

ADC32RF52 デュアル・チャネル、14 ビット、1.5GSPS、RF サンプリング・データ・コンバータ

1 特長

- 14 ビット、デュアル・チャネル 1.5GSPS ADC
- ノイズ・スペクトル密度:
 - NSD = -153dBFS/Hz (AVG なし)
 - NSD = -156dBFS/Hz (2x AVG)
 - NSD = -159dBFS/Hz (4x AVG)
- シングル・コア (非インターリーブ) ADC アーキテクチャ
- アパーチャ・ジッタ: 50fs
- 低いクローズイン残留位相ノイズ:
 - 133dBc/Hz (10kHz オフセット時)
- スペクトラム性能 ($f_{IN} = 900\text{MHz}$ 、-4dBFS 時):
 - 2 倍の内部平均化
 - SNR: 66.8dBFS
 - SFDR HD2, 3: 74dBc
 - SFDR の最大スプリアス: 90dBFS
- 入力フルスケール: 1.0/1.1Vpp (1/1.8dBm)
- コード・エラー・レート (CER): 10^{-15}
- フルパワー入力帯域幅 (-3dB): 1.6GHz
- JESD204B シリアル・データ・インターフェイス
 - 最大レーン速度: 13Gbps
 - サブクラス 1 の確定的レイテンシをサポート
- デジタル・ダウンコンバータ
 - ADC チャンネルごとに最大 4 つの DDC
 - 複雑な出力: 4 倍、16 倍～128 倍のデシメーション (間引き)
 - 48 ビット NCO による位相コヒーレント周波数ホッピング
 - 高速周波数ホッピング: 1us 未満
- 消費電力: 1.8W/チャネル (2x AVG)
- 電源: 1.8V、1.2V

2 アプリケーション

- フェーズド・アレイ・レーダー
- スペクトル・アナライザ
- ソフトウェア無線 (SDR)
- 電子戦
- 高速デジタイザ
- ケーブル・インフラストラクチャ
- 通信インフラ

3 概要

ADC32RF52 は、シングル・コアの 14 ビット、1.5GSPS、デュアル・チャネル A/D コンバータ (ADC) であり、最大 2 GHz の入力周波数での RF サンプリングをサポートします。このデザインは、信号対雑音比 (SNR) を最大化し、-153dBFS/Hz のノイズ・スペクトル密度を実現します。追加の内蔵 ADC をオンチップ信号平均化と共に使用すると、ノイズ密度は -156dBFS/Hz (2x AVG) および -159dBFS/Hz (4x AVG) に向上します。

各 ADC チャンネルは、位相コヒーレント周波数ホッピングをサポートする 48 ビット NCO を使用する、クワッド・バンドのデジタル・ダウンコンバータ (DDC) に接続できます。NCO 周波数制御に GPIO ピンを使用すると、1μs 未満で周波数ホッピングを実現できます。

ADC32RF52 は、サブクラス 1 の確定的レイテンシを持つ JESD204B シリアル・データ・インターフェイスをサポートし、最大 13Gbps のデータ・レートを使用します。

電力効率の優れた ADC アーキテクチャは、1.5Gsp/s で 1.4W/ch の消費電力を実現し、低サンプリング・レートで電力スケールングを実現します。

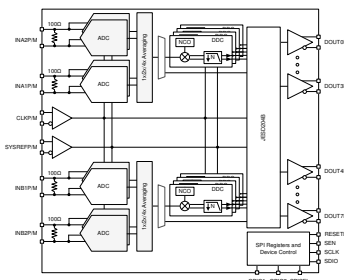
パッケージ情報

部品番号	パッケージ (1)	パッケージ・サイズ (2)
ADC32RF52	QFN (64)	9mm×9mm

- 利用可能なすべてのパッケージについては、データシートの末尾にあるパッケージ・オプションについての付録を参照してください。
- パッケージ・サイズ (長さ×幅) は公称値であり、該当する場合はピンも含まれます。

表 3-1. デバイスの比較

部品番号	サンプリング・レート
ADC32RF55	3GSPS
ADC32RF54	2.6GSPS
ADC32RF52	1.5GSPS



ブロック図



Table of Contents

1 特長	1	7.2 機能ブロック図.....	26
2 アプリケーション	1	7.3 Feature Description.....	27
3 概要	1	7.4 Device Functional Modes.....	64
4 Revision History	2	7.5 Programming.....	65
5 Pin Configuration and Functions	3	7.6 Register Maps.....	67
6 Specifications	6	8 Application and Implementation	92
6.1 Absolute Maximum Ratings.....	6	8.1 Application Information.....	92
6.2 ESD Ratings.....	6	8.2 Typical Applications.....	92
6.3 Recommended Operating Conditions.....	6	8.3 Initialization Set Up.....	95
6.4 Thermal Information.....	7	8.4 Power Supply Recommendations.....	105
6.5 Electrical Characteristics - Power Consumption.....	7	8.5 Layout.....	106
6.6 Electrical Characteristics - DC Specifications.....	8	9 Device and Documentation Support	109
6.7 Electrical Characteristics - AC Specifications (Dither DISABLED).....	10	9.1 ドキュメントの更新通知を受け取る方法.....	109
6.8 Electrical Characteristics - AC Specifications (Dither ENABLED).....	12	9.2 サポート・リソース.....	109
6.9 Timing Requirements.....	14	9.3 Trademarks.....	109
6.10 Typical Characteristics.....	16	9.4 静電気放電に関する注意事項.....	109
7 Detailed Description	26	9.5 用語集.....	109
7.1 Overview.....	26	10 Mechanical, Packaging, and Orderable Information	109

4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

DATE	REVISION	NOTES
September 2023	*	Initial Release

5 Pin Configuration and Functions

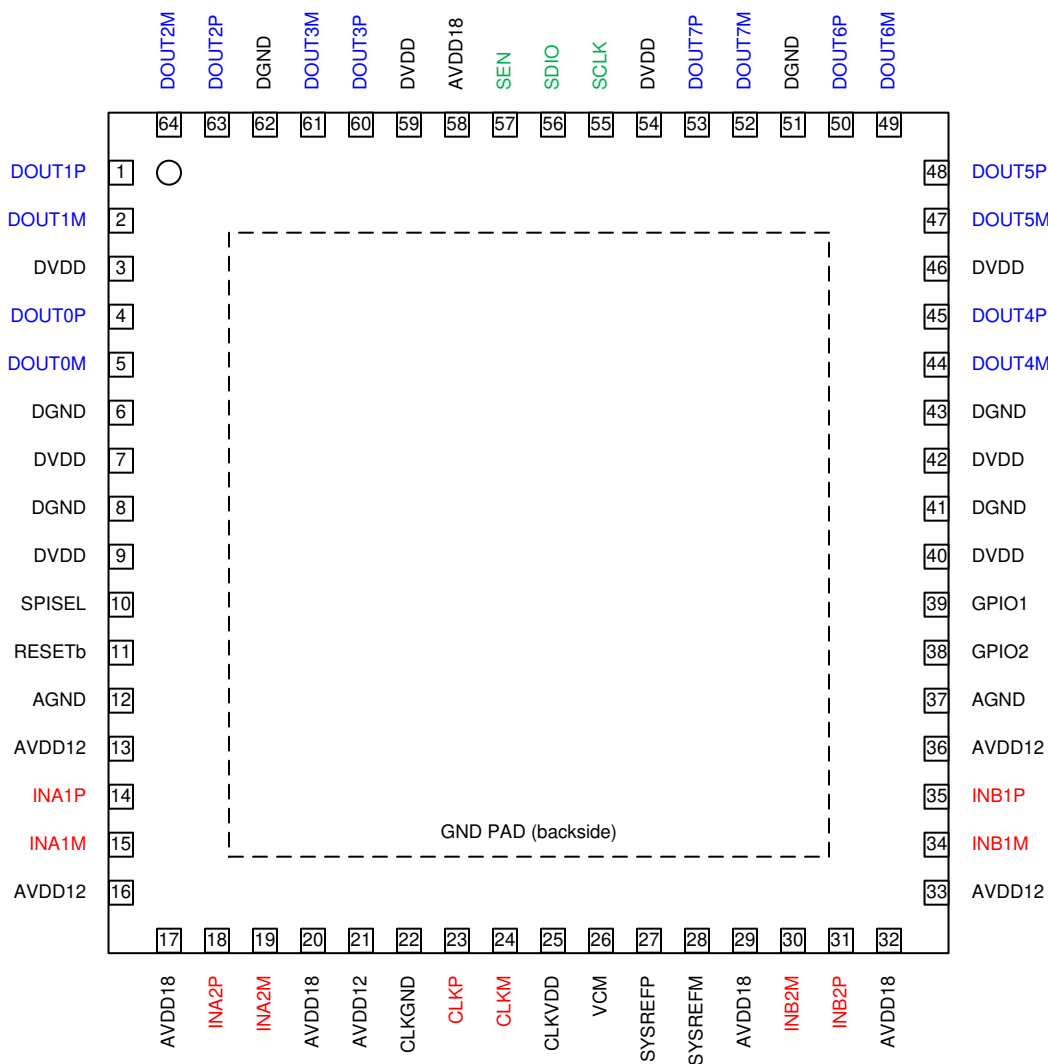


**図 5-1. RTD (VQFN) Package, 64 Pin
(Top View)**

表 5-1. Pin Functions

PIN		TYPE	DESCRIPTION
NAME	NO.		
Analog Inputs			
INA1P	14	I	Differential analog input for channel A. 100 Ω (default) or 50 Ω differential internal termination.
INA1M	15		
INA2P	18	I	Differential analog input for alternate channel A input. This input is used for additional ADC averaging for channel A. 100 Ω (default) or 50 Ω differential internal termination. Should be connected to GND if unused.
INA2M	19		
INB1P	35	I	Differential analog input for channel B. 100 Ω (default) or 50 Ω differential internal termination.
INB1M	34		

表 5-1. Pin Functions (続き)

PIN		TYPE	DESCRIPTION
NAME	NO.		
INB2P	31	I	Differential analog input for alternate channel B input. This input is used for additional ADC averaging for channel B. 100 Ω (default) or 50 Ω differential internal termination. Should be connected to GND if unused.
INB2M	30		
VCM	26	O	Common-mode voltage output for the analog inputs.
Clock, Synchronization			
CLKP	23	I	Differential sampling clock input. 100 Ω differential internal termination.
CLKM	24		
SYSREFP	27	I	Differential external synchronization input.
SYSREFM	28		
Control			
RESETb	11	I	Hardware reset. Active low. This pin has an internal 21 kΩ pullup resistor to AVDD18.
SEN	57	I	Serial interface enable. Active low. This pin has an internal 21 kΩ pull-up resistor to AVDD18.
SCLK	55	I	Serial interface clock input. This pin has an internal 21 kΩ pull-down resistor.
SDIO	56	I/O	Serial interface data input and output. This pin has an internal 21 kΩ pull-down resistor.
GPIO1	39	I	GPIO control pin. This pin is configured through SPI interface for power down or NCO control function.
GPIO2	38	I	GPIO control pin. This pin is configured through SPI interface for power down or NCO control function.
SPISEL	10	I	Determines SPI control: either normal SPI for register writes or fast access to NCO selection only for fast frequency hopping.
Digital Data Interface			
DOUT0P	4	O	JESD204B high-speed serial data output interface pins for channel A.
DOUT0M	5		
DOUT1P	1		
DOUT1M	2		
DOUT2P	63		
DOUT2M	64		
DOUT3P	60		
DOUT3M	61		
DOUT4P	45	O	JESD204B high-speed serial data output interface pins for channel B.
DOUT4M	44		
DOUT5P	48		
DOUT5M	47		
DOUT6P	50		
DOUT6M	49		
DOUT7P	53		
DOUT7M	52		
Power Supply			
AVDD18	17,20,29,32, 58	I	Analog 1.8-V power supply
AVDD12	13,16,21,33, 36	I	Analog 1.2-V power supply
CLKVDD	25	I	Clock 1.2-V power supply. Very sensitive to power supply noise. Directly impacts close in aperture phase noise.
DVDD	3,7,9,40,42, 46,54,59	I	Digital 1.2-V power supply
AGND	12,37	I	Analog ground, shorted to thermal pad.
CLKGND	22	I	Clock ground.

表 5-1. Pin Functions (続き)

PIN		TYPE	DESCRIPTION
NAME	NO.		
DGND	6,8,41,43,51,62	I	Digital ground.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
Supply voltage range, AVDD18		−0.3	2.1	V
Supply voltage range, AVDD12/CLKVDD/DVDD		−0.3	1.4	V
Voltage applied to input pins	INA1P/M, INB1P/M, INA2P/M, INB2P/M	−0.6	1.2	V
	CLKP/M	−0.3	VDDCLK + 0.3	
	SYSREFP/M	−0.3	AVDD12 + 0.6	
	GPIO1/2, PDN, RESET, SCLK, SEN, SDIO, SPISEL	−0.3	AVDD18 + 0.2	
Peak RF input power (INx1P/M, INx2P/M)	Differential 100 Ω termination.		12	dBm
Junction temperature, T _J			125	°C
Storage temperature, T _{stg}		−65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	± 1000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 ⁽²⁾	± 500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
AVDD18	1.8 V analog supply		1.75	1.8	1.85	V
AVDD12	1.2 V analog supply		1.15	1.2	1.225	
CLKVDD	1.2 V clock supply		1.175	1.2	1.225	
DVDD	1.2 V digital supply		1.15	1.2	1.225	
T _A	Operating free-air temperature		−40		85	°C
T _J	Operating junction temperature				105 ⁽¹⁾	°C

- (1) Prolonged use above this junction temperature may increase the device failure-in-time (FIT) rate.

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		ADC32RF52	UNIT
		RTD (QFN)	
		64 Pins	
R _{ΘJA}	Junction-to-ambient thermal resistance	20.1	°C/W
R _{ΘJC(top)}	Junction-to-case (top) thermal resistance	6.8	°C/W
R _{ΘJB}	Junction-to-board thermal resistance	5.2	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	0.1	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	5.1	°C/W
R _{ΘJC(bot)}	Junction-to-case (bottom) thermal resistance	0.5	°C/W

(1) For more information about thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, SPRA953.

6.5 Electrical Characteristics - Power Consumption

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V and –1-dBFS differential input, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
FS = 1.5 GSPS						
I _{AVDD18}	Supply current, 1.8 V analog supply	Bypass mode, LMFS = 8224		240		mA
I _{AVDD12}	Supply current, 1.2 V analog supply			700		
I _{CLKVDD}	Supply current, 1.2 V clock supply			100		
I _{DVDD}	Supply current, 1.2 V digital supply			1200		
P _{DIS}	Power dissipation			2.8		W
I _{AVDD18}	Supply current, 1.8 V analog supply	2x averaging, LMFS = 8224		320		mA
I _{AVDD12}	Supply current, 1.2 V analog supply			900		
I _{CLKVDD}	Supply current, 1.2 V clock supply			100		
I _{DVDD}	Supply current, 1.2 V digital supply			1400		
P _{DIS}	Power dissipation			3.55		W
I _{AVDD18}	Supply current, 1.8 V analog supply	4x averaging, LMFS = 8224		500	600	mA
I _{AVDD12}	Supply current, 1.2 V analog supply			1300	1700	
I _{CLKVDD}	Supply current, 1.2 V clock supply			120	150	
I _{DVDD}	Supply current, 1.2 V digital supply			1800	2900	
P _{DIS}	Power dissipation			4.85		W
POWER DOWN MODES						
P _{DIS}	Power down mode power consumption			190		mW

6.6 Electrical Characteristics - DC Specifications

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V and –1-dBFS differential input, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
DC ACCURACY							
DNL	Differential nonlinearity	F _{IN} = 10 MHz	±1			LSB	
INL	Integral nonlinearity	F _{IN} = 10 MHz	±8			LSB	
V _{OS_ERR}	Offset error		±0.2			%FSR	
GAIN _{ERR}	Gain error		±0.2			%FSR	
GAIN _{Match}	Gain matching across channels		±0.2			dB	
ADC ANALOG INPUTS (INA1P/M, INB1P/M, INA2P/M, INB2P/M)							
FS	Input full scale (differential)	1x or 2x AVG, RSW = 0	0.95			V _{pp}	
		1x AVG, RSW = 1	1.0				
		2x AVG, RSW = 1	1.1				
V _{ICM}	Input common model voltage		250	350	450	mV	
Z _{IN}	Differential input impedance	Differential at 100 MHz	100			Ω	
V _{OCM}	Output common mode voltage		350			mV	
BW	Analog Input Bandwidth (-3 dB)	No averaging, RSW = 1	1.6			GHz	
		2x or 4x averaging, RSW = 1	1.5				
Phase imbalance, analog input			±2			deg	
Amplitude imabalance, analog input			±0.5			dB	
CLOCK INPUT (CLKP/M)							
Input clock frequency			500		1500	MHz	
V _{ID}	Differential input voltage		1			2.4	V _{pp}
V _{ICM}	Input common mode voltage		0.65	0.75	0.85	V	
Z _{IN}	Differential input impedance	Differential at 2.6 GHz	100			Ω	
Clock duty cycle			45	50	55	%	
SYSREF INPUT (SYSREFP/M)							
V _{ID}	Differential input voltage		600	800	1000	mV _{pp}	
V _{ICM}	Input common mode voltage	Input common mode voltage	1.05	1.2	1.4	V	
Z _{IN}	Differential input impedance		100			Ω	
DIGITAL INPUTS (RESET, PDN, SCLK, SEN, SDIO, GPIO1/2, SPISEL)							
V _{IH}	High-level input voltage		0.8			V	
V _{IL}	Low-level input voltage		0.4			V	
C _I	Input capacitance		0.6			pF	
DIGITAL OUTPUT (SDIO)							
V _{OH}	High-level output voltage	I _{LOAD} = -400 uA	AVDD18 – 0.1	AVDD18		V	
V _{OL}	Low-level output voltage	I _{LOAD} = 400 uA	0.1			V	
CML SERDES OUTPUTS: DOUT[0:7]P/M							
V _{OD}	Serdes transmitter output amplitude	differential peak-peak	700			mV _{pp}	
V _{OCM}	Serdes transmitter output common mode		425			mV	
Z _{TX}	Serdes transmitter single ended termination impedance		50			Ω	

6.6 Electrical Characteristics - DC Specifications (続き)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V and –1-dBFS differential input, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Transmitter short-circuit current	Transmitter pins shorted to any voltage between –0.25 V and 1.45 V	–100		100	mA

6.7 Electrical Characteristics - AC Specifications (Dither DISABLED)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V, -1-dBFS differential input and dither DISABLED, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
NSD	Noise Spectral Density	$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ no averaging		-153.2		dBFS/Hz
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 2x averaging		-156.0		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 4x averaging		-158.6		
NF	Noise Figure	$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ no averaging		22.1		dB
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 2x averaging		21.0		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 4x averaging		20.2		
SNR	Signal-to-noise ratio no averaging	$f_{IN} = 100\text{ MHz}$		64.1		dBFS
		$f_{IN} = 600\text{ MHz}$		64.1		
		$f_{IN} = 900\text{ MHz}$	61.5	63.9		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		65.1		
		$f_{IN} = 1.4\text{ GHz}$		63.6		
	Signal-to-noise ratio 2x averaging	$f_{IN} = 100\text{ MHz}$		66.5		
		$f_{IN} = 600\text{ MHz}$		66.6		
		$f_{IN} = 900\text{ MHz}$		66.3		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		67.9		
		$f_{IN} = 1.4\text{ GHz}$		65.9		
	Signal-to-noise ratio 4x averaging	$f_{IN} = 100\text{ MHz}$		69.3		
		$f_{IN} = 600\text{ MHz}$		69.2		
		$f_{IN} = 900\text{ MHz}$		68.5		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		69.9		
		$f_{IN} = 1.4\text{ GHz}$		65.9		
SINAD	Signal to noise and distortion ratio	$f_{IN} = 100\text{ MHz}$		60.6		dBFS
		$f_{IN} = 600\text{ MHz}$		62.2		
		$f_{IN} = 900\text{ MHz}$		62.1		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		62.1		
		$f_{IN} = 1.4\text{ GHz}$		62.0		
ENOB	Effective number of bits	$f_{IN} = 100\text{ MHz}$		10.4		Bits
		$f_{IN} = 600\text{ MHz}$		10.4		
		$f_{IN} = 900\text{ MHz}$		10.3		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		10.5		
		$f_{IN} = 1.4\text{ GHz}$		10.3		
THD	Total Harmonic Distortion (First five harmonics)	$f_{IN} = 100\text{ MHz}$		64		dBc
		$f_{IN} = 600\text{ MHz}$		67		
		$f_{IN} = 900\text{ MHz}$		67		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		65		
		$f_{IN} = 1.4\text{ GHz}$		68		

6.7 Electrical Characteristics - AC Specifications (Dither DISABLED) (続き)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V, -1-dBFS differential input and dither DISABLED, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
HD2	Second Harmonic Distortion	$f_{IN} = 100\text{ MHz}$		72		dBFS
		$f_{IN} = 600\text{ MHz}$		70		
		$f_{IN} = 900\text{ MHz}$		71		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		69		
		$f_{IN} = 1.4\text{ GHz}$		69		
HD3	Third Harmonic Distortion	$f_{IN} = 100\text{ MHz}$		65		dBFS
		$f_{IN} = 600\text{ MHz}$		73		
		$f_{IN} = 900\text{ MHz}$		71		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		70		
		$f_{IN} = 1.4\text{ GHz}$		81		
Non HD2,3	Spur free dynamic range (excluding HD2 and HD3)	$f_{IN} = 100\text{ MHz}$		82		dBFS
		$f_{IN} = 600\text{ MHz}$		83		
		$f_{IN} = 900\text{ MHz}$		83		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		93		
		$f_{IN} = 1.4\text{ GHz}$		81		
IMD3	Two tone inter-modulation distortion	$f_1 = 900\text{ MHz}$, $f_2 = 1000\text{ MHz}$, $A_{IN} = -7\text{ dBFS/tone}$		71		dBc

6.8 Electrical Characteristics - AC Specifications (Dither ENABLED)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V, -4-dBFS differential input and dither ENABLED, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN ⁽²⁾	TYP	MAX	UNIT
NSD ⁽¹⁾	Noise Spectral Density	$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ no averaging		-153.4		dBFS/Hz
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 2x averaging		-156.1		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 4x averaging		-158.7		
NF ⁽¹⁾	Noise Figure	$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ no averaging		22.2		dB
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 2x averaging		20.9		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$ 4x averaging		20.5		
SNR ⁽¹⁾	Signal-to-noise ratio no averaging	$f_{IN} = 100\text{ MHz}$		63.6		dBFS
		$f_{IN} = 600\text{ MHz}$		64.5		
		$f_{IN} = 900\text{ MHz}$	62.0	64.4		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$	62.3	65.2		
		$f_{IN} = 1.4\text{ GHz}$		63.8		
	Signal-to-noise ratio 2x averaging	$f_{IN} = 100\text{ MHz}$		66.3		
		$f_{IN} = 600\text{ MHz}$		66.9		
		$f_{IN} = 900\text{ MHz}$		66.8		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		68.0		
		$f_{IN} = 1.4\text{ GHz}$		66.1		
	Signal-to-noise ratio 4x averaging	$f_{IN} = 100\text{ MHz}$		69.2		
		$f_{IN} = 600\text{ MHz}$		69.1		
		$f_{IN} = 900\text{ MHz}$	67.0	68.8		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$	67.7	69.5		
		$f_{IN} = 1.4\text{ GHz}$		67.0		
SINAD ⁽¹⁾	Signal to noise and distortion ratio	$f_{IN} = 100\text{ MHz}$		62.2		dBFS
		$f_{IN} = 600\text{ MHz}$		63.4		
		$f_{IN} = 900\text{ MHz}$		63.6		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		64.3		
		$f_{IN} = 1.4\text{ GHz}$		62.8		
ENOB ⁽¹⁾	Effective number of bits	$f_{IN} = 100\text{ MHz}$		10.3		Bits
		$f_{IN} = 600\text{ MHz}$		10.4		
		$f_{IN} = 900\text{ MHz}$		10.4		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		10.5		
		$f_{IN} = 1.4\text{ GHz}$		10.3		
THD	Total Harmonic Distortion (First five harmonics)	$f_{IN} = 100\text{ MHz}$		68		dBc
		$f_{IN} = 600\text{ MHz}$		72		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		72		
		$f_{IN} = 900\text{ MHz}$		72		
		$f_{IN} = 1.4\text{ GHz}$		71		

6.8 Electrical Characteristics - AC Specifications (Dither ENABLED) (続き)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, AVDDCLK, DVDD = 1.2 V, -4-dBFS differential input and dither ENABLED, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN ⁽²⁾	TYP	MAX	UNIT
HD2	Second Harmonic Distortion	$f_{IN} = 100\text{ MHz}$		75		dBFS
		$f_{IN} = 600\text{ MHz}$		75		
		$f_{IN} = 900\text{ MHz}$	70	74		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		84		
		$f_{IN} = 1.4\text{ GHz}$		72		
HD3	Third Harmonic Distortion	$f_{IN} = 100\text{ MHz}$		70		dBFS
		$f_{IN} = 600\text{ MHz}$		77		
		$f_{IN} = 900\text{ MHz}$	71	79		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		75		
		$f_{IN} = 1.4\text{ GHz}$		81		
Non HD2,3	Spur free dynamic range (excluding HD2 and HD3)	$f_{IN} = 100\text{ MHz}$		92		dBFS
		$f_{IN} = 600\text{ MHz}$		89		
		$f_{IN} = 900\text{ MHz}$	85	90		
		$f_{IN} = 900\text{ MHz}$, $A_{IN} = -20\text{ dBFS}$		98		
		$f_{IN} = 1.4\text{ GHz}$		94		
IMD3	Two tone inter-modulation distortion	$f_1 = 900\text{ MHz}$, $f_2 = 1000\text{ MHz}$, $A_{IN} = -10\text{ dBFS/ tone}$	74	84		dBFS

(1) Measured from 60 MHz to Nyquist ($F_S/2$) excluding dither

(2) SNR, HD3 minimum values are specified by ATE, HD2 and Non HD23 are specified by bench characterization.

6.9 Timing Requirements

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8V, AVDD12, AVDDCLK, DVDD = 1.2V and –1-dBFS differential input, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC TIMING SPECIFICATIONS						
T_{AD}	Aperture Delay			0.17		ns
	Aperture Delay variation			0.07		ns
T_A	Aperture Jitter			50		fs
Overload recovery time		3-dB overload condition		10		clock cycles
		6-dB overload condition		50		
t_{ADC}	ADC latency from sampling instant to internal hand-off to digital			68		clock cycles
	Internal propagation delay			5		ns
	Latency adder for 2x or 4x averaging			4		clock cycles
	Deterministic delay from digital block (DDC (if used) and JESD interface)	LMFS = 8-2-8-20		260		clock cycles
		LMFS = 8-2-2-4		280		
		4x complex decimation, LMFS = 8-4-2-2		456		
		4x real decimation, LMFS = 4-2-2-2		456		
		4x decimation, F (number of octets) = 2		394		
		4x decimation, F = 4		374		
		4x decimation, F = 8		367		
		8x decimation, F = 2		560		
		8x decimation, F = 4		520		
		8x decimation, F = 8		506		
		8x decimation, F = 16		491		
		16x decimation, F = 2		900		
		16x decimation, F = 4		820		
		16x decimation, F = 8		792		
		16x decimation, F = 16		762		
		16x decimation, F = 32		748		
		32x decimation, F = 2		1596		
		32x decimation, F = 4		1436		
		32x decimation, F = 8		1380		
		32x decimation, F = 16		1320		
		32x decimation, F = 32		1292		
		64x decimation, F = 2		2940		
		64x decimation, F = 4		2620		
		64x decimation, F = 8		2508		
		64x decimation, F = 16		2388		
		64x decimation, F = 32		2332		
		128x decimation, F = 2		5668		
		128x decimation, F = 4		5028		
		128x decimation, F = 8		4804		
		128x decimation, F = 16		4564		
		128x decimation, F = 32		4452		

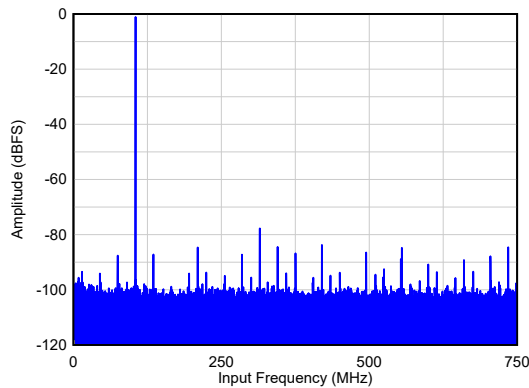
6.9 Timing Requirements (続き)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, Bypass mode, 50% clock duty cycle, AVDD18 = 1.8V, AVDD12, AVDDCLK, DVDD = 1.2V and –1-dBFS differential input, unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SERIAL PROGRAMMING INTERFACE (SCLK, SEN, SDIO) - Input						
f _{CLK(SCLK)}	Serial clock frequency		1		20	MHz
t _{SU(SEN)}	SEN to rising edge of SCLK		10			ns
t _{H(SEN)}	SEN from rising edge of SCLK		10			ns
t _{SU(SDIO)}	SDIO to rising edge of SCLK		10			ns
t _{H(SDIO)}	SDIO from rising edge of SCLK		10			ns
SERIAL PROGRAMMING INTERFACE (SDIO) - Output						
t _(OZD)	SDIO tri-state to driven				10	ns
t _(ODZ)	SDIO data to tri-state				14	ns
t _(OD)	SDIO valid from falling edge of SCLK				10	ns
TIMING: SYSREFP/M						
t _{s(SYSREF)}	Setup time, SYSREFP/M valid to rising edge of CLKP/M		50			ps
t _{h(SYSREF)}	Hold time, SYSREFP/M valid to rising edge of CLKP/M		50			ps
CML SERDES OUTPUTS: DA[0:3]P/M, DB[0:3]P/M						
f _{Serdes}	Serdes bit rate		0.5	12.8	13.0	Gbps
R _J	Random jitter, RMS	RPAT, 6.4 Gbps	0.7			ps
		RPAT, 12.8 Gbps	0.6			
D _J	Deterministic jitter, peak to peak	RPAT, 6.4 Gbps	8.9			ps
		RPAT, 12.8 Gbps	14.7			
T _J	Total jitter, peak to peak	RPAT, 6.4 Gbps	19.5			ps
		RPAT, 12.8 Gbps	24			

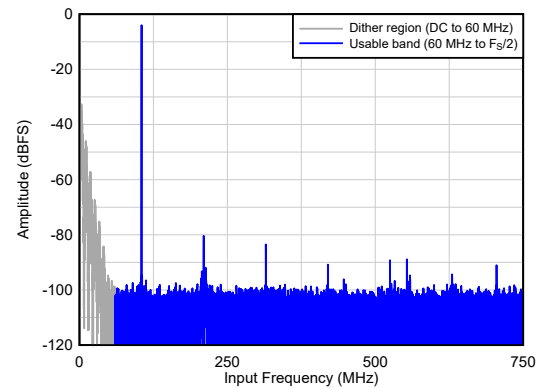
6.10 Typical Characteristics

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1 dBFS differential input, Dither = DIS, unless otherwise noted



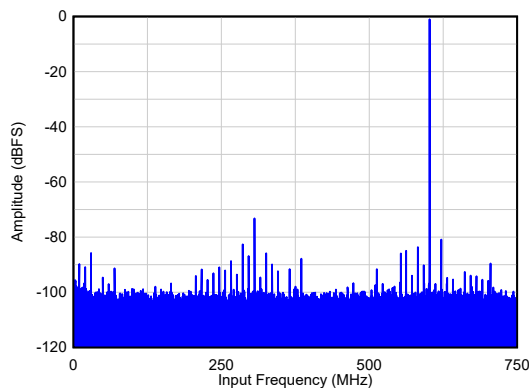
SNR = 64.5 dBFS, HD23 = 77 dBc, Non HD23 = 84 dBFS
 $A_{IN} = -1\text{ dBFS}$, 1x AVG, Dither = DIS

Figure 6-1. Single Tone FFT at $F_{IN} = 100\text{ MHz}$



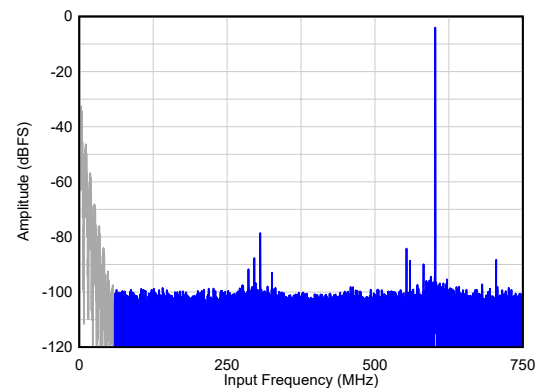
SNR = 64.3 dBFS¹, HD23 = 76 dBc, Non HD23 = 89 dBFS
 $A_{IN} = -4\text{ dBFS}$, 1x AVG, Dither = EN

Figure 6-2. Single Tone FFT at $F_{IN} = 100\text{ MHz}$



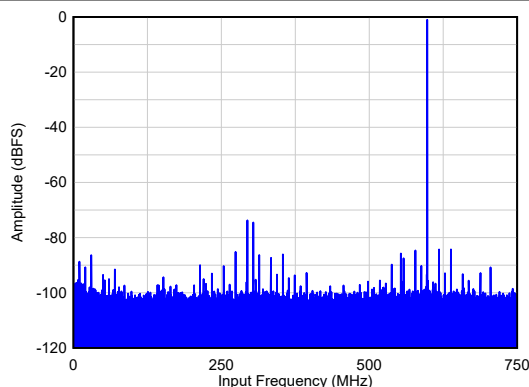
SNR = 64.4 dBFS, HD23 = 72 dBc, Non HD23 = 81 dBFS
 $A_{IN} = -1\text{ dBFS}$, 1x AVG, Dither = DIS

Figure 6-3. Single Tone FFT at $F_{IN} = 600\text{ MHz}$



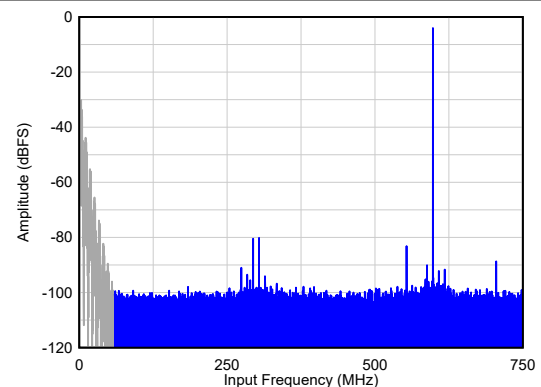
SNR = 64.4 dBFS¹, HD23 = 75 dBc, Non HD23 = 84 dBFS
 $A_{IN} = -4\text{ dBFS}$, 1x AVG, Dither = EN

Figure 6-4. Single Tone FFT at $F_{IN} = 600\text{ MHz}$



SNR = 64.3 dBFS, HD23 = 72 dBc, Non HD23 = 84 dBFS
 $A_{IN} = -1\text{ dBFS}$, 1x AVG, Dither = DIS

Figure 6-5. Single Tone FFT at $F_{IN} = 900\text{ MHz}$



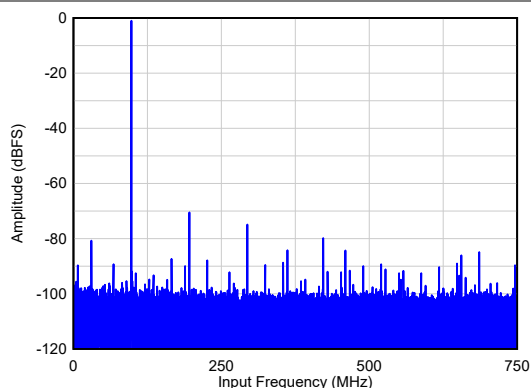
SNR = 64.4 dBFS¹, HD23 = 76 dBc, Non HD23 = 83 dBFS
 $A_{IN} = -4\text{ dBFS}$, 1x AVG, Dither = EN

