LMP8646 Precision Current Limiter

1 Features

- Provides Circuit Protection and Current Limiting
- Single Supply Operation
- –2-V to 76-V Common-Mode Voltage Range
- Variable Gain Set by External Resistor
- Adjustable Bandwidth Set by External Capacitor
- Buffered Output
- 3% Output Accuracy Achievable at V_{SENSE} = 100 mV
- Key Specifications:
  - Supply Voltage Range 2.7 V to 12 V
  - Output Current (Source) 0 to 5 mA
  - Gain Accuracy 2.0% (max)
  - Transconductance 200 μA/V
  - Offset ±1 mV (Maximum)
  - Quiescent Current 380 μA
  - Input Bias 12 μA (Typical)
  - PSRR 85 dB
  - CMRR 95 dB
  - Temperature Range −40°C to 125°C
  - 6-Pin SOT Package

2 Applications

- High-Side and Low-Side Current Limit
- Circuit Fault Protection
- Battery and Supercap Charging
- LED Constant Current Drive
- Power Management

3 Description

The LMP8646 is a precision current limiter used to improve the current limit accuracy of any switching or linear regulator with an available feedback node.

The LMP8646 accepts input signals with a common-mode voltage ranging from –2 V to 76 V. It has a variable gain which is used to adjust the sense current. The gain is configured with a single external resistor, R_G, providing a high level of flexibility and accuracy up to 2%. The adjustable bandwidth, which allows the device to be used with a variety of applications, is configurable with a single external capacitor in parallel with R_G. In addition, the output is buffered in order to provide a low output impedance.

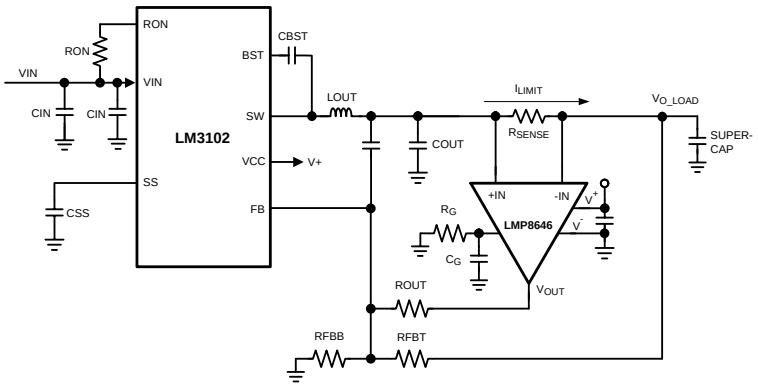
The LMP8646 is an ideal choice for industrial, automotive, telecommunications, and consumer applications where circuit protection and improved precision systems are required. The LMP8646 is available in a 6-pin SOT package and can operate at temperature range of −40°C to 125°C.

Device Information(1)

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMP8646	SOT (6)	2.90 mm × 1.60 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

Typical Application



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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (March 2013) to Revision B — **Page**

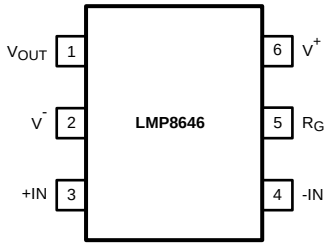
- Added *Pin Configuration and Functions* section, *Handling Rating* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section ... 1

Changes from Original (March 2013) to Revision A — **Page**

- Changed layout of National Semiconductor Data Sheet to TI format ... 22

5 Pin Configuration and Functions

DDC Package
6-Pin SOT
Top View



Pin Functions

PIN		DESCRIPTION
NAME	NO.	
V_{OUT}	1	Single-Ended Output Voltage
V^-	2	Negative Supply Voltage. This pin should be connected to ground.
+IN	3	Positive Input
-IN	4	Negative Input
R_G	5	External Gain Resistor. An external capacitance (C_G) may be added in parallel with R_G to limit the bandwidth.
V^+	6	Positive Supply Voltage

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)[1][1]

	MIN	MAX	UNIT
Supply Voltage ($V_S = V^+ - V^-$)		13.2	V
Differential voltage +IN- (-IN)		6	V
Voltage at pins +IN, -IN	–6	80	V
Voltage at R_G pin		13.2	V
Voltage at OUT pin	V^-	V^+	V
Junction Temperature[2]		150	°C
Storage temperature range	–65	150	°C
For soldering specifications see SNOA549			

(1) *Absolute Maximum Ratings* indicate limits beyond which damage to the device may occur. *Recommended Operating Conditions* indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the *Electrical Characteristics: 2.7 V* tables.
(2) The maximum power dissipation must be derated at elevated temperatures and is dictated by $T_{J(MAX)}$, θ_{JA}, and the ambient temperature, T_A. The maximum allowable power dissipation $P_{DMAX} = (T_{J(MAX)} - T_A)/ \theta_{JA}$ or the number given in Absolute Maximum Ratings, whichever is lower.

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$ Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001[1]	Pins +IN and -IN	±4000	V
		All pins except +IN and -IN	±2000	
	Charged-device model (CDM), per JEDEC specification JESD22-C101[2]		±1250	
	Machine model		±250	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

	MIN	MAX	UNIT
Supply Voltage ($V_S = V^+ - V^-$)	2.7	12	V
Temperature Range[1]	–40	125	V

(1) The maximum power dissipation must be derated at elevated temperatures and is dictated by $T_{J(MAX)}$, θ_{JA}, and the ambient temperature, T_A. The maximum allowable power dissipation $P_{DMAX} = (T_{J(MAX)} - T_A)/ \theta_{JA}$ or the number given in Absolute Maximum Ratings, whichever is lower.

6.4 Thermal Information

THERMAL METRIC[1]		LMP8646 DDC 6 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	96	°C/W

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.

6.5 Electrical Characteristics: 2.7 V

Unless otherwise specified, all limits ensured for at T_A = 25°C, V_S= (V^+ – V^-) = (2.7 V - 0 V) = 2.7 V, −2 V < V_{CM} < 76 V, R_G= 25 kΩ, R_L = 10 kΩ.(1)

PARAMETER		TEST CONDITIONS	MIN(2)	TYP(3)	MAX(2)	UNIT
V_{OFFSET}	Input Offset Voltage	V_{CM} = 2.1 V	–1		1	mV
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–1.7		1.7	
TCV_{OS}	Input Offset Voltage Drift(4)(5)	V_{CM} = 2.1 V			7	µV/°C
I_B	Input Bias Current(6)	V_{CM} = 2.1 V		12	20	µA
e_{ni}	Input Voltage Noise(5)	f > 10 kHz, R_G = 5 kΩ		120		nV/√Hz
V_{SENSE}	Max Input Sense Voltage(5)	V_{CM} = 12 V, R_G = 5 kΩ			600	mV
Gain A_V	Adjustable Gain Setting(5)	V_{CM} = 12 V	1		100	V/V
Gm	Transconductance = 1/R_{IN}	V_{CM} = 2.1 V		200		µA/V
	Accuracy	V_{CM} = 2.1 V	–2%		2%	
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–3.4%		3.4%	
	Gm drift(5)	−40°C to 125°C, V_{CM}= 2.1 V			140	ppm /°C
PSRR	Power Supply Rejection Ratio	V_{CM} = 2.1 V, 2.7 V < V^+ < 12 V	85			dB
CMRR	Common-Mode Rejection Ratio	2.1 V < V_{CM} < 76 V	95			dB
		–2 V <V_{CM} < 2.1 V	55			
SR	Slew Rate(7)(5)	V_{CM} = 5 V, C_G = 4 pF, V_{SENSE} from 25 mV to 175 mV, C_L = 30 pF, R_L = 1MΩ		0.5		V/µs
I_S	Supply Current	V_{CM} = 2.1 V		380	610	uA
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C			807	
		V_{CM} = –2 V		2000	2500	
		V_{CM} = –2 V, –40°C ≤ T_J ≤ 125°C			2700	
V_{OUT}	Maximum Output Voltage	V_{CM} = 2.1 V, R_G = 500 kΩ	1.1			V
	Minimum Output Voltage	V_{CM} = 2.1 V			20	mV
	Maximum Output Voltage	VS = V_{CM} = 3.3 V, R_G = 500 kΩ	1.6			V
	Minimum Output Voltage	VS = V_{CM} = 3.3 V, R_G = 500 kΩ			22	mV
I_{OUT}	Output current(5)	Sourcing, V_{OUT}= 600 mV, R_G = 150 kΩ		5		mA
C_{LOAD}	Max Output Capacitance Load(5)			30		pF

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T_J = T_A. No assurance of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T_J > T_A.
(2) All limits are specified by testing, design, or statistical analysis.
(3) Typical values represent the most likely parametric norm at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.
(4) Offset voltage temperature drift is determined by dividing the change in V_{OS} at the temperature extremes by the total temperature change.
(5) This parameter is specified by design and/or characterization and is not tested in production.
(6) Positive Bias Current corresponds to current flowing into the device.
(7) The number specified is the average of rising and falling slew rates and measured at 90% to 10%.

