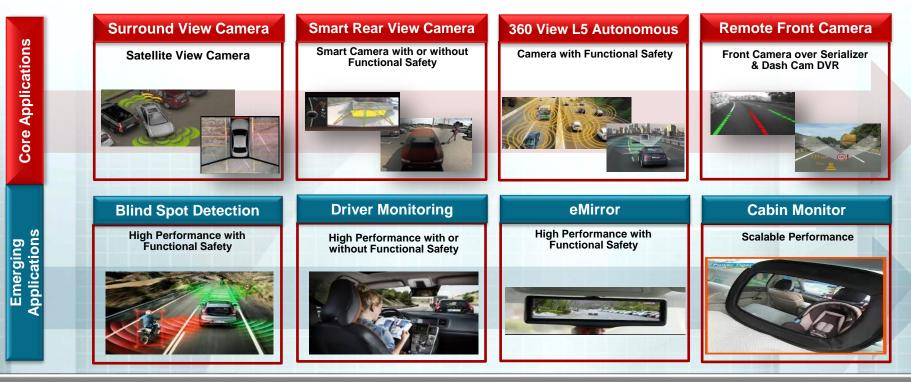
# TI 車用微型高度整合降壓轉換器兼容機 能安全解決方案

April 2019



## **Auto Camera Module PMIC - Target Auto Camera Applications**



Scalable Platforms from functional safety to non-safety Auto Camera Applications with Future Proof Autonomous Driving Vehicles



# **Automotive Camera PMIC**

Integrated Power Management April, 2019



# Mid Vin Multi-rail Camera PMIC

#### Preliminary Subject to Change

#### **Features**

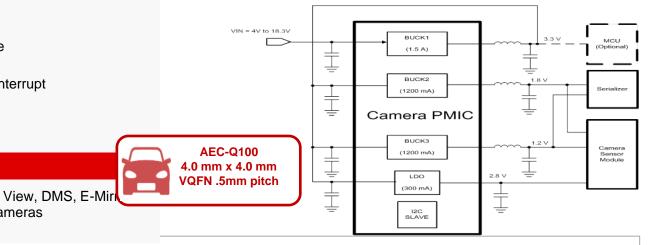
- Mid Vin Buck Regulator, Vout= 3.0V 4.0V
  - Operating  $V_{IN}$  Range from 4.0V 18.3V
  - 1.5A, 2.3 MHz switching frequency, spread spectrum
- Two Low Vin Buck Regulators, Vout = 0.9V 1.9V
  - Operating  $V_{IN}$  Range from 2.5V 5.5V
  - 1.2A, 2.3 MHz switching frequency , spread spectrum
- Low Noise LDO, Vout= 2.7V 3.3V, 25mV steps
  - Operating V<sub>IN</sub> Range from 2.2V 5.5V
  - High PSRR (~75dB @ 1KHz)
  - 300mA; 300mV Dropout
- Up to 3.4MHz High Speed I2C interface
- Programmable up/down sequencing
- Power Good, OV/UV/OC/system fault interrupt
- Forced PWM
- 150°C max Junction Temp

## Applications

Surround View, Rear View, Front View, DMS, E-Mirl
DVR and Autonomous Driving Cameras

#### Benefits

- Cost Optimized low-cost, low noise solution for camera modules
- Solution Size Optimized and Fully Integrated power solution in a 4.0 x 4.0 mm QFN package with wettable flanks
- Flexibility and Efficiency enabled by triple DCDC/ one LDO design with factory programmed voltage & sequence with 130nm process
- Ease of Design with user programmability during project development
- Better Reliability and Component Logistics with less components compared to discrete power





Support Automotive Imagers from the Following Companies Plus Other Imager Vendors





