

# Using Read Margin Modes in TMS470 F05 Flash Microcontrollers

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## ABSTRACT

TMS470 microcontroller devices built using the F05 flash process have a built-in mechanism for detecting weak or degraded flash bits before they fail. A way of using this mechanism is discussed in this application report.

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### Contents

1	Background.....	1
2	The Read Margin Modes .....	2
3	Using the Read Margin Modes .....	2
4	Additional Flash Control Registers .....	4
5	Impact on ROM Devices.....	6
Appendix A Source Code .....		7

### List of Figures

1	Flash Module Test Control Register (FMTCR) [offset = 0x3C12h] .....	5
2	Flash Module Data Path Test Register (FMDTR) [offset = 0x0012h].....	5

### List of Tables

1	Flash Module Test Control Register (FMTCR) Field Descriptions .....	5
2	Flash Module Datapath Test Register (FMDTR) Field Descriptions .....	5

## 1 Background

TMS470 F05 flash cells are composed of transistors with an extra isolated gate: the floating gate. If this floating gate is neutrally charged, the transistor allows current flow when a preselected gate voltage is applied. This is the 1 state. If extra electrons are forced onto this floating gate, the field they create keeps the transistor turned off even with the gate voltage applied. This creates the 0 state. Imperfections in the flash cell may, over time, allow the electrons to escape from the floating gate, or allow extra electrons to be added to the floating gate, thus changing the state of the cell. Automotive safety-critical applications, such as airbag controllers and anti-lock brake systems, require a means of detecting these defective cells before they cause a system failure.

Traditional means of detecting failing nonvolatile memory locations, such as doing checksums and parallel signature analysis techniques, are inadequate alone because they require the memory location to completely fail before they are detectable. Small, almost imperceptible, differences in the timing paths between data reads and instruction fetches may allow checksum reads to pass even though instruction fetches from the same location will fail. A better mechanism for early detection of potential failing bits is required.

This application report explains a method of quickly checking the flash memory contents while minimizing the time that interrupts are disabled. A device with 512K bytes of flash in two banks, write protection keys at address 0x3FF0, and a maximum speed of 48 MHz is used in this example.

## 2 The Read Margin Modes

Control register bits in the F05 flash wrapper allow the user to select one of two modes for checking flash cells: read margin one mode or read margin zero mode. These modes effectively change the reference current used to determine if a bit is a 1 or a 0. Since the current through a flash cell is related to the voltage applied to the gate and the number of electrons on the floating gate, it is easier to refer to the state of the cell by the gate voltage that would be needed to match the standard reference current. For example, in the normal read mode, if a cell passes less than the reference current when 5.0 V are applied to the gate, the cell is a 0. If the cell passes more than the reference current when 5.0 V are applied to the gate, the cell is a 1.

In read margin zero mode, the current ratio is changed such that it is equivalent to applying 5.2 V to the gate. This voltage checks that the programmed cells have at least 200 mV of margin before the bit might flip to a 1. Normal programmed cells will have a threshold voltage ( $V_t$ ) of 6.5 V or more.

In read margin one mode, the current ratio is changed such that it is equivalent to applying 4.8 V to the gate. This voltage checks that the erased cells have at least 200 mV of margin before the bit might flip to a 0. Normal erased cells will have a  $V_t$  of 4.5 V or less.

Programmed cells have an excess of electrons. The negatively charged floating gate will leak electrons to achieve a neutral state if there are any leakage paths. This leakage is called data retention loss (DRL). Erased cells, on the other hand, have a neutrally charged floating gate. They are less likely to gain or lose electrons. However, some defects allow the floating gate to gain electrons while the read voltage is applied to the gate. Therefore, both read margin zero and read margin one tests should be run to guarantee properly functioning flash. If it is only possible to run one test, the read margin zero test is the more critical of the two, since it catches the more common failure mechanism.

Properly functioning flash cells will read properly in either read margin mode for the full lifetime guaranteed by the device specification.

## 3 Using the Read Margin Modes

There are several steps to using the read margin modes:

- Initialize the flash.
- Copy the routine to perform the read margin check into RAM.
- Execute the routine.

