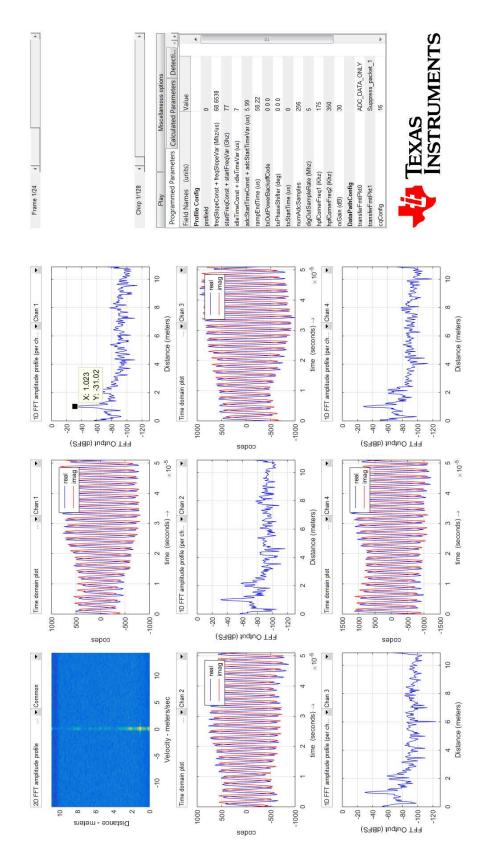
Parameter	Value	Comments
Start frequency (GHz)	77	
Frequency slope (MHz)	68.65	
Tx start time (uSec)	0	
ADC start time (uSec)	5.99	
Idle time (uSec)	12	Inter Chirp power saving enabled for idle time+Tx start time >10usec
ADC samples	256	
Sample rate (Kbps)	5000	
Ramp end time	58.22	
Rx gain	48	

## Table 9. Sensor Configuration

## 4.2.2 System Test With Static Object

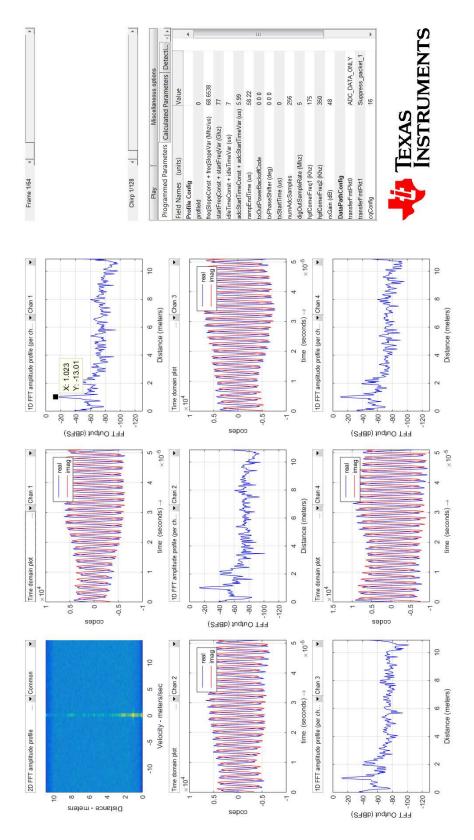
The test involves detecting an object at approximately 1m from the sensor. Both captures with LDO and LC filter schemes are shown below. No major degradation in the signal power is detected as shown below.





