

Interfacing TMS320C5x and Parallel Stereo CODEC with other TMS320 DSP Considerations

APPLICATION REPORT: SPRA097

Mathew George, Jr

*Digital Signal Processing Solutions
December 1997*



IMPORTANT NOTICE

Texas Instruments (TI) reserves the right to make changes to its products or to discontinue any semiconductor product or service without notice, and advises its customers to obtain the latest version of relevant information to verify, before placing orders, that the information being relied on is current.

TI warrants performance of its semiconductor products and related software to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are utilized to the extent TI deems necessary to support this warranty. Specific testing of all parameters of each device is not necessarily performed, except those mandated by government requirements.

Certain application using semiconductor products may involve potential risks of death, personal injury, or severe property or environmental damage ("Critical Applications").

TI SEMICONDUCTOR PRODUCTS ARE NOT DESIGNED, INTENDED, AUTHORIZED, OR WARRANTED TO BE SUITABLE FOR USE IN LIFE-SUPPORT APPLICATIONS, DEVICES OR SYSTEMS OR OTHER CRITICAL APPLICATIONS.

Inclusion of TI products in such applications is understood to be fully at the risk of the customer. Use of TI products in such applications requires the written approval of an appropriate TI officer. Questions concerning potential risk applications should be directed to TI through a local SC sales office.

In order to minimize risks associated with the customer's applications, adequate design and operating safeguards should be provided by the customer to minimize inherent or procedural hazards.

TI assumes no liability for applications assistance, customer product design, software performance, or infringement of patents or services described herein. Nor does TI warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right of TI covering or relating to any combination, machine, or process in which such semiconductor products or services might be or are used.

TRADEMARKS

TI is a trademark of Texas Instruments Incorporated.

Other brands and names are the property of their respective owners.

CONTACT INFORMATION

US TMS320 HOTLINE	(281) 274-2320
US TMS320 FAX	(281) 274-2324
US TMS320 BBS	(281) 274-2323
US TMS320 email	dsph@ti.com

Contents

Abstract	7
Product Support.....	8
World Wide Web	8
Email	8
INTRODUCTION.....	9
SYSTEM CONFIGURATION.....	10
System Modes.....	10
System Block Diagram	11
System Registers and Bits.....	13
SYSTEM OPERATION	17
Mode 1 Programmed I/O	17
Mode 2 Interrupt Driven.....	19
Mode 3 Stereo Codec DMA.....	20
SYSTEM CONSIDERATIONS	24
FIFO25	
External DMA	26
Serial Codec with DSP “DMA”	27
Parallel Codec with Separate Bus and External DMA Optional.....	28
CONCLUSION	29
REFERENCES.....	30
Appendix A - Code	31
Mode 1 - PIO Digital Loopback.....	31
Mode 2 - Interrupt Driven Digital Loopback.....	35
Mode 3 - Stereo Codec DMA Digital Loopback.....	39
Mode 3 - Stereo Codec DMA Digital Loopback with Intermediate Buffer and Interrupts.....	43
Appendix B - Stereo Codec DMA Structure.....	48
Stereo Codec DMA Schematic	48
Stereo Codec DMA FSM's.....	49

Figures

Figure 1. Connection of TMS320C5x DSP to Parallel Stereo Codec	12
Figure 2. Mode 1 - PIO Connection of TMS320C5x Parallel Stereo Codec.....	18
Figure 3. Mode 2 - Interrupt Connection of TMS320C5x Parallel Stereo Codec.....	19
Figure 4. Mode 3 - DMA Controller Connection of TMS320C5x Parallel Stereo Codec.....	21
Figure 5. Mode 3 - Test Code in Appendix A (Digital Loopback with DMA)	23
Figure 6. Basic DSP/SRAM/Codec System	24
Figure 7. FIFO DSP/SRAM/Codec System.....	25
Figure 8. External DMA DSP/SRAM/Codec System	26
Figure 9. DSP with "DMA"/SRAM/Serial Codec System.....	27
Figure 10. DSP/SRAM/Parallel Codec with Separate Bus and External DMA System	28
Figure 11. DMA Controller for Parallel Codec	48

Tables

Table 1. Smart Registers	13
Table 2. PC Status Register Definition.....	13
Table 3. PCSR Explanation	14
Table 4. Bit I/O Register Definition.....	14
Table 5. Bit I/O Explanation	15
Table 6. DSP Control Register Bit Definitions	15
Table 7. SYSCFG Explanation	15
Table 8. Address Receive Register (ARR) Bit Definitions	16
Table 9. Receive Buffer (BXR) Size Register Bit Definitions	16
Table 10. Address Transmit Register (AXR) Bit Definitions:.....	16
Table 11. Transmit Buffer (BXK) Size Register:	16

Interfacing TMS320C5x and Parallel Stereo CODEC with other TMS320 DSP Considerations

Abstract

The CS4231 is a 16 bit stereo codec chip with various features, such as multiple analog inputs and outputs, mixing, and gain capabilities, that make them ideal for computer sound applications [1][2]. The digital interface consists of a parallel 8-bit bus and is meant to directly connect to a PC (ISA/EISA) interface. Since it is a glueless interface to a PC bus, it looks a bit different from a TMS320C5x or other TMS320 DSPs with asynchronous memory interface. This Application Note describes an optimum interface to a TMS320C5x DSP. Note that other TMS320 DSP asynchronous buses are very similar and most of the interface described here will also apply to any TMS320 DSP system. In this implementation the TMS320C5x and codec share the same bus with SRAM. This tradeoff keeps pin count and thus cost down, at the cost of performance. A separate codec bus mapped into the DSP's memory or I/O space would make the system more efficient and is briefly described at the end of this Application Note along with other system considerations.



Product Support

World Wide Web

Our World Wide Web site at www.ti.com contains the most up to date product information, revisions, and additions. Users registering with TI&ME can build custom information pages and receive new product updates automatically via email.

Email

For technical issues or clarification on switching products, please send a detailed email to dsph@ti.com. Questions receive prompt attention and are usually answered within one business day.



INTRODUCTION

The CS4231 is a 16 bit stereo codec chip with various features, such as multiple analog inputs and outputs, mixing, and gain capabilities, that make them ideal for computer sound applications [1][2]. The digital interface consists of a parallel 8-bit bus and is meant to directly connect to a PC (ISA/EISA) interface. Since it is a glueless interface to a PC bus, it looks a bit different from a TMS320C5x or other TMS320 DSPs with asynchronous memory interface. This Application Note describes an optimum interface to a TMS320C5x DSP. Note that other TMS320 DSP asynchronous buses are very similar and most of the interface described here will also apply to any TMS320 DSP system. In this implementation the TMS320C5x and codec share the same bus with SRAM. This tradeoff keeps pin count and thus cost down, at the cost of performance. A separate codec bus mapped into the DSP's memory or I/O space would make the system more efficient and is briefly described at the end of this Application Note along with other system considerations.

SYSTEM CONFIGURATION

This TMS320C5x implementation was done with a TPC1280 FPGA acting as the glue logic. It was meant to be a prototype for an ASIC/cDSP type system with minimum hardware and concurrent playback and capture. Thus the system was designed within these parameters, assuming a roadmap to ASIC/cDSP. There are a variety of other ways that this interface could be accomplished if discrete logic or an FPGA with FIFOs will be in the final system. Thus some aspects could be more efficient using a faster ASIC or even discrete logic or PLDs. The needs of the system seem to differ based on the DSP software/OS to be used. As much flexibility was put into this system as possible (such as polled and interrupt modes) to allow determination by the programmer based on the specific system.

System Modes

Thus the following three progressive levels of interface were implemented:

- 1) **Programmed I/O** - Necessary for initialization of the codec, but slow in actual operation due to the use of bit polling for capture and playback. Uses the least amount of pins and the DSP does all the work. This is not an efficient configuration.
- 2) **Interrupt driven** - Various possible configurations, but the general idea is that the DSP is somehow interrupted by the codec for capture and playback. It is faster than mode 1, but uses more pins and logic. Again the DSP does all the work. In this implementation, the number of interrupt pins used was minimized as a tradeoff for more software protocol. This mode is *probably* more efficient if classic assembly-level, low-overhead DSP code is used.



- 3) **Stereo Codec DMA** - Again various configurations, but the general idea is that the DSP is put in -HOLD (i.e. taken off the bus) based on an interrupt. Then external logic (i.e. a DMA controller implemented in the FPGA and modeled after the Buffered Serial Port seen in the TMS320C56/57 and TMS320C54x DSPs [7]) will copy the data for capture and playback between the DSP and memory. Mode 3 needs more pins and is faster than mode 1. (Again, as in mode 2, the number of interrupt pins was minimized). The DSP is oblivious to this task until an interrupt tells it that input or output buffers in memory are full and need to be processed. But there can be some overhead if the DSP needs to access external memory [3]. Mode 3 uses the same number of pins as mode 2 and (regarding speed) is *probably* more efficient, if a less-classic, C-based multi-tasking operating system, higher-overhead DSP code is used.

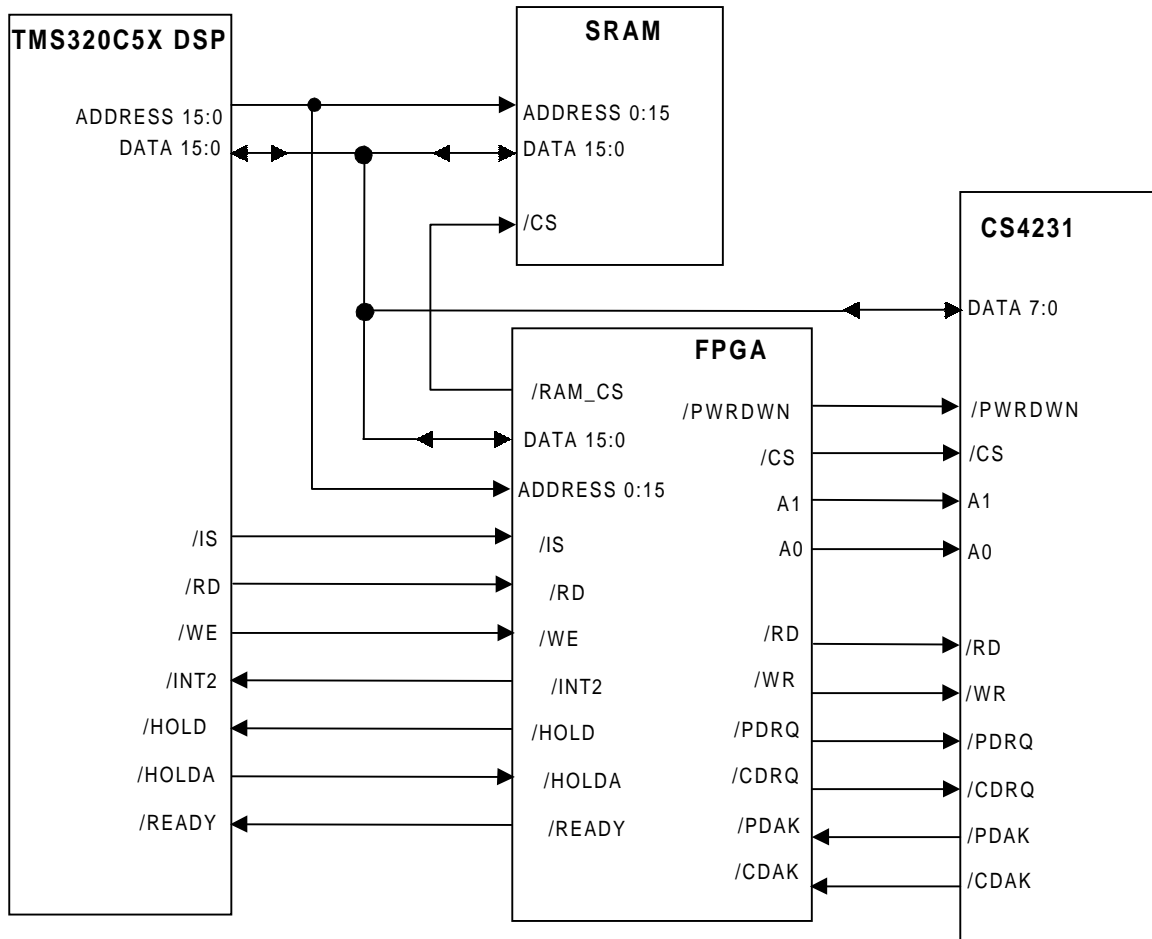
NOTE:

Note that in mode 1, the codec is placed in the PIO mode and uses the command interface. The command interface is there by default in a polled fashion and no additional pins are required. But while in modes 2 and 3, the DSP is in DMA mode and uses DMA pins (PDRQ/CDRQ and -PDAK/-CDAK). Note that these modes may be mixed, using one for playback and the other for capture if so desired.

