LPV821 650nA高精度ナノパワー・ゼロドリフト・アンプ

1 特長

- 静止電流: 650nA
- 低いオフセット電圧: ±10µV (最大値)
- オフセット電圧ドリフト係数: ±0.096µV/℃ (最大値)
- 0.1Hz～10Hzのノイズ: 3.9μV_{PP}
- 入力バイアス電流: ±7pA
- ゲイン帯域幅: 8kHz
- 電源電圧: 1.7V～3.6V
- レール・ツー・レール入出力
- 業界標準のパッケージ
  - シングル: 5ピンSOT-23
- EMI強化

2 アプリケーション

- バッテリ駆動計測器
- ガス検出
- プロセス分析
- フォルト監視
- 電流検出
  - シャント抵抗
  - 変流器
- 温度計測
  - 高インピーダンス・サーミスタ
  - RTD、熱電対
- 歪みゲージ
  - 電子重量計
  - 圧力センサ

3 概要

LPV821は、低い入力オフセット電圧が要求されるワイヤレス/有線機器の「常時オン」センシング・アプリケーションに適した、1チャネルのナノパワー・ゼロドリフト・オペアンプです。初期オフセット電圧とオフセット・ドリフトが低く、650nAの静止電流で8kHzの帯域幅を提供するLPV821は、業界最低水準の消費電力を実現するゼロドリフト・アンプであり、消費電流、温度、ガス、または歪みゲージを監視する最終機器に使用できます。

LPV821ゼロドリフト・オペアンプは、独自の自動較正技術の採用により、低いオフセット電圧(最大10µV)を実現しながら、時間経過および温度変動に対するドリフトを最小限に抑えることができます。LPV821アンプは、オフセット電圧が低く、静止電流が極めて低いだけでなく、バイアス電流も非常に低いため(ピコアンペア単位)、出力インピーダンスの高いセンサ監視アプリケーションや、メガオームのフィードバック抵抗を含むアンプ構成で通常発生する誤差を低減できます。

製品情報(1)

型番	チャネル数	パッケージ	本体サイズ(公称)
LPV821	1	SOT-23 (5)	2.90mm×1.60mm
LPV822 (2)	2	WSON (8)	2.00mm×2.00mm

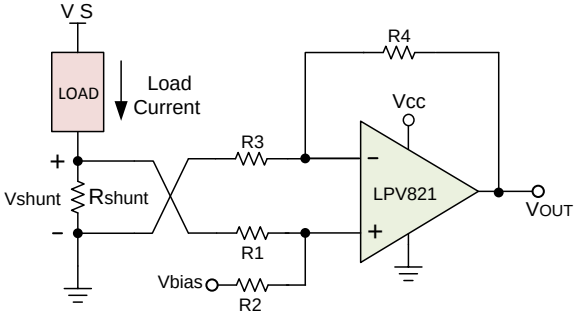
高精度ナノパワー・アンプ・ファミリ

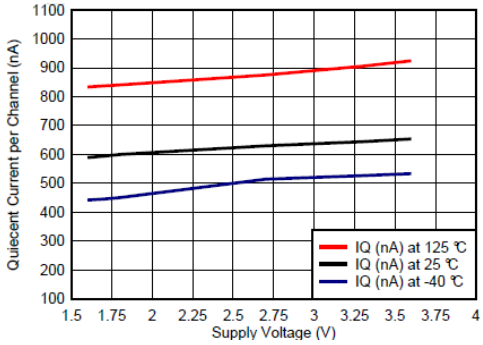
ファミリ	チャネル数	I_Q/チャネル	V_{OS} (最大値)	V_{SUPPLY}
LPV821	1	650nA	10µV	1.7～3.6V
LPV811	1	450nA	370µV	1.6～5.5V
LPV812	2	425nA	300µV	1.6～5.5V
OPA369	1、2	800nA	750µV	1.8～5.5V

(1) 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。

(2) 近日リリース予定

ローサイド、常時オンの電流検出





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4 改訂履歴

2017年8月 発行のものから更新 **Page**

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5 概要（続き）

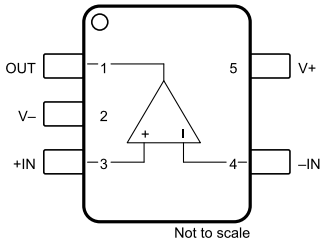
またLPV821アンプは、レール・ツー・レール入力同相範囲を持つ入力段と、レールから12mV以内でスイングする出力段を特長とすることから、最大限に広いダイナミック・レンジを確保できます。さらにEMI強化型であるため、携帯電話、WiFi、無線送信機、タグ・リーダーから発生する不要なRF信号への感受性が低下しています。

LPV821ゼロドリフト・アンプは最低1.7Vの単一電源電圧で動作することから、－40℃～125℃の広い温度範囲にわたり低バッテリ状態での連続動作が可能です。LPV821 (シングル)は、業界標準の5ピンSOT-23パッケージで供給されます。

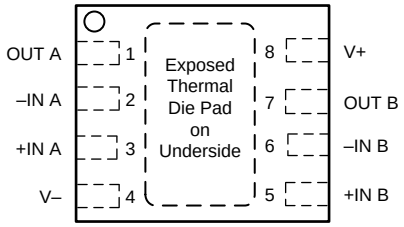
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6 Pin Configuration and Functions

LPV821 5-Pin SOT-23
DBV Package
Top View



LPV822 8-Pin WSON
DSG Package
Top View



Pin Functions: LPV821 DBV

PIN		I/O	DESCRIPTION
NAME	NUMBER		
OUT	1	O	Output
V–	2	P	Negative (lowest) power supply
+IN	3	I	Non-Inverting Input
–IN	4	I	Inverting Input
V+	5	P	Positive (highest) power supply

Pin Functions: LPV822 DSG (Preview)

PIN		I/O	DESCRIPTION
NAME	NUMBER		
OUT A	1	O	Channel A Output
-IN A	2	I	Channel A Inverting Input
+IN A	3	I	Channel A Non-Inverting Input
V-	4	P	Negative (lowest) power supply
+IN B	5	I	Channel B Non-Inverting Input
-IN B	6	I	Channel B Inverting Input
OUT B	7	O	Channel B Output
V+	8	P	Positive (highest) power supply

