



TAS5614LA 150W 立体声/300W 单声道 PurePath™ HD 数字输入 D 类功率级

1 特性

- PurePath™ HD 集成反馈提供:
 - 1W 功率/4Ω 负载条件下的总谐波失真 (THD) 为 0.03%
 - 电源抑制比 (PSRR) > 65dB (无输入信号)
 - (A 加权) 信噪比 (SNR) > 105dB
- 用于控制 G 类电源的预钳位输出
- 通过使用 60mΩ 输出金属氧化物半导体场效应晶体管 (MOSFET) 减小了散热器体积, 满输出功率时效率 > 90%
- 总谐波失真+噪声 (THD+N) 为 10% 时的输出功率
 - 150W/4Ω, 桥接负载 (BTL) 立体声配置
 - 300W/2Ω, 并行桥接负载 (PBTL) 单声道配置
- THD+N 为 1% 时的输出功率
 - 125W/4Ω, 桥接负载 (BTL) 立体声配置
 - 65W/8Ω, 桥接负载 (BTL) 立体声配置
- 启动时无喀哒声和噼啪声
- 采用具有错误报告功能的自我保护设计, 包含欠压保护 (UVP)、过热保护和短路保护
- 采用推荐的系统设计时, 符合电磁干扰 (EMI) 标准
- 采用 44 引脚散热薄型小外形尺寸 (HTSSOP) (DDV) 封装, 减小了电路板尺寸

2 应用

- 蓝光碟™ 和 DVD 接收器
- 高功率条形音响
- 有源超低音扬声器和有源扬声器
- 微型 Combo 系统

3 说明

TAS5614LA 器件是一款基于 TAS5614LA 的功能优化 D 类功率放大器。

TAS5614LA 使用大型金属氧化物半导体场效应晶体管 (MOSFET) 提升功率效率, 并采用新型栅极驱动方案降低空闲状态下和输出信号较低时的损耗, 从而减小散热器尺寸。

该器件可使用独特的预钳位输出信号来控制 G 类电源。这一优势与 TAS5614LA 的低空闲损耗和高功率效率相结合, 可实现行业领先水平的效率, 从而确保构建超级“绿色”系统。

TAS5614LA 使用恒定电压增益。内部匹配增益电阻器确保了一个高电源抑制比, 使得输出电压只取决于音频输入电压并避免了任何电源的人工缺陷。

TAS5614LA 的高集成度使得放大器易于使用; 另外, 使用 TI 的参考原理图和 PCB 布局缩短了设计时间。

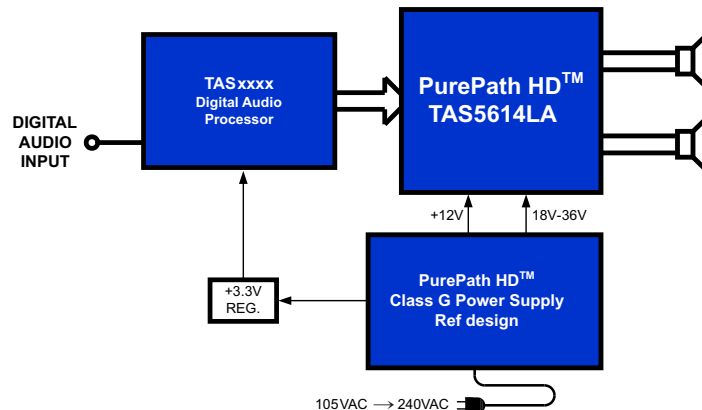
TAS5614LA 采用节省空间的表面贴装 44 引脚 HTSSOP 封装。

器件信息⁽¹⁾

器件型号	封装	封装尺寸 (标称值)
TAS5614LA	HTSSOP (44)	14.00mm x 6.10mm

(1) 要了解所有可用封装, 请见数据表末尾的可订购产品附录。

TAS5614LA 典型应用框图



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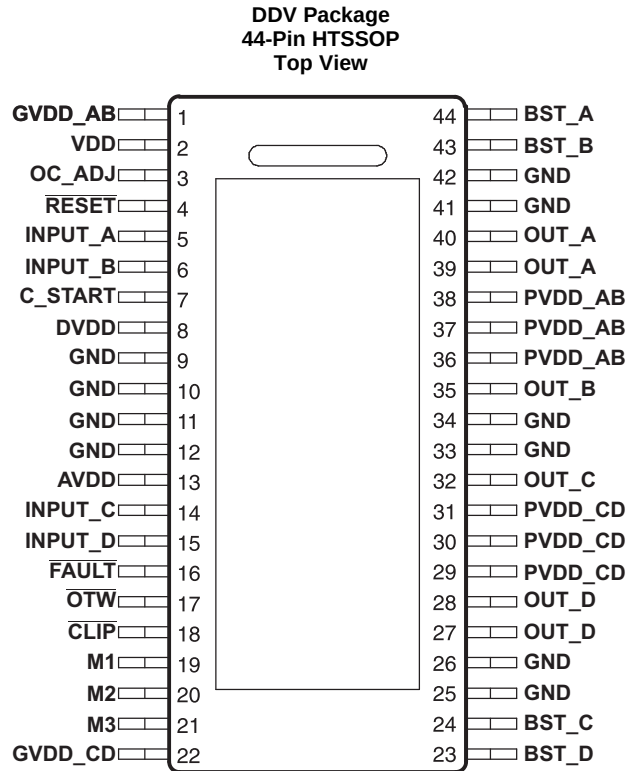
4 修订历史记录

Changes from Original (May 2012) to Revision A

Page

- 已添加 引脚配置和功能部分, ESD 额定值表, 特性描述部分, 器件功能模式, 应用和实施部分, 电源相关建议部分, 布局部分, 器件和文档支持部分以及机械、封装和可订购信息部分 **1**

5 Pin Configuration and Functions



Pin Functions

PIN		I/O/P ⁽¹⁾	DESCRIPTION
NAME	NO.		
AVDD	13	P	Internal voltage regulator, analog section
BST_A	44	P	Bootstrap pin, A-side
BST_B	43	P	Bootstrap pin, B-side
BST_C	24	P	Bootstrap pin, C-side
BST_D	23	P	Bootstrap pin, D-side
CLIP	18	O	Clipping warning, open drain, active low
C_START	7	O	Start-up ramp
DVDD	8	P	Internal voltage regulator, digital section
FAULT	16	O	Shutdown signal, open drain, active low
GND	9, 10, 11, 12, 25, 26, 33, 34, 41, 42	P	Ground
GVDD_AB	1	P	Gate-drive voltage supply, AB-side
GVDD_CD	22	P	Gate-drive voltage supply, CD-side
INPUT_A	5	I	PWM input signal for half-bridge A
INPUT_B	6	I	PWM input signal for half-bridge B
INPUT_C	14	I	PWM input signal for half-bridge C
INPUT_D	15	I	PWM input signal for half-bridge D
M1	19	I	Mode selection 1 (LSB)
M2	20	I	Mode selection 2
M3	21	I	Mode selection 3 (MSB)
OC_ADJ	3	O	Overcurrent threshold programming pin

(1) I = Input, O = Output, P = Power

Pin Functions (continued)

PIN		I/O/P ⁽¹⁾	DESCRIPTION
NAME	NO.		
$\overline{\text{OTW}}$	17	O	Overtemperature warning, open drain, active low
OUT_A	39, 40	O	Output, half-bridge A
OUT_B	35	O	Output, half-bridge B
OUT_C	32	O	Output, half-bridge C
OUT_D	27, 28	O	Output, half-bridge D
PVDD_AB	36, 37, 38	P	PVDD supply for half-bridge A and B
PVDD_CD	29, 30, 31	P	PVDD supply for half-bridge C and D
$\overline{\text{RESET}}$	4	I	Device reset input, active low
VDD	2	P	Input power supply
PowerPAD™	–	P	Ground, connect to grounded heat sink

6 Specifications

6.1 Absolute Maximum Ratings

 over operating free-air temperature range unless otherwise noted ⁽¹⁾

	MIN	MAX	UNIT
VDD to GND, GVDD_X ⁽²⁾ to GND	–0.3	13.2	V
PVDD_X ⁽²⁾ to GND ⁽³⁾ , OUT_X to GND ⁽³⁾ , BST_X to GVDD_X ⁽²⁾⁽³⁾	–0.3	50	V
BST_X to GND ⁽³⁾⁽⁴⁾	–0.3	62.5	V
DVDD to GND	–0.3	4.2	V
AVDD to GND	–0.3	8.5	V
OC_ADJ, M1, M2, M3, C_START, INPUT_X to GND	–0.3	4.2	V
$\overline{\text{RESET}}$, $\overline{\text{FAULT}}$, $\overline{\text{OTW}}$, $\overline{\text{CLIP}}$ to GND	–0.3	4.2	V
Maximum continuous sink current ($\overline{\text{FAULT}}$, $\overline{\text{OTW}}$, $\overline{\text{CLIP}}$)		9	mA
Maximum operating junction temperature, T _J	0	150	°C
Lead temperature		260	°C
Storage temperature, T _{stg}	–40	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) GVDD_X and PVDD_X represents a full bridge gate drive or power supply. GVDD_X is GVDD_AB or GVDD_CD, PVDD_X is PVDD_AB or PVDD_CD
- (3) These voltages represents the DC voltage + peak AC waveform measured at the pin of the device in all conditions.
- (4) Maximum BST_X to GND voltage is the sum of maximum PVDD to GND and GVDD to GND voltages minus a diode drop.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	2000
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	500

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
PVDD_X	Full-bridge supply	DC supply voltage	12	36	38	V
GVDD_X	Supply for logic regulators and gate-drive circuitry	DC supply voltage	10.8	12	13.2	V
VDD	Digital regulator supply voltage	DC supply voltage	10.8	12	13.2	V
R _L	Load impedance	BTL	3.0	4.0		Ω
		SE	1.5	3.0		
		PBTL	1.5	2.0		
L _{OUTPUT}	Output filter inductance	Minimum inductance at overcurrent limit, including inductor tolerance, temperature and possible inductor saturation	5			μH
F _{PWM}	PWM frame rate		352	384	500	kHz
C _{PVDD}	PVDD close decoupling capacitors		0.44	1		μF
C _{START}	Start-up ramp capacitor	BTL and PBTL configuration		100		nF
		SE and 1xBTL+2xSE configuration		1		μF
R _{OC}	Overcurrent programming resistor	Resistor tolerance = 5%	24		33	kΩ
R _{OC_LATCHED}	Overcurrent programming resistor	Resistor tolerance = 5%	47	62	68	kΩ
T _J	Junction temperature		0		125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TAS5614LA	UNIT
		DDV (HTSSOP)	
		44 PINS	
R _{θJH}	Junction-to-heat sink thermal resistance	2.3	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	0.8	
R _{θJB}	Junction-to-board thermal resistance	2.1	
Ψ _{JT}	Junction-to-top characterization parameter	0.8	
Ψ _{JB}	Junction-to-board characterization parameter	2.1	
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	n/a	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

PVDD_X = 36 V, GVDD_X = 12 V, VDD = 12 V, T_C (Case temperature) = 75°C, f_S = 384 kHz, unless otherwise specified.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INTERNAL VOLTAGE REGULATOR AND CURRENT CONSUMPTION						
DVDD	Voltage regulator, only used as a reference node	VDD = 12 V	3.0	3.3	3.6	V
AVDD	Voltage regulator, only used as a reference node	VDD = 12 V		7.8		V
I _{VDD}	VDD supply current	Operating, 50% duty cycle		20		mA
		Idle, reset mode		20		
I _{GVDD_X}	Gate-supply current per full-bridge	50% duty cycle		9		mA
		Reset mode		2		
I _{PVDD_X}	Full-bridge idle current	50% duty cycle without load		23		mA
		RESET low		1.9		
		VDD and GVDD_X at 0V		0.35		
OUTPUT-STAGE MOSFETs						
R _{DS(on), LS}	Drain-to-source resistance, low side (LS)	T _J = 25°C, excludes metalization resistance, GVDD = 12 V		60	100	mΩ
R _{DS(on), HS}	Drain-to-source resistance, high side (HS)			60	100	mΩ
I/O PROTECTION						
V _{uwp,GVDD}	Undervoltage protection limit, GVDD_X			8.5		V
V _{uwp,GVDD, hyst} ⁽¹⁾				0.7		V
V _{uwp,VDD}	Undervoltage protection limit, VDD			8.5		V
V _{uwp,VDD, hyst} ⁽¹⁾				0.7		V
V _{uwp,PVDD}	Undervoltage protection limit, PVDD_X			8.5		V
V _{uwp,PVDD,hyst} ⁽¹⁾				0.7		V
OTW ⁽¹⁾	Overtemperature warning		115	125	135	°C
OTW _{hyst} ⁽¹⁾	Temperature drop needed below OTW temperature for OTW to be inactive after OTW event.			25		°C
OTE ⁽¹⁾	Overtemperature error		145	155	165	°C
OTE-OTW _{differential} ⁽¹⁾	OTE-OTW differential			30		°C
OTE _{HYST} ⁽¹⁾	A device reset is needed to clear FAULT after an OTE event			25		°C
OLPC	Overload protection counter	f _{PWM} = 384 kHz		2.6		ms
I _{OC}	Overcurrent limit protection	Resistor – programmable, nominal peak current in 1-Ω load, ROC = 24 kΩ		15		A
I _{OC_LATCHED}	Overcurrent limit protection, latched	Resistor – programmable, nominal peak current in 1-Ω load, ROC = 62 kΩ		15		A
I _{OCT}	Overcurrent response time	Time from application of short condition to Hi-Z of affected half bridge		150		ns
I _{PD}	Internal pulldown resistor at output of each half bridge	Connected when RESET is active to provide bootstrap charge. Not used in SE mode.		3		mA
STATIC DIGITAL SPECIFICATIONS						
V _{IH}	High level input voltage	INPUT_X, M1, M2, M3, RESET	1.9			V
V _{IL}	Low level input voltage				0.8	V
LEAKAGE	Input leakage current				100	μA
OTW / SHUTDOWN (FAULT)						
R _{INT_PU}	Internal pullup resistance, OTW, CLIP, FAULT to DVDD		20	26	33	kΩ
V _{OH}	High level output voltage	Internal pullup resistor	3	3.3	3.6	V
V _{OL}	Low level output voltage	I _O = 4 mA		200	500	mV
FANOUT	Device fanout OTW, FAULT, CLIP	No external pullup		30		devices

(1) Specified by design.