System Block Diagram

The following block diagram shows how the digital aspects of how the DSP/codec system appears (Figure 1). All three modes are supported here. Some pins may be eliminated if just a particular mode is needed. These are described in more detail in the System Operation section.

Figure 1. Connection of TMS320C5x DSP to Parallel Stereo Codec



Three devices are connected to the TMS320C5x external bus: the SRAM, the codec and an FPGA. The SRAM is usually the most used, since the program is running from there. It is mapped into the program and/or data space (dual mapped in this case with a zero decode logic [4]). The four codec parallel Interface Registers R0-R3 are mapped into the DSP I/O space from 58h-5Bh. Various FPGA registers that control the codec (and other things) are mapped into DSP I/O space 50h-54h and 5Ch-5Fh.



System Registers and Bits

Table 1 describes the registers used in this implementation. Much of this comes from the original implementation and can be ignored. Registers with any codec relevant bits are in bold (for a full description of these registers please see reference [5]):

Table 1. Smart Registers

Register	Memory Address		Default Value	Access	
	PCMCIA Common Memory	'C5x I/O Space		PC	DSP
SIGR	000400h		xxxx	R/W	
Reserved	000000h				
DSPCR	000002h		0108h	R/W	
DSPSR	000004h		0xxxh	R	
DSPTXD	000006h	0050h	0000h	R	W
DSPRXD	000008h	0051h	0000h	W	R
Reserved	00000Ah-00000Fh				
PCSR		0052h	000xh		R
BIOR		0053h	000xh		R/W R
SYSCFG		0054h	0080h		R/W
Reserved		0055h-0057h			
CODEC R0		0058h	xx80h		R/W
CODEC R1		0059h	xx80h		R/W
CODEC R2		005Ah	xx80h		R/W
CODEC R3		005Bh	xx80h		R/W
ARR		005Ch	0000h		R/W
BKR		005Dh	0000h		R/W
AXR		005Eh	0000h		R/W
BKX		005Fh	xx80h		R/W

The codec relevant bits are described in the following few Tables 2, 3, 4, 5, 6, 7, 8, 9, 10, and 11. Notice that they are in bold; please ignore the other bits. (Again for a full description of these all these registers and bits please see [5]). Note that some of the bits used for Mode 3 were placed in PC accessible registers DSPCR/DSPSR so that capture/play data was in shared memory that the PC could directly access. But this has not been stressed in this application note. See [5] for more detail.

Table 2. PC Status Register Definition

15-8	7	6	5	4	3	2	1	0
Reserved	XH	RH	XINT	RINT	PDQR	CDQR	RXFULL	TXEMPTY

Table 3. PCSR Explanation

Bit	Name	Description
2	CDRQ	This bit reflects the value of the stereo codec's CDRQ pin
3	PDRQ	This bit reflects the value of the stereo codec's PDRQ pin.
4	RINT	Receive (Capture) Interrupt: This bit becomes active when the DSP needs to service a capture interrupt. In Mode 2 (BRE=0) this means that the DSP must move data from the codec to memory, and the bit is cleared by doing enough of these moves to make CDRQ inactive. In Mode 3 (BRE=1) it means that the capture buffer from the codec is full and needs servicing by the DSP, and the bit is cleared when PCSR is read (So just do it once). The default value of this bit is 0.
5	XINT	Transmit (Playback) Interrupt: This bit becomes active when the DSP needs to service a playback interrupt. In Mode 2 (BXE=0) this means that the DSP must move data from memory to the codec, and the bit is cleared by doing enough of these moves to make PDRQ inactive. In Mode 3 (BXE=1) it means that the playback buffer from the codec is full and needs servicing by the DSP, and the bit is cleared when PCSR is read (So just do it once). The default value of this bit is 0.
6	RH	(Receive Half) This bit indicates which half of the buffer has been processed. It should be considered a full flag so if RH=0 then the first half of the buffer (defined by ARR and BKR) is full and needs to be processed. The default value is 0.
7	XH	(Transmit Half) This bit indicates which half of the buffer has been processed. It should be considered an empty flag so if RH=0 then the first half of the buffer (defined by AXR and BKX) is empty and needs to be filled. The default value is 0.
8	Reserved	These bits are reserved and may reflect any value that has no relevance to the operation of the card.

Table 4. Bit I/O Register Definition

15	14	13	12	11	10-8	7-4	3	2	1-0
-PDAK	-CDAK	CODECA1	CODECA0	-PWRDWN	O2-O0	Reserved	PDRQ	CDRQ	I1-I0



Table 5. Bit I/O Explanation

Bit	Name	Description
2	CDRQ	This bit reflects the value of the stereo codec's CDRQ pin.
3	PDRQ	This bit reflects the value of the stereo codec's PDRQ pin.
4-7	Reserved	These bits are reserved and may reflect any value that has no relevance to the operation of the card.
11	-PWRDWN	This bit output is directly connected to the -PWRDN pin of the codec for reset of the codec. The default is 0.
12-13	CODEC A0 CODEC A1	These are the address bits to the codec that are latched by the FPGA to make the t_{ADHD} timing. Their corresponding pins will latch the last value of the address bits following a codec access. <i>They totally bypass the BIOR protocol (presently) their bit value has no meaning. There is no way to make them bit outputs.</i> The default is 0.
14	-CDAK	This bit reflects that value of the pin to codec -CDAK input when in Mode 2 (BRE=0 in SYSCFG Register). Thus this pin is used to manually toggle -CDAK in Mode 2. If in Mode 3 (BRE=1), then this bit will not reflect the -CDAK pin since the FSM will handle the toggling. The default is 0. Be sure to change to one in Mode 2 before -PWRDWN=1.
15	-PDAK	This bit reflects that value of the pin to codec -PDAK input when in Mode 2 (BXE=0 in SYSCFG Register). Thus this pin is used to manually toggle -PDAK in Mode 2. If in Mode 3 (BXE=1), then this bit will not reflect the -PDAK pin since the FPGA FSM will handle the toggling. The default is 0. Be sure to change to one in Mode 2 before -PWRDWN=1.

Table 6. DSP Control Register Bit Definitions

15-12	11-8	7	6	5-4	3	2	1-0
EXCP7-4 EXDP3-0	EXCP3-0 EXPP3-0	CPD/ -SPD	BXE	GLODAP 1-0	PHD	BRE	CLK DIVISOR 1-0

Table 7. SYSCFG Explanation

Bit	Name	Description
2	BRE	Receive Autobuffering Enable Bit. This bit enables the DMA for receive (capture) operation if BRE=1, i.e. Mode 3. This bit must be 0 for capture in mode 1 or 2 to occur. <i>Note that BRE is mutually exclusive to BXE.</i> The default is 0.
6	BXE	Transmit Autobuffering Enable Bit. This bit enables the DMA for transmit (playback) operation if BXE=1, i.e. Mode 3. This bit must be 0 for playback in mode 1 or 2 to occur. <i>Note that BXE is mutually exclusive to BRE.</i> The default is 0.

Stereo Codec Registers R0-R3:

- See [1] or [2] for definition of:
- Index Address Register
- Indexed Data Register
- Status Register
- PIO Data Register

Table 8. Address Receive Register (ARR) Bit Definitions

15-0
Receive (Capture) Buffer 16-Bit Beginning Address

The ARR 16 bit register (Table 8) gives the beginning address of the receive buffer for Stereo Codec external DMA.

Table 9. Receive Buffer (BXR) Size Register Bit Definitions

15-0
Receive (Capture) Buffer 16-Bit Ending Address

This 16 bit register (Table 9) gives the ending address of the receive buffer for Stereo Codec external DMA. (Note that this is slightly different than the BSP spec because of limited combinatorial gates in the FPGA).

Table 10. Address Transmit Register (AXR) Bit Definitions:

15-0
Transmit (Playback) Buffer 16-Bit Beginning Address

This 16 bit register (Table 10) gives the beginning address of the transmit buffer for Stereo Codec external DMA.

Table 11. Transmit Buffer (BXK) Size Register:

15-0
Transmit (Playback) Buffer 16-Bit Ending Address

This 16 bit register (Table 11) gives the ending address of the transmit buffer for Stereo Codec external DMA. (Note that this is slightly different than the BSP spec because of limited combinatorial gates in the FPGA).



SYSTEM OPERATION

The architecture described in this Application Note allows for the use of all three modes. DSP specific system level considerations can be found in various literature items available from TI, especially [6].

From the codec standpoint, it needs to be programmed after coming out of reset (unfortunately misnamed as -PDWN). This operation is done by addressing the R0-R3 registers in decoded logic and can be observed in the code section for all modes. Basically this programming involves setting of codec I/O channels, data format, gains, etc. since the huge flexibility in these parts rarely allow the system to be up and running, as is seen with more classic DSP codecs such as the TLC3204x family. Use of IN/OUT instructions was essential in the design because of the relatively slow FPGA accesses when compared to that of the DSP, especially turn-off time. Memory-mapped I/O accesses using the DSP are NOT advised.

Another system aspect that should be appreciated is how slow the codec cycles are (several hundred nanoseconds) compared to a 40 or 50 MIP DSP. This aspect is due to the analog noise margins that increased digital speeds would incur. This fact drove the decision to ignore certain functions that are provided in the codec (such as capture and play ready bits in modes 2 and 3, thus ignoring the codec INT pin) and to move these functions to the FPGA. The assumption is that when the interface logic is made discrete, or more likely into an ASIC or cDSP, the system will run operate faster.