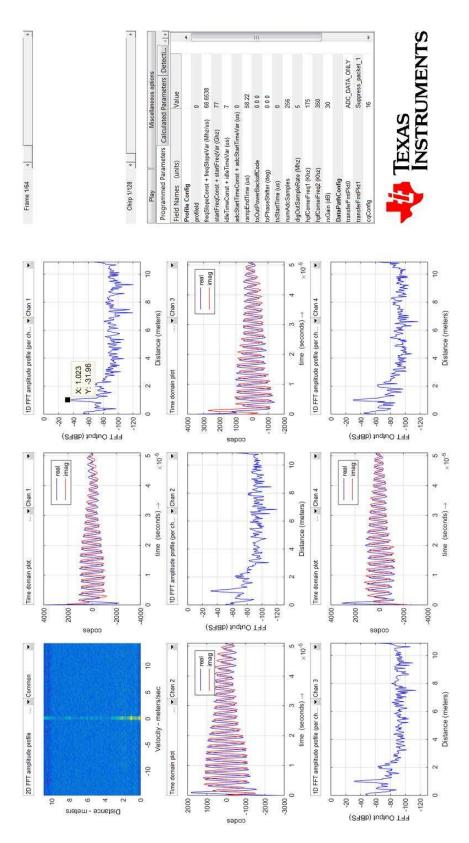


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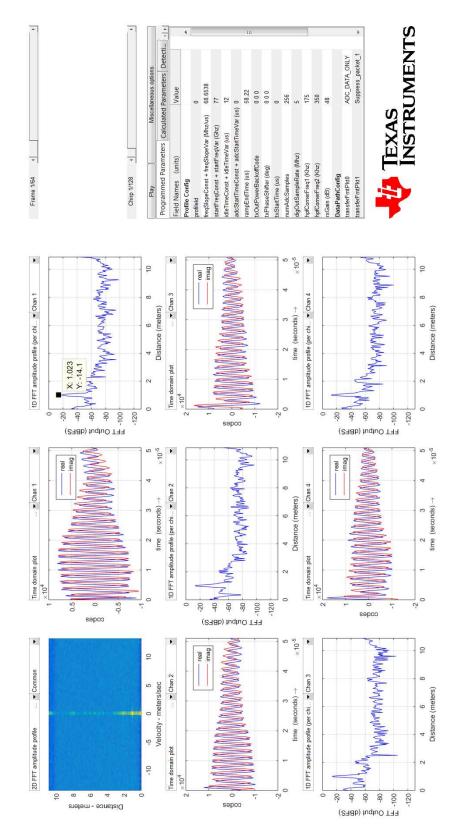


Figure 7. Capture With LC Filter Scheme, RX Gain-30dB

PM Scheme	RX Gain(dB)	SNR(dB)-RBW 152.6Hz
LDO	30	81.93
	48	83.9
LC Filter	30	79.6
	48	81.9

## 4.2.3 Spur/Noise Floor Level

For Spur level measurements, a continuous tone at 77 GHz is transmitted and the received signal is analyzed with 524288 samples for the presence of the PMIC switching frequency spur at ~4 MHz. The Rx gain is set at 48dB with an observation that PMIC spur level tracks the Rx gain.



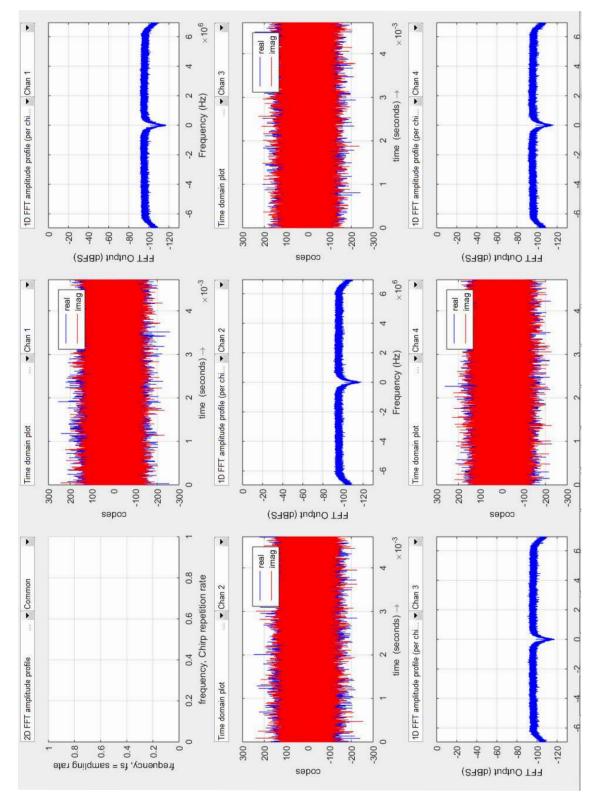


Figure 8. LDO Scheme – Spur Level

NOTE: No PMIC switching Frequency (approximately 4 MHz) Spur seen.