### 3.1 *Initializing the Flash*

Programmed bits (0s) will start to fail at low speed. Erased bits (1s) will start to fail at high speed. If enough execution time is available, it is best to do a read margin zero check at slow speed, or with extra wait states, and a read margin one check at high speed. If there is enough time available, the routine running from RAM can change the wait states from one to fifteen while the read margin zero check is being done. Often, for in-system checks, not much time is available. Then it is acceptable to do both checks, or only the read margin zero check, at the normal operating speed. In this case, the normal flash initialization is used. It consists of the following steps:

- Enter configuration mode.
- Set the flash wait states.
- Enable pipeline mode.
- Match the flash keys.
- Leave configuration mode.
- Change the PLL to increase the clock speed.

### 3.1.1 Example of Initialization Routine

Here is an example of the beginning of the initialization code. The complete source code for this example can be found in [Appendix A](#). The register addresses and macros used in this example are defined in the header file *misc.h*.

```
#include "misc.h"
const unsigned int key[]={0xffffffff,0xffffffff,0xffffffff,0xffffffff};
void c_int00()
{
    unsigned int i;
    GLBLCNTL = 0x0017;           // SYSCLK = 12MHz (12MHz in)
    FMMAC2 = 0xFFFF8 + 0;      // Select bank 0
    FMBAC2 = 0x7F11;           // 1 wait state
    FMMAC2 = 0xFFFF8 + 1;      // Select bank 1
    FMBAC2 = 0x7F11;           // 1 wait state
    FMREGOPT = 1;              // ENABLE PIPELINE MODE
    for(i=0;i<4;i++)           // Match the keys
    {
        KEY_LOCATION[i];
        FMPKEY=key[i];
    }
    GLBLCNTL = 0x0001;         // SYSCLK = 48MHz (12MHz in)
    SYSPCR = 0x07;            // ICLK = 16MHz, enable peripherals
    ...
}
```

Matching the flash keys is only required if the key locations are part of the flash memory that will be checked for margin. Matching the keys is done here in the startup code because it must be done in configuration mode.

### 3.2 Example of Main Code

The main program is responsible for copying the check routine to the RAM and executing this routine. In this example, the parallel signature analysis (PSA) calculation is broken into blocks to allow interrupts to be serviced between blocks. The `BLOCK_SIZE` parameter determines how long interrupts are disabled. Also, the block size must be chosen such that a single call to the function *ram\_psa()* does not cross a bank boundary.

```
#include "misc.h"
#define BLOCK_SIZE 0x800           //Number of words to check
static load(unsigned int *load,unsigned int *start, unsigned int size);
extern unsigned int Load_RAM_PSA, Run_RAM_PSA;
extern unsigned int Size_RAM_PSA,psa_value;
main()
{
    unsigned int size,count,bank;
    volatile unsigned int *address;
    load(&Load_RAM_PSA,&Run_RAM_PSA,(unsigned int)&Size_RAM_PSA);
    // Read Margin 0
    ENABLE_PSA;                   //Initialize PSA value to zero
    PSA=0;
    DISABLE_PSA;
    address=0;                    //start check at address zero
    count=(FLASH_SIZE-4)>>2;      //0x80000 bytes of flash (less 32-bit PSA at end)
    do
    {
        size=(count>BLOCK_SIZE) ? BLOCK_SIZE: count;
        bank=((unsigned int)address<BANK1_START) ? 0 : 1;
        address=ram_psa(address,size,bank,MARGIN0);           // execute this code in RAM
    } while (count-=size);
    if (PSA!=psa_value)
    {
        // Read margin 0 error code goes here
    }
    // Read Margin 1
    ENABLE_PSA;                   //Initialize PSA value to zero
    PSA=0;
    DISABLE_PSA;
    address=0;                    //start check at address zero
    count=(FLASH_SIZE-4)>>2;      //0x80000 bytes of flash (less 32-bit PSA at end)
    do
```

## Additional Flash Control Registers

---

```

    { size=(count>BLOCK_SIZE) ? BLOCK_SIZE: count;
      bank=((unsigned int)address<BANK1_START) ? 0 : 1;
      address=ram_psa(address,size,bank,MARGIN1);          // execute this code in RAM
    } while (count-=size);
    if (PSA!=psa_value)
    { // Read margin 1 error code goes here
    }
    // Rest of program goes here
}
static load(unsigned int *load,unsigned int *start, unsigned int size)
{ size=(size+3)>>2; //convert from bytes to words and round up
  do
  { *start++=*load++;
  } while (--size);
}