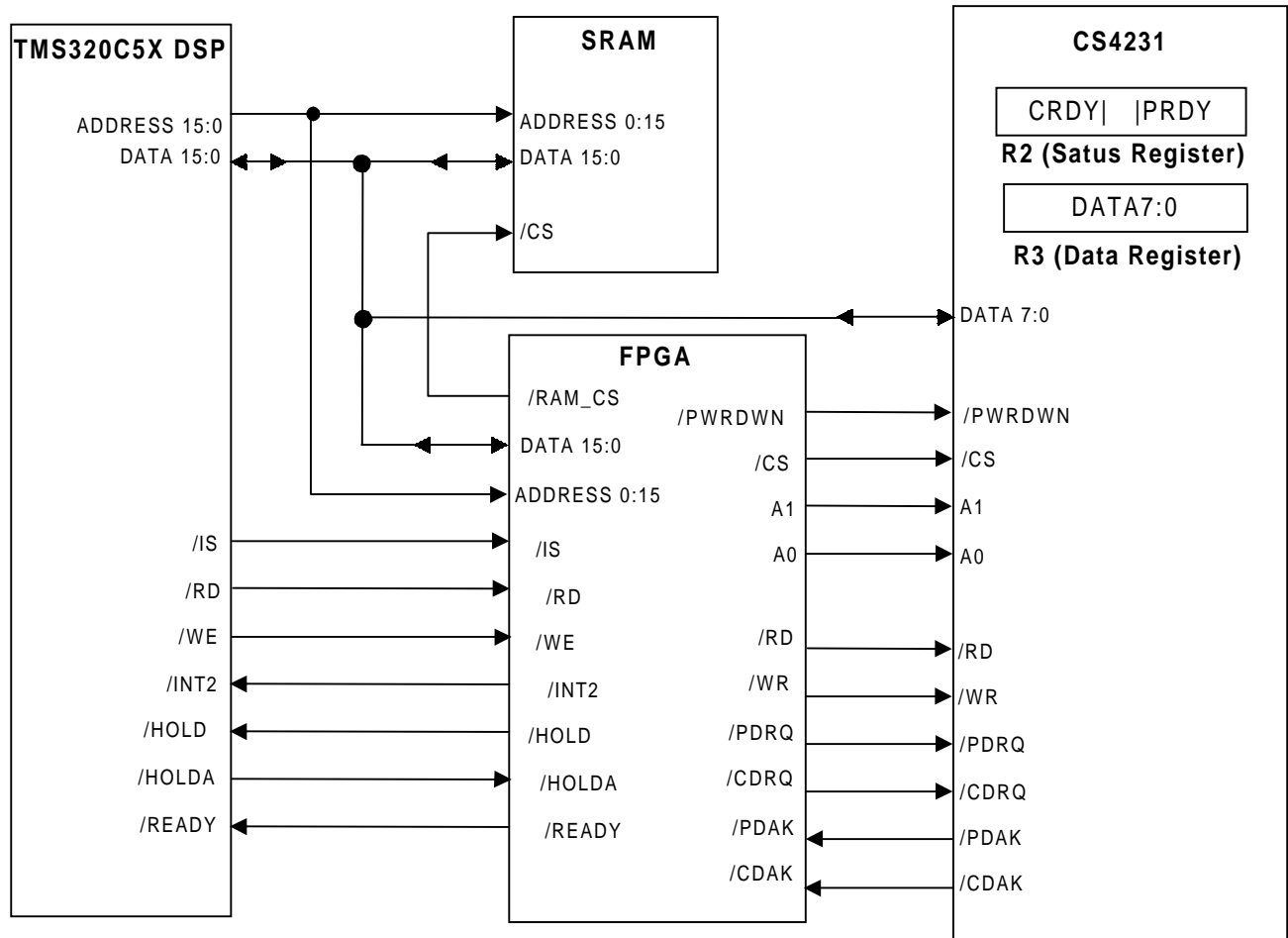
Mode 1 Programmed I/O

From a hardware standpoint, the decode necessary for the programming makes this almost a default mode. The playback function is readily available since the DSP is writing to the codec. But in the case of capture, the t_{ADHD} address hold timing from the DSP is too fast for the codec which, as mentioned earlier, was made for a slower PC bus. Thus latching of the address lines for the codec is essential for reliable capture.

NOTE:

Figure 2 shows mode 1 PIO, whose only difference from the main block diagram in Figure 1 is the stress on stereo codec Direct Registers.

Figure 2. Mode 1 - PIO Connection of TMS320C5x Parallel Stereo Codec



From the software standpoint, the codec must first be programmed into the PIO mode and various bits polled. Then PIO Capture and Playback bits (CRDY/PRDY) in the codec Status Register R2 (called Direct 2 Status on AD65) is polled by the DSP in a tight loop before receiving or sending data. Obviously this mode ends up becoming slow since it is poll driven. Also note that each of these codec accesses are in the hundreds of nanoseconds, slow to a DSP. Code for PIO that does a simple digital loop back can be seen in Appendix A.

```

Loop: Test codec Status Register R2 for CRDY/PRDY
      Read/write data from/to codec Data Register R3
      Goto Loop
    
```

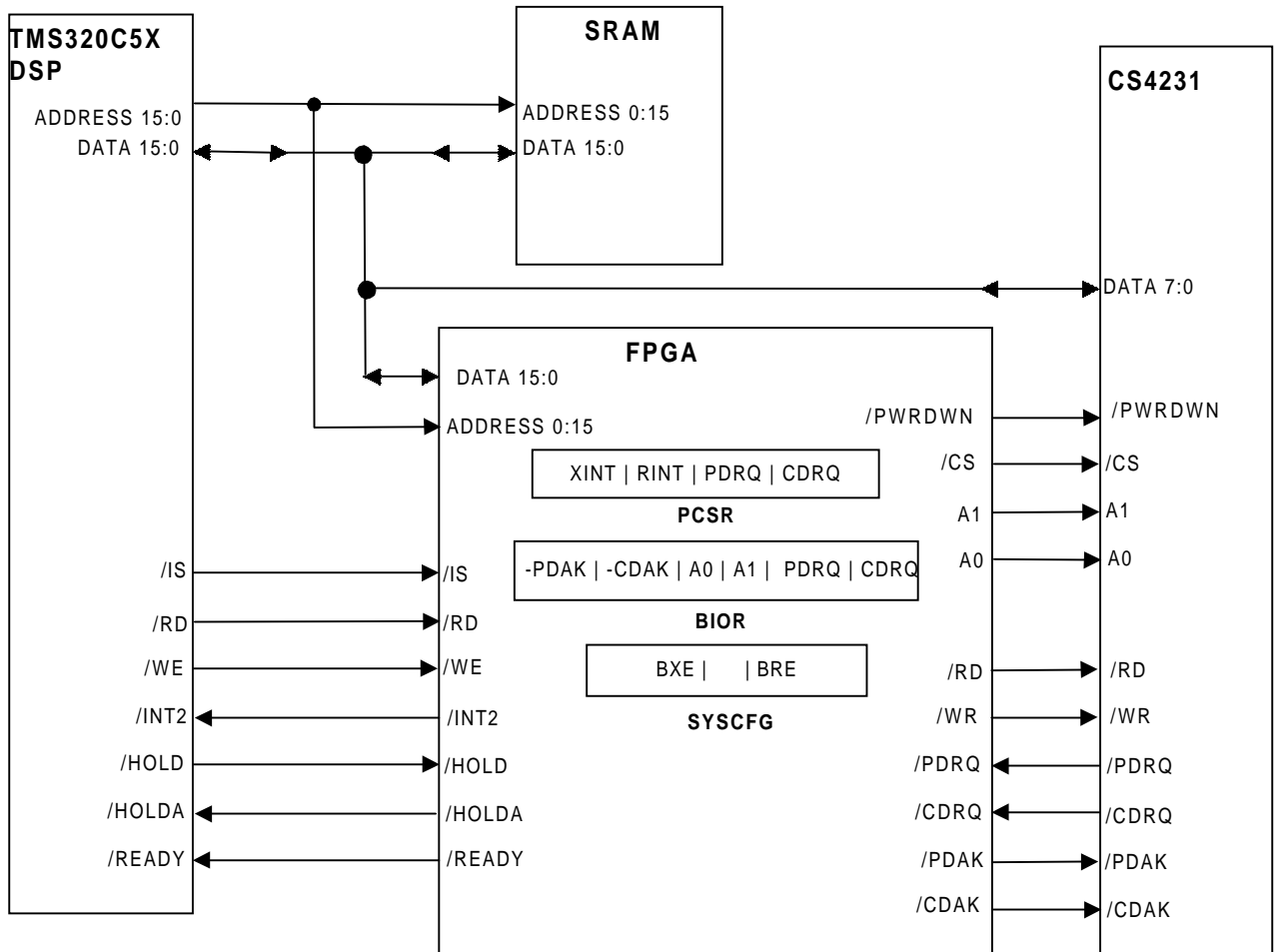


Thus the other two modes place the codec in the DMA mode using the PDRQ and CDRQ pins. As mentioned earlier, the INT pin is not used because it does not differentiate between capture and play. This function was moved to the FPGA. This is not much faster, but was done based on the assumption that an ASIC/cDSP implementation was the final goal. Note that though the next two modes use the same pins, they handle data movement quite differently.

Mode 2 Interrupt Driven

In this mode after putting the codec into DMA mode the DSP handles not only the data movement interrupt-based, but also the handshake with DMA acknowledge pins -CDAK and -PDAK. The following Figure 3 shows the relevant configuration.

Figure 3. Mode 2 - Interrupt Connection of TMS320C5x Parallel Stereo Codec



The PDRQ/CDRQ requests have been multiplexed to the same DSP interrupt pin -INT2. The CDRQ and PDRQ bits in the DSPSR register must then be read and the appropriate action taken. Whether capture or play, the DSP must write to the CDAK or PDAK bits in the SYSCFG register to manually exercise the DMA mode. Thus the following sequence must occur in the ISR, assuming simultaneous capture and play.

- 1) Read PCSR and test if CDRQ, PDRQ or both are high.
- 2) Write 0 to -CDAK/-PDAK bit in SYSCFG (based on whichever is higher priority) to acknowledge the DMA cycle.
- 3) Read/write data value from/to codec before/after writing/reading to memory.
- 4) Write 1 to -CDAK/-PDAK bit in SYSCFG to end DMA cycle acknowledgement.
- 5) Repeat for number of bytes.

The last step is required since FPGA will pend and interrupt the DSP if PDRQ or CDRQ is high. If the DSP chooses to mask this interrupt, then data will be lost. Code that exercises some simple digital loopback in this mode may be found in Appendix A.