**ON Semiconductor** 

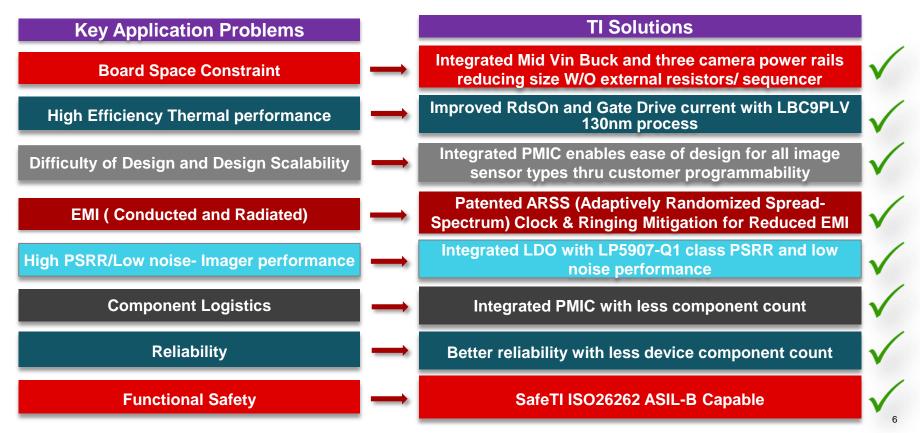




#### Contact TI for a list of Imagers Supported



# **Next Gen PMIC Value Propositions**

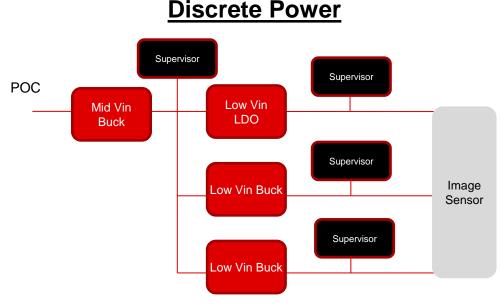




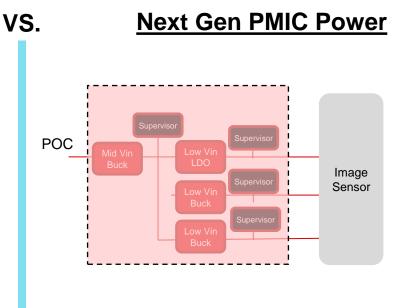
# Space Saving and Component Count Reduction



## Auto Camera Module Power with Functional Safety – Discrete vs. PMIC



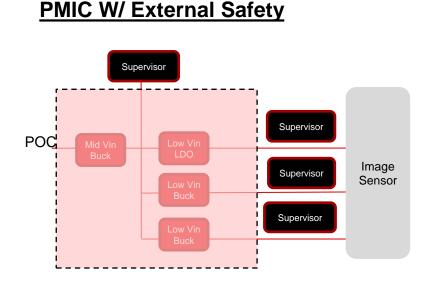
- Eight power components
- Eight resistors (voltage settings)
- Huge PCB routing/spacing overhead



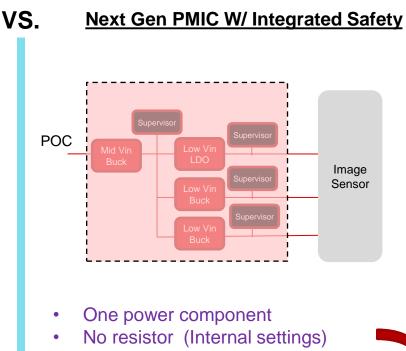
- One power component
- No resistor (Internal settings)
- Minimum PCB routing overhead



## Auto Camera Module Power with Functional Safety – PMIC with External Safety vs. PMIC with Integrated Safety



- Five power components
- Eight resistors (voltage settings)
- Large PCB routing/spacing overhead



