

## 11.35-Gbps Differential Modulator Driver with Output Waveform Shaping

Check for Samples: [ONET1151M](#)

### FEATURES

- 1.5- $V_{PP}$  Single-Ended Output Voltage into a 50- $\Omega$  Load
- Programmable Input Equalizer
- Output Pre-emphasis
- Adjustable Rise and Fall Times
- Cross-Point Control
- Output Polarity Select
- 2-Wire Digital Interface
- Single 3.3-V Supply

- –40°C to 100°C Operation
- Surface Mount 3-mm x 3-mm 16-Pin RoHS Compliant QFN Package

### APPLICATIONS

- SONET OC-192/SDH STM-64 Optical Transmitters
- 10-Gigabit Ethernet Optical Transmitters
- SFP+ and XFP Transceiver Modules

### DESCRIPTION

The ONET1151M is a high-speed, 3.3-V modulator driver designed to modulate a differentially driven Mach Zehnder Modulator at data rates from 1 Gbps up to 11.35 Gbps.

The output amplitude can be controlled with an externally applied voltage. A 2-wire serial interface allows digital control of the equalizer, output pre-emphasis, eye crossing point, rise and fall times, and the amplitude, eliminating the need for external components. Output waveform control, in the form of pre-emphasis, cross-point adjustment and rise and fall time adjustment are available to improve the optical eye mask margin.

An optional input equalizer with 10 dB of boost at 5 GHz can be used for equalization of up to 300-mm (12 in.) of microstrip or stripline transmission line on FR4 printed circuit boards.

The modulator driver is characterized for operation from –40°C to 100°C case temperature and is available in a small footprint 3-mm x 3-mm 16-pin RoHS compliant QFN package.



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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## BLOCK DIAGRAM

Figure 1 shows a simplified block diagram of the ONET1151M. The modulator driver consists of an equalizer, a limiter, an output driver, power-on reset circuitry, a 2-wire serial interface including a control logic block, a modulation current generator, and an analog reference block.

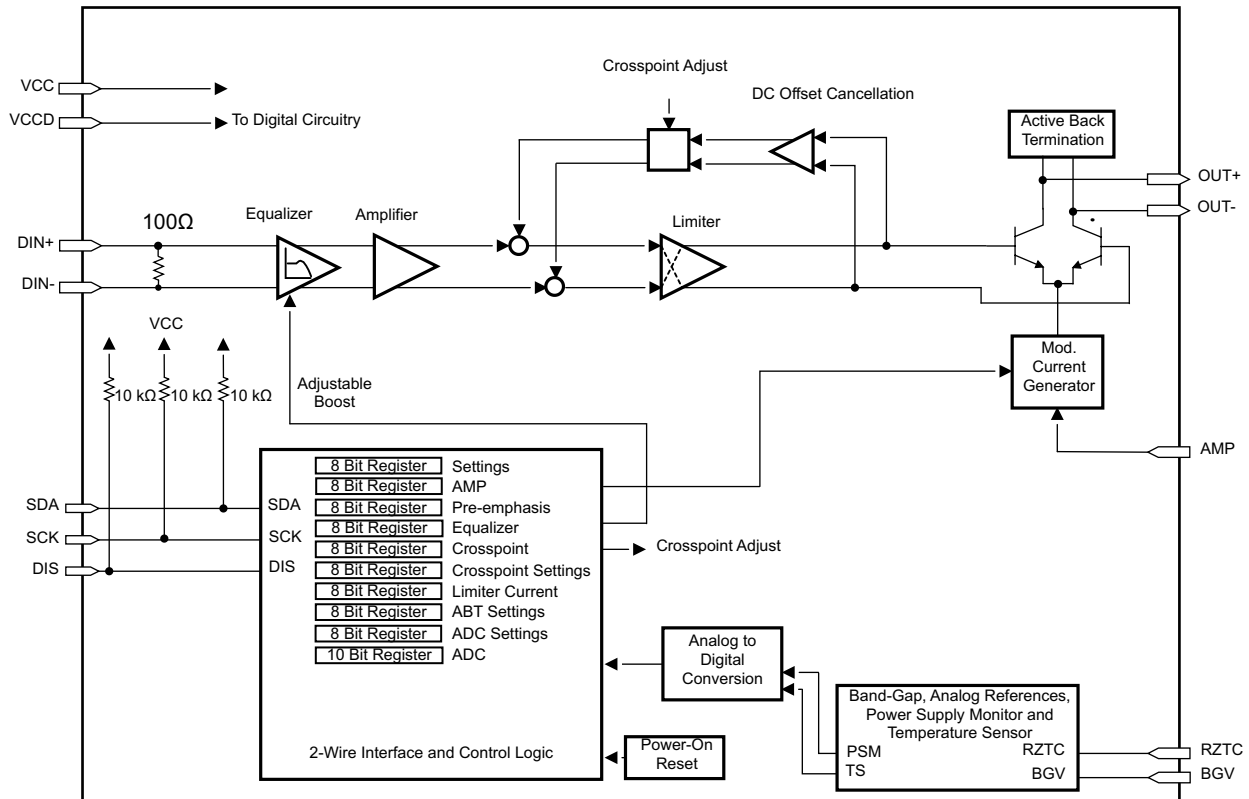
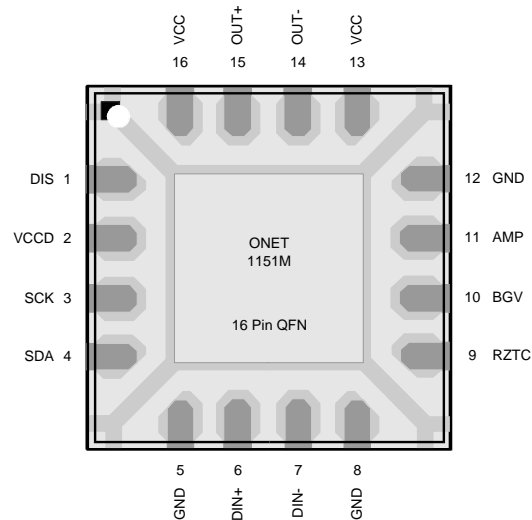


Figure 1. Simplified Block Diagram of the ONET1151M

## PACKAGE

The ONET1151M is packaged in a small footprint 3-mm × 3-mm 16-pin RoHS compliant QFN package with a lead pitch of 0.5 mm.



