

## **EtherCAT<sup>®</sup> Master on Sitara<sup>™</sup> Processors**

EtherCAT<sup>®</sup> Master on Sitara<sup>™</sup> Processors Training Series [Part 2] Acontis and CoDeSys EtherCAT Master Software Architectures



# **Training series agenda**

### Part 1:

- Overview of Training Series
- Sitara processors family in factory automation
- EtherCAT protocol technology review

### Part 2:

- Acontis EtherCAT master software architecture on top of TI-RTOS and RT Linux
- CoDeSys EtherCAT master software architecture on top of RT Linux **Part 3**:
- EtherCAT master + time-triggered send (TTS)
- EtherCAT master on Sitara: A scalable and flexible solution



### Acontis EtherCAT Master Software Architecture on TI-RTOS and RT Linux



# **Acontis EC-Master features**

acontis

- EtherCAT master (EC-Master) Class A and Class B available
- Integrated diagnostics capabilities
- Optimized link layers for real-time systems
- Different OS are supported, among them TI-RTOS and Linux.
- Acontis offers EC-Engineer as a configuration and diagnostics tool, which can be used online or offline.





## Acontis EC-Master Stack modules

L\_\_\_





## **EtherCAT Masters TI Designs**

EtherCAT Master Reference Design on Sitara AM57x Gb Ethernet and PRU-ICSS with TTS: <u>http://www.ti.com/tool/tidep0079</u>

Acontis EtherCAT Master Stack Reference Design: <a href="http://www.ti.com/tool/tidep0043">http://www.ti.com/tool/tidep0043</a>







TI Home > TI Designs > Processors > EtherCAT® Master Reference Design on Sitara AM57x Gb Ethernet and PRU-ICSS with Time Triggered Send

Worldwide (In English)

#### EtherCAT® Master Reference Design on Sitara AM57x Gb Ethernet and PRU-ICSS with Time Triggered Send

(ACTIVE) TIDEP0079

distributed clocking is not used.



\$899.00(USD)

#### 堪 Texas Instruments

7





# **Acontis EC-Master software block diagrams**

**GMAC (CPSW)** 



NOTE: EC-Master can run on PRU-ICSS Ethernet ports or GMAC ports when using AM57x IDK boards.

On AM335x, AM437x boards, EC-Master runs on CPSW ports.





**PRU-ICSS** 

## EtherCAT Master: Bus timing diagram (CPU load)

### CPU load measured in Inputs, Outputs, Administration, and Send Acyclic periods





## Acontis EC-Master: CPU load benchmark

#### Table 1. AM572x EC-Master CPU Performance Operating on GMAC

Sitara AM572x 1000 MHz NIC: GMAC TI-RTOS (SYS/BIOS)				
NUMBER	EC-MASTER JOB	AVERAGE µs		
1	I: Process Inputs	9		
2	O: Send Outputs	5		
3	A: Administration	4		
4	M: Send Acyclic Frame	2		
Total CPU Time		20		

#### Table 2. AM572x EC-Master CPU Performance Operating on ICSS\_PRU

Sitara AM572x 1000 MHz NIC: ICSS_PRU TI-RTOS (SYS/BIOS)				
NUMBER	EC-MASTER JOB	AVERAGE µs		
1	I: Process Inputs	3		
2	O: Send Outputs	15		
3	A: Administration	5		
4	M: Send Acyclic Frame	2		
Total CPU Time		25		

TI design link: http://www.ti.com/lit/ug/tidubz1b/tidubz1b.pdf



acontis

### **CoDeSys EtherCAT Master Software Architecture on RT Linux**



# CoDeSys development system



### **CoDeSys development system:**

- A powerful IEC 61131-3 programming tool for programmable logic controllers
- Produces native machine code for different processors

### **Runtime features:**

- CoDeSys runtime system architecture is based on components.
- Each component has a well-defined interface.
- Users can 'pick' the right modules for their application.



# **CoDeSys runtime modules**







# **CoDeSys EtherCAT Master**



- EtherCAT Master protocol stack realized as CoDeSys library:
  - Compiled together with the application
  - Portable for different compatible platforms
- Support of multiple EtherCAT gateway clamps:
  - Integrated gateway functionality
  - Possible multiple fieldbuses
- Integrated diagnostics: Generic and EtherCAT-specific
- Integrated safety up to SIL3 with EtherCAT Safety Module
- Operating system for Sitara: RT Linux
- TI design coming soon