6.6 Audio Specification Stereo (BTL)

Audio performance is recorded as a chipset consisting of a PWM Processor (modulation index limited to 97.7%) and a TAS5614LA power stage with PCB and system configurations in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 36 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 384\text{ kHz}$, $R_{OC} = 24\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
P _O Power output per channel	$R_L = 4\ \Omega$, 10% THD+N		150		W
	$R_L = 4\ \Omega$, 1% THD+N		125		
THD+N Total harmonic distortion + noise	1-W, 1-kHz signal		0.03%		
V _n Output integrated noise	A-weighted, AES17 measuring filter		180		μV
V _{OS} Output offset voltage	No signal		10	20	mV
SNR Signal-to-noise ratio ⁽¹⁾	A-weighted, AES17 measuring filter		105		dB
DNR Dynamic range	A-weighted, –60 dBFS (rel 1% THD+N)		105		dB
P _{idle} Power dissipation due to Idle losses (IPVDD_X)	P _O = 0, channels switching ⁽²⁾		1.6		W

(1) SNR is calculated relative to 1% THD-N output level.

(2) Actual system idle losses also are affected by core losses of output inductors.

6.7 Audio Specification 4 Channels (SE)

Audio performance is recorded as a chipset consisting of a PWM Processor (modulation index limited to 97.7%) and a TAS5614LA power stage with PCB and system configurations in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 36 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 384\text{ kHz}$, $R_{OC} = 24\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, $C_{DCB} = 470\ \mu\text{F}$, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
P _O Power output per channel	$R_L = 3\ \Omega$, 10% THD+N		50		W
	$R_L = 3\ \Omega$, 1% THD+N		42		
THD+N Total harmonic distortion + noise	1-W, 1-kHz signal		0.025%		
V _n Output integrated noise	A-weighted, AES17 measuring filter		180		μV
SNR Signal-to-noise ratio ⁽¹⁾	A-weighted, AES17 measuring filter		102		dB
DNR Dynamic range	A-weighted, –60 dBFS (rel 1% THD+N)		102		dB
P _{idle} Power dissipation due to Idle losses (IPVDD_X)	P _O = 0, channel switching ⁽²⁾		1.6		W

(1) SNR is calculated relative to 1% THD-N output level.

(2) Actual system idle losses also are affected by core losses of output inductors.

6.8 Audio Specification Mono (PBTL)

Audio performance is recorded as a chipset consisting of a PWM Processor (modulation index limited to 97.7%) and a TAS5614LA power stage with PCB and system configurations in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 36 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 384\text{ kHz}$, $R_{OC} = 24\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P _O	Power output per channel	$R_L = 2\ \Omega$, 10%, THD+N		300		W
		$R_L = 3\ \Omega$, 10% THD+N		200		
		$R_L = 4\ \Omega$, 10% THD+N		160		
		$R_L = 2\ \Omega$, 1% THD+N		250		
		$R_L = 3\ \Omega$, 1% THD+N		160		
		$R_L = 4\ \Omega$, 1% THD+N		130		
THD+N	Total harmonic distortion + noise	1-W, 1-kHz signal		0.025%		
V _n	Output integrated noise	A-weighted, AES17 measuring filter		180		μV
V _{OS}	Output offset voltage	No signal		10	20	mV
SNR	Signal to noise ratio ⁽¹⁾	A-weighted, AES17 measuring filter		105		dB
DNR	Dynamic range	A-weighted, –60 dBFS (rel 1% THD)		105		dB
P _{idle}	Power dissipation due to idle losses (IPVDD_X)	P _O = 0, All channels switching ⁽²⁾		1.6		W

(1) SNR is calculated relative to 1% THD-N output level.

(2) Actual system idle losses are affected by core losses of output inductors.

6.9 Typical Characteristics

6.9.1 BTL Configuration

Measurement conditions are: 1 kHz, PVDD_X = 36 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 384\ \text{kHz}$, $R_{OC} = 24\ \text{k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, 20-Hz to 20-kHz BW (AES17 low-pass filter), unless otherwise noted.

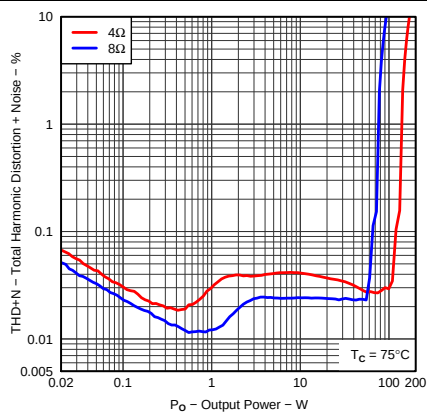


图 1. Total Harmonic + Noise vs Output Power, 1 kHz

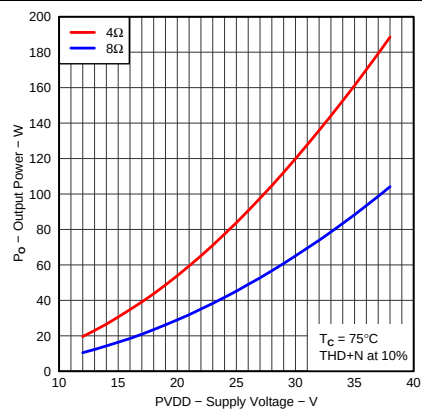


图 2. Output Power vs Supply Voltage vs Distortion + Noise = 10%

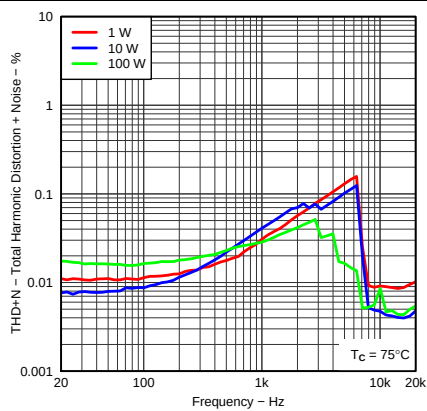


图 3. Total Harmonic Distortion + Noise vs Frequency, 4 Ω

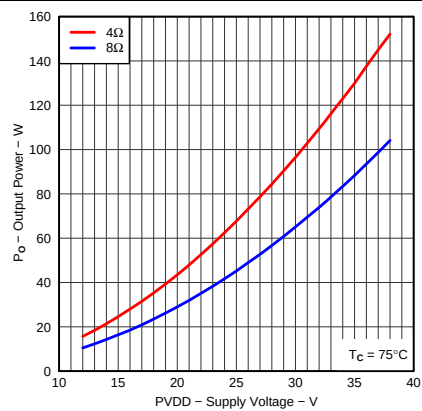


图 4. Output Power vs Supply Voltage, vs Distortion + Noise = 1%

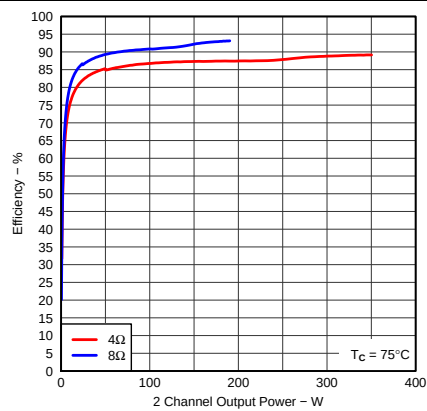


图 5. System Efficiency vs Output Power

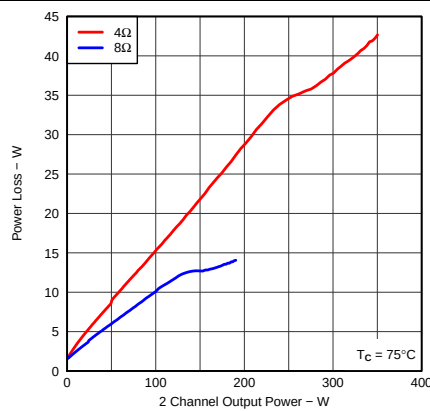


图 6. System Power Loss vs Output Power

BTL Configuration (接下页)

Measurement conditions are: 1 kHz, PVDD_X = 36 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 384\ \text{kHz}$, $R_{OC} = 24\ \text{k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, 20-Hz to 20-kHz BW (AES17 low-pass filter), unless otherwise noted.