Minimum PCB routing overhead

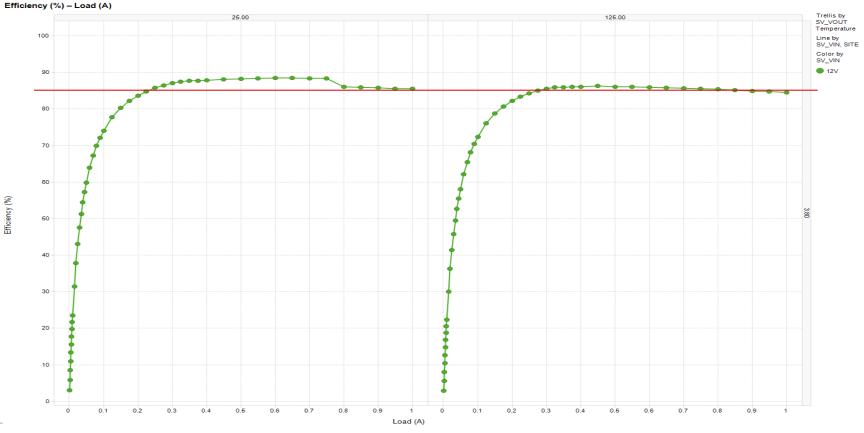




# **Efficiency Measurement**



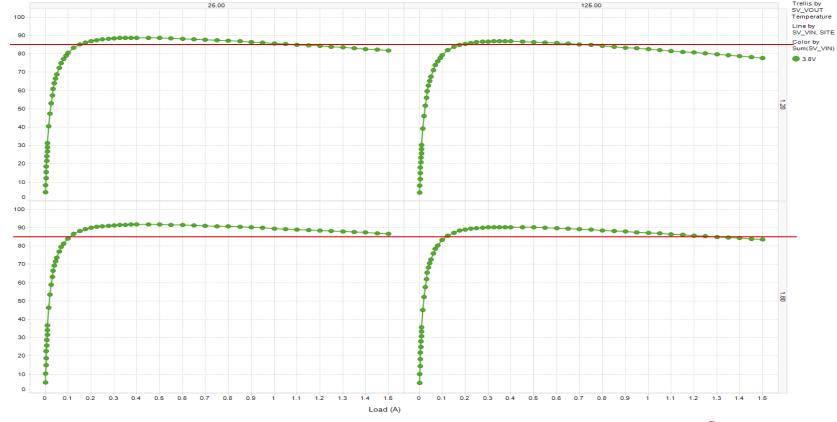
## BUCK1 Efficiency ( $V_{IN}$ =12V, $V_{OUT}$ = 3.8V) Measured



🜵 Texas Instruments

# BUCK2 Efficiency ( $V_{IN} = 3.8V$ , $V_{OUT} = 1.2V/1.8V$ ) Measured

Efficiency (%) - Load (A)

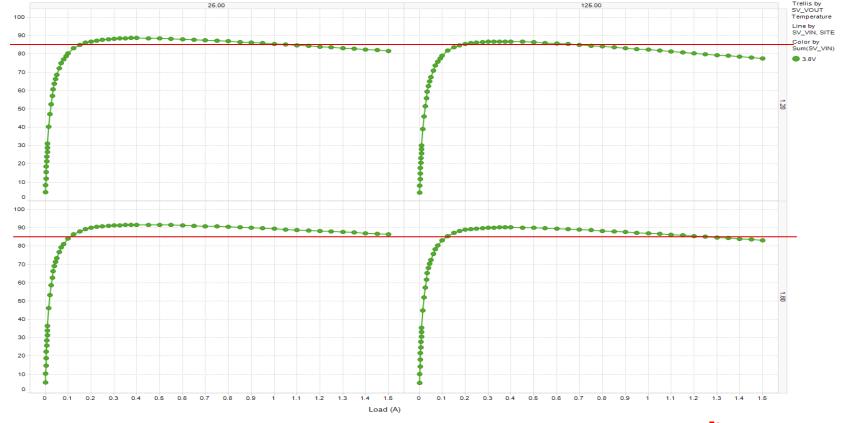


🜵 Texas Instruments

Efficiency (%)

## BUCK3 Efficiency ( $V_{IN} = 3.8V$ , $V_{OUT} = 1.2V/1.8V$ ) Measured

Efficiency (%) - Load (A)



🜵 Texas Instruments

Efficiency (%)

# **Ease of Use and User Programmability**



## **Customer EEPROM Configurability during Development**

#### 1. Socketed EVM Method

- Insert the 1 PMIC device into the socket of the socketed EVM
- Program the PMIC device with the GUI provided by TI
  - Configure Output voltage settings
  - Configure Power sequencing
  - Configure Other parameters (e.g. Spread Spectrum on/off and etc.)
- Remove the PMIC device from the socketed EVM and put it on the customer development board
- Turn on the development board power

#### 2. Development Board Method

- Solder the PMIC device onto the customer development board
  - By pulling up the SEQ pin, Buck1 and Buck2 power rails are enabled for 3.3V and 1.8V to support Serializer backchannel programming. Buck3 and LDO are default off if the GPIO pin is pulled down or no connect.
- Program the PMIC device thru Serializer's I2C backchannel
  - Configure Output voltage settings
  - Configure Power sequencing
  - Configure Other parameters (e.g. Spread Spectrum on/off and etc.)
- · Restart the development board power and PMIC will output desired output voltages and power sequencing and etc