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7 Specifications

7.1 Absolute Maximum Ratings

See (1)

		MIN	MAX	UNIT
Voltage	Supply, V_S = (V+) - (V–)	-0.3	4	V
	Input/Output Pin Voltage(2) (3)	(V–) - 0.3	(V+) + 0.3	
	Differential Input Voltage +IN - (-IN)(2)	- 0.3	+ 0.3	
Current	Signal input terminals(2)	–10	10	mA
	Output short-circuit(4)	Continuous	Continuous	
Junction temperature			150	°C
Operating ambient temperature		–40	125	
Storage temperature, T_{stg}		–65	150	

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under . Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) Input terminals are diode-clamped to the power-supply rails. Input signals that can swing more than 0.3 V beyond the supply rails should be current limited to 10 mA or less.
(3) Not to exceed -0.3V or +4.0V on ANY pin, referred to V-
(4) Short-circuit to ground, one amplifier per package.

7.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)	±750	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Supply voltage	V_S = (V+) - (V–)	1.7		3.6	V
Specified temperature		–40		125	°C

7.4 Thermal Information

THERMAL METRIC		LPV821 DBV (SOT) 5 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	218.4	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	101.3	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	52.9	°C/W
ψ_{JT}	Junction-to-top characterization parameter	18.9	°C/W
ψ_{JB}	Junction-to-board characterization parameter	52.4	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

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7.5 Electrical Characteristics

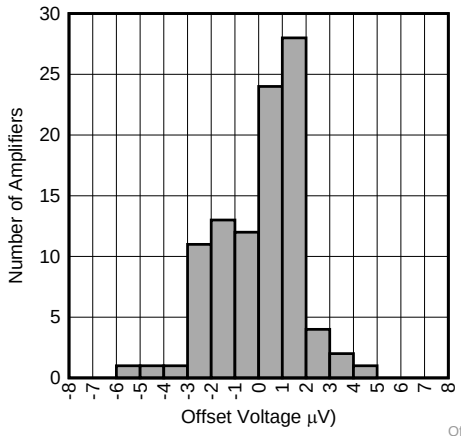
T_A = 25°C, V_S = 1.8 V to 3.3 V, V_{CM} = V_{OUT} = V_S/2, and R_L≥ 10 MΩ to V_S / 2, unless otherwise noted.

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
OFFSET VOLTAGE							
V_{OS}	Input offset voltage	V_S = 3.3 V			±1.5	±10	µV
dV_{OS}/dT	Input offset voltage drift	T_A = –40°C to 125°C, V_S = 3.3 V			±0.02	±0.096	µV/°C
PSRR	Power-supply rejection ratio	V_S = 1.8 V to 3.3 V			0.4	4.5	µV/V
INPUT BIAS CURRENT							
I_B	Input bias current	+IN	T_A= 25°C		7		pA
			T_A= 125°C		7		
		-IN	T_A= 25°C		-7		
			T_A= 125°C		-250		
I_{OS}	Input offset current				14		pA
NOISE							
E_n	Input voltage noise	f = 0.1 Hz to 10 Hz			3.9		μV_{PP}
e_n	Input voltage noise density	f = 100 Hz			215		nV/√Hz
i_n	Input current noise density	f = 100 Hz			1		fA/√Hz
INPUT VOLTAGE							
V_{CM}	Common-mode voltage range			(V–)		(V+)	V
CMRR	Common-mode rejection ratio	(V–) ≤ V_{CM} ≤ (V+), V_S = 3.3 V		100	125		dB
INPUT CAPACITANCE							
	Differential				3.3		pF
	Common-mode				3.7		pF
OPEN-LOOP GAIN							
A_{OL}	Open-loop voltage gain	(V–) + 0.1 V ≤ V_O ≤ (V+) – 0.1 V, R_L = 100 kΩ to V_S / 2			135		dB
FREQUENCY RESPONSE							
GBW	Gain-bandwidth product	C_L = 20 pF, R_L = 10 MΩ			8		kHz
SR	Slew rate	G = +1, C_L = 20 pF			3.3		V/ms
OUTPUT							
V_{OH}	Voltage output swing from positive rail	R_L = 100 kΩ to V^+/2, V_S = 3.3 V				12	mV
V_{OL}	Voltage output swing from negative rail	R_L = 100 kΩ to V^+/2, V_S = 3.3 V				12	
I_{SC}	Short-circuit current	Sourcing, V_O to V–, $V_{IN\ (diff)}$ = 100 mV, V_S = 3.3 V			21		mA
		Sinking, V_O to V+, $V_{IN\ (diff)}$ = –100 mV, V_S = 3.3 V			50		
C_L	Capacitive load drive				See 表 1		
Z_O	Open-loop output impedance	f = 100 Hz, I_O = 0 A			80		kΩ
POWER SUPPLY							
I_Q	Quiescent current per channel	V_{CM} = V_S/2, I_O = 0, V_S = 3.3 V			650	790	nA

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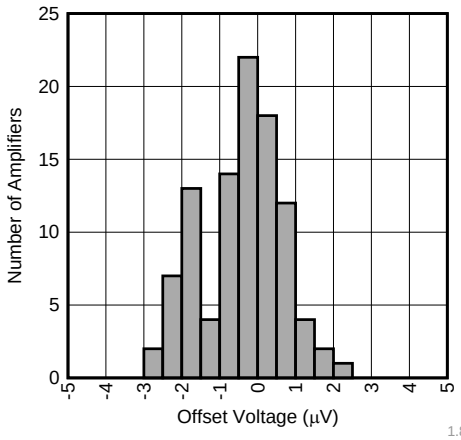
7.6 Typical Characteristics

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L≥ 10 MΩ, unless otherwise noted.



