

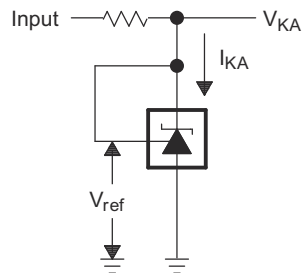
TLA431, TLA432 All-Capacitor Stable Precision Programmable Reference

1 Features

- No output capacitor required
- Stable with all capacitive loads
- Reference voltage tolerance at 25°C
 - 1% (A grade)
- Adjustable output voltage: V_{ref} to 36V
- Operation from –40°C to 125°C
- Typical temperature drift (TLA43xA)
 - 8mV (I temperature)
 - 11mV (Q temperature)
- Low output noise
- Typical output impedance: 0.2Ω
- Sink-current capability: 0.2mA to 100mA
- Pin-compatible with industry-standard TL431 and TL432
- Available in ultra-small DRL package

2 Applications

- [Rack server power](#)
- [Industrial AC/DC](#)
- [AC inverter and VF drives](#)
- [Servo drive control module](#)
- [Notebook PC power adapter design](#)



Simplified Schematic

3 Description

The TLA431 and TLA432 devices are three-terminal adjustable shunt regulators that are stable with all capacitor loads. The devices are pin compatible with the industry standard TL431 and TL432 but with improved stability to support all capacitor loads. The output cathode voltage can be set to any value between V_{ref} (2.495V) and 36V, with two external resistors. These devices have a typical output impedance of 0.2Ω. Active output circuitry provides a very sharp turn-on characteristic, making these devices excellent replacements for Zener diodes in many applications, such as onboard regulation, adjustable power supplies, and switching power supplies. The TLA431 also functions as a comparator for undervoltage monitoring. The internal amplifier and reference of the TLA431 is used as an error amplifier in isolated optocoupler flyback power supplies. The TLA432 device has exactly the same functionality and electrical specifications as the TLA431 device.

The TLA431 and TLA432 devices are specified in two temperature grades, I and Q. In addition, the devices offer good stability reference voltage over the entire temperature range.

Package Information

| PART NUMBER | PACKAGE (PIN) ⁽¹⁾ | PACKAGE SIZE ⁽²⁾ |
|-------------|------------------------------|-----------------------------|
| TLA431 | DBZ (SOT-23, 3) | 2.90mm × 1.30mm |
| TLA432 | DBZ (SOT-23, 3) | 2.90mm × 1.30mm |
| TLA431 | SOT5X3 (6) | 1.20mm × 1.60mm |

- (1) For all available packages, see the orderable addendum at the end of the data sheet.
- (2) The package size (length × width) is a nominal value and includes pins, where applicable.



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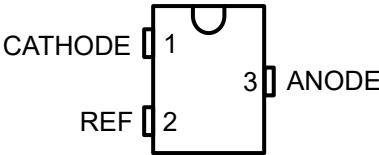
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4 Device Comparison Table

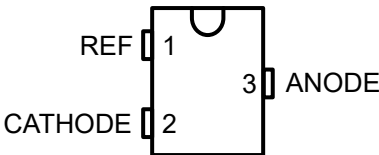
Table 4-1. Device Comparison

| DEVICE PINOUT | INITIAL ACCURACY | OPERATING FREE-AIR TEMPERATURE (T _A) |
|---------------|------------------|--|
| TLA431 | A: 1% | I: -40°C to 85°C |
| TLA432 | | Q: -40°C to 125°C |

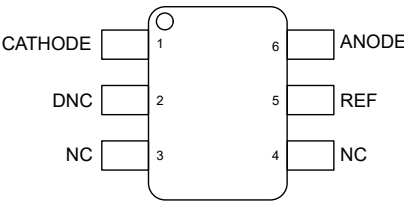
5 Pin Configuration and Functions



**Figure 5-1. DBZ Package,
3-Pin SOT-23, TLA431 (Top View)**



**Figure 5-2. DBZ Package,
3-Pin SOT-23, TLA432 (Top View)**



**Figure 5-3. DRL Package,
6-Pin SOT-563, TLA431 (Top View)**

Table 5-1. Pin Functions

| NAME | PIN | | | TYPE ⁽¹⁾ | DESCRIPTION |
|---------|--------|--------|--------|---------------------|--|
| | TLA431 | TLA432 | TLA432 | | |
| | DBZ | DRL | DBZ | | |
| ANODE | 3 | 6 | 3 | O | Common pin, normally connected to ground |
| CATHODE | 1 | 1 | 2 | I/O | Shunt Current/Voltage input |
| DNC | - | 2 | - | - | Do not connect |
| NC | - | 3, 4 | - | - | No connect |
| REF | 2 | 5 | 1 | I | Threshold relative to common anode |

(1) O = output, I = input, I/O = bidirectional

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | | MIN | MAX | UNIT |
|---------------------|--------------------------------------|--|-------|-----|------|
| V _{KA} | Cathode Voltage ⁽²⁾ | | | 37 | V |
| I _{KA} | Continuous Cathode Current Range | | –100 | 150 | mA |
| I _{I(ref)} | Reference Input Current | | –0.05 | 10 | mA |
| T _J | Operating Junction Temperature Range | | –40 | 150 | C |
| T _{stg} | Storage Temperature Range | | –65 | 150 | C |

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) All voltage values are with respect to ANODE, unless otherwise noted.

6.2 ESD Ratings

| | | | | VALUE | UNIT |
|--------------------|-------------------------|--|-------------|-------|------|
| V _(ESD) | Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 pins ⁽¹⁾ | DBZ Package | ±2000 | V |
| | | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 pins ⁽¹⁾ | DRL Package | ±1500 | V |
| | | Charged-device model (CDM), per JEDEC specification JESD22- ±1000 VC101 ⁽²⁾ | | ±1000 | |

- (1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

See ⁽¹⁾

| | | | MIN | MAX | UNIT |
|-----------------|----------------------------------|----------|------------------|-----|------|
| V _{KA} | Cathode Voltage | | V _{REF} | 36 | V |
| I _{KA} | Continuous Cathode Current Range | | 0.2 | 100 | mA |
| T _A | Operating Free-Air Temperature | TLA43xxI | –40 | 85 | C |
| | | TLA43xxQ | –40 | 125 | C |

- (1) Maximum power dissipation is a function of T_{J(max)}, θ_{JA}, and T_A. The maximum allowable power dissipation at any allowable ambient temperature is P_D = (T_{J(max)} – T_A)/θ_{JA}. Operating at the absolute maximum T_J of 150°C can affect reliability.