Figure 6-6. Single Tone FFT at $F_{IN} = 900\text{ MHz}$

¹ Measured from 60 MHz to $F_S/2$

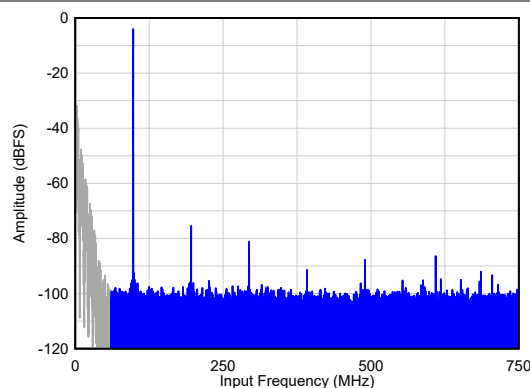
6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted



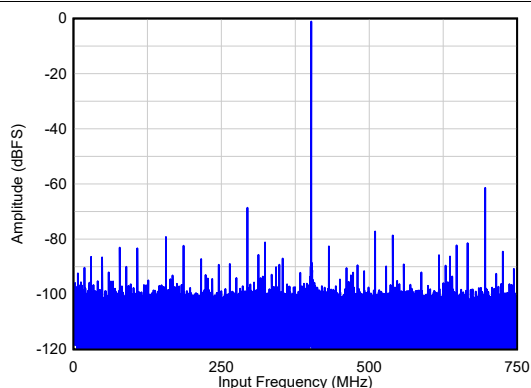
SNR = 63.8 dBFS, HD23 = 69 dBc, Non HD23 = 80 dBFS
 $A_{IN} = -1$ dBFS, 1x AVG, Dither = DIS

Figure 6-7. Single Tone FFT at $F_{IN} = 1400$ MHz



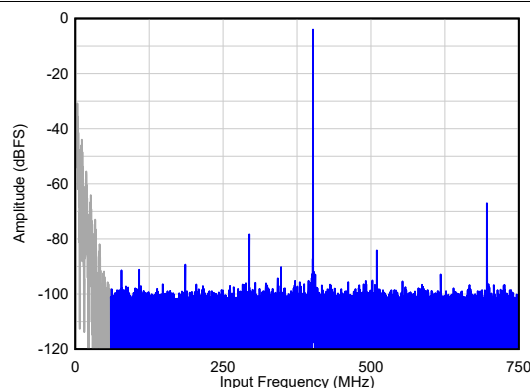
SNR = 64.1 dBFS¹, HD23 = 71 dBc, Non HD23 = 86 dBFS
 $A_{IN} = -4$ dBFS, 1x AVG, Dither = EN

Figure 6-8. Single Tone FFT at $F_{IN} = 1400$ MHz



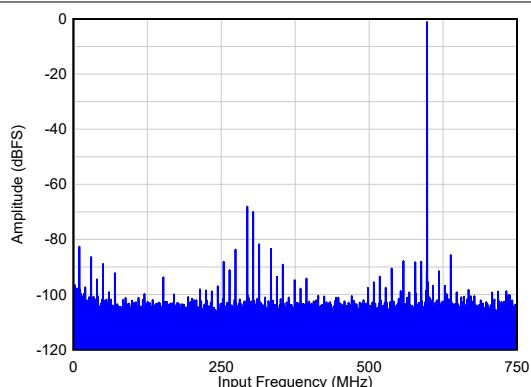
SNR = 62.6 dBFS, HD23 = 60 dBc, Non HD23 = 79 dBFS
 $A_{IN} = -1$ dBFS, 1x AVG, Dither = DIS

Figure 6-9. Single Tone FFT at $F_{IN} = 1900$ MHz



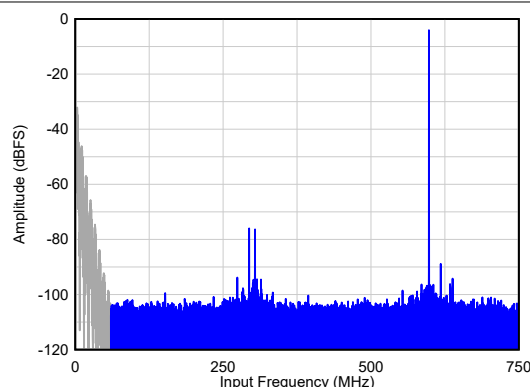
SNR = 63.4 dBFS¹, HD23 = 63 dBc, Non HD23 = 89 dBFS
 $A_{IN} = -4$ dBFS, 1x AVG, Dither = EN

Figure 6-10. Single Tone FFT at $F_{IN} = 1900$ MHz



SNR = 66.8 dBFS, HD23 = 67 dBc, Non HD23 = 82 dBFS
 $A_{IN} = -1$ dBFS, 2x AVG, Dither = DIS

Figure 6-11. Single Tone FFT at $F_{IN} = 900$ MHz

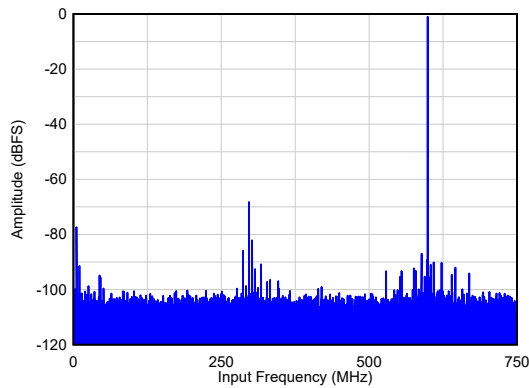


SNR = 67.0 dBFS¹, HD23 = 72 dBc, Non HD23 = 89 dBFS
 $A_{IN} = -4$ dBFS, 2x AVG, Dither = EN

Figure 6-12. Single Tone FFT at $F_{IN} = 900$ MHz

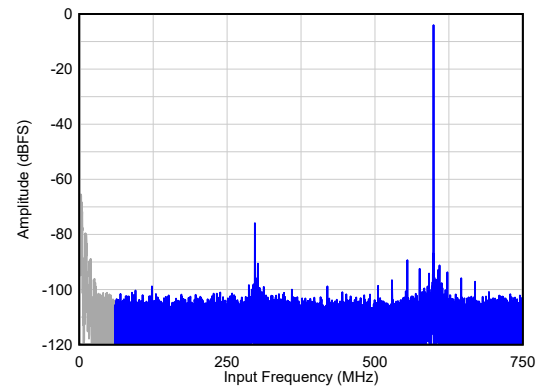
6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted



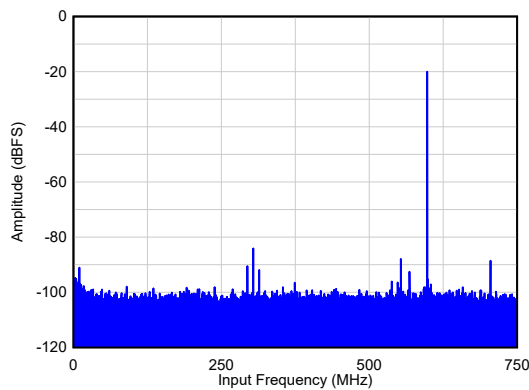
SNR = 66.8 dBFS, HD23 = 67 dBc, Non HD23 = 82 dBFS
 $A_{IN} = -1$ dBFS, 4x AVG, Dither = DIS

Figure 6-13. Single Tone FFT at $F_{IN} = 900$ MHz



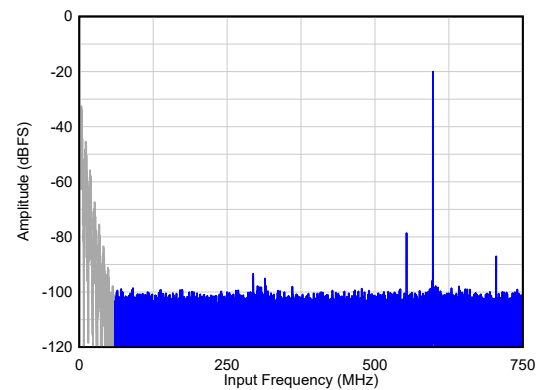
SNR = 67.0 dBFS¹, HD23 = 75 dBc, Non HD23 = 89 dBFS
 $A_{IN} = -4$ dBFS, 4x AVG, Dither = EN

Figure 6-14. Single Tone FFT at $F_{IN} = 900$ MHz



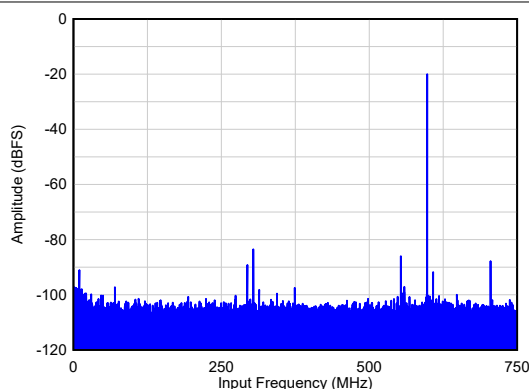
SNR = 65.2 dBFS, HD23 = 64 dBc, Non HD23 = 88 dBFS
 $A_{IN} = -20$ dBFS, 1x AVG, Dither = DIS

Figure 6-15. Single Tone FFT at $F_{IN} = 900$ MHz



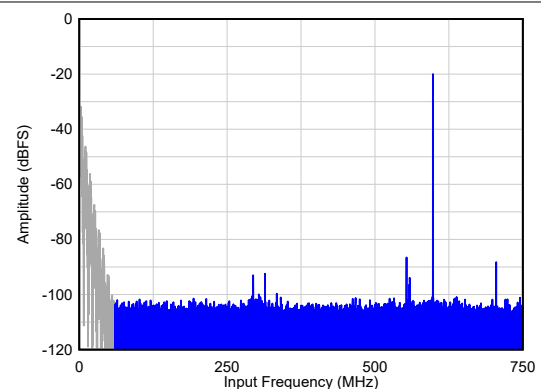
SNR = 64.8 dBFS¹, HD23 = 59 dBc, Non HD23 = 79 dBFS
 $A_{IN} = -20$ dBFS, 1x AVG, Dither = EN

Figure 6-16. Single Tone FFT at $F_{IN} = 900$ MHz



SNR = 67.9 dBFS, HD23 = 64 dBc, Non HD23 = 86 dBFS
 $A_{IN} = -20$ dBFS, 2x AVG, Dither = DIS

Figure 6-17. Single Tone FFT at $F_{IN} = 900$ MHz

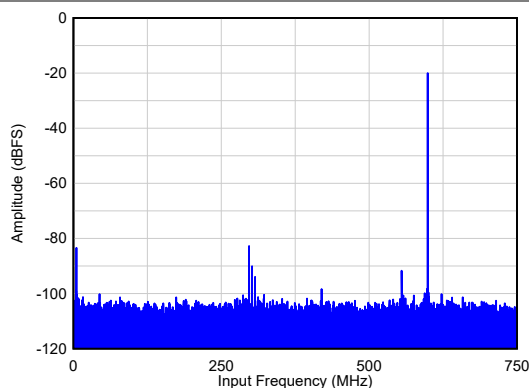


SNR = 67.6 dBFS¹, HD23 = 67 dBc, Non HD23 = 87 dBFS
 $A_{IN} = -20$ dBFS, 2x AVG, Dither = EN

Figure 6-18. Single Tone FFT at $F_{IN} = 900$ MHz

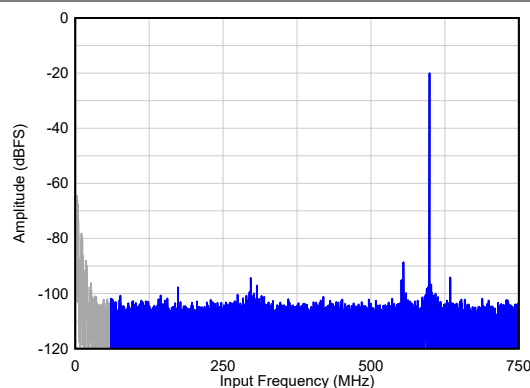
6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted



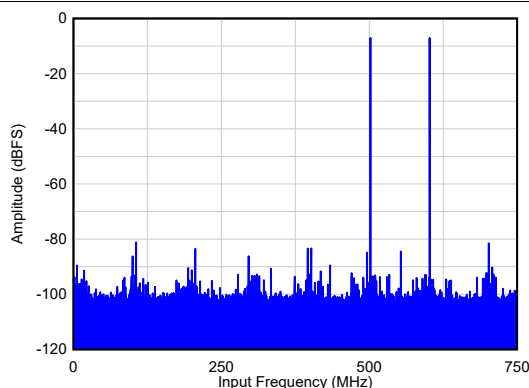
SNR = 67.9 dBFS, HD23 = 64 dBc, Non HD23 = 86 dBFS
 $A_{IN} = -20$ dBFS, 4x AVG, Dither = DIS

6-19. Single Tone FFT at $F_{IN} = 900$ MHz



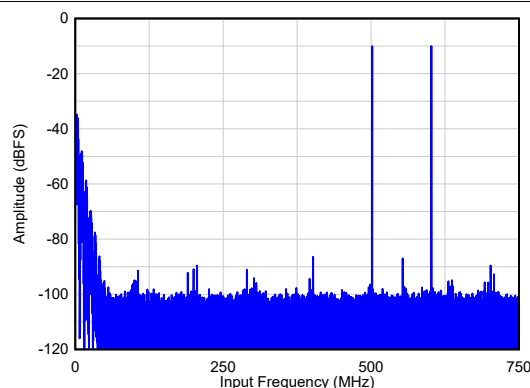
SNR = 67.6 dBFS¹, HD23 = 67 dBc, Non HD23 = 87 dBFS
 $A_{IN} = -20$ dBFS, 4x AVG, Dither = EN

6-20. Single Tone FFT at $F_{IN} = 900$ MHz



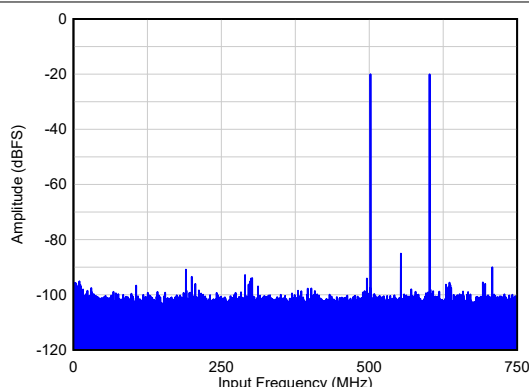
IMD3 = 73 dBc
 $A_{IN} = -7$ dBFS/tone, 1x AVG, Dither = DIS

6-21. Two Tone FFT at $F_{IN} = 900, 1000$ MHz



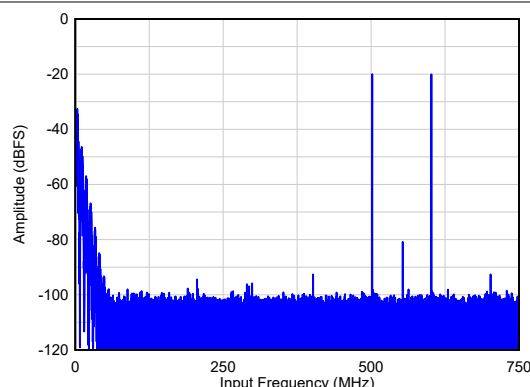
IMD3 = 75 dBc
 $A_{IN} = -10$ dBFS/tone, 1x AVG, Dither = EN

6-22. Two Tone FFT at $F_{IN} = 900, 1000$ MHz



IMD3 = 70 dBc
 $A_{IN} = -20$ dBFS/tone, 1x AVG, Dither = DIS

6-23. Two Tone FFT at $F_{IN} = 900, 1000$ MHz

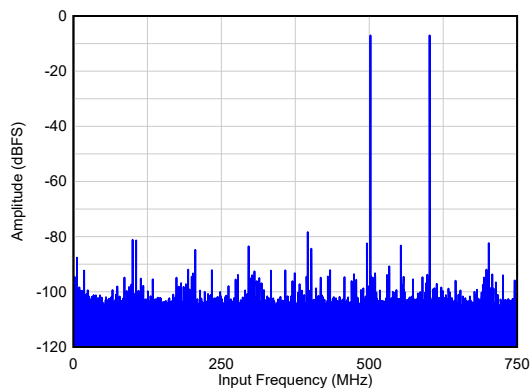


IMD3 = 72 dBc
 $A_{IN} = -20$ dBFS/tone, 1x AVG, Dither = EN

6-24. Two Tone FFT at $F_{IN} = 900, 1000$ MHz

6.10 Typical Characteristics (continued)

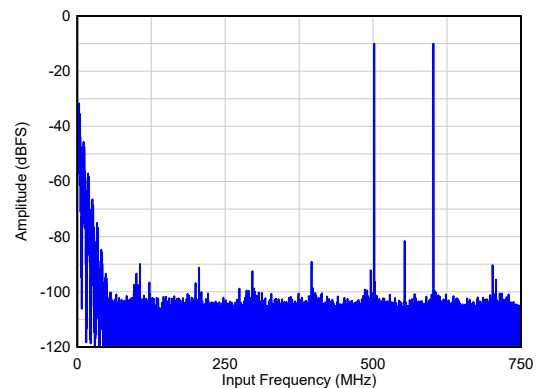
Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, $AVDD18 = 1.8\text{ V}$, $AVDD12$, $CLKVDD$, $DVDD = 1.2\text{ V}$ and -1 dBFS differential input, Dither = DIS, unless otherwise noted



IMD3 = 72 dBc

$A_{IN} = -7\text{ dBFS/ton}$, 2x AVG, Dither = DIS

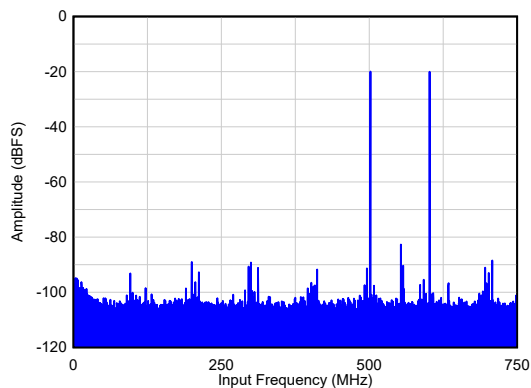
FIG 6-25. Two Tone FFT at $F_{IN} = 900, 1000\text{ MHz}$



IMD3 = 79 dBc

$A_{IN} = -10\text{ dBFS/ton}$, 2x AVG, Dither = EN

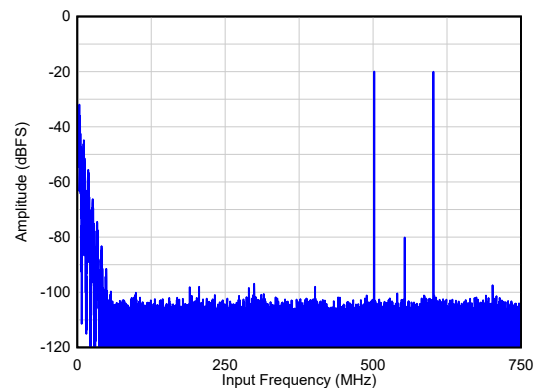
FIG 6-26. Two Tone FFT at $F_{IN} = 900, 1000\text{ MHz}$



IMD3 = 63 dBc

$A_{IN} = -20\text{ dBFS/ton}$, 2x AVG, Dither = DIS

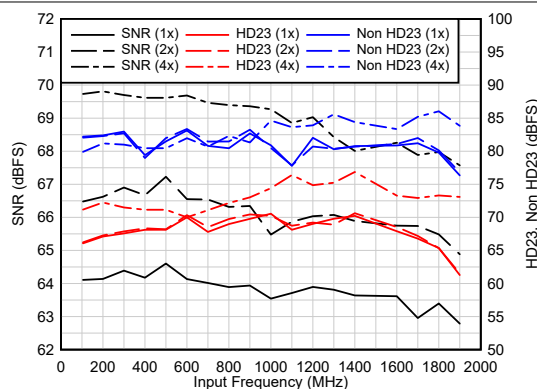
FIG 6-27. Two Tone FFT at $F_{IN} = 900, 1000\text{ MHz}$



IMD3 = 77 dBc

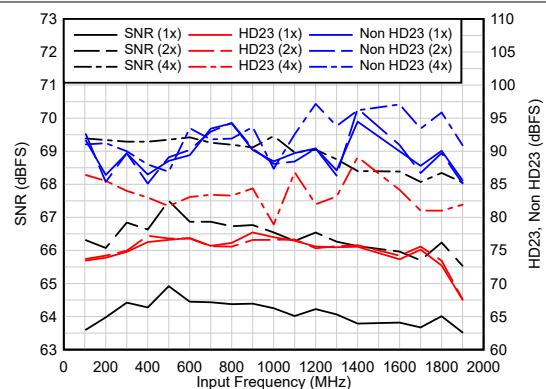
$A_{IN} = -20\text{ dBFS/ton}$, 2x AVG, Dither = EN

FIG 6-28. Two Tone FFT at $F_{IN} = 900, 1000\text{ MHz}$



$A_{IN} = -1\text{ dBFS}$, Dither = DIS

FIG 6-29. AC Performance vs F_{IN}



$A_{IN} = -4\text{ dBFS}$, Dither = EN

FIG 6-30. AC Performance vs F_{IN}

6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, $AVDD18 = 1.8\text{ V}$, $AVDD12, CLKVDD, DVDD = 1.2\text{ V}$ and -1 dBFS differential input, Dither = DIS, unless otherwise noted

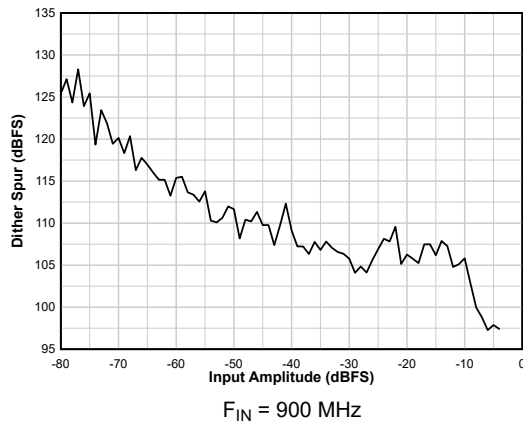


FIG 6-31. Dither Spur vs A_{IN}

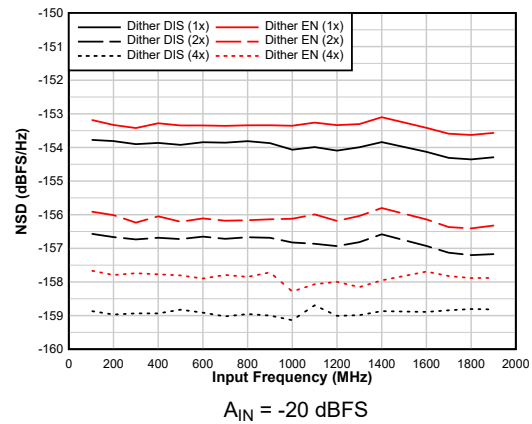


FIG 6-32. NSD Performance vs F_{IN}

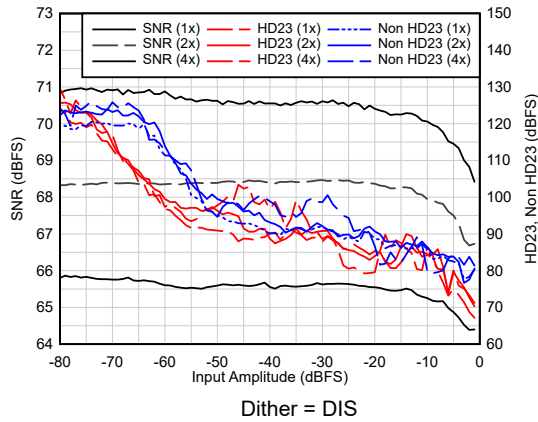


FIG 6-33. AC Performance vs A_{IN}

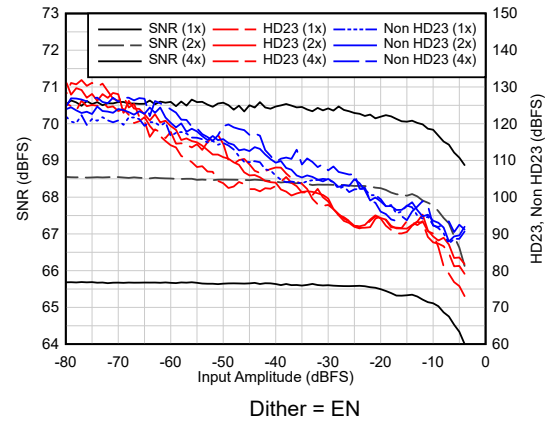


FIG 6-34. AC Performance vs A_{IN}

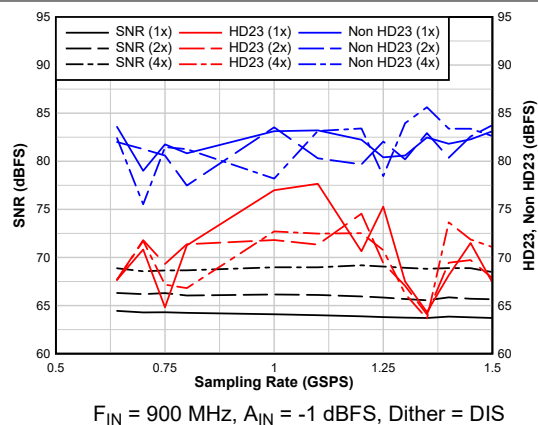


FIG 6-35. AC Performance vs F_S

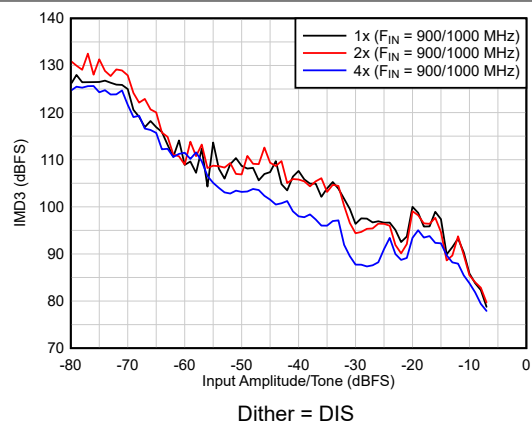


FIG 6-36. IMD3 Performance vs A_{IN}

6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted

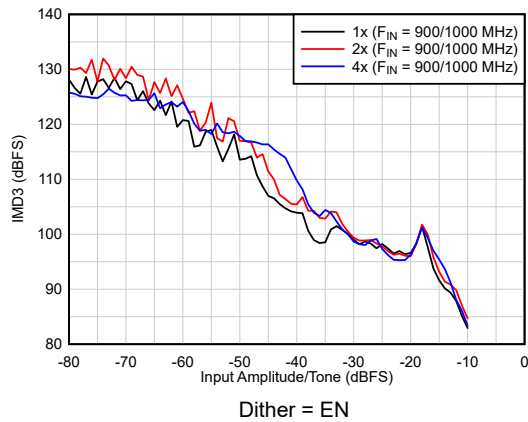


FIG 6-37. IMD3 Performance vs A_{IN}

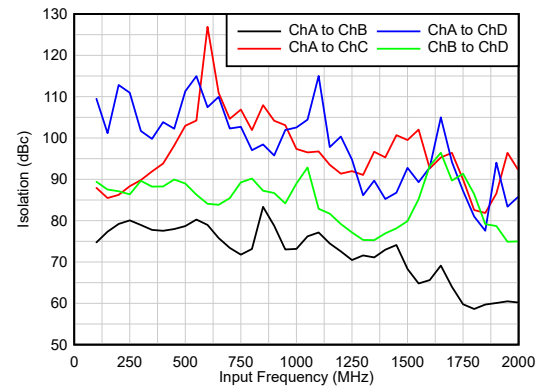


FIG 6-38. Isolation vs Input Frequency

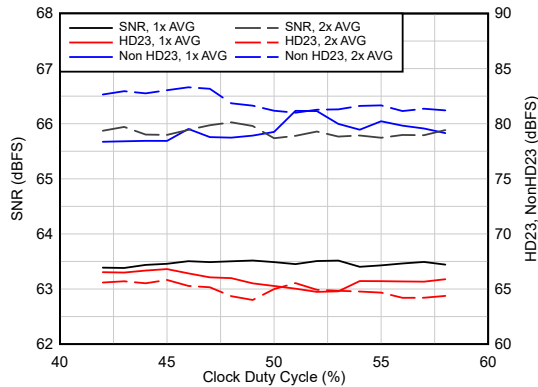


FIG 6-39. AC Performance vs Clock Duty Cycle

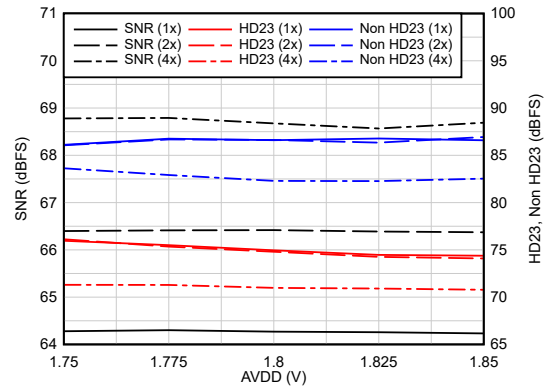


FIG 6-40. AC Performance vs AVDD18

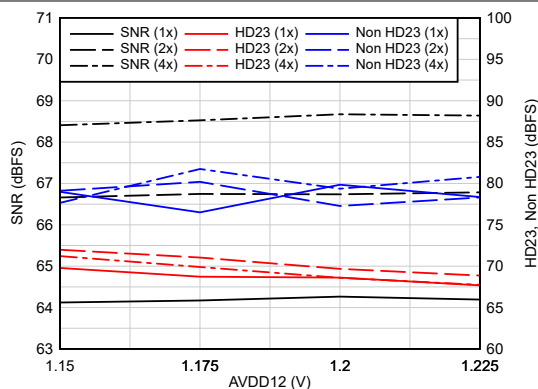


FIG 6-41. AC Performance vs AVDD12

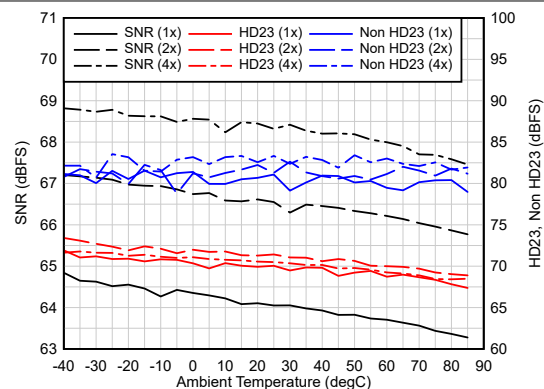
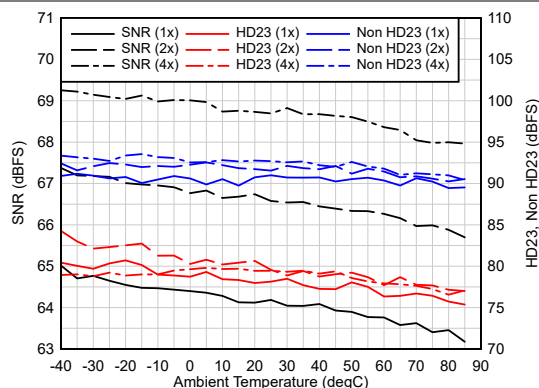


FIG 6-42. AC Performance vs Temperature

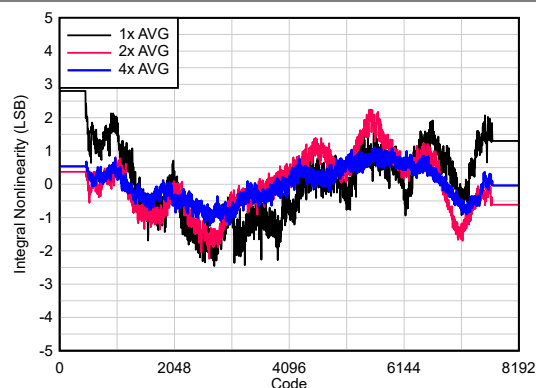
6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted



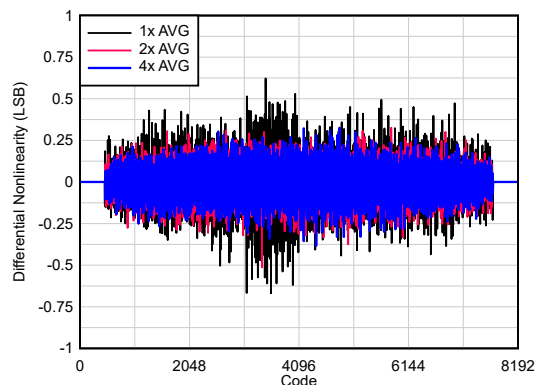
$F_{IN} = 900\text{ MHz}$, $A_{IN} = -1\text{ dBFS}$, Dither = EN

Figure 6-43. AC Performance vs Temperature



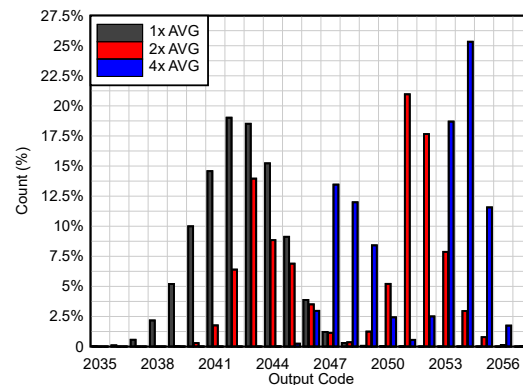
$F_{IN} = 900\text{ MHz}$, Dither = DIS, 13-bit output

Figure 6-44. INL vs Code



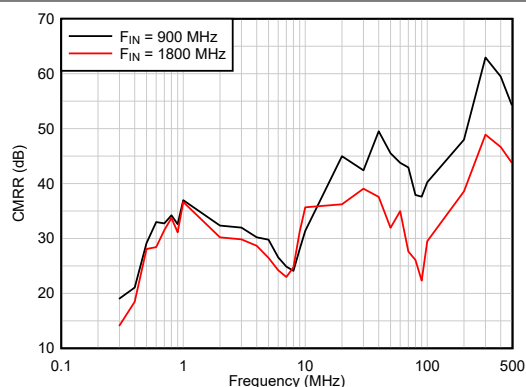
$F_{IN} = 900\text{ MHz}$, Dither = DIS, 13-bit output

Figure 6-45. DNL vs Code



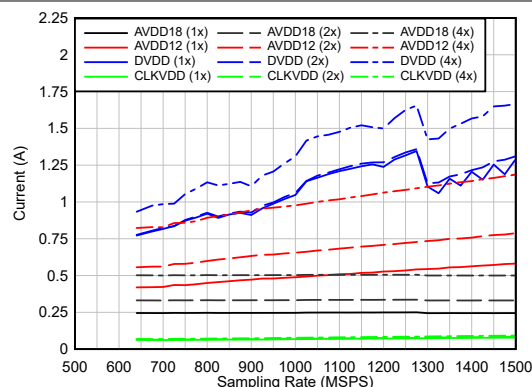
Dither = DIS

Figure 6-46. DC Offset Histogram



$A_{IN} = -1\text{ dBFS}$, 1x AVG, Dither = DIS

Figure 6-47. CMRR

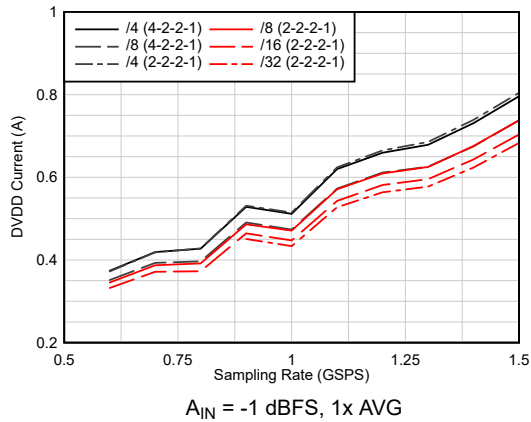


DDC Bypass

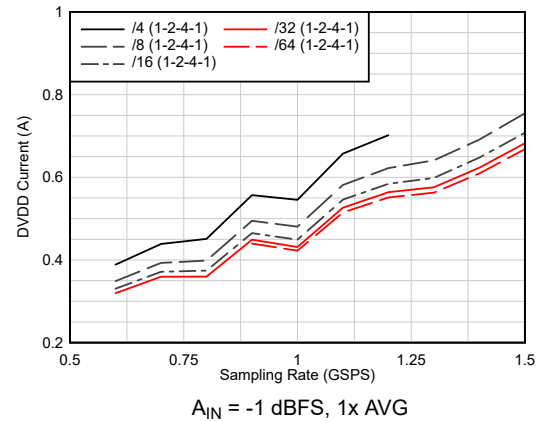
Figure 6-48. Current vs Sampling Rate vs Averaging