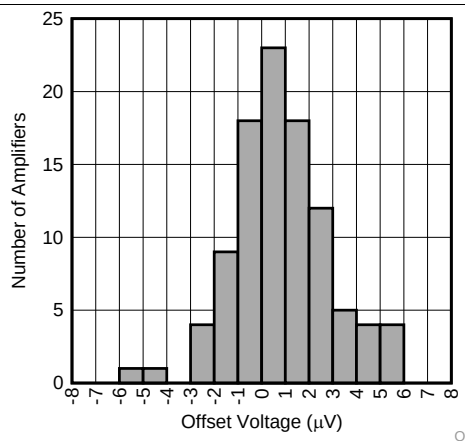
V_S = 1.8 V N = 98 units T_A = -40°C

図 1. Offset Voltage Distribution, Vs = 1.8 V



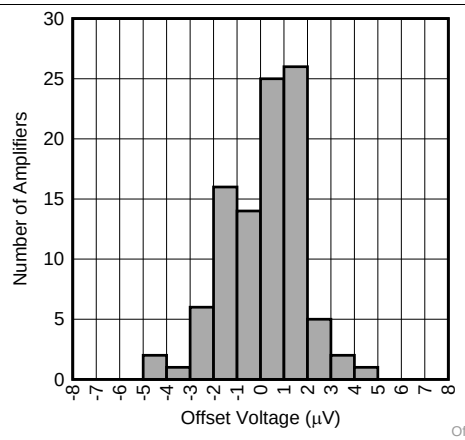
V_S = 1.8 V N = 98 units T_A = 25°C

図 2. Offset Voltage Distribution, Vs = 1.8 V



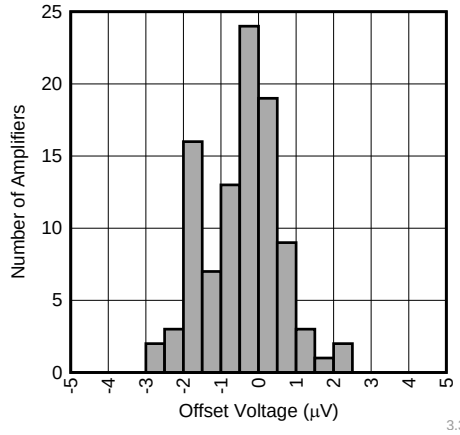
V_S = 1.8 V N = 98 units T_A = 125°C

図 3. Offset Voltage Distribution, Vs = 1.8 V



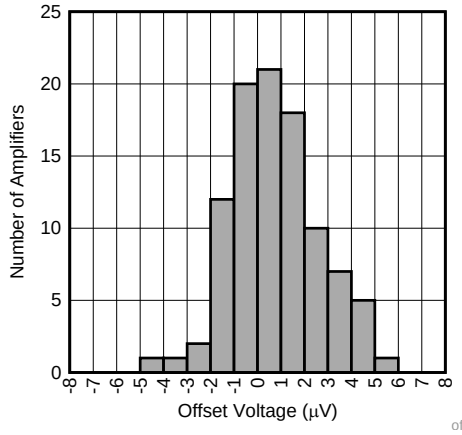
V_S = 3.3 V N = 98 units T_A = -40°C

図 4. Offset Voltage Distribution, Vs = 3.3 V



V_S = 3.3 V N = 98 units T_A = 25°C

図 5. Offset Voltage Distribution, Vs = 3.3 V



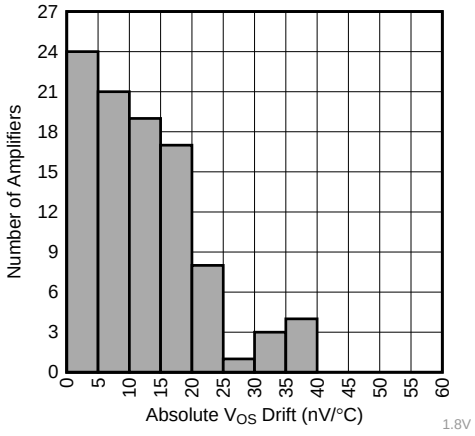
V_S = 3.3 V N = 98 units T_A = 125°C

図 6. Offset Voltage Distribution, Vs = 3.3 V

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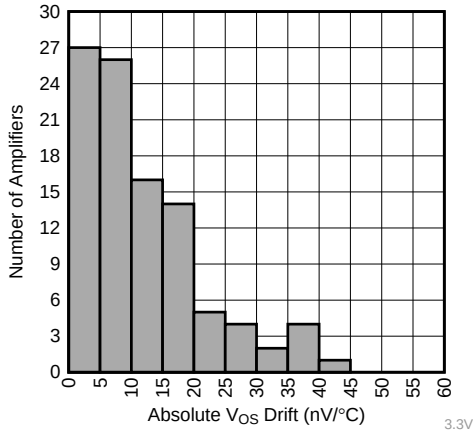
Typical Characteristics (continued)

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L≥ 10 MΩ, unless otherwise noted.