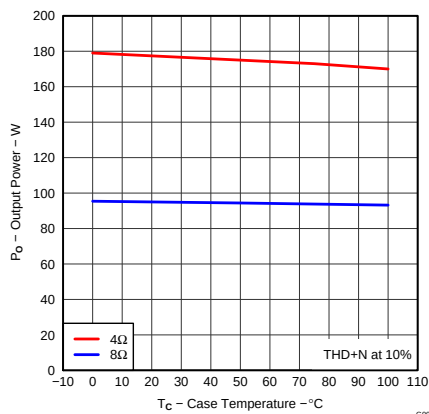


图 7. Output Power vs Temperature

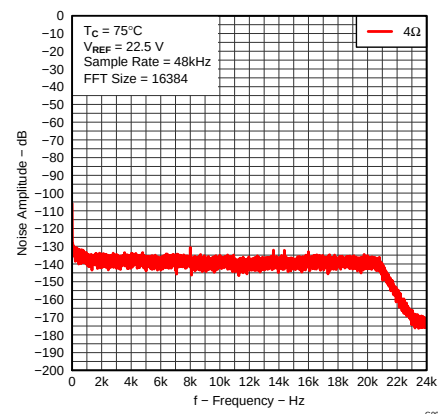


图 8. Noise Amplitude vs Frequency

6.9.2 SE Configuration

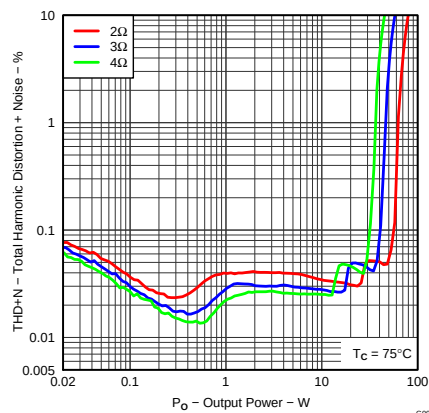


图 9. Total Harmonic Distortion + Noise vs Output Power

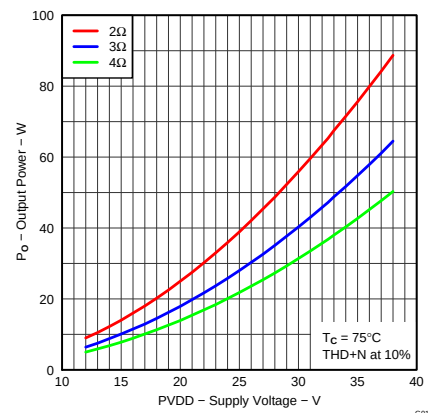


图 10. Output Power vs Supply Voltage

6.9.3 PBTL Configuration

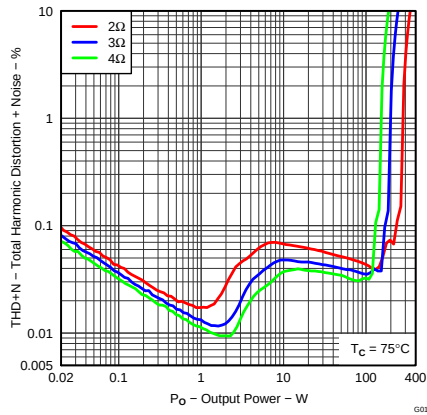


图 11. Total Harmonic Distortion + Noise vs Output Power

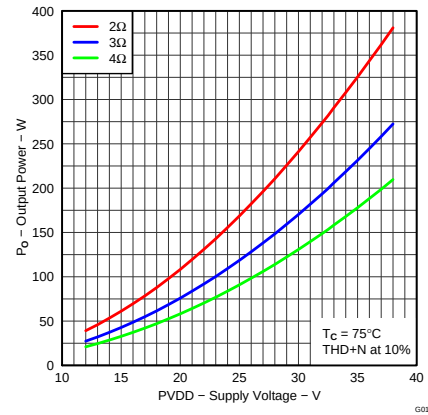


图 12. Output Power vs Supply Voltage

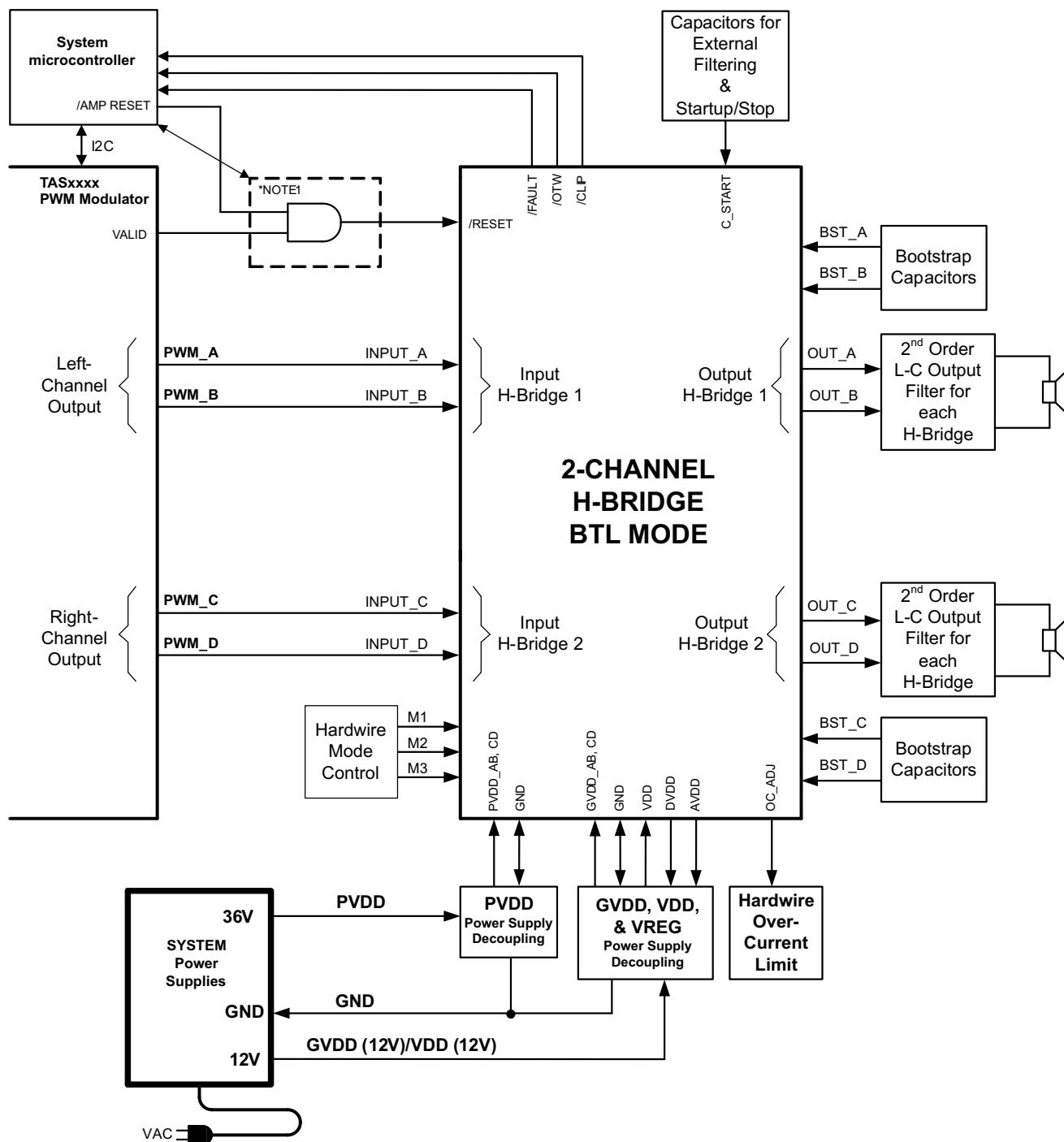
7 Detailed Description

7.1 Overview

TAS5614LA is a PWM input, audio PWM (class-D) amplifier. The output of the TAS5614LA can be configured for single-ended, BTL (Bridge-Tied Load) or parallel BTL (PBTL) output. It requires two rails for power supply, PVDD and 12 V (GVDD and VDD).

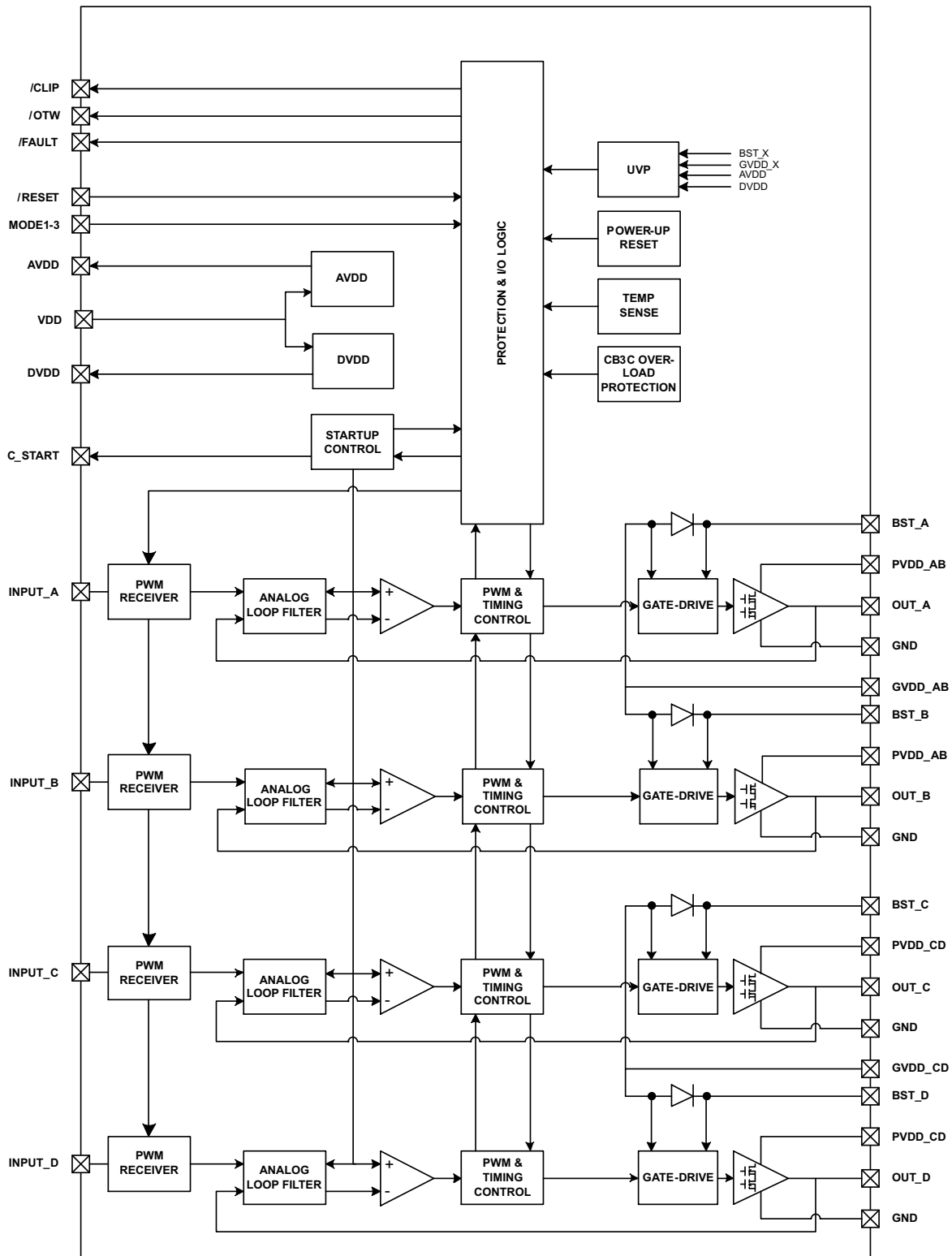
[Functional Block Diagrams](#) shows typical connections for BTL outputs. Detailed schematic can be viewed in TAS5614LA EVM user's guide ([SLAU375](#)).

7.2 Functional Block Diagrams



(1) Logic AND is inside or outside the microprocessor.

图 13. Typical System Block Diagram

Functional Block Diagrams (接下页)

图 14. Functional Block Diagram

7.3 Feature Description

7.3.1 Power Supplies

To facilitate system design, the TAS5614LA needs only a 12-V supply in addition to the (typical) 36-V power-stage supply. An internal voltage regulator provides suitable voltage levels for the digital and low-voltage analog circuitry. Additionally, all circuitry requiring a floating voltage supply, for example, the high-side gate drive, is accommodated by built-in bootstrap circuitry requiring only an external capacitor for each half-bridge.

To provide outstanding electrical and acoustical characteristics, the PWM signal path including gate drive and output stage is designed as identical, independent half-bridges. For this reason, each half-bridge has separate bootstrap pins (BST_X) and each full-bridge has separate power stage supply (PVDD_X) and gate supply (GVDD_X) pins. Furthermore, an additional pin (VDD) is provided as supply for all common circuits. Although supplied from the same 12-V source, it is highly recommended to separate GVDD_AB, GVDD_CD, and VDD on the printed-circuit board (PCB) by RC filters (see application diagram for details). These RC filters provide the recommended high-frequency isolation. Special attention should be paid to placing all decoupling capacitors as close to their associated pins as possible. In general, inductance between the power supply pins and decoupling capacitors must be avoided. (See reference board documentation for additional information.)

Special attention should be paid to the power-stage power supply; this includes component selection, PCB placement, and routing. As indicated, each full-bridge has independent power-stage supply pins (PVDD_X). For optimal electrical performance, EMI compliance, and system reliability, it is important that each PVDD_X connection is decoupled with minimum $2 \times 220\text{-nF}$ ceramic capacitors placed as close as possible to each supply pin. TI recommends following the PCB layout of the TAS5614LA reference design. For additional information on recommended power supply and required components, see the application diagrams in this data sheet.

The 12-V supply should be from a low-noise, low-output-impedance voltage regulator. Likewise, the 36-V power-stage supply is assumed to have low output impedance and low noise. The power-supply sequence is not critical as facilitated by the internal power-on-reset circuit. Moreover, the TAS5614LA is fully protected against erroneous power-stage turn on due to parasitic gate charging when power supplies are applied. Thus, voltage-supply ramp rates (dV/dt) are noncritical within the specified range (see [Recommended Operating Conditions](#)).

7.3.1.1 Boot Strap Supply

For a properly functioning bootstrap circuit, a small ceramic capacitor must be connected from each bootstrap pin (BST_X) to the power-stage output pin (OUT_X). When the power-stage output is low, the bootstrap capacitor is charged through an internal diode connected between the gate-drive power-supply pin (GVDD_X) and the bootstrap pin. When the power-stage output is high, the bootstrap capacitor potential is shifted above the output potential and thus provides a suitable voltage supply for the high-side gate driver. In an application with PWM switching frequencies in the range from 300 kHz to 400 kHz, TI recommends to use 33-nF ceramic capacitors, size 0603 or 0805, for the bootstrap supply. These 33-nF capacitors ensure sufficient energy storage, even during minimal PWM duty cycles, to keep the high-side power stage FET (LDMOS) fully turned on during the remaining part of the PWM cycle.

7.3.2 System Power-Up and Power-Down Sequence

7.3.2.1 Powering Up

The TAS5614LA does not require a power-up sequence. The outputs of the H-bridges remain in a high-impedance state until the gate-drive supply voltage (GVDD_X) and VDD voltage are above the undervoltage protection (UVP) voltage threshold (see [Electrical Characteristics](#)). Although not specifically required, TI recommends holding RESET in a low state while powering up the device. This allows an internal circuit to charge the external bootstrap capacitors by enabling a weak pulldown of the half-bridge output.

7.3.2.2 Powering Down

The TAS5614LA does not require a power-down sequence. The device remains fully operational as long as the gate-drive supply (GVDD_X) voltage and VDD voltage are above the undervoltage protection (UVP) voltage threshold (see [Electrical Characteristics](#)). Although not specifically required, it is a good practice to hold RESET low during power down, thus preventing audible artifacts including pops or clicks.

Feature Description (接下页)

7.3.3 Start-up and Shutdown Ramp Sequence

The integrated start-up and stop sequence ensures a click and pop free startup and shutdown sequence of the amplifier. The start-up sequence uses a voltage ramp with a duration set by the CSTART capacitor. The sequence uses the input PWM signals to generate output PWM signals, hence input idle PWM should be present during both startup and shut down ramping sequences.

VDD, GVDD_X, and PVDD_X power supplies must be turned on and with settled outputs before starting the start-up ramp by setting $\overline{\text{RESET}}$ high.

During start-up and shutdown ramp the input PWM signals should be in muted condition with the PWM processor noise shaper activity turned off (50% duty cycle).

The duration of the start-up and shutdown ramp is 100 ms + X ms, where X is the CSTART capacitor value in nF.

TI recommends using 100-nF CSTART in BTL and PBTL mode and 1 μF in SE mode configuration. This results in ramp times of 200 ms and 1.1 s, respectively. The longer ramp time in SE configuration allows charge and discharge of the output ac coupling capacitor without audible artifacts.

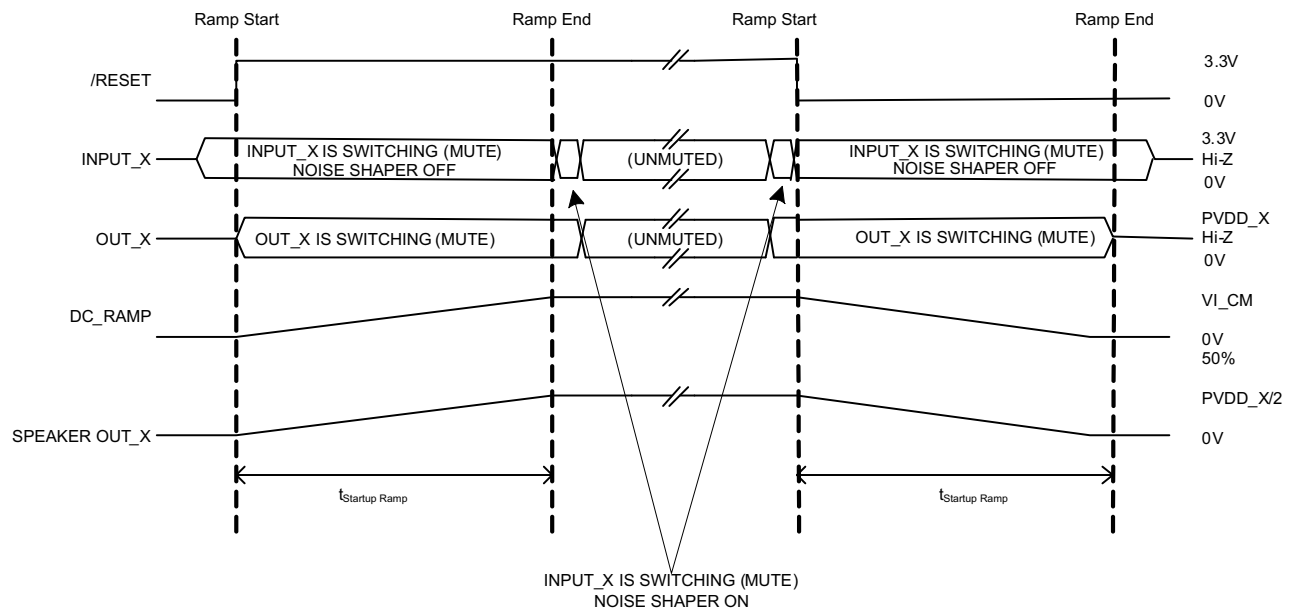


图 15. Start-up/Shutdown Ramp

7.3.4 Unused Output Channels

If all available output channels are not used, TI recommends disabling switching of unused output nodes to reduce power consumption. Furthermore by disabling unused output channels the cost of unused output LC demodulation filters can be avoided.

Disabling a channel is done by leave the bootstrap capacitor (BST) unstuffed and connecting the respective input to GND. The unused output pin(s) can be left floating. Please note that the PVDD decoupling capacitors still need to be mounted.

