

Meeting Space-Grade Requirements for Mission Critical Applications

Precision Analog solutions for Satellite Subsystems

Jason Clark,
Systems Engineering Manager, Space and Avionics Systems team

Michael Seidl,
Systems Engineer, Systems Engineering & Marketing - Aerospace

Agenda

- **Space Product Overview**
- **Analog front-end design with TI tooling landscape**
- **Space-grade, 50-krad, overcurrent event-detection circuit**
- **Linear Thermoelectric Cooler (TEC) Driver Circuit with high accuracy and stability and minimized noise emissions**
- **Rad-Hard and Rad-Tolerant Current Measurement Solutions**

Texas Instruments

Space Product Overview

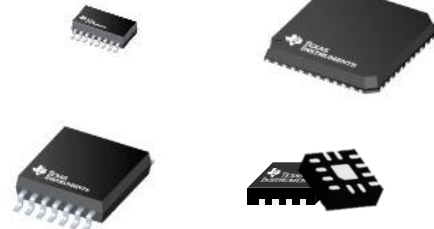
June 2022

www.ti.com/space

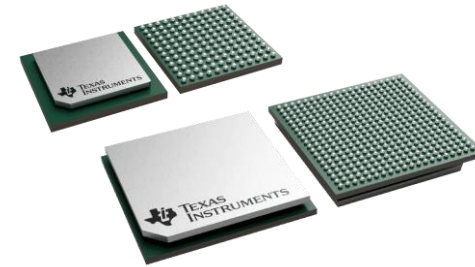
Space Products Types



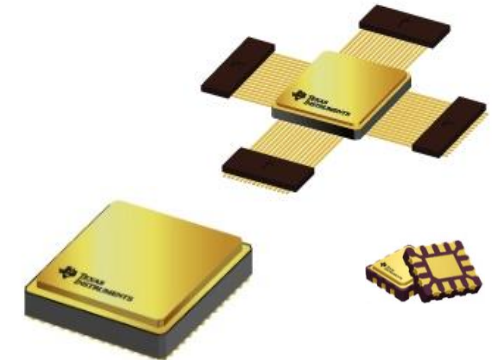
Rad Tolerant Plastic
TI Space EP



Rad Hard Plastic
QML Class P Precursor



Rad Hard FC BGA
QML Class Y Precursor
with Organic Substrate

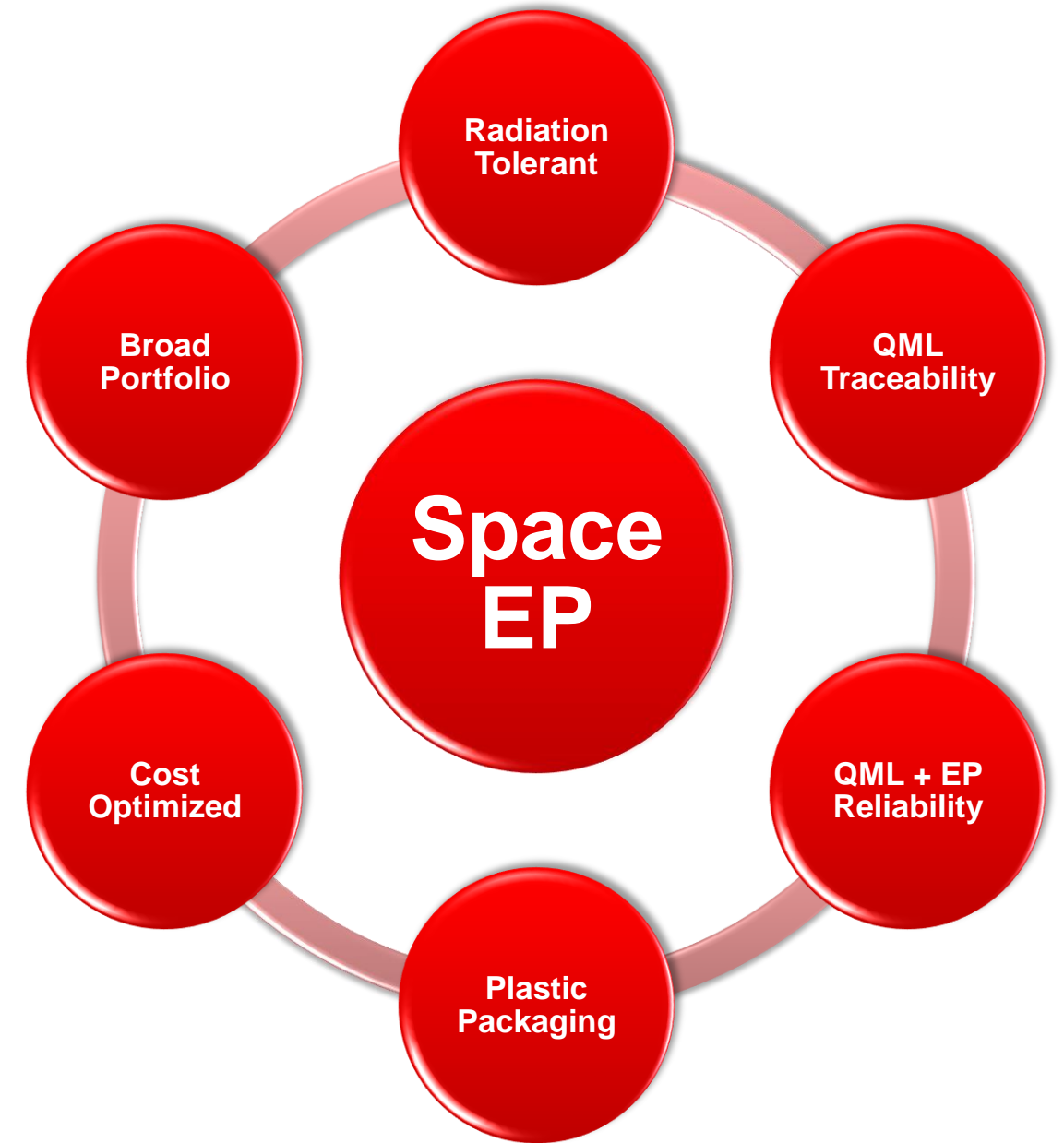


Rad Hard Hermetic
QML Class V

Packaging	Plastic	Plastic	FC on Organic Substrate	Ceramic / Metal Can
Mil. Spec	VID	VID/SMD*	VID/SMD*	SMD
Burnin	No	Yes	Yes	Yes
TID Char	30 – 50 krad(Si)		50 – 300 krad(Si)	
TID RLAT	20, 30, or 50 krad(Si)		Non-RHA, 50, 100, or 300 krad(Si)	
DSEE/SEL	43 MeV·cm ² /mg		≥ 60 MeV·cm ² /mg	

What is Space EP?

- Cost effective **radiation tolerant** solution typically for shorter duration high volume small satellites
- **Space EP = Radiation + Reliability + Traceability**
 - **Radiation**
 - TID Characterization **30 - 50 krad (ELDRS-Free)**
 - TID Radiation Lot Acceptance (RLAT): **20, 30, or 50 krad**
 - SEL/SEB/SEGR Immune to **43 MeV-cm²/mg**
 - **Reliability**
 - Military Temperature Range : -55°C to +125°C
 - Robust Material Set:
Lead Frame, Mold Compound, Au Bond Wire, etc.
 - Enhanced Qualification (HAST, Extended Temp, Meets MIL-PRF 38535 Class N)
 - **QML-Like Traceability**
 - Wafer Lot Traceability
 - Vendor Item Drawing (VID) – MilSpec



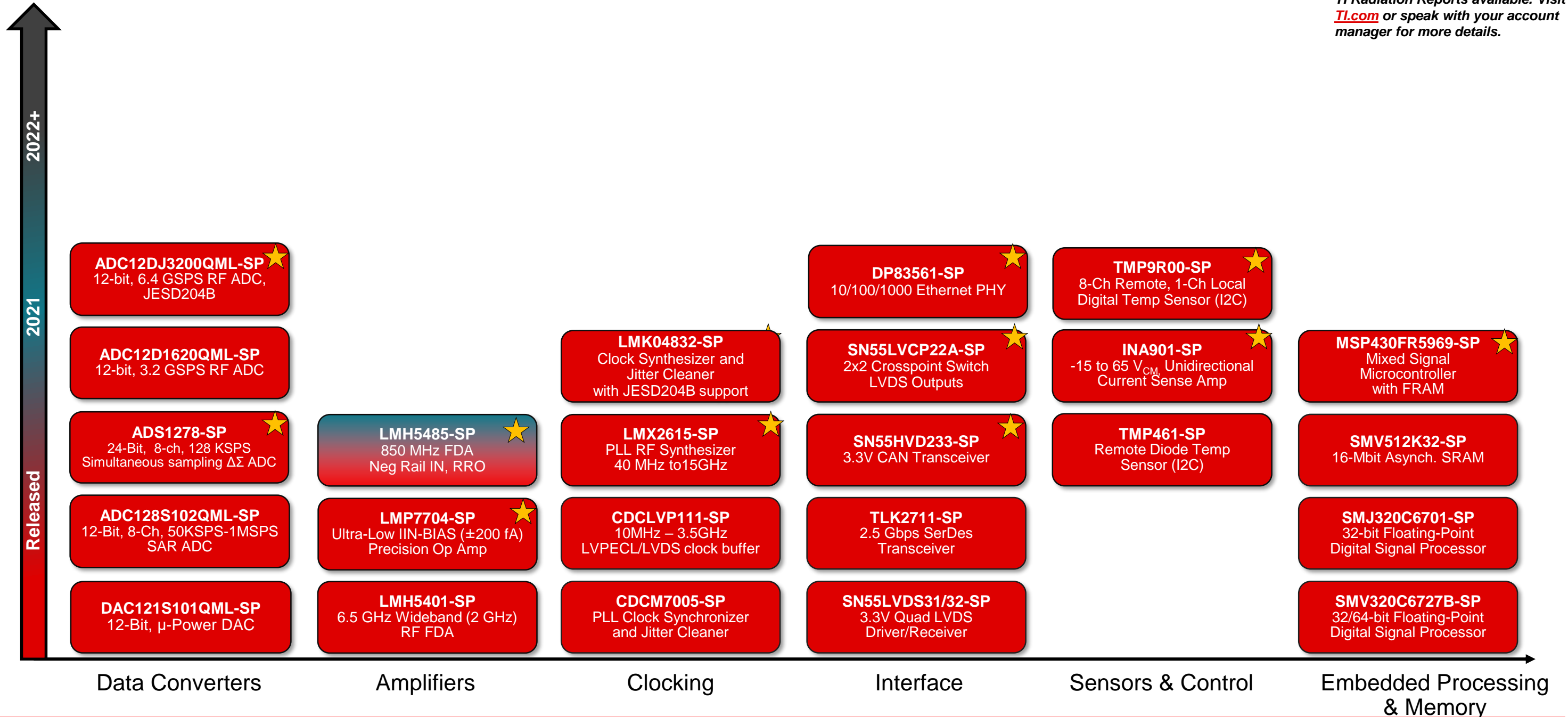
Space Signal Chain Products Roadmap

Released

★ New (2018~22)

In Development

TI Radiation Reports available. Visit TI.com or speak with your account manager for more details.