**Figure 2. 16-Pin QFN Package, 3-mm x 3-mm (Top View)**

**Table 1. PIN DESCRIPTIONS**

PIN		TYPE	DESCRIPTION
NAME	NO.		
DIS	1	Digital-in	Disables bias, modulation, and peaking currents when set to high state. Includes a 10-kΩ or 40-kΩ pullup resistor to VCC.
VCCD	2	Supply	3.3 V ± 10% supply voltage for the digital logic. Connect to VCC.
SCK	3	Digital-in	2-wire interface serial clock. Includes a 10-kΩ or 40-kΩ pullup resistor to VCC.
SDA	4	Digital-in/out	2-wire interface serial data input. Includes a 10-kΩ or 40-kΩ pullup resistor to VCC.
GND	5, 8, 12	Supply	Circuit ground
DIN+	6	Analog-in	Non-inverted data input. On-chip differentially 100-Ω terminated to DIN-. Must be AC coupled.
DIN-	7	Analog-in	Inverted data input. On-chip differentially 100-Ω terminated to DIN+. Must be AC coupled.
RZTC	9	Analog	Connect external zero TC 28.7-kΩ resistor to ground (GND). Used to generate a defined zero TC reference current for internal DACs.
BGV	10	Analog-out	Buffered bandgap voltage with 1.16-V output. This is a replica of the bandgap voltage at RZTC.
AMP	11	Analog-in	Output amplitude control. Output amplitude can be adjusted by applying a voltage of 0 to 2.5 V to this pin.
VCC	13, 16	Supply	3.3 V ± 10% supply voltage. Connect to VCCD.
OUT-	14	CML-out (current)	Inverted data output
OUT+	15	CML-out (current)	Non-inverted data output
EP	EP	Thermal	Exposed die pad (EP) must be grounded.

**ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>**

over operating free-air temperature range (unless otherwise noted)

PARAMETER		VALUE		UNIT
		MIN	MAX	
$V_{CC}$	Supply voltage <sup>(2)</sup>	-0.3	4	V
$V_{DIS}$ , $V_{RZTC}$ , $V_{SCK}$ , $V_{SDA}$ , $V_{BGV}$ , $V_{AMP}$ , $V_{DIN+}$ , $V_{DIN-}$ , $V_{OUT+}$ , $V_{OUT-}$	Voltage at DIS, RZTC, SCK, SDA, BGV, AMP, DIN+, DIN-, OUT+, OUT- <sup>(2)</sup>	-0.3	4	V
$I_{DIN-}$ , $I_{DIN+}$	Max. current at input pins		25	mA
$I_{MOD+}$ , $I_{MOD-}$	Max. current at output pins		35	mA
ESD	ESD rating at all pins except OUT+ and OUT-		2	kV (HBM)
	ESD rating at OUT+ and OUT-		1.5	kV (HBM)
$T_{J, max}$	Maximum junction temperature		125	°C
$T_{STG}$	Storage temperature range	-65	150	°C
$T_C$	Case temperature	-40	110	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

**RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range (unless otherwise noted)

PARAMETER		CONDITION	VALUE			UNIT
			MIN	TYP	MAX	
$V_{CC}$	Supply voltage		2.97	3.3	3.63	V
$V_{IH}$	Digital input high voltage	DIS, SCK, SDA	2			V
$V_{IL}$	Digital input low voltage	DIS, SCK, SDA			0.8	V
$R_{RZTC}$	Zero TC resistor value <sup>(1)</sup>	1.16-V bandgap bias across resistor, E96, 1% accuracy	28.4	28.7	29	kΩ
$V_{IN}$	Differential input voltage swing		150		1200	mV <sub>p-p</sub>
$V_{AMP}$	Amplitude control input voltage range		0		2.5	V
$t_{R-IN}$	Input rise time	20%–80%		30	55	ps
$t_{F-IN}$	Input fall time	20%–80%		30	55	ps
$T_C$	Temperature at thermal pad		-40		100	°C

(1) Changing the value alters the DAC ranges and the current consumption.

## DC ELECTRICAL CHARACTERISTICS

over recommended operating conditions with 50-Ω output load,  $V_{OUT+} = 1.5 V_{PP}$  and  $R_{RZTC} = 28.7 \text{ k}\Omega$ , unless otherwise noted. Typical operating condition is at 3.3 V and  $T_A = 25^\circ\text{C}$

PARAMETER	CONDITION	VALUE			UNIT
		MIN	TYP	MAX	
$V_{CC}$ Supply voltage		2.97	3.3	3.63	V
$I_{VCC}$ Supply current	$V_{CC} = 3.47 \text{ V}$ , PKENA = 1			100	mA
	$V_{CC} = 3.63 \text{ V}$ , PKENA = 1			105	
P Power Dissipation	$V_{CC} = 3.47 \text{ V}$ , PKENA = 1			347	mW
	$V_{CC} = 3.63 \text{ V}$ , PKENA = 1			381	
$R_{IN}$ Data input resistance	Differential between DIN+ / DIN-	80	100	120	$\Omega$
$I_{IH}$ High level digital input current	SCK, SDA, DIS set to $V_{CC}^{(1)}$	–10		10	$\mu\text{A}$
$I_{IL}$ Low level digital input current	SCK, SDA, DIS set to GND $^{(1)}$	–500		500	$\mu\text{A}$
$V_{CC-RST}$ $V_{CC}$ reset threshold voltage	$V_{CC}$ voltage level which triggers power-on reset	2.3	2.5	2.8	V
$V_{CC-RSTHYS}$ $V_{CC}$ reset threshold voltage hysteresis			100		mV

(1) Assured by simulation over process, supply and temperature variation

## AC ELECTRICAL CHARACTERISTICS

over recommended operating conditions with 50-Ω output load,  $V_{OUT+} = 1.5 V_{PP}$  and  $R_{RZTC} = 28.7 \text{ k}\Omega$  unless otherwise noted. Typical operating condition is at  $V_{CC} = 3.3 \text{ V}$  and  $T_A = 25^\circ\text{C}$ .

PARAMETER	CONDITION	VALUE			UNIT
		MIN	TYP	MAX	
Data rate				11.35	Gbps
SDD11 Differential input return gain	$0.01 \text{ GHz} < f < 5 \text{ GHz}$		–15		dB
	$5 \text{ GHz} < f < 11.1 \text{ GHz}$		–8		
SCD11 Differential to common mode conversion gain	$0.01 \text{ GHz} < f < 11.1 \text{ GHz}$		–15		dB
$V_{O-MIN}$ Minimum output amplitude	50-Ω load, single-ended			300	$\text{mV}_{PP}$
$V_{O-MAX}$ Maximum output amplitude	50-Ω load, single-ended, OASH0 = OASH1 = 0	1.4			$V_{PP}$
Output amplitude stability	50-Ω load, single-ended			200	mV
$t_{R-OUT}$ Output rise time	20% – 80%, $t_{R-IN} < 40 \text{ ps}$ , 50-Ω load, single-ended, cross point = 50%. $^{(1)}$		26	36	ps
$t_{F-OUT}$ Output fall time	20% – 80%, $t_{F-IN} < 40 \text{ ps}$ , 50-Ω load, single-ended, cross point = 50%. $^{(1)}$		26	36	ps
ISI Intersymbol interference $^{(2)}$	EQENA = 0, K28.5 pattern at 11.35 Gbps, 150-mV <sub>PP</sub> , 600-mV <sub>PP</sub> , 1200-mV <sub>PP</sub> differential input voltage, single-ended output. 750 mV <sub>PP</sub> ≤ $V_{OUT}$ ≤ 1.5 V <sub>PP</sub>		5	10	ps <sub>p-p</sub>
	EQENA = 1, K28.5 pattern at 11.35 Gbps with 12-inch transmission line at the input, 150-mV <sub>PP</sub> , 600-mV <sub>PP</sub> , 1200-mV <sub>PP</sub> input to transmission line, single-ended output. 750 mV <sub>PP</sub> ≤ $V_{OUT}$ ≤ 1.5 V <sub>PP</sub> .		6		
RJ Random output jitter	EQENA = 0		0.3	0.6	ps <sub>RMS</sub>
High cross point control range	50-Ω load, single-ended		75		%
Low cross point control range	50-Ω load, single-ended		25		%

(1) 1010 pattern with PKENA = 1 and PEADJ (Register 2) set to 0x0F.