6.4 Thermal Information

| THERMAL METRIC ⁽¹⁾ | | TLA43x | | UNIT |
|-------------------------------|---|--------|--------|------|
| | | DBZ | DRL | |
| | | 3 PINS | 6 PINS | |
| R _{θJA} | Junction-to-ambient thermal resistance | 218.8 | 191.8 | C/W |
| R _{θJC(top)} | Junction-to-case (top) thermal resistance | 115.8 | 98.0 | C/W |
| R _{θJB} | Junction-to-board thermal resistance | 53.1 | 143.0 | C/W |
| ψ _{JT} | Junction-to-top characterization resistance | 16.6 | 8.83 | C/W |
| ψ _{JB} | Junction-to-board characterization resistance | 52.6 | 141.62 | C/W |

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics application note](#).

6.5 Electrical Characteristics

over recommended operating conditions, $T_A = 25^\circ\text{C}$ (unless otherwise noted)

| PARAMETER | TEST CIRCUIT | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|--------------------------------|--|---|----------------|---------------|
| V_{ref} | Reference Voltage | See Figure 7-1 | $V_{KA} = V_{\text{ref}}, I_{KA} = 10\text{mA}$ | TLA43xAx devices | 2470 2495 2520 | mV |
| $V_{I(\text{dev})}$ | Deviation of reference input voltage over full temperature range ⁽¹⁾ | See Figure 7-1 | $V_{KA} = V_{\text{ref}}, I_{KA} = 10\text{mA}, -40^\circ\text{C} < T_J < 85^\circ\text{C}$ | TLA43xxI devices | 8 17 | mV |
| $V_{I(\text{dev})}$ | Deviation of reference input voltage over full temperature range ⁽¹⁾ | See Figure 7-1 | $V_{KA} = V_{\text{ref}}, I_{KA} = 10\text{mA}, -0^\circ\text{C} < T_J < 90^\circ\text{C}$ | TLA43xxQ devices | 5 13 | mV |
| $V_{I(\text{dev})}$ | Deviation of reference input voltage over full temperature range ⁽¹⁾ | See Figure 7-1 | $V_{KA} = V_{\text{ref}}, I_{KA} = 10\text{mA}, -40^\circ\text{C} < T_J < 125^\circ\text{C}$ | TLA43xxQ devices | 11 20 | mV |
| $\Delta V_{\text{ref}} / \Delta V_{KA}$ | Ratio of change in reference voltage to the change in cathode voltage | See Figure 7-2 | $I_{KA} = 10\text{mA}$ | $\Delta V_{KA} = 10\text{V} - V_{\text{ref}}$ | -1.4 -2.7 | mV/V |
| | | | | $\Delta V_{KA} = 36\text{V} - 10\text{V}$ | -1 -2 | mV/V |
| I_{ref} | Reference Input Current | See Figure 7-2 | $I_{KA} = 10\text{mA}, R1 = 10\text{k}\Omega, R2 = \infty$ | | 2 4 | μA |
| $I_{I(\text{dev})}$ | Deviation of reference input current over full temperature range ⁽¹⁾ | See Figure 7-2 | $I_{KA} = 10\text{mA}, R1 = 10\text{k}\Omega, R2 = \infty$ | | 0.8 2.5 | μA |
| I_{min} | Minimum cathode current for regulation | See Figure 7-1 | $V_{KA} = V_{\text{ref}}$ | | 0.15 0.2 | mA |
| I_{off} | Off-state cathode current | See Figure 7-3 | $V_{KA} = 36\text{V}, V_{\text{ref}} = 0$ | | 0.1 0.5 | μA |
| $ Z_{KA} $ | Dynamic Impedance ⁽²⁾ | See Figure 7-1 | $V_{KA} = V_{\text{ref}}, I_{KA} = 1\text{mA to } 100\text{mA}$ | | 0.2 0.5 | Ω |

- (1) The deviation parameters $V_{I(\text{dev})}$ and $I_{I(\text{dev})}$ are defined as the differences between the maximum and minimum values obtained over the rated temperature range. For more details on $V_{I(\text{dev})}$ and how $V_{I(\text{dev})}$ relates to the average temperature coefficient, see [Parameter Measurement Information](#).
- (2) The dynamic impedance is defined by $|Z_{KA}| = \Delta V_{KA} / \Delta I_{KA}$. For more details on $|Z_{KA}|$ and how $|Z_{KA}|$ relates to V_{KA} , see [Parameter Measurement Information](#).

6.6 Typical Characteristics

Data at high and low temperatures are applicable only within the recommended operating free-air temperature ranges of the various devices.