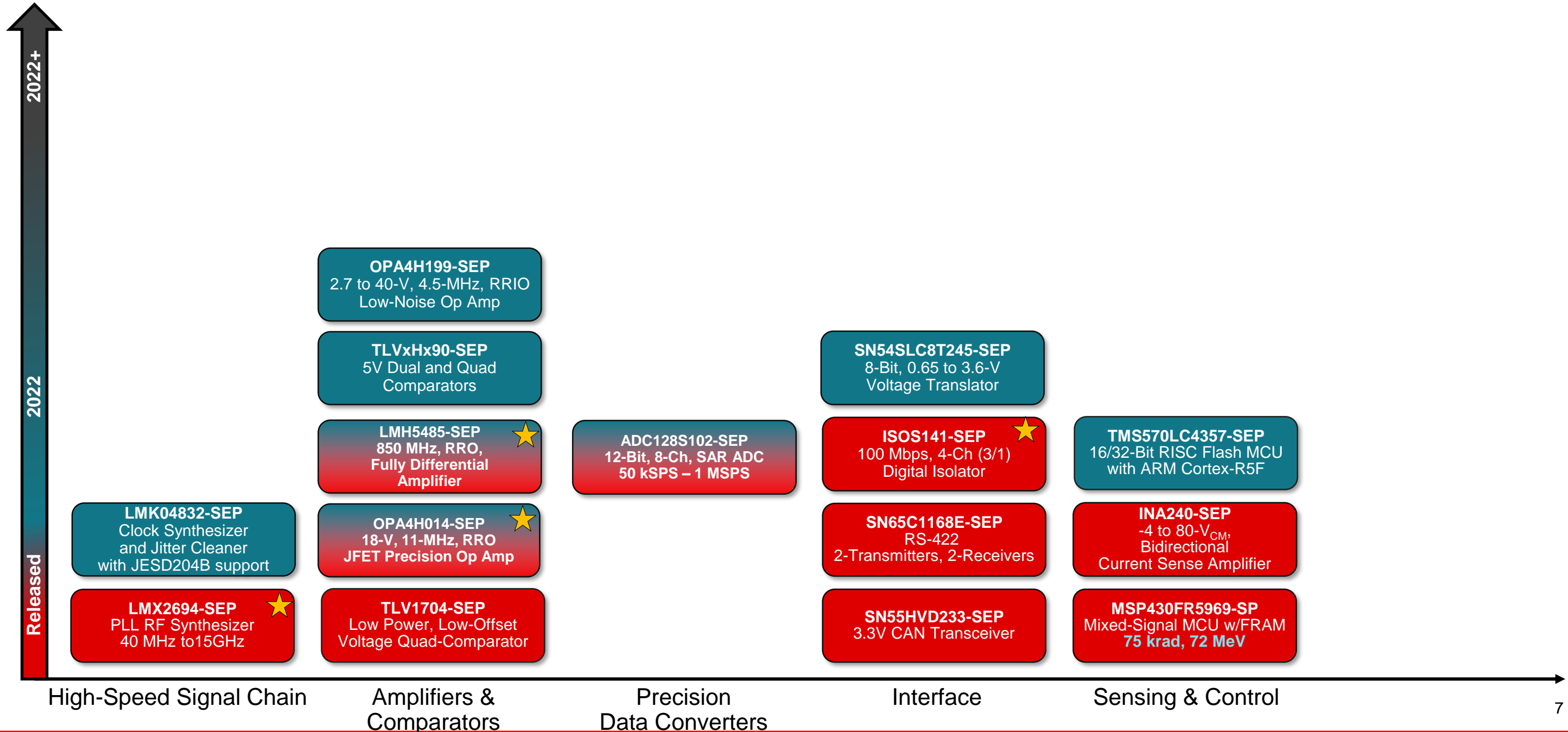
Space EP Products Roadmap

Concept

In Development

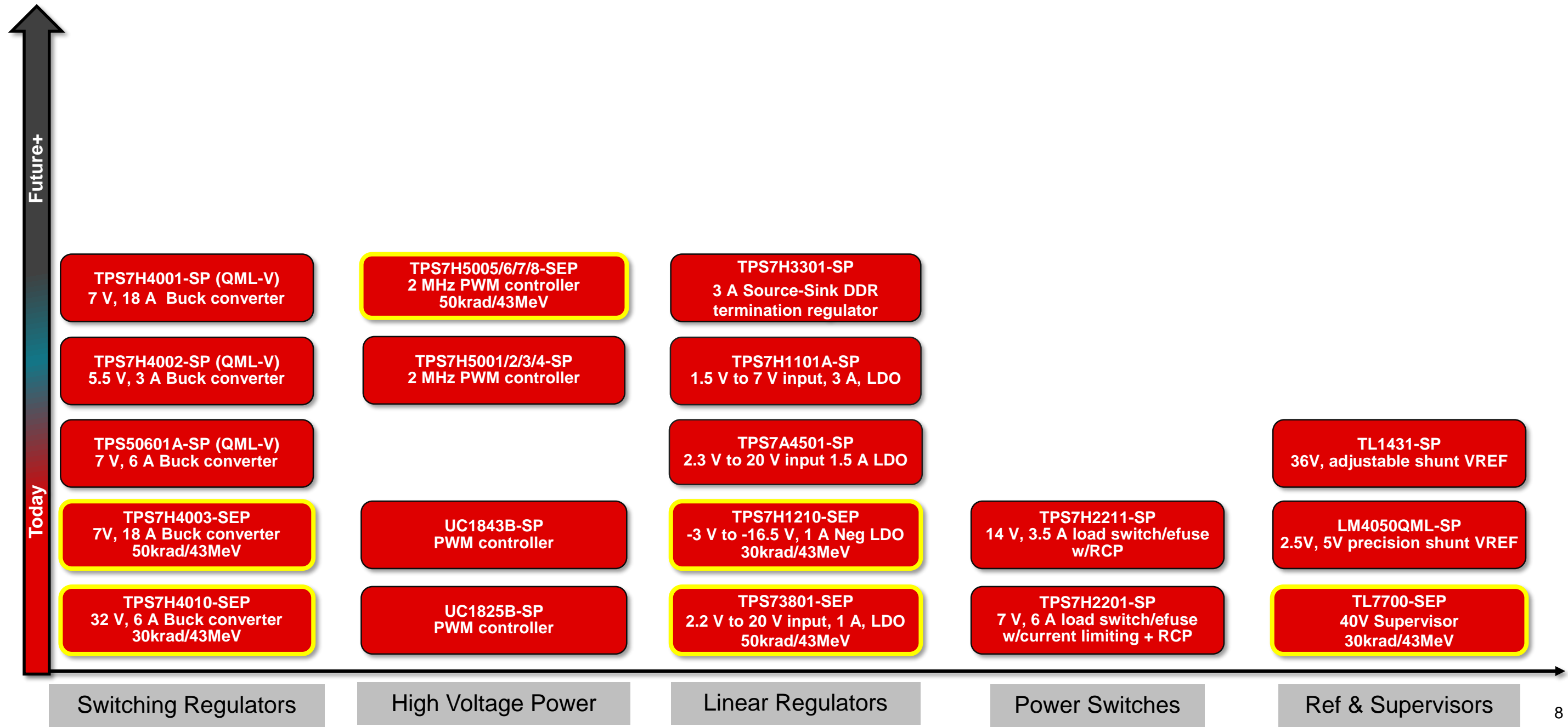
Released

★ New (2021~22)



Space Power Roadmap

Concept	Released
In Development	Plastic Package



Space Grade Satellite Telemetry Reference Design

TIDA-010197

Benefits

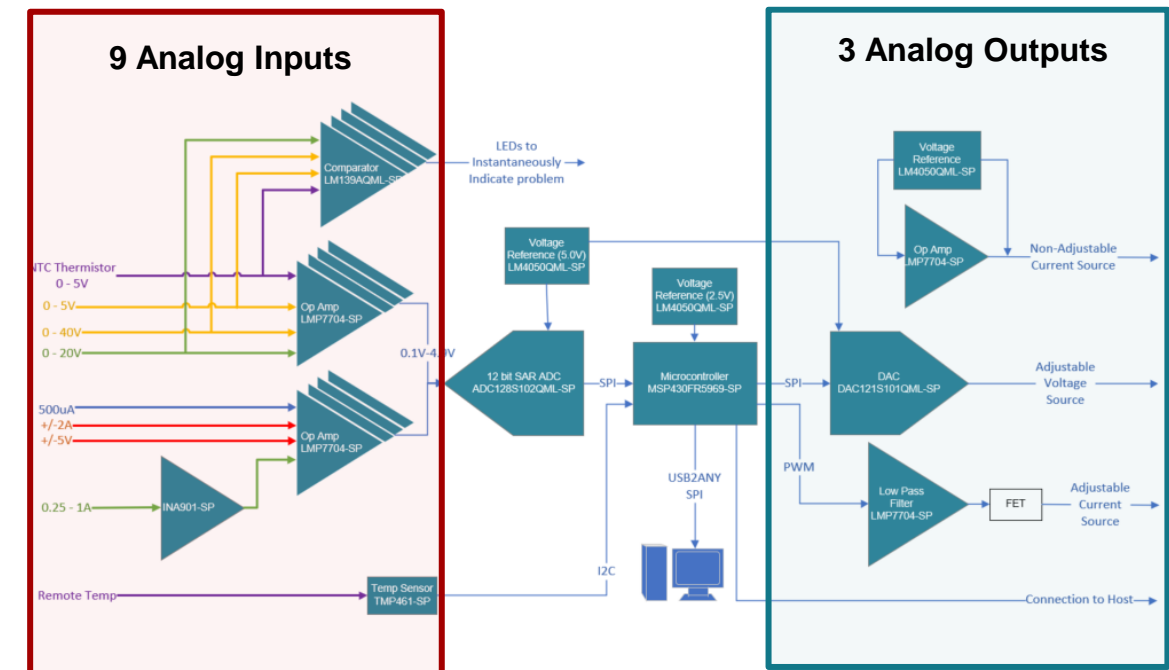
- All inclusive telemetry module to monitor a variety of measurements:
 - Voltage, Current, Temperature, Sensors (Current Output)
- Options for “5 V Rail” or “5 V and 12V Rails”
- Multiple integration options for different size, cost, and accuracy needs
 - Integrated MCU ADC (50~75 krad and 72 MeV)
 - ADC128S102QML-SP 12-Bit ADC (100 krad and 75 MeV)

Devices

- ADC128S102QML-SP 8-Ch, 12-bit ADC
- MSP430FR5969-SP FRAM Mixed-Signal Microcontroller
- LMP7704-SP Precision Quad Op Amp
- LM158QML-SP GP Dual Op Amp
- DAC121S101QML-SP 12-Bit DAC
- LM4050QML-SP Shunt Voltage Reference
- TMP461-SP Digital Output (I2C) Temp Sensor
- INA901-SP Current Sense Amp
- LM139QML-SP Quad Comparator

Target Applications

- Satellites
 - Health Monitoring / Telemetry
 - Power Monitoring on Busses
 - RF PA Biasing
 - TEC Monitor
 - Attitude & Orbit Control System (AOCS)



Multichannel JESD204B Clocking Reference Design for Space Payloads - [TIDA-010191](#)

Features

- Multi-channel JESD204B complaint clocking solution,
 - Converter Device clock frequency – **LMX2615-SP** (max – **15 GHz**)
 - Converter SYSREF provided for JESD204B interface – **LMX2615-SP**
- Scalable clocking solution, which can generate various DEVCLK by LMX2615-SP or LMK04832-SP
- Option to generate high frequency local oscillator for front end mixer
- Complete small, highly efficient power subsystem using DC/DC and LDO regulators/modules

Benefits

- JESD204B compatible clocking solution for high dynamic range and high SNR multi-channel signal chain
- Configurable phase synchronization to achieve low skew in multi-channel system
- Power efficiency optimized power subsystem for clock generation
- Easily interface with high speed data converters and synchronization
- Compares performance of multiple clocking solution of different complexity and cost

Target Applications

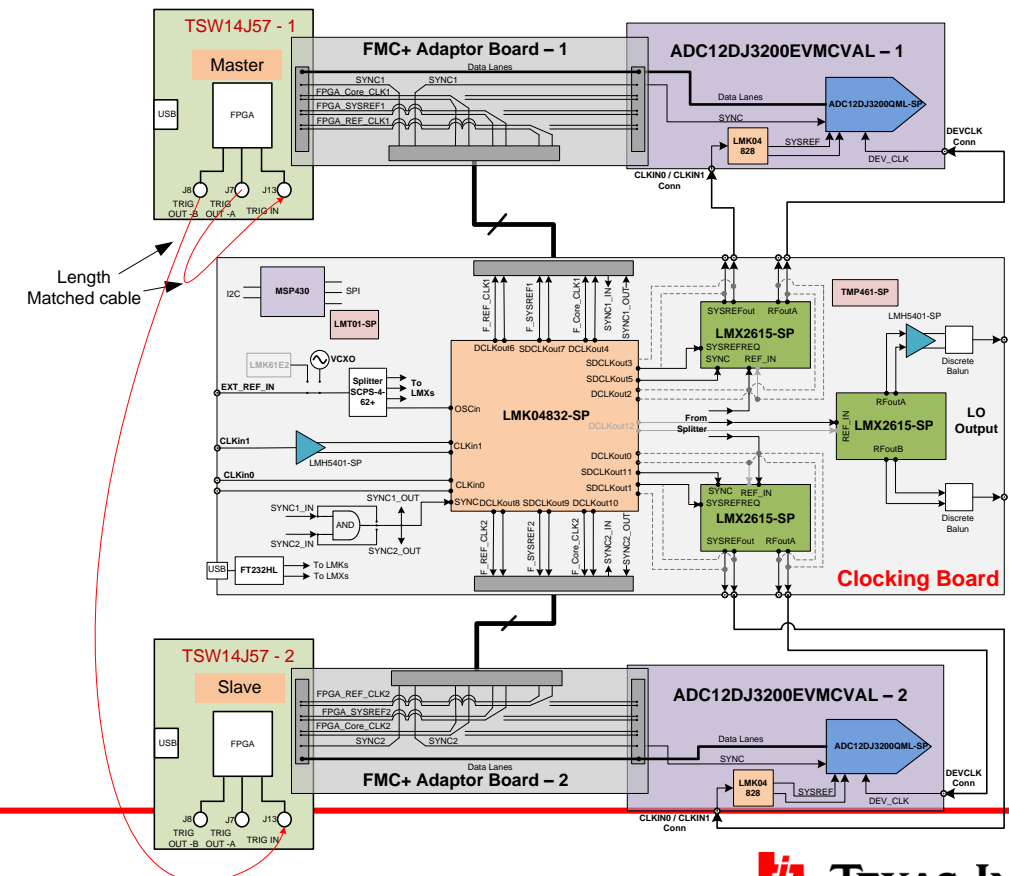
- [Communications Payload](#)
- [Radar Payload](#)
- [Command and data handling](#)

Tools & Resources

- [TIDA-010191](#)
- Design Guide
- Design Files: Schematics, BOM, Gerber, Software

Devices:

- [ADC12DJ3200QML-SP](#)
- [ADC12DJ3200EVMCVAL](#)
- [LMX2615-SP](#)
- [LMK04832-SP](#)
- [TSW14J57EVM](#)



TI Space Documentation



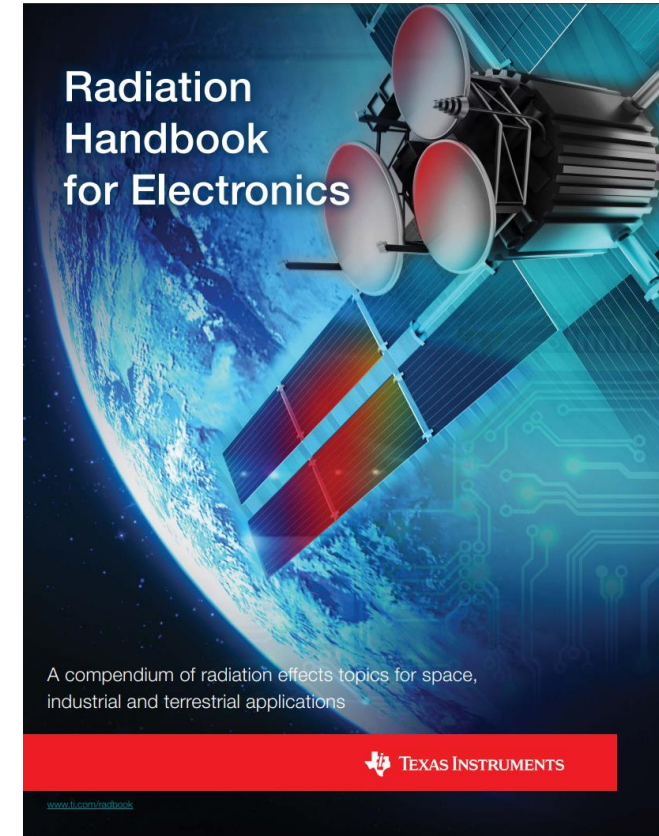
Space Product Guide

- All TI products for Space
- Includes device listing for QMLV, Space-EP, Die, EMs, and Mechanical Samples
- Updated in March 2022



Space Circuit Handbook

- Ebook of useful space circuit designs including step-by-step instructions, formulas, and simulations to quickly get your design started



Radiation Handbook

- Provides explanation of radiation effects on semiconductors including TID, NDD, and SEE
- Written by industry experts Rob Baumann and Kirby Kruckmeyer

Visit www.ti.com/space for additional information

Analog front-end design for data acquisition systems with TI's tooling landscape

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Analog front-end design for data acquisition systems with TI's tooling landscape

- Data acquisition system design goals & challenges
- Component & topology selection with Analog Engineer's Calculator
- Design iterations with TINA-TI simulator
 - Basic functionality
 - Noise analysis / ENOBs
 - Linearity / frequency response
 - Stability (Phase- & gain margin)
 - Settling time
- Summary

Space-grade precision data acquisition

Target applications

Satellite precision data acquisition systems:

- Thermal control of optical instruments / camera system
- Linear displacement (position) sensing / motion control
- Gyro sensor
- Atomic clock

Design goals and challenges

- **Strong signal performance for ENOB of 16 and higher:**
 - Low noise addition from active components
 - Low noise floor (single digit nV/\sqrt{Hz})
 - High linearity for low distortion from harmonics ($< -110dBc$, up-to 40kHz)
 - Low quantification noise / short enough settling time (μV -level after $1/fz$)
 - Strong common mode noise suppression (down to zero impact)
 - Low drift (e.g. offset drift of $< 1 \mu V/^{\circ}C$; input bias current drift of $< 20nA$)
 - high stability (phase margin of $60^{\circ}+$)
- **Low power consumption per channel** (down to 10s of mW, highly dependent on mode of operation)
- **Smallest possible board area & cost**
- **Optimized input buffer stage:**
 - Input impedance target $>100k\Omega$
 - Input full scale range (FSR) much smaller or much greater than ADC's FSR of typically 5V
 - Common mode voltage equal or unequal to 0V

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Component & topology selection

Identifying the right ADC

Example specification / design goals:

- Channel Count: 8 Channels
- Bandwidth and Sampling Rate: 40 kHz, > 100 kSamples/s
- Input Full Scale Range (FSR) : +/- 10V FSR
- Common Mode Voltage: ~ 0V common mode
- Target Resolution/ENOB: > 16 Bit
- Input Impedance (ZIN) Target: > 100 kOhm



TI Space Products (Rev. 1)

Find the right parts for your space grade design with our updated Space Products Guide

[Download \(PDF, 4292KB\)](#)

<http://www.ti.com/spaceguide>

<https://www.ti.com/applications/industrial/aerospace-defense/space/overview.html>

Precision ADCs (≤ 10 MSPS)

Part Number ¹	Military Spec	Qualification Level	TID Char. (krad)	TID RLAT (krad)	SEL (MeV•cm ² /mg)	Res. (Bits)	Sample Rate (Max) (kSPS)	# of Ch	Multi-Ch Config.	SNR (dB)	INL (Max) (\pm LSB)	Input Type	Ref. Voltage (V)	Power (Typ) (mW)	Type	Package Group	ECCN ²
ADC128S102QML-SP	5962-07227	QMLV-RHA	100	100	120	12	1000	8	Multiplexed	72	1.1	Single ended	Supply	2.3	SAR	CFP, Die	EAR99 [†]
ADS1278-SP	–	TI Space Grade	75	50	68	24	128	8	Simultaneous	111	201.4	Differential	External	530	$\Delta\Sigma$	CQFP	EAR99 [†]
ADS1282-SP	5962-14231	QMLV-RHA	50	50	60	32	4	2	Multiplexed	130	–	Differential	External	25	$\Delta\Sigma$	CFP	EAR99 [†]

Component & topology selection

Identifying the right op amp

Example specification / design goals:

- Channel Count: 8 Channels
- Bandwidth and Sampling Rate: 40 kHz, > 100 kSamples/s
- Input Full Scale Range (FSR) : +/- 10V FSR
- Common Mode Voltage: ~ 0V common mode
- Target Resolution/ENOB: > 16 Bit
- Input Impedance (ZIN) Target: > 100 kOhm

Step 2:

Enter modulation frequency of 8.192 MHz in **ANALOG-ENGINEER'S CALCULATOR** tool*, click 'Calculate' and read back the **Min UGBW = 5.215 MHz**.

The screenshot shows the 'Analog Engineer's Calculator' interface. The 'Modulation Freq' field is highlighted with a red circle and contains the value '8.192M'. The 'Min UGBW' field is also highlighted with a red circle and contains '5.215M'. To the right, a circuit diagram shows a fully differential amplifier (FDA) with input resistors (Rg, Rf), feedback resistors (Rf, Rf), and a load resistor (Rfilt/2). The output is connected to a delta-sigma ADC (ΔΣ ADC) with a sampling capacitor (Csh) and a feedback capacitor (Cfilt/10).

*Download for free @ <https://www.ti.com/tool/ANALOG-ENGINEER-CALC>

Step 1:

Read modulation frequency from ADS1278-SP data sheet:

The screenshot shows the 'Selectable Operating Modes' table from the ADS1278-SP data sheet. The modes listed are:

- High-Speed: 128 kSPS, 106-dB SNR
- High-Resolution: 52 kSPS, 111-dB SNR
- Low-Power: 52 kSPS, 31 mW/ch
- Low-Speed: 10 kSPS, 7 mW/ch

Input leakage	$0 < V_{IN\ DIGITAL} < IOVDD$	± 11
Master clock rate (f_{CLK})	High-Speed mode ⁽⁴⁾	32.768
	Other modes	27

Table 4. Modulator Frequency (F_{MOD}) Mode Selection

MODE SELECTION	CLKDIV	f_{MOD}
High-Speed	1	$f_{CLK} / 4$

$$32.768\text{MHz} / 4 = 8.192\text{MHz}$$

Step 3:

Select OpAmp. E.g. LMH5485-SP

Fully Differential Amplifiers (FDAs)

Part Number ¹	Military Spec	Qualification Level	TID Char. (krad)	TID RLAT (krad)	SEL (MeV·cm ² /mg)	V _S Min (V)	V _S Max (V)	GBW (MHz)	BW @ A _{CL} (MHz)	Min. A _{CL} (MHz)	Slew Rate (Typ) (V/μs)	V _n at Flatband (nV/√Hz)	CMRR (Typ) (dB)	Rail-to-Rail
LMH5401-SP	5962-17214	QMLV-RHA	100	100	85	3.15	5.25	6500	4100	5	17500	1.25	72	No
LMH5485-SP	5962-19204	QMLV-RHA	100	100	75	2.7	5.4	850	620	1	1500	2.2	100	In to V-
THS4511-SP	5962-07222	QMLV	150	-	Bipolar	3.75	5.25	3000	1100	1	5100	2	80	In to V-
THS4513-SP	5962-07223	QMLV	150	-	Bipolar	3	5.5	3000	1100	1	5100	2.2	90	No

Getting started with the design

R0-dif = Open-loop output impedance
 closed-loop output impedance x open-loop gain = open loop output impedance
 LMH5485-SP data sheet:

Closed-loop output impedance	f = 10 MHz (differential)	0.1	Ω
------------------------------	---------------------------	-----	---

Figure 7.1: Gain vs. frequency curve:
 ~38dB @ 8.192 MHz

→ ~80 x 0.1 Ohm = 8 Ohm

Riso typically small, use '0' for now:

Rg & Rf must be the same for unity gain. Use 1K.

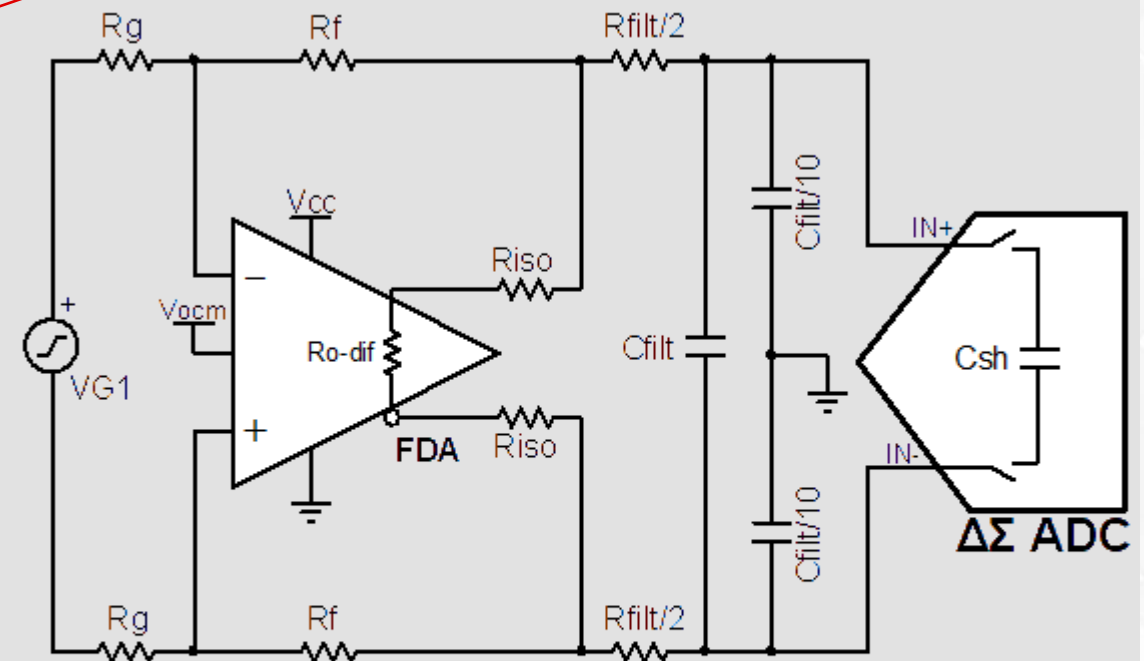
Cfilt shall be at least 20x bigger than Csh. 2.2nF is in the middle of Cfilt_min & Cfilt_max.

Modulation Freq 8.192M Hz	Ipp 8m A	Min UGBW 5.215M Hz
Ro-dif 8 ohm	fin(max) 50k Hz	Tacq 61.04n s
Riso 0 ohm	V(FSR)pp 5 V	Leq 2.996n H
Rg 1k ohm	Selected UGBW 850M Hz	Cfilt_max 5.09296n F
Rf 1k ohm	Csh 9p V	Cfilt_max(standard) 5.1n F
Cfilt 2.2n F		Cfilt_min(standard) 180p F
		Rfilt/2 1.17 Ohm

Calculate Help

Ipp data sheet allows for up-to 75mA. 8mA shall be enough to calculate with. With that Cfilt_max comes out as 5.1nF.

fin required bandwidth is 40kHz. Let's give some margin



From ADS1278-SP data sheet, Figure 63:

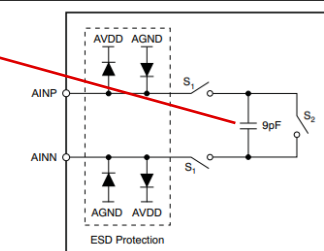


Figure 63. Equivalent Analog Input Circuitry

Agenda

Analog Front End design for data acquisition systems with TI's tooling landscape

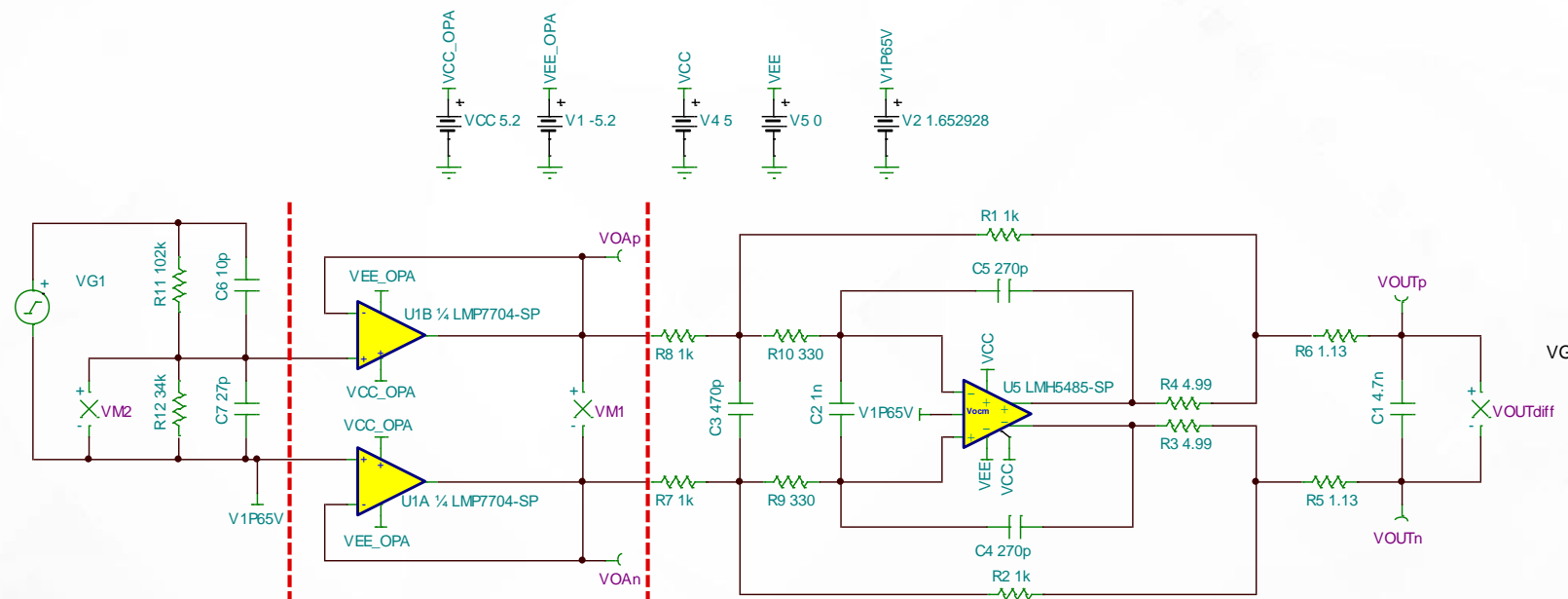
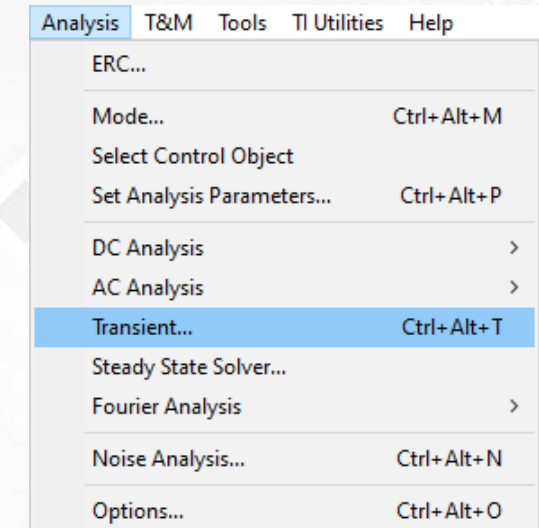
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Basic functionality: Time domain response

Complete the design for simulation:

- Add VG1 with 40 kHz, $\pm 10V$.
- Add attenuation Stage for $\pm 10V$ Input (with $Z_{IN} \geq 100\text{ k}\Omega \parallel 10\text{ pF}$): $\pm 2.5V$
- Add Input buffer stage based on LMP7704-SP

- Use Analysis \rightarrow Transient...