```

### 3.3 Routine Run from RAM

The code that actually calculates the PSA exists in a separate file. This separate file makes it easier to identify this routine to the linker for loading into RAM. This is the routine that is copied into RAM in main() and then executed. In this routine, interrupts are disabled by software interrupt (SWI) routines. Two special test registers are written to in configuration mode. Normally, you cannot use configuration mode at frequencies above 24 MHz. Since, in this case, flash is neither read nor written while in configuration mode, you can execute the routine from RAM and write to the flash control registers in configuration mode at the full speed of the part.

```

#include "misc.h"
volatile unsigned int *ram_psa(volatile unsigned int *address,
                               unsigned int length,
                               unsigned int bank,
                               MODE mode)
{
    INT_DISABLE();          // SWI routine
    GLBLCNTL = 0x0011;     // enter config mode
    FMMAC2 = 0xFFFF8 + bank; // Select the bank
    FMTCR=0x2FC0+mode;    // Enter read margin test mode
    FMDTR=0xB;           // TEZ low (active)
    GLBLCNTL = 0x0001;    // leave config mode
    ENABLE_PSA;
    do
    { *address++;
    } while (--length!=0);
    DISABLE_PSA;
    GLBLCNTL = 0x0011;     // enter config mode
    FMDTR=0xF;           // TEZ high (inactive)
    FMTCR=0x03C0;        // Leave read margin test mode
    GLBLCNTL = 0x0001;    // leave config mode
    INT_ENABLE();        // SWI routine
    return address;
}

```

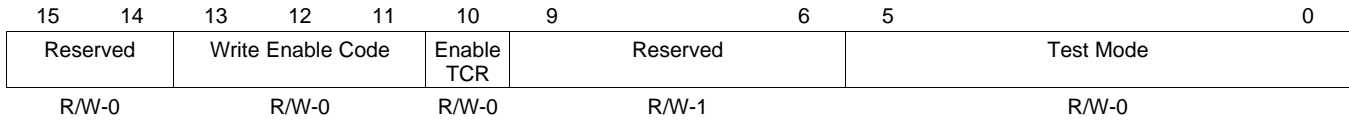
## 4 Additional Flash Control Registers

Two flash test control registers are used in this example that are not documented in the "TMS470R1x F05 Flash Reference Guide, literature number SPNU213. These are the flash module test control register (FMTCR) and the flash module data test register. These two registers implemented as 16-bit registers. They can be written in word or half word accesses only. They are described below.

#### 4.1 Flash Module Test Control Register (FMTCR)

Figure 1 and Table 1 describe this register.

**Figure 1. Flash Module Test Control Register (FMTCR) [offset = 0x3C12h]**



R = Read; W = Write; -n = value after reset

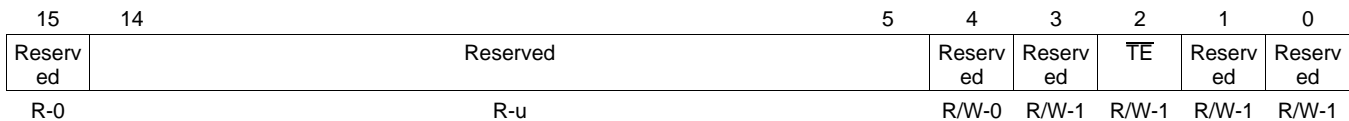
**Table 1. Flash Module Test Control Register (FMTCR) Field Descriptions**

Bit	Field	Value	Description
15–14	Reserved	00	When these bits are written, they must be written as 0.
13–11	Write Enable Code	0–111	These bits must be written as 101.
10	Enable TCR		This bit must be written as a 1 to enable flash test modes.
9–6	Reserved	1111	When these bits are written, they must be written as 1.
5–0	Test Mode	000000 010010 010011 All other values	These bits determine which test mode is entered if bit 10, Enable TCR, is set. The flash is in normal read mode. The flash is in read margin zero mode. The flash is in read margin one mode. These values are reserved and should not be used.