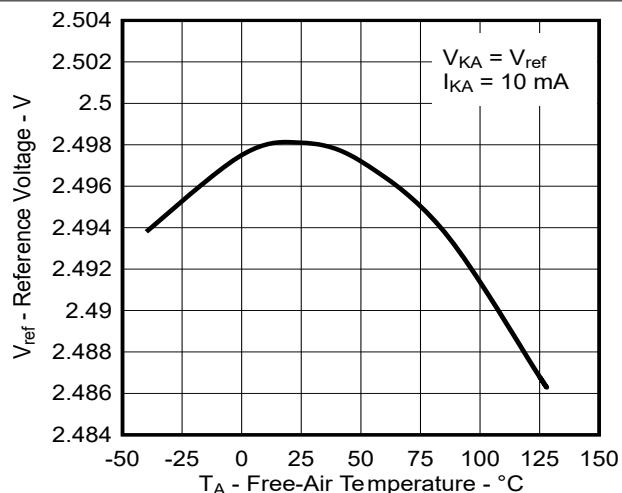


Figure 6-1. Reference Voltage vs Free-Air Temperature

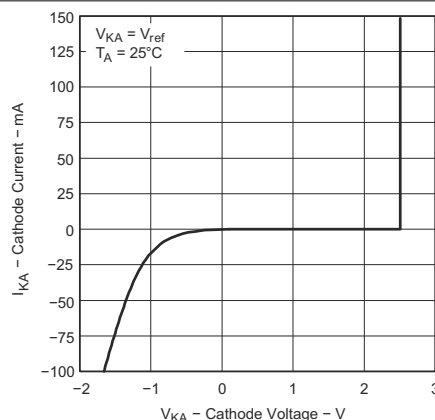


Figure 6-2. Cathode Current vs Cathode Voltage

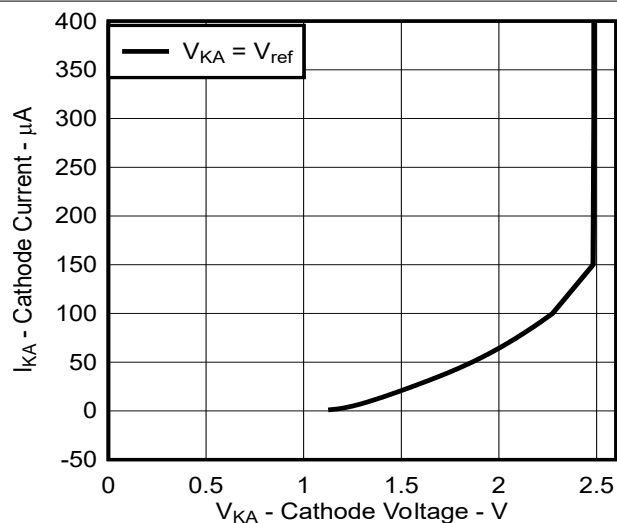


Figure 6-3. Cathode Current vs Cathode Voltage

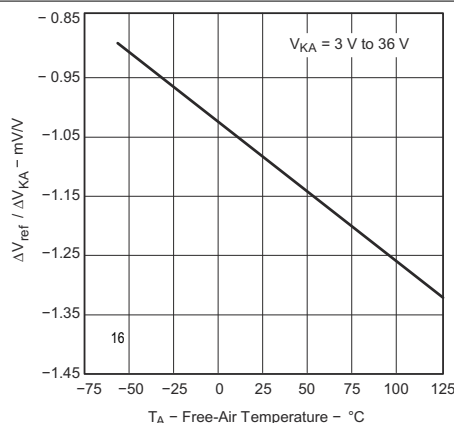


Figure 6-4. Ratio of Delta Reference Voltage to Delta Cathode Voltage vs Free-Air Temperature