## Next Gen PMIC Customer EEPROM Configurability In Development

- Benefits
  - Ease of Use
    - GUI and Socketed EVM ease of use as well as easy on board programming
  - Massively Reduce Cycle Time of Parameter Tuning Iterations During Project Development
    - · Faster time to market and development time saving
  - Scalable to Support Various image Sensor Types, Serializers and ISPs/SoCs
    - One PMIC scalable for multiple camera module platforms
  - Eliminate the Need of External Voltage Divider Resistors for Voltage Settings
    - Space saving
    - · Less components in material logistics
  - Eliminate the Need of External Power Sequencer or Sequencing Logic
    - Space saving
    - Cost Saving
    - · Less components in material logistics and less components for better reliability



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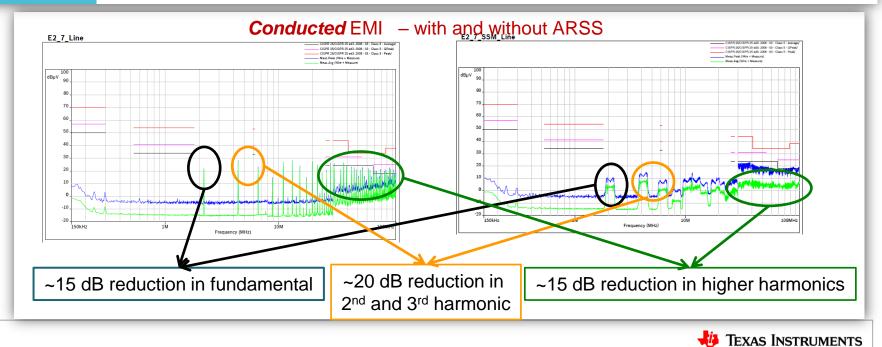
# **EMI Reduction**



# **ARSS: Adaptively Randomized Spread Spectrum**

EMI Mitigation IP

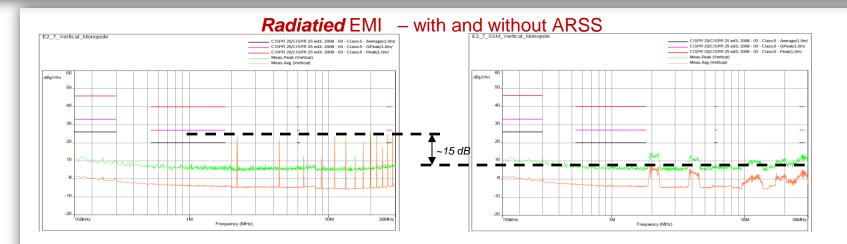
Value Proposition	Algorithm & circuit design <b>that reduces conducted and radiated EMI spurs</b> by > <b>10dB</b> without affecting the voltage ripple or efficiency, through advanced, randomized spreading of switching frequency.
Differentiation	Ability to achieve >10dB reduction in fundamental spur with only 10% frequency spreading. The approach also avoids low frequency spurs caused by triangular modulation spread spectrum techniques.



# **ARSS: Adaptively Randomized Spread Spectrum**

**EMI Mitigation IP** 

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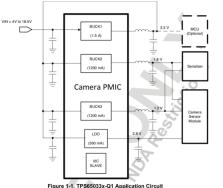


~15 dB average reduction across radiated 150 kHz to 30 MHz range

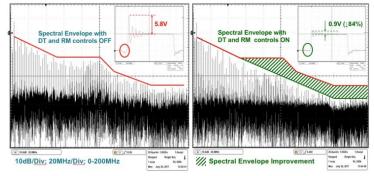


#### **Ringing Mitigation IP, Dead-Time Control IP** Implementation for EMC

- Ringing mitigation IP and dead-time control IP
- Focus on EMI mitigation in the pre-regulator MVBK
- Ringing mitigation scheme includes "passive" and "active" elements
- LVBK power stage techniques
  - Slew rate controlled gate driver design
  - Patented adaptive dead-time control to minimize reverse recovery
- Silicon-proven ARSS Spread Spectrum Modulation IP to be used in both MVBK and LVBK and will add additional robustness



#### **Transient/Frequency Performance (Measured)**



+10dB ringing reduction on the switch-node, **without Spread-Spectrum Modulation**, enabling hot-rod level transient performance in a wire-bonded package (QFN)