表 1. Unused Output Channels

OPERATING MODE	PWM INPUT	OUTPUT CONFIGURATION	UNUSED CHANNEL	INPUT_A	INPUT_B	INPUT_C	INPUT_D	UNSTUFFED COMPONENT
000	2N + 1	2 x BTL	AB CD	GND PWMA	GND PWMb	PWMc GND	PWMD GND	BST_A and BST_B capacitors BST_C and BST_D capacitors
001	1N + 1							
010	2N + 1							

Feature Description (接下页)

表 1. Unused Output Channels (接下页)

OPERATING MODE	PWM INPUT	OUTPUT CONFIGURATION	UNUSED CHANNEL	INPUT_A	INPUT_B	INPUT_C	INPUT_D	UNSTUFFED COMPONENT
101	1N + 1	4 x SE	A	GND	PWMB	PWMC	PWMD	BST_A capacitor
			B	PWMA	GND	PWMC	PWMD	BST_B capacitor
			C	PWMA	PWMB	GND	PWMD	BST_C capacitor
			D	PWMA	PWMB	PWMC	GND	BST_D capacitor

7.3.5 Device Protection System

The TAS5614LA contains advanced protection circuitry carefully designed to facilitate system integration and ease of use, as well as to safeguard the device from permanent failure due to a wide range of fault conditions such as short circuits, overload, overtemperature, and undervoltage. The TAS5614LA responds to a fault by immediately setting the power stage in a high-impedance (Hi-Z) state and asserting the **FAULT** pin low. In situations other than overload and overtemperature error (OTE), the device automatically recovers when the fault condition has been removed, that is, the supply voltage has increased.

The device will function on errors, as shown in the following table.

表 2. Device Protection

BTL MODE		PBTL MODE		SE MODE	
CHANNEL FAULT	TURNS OFF	CHANNEL FAULT	TURNS OFF	CHANNEL FAULT	TURNS OFF
A	A+B	A	A+B+C+D	A	A+B
B		B		B	
C	C+D	C		C	C+D
D		D		D	

Bootstrap UVP does not shutdown according to the table, it shuts down the respective high-side FET.

7.3.6 Pin-to-Pin Short-Circuit Protection (PPSC)

The PPSC detection system protects the device from permanent damage if a power output pin (OUT_X) is shorted to GND or PVDD_X. For comparison, the OC protection system detects an overcurrent after the demodulation filter where PPSC detects shorts directly at the pin before the filter. PPSC detection is performed at start-up that is, when VDD is supplied, consequently a short to either GND or PVDD_X after system start-up will not activate the PPSC detection system. When PPSC detection is activated by a short on the output, all half-bridges are kept in a Hi-Z state until the short is removed, the device then continues the start-up sequence and starts switching. The detection is controlled globally by a two step sequence. The first step ensures that there are no shorts from OUT_X to GND, the second step tests that there are no shorts from OUT_X to PVDD_X. The total duration of this process is roughly proportional to the capacitance of the output LC filter. The typical duration is <15 ms/μF. While the PPSC detection is in progress, **FAULT** is kept low, and the device will not react to changes applied to the **RESET** pins. If no shorts are present the PPSC detection passes, and **FAULT** is released. A device reset will not start a new PPSC detection. PPSC detection is enabled in BTL and PBTL output configurations, the detection is not performed in SE mode. To prevent tripping the PPSC detection system TI recommends not inserting resistive load to GND or PVDD_X.

7.3.7 Overtemperature Protection

The TAS5614LA has a two-level temperature-protection system that asserts an active-low warning signal (**OTW**) when the device junction temperature exceeds 125°C (typical). If the device junction temperature exceeds 155°C (typical), the device is put into thermal shutdown, resulting in all half-bridge outputs being set in the high-impedance (Hi-Z) state and **FAULT** being asserted low. OTE is latched in this case. To clear the OTE latch, **RESET** must be asserted. Thereafter, the device resumes normal operation.

7.3.8 Overtemperature Warning, $\overline{\text{OTW}}$

The overtemperature warning $\overline{\text{OTW}}$ asserts when the junction temperature has exceeded recommended operating temperature. Operation at junction temperatures above $\overline{\text{OTW}}$ threshold is exceeding recommended operation conditions and is strongly advised to avoid.

If $\overline{\text{OTW}}$ asserts, action should be taken to reduce power dissipation to allow junction temperature to decrease until it gets below the $\overline{\text{OTW}}$ hysteresis threshold. This action can be decreasing audio volume or turning on a system cooling fan.

7.3.9 Undervoltage Protection (UVP) and Power-On Reset (POR)

The UVP and POR circuits of the TAS5614LA fully protect the device in any power-up/down and brownout situation. While powering up, the POR circuit resets the overload circuit (OLP) and ensures that all circuits are fully operational when the GVDD_X and VDD supply voltages reach stated in [Electrical Characteristics](#). Although GVDD_X and VDD are independently monitored, a supply voltage drop below the UVP threshold on any VDD or GVDD_X pin results in all half-bridge outputs immediately being set in the high-impedance (Hi-Z) state and FAULT being asserted low. The device automatically resumes operation when all supply voltages have increased above the UVP threshold.

7.3.10 Error Reporting

Note that asserting RESET low forces the FAULT signal high, independent of faults being present. TI recommends monitoring the OTW signal using the system micro controller and responding to an overtemperature warning signal by, for example, turning down the volume to prevent further heating of the device resulting in device shutdown (OTE).

To reduce external component count, an internal pullup resistor to 3.3 V is provided on both $\overline{\text{FAULT}}$ and $\overline{\text{OTW}}$ outputs.

The $\overline{\text{FAULT}}$, $\overline{\text{OTW}}$, pins are active-low, open-drain outputs. Their function is for protection-mode signaling to a PWM controller or other system-control device.

Any fault resulting in device shutdown is signaled by the $\overline{\text{FAULT}}$ pin going low. Likewise, $\overline{\text{OTW}}$ goes low when the device junction temperature exceeds 125°C (see the following table).

表 3. Error Reporting

FAULT	OTW	DESCRIPTION
0	0	Overtemperature (OTE) or overload (OLP) or undervoltage (UVP)
0	1	Overload (OLP) or undervoltage (UVP)
1	0	Junction temperature higher than 125°C (overtemperature warning)
1	1	Junction temperature lower than 125°C and no OLP or UVP faults (normal operation)

7.3.11 Fault Handling

If a fault situation occurs while in operation, the device will act accordingly to the fault being a global or a channel fault. A global fault is a chip-wide fault situation and will cause all PWM activity of the device to be shut down, and will assert FAULT low. A global fault is a latching fault and clearing FAULT and restart operation requires resetting the device by toggling RESET. Toggling RESET should never be allowed with excessive system temperature, so it is advised to monitor RESET by a system microcontroller and only allow releasing RESET (RESET high) if the OTW signal is cleared (high). A channel fault will result in shutdown of the PWM activity of the affected channel(s). Note that asserting RESET low forces the FAULT signal high, independent of faults being present. TI recommends monitoring the OTW signal using the system micro controller and responding to an over temperature warning signal by, for example, turning down the volume to prevent further heating of the device resulting in device shutdown (OTE).

表 4. Fault Handling

FAULT or EVENT	FAULT or EVENT DESCRIPTION	GLOBAL or CHANNEL	REPORTING METHOD	LATCHED or SELF CLEARING	ACTION NEEDED TO CLEAR	OUTPUT FETs
PVDD_X UVP	Voltage Fault	Global	$\overline{\text{FAULT}}$ Pin	Self Clearing	Increase affected supply voltage	Hi-Z
VDD UVP						
GVDD_X UVP						
AVDD UVP						
POR (DVDD UVP)	Power On Reset	Global	$\overline{\text{FAULT}}$ Pin	Self Clearing	Allow DVDD to rise	H-Z
BST UVP	Voltage Fault	Channel (half bridge)	None	Self Clearing	Allow BST cap to recharge (low side on, VDD 12 V)	High Side Off
OTW	Thermal Warning	Global	$\overline{\text{OTW}}$ Pin	Self Clearing	Cool below lower OTW threshold	Normal operation
OTE (OTSD)	Thermal Shutdown	Global	$\overline{\text{FAULT}}$ Pin	Latched	Toggle $\overline{\text{RESET}}$	Hi-Z
OLP (CBC >2.6 ms)	OC shutdown	Channel	$\overline{\text{FAULT}}$ Pin	Latched	Toggle $\overline{\text{RESET}}$	Hi-Z
Latched OC (ROC > 47k)	OC shutdown	Channel	$\overline{\text{FAULT}}$ Pin	Latched	Toggle $\overline{\text{RESET}}$	Hi-Z
CBC (24k < ROC < 33k)	OC Limiting	Channel	None	Self Clearing	reduce signal level or remove short	Flip state, cycle by cycle at fs/2
Stuck at Fault ⁽¹⁾ (1 to 3 channels)	No PWM	Channel	None	Self Clearing	resume PWM	Hi-Z
Stuck at Fault ⁽¹⁾ (All channels)	No PWM	Global	None	Self Clearing	resume PWM	Hi-Z

(1) Stuck at Fault occurs when input PWM drops below minimum PWM frame rate given in [Recommended Operating Conditions](#).

7.3.12 Device Reset

When $\overline{\text{RESET}}$ is asserted low, all power-stage FETs in the four half-bridges are forced into a high-impedance (Hi-Z) state.

In BTL modes, to accommodate bootstrap charging prior to switching start, asserting the reset input low enables weak pulldown of the half-bridge outputs. In the SE mode, the output is forced into a high impedance state when asserting the reset input low. Asserting reset input low removes any fault information to be signaled on the $\overline{\text{FAULT}}$ output, that is, $\overline{\text{FAULT}}$ is forced high. A rising-edge transition on reset input allows the device to resume operation after an overload fault. To ensure thermal reliability, the rising edge of $\overline{\text{RESET}}$ must occur no sooner than 4 ms after the falling edge of $\overline{\text{FAULT}}$.

7.4 Device Functional Modes

There are three main output modes that the user can configure the device as per application requirement. In addition there are two PWM modulation modes, AD and BD.

AD modulation can have single-ended (SE) or differential analog inputs. AD modulation can also be configured to have SE, BTL, BTL+SE, or PBTL outputs. BD modulation requires differential analog inputs.

BD modulation can only be configured in BTL or PTBL mode.

Device Functional Modes (接下页)

7.4.1 Mode Selection Pins

MODE PINS			PWM INPUT ⁽¹⁾	OUTPUT CONFIGURATION	INPUT A	INPUT B	INPUT C	INPUT D	MODE
M3	M2	M1							
0	0	0	2N + 1	2 x BTL	PWMA	PWMB	PWMC	PWMD	AD mode
0	0	1	1N + 1 ⁽²⁾	2 x BTL	PWMA	Unused	PWMC	Unused	AD mode
0	1	0	2N + 1	2 x BTL	PWMA	PWMB	PWMC	PWMD	BD mode
0	1	1	1N + 1 ⁽²⁾	1 x BTL + 2 x SE	PWMA	Unused	PWMC	PWMD	AD mode
1	0	0	2N + 1	1 x PBTL	PWMA	PWMB	0	0	AD mode
1	0	0	1N + 1 ⁽²⁾	1 x PBTL	PWMA	Unused	0	1	AD mode
1	0	0	2N + 1	1 x PBTL	PWMA	PWMB	1	0	BD mode
1	0	1	1N + 1	4 x SE ⁽³⁾	PWMA	PWMB	PWMC	PWMD	AD mode

- (1) The 1N and 2N naming convention is used to indicate the number of PWM lines to the power stage per channel in a specific mode.
- (2) Using 1N interface in BTL and PBTL mode results in increased DC offset on the output terminals.
- (3) The 4xSE mode can be used as 1xBTL + 2xSE configuration by feeding a 2N PWM signal to either INPUT_AB or INPUT_CD for improved dc offset accuracy

8 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

8.1.1 System Design Consideration

A rising-edge transition on reset input allows the device to execute the startup sequence and starts switching.

Apply audio only according to the timing information for startup and shutdown sequence. That will start and stop the amplifier without audible artifacts in the output transducers.

The $\overline{\text{CLIP}}$ signal indicates that the output is approaching clipping (when output PWM starts skipping pulses due to loop filter saturation). The signal can be used to initiate an audio volume decrease or to adjust the power supply rail.

The device inverts the audio signal from input to output.

The DVDD and AVDD pins are not recommended to be used as a voltage source for external circuitry.

8.2 Typical Applications

The following sections discuss in detail three typical audio PWM (class-D) configurations:

- Differential input, stereo BTL outputs
- Differential input, mono PBTL output
- Single-ended inputs, quad single-ended outputs.