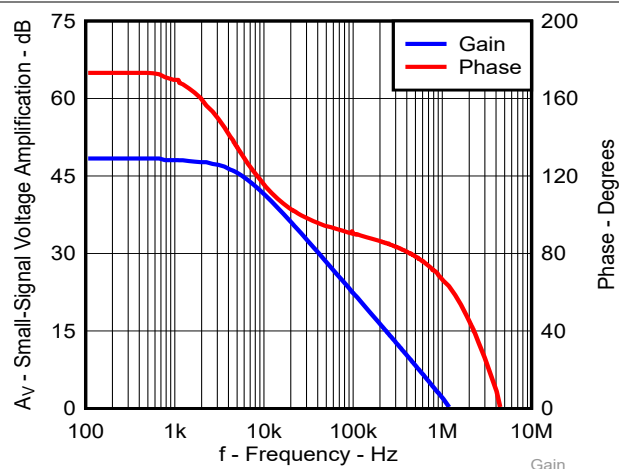


Figure 6-5. Small-Signal Voltage Amplification vs Frequency

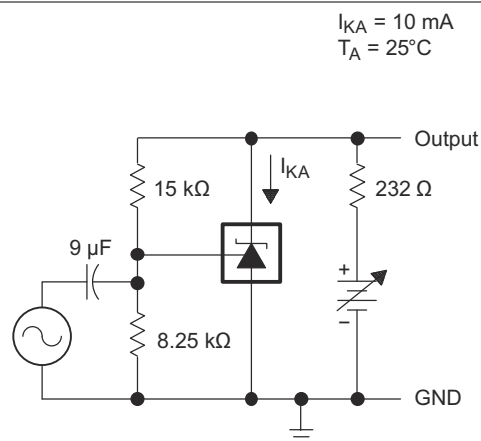


Figure 6-6. Test Circuit for Voltage Amplification

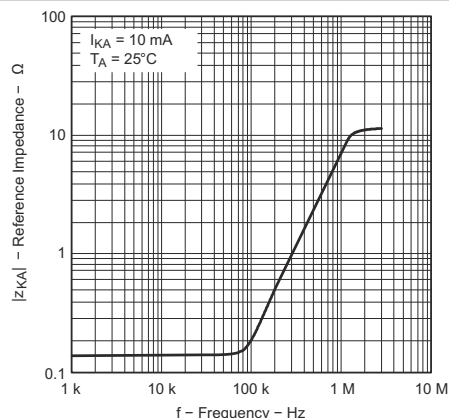


Figure 6-7. Reference Impedance vs Frequency

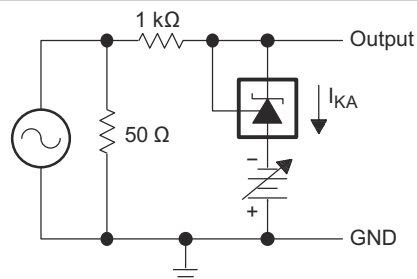


Figure 6-8. Test Circuit for Reference Impedance

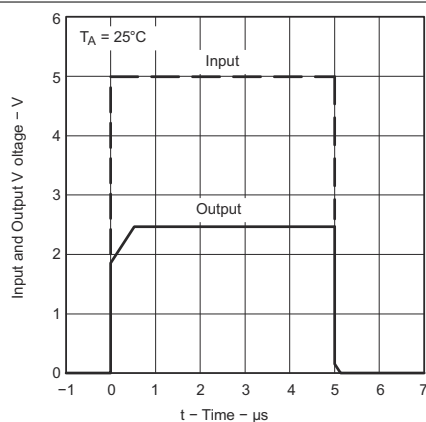


Figure 6-9. Pulse Response

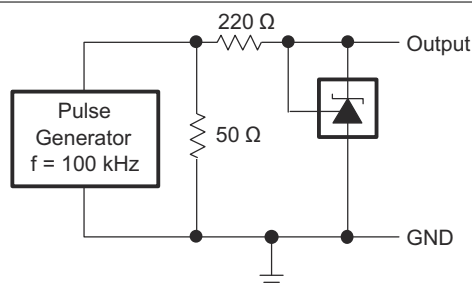


Figure 6-10. Test Circuit for Pulse Response

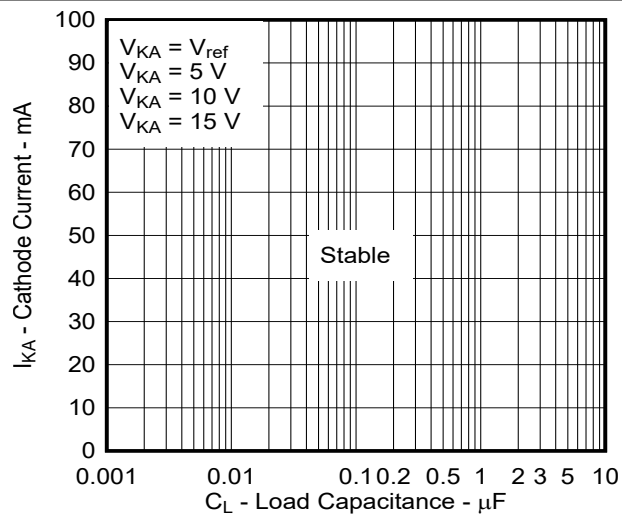
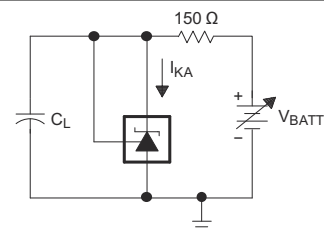
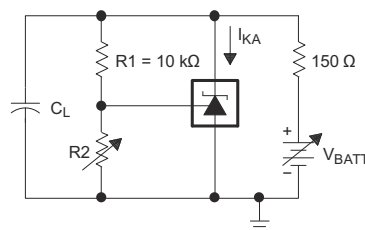


Figure 6-11. Stability Boundary Conditions



TEST CIRCUIT FOR CURVE A



TEST CIRCUIT FOR CURVES B, C, AND D

Figure 6-12. Test Circuit for Stability Boundary Conditions

7 Parameter Measurement Information

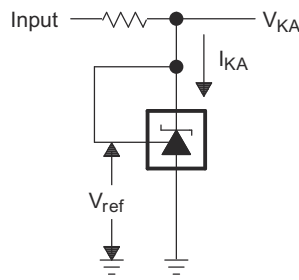


Figure 7-1. Test Circuit for $V_{KA} = V_{ref}$

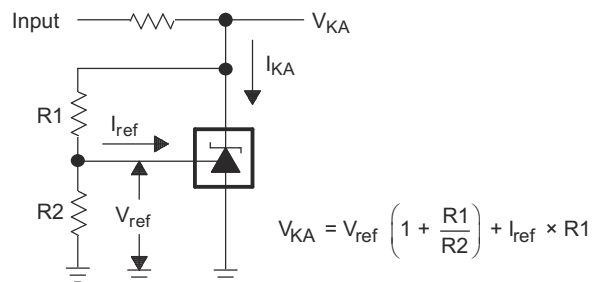


Figure 7-2. Test Circuit for $V_{KA} > V_{ref}$

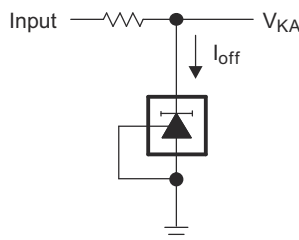


Figure 7-3. Test Circuit for I_{off}

7.1 Temperature Coefficient

The deviation of the reference voltage, V_{ref} , over the full temperature range is known as $V_{I(dev)}$. The parameter of $V_{I(dev)}$ can be used to find the temperature coefficient of the device. The average full-range temperature coefficient of the reference input voltage, $\alpha_{V_{ref}}$, is defined as:

$$|\alpha_{V_{ref}}| \left(\frac{\text{ppm}}{^{\circ}\text{C}} \right) = \frac{\left[\frac{V_{I(dev)}}{V_{ref} \text{ at } 25^{\circ}\text{C}} \right] \times 10^6}{\Delta T_A} \quad (1)$$

- ΔT_A is the rated operating temperature range of the device
- $\alpha_{V_{ref}}$ is positive or negative, depending on whether minimum V_{ref} or maximum V_{ref} , respectively, occurs at the lower temperature

$$\left| \alpha_{V_{ref}} \right| \left(\frac{\text{ppm}}{^{\circ}\text{C}} \right) = \frac{\left(\frac{V_{I(\text{dev})}}{V_{ref \text{ at } 25^{\circ}\text{C}}} \right) \times 10^6}{\Delta T_A}$$

where:

ΔT_A is the rated operating temperature range of the device.

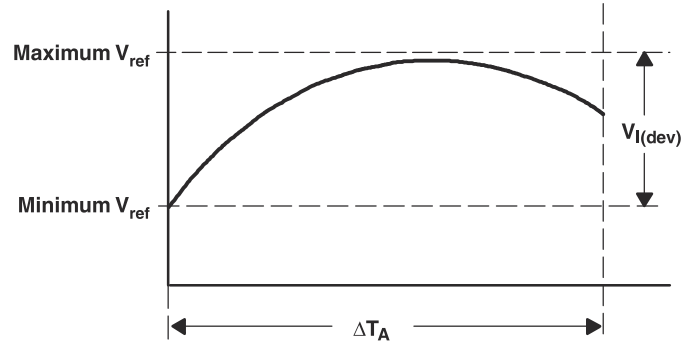


Figure 7-4. $\alpha_{V_{ref}}$ Average Temperature Coefficient

The full-range temperature coefficient is an average and therefore any subsection of the rated operating temperature range can yield a value that is greater or less than the average. For more details on temperature coefficient, refer to the [Voltage Reference Selection Basics White Paper](#).

7.2 Dynamic Impedance

The dynamic impedance is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{KA}} \quad (2)$$

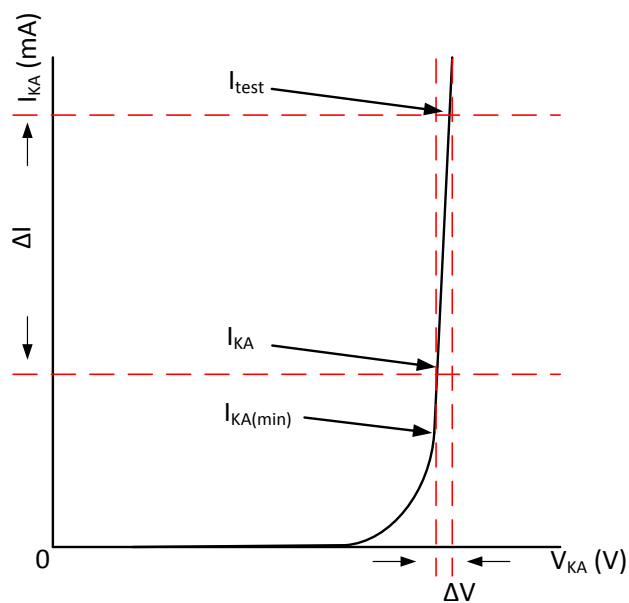
When the device operates with two external resistors (see [Figure 6-8](#)), the total dynamic impedance of the circuit is given by:

$$|z'| = \frac{\Delta V}{\Delta I} \quad (3)$$

Which is approximately equal to:

$$|Z_{KA}| \left[1 + \frac{R1}{R2} \right] \quad (4)$$

The V_{KA} of the device can be affected by the dynamic impedance. The device test current I_{test} for V_{KA} is specified in the [Section 6.5](#). Any deviation from I_{test} can cause deviation on the output V_{KA} . [Figure 7-5](#) shows the effect of the dynamic impedance on the V_{KA} .