6.10 Typical Characteristics (continued)

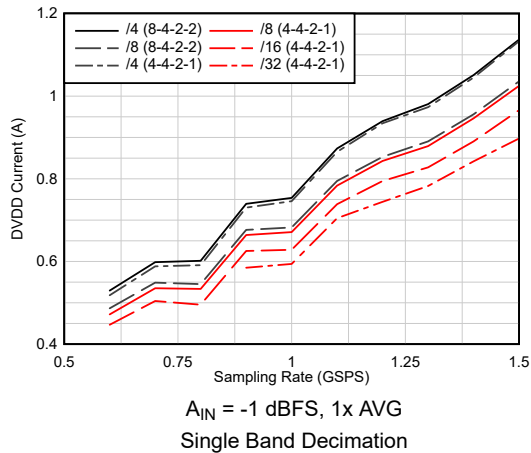
Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, $AVDD18 = 1.8\text{ V}$, $AVDD12$, $CLKVDD$, $DVDD = 1.2\text{ V}$ and -1 dBFS differential input, Dither = DIS, unless otherwise noted



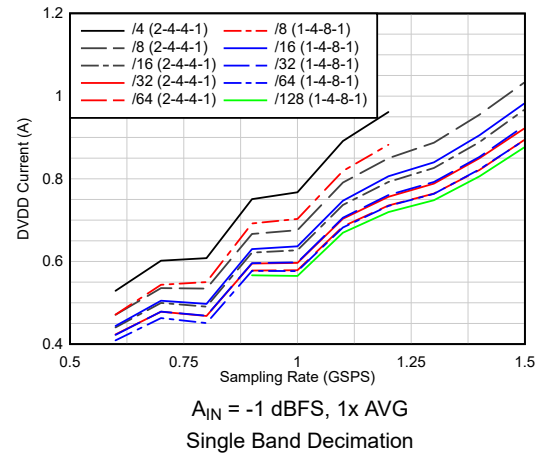
6-49. Current vs Sampling Rate vs Real Decimation



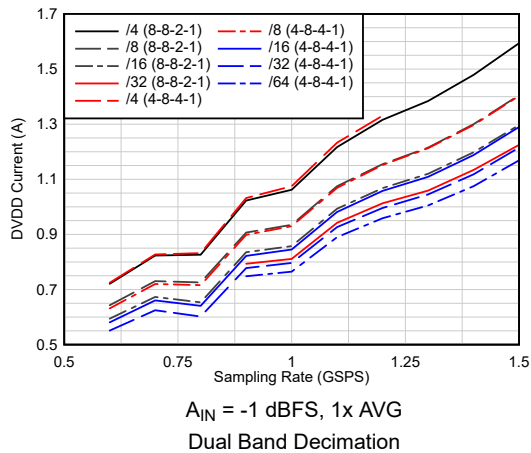
6-50. Current vs Sampling Rate vs Real Decimation



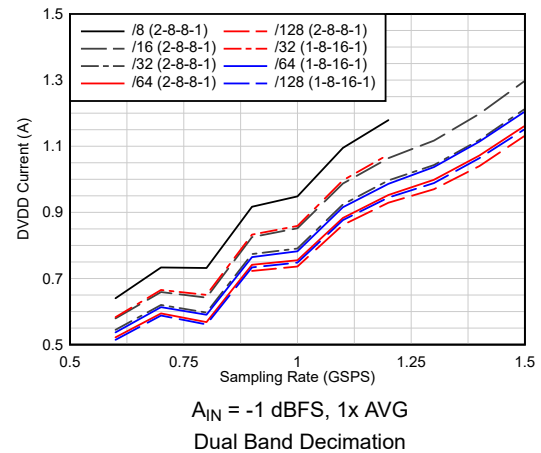
6-51. Current vs Sampling Rate vs Complex Decimation



6-52. Current vs Sampling Rate vs Complex Decimation



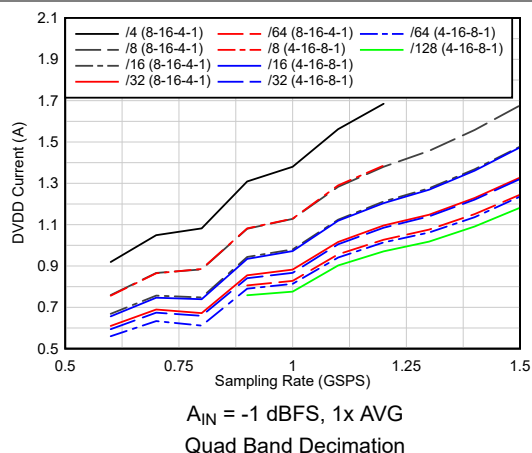
6-53. Current vs Sampling Rate vs Complex Decimation



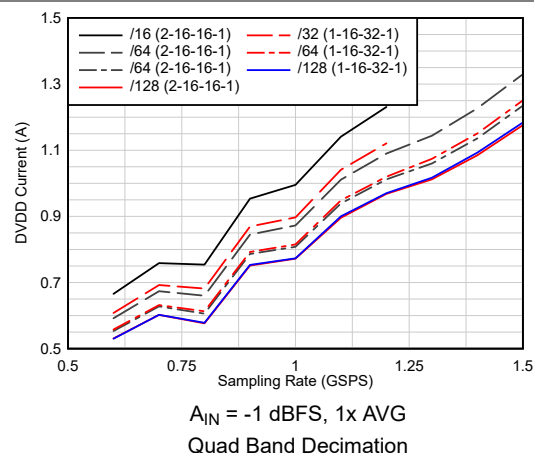
6-54. Current vs Sampling Rate vs Complex Decimation

6.10 Typical Characteristics (continued)

Typical values are at $T_A = 25^\circ\text{C}$, ADC sampling rate = 1.5 GSPS, 50% clock duty cycle, AVDD18 = 1.8 V, AVDD12, CLKVDD, DVDD = 1.2 V and -1-dBFS differential input, Dither = DIS, unless otherwise noted



6-55. Current vs Sampling Rate vs Complex Decimation



6-56. Current vs Sampling Rate vs Complex Decimation

7 Detailed Description

7.1 Overview

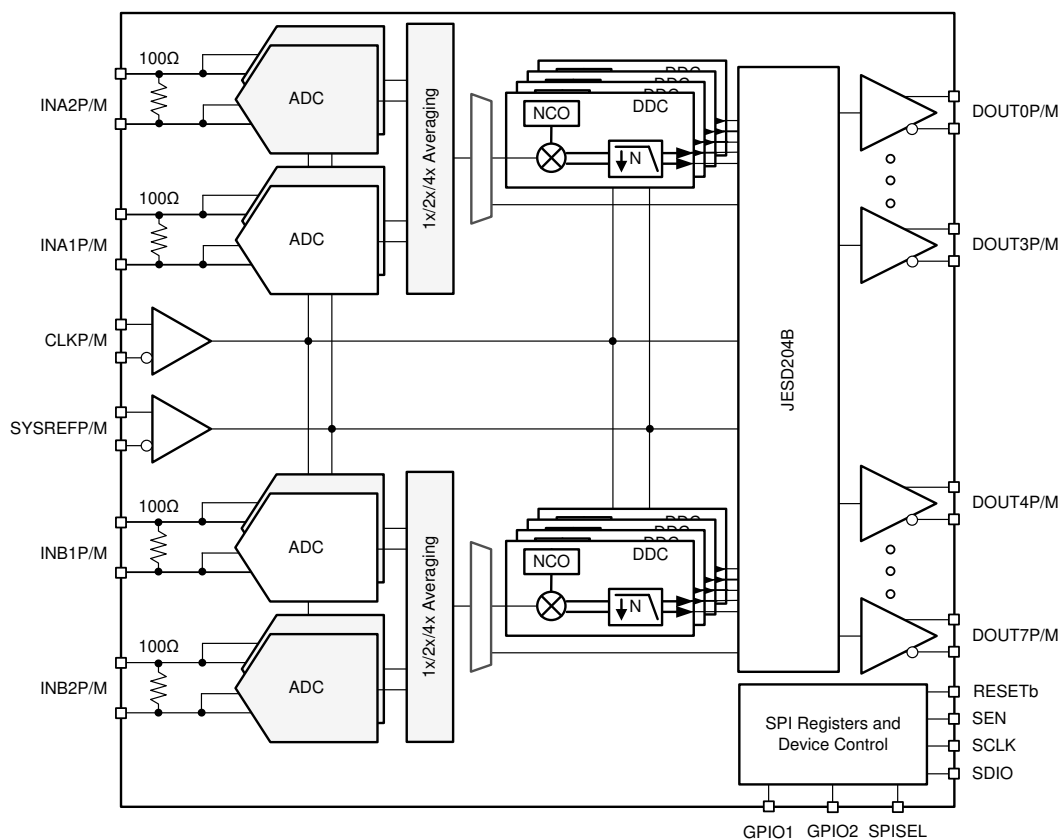
The ADC32RF52 is a single core (non-interleaved) 14-bit, 1.5 GSPS, dual channel analog to digital converter (ADC). The design maximizes signal-to-noise ratio (SNR) and delivers a noise spectral density of -151 dBFS/Hz. Additional internal ADCs can be used for on-chip averaging (2x and 4x) to further improve the noise density to as low as -156 dBFS/Hz.

The analog signal input is non-buffered to save power consumption with a nominal differential input impedance of 100 Ω . The full power input bandwidth is 2.3 GHz (-3 dB) and the device supports direct RF sampling with input frequencies in the through the L-band. The device is designed for low residual phase noise to support high performance radar applications. The sampling clock input has a dedicated power supply input which requires a very clean power supply.

Each ADC channel can be connected to a quad-band digital down-converter (DDC) using a 48-bit NCO which supports phase coherent frequency hopping. Using the GPIO pins for NCO frequency control, frequency hopping can be achieved in less than 1 μ s. The digital down converters support a wide range of instantaneous bandwidth (IBW) coverage - from single wide band mode with 4x complex decimation to up to four narrow bandwidth channels with as high as 128x complex decimation.

The ADC32RF52 supports the JESD204B serial data interface with subclass 1 deterministic latency using data rates up to 13.0 Gbps.

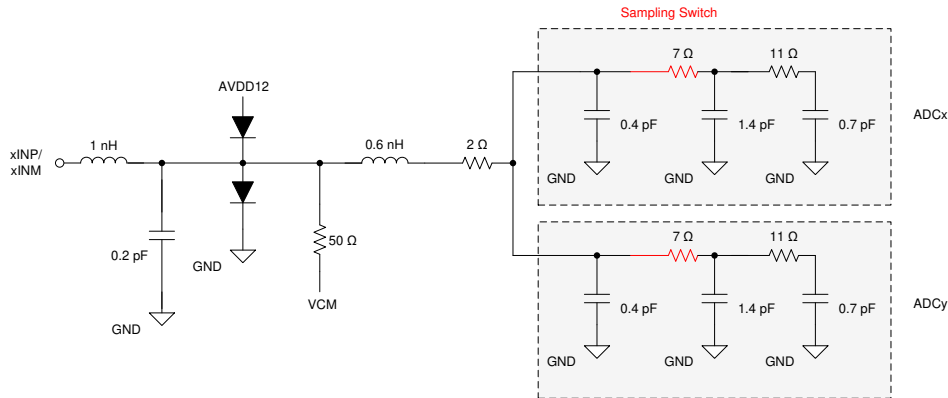
7.2 機能ブロック図



7.3 Feature Description

7.3.1 Analog Inputs

The ADC32RF52 provides up to four internal ADCs per channel for purpose of averaging to improve the noise performance. Two ADCs internally are connected to the same differential input pins as shown in the equivalent input schematic (see 7-1). The analog inputs have a differential 100 Ω split termination with internal biasing. This can be changed to differential 50 Ω termination via SPI register write. When only a single ADC is used, there is a minor parasitic capacitance remaining from the unused ADC.



7-1. Equivalent Input Schematic

7.3.1.1 Input Bandwidth and Full-Scale

The input bandwidth (-3 dB) and input fullscale are dependent on what input termination and averaging mode are chosen as shown in the summary in 7-1. With 2x averaging enabled, the -3 dB bandwidth reduces to ~ 1.5 GHz and 100 Ω differential termination - the bandwidth can be increased by changing the input termination to 50 Ω differential.

表 7-1. Digital averaging vs Full Power Input Bandwidth (-3 dB)

# of ADCs averaged	Input Bandwidth (-3 dB)	Reset Switch	Selected differential input termination	Input Full-scale
1 (Default)	1.6 GHz	1	100 Ω	+ 1 dBm
2	1.5 GHz	1		+ 1.8 dBm
4	1.5 GHz	1		+1.8 dBm
1	1.5 GHz	0		+ 0.5 dBm
2	0.8 GHz	0		
4	0.4 GHz	0		

There is an internal RESET switch which resets the sampling capacitor to VCM in between samples when enabled. The full power input bandwidth plots with input RESET switch disabled (RSW0) and enabled (RSW1) are shown in 7-2.

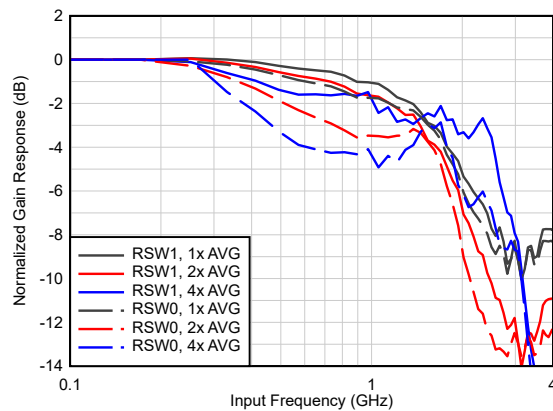


図 7-2. Full power input bandwidth

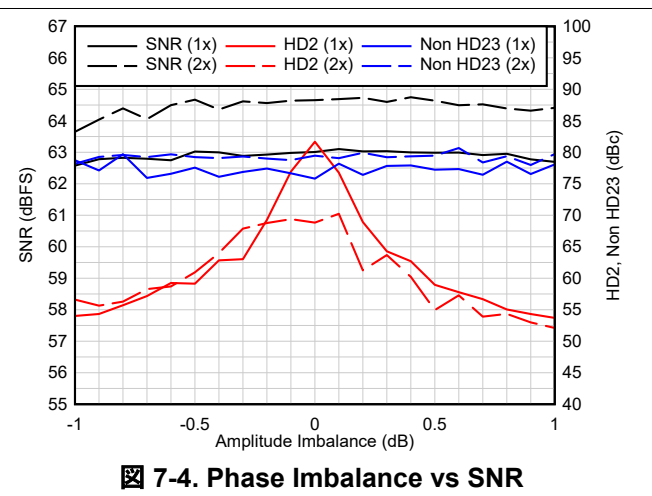
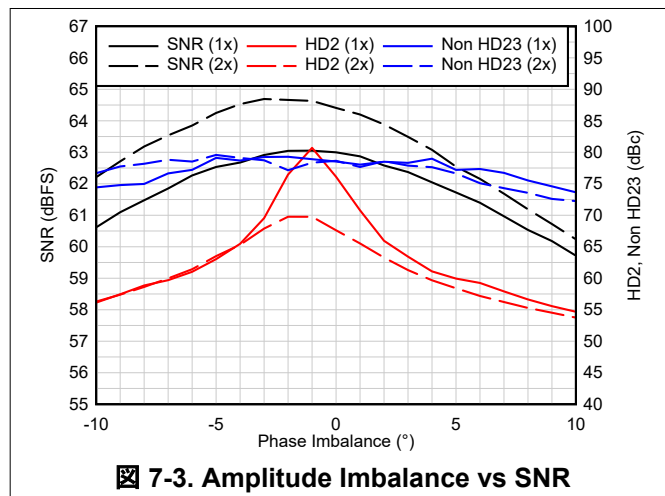
The RESET switch is enabled by default and can be disabled with the following register writes:

表 7-2. Register Write Example for Configuring the RESET Switch

ADDR	DATA	DESCRIPTION
0x05	0x40	Select ANALOG page
0x6D	0xC0	Disable RESET Switch (to enable: 0x00)
0x6E	0x08	Disable RESET Switch (to enable: 0x00)

7.3.1.2 Input Imbalance

The AC performance is sensitive to amplitude and phase imbalance of the analog inputs, as shown in 図 7-3 and 図 7-4 for 1x and 2x internal averaging ($F_S = 1.5$ GSPS, $F_{IN} = 0.9$ GHz, $A_{IN} = -1$ dBFS, dither = DIS).



7.3.1.3 Overrange Indication

The ADC provides two options (configured using SPI) to indicate if input fullscale overrange occurred:

- Fast Overrange on GPIO1/2 pins: indication is available after ~ 6 clock cycles and the overrange indication flag stays high (sticky) until it is cleared via SPI register writes. Note: OVRA and OVRB or OR-ed together and given on GPIO1 and 2.
- Overrange embedded in JESD stream: in this configuration the overrange indicator replaces the LSB of the output data of the corresponding channel. The indicator is output ahead of the data and is updated every clock cycle.

表 7-3. JESD OVR Latency

Decimation	# of Bands	OVR Latency (incl JESD, in sampling clock cycles)
DDC Bypass	-	140-144
8	Single (real and complex), dual	44
	Quad	33
16	Single (real and complex), dual	80
	Quad	58
32	Single (real and complex), dual	152
	Quad	108
64	Single (real and complex), dual	296
	Quad	208
128	Single (real and complex), dual	584
	Quad	408

The overrange output flag (GPIO or JESD) is the output of individual overrange flags of all ADCs per channel being used. For example, in non-averaged mode the overrange indication per channel is for a single ADC while in 4x average mode the overrange flag of all 4 ADCs are OR-ed together. 表 7-4 shows how to configure the OVR using SPI registers.

表 7-4. Programming example to configure the OVR to GPIO or JESD

ADDR	DATA	DESCRIPTION	ADDR	DATA	DESCRIPTION
OVRA on GPIO1 and OVRB on GPIO2, OVR sticky			OVR on JESD		
0x05	0x02	Select DIGITAL page	0x05	0x02	Select DIGITAL page
0x238	0xF0		0x2E	D0	Set D0 = 1 to enable OVR on JESD
0x383	0x02	Enable individual OVR on GPIO	0x05	0x00	
Clear OVR			These extra writes are only needed using decimation		
0x05	0x40	Select ANALOG page	0x05	0x18	Select DDCA & DDCB page at same time
0x74	0x04	Clear OVR flag chA	0x20	0x06	Enable OVR on JESD
0x74	0x00				
0x84	0x04	Clear OVR flag chB			
0x84	0x00				
Change OVR from sticky to non sticky (self clear)					
0x05	0x40	Select ANALOG page			
0x31	0x06	Set OVR to non-sticky			

7.3.1.4 Analog out-of-band dither

The ADC32RF52 provides optional (enabled via SPI writes) analog out-of-band, large amplitude dither. It has a bandwidth of ~ 20 MHz located at DC and an adjustable amplitude with a maximum dither power of ~ -20 dBFS (PAR ~ 9 dB). The dither is completely rolled-off into the noise floor within ~ 100 MHz as illustrated in [Figure 7-5](#). Since the dither is large amplitude it is recommended for the signal input not to exceed -2.5 dBFS to avoid input saturation. The dither signal also couples to the input signal and, depending on input frequency, can degrade the close in phase noise for offsets > 1 MHz.

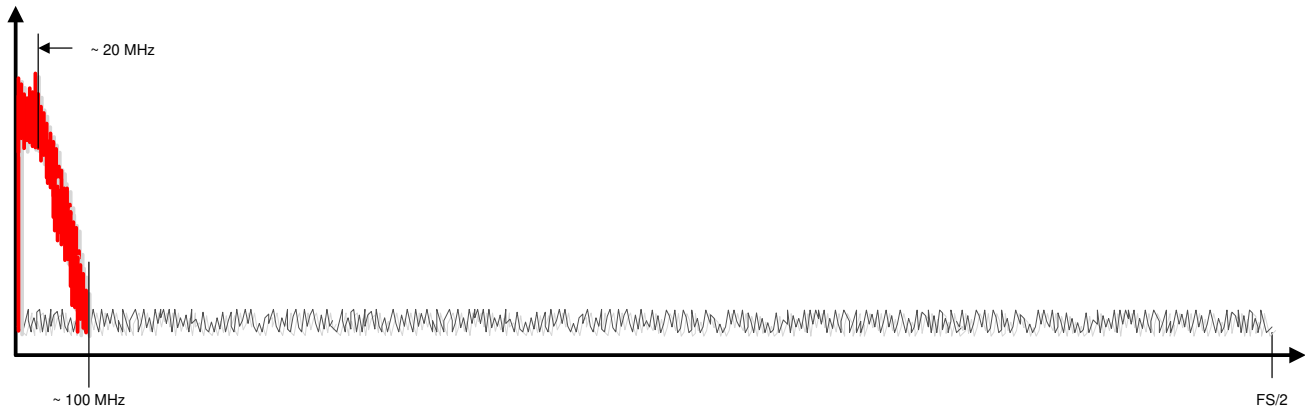


Figure 7-5. Analog out-of-band dither

In the frequency domain the dither signal shows up like individual tones as shown in [Figure 7-6](#). The dither update frequency can be adjusted with the dither divider setting. The dither update frequency is: $F_S / 4 / 2047 / \text{'Dither Divider'}$. In the frequency spectrum there will be 2 larger dither spurs at $F_{IN} \pm F_S / 4 / \text{'Dither Divider'}$.

By default, the divider is set to 50, which translates to a dither spur spacing of ~ 7 kHz. A divider setting of 32 translates to a dither spacing of ~ 11 kHz as shown in [Figure 7-7](#). The lower the divider setting, the higher the dither tone frequency. [Figure 7-6](#) also shows that the dither energy reduces as the offset frequency increases - less dither energy reduces the higher harmonic spur improvement.

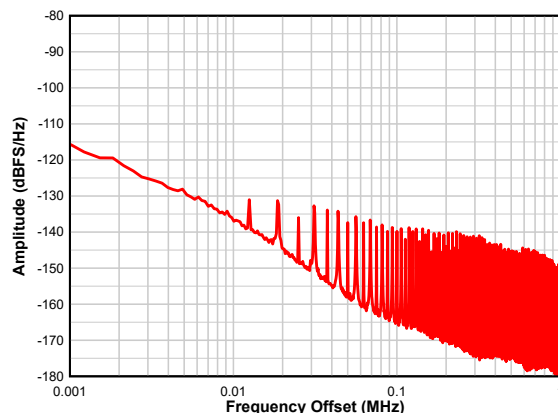


Figure 7-6. Dither Close-Up

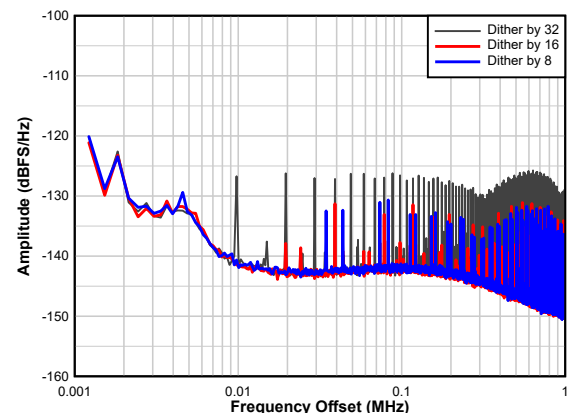


Figure 7-7. Dither vs Dither Divider Setting

The analog dither needs to be enabled in multiple locations. Different dither amplitudes should be used depending on internal averaging used as shown in 表 7-5.

表 7-5. Recommended Dither Amplitude Settings

Mode	Amplitude	Dither Amp1	Dither Amp2
1x AVG	+/-1024 codes	0	0
1x AVG	+/-768 codes	0	-4
2x/4x AVG	+/-1024 codes	3	0
2x/4x AVG	+/-768 codes	0	0

The internal analog dither can be enabled via the following register writes. The dither divider is set in register 0xB1 as actual -1 (e.g. a divider of 48 would be programmed as 47, default is 0x00 which is divider = 50). See 表 7-6.

表 7-6. Register Write Example for Configuring the Internal Dither

ADDR	DATA	DESCRIPTION	ADDR	DATA	DESCRIPTION
0x05	0x40	Select ANALOG page	0xB1	0x00	Sets dither divider. 0x00 = /50
0xA8	0x00	DITHER AMP1: 3 = 0x80, 0 = 0x00	0xB2	0x00	
0xCD	0x00	DITHER AMP2: -4 = 0x40, 0 = 0x00	0xAF	0x18	
0x04	0x01		0xAF	0x10	0x10 = dither ENABLED, 0x90 = dither DISABLED
0x20	0x04		0x04	0x01	
0x91	0x40		0x20	0x00	
0xAF	0x10		0x04	0x00	

7.3.2 Sampling Clock Input

The internal sampling clock path was designed for lowest residual phase noise contribution. The sampling clock circuitry requires a dedicated low noise power supply for best performance. The internal residual clock phase noise is also sensitive to clock amplitude and for best performance the clock amplitude should be larger than $1 V_{PP}$.

表 7-7. Internal Aperture Clock Phase Noise
($F_S = 1.5$ Gsps, $V_{IN} = 1 V_{PP}$)

Frequency Offset (MHz)	Amplitude (dBc/Hz)
0.001	-123
0.01	-133
0.1	-143
1	-152
10	-157
250	-160

The clock input and ADC sampling circuitry also have an amplitude noise component which modulates on to the sampled input signal. Unlike phase noise, the amplitude noise does not scale with input frequency as shown in 図 7-8. This noise component can dominate the close in noise performance at lower input frequencies.

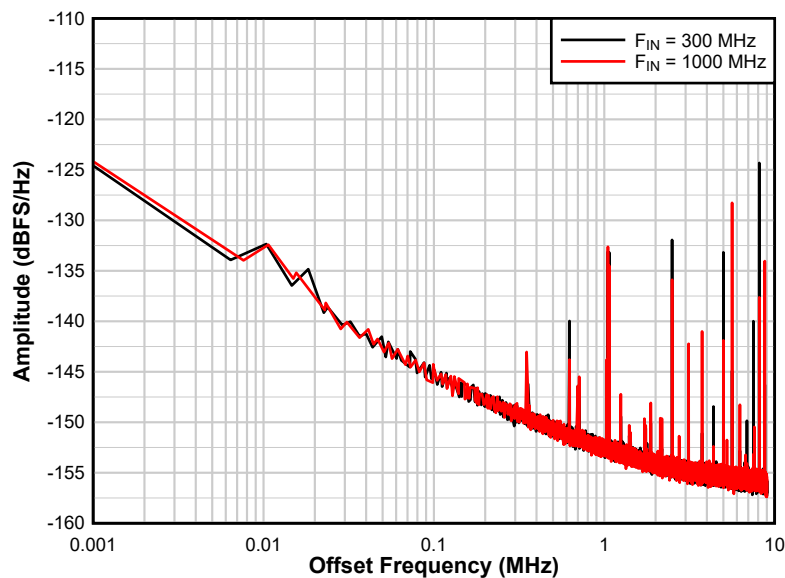


図 7-8. Amplitude Noise

The internal aperture jitter is also dependent on the amplitude of the external clock input signal. [Figure 7-9](#) and [Figure 7-10](#) show the expected SNR performance with dither on/off across clock amplitude.

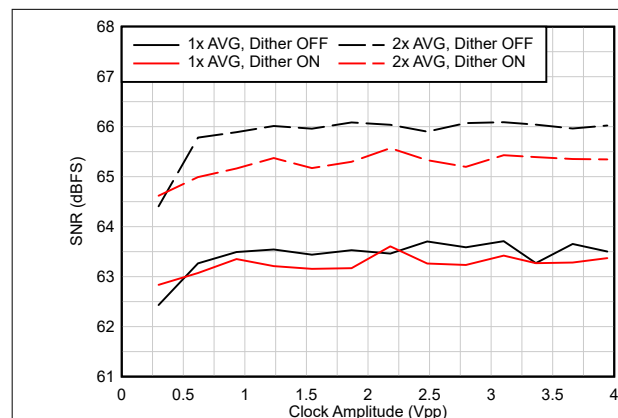


Figure 7-9. SNR vs Clock Amplitude ($F_{IN} = 900 \text{ MHz}$)

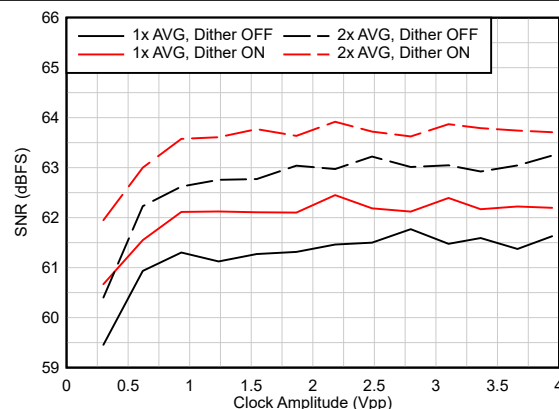


Figure 7-10. SNR vs Clock Amplitude ($F_{IN} = 1800 \text{ MHz}$)

The sampling clock input is internally terminated to 100Ω differentially and provides a return loss better than 10 dB (see [Figure 7-11](#)). The clock input consists of a single clock input buffer followed by a dedicated clock buffer for ADCA1/2 as well as ADCB1/2. When averaging multiple ADCs, there are some close in clock buffer noise which is correlated; and thus, does not improve with averaging.

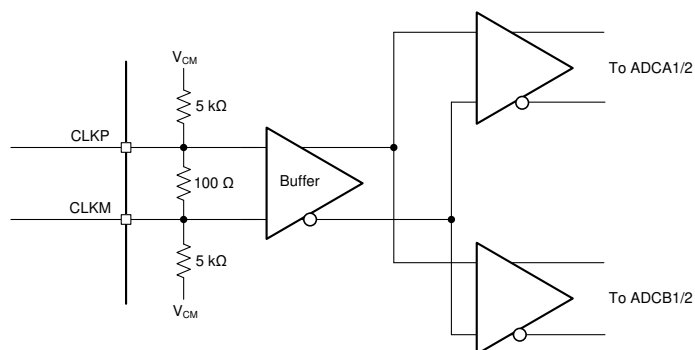


Figure 7-11. Clock Input Internal Circuitry

7.3.3 SYSREF

The SYSREF input signal is used to reset internal digital blocks and align them to the internal multi-frame clock to achieve deterministic latency subclass 1. The SYSREF input signal can be AC or DC coupled (selected via SPI register option) as shown in 図 7-12. The ADC32RF5x has internal 100-Ω termination for DC coupling and internal biasing when using AC coupling.

A register mask can be used to only give SYSREF to the NCO (see NCO section) in the decimation filter block and leave all other blocks such as JESD interface unaffected.

When giving a periodic SYSREF signal, the frequency must be a sub-harmonic of the internal local multi-frame clock (LMFC). The LMFC frequency is determined by the selected decimation: frames per multi-frame setting (K), samples per frame (S), and the device sampling frequency (FS).

表 7-8. LMFC and SYSREF settings for different operating modes

Operating Mode	LMFS Mode	LMFC Clock Frequency	SYSREF Frequency
DDC Bypass Mode	82820	$FS / (20 \times K)$	$FS / (N \times 20 \times K)$
	8224	$FS / (4 \times K)$	$FS / (N \times 4 \times K)$
Decimation	Various	$FS / (D \times S \times K)$	$FS / (N \times D \times S \times K)$

Where N is an integer value (1, 2, 3...).

After enabling SYSREF input, the internal SYSREF input ignores any incoming SYSREF pulse after the first 16 pulses.

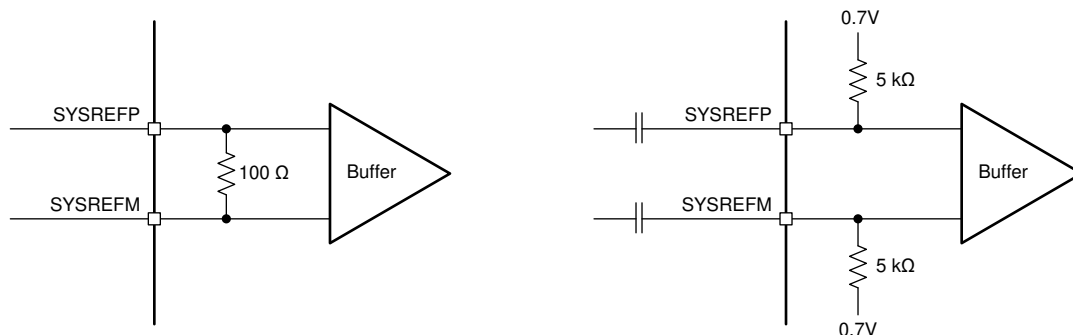


図 7-12. SYSREF Input Circuitry and Edge Alignment

The internal synchronization using the external SYSREF signal can be enabled with the following register writes (see 表 7-9)

表 7-9. Register write example for enabling SYSREF synchronization

ADDR	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x236	0x02	Enable internal SYSREF input and clear SYSREF pulse counter
0x236	0x03	Starts internal SYSREF counter

AC coupling with internal biasing of the SYSREF input can be enabled with the following SPI register writes (see 表 7-10)

表 7-10. Register write example for enabling SYSREF AC coupling

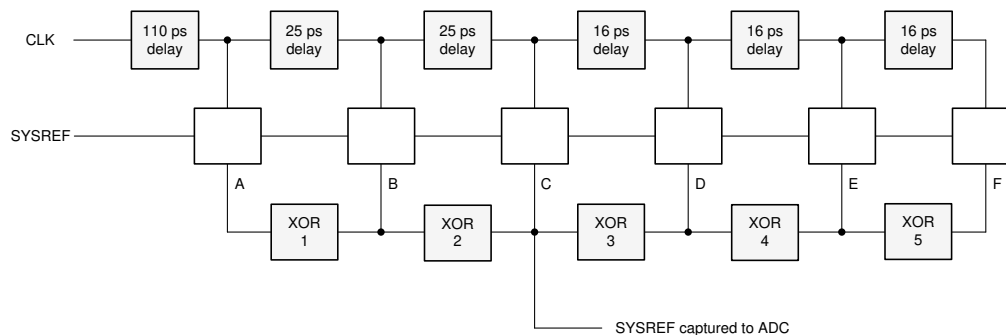
ADDR	DATA	DESCRIPTION
0x05	0x40	Select ANALOG page
0xB4	0x01	Enable external AC coupling with internal biasing on SYSREF

7.3.3.1 SYSREF Capture Detection

The SYSREF input signal rising edge should be edge aligned with the rising edge of the sampling clock to maximize the setup and hold times. The ADC32RF52 includes an internal SYSREF monitoring circuitry to detect possible metastability resulting in a clock cycle slip; and thus, misalignment across devices.