(2) Jitter at the eye crossing point.

## AC ELECTRICAL CHARACTERISTICS (continued)

over recommended operating conditions with 50-Ω output load,  $V_{OUT+} = 1.5 V_{PP}$  and  $R_{RZTC} = 28.7\text{ k}\Omega$  unless otherwise noted. Typical operating condition is at  $V_{CC} = 3.3\text{ V}$  and  $T_A = 25^\circ\text{C}$ .

PARAMETER	CONDITION	VALUE			UNIT
		MIN	TYP	MAX	
Cross point stability	50-Ω load, single-ended, $V_{IN} = 180\text{ mV}_{PP}$ , 600 mV <sub>PP</sub> and 1200 mV <sub>PP</sub> , $V_{OUT} = 1.2 V_{PP}$		±5		pp
Cross point stability vs. input amplitude	50-Ω load, single-ended, $V_{IN} = 180\text{ mV}_{PP}$ , 600 mV <sub>PP</sub> and 1200 mV <sub>PP</sub> , $V_{OUT} = 1.2 V_{PP}$	–6		6	pp
BW <sub>AMP</sub> Bandwidth of AMP input			2.5		kHz
T <sub>OFF</sub> Transmitter disable time	Rising edge of DIS to $V_{OUT+} \leq 0.15 V_{PP}$ <sup>(3)</sup>		0.05	5	μs
T <sub>ON</sub> Disable negate time	Falling edge of DIS to $V_{OUT+} \geq 1.2 V_{PP}$ <sup>(3)</sup>			1	ms
T <sub>INIT1</sub> Power-on to initialize	Power-on to registers ready to be loaded <sup>(3)</sup>		1	10	ms
T <sub>INIT2</sub> Initialize to transmit	Register load STOP command to part ready to transmit valid data <sup>(3)</sup>			2	ms

(3) Assured by simulation over process, supply, and temperature variation.

## DETAILED DESCRIPTION

### EQUALIZER

The data signal is applied to an input equalizer by means of the input signal pins DIN+ / DIN–, which provide on-chip differential 100-Ω line-termination. The equalizer is enabled by setting EQENA to 1 (bit 1 of register 0). Equalization of up to 300-mm (12 in.) of microstrip or stripline transmission line on FR4 printed circuit boards can be achieved. The amount of equalization is digitally controlled by the 2-wire interface and control logic block and is dependant on the register settings EQADJ[0..7] (register 3). The equalizer can be turned off and bypassed by setting EQENA to 0. For details about the equalizer settings, see [Table 16](#).

### LIMITER

By limiting the output signal of the equalizer to a fixed value, the limiter removes any overshoot after the input equalization and provides the input signal for the output driver. Adjustments to the limiter bias current and emitter follower current can be made to trade off the rise and fall times and supply current. The limiter bias current is adjusted through LIMCSGN (bit 7 of register 6) and LIMC[0..2] (bits 4, 5 and 6 of register 6). The emitter follower current is adjusted through EFCSGN (bit 3 of register 6) and EFC[0..2] (bits 0, 1 and 2 of register 6). In addition, the slope of the emitter follower current can be modified with the EFCRNG bit (bit 3 of register 5). Setting EFCRNG to 1 results in a steeper slope.

### HIGH-SPEED OUTPUT DRIVER

The modulation current is sunk from the common emitter node of the limiting output driver differential pair by means of a modulation current generator, which is digitally controlled by the 2-wire serial interface. The collector nodes of the output stages are connected to the output pins OUT+ and OUT–. The collectors have internal active back termination. The outputs are optimized to drive a 50-Ω single-ended load and to obtain the maximum single-ended output voltage of 1.5 V<sub>PP</sub>, AC coupling and inductive pullups to VCC are required. The active back termination emitter follower current is adjusted through ABTSGN (bit 3 of register 7) and ABTEF[0..2] (bits 0, 1 and 2 of register 7). ABTUP (bit 7 of register 7) and ABTDWN (bit 6 of register 7) can control the active back termination auxiliary buffer amplitude. Setting ABTUP to 1 increases the amplitude and setting ABTDWN to 1 decreases the amplitude. For most instances, these settings may be left in the default mode.

For waveform shaping, output pre-emphasis can be enabled by setting PKENA to 1 (bit 5 of register 0) and adjusting the peaking height through PEADJ[0..3] (register 2).

In addition, the polarity of the output pins can be inverted by setting the output polarity switch bit, POL (bit 2 of register 0) to 1.

### MODULATION CURRENT GENERATOR

The modulation current generator provides the current for the current modulator described above. The modulation current generator is controlled by applying an analog voltage in the range of 0 to 2.5 V to the AMP pin, or it can be digitally controlled by the 2-wire interface block. The default method of control is through the AMP pin. To digitally control the output amplitude set AMPCTRL (bit 0 of register 0) to 1.

An 8-bit wide control bus, AMP[0..7] (register 1), can be used to set the desired modulation current, and therefore, the output voltage.

To decrease the output amplitude by approximately 18% set OARNG to 1 (bit 7 of register 5), to increase it by approximately 30 mV<sub>PP</sub> set OASH0 (bit 5 of register 5) to 1, or to increase it by approximately 60 mV<sub>PP</sub> set OASH1 (bit 6 of register 5) to 1.

The modulation current, and therefore the output signal, can be disabled by setting the DIS input pin to a high level or by setting ENA to 0 (bit 7 of register 0).

## DC OFFSET CANCELLATION AND CROSS POINT CONTROL

The ONET1151M has DC offset cancellation to compensate for internal offset voltages. The offset cancellation can be disabled and the eye crossing point adjustment enabled by setting CPENA to 1 (bit 3 of register 0). The crossing point can be moved toward the one level by setting CPSGN to 0 (bit 7 of register 4) and it can be moved toward the zero level by setting CPSGN to 1. The percentage of shift depends upon the register settings CPADJ[0..6] (register 4) and the high cross point adjustment range bits HICP[0..1] (bits 0 and 1 of register 5). Setting HICP0 and HICP1 to 1 results in the maximum adjustment range but increases the supply current.

## ANALOG REFERENCE AND TEMPERATURE SENSOR

The ONET1151M modulator driver is supplied by a single 3.3-V  $\pm$  10% supply voltage connected to the VCC and VCCD pins. This voltage is referred to ground (GND) and can be monitored as a 10-bit unsigned digital word through the 2-wire interface.

On-chip bandgap voltage circuitry generates a reference voltage, independent of the supply voltage, from which all other internally required voltages and bias currents are derived.

An external zero temperature coefficient resistor must be connected from the RZTC pin of the device to ground. This resistor is used to generate a precise, zero-TC current which is required as a reference current for the on-chip DACs.

In order to minimize the module component count, the ONET1151M provides an on-chip temperature sensor. The temperature can be monitored as a 10-bit unsigned digital word through the 2-wire interface.