6.6 Electrical Characteristics: 5 V

Unless otherwise specified, all limits ensured for at T_A = 25°C, V_S= V^+-V^-, V^+ = 5 V, V^- = 0 V, −2 V < V_{CM} < 76 V, R_g= 25 kΩ, R_L = 10 kΩ.(1)

PARAMETER		TEST CONDITIONS	MIN(2)	TYP(3)	MAX(2)	UNIT
V_{OFFSET}	Input Offset Voltage	V_{CM} = 2.1 V	–1		1	mV
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–1.7		1.7	
TCV_{OS}	Input Offset Voltage Drift(4)(5)	V_{CM} = 2.1 V			7	µV/°C
I_B	Input Bias Current(6)	V_{CM} = 2.1 V		12.5	22	µA
e_{ni}	Input Voltage Noise(5)	f > 10 kHz, R_G = 5 kΩ		120		nV/√Hz
$V_{SENSE(MAX)}$	Max Input Sense Voltage(5)	V_{CM} = 12 V, R_G = 5 kΩ		600		mV
Gain A_V	Adjustable Gain Setting(5)	V_{CM} = 12 V	1		100	V/V
Gm	Transconductance = 1/R_{IN}	V_{CM} = 2.1 V		200		µA/V
	Accuracy	V_{CM} = 2.1 V	–2%		2%	
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–3.4%		3.4%	
	Gm drift(5)	−40°C to 125°C, V_{CM}= 2.1 V			140	ppm /°C
PSRR	Power Supply Rejection Ratio	V_{CM} = 2.1 V, 2.7 V < V^+ < 12 V,	85			dB
CMRR	Common-Mode Rejection Ratio	2.1 V <V_{CM} < 76 V	95			dB
		–2 V < V_{CM} < 2.1 V	55			
SR	Slew Rate(7)(5)	V_{CM} = 5 V, C_G = 4 pF, V_{SENSE} from 100 mV to 500 mV, C_L = 30 pF, R_L= 1MΩ		0.5		V/µs
I_S	Supply Current	V_{CM} = 2.1 V		450	660	uA
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C			939	
		V_{CM} = –2 V		2100	2800	
		V_{CM} = –2 V, –40°C ≤ T_J ≤ 125°C			3030	
V_{OUT}	Maximum Output Voltage	V_{CM} = 5 V, R_G= 500 kΩ	3.3			V
	Minimum Output Voltage	V_{CM} = 2.1 V			22	mV
I_{OUT}	Output current(5)	Sourcing, V_{OUT}= 1.65 V, R_G = 150 kΩ		5		mA
C_{LOAD}	Max Output Capacitance Load(5)			30		pF

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T_J = T_A. No assurance of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T_J > T_A.
(2) All limits are specified by testing, design, or statistical analysis.
(3) Typical values represent the most likely parametric norm at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.
(4) Offset voltage temperature drift is determined by dividing the change in V_{OS} at the temperature extremes by the total temperature change.
(5) This parameter is specified by design and/or characterization and is not tested in production.
(6) Positive Bias Current corresponds to current flowing into the device.
(7) The number specified is the average of rising and falling slew rates and measured at 90% to 10%.

6.7 Electrical Characteristics: 12 V

Unless otherwise specified, all limits ensured for at T_A = 25°C, V_S= V^+ - V^-, V^+ = 12 V, V^- = 0 V, −2 V < V_{CM} < 76 V, R_g= 25 kΩ, R_L = 10 kΩ.(1)

PARAMETER		TEST CONDITIONS	MIN(2)	TYP(3)	MAX(2)	UNIT
V_{OFFSET}	Input Offset Voltage	V_{CM} = 2.1 V	–1		1	mV
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–1.7		1.7	
TCV_{OS}	Input Offset Voltage Drift(4)(5)	V_{CM} = 2.1 V			7	µV/°C
I_B	Input Bias Current(6)	V_{CM} = 2.1 V		13	23	µA
e_{ni}	Input Voltage Noise(5)	f > 10 kHz, R_G = 5 kΩ		120		nV/√Hz
$V_{SENSE(MAX)}$	Max Input Sense Voltage(5)	V_{CM} =12 V, R_G = 5 kΩ		600		mV
Gain A_V	Adjustable Gain Setting(5)	V_{CM} = 12 V	1		100	V/V
Gm	Transconductance = 1/R_{IN}	V_{CM} = 2.1 V		200		µA/V
	Accuracy	V_{CM} = 2.1 V	–2%		2%	
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C	–3.4%		3.4%	
	Gm drift(5)	−40°C to 125°C, V_{CM} =2.1 V			140	ppm /°C
PSRR	Power Supply Rejection Ratio	V_{CM} = 2.1 V, 2.7 V < V^+ < 12 V	85			dB
CMRR	Common-Mode Rejection Ratio	2.1 V < V_{CM} < 76 V	95			dB
		–2 V < V_{CM} < 2.1 V	55			
SR	Slew Rate(7)(5)	V_{CM} = 5 V, C_G = 4 pF, V_{SENSE} from 100 mV to 500 mV, C_L = 30 pF, R_L=1 MΩ		0.6		V/µs
I_S	Supply Current	V_{CM} = 2.1 V		555	845	uA
		V_{CM} = 2.1 V, –40°C ≤ T_J ≤ 125°C			1123	
		V_{CM} = –2 V		2200	2900	
		$_{CM}$ = –2 V, –40°C ≤ T_J ≤ 125°C			3110	
V_{OUT}	Maximum Output Voltage	V_{CM} = 12 V, R_G= 500 kΩ,	10			V
	Minimum Output Voltage	V_{CM} = 2.1 V			24	mV
I_{OUT}	Output current(5)	Sourcing, V_{OUT}= 5.25 V, R_G = 150 kΩ		5		mA
C_{LOAD}	Max Output Capacitance Load(5)			30		pF

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T_J = T_A. No assurance of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T_J > T_A.
(2) All limits are specified by testing, design, or statistical analysis.
(3) Typical values represent the most likely parametric norm at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.
(4) Offset voltage temperature drift is determined by dividing the change in V_{OS} at the temperature extremes by the total temperature change.
(5) This parameter is specified by design and/or characterization and is not tested in production.
(6) Positive Bias Current corresponds to current flowing into the device.
(7) The number specified is the average of rising and falling slew rates and measured at 90% to 10%.

6.8 Typical Characteristics

Unless otherwise specified: T_A = 25°C, V_S= V^+ - V^-, V_{SENSE}= +IN - (-IN), R_L = 10 kΩ.

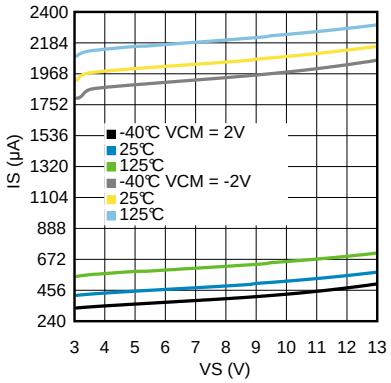


Figure 1. Supply Curent vs. Supply Voltage for V_{CM} = 2 V

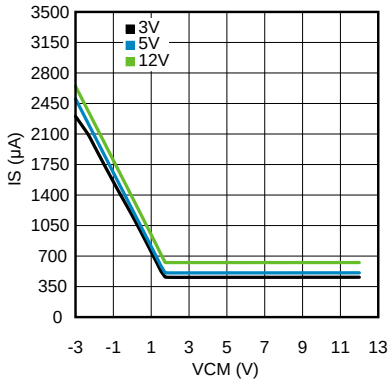


Figure 2. Supply Current vs. V_{CM}

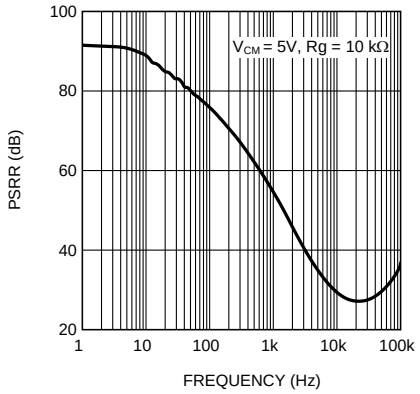


Figure 3. AC PSRR vs. Frequency

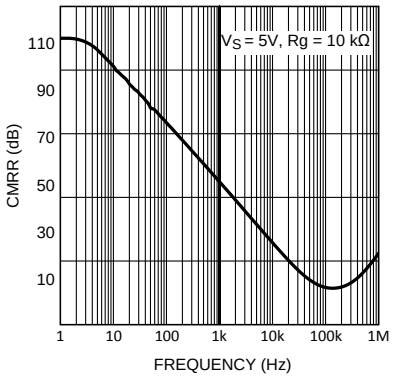


Figure 4. AC CMRR vs. Frequency

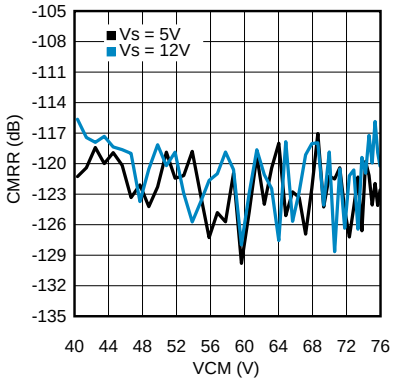


Figure 5. CMRR vs. High V_{CM}

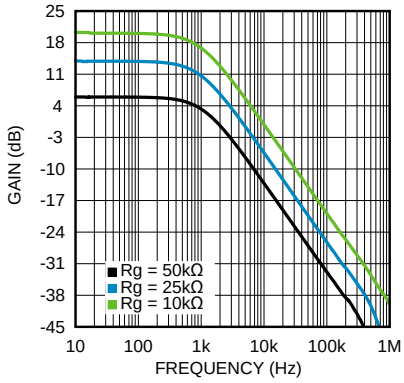


Figure 6. Gain vs. Frequency (BW = 1kHz)

Typical Characteristics (continued)

Unless otherwise specified: T_A = 25°C, V_S= V^+ - V^-, V_{SENSE}= +IN - (-IN), R_L = 10 kΩ.