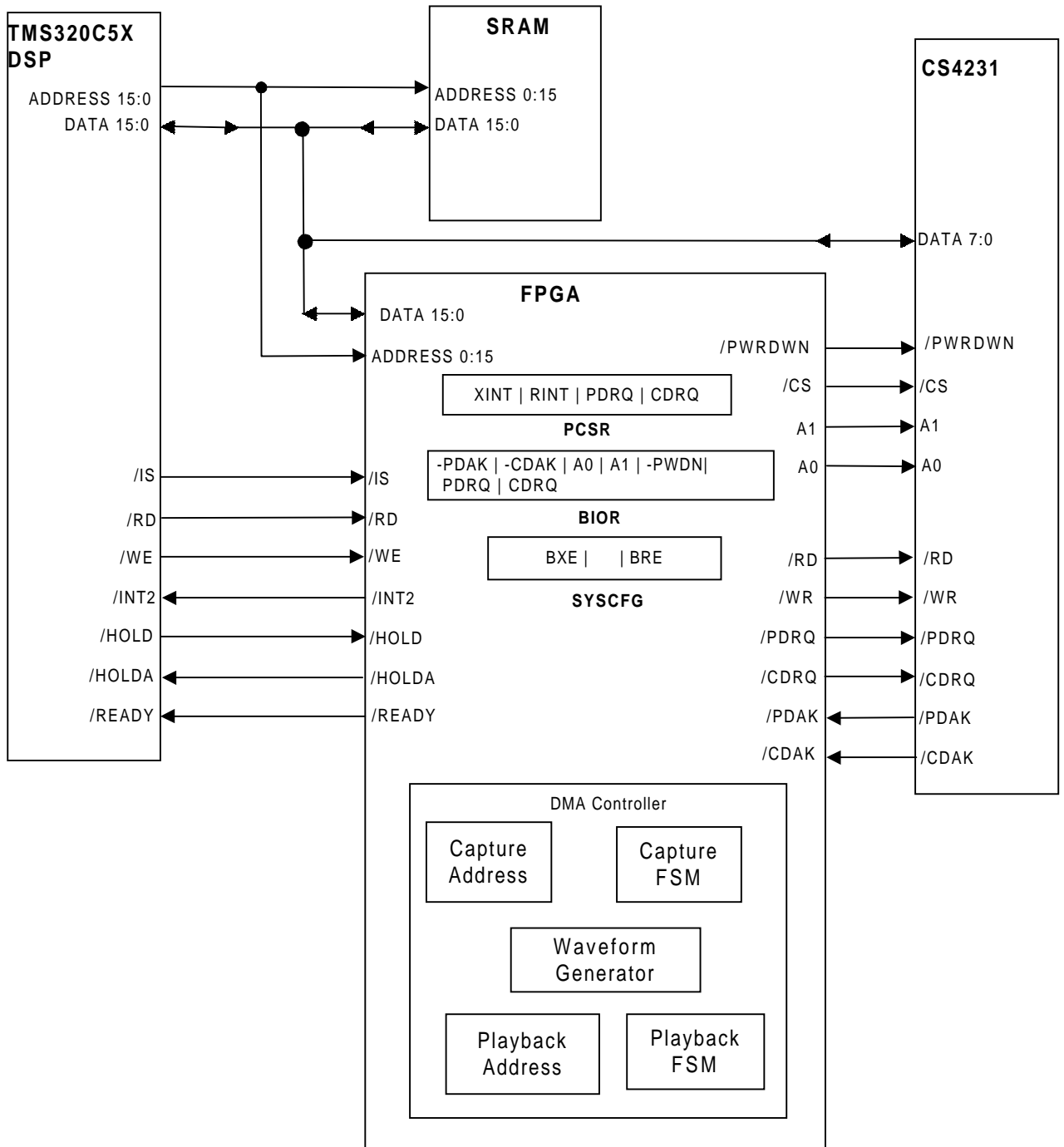
Mode 3 Stereo Codec DMA

In this mode the DSP is taken off the bus (using the -HOLD/-HOLDA protocol) and the data is copied back and forth between the DSP and memory. A DMA controller is designed into the FPGA that consists of three parts each for receive and transmit. These parts are: a finite state machine to act as the intelligent entity, address generation blocks, and wave form generation module. Parts of the wave form generation module can be shared between capture and playback parts since the single bus prevents them from occurring at the exact same time (even though they may run concurrently). If there is any conflict for resources, priority has been given to the capture module.

The following figure shows how these modules are constructed in the FPGA.



Figure 4. Mode 3 - DMA Controller Connection of TMS320C5x Parallel Stereo Codec





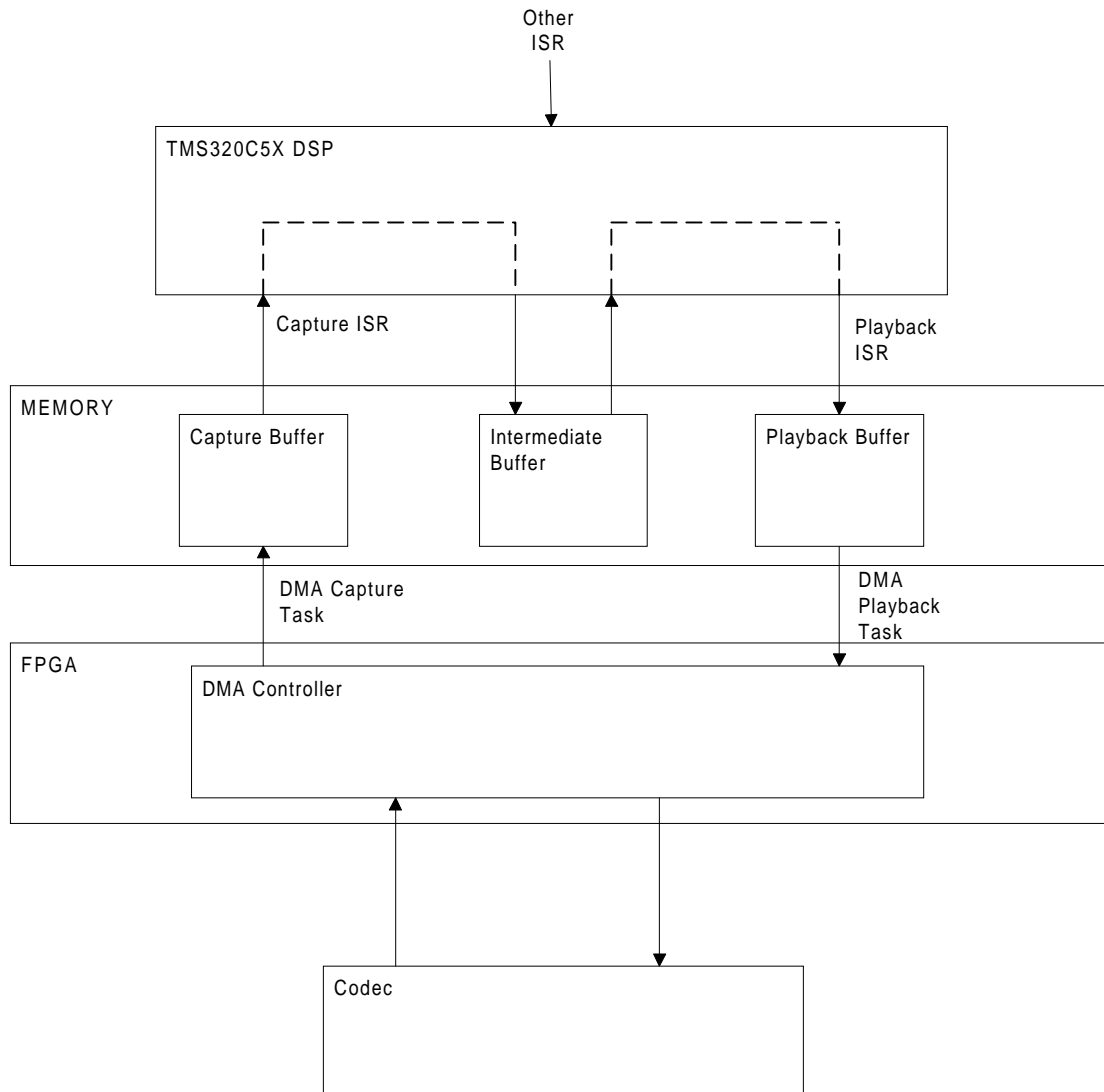
As mentioned earlier, this logic was designed to look similar to [7]. The capture and playback buffers may be placed anywhere in external memory. The DSP will be interrupted when the DMA controller reaches either the halfway point or end of the buffer. Then the RH/XH flag must be read to determine which half of the buffer needs servicing. The DMA controller for capture or play is enabled by the BRE and BXE flags respectively. The schematics for the FSM's and Address Generators can be seen in Appendix B. A full description of this would be found in [9].

From a software standpoint, after the DMA is setup the DSP needs to deal with the data only when a buffer is full or empty. The code looks similar to the interrupt driven except that the acknowledges are handled by the FSM and large buffers of data are used. Thus the following sequence must occur in the ISR, assuming simultaneous capture and play.

- 1) Read PCSR and test if RINT, XINT or both are high.
- 2) Test RH or XH to see which buffer may now be manipulated.
- 3) Change buffer pointers for main code to deal with these buffers.

In Appendix A, some code may be found that does some simple digital loopback. Appendix A also has a bit more interesting loopback code (Figure 5).

Figure 5. Mode 3 - Test Code in Appendix A (Digital Loopback with DMA)

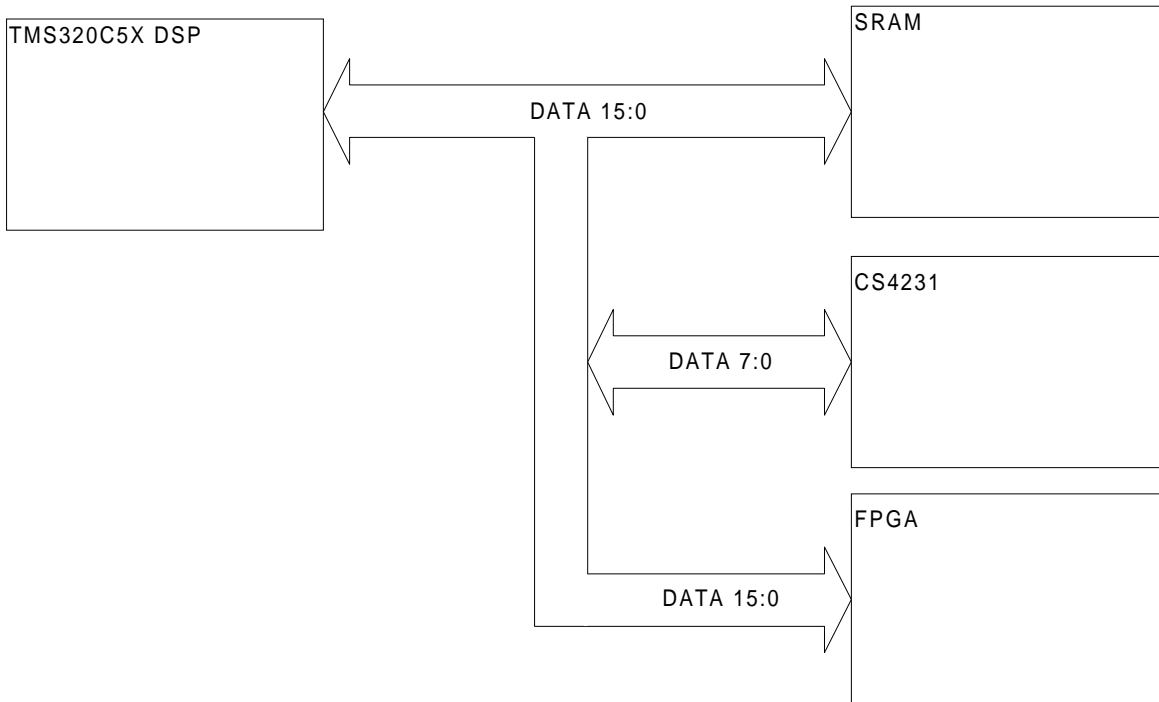


That sets up an intermediate buffer so that the capture ISR copies data from the capture buffer and puts it into the intermediary buffer. Meanwhile the playback ISR copies data from the intermediary buffer to the playback buffer. While all this is happening, the FSM's are copying data to and from the codec from the capture and playback buffers. Also a second interrupt is occurring while all this is happening.

SYSTEM CONSIDERATIONS

The basic system described previously in this Application Note looks as follows in Figure 6.