# High PSRR and Low Noise LDO



## LDO PSRR

Frequency	Measured Value	Target Spec
1KHz	74 dB	75
10KHz	71 dB	65
100KHz	53 dB	40
1MHz	35 dB	20

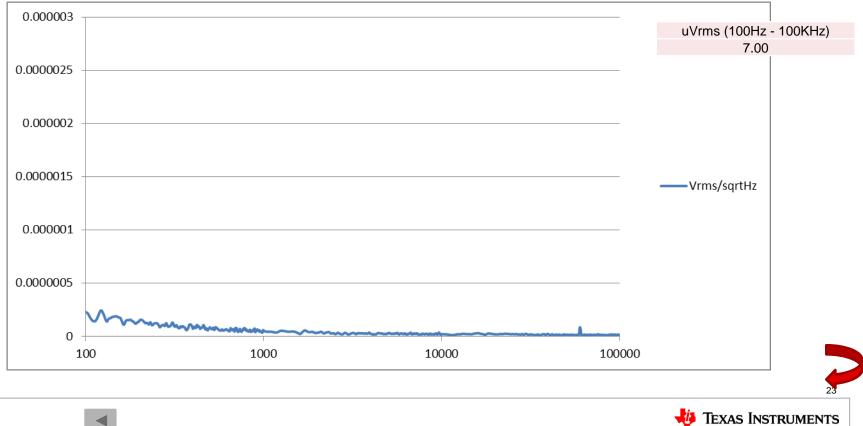
 $T_A = 25^{\circ}C$  $V_{IN} = 3.3V$  $V_{OUT} = 2.8V$  $I_{OUT} = 300mA$ 

PSRR performance will be higher than the numbers shown if Vin and Vout delta is increased



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# LDO Noise, 3.3Vin, 2.8Vout, 300mA



# **Functional Safety**



# **Next Gen PMIC Functional Safety**

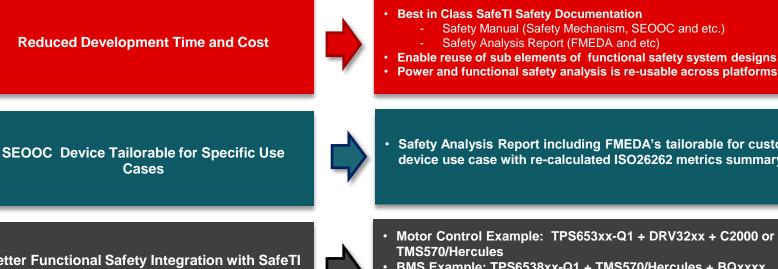
- TI SafeTI<sup>™</sup> devices are catalog devices developed as Safety Elements out of Context (SEooC)
  - Safety Element out of Context (SEooC) A safety-related element which is not developed for a specific item (specific system, application, safety goal).. This means it is not developed in the context of a particular vehicle.
  - A SEooC developed in accordance to ISO 26262: Is intended to be reusable under given assumptions. SafeTI<sup>™</sup> documentation is provided to help customers put the SEooC into the context of their system
- The PMIC device is ASIL-B capable metrics with SPFm ≥90% and LFm ≥60% for permanent random hardware and transient failures
- The development process of the PMIC device complies with SafeTI™ ISO26262 ASIL-D requirements



# SafeTI<sup>™</sup> Functional Safety PMIC Benefits

## **Benefits**

# **TI Solutions**





 Safety Analysis Report including FMEDA's tailorable for customer device use case with re-calculated ISO26262 metrics summary



**Better Functional Safety Integration with SafeTI** Combo



- Motor Control Example: TPS653xx-Q1 + DRV32xx + C2000 or
- BMS Example: TPS6538xx-Q1 + TMS570/Hercules + BQxxxx
- ADAS (Camera or Radar): TPS65917/9-Q1 + TDA2Ex,
- ADAS (Camera): Next Gen camera PMIC + TI FPD-Link