## POWER-ON RESET

The ONE1151M has power on reset circuitry which ensures that all registers are reset to zero during startup. After the power-on to initialize time ( $t_{INIT1}$ ), the internal registers are ready to be loaded. The part is ready to transmit data after the initialize to transmit time ( $t_{INIT2}$ ), assuming that the chip enable bit ENA is set to 1 and the disable pin DIS is low. The DIS pin has an internal 10-k $\Omega$  pullup resistor so the pin must be pulled low to enable the outputs.

The ONET1151M can be disabled using either the ENA control register bit or the disable pin DIS. In both cases the internal registers are not reset. After the disable pin DIS is set low and/or the enable bit ENA is set back to 1, the part returns to its prior output settings.

## ANALOG TO DIGITAL CONVERTER

The ONET1151M has an internal 10-bit analog to digital converter (ADC) that converts the analog monitors for temperature and power supply voltage into a 10-bit unsigned digital word. The first eight most significant bits (MSBs) are available in register 14 and the two least significant bits (LSBs) are available in register 15. Depending on the accuracy required, eight bits or 10 bits can be read. However, due to the architecture of the 2-wire interface, in order to read the two registers, two separate read commands have to be sent.

The ADC is enabled by default. To monitor a particular parameter, select the parameter with ADCSEL (bit 0 of register 13). [Table 2](#) lists the ADCSEL bits and the monitored parameters.

**Table 2. ADC Selection Bits and the Monitored Parameter**

ADCSEL	Monitored Parameter
0	Temperature
1	Supply voltage

If it is not desired to use the ADC to monitor the two parameters then the ADC can be disabled by setting ADCDIS to 1 (bit 7 of register 13) and OSCDIS to 1 (bit 6 of register 13).

The digital word read from the ADC can be converted to its analog equivalent through the following formulas:

Temperature without a mid point calibration:

$$\text{Temperature (}^{\circ}\text{C)} = \frac{(\text{ADCx} - 264)}{6}$$

Temperature with a mid point calibration:

$$\text{Temperature (}^{\circ}\text{C)} = \frac{(T_{\text{cal}} (^{\circ}\text{C)} + 273) \times (\text{ADCx} + 1362)}{(\text{ADC}_{\text{cal}} + 1362) - 273}$$

Power supply voltage:

$$\text{Power supply voltage (V)} = \frac{2.25 \times (\text{ADCx} + 1380)}{1409}$$

## 2-WIRE INTERFACE AND CONTROL LOGIC

The ONET1151M uses a 2-wire serial interface for digital control. For example, the two circuit inputs, SDA and SCK, are respectively driven by the serial data and serial clock from a microprocessor. The SDA and SCK pins have internal 10-kΩ pullups to VCC. If a common interface is used to control multiple parts, the internal pullups can be set to 40 kΩ by setting HITERM to 1 (bit 6 of register 0). The internal pullup for the DIS pin is also set to 40 kΩ when HITERM is set to 1.

The 2-wire interface allows write access to the internal memory map to modify control registers and read access to read out the control signals. The ONET1151M is a slave device only which means that it cannot initiate a transmission itself; it always relies on the availability of the SCK signal for the duration of the transmission. The master device provides the clock signal as well as the START and STOP commands. The protocol for a data transmission is as follows:

1. START command
2. 7-bit slave address (0001000) followed by an eighth bit which is the data direction bit (R/W). A zero indicates a WRITE and a 1 indicates a READ.
3. 8-bit register address
4. 8-bit register data word
5. STOP command

Regarding timing, the ONET1151M is I<sup>2</sup>C™ compatible. The typical timing is shown in [Figure 3](#) and complete data write and read transfers are shown in [Figure 4](#). Parameters for [Figure 3](#) are defined in [Table 3](#).

**Bus Idle:** Both SDA and SCK lines remain HIGH.

**Start Data Transfer:** A START condition (S) is defined by a change in the state of the SDA line from HIGH to LOW while the SCK line is HIGH. Each data transfer is initiated with a START condition.

**Stop Data Transfer:** A STOP condition (P) is defined by a change in the state of the SDA line from LOW to HIGH while the SCK line is HIGH. Each data transfer is terminated with a STOP condition. However, if the master still wishes to communicate on the bus, it can generate a repeated START condition and address another slave without first generating a STOP condition.

**Data Transfer:** Only one data byte can be transferred between a START and a STOP condition. The receiver acknowledges the transfer of data.

**Acknowledge:** Each receiving device, when addressed, is obligated to generate an acknowledge bit. The transmitter releases the SDA line and a device that acknowledges must pull down the SDA line during the acknowledge clock pulse in such a way that the SDA line is stable LOW during the HIGH period of the acknowledge clock pulse. Setup and hold times must be taken into account. When a slave-receiver does not acknowledge the slave address, the data line must be left HIGH by the slave. The master can then generate a STOP condition to abort the transfer. If the slave-receiver does acknowledge the slave address but some time later in the transfer cannot receive any more data bytes, the master must abort the transfer. This is indicated by the slave generating the not acknowledge on the first byte to follow. The slave leaves the data line HIGH and the master generates the STOP condition.

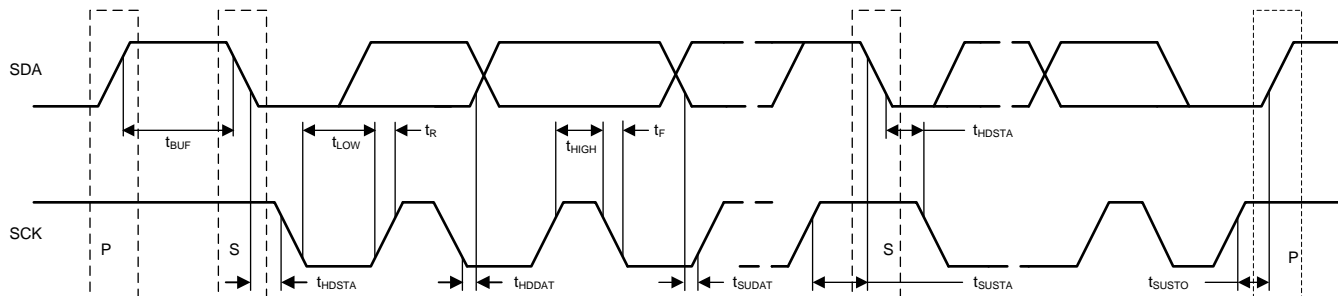
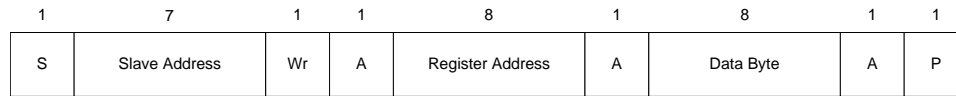
Figure 3. I<sup>2</sup>C Timing Diagram