Figure 6. Basic DSP/SRAM/Codec System



The problem with this architecture, which should minimize the time that the DSP is not accessing the SRAM, is compounded by the relatively slow access time of the stereo codec in relation to the codec. Three possible methods of speeding up this interface are described below, with different costs:

- 1) FIFO
- 2) External DMA
- 3) Serial Port (with internal DSP DMA)

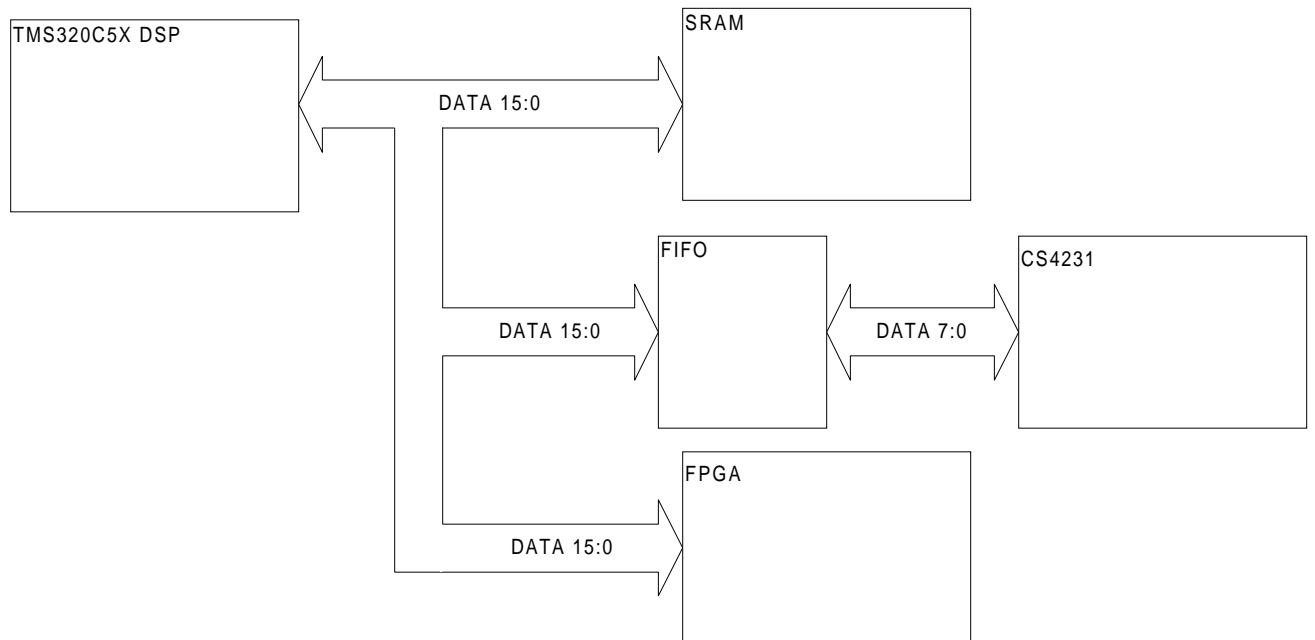
NOTE:

Note that they all ignore the speed of the FPGA/ASIC/logic (which will be addressed later) and that only two were implemented in this paper.

FIFO

In this implementation a FIFO is added as a classical mismatched speed bus interface solution. If the FIFO is fast enough, then the DSP can access data at zero wait states even though the codec interface is in the hundreds of nanoseconds. This method is probably the medium simplicity though higher cost since an additional part (and also interface glue logic) will need to be added. See Figure 7.

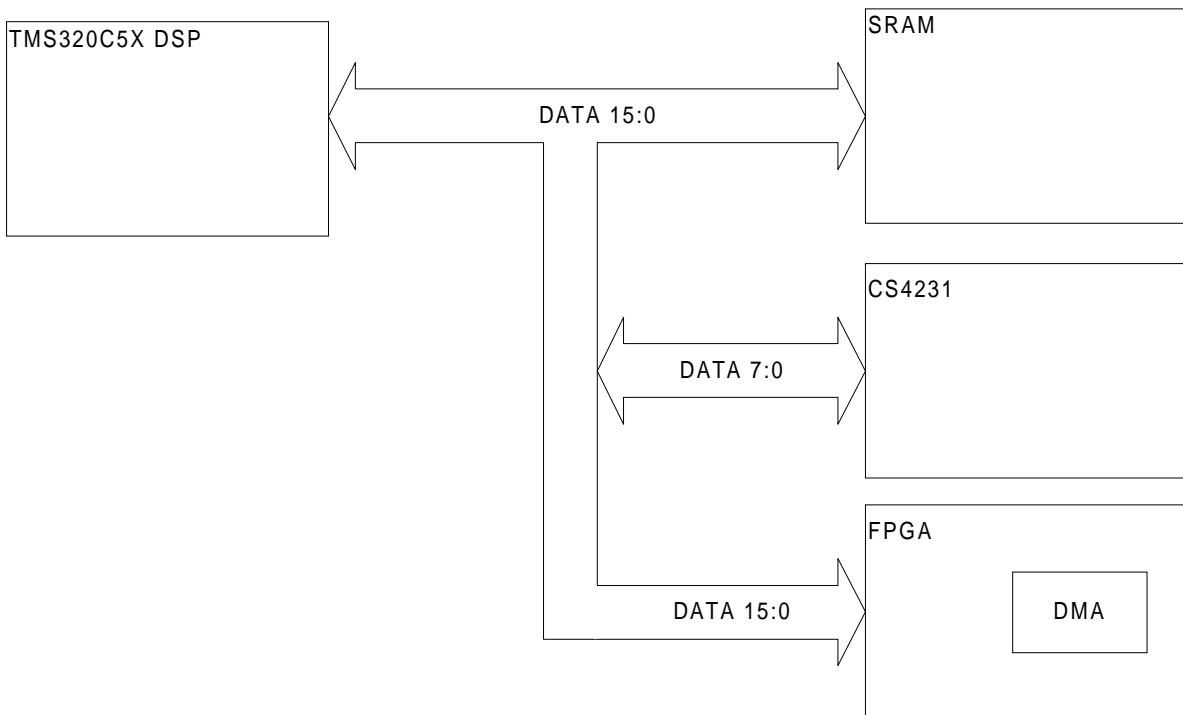
Figure 7. FIFO DSP/SRAM/Codec System



External DMA

This implementation was discussed in detail in this paper. It takes the burden off the DSP to do the data moving work, but is quite complicated. It is not that expensive, since existing logic may be used. This method is probably the most complex, and is medium-to-higher cost since much design and added logic are needed. See Figure 8. Note that TMS320 DSPs with their own DMA controllers exist, but much data is still going over the same bus, hence limiting the bandwidth.

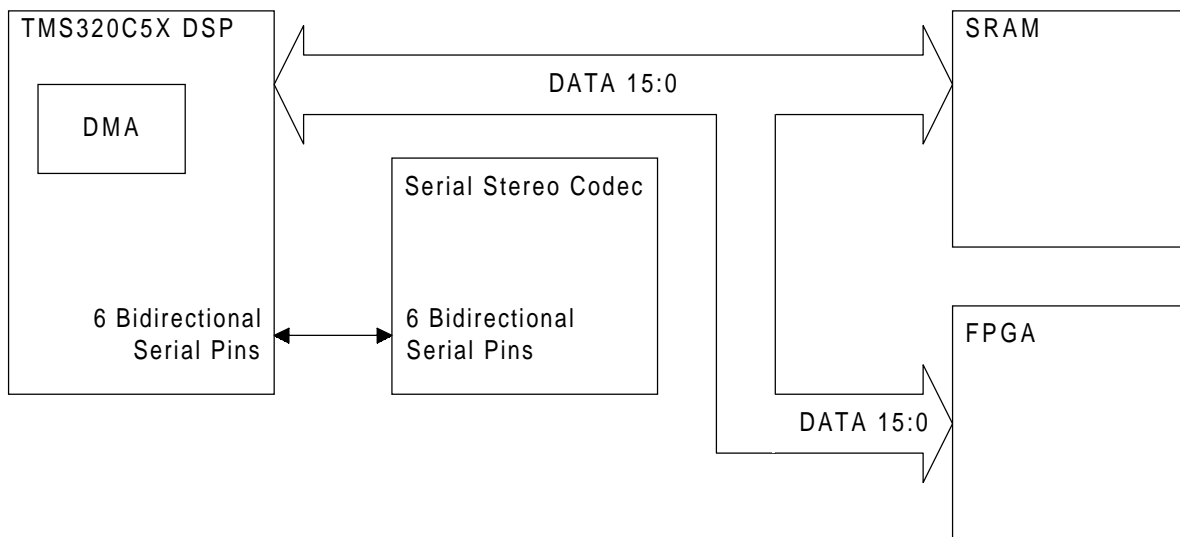
Figure 8. External DMA DSP/SRAM/Codec System



Serial Codec with DSP “DMA”

In this implementation an alternative serial bus is given to the codec so that it does not conflict with the SRAM. It is important here for the DSP to have some sort of bi-directional DMA capability, which may be seen in TMS320C5x/C54x parts with the buffered serial port or TMS320C32/TMS320C6xxx with multiple DMA channels (see Figure 9). This system probably makes the most sense for the mass market customer who is not doing a cDSP/ASIC.

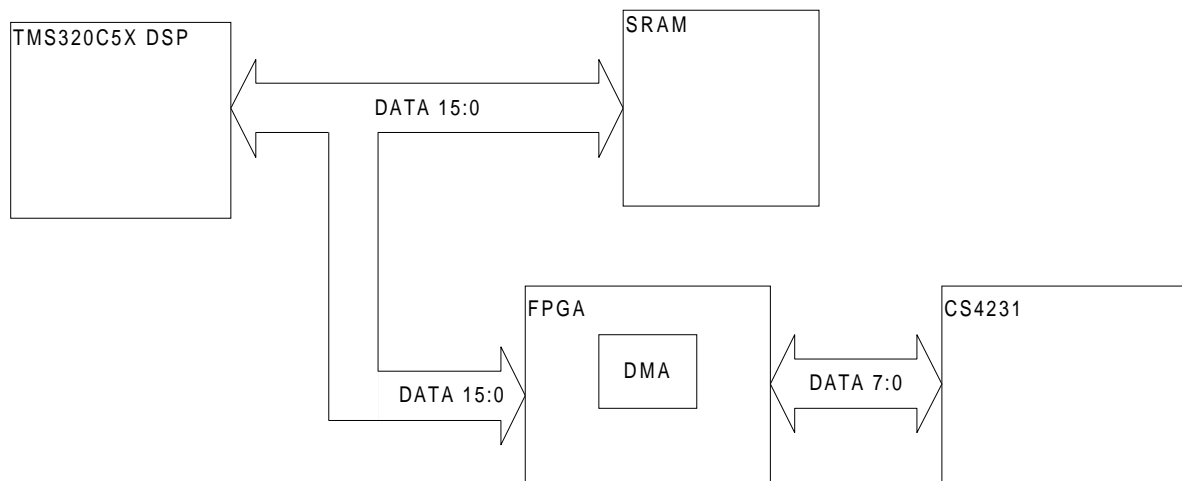
Figure 9. DSP with “DMA”/SRAM/Serial Codec System



Parallel Codec with Separate Bus and External DMA Optional

This implementation should be mentioned as the ideal for performance. A separate data bus is created through logic to feed the DSP. Thus the DSP is protected from the slowness of the codec in a FIFO like style if a fast ASIC is used for the logic. The use of the DMA is optional based on the system. Of course this implementation will cost the most pins. This implementation probably makes the most sense for the cDSP customer.