#### 4.2 Flash Module Data Path Test Register (FMDTR)

Figure 2 and Table 2 describe this register. There is a copy of this register for each bank in the flash module. The appropriate bank must be selected in the Module Access Control Register number 2 (FMMA2) before writing to this register.

**Figure 2. Flash Module Data Path Test Register (FMDTR) [offset = 0x0012h]**



R = Read; W = Write; -n = value after reset; -u = undefined

**Table 2. Flash Module Datapath Test Register (FMDTR) Field Descriptions**

Bit	Field	Description
15	Reserved	When this bit is written, it must be written as 0.
14–5	Reserved	Reads of these bits are undefined and writes have no effect.
4	Reserved	When this bit is written, it must be written as 0.
3	Reserved	When this bit is written, it must be written as 1.
2	$\overline{TE}$	Test enable. This bit is active low. When written as 0, the test mode defined in the TCR bits is applied. When written as 1, the test mode is disabled.
1	Reserved	When this bit is written, it must be written as 1.
0	Reserved	When this bit is written, it must be written as 1.

## **5 Impact on ROM Devices**

TMS470R1x ROM devices built using the ROM pipeline wrapper (RPW) can execute the code in this example without error. ROM memory does not have the same failure mechanism as flash memory, and the read margin modes are not supported in the ROM devices. However, writing to the locations of the flash control registers will not cause a memory exception. On ROM devices, this routine will be a PSA check of the ROM memory, but no margin is applied to the ROM. This lack of margin is acceptable since ROM memory cells, unlike flash cells, are not subject to DRL.

## Appendix A Source Code

### A.1 misc.h

```

#define PSA          (*(volatile unsigned int *)0xFFFFF40)
#define ENABLE_PSA  ((*(volatile unsigned int *)0xFFFFF50)=0)
#define DISABLE_PSA (*(volatile unsigned int *)0xFFFFF50)=1)
#define SYSPCR      (*(volatile unsigned int *)0xFFFFFD30)
#define GLBLCNTL    (*(volatile unsigned int *)0xFFFFFDC)
#define MFBHR0      (*(volatile unsigned int *)0xFFFFFE00)
#define MFBALR0     (*(volatile unsigned int *)0xFFFFFE04)
#define MFBHR2      (*(volatile unsigned int *)0xFFFFFE10)
#define MFBALR2     (*(volatile unsigned int *)0xFFFFFE14)
#define HETDIR      (*(volatile unsigned int *)0xFFFF7FC34)
#define HETDOUT     (*(volatile unsigned int *)0xFFFF7FC3C)
#define FLASH_BASE  0xFFE88000
#define FMREGOPT    (*(volatile unsigned int *)(FLASH_BASE+0x1C00))
#define FMPKEY      (*(volatile unsigned int *)(FLASH_BASE+0x1C0C))
#define FMDTR       (*(volatile unsigned int *)(FLASH_BASE+0x0010))
#define FMTCR       (*(volatile unsigned int *)(FLASH_BASE+0x3C10))
#define FMMAC2      (*(volatile unsigned int *)(FLASH_BASE+0x3C04))
#define FMBAC2      (*(volatile unsigned int *)(FLASH_BASE+0x0004))
#define KEY_LOCATION ((volatile unsigned int *)0x3ff0)
#define BANK1_START 0x40000
#define FLASH_SIZE  0x80000
void INT_ENABLE();
void INT_DISABLE();
#pragma SWI_ALIAS(INT_ENABLE, 5)
#pragma SWI_ALIAS(INT_DISABLE,6)
typedef enum { NORMAL=0, MARGIN0=18, MARGIN1=19} MODE;
volatile unsigned int *ram_psa(volatile unsigned int *address,
                               unsigned int length,
                               unsigned int bank,
                               MODE mode);

```

### A.2 intvecs.asm

```

.state32
.global _c_int00
.global _ISR_SWI
        .global _psa_value
        .global PSA

.sect ".intvecs"
b    _c_int00          ; RESET INTERRUPT
b    #-8              ; UNDEFINED INSTRUCTION INTERRUPT
b    _ISR_SWI         ; SOFTWARE INTERRUPT
b    #-8              ; ABORT (PREFETCH) INTERRUPT
b    #-8              ; ABORT (DATA) INTERRUPT
b    #-8              ; RESERVED
b    #-8              ; IRQ INTERRUPT
b    #-8              ; FIQ INTERRUPT
        .sect ".psa_value"
_psa_value
        .word PSA
.end