The sampling clock gets delayed by ~160 ps and then captures the SYSREF signal. The SYSREF monitoring circuitry captures the SYSREF signal ± 50 ps (-50, -25, +16, +32, +48 ps) around the main SYSREF capture. In ideal conditions no SYSREF transition happens within the 100 ps SYSREF capture window and all XOR flags show "0". If a SYSREF/clock misalignment happens and the SYSREF transition falls within the SYSREF monitoring window, then one of the XOR flags (which monitor adjacent SYSREF captures within the window) shows a "1" and the SYSREF can be adjusted externally.

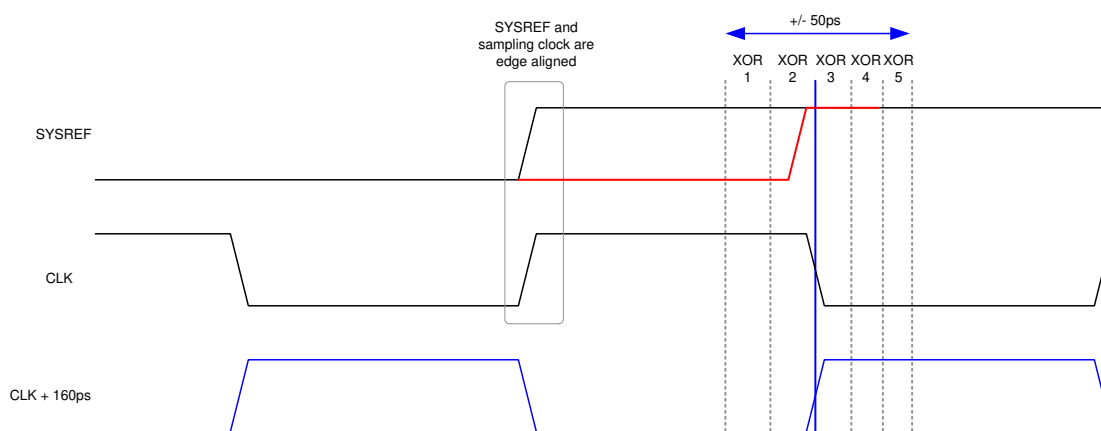
The SYSREF monitor registers are not 'sticky' registers - they get updated at every rising edge of SYSREF.



7-13. SYSREF Detection Circuitry

The example in 7-14 shows a misaligned SYSREF signal where the SYSREF signal arrives much later than the sampling clock rising edge. The SYSREF window feature checks if the SYSREF transition is within ± 50 ps of the instant when the SYSREF signal gets captured by the sampling clock.

In this example, the delayed SYSREF signal transitions between the "B" and "C" flip flop which raises the XOR2 flag. The XOR flags get reported in register 0x22F in the digital page. In this example, Register 0x22F reads back 0x8B, as shown in 7-11.



7-14. Detection of SYSREF Transition within Capture Window

表 7-11. SYSREF Window Register Example (0x22F)

ADDR	D7	D6	D5	D4	D3	D2	D1	D0
0x22F	1	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1	SYSREF OR	1
	1	0	0	0	1	0	1	1

7.3.4 ADC Foreground Calibration

The internal ADC architecture is sensitive to temperature changes. The ADC32RF52 contains two additional internal ADC cores (one for channel A1/2 and one for channel B1/2) which are used whenever one of the ADCs is in calibration. ADCs are calibrated as pairs where one ADC at a time is connected to the internal calibration DAC. The calibration is configured via SPI register writes and can be executed using SPI register writes or using the GPIO1 pin. When executed, the calibration takes $\sim 46 \text{ ms} \times 1.5 \text{ GSPS} / F_S$ per ADC pair ($\sim 23 \text{ ms} \times 1.5 \text{ GSPS} / F_S$ per ADC). The example in [Figure 7-15](#) shows 2x internal averaging where 4 ADC cores (#1, #2 for chA1 and #6, #7 for chB1) are used in operation and ADCs #5 and #10 for calibration.

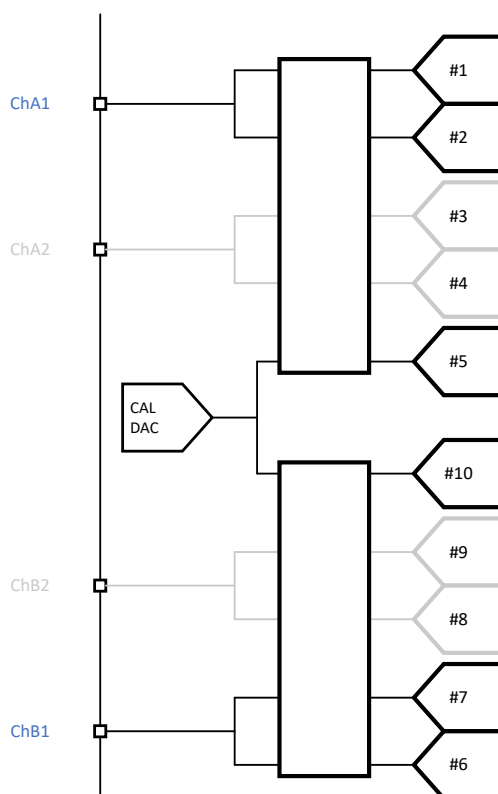


図 7-15. Internal ADC setup for 2x averaging mode

7.3.4.1 Calibration Control

Figure 7-16 shows a timing diagram of the calibration control using GPIO1 pin.

When GPIO1 transitions to LOW logic state:

- an ADC pair gets swapped out within ~ 120 ns
- a new calibration gets triggered immediately

If GPIO1 is being held low when the calibration of an ADC pair is completed, the next ADC pair is switched and a new calibration is triggered. The order in which ADC pair gets calibrated can be configured via SPI to serial or random.

When using 2x averaging for example, the calibration is executed for 3 ADC pairs to make sure all ADCs in use have been recently calibrated.

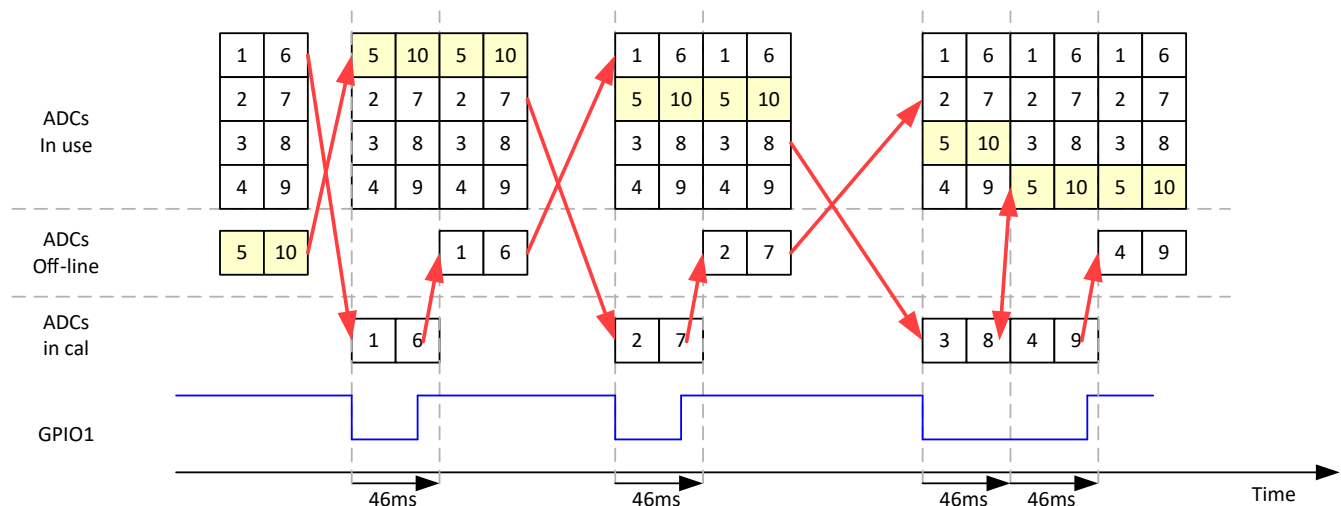


Figure 7-16. Timing diagram - calibration (4x AVG example)

Figure 7-17 shows the ADC switch happens approximate 120 ns after the logic level change on GPIO1 is detected.

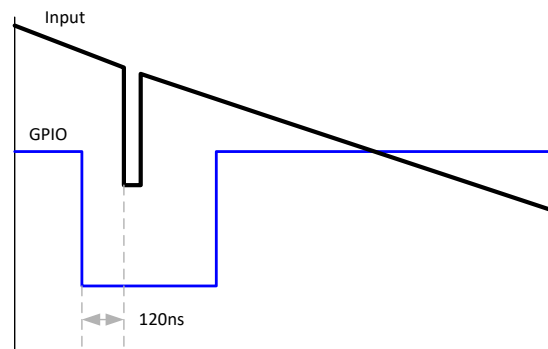


Figure 7-17. Timing diagram shows the ADC switch

7.3.4.2 ADC Switch

During the ADC transition, the amplitude drops for 1-2 samples as shown in 図 7-18. The gain variation from one ADC to the next is $\sim < 0.05$ dB while the phase change is less 0.01 deg as shown in 図 7-19.

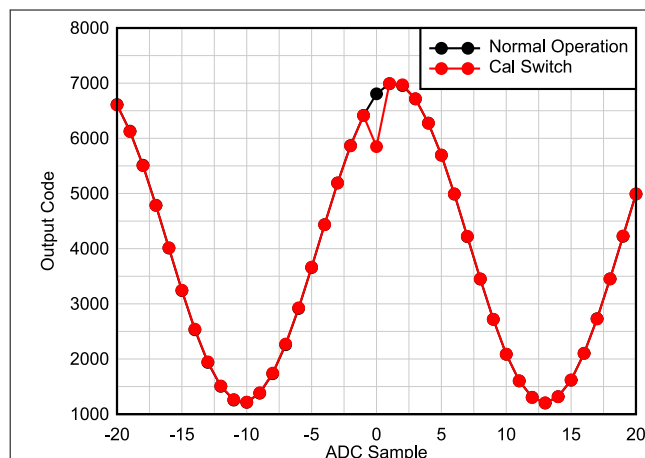


図 7-18. Output Code vs ADC Sample

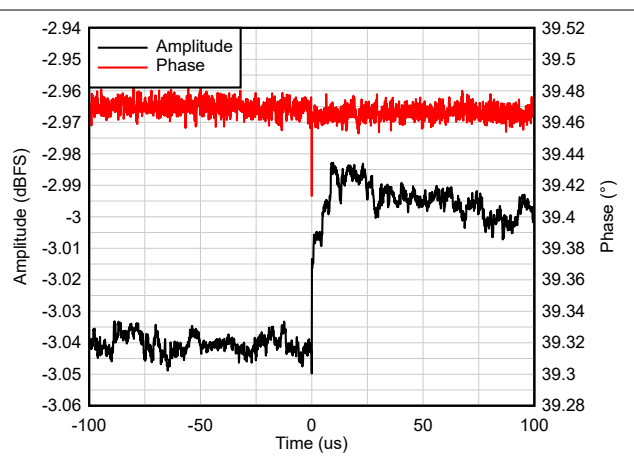


図 7-19. Amplitude and Phase vs Time

7.3.4.3 Calibration Configuration

The ADC32RF5x provides 3 different options to configure the internal foreground calibration:

- Calibrate all ADCs one time using SPI trigger (after initial power up or during operation) - see 表 7-12
- Continuous calibration - see 表 7-13
- Calibrate 2 ADC pairs at a time using GPIO trigger - see 表 7-14

The status of the calibration can be read back from register 0x298 (CALIBRATION page). Successful calibration reads back 0x0E on the 4 LSB of that register.

表 7-12. Register Writes for power up calibration or SINGLE calibration of all ADCs Using SPI

ADDR	DATA	DESCRIPTION
0x05	0x20	Select CALIBRATION page
0x46	0x02	
0x45	0x8A	Toggle calibration start
0x45	0x0A	
wait		2.6 seconds x 1.5 GSPS / F _S

表 7-13. Register Writes to Trigger CONTINUOUS Calibration of all ADCs Using SPI

ADDR	DATA	DESCRIPTION
0x05	0x20	Select CALIBRATION page
0x46	0x03	
0x45	0x0A	

表 7-14. Register Writes to Trigger ADC Pair Calibration Using the GPIO Pin

ADDR	DATA	DESCRIPTION
0x05	0x20	Select CALIBRATION page
0x46	0x02	
0x45	0x4A	
0x05	0x02	Select DIGITAL page
0x234	0x04	Use GPIO1 pin to freeze calibration switch

7.3.5 Decimation Filter

The ADC32RF52 provides up to four digital down converters per ADC channel (see [Figure 7-20](#)). The decimation filters provide a flexible option to cover a wide range of instantaneous bandwidths (IBW) as shown in [Table 7-15](#). Single band decimation supports a wide bandwidth up to complex decimation by 4x while up to four narrow band channels with up to 128x complex decimation are supported in quad band decimation mode.

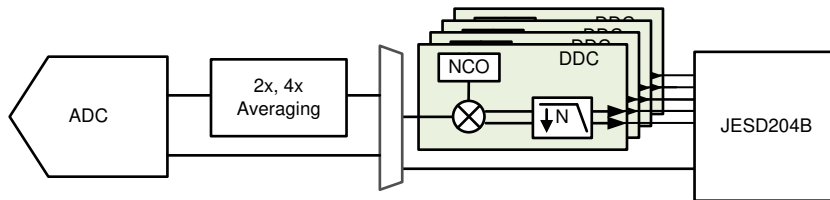


図 7-20. Digital Decimation Filter Options

表 7-15. Summary of Different Decimation Filter Band Options

# of DDCs	Minimum Complex Decimation	Maximum Complex Decimation
1	4	128
2	8	128
4	16	128

The decimation filter can be configured to two different operating modes:

- **Complex Decimation:** This mode provides complex output with ~ 80% passband bandwidth using a 48-bit phase coherent NCO.

During the complex mixing operation the digital output is reduced by 6-dB. This reduces the fullscale from 0-dBFS to -6-dBFS. This 6-dB change applies to signals and noise and thus no dynamic range is lost.

- **Real Decimation:** In real decimation mode, the complex mixer is bypassed (NCO is set to 0 for lowest power consumption), and the digital filter acts as a low pass filter. There is no frequency shifting and the output passband bandwidth is ~ 40%.

Since the JESD204B interface is common across ADC channel A and B, the decimation ratio as well as the # of DDCs/ADC has to be the same across channels A and B.

By default, the output of values of the decimation filter are rounded to 16-bit resolution. To avoid quantization noise limitation when using high order of decimation (that is /64 or /128), a special 20-bit output mode can be enabled (see [20-bit mode](#)).

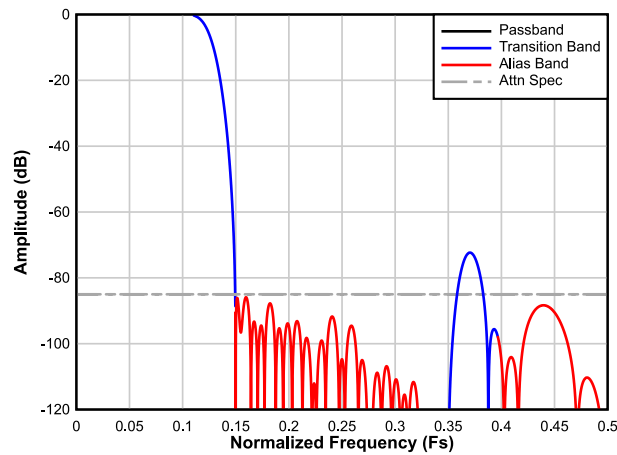
[表 7-16](#) provides an overview of the available complex decimation settings and resulting complex and real output bandwidths.

表 7-16. Complex Decimation Setting vs Output Bandwidth

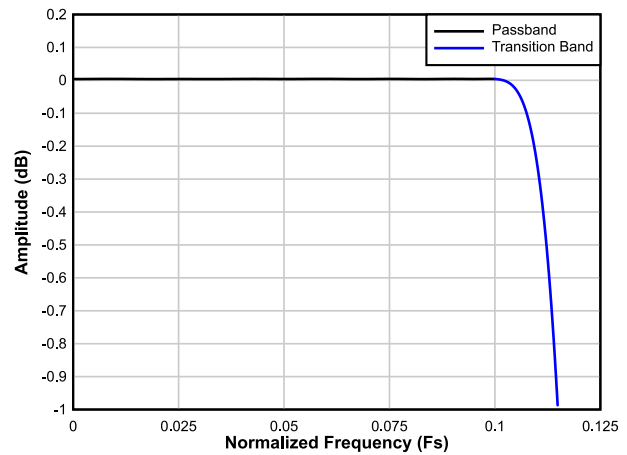
Decimation Factor N (complex)	Complex Output Bandwidth per DDC	$F_S = 1.5 \text{ Gps}$		Real Output Bandwidth per DDC	$F_S = 1.5 \text{ Gps}$	
		Complex Output Rate per DDC	Complex Output Bandwidth per DDC		Real Output Rate per DDC	Real Output Bandwidth per DDC
4	$0.8 \times F_S / 4$	375 Msps	300 MHz	$0.4 \times F_S / 4$	375 Msps	150 MHz
8	$0.8 \times F_S / 8$	187.5 Msps	150 MHz	$0.4 \times F_S / 8$	187.5 Msps	75 MHz
16	$0.8 \times F_S / 16$	93.75 Msps	75 MHz	$0.4 \times F_S / 16$	93.75 Msps	37.5 MHz
32	$0.8 \times F_S / 32$	46.875 Msps	37.5 MHz	$0.4 \times F_S / 32$	46.875 Msps	18.75 MHz
64	$0.8 \times F_S / 64$	23.4375 Msps	18.75 MHz	$0.4 \times F_S / 64$	23.4375 Msps	9.375 MHz
128	$0.8 \times F_S / 128$	11.71875 Msps	9.375 MHz	$0.4 \times F_S / 128$	11.71875 Msps	4.6875 MHz

7.3.5.1 Decimation Filter Response

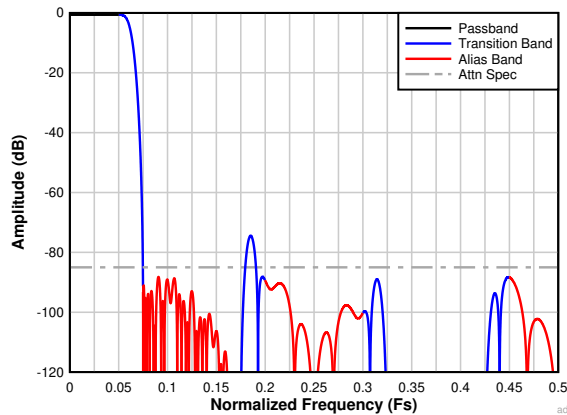
This section provides the different decimation filter responses with a normalized ADC sampling rate. The complex filter pass band is ~ 80% (-1 dB) with a minimum of 85 dB stop band rejection.



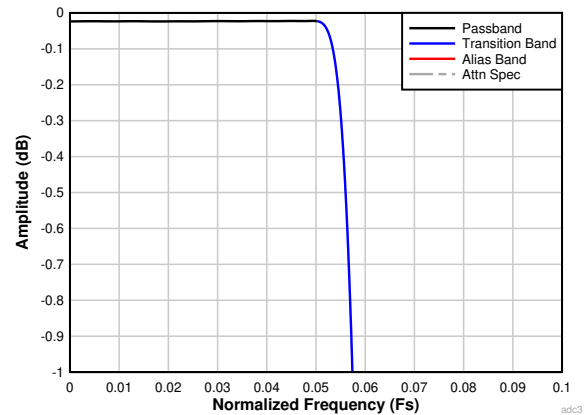
7-21. Complex Decimation by 4 Filter Response



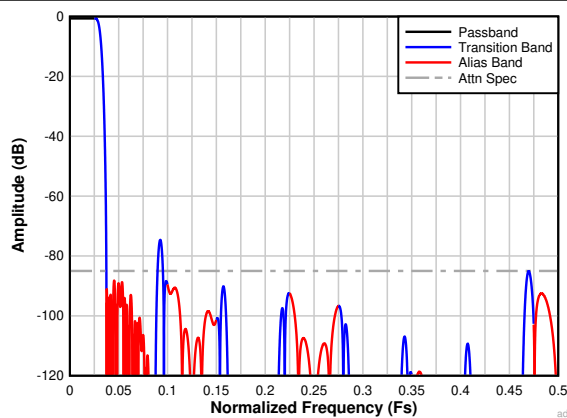
7-22. Decimation by 4 Passband Ripple Response



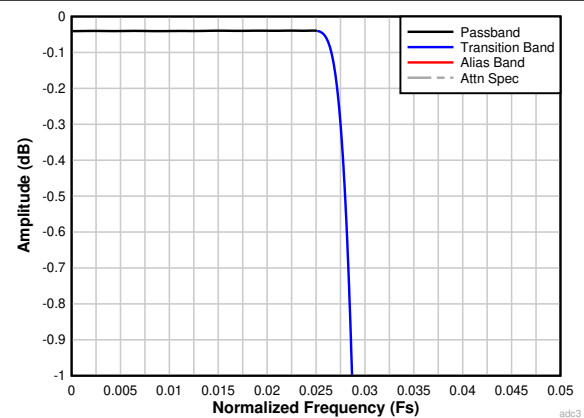
7-23. Complex Decimation by 8 Filter Response



7-24. Decimation by 8 Passband Ripple Response



7-25. Complex Decimation by 16 Filter Response



7-26. Decimation by 16 Passband Ripple Response

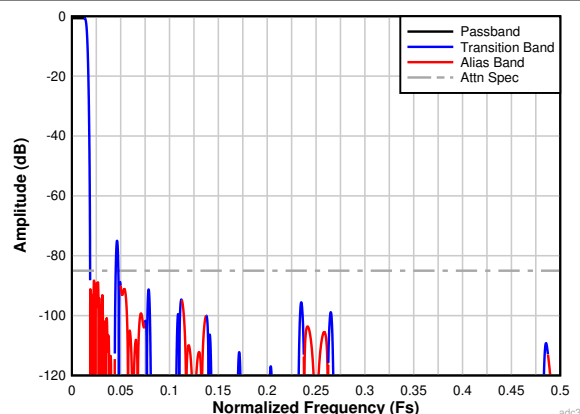


図 7-27. Complex Decimation by 32 Filter Response

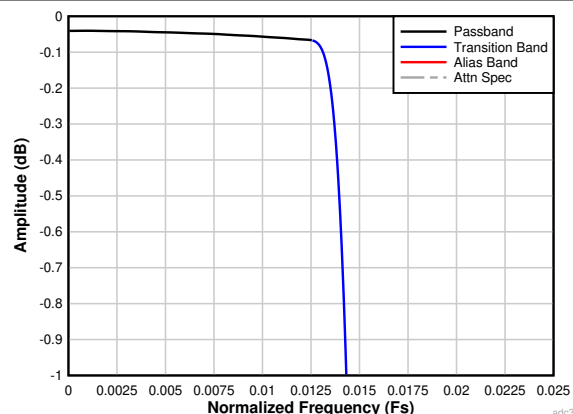


図 7-28. Decimation by 32 Passband Ripple Response

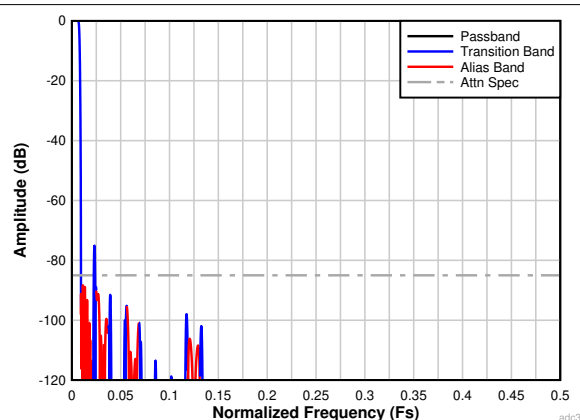


図 7-29. Complex Decimation by 64 Filter Response

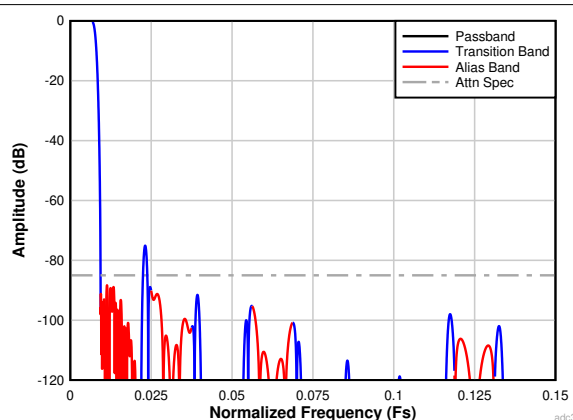


図 7-30. Complex Decimation by 64 Filter Response

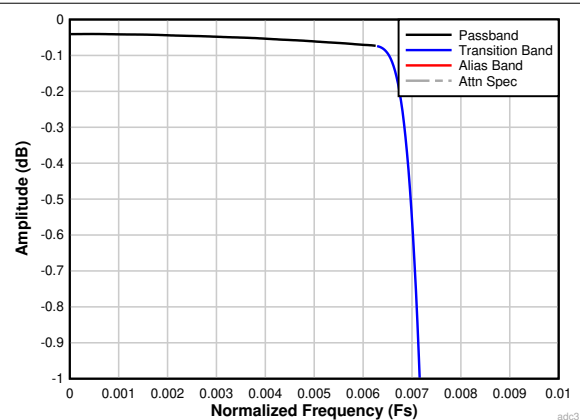


図 7-31. Decimation by 64 Passband Ripple Response

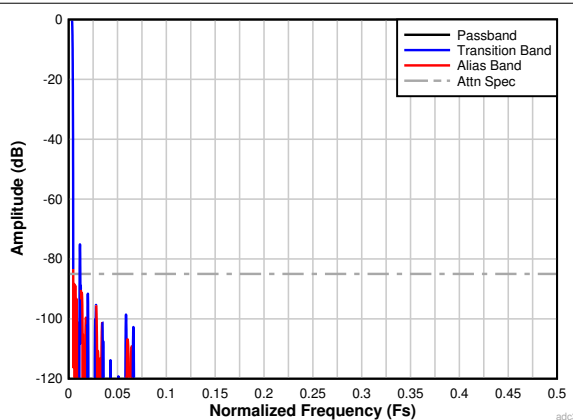


図 7-32. Complex Decimation by 128 Filter Response

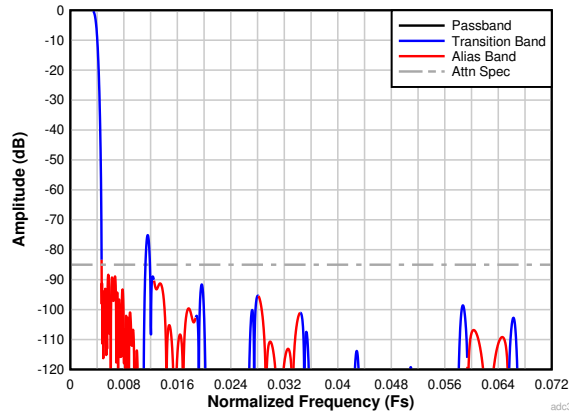


図 7-33. Complex Decimation by 128 Filter Response

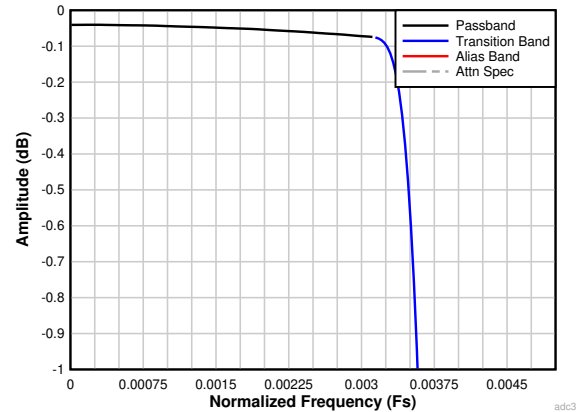


図 7-34. Decimation by 128 Passband Ripple Response

7.3.5.2 Decimation Filter Configuration

The decimation filter is configured with these register writes.

表 7-17. Register writes to enable the internal decimation filter

ADDR	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x2C		Select single/dual/quad band
0x2D		Select decimation
0x05	0x04	Select JESD page
0x22		Select LMFS mode
0x24		Select DDC CLK setting
0x25		Select JESD TX CLK DIV setting
0x9F		Select JESD PLL 1/2 settings
0xA0		Select JESD PLL INPUT1 setting
0xA1		Select JESD PLL INPUT2 settings
0xA2		Select JESD PLL INPUT3 settings

7.3.5.3 20-bit Output Mode

The device includes a 20-bit output resolution mode which can be used for high order decimation (e.g. 64x, 128x) to avoid SNR degradation due to quantization noise limitation. In this mode the output data is transmitted at 2x the output rate. The 20-bit sample from the DDC gets expanded to 32-bit by adding 12x 0s, and occupies 2 consecutive 16-bit samples. This doubles the number of octets 'F' and the proper LMFS mode and JESD PLL settings have to be selected.

So for example a single band complex decimation would go from LMFS = 2441 (16-bit output mode) to LMFS = 2481 (20-bit output mode) as illustrated in 表 7-18.

表 7-18. JESD Frame Assembly Comparison between 16-bit and 20-bit Output Mode

LMFS = 2441				LMFS = 2481							
xI ₀ [15:8]	xI ₀ [7:0]	xQ ₀ [15:8]	xQ ₀ [7:0]	xI ₀ [31:24]	xI ₀ [23:16]	xI ₀ [15:8]	xI ₀ [7:0]	xQ ₀ [31:24]	xQ ₀ [23:16]	xQ ₀ [15:8]	xQ ₀ [7:0]
				20-bit sample I				20-bit sample Q			
				0000 00000000				0000 00000000			

The 20-bit output mode is enabled by setting D7 in 0x2C (DIGITAL page) and selecting viable decimation and LMFS mode.

7.3.5.4 Dynamic Switching

The ADC32RF52 supports a dynamic switch mode between two decimation filter configurations without the need to resynchronize the JESD204B interface. This enables support for single, wideband DDC and 4 narrow band DDCs that can be switched in between with minimum impact on latency.

Two different configurations are supported in the dynamic switching mode. Each configuration maintains the # of serdes lanes and serdes output rate during the switch. 表 7-19 shows the specific supported configurations for LMFS and decimation settings for a 2 lane and a 1 lane setup. Since the amount of output data in quad band mode is four times larger compared to single band, the decimation factor in quad band mode needs to be reduced by a factor of four compared to the single band case.

表 7-19. Dynamic switch configuration modes

	Single Band DDC		Quad Band DDC	
	LMFS	Complex Decimation	LMFS	Complex Decimation
2 lanes	2-4-16-4	/16	2-16-16-1	/64
1 lane	1-4-32-4	/32	1-16-32-1	/128

There is no information in the JESD204B output data stream indicating if the output data is quad band or single band. The JESD204B receiving device controls the switching and thus needs to decode the incoming data for quad band or single band mode. The LMFS value transmitted ILA when the JESD204B link is established is always from the quad band mode to avoid ILA errors at the start of the link.

7.3.5.4.1 2 Lane Mode

JESD transmit (TX) will operate in LMFS = 2-16-16-1 in both the quad and single band modes. The JESD receiver should be configured to and switched between 2-4-16-4 and 2-16-16-1.

表 7-20. 2 lane dynamic switch frame assembly

LMFS	FRAME ASSEMBLY															
2-16-16-1	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]
	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]
2-4-16-4	AI ₀ [15:8]	AI ₀ [7:0]	AI ₁ [15:8]	AI ₁ [7:0]	AI ₂ [15:8]	AI ₂ [7:0]	AI ₃ [15:8]	AI ₃ [7:0]	AQ ₀ [15:8]	AQ ₀ [7:0]	AQ ₁ [15:8]	AQ ₁ [7:0]	AQ ₂ [15:8]	AQ ₂ [7:0]	AQ ₃ [15:8]	AQ ₃ [7:0]
	BI ₀ [15:8]	BI ₀ [7:0]	BI ₁ [15:8]	BI ₁ [7:0]	BI ₂ [15:8]	BI ₂ [7:0]	BI ₃ [15:8]	BI ₃ [7:0]	BQ ₀ [15:8]	BQ ₀ [7:0]	BQ ₁ [15:8]	BQ ₁ [7:0]	BQ ₂ [15:8]	BQ ₂ [7:0]	BQ ₃ [15:8]	BQ ₃ [7:0]

7.3.5.4.2 1 Lane Mode

JESD transmit (TX) will operate in LMFS = 1-16-32-1 in both the quad and single band modes. The JESD receiver should be configured to and switched between 1-4-32-4 and 1-16-32-1.

表 7-21. 2 lane dynamic switch frame assembly

LMFS	FRAME ASSEMBLY																
1-16-32-1	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]	...
	...	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]

表 7-21. 2 lane dynamic switch frame assembly (続き)

LMFS	FRAME ASSEMBLY																	
1-4- 32-4	AI ₀ [15:8]	AI ₀ [7:0]	AI ₁ [15:8]	AI ₁ [7:0]	AI ₂ [15:8]	AI ₂ [7:0]	AI ₃ [15:8]	AI ₃ [7:0]	AQ ₀ [15:8]	AQ ₀ [7:0]	AQ ₁ [15:8]	AQ ₁ [7:0]	AQ ₂ [15:8]	AQ ₂ [7:0]	AQ ₃ [15:8]	AQ ₃ [7:0]	...	
	...	BI ₀ [15:8]	BI ₀ [7:0]	BI ₁ [15:8]	BI ₁ [7:0]	BI ₂ [15:8]	BI ₂ [7:0]	BI ₃ [15:8]	BI ₃ [7:0]	BQ ₀ [15:8]	BQ ₀ [7:0]	BQ ₁ [15:8]	BQ ₁ [7:0]	BQ ₂ [15:8]	BQ ₂ [7:0]	BQ ₃ [15:8]	BQ ₃ [7:0]	

7.3.5.5 Numerically Controlled Oscillator (NCO)

Each digital down-converter (DDC) uses a 48-bit numerically controlled oscillator (NCO) to fine tune the frequency placement prior to the digital filtering. Different NCO frequencies for each DDC are programmed using SPI register writes and the desired NCO frequency can be selected using SPI or the GPIO pins. When using the GPIO pins for NCO frequency control, frequency hopping can be achieved in less than 1 μ s. The digital NCO is designed to have a SFDR of at least 100 dB. The number of available, programmable NCO frequencies depends on # of DDC bands used as illustrated in 表 7-22.

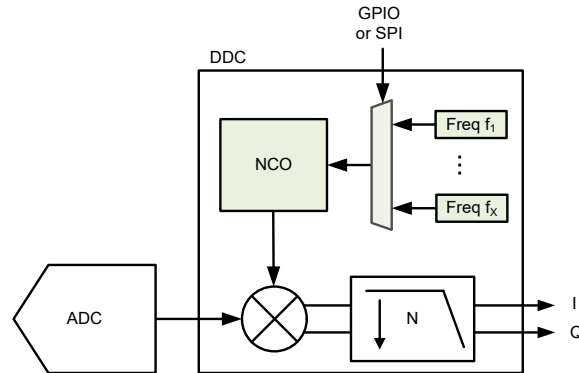


図 7-35. NCO Block Diagram

表 7-22. Available # of Frequencies per NCO depending on # of DDCs used

# of DDCs used	# of Frequencies per NCO
1	8
2	4
4	4

There are two different NCO operating modes available - phase continuous and infinite phase coherent.

Phase Continuous NCO: During a NCO frequency change, the NCO phase gradually adjusts to the new frequency as shown in 図 7-36. The 'dashed' line shows the phase of original f_1 frequency.

Infinite Phase Coherent NCO: With a phase coherent NCO, all frequencies are synchronized to a single event using SYSREF. This enables an infinite amount of frequency hops without the need to reset the NCO as phase coherency is maintained between frequency hops. This is illustrated in 図 7-36 (right). When returning to the original frequency f_1 the NCO phase appears as if the NCO had never changed frequencies.