Figure 10. DSP/SRAM/Parallel Codec with Separate Bus and External DMA System





CONCLUSION

There are MANY ways to hook up these two parts. The important thing is to understand the parts and find the optimum configuration from both hardware AND software aspects. The limiting tradeoffs are those between design complexity and bus bandwidth.



REFERENCES

- 1) Crystal Data Book
- 2) TLC320AD65 Data Sheet
- 3) TMS320C5x User's Guide (p. HOLD)
- 4) Designer Notebook Page #4x.
- 5) PCMCIA DSP/Memory Card for the TMS320C5x Specification
- 6) PCMCIA DSP/Memory Card for the TMS320C5x Application Note
- 7) TMS320C57 Buffered Serial Port Spec
- 8) TLC320AD65 Data Sheet - P_PORT Addendum
- 9) FPGA Spec



Appendix A - Code

The following section has all sorts of code that was written for a system based on [5]. Note in all cases that the codec is first initialized in either PIO or DMA mode and then put into its function. Note that there is a good amount of redundancy in the code, but all of it is fully functional.

Mode 1 - PIO Digital Loopback

This code initializes the codec in PIO mode with appropriate inputs and gains and then uses mode 1 - PIO to do the digital loopback one sample at a time.

```
.mmregs
.include "cs4231.inc"

LEFT_ADC_GAIN .set 02h
CFS           .set CS4231_48KHZ

.sect "vectors"

b      init      ;00; Reset.
.space 2 * 16    ;02; Vector for external interrupt
           ; INT1.
.space 2 * 16    ;04; Vector for external interrupt
           ; INT2.
.space 2 * 16    ;06; Vector for external interrupt
           ; INT3.
.space 2 * 16    ;08; timer interrupt vector - TINT
.space 2 * 16    ;0A; Serial port receive interrupt
           ; RINT
.space 2 * 16    ;0C; Serial port transmit
           ; interrupt XINT
.space 4 * 16    ;0E; vectors for TDM port TRNT,
           ; TXNT
.space 2 * 16    ;12; vector for external interrupt
           ; INT4
.space 14 * 16   ;14; Reserved space. Should not be
           ; used.
.space 2 * 16    ;22; Trap instruction vector
.space 2 * 16    ;24; Non Maskable Interrupt vector
.space 4 * 16    ;26; Reserved space. Should not be
           ; used.

.text

init:
ldp    #0
splk   #0000000110b, IMR
clrc   OVM      ; Disable overflow saturation mode
splk   #001Fh, CWSR
```



```
splk    #0000h, PDWSR
splk    #0FFFAh, IOWSR      ; 3 wait (I/O)

call    _InitAIC

lacc    #08000h ; set up circular buffer pointers
sacl    CBSR1    ; buffer1 = 8000 -> ffff
lacc    #0FFFFh ;
sacl    CBER1    ;
lar     AR7,#08000h ; set receive buffer
lacc    #11101111b ;
sacl    CBCR

lacc    #0
mar     *, AR7
rpt     #8000h
sacl    *+

SET_CS4231 I9, CS4231_ENABLE
                ; Capture and Playback enabled.

Clrc    INTM      ; Globally enable interrupts

Loop:

in      TEMP0, CS4231_R2
nop
lacl    TEMP0
and     #00100000B
bcnd    Capture, NEQ

lacl    TEMP0
and     #00000010B
bcnd    Playback, NEQ
b       Loop

Capture:

in      *, CS4231_R3
lacl    *
and     #0FFh
sacb

in      *, CS4231_R3
lacc    *, 8
sacl    TEMP0
lacb
or      TEMP0
sacl    *

b       Loop

Playback:
```




```

        lacc      *+
        sacl     TEMP0
        out      TEMP0, CS4231_R3
        rpt      #07h
        sfr
        sacl     TEMP0
        out      TEMP0, CS4231_R3
        b        Loop

;*****
;
; _InitAIC() - AIC Initialization Routine
;
;*****
_InitAIC:
        zap
        sacl     TEMP1          ; TEMP1 <- clears MCE

        lacc     #8F00h         ; Take out of reset
        sacl     TEMP0
        out      TEMP0, CS4231_PDWN
        rpt      #0F000h       ; Wait a while longer (Dag)
        nop

Wait_80:
        in       TEMP0, CS4231_R1
        nop
        cpl      #80h, TEMP0
        bcnd     Wait_80, TC
;
; ===== Clear previous states =====
;
        IS_CS4231_RDY TEMP0 ; Wait for PIO ready

        SET_CS4231 I9, 0 ; Disable playback and capture
        out      TEMP0, CS4231_R2
                        ; Clear interrupts

; ===== Configure CODEC =====

        IS_CS4231_RDY TEMP0

        SET_CS4231 SETMCE | I12, CS4231_SETMODE2
                        ; Set the MODE2

        SET_CS4231 SETMCE | I9, CS4231_P_PIO | CS4231_C_PIO

        SET_CS4231 SETMCE | I28, CS4231_MONO | CS4231_16LINEAR
                        ; Set The Capture mode to
                        ; 16-bit linear

```



```
SET_CS4231 SETMCE | I8, CFS | CS4231_MONO |
                                CS4231_16LINEAR
                                ; Set 16-bit, mono.

rpt    #0FFFFh
nop

IS_CS4231_RDY TEMP0    ; Clocks must resynch.

SET_CS4231 SETMCE | I0, CS4231_MIC | LEFT_ADC_GAIN
                                ; Left ADC input source select : Microphone.

SET_CS4231 SETMCE | I6, CS4231_SETGAIN
                                ; Left DAC attenuator.

;
; ===== Recalibrate CS4231 =====
;

lacc    #SETMCE | I9    ; Set up R0 by setting Index
                                ; to I9
sac1    TEMP0          ; and setting MCE.
out     TEMP0, CS4231_R0
                                ; Set the ACAL bits in

in     TEMP0, CS4231_R1
nop
lacl    TEMP0          ; Set ACI bit in I9 without clearing
or     #CS4231_SETACAL ; any other bits. This will
sac1    TEMP0          ; cause device to recalibrate.
out     TEMP0, CS4231_R1
nop
out     TEMP1, CS4231_R0
                                ; Clear MCE to initiate calibration
nop

Wait_cal:
in     TEMP0, CS4231_R1
nop
cpl    #80h, TEMP0
bcnd   Wait_cal, TC

lacl    #I11
sac1    TEMP0
out     TEMP0, CS4231_R0
                                ; Wait until the device is
Notdone:                                ; finished calibrating.
in     TEMP0, CS4231_R1
nop
bit     TEMP0, BIT5          ; This bit indicates the
                                ; status of calibration.
bcnd   Notdone, TC
ret
```



Mode 2 - Interrupt Driven Digital Loopback

This code initializes the codec in DMA simultaneous capture/playback mode with appropriate inputs and gains and then uses mode 2 - Interrupt Driven to do the digital loopback one sample at a time. Again the DSP is doing the moving based on interrupts from the codec based on PDRQ/CDRQ. Also the DSP must manually toggle -CDAK/-PDAK lines.

* This uses DMA mode - Interrupt PDRQ

```
.mmregs
.sect "vectors"

B start      ;00; RESET
INT1         B pc_isr      ;02; vectors for interrupts int1-int3
INT2         B codec_isr
INT3         B INT3
             .space 2 * 16 ;08; timer interrupt vector - TINT
receive B    receive      ;0A; Serial port receive interrupt
             ; RINT
transmit B   transmit     ;0C; Serial port transmit interrupt
             ; XINT
             .space 4 * 16 ;0E; vectors for TDM port TRNT,
             ; TXNT
             .space 2 * 16 ;12; vector for external interrupt
             ; INT4
             .space 14 * 16 ;14; Reserved space. Should
             ; not be used.
             .space 2 * 16 ;22; Trap instruction vector
             .space 2 * 16 ;24; Non Maskable Interrupt
             ; vector
             .space 4 * 16 ;26; Reserved space. Should
             ; not be used.

.text
start:
LDP #0
LACC #0000h      ; Reset codec
SACL 61h
OUT 61h, 53h
RPT #0f000h     ; Wait
NOP
LACC #0c800h    ; Take out of reset & -CDAK/-PDAK high
SACL 61h
OUT 61h, 53h
RPT #0f000h     ; Wait a while longer (Dag)
NOP
stuck:
IN 61h, 58h     ; Checking for 80h
LACL 61h
AND #0080h
BCND stuck, NEQ
```



```
LACC #0009h    ; Flip MCE bit=1 and Register 9
SACL 61h
OUT 61h, 58h
LACC #0008h    ; Switch to DMA Dual Channel Mode
SACL 61h
OUT 61h, 59h

LACC #000bh    ; Flip MCE bit=0 and Register 11
SACL 61h
OUT 61h, 58h

stuck1:       IN 61h, 58h    ; Checking for 80h
LACL 61h
AND #0080h
BCND stuck1, NEQ

stuck2:       IN 61h, 58h    ; Checking for 20h on register 11
LACL 61h
AND #0020h
BCND stuck2, NEQ

LACC #0009h    ; Set to register 9
SACL 61h
OUT 61h, 58h
LACC #000bh    ; Enable any playback/capture
SACL 61h
OUT 61h, 59h

LACC #0000h    ; Set to Left Input Register
SACL 61h
OUT 61h, 58h
LACC #0000h    ; Write to Left Input Register
;Making this 7h sounds better, but codec cuts out!
SACL 61h
OUT 61h, 59h
LACC #0006h    ; Set to Left Output Register
SACL 61h
OUT 61h, 58h
LACC #0000h    ; Write to Left Output Register
SACL 61h
OUT 61h, 59h

lacc #08000h   ; set up circular buffer pointers
sac1 CBSR1    ; buffer1 = 8000 -> ffff
lacc #08000h
sac1 CBSR2
lacc #0800fh   ; buffer2 = ffff -> 8000
sac1 CBER1
lacc #0800fh   ; buffer2 = ffff -> 8000
sac1 CBER2
lar AR6,#08000h ; set receive buffer
lar AR7,#08000h ; set transmit buffer
```



```

        lacc #0000000011111110b ; buf1=AR7, buf2=AR6,
                                ; enable both
        sacl CBCR ;
; Set up block registers
        LACC #8000h ; ARR Value
        SACL 61h
        OUT 61h, 5Ch ; Write
        LACC #08010h ; BKR Value
        SACL 61h
        OUT 61h, 5Dh ; Write
        LACC #0a000h ; AXR Value
        SACL 61h
        OUT 61h, 5Eh ; Write
        LACC #0a010h ; BKX Value
        SACL 61h
        OUT 61h, 5Fh ; Write

;Set up DMA and Interrupts
        LACC #0ffffh
        SACL IFR
        LACC #02h ; mask on PC and codec ISR
        SACL IMR
        IN 61h, 51h ; bogus read from DSPRXD
        LACC #080h ; disable BXE and BRE
        SACL 61h
        OUT 61h, 54h
        CLRC INTM

loop:
        NOP
        IN 61h, 51h ; bogus read from DSPRXD
        OUT 61h, 50h ; bogus write to DSPTXD
        NOP
        B loop

loop1:
        MAR *, AR6
        IN 61h, 5ah
        LACL 61h
        AND #20h
        BCND loop1, EQ
loop2:
        IN *, 5bh ; Read data
        IN 61h, 5ah
        LACL 61h
        AND #02h
        BCND loop2, EQ
        OUT *, 5bh ; Write data
;
; RPT #5000 ; Wait
;
        B loop1
;
; playback:
        RPT #5000 ; Wait
        NOP
        OUT *, 5bh ; Write data