```

### A.3 startup.c

```

#include "misc.h"
/*-----*/
/* extern reference to cinit section */
/*-----*/
/* stack pointers (initial values) */

```

## Main.c

```

asm("          .text");
asm("          .global _StackSUPER_");
asm("s_stack:  .long  _StackSUPER_");
const unsigned int key[]={0xffffffff,0xffffffff,0xffffffff,0xffffffff};
/* the name c_int00 has a special meaning for the TMS470 compiler          */
/* DONT CHANGE IT!                                                         */
void c_int00()
{  unsigned int i;
   /* --- SYSTEM MODULE SETUP ----- */
   /* setup system registers SAR module                                     */
   GLBLCNTL = 0x0017;              // SYSCLK = 12MHz (12MHz in)
   FMMAC2 = 0xFFF8 + 0;           // Select bank 0
   FMBAC2 = 0x7F11;              // 1 wait state
   FMMAC2 = 0xFFF8 + 1;          // Select bank 1
   FMBAC2 = 0x7F11;              // 1 wait state
   FMREGOPT = 1;                  // ENABLE PIPELINE MODE
   for(i=0;i<4;i++)              // Match the keys
   {  KEY_LOCATION[i];
      FMPKEY=key[i];
   }
   GLBLCNTL = 0x0001;              // SYSCLK = 48MHz (12MHz in)
   SYSPCR = 0x07;                 // ICLK = 16MHz, enable peripherals
   *(volatile unsigned int *)0x24; // dummy read to flush data pipeline
   /* setup ROM/RAM chip selects                                          */
   /* nEMUCS2 internal RAM block0                                         */
   MFBahr2 = 0x0050;              // address: 0x00500000
   MFBalr2 = 0x0040;              // size:      8k
   /* nEMUCS/nCS0 is the internal FLASH/ROM                               */
   MFBahr0 = 0x0000;              // address: 0x00000000
   MFBalr0 = 0x01A0;              // size:     512K
   /* --- STACKS ----- */
   /* set supervisor stack (INITIAL MODE AFTER RESET)                    */
   asm(" ldr sp,s_stack");
   main();
}

```

## A.4 Main.c

```

#include "misc.h"
#define BLOCK_SIZE 0x800          //Number of words to check
static load(unsigned int *load,unsigned int *start, unsigned int size);
extern unsigned int Load_RAM_PSA, Run_RAM_PSA;
extern unsigned int Size_RAM_PSA,psa_value;
main()
{  unsigned int size,count,bank;
   volatile unsigned int *address;
   load(&Load_RAM_PSA,&Run_RAM_PSA,(unsigned int)&Size_RAM_PSA);
   HETDIR=0x0000000F;
   HETDOUT=0x00000000;
   // Read Margin 0
   ENABLE_PSA;          //Initialize PSA value to zero
   PSA=0;
   DISABLE_PSA;
   address=0;           //start check at address zero
   count=(FLASH_SIZE-4)>>2; //0x80000 bytes of flash (less 32-bit PSA at end)
   do
   {  size=(count>BLOCK_SIZE) ? BLOCK_SIZE: count;
      bank=((unsigned int)address<BANK1_START) ? 0 : 1;
      address=ram_psa(address,size,bank,MARGIN0);          // execute this code in RAM
   } while (count--=size);
   if (PSA!=psa_value)
   {  HETDOUT=1;
      // Read Margin 1
      ENABLE_PSA;          //Initialize PSA value to zero
      PSA=0;
   }
}

```



```

DISABLE_PSA;
address=0;          //start check at address zero
count=(FLASH_SIZE-4)>>2; //0x80000 bytes of flash (less 32-bit PSA at end)
do
{
  size=(count>BLOCK_SIZE) ? BLOCK_SIZE: count;
  bank=((unsigned int)address<BANK1_START) ? 0 : 1;
  address=ram_psa(address,size,bank,MARGIN1);    // execute this code in RAM
} while (count-=size);
if (PSA!=psa_value)
  HETDOUT=2;
for(;;);
}
static load(unsigned int *load,unsigned int *start, unsigned int size)
{
  size=(size+3)>>2; //convert from bytes to words and round up
  do
  {
    *start++=*load++;
  } while (--size);
}