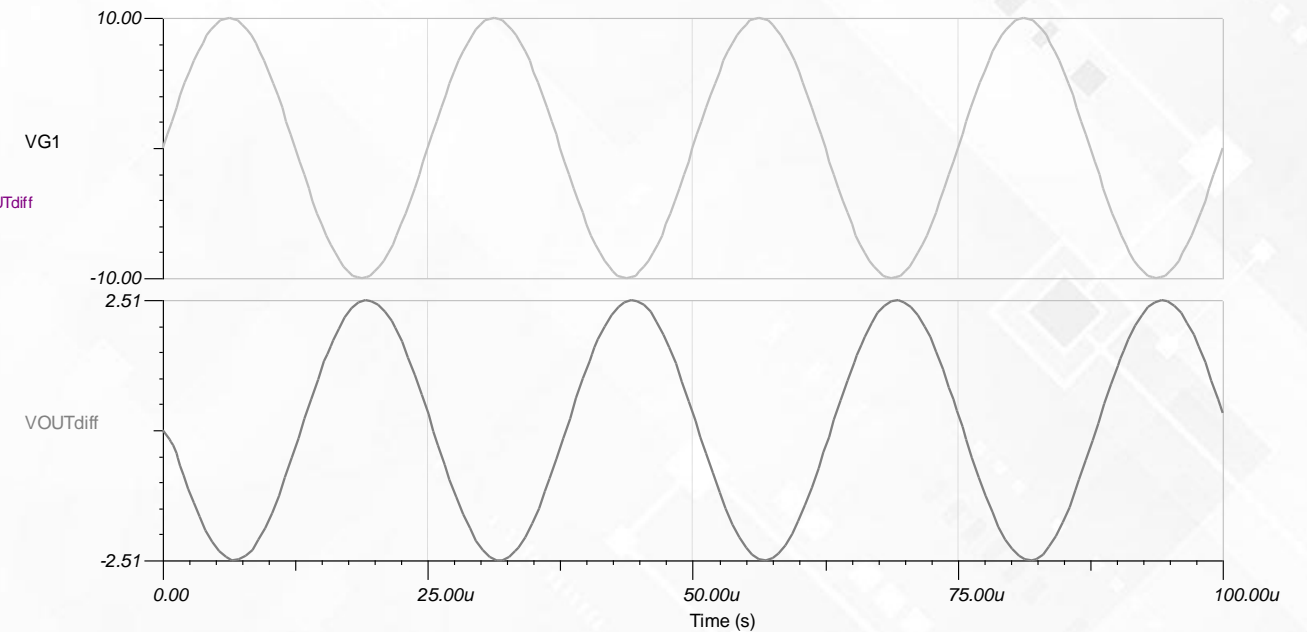


Attenuation Stage
(Only for $\pm 10V$ Input)

Input Buffer Stage
(with Ultra-Low I_B OpAmp)

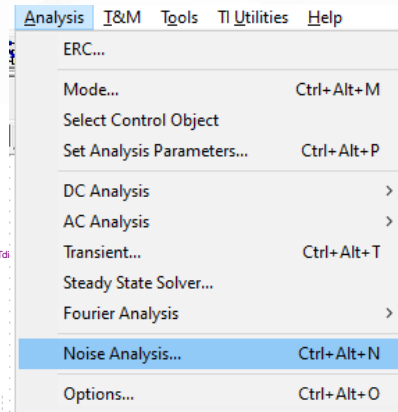
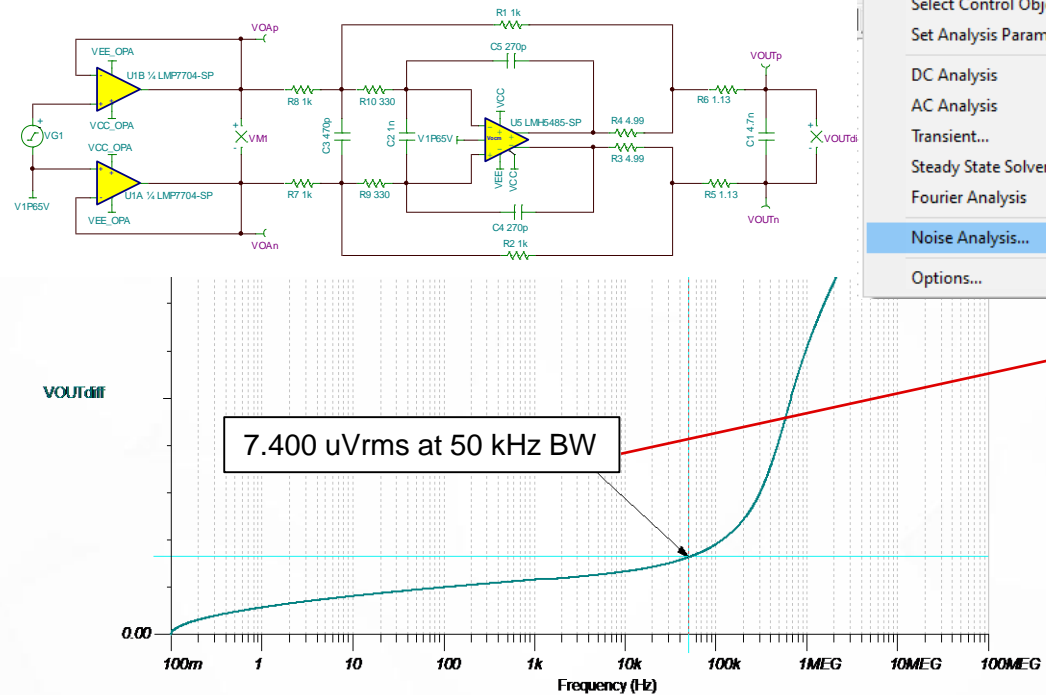
ADC Driver
(using Fully-Diff Amp)

$R_{IN} > 100\text{ k}\Omega$



Noise and ENOB

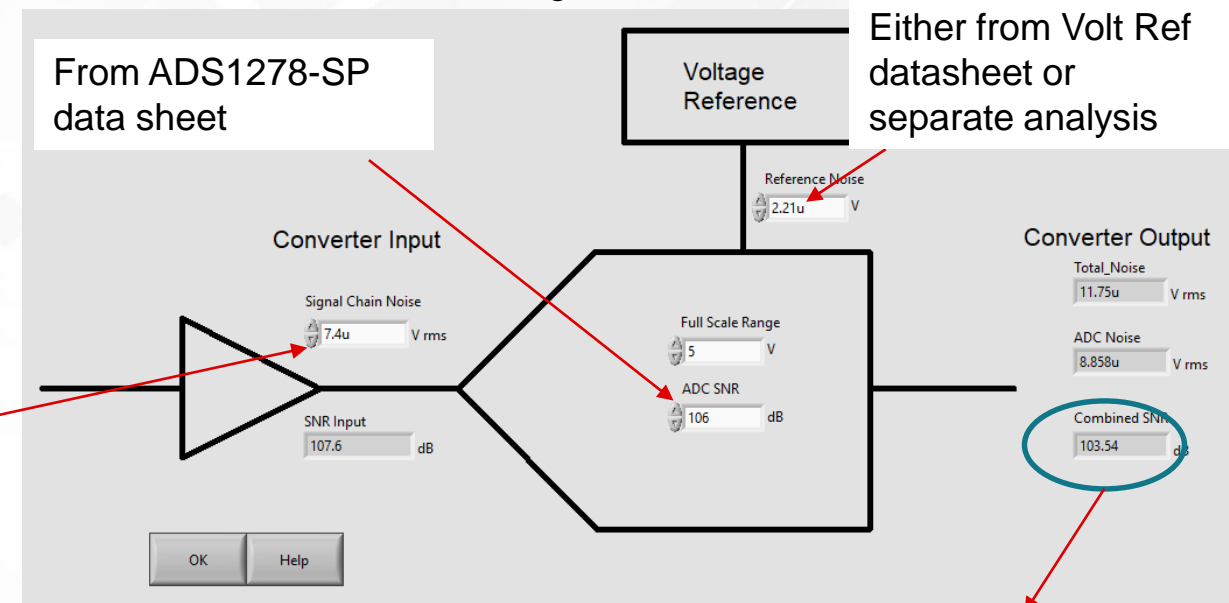
1. Use Analysis → Noise Analysis



3. Use of standard conversion formula
 'ENOB = (SNR - 1.76)/6.02 dB' to
 calculate **ENOB = 16.91 Bits**

4. TINA-TI does not account for non-linearity. A quick look at the THD is necessary:
 LMH5485-SP data sheet shows distortion from HD2 of -118 dBc for 50 kHz and below. Much lower than 103.54dB identified above and can be ignored.

2. Enter data into **ANALOG-ENGINEER'S CALCULATOR** tool
 'Data Converters' → 'ADC + Signal Chain Noise':



➤ SNR based on AFE Noise + VREF Noise = **103.54 dB**

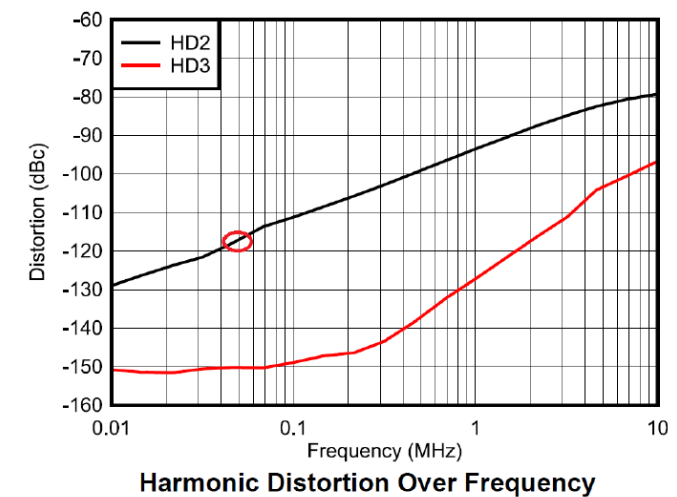
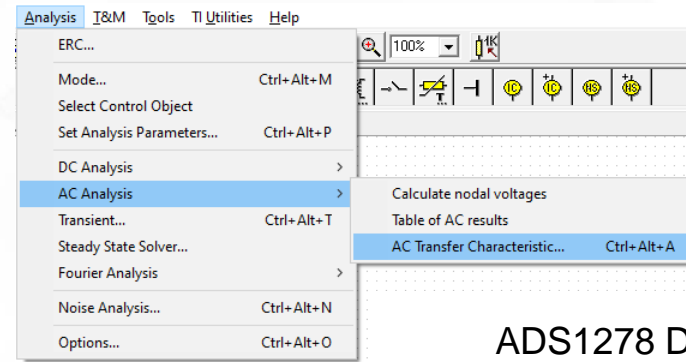
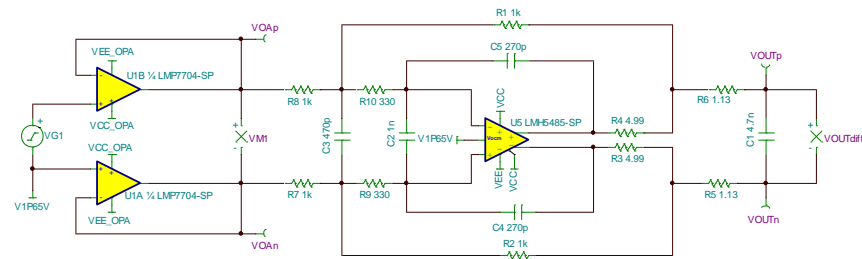


Figure 2-7. LMH5485-SP Data Sheet Shows THD of About -118 dBc for f = 50 kHz in its Harmonic Distortion Over Frequency Chart

Linearity / frequency response

Use Analysis → AC Analysis → AC Transfer Characteristics



ADS1278 Digital Filter Response $F_{in}/F_{data}=0.5$;
 $F_{data} = 128\text{kpsps} \rightarrow \text{Cut-off@ } \sim 60\text{kHz}$

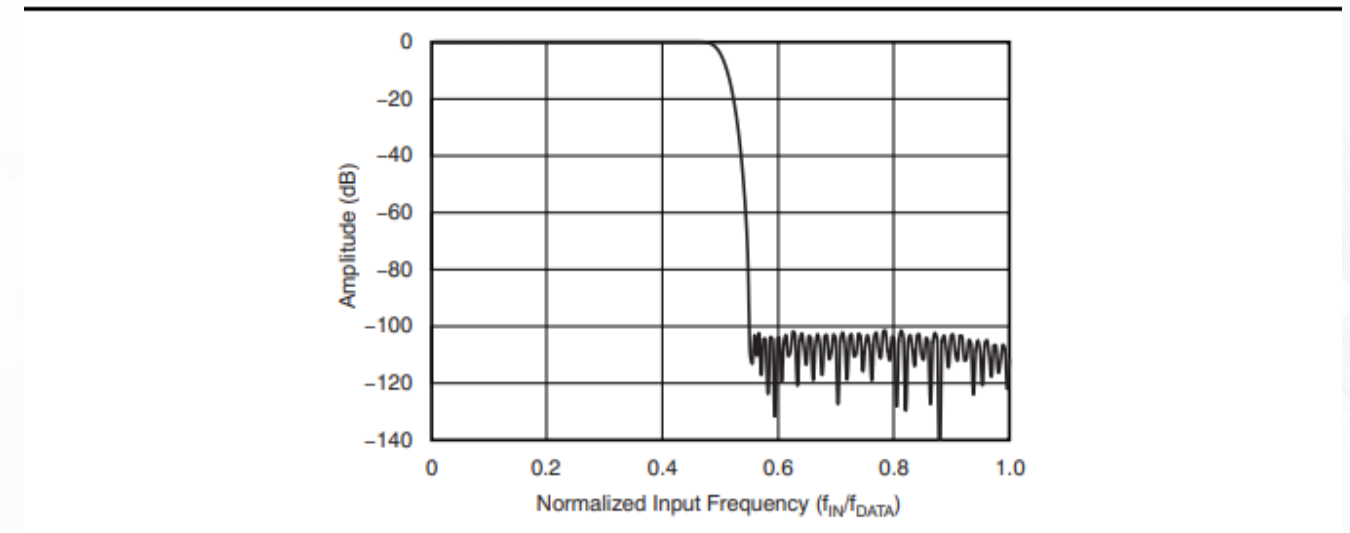
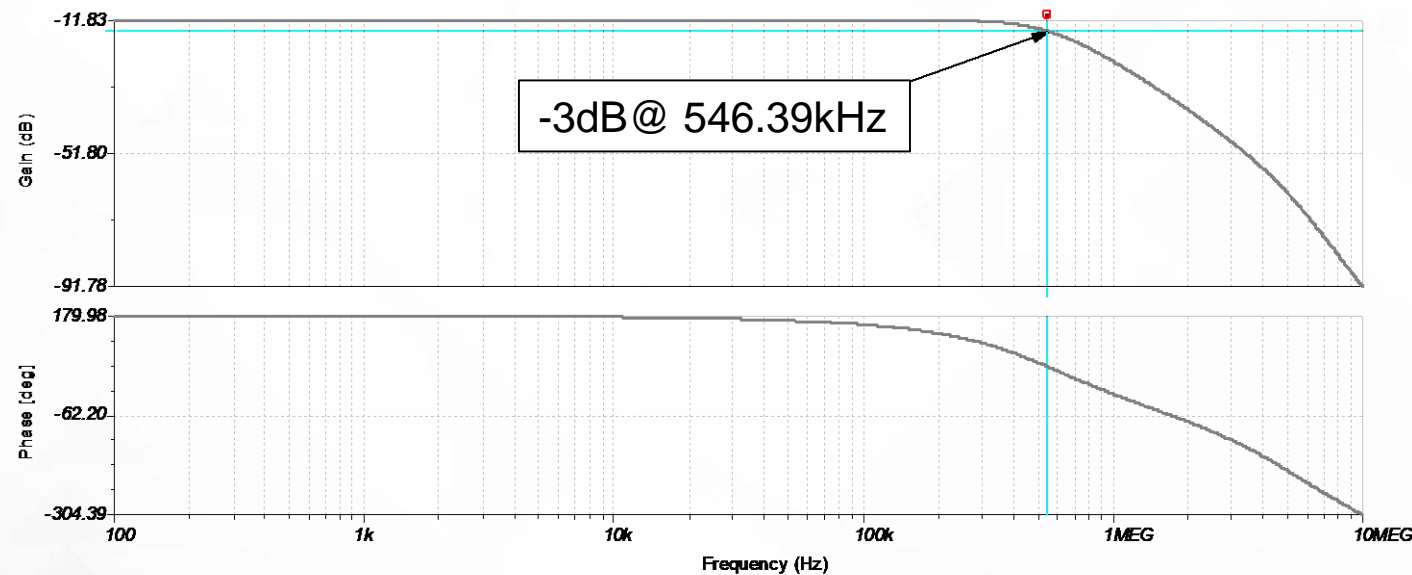