```



```

        B      playback

pc_isr:      NOP
             SETC XF
             RPT #100
             NOP
             CLRC XF
             RETE

; This one is for Level2
codec_isr:
             SETC XF
             NOP
             IN   60h, 52h      ; Read PCSR
             LACL 60h
; Need to change these bits, eh!
             AND  #0004h      ; Test CDRQ
             BCND cap_serve, NEQ
ptest:      LACL 60h          ; Test PDRQ
             AND  #0008h
             BCND play_serve, NEQ

isr_done NOP
             CLRC XF
             RETE

cap_serve:
             MAR  *,AR6
             LACC #08800h      ; -CDAK low
             SACL 61h
             OUT  61h, 53h
             IN   61h, 5bh      ; Read Value
             LACL 61h
             SACL *+
             LACC #0c800h      ; -CDAK high
             SACL 61h
             OUT  61h, 53h
             B    ptest

play_serve:
             MAR  *,AR7
             LACC #04800h      ; -PDAK low
             SACL 61h
             OUT  61h, 53h
             LACL *+
             SACL 61h
             OUT  61h, 5bh      ; Play Value
             LACC #0c800h      ; -PDAK high
             SACL 61h
             OUT  61h, 53h
             B    isr_done
```



Mode 3 - Stereo Codec DMA Digital Loopback

This code initializes the codec in DMA simultaneous capture/playback mode with appropriate inputs and gains and then uses mode 3 - Stereo Codec to do the digital loopback one sample at a time. But here the DMA controller is doing the moving based on CDRQ/PDRQ, not the DSP. Capture and playback buffers are set as one and the same (8000h-B000h in DSP data memory). The DSP processes the data based on interrupts from the DMA controller. Also the FSM's in the DMA Controller must toggle the -CDAK/-PDAK lines.

* This uses DMA mode

```
.mmregs
.sect "vectors"

B start      ;00; RESET
INT1         B pc_isr    ;02; vectors for interrupts int1-int3
INT2         B codec_isr
INT3         B INT3
             .space 2 * 16 ;08; timer interrupt vector - TINT
receive B    receive     ;0A; Serial port receive interrupt RINT
transmit B   transmit    ;0C; Serial port transmit interrupt XINT
             .space 4 * 16 ;0E; vectors for TDM port TRNT, TXNT
             .space 2 * 16 ;12; vector for external interrupt
                   ; INT4
             .space 14 * 16 ;14; Reserved space. Should not
                   ; be used.
             .space 2 * 16 ;22; Trap instruction vector
             .space 2 * 16 ;24; Non Maskable Interrupt vector
             .space 4 * 16 ;26; Reserved space. Should not be
                   ; used.

.text
start:
LDP #0
LACC #0c000h      ; Reset codec
SACL 61h
OUT 61h, 53h
RPT #0f000h      ; Wait
NOP
LACC #0c800h      ; Take out of reset
SACL 61h
OUT 61h, 53h
RPT #0f000h      ; Wait a while longer (Dag)
NOP
stuck:
IN 61h, 58h      ; Checking for 80h
LACL 61h
AND #0080h
BCND stuck, NEQ
```



```
LACC #0049h    ; Flip MCE bit=1 and Register 9
SACL 61h
OUT 61h, 58h
LACC #0008h    ; Switch to DMA Dual Channel Mode
SACL 61h
OUT 61h, 59h

LACC #0048h    ; Set to register 8
SACL 61h
OUT 61h, 58h
;
LACC #0040h    ; 16 `bit mono
LACC #0000h    ; 8 `bit mono
SACL 61h
OUT 61h, 59h

LACC #000bh    ; Flip MCE bit=0 and Register 11
SACL 61h
OUT 61h, 58h

stuck1:      IN 61h, 58h ; Checking for 80h
LACL 61h
AND #0080h
BCND stuck1, NEQ

stuck2:      IN 61h, 58h ; Checking for 20h on register 11
LACL 61h
AND #0020h
BCND stuck2, NEQ

LACC #0009h    ; Set to register 9
SACL 61h
OUT 61h, 58h
LACC #000bh    ; Enable any playback/capture
SACL 61h
OUT 61h, 59h

LACC #0000h    ; Set to Left Input Register
SACL 61h
OUT 61h, 58h
LACC #0000h    ; Write to Left Input Register
;Making this 7h sounds better, but codec cuts out!
SACL 61h
OUT 61h, 59h
LACC #0006h    ; Set to Left Output Register
SACL 61h
OUT 61h, 58h
LACC #0000h    ; Write to Left Output Register
SACL 61h
OUT 61h, 59h

lacc #09000h   ; set up circular buffer pointers
sac1 CBSR1    ; buffer1 = 8000 -> ffff
```




```

    sac1    CBSR2                ;
           lacc #0900fh          ; buffer2 = ffff -> 8000
           sac1 CBER1            ;
    sac1    CBER2                ;
           lar  AR6,#09000h      ; set receive buffer
           lar  AR7,#09000h      ; set transmit buffer
           lacc #0000000011101111b ; buf1=AR7, buf2=AR6,
                                   ; enable both

           sac1 CBC
; Set up block registers
    LACC #8000h      ; ARR Value
    SACL 61h
    OUT 61h, 5Ch    ; Write
    LACC #0b000h    ; BKR Value
    SACL 61h
    OUT 61h, 5Dh    ; Write
    LACC #8000h    ; AXR Value
    SACL 61h
    OUT 61h, 5Eh    ; Write
    LACC #0b000h    ; BKX Value
    SACL 61h
    OUT 61h, 5Fh    ; Write

;Set up DMA and Interrupts
    LACC #0ffffh
    SACL IFR
    LACC #03h      ; mask on PC and codec ISR
    SACL IMR
    IN 61h, 51h    ; bogus read from DSPRXD
    LACC #0c4h     ; Enable BXE and BRE
    SACL 61h
    OUT 61h, 54h
    CLRC INTM
;
    SETC INTM

loop:
    NOP
    IN 61h, 51h    ; bogus read from DSPRXD
    OUT 61h, 50h   ; bogus write to DSPTXD
    NOP
    B loop

loop1:
    MAR *, AR6
    IN 61h, 5ah
    LACL 61h
    AND #20h
    BCND loop1, EQ
    IN *, 5bh      ; Read data
loop2:
    IN 61h, 5ah
    LACL 61h
    AND #02h
    BCND loop2, EQ
    OUT *+, 5bh    ; Write data

```



```
;          RPT  #5000          ; Wait
;          NOP
;          B    loop1
playback:
          RPT  #5000          ; Wait
          NOP
          OUT  *+, 5bh        ; Write data
          B    playback

pc_isr:  NOP

          SETC XF
          RPT  #100
          NOP
          CLRC XF
          RETE

codec_isr:

          SETC XF
          NOP
          IN  60h, 52h ; Read PCSR - Will clear all interrupts!
          LACL 60h
          AND  #0010h        ; Test RHFULL
          BCND cap_serve, NEQ
ptest:   LACL 60h            ; Test XHFULL
          AND  #0020h
          BCND play_serve, NEQ

isr_done NOP

          CLRC XF
          RETE

cap_serve:

          LACL 60h            ; Test which half DMA is cap
          AND  #0040h
          BCND dmachigh, NEQ
dmaclow  NOP                ; Process high
          MAR  *,AR6
          RPT  #0eh
          BLDD #8000h, *+
          B    isr_done
dmachigh NOP                ;Process low
          MAR  *,AR6
          RPT  #0eh
          BLDD #8000h, *+
          B    isr_done

play_serve:

          LACL 60h            ; Test which half DMA is play
          AND  #0080h
          BCND dmaphigh, NEQ
dmaplow  NOP                ; Process high
          MAR  *,AR7
          RPT  #0eh
```



```

                                BLDD  *, #8010h
                                B      isr_done
dmaphigh                       NOP                    ;Process low
                                MAR    *, AR7
                                RPT    #0eh
                                BLDD  *, #8010h
                                B      isr_done

```

Mode 3 - Stereo Codec DMA Digital Loopback with Intermediate Buffer and Interrupts

This code is graphically represented in Figure 5. It initializes the codec in DMA simultaneous capture/playback mode with appropriate inputs and gains and then uses mode 3 - Stereo Codec to do the digital loopback one sample at a time. Again the DMA controller is doing the moving based on CDRQ/PDRQ, not the DSP. The DSP processes the data based on interrupts from the DMA controller. But as an added twist, the capture/play buffers are different now (8000h-8010h and A000h-A0010h, respectively) and there is an intermediate buffer (9000h-9010h) and the DSP ISR's move the data to and from it. Also the FSM's in the DMA Controller must toggle -CDAK/-PDAK lines.

DMA Cap Play

* This uses DMA mode

```

                                .mmregs
                                .sect "vectors"

                                B start      ;00; RESET
INT1                            B pc_isr    ;02; vectors for interrupts int1-int3
INT2                            B codec_isr
INT3                            B INT3

                                .space 2 * 16 ;08; timer interrupt vector - TINT
receive B                       receive    ;0A; Serial port receive interrupt RINT
transmit B                      transmit   ;0C; Serial port transmit interrupt XINT
                                .space 4 * 16 ;0E; vectors for TDM port
                                ; TRNT, TXNT

                                .space 2 * 16 ;12; vector for external
                                ; interrupt INT4

                                .space 14 * 16 ;14; Reserved space. Should
                                ; not be used.

                                .space 2 * 16 ;22; Trap instruction vector
                                .space 2 * 16 ;24; Non Maskable Interrupt
                                ; vector

                                .space 4 * 16 ;26; Reserved space. Should
                                ; not be used.

                                .text
start:                          LDP #0
                                LACC #0C000h ; Reset codec