```

## A.5 ram\_psa.c

```

#include "misc.h"
volatile unsigned int *ram_psa(volatile unsigned int *address,
                               unsigned int length,
                               unsigned int bank,
                               MODE mode)
{
  INT_DISABLE();          // SWI routine
  GLBLCNTL = 0x0011;     // enter config mode
  FMMAC2 = 0xFFF8 + bank; // Select the bank
  FMTCR=0x2FC0+mode;     // Enter read margin test mode
  FMDTR=0xB;             // TEZ low (active)
  GLBLCNTL = 0x0001;     // leave config mode
  ENABLE_PSA;
  do
  {
    *address++;
  } while (--length!=0);
  DISABLE_PSA;
  GLBLCNTL = 0x0011;     // enter config mode
  FMDTR=0xF;            // TEZ high (inactive)
  FMTCR=0x03C0;         // Leave read margin test mode
  GLBLCNTL = 0x0001;     // leave config mode
  INT_ENABLE();         // SWI routine
  return address;
}

```

## A.6 swi.c

```

/*-----*/
/* NOTE: this must be compiled with -o2 in 32-bit mode and can't have more */
/*           than three parameters                                           */
#pragma INTERRUPT(ISR_SWI, SWI)
void ISR_SWI(unsigned r0, unsigned r1, unsigned r2, unsigned r3)
{
  asm(" ldrb  r3, [lr, #-1]");
  switch (r3)
  {
  case 0:
    /* WRITE_REGISTER_SVC */
    *(unsigned int *)r0 = r1;
    return;
  case 1:
    /* enable FIQ interrupt */
    asm(" mrs  r0, spsr");
    asm(" bic  r0, r0, #0x40");
    asm(" msr  spsr, r0");

```

```

        return;
    case 2:
        /* disable FIQ interrupt */
        asm(" mrs   r0, spsr");
        asm(" orr   r0, r0, #0x40");
        asm(" msr   spsr, r0");
        return;
    case 3:
        /* enable IRQ interrupt */
        asm(" mrs   r0, spsr");
        asm(" bic   r0, r0, #0x80");
        asm(" msr   spsr, r0");
        return;
    case 4:
        /* disable IRQ interrupt */
        asm(" mrs   r0, spsr");
        asm(" orr   r0, r0, #0x80");
        asm(" msr   spsr, r0");
        return;
    case 5:
        /* enable both interrupts */
        asm(" mrs   r0, spsr");
        asm(" bic   r0, r0, #0xC0");
        asm(" msr   spsr, r0");
        return;
    case 6:
        /* disable both interrupts */
        asm(" mrs   r0, spsr");
        asm(" orr   r0, r0, #0xC0");
        asm(" msr   spsr, r0");
        return;
    }
}

```

## A.7 *link32.lcf*

```

/*****
/* LINKER COMMAND FILE                                     */
/*                                                         */
/*****
/* OPTIONS                                                */
/*****
-c                /* ROM AUTOINITIALIZATION MODEL        */
-l rts32.lib
-x
-stack 0x800      /* SOFTWARE STACK SIZE                               */
/*****
/* SPECIFY THE SYSTEM MEMORY MAP                          */
/*****
MEMORY
{
    ROM      (RX) :   origin=0x00000000   length=0x00080000
    RAM      (RW) :   origin=0x00500000   length=0x00002000
}
/*****
/*****
/* SPECIFY THE SECTIONS ALLOCATION INTO MEMORY            */
/*****
SECTIONS
{
    .intvecs : {} > 0      /* INTERRUPT VECTORS          */
    .text : {} > ROM
    .PSA: palign=4, run=RAM, load=ROM,
        LOAD_START(_Load_RAM_PSA),

```

```
        RUN_START(_Run_RAM_PSA),
        SIZE(_Size_RAM_PSA)
    { ram_psa.obj
    }
    .const: {} > ROM
.psa_value : {} > 0x7ffc
.bss : {} > RAM
.stack : { .+=0x800;
           _StackSUPER=.;
           } >RAM
}
PSA = 0xE9577DEB;
```

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DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Military	<a href="http://www.ti.com/military">www.ti.com/military</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Optical Networking	<a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
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