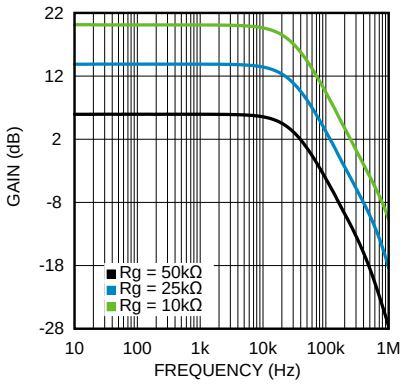


Figure 7. Gain vs. Frequency (BW = 35 kHz)

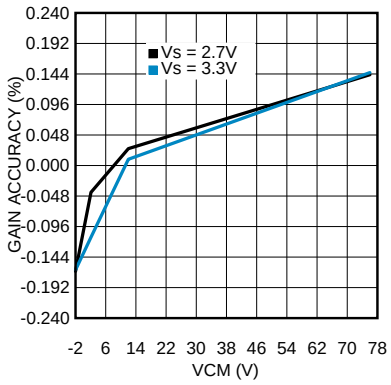


Figure 8. Gain Accuracy vs. V_{CM}

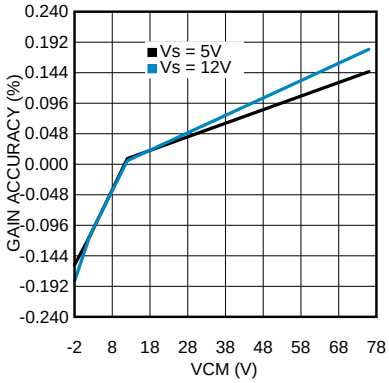


Figure 9. Gain Accuracy vs. V_{CM}

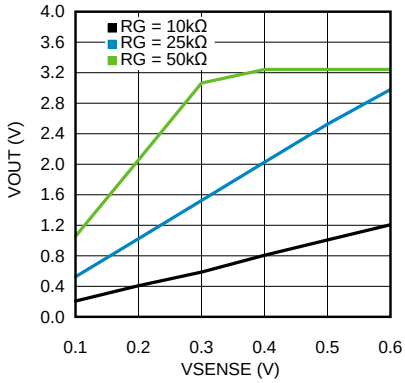


Figure 10. V_{OUT} vs. V_{SENSE}

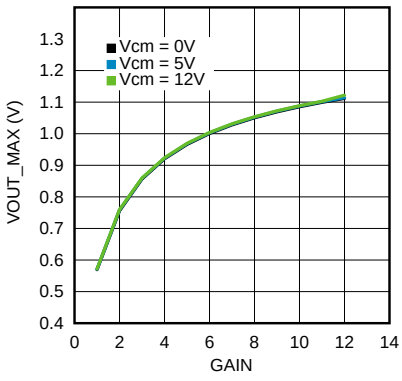


Figure 11. V_{OUT_MAX} vs. Gain at Vs = 2.7 V

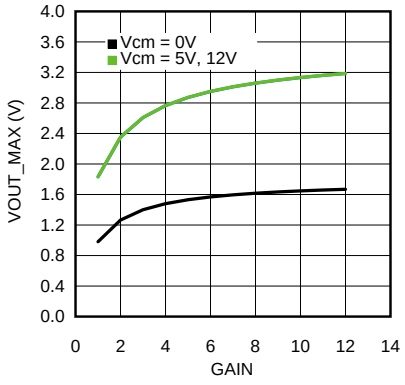


Figure 12. V_{OUT_MAX} vs. Gain at Vs = 5.0 V

Typical Characteristics (continued)

Unless otherwise specified: T_A = 25°C, V_S= V^+ - V^-, V_{SENSE}= +IN - (-IN), R_L = 10 kΩ.

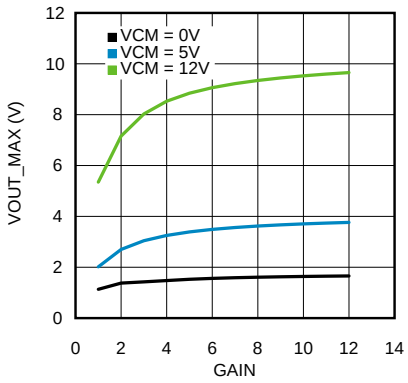


Figure 13. V_{OUT_MAX} vs. Gain at Vs = 12 V

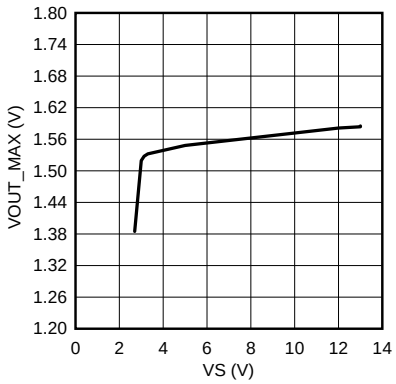


Figure 14. V_{OUT_MAX} vs. V_S at V_{CM} = –2 V

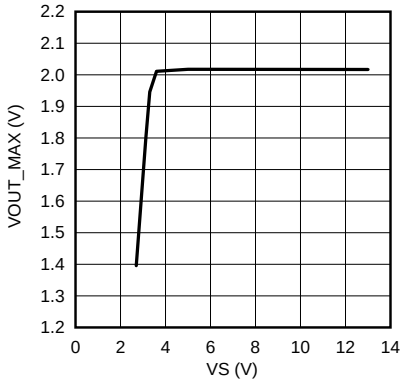


Figure 15. V_{OUT_MAX} vs. V_S at V_{CM} = 2.1 V

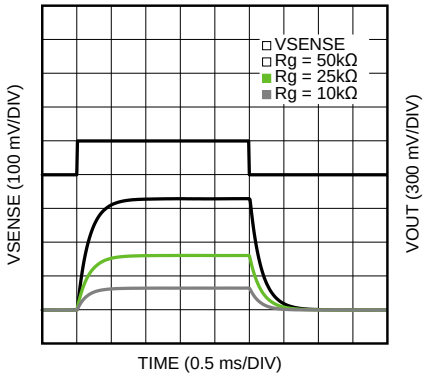


Figure 16. Large Step Response at BW = 1kHz

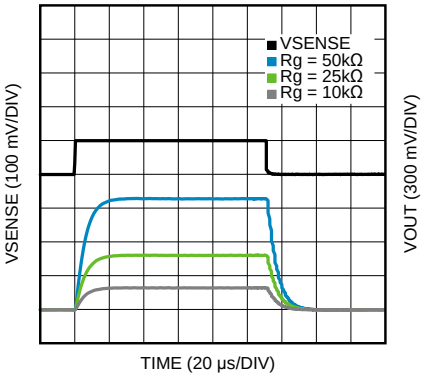


Figure 17. Large Step Response at BW = 35 kHz

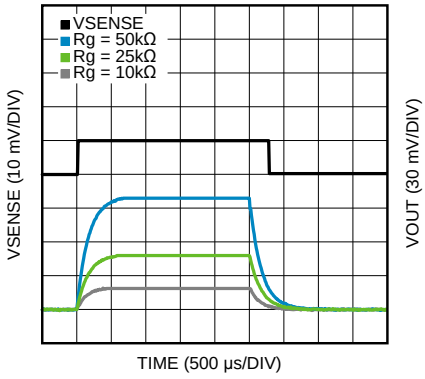


Figure 18. Small Step Response at BW = 1 kHz

Typical Characteristics (continued)

Unless otherwise specified: T_A = 25°C, V_S= V^+ - V^-, V_{SENSE}= +IN - (-IN), R_L = 10 kΩ.

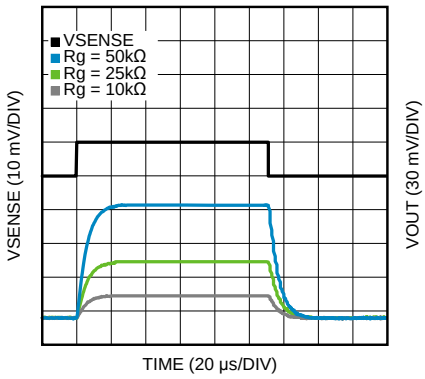


Figure 19. Small Step Response at BW = 35 kHz

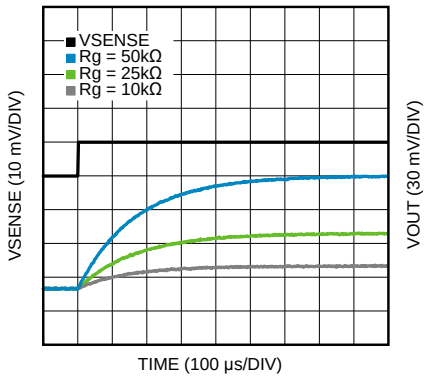


Figure 20. Settling Time (Rise) at 1 kHz

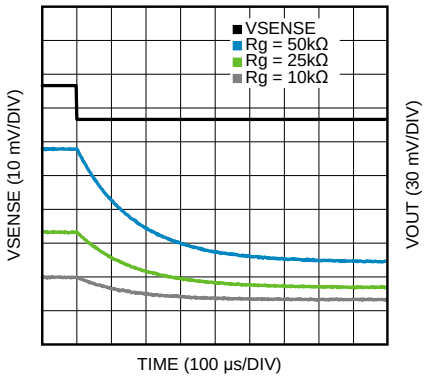


Figure 21. Settling Time (Fall) at 1 kHz

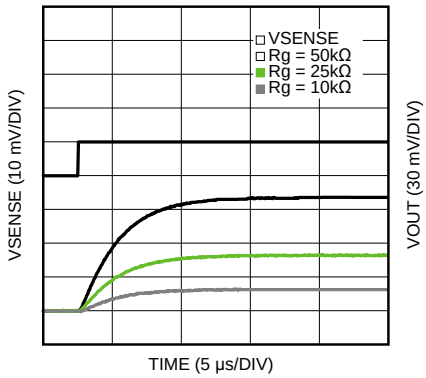


Figure 22. Settling Time (Rise) at 35 kHz

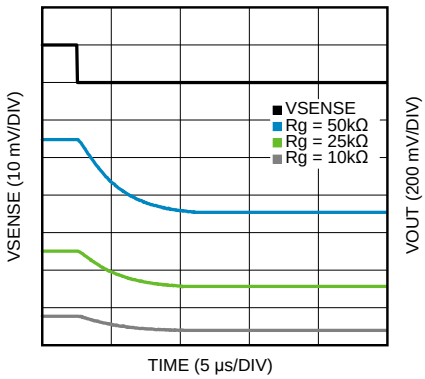


Figure 23. Settling Time (Fall) at 35 kHz

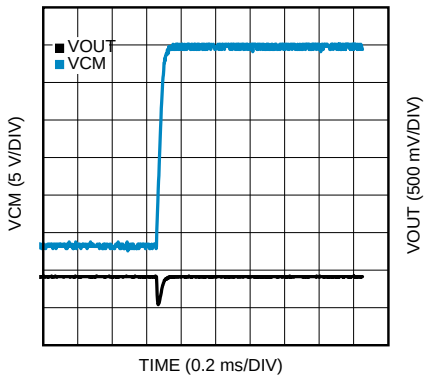


Figure 24. Common-Mode Step Response (Rise) at 35 kHz

Typical Characteristics (continued)

Unless otherwise specified: T_A = 25°C, V_S= V^+ - V^-, V_{SENSE}= +IN - (-IN), R_L = 10 kΩ.