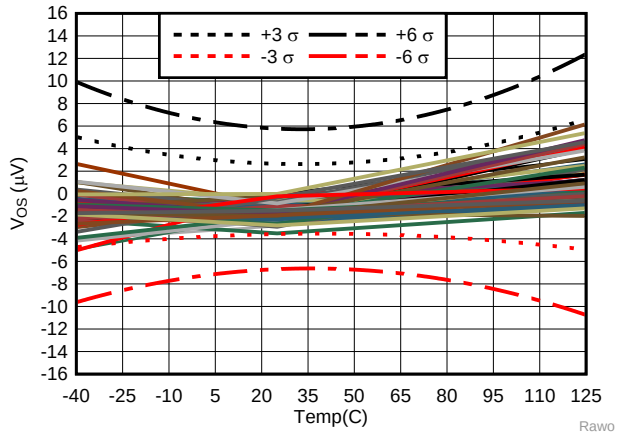
V_S = 1.8 V N = 98 units

図 7. Offset Voltage Drift Distribution, Vs = 1.8 V



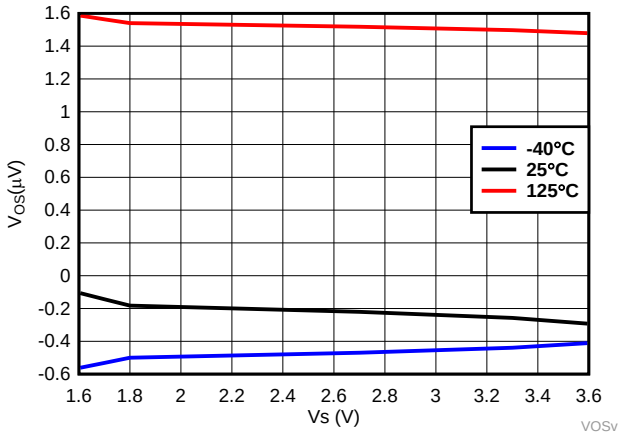
V_S = 3.3 V N = 98 units

図 8. Offset Voltage Drift Distribution, Vs = 3.3 V



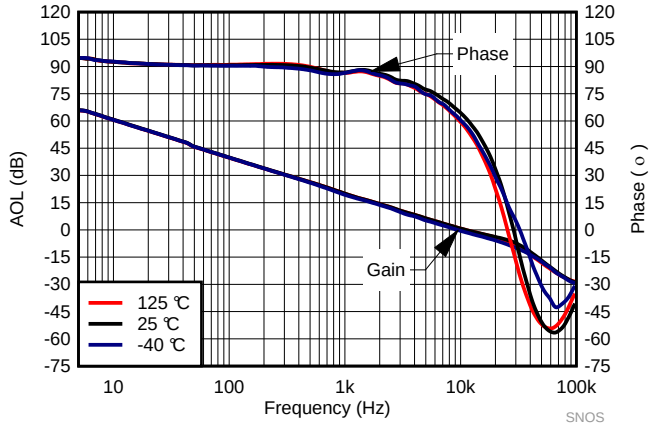
V_S = 3.3 V N = 98 units

図 9. Offset Voltage vs Temperature, Vs = 3.3 V



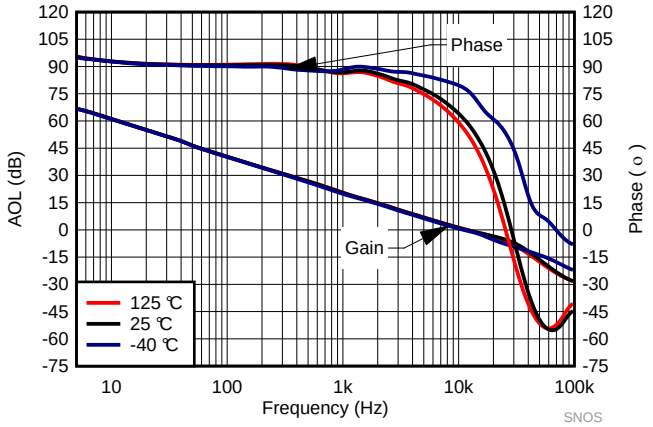
T_A = –40, 25, 125°C

図 10. Offset Voltage vs Supply Voltage



V_S = 1.8 V C_L = 20 pF T_A = –40, 25, 125°C

図 11. Open-Loop Gain and Phase vs Frequency



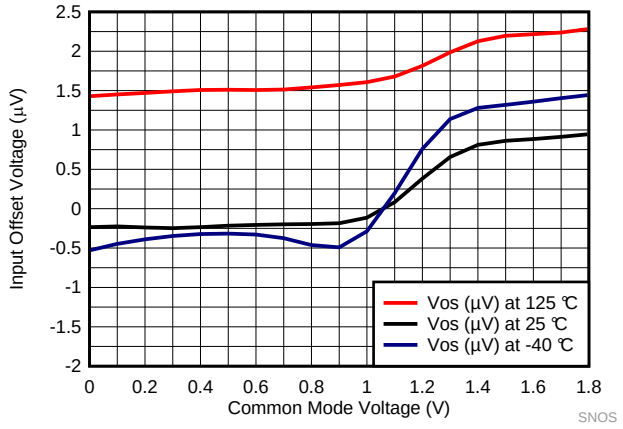
V_S = 3.3 V C_L = 20 pF T_A = –40, 25, 125°C

図 12. Open-Loop Gain and Phase vs Frequency

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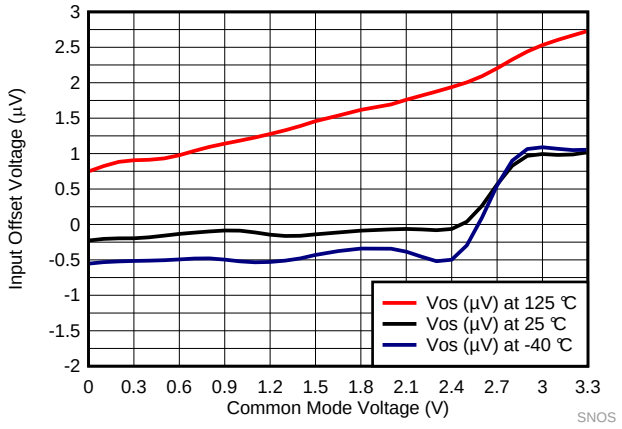
Typical Characteristics (continued)

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L ≥ 10 MΩ, unless otherwise noted.