Figure 54. Frequency Response For High-Speed, Low-Power, And Low-Speed Modes

- 3 dB Bandwidth 546.39 kHz for AFE
 - very well above the cut off frequency of 60kHz of ADS1278's digital filter response. → Meets the linearity requirement
 - $f_{mod} = 8.192 \text{ MHz}$. Provides 60dB+ anti-aliasing suppression for signal components at 4.096MHz and higher.

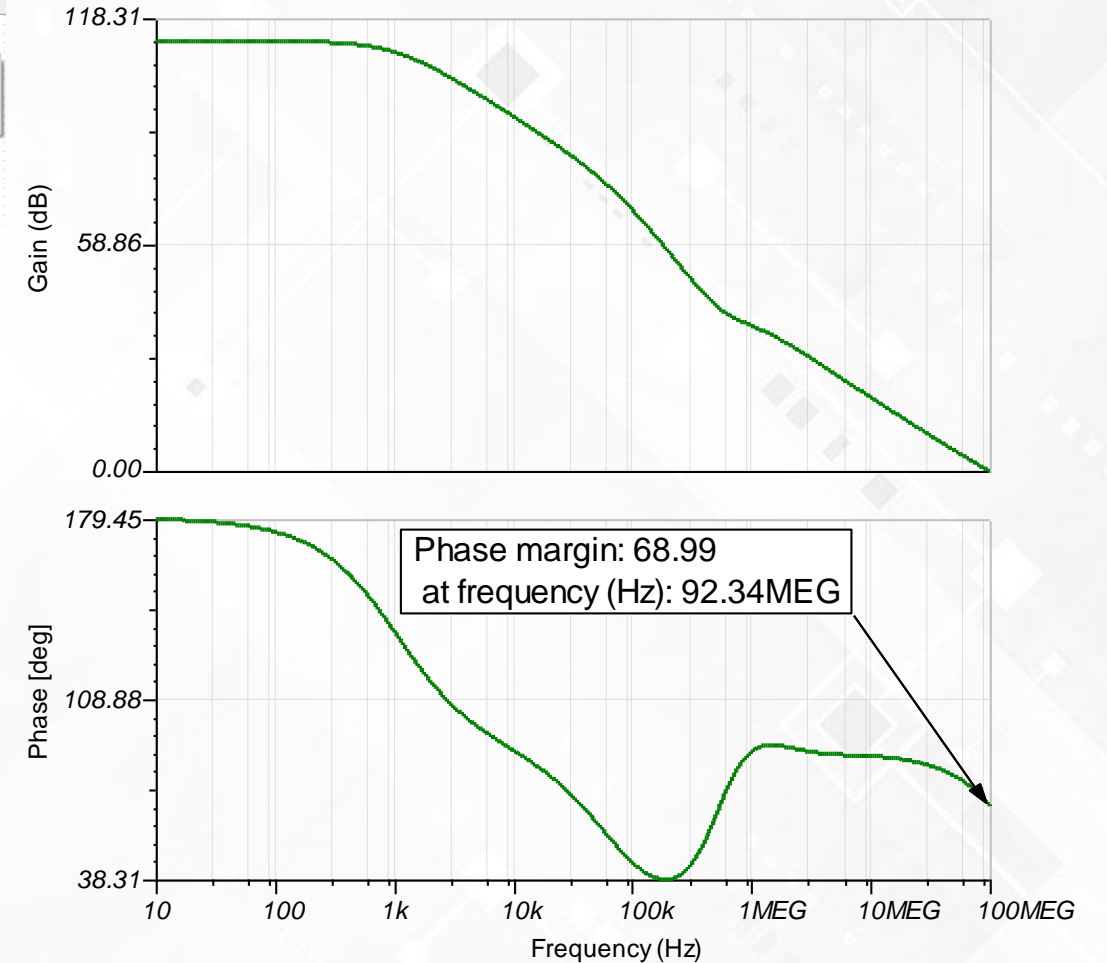
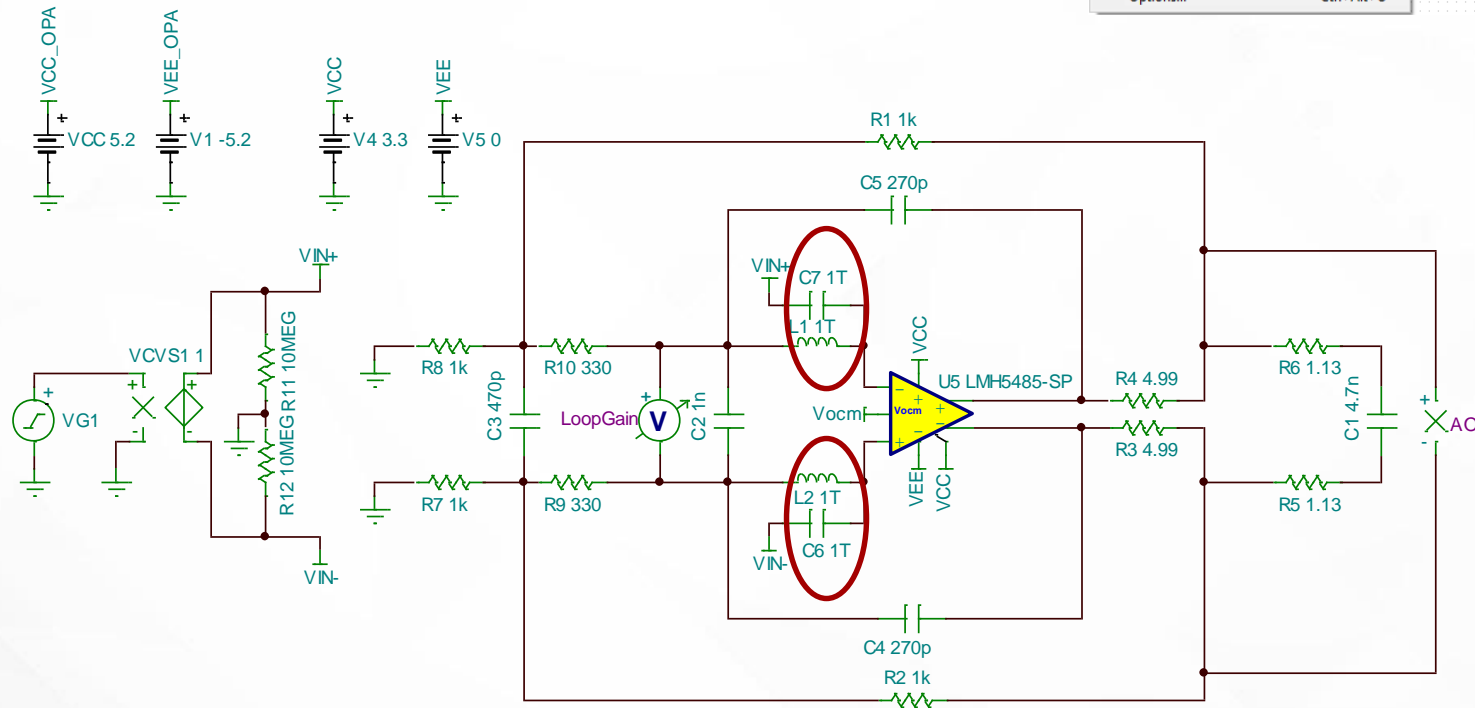
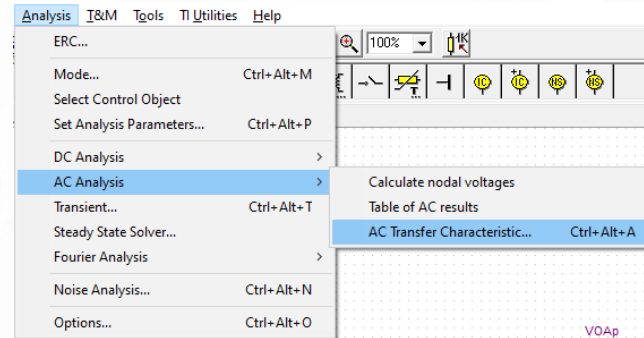
Stability analysis of closed loop system

Use Analysis → AC Analysis → AC Transfer Characteristics

To enable simulation from DC to high frequency:

Add L1 & L2 with Terra Henry (open for AC / short for DC)

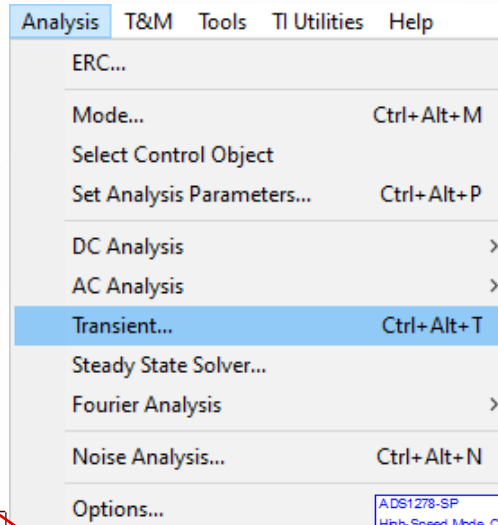
And C7 & C8 with Terra Farad (short for AC / open for DC)