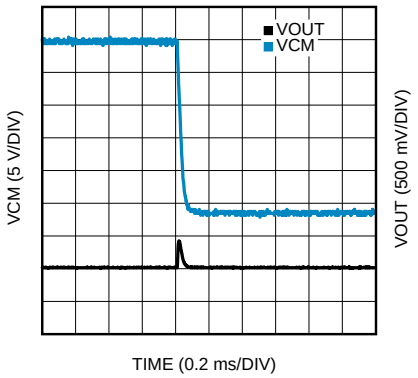


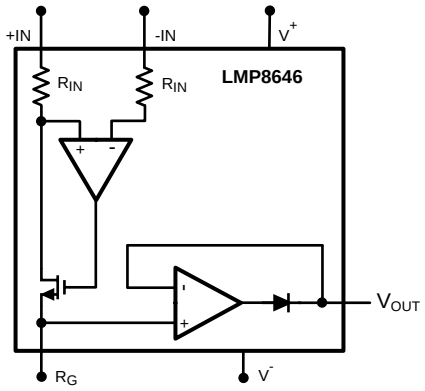
Figure 25. Common-Mode Step Response (Fall) at 35 kHz

7 Detailed Description

7.1 Overview

The LMP8646 is a single-supply precision current limiter with variable gain selected through an external resistor (R_G) and a variable bandwidth selected through an external capacitor (C_G) in parallel with R_G. Its common-mode of operation is –2 V to 76 V, and the LMP8646 has an buffered output to provide a low-output impedance. More details of the LMP8646's functional description can be seen in the following subsections.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Theory of Operation

As seen from Figure 26, the sense current flowing through R_{SENSE} develops a voltage drop equal to V_{SENSE}. The high impedance inputs of the amplifier does not conduct this current and the high open-loop gain of the sense amplifier forces its noninverting input to the same voltage as the inverting input. In this way the voltage drop across R_{IN} matches V_{SENSE}. The current I_{IN} flowing through R_{IN} has the following equation:

$$I_{IN} = V_{SENSE} / R_{IN} = R_{SENSE} * I_{SENSE} / R_{IN}$$

where

- $R_{IN} = 1/Gm = 1/(200\ \mu A/V) = 5\ kOhm$ (1)

I_{IN} flows entirely across the external gain resistor R_G to develop a voltage drop equal to:

$$V_{RG} = I_{IN} * R_G = (V_{SENSE}/R_{IN}) * R_G = [(R_{SENSE} * I_{SENSE}) / R_{IN}] * R_G \quad (2)$$

This voltage is buffered and showed at the output with a very low impedance allowing a very easy interface of the LMP8646 with the feedback of many voltage regulators. This output voltage has the following equation:

$$V_{OUT} = V_{RG} = [(R_{SENSE} * I_{SENSE}) / R_{IN}] * R_G \quad (3)$$

$$V_{OUT} = V_{SENSE} * R_G / R_{IN} \quad (4)$$

$$V_{OUT} = V_{SENSE} * R_G / (5\ kOhm) \quad (5)$$

$$V_{OUT} = V_{SENSE} * Gain$$

where

- $Gain = R_G / R_{IN}$ (6)

Feature Description (continued)

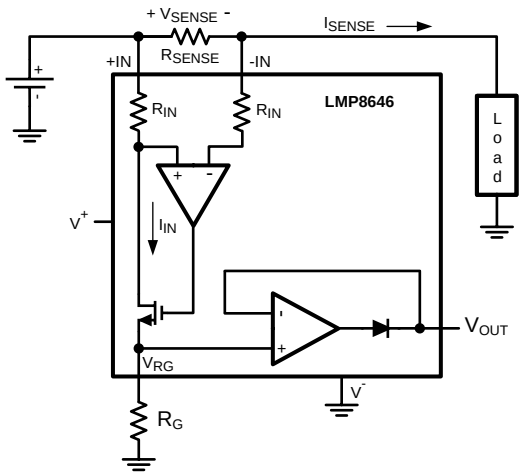


Figure 26. Current Monitor

7.3.1.1 Maximum Output Voltage, V_{OUT_MAX}

The maximum output voltage, V_{OUT_MAX}, depends on the supply voltage, $V_S = V^+ - V^-$, and on the common-mode voltage, $V_{CM} = (+IN + -IN) / 2$.

The following subsections show three cases to calculate for V_{OUT_MAX}.

7.3.1.1.1 Case 1: $-2\ V < V_{CM} < 1.8\ V$, and $V_S > 2.7\ V$

If $V_S \geq 5$ V,

then $V_{OUT\_MAX} = 1.3$ V.

Else if Vs = 2.7 V,

then $V_{OUT\_MAX} = 1.1$ V.

7.3.1.1.2 Case 2: $1.8\ V < V_{CM} < V_S$, and $V_S > 3.3\ V$

In this case, V_X is a fixed value that depends on the supply voltage. V_X has the following values:

If $V_S = 12$ V, then $V_X = 10$ V.

Else if $V_S = 5$ V, then $V_X = 3.3$ V .

Else if $V_S = 2.7$ V, then $V_X = 1.1$ V.

If $V_X \leq (V_{CM} - V_{SENSE} - 0.25)$,

then $V_{OUT\_MAX} = V_X$.

Else,

$V_{OUT\_MAX} = (V_{CM} - V_{SENSE} - 0.25)$.

For example, if $V_{CM} = 4$ V, $V_S = 5$ V (and thus $V_X = 3.3$ V), $V_{SENSE} = 0.1$ V, then $V_{OUT\_MAX} = 3.3$ V because 3.3 V ≤ (4 - 0.1 - 0.25).

7.3.1.1.3 Case 3: $V_{CM} > V_S$, and $V_S > 2.7\ V$

If $V_S = 12$ V, then $V_{OUT\_MAX} = 10$ V.

Else if $V_S = 5$ V, then $V_{OUT\_MAX} = 3.3$ V .

Else if $V_S = 2.7$ V, then $V_{OUT\_MAX} = 1.1$ V.

7.4 Device Functional Modes

7.4.1 Output Accuracy

The output accuracy is the device error contributed by the LMP8646 based on its offset and gain errors. The LMP8646 output accuracy has the following equations:

$$\text{Output Accuracy} = \left| \frac{V_{OUT\_THEO} - V_{OUT\_CAL}}{V_{OUT\_THEO}} \right| \times 100(\%)$$

$$\text{where } V_{OUT\_THEO} = (V_{SENSE}) \times \frac{R_G}{1/Gm}$$

$$\text{and } V_{OUT\_CALC} = \frac{(V_{SENSE} + V_{OFFSET}) \times R_G}{1/[Gm\ (1 + Gm\_Accuracy)]}$$

Output Accuracy Equations (7)

For example, assume V_{SENSE} = 100 mV, R_G = 10 kOhm, and it is known that V_{OFFSET} = 1 mV and Gm_Accuracy = 2% (Electrical Characteristics Table), then the output accuracy can be calculated as:

$$V_{OUT\_THEO} = (100\ mV) \times \frac{10\ k\Omega}{1/(200\mu)} = 0.2V$$

$$V_{OUT\_CALC} = \frac{(100\ mV + 1\ mV) \times 10\ k\Omega}{1/[200\mu\ (1 + 2/100)]} = 0.20604V$$

$$\text{Output Accuracy} = \left| \frac{0.2V - 0.20604V}{0.2V} \right| \times 100 = 3.02\%$$

Output Accuracy Example (8)

In fact, as V_{SENSE} decreases, the output accuracy worsens as seen in Figure 27. These equations provide a valuable tool to estimate how the LMP8646 affects the overall system performance. Knowing this information allows the system designer to pick the appropriate external resistances (R_{SENSE} and R_G) to adjust for the tolerable system error. Examples of this tolerable system error can be seen in the next sections.

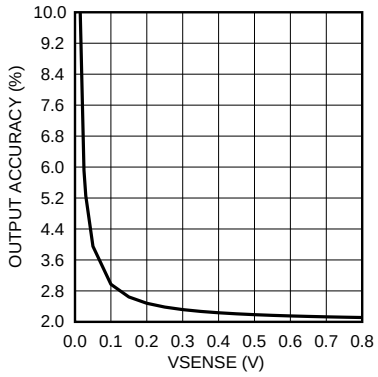


Figure 27. Output Accuracy vs. V_{SENSE}

7.4.2 Selection of the Sense Resistor, R_{SENSE}

The accuracy of the current measurement also depends on the value of the shunt resistor R_{SENSE}. Its value depends on the application and is a compromise between small-signal accuracy and maximum permissible voltage loss in the load line.

R_{SENSE} is directly proportional to V_{SENSE} through the equation $R_{SENSE} = (V_{SENSE}) / (I_{SENSE})$. If V_{SENSE} is small, then there is a smaller voltage loss in the load line, but the output accuracy is worse because the LMP8646 offset error will contribute more. Therefore, high values of R_{SENSE} provide better output accuracy by minimizing the effects of offset, while low values of R_{SENSE} minimize the voltage loss in the load line. For most applications, best performance is obtained with an R_{SENSE} value that provides a V_{SENSE} of 100 mV to 200 mV.