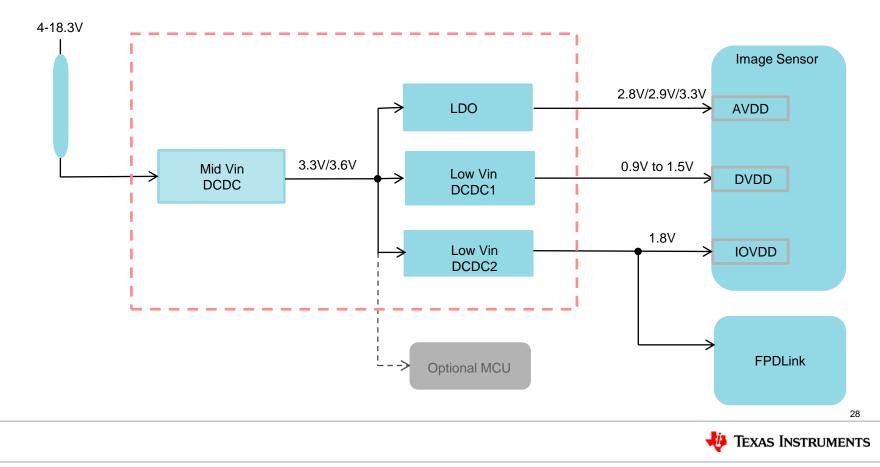




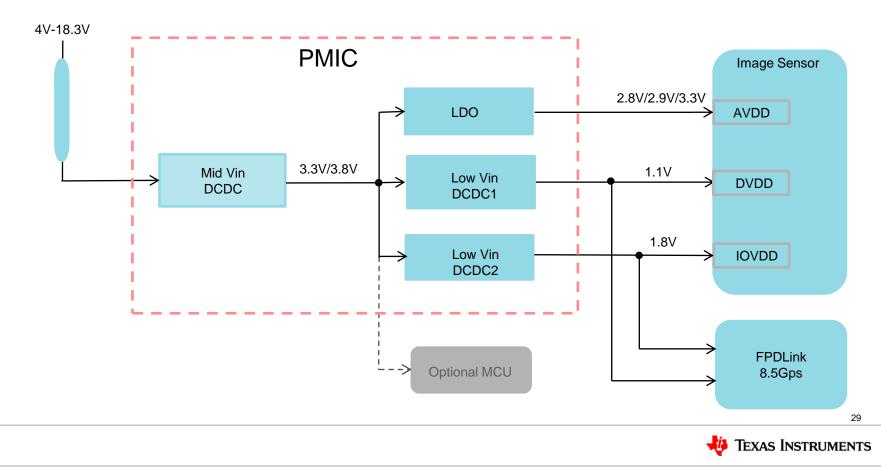
# Next Gen PMIC Application Block Diagrams



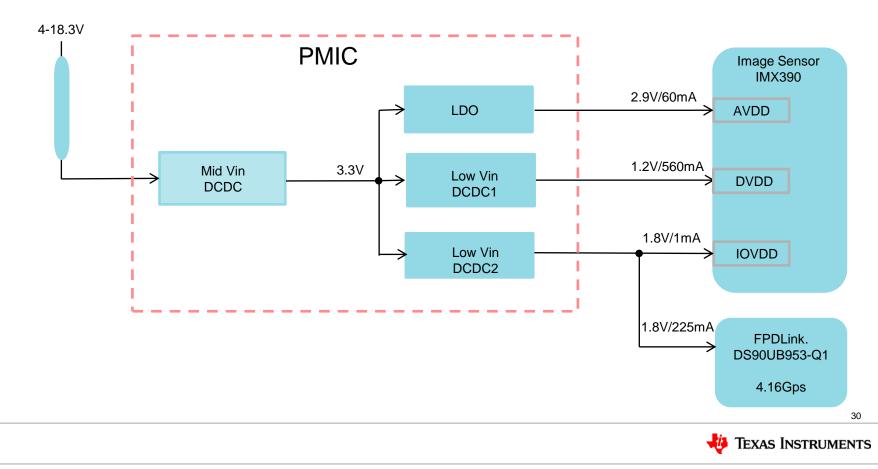
## PMIC in Automotive Camera Module With Single 1.8V Vin FPD-link