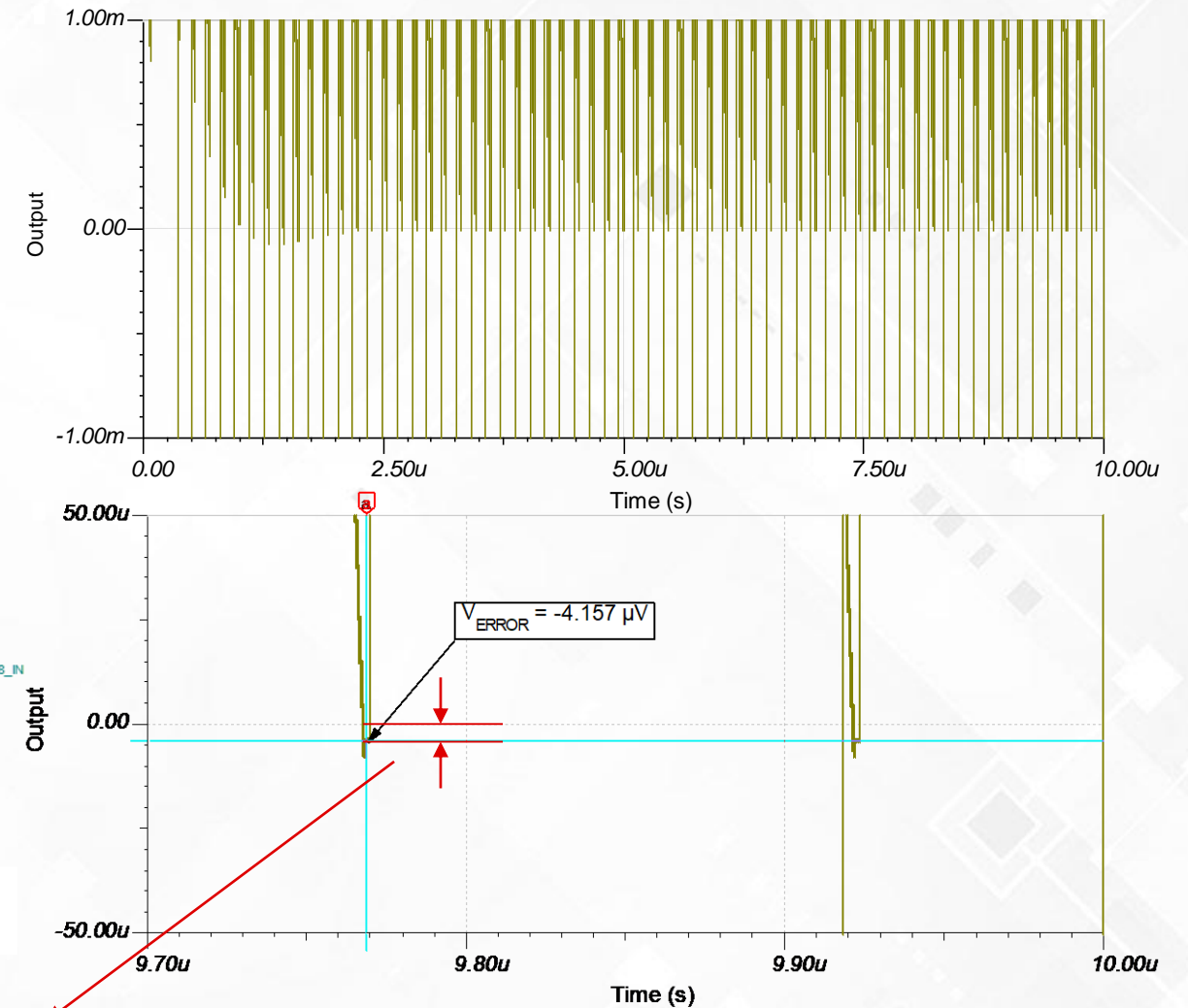
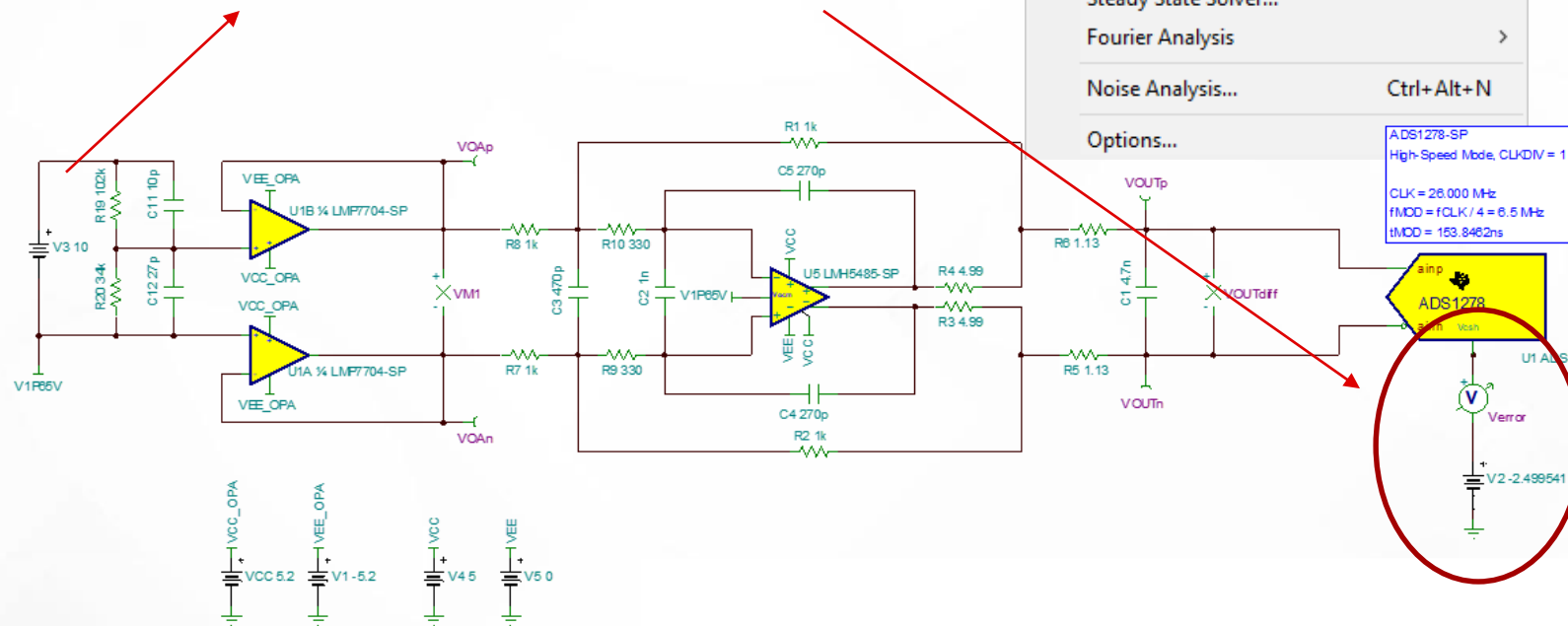
- Phase Margin for Ain+ and Ain- Amplifier paths, 68.99 Deg @ cross-over point
- Dip in phase margin at ~150KHz might allow for some ringing...

Settling time driving ADC input

Use Analysis → Transient...



Take advantage of ADS1278 model's Vcsh output to analyze voltage on sampling capacitor for max DC input (10V at input generate Vdiff -2.499541V).



- Sampled output voltage error of ADS1278 is -4.157 uV after full settling of step input.
- This error appears as a gain error, and reduces to approximately 0V at 0V input.
- Gain Error $\sim [(2.5\text{V} - 4.157\text{e-}6\text{V}) / 2.5\text{V} - 1] * 100 = -0.00016628\% = -1.6628 \text{ ppm}$ (~20bit resolution)

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Analog Front End design for data acquisition systems with TI's tooling landscape

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Summary

- Designing the analog front end is a multi-dimensional challenge and does typically require an iterative development process.
- TI products, available simulation models and tools enable designers:
 - to identify a good starting point quickly
 - quick and easy validation of several system aspects such as frequency response, stability, noise levels, settling times, etc.:
 - Quick understanding of the design behavior
 - Fast design iterations
 - High confidence into design success prior start of actual hardware design
- Tools are downloadable for free
- Technical support available via e2e forum or your local TI representatives
- All details of this presentation are described in the application note:

[Analog Front-End Design With Texas Instruments' Tooling Landscape](#)

ADS1278-SP AFE Test Board

In development

Performance vs. power of four different AFE architectures

Features

- Multiple configuration options for power, clocking, V_{REF} & V_{OCM}
- Dual channel inputs with four different AFE topologies:
 - Direct FDA
 - Instrumentation Amplifier: Direct or + MFB FDA
 - SE Input Buffer + MFB FDA

Target Applications

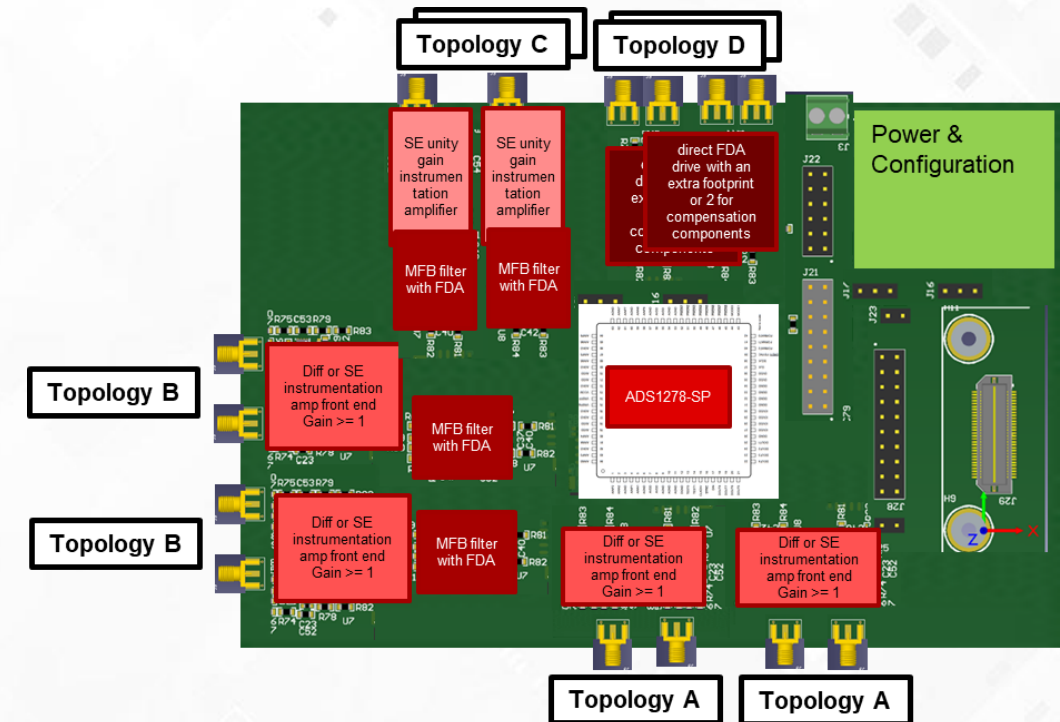
- Satellite precision data acquisition systems:
- Thermal control of optical instruments / camera systems
- Linear displacement (position) sensing / motion control
- Gyro sensors
 - Atomic clock

Devices

- [ADS1278-SP](#) 24-Bit 8-Ch Simultaneous-Sampling Delta-Sigma ADC
- [LMH5485-SP](#) 850-MHz fully differential amplifier
- [LMP7704-SP](#) precision, low-input bias, RRIO, wide supply range amplifiers
- [LMH6628QML-SP](#) Dual Wideband, Low Noise, Voltage Feedback Op Amp
- [LM4050QML-SP](#) 2.5-V or 5-V shunt voltage reference
- [TPS7H1101A-SP](#) 1.5-V to 7-V input, 3-A low-noise low-dropout (LDO) regulator
- [TPS50601A-SP](#) 3-V to 7-V input, 6-A synchronous step-down converter

Benefits

- High resolution of up to 18 ENOB across wide temperature range
- High PSRR and rail-to-rail capabilities enable simplified power supply design (Unipolar supply, no LDO)
- Low power consumption & board size per channel



Space-grade, 50-krad, overcurrent event-detection circuit

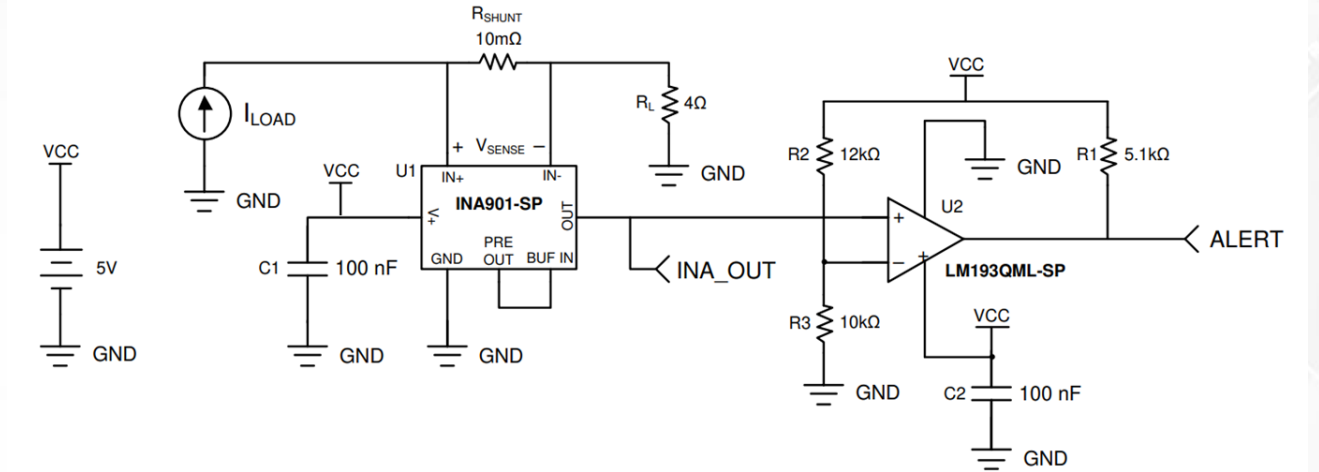
**Example from TI's
"Spacecraft Circuit Design
Handbook"**

Web Address with more collateral:

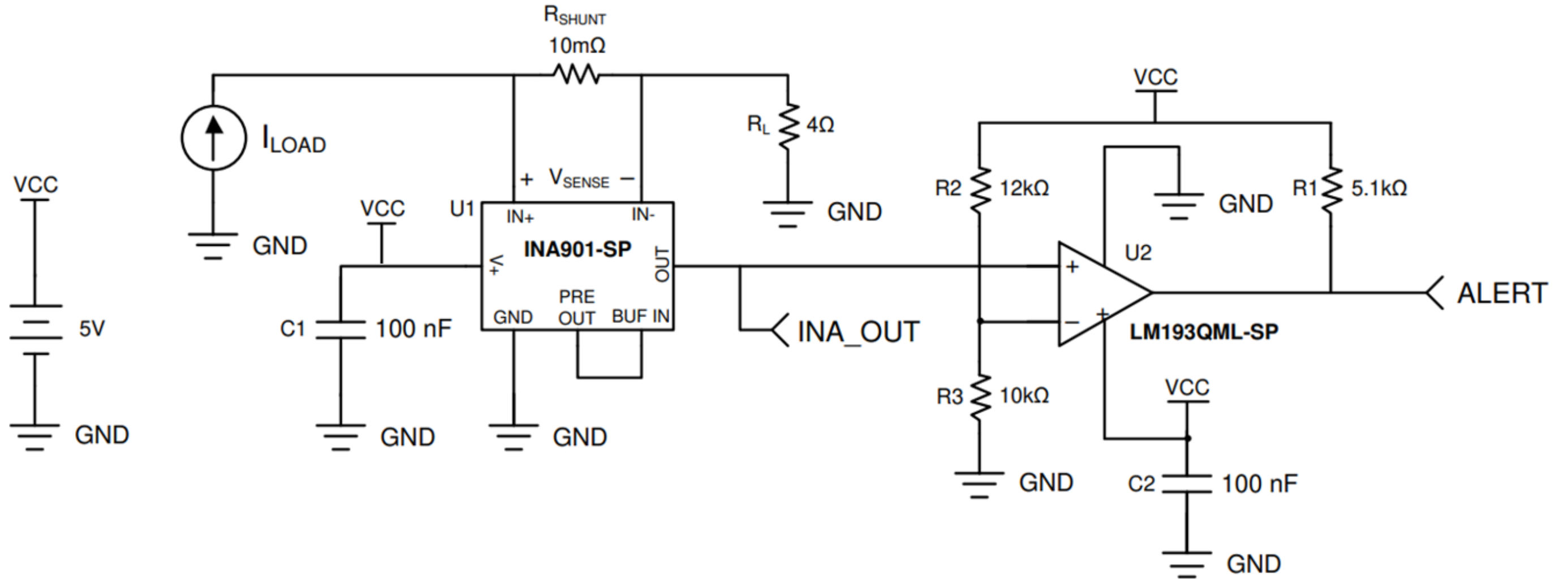
<https://www.ti.com/applications/industrial/aerospace-defense/space/overview.html>

Problem and proposal

- Space radiation can lead to latch-up
 - Parasitic SCR triggers
 - Steep current rise
 - Component death by overheat
- Detected “quickly” -> no problem
 - Unidirectional current sense can detect abnormal behavior
 - Over current events could then trigger power cycling
- This circuit example shows high side current sense
 - Nominal currents from 5A to 10A
 - Sense resistor of only 10 m Ω ($P_{\max} < 1W$)
 - Comparator triggers ALERT at $I > 11A$ ($V_{OC} > 2.2 V$)