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8.2.1 Typical BTL Application

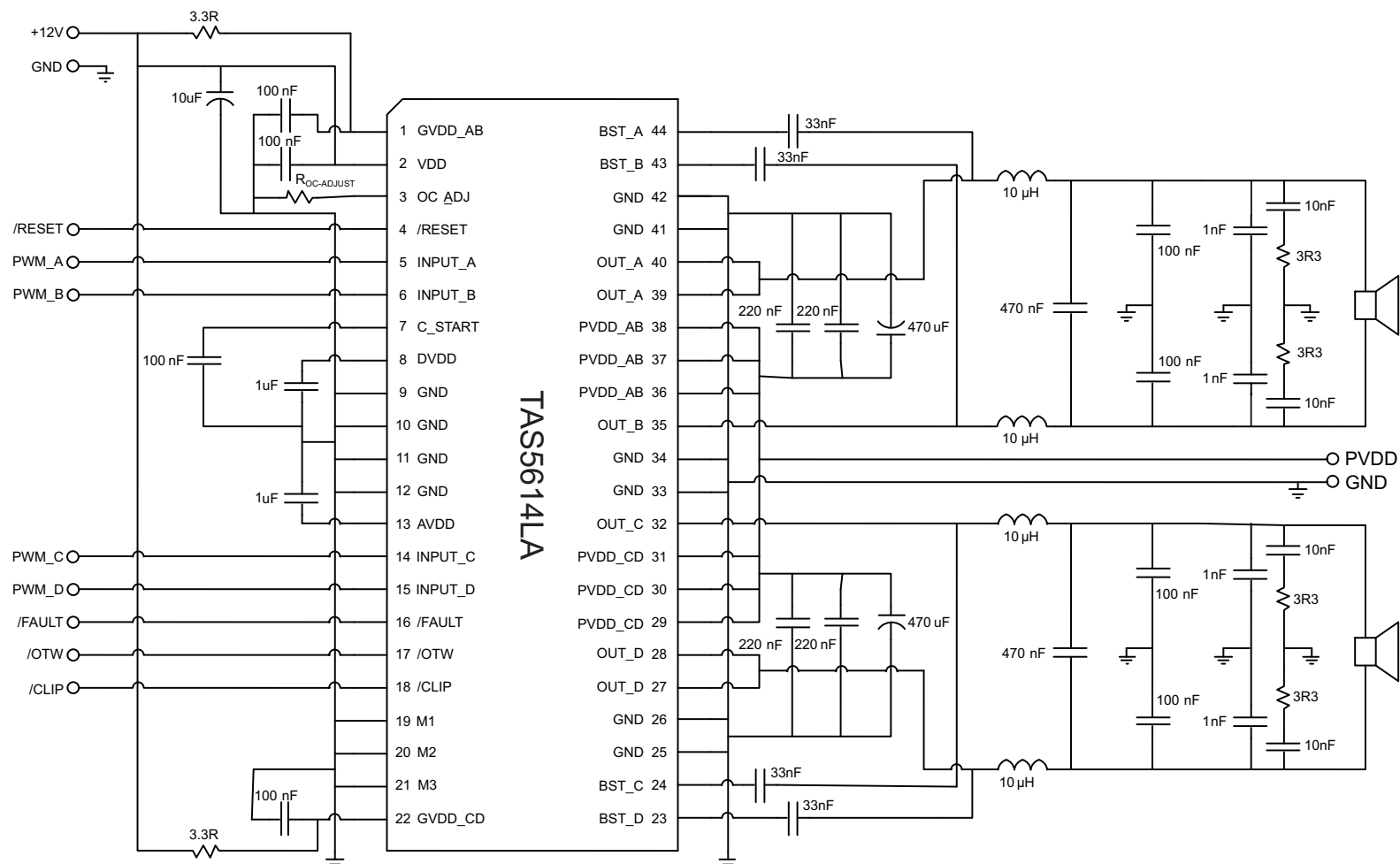


图 16. Typical Differential (2N) BTL Application With AD Modulation Filters

8.2.1.1 Design Requirements

See 图 16 for application schematic. In this application, differential PWM inputs are used with AD modulation from the PWM modulator (TAS5558). AD modulation scheme is defined as PWM(+) is opposite polarity from PWM(-).

8.2.1.2 Detailed Design Procedure

- Pin 1 - GVDD_AB is the gate drive voltage for half-bridges A and B. This pin needs a 3.3-Ω isolation resistor and a 0.1-uF decoupling capacitor.
- Pin 2 - VDD is the supply for internal voltage regulators AVDD and DVDD. This pin needs a 10-uF bulk capacitor and a 0.1-uF decoupling capacitor.
- Pin 3 - Roc adjust is the overcurrent programming resistor. Depending on the application, this resistor can be between 24 kΩ to 68 kΩ.
- Pin 4 - RESET pin when asserted, it keeps outputs Hi-Z and no PWM switching. This pin can be controlled by a microprocessor.
- Pins 5 and 6 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 7 - Start-up ramp capacitor should be 0.1 uF for BTL configuration.
- Pin 8 - Digital output supply pin is connected to 1-uF decoupling capacitor.
- Pins 9-12 - Ground pins are connected to board ground.
- Pin 13 - Analog output supply pin is connected to 1-uF decoupling capacitor.
- Pins 14 and 15 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 16 - Fault pin can be monitored by a micro-controller via GPIO pin. System can decide to assert reset or shutdown.
- Pin 17 - Overtemperature warning pin can be monitored by a microcontroller through a GPIO pin. System can decide to turn on fan or lower output power.
- Pin 18 - Output clip indicator can be monitored by a microcontroller via a GPIO pin. System can decide to lower the volume.
- Pins 19-21 - Mode pins set the input and output configurations. For this configuration M1-M3 are grounded. These mode pins must be hardware configured, such as, not through GPIO pins from a micro-controller.
- Pin 22 - GVDD_CD is the gate drive voltage for half-bridges C and D. This pin needs a 3.3-Ω isolation resistor and a 0.1-uF decoupling capacitor.
- Pins 23, 24, 43, 44 - Bootstrap pins for half-bridges A, B, C, and D. Connect 33 nF from this pin to corresponding output pins.
- Pins 25, 26, 33, 34, 41, 42 - These ground pins should be used to ground decoupling capacitors from PVDD_X.
- Pins 27, 28, 32, 35, 39, 40 - Output pins from half-bridges A, B, C, and D. Connect appropriate bootstrap capacitors and differential LC filter as shown in 图 16.
- Pins 29, 30, 31, 36, 37, 38 - Power supply pins to half-bridges A, B, C, and D. A and B form a full-bridge and C and D form another full-bridge. A 470-uF bulk capacitor is recommended for each full-bridge power pins. Two 0.22-μF decoupling capacitors are placed on each full-bridge power pins. See 图 16 for details.

8.2.1.3 Application Curves

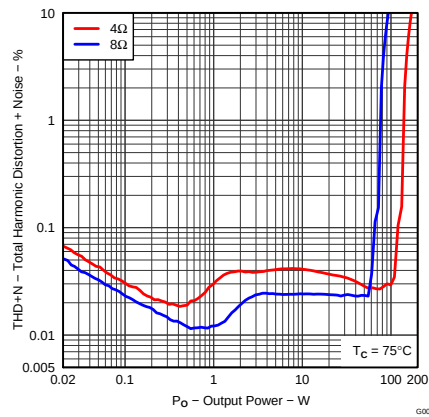


图 17. Total Harmonic + Noise vs Output Power, 1 kHz

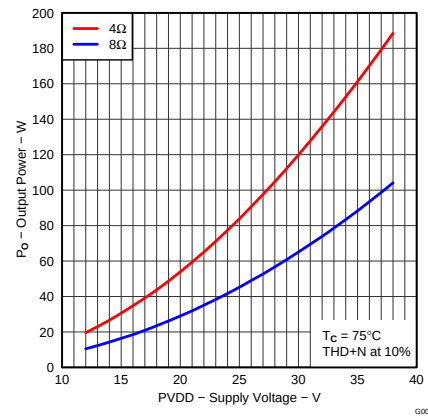


图 18. Output Power vs Supply Voltage vs Distortion + Noise = 10%

8.2.2 Typical SE Configuration

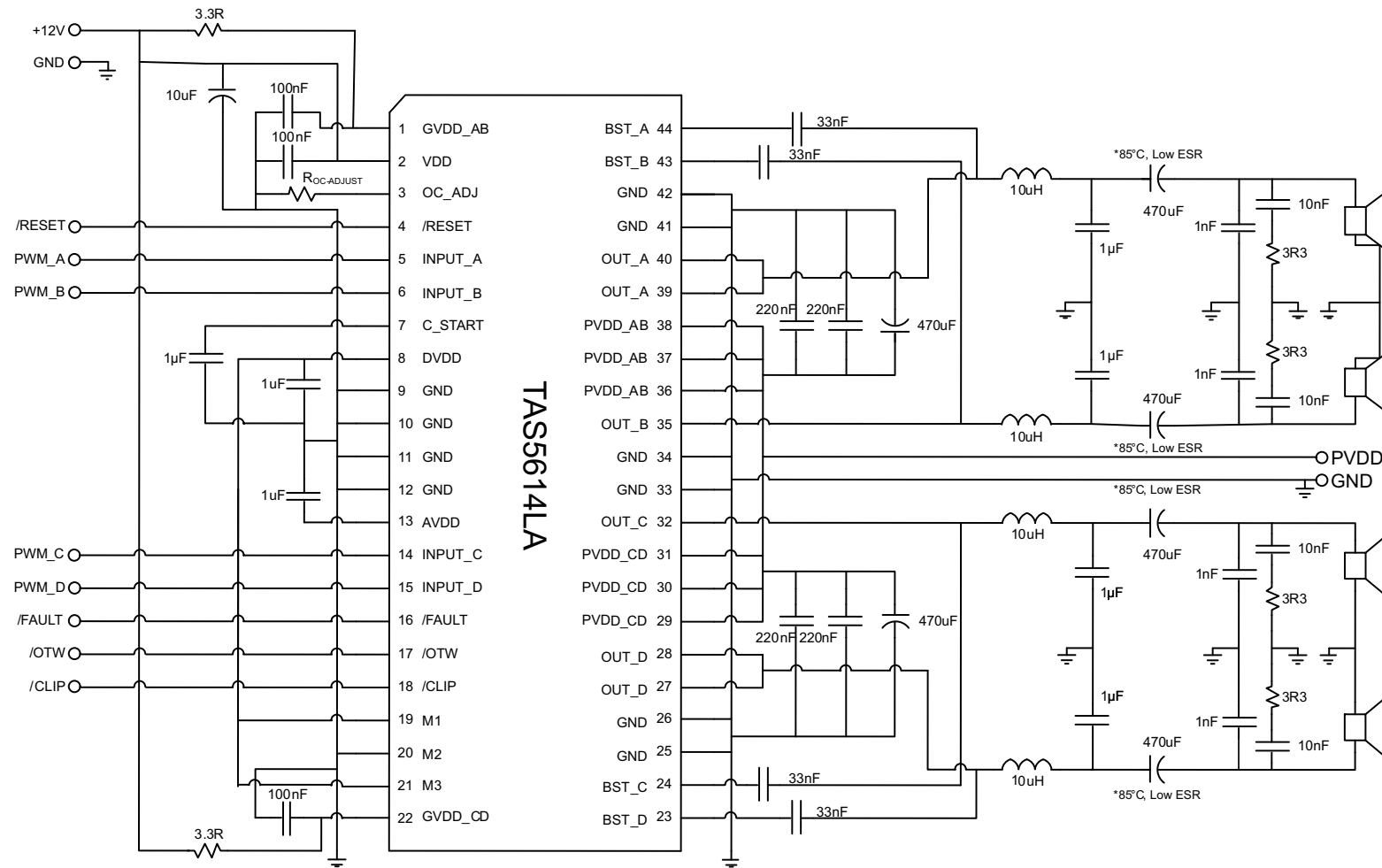


图 19. Typical (1N) SE Application

8.2.2.1 Design Requirements

See [图 19](#) for application schematic. In this application, four single-ended PWM inputs are used with AD modulation from the PWM modulator such as the TAS5558. AD modulation scheme is defined as PWM(+) is opposite polarity from PWM(-). The single-ended (SE) output configuration is often used to drive 4 independent channels in one TAS5614LA device.

8.2.2.2 Detailed Design Procedure

- Pin 1 - GVDD_AB is the gate drive voltage for half-bridges A and B. It needs a 3.3-Ω isolation resistor and a 0.1-uF decoupling capacitor.
- Pin 2 - VDD is the supply for internal voltage regulators AVDD and DVDD. It needs a 10-uF bulk cap and a 0.1-uF decoupling capacitor.
- Pin 3 - Roc adjust is the overcurrent programming resistor. Depending on the application, this resistor can be between 24 kΩ to 68 kΩ.
- Pin 4 - RESET pin when asserted, it keeps outputs Hi-Z and no PWM switching. This pin can be controlled by a microprocessor.
- Pins 5 and 6 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 7 - Start up ramp capacitor should be 1 uF for SE configuration.
- Pin 8 - Digital output supply pin is connected to 1-uF decoupling cap.
- Pins 9-12 - Ground pins are connected to board ground.
- Pin 13 - Analog output supply pin is connected to 1-uF decoupling cap.
- Pins 14 and 15 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 16 - Fault pin can be monitored by a microcontroller through GPIO pin. System can decide to assert reset or shutdown.
- Pin 17 - Overtemperature warning pin can be monitored by a microcontroller through a GPIO pin. System can decide to turn on fan or lower output power.
- Pin 18 - Output clip indicator can be monitored by a microcontroller through a GPIO pin. System can decide to lower the volume.
- Pins 19-21 - Mode pins set the input and output configurations. For this configuration M1-M3 are grounded. These mode pins must be hardware configured, such as, not through GPIO pins from a microcontroller.
- Pin 22 - GVDD_CD is the gate drive voltage for half-bridges C and D. This pin needs a 3.3-Ω isolation resistor and a 0.1-uF decoupling capacitor.
- Pins 23, 24, 43, 44 - Bootstrap pins for half-bridges A, B, C, and D. Connect 33 nF from this pin to corresponding output pins.
- Pins 25, 26, 33, 34, 41, 42 - These ground pins should be used to ground decoupling capacitors from PVDD_X.
- Pins 27, 28, 32, 35, 39, 40 - Output pins from half-bridges A, B, C, and D. Connect appropriate bootstrap capacitors and differential LC filter as shown in [图 19](#).
- Pins 29, 30, 31, 36, 37, 38 - Power supply pins to half-bridges A, B, C, and D. A and B form a full-bridge and C and D form another full-bridge. A 470-uF bulk cap is recommended for each full-bridge power pins. Two 0.22-μF decoupling capacitors are placed on each full-bridge power pins. See [图 19](#) for details.