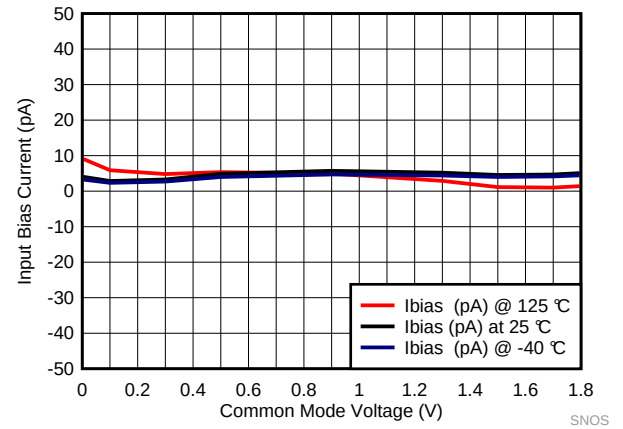
V_S = 1.8 V

図 13. Input Offset Voltage vs Input Common Mode Voltage



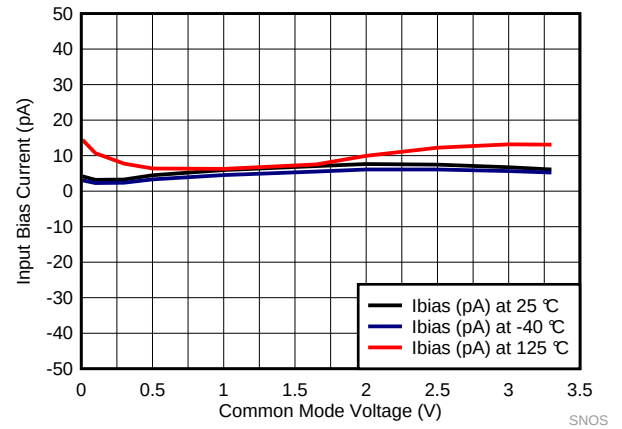
V_S = 3.3 V

図 14. Input Offset Voltage vs Input Common Mode Voltage



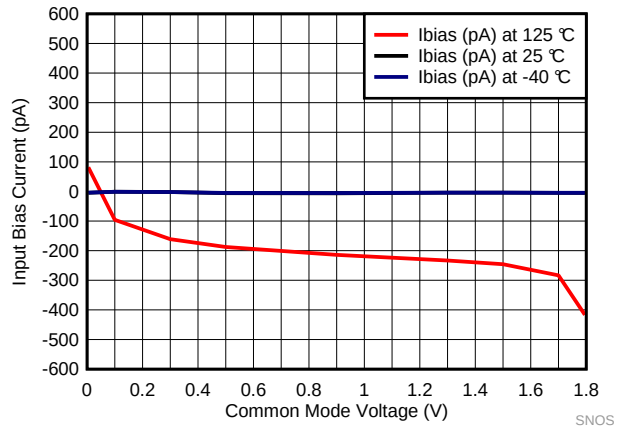
V_S = 1.8 V

図 15. Input Bias Current on +IN Input Pin vs Common Mode Voltage



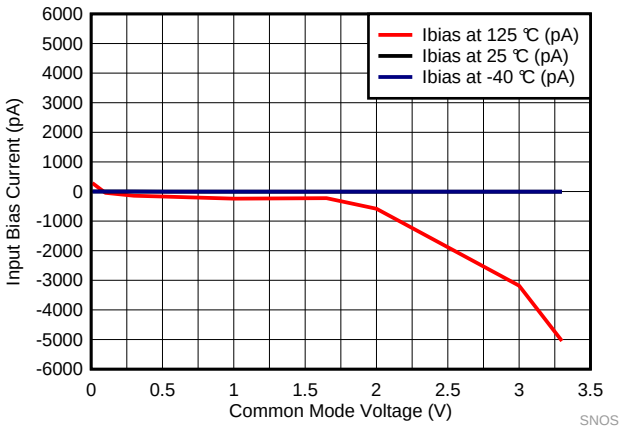
V_S = 3.3 V

図 16. Input Bias Current on +IN Input Pin vs Common Mode Voltage



V_S = 1.8 V

図 17. Input Bias Current on –IN Pin vs Common Mode Voltage



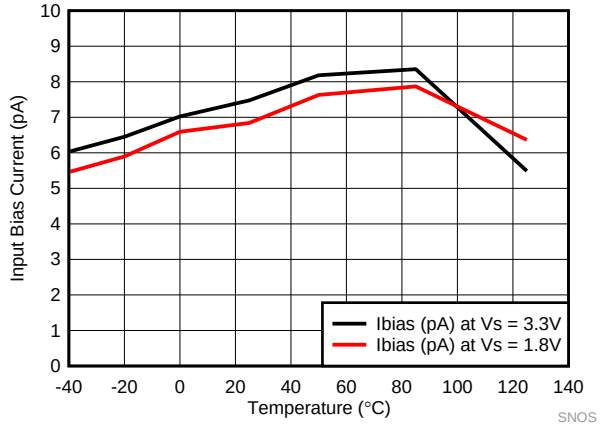
V_S = 3.3 V

図 18. Input Bias Current on –IN Input Pin vs Common Mode Voltage

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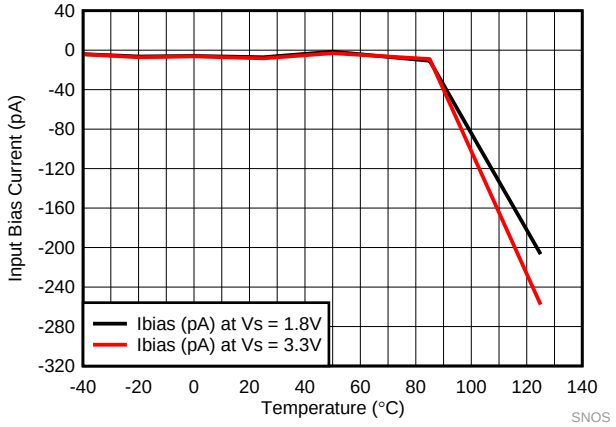
Typical Characteristics (continued)

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L≥ 10 MΩ, unless otherwise noted.