Device Functional Modes (continued)

7.4.2.1 R_{SENSE} Consideration for System Error

The output accuracy described in the previous section talks about the error contributed just by the LMP8646. The system error, however, consists of the errors contributed by the LMP8646 as well as other external resistors such as R_{SENSE} and R_G. Let's rewrite the output accuracy equation for the system error assuming that R_{SENSE} is non-ideal and R_G is ideal. This equation can be seen as:

$$\text{System Error} = \left| \frac{V_{OUT\_THEO} - V_{OUT\_CAL}}{V_{OUT\_THEO}} \right| \times 100(\%)$$

$$\text{where } V_{OUT\_THEO} = (R_{SENSE} \times I_{SENSE}) \times \frac{R_G}{1/Gm}$$

$$\text{and } V_{OUT\_CALC} = \frac{[R_{SENSE}\,(1+\text{Tolerance}) \times I_{SENSE} + V_{OFFSET}] \times R_G}{1/[Gm\,(1 + Gm\_Accuracy)]}$$

System Error Example Assuming R_{SENSE} is Non-ideal and R_G is Ideal (9)

Continuing from the previous output accuracy example, we can calculate for the system error assuming that R_{SENSE} = 100 mOhm (with 1% tolerance), I_{SENSE} = 1A, and R_G = 10 kOhm. From the Electrical Characteristics Table, it is also known that V_{OFFSET} = 1 mV and Gm_Accuracy = 2%.

$$V_{OUT\_THEO} = (100\ m\Omega \times 1A) \times \frac{10\ k\Omega}{1/(200\mu)} = 0.2V$$

$$V_{OUT\_CALC} = \frac{[100\ m\Omega\,(1+1/100) \times 1A + 1mV] \times 10\ k\Omega}{1/[200\mu\,(1 + 2/100)]} = 0.20808V$$

$$\text{System Error} = \left| \frac{0.2V - 0.20808V}{0.2V} \right| \times 100 = 4.04\%$$

System Error Example Assuming RSENSE is Non-ideal and RG is Ideal (10)

Because an R_{SENSE} tolerance will increase the system error, we recommend selecting an R_{SENSE} resistor with low tolerance.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LMP8646 can be driven by many different regulators with a feedback pin and connected to many different types of loads such as capacititve and resistive. The following sections gives three typical applications of the LMP8646.

8.2 Typical Applications

8.2.1 Application #1: Current Limiter With a Capacitive Load

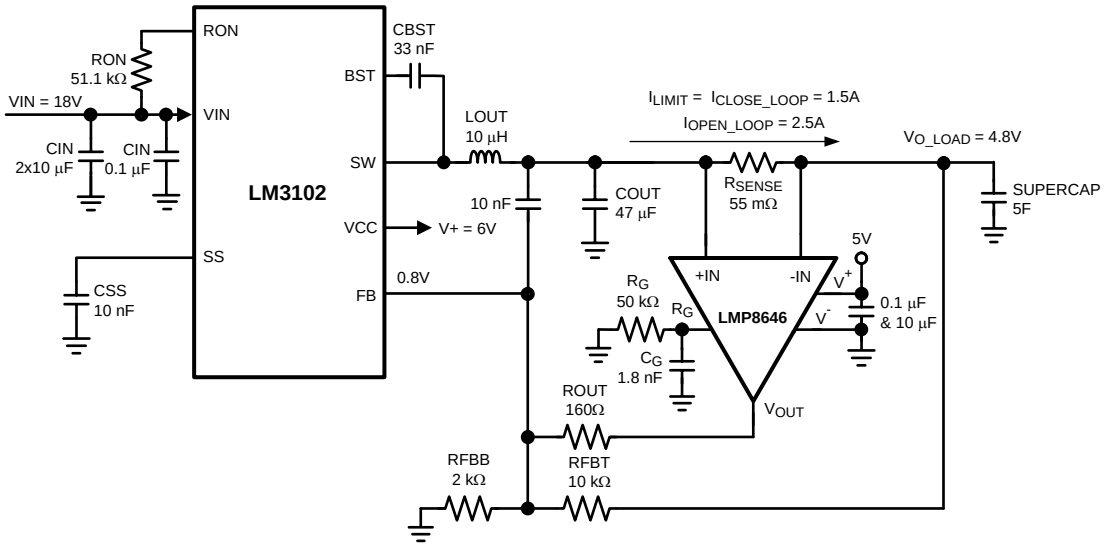


Figure 28. SuperCap Application With LM3102 Regulator

8.2.1.1 Design Requirements

A supercap application requires a very high capacitive load to be charged. This example assumes the output capacitor is 5F with a limited sense current at 1.5A. The LM3102 will provide the current to charge the supercap, and the LMP8646 will monitor this current to make sure it does not exceed the desired 1.5A value.

8.2.1.2 Detailed Design Procedure

To limit the capacitor current, first connect the LMP8646 output to the feedback pin of the LM3102, as shown in Figure 28. This feedback voltage at the FB pin is compared to a 0.8V internal reference. Any voltage above this 0.8V means the output current is above the desired value of 1.5A, and the LM3102 will reduce its output current to maintain the desired 0.8V at the FB pin.

The following steps show the design procedures for this supercap application. In summary, the steps consist of selecting the components for the voltage regulator, integrating the LMP8646 and selecting the proper values for its gain, bandwidth, and output resistor, and adjusting these components to yield the desired performance.

Step 1: Choose the components for the Regulator.

Refer to the LM3102 evaluation board application note (AN-1646) to select the appropriate components for the LM3102 voltage regulator.

Typical Applications (continued)

Step 2: Choose the sense resistor, R_{SENSE}

R_{SENSE} sets the voltage V_{SENSE} between +IN and -IN and has the following equation:

$$R_{SENSE} = V_{OUT} / [(I_{LIMIT}) * (R_G / 5kOhm)] \quad (11)$$

In general, R_{SENSE} depends on the output voltage, limit current, and gain. Refer to section *Selection of the Sense Resistor, R_{SENSE}* to choose the appropriate R_{SENSE} value; this example uses 55 mOhm.

Step 3: Choose the gain resistor, R_G, for LMP8646

R_G is chosen from the limited sense current. As stated, $V_{OUT} = (R_{SENSE} * I_{LIMIT}) * (R_G / 5kOhm)$. Since $V_{OUT} = V_{FB}$ = 0.8V, the limited sense current is 1.5A, and R_{SENSE} is 55 mOhm, R_G can be calculated as:

$$R_G = (V_{OUT} * 5\ kOhm) / (R_{SENSE} * I_{LIMIT}) \quad (12)$$

$$R_G = (0.8 * 5\ kOhm) / (55\ mOhm * 1.5A) = 50\ kOhm\ (approximate) \quad (13)$$

Step 4: Choose the Bandwidth Capacitance, C_G.

The product of C_G and R_G determines the bandwidth for the LMP8646. Refer to the Typical Performance Characteristics plots to see the range for the LMP8646 bandwidth and gain. Since each application is very unique, the LMP8646 bandwidth capacitance, C_G, needs to be adjusted to fit the appropriate application.

Bench data has been collected for the supercap application with the LM3102 regulator, and we found that this application works best for a bandwidth of 500 Hz to 3 kHz. Operating outside of this recommended bandwidth range might create an undesirable load current ringing. We recommend choosing a bandwidth that is in the middle of this range and using the equation $C_G = 1/(2*pi*R_G*Bandwidth)$ to find C_G. For example, if the bandwidth is 1.75 kHz and R_G is 50 kOhm, then C_G is approximately 1.8 nF. After this selection, capture the plot for I_{LIMIT} and adjust C_G until a desired load current plot is obtained.

Step 5: Calculate the Output Accuracy and Tolerable System Error

Since the LMP8646 is a precision current limiter, the output current accuracy is extremely important. This accuracy is affected by the system error contributed by the LMP8646 device error and other errors contributed by external resistances, such as R_{SENSE} and R_G.

In this application, $V_{SENSE} = I_{LIMIT} * R_{SENSE}$ = 1.5A * 55 mOhm = 0.0825V, and R_G = 50 kOhm. From the Electrical Characteristics Table, it is known that V_{OFFSET} = 1 mV and Gm_Accuracy = 2%. Using the equations shown in Equation 8, the output accuracy can be calculated as 3.24%.

After figuring out the LMP8646 output accuracy, choose a tolerable system error or the output current accuracy that is bigger than the LMP8646 output accuracy. This tolerable system error will be labeled as I_{ERROR}, and it has the equation $I_{ERROR} = (I_{MAX} - I_{LIMIT})/I_{MAX}$ (%). In this example, we will choose an I_{ERROR} of 5%, which will be used to calculate for ROUT shown in the next step.

Step 6: Choose the output resistor, ROUT

At start-up, the capacitor is not charged yet and thus the output voltage of the LM3102 is very small. Therefore, at start-up, the output current is at its maximum (I_{MAX}). When the output voltage is at its nominal, then the output current will settle to the desired limited value. Because a large current error is not desired, ROUT needs to be chosen to stabilize the loop with minimal initial start-up current error. Follow the equations and example below to choose the appropriate value for ROUT to minimize this initial error.

As discussed in step 4, the allowable I_{ERROR} is 5%, where $I_{ERROR} = (I_{MAX} - I_{LIMIT})/I_{MAX}$ (%). Therefore, the maximum allowable current is calculated as: $I_{MAX} = I_{LIMIT}$ (1+ I_{ERROR}) = 1.5A * (1 + 5/100) = 1.575 A.

Next, use Equation 14 below to calculate for ROUT:

$$ROUT = \frac{(I_{MAX} * R_{SENSE} * Gain - V_{FB})}{\frac{V_{FB}}{RFBB} - \frac{(V_{O\_REG\_MIN} - V_{FB})}{RFBT}} \quad (14)$$

For example, assume the minimum LM3102 output voltage, $V_{O\_REG\_MIN}$, is 0.6V, then ROUT can be calculated as ROUT = [1.575A * 55 mOhm * (49.9k / 5k) - 0.8] / [(0.8 / 2k) - (0.6 - 0.8) / 10k] = 153.6 Ohm.

Typical Applications (continued)

Populate ROUT with a resistor that is as close as possible to 153.6 Ohm (this application uses 160 Ohm). If the limited sense current has a gain error and is not 1.5A at any point in time, then adjust this ROUT value to obtain the desired limit current.

We recommend that the value for ROUT is at least 50 Ohm.