**Figure 7-5. Dynamic Impedance**

8 Detailed Description

8.1 Overview

The TLA431 and TLA432 devices are three-terminal adjustable shunt regulators that are stable with all capacitor loads. This standard device has proven ubiquity and versatility across a wide range of applications, ranging from power to signal path. This device is pin compatible with the industry standard TL431. The TLA431 contains an accurate voltage reference & op amp, which are very fundamental analog building blocks. TLA431 has improved the stability for capacitive loads. TLA431 is used in conjunction with external components to behave as a single voltage reference, error amplifier, current sink, voltage clamp or comparator with an integrated reference.

TLA431 can be operated and adjusted to cathode voltages from 2.495V to 36V, making this part optimum for a wide range of end equipment in industrial, auto, telecom & computing. For this device to behave as a shunt regulator or error amplifier, $>0.2\text{mA}$ ($I_{\min}(\text{max})$) must be supplied in to the cathode pin. Under this condition, feedback can be applied from the Cathode and Ref pins to create a replica of the internal reference voltage.

The TLA432 device has exactly the same functionality and electrical specifications as the TLA431 device. The TLA43xAI devices are characterized for operation from -40°C to 85°C , and the TLA43xAQ devices are characterized for operation from -40°C to 125°C .

8.2 Functional Block Diagram

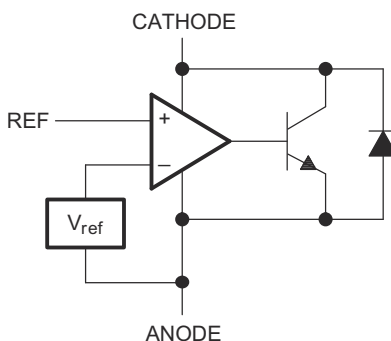


Figure 8-1. Equivalent Schematic

8.3 Feature Description

TLA431 consists of an internal reference and amplifier that outputs a sink current base on the difference between the reference pin and the virtual internal pin. The sink current is produced by the internal Darlington pair. A Darlington pair is used for this device to be able to sink a maximum current of 100mA.

When operated with enough voltage headroom ($\geq 2.495\text{V}$) and cathode current (I_{KA}), TLA431 forces the reference pin to 2.495V. However, the reference pin can not be left floating, as the reference pin needs $I_{REF} \geq 4\mu\text{A}$ (see the [Electrical Characteristics](#)). This is because the reference pin is driven into an npn, which needs base current in order operate properly.

When feedback is applied from the Cathode and Reference pins, TLA431 behaves as a Zener diode, regulating to a constant voltage dependent on current being supplied into the cathode. This is due to the internal amplifier and reference entering the proper operating regions. The same amount of current needed in the above feedback situation must be applied to this device in open loop, servo or error amplifying implementations for the TLA431 to be in the proper linear region giving the TLA431 enough gain.

TLA431 is internally compensated to be stable without an output capacitor between the cathode and anode.

8.4 Device Functional Modes

8.4.1 Closed Loop

When the cathode/output voltage or current of TLA431 is being fed back to the reference/input pin in any form, this device is operating in closed loop. The majority of applications involving TLA431 use the TLA431 in this

manner to regulate a fixed voltage or current. The feedback enables this device to behave as an error amplifier, computing a portion of the output voltage and adjusting the cathode to maintain the desired regulation. This is done by relating the output voltage back to the reference pin in a manner to make the reference pin equal to the internal reference voltage, which can be accomplished via resistive or direct feedback.

8.4.1.1 Stability (Closed Loop)

TLA431 is internally compensated to be stable without an output capacitor between the cathode and anode as shown in [Figure 8-2](#). The TLA431 is also stable across all capacitive loads from cathode to anode. This includes the popular 0.1µF capacitor load. The TLA431 has been tested to have stable operation with no capacitive loads up to capacitors larger than 10µF. See [Figure 6-11](#) for stability chart and test setup.

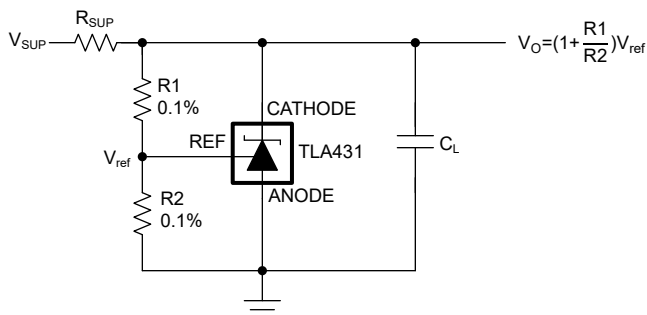


Figure 8-2. TLA431 with load capacitor

The TLA431 is sensitive to capacitance on the REF pin when the REF is isolated from cathode. For stable voltage regulation, do not add capacitance to the REF pin as shown in [Figure 8-3](#).

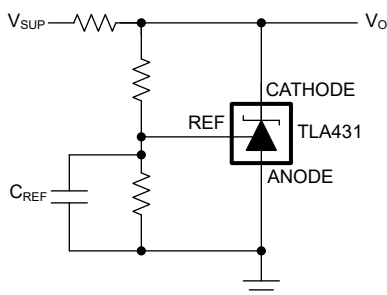


Figure 8-3. TLA431 with capacitor on REF pin

8.4.2 Open Loop (Comparator)

When the cathode or output voltage, or current of TLA431 is not being fed back to the reference/input pin in any form, this device is operating in open loop. With proper cathode current (I_{ka}) applied to this device, TLA431 has the characteristics shown in [Figure 9-4](#). With such high gain in this configuration, TLA431 is typically used as a comparator. With the reference integrated makes TLA431 the preferred choice when users are trying to monitor a certain level of a single signal.