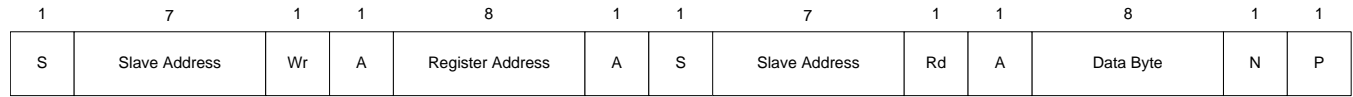
Table 3. Timing Diagram Definitions

Parameter	Symbol	Min	Max	Unit
SCK clock frequency	$f_{SCK}$		400	kHz
Bus free time between STOP and START conditions	$t_{BUF}$	1.3		$\mu s$
Hold time after repeated START condition. After this period, the first clock pulse is generated	$t_{HDSTA}$	0.6		$\mu s$
Low period of the SCK clock	$t_{LOW}$	1.3		$\mu s$
High period of the SCK clock	$t_{HIGH}$	0.6		$\mu s$
Setup time for a repeated START condition	$t_{SUSTA}$	0.6		$\mu s$
Data HOLD time	$t_{HDDAT}$	0		$\mu s$
Data setup time	$t_{SUDAT}$	100		ns
Rise time of both SDA and SCK signals	$t_R$		300	ns
Fall time of both SDA and SCK signals	$t_F$		300	ns
Setup time for STOP condition	$t_{SUSTO}$	0.6		$\mu s$

## Write Sequence



## Read Sequence



## Legend

S	Start Condition
Wr	Write Bit (bit value = 0)
Rd	Read Bit (bit value = 1)
A	Acknowledge
N	Not Acknowledge
P	Stop Condition

**Figure 4. Programming Sequence**

## REGISTER MAPPING

The register mapping for register addresses 0 (0x00) through 15 (0x0F) are listed in [Table 4](#) through [Table 15](#). [Table 16](#) describes the circuit functionality based on the register settings.

**Table 4. Register 0 (0x00) Mapping – Control Settings**

Register Address 0 (0x00)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ENA	HITERM	PKENA	PKRNG	CPENA	POL	EQENA	AMPCTRL

**Table 5. Register 1 (0x01) Mapping – Modulation Amplitude**

Register Address 1 (0x01)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
AMP7	AMP6	AMP5	AMP4	AMP3	AMP2	AMP1	AMP0

**Table 6. Register 2 (0x02) Mapping – Pre-Emphasis Adjust**

Register Address 2 (0x02)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	-	-	-	PEADJ3	PEADJ2	PEADJ1	PEADJ0

**Table 7. Register 3 (0x03) Mapping – Equalizer Adjust**

Register Address 3 (0x03)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
EQADJ7	EQADJ6	EQADJ5	EQADJ4	EQADJ3	EQADJ2	EQADJ1	EQADJ0

**Table 8. Register 4 (0x04) Mapping – Cross Point Adjust**

Register Address 4 (0x04)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CPSGN	CPADJ6	CPADJ5	CPADJ4	CPADJ3	CPADJ2	CPADJ1	CPADJ0

**Table 9. Register 5 (0x05) Mapping – CPA Settings**

Register Address 5 (0x05)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
OARNG	OASH1	OASH0	-	EFCRNG	-	HICP1	HICP0

**Table 10. Register 6 (0x06) Mapping – Limiter Bias Current Adjust**

Register Address 6 (0x06)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
LIMCSGN	LIMC2	LIMC1	LIMC0	EFCSGN	EFC2	EFC1	EFC0

**Table 11. Register 7 (0x07) Mapping – ABT – Emitter Follower Control**

Register Address 7 (0x07)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ABTUP	ABTDWN	-	-	ABTSGN	ABTEF2	ABTEF1	ABTEF0

**Table 12. Register 8 (0x08) – Register 12 (0x0C) Mapping – Not Used**

Register Address 8 (0x08)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	-	-	-	-	-	-	-

**Table 13. Register 13 (0x0D) Mapping – ADC Settings**

Register Address 13 (0x0D)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADCDIS	OSCDIS	-	-	-	-	-	ADCSEL

**Table 14. Register 14 (0x0E) Mapping – ADC Output (Read Only)**

Register Address 14 (0x0E)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADC9	ADC8	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2

**Table 15. Register 15 (0x0F) Mapping – ADC Output (Read Only)**

Register Address 15 (0x0F)							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	-	-	-	-	-	ADC1	ADC0

**Table 16. Register Functionality**

Register	Bit	Symbol	Function
0	7	ENA	Enable chip bit: 1 = Chip enabled 0 = Chip disabled
	6	HITERM	SCK, SDA and DIS pin input termination select bit: 1 = 40 kΩ selected 0 = 10 kΩ selected
	5	PKENA	Output pre-emphasis enable bit: 1 = Pre-emphasis enabled (height controlled by register 2) 0 = Pre-emphasis disabled
	4	PKRNG	Output pre-emphasis range bit: 1 = High range enabled 0 = Default range
	3	CPENA	Cross point adjust enable bit: 1 = Cross point adjustment is enabled 0 = DC offset cancellation is enabled
	2	POL	Output polarity switch bit: 1: Pin 15 = OUT- and pin 14 = OUT+ 0: Pin 15 = OUT+ and pin 14 = OUT-
	1	EQENA	Input equalizer enable bit: 1 = Equalizer enabled (boost controlled by register 3) 0 = Equalizer disabled
	0	AMPCTRL	Amplitude control selection bit: 1 = Amplitude control through the serial interface 0 = Amplitude control by an analog voltage input at AMP pin
1	7	AMP7	Output amplitude setting  Output voltage: 300 mV <sub>PP</sub> to 1.5 V <sub>PP</sub> in 256 steps
	6	AMP6	
	5	AMP5	
	4	AMP4	
	3	AMP3	
	2	AMP2	
	1	AMP1	
	0	AMP0	
2	7	-	
	6	-	
	5	-	
	4	-	
	3	PEADJ3	Pre-emphasis adjustment
	2	PEADJ2	0 = no pre-emphasis
	1	PEADJ1	> 0 = pre-emphasis added to output signal
	0	PEADJ0	
3	7	EQADJ7	Equalizer adjustment setting  Maximum equalization for 00000000 Minimum equalization for 11111111
	6	EQADJ6	
	5	EQADJ5	
	4	EQADJ4	
	3	EQADJ3	
	2	EQADJ2	
	1	EQADJ1	
	0	EQADJ0	