Step 7: Adjusting Components

Capture the output current and output voltage plots and adjust the components as necessary. The most common components to adjust are C_G to decrease the current ripple and ROUT to get a low current error. An example output current and voltage plot can be seen in Figure 29.

8.2.1.3 Application Curve

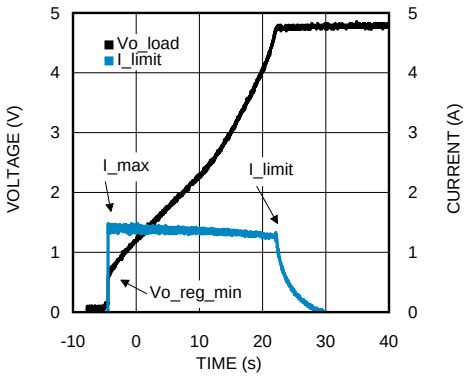


Figure 29. SuperCap Application With LM3102 Regulator Plot

8.2.2 Application #2: Current Limiter With a Resistive Load

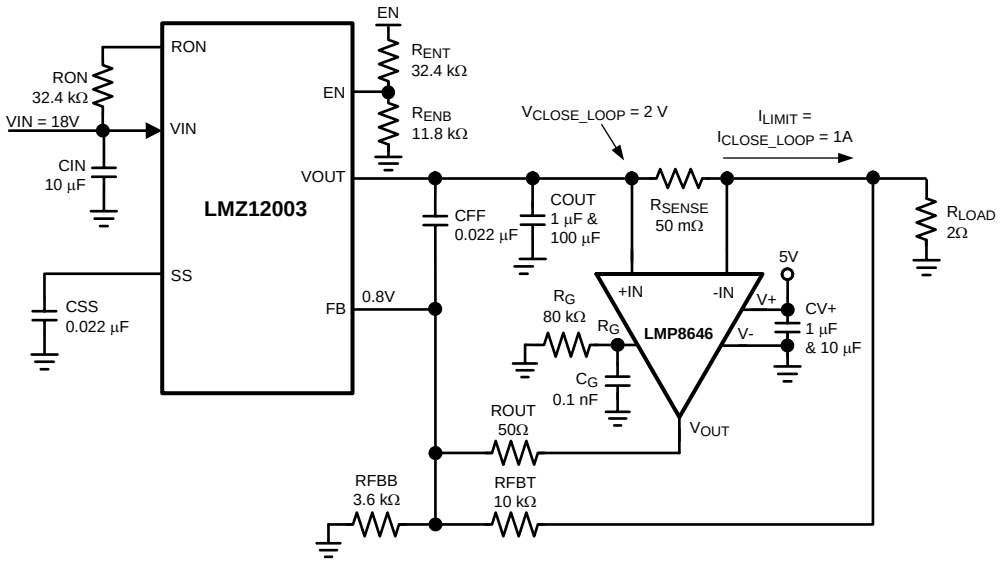


Figure 30. Resistive Load Application With LMZ12003 Regulator

Typical Applications (continued)

8.2.2.1 Design Requirements

This subsection describes the design process for a resistive load application with the LMZ12003 voltage regulator as seen in Figure 30. To see the current limiting capability of the LMP8646, the open-loop current must be greater than the close-loop current. An open-loop occurs when the LMP8646 output is not connected the LMZ12003's feedback pin. For this example, we will let the open-loop current to be 1.5A and the close-loop current, I_{LIMIT}, to be 1A.

8.2.2.2 Detailed Design Procedure

Step 1: Choose the components for the Regulator.

Refer to the LMZ12003 application note (AN-2031) to select the appropriate components for the LMZ12003.

Step 2: Choose the sense resistor, R_{SENSE}

R_{SENSE} sets the voltage V_{SENSE} between +IN and -IN and has the following equation:

$$R_{SENSE} = V_{OUT} / [(I_{LIMIT}) * (R_G / 5kOhm)] \quad (15)$$

In general, R_{SENSE} depends on the output voltage, limit current, and gain. Refer to section *Selection of the Sense Resistor, R_{SENSE}* to choose the appropriate R_{SENSE} value; this example uses 50 mOhm.

Step 3: Choose the gain resistor, R_G, for LMP8646

R_G is chosen from I_{LIMIT}. As stated, $V_{OUT} = (R_{SENSE} * I_{LIMIT}) * (R_G / 5kOhm)$. Since $V_{OUT} = V_{FB} = 0.8V$, $I_{LIMIT} = 1A$, and $R_{SENSE} = 50$ mOhm , R_G can be calculated as:

$$R_G = (V_{OUT} * 5\ kOhm) / (R_{SENSE} * I_{LIMIT}) \quad (16)$$

$$R_G = (0.8 * 5\ kOhm) / (50\ mOhm * 1A) = 80\ kOhm \quad (17)$$

Step 4: Choose the Bandwidth Capacitance, C_G.

The product of C_G and R_G determines the bandwidth for the LMP8646. Refer to the Typical Performance Characteristics plots to see the range for the LMP8646 bandwidth and gain. Since each application is very unique, the LMP8646 bandwidth capacitance, C_G, needs to be adjusted to fit the appropriate application.

Bench data has been collected for this resistive load application with the LMZ12003 regulator, and we found that this application works best for a bandwidth of 2 kHz to 30 kHz. Operating anything less than this recommended bandwidth might prevent the LMP8646 from quickly limiting the current. We recommend choosing a bandwidth that is in the middle of this range and using the equation: $C_G = 1/(2*pi*R_G*Bandwidth)$ to find C_G (this example uses a C_G value of 0.1nF). After this selection, capture the load current plot and adjust C_G until a desired output current plot is obtained.

Step 5: Choose the output resistor, ROUT, for the LMP8646

ROUT plays a very small role in the overall system performance for the resistive load application. ROUT was important in the supercap application because it affects the initial current error. Because current is directly proportional to voltage for a resistive load, the output current is not large at start-up. The bigger the ROUT, the longer it takes for the output voltage to reach its final value. We recommend that the value for ROUT is at least 50 Ohm, which is the chosen value for this example.

Step 6: Adjusting Components

Capture the output current and output voltage plots and adjust the components as necessary. The most common component to adjust is C_G for the bandwidth. An example of the output current and voltage plot can be seen in Figure 31.

Typical Applications (continued)

8.2.2.3 Application Curve

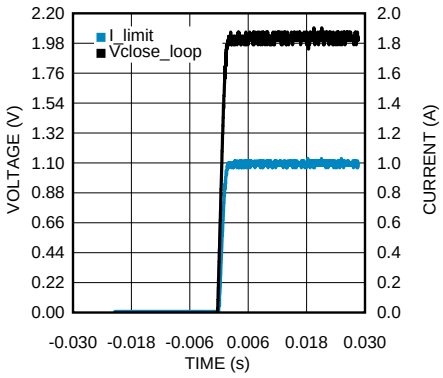


Figure 31. Plot for the Resistive Load Application With LMZ12003 Regulator Plot

8.2.3 Application #3: Current Limiter With a Low-Dropout Regulator and Resistive Load

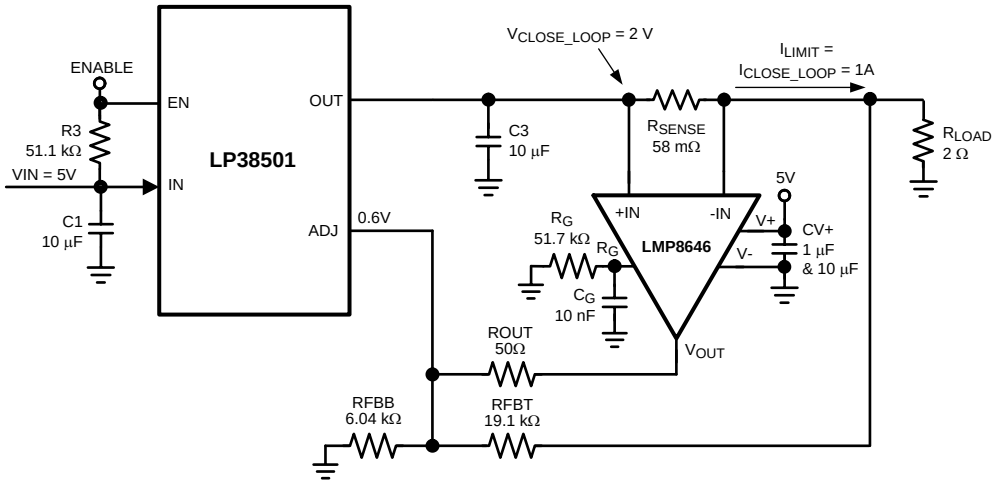


Figure 32. Resistive Load Application With LP38501 Regulator

8.2.3.1 Design Requirements

This next example is the same as the last example, except that the regulator is now a low-dropout regulator, the LP38501, as seen in Figure 32. For this example, we will let the open-loop current to be 1.25A and the close-loop current, I_{LIMIT}, to be 1A.

8.2.3.2 Detailed Design Procedure

Step 1: Choose the components for the Regulator.

Refer to the LP38501 application note (AN-1830) to select the appropriate components for the LP38501.

Step 2: Choose the sense resistor, R_{SENSE}

R_{SENSE} sets the voltage V_{SENSE} between +IN and -IN and has the following equation:

$$R_{SENSE} = V_{OUT} / [(I_{LIMIT}) * (R_G / 5kOhm)] \quad (18)$$

In general, R_{SENSE} depends on the output voltage, limit current, and gain. Refer to section *Selection of the Sense Resistor, R_{SENSE}* to choose the appropriate R_{SENSE} value; this example uses 58 mOhm.

Step 3: Choose the gain resistor, R_G, for LMP8646

Typical Applications (continued)

R_G is chosen from I_{LIMIT}. As stated, V_{OUT} = (R_{SENSE} * I_{LIMIT}) * (R_G / 5kOhm). Since V_{OUT} = ADJ = 0.6V, I_{LIMIT} = 1A, and R_{SENSE} = 58 mOhm , R_G can be calculated as:

$$R_G = (V_{OUT} * 5\ kOhm) / (R_{SENSE} * I_{LIMIT}) \quad (19)$$

$$R_G = (0.6 * 5\ kOhm) / (58\ mOhm * 1A) = 51.7\ kOhm \quad (20)$$

Step 4: Choose the Bandwidth Capacitance, C_G.