9 Applications and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

As this device has many applications and setups, there are many situations that this data sheet can not characterize in detail.

Application note [Setting the Shunt Voltage on an Adjustable Shunt Regulator](#) (SLVA445) assists designers in setting the shunt voltage to achieve optimum accuracy for this device.

9.2 Typical Applications

9.2.1 Shunt Regulator/Reference

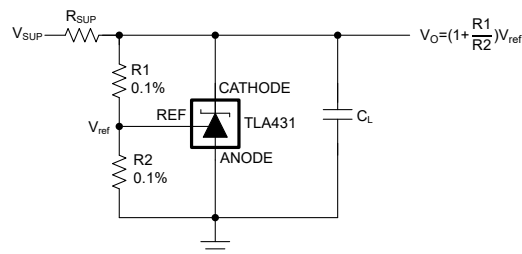


Figure 9-1. Shunt Regulator Schematic

9.2.1.1 Design Requirements

For this design example, use the parameters listed in [Table 9-2](#) as the input parameters.

Table 9-1. Design Parameters

| DESIGN PARAMETER | EXAMPLE VALUE |
|---|---------------|
| Reference Initial Accuracy | 1.0% |
| Supply Voltage | 24V |
| Cathode Current (I _k) | 5mA |
| Output Voltage Level | 2.5V - 36V |
| Load Capacitance | 0.1μF |
| Feedback Resistor Values and Accuracy (R1 & R2) | 10kΩ |

9.2.1.2 Detailed Design Procedure

When using TLA431 as a Shunt Regulator, determine the following:

- Input voltage range
- Temperature range
- Total accuracy
- Cathode current
- Reference initial accuracy
- Output capacitance

9.2.1.2.1 Programming Output/Cathode Voltage

To program the cathode voltage to a regulated voltage a resistive bridge must be shunted between the cathode and anode pins with the mid point tied to the reference pin. This can be seen in [Figure 9-1](#), with R1 and R2 being

the resistive bridge. The cathode/output voltage in the shunt regulator configuration can be approximated by the equation shown in [Figure 9-1](#). The cathode voltage can be more accurately determined by taking in to account the cathode current:

$$V_O = \left[1 + \frac{R_1}{R_2}\right] \times V_{REF} - I_{REF} \times R_1 \quad (5)$$

For this equation to be valid, TLA431 must be fully biased so that the TLA431 has enough open loop gain to mitigate any gain error. This can be done by meeting the I_{min} specification denoted in the [Electrical Characteristics](#).

9.2.1.2.2 Total Accuracy

When programming the output above unity gain ($V_{KA}=V_{REF}$), TLA431 is susceptible to other errors that can effect the overall accuracy beyond V_{REF} . These errors include:

- R_1 and R_2 accuracies
- $V_{I(dev)}$ - Change in reference voltage over temperature
- $\Delta V_{REF} / \Delta V_{KA}$ - Change in reference voltage to the change in cathode voltage
- $|z_{KA}|$ - Dynamic impedance, causing a change in cathode voltage with cathode current

Worst case cathode voltage can be determined taking all of the variables in to account. Application note [Setting the Shunt Voltage on an Adjustable Shunt Regulator](#) (SLVA445) assists designers in setting the shunt voltage to achieve optimum accuracy for this device.

9.2.1.2.3 Start-Up Time

As shown in [Figure 9-2](#), TLA431 has a fast response up to about 2V and then slowly charges to the programmed value.

9.2.1.3 Application Curve

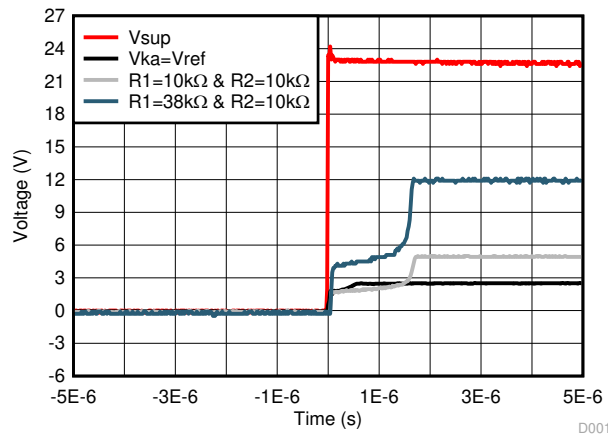


Figure 9-2. TLA431 Start-Up Response

9.2.2 Comparator With Integrated Reference

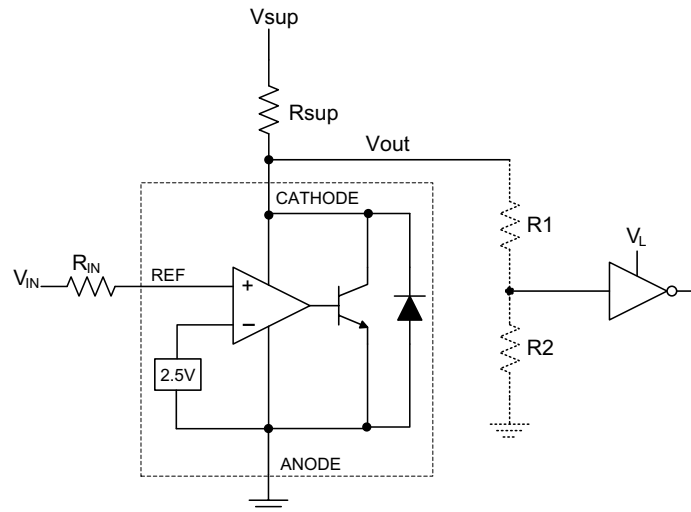


Figure 9-3. Comparator Application Schematic

9.2.2.1 Design Requirements

For this design example, use the parameters listed in [Table 9-2](#) as the input parameters.