**Table 16. Register Functionality (continued)**

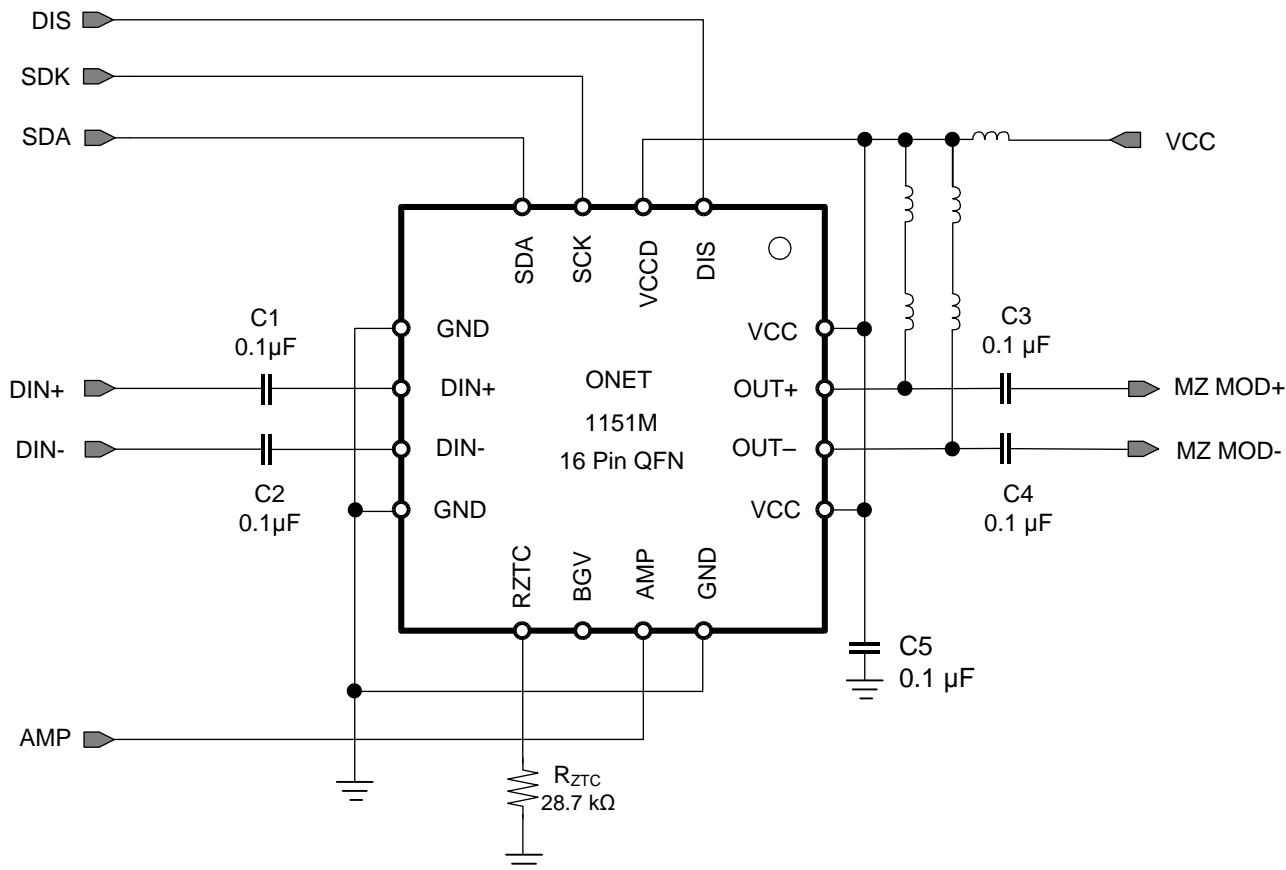
Register	Bit	Symbol	Function
4	7	CPSGN	Eye cross-point adjustment setting
	6	CPADJ6	CPSGN = 0 (positive shift)
	5	CPADJ5	Maximum shift for 1111111
	4	CPADJ4	Minimum shift for 0000000
	3	CPADJ3	CPSGN = 1 (negative shift)
	2	CPADJ2	Maximum shift for 1111111
	1	CPADJ1	Minimum shift for 0000000
	0	CPADJ0	
5	7	OARNG	Output amplitude range bit: 1 = Decrease output amplitude by approximately 18% 0 = Default range
	6	OASH1	Upper output amplitude shift bit: 1 = Output amplitude shifted upwards by approximately 60 mV <sub>PP</sub> 0 = Default
	5	OASH0	Lower output amplitude shift bit: 1 = Output amplitude shifted upwards by approximately 30 mV <sub>PP</sub> 0 = Default
	4	-	
	3	EFCRNG	Emitter follower current slope selection: 1 = Step slope 0 = Shallow slope
	2	-	
	1 0	HICP1 HICP0	High cross point adjustment range bits: 00 = Default adjustment range 11 = Maximum increase in the adjustment range
6	7	LIMCSGN	Limiter bias current sign bit: 1 = Decrease limiter bias current 0 = Increase limiter bias current
	6 5 4	LIMC2 LIMC1 LIMC0	Limiter bias current selection bits: 000 = No change 111 = Maximum current change
	3	EFCSGN	Emitter follower current sign bit: 1 = Increase emitter follower current 0 = Decrease emitter follower current
	2 1 0	EFC2 EFC1 EFC0	Emitter follower current selection bits: 000 = No change 111 = Maximum current change
7	7	ABTUP	Active back termination auxiliary buffer amplitude control bit: 1 = Increase amplitude 0 = Default setting
	6	ABTDWN	Active back termination auxiliary buffer amplitude control bit: 1 = Decrease amplitude 0 = Default setting
	5	-	
	4	-	
	3	ABTSGN	Active back termination emitter follower current sign bit: 1 = Increase emitter follower current 0 = Decrease emitter follower current
	2 1 0	ABTEF2 ABTEF1 ABTEF0	Active back termination emitter follower current selection bits: 000 = No change 111 = Maximum current change

**Table 16. Register Functionality (continued)**

Register	Bit	Symbol	Function
13	7	ADCDIS	ADC disable bit: 1 = ADC disabled 0 = ADC enabled
	6	OSCDIS	ADC oscillator bit: 1 = Oscillator disabled 0 = Oscillator enabled
	5	-	
	4	-	
	3	-	
	2	-	
	1	-	
	0	ADCSEL	ADC input selection bits: 1 = Supply monitor 0 = Temperature sensor
14	7	ADC9 (MSB)	Digital representation of the ADC input source (read only)
	6	ADC8	
	5	ADC7	
	4	ADC6	
	3	ADC5	
	2	ADC4	
	1	ADC3	
	0	ADC2	
15	7	-	
	6	-	
	5	-	
	4	-	
	3	-	
	2	-	
	1	ADC1	Digital representation of the ADC input source (read only)
	0	ADC0 (LSB)	

## APPLICATION INFORMATION

Figure 5 shows a typical application circuit using the ONET1151M. The modulator must be AC coupled to the driver for proper operation. The output amplitude is controlled through the AMP pin and the rest of the functions are controlled through the 2-wire interface (SDA or SCK) by a microcontroller.



Pullup inductors from MOD+ and MOD- to VCC are required.