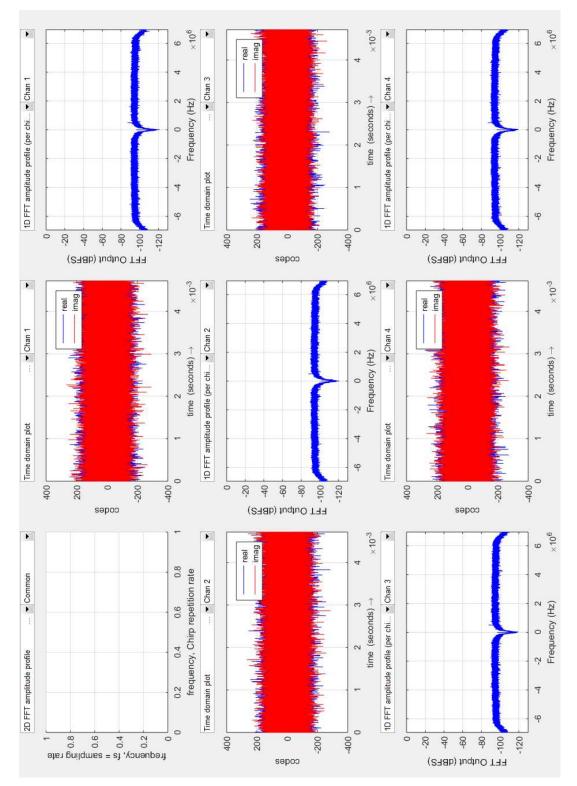


Figure 9. LDO Scheme - Noise Floor With Tx –OFF



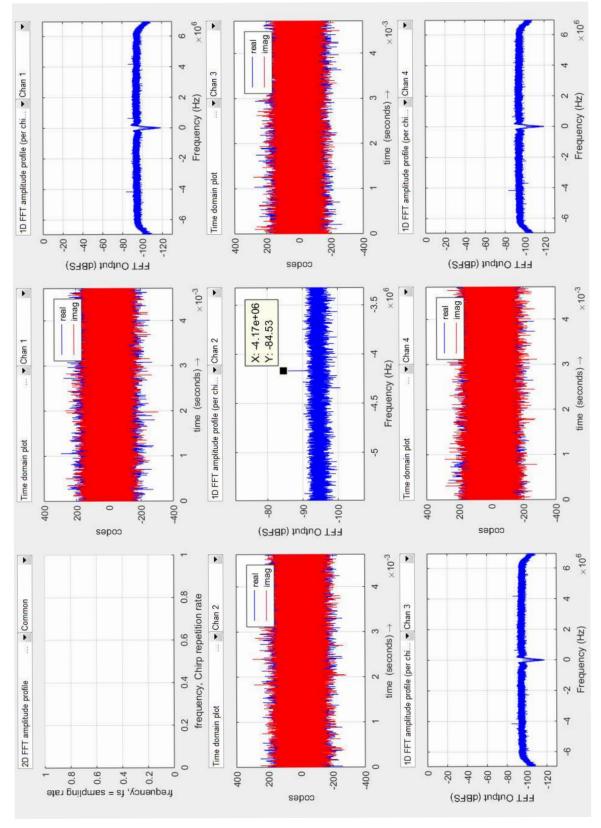
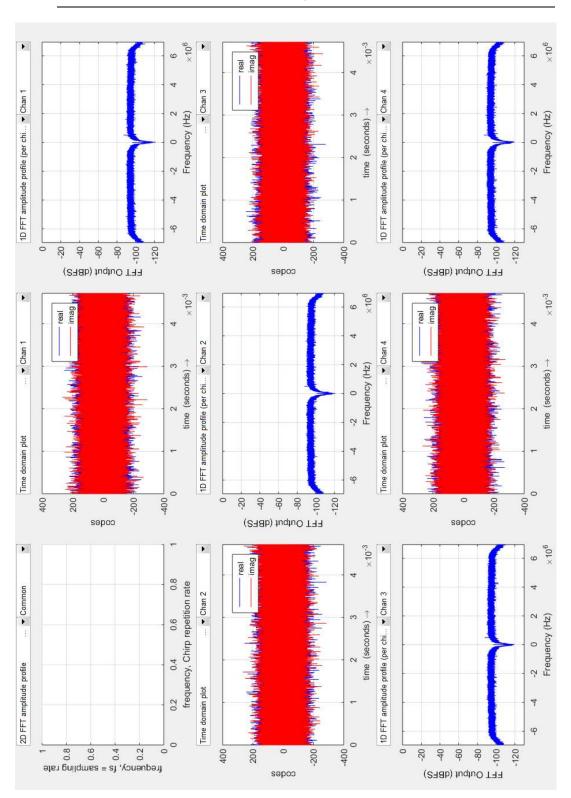


Figure 10. LC Filter Scheme – Spur Level





NOTE: PMIC spur is observed at -84.53 dBFS at RX gain of 48dB.

Figure 11. LC Filter Scheme - Noise Floor With Tx –OFF



Summary

## 5 Summary

This application report proposes two power management schemes for XWR1xxx devices. Section 4 puts forth an optimal scheme with respect to bill of material and power dissipation, using LC filters. Section 3 explains a scheme using LDOs for achieving better power supply ripple/noise rejection. The LC Filter solution scores better on the Cost and overall System Power saving front in comparison to the LDO scheme."

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