Table 9-2. Design Parameters

| DESIGN PARAMETER | EXAMPLE VALUE |
|--|----------------|
| Input Voltage Range | 0V to 5V |
| Input Resistance | 10kΩ |
| Supply Voltage | 24V |
| Cathode Current (I_K) | 5mA |
| Output Voltage Level | $2V - V_{SUP}$ |
| Logic Input Thresholds V_{IH}/V_{IL} | V_L |

9.2.2.2 Detailed Design Procedure

When using TLA431 as a comparator with reference, determine the following:

- Input Voltage Range
- Reference Voltage Accuracy
- Output logic input high and low level thresholds
- Current Source resistance

9.2.2.2.1 Basic Operation

In the configuration shown in [Figure 9-3](#) TLA431 behaves as a comparator, comparing the V_{REF} pin voltage to the internal virtual reference voltage. When provided a proper cathode current (I_K), TLA431 has enough open loop gain to provide a quick response. This can be seen in [Figure 9-4](#), where the $R_{SUP}=10k\Omega$ ($I_{KA}=500\mu A$) situation responds much slower than $R_{SUP}=1k\Omega$ ($I_{KA}=5mA$). Operation near and below I_{min} can result in low gain, leading to a slow response.

9.2.2.2.1.1 Overdrive

Slow or inaccurate responses can also occur when the reference pin is not provided enough overdrive voltage. This is the amount of voltage that is higher than the internal virtual reference. The more overdrive voltage provided, the faster the TLA431 response.

For applications where TLA431 is being used as a comparator, good design practice is to set the trip point to greater than the positive expected error (for example, +1.0% for the A version). For fast response, setting the trip point to >10% of the internal V_{REF} can suffice.

For minimal voltage drop or difference from V_{IN} to the ref pin, use an input resistor <10k Ω to provide I_{REF} .

9.2.2.2.2 Output Voltage and Logic Input Level

For the TLA431 to properly be used as a comparator, the logic output must be readable by the receiving logic device. This is accomplished by knowing the input high and low level threshold voltage levels, typically denoted by V_{IH} and V_{IL} .

As seen in Figure 9-4, TLA431's output low level voltage in open-loop/comparator mode is approximately 2V, which is typically sufficient for 5V supplied logic. However, 5V does not work for 3.3V and 1.8V supplied logic. To accommodate this a resistive divider can be tied to the output to attenuate the output voltage to a voltage legible to the receiving low voltage logic device.

TLA431's output high voltage is equal to V_{SUP} due to TLA431 being open-collector. If V_{SUP} is much higher than the receiving logic's maximum input voltage tolerance, the output must be attenuated to accommodate the outgoing logic's reliability.

When using a resistive divider on the output, be sure to make the sum of the resistive divider (R_1 & R_2 in Figure 9-3) is much greater than R_{SUP} to not interfere with TLA431's ability to pull close to V_{SUP} when turning off.

9.2.2.2.1 Input Resistance

TLA431 requires an input resistance in this application to source the reference current (I_{REF}) needed from this device to be in the proper operating regions while turning on. The actual voltage seen at the ref pin is

$$V_{REF} = V_{IN} - I_{REF} \times R_{IN} \quad (6)$$

Since I_{REF} can be as high as 4 μ A, the recommendation is to use a resistance small enough that mitigate the error that I_{REF} creates from V_{IN} .

9.2.2.3 Application Curve

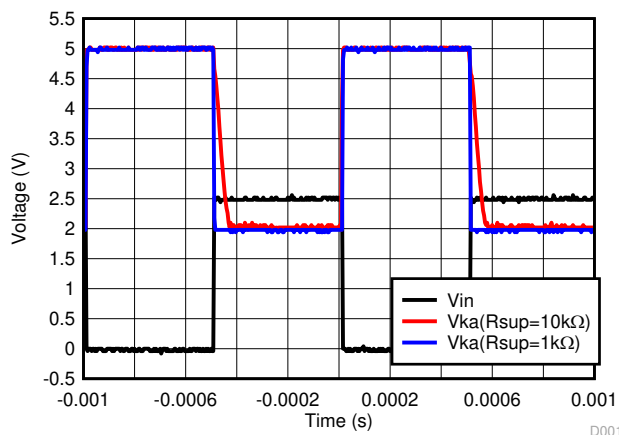
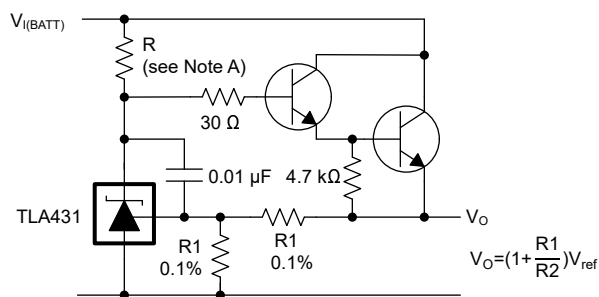


Figure 9-4. Output Response With Various Cathode Currents

9.3 System Examples



A. R is designed to provide cathode current $\geq 0.2\text{mA}$ to the TLA431 at minimum $V_{(BATT)}$.

Figure 9-5. Precision High-Current Series Regulator

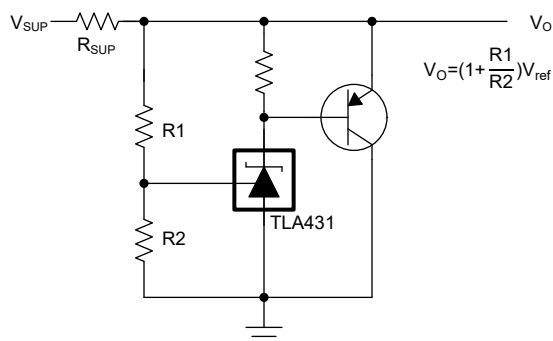
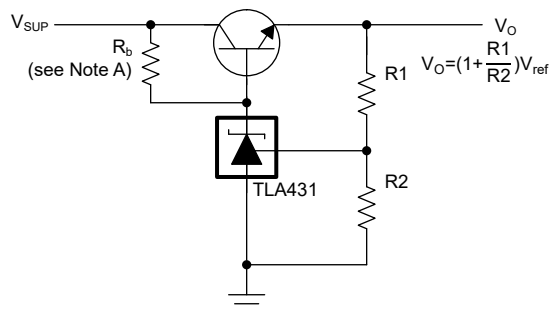
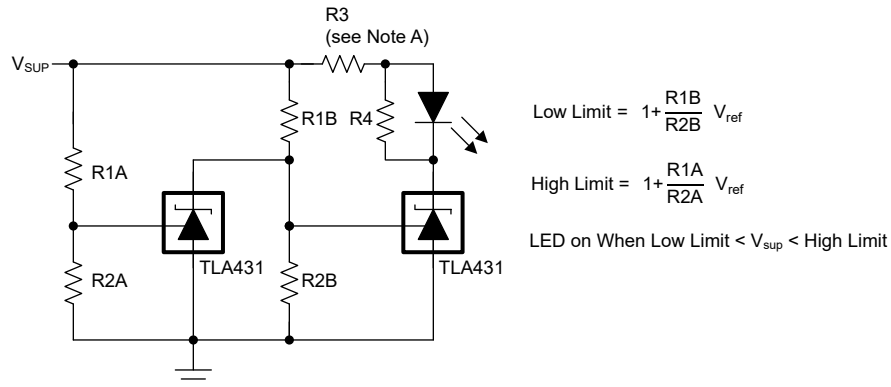


Figure 9-6. High-Current Shunt Regulator



A. R_b is designed to provide cathode current $\geq 0.2\text{mA}$ to the TLA431.

Figure 9-7. Efficient Precision Regulator



A. Select R3 and R4 to provide the desired LED intensity and cathode current $\geq 0.2\text{mA}$ to the TLA431 at the available V_{sup} .