**Figure 5. Differential AC Coupled Drive**

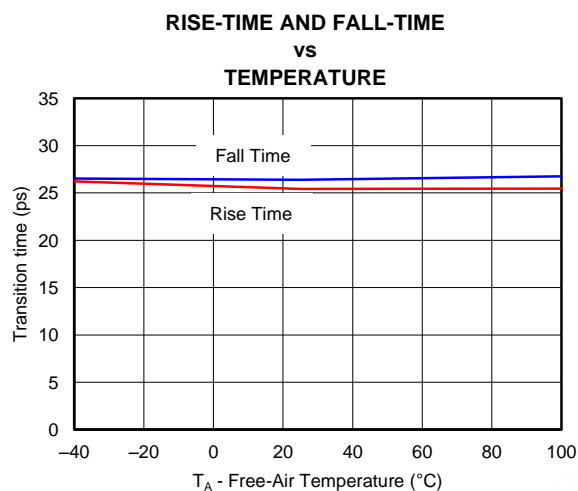
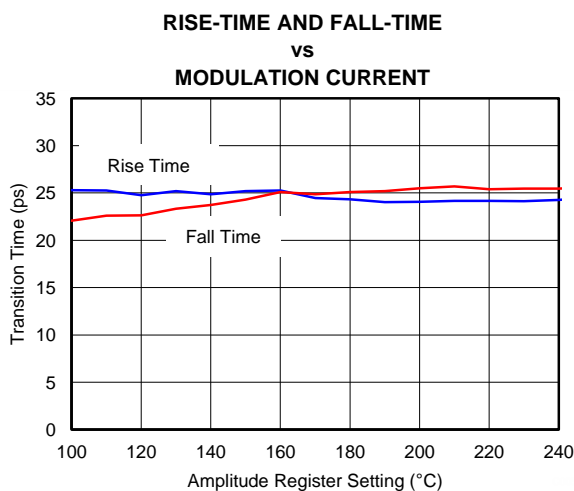
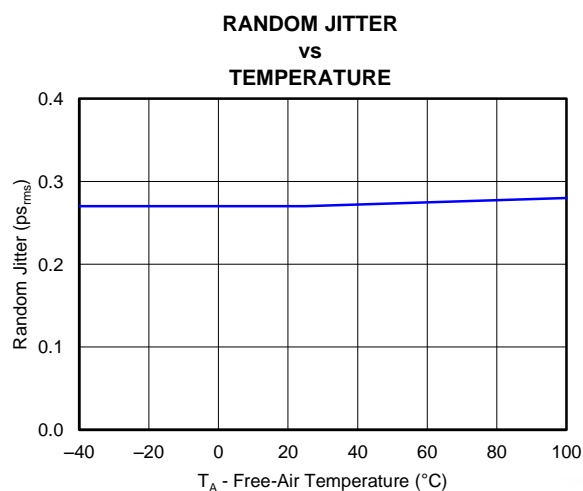
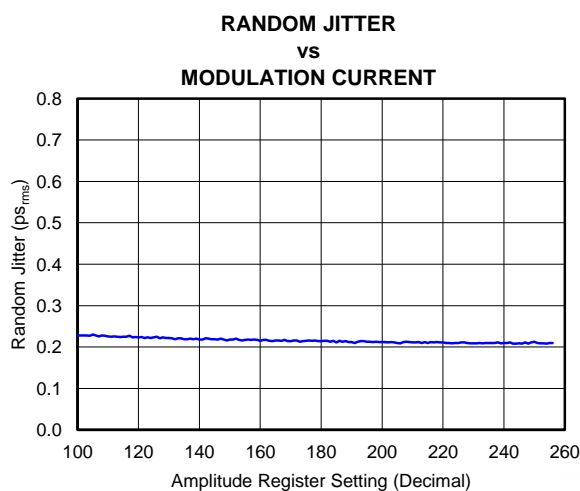
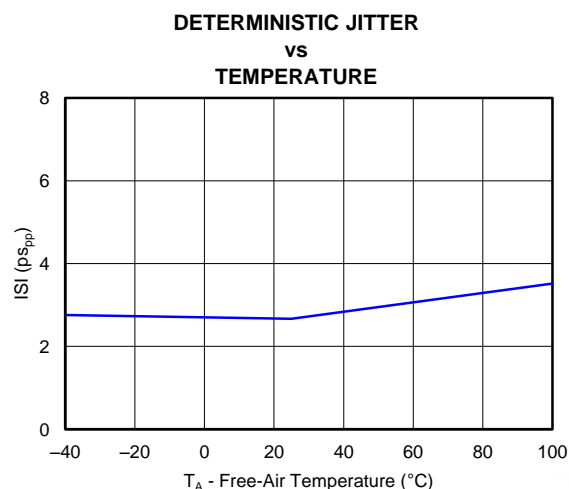
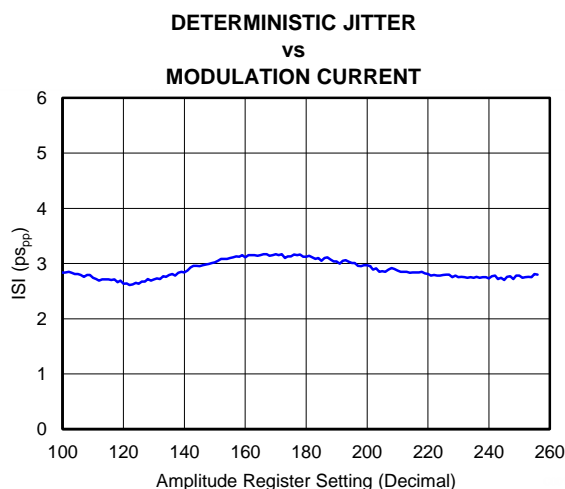
### Layout Guidelines

For optimum performance, use 50-Ω transmission lines (100-Ω differential) for connecting the signal source to the DIN+ and DIN- pins and 50-Ω transmission lines (100-Ω differential) for connecting the OUT+ and OUT- modulation current outputs to the modulator. The length of the transmission lines should be kept as short as possible to reduce loss and pattern-dependent jitter.

In addition, VCCD can be connected to VCC and filtered from a common supply.

## TYPICAL CHARACTERISTICS

Typical operating condition is at  $V_{CC} = 3.3\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $V_{OUT} = 1.5\text{ V}_{PP}$  single ended,  $EQENA = 0$ ,  $PKENA = 1$  with  $PEADJ = 0x0F$  and  $V_{IN} = 600\text{ mV}_{PP}$  (unless otherwise noted).



## TYPICAL CHARACTERISTICS (continued)

Typical operating condition is at  $V_{CC} = 3.3\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $V_{OUT} = 1.5\text{ V}_{PP}$  single ended, EQENA = 0, PKENA = 1 with PEADJ = 0x0F and  $V_{IN} = 600\text{ mV}_{PP}$  (unless otherwise noted).

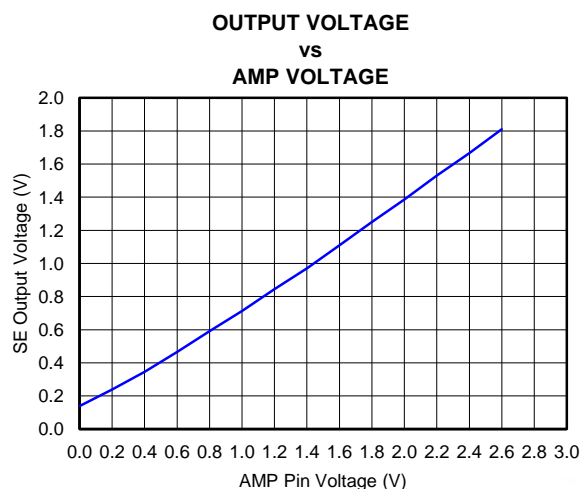


Figure 12.

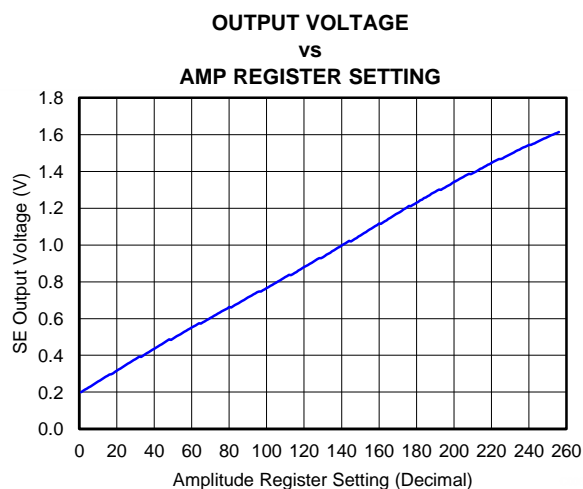


Figure 13.