The product of C_G and R_G determines the bandwidth for the LMP8646. Refer to the Typical Performance Characteristics plots to see the range for the LMP8646 bandwidth and gain. Since each application is very unique, the LMP8646 bandwidth capacitance, C_G, needs to be adjusted to fit the appropriate application.

Bench data has been collected for this resistive load application with the LP38501 regulator, and we found that this application works best for a bandwidth of 50 Hz to 300 Hz. Operating anything larger than this recommended bandwidth might prevent the LMP8646 from quickly limiting the current. We recommend choosing a bandwidth that is in the middle of this range and using the equation: C_G = 1/(2*pi*R_G*Bandwidth) to find C_G (this example uses a C_G value of 10 nF). After this selection, capture the plot for I_{SENSE} and adjust C_G until a desired sense current plot is obtained.

Step 5: Choose the output resistor, ROUT, for the LMP8646

ROUT plays a very small role in the overall system performance for the resistive load application. ROUT was important in the supercap application because it affects the initial current error. Because current is directly proportional to voltage for a resistive load, the output current is not large at start-up. The bigger the ROUT, the longer it takes for the output voltage to reach its final value. We recommend that the value for ROUT is at least 50 Ohm, which is the value we used for this example.

Step 6: Adjusting Components

Capture the output current and output voltage plots and adjust the components as necessary. The most common component to adjust is C_G for the bandwidth. An example plot of the output current and voltage can be seen in Figure 33.

8.2.3.3 Application Curve

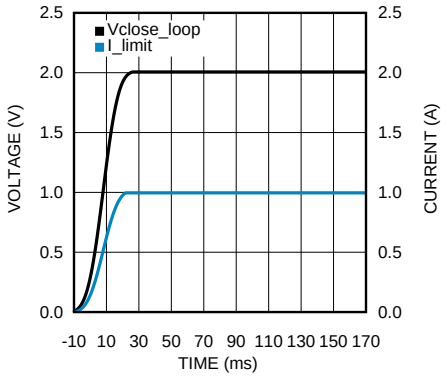


Figure 33. Plot for the Resistive Load Application With the LP38501 LDO Regulator

9 Power Supply Recommendations

Source V+ with an external voltage as recommended in the electrical characteristics table. It is recommended to place a 100nF ceramic bypass capacitor to ground as close to possible to the V+ pin. In addition, an electrolytic or tantalum capacitor of 10µF is recommended. The bulk capacitor does not need to be in close vicinity with the LMP8646 and could be close to the voltage source terminals or at the output of the voltage regulator powering the LMP8646.

10 Layout

10.1 Layout Guidelines

- In a 4-layer board design, the recommended layer stack order from top to bottom is: signal, power, ground, and signal
- Bypass capacitors should be placed in close proximity to the V+ pin
- The trace for pins +IN and -IN should be big enough to handle the current running through it.

10.2 Layout Example

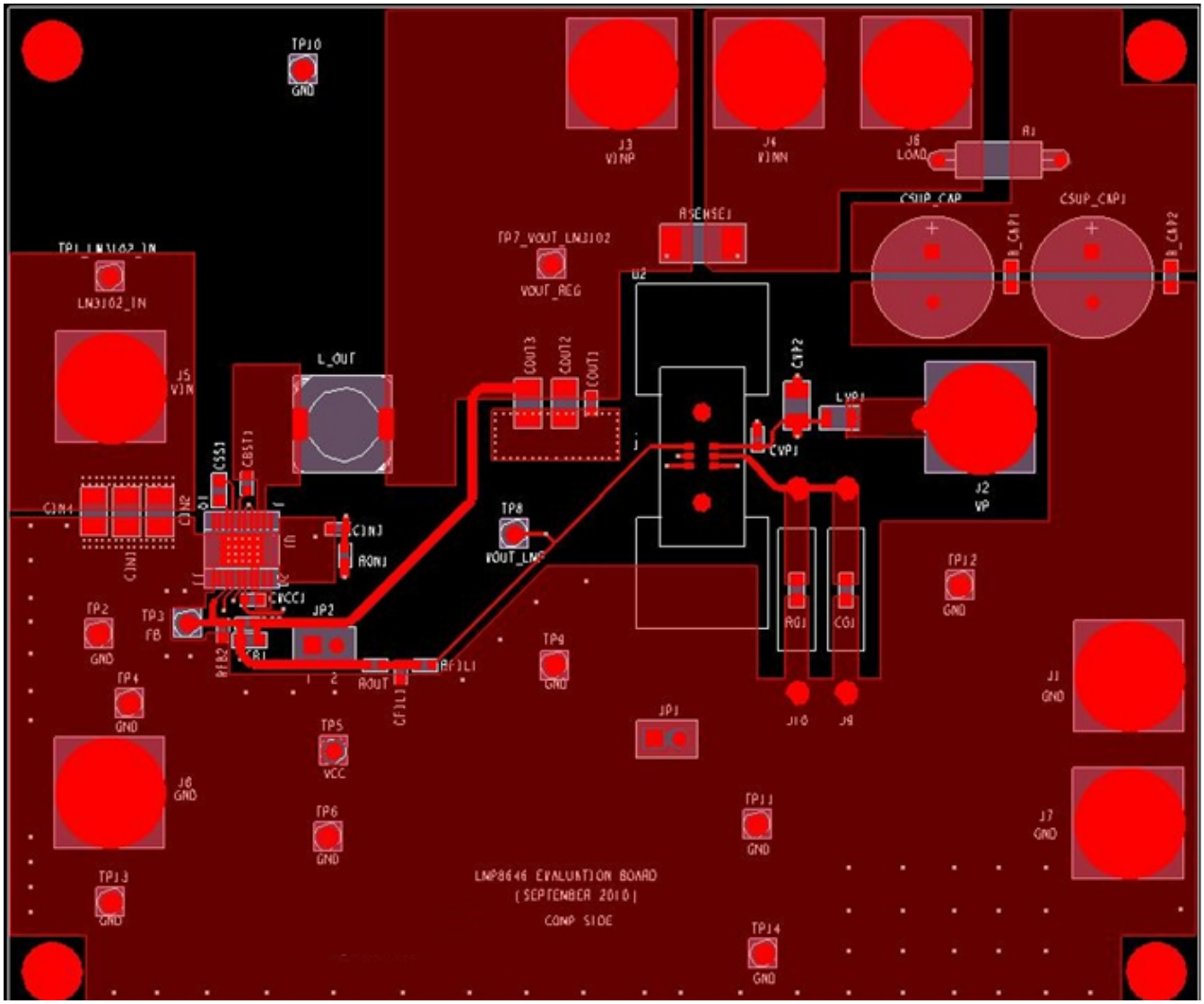


Figure 34. LMP8646 Evaluation Board Layout

11 Device and Documentation Support

11.1 Trademarks

All trademarks are the property of their respective owners.

11.2 Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.3 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LMP8646MK/NOPB	Active	Production	SOT-23-THIN (DDC) | 6	1000 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MK/NOPB.A	Active	Production	SOT-23-THIN (DDC) | 6	1000 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MK/NOPB.B	Active	Production	SOT-23-THIN (DDC) | 6	1000 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKE/NOPB	Active	Production	SOT-23-THIN (DDC) | 6	250 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKE/NOPB.A	Active	Production	SOT-23-THIN (DDC) | 6	250 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKE/NOPB.B	Active	Production	SOT-23-THIN (DDC) | 6	250 | SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/G4	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/G4.A	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/G4.B	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/NOPB	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/NOPB.A	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A
LMP8646MKX/NOPB.B	Active	Production	SOT-23-THIN (DDC) | 6	3000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	AK7A

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

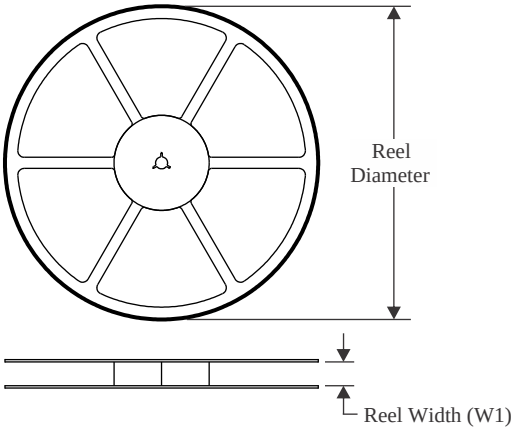
(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

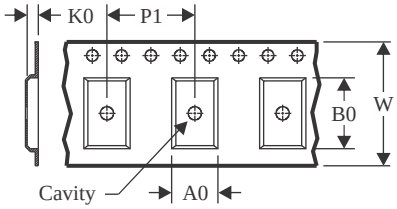
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