Circuit diagram



Comments

- INA901-SP is a space grade precise current sense amplifier
- INA901 generates in this circuit 200 mV / A
- LM193QML-SP works as voltage comparator for immediate action
 - Threshold set to 2.2 V (11 A)
- Signal could be further processed in ADC and MCU (FFT, fast fourier transform)
- Unusual power pattern could then trigger actions as well
 - Transmit to ground station
 - Ground station could decide what to do

Design process

- Steps of circuit design shown in “Spacecraft Circuit Design Handbook”
- Calculation of shunt R1
- Calculation of R2 and R3 for correct trigger
- Calculation of trigger (offset) error depending on
 - Set threshold
 - Input current
- Find the book here: <https://www.ti.com/lit/eb/slyy214/slyy214.pdf>

Linear Thermoelectric Cooler (TEC) Driver Circuit with high accuracy and stability and minimized noise emissions

Space-grade, 100-krad, linear thermoelectric cooler (TEC) driver circuit

- Star tracker systems
- Temperature regulation CCD-based Infrared Camera
- Laser Communication Systems
- Wide Field Planetary Camera

Design challenge/problem statement

- Survive **100-krad** (Si) total dose, high immunity to SEL $\geq 75\text{MeV-cm}^2/\text{mg}$
- Bi-directional current control (**+/- 2.5A**)
- Avoid any hard switching to **avoid EMI**
- Keep **board area** requirements as low as possible
- High accuracy (**1mA**)

Target End Equipment:

- Laser communications payload
- Optical imaging payload
- Star tracker
- Satellite motor & actuator drive

Solution description

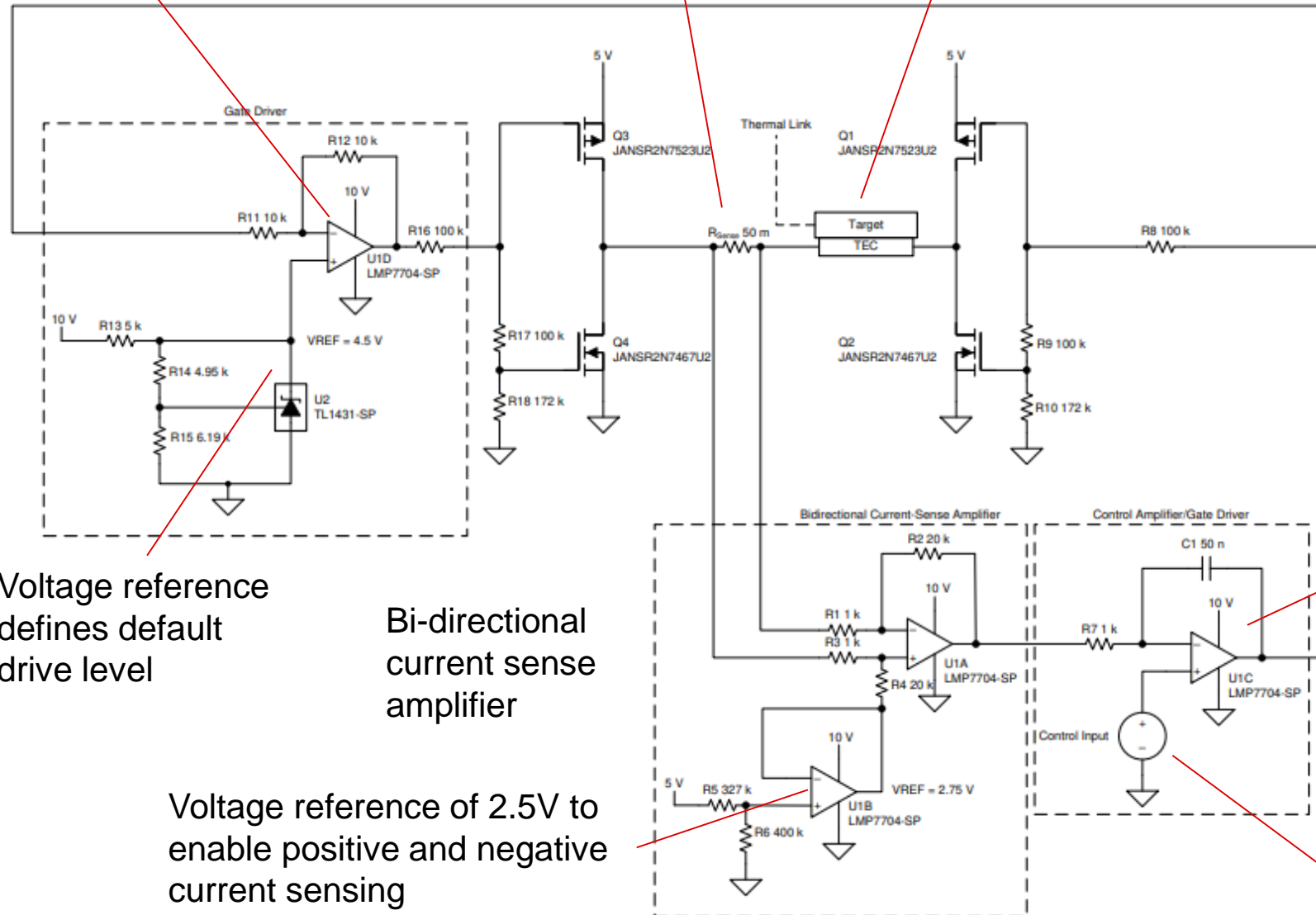
A **Linear H-Bridge** driver provides:

- 1. Low noise:** TECs are usually used in high accuracy imaging systems.
No EMI is induced since there is no switching
- 2. High accuracy:** Current control error within 1mA
- 3. Low design complexity:** No MCU, only non-complex components

- Control amplifier handles the feedback from the current sense amplifier
- Drives the right half bridge directly

Driver for the left half bridge

Current shunt resistor TEC Element



Voltage reference defines default drive level

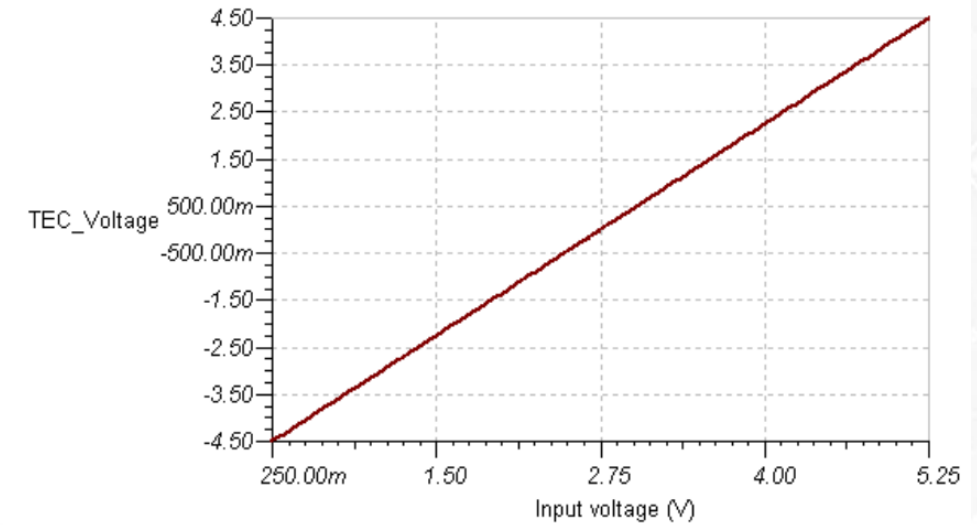
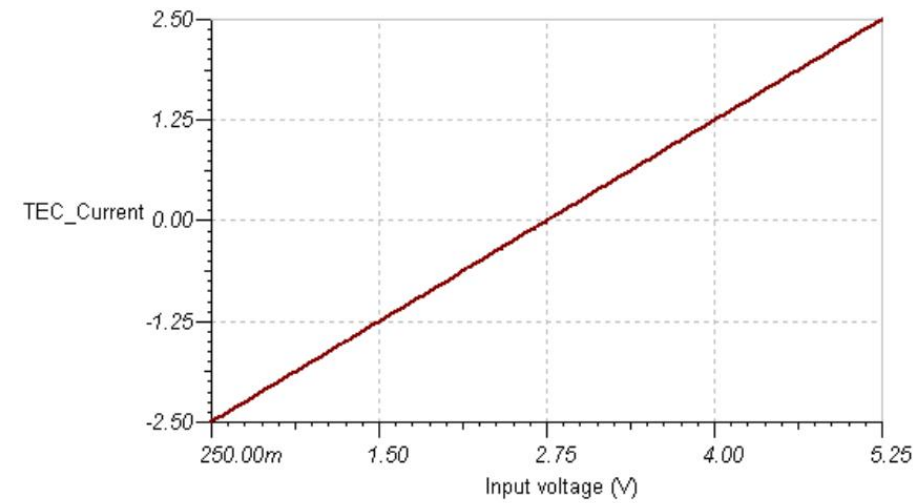
Bi-directional current sense amplifier

Voltage reference of 2.5V to enable positive and negative current sensing

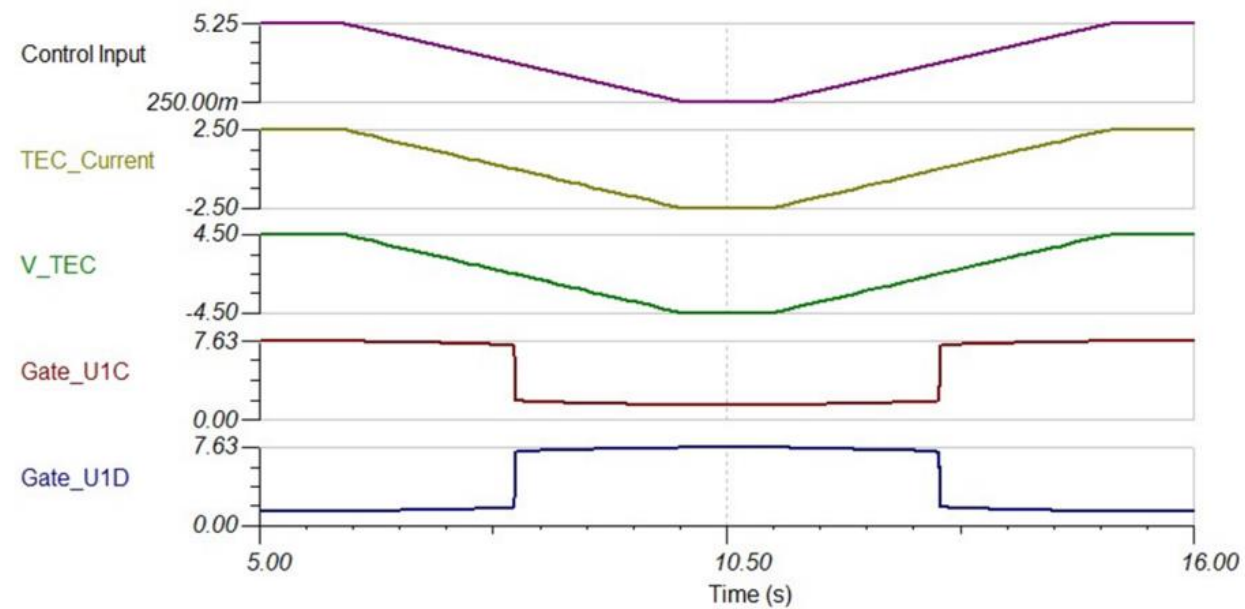
Control input from outer temperature control loop

Validation results

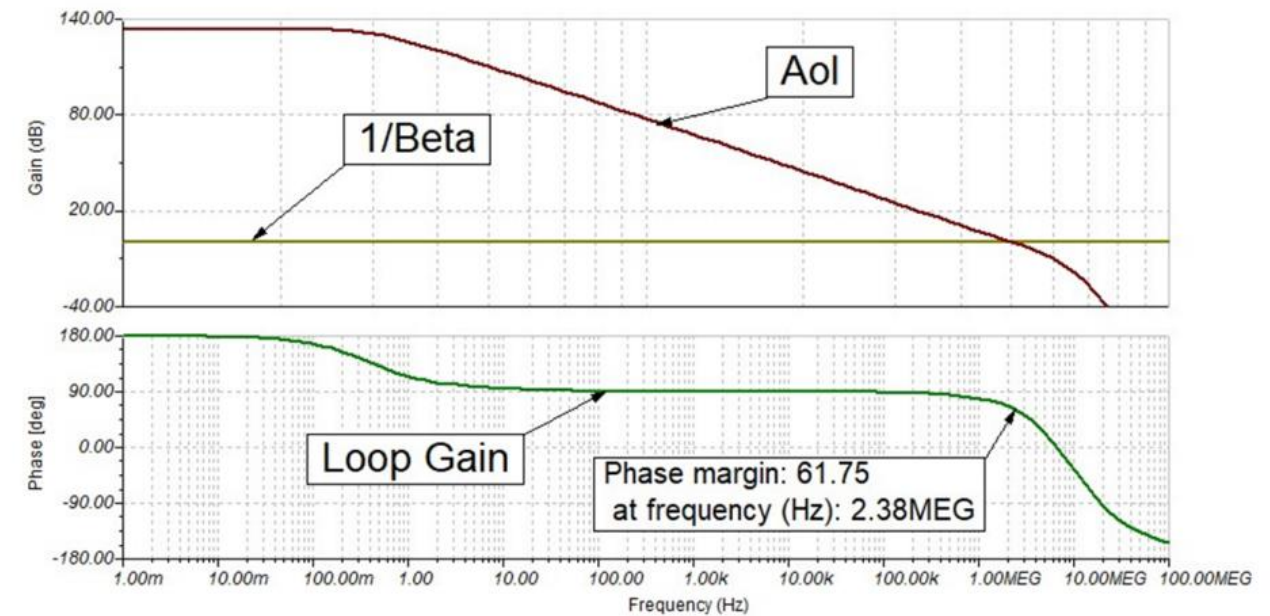
TEC Element Ratings



Transient Simulation



System Stability



Space-grade, 100-krad, linear thermoelectric cooler (TEC) driver circuit

Summary

- The design meets all design criteria in terms of max **current rating** and **voltage rating** of the TEC, **high accuracy**, **stability** and **radiation hardness**
- The linear driver avoids any switching and keeps **EMI low**
- **Low complexity** with very small board space requirements (e.g. the four OpAmps are integrated in a single package). Only two voltage rails required.
- Application brief with design steps under [Space-Grade, 100-krad, Linear Thermoelectric Cooler \(TEC\) Driver Circuit](#)