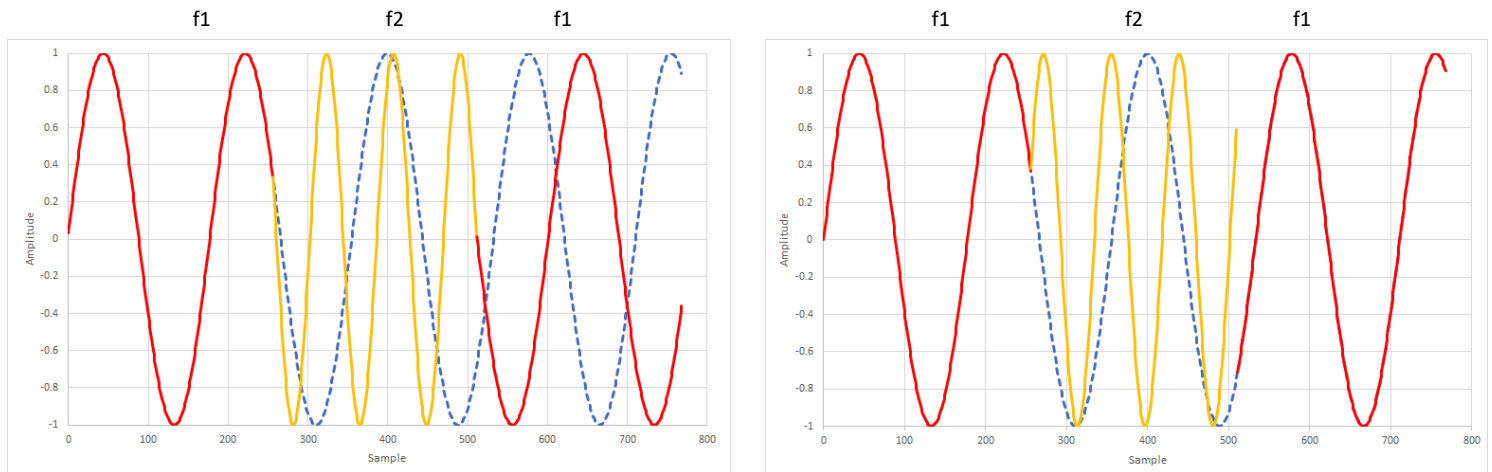


図 7-36. Phase Continuous (left) and Infinite Phase Coherent (right) NCO Frequency Switching

The oscillator generates a complex exponential sequence of:

$$e^{j\omega n} \text{ (default) or } e^{-j\omega n} \quad (1)$$

where: frequency (ω) is specified as a signed number by the 48-bit register setting

The complex exponential sequence is multiplied with the real input from the ADC to mix the desired carrier to a frequency equal to $f_{IN} + f_{NCO}$. The NCO frequency can be tuned from $-F_S/2$ to $+F_S/2$ and is processed as a signed, 2s complement number.

The NCO frequency setting is set by the 48-bit register value given and calculated as:

$$\text{NCO frequency (0 to } +F_S/2\text{): } \text{NCO} = f_{NCO} \times 2^{48} / F_S \quad (2)$$

$$\text{NCO frequency } (-F_S/2 \text{ to } 0\text{): } \text{NCO} = (f_{NCO} + F_S) \times 2^{48} / F_S \quad (3)$$

where:

- NCO = NCO register setting (decimal value)
- f_{NCO} = Desired NCO frequency (MHz)
- F_S = ADC sampling rate (MSPS)

The NCO programming is illustrated with this example:

- ADC sampling rate $F_S = 1300$ MSPS
- Desired NCO frequency = 460 MHz

$$\text{NCO frequency setting} = f_{NCO} \times 2^{48} / F_S = 460 \text{ MHz} \times 2^{48} / 1300 \text{ MSPS} = 99,598,837,913,001 \quad (4)$$

表 7-23 shows the register writes to set frequency 1 of NCO1 of DDCA to that frequency:

表 7-23. Example register writes to change NCO frequency

ADDR	DATA	DESCRIPTION
0x05	0x08	Select DDCA page
0x105	0x5A	Frequency = 460 MHz with $F_S = 1.3$ GSPS 99,598,837,913,001 = 0x5A95A95A95A9 where the MSB goes to address 0x105 and the LSB to 0x100.
0x104	0x95	
0x103	0xA9	
0x102	0x5A	
0x101	0x95	
0x100	0xA9	

表 7-23. Example register writes to change NCO frequency (続き)

ADDR	DATA	DESCRIPTION
0x181	0x00	Load and update NCO1 with the new frequency.
0x181	0x30	0x30 updates the NCO values, 0x00 clears the register for the next update.

7.3.5.6 NCO Frequency Programming

There are 4 separate NCOs per channel - one for each band (e.g. NCO1 = band 1) and 4 different frequencies can be programmed per NCO as shown in 図 7-37. The NCO frequencies are located in the DDCA/B pages (0x05 0x08 for channel A and 0x05 0x10 for channel B) in registers 0x100 to 0x17D. Depending on # of bands used, the frequencies for each NCO are selected in registers 0x3B and 0x41 (DIGITAL page) as shown in 表 7-24. If the NCO frequencies are the same for channel A and channel B they can be written to both DDCA and DDCB pages simultaneously by selecting both pages (0x05 0x18).

Channel A

Channel B

NCO1	NCO3	NCO1	NCO3
1: 0x100..0x105	1: 0x140..0x145	1: 0x100..0x105	1: 0x140..0x145
2: 0x108..0x10D	2: 0x148..0x14D	2: 0x108..0x10D	2: 0x148..0x14D
3: 0x110..0x115	3: 0x150..0x155	3: 0x110..0x115	3: 0x150..0x155
4: 0x118..0x11D	4: 0x158..0x15D	4: 0x118..0x11D	4: 0x158..0x15D
NCO2	NCO4	NCO2	NCO4
1: 0x120..0x125	1: 0x160..0x165	1: 0x120..0x125	1: 0x160..0x165
2: 0x128..0x12D	2: 0x168..0x16D	2: 0x128..0x12D	2: 0x168..0x16D
3: 0x130..0x135	3: 0x170..0x175	3: 0x130..0x135	3: 0x170..0x175
4: 0x138..0x13D	4: 0x178..0x17D	4: 0x138..0x13D	4: 0x178..0x17D

図 7-37. Multi-Band NCO

Single band DDC uses the frequencies of both NCO1 and NCO2 for a combined 8 different frequencies for NCO1 using 3 bit control (NCO2 CHx [1] and NCO1 CHx [1:0]). The NCO2 selection bit (D3) decides if frequencies from NCO1 or NCO2 are being used. In dual and quad band DDC operating mode there are 4 frequencies per NCO available and selected using 2 register bits (NCOx CHx [1:0]). The NCO frequency selection registers are shown in 表 7-24.

表 7-24. NCO Frequency Selection SPI Interface Registers

# OF BANDS	ADDR	D7	D6	D5	D4	D3	D2	D1	D0
SINGLE	0x3B	0	0	0	0	NCO2 CHA [1]	0	NCO1 CHA [1:0]	
	0x41	0	0	0	0	NCO2 CHB [1]	0	NCO1 CHB [1:0]	
DUAL	0x3B	0	0	0	0	NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	0x41	0	0	0	0	NCO2 CHB [1:0]		NCO1 CHB [1:0]	
QUAD	0x3B	NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	0x41	NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]	

To select a different frequency for the NCO, two registers (0x3B and 0x41) in the DIGITAL page have to be updated. Assuming a SPI clock frequency of 10 MHz (100 ns period), programming two registers (2x (16 bit address and 8 bit data) = 48 bit) means that the NCO frequency would be updated in ~ 5 us.

When updating the currently being used NCO frequency to a new frequency, the following command has to be written to load the new frequency into the NCO - 0x181 0x00/0x30 in each of the DDCA/B pages.

表 7-25. Example Register Writes

ADDR	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x3B	0x01	Select frequency 2 for NCO1 of channel A.
0x05	0x08	Select DDCA page
0x10D...0x108	0x..	Write new frequency in frequency 2 of NCO1 of channel A

表 7-25. Example Register Writes (続き)

ADDR	DATA	DESCRIPTION
0x181	0x00	Update NCO with current frequencies from the register map.
0x181	0x30	

The NCO phase accumulators can be reset using the external SYSREF signal. A SYSREF mask can be setup such the SYSREF signal only goes to the NCO and the remaining device remains unaffected. The following register writes configure the SYSREF mask to only affect the NCO. After completion the SYSREF mask should be set back to default.

表 7-26. Example Register Writes to configure the SYSREF MASK

ADDR	DATA	DESCRIPTION
0x05	0x18	Select DDCAB/CD page
0x181	0x40	Reset NCO phases with SYSREF toggle
0x05	0x02	Select Digital Page
0x357	0xA2	SYSREF mask settings (0x00 is mask default)
0x358	0x02	SYSREF mask settings (0x00 is mask default)

7.3.5.7 Fast Frequency Hopping

The ADC32RF52 supports several different options to update the NCO frequencies. Fast frequency hopping can be achieved in one of the following ways:

- Using the GPIO1/2 pins to select the NCO frequency
- Using the GPIO1/2, SPISEL and SCLK/SDIO pins to select the NCO frequency
- Using the GPIO1/2 pins to program the NCO frequency selection (Fast SPI)

NCO CONTROL	SCLK	SDATA	SPISEL	GPIO1	GPIO2	NCO SEL MODE
Regular SPI (default)	SPI Interface		0	used for other purpose		00
GPIO1/2	SPI Interface		0	used for NCO control		00
GPIO1/2, SPISEL, SCLK/SDATA	NCO CONTROL		1	used for NCO control		00
FAST SPI	SPI Interface		1	SDATA	SCLK	10

The internal NCO is switched very quickly however the switching time depends primarily on the time it takes to flush out the decimation filter as shown in [表 7-27](#).

表 7-27. NCO switching time ($F_S = 1.5$ GSPS) vs decimation setting

Decimation Setting	NCO Switching Time
/4	~ 500 ns
/8	~ 700 ns
/16	~ 1.2 μ s
/32	~ 2 μ s
/64	~ 4 μ s
/128	~ 8 μ s

7.3.5.7.1 Fast frequency hopping using the GPIO1/2 pins

The NCO frequency is selected as shown in [表 7-28](#). This mode is enabled with the following register writes:

1. Set 0x234 to 0x03 (NCO SEL MODE = 0, GPIO MODE = 3)

表 7-28. NCO Frequency Selection using GPIO1/2 Pins

# OF BANDS	GPIO2	GPIO1	GPIO2	GPIO1	GPIO2	GPIO1	GPIO2	GPIO1
SINGLE	0	0	0	0	0	0	NCO1 CHA [1:0]	
	0	0	0	0	0	0	NCO1 CHB [1:0]	
DUAL	0	0	0	0	NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	0	0	0	0	NCO2 CHB [1:0]		NCO1 CHB [1:0]	
QUAD	NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]	

7.3.5.7.2 Fast frequency hopping using GPIO1/2, SEN and SDATA pins

2 pins for channel A and 2 for channel B?

This mode is enabled by setting the SPISEL to logic high and using the following register writes:

1. Set 0x234 to 0x63 (NCO SEL MODE = 3, GPIO MODE = 3)

表 7-29. NCO Frequency Selection SPI Interface Registers

# OF BANDS	SDATA	SEN	GPIO2	GPIO1	SDATA	SEN	GPIO2	GPIO1
SINGLE	0	0	0	0	NCO2 CHA [1]	0	NCO1 CHA [1:0]	
	0	0	0	0	NCO2 CHB [1]	0	NCO1 CHB [1:0]	
DUAL	0	0	0	0	NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	0	0	0	0	NCO2 CHB [1:0]		NCO1 CHB [1:0]	
QUAD	NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]	

7.3.5.7.3 Fast frequency hopping using the fast SPI

In this mode the GPIO1/2 pins are used as a "fast SPI" input which only updates the NCO selection registers. No register address information needs to be sent. GPIO1 pin is SDATA and GPIO2 pin is SCLK.

This mode is enabled by setting the SPISEL to logic high and using the following register write:

1. Set 0x234 to 0x43 (NCO SEL MODE = 2, GPIO MODE = 3)

The NCO frequencies are selected as shown in [表 7-30](#).

表 7-30. NCO Frequency Programming using FAST SPI

# OF BANDS	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
SINGLE	0	0	0	0	NCO1 CHB [2]	0	NCO1 CHB [1:0]		0	0	0	0	NCO1 CHA [2]	0	NCO1 CHA [1:0]	
DUAL	0	0	0	0	NCO2 CHB [1:0]		NCO1 CHB [1:0]		0	0	0	0	NCO2 CHA [1:0]		NCO1 CHA [1:0]	
QUAD	NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]		NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	

7.3.6 JESD204B Interface

The ADC32RF52 uses the JESD204B high-speed serial interface to transfer data from the ADC to the receiving logic device. ADC32RF5x serialized lanes are capable of operating up to 13.0 Gbps, slightly above the JESD204B max lane rate. A maximum of 8 lanes can be used to allow lower lane rates for interfacing with speed limited logic devices. [Figure 7-38](#) shows a simplified block diagram of the JESD204B interface.

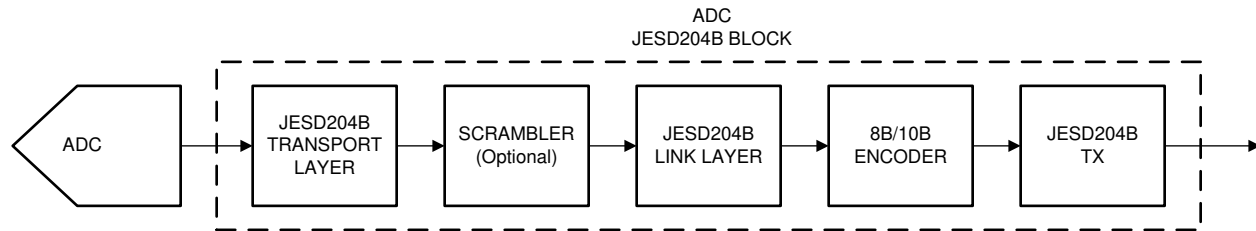


Figure 7-38. JESD204B Block Diagram

7.3.6.1 JESD204B Initial Lane Alignment (ILA)

The receiving device starts the initial lane alignment process by deasserting the $\overline{\text{SYNC}}$ signal. When a logic low state is detected on the $\overline{\text{SYNC}}$ input, the ADC starts transmitting comma characters (K28.5) to establish the code group synchronization, as shown in [Figure 7-39](#). When synchronization is completed, the receiving device reasserts the $\overline{\text{SYNC}}$ signal and the ADC starts the initial lane alignment sequence with the next local multi-frame clock (LMFC) boundary. The ADC transmits four multi-frames, each containing K frame (K is SPI programmable). Each of the multi-frames contains the frame start and frame end symbols. The second multi-frame also contains the JESD204B link configuration data.

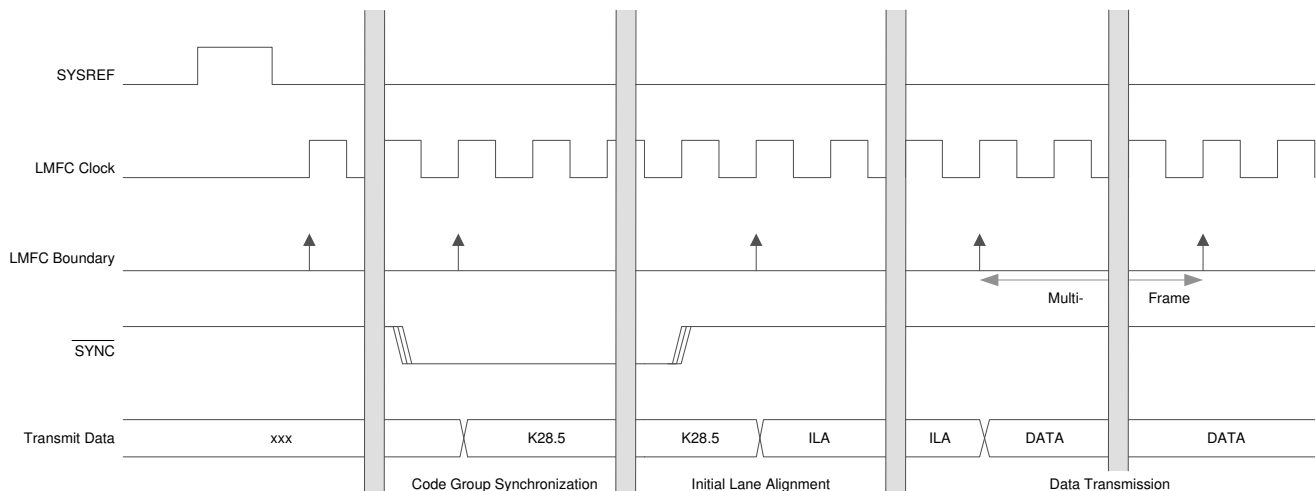


Figure 7-39. JESD204B Internal Timing Diagram

7.3.6.1.1 $\overline{\text{SYNC}}$ Signal

The $\overline{\text{SYNC}}$ signal can be issued using one of two different methods:

- One of the GPIO1/2 pins can be configured via SPI to become the $\overline{\text{SYNC}}$ input pin (address 0x234 in the digital page)
- The synchronization command can be issued via SPI register write (address 0x21 in the JESD page)

When using the GPIO1/2 pins for the $\overline{\text{SYNC}}$ signal input, the device also supports the option to invert the signal polarity (address 0x236 in the digital page).

7.3.6.2 JESD204B Frame Assembly

The JESD204B standard defines the following parameters:

- L: number of lanes per link
- M: number of converters per device
- F: number of octets per frame clock period
- S: number of samples per frame

7.3.6.3 JESD204B Frame Assembly in Bypass Mode

表 7-31 lists the available JESD204B formats and corresponding valid sampling rate ranges for the ADC32RF5x. The sampling rates are limited by the minimum and maximum SERDES line rate as well as ADC sampling clock frequencies. The JESD204B frame assembly for the different lanes is shown in 表 7-32.

When internal digital averaging is used, the output resolution is automatically adjusted from 14-bit to 16-bit to avoid quantization noise limitation.

表 7-31. JESD Mode Options: Bypass Mode

DECIMATION SETTING D (complex)	OUTPUT RESOLUTION (Bits)	L	M	F	S	MIN F _S (Gsp/s)	MAX F _S (Gsp/s)	RATIO [f _{SERDES} /F _S]
Bypass	12 ⁽¹⁾	8	2	8	20	0.5	1.5	4
	14/16 ⁽²⁾	8	2	2	4	0.5	1.5	5
		4	2	2	2	0.5	1.5	10

(1) In this output mode, two LSBs are truncated to a 12-bit output.

(2) When using digital averaging the output resolution changes to 16-bit.

表 7-32. JESD Sample Frame Assembly: Bypass Mode

OUTPUT LANE	LMFS = 82820								LMFS = 8224		LMFS = 4222	
DOUT0	A ₀ [11:4]	A ₀ [3:0], A ₁ [11:8]	A ₁ [7:0]	A ₂ [11:4]	A ₂ [3:0], A ₃ [11:8]	A ₃ [7:0]	A ₄ [11:4]	A ₄ [3:0], 0000	A ₀ [13:6]	A ₀ [5:0], 00	A ₀ [13:6]	A ₀ [5:0], 00
DOUT1	A ₅ [11:4]	A ₅ [3:0], A ₆ [11:8]	A ₆ [7:0]	A ₇ [11:4]	A ₇ [3:0], A ₈ [11:8]	A ₈ [7:0]	A ₉ [11:4]	A ₉ [3:0], 0000	A ₁ [13:6]	A ₁ [5:0], 00	A ₁ [13:6]	A ₁ [5:0], 00
DOUT2	A ₁₀ [11:4]	A ₁₀ [3:0], A ₁₁ [11:8]	A ₁₁ [7:0]	A ₁₂ [11:4]	A ₁₂ [3:0], A ₁₃ [11:8]	A ₁₃ [7:0]	A ₁₄ [11:4]	A ₁₄ [3:0], 0000	A ₂ [13:6]	A ₂ [5:0], 00	B ₀ [13:6]	B ₀ [5:0], 00
DOUT3	A ₁₅ [11:4]	A ₁₅ [3:0], A ₁₆ [11:8]	A ₁₆ [7:0]	A ₁₇ [11:4]	A ₁₇ [3:0], A ₁₈ [11:8]	A ₁₈ [7:0]	A ₁₉ [11:4]	A ₁₉ [3:0], 0000	A ₃ [13:6]	A ₃ [5:0], 00	B ₁ [13:6]	B ₁ [5:0], 00
DOUT4	B ₀ [11:4]	B ₀ [3:0], B ₁ [11:8]	B ₁ [7:0]	B ₂ [11:4]	B ₂ [3:0], B ₃ [11:8]	B ₃ [7:0]	B ₄ [11:4]	B ₄ [3:0], 0000	B ₀ [13:6]	B ₀ [5:0], 00		
DOUT5	B ₅ [11:4]	B ₅ [3:0], B ₆ [11:8]	B ₆ [7:0]	B ₇ [11:4]	B ₇ [3:0], B ₈ [11:8]	B ₈ [7:0]	B ₉ [11:4]	B ₉ [3:0], 0000	B ₁ [13:6]	B ₁ [5:0], 00		
DOUT6	B ₁₀ [11:4]	B ₁₀ [3:0], B ₁₁ [11:8]	B ₁₁ [7:0]	B ₁₂ [11:4]	B ₁₂ [3:0], B ₁₃ [11:8]	B ₁₃ [7:0]	B ₁₄ [11:4]	B ₁₄ [3:0], 0000	B ₂ [13:6]	B ₂ [5:0], 00		
DOUT7	B ₁₅ [11:4]	B ₁₅ [3:0], B ₁₆ [11:8]	B ₁₆ [7:0]	B ₁₇ [11:4]	B ₁₇ [3:0], B ₁₈ [11:8]	B ₁₈ [7:0]	B ₁₉ [11:4]	B ₁₉ [3:0], 0000	B ₃ [13:6]	B ₃ [5:0], 00		

7.3.6.4 JESD204B Frame Assembly with Complex Decimation - Single Band

表 7-33 lists the available JESD204B interface formats and corresponding valid sampling rate ranges for the ADC32RF5x with complex decimation (single band). The sampling rates are limited by the minimum and maximum SERDES line rate as well as ADC sampling clock frequencies. The JESD204B frame assembly for the different lanes is shown in 表 7-32.

表 7-33. JESD Mode Options: Complex Decimation - Single Band

DECIMATION SETTING D (complex)	L	M	F	S	MIN F _S (Gsp/s)	MAX F _S (Gsp/s)	RATIO [f _{SERDES} /(F _S /D)]
/4	4	4	2	1	0.5	1.5	20
/8							
/16							
/32							
/8	2	4	4	1	0.5	1.5	40
/16							
/32							
/64							
/8	1	4	8	1	0.5	1.3	80
/16							
/32							
/64							
/128					0.8		

表 7-34. JESD Sample Frame Assembly: Complex Decimation - Single Band

OUTPUT LANE	LMFS = 4421		LMFS = 2441				LMFS = 1481							
DOUT0	AI ₀ [15:8]	AI ₀ [7:0]	AI ₀ [15:8]	AI ₀ [7:0]	AQ ₀ [15:8]	AQ ₀ [7:0]	AI ₀ [15:8]	AI ₀ [7:0]	AQ ₀ [15:8]	AQ ₀ [7:0]	BI ₀ [15:8]	BI ₀ [7:0]	BQ ₀ [15:8]	BQ ₀ [7:0]
DOUT1	AQ ₀ [15:8]	AQ ₀ [7:0]	BI ₀ [15:8]	BI ₀ [7:0]	BQ ₀ [15:8]	BQ ₀ [7:0]								
DOUT2	BI ₀ [15:8]	BI ₀ [7:0]												
DOUT3	BQ ₀ [15:8]	BQ ₀ [7:0]												
DOUT4														
DOUT5														
DOUT6														
DOUT7														

7.3.6.5 JESD204B Frame Assembly with Complex Decimation - Dual Band

表 7-35 lists the available JESD204B interface formats and corresponding valid sampling rate ranges for the ADC32RF5x with complex decimation (dual band). The sampling rates are limited by the minimum and maximum SERDES line rate as well as ADC sampling clock frequencies. The JESD204B frame assembly for the different lanes are shown in 表 7-36 and 表 7-37.

表 7-35. JESD Mode Options: Complex Decimation - Dual Band

DECIMATION SETTING D (complex)	L	M	F	S	MIN F _S (Gbps)	MAX F _S (Gbps)	RATIO [f _{SERDES} /(F _S /D)]
/8	8	8	2	1	0.5	1.5	20
/16					0.8		
/32							
/8	4	8	4	1	0.5	1.5	40
/16					0.8		
/32							
/64							
/8	2	8	8	1	0.5	1.3	80
/16						1.5	
/32							
/64							
/128					0.8		
/16	1	8	16	1	0.5	1.3	160
/32						1.5	
/64							
/128							

表 7-36. JESD Sample Frame Assembly: Complex Decimation - Dual Band

OUTPUT T LANE	LMFS = 8821		LMFS = 4841				LMFS = 2881							
DOUT0	A1I ₀ [15:8]	A1I ₀ [7:0]	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]
DOUT1	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]
DOUT2	A2I ₀ [15:8]	A2I ₀ [7:0]	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]								
DOUT3	A2Q ₀ [15:8]	A2Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]								
DOUT4	B1I ₀ [15:8]	B1I ₀ [7:0]												
DOUT5	B1Q ₀ [15:8]	B1Q ₀ [7:0]												
DOUT6	B2I ₀ [15:8]	B2I ₀ [7:0]												
DOUT7	B2Q ₀ [15:8]	B2Q ₀ [7:0]												

表 7-37. JESD Sample Frame Assembly: Complex Decimation - Dual Band

OUTPUT LANE	LMFS = 1-8-16-1															
	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]
DOUT 0																
DOUT 1																
DOUT 2																
DOUT 3																
DOUT 4																
DOUT 5																
DOUT 6																
DOUT 7																

7.3.6.6 JESD204B Frame Assembly with Complex Decimation - Quad Band

表 7-38 lists the available JESD204B interface formats and corresponding valid sampling rate ranges for the ADC32RF5x with complex decimation (quad band). The sampling rates are limited by the minimum and maximum SERDES line rate as well as ADC sampling clock frequencies. The JESD204B frame assembly for the different lanes are shown in 表 7-39, 表 7-40 and 表 7-41.

表 7-38. JESD Mode Options: Complex Decimation - Quad Band

DECIMATION SETTING D (complex)	L	M	F	S	MIN F _S (Gbps)	MAX F _S (Gbps)	RATIO [f _{SERDES} /(F _S /D)]
/16	8	16	4	1	0.5	1.5	40
/32					0.8		
/64							
/16	4	16	8	1	0.5	1.5	80
/32					0.8		
/64							
/128							
/16	2	16	16	1	0.5	1.3	160
/32						1.5	
/64							
/128							
/16	1	16	32	1	0.5	0.65	320
/32						1.3	
/64						1.5	
/128							

表 7-39. JESD Sample Frame Assembly: Complex Decimation - Quad Band

OUTPUT LANE	LMFS = 8-16-4-1				LMFS = 4-16-8-1							
DOUT0	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]
DOUT1	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]
DOUT2	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]
DOUT3	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]
DOUT4	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]								
DOUT5	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]								
DOUT6	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]								
DOUT7	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]								

表 7-40. JESD Sample Frame Assembly: Complex Decimation - Quad Band

OUT UT LANE	LMFS = 2-16-16-1															
DOUT 0	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]
DOUT 1	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]
DOUT 2																
DOUT 3																
DOUT 4																
DOUT 5																
DOUT 6																
DOUT 7																

表 7-41. JESD Sample Frame Assembly: Complex Decimation - Quad Band

OUT UT LANE	LMFS = 1-16-32-1																
DOUT 0	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A3I ₀ [15:8]	A3I ₀ [7:0]	A3Q ₀ [15:8]	A3Q ₀ [7:0]	A4I ₀ [15:8]	A4I ₀ [7:0]	A4Q ₀ [15:8]	A4Q ₀ [7:0]	...
	...	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]	B3I ₀ [15:8]	B3I ₀ [7:0]	B3Q ₀ [15:8]	B3Q ₀ [7:0]	B4I ₀ [15:8]	B4I ₀ [7:0]	B4Q ₀ [15:8]	B4Q ₀ [7:0]
DOUT 1																	
DOUT 2																	
DOUT 3																	
DOUT 4																	
DOUT 5																	
DOUT 6																	
DOUT 7																	

7.3.7 SERDES Output MUX

The SERDES output block contains one digital mux per SERDES output lane with a 3-bit register. This allows routing any of the 8 digital streams to any output serdes transmitter as shown in the example in 図 7-40. The MUX can be used to reorder lanes as well as duplicate lane outputs (for example in LMFS = 1-4-8-1 mode the same output stream could be duplicated on all 8 lanes).

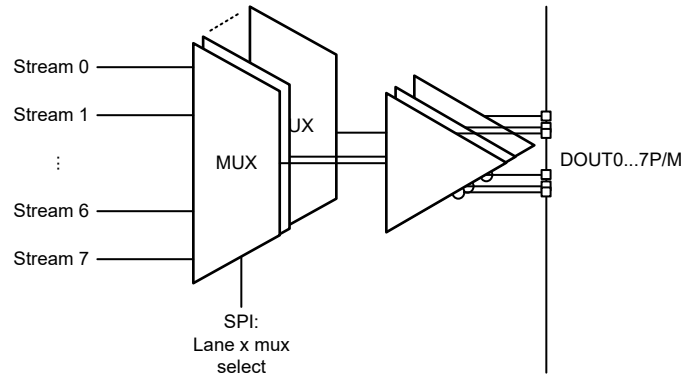


図 7-40. SERDES output mux for DOUT0

By default after power the active SERDES lanes start on lane DOUT0 as shown for the complex decimation dual band example in 表 7-42. After power up the output is transmitted on lanes DOUT0..3. Using the digital output muxes, the output data for channel B is shifted from lanes DOUT2,3 to DOUT4,5. All SERDES transmitters are powered up and enabled by default. After configuring the output mux unused lanes can be powered down to save power consumption.

表 7-42. JESD Sample Frame Assembly: Complex Decimation - Dual Band with LMFS = 4841

OUTPUT LANE	Default				Using MUX			
DOUT0	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]	A1I ₀ [15:8]	A1I ₀ [7:0]	A1Q ₀ [15:8]	A1Q ₀ [7:0]
DOUT1	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]	A2I ₀ [15:8]	A2I ₀ [7:0]	A2Q ₀ [15:8]	A2Q ₀ [7:0]
DOUT2	B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]				
DOUT3	B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]				
DOUT4					B1I ₀ [15:8]	B1I ₀ [7:0]	B1Q ₀ [15:8]	B1Q ₀ [7:0]
DOUT5					B2I ₀ [15:8]	B2I ₀ [7:0]	B2Q ₀ [15:8]	B2Q ₀ [7:0]
DOUT6								
DOUT7								

表 7-43 shows the register writes to shift the output lanes from default as illustrated in 表 7-42.

表 7-43. Example register writes to shift the output serdes lanes using the SERDES Output MUX

ADDR	DATA	DESCRIPTION
0x05	0x04	Select JESD page
0x81	0x54	Select internal JESD streams 4 and 5 to lanes DOUT2 and DOUT3
0x82	0x32	Select internal JESD streams 2 and 3 to lanes DOUT4 and DOUT5

7.3.8 Test Pattern

The ADC32RF5x provides two different options to output test patterns instead of the actual output data of the ADC to simplify the serial interface and system debug of the JESD204B digital interface link. The output data path is shown in [図 7-41](#).

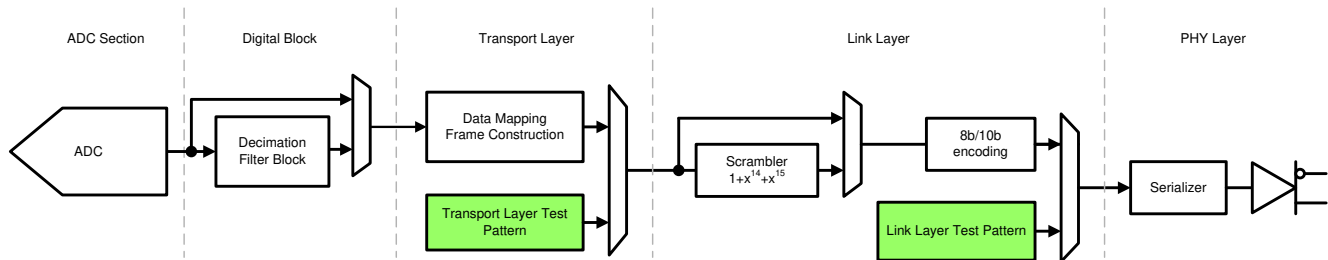


図 7-41. Test Pattern Options

The available test patterns in each block are described in [表 7-44](#). Both test pattern blocks replace output data from the digital block (and not from the ADC) and therefore are available in decimation or decimation bypass mode. The test patterns are synchronized with the SYSREF signal.

表 7-44. Test Pattern Overview

TEST PATTERN LOCATION	TYPE	8b/10b encoded	REGISTER PAGE	REGISTER
TRANSPORT LAYER	CUSTOM PATTERN	Yes	JESD 0x05 0x04	0x2E, D0
	TOGGLE 1010 PATTERN	Yes		0x2E, D1
	RAMP PATTERN	Yes		0x2E, D2
	PRBS PATTERN ($2^7 \dots 2^{31}$)	Yes		0x2F, D0
LINK LAYER	JESD204B TEST PATTERNS	Depends		0x2D, D2-D0
	PRBS PATTERN ($2^7 \dots 2^{31}$)	No		0x2F, D4

The RAMP pattern provides two different output options. Internally each ADC data bus consists of parallel data streams. The RAMP pattern is generated for each stream and a different starting value can be set for each stream. By default all starting values are 0 and increment = 1. For example, DDC bypass mode uses 4 internal data streams per ADC channel. Enabling a RAMP pattern would show a 'slow' ramp which increments once every 4 clock cycles with starting values set to 0 and ramp increment = 1.

On other hand a RAMP pattern which increments every clock cycle can be set using different starting values (e.g. 0/1/2/3) for the 4 streams and setting the RAMP increment to 4. Table [表 7-45](#) shows the register addresses for the different digital streams being used for each operating mode.

表 7-45. Register address for RAMP starting values based on operating mode

Address (JESD Page)	Bypass Mode LMFS = 8224	Complex Decimation Single Band	Complex Decimation Dual Band	Complex Decimation Quad Band
0xA4/A5/A6	A ₀	A1I ₀	A1I ₀	A1I ₀
0xA8/A9/AA	A ₁	A1Q ₀	A1Q ₀	A1Q ₀
0xAC/AD/AE	A ₂		A2I ₀	A2I ₀
0xB0/B1/B2	A ₃		A2Q ₀	A2Q ₀
0xB4/B5/B6				A3I ₀
0xB8/B9/BA				A3Q ₀
0xBC/BD/BE				A4I ₀
0xC0/C1/C2				A4Q ₀
0xC4/C5/C6	B ₀	B1I ₀	B1I ₀	B1I ₀
0xC8/C9/CA	B ₁	B1Q ₀	B1Q ₀	B1Q ₀

表 7-45. Register address for RAMP starting values based on operating mode (続き)

Address (JESD Page)	Bypass Mode LMFS = 8224	Complex Decimation Single Band	Complex Decimation Dual Band	Complex Decimation Quad Band
0xCC/CD/CE	B ₂		B2I ₀	B2I ₀
0xD0/D1/D2	B ₃		B2Q ₀	B2Q ₀
0xD4/D5/D6				B3I ₀
0xD8/D9/DA				B3Q ₀
0xDC/DD/DE				B4I ₀
0xE0/E1/E2				B4Q ₀

7.3.8.1 Transport Layer

The transport layer maps the ADC output data into 8-bit octets and constructs the JESD204B frames using the LMFS parameters. Tail bits or 0's are added when needed. Alternatively, test patterns can be substituted instead of the ADC data with the JESD frame, as shown in 表 7-44.