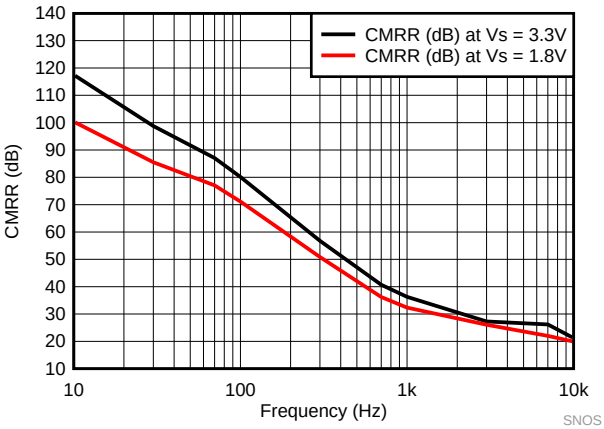
V_S = 3.3 V and 1.8 V

図 19. Input Bias Current ON +IN Input vs Temperature



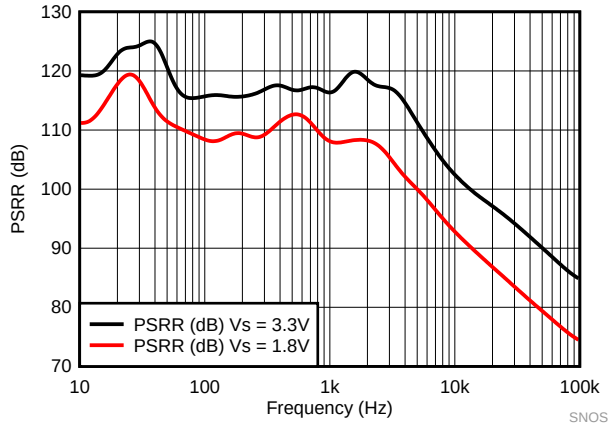
V_S = 3.3 V and 1.8 V

図 20. Input Bias Current on –IN Input Pin vs Temperature



V_S = 3.3 V and 1.8 V

図 21. CMRR vs Frequency



V_S = 3.3 V and 1.8 V

図 22. PSRR vs Frequency

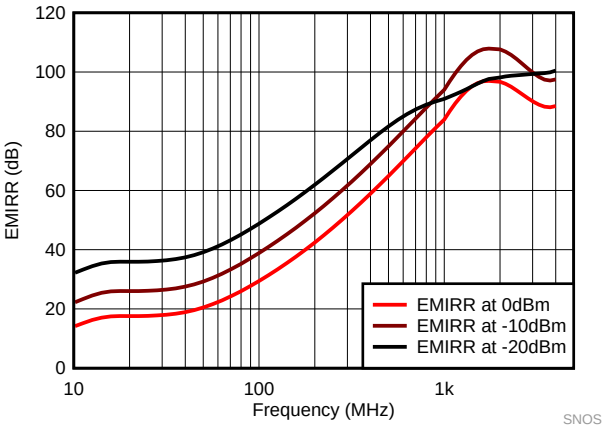
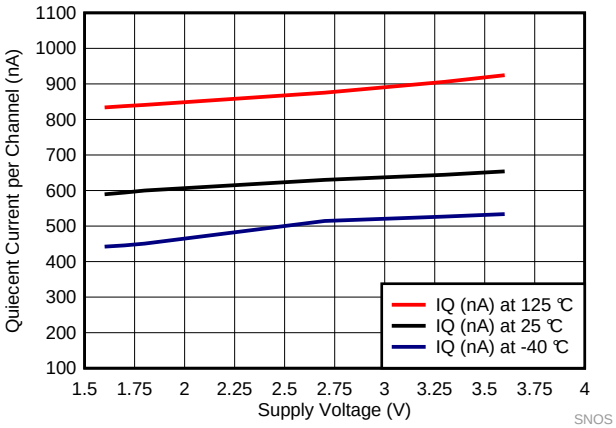


図 23. EMIRR Performance

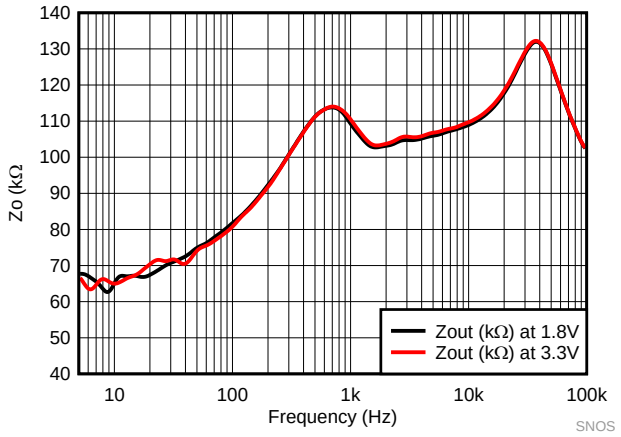


T_A = –40, 25, 125°C

図 24. Per Channel Quiescent Current vs Supply Voltage

Typical Characteristics (continued)

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L≥ 10 MΩ, unless otherwise noted.



V_S = 3.3 V and 1.8 V

図 25. Open Loop Output Impedance

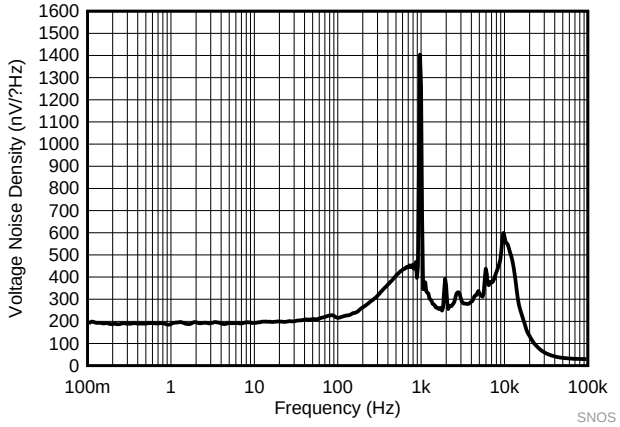
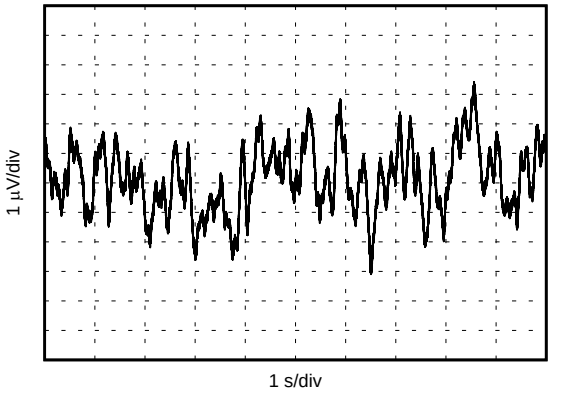
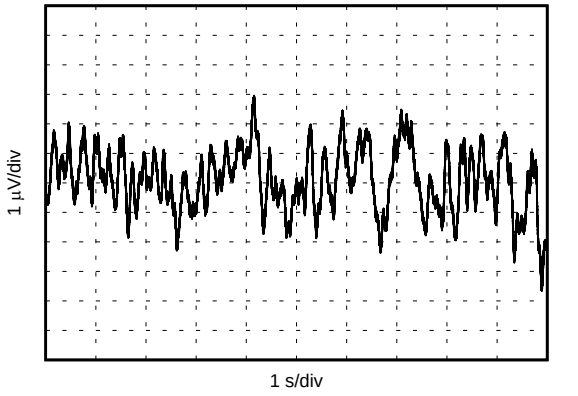