Figure 9-8. Voltage Monitor

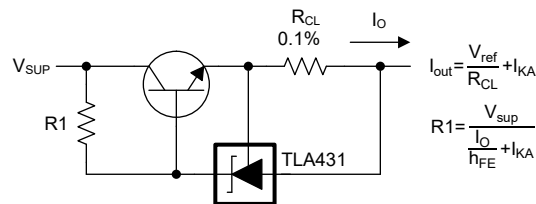


Figure 9-9. Precision Current Limiter

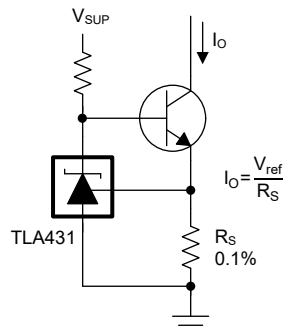


Figure 9-10. Precision Constant-Current Sink

9.4 Power Supply Recommendations

When using TLA431 as a Linear Regulator to supply a load, designers typically use a bypass capacitor on the output/cathode pin. The TLA431 is stable with all capacitive loads.

To not exceed the maximum cathode current, be sure that the supply voltage is current limited. Also, be sure to limit the current being driven into the Ref pin, as not to exceed the absolute maximum rating.

For applications shunting high currents, pay attention to the cathode and anode trace lengths, adjusting the width of the traces to have the proper current density.

9.5 Layout

9.5.1 Layout Guidelines

Bypass capacitors need to be placed as close to the part as possible to limit ESR. Current-carrying traces need to have widths appropriate for the amount of current the traces are carrying; in the case of the TLA431, the currents are be low.

9.5.2 Layout Example

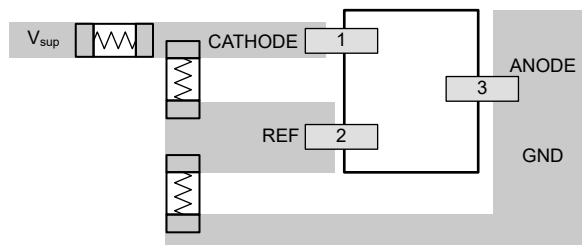


Figure 9-11. TLA431 DBZ Layout Example

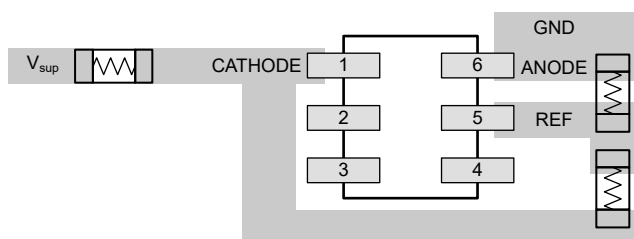
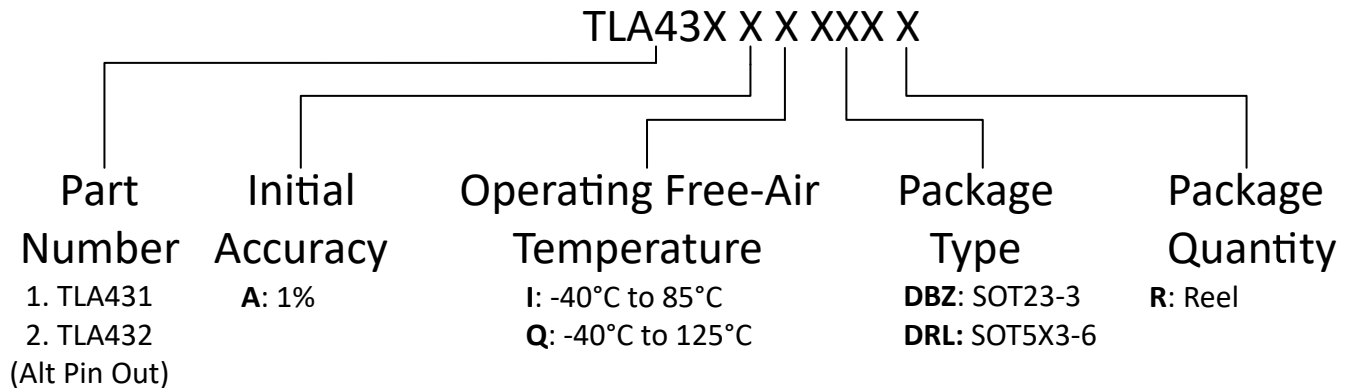


Figure 9-12. TLA431 DRL Layout Example

10 Device and Documentation Support

10.1 Device Nomenclature

TI assigns suffixes and prefixes to differentiate all the combinations of the TLA43x family. The Eco Plan designator is a legacy designator that was used to differentiate Pb-free and Green devices. More details and possible orderable combinations are located on the Package Option Addendum in [Mechanical, Packaging, and Orderable Information](#).



10.2 Documentation Support

10.2.1 Related Documentation

- Texas Instruments, [Setting the Shunt Voltage on an Adjustable Shunt Regulator application note](#)
- Texas Instruments, [Voltage reference selection basics white paper](#)

10.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](https://www.ti.com). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

10.4 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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10.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

10.7 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

11 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| Changes from Revision B (November 2025) to Revision C (December 2025) | Page |
|--|-------------|
| • Added DRL package ESD ratings..... | 5 |

| Changes from Revision A (October 2024) to Revision B (November 2025) | Page |
|---|-------------|
| • Added DRL package information..... | 1 |
| • Removed PREVIEW for DRL throughout the document..... | 1 |
| • Added DRL layout example..... | 21 |

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser based versions of this data sheet, refer to the left hand navigation.

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