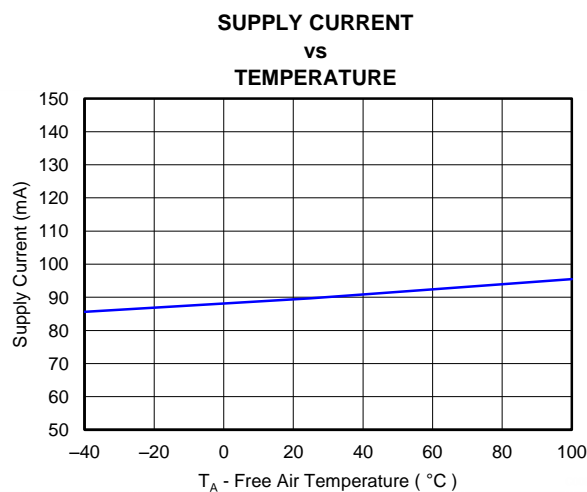


Figure 14.

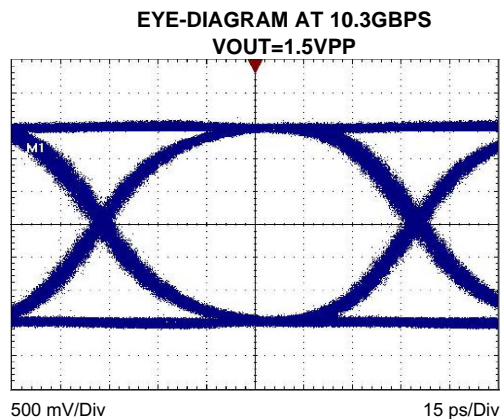


Figure 15.

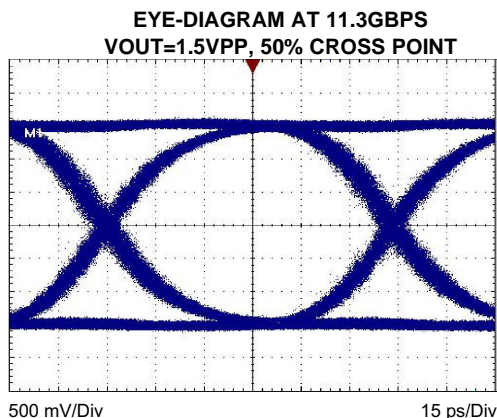


Figure 16.

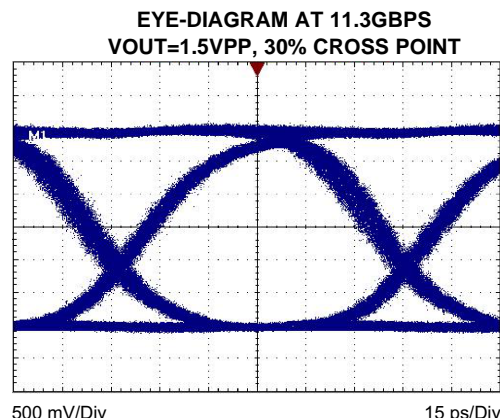


Figure 17.

### TYPICAL CHARACTERISTICS (continued)

Typical operating condition is at  $V_{CC} = 3.3\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $V_{OUT} = 1.5\text{ V}_{PP}$  single ended, EQENA = 0, PKENA = 1 with PEADJ = 0x0F and  $V_{IN} = 600\text{ mV}_{PP}$  (unless otherwise noted).

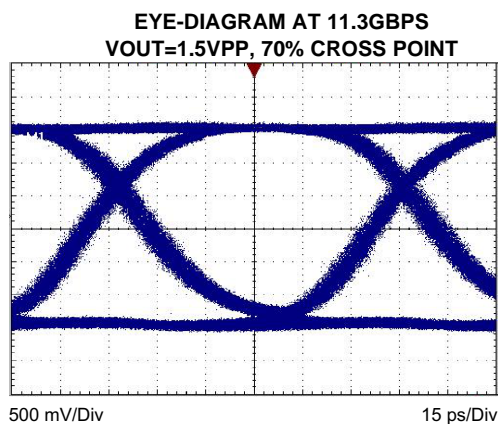


Figure 18.

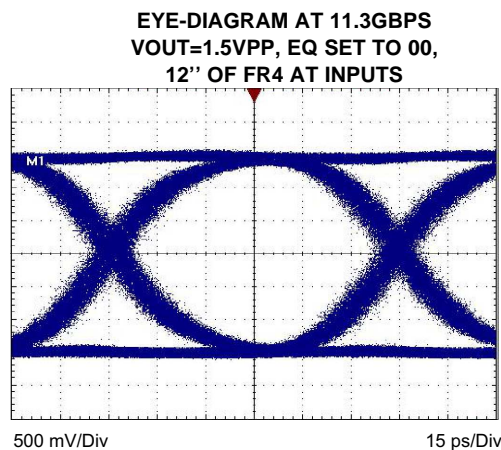


Figure 19.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">ONET1151MRGTR</a>	Obsolete	Production	VQFN (RGT)   16	-	-	Call TI	Call TI	-40 to 100	1151M
<a href="#">ONET1151MRGTT</a>	Obsolete	Production	VQFN (RGT)   16	-	-	Call TI	Call TI	-40 to 100	1151M

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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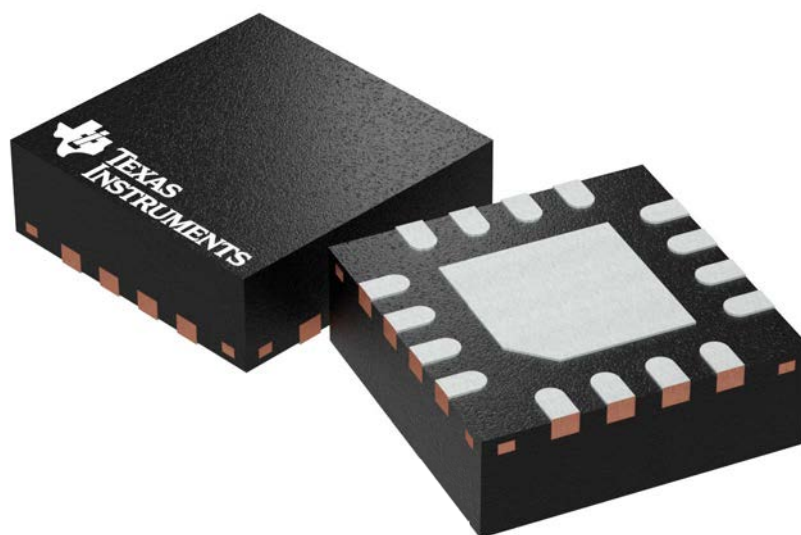
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**RGT 16**

**GENERIC PACKAGE VIEW**

**VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4203495/1

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