## **CoDeSys EtherCAT Master library**



#### EtherCAT Master Lib

1	Library Manager 🗙						
💁 Add	🕁 Add library 🗙 Delete library 🖙 Properties 📷 Details 🛛 🐺 Placeholders 🎁 Library repository						
Name		Namespace	Effective version				
+10	Standard = Standard, 3.5.7.0 (System)	Standard	3.5.7.0				
±-+10	BreakpointLogging = Breakpoint Logging Functions, 3.5.5.0 (3S - Smart Software Soluti	BPLog	3.5.5.0				
÷- +10	VisuDialogs = VisuDialogs, 3.5.7.0 (System)	VisuDialogs	3.5.7.0				
±-+10	IoStandard = IoStandard, 3.5.1.0 (System)	IoStandard	3.5.1.0				
10	3SLicense = 3SLicense, 3.5.6.0 (3S - Smart Software Solutions GmbH)	_3S_LICENSE	3.5.6.0				
±	SM3_Basic = SM3_Basic, 3.5.7.20 (3S - Smart Software Solutions GmbH)	SM3_Basic	3.5.7.20				
±- +10	SM3_CNC = SM3_CNC_3.5.7.0.(3S - Smart Software Solutions GmbH)	SM3_CNC	3.5.7.0				
÷ •10	IODrvEtherCAT = IODrvEtherCAT, 3.5.7.0 (3S - Smart Software Solutions GmbH)	IoDrvEthercatLib	3.5.7.0				
+ •10	SM3_Drive_ETC = SM3_Drive_ETC, 3.5.7.0 (3S - Smart Software Solutions GmbH)	SM3_Drive_ETC	3.5.7.0				
+-+10	SM3_Drive_ETC_EL2521, 3.5.7.0 (3S - Smart Software Solutions GmbH)	SM3_Drive_ETC_EL2521	3.5.7.0				
	IODrvEL6900 = IODrvEL6900, 3.5.6.0 (3S - Smart Software Solutions GmbH)	IoDrvEL6900	3.5.6.0				
+ •10	SM3_Drive_ETC_Schneider_Lexium32, 3.5.5.0 (3S - Smart Software Solutions GmbH)	SM3_Drive_ETC_Schneider_Lexium32	3.5.5.0				
*-+10	SM3_Drive_ETC_STOEBER_SD6, 3.5.7.0 (3S - Smart Software Solutions GmbH)	SM3_Drive_ETC_Stoeber_SD6	3.5.7.0				
±-+10	SM3_Drive_ETC_DANAHERS400S600, 3.5.3.0 (3S - Smart Software Solutions GmbH)	SM3_Drive_ETC_DANAHERS400S600	3.5.3.0				
+- +10	IoDrvProfinetMaster = IoDrvEL6631, 3.5.7.0 (3S - Smart Software Solutions GmbH)	IoDrvEL6631Lib	3.5.7.0				
±-+10	EL6751_CANMiniDriver = EL6751_CANMiniDriver, 3.5.2.0 (3S - Smart Software Solution	EL6751_CANMiniDriver	3.5.2.0				
± - +10	3S CANopenSlaveStack = 3S CANopenSlaveStack, 3.5.6.20 (3S - Smart Software Soluti	_3SCSS	3.5.6.20				

#### EtherCAT Master with other fieldbuses

🖹 🗐 EtherCAT_Master_SoftMotion (EtherCAT Master SoftMotion)				
🖃 💮 EK1100 (EK1100 EtherCAT Coupler (2A E-Bus))				
🖶 🏢 EL2521_0024 (EL2521 1Ch. Pulse Train Output (SoftMotion))				
EL2008 (EL2008 8Ch. Dig. Output 24V, 0.5A)				
🖳 📑 EL6900 (EL6900, FSoE PLC with Safety Plugins)				
EL6631 (EL6631 PROFINET IO Controller)				
🖹 👔 EL6631_Profinet_Gateway (EL6631 Profinet Gateway)				
🖻 👘 s20_pn_вк (s20-pn-вк)				
I S20 AO 8 (S20-AO-8)				
EL6751_CANMiniDriver_1 (EL6751 CAN MiniDriver (32 Messages)				
🖃 🍐 CANbus				
🖃 🚮 CANopen_Manager (CANopen_Manager)				
🖹 - \iint BL20_E_GW_CO (BL20-E-GW-CO)				
Generic_BL20_2DI (Generic BL20-2DI)				
Generic BL20 2DO (Generic BL20-2DO)				
EL6631_0010 (EL6631-0010 PROFINET IO Device)				
EL6631_0010_1 (EL6631-0010)				
EL6731 (EL6731 PROFIBUS DP Master)				
🖻 💮 EL6731_PB_Master (EL6731-PB Master)				
□ 2 IL_PB_BK_DIS_DO4_EF (IL PB BK DI8 DO4/EF)				
S III BK DI8 DO4 8Bit (BK: DI8 DO4 (8Bit))				
SD6 (SD6_CBM_SoftMotion)				
🖓 Z_Axis (SM_Drive_ETC_STOEBER_SD6)				
AX2000_B110 (AX2000-B110 EtherCAT Drive (CoE) SoftMotion incl. Encoder)				
🕬 M2 (SM_Drive_EtherCAT_BeckhoffAX2xxx)				



# **CoDeSys system block diagram**







## For more information

- Sitara Processors Overview http://www.ti.com/sitara
- EtherCAT Masters TI Designs:
  - Acontis EtherCAT Master Stack Reference Design: <u>http://www.ti.com/tool/tidep0043</u>
  - EtherCAT Master Reference Design on Sitara AM57x Gb Ethernet and PRU-ICSS with TTS: <u>http://www.ti.com/tool/tidep0079</u>
- Online training:
  - Sitara AM57x Processors: <u>https://training.ti.com/am57x-sitara-processors-training-series</u>
  - Sitara AM437x Processors: <u>https://training.ti.com/am437x</u>
- CoDeSys EtherCAT Master: <a href="https://www.codesys.com/products/codesys-fieldbus/industrial-ethernet/ethercat.html">https://www.codesys.com/products/codesys-fieldbus/industrial-ethernet/ethercat.html</a>
- Acontis EtherCAT Master for TI processors: <u>http://www.acontis.com/eng/products/downloads/ethercat-for-ti-processors.html</u>
- Other industrial protocols: <u>http://www.ti.com/tool/PRU-ICSS-INDUSTRIAL-SW</u>
- For questions about this training, refer to the E2E Sitara Processors Forums: <u>https://e2e.ti.com/support/arm/sitara\_arm/f/791</u>







©Copyright 2017 Texas Instruments Incorporated. All rights reserved.

This material is provided strictly "as-is," for informational purposes only, and without any warranty. Use of this material is subject to TI's **Terms of Use**, viewable at TI.com