8.2.2.3 Application Curves

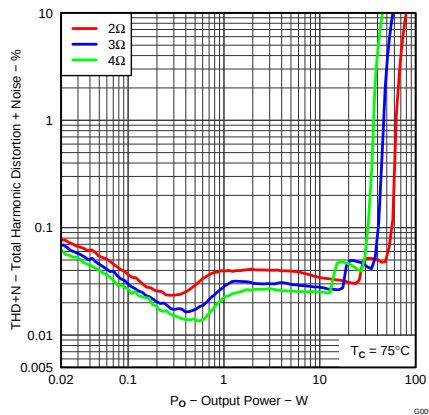


图 20. Total Harmonic Distortion + Noise vs Output Power

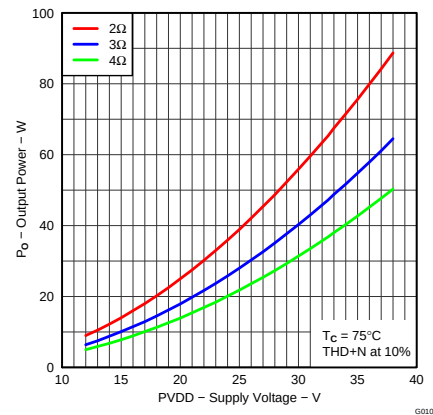


图 21. Output Power vs Supply Voltage

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8.2.3 Typical PBTL Configuration

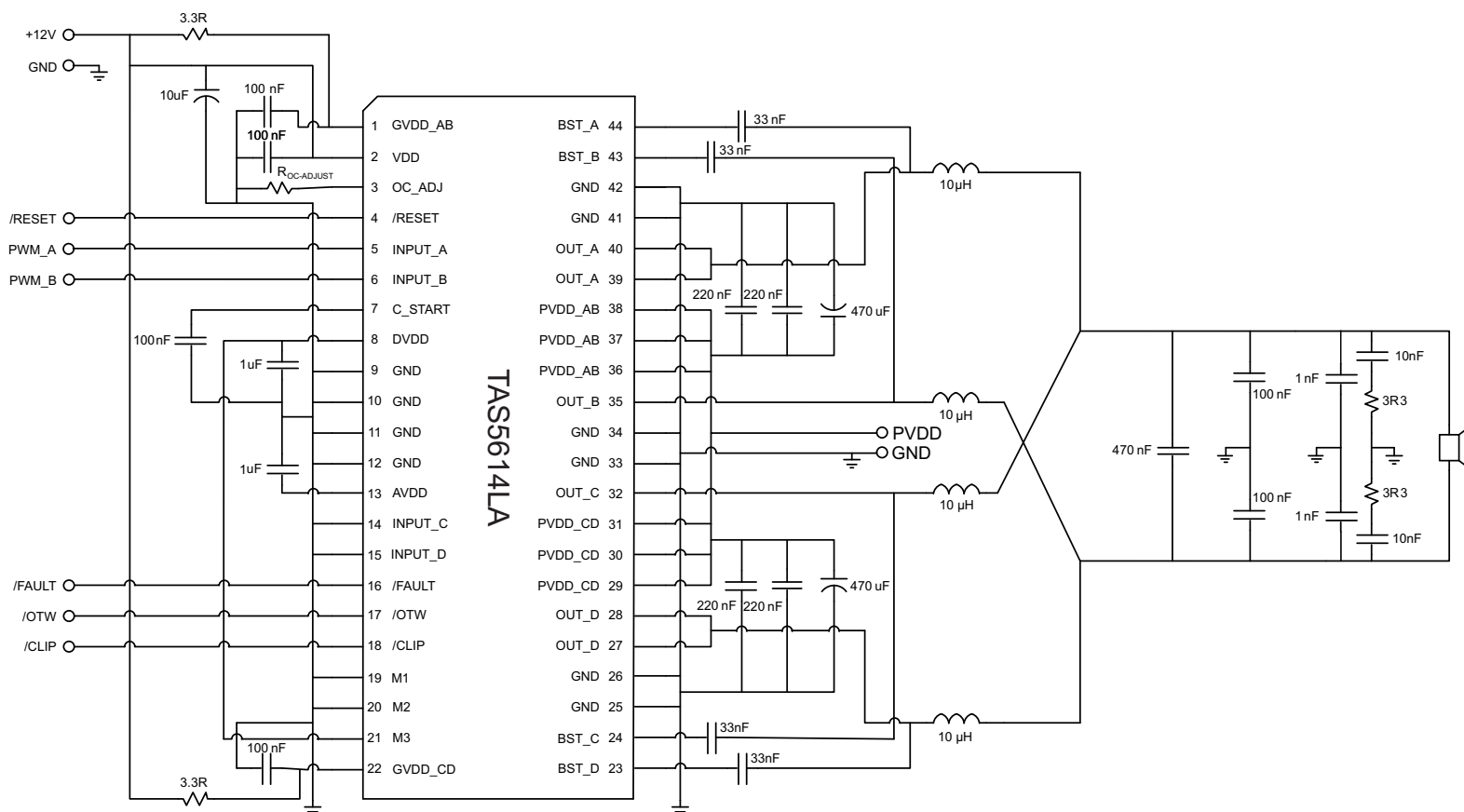


图 22. Typical Differential (2N) PBTL Application With AD Modulation Filter

8.2.3.1 Design Requirements

See 图 22 for application schematic. In this application, one differential PWM input is used with AD modulation from the PWM modulator such as the TAS5558. AD modulation scheme is defined as PWM(+) is opposite polarity from PWM(-). The output PBTl configuration is often used to drive lower impedance load such as a subwoofer.

8.2.3.2 Detailed Design Procedure

- Pin 1 - GVDD_AB is the gate drive voltage for half-bridges A and B. This pin needs a 3.3-Ω isolation resistor and a 0.1-μF decoupling capacitor.
- Pin 2 - VDD is the supply for internal voltage regulators AVDD and DVDD. This pin needs a 10-μF bulk cap and a 0.1-μF decoupling capacitor.
- Pin 3 - Roc adjust is the over-current programming resistor. Depending on the application, this resistor can be between 24 kΩ to 68 kΩ.
- Pin 4 - RESET pin when asserted, it keeps outputs Hi-Z and no PWM switching. This pin can be controlled by a microprocessor.
- Pins 5 and 6 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 7 - Start up ramp capacitor should be 0.1 μF for PBTl configuration.
- Pin 8 - Digital output supply pin is connected to 1-μF decoupling capacitor.
- Pins 9-12 - Ground pins are connected to board ground.
- Pin 13 - Analog output supply pin is connected to 1-μF decoupling cap.
- Pins 14 and 15 - These are PWM (+) and PWM (-) pins with signals provided by a PWM modulator such as TAS5558. These are PWM differential pair.
- Pin 16 - Fault pin can be monitored by a microcontroller through GPIO pin. System can decide to assert reset or shutdown.
- Pin 17 - Overtemperature warning pin can be monitored by a microcontroller through a GPIO pin. System can decide to turn on fan or lower output power.
- Pin 18 - Output clip indicator can be monitored by a microcontroller through a GPIO pin. System can decide to lower the volume.
- Pins 19-21 - Mode pins set the input and output configurations. For this configuration M1-M3 are grounded. These mode pins must be hardware configured, such as, not through GPIO pins from a microcontroller.
- Pin 22 - GVDD_CD is the gate drive voltage for half-bridges C and D. It needs a 3.3-Ω isolation resistor and a 0.1-μF decoupling capacitor.
- Pins 23, 24, 43, 44 - Bootstrap pins for half-bridges A, B, C, and D. Connect 33 nF from this pin to corresponding output pins.
- Pins 25, 26, 33, 34, 41, 42 - These ground pins should be used to ground decoupling capacitors from PVDD_X.
- Pins 27, 28, 32, 35, 39, 40 - Output pins from half-bridges A, B, C, and D. Connect appropriate bootstrap capacitors and differential LC filter as shown in 图 22.
- Pins 29, 30, 31, 36, 37, 38 - Power supply pins to half-bridges A, B, C, and D. A and B form a full-bridge and C and D form another full-bridge. A 470-μF bulk cap is recommended for each full-bridge power pins. Two 0.22-μF decoupling capacitors are placed on each full-bridge power pins. See 图 22 for details.

8.2.3.3 Application Curves

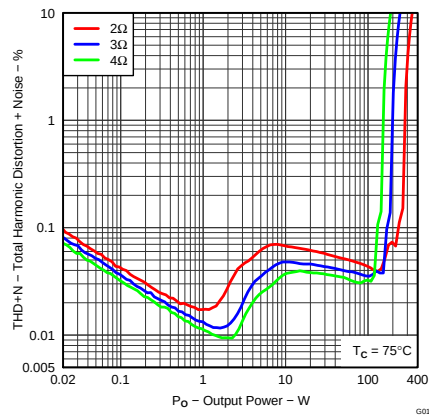


图 23. Total Harmonic Distortion + Noise vs Output Power

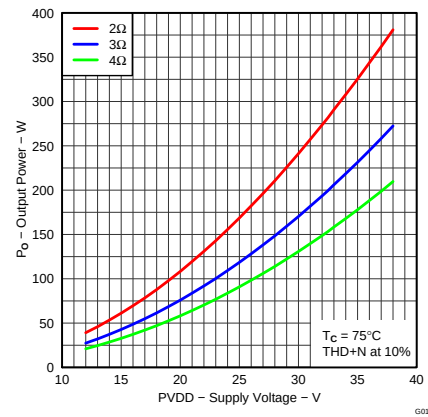


图 24. Output Power vs Supply Voltage

9 Power Supply Recommendations

The most important parameters are the absolute maximum rating on PVDD pins, bootstrap pins, and output pins. Over stress the device with higher than maximum voltage rating may shorten device lifetime operation and even cause device damage. Be sure that the specifications in [Specifications](#) are observed. For best audio performance, low ESR bulk caps are recommended. Depending on the application 470- μ F capacitor or higher should be used. As always, decoupling capacitors must be placed no more than 1 mm from the power supply pins. If PCB space is not allowed for close placement of the decoupling capacitor, the decoupling capacitors can be placed on the back side of the device with vias. However, it still needs to be right below the pins.

10 Layout

10.1 Layout Guidelines

10.1.1 PCB Material Recommendation

FR-4 Glass Epoxy material with 1 oz. (35 μ m) is recommended for use with the TAS5614LA. The use of this material can provide for higher power output, improved thermal performance, and better EMI margin (due to lower PCB trace inductance).

10.1.2 PVDD Capacitor Recommendation

The large capacitors used in conjunction with each full-bridge, are referred to as the PVDD Capacitors. These capacitors should be selected for proper voltage margin and adequate capacitance to support the power requirements. In practice, with a well designed system power supply, 1000 μ F, 50 V should support most applications. The PVDD capacitors should be low ESR type because they are used in a circuit associated with high-speed switching.

10.1.3 Decoupling Capacitor Recommendation

To design an amplifier that has robust performance, passes regulatory requirements, and exhibits good audio performance, good quality decoupling capacitors should be used. In practice, X5R or better should be used in this application.

The voltage of the decoupling capacitors should be selected in accordance with good design practices. Temperature, ripple current, and voltage overshoot must be considered. This fact is particularly true in the selection of the close decoupling capacitor that is placed on the power supply to each half-bridge. It must withstand the voltage overshoot of the PWM switching, the heat generated by the amplifier during high power output, and the ripple current created by high power output. A minimum voltage rating of 50V is required for use with a 36-V power supply.

See the TAS5614LADDVEVM user's guide, [SLAU375](#), for more details including layout and bill of materials.

10.1.4 Circuit Component and Printed Circuit Board Recommendation

These requirements must be followed to achieve best performance and reliability and minimum ground bounce at rated output power of TAS5614LA.

10.1.4.1 Circuit Component Requirements

A number of circuit components are critical to performance and reliability. They include LC filter inductors and capacitors, decoupling capacitors and the heatsink. The best detailed reference for these is the TAS5614LA EVM BOM in the user's guide, which includes components that meet all the following requirements.

- High frequency decoupling capacitors: small high frequency decoupling capacitors are placed next to the IC to control switching spikes and keep high frequency currents in a tight loop to achieve best performance and reliability and EMC. They must be high quality ceramic parts with material like X7R or X5R and voltage ratings at least 30% greater than PVDD, to minimize loss of capacitance caused by applied dc voltage. (Capacitors made of materials like Y5V or Z5U should never be used in decoupling circuits or audio circuits because their capacitance falls dramatically with applied dc and ac voltage, often to 20% of rated value or less.)
- Bulk decoupling capacitors: large bulk decoupling capacitors are placed as close as possible to the IC to

Layout Guidelines (接下页)

stabilize the power supply at lower frequencies. They must be high quality aluminum parts with low ESR and ESL and voltage ratings at least 25% more than PVDD to handle power supply ripple currents and voltages

- LC filter inductors: to maintain high efficiency, short circuit protection and low distortion, LC filter inductors must be linear to at least the OCP limit and must have low DC resistance and core losses. For SCP, minimum working inductance, including all variations of tolerance, temperature and current level, must be 5 μ H. Inductance variation of more than 1% over the output current range can cause increased distortion.
- LC filter capacitors: to maintain low distortion and reliable operation, LC filter capacitors must be linear to twice the peak output voltage. For reliability, capacitors must be rated to handle the audio current generated in them by the maximum expected audio output voltage at the highest audio frequency.
- Heatsink: The heatsink must be fabricated with the PowerPAD contact area spaced 1.0 mm $\pm$ 0.01 mm above mounting areas that contact the PCB surface. It must be supported mechanically at each end of the IC. This mounting ensures the correct pressure to provide good mechanical, thermal and electrical contact with TAS5614LA PowerPAD. The PowerPAD contact area must be bare and must be interfaced to the PowerPAD with a thin layer (about 1 mil) of a thermal compound with high thermal conductivity.

10.1.4.2 Printed Circuit Board Requirements

PCB layout, audio performance, EMC and reliability are linked closely together, and solid grounding improves results in all these areas. The circuit produces high, fast-switching currents, and care must be taken to control current flow and minimize voltage spikes and ground bounce at IC ground pins. Critical components must be placed for best performance and PCB traces must be sized for the high audio currents that the IC circuit produces.

Grounding: ground planes must be used to provide the lowest impedance and inductance for power and audio signal currents between the IC and its decoupling capacitors, LC filters and power supply connection. The area directly under the IC should be treated as central ground area for the device, and all IC grounds must be connected directly to that area. A matrix of vias must be used to connect that area to the ground plane. Ground planes can be interrupted by radial traces (traces pointing away from the IC), but they must never be interrupted by circular traces, which disconnect copper outside the circular trace from copper between it and the IC. Top and bottom areas that do not contain any power or signal traces should be flooded and connected with vias to the ground plane.