7.3.8.2 Link Layer

The link layer contains the scrambler and the 8b/10b encoding of any data passed on from the transport layer. Additionally, the link layer also handles the initial lane alignment sequence that can be manually restarted. The link layer test patterns are intended for testing the quality of the link (jitter testing and so forth). The test patterns do not pass through the 8b/10b encoder and contain the options listed in 表 7-44.

7.3.8.3 Internal Capture Memory Buffer

The ADC includes a small internal capture memory buffer which can store up to 64 samples. Once a strobe is given to the memory using SPI register write, the memory will store the next continuous 64 samples of one ADC channel (selected via SPI register write) and stop. The samples are captured from the ADC cores (prior to averaging or decimation). These samples can be read back using the SPI interface without involving the JESD204B interface at all.

This mode allows debug of the analog front end during the initial bring-up phase even if the JESD204B interface is not operational yet.

表 7-46. Register writes to enable the internal sample capture buffer

ADDR	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x34		Select ADC channel (D5/D4) and give strobe (D6). The 64 samples are stored in 0x800 to 0x87F in the digital page

7.4 Device Functional Modes

The device offers two different operating modes: bypass mode (1x AVG) and digital averaging (2x/4x AVG). Both operating modes use the same digital back end and JESD204B output configurations.

7.4.1 Digital Averaging

The ADC32RF52 provides a total of eight internal single core 1.5 Gsps ADCs. Normal bypass mode uses only two ADC cores (one ADC per channel). However the additional six ADCs can be used to trade off further noise density improvement against additional power consumption. [Figure 7-42](#) shows the internal block diagrams for the digital averaging modes. In averaging mode the output resolution is increased to 16-bit to avoid quantization noise limitation.

In 2x averaging mode (left) one external input is connected to the INx1 input where two ADC cores internally average the input signal. In 4x averaging (right) the signal has to be split externally and connected to both the INx1 and INx2 inputs where four ADC cores internally average the signal.

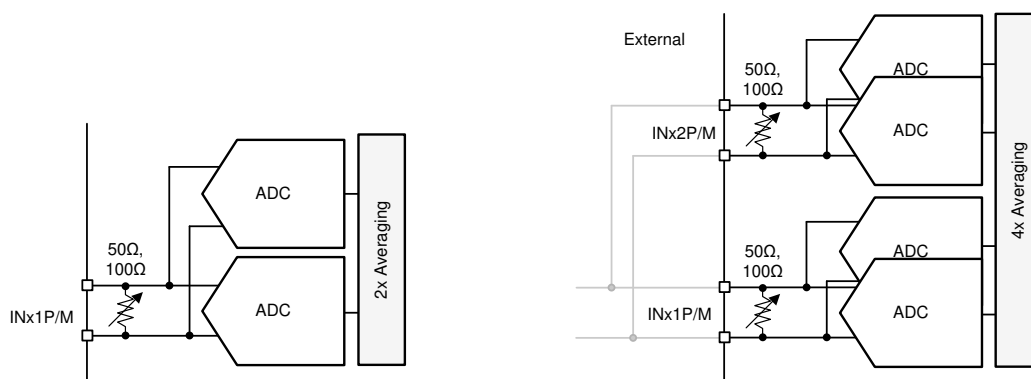


図 7-42. Internal digital averaging (left: 2x, right: 4x)

[表 7-47](#) provides a trade-off comparison of the 3 different averaging mode options vs the default, non-averaged mode.

表 7-47. Digital averaging vs full power input bandwidth (–3 dB)

# of ADCs averaged	ADC inputs used for averaging	Input Bandwidth (–3 dB)	Selected differential input termination	Noise density
Default	INx1	1.6 GHz	100 Ω	–153 dBFS/Hz
2	INx1	1.5 GHz	100 Ω	–156 dBFS/Hz
4	INx1, INx2	1.5 GHz	100 Ω	–159 dBFS/Hz

Digital averaging improves decorrelated noise contributions by 3 dB per 2x AVG (ideal) while correlated noise does not improve with averaging. Some of the dominant noise sources are correlated (e.g. clock jitter (external or first clock input buffer) or power supply noise) while others (e.g. ADC thermal noise, clock distribution buffers) are decorrelated. [Figure 7-43](#) illustrates a performance example comparison across averaging options.

SNR: When operating close to ADC fullscale, some of the SNR limitation is due to jitter and hence the SNR improvement won't reach 3 dB (2x AVG) or 6 dB (4x AVG). As the input fullscale is reduced, the clock jitter contribution to SNR becomes less and the SNR improvement is approaching the ideal 3 dB per 2x AVG. The same phenomenon can be observed when using digital decimation. As the decimation factor increases, the close-in (correlated noise) becomes the more dominating noise unless the input signal amplitude is reduced.

SFDR: The amplitude of low order harmonics (HD2-HD5) and IMD3 typically is very similar across ADCs and thus the improvement with averaging is very small.

7.5 Programming

The device is primarily configured and controlled using the serial programming interface (SPI) however it can operate in a default configuration without requiring the SPI interface. Furthermore the power down function as well as NCO frequency hopping or JESD synchronization are possible via pin control (GPIO1/2 pins).

7.5.1 GPIO Pin Control

There are several commands which can be executed using SPI programming or GPIO pins. 表 7-48 provides an overview of the commands available using GPIO pins.

表 7-48. GPIO Pin Command Options

FEATURE	DESCRIPTION
JESD SYNC	Support for single ended CMOS or differential LVDS
NCO Control	Fast frequency hopping with 3 different control options
Fast Overrange	GPIO1 indicates overrange for channel B and GPIO2 for channel B. In this mode the overrange indication is 'sticky' - the flag stays high until it is cleared using SPI commands.
Calibration Freeze	Freezes swapping of calibration ADC

7.5.2 Configuration using the SPI interface

The device has a set of internal registers that can be accessed by the serial interface formed by the SEN (serial interface enable), SCLK (serial interface clock) and SDIO (serial interface data input/output) pins. Serially shifting bits into the device is enabled when SEN is low. Serial data input are latched at every SCLK rising edge when SEN is active (low). The serial data are loaded into the register at every 24th SCLK rising edge when SEN is low. When the word length exceeds a multiple of 24 bits, the excess bits are ignored. Data can be loaded in multiples of 24-bit words within a single active SEN pulse. The interface can function with SCLK frequencies from 20 MHz down to ~ 1 MHz and also with a non-50% SCLK duty cycle.

7.5.2.1 Register Write

The internal registers can be programmed following these steps:

1. Drive the SEN pin low
2. Set the R/W bit to 0 (bit A15 of the 16-bit address) and bits A[14:12] in address field to 0.
3. Initiate a serial interface cycle by specifying the address of the register (A[11:0]) whose content is written and
4. Write the 8-bit data that are latched in on the SCLK rising edges

Figure 7-43 shows the timing requirements for the serial register write operation.

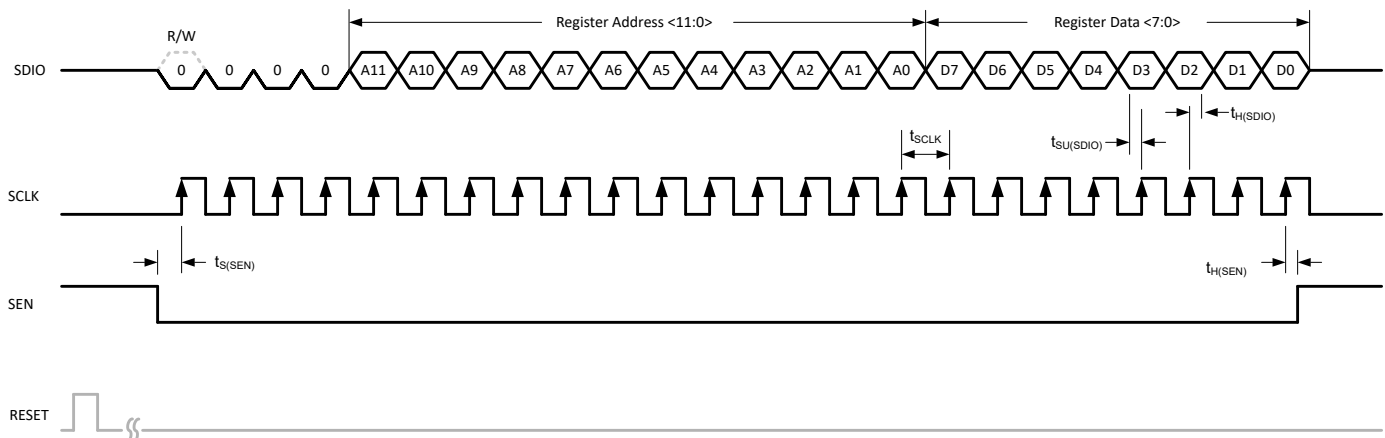


Figure 7-43. Serial Register Write Timing Diagram

7.5.2.2 Register Read

The device includes a mode where the contents of the internal registers can be read back using the SDIO pin. This readback mode can be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC. The procedure to read the contents of the serial registers is as follows:

1. Drive the SEN pin low
2. Set the R/W bit (A15) to 1. This setting disables any further writes to the registers. Set A[14:12] in address field to 0.
3. Initiate a serial interface cycle specifying the address of the register (A[11:0]) whose content must be read
4. The device outputs the contents (D[7:0]) of the selected register on the SDIO pin
5. The external controller can latch the contents at the SCLK falling edge

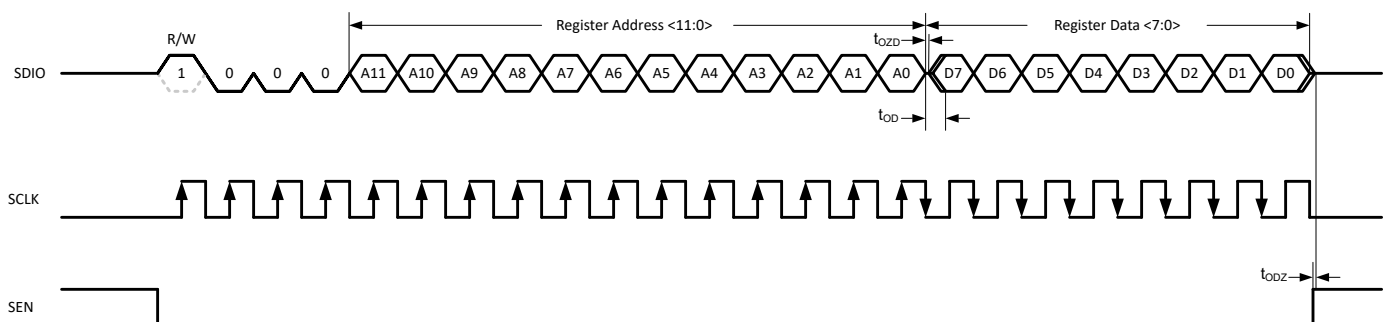


Figure 7-44. Serial Register Read Timing Diagram

7.6 Register Maps

表 7-49. Register Map Summary

PAGE	REGISTER ADDRESS	REGISTER DATA							
	A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
GLOBAL	0x00	0	0	0	0	0	0	0	RESET
	0x05	MEM PAGE	ANALOG PAGE	CALIB PAGE	DDCB PAGE	DDCA PAGE	JESD PAGE	DIGITAL PAGE	0
DIGITAL	0x2C	20-BIT OUT	DDC BAND SEL		0	0	0	DDC REAL	BYP EN
	0x2D	0	DECIMATION			0	0	0	0
	0x2E	0	0	0	0	AVG EN	AVG SEL(1)		OVR ON JESD
	0x33	0	0	0	1	FORMAT	0	GBL PDN	0
	0x34	0	MEM STROBE	MEM CH SEL		0	0	0	0
	0x3B	NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	
	0x41	NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]	
	0x22F	1	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1	SYSREF OR	1
	0x234	0	NCO SEL MODE		0	0	GPIO MODE		
	0x235	NCO SEL SOURCE							
	0x236	0	GPIO2 INV	GPIO1 INV	GPIO SWAP	0	0	SYSREF RESET	SYSREF EN
	0x237	0	0	0	0	0	GPIO2 CFG	0	GPIO1 CFG
	0x238	OVR OUTPUT CFG				0	0	0	0
JESD	0x20	K							
	0x21	0	SYNC SPI EN	SYNC SPI	0	0	SYSREF MODE		
	0x22	LMFS MODE							
	0x24	DDC CLK DIV							
	0x25	JESD TX CLK DIV							
	0x27	0	0	DROP LSB	0	0	0	CLK BAL EN	0
	0x28	JESD TX LANE EN							
	0x2B	0	0	0	0	0	0	0	SYNC INV
	0x2D	0	0	0	0	0	TEST SEQ SEL		
	0x2E	RAMP INCR				0	RAMP EN	ALT PAT	0
	0x2F	0	PRBS PAT		PRBS EN	0	0	0	0

表 7-49. Register Map Summary (続き)

PAGE	REGISTER ADDRESS	REGISTER DATA							
	A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
JESD	0x53	SCR EN	0	0	0	0	0	0	0
	0x7A	JESD LANE POL INV							
	0x80	0	LANE DOUT1 SEL			0	LANE DOUT0 SEL		
	0x81	0	LANE DOUT3 SEL			0	LANE DOUT2 SEL		
	0x82	0	LANE DOUT5 SEL			0	LANE DOUT4 SEL		
	0x83	0	LANE DOUT7 SEL			0	LANE DOUT6 SEL		
	0x84	0	0	0	0	0	0	JESD PLL FACTOR	
	0x89	TX EMPH DOUT1 [0]	TX EMPH DOUT0 [5:0]						0
	0x8A	0	0	0	TX EMPH DOUT1 [5:1]				
	0x8B	TX EMPH DOUT3 [0]	TX EMPH DOUT2 [5:0]						0
	0x8C	0	0	0	TX EMPH DOUT3 [5:1]				
	0x8D	TX EMPH DOUT5 [0]	TX EMPH DOUT4 [5:0]						0
	0x8E	0	0	0	TX EMPH DOUT5 [5:1]				
	0x8F	TX EMPH DOUT7 [0]	TX EMPH DOUT6 [5:0]						0
	0x90	0	0	0	TX EMPH DOUT7 [5:1]				
	0x9D	PD DOUT7 [0]	PD DOUT6 [0]	PD DOUT5 [0]	PD DOUT4 [0]	PD DOUT3 [0]	PD DOUT2 [0]	PD DOUT1 [0]	PD DOUT0 [0]
	0x9E	PD DOUT7 [1]	PD DOUT6 [1]	PD DOUT5 [1]	PD DOUT4 [1]	PD DOUT3 [1]	PD DOUT2 [1]	PD DOUT1 [1]	PD DOUT0 [1]
	0x9F	0	JESD PLL1			0	JESD PLL2		
	0xA0	0	JESD PLL INPUT1			0	0	0	0
	0xA1	0	JESD PLL INPUT2			0	0	0	0
	0xA2	0	0	0	0	JESD PLL INPUT3			0
	0xA4..A6	START VALUE JESD RAMP [19:0]							
	0xA8..AA	START VALUE JESD RAMP [19:0]							
	0xAC..AE	START VALUE JESD RAMP [19:0]							
	0xB0..B2	START VALUE JESD RAMP [19:0]							
	0xB4..B6	START VALUE JESD RAMP [19:0]							
	0xB8..BA	START VALUE JESD RAMP [19:0]							
	0xBC..BE	START VALUE JESD RAMP [19:0]							
	0xC0..C2	START VALUE JESD RAMP [19:0]							
	0xC4..C6	START VALUE JESD RAMP [19:0]							
	0xC8..CA	START VALUE JESD RAMP [19:0]							
	0xCC..CE	START VALUE JESD RAMP [19:0]							
	0xD0..D2	START VALUE JESD RAMP [19:0]							
	0xD4..D6	START VALUE JESD RAMP [19:0]							
	0xD8..DA	START VALUE JESD RAMP [19:0]							
	0xDC..DE	START VALUE JESD RAMP [19:0]							
	0xE0..E2	START VALUE JESD RAMP [19:0]							

表 7-49. Register Map Summary (続き)

PAGE	REGISTER ADDRESS	REGISTER DATA							
	A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
DDCA/B	0x100..0x105	NCO1 FREQUENCY1 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x108..0x10D	NCO1 FREQUENCY2 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x110..0x115	NCO1 FREQUENCY3 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x118..0x11D	NCO1 FREQUENCY4 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x120..0x125	NCO2 FREQUENCY1 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x128..0x12D	NCO2 FREQUENCY2 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x130..0x135	NCO2 FREQUENCY3 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x138..0x13D	NCO2 FREQUENCY4 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x140..0x145	NCO3 FREQUENCY1 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x148..0x14D	NCO3 FREQUENCY2 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x150..0x155	NCO3 FREQUENCY3 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x158..0x15D	NCO3 FREQUENCY4 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x160..0x165	NCO4 FREQUENCY1 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x168..0x16D	NCO4 FREQUENCY2 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x170..0x175	NCO4 FREQUENCY3 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x178..0x17D	NCO4 FREQUENCY4 [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
	0x180	0	0	DDC PDN	DDC DITH PDN	REAL DDC	DB/QB DDC	0	NCO MODE
	0x181	0	0	LOAD NCO		0	0	0	0
CALIBRATION	0x34	0	0	0	0	0	AVG SEL(2)		1
	0x45	CAL SPI	CAL GPIO	0	0	1	0	1	0
	0x298	0	0	0	0	CAL STATUS			
ANALOG	0x6D	RESET SW [1:0]		0	0	0	0	0	0
	0x6E	0	0	0	0	0	0	RESET SW [3:2]	
	0x7B	0	0	TERM A	0	0	0	0	TERM A
	0x8B	0	0	TERM B	0	0	0	0	TERM B
	0xA8	0	DITHER AMP1				0	0	0
	0xAF	DITHER DIS	0	0	1	0	0	0	0
	0xB1	DITHER DIVIDER							
	0xB4	0	0	0	0	0	0	0	SYSREF AC EN
	0xCD	0	DITH AMP2			0	0	0	0
	0xE6	TX SWING [0]	0	0	0	0	0	0	0
	0xE7	0	0	0	0	0	0	TX SWING [2:1]	

7.6.1 Detailed Register Description

図 7-45. Register 0x00

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	RESET
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-50. Register 0x00 Field Descriptions

Bit	Field	Type	Reset	Description
7-1	0	R/W	0	Must write 0
0	RESET	R/W	0	This bit resets all internal registers to the default values. Does not self clear to 0.

図 7-46. Register 0x05

7	6	5	4	3	2	1	0
MEM PAGE	ANALOG PAGE	CALIB PAGE	DDCB PAGE	DDCA PAGE	JESD PAGE	DIGITAL PAGE	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-51. Register 0x05 Field Descriptions

Bit	Field	Type	Reset	Description
7	MEM PAGE	R/W	0	This bit enables access to the MEMORY page 0: MEMORY page access disabled 1: MEMORY page access enabled
6	ANALOG PAGE	R/W	0	This bit enables access to the ANALOG page 0: ANALOG page access disabled 1: ANALOG page access enabled
5	CALIB PAGE	R/W	0	This bit enables access to the CALIBRATION page 0: CALIBRATION page access disabled 1: CALIBRATION page access enabled
4	DDCB PAGE	R/W	0	This bit enables access to the DDCB page. Contents can be written to DDCA and DDCB page simultaneously if it is identical. 0: DDCB page access disabled 1: DDCB page access enabled.
3	DDCA PAGE	R/W	0	This bit enables access to the DDCA page. Contents can be written to DDCA and DDCB page simultaneously if it is identical. 0: DDCA page access disabled 1: DDCA page access enabled
2	JESD PAGE	R/W	0	This bit enables access to the JESD page 0: JESD page access disabled 1: JESD page access enabled
1	DIGITAL PAGE	R/W	0	This bit enables access to the DIGITAL page 0: DIGITAL page access disabled 1: DIGITAL page access enabled
0	0	R/W	0	Must write 0

図 7-47. Register 0x2C (DIGITAL page)

7	6	5	4	3	2	1	0
20-BIT OUT	DDC BAND SEL		0	0	0	DDC REAL	BYP EN
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-52. Register 0x2C Field Descriptions

Bit	Field	Type	Reset	Description
7	20-BIT OUT	R/W	0	This bit enables the 20-bit output mode. It carries the output sample with 20-bit output resolution from the DDC and the sample is filled to 32-bit with 12 trailing 0s. 0: Normal operation 1: 20-bit output mode
6-5	DDC BAND SEL	R/W	00	Selects 1, 2 or 4 DDC per ADC when complex decimation is enabled 0: Single band 1: Dual band 2: Quad band 3: not used
4-2	0	R	0	Must write 0
1	DDC REAL	R/W	0	This bit enables real decimation filter (NCO = 0). BYP EN (D0) must be set to 0. 0: Complex decimation 1: Real decimation
0	BYP EN	R/W	0	This bit enables DDC bypass mode 0: Decimation filter enabled. Complex decimation by default unless D1 is set 1: Decimation filter bypass

図 7-48. Register 0x2D (DIGITAL page)

7	6	5	4	3	2	1	0
0	DECIMATION			0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-53. Register 0x2D Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-4	DECIMATION	R/W	0	Selects decimation. 0,1: not used 2: Decimation by 4 3: Decimation by 8 4: Decimation by 16 5: Decimation by 32 6: Decimation by 64 7: Decimation by 128
3-0	0	R/W	0	Must write 0

図 7-49. Register 0x2E (DIGITAL page)

7	6	5	4	3	2	1	0
0	0	0	0	AVG EN	AVG SEL (1)		OVR ON JESD
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-54. Register 0x2E Field Descriptions

Bit	Field	Type	Reset	Description
7-4	0	R/W	0	Must write 0
3	AVG EN	R/W	0	This bit enables averaging 0: no average 1: ADC averaging enabled
2-1	AVG SEL (1)	R/W	00	Selects ADC averaging. Also AVG SEL (2) in CALIBRATION page needs to be set. 0: no average 1: 2 ADC average 2: 4 ADC average
0	OVR ON JESD	R/W	0	This bit enables to output OVR flag to replace the LSB in the JESD output stream 0: OVR on GPIO 1: OVR replaces LSB on JESD stream

図 7-50. Register 0x33 (DIGITAL page)

7	6	5	4	3	2	1	0
0	0	0	1	FORMAT	0	GBL PDN	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-55. Register 0x33 Field Descriptions

Bit	Field	Type	Reset	Description
7-5	0	R/W	0	Must write 0
4	1	R/W	0	Must write 1
3	FORMAT	R/W	0	This register bit determines the output data format in DDC bypass mode only. 0: Offset Binary 1: 2s Complement DDC mode only supports 2s complement output format.
2	0	R/W	0	Must write 0
1	GBL PDN	R/W	0	This register bit enables global power down mode 0: normal operation 1: global power down mode enabled
0	0	R/W	0	Must write 0

図 7-51. Register 0x34 (DIGITAL page)

7	6	5	4	3	2	1	0
0	MEM STROBE	MEM CH SEL		0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-56. Register 0x34 Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6	MEM STROBE	R/W	0	This register enables fast power down mode 0: normal operation 1: fast power down mode enabled

表 7-56. Register 0x34 Field Descriptions (続き)

Bit	Field	Type	Reset	Description
5-4	MEM CH SEL	R/W	0	This register selects which ADC channel is used to fill up the capture sample buffer. Only 1 channel can be selected at a time and the samples are captured from the ADC core without averaging or decimation. 00: capture memory is filled from chA1 input 01: capture memory is filled from chA2 input 10: capture memory is filled from chB1 input 11: capture memory is filled from chB2 input
0	0	R/W	0	Must write 0

図 7-52. Register 0x3B (DIGITAL page)

7	6	5	4	3	2	1	0
NCO4 CHA [1:0]		NCO3 CHA [1:0]		NCO2 CHA [1:0]		NCO1 CHA [1:0]	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-57. Register 0x3B Field Descriptions

Bit	Field	Type	Reset	Description
7-6	NCO4 CHA [1:0]	R/W	00	This register is used when selecting the NCO frequency for channel A, band 4 with the SPI interface in quad DDC mode.
5-4	NCO3 CHA [1:0]	R/W	00	This register is used when selecting the NCO frequency for channel A, band 3 with the SPI interface in quad DDC mode.
3-2	NCO2 CHA [1:0]	R/W	00	In single band DDC mode this register is used to select between NCO bank 1 or 2. 00: NCO bank 1 01: NCO bank 2 In dual band DDC mode this register is used to select the NCO frequency for channel A, band 2 with the SPI interface.
1-0	NCO1 CHA [1:0]	R/W	00	This register is used when selecting the NCO1 of channel A with the SPI interface.

図 7-53. Register 0x41 (DIGITAL page)

7	6	5	4	3	2	1	0
NCO4 CHB [1:0]		NCO3 CHB [1:0]		NCO2 CHB [1:0]		NCO1 CHB [1:0]	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-58. Register 0x41 Field Descriptions

Bit	Field	Type	Reset	Description
7-6	NCO4 CHB [1:0]	R/W	00	This register is used when selecting the NCO frequency for channel B, band 4 with the SPI interface in quad DDC mode.
5-4	NCO3 CHB [1:0]	R/W	00	This register is used when selecting the NCO frequency for channel B, band 3 with the SPI interface in quad DDC mode.
3-2	NCO2 CHB [1:0]	R/W	00	In single band DDC mode this register is used to select between NCO bank 1 or 2 of channel B. 00: NCO bank 1 01: NCO bank 2 In dual band DDC mode this register is used to select the NCO frequency for channel B, band 2 with the SPI interface.
1-0	NCO1 CHB [1:0]	R/W	00	This register is used when selecting the NCO1 of channel B with the SPI interface.

図 7-54. Register 0x22F (DIGITAL page)

7	6	5	4	3	2	1	0
1	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1	SYSREF OR	1
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-59. Register 0x22F Field Descriptions

Bit	Field	Type	Reset	Description
7	1	R/W	1	Must write 1
6-2	SYSREF X1..5	R/W	0	These bits are the XOR flags from the SYSREF window monitoring circuitry. The sampling clock gets delayed internally by ~ 160 ps and used to capture the SYSREF signal. If a SYSREF signal transition happens within +/- 50 ps of the SYSREF capture the appropriate XOR flag gets raised. These bits are not sticky - they get overwritten with the next SYSREF rising edge. X1: Window from 110 ps to 135 ps after the rising sampling clock edge X2: Window from 135 ps to 160 ps after the rising sampling clock edge X3: Window from 160 ps to 176 ps after the rising sampling clock edge X4: Window from 176 ps to 192 ps after the rising sampling clock edge X5: Window from 192 ps to 208 ps after the rising sampling clock edge 0: No SYSREF transition detected 1: SYSREF transition detected within given window
1	SYSREF OR	R/W	0	This bit is the output of the five SYSREF XOR flags logically OR'ed together. 0: no SYSREF flag raised 1: one of the five SYSREF XOR flags is raised.
0	1	R/W	1	Must write 1

図 7-55. Register 0x234 (DIGITAL page)

7	6	5	4	3	2	1	0
0	NCO SEL MODE			0	0	GPIO MODE	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-60. Register 0x234 Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-5	NCO SEL MODE	R/W	00	These bits select control of the NCO selection in complex decimation. 0: NCO selection using GPIO pins (GPIO MODE (D2-D0) needs to be set accordingly) 2: GPIO1/2 pins are used as a fast serial interface only for the NCO selection for each digital mixer 3: GPIO1/2, SCLK, SDIO pins are used for NCO selection. others: not used Register 0x235 may need to be set as well.
4-3	0	R/W	0	Must write 0

表 7-60. Register 0x234 Field Descriptions (続き)

Bit	Field	Type	Reset	Description
2-0	GPIO MODE	R/W	000	This register sets the functionality of the two GPIO pins 0: GPIO pins are used as SYNC input (LVDS), GPIO1 = SYNCP, GPIO2 = SYNCM 1: GPIO1 is used as SYNC input (CMOS) 3: Both GPIO pins are used to select NCOs for the decimation filters 4: GPIO1 is used to disable the calibration 5: GPIO1 is used as start of SYSREF counter others: not used

図 7-56. Register 0x235 (DIGITAL page)

7	6	5	4	3	2	1	0
NCO SEL SOURCE							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-61. Register 0x235 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	NCO SEL SOURCE	R/W	0	This register works in conjunction with NCO SEL MODE (0x234). 0x00: NCO selection other than regular SPI (GPIO, Fast SPI etc) 0xFF: NCO selection using regular SPI with addresses 0x3B/41.

図 7-57. Register 0x236 (DIGITAL page)

7	6	5	4	3	2	1	0
0	GPIO2 INV	GPIO1 INV	GPIO SWAP	0	0	SYSREF RESET	SYSREF EN
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-62. Register 0x236 Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6	GPIO2 INV	R/W	0	This bit inverts polarity of the GPIO2 pin 0: Polarity as is 1: Polarity inverted
5	GPIO1 INV	R/W	0	This bit inverts polarity of the GPIO1 pin 0: Polarity as is 1: Polarity inverted
4	GPIO SWAP	R/W	0	This bit swaps GPIO1 and GPIO2 pins internally. 0: Normal operation 1: GPIO1 and GPIO2 are swapped
3-2	0	R/W	0	Must write 0
1	SYSREF RESET	R/W	0	This bit enables and clears the internal SYSREF counter: 0: Normal operation 1: Enables SYSREF and clears the internal counter
0	SYSREF EN	R/W	0	This bit starts the internal SYSREF counter: 0: Normal operation 1: Starts SYSREF counter

図 7-58. Register 0x237 (DIGITAL page)

7	6	5	4	3	2	1	0
0	0	0	0	0	GPIO2 CFG	0	GPIO1 CFG
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-63. Register 0x237 Field Descriptions

Bit	Field	Type	Reset	Description
7-3	0	R/W	0	Must write 0
2	GPIO2 CFG	R/W	0	This bit configures GPIO2 pin either as input or output. 0: GPIO2 pin is input 1: GPIO2 pin is output
1	0	R/W	0	Must write 0
0	GPIO1 CFG	R/W	0	This bit configures GPIO1 pin either as input or output. 0: GPIO1 pin is input 1: GPIO1 pin is output

図 7-59. Register 0x238 (DIGITAL page)

7	6	5	4	3	2	1	0
OVR OUTPUT CFG				0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-64. Register 0x238 Field Descriptions

Bit	Field	Type	Reset	Description
7-4	OVR OUTPUT CFG	R/W	0000	This bit configures if the overrange indication (OVR) is output on JESD output stream or on GPIO pins 0000: OVR on JESD 1111: OVR on GPIO
3-0	0	R/W	0	Must write 0

図 7-60. Register 0x20 (JESD page)

7	6	5	4	3	2	1	0
K							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-65. Register 0x20 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	K	R/W	00000000	This is JESD204B parameter K which sets number of frames in a multi-frame. Bit value is set as K minus 1.

図 7-61. Register 0x21 (JESD page)

7	6	5	4	3	2	1	0
0	SYNC SPI EN	SYNC SPI	0	0	SYSREF MODE		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-66. Register 0x21 Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6	SYNC SPI EN	R/W	0	This bit enables JESD SYNC control using SPI (ignoring SYNC using GPIO1/2 pins) using bit D5 (SYNC SPI). 0: SPI SYNC disabled 1: SPI SYNC (using register bit D5) enabled
5	SYNC SPI	R/W	0	This bit enables JESD SYNC. SYNC control via SPI must be enabled also (D6). 0: ADC outputs data (SYNC disabled) 1: SYNC enabled (ADC outputs K28.5 characters for JESD interface synchronization)
4-3	0	R/W	0	Must write 0
2-0	SYSREF MODE	R/W	000	This register controls how the ADC processes incoming SYSREF pulses. 0: Ignore all SYSREF pulses 1: Use all SYSREF pulses 2: Don't use SYSREF pulses 3: Skip one SYSREF pulse then use only the next one 4: Skip one SYSREF pulse then use all pulses 5: Skip two SYSREF pulses and then use one 6: Skip two SYSREF pulses and then use all

図 7-62. Register 0x22 (JESD page)

7	6	5	4	3	2	1	0
JESD MODE							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-67. Register 0x22 Field Descriptions

Bit	Field	Type	Reset	Description
7:0	JESD MODE	R/W	00000000	This register sets the LMFS configuration 0: LMFS = 8-2-8-20 (also bit DROP LSB in 0x27 needs to be set) 1: LMFS = 8-2-2-4 3: LMFS = 8-4-2-2 4: LMFS = 8-16-4-1 5: LMFS = 4-16-8-1 6: LMFS = 2-16-16-1 7: LMFS = 1-16-32-1 8: LMFS = 8-8-2-1 9: LMFS = 4-8-4-1 10: LMFS = 2-8-8-1 11: LMFS = 1-8-16-1 12: LMFS = 4-4-2-1 13: LMFS = 2-4-4-1 14: LMFS = 1-4-8-1 15: LMFS = 2-2-2-1 16: LMFS = 1-2-4-1 others: not used

図 7-63. Register 0x24 (JESD page)

7	6	5	4	3	2	1	0
DDC CLK DIV							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-68. Register 0x24 Field Descriptions

Bit	Field	Type	Reset	Description
7:0	DDC CLK DIV	R/W	00000000	This register sets the internal clock divider when using the decimation filter. See 表 7-70 .

図 7-64. Register 0x25 (JESD page)

7	6	5	4	3	2	1	0
JESD TX CLK DIV							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-69. Register 0x25 Field Descriptions

Bit	Field	Type	Reset	Description
7:0	JESD TX CLK DIV	R/W	00000000	This register sets the internal clock divider for the selected LMFS output mode. See 表 7-70 for 16-bit and 表 7-71 for 20-bit output.

表 7-70. Register Settings for 0x24/0x25 Based on Bypass/Decimation and LMFS Mode (16-bit Output)

LMFS	0x24 (DDC CLK DIV)							0x25 (JESD TX CLK DIV)						
	BYP	/4	/8	/16	/32	/64	/128	BYP	/4	/8	/16	/32	/64	/128
8-2-2-4	0							0						
8-2-8-20	0							4						
8-4-8-10	1							4						
8-4-2-2	1	0	0	0	0			0	1	1	1	1		
8-8-2-1		0	0	0	0	0			0	0	0	0	0	
8-16-4-1		1	1	1	1	1	1		0	0	0	0	0	0
4-2-2-2		0	0	0	0	0	0		1	1	1	1	1	1
4-4-2-1		0	0	0	0	0			0	0	0	0	0	
4-8-4-1		1	1	1	1	1	1		0	0	0	0	0	0
4-16-8-1		3	3	3	3	3	3		0	0	0	0	0	0
2-2-2-1		0	0	0	0	0			0	0	0	0	0	
2-4-4-1		1	1	1	1	1	1		0	0	0	0	0	0
2-8-8-1		3	3	3	3	3	3		0	0	0	0	0	0
2-16-16-1			7	7	7	7	7			0	0	0	0	0
1-2-4-1		1	1	1	1	1	1		0	0	0	0	0	0
1-4-8-1		3	3	3	3	3	3		0	0	0	0	0	0
1-8-16-1			7	7	7	7	7			0	0	0	0	0
1-16-32-1				15	15	15	15				0	0	0	0

表 7-71. Register Settings for 0x24/0x25 Based on Decimation and LMFS Mode (20-bit Output).