```



```

        SACL 61h
        OUT 61h, 53h
        RPT #0f000h      ; Wait
        NOP
        LACC #0C800h     ; Take out of reset
        SACL 61h
        OUT 61h, 53h
        RPT #0f000h     ; Wait a while longer (Dag)
        NOP
stuck:  IN 61h, 58h     ; Checking for 80h
        LACL 61h
        AND #0080h
        BCND stuck, NEQ

        LACC #0049h     ; Flip MCE bit=1 and Register 9
        SACL 61h
        OUT 61h, 58h
        LACC #0008h     ; Switch to DMA Dual Channel Mode
        SACL 61h
        OUT 61h, 59h

        LACC #0048h     ; Set to register 8
        SACL 61h
        OUT 61h, 58h   ; works better with 8
;      LACC #0040h     ; 16 `bit mono
;      LACC #0000h     ; 8 `bit mono
        SACL 61h
        OUT 61h, 59h

        LACC #000bh     ; Flip MCE bit=0 and Register 11
        SACL 61h
        OUT 61h, 58h

stuck1: IN 61h, 58h     ; Checking for 80h
        LACL 61h
        AND #0080h
        BCND stuck1, NEQ

stuck2: IN 61h, 58h     ; Checking for 20h on register 11
        LACL 61h
        AND #0020h
        BCND stuck2, NEQ

        LACC #0009h     ; Set to register 9
        SACL 61h
        OUT 61h, 58h
        LACC #000bh     ; Enable any playback/capture
        SACL 61h
        OUT 61h, 59h

        LACC #0000h     ; Set to Left Input Register
        SACL 61h
```



```

        OUT  61h, 58h
        LACC #0000h      ; Write to Left Input Register
;Making this 7h sounds better, but codec cuts out!
        SACL 61h
        OUT  61h, 59h
        LACC #0006h      ; Set to Left Output Register
        SACL 61h
        OUT  61h, 58h
        LACC #0000h      ; Write to Left Output Register
        SACL 61h
        OUT  61h, 59h

        lacc #09000h     ; set up circular buffer pointers
        sacl CBSR1       ; buffer1 = 8000 -> ffff
        lacc #0a000h
sacl   CBSR2            ;
        lacc #0900fh     ; buffer2 = ffff -> 8000
        sacl CBER1      ;
        lacc #0a00fh     ; buffer2 = ffff -> 8000
sacl   CBER2            ;
        lar  AR6,#09000h ; set receive buffer
        lar  AR7,#0a000h ; set transmit buffer
        lacc #0000000011111110b
                                ; buf1=AR7, buf2=AR6, enable both
        sacl CBCR       ;

; Set up block registers
        LACC #8000h     ; ARR Value
        SACL 61h
        OUT  61h, 5Ch   ; Write
        LACC #08010h   ; BKR Value
        SACL 61h
        OUT  61h, 5Dh   ; Write
        LACC #0a000h   ; AXR Value
        SACL 61h
        OUT  61h, 5Eh   ; Write
        LACC #0a010h   ; BKX Value
        SACL 61h
        OUT  61h, 5Fh   ; Write

;Set up DMA and Interrupts
        LACC #0ffffh
        SACL IFR
        LACC #02h      ; mask on PC and codec ISR
        SACL IMR
        IN   61h, 51h   ; bogus read from DSPRXD
        LACC #0c4h     ; Enable BXE and BRE
        SACL 61h
        OUT  61h, 54h
        CLRC INTM

loop:   NOP
        IN   61h, 51h   ; bogus read from DSPRXD

```



```

        OUT  61h, 50h      ; bogus write to DSPTXD
        IN   61h, 5ch      ; bogus read from DSPRXD
        IN   61h, 5dh      ; bogus read from DSPRXD
        IN   61h, 5eh      ; bogus read from DSPRXD
        IN   61h, 5fh      ; bogus read from DSPRXD
        NOP
        B    loop

loop1:   MAR  *, AR6
        IN   61h, 5ah
        LACL 61h
        AND  #20h
        BCND loop1, EQ
loop2:   IN   *, 5bh       ; Read data
        IN   61h, 5ah
        LACL 61h
        AND  #02h
        BCND loop2, EQ
        OUT  *+, 5bh      ; Write data
;       RPT  #5000       ; Wait
;       NOP
        B    loop1

playback:
        RPT  #5000       ; Wait
        NOP
        OUT  *+, 5bh      ; Write data
        B    playback

pc_isr: NOP

        SETC XF
        RPT  #100
        NOP
        CLRC XF
        RETE

codec_isr:

        SETC XF
        NOP
        IN  60h, 52h ; Read PCSR - Will clear all interrupts!
        LACL 60h
        AND  #0010h   ; Test RHFULL
        BCND cap_serve, NEQ
ptest:  LACL 60h     ; Test XHFULL
        AND  #0020h
        BCND play_serve, NEQ

isr_done NOP

        CLRC XF
        RETE

cap_serve:

        LACL 60h          ; Test which half DMA is cap
```



```

                                AND    #0040h
                                BCND   dmachigh, NEQ
dmaclow                        NOP                    ; Process high
                                MAR    *,AR6
                                RPT    #07h
                                BLDD   #8000h, *+
                                IN     61h, 5ch        ; Bogus Read
                                B      ptest
dmachigh                       NOP                    ;Process low
                                MAR    *,AR6
                                RPT    #07h
                                BLDD   #8008h, *+
                                IN     61h, 5ch        ; Bogus Read
                                B      ptest

play_serve:
                                LACL   60h            ; Test which half DMA is play
                                AND    #0080h
;Why?
dmalow                        BCND   dmaphigh,  NEQ
                                NOP                    ; Process high
                                MAR    *,AR7
                                RPT    #07h
                                BLDD   #9000h, *+
                                IN     61h, 5eh        ; Bogus Read
                                B      isr_done
dmaphigh                       NOP                    ;Process low
                                MAR    *,AR7
                                RPT    #07h
                                BLDD   #9008h, *+
                                IN     61h, 5eh        ; Bogus Read
                                B      isr_done

```

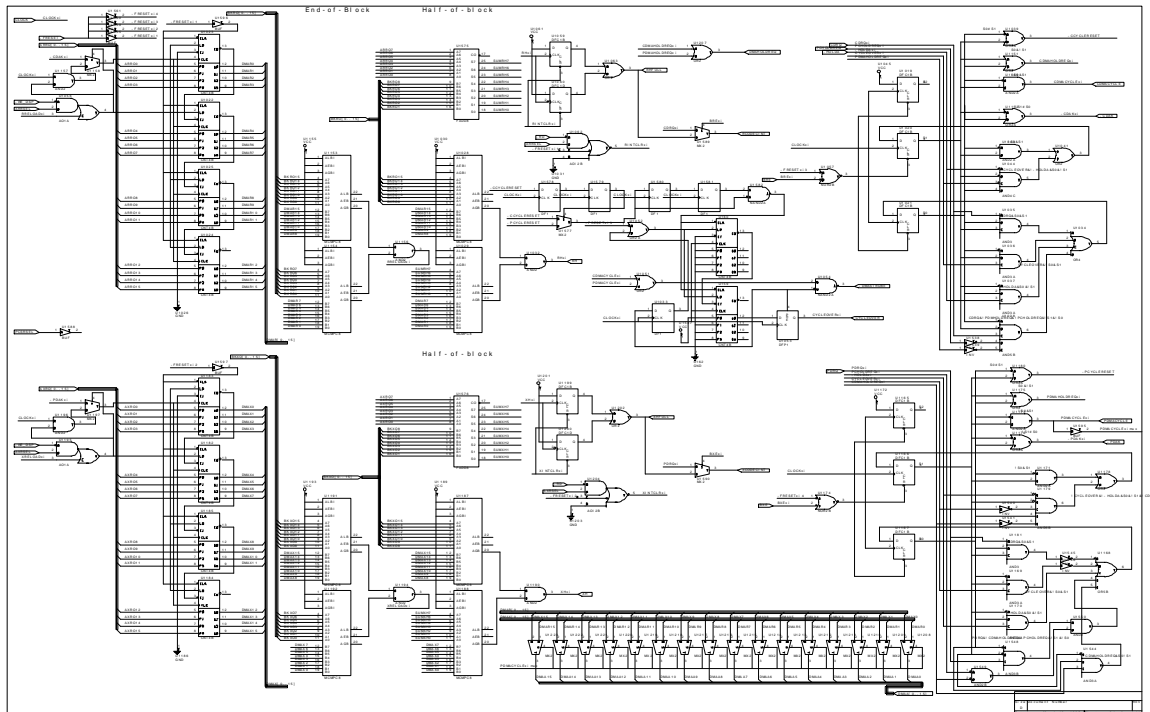
Appendix B - Stereo Codec DMA Structure

This Appendix addresses some specifics about the external DMA Controller that copies data between codec and external memory.

Stereo Codec DMA Schematic

Figure 11 displays the main schematic for the DMA controller. The top half is the capture section while the bottom is playback. All the way in the top left corner are the address generator counters. Farther to the right are the RH adders and comparators along with interrupt generators. Then all the way in the right top corner (with the 3 flip-flops) is the capture FSM. Right in the middle is the beginning of the waveform generators (continued in another sheet not shown here) that is a counter that executes the codec read and write cycles. Finally, tucked into the bottom left, are multiplexors going to the 'C51 address bus. For much more detail see [9].

Figure 11. DMA Controller for Parallel Codec





Stereo Codec DMA FSM's

The following two ABEL files describe the FSM's used for capture and play respectively. Note that capture was given higher priority.

```

module FSM_maker

    U5      device      'P22V10';

    "inputs
    CLK          Pin 1;
    CDRQ         Pin 2;
    PCHOLDREQ   Pin 3;
    HOLDA_      Pin 4;
    CYCLEOVER   Pin 5;
    PDMAHOLDREQ Pin 6;

    "outputs
    CDMAHOLDREQ Pin 23;
    CDMACYCLE   Pin 22;
    CDAK_       Pin 21;
    CCYCLERESET_ Pin 20;
    S0          Pin 19;
    S1          Pin 18;

    FSM         = [S1, S0];

    "states

    idle        = ^b000;
    reqbus      = ^b001;
    cycle       = ^b010;
    dmafork     = ^b011;

state_diagram FSM

state idle:
    CDMAHOLDREQ =0;
    CDMACYCLE   =0;
    CDAK_       =1;
    CCYCLERESET_ =1;
    if [(PCHOLDREQ==0) & (CDRQ==1) & (PDMAHOLDREQ==0)] then reqbus
    else
        idle;

state reqbus:
    CDMAHOLDREQ =1;
    CDMACYCLE   =0;
    CDAK_       =1;
    CCYCLERESET_ =0;
    if [(CYCLEOVER==0) & (HOLDA_==0)] then cycle
    else
        reqbus;

state cycle:

```



```
    CDMAHOLDREQ  =1;
    CDMACYCLE    =1;
    CDAK_        =0;
    CCYCLERESET_ =1;
    if (CYCLEOVER==1) then dmafork
    else          cycle;

state dmafork:
    CDMAHOLDREQ=1;
    CDMACYCLE  =0;
    CDAK_      =1;
    CCYCLERESET_ =1;
    if (CDRQ==1) then reqbus
    else          idle;

end FSM_maker
```

```
module FSM_maker

    U5      device      'P22V10';

    "inputs
    CLK          Pin 1;
    PDRQ         Pin 2;
    PCHOLDREQ    Pin 3;
    HOLDA_       Pin 4;
    CYCLEOVER    Pin 5;
    CDMAHOLDREQ  Pin 6;

    "outputs
    PDMAHOLDREQ  Pin 23;
    PDMACYCLE    Pin 22;
    PDAK_        Pin 21;
    PCYCLERESET_ Pin 20;
    S0           Pin 19;
    S1           Pin 18;

    FSM          = [S1, S0];

    "states

    idle         = ^b000;
    reqbus       = ^b001;
    cycle        = ^b010;
    dmafork      = ^b011;

state_diagram FSM

state idle:
```



```
    PDMAHOLDREQ  =0;
    PDMACYCLE    =0;
    PDAK_        =1;
    PCYCLERESET_ =1;
    if [(PCHOLDREQ==0) & (PDRQ==1) & (CDMAHOLDREQ==0)] then
    reqbus
    else
        idle;

state reqbus:
    PDMAHOLDREQ  =1;
    PDMACYCLE    =0;
    PDAK_        =1;
    PCYCLERESET_ =0;
    if [(CYCLEOVER==0) & (HOLDA_==0) & (CDMAHOLDREQ==0)] then cycle
    else
        reqbus;

state cycle:
    PDMAHOLDREQ  =1;
    PDMACYCLE    =1;
    PDAK_        =0;
    PCYCLERESET_ =1;
    if (CYCLEOVER==1) then dmafork
    else
        cycle;

state dmafork:
    PDMAHOLDREQ  =1;
    PDMACYCLE    =0;
    PDAK_        =1;
    PCYCLERESET_ =1;
    if (PDRQ==1) then reqbus
    else
        idle;

end FSM_maker
```