図 26. Voltage Noise Spectral Density vs Frequency



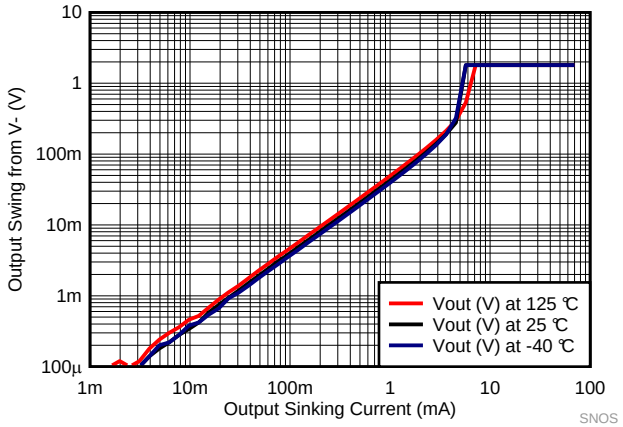
V_S = 3.3 V

図 27. 0.1-Hz to 10-Hz Noise, Vs = 3.3 V



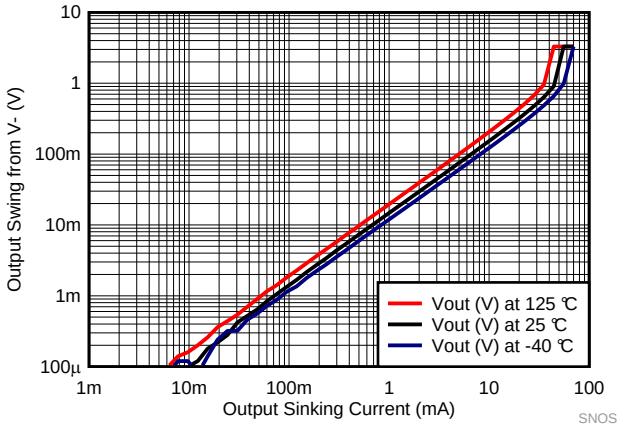
V_S = 1.8 V

図 28. 0.1-Hz to 10-Hz Noise, Vs = 1.8 V



V_S = 1.8 V TA = –40, 25, 125°C

図 29. Output Swing vs. Sinking Current, 1.8 V



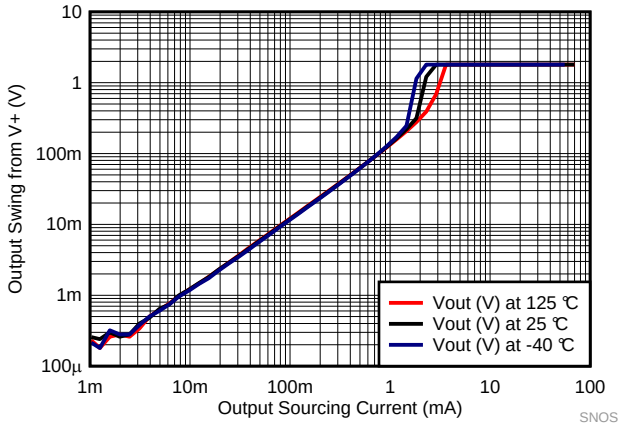
V_S = 3.3 V T_A = –40, 25, 125°C

図 30. Output Swing vs. Sinking Current, 3.3 V

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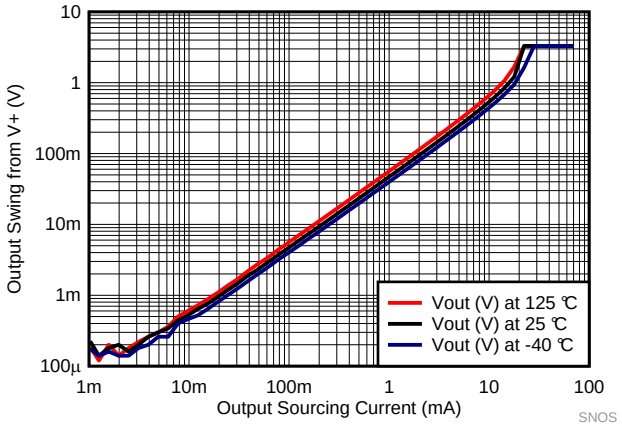
Typical Characteristics (continued)

At T_A = 25°C, V_S = 3.3 V, V_{CM} = V_{OUT} = V_S/2, C_L = 20 pF, and R_L ≥ 10 MΩ, unless otherwise noted.