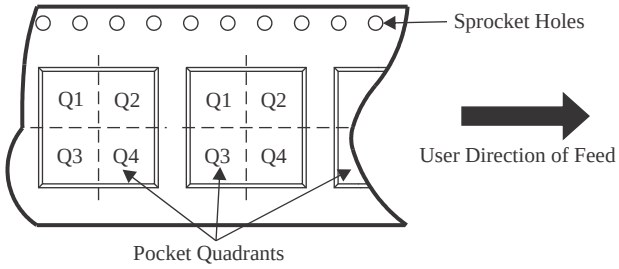


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

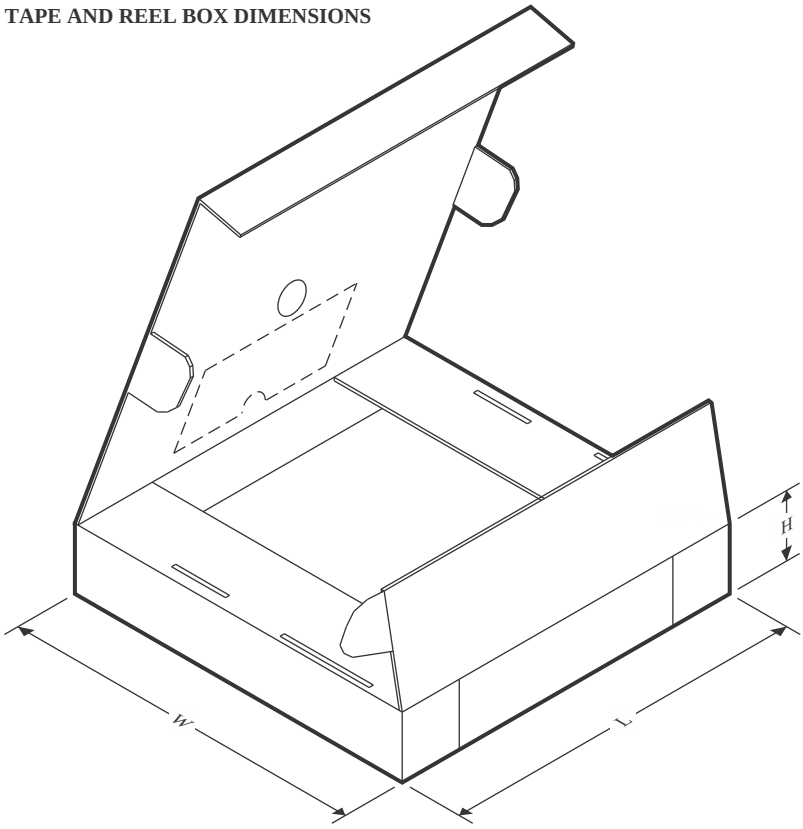
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMP8646MK/NOPB	SOT-23-THIN	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP8646MKE/NOPB	SOT-23-THIN	DDC	6	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP8646MKX/G4	SOT-23-THIN	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP8646MKX/NOPB	SOT-23-THIN	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

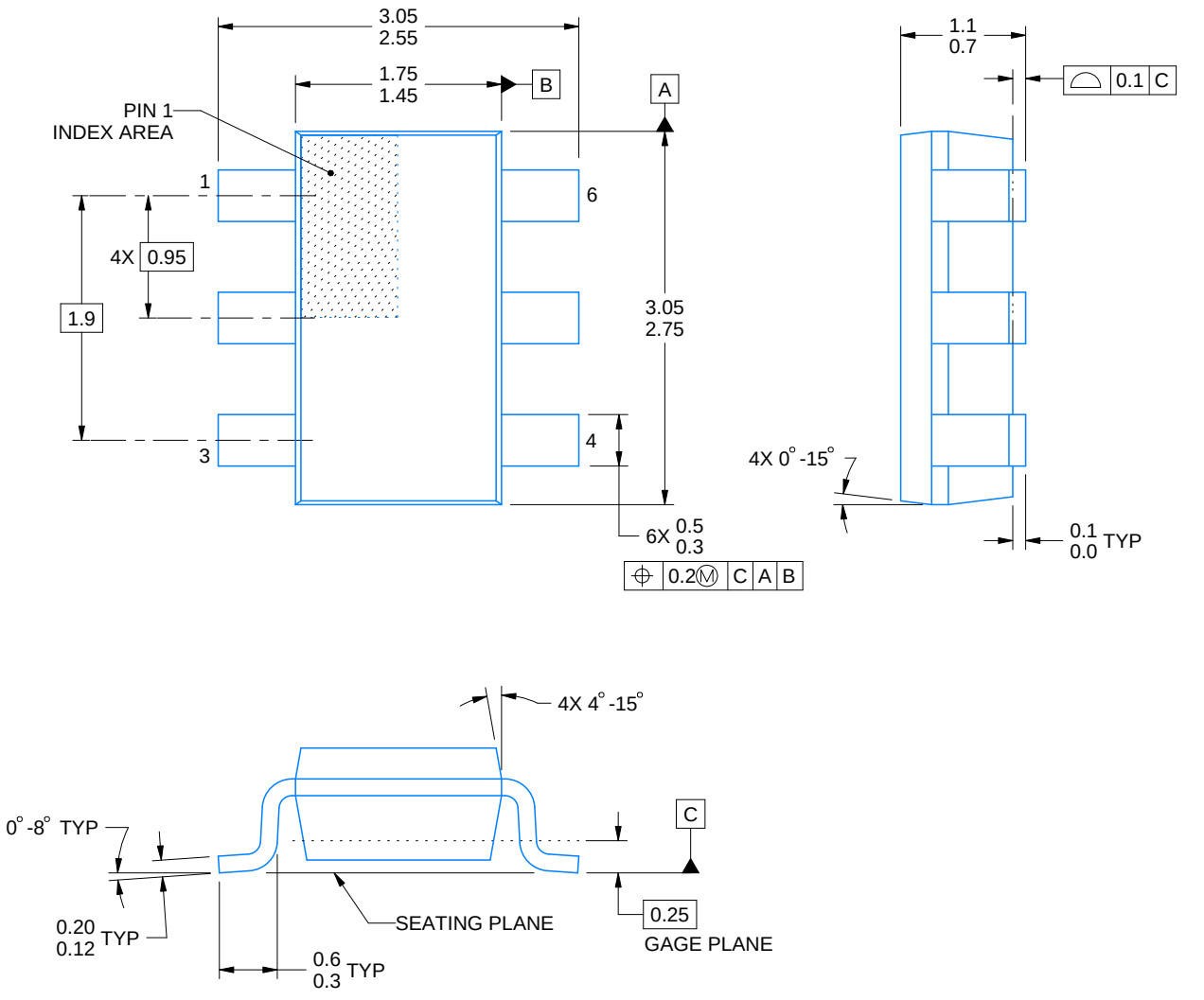
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMP8646MK/NOPB	SOT-23-THIN	DDC	6	1000	208.0	191.0	35.0
LMP8646MKE/NOPB	SOT-23-THIN	DDC	6	250	208.0	191.0	35.0
LMP8646MKX/G4	SOT-23-THIN	DDC	6	3000	208.0	191.0	35.0
LMP8646MKX/NOPB	SOT-23-THIN	DDC	6	3000	208.0	191.0	35.0

PACKAGE OUTLINE

DDC0006A

SOT-23 - 1.1 max height

SMALL OUTLINE TRANSISTOR



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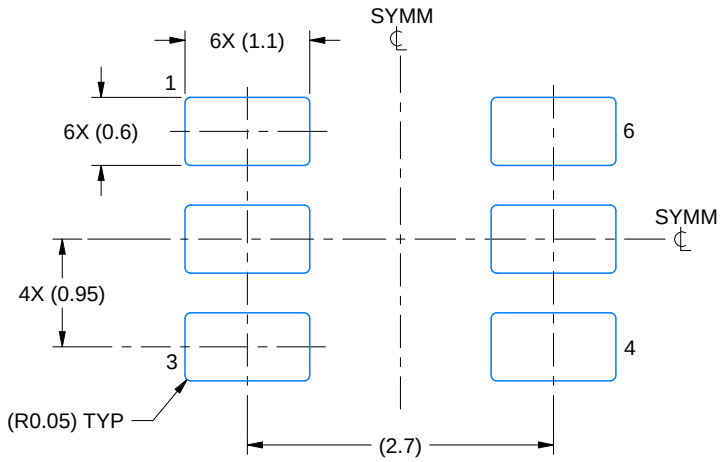
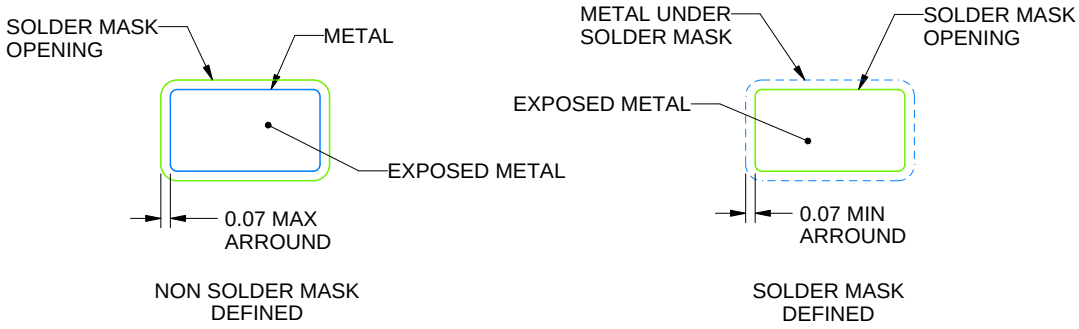
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-193.



LAND PATTERN EXAMPLE
EXPLOSED METAL SHOWN
SCALE:15X



SOLDERMASK DETAILS

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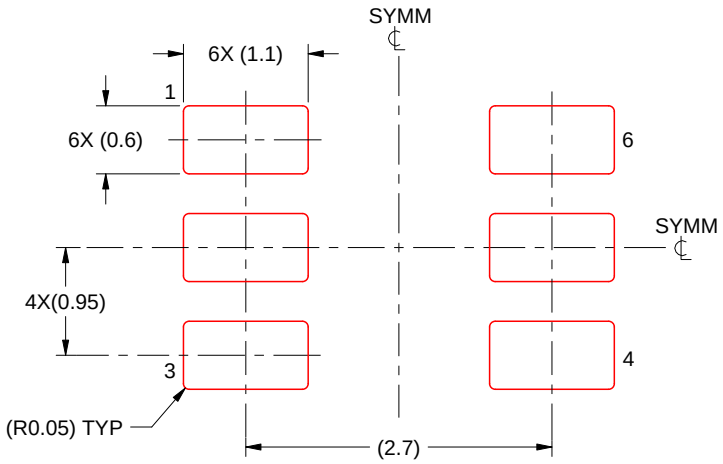
NOTES: (continued)

4. Publication IPC-7351 may have alternate designs.
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 THICK STENCIL
SCALE:15X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
7. Board assembly site may have different recommendations for stencil design.

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