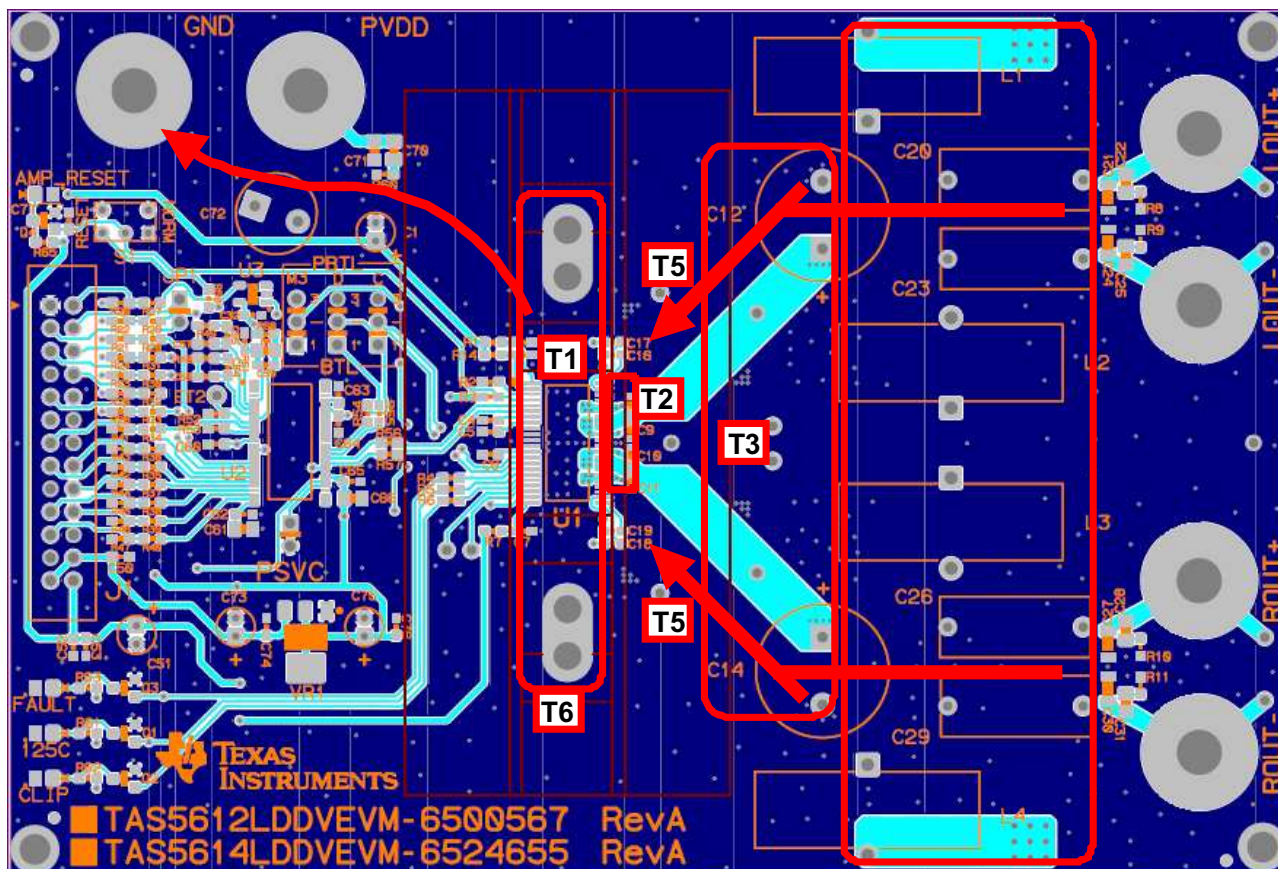
Decoupling capacitors: high frequency decoupling capacitors must be located within 2 mm of the IC and connected directly to PVDD and GND pins with solid traces. Vias must not be used to complete these connections, but several vias must be used at each capacitor location to connect top ground directly to the ground plane. Placement of bulk decoupling capacitors is less critical, but they still must be placed as close as possible to the IC with strong ground return paths. Typically the heatsink sets the distance.

LC filters: LC filters must be placed as close as possible to the IC after the decoupling capacitors. The capacitors must have strong ground returns to the IC through top and bottom grounds for effective operation.

PCB copper must be at least 1 ounce thickness. PVDD and output traces must be wide enough to carry expected average currents without excessive temperature rise. PWM input traces must be kept short and close together on the input side of the IC and must be shielded with ground flood to avoid interference from high power switching signals.

The heatsink must be grounded well to the PCB near the IC, and a thin layer of highly conductive thermal compound (about 1 mil) must be used to connect the heatsink to the PowerPAD.

10.2 Layout Example



Note T1: Bottom and top layer ground plane areas are used to provide strong ground connections. The area under the IC must be treated as central ground, with IC grounds connected there and a strong via matrix connecting the area to bottom ground plane. The ground path from the IC to the power supply ground through top and bottom layers must be strong to provide very low impedance to high power and audio currents.

Note T2: Low impedance X7R or X5R ceramic high frequency decoupling capacitors must be placed within 2 mm of PVDD and GND pins and connected directly to them and to top ground plane to provide good decoupling of high frequency currents for best performance and reliability. Their dc voltage rating must be $2 \times PVDD$.

Note T3: Low impedance electrolytic bulk decoupling capacitors must be placed as close as possible to the IC. Typically the heat sink sets the distance. Wide PVDD traces are routed on the top layer with direct connections to the pins, without going through vias.

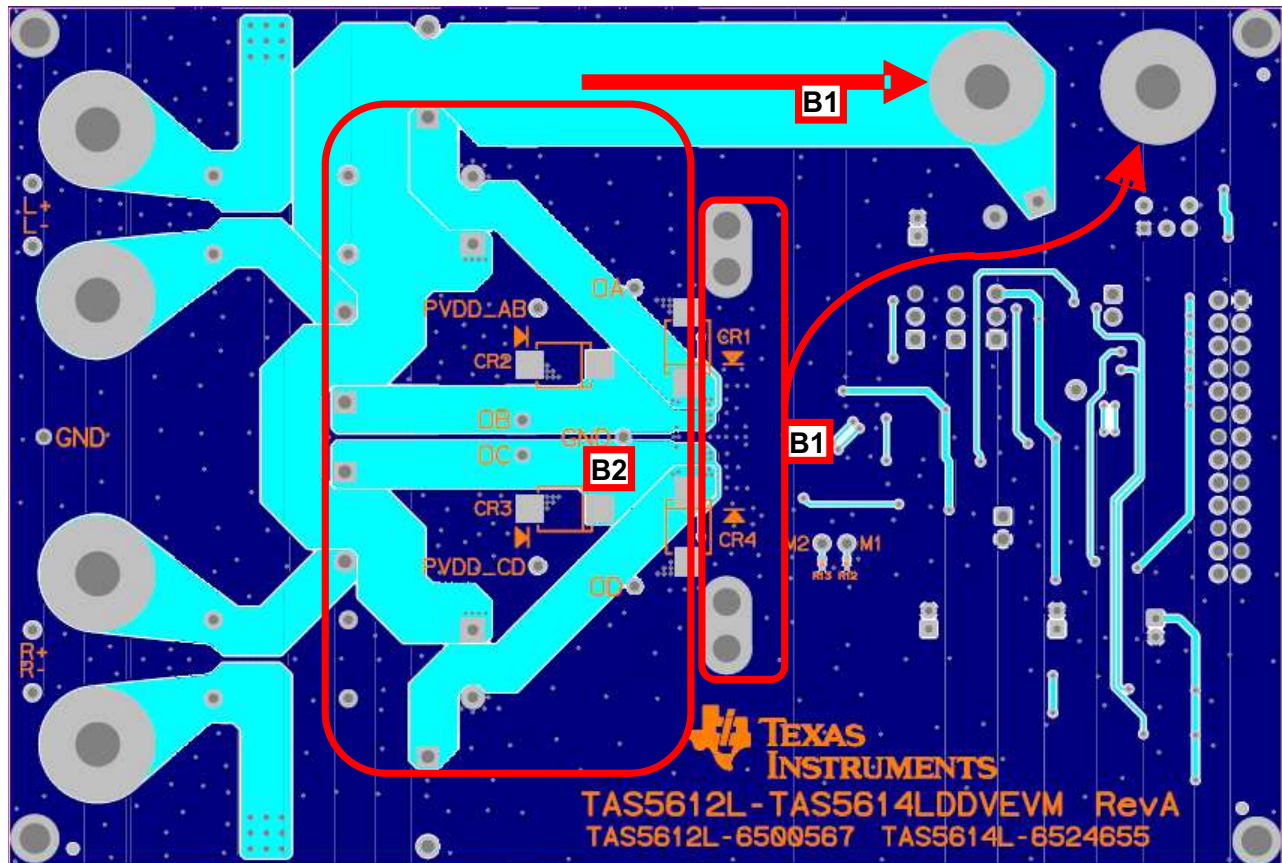
Note T4: LC filter inductors and capacitors must be placed as close as possible to the IC after decoupling capacitors. Inductors must have low dc resistance and switching losses and must be linear to at least the OCP (over current protection) limit. Capacitors must be linear to at least twice the maximum output voltage and must be capable of conducting currents generated by the maximum expected high frequency output.

Note T5: Bulk decoupling capacitors and LC filter capacitors must have strong ground return paths through ground plane to the central ground area under the IC.

Note T6: The heatsink must have a good thermal and electrical connection to PCB ground and to the IC PowerPAD. It must be connected to the PowerPAD through a thin layer, about 1 mil, of highly conductive thermal compound.

图 25. Printed Circuit Board - Top Layer

Layout Example (接下页)



Note B1: A wide PVDD bus and a wide ground path must be used to provide very low impedance to high power and audio currents to the power supply. Top and bottom ground planes must be connected with vias at many points to reinforce the ground connections.

Note B2: Wide output traces can be routed on the bottom layer and connected to output pins with strong via arrays.

图 26. Printed Circuit Board - Bottom Layer

11 器件和文档支持

11.1 商标

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蓝光碟 is a trademark of Blu-ray Disk Association (BDA).

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11.2 静电放电警告



这些装置包含有限的内置 ESD 保护。存储或装卸时，应将导线一起截短或将装置放置于导电泡棉中，以防止 MOS 门极遭受静电损伤。

11.3 术语表

[SLYZ022](#) — TI 术语表。

这份术语表列出并解释术语、首字母缩略词和定义。

12 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 这些数据会在无通知且不
对本文档进行修订的情况下发生改变。 欲获得该数据表的浏览器版本，请查阅左侧的导航栏。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TAS5614LADDV	Active	Production	HTSSOP (DDV) 44	35 TUBE	Yes	NIPDAU	Level-3-260C-168 HR	0 to 125	TAS5614LA
TAS5614LADDV.B	Active	Production	HTSSOP (DDV) 44	35 TUBE	Yes	NIPDAU	Level-3-260C-168 HR	0 to 125	TAS5614LA
TAS5614LADDVR	Active	Production	HTSSOP (DDV) 44	2000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	0 to 125	TAS5614LA
TAS5614LADDVR.B	Active	Production	HTSSOP (DDV) 44	2000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	0 to 125	TAS5614LA

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

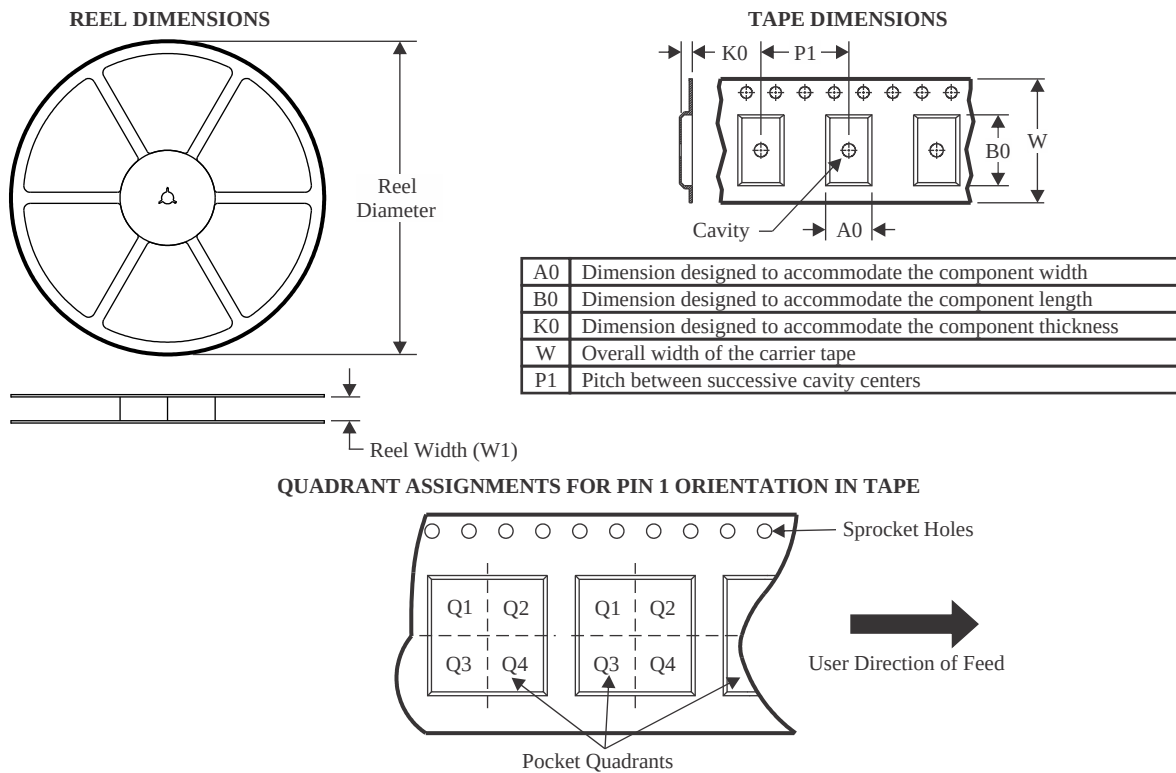
⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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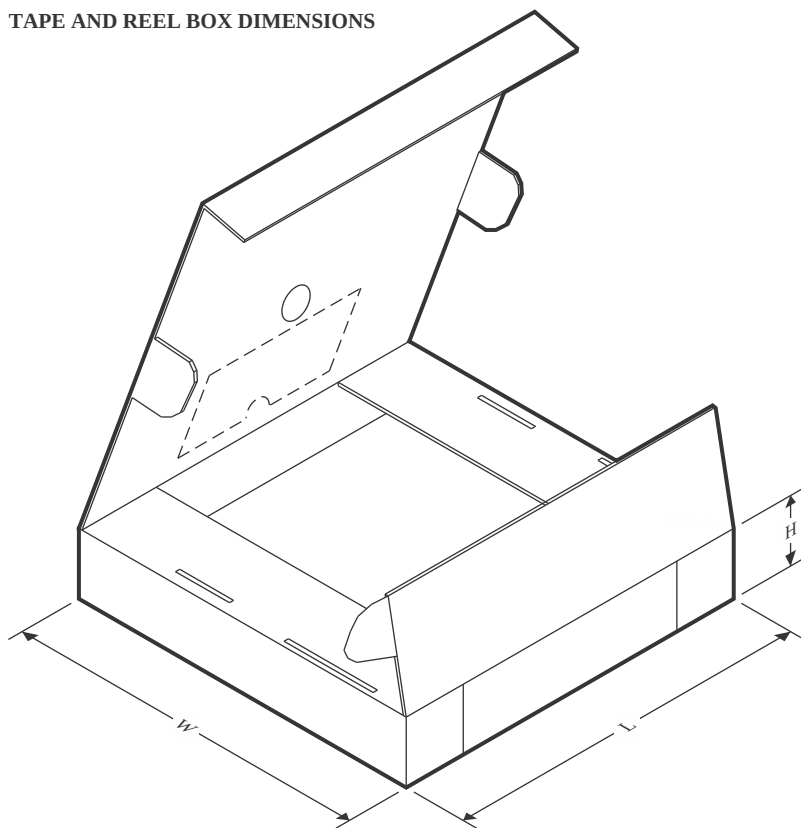
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TAS5614LADDVR	HTSSOP	DDV	44	2000	330.0	24.4	8.6	15.6	1.8	12.0	24.0	Q1