Rad-Hard and Rad-Tolerant Current Measurement Solutions

Very Wide Common Voltage Current Sense Amplifier with Split Stage for Filtering



Features

- Radiation: TID 50krad RHA, SEL 85 MeV.cm²/mg (125 C)
- -15V to 65V common-mode range independent of supply
- 2.7V to 16V supply
- Split stages for filtering
- Bandwidth up to 130kHz
- Gain: 20V/V
- Package: Ceramic 8-lead HKX 6.5mm x 6.5mm
- Option for KGD



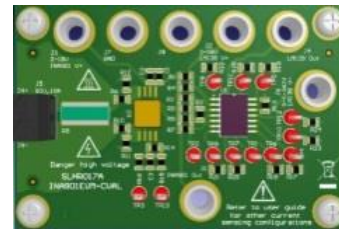
Applications

- Current Monitor for current mode control DC-DC Converter
- Current Measurement in an H-Bridge for Motor Control
- Latching Current Limiters on High common mode bus
- Current sensing on GaN modules for increased efficiency



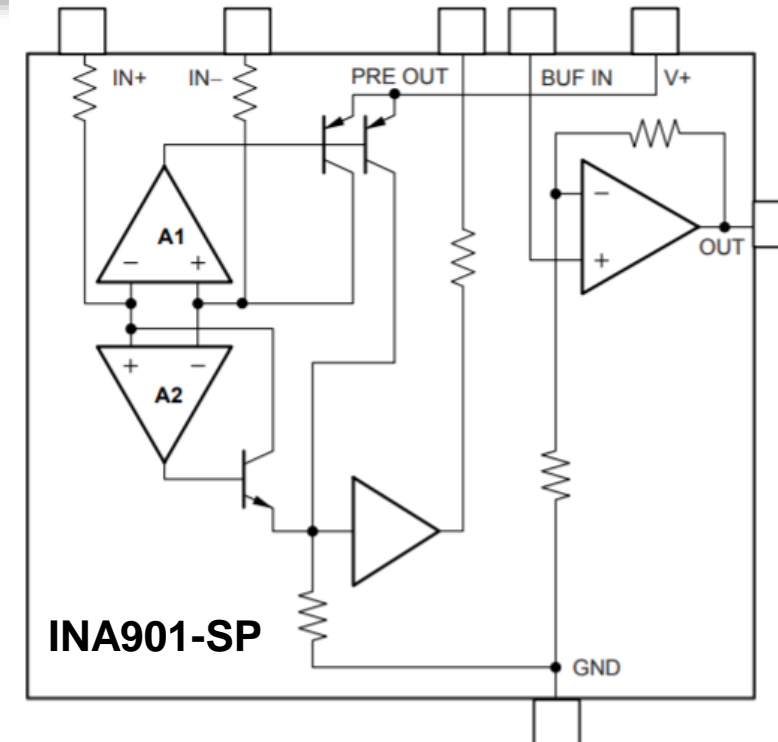
Tools and Resources

- Product folder: [LINK](#)
- SMD datasheet: [LINK](#)
- Evaluation board (EVM): [LINK](#)
- Radiation reports: [LINK](#)



Benefits

- Eliminates need for additional protective components in the event of CMR reversals
- Preserves buffered voltage output and saves using an additional op amp
- Simplifies design of current control loops
- Enables a flexible circuit design
- QMLV Qualified 5962-1821001VXC



INA240-SEP

-4V to 80V Bi-Directional with PWM Rejection CSA For Large Common-Mode Transients



Features

- TID Characterization (ELDRS Free) to **30 krad(Si)**
- SEL Immune to LET = **43 MeV·cm²/mg** at 125°C
- High Accuracy
 - Input Offset Voltage: **25 μV (max)** with **250 nV/°C Max. Drift**
 - Gain Error: **±0.25% (max)** with **2.5 ppm/°C Max. Drift**
- Available in Military) Temperature Range **-55°C to 125°C**
- Fixed Gain: **20 V/V**
- Package: **8-Pin TSSOP** (3.0 × 4.4 mm)



Applications

- Low Earth Orbit Space Applications
- Power Supervision
- Overcurrent and Undercurrent Detection
- Satellites Telemetry
- Motor Control Loops



Tools and Resources

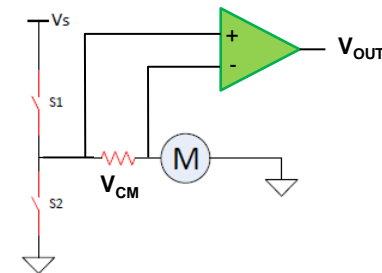
- Product folder: [LINK](#)
- Military Datasheet (VID): [LINK](#)
- Reliability & Radiation Reports: [LINK](#)



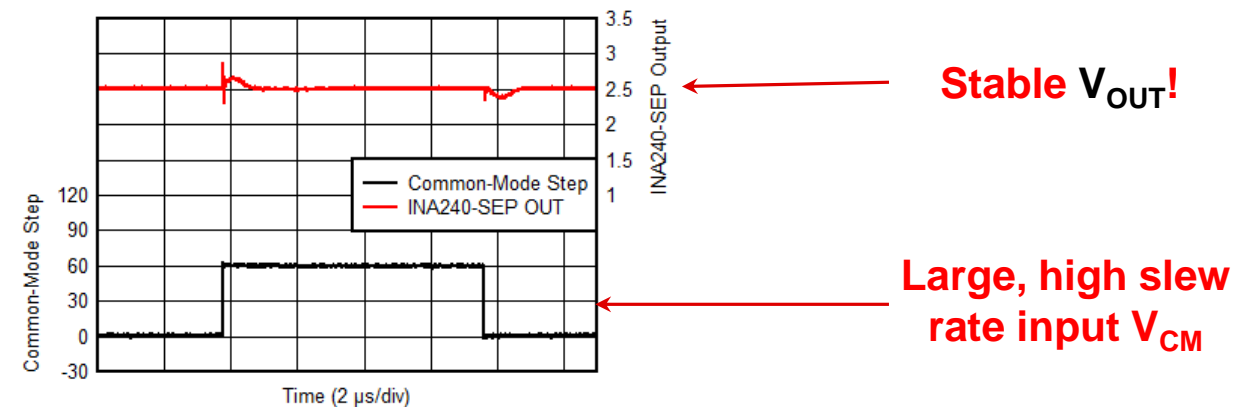
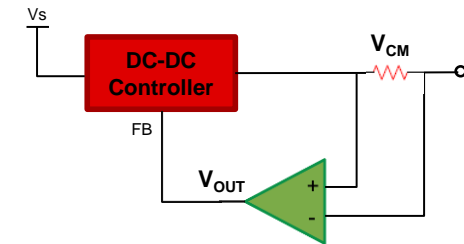
Benefits

- Radiation Lot Acceptance Testing (RLAT) to 20 krad(Si)
- Vendor Item Drawing (VID) [V62/18615](#)
- Large input range to integrate into increasing common-mode voltage applications
- High accuracy minimizes system margins
- High CMRR allows for direct in-line motor current sensing

In-Line Motor Current Sensing

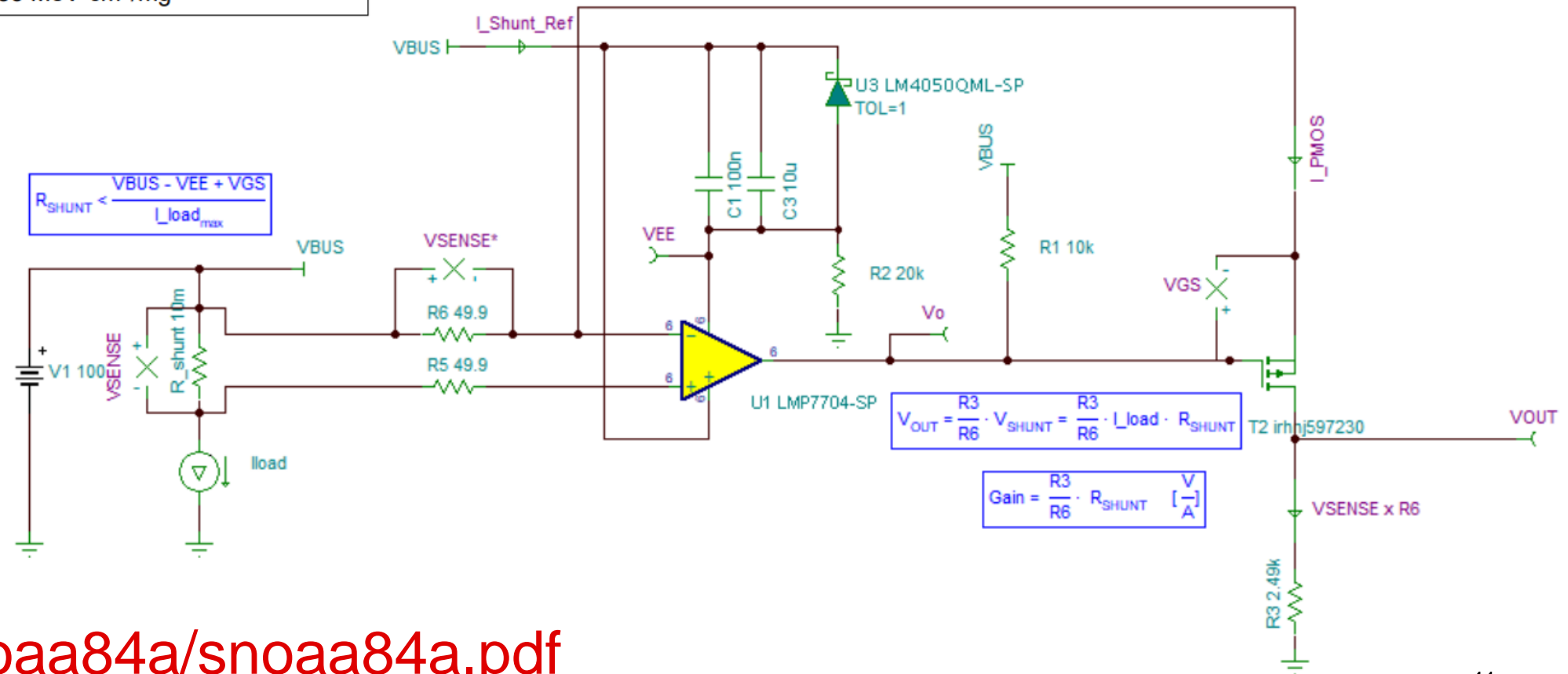


High-Side DC-DC Current Sensing



High Common Mode Current Measurement

Parameter	Value
Common-Mode Voltage (VCM)	100 V
Load Current (I _{load} or I _{shunt})	1 A to 10A
Output Voltage (V _{out})	0.5 V to 5 V
Output Voltage Error	< 0.7%
Power Consumption	< 700 mW
Total Ionizing Dose (TID)	100-krad (Si)
Single Event Latch-up (SEL) Immunity	85 MeV·cm ² /mg



- <https://www.ti.com/lit/an/snoaa84a/snoaa84a.pdf>

Space Grade Satellite Telemetry Reference Design

TIDA-010197

Benefits

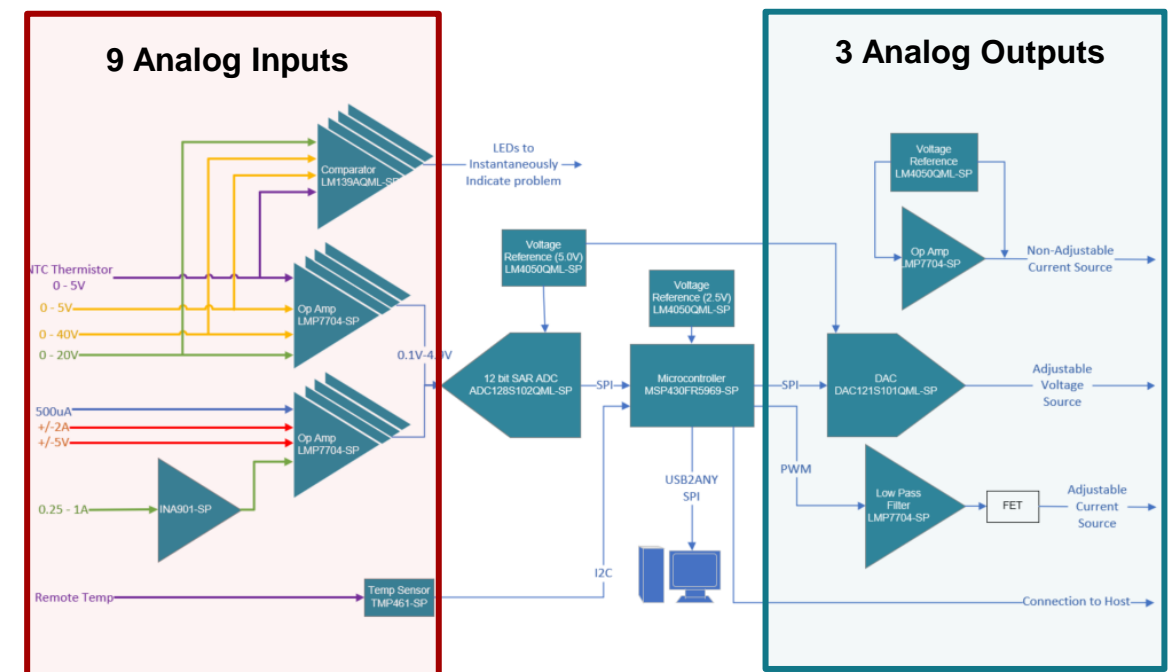
- All inclusive telemetry module to monitor a variety of measurements:
 - Voltage, Current, Temperature, Sensors (Current Output)
- Options for “5 V Rail” or “5 V and 12V Rails”
- Multiple integration options for different size, cost, and accuracy needs
 - Integrated MCU ADC (50~75 krad and 72 MeV)
 - ADC128S102QML-SP 12-Bit ADC (100 krad and 75 MeV)

Devices

- ADC128S102QML-SP 8-Ch, 12-bit ADC
- MSP430FR5969-SP FRAM Mixed-Signal Microcontroller
- LMP7704-SP Precision Quad Op Amp
- LM158QML-SP GP Dual Op Amp
- DAC121S101QML-SP 12-Bit DAC
- LM4050QML-SP Shunt Voltage Reference
- TMP461-SP Digital Output (I2C) Temp Sensor
- INA901-SP Current Sense Amp
- LM139QML-SP Quad Comparator

Target Applications

- Satellites
 - Health Monitoring / Telemetry
 - Power Monitoring on Busses
 - RF PA Biasing
 - TEC Monitor
 - Attitude & Orbit Control System (AOCS)



Web address with more collateral:

<https://www.ti.com/applications/industrial/aerospace-defense/space/overview.html>

The “Spacecraft Circuit Design Handbook”:

<https://www.ti.com/lit/eb/slyy214/slyy214.pdf>

Thanks