LMFS	0x24 (DDC CLK DIV)							0x25 (JESD TX CLK DIV)						
	BYP	/4	/8	/16	/32	/64	/128	BYP	/4	/8	/16	/32	/64	/128
8-8-4-1		1	1	1	1	1	1		0	0	0	0	0	0
8-16-8-1		3	3	3	3	3	3		0	0	0	0	0	0
4-4-4-1		1	1	1	1	1	1		0	0	0	0	0	0
4-8-8-1		3	3	3	3	3	3		0	0	0	0	0	0
4-16-16-1			7	7	7	7	7			0	0	0	0	0
2-2-4-1		1	1	1	1	1	1		0	0	0	0	0	0
2-4-8-1		3	3	3	3	3	3		0	0	0	0	0	0
2-8-16-1			7	7	7	7	7			0	0	0	0	0
2-16-32-1				15	15	15	15				0	0	0	0
1-2-8-1		3	3	3	3	3	3		0	0	0	0	0	0
1-4-16-1			7	7	7	7	7			0	0	0	0	0
1-8-32-1				15	15	15	15				0	0	0	0
1-16-64-1					31	31	31					0	0	0

図 7-65. Register 0x27 (JESD page)

7	6	5	4	3	2	1	0
0	0	DROP LSB	0	0	0	CLK BAL EN	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-72. Register 0x27 Field Descriptions

Bit	Field	Type	Reset	Description
7-6	0	R/W	0	Must write 0
5	DROP LSB	R/W	0	This register needs to be set when using the 12-bit output LMFS mode. 0: Drop LSB disabled 1: Drop LSB enabled when using LMFS = 8-2-8-2-20
4-2	0	R/W	0	Must write 0
1	CLK BAL EN	R/W	0	This register bit needs to be enabled in bypass mode LMFS = 8-2-2-4 only to improve some internal clock balancing. 0: CLK BAL disabled 1: CLK BAL EN. Set for LMFS = 8-2-2-4
0	0	R/W	0	Must write 0

図 7-66. Register 0x28 (JESD page)

7	6	5	4	3	2	1	0
JESD LANE EN							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-73. Register 0x28 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	JESD LANE EN	R/W	11111111	This register turns on individual output lanes 0: Lane powered down 1: Serdes lane enabled D0: Lane DOUT0 D1: Lane DOUT1 ... D7: Lane DOUT7

図 7-67. Register 0x2B

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	SYNC INV
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-74. Register 0x2B Field Descriptions

Bit	Field	Type	Reset	Description
7-1	0	R/W	0	Must write 0
0	SYNC INV	R/W	0	This register inverts the polarity from external SYNC pin 0: Polarity as is 1: Polarity inverted

図 7-68. Register 0x2D (JESD page)

7	6	5	4	3	2	1	0
0	0	0	0	0	JESD SEQ SEL		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-75. Register 0x2D Field Descriptions

Bit	Field	Type	Reset	Description
7-3	0	R/W	0	Must write 0
2-0	JESD SEQ SEL	R/W	000	This register selects the JESD test pattern sequence 0: Test sequence disabled 1: Repeat D21.5 high frequency pattern for random jitter (RJ) 2: Repeat K28.5 mixed frequency pattern for deterministic jitter (DJ) 3: Repeat initial lane alignment (ILA) sequence 4: Modified random pattern 5: Scrambled jitter pattern 6: Repeat K28.7 low frequency pattern 7: Short test pattern

図 7-69. Register 0x2E (JESD page)

7	6	5	4	3	2	1	0
RAMP INCR				0	RAMP EN	ALT PAT	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-76. Register 0x2E Field Descriptions

Bit	Field	Type	Reset	Description
7-4	RAMP INCR	R/W	0000	This register value sets the increment step size for the ramp pattern on 16-bit output. The step size is RAMP INCR plus 1.
3	0	R/W	0	Must write 0
2	RAMP EN	R/W	0	Enables RAMP output pattern in the TRANSPORT LAYER.
1	ALT PAT	R/W	0	Enables a toggle pattern switching between 0x0000 and 0xFFFF in the TRANSPORT LAYER
0	0	R/W	0	Must write 0

図 7-70. Register 0x2F (JESD page)

7	6	5	4	3	2	1	0
0	SERDES PRBS		SERDES PRBS EN	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-77. Register 0x2F Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-5	SERDES PRBS	R/W	0	This register selects the PRBS pattern in the LINK LAYER (no 8b/10b encoding). PRBS pattern must be enabled (D4). 0: PRBS 2 ⁷ -1 1: PRBS 2 ¹⁵ -1 2: PRBS 2 ²³ -1 3: PRBS 2 ³¹ -1
4	SERDES PRBS EN	R/W	0	This register enables PRBS test pattern in the LINK LAYER 0: Test pattern mode disabled 1: PRBS test pattern mode enabled
3-0	0	R/W	0	Must write 0

図 7-71. Register 0x53 (JESD page)

7	6	5	4	3	2	1	0
SCR EN	0	0	0	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-78. Register 0x53 Field Descriptions

Bit	Field	Type	Reset	Description
7	SCR EN	R/W	0	Enables scrambling of the JESD output data 0: Output scrambling disabled 1: Output scrambling enabled
6-0	0	R/W	0	Must write 0

図 7-72. Register 0x7A (JESD page)

7	6	5	4	3	2	1	0
JESD LANE POL INV							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-79. Register 0x7A Field Descriptions

Bit	Field	Type	Reset	Description
7-0	JESD LANE POL INV	R/W	00000000	This register inverts the polarity of the individual SERDES output lanes. Register bit D0 corresponds to SERDES lane DOUT0, D1 to DOUT1 etc 0: Output polarity as is 1: Output polarity inverted

図 7-73. Register 0x80/81/82/83 (JESD page)

ADDR	7	6	5	4	3	2	1	0
0x80	0	LANE DOUT1 SEL			0	LANE DOUT0 SEL		
0x81	0	LANE DOUT3 SEL			0	LANE DOUT2 SEL		
0x82	0	LANE DOUT5 SEL			0	LANE DOUT4 SEL		
0x83	0	LANE DOUT7 SEL			0	LANE DOUT6 SEL		
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-80. Register 0x80/81/82/83 Field Descriptions

Bit	Field	Type	Reset	Description
7,3	0	R/W	0	Must write 0
6-4	LANE DOUT1/3/5/7 SEL	R/W	000	These register bits control the output mux. Any physical serdes output lane (DOUTx) can be connected to any JESD digital stream. By default lane DOUT0 is connected to JESD stream 0, lane DOUT1 to JESD stream 1 etc. 0: JESD stream 0 1: JESD stream 1 ... 7: JESD stream 7
2-0	LANE DOUT0/2/4/6 SEL	R/W	000	

図 7-74. Register 0x84 (JESD page)

7	6	5	4	3	2	1	0
0	0	0	0	0	0	JESD PLL FACTOR	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-81. Register 0x84 Field Descriptions

Bit	Field	Type	Reset	Description
7-2	0	R/W	0	Must write 0
1-0	JESD PLL FACTOR	R/W	00	This register bit must be set for 12-bit output LMFS = 8-2-8-20 only. 0: all other JESD LMFS modes 1: Set for LMFS = 8-2-8-20

図 7-75. Register 0x89/8A/8B/8C/8D/8E/8F/90 (JESD page)

ADDR	7	6	5	4	3	2	1	0
0x89	TX EMPH DOUT1 [0]	TX EMPH DOUT0 [5:0]						0
0x8A	0	0	0	TX EMPH DOUT1 [5:1]				
0x8B	TX EMPH DOUT3 [0]	TX EMPH DOUT2 [5:0]						0
0x8C	0	0	0	TX EMPH DOUT3 [5:1]				
0x8D	TX EMPH DOUT5 [0]	TX EMPH DOUT4 [5:0]						0
0x8E	0	0	0	TX EMPH DOUT5 [5:1]				
0x8F	TX EMPH DOUT7 [0]	TX EMPH DOUT6 [5:0]						0
0x90	0	0	0	TX EMPH DOUT7 [5:1]				
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-82. Register 0x89/8A/8B/8C/8D/8E/8F/90 Field Descriptions

Bit	Field	Type	Reset	Description
7-5,0	0	R/W	0	Must write 0
6-1	TX EMPH DOUT0/2/4/6 [5:0]	R/W	000000	These bits select the amount of de-emphasis for the JESD output transmitter. The de-emphasis value in dB is measured as the ratio between the peak value after the signal transition to the settled value of the voltage in one bit period. 0: 0 dB 1: -1 dB 3: -2 dB 7: -4.1 dB 15: -6.2 dB 31: -8.2 dB 63: -11.5 dB
4-0,7	TX EMPH DOUT1/3/5/7 [5:0]	R/W	000000	

図 7-76. Register 0x9D/9E (JESD page)

7	6	5	4	3	2	1	0
PD DOUT7 [0,1]	PD DOUT6 [0,1]	PD DOUT5 [0,1]	PD DOUT4 [0,1]	PD DOUT3 [0,1]	PD DOUT2 [0,1]	PD DOUT1 [0,1]	PD DOUT0 [0,1]
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-83. Register 0x9D/9E Field Descriptions

Bit	Field	Type	Reset	Description
7-0	PD DOUTx [0,1]	R/W	0	Register 0x9D and 0x9E allow power down of individual serdes output lanes. Register 0x9D (PD DOUTx [0]) covers the output driver, 0x9E (PD DOUTx [1]) covers the associated internal high-speed data clock. 0: Output lane enabled 1: Output lane powered down

図 7-77. Register 0x9F (JESD page)

7	6	5	4	3	2	1	0
0	JESD PLL1			0	JESD PLL2		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-84. Register 0x9F Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-4	JESD PLL1	R/W	000	Internal JESD PLL input divider setting. See 表 7-86 how to configure it for the different decimation and LMFS settings.
3	0	R/W	0	Must write 0
2-0	JESD PLL2	R/W	000	Internal JESD PLL input divider setting. See 表 7-86 how to configure it for the different decimation and LMFS settings.

図 7-78. Register 0xA0/A1/A2 (JESD page)

ADDR	7	6	5	4	3	2	1	0
0xA0	0	JESD PLL INPUT1			0	0	0	0
0xA1	0	JESD PLL INPUT2			0	0	0	0
0xA2	0	0	0	0	JESD PLL INPUT3			0
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-85. Register 0xA0/A1/A2 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	0	R/W	0	Must write 0
6-4	JESD PLL INPUT1/2	R/W	000	Internal JESD PLL input divider setting. See 表 7-86 (16-bit output) and 表 7-87 (20-bit output) how to configure it for the different decimation and LMFS settings.
3-1	JESD PLL INPUT3	R/W	000	Internal JESD PLL input divider setting. See 表 7-86 (16-bit output) and 表 7-87 (20-bit output) how to configure it for the different decimation and LMFS settings.

表 7-86. Register settings for 0x9F/A0/A1/A2 based on bypass/decimation and LMFS mode (16-bit output)

JESD PLL1/2, JESD PLL INPUT 1/2															JESD PLL INPUT 3						
LMFS	BYP	/4	/8	/16	/32	/64	/128	BYP	/4	/8	/16	/32	/64	/128							
8-2-2-4	0							0													
8-2-8-20	0							0													
8-4-8-10	0							1													

表 7-86. Register settings for 0x9F/A0/A1/A2 based on bypass/decimation and LMFS mode (16-bit output)
(続き)

	JESD PLL1/2, JESD PLL INPUT 1/2							JESD PLL INPUT 3						
8-4-2-2	0	1	2	3	3			1	0	0	0	2		
8-8-2-1		0	1	2	3	4			0	0	0	0	0	
8-16-4-1		0	0	1	2	3	4		1	0	0	0	0	0
4-2-2-2		1	2	3					0	0	0			
4-4-2-1		0	1	2	3	4			0	0	0	0	0	
4-8-4-1		0	0	1	2	3	4		1	0	0	0	0	0
4-16-8-1		0	0	0	1	2	3		3	1	0	0	0	0
2-2-2-1		0	1	2	3	4			0	0	0	0	0	
2-4-4-1		0	0	1	2	3	4		0	0	0	0	0	0
2-8-8-1		0	0	0	1	2	3		3	1	0	0	0	0
2-16-16-1			0	0	0	1	2			3	1	0	0	0
1-2-4-1		0	0	1	2	3	4		1	0	0	0	0	0
1-4-8-1		0	0	0	1	2	3		3	1	0	0	0	0
1-8-16-1			0	0	0	1	2			3	1	0	0	0
1-16-32-1				0	0	0	1				3	1	0	0

表 7-87. Register settings for 0x9F/A0/A1/A2 based on decimation and LMFS mode (20-bit output)

	JESD PLL1/2, JESD PLL INPUT 1/2							JESD PLL INPUT 3						
LMFS	/4	/8	/16	/32	/64	/128		/4	/8	/16	/32	/64	/128	
8-8-4-1	0	0	1	2	3	4		1	0	0	0	0	0	
8-16-8-1	0	0	0	1	2	3		3	1	0	0	0	0	
4-4-4-1	0	0	1	2	3	4		1	0	0	0	0	0	
4-8-8-1	0	0	0	1	2	3		3	1	0	0	0	0	
4-16-16-1		0	0	0	1	2			3	1	0	0	0	
2-2-4-1	0	0	1	2	3	4		1	0	0	0	0	0	
2-4-8-1	0	0	0	1	2	3		3	1	0	0	0	0	
2-8-16-1		0	0	0	1	2			3	1	0	0	0	
2-16-32-1			0	0	0	1				3	1	0	0	
1-2-8-1	0	0	0	1	2	3		3	1	0	0	0	0	
1-4-16-1		0	0	0	1	2			3	1	0	0	0	
1-8-32-1			0	0	0	1				3	1	0	0	
1-16-64-1				0	0	0					3	1	0	

図 7-79. Register 0xA4..0xE2 (JESD page)

7	6	5	4	3	2	1	0
START VALUE JESD RAMP [19:0]							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-88. Register 0xA4..0xE2 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	START VALUE JESD RAMP [19:0]	R/W	00000000	The JESD RAMP test pattern is designed to act as an individual RAMP pattern on each digital stream. See セクション 7.3.8 for detailed examples. Different registers are being used to set RAMP starting values for different operating modes.

図 7-80. Register 0x100..0x17D (DDCA/B page)

7	6	5	4	3	2	1	0
NCOx FREQUENCYx [7:0],[15:8],[23:16],[31:24],[39:32],[47:40]							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-89. Register 0x100..0x17D Field Descriptions

Bit	Field	Type	Reset	Description
47:0	NCOx FREQUENCYx	R/W	0	The frequencies for NCOs are located in addresses 0x100 to 0x17D. Each frequency is 48-bit and the MSB starts on the highest address as illustrated in <i>NCO Frequency Programming</i> .

図 7-81. Register 0x180 (DDCA/B page)

7	6	5	4	3	2	1	0
0	0	DDC PDN	DDC DITH PDN	REAL DDC	DB/QB DDC	0	NCO MODE
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-90. Register 0x180 Field Descriptions

Bit	Field	Type	Reset	Description
7-6	0	R/W	0	Must write 0
5	DDC PDN	R/W	0	This bit powers down the DDC mixer and NCO 0: DDC block enabled 1: DDC block powered down
4	DDC DITH PDN	R/W	0	This bit powers down the dither in the DDC digital block 0: DDC dither enabled 1: DDC dither powered down
3	REAL DDC	R/W	0	Set this bit to 1 in real decimation mode to disable the NCO. 0: Complex Decimation 1: Real Decimation
2	DB/QB DDC	R/W	0	This register splits the NCOs for dual or quad band operation. 0: Dual Band 1: Quad Band
1	0	R/W	0	Must write 0
0	NCO MODE	R/W	0	This register selects phase coherent or phase continuous operation of the NCO. 0: Phase continuous 1: Phase coherent

図 7-82. Register 0x181 (DDCA/B page)

7	6	5	4	3	2	1	0
0	0	LOAD NCO		0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-91. Register 0x181 Field Descriptions

Bit	Field	Type	Reset	Description
7-6	0	R/W	0	Must write 0
5-4	LOAD NCO	R/W	00	This register loads all the NCO frequencies from the memory to the NCOs. To update the NCO this register has to be set to 3 and back to 0 as shown in <i>NCO Frequency Programming</i> .
3-0	0	R/W	0	Must write 0

表 7-92. NCO frequency programming example

ADDR	DATA	DESCRIPTION
0x105	0x4E	Frequency = 460 MHz with $F_S = 1.3$ GSPS 99,598,837,913,001 = 0x5A95A95A95A9 where the MSB goes to address 0x105 and the LSB to 0x100.
0x104	0x81	
0x103	0xB4	
0x102	0xE8	
0x101	0x1B	
0x100	0x4E	
0x181	0x00	Load and update all NCO frequencies
0x181	0x30	

図 7-83. Register 0x34 (CALIBRATION page)

7	6	5	4	3	2	1	0
0	0	0	0	0	AVG SEL (2)		1
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-93. Register 0x34 Field Descriptions

Bit	Field	Type	Reset	Description
7-3	0	R/W	0	Must write 0
2-1	AVG SEL (2)	R/W	00	Selects ADC averaging. Also AVG SEL (1) in DIGITAL page needs to be set. 0: no average 01: 2 ADC average 10: not used 11: 4 ADC average
0	1	R/W	1	Must write 1

図 7-84. Register 0x45 (CALIBRATION page)

7	6	5	4	3	2	1	0
CAL SPI	CAL GPIO	0	0	1	0	1	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-94. Register 0x45 Field Descriptions

Bit	Field	Type	Reset	Description
7	CAL SPI	R/W	0	This register triggers the calibration using SPI write. It needs to be toggled (0=>1=>0).
6	CAL GPIO	R/W	0	This register triggers the calibration using the GPIO1 pin.
5-4	0	R/W	0	Must write 0
3	1	R/W	1	Must write 1
2	0	R/W	0	Must write 0
1	1	R/W	1	Must write 1
0	0	R/W	0	Must write 0

図 7-85. Register 0x298 (CALIBRATION page)

7	6	5	4	3	2	1	0
0	0	0	0	CAL STATUS			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-95. Register 0x298 Field Descriptions

Bit	Field	Type	Reset	Description
7-4	0	R/W	0	Must write 0
3-0	CAL STATUS	R/W	0000	This register can be used to check if calibration state machine has finished without any errors. A value of 0xE indicates successful calibration.

図 7-86. Register 0x6D/6E (ANALOG page)

7	6	5	4	3	2	1	0
RESET SW [1:0]		0	0	0	0	0	0
0	0	0	0	0	0	RESET SW [3:2]	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-96. Register 0x6D/6E Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESET SW [1:0]	R/W	00	This register disables the sampling reset switch. 00: Sampling reset switch enabled 1: Sampling reset switch disabled
5-0	0	R/W	0	Must write 0
1-0	RESET SW [3:2]	R/W	00	This register disables the sampling reset switch. 00: Sampling reset switch enabled 1: Sampling reset switch disabled
7-2	0	R/W	0	Must write 0

図 7-87. Register 0x7B (ANALOG page)

7	6	5	4	3	2	1	0
0	0	TERM A	0	0	0	0	TERM A
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-97. Register 0x7B Field Descriptions

Bit	Field	Type	Reset	Description
7-6	0	R/W	0	Must write 0
5,0	TERM A	R/W	00	These registers set the internal termination resistor at the analog inputs for channel A1 and A2. Both registers need to be set to the same value. 0: 100 ohm differential termination 1: 50 ohm differential termination
4-1	0	R/W	0	Must write 0

図 7-88. Register 0x8B (ANALOG page)

7	6	5	4	3	2	1	0
0	0	TERM B	0	0	0	0	TERM B
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-98. Register 0x8B Field Descriptions

Bit	Field	Type	Reset	Description
7-6	0	R/W	0	Must write 0
5,0	TERM B	R/W	00	These registers set the internal termination resistor at the analog inputs for channel B1 and B2. Both registers need to be set to the same value. 0: 100 ohm differential termination 1: 50 ohm differential termination
4-1	0	R/W	0	Must write 0

図 7-89. Register 0xA8 (ANALOG page)

7	6	5	4	3	2	1	0
0	DITH AMP1				0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-99. Register 0xA8 Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-3	DITH AMP1	R/W	0000	This register sets dither amplitude coarse gain. There are two recommended settings: 0000: Amplitude = 0 0011: Amplitude = 3 Here is a list of all the settings: 0000: Amplitude = 0 (smallest) 0001: Amplitude = 1 ... 1110: Amplitude = 14 1111: Amplitude = 15 (largest)
2-0	0	R/W	0	Must write 0

図 7-90. Register 0xAF (ANALOG page)

7	6	5	4	3	2	1	0
DITHER DIS	0	0	1	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-100. Register 0xAF Field Descriptions

Bit	Field	Type	Reset	Description
7	DITHER DIS	R/W	0	This register disables internal dither. 0: Dither enabled 1: Dither disabled
6-5	0	R/W	0	Must write 0
4	1	R/W	0	Must write 1
3-0	0	R/W	0	Must write 0

図 7-91. Register 0xB1 (ANALOG page)

7	6	5	4	3	2	1	0
DITHER DIVIDER							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-101. Register 0xB1 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	DITHER DIVIDER	R/W	0	This register sets the dither divider frequency. SPI write is actual -1. For example a divider of 48 is 47 (0x2F). 0x00 (default) is a divide /50

図 7-92. Register 0xB4 (ANALOG page)

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	SYSREF AC
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-102. Register 0xB4 Field Descriptions

Bit	Field	Type	Reset	Description
7-1	0	R/W	0	Must write 0
0	SYSREF AC	R/W	0	This register enables external AC coupling of the SYSREF input with internal biasing. 0: External DC coupling with internal 100 Ω termination 1: External AC coupling with internal biasing

図 7-93. Register 0xCD (ANALOG page)

7	6	5	4	3	2	1	0
0	DITH AMP2			0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-103. Register 0xCD Field Descriptions

Bit	Field	Type	Reset	Description
7	0	R/W	0	Must write 0
6-4	DITH AMP2	R/W	0	This register sets dither amplitude fine gain. There are two recommended settings: 000: Amplitude = 0 100: Amplitude = -4 Here is a list of all the settings: 000: Amplitude = 0 001: Amplitude = 1 010: Amplitude = 2 011: Amplitude = 3 (largest) 100: Amplitude = -4 (smallest) 101: Amplitude = -3 110: Amplitude = -2 111: Amplitude = -1
3-0	0	R/W	0	Must write 0

図 7-94. Register 0xE6/E7 (ANALOG page)

ADDR	7	6	5	4	3	2	1	0
0xE6	TX SWING [0]	0	0	0	0	0	0	0
0xE7	0	0	0	0	0	0	TX SWING [2:1]	
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 7-104. Register 0xE6/E7 Field Descriptions

Bit	Field	Type	Reset	Description
7-0	0	R/W	0	Must write 0
1,0,7	TX SWING [2:0]	R/W	000	This register adjusts the output amplitude on all 8 serdes lanes. 0: 850 mVpp 1: 825 mVpp 2: 800 mVpp 3: 775 mVpp 4: 950 mVpp 5: 925 mVpp 6: 900 mVpp 7: 875 mVpp

8 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The ADC32RF5x can be used in a wide range of applications including radar, frequency domain digitizer and spectrum analyzer, test and communications equipment and software-defined radios (SDRs). The Typical Applications section describe one configuration that meets the needs of a number of these applications.

8.2 Typical Applications

8.2.1 Wideband RF Sampling Receiver

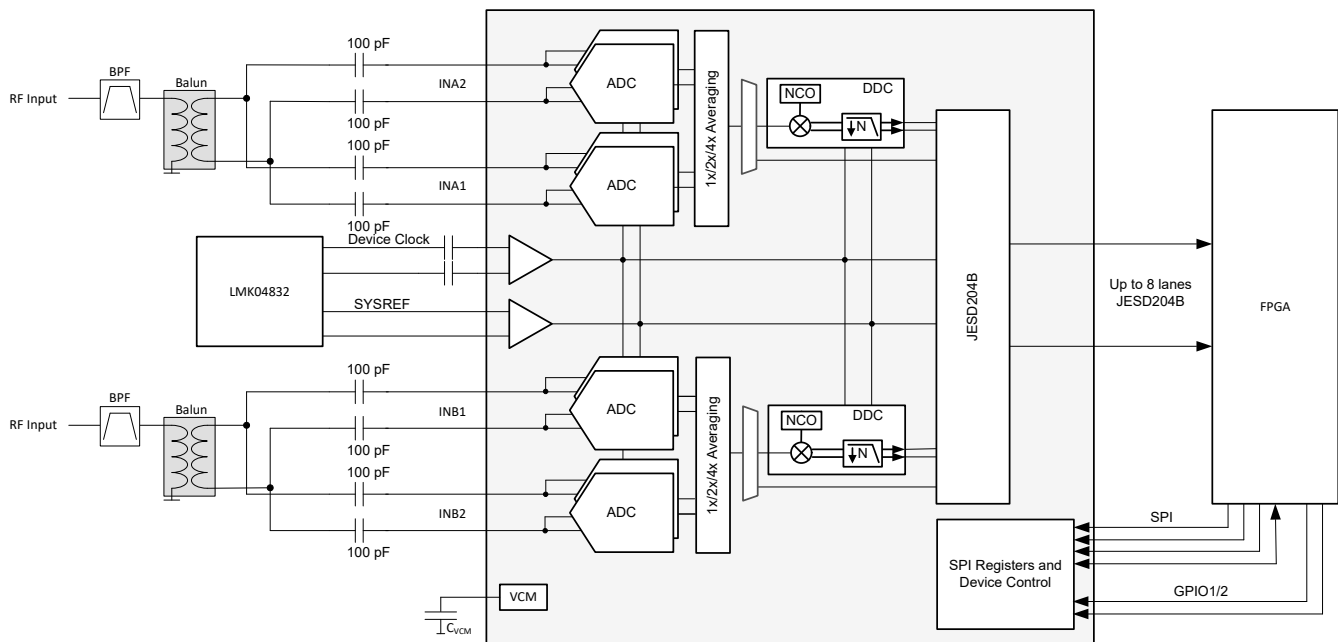


図 8-1. Typical Configuration for Wideband RF Sampling

8.2.1.1 Design Requirements

8.2.1.1.1 Input Signal Path

Appropriate band limiting filters should be used to rejected unwanted frequencies in the receive signal path.

A 1:2 (for 100 ohm effective termination impedance) or a 1:1 (for 50 ohm effective termination impedance) balun transformer is needed to convert the single ended RF input to differential for input to the ADC. The balun outputs should be AC coupled with 100 pF capacitors. The balun should have good amplitude (< 0.5 dB) and phase balance (less than 2 deg) within the frequency range of interest. A back-to-back balun configuration often times gives better SFDR performance. 表 8-1 lists a number of recommended baluns for different impedance ratios and frequency ranges.

The S-parameters of the ADC input can be used to design the front end matching network.

表 8-1. Recommended Baluns

PART NUMBER	MANUFACTURER	IMPEDANCE RATIO	AMPLITUDE BALANCE (dB)	PHASE BALANCE (°)	FREQUENCY RANGE
BAL-0009SMG	Marki Microwave	1:2	0.6	5	0.5 MHz to 9 GHz
TCM2-43X+	Minicircuits	1:2	0.5	7	10 MHz to 4 GHz
TCM2-33WX+	Minicircuits	1:2	0.7	4	10 MHz to 3 GHz
TC1-1-13M+	Minicircuits	1:1	0.5	2-3	10 MHz to 3 GHz

8.2.1.1.2 Clocking

The ADC32RF52 clock inputs must be AC-coupled to the device to provide the rated performance. The clock source must have low jitter (integrated phase noise) for the ADC to meet the stated SNR performance, especially when operating at higher input frequencies. The clock signal may need to be filtered with a band pass filter to remove some of the broad band clock noise.

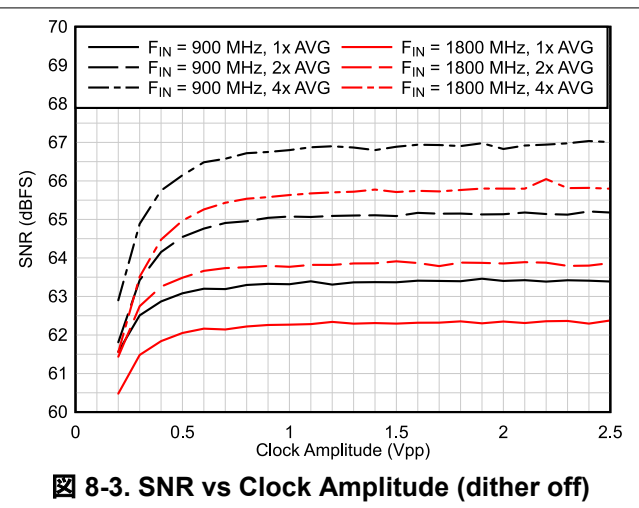
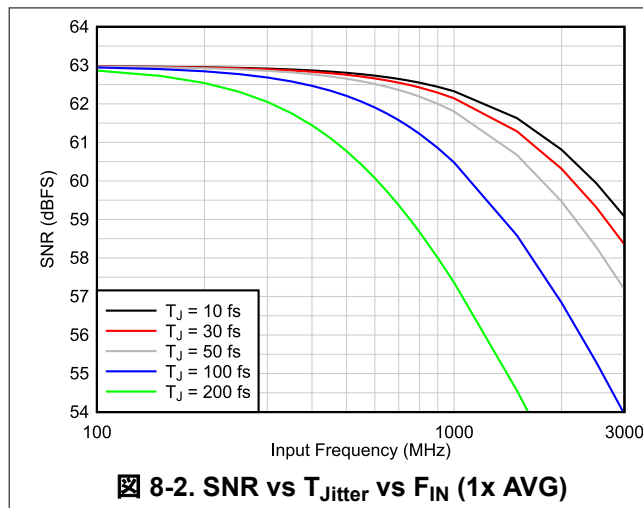
The JESD204B data converter system (ADC and FPGA) requires additional SYSREF and device clocks. The LMK04828 or LMK04832 devices are suitable to generate these clocks. Depending on the ADC clock frequency and jitter requirements, this device may also be used as a system clock synthesizer or as a device clock and SYSREF distribution device when using multiple ADC32RF52 devices in a system.

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Sampling Clock

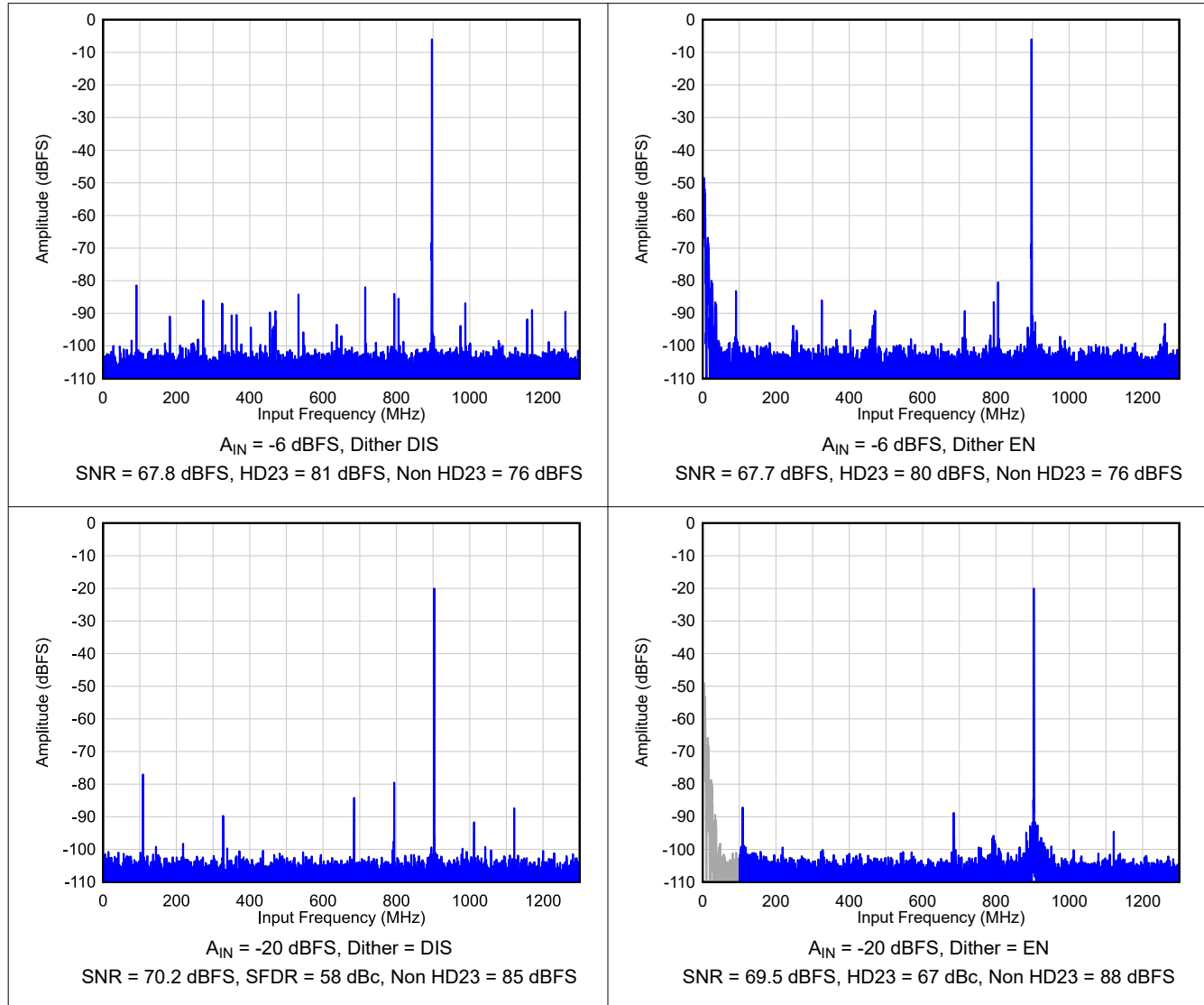
To maximize the SNR performance of the ADC a very low jitter (< 50 fs) sampling clock is required. 8-2 shows the estimated SNR performance vs input frequency vs external clock jitter. The internal ADC aperture jitter also has some dependency to the clock amplitude (gets more sensitive with higher input frequency) as shown in 8-3.

When using averaging and/or decimation, the SNR for a single ADC core should be estimated first before adding the SNR improvement from internal averaging and/or decimation.



8.2.1.3 Application Curves

The following application curves demonstrate performance and results only of the ADC using a balun front end and configured to 4x internal averaging. The input frequency is 900 MHz ($F_S = 2.6$ GSPS) and input amplitudes of -6 and -20 dBFS are shown with dither enabled/disabled.



8.3 Initialization Set Up

After power-up, the internal registers must be initialized to their default values through a hardware reset by applying a low pulse on the RESET pin, as shown in 図 8-4.

1. Apply 1.2 V DVDD digital power supply
2. Apply remaining 1.2 V power supplies (AVDD12, CLKVDD), in no specific order
3. Apply 1.8 V AVDD18 power supply
4. Apply hardware reset. After hardware reset is released, the default registers are loaded from internal fuses.
5. Begin programming the internal registers using the SPI interface.

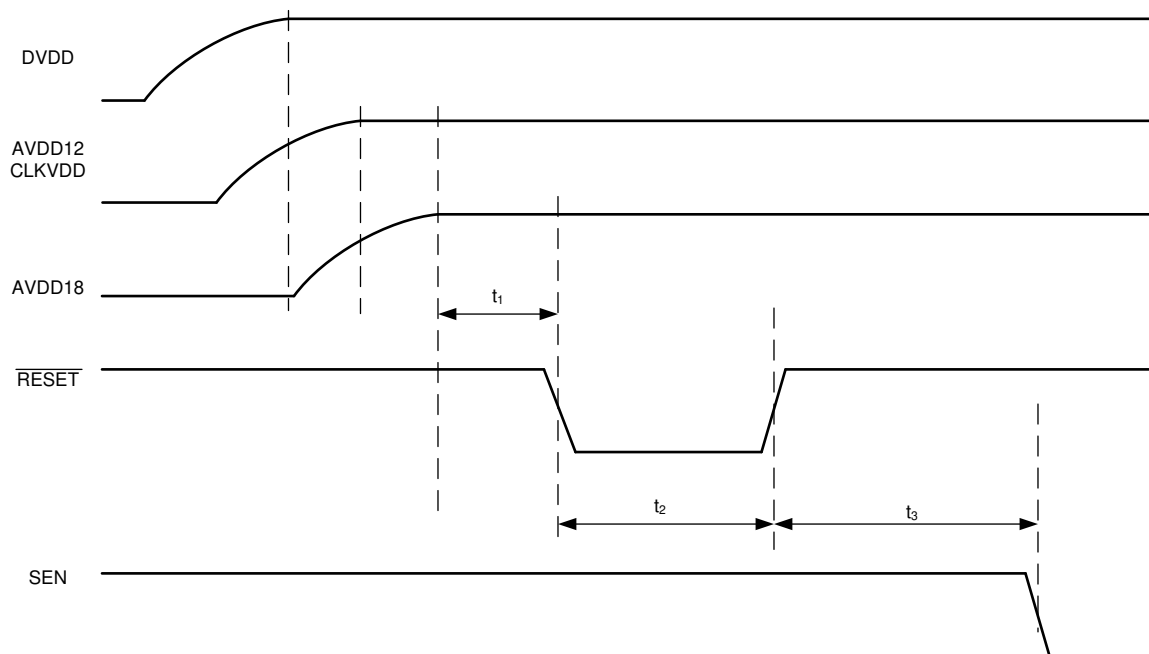


図 8-4. Initialization of serial registers after power up

表 8-2. Power-up timing

		MIN	TYP	MAX	UNIT
t_1	Power-on delay: delay from power up to active high RESET pulse	1			ms
t_2	Reset pulse width: active low RESET pulse width	100			ns
t_3	Register write delay: delay from RESET disable to SEN active	45k			Clock cycles

8.3.1 Initial Device Configuration After Power-Up

The following section outlines the sequence of register writes for the device configuration after initial power up.