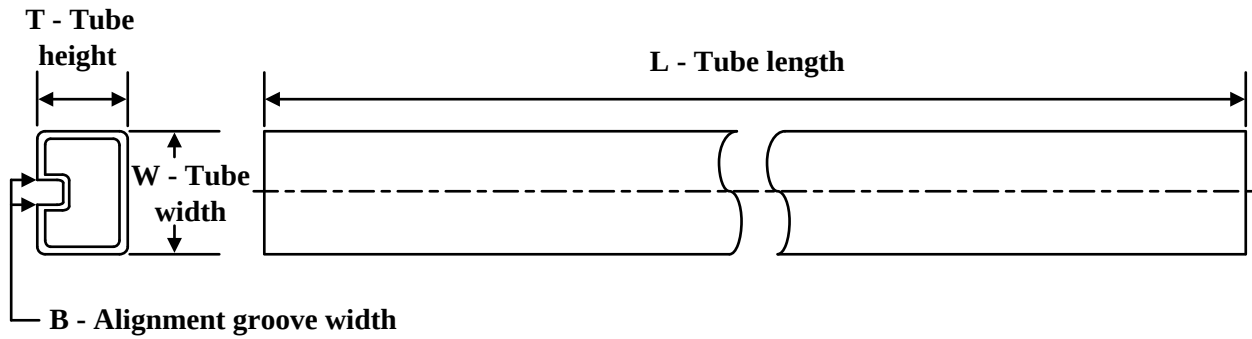
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

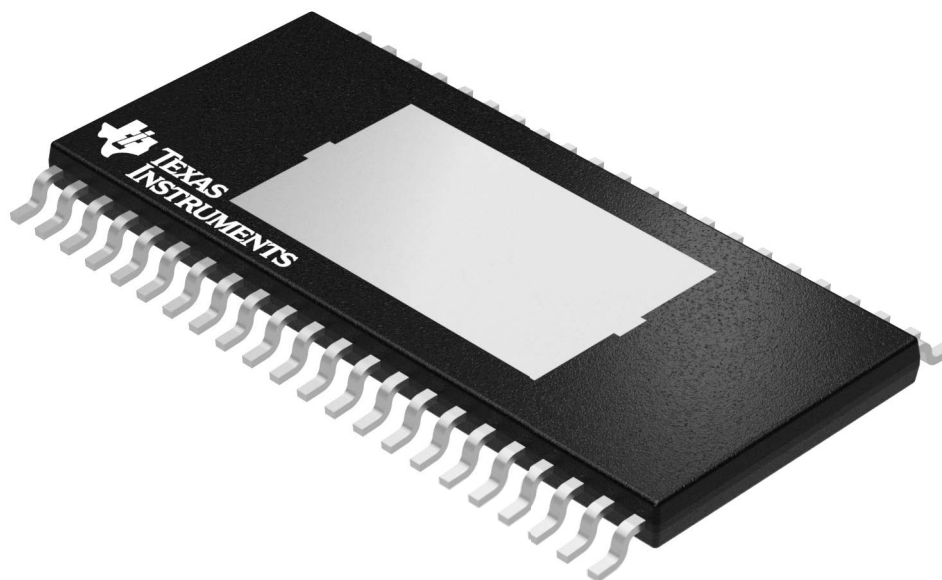
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TAS5614LADDVR	HTSSOP	DDV	44	2000	350.0	350.0	43.0

TUBE

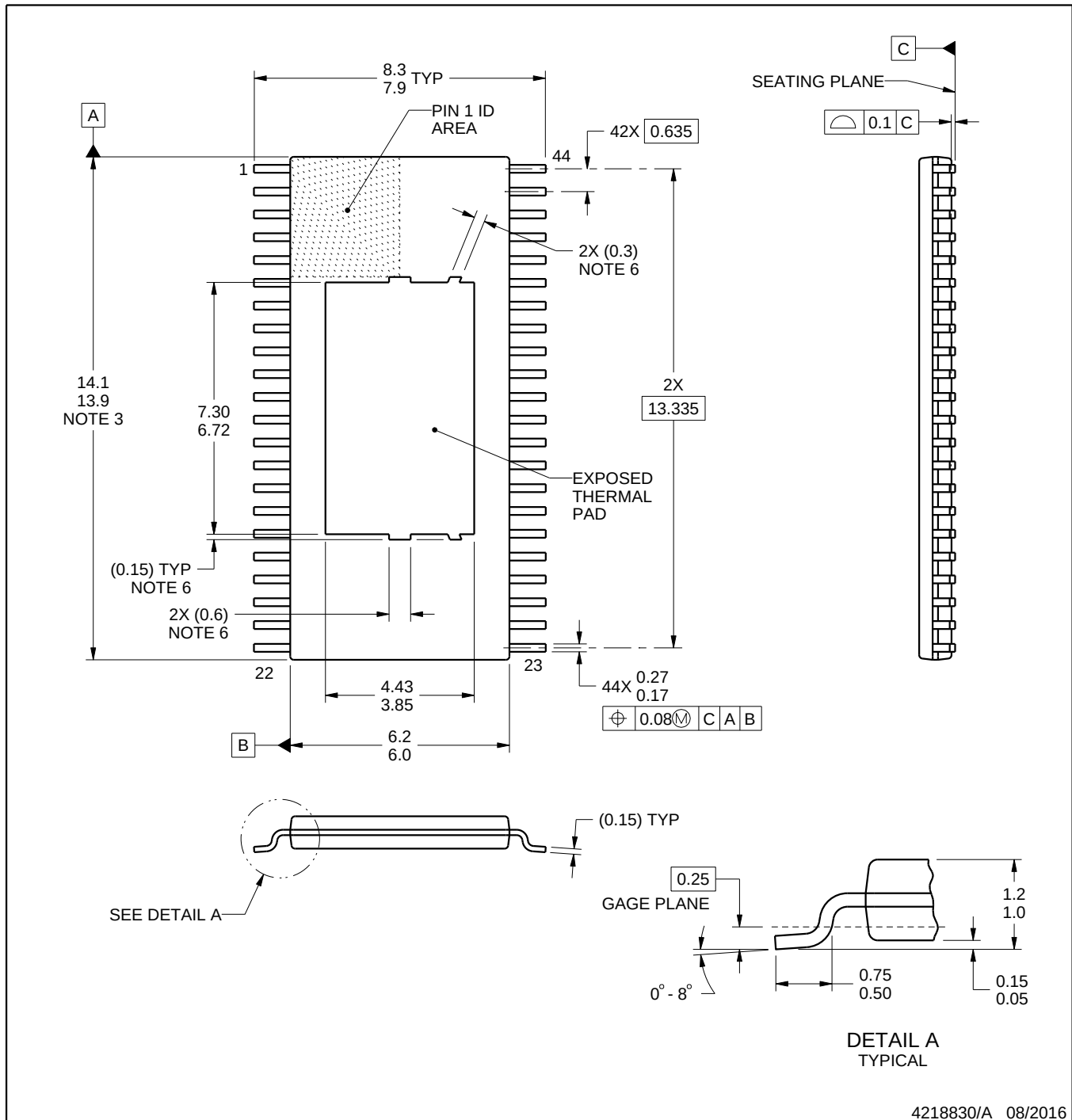
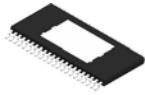


*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TAS5614LADDV	DDV	HTSSOP	44	35	530	11.89	3600	4.9
TAS5614LADDV.B	DDV	HTSSOP	44	35	530	11.89	3600	4.9



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



4218830/A 08/2016

NOTES:

PowerPAD is a trademark of Texas Instruments.

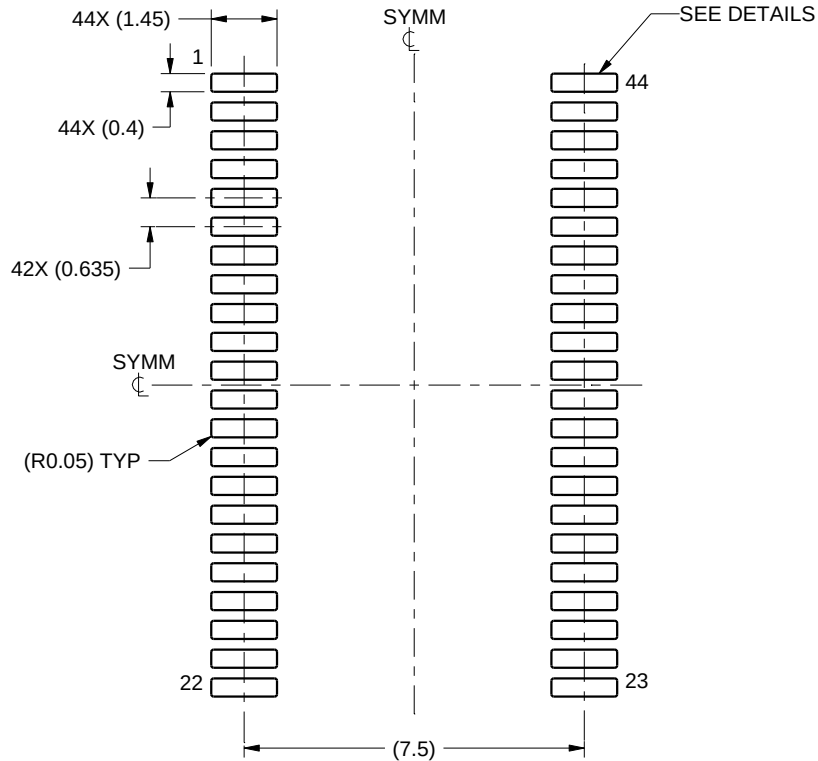
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-153.
5. The exposed thermal pad is designed to be attached to an external heatsink.
6. Features may differ or may not be present.

EXAMPLE BOARD LAYOUT

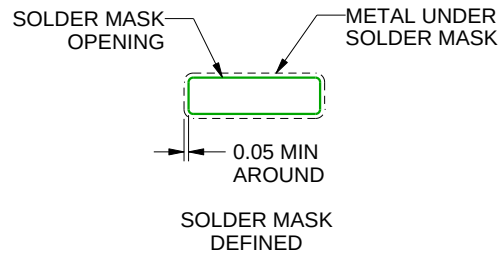
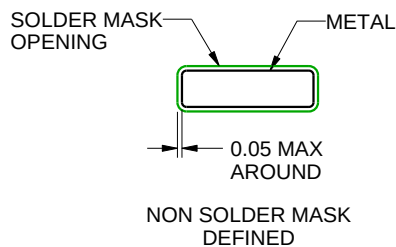
DDV0044D

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE
SCALE:6X



SOLDER MASK DETAILS
NOT TO SCALE

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NOTES: (continued)

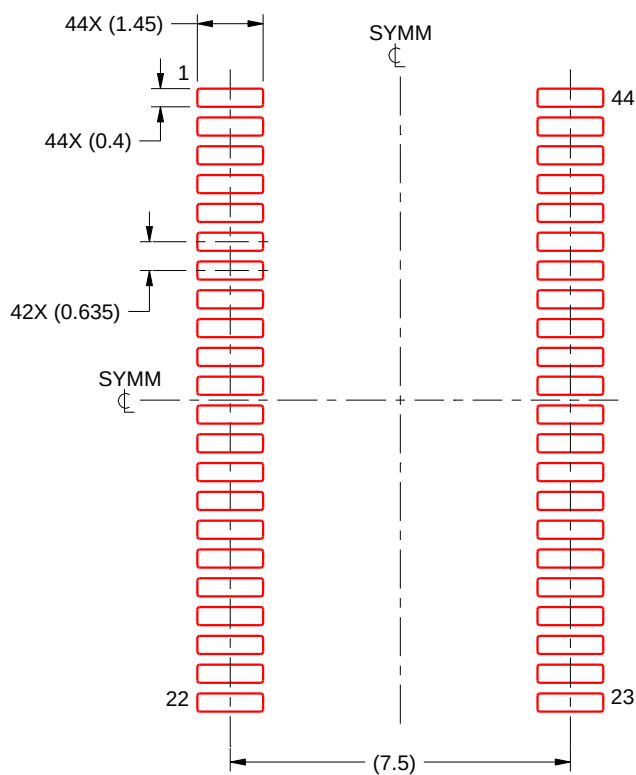
7. Publication IPC-7351 may have alternate designs.
8. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DDV0044D

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE
BASED ON 0.125 MM THICK STENCIL
SCALE :6X

4218830/A 08/2016

NOTES: (continued)

9. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
10. Board assembly site may have different recommendations for stencil design.

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最后更新日期：2025 年 10 月