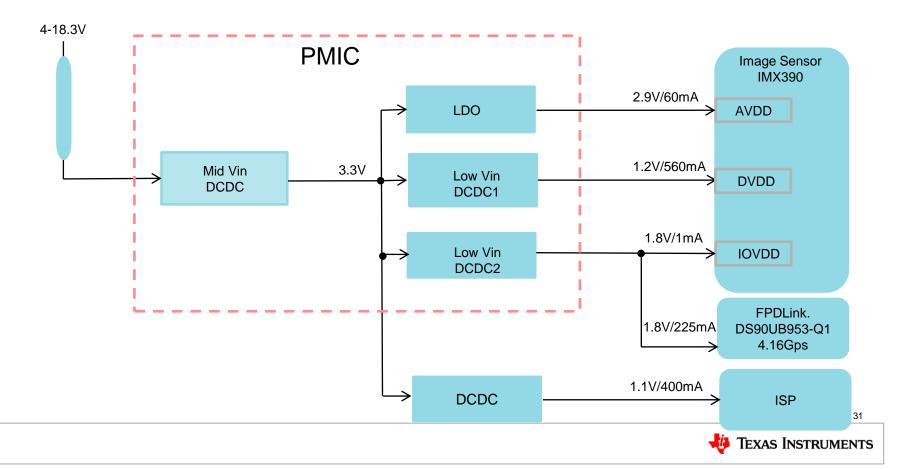
## **PMIC in Automotive Camera Module** With Dual Voltage FPD-link - Voltage of imager DVDD is same as FPD-link's



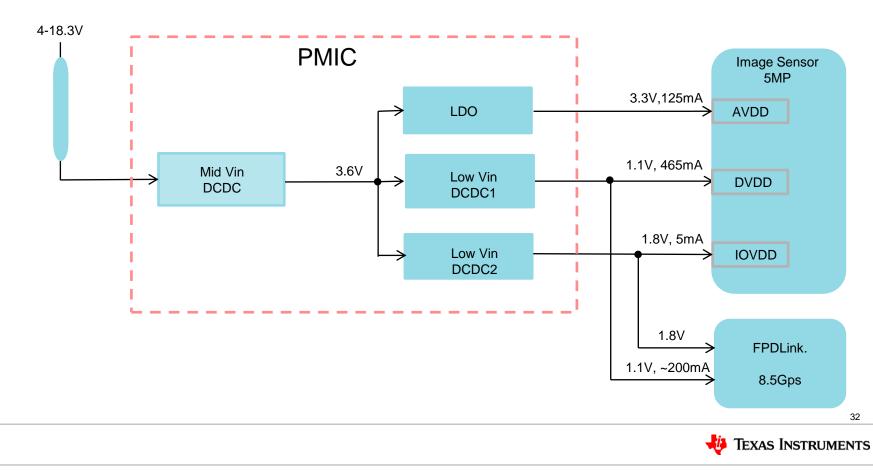
## PMIC in Automotive Camera Module – Sony IMX390 With Single Voltage FPD-link



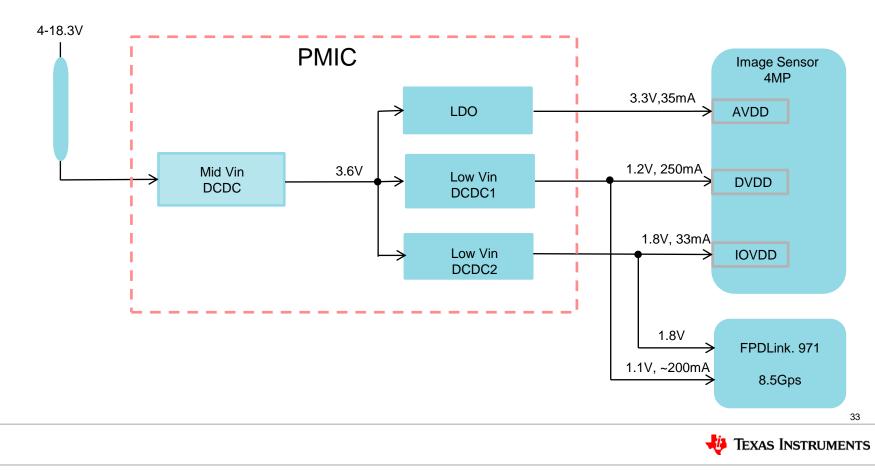
## PMIC in Automotive Camera Module – Sony IMX390 With Single Voltage FPD-link



### **PMIC in Automotive Camera Module – Example** With Dual Voltage FPD-link - Voltage of imager DVDD is same as FPD-link's



#### **PMIC in Automotive Camera Module – Example** With Dual Voltage FPD-link - Voltage of imager DVDD is same as FPD-link's



## **PMIC in Automotive Camera Module** With Dual Voltage FPD-link - Voltage of imager DVDD is different from FPD-link's