表 8-3. Summary of programming steps after initial power up

Step	Section	Description
1	RESET	Hardware and software RESET to reset all registers to known state
2	DEVICE CONFIG	Configures the digital operating modes like averaging, test pattern output, input termination, internal dither and decimation.
3	JESD	Configures the JESD204B interface
4	SYSREF	Enables SYSREF input and resets internal circuits based on external SYSREF signal.
5	JESD	Clears and configures some of the JESD registers
6	TRIM	Set trim settings for best analog performance
7	CALIB CONFIG	Configure the calibration settings
8	SYSREF	Issue SYSREF for trim settings to go into effect
9	RUN CALIB	Run power up calibration
10	JESD	Synchronize the JESD interface with the receiver

The following section outlines the detailed register writes for the device configuration after initial power up. This includes all the register writes (fields in grey) which are not documented in the register summary table. The register examples are given for 2x internal averaging, DDC bypass mode (LMFS = 8224).

8.3.1.1 STEP 1: RESET

After the initial power up, both hardware and software reset are required.

表 8-4. Register Programming Sequence for Software RESET

ADDRESS	DATA	DESCRIPTION
0x00	0x01	Software set and reset
0x00	0x00	
0x01	0x00	These two resets are staggered to minimize strain on external power supply.
0x09	0x20	
0x09	0x80	
0x09	0x00	
0x08	0x01	Internal memory reset (set and reset)
0x08	0x00	
0x05	0x40	Select ANALOG page
0x47	0x80	Analog reset (set and reset)
0x47	0x00	

8.3.1.2 STEP 2: Device Configuration

In this step, the operating mode and digital features (DDC, test pattern) are configured.

表 8-5. Register Programming Sequence for Device Configuration

ADDRESS	DATA	DESCRIPTION
0x05	0x20	Select CALIBRATION page
0x34	0x03	Select 2x averaging (1x AVG: 0x01, 4x AVG: 0x07)
0x05	0x02	Select DIGITAL page
0x2C	0x01	Select DDC Bypass mode
0x2D	0x00	No decimation, step can be skipped
0x2E	0x0B	Select 2x averaging (1x: 0x09, 2x: 0x0B, 4x: 0x0D), OVR on JESD
0x23C	0x07	Set register to 0x07
0x33	0x10	Set register to 0x10
0x2F	0x11	Set register to 0x11 (1x: 0x55, 2x: 0x11, 4x: 0xE1)
0x30	0x11	Set register to 0x11 (1x: 0x55, 2x: 0x11, 4x: 0xE1)
0x05	0x40	Select ANALOG page
0x7B/8B	0x00	Select internal input termination (0x00 = 100 Ω)
0xA8	0x00	DITHER AMP1: 3 = 0x80, 0 = 0x00
0xCD	0x00	DITHER AMP2: -4 = 0x40, 0 = 0x00
0x04	0x01	
0x20	0x04	
0x91	0x40	
0xAF	0x10	
0xB1	0x00	Sets dither divider. 0x00 = /50
0xB2	0x00	
0xAF	0x18	
0xAF	0x10	0x10 = dither ENABLED, 0x90 = dither DISABLED
0x04	0x01	
0x20	0x00	
0x04	0x00	
0x05	0x02	
0x363	0x01	
0x05	0x18	Select DDCA and DDCB pages, load non linearity correction (NLC) trims
0x21D	0x00	
0x21E	0x01	
0x205	0x03	
0x204	0xFF	
0x31D	0x00	
0x31E	0x01	
0x305	0x03	
0x304	0xFF	
0x31C	0x3E	
0x325	0x00	Load NLC
0x325	0x01	
0x325	0x00	

表 8-5. Register Programming Sequence for Device Configuration (続き)

ADDRESS	DATA	DESCRIPTION
Sampling Rate	640 - 1500 MSPS	
Nyquist Zone	1st	2nd
0x206	0x0E	0x0F
0x207	0x00	0x00
0x208	0x00	0x00
0x209	0x00	0x00
0x20A	0xF5	0xF4
0x20B	0x03	0x03
0x20C	0x27	0x28
0x20D	0x00	0x00
0x210	0xFC	0F9
0x211	0x03	0x03
0x212	0x5F	0xFD
0x213	0x03	0x03
0x21A	0x3C	0x3D
0x21C	0x00	0x00
0x223	0xFF	0xFF
0x224	0xFF	0xFF
0x225	0x00	Load NLC
0x225	0x01	
0x225	0x00	
0x20	0x02	OVR MUX EN
0x203	0x30	
0x303	0x30	
0x180	0x30	

8.3.1.3 STEP 3: JESD Interface Configuration (1)

In this step, the JESD204B digital interface and the parameters are configured.

表 8-6. Register Programming Sequence for JESD204B Interface Configuration

ADDRESS	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x81	0x00	Set register to 0x00
0x80	0xF0	Set register to 0xF0
0x7F	0xFF	Set register to 0xFF
0x7E	0xFF	Set register to 0xFF
0x7D	0xFF	Set register to 0xFF
0x7C	0xFF	Set register to 0xFF
0x7B	0x3B	Set register to 0x3B
0x7A	0x28	Set register to 0x28
0x79	0x51	Set register to 0x51
0x78	0x40	Set register to 0x40
0x05	0x04	Select JESD page
0x23	0x03	Set register to 0x03
0x29	0xFF	Set register to 0xFF

表 8-6. Register Programming Sequence for JESD204B Interface Configuration (続き)

ADDRESS	DATA	DESCRIPTION
0x20	0x0F	Select K (0x0F: K=15)
0x21	0x01	SYSREF mode
0x22	0x01	Select LMFS configuration (LMFS = 8-2-2-4)
0x24	0x00	Select DDC CLK DIV
0x25	0x00	Select JESD TX CLK DIV
0x26	0x00	
0x27	0x02	Select CLK BAL EN for LMFS = 8-2-2-4
0x53	0x80	Output scrambler EN/DIS (SCR EN)
0x5C	0x01	F-1 in ILA (F=2)
0x5D	0x0F	K-1 in ILA (K=15)
0x6E	0x11	
0xA0	0x00	
0xA1	0x00	Select JESD PLL INPUT divider 1/2/3
0xA2	0x00	
0x9F	0x00	Select JESD PLL setting
0x2A	0x0C	
0x23	0x02	JESD INIT toggle
0x23	0x00	

8.3.1.4 STEP 4: SYSREF Synchronization

After device and JESD204B interface configuration a synchronization using external SYSREF is necessary.

表 8-7. Device Synchronization Using External SYSREF

ADDRESS	DATA	DESCRIPTION
0x05	0x02	Select DIGITAL page
0x236	0x02	Enable internal SYSREF input and clear SYSREF pulse counter
0x236	0x03	Starts SYSREF counter

8.3.1.5 STEP 5: JESD Interface Configuration (2)

Some registers of the JESD204B interface need to be set after the first SYSREF.

表 8-8. Register Programming Sequence for JESD204B Interface Configuration

ADDRESS	DATA	DESCRIPTION
0x05	0x04	Select JESD page
0x29	0x00	
0x84	0x00	JESD PLL factor

8.3.1.6 STEP 6: Analog Trim Settings

The following registers need to be set for best analog performance. The register write order is all writes in first 2 columns before moving to the next set of address/data in middle columns, and so on.

表 8-9. Analog Trim Setting Registers

ADDR	DATA	ADDR	DATA	ADDR	DATA
0x05	0x40	0xA8	1x AVG: 0x18 2x/4x AVG: F _S <1.1 GSPS: 0x00 F _S =1.1-1.5 GSPS: 0x08	0x56	0x0F
0xE8	0xF0			0x6E	0x08
0xE9	0x01			0x102	0x02
0x4B	0x1F	0xCD	0x00	0x103	0xD9
0x5B	0x01	0xCE	0x00	0xA7	0x00
0xEA	0x00	0x100	See 表 8-10 for sample rate dependent trim registers	0xA6	0x08
0xEB	0x03	0x101		0x05	0x20
0x95	0x00	0x104		0xC9	0x09
0xFC	0x28	0x105		0x102	0xFE
0xE0	0x8E	0x107	0x10	0x103	0x03
0xE1	0x03	0x05	0x20	0x104	0xD4
0x4C	0x40	0x30	0xE8	0x105	0x03
0x4E	0x01	0x31	0xFF	0x106	0xFE
0x4E	0x00	0x30	0x08	0x107	0x03
0xA1	0x01	0x31	0x80	0x108	0xBC
0xF8	0x00	0x32	0x03	0x109	0x1A
0x31	0x20	0x05	0x02	0x101	0x01
0xFD	0x1C	0x243	0x02	0x159	0x63
0xAA	0x02	0x05	0x20	0x05	0x40
0x4D	0x80	0x36	0x04	0x31	0x00
0xB3	0x30	0x1F8	0x01	0x4D	0x00
0x64	0x10	0x1FC	0x0A	0x62	0x10
0x62	0x12	0x1F0	0x20	0x56	0x0E
0xFE	0x80	0x1F1	0x0C	0x56	0x0C
0xFC	0x28	0x05	0x40	0x56	0x08
0xFF	0x14	0x39	0x40	0x56	0x00
0x106	0x00	0x56	0x01	0x6E	0x00
0x107	0x00	0x56	0x03	0xF8	0x06
0x3B	0x0C	0x56	0x07		

表 8-10. Sample rate dependent trim registers

F _S (GSPS)	0x100	0x101	0x104	0x105
0.6-0.7	0x48	0x00	0x01	0x01
0.7-0.9	0xC8	0x01	0x81	0x00
0.9-1.1	0x48	0x01	0x81	0x00
1.1-1.3	0xC8	0x00	0x81	0x00
1.3-1.5	0x48	0x00	0x81	0x00

8.3.1.7 STEP 7: Calibration Configuration

The following registers configure the internal foreground calibration. The register write order is all writes in first 2 columns before moving to the next set of address/data in middle columns, and so on.

表 8-11. Calibration Register Settings

ADDRESS	DATA	ADDRESS	DATA	ADDRESS	DATA
0x05	0x40	0xFC	0x13	0x47	0xC7
0x68	0xC0	0xFD	0x08	0x46	0x13
0x69	0xFF	0x36	0x04	0xFC	0x13
0x05	0x20	0x36	0x05	0xFD	0x00
0x46	0x03	0x36	0x04	0x36	0x04
0x47	0xC2	0xFC	0x13	0x36	0x05
0x46	0x13	0xFD	0x0A	0x36	0x04
0x1AE	0x00	0x36	0x04	0xFC	0x13
0x1E6	0x1C	0x36	0x05	0xFD	0x02
0x1AE	0x00	0x36	0x04	0x36	0x04
0x1E6	0x1C	0xFC	0x13	0x36	0x05
0x1E9	0x08	0xFD	0x0C	0x36	0x04
0x1E9	0xA8	0x36	0x04	0xFC	0x13
0x1E8	0x02	0x36	0x05	0xFD	0x04
0x1E8	0x06	0x36	0x04	0x36	0x04
0x1E8	0x04	0xFC	0x13	0x36	0x05
0x1E8	0x00	0xFD	0x0E	0x36	0x04
0x1E9	0xA0	0x36	0x04	0xFC	0x13
0x1F0	0x28	0x36	0x05	0xFD	0x06
0x1F1	0x0C	0x36	0x04	0x36	0x04
0x1F0	0x2A	0xFC	0x03	0x36	0x05
0x1F0	0x2E	0x36	0x04	0x36	0x04
0x1F0	0x2C	0x46	0x03	0xFC	0x13
0x1F0	0x28	0x47	0xC0	0xFD	0x08
0x1F0	0x08	0x46	0x13	0x36	0x04
0x1F0	0x18	0x46	0x03	0x36	0x05
0x1F0	0x38	0x47	0xC7	0x36	0x04
0x1F1	0x0C	0x46	0x13	0xFC	0x13
0x1F0	0x3A	0x1AE	0x00	0xFD	0x0A
0x1F0	0x3E	0x1E6	0x1C	0x36	0x04
0x1F0	0x3C	0x1AE	0x00	0x36	0x05
0x1F0	0x38	0x1E6	0x1C	0x36	0x04
0x1F0	0x18	0x1E9	0xA8	0xFC	0x13
0x1F0	0x10	0x1E8	0x02	0xFD	0x0C
0x1AE	0x00	0x1E8	0x06	0x36	0x04
0x1E6	0x1C	0x1E8	0x04	0x36	0x05
0x1AE	0x00	0x1E8	0x00	0x36	0x04
0x1E6	0x1C	0x1E9	0xA0	0xFC	0x13
0x47	0xC0	0x1F0	0x18	0xFD	0x0E
0x46	0x03	0x1F0	0x08	0x36	0x04
0x47	0xC2	0x1F0	0x28	0x36	0x05

表 8-11. Calibration Register Settings (続き)

ADDRESS	DATA	ADDRESS	DATA	ADDRESS	DATA
0x46	0x13	0x1F1	0x0C	0x36	0x04
0xFC	0x13	0x1F0	0x2A	0xFC	0x03
0xFD	0x00	0x1F0	0x2E	0x36	0x04
0x36	0x04	0x1F0	0x2C	0x46	0x03
0x36	0x05	0x1F0	0x28	0x47	0xC0
0x36	0x04	0x1F0	0x08	0x46	0x13
0xFC	0x13	0x1F0	0x18	0x05	0x40
0xFD	0x02	0x1F0	0x38	0x68	0x40
0x36	0x04	0x1F1	0x0C	0x69	0xFD
0x36	0x05	0x1F0	0x3A	0x69	0xF5
0x36	0x04	0x1F0	0x3E	0x69	0xD5
0xFC	0x13	0x1F0	0x3C	0x69	0x55
0xFD	0x04	0x1F0	0x38	0x68	0x00
0x36	0x04	0x1F0	0x18	0x69	0x54
0x36	0x05	0x1F0	0x10	0x69	0x50
0x36	0x04	0x1AE	0x00	0x69	0x40
0xFC	0x13	0x1E6	0x1C	0x69	0x00
0xFD	0x06	0x1AE	0x00	0x93	0x0E
0x36	0x04	0x1E6	0x1C	0x94	0x70
0x36	0x05	0x47	0xC0	0x94	0x77
0x36	0x04	0x46	0x03		

8.3.1.8 STEP 8: SYSREF Synchronization

After setting the analog trim registers, a synchronization using external SYSREF is necessary.

表 8-12. Device Synchronization Using External SYSREF

ADDRESS	DATA	DESCRIPTION
0x05	0x18	Select DDCA and DDCB pages
0x181	0x34	Resets the NCO using a single SYSREF pulse
0x181	0x30	
0x05	0x02	Select DIGITAL page
0x236	0x02	Enable internal SYSREF input and clear SYSREF pulse counter
0x236	0x03	Starts SYSREF counter

8.3.1.9 STEP 9: Run Power up Calibration

The following registers start the power up foreground calibration. The register write order is all writes in first 2 columns before moving to the next set of address and/or data in middle columns, and so on.

表 8-13. Calibration Register Settings

ADDRESS	DATA	ADDRESS	DATA	ADDRESS	DATA
0x05	0x20	0x05	0x00	0x95	0x00
0xE7	0x01	0x04	0x01	0x96	0x00
0x174	0x02	0x20	0x1F	0x97	0x10
0x178	0x00	0x93	0x20	0x9C	0x00
0x17C	0x22	0x04	0x01	0x57	0x1E
0x3C	0x00	0x20	0x00	0xFE	0x10

表 8-13. Calibration Register Settings (続き)

ADDRESS	DATA	ADDRESS	DATA	ADDRESS	DATA
0xFC	0x03	0x04	0x00	0xFF	0x19
0xFD	0x00	0x05	0x20	0x46	0x02
0x154	0x1C	0xC0	0x7C	0x45	0x8A
0x155	0x03	0xBC	0x3C	0x45	0x0A
0xFC	0x03	0xC9	0x01	Delay 2.6 x 1.5 GSPS/ F _S seconds	
0xEE	0x26	0xC9	0x00	0xFE	0x00
0xEF	0x02	0xC9	0x06	0xFF	0x00
0x18C	0x88	0x38	0x01	0x89	0x00
0xAE	0xC8	0x110	0x10	0x95	0x00
0xAF	0x00	0x111	0x42	0x96	0x00
0xB0	0x4C	0x112	0xA6	0x97	0x00
0xB1	0x3F	0x112	0xD6	0x9C	0x00
0x4F	0x46	0x113	0xBB	0x57	0x1A
0x50	0x2C	0x113	0xDB	0x57	0x3A
0x51	0x05	0x114	0xF4	0x57	0x7A
0x154	0x7C	0x114	0x64	0x57	0xFA
0x158	0x7C	0x115	0x0E	0x58	0x01
0x159	0x6F	0x115	0xFE	0x58	0x03
0x15C	0x7C	0x116	0x0D	0x58	0x07
0x15D	0x3F	0x116	0xDD	0x58	0x0F
0x160	0x7C	0x117	0x0D	0x58	0x1F
0x161	0x3F	0x117	0xDD	0x58	0x3F
0x164	0x7C	0x46	0x03	0x45	0x8A
0x165	0x4F	0x3D	0x00	0x45	0x0A
0x16C	0x7C	0x45	0x0A	Delay 2.6 x 1.5 GSPS/ F _S seconds	
0x1B0	0x1C	0x46	0x02	0x47	0xC0
0x1B1	0x5F	0x64	0x4A	0x46	0x03
0x1D8	0x1C	0x65	0x05	0x47	0xC0
0x1D9	0xAF	0x68	0x28	0x05	0x80
0xB2	0x1F	0x69	0x5E	0x20	0x1F
0xB5	0x7F	0x6A	0x3D	0x9D	0x05
0x165	0xFF	0x6B	0x8F	0x9E	0x08
0x38	0x01	0x6C	0x44	0x8B	0x40
0xA4	0x30	0x57	0xDA	0x20	0x00
0xC5	0x7F	0x57	0x9A	0x05	0x00
0xA8	0x00	0x57	0x1A	0x04	0x01
0xA2	0x63	0x58	0x3E	0x20	0x1F
0xA3	0x00	0x58	0x3C	0x9D	0x05
0xAD	0x02	0x58	0x38	0x9E	0x08
0x05	0x80	0x58	0x30	0x8B	0x40
0x20	0x1F	0x58	0x20	0x20	0x00
0x93	0x20	0x58	0x00	0x04	0x00
0x20	0x00	0x89	0x20		

8.3.1.10 STEP 10: JESD Interface Synchronization

The JESD interface can be synchronized using SPI writes or the GPIO1 pin.

表 8-14. JESD Interface Synchronization Using SPI Writes

ADDRESS	DATA	DESCRIPTION
0x05	0x04	Select JESD page
0x21	0x41	Configure ADC to control SYNC using SPI writes
0x21	0x61	Configure JESD interface to send K28.5 characters for receiver synchronization
0x21	0x41	Configure JESD interface to send normal ADC data

8.4 Power Supply Recommendations

The ADC32RF5x requires four different power-supplies. The AVDD18, AVDD12 and CLKVDD rail provides power for the internal analog and clocking circuits of the ADC while the DVDD rail powers the digital logic (including averaging and decimation filter) and the JESD204B digital interface.

Power sequencing is required as shown in [セクション 8.3](#). The AVDD18, AVDD12 and especially the CLKVDD power supply must be low noise to achieve data sheet performance. For applications operating near DC, the 1/f noise contribution of the power supply needs to be considered as well.

Power supply decoupling capacitors (0.1 μ F) as close to the pins as possible on the top layer are recommended.

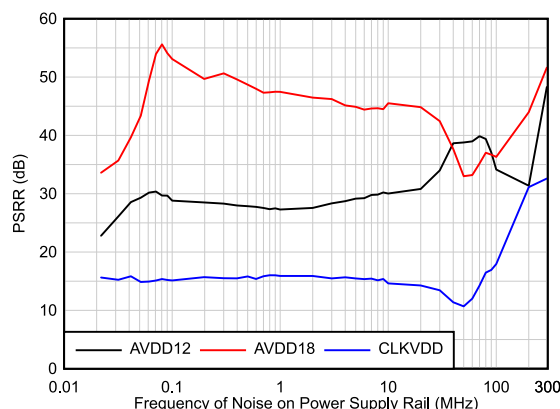


図 8-5. Power supply rejection ratio (PSRR) vs frequency

The recommended power supply architecture for a low noise design is to first use a high-efficiency step down switching regular, followed by a second stage of regulation using a low noise LDO for each power rail as shown in [図 8-6](#). This provides additional switching noise reduction and improved voltage accuracy.

TI WEBENCH® Power Designer can be used to select and design the individual power-supply elements. Recommended switching regulators for the first stage include the LMS3635, and similar devices. Recommended low dropout (LDO) linear regulators include the TPS7A8400, and similar devices.

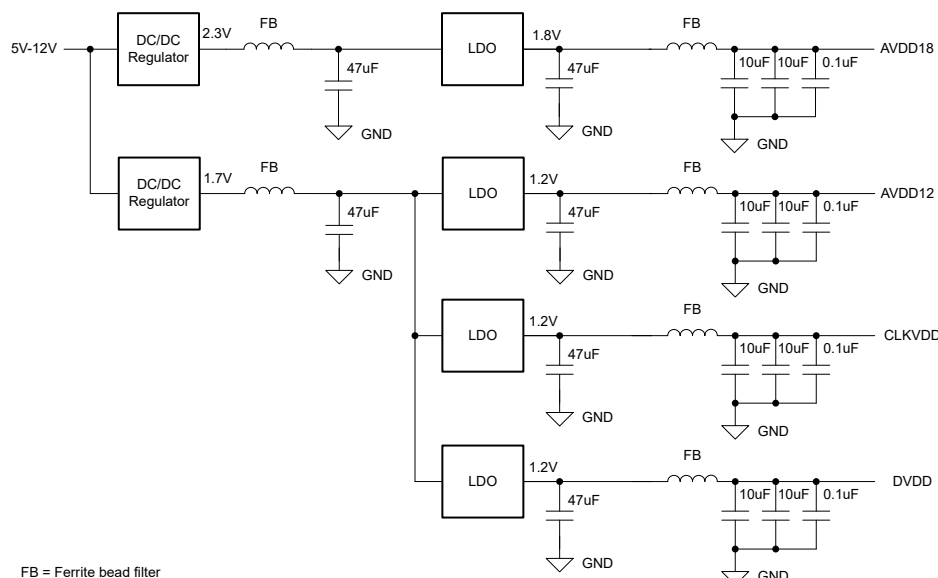


図 8-6. Power supply design example

AVDD12 or CLKVDD should not be shared with the DVDD to prevent digital switching noise from coupling into the analog domain.

8.5 Layout

8.5.1 Layout Guidelines

There are several critical signals which require specific care during board design:

1. Analog input and clock signals
 - Traces should be as short as possible and vias should be avoided where possible to minimize impedance discontinuities.
 - Traces should be routed using loosely coupled 100-Ω differential traces.
 - Differential trace lengths should be matched as close as possible to minimize phase imbalance and HD2 degradation.
2. Digital JESD204B output interface
 - Traces should be routed using tightly coupled 100-Ω differential traces.
3. Power and ground connections
 - Provide low resistance connection paths to all power and ground pins.
 - Use power and ground planes instead of traces.
 - Avoid narrow, isolated paths which increase the connection resistance.
 - Use a signal/ground/power circuit board stackup to maximize coupling between the ground and power plane.

8.5.2 Layout Example

The following screen shot shows the top layer of the ADC32RF5x EVM.

- The input signal traces are routed as differential signals on the top layer avoiding vias. Care is taken to maintain symmetry between positive and negative input with matched trace length to minimize phase imbalance.
 - ☒ [8-7](#) shows the layout example for 1x and 2x averaging configuration
 - ☒ [8-8](#) shows the layout example for 4x averaging configuration
- JESD204B output interface lanes are routed differential and length matched
- Bypass caps are close to the power pins on the top layer avoiding vias.

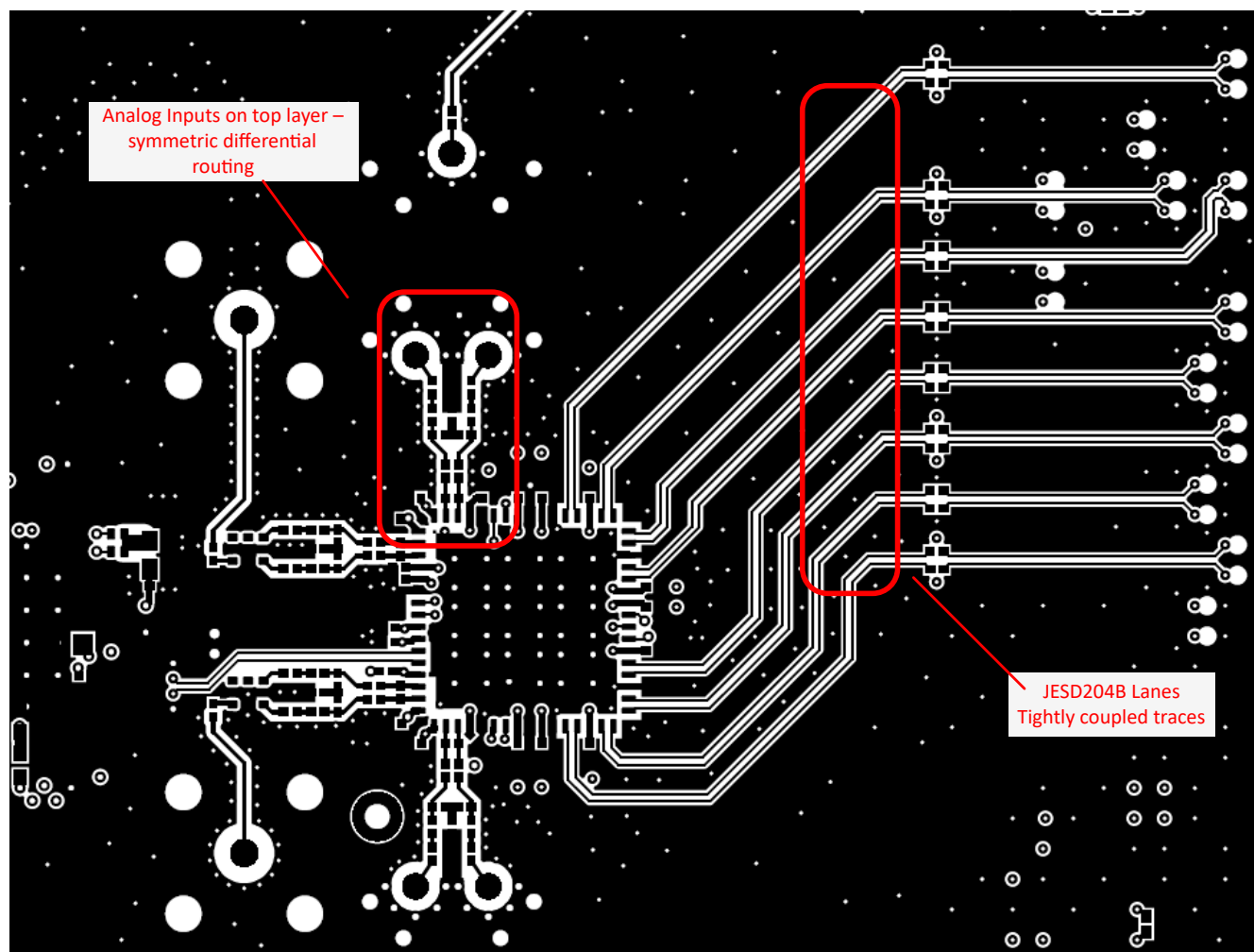


図 8-7. Layout example: top layer of ADC32RF5x EVM

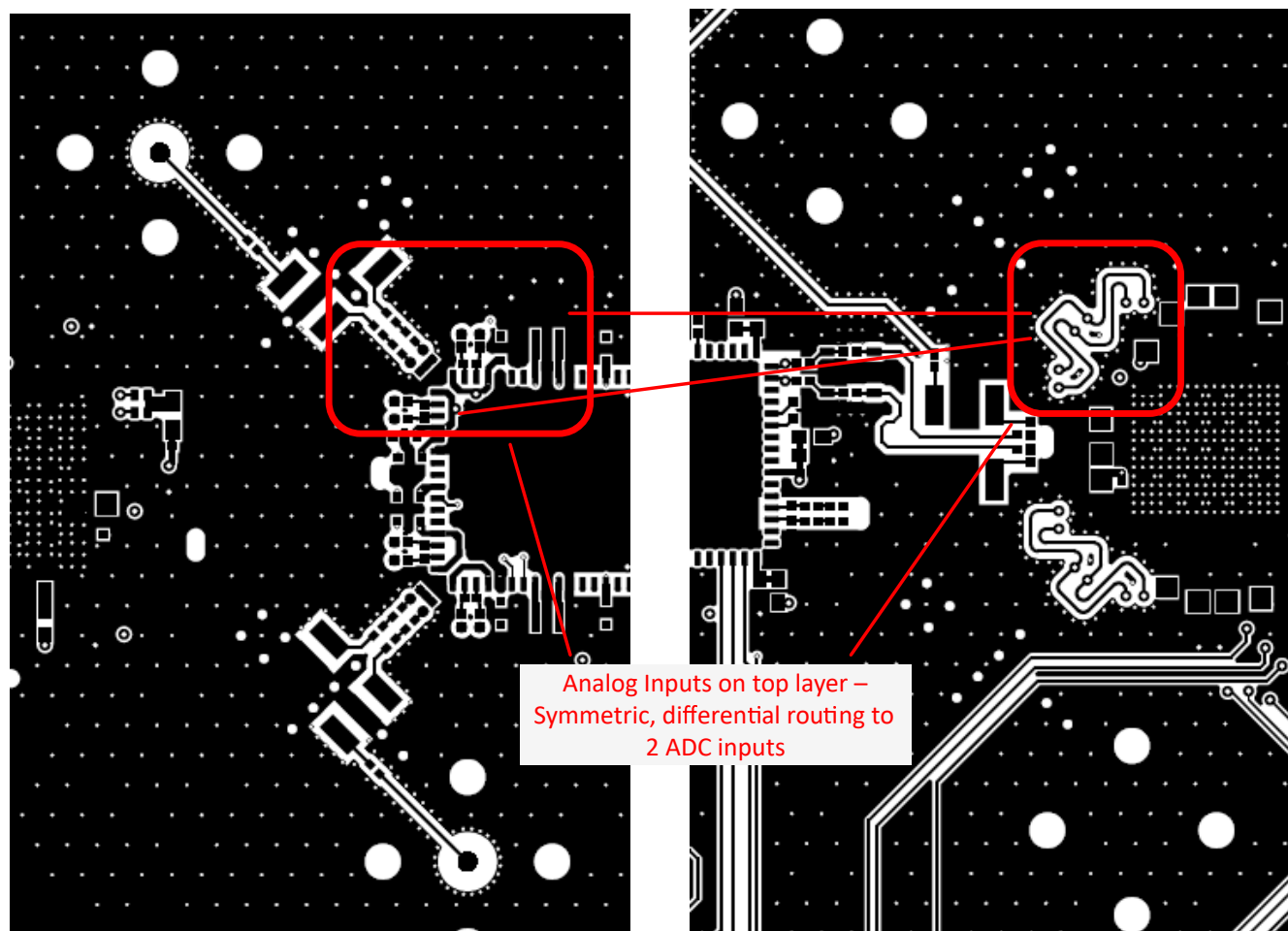


図 8-8. Layout example for 4x AVG: ADC32RF5x EVM

9 Device and Documentation Support

9.1 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.com のデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

9.2 サポート・リソース

TI E2E™ サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の[使用条件](#)を参照してください。

9.3 Trademarks

TI E2E™ is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

9.4 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

9.5 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
ADC32RF52IRTD	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ32RF52
ADC32RF52IRTD.A	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ32RF52
ADC32RF52IRTDI	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAU NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ32RF52
ADC32RF52IRTDI.A	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ32RF52

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

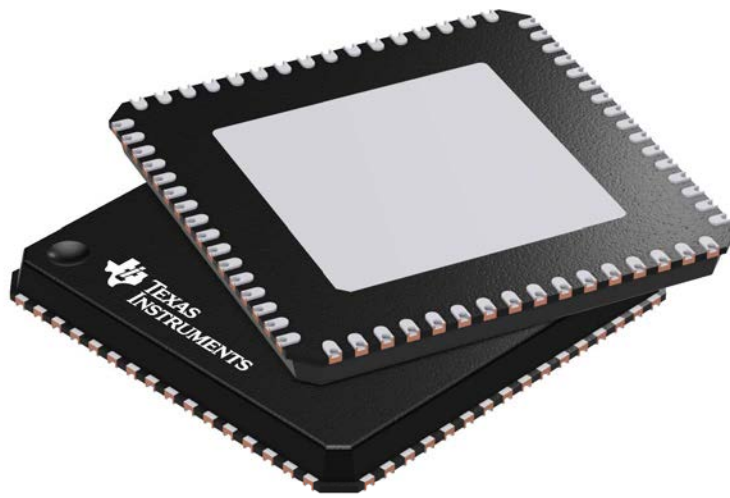
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

GENERIC PACKAGE VIEW

RTD 64

VQFNP - 0.9 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4205146/D

VQFN - 0.9 mm max height

Diagram illustrating the dimensions and layout of a square component, likely a microcontroller or sensor module, showing the placement of pins and the location of the PIN 1 ID.

The component is square, with overall dimensions of 9.1 mm (width) and 9.1 mm (height). The internal dimensions, excluding the pin area, are 8.9 mm (width) and 8.9 mm (height).

The diagram shows the component with pins along all four edges. The PIN 1 ID is located near the top-left corner.

Dimensions and labels:

- Overall width: 9.1
- Overall height: 9.1
- Internal width: 8.9
- Internal height: 8.9
- Pin 1 ID location: PIN 1 ID
- Pin 1 ID location (internal): (8.71)

0.975
0.875

(0.2)

4X (45° X0.42)

17

32

33

6.866 ± 0.1

48

49

64

65

5.566 ± 0.1

16

1

64X 0.5

64X 0.3

64X 0.3
0.2

SEATING PLANE

C

0.08 C

SYMM

SYMM

PIN 1 ID

0.1	C	B	A
0.05	C		

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

重要なお知らせと免責事項

TI は、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとし、TI は一切の責任を拒否します。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプリケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TI の製品は、[TI の販売条件](#)、[TI の総合的な品質ガイドライン](#)、[ti.com](#) または TI 製品などに関連して提供される他の適用条件に従い提供されます。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありません。TI がカスタム、またはカスタマー仕様として明示的に指定していない限り、TI の製品は標準的なカタログに掲載される汎用機器です。

お客様がいかなる追加条項または代替条項を提案する場合も、TI はそれらに異議を唱え、拒否します。

Copyright © 2025, Texas Instruments Incorporated

最終更新日：2025 年 10 月