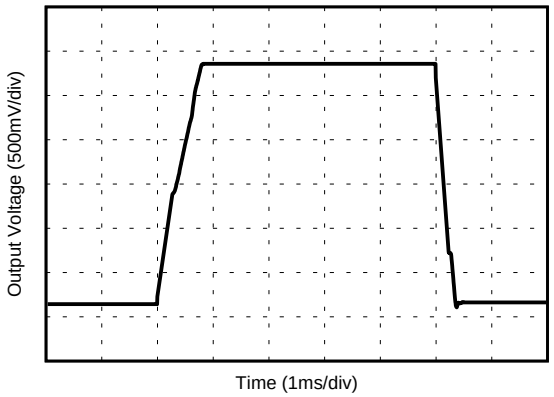
V_S = 1.8 V TA = –40, 25, 125°C

図 31. Output Swing vs Sourcing Current, 1.8 V



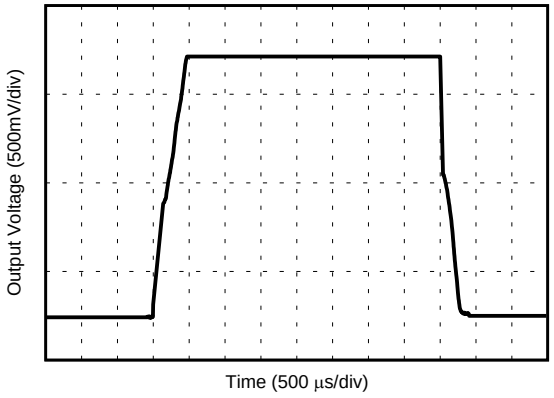
V_S = 3.3 V T_A = –40, 25, 125°C

図 32. Output Swing vs Sourcing Current, 3.3 V



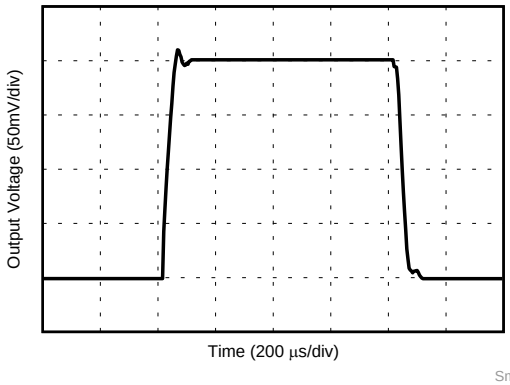
V_{IN} = 2.64 V_{PP} G = 1 R_L = 1 MΩ

図 33. Large-Signal Response, 3.3V



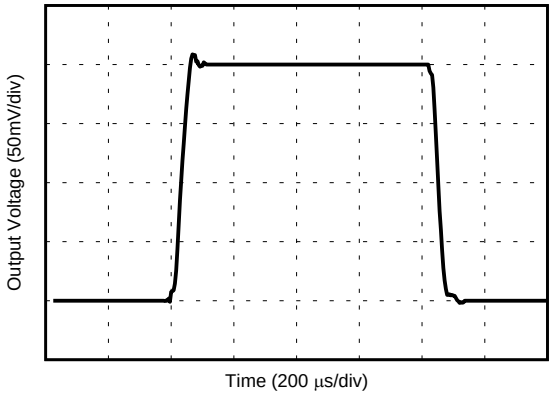
V_{IN} = 1.44 V_{PP} G = 1 R_L = 1 MΩ

図 34. Large-Signal Response, 1.8V



V_{IN} = 0.2 V_{PP} G = 1 R_L = 1 MΩ

図 35. Small Signal Response, 3.3V



V_{IN} = 0.2 V_{PP} G = 1 R_L = 1 MΩ

図 36. Small-Signal Response, 1.8V

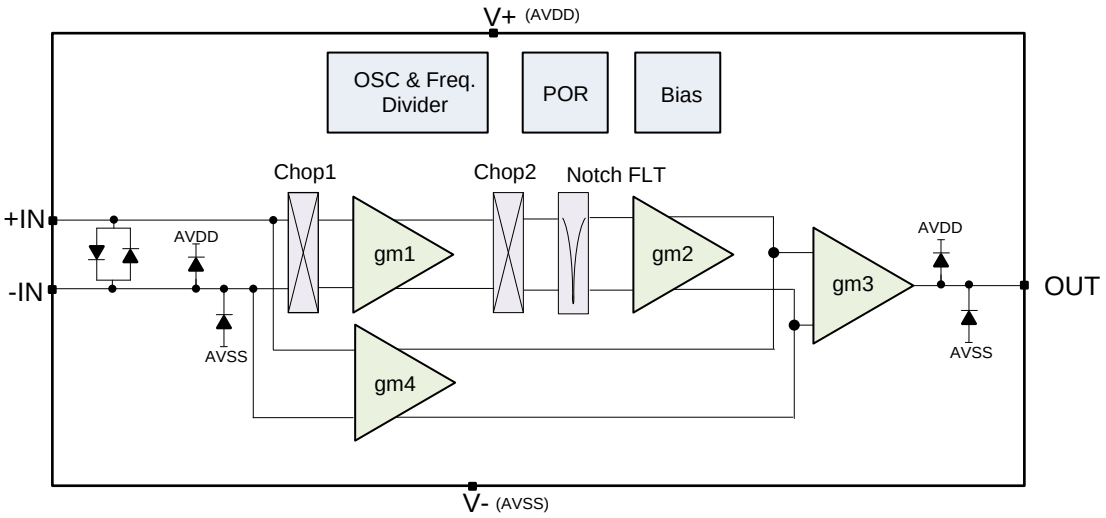
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8 Detailed Description

8.1 Overview

The LPV821 is a zero-drift, nanopower, rail-to-rail input and output operational amplifier. The device operates from 1.7 V to 3.7 V, is unity-gain stable, and is suitable for a wide range of general-purpose applications. The zero-drift architecture provides ultra low offset voltage and near-zero offset voltage drift.

8.2 Functional Block Diagram



8.3 Feature Description

The LPV821 is unity-gain stable and uses an auto-calibration technique to provide low offset voltage and very low drift over time and temperature. For lowest offset voltage and precision performance, optimize circuit layout and mechanical conditions. Avoid temperature gradients that create thermoelectric (Seebeck) effects in the thermocouple junctions formed from connecting dissimilar conductors. Cancel these thermally-generated potentials by assuring they are equal on both input terminals. Other layout and design considerations include:

- Use low thermoelectric-coefficient conditions (avoid dissimilar metals).
- Thermally isolate components from power supplies or other heat sources.
- Shield operational amplifier and input circuitry from air currents, such as cooling fans.

  Following these guidelines reduces the likelihood of junctions being at different temperatures, which can cause thermoelectric voltages of 0.1 μV/°C or higher, depending on materials used.

8.3.1 Operating Voltage

The LPV821 operational amplifier operates over a power-supply range of 1.7 V to 3.6 V (±0.85 V to ± 1.8 V). Parameters that vary over supply voltage or temperature are shown in the *Typical Characteristics* section.

注意

Supply voltages higher than 4 V (absolute maximum) can permanently damage the device.

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Feature Description (continued)

8.3.2 Input

The LPV821 input common-mode voltage range extends to the supply rails. Typically, the input bias current is approximately 7 pA; however, input voltages that exceed the power supplies can cause excessive current to flow into or out of the input pins. Momentary voltages greater than the power supply can be tolerated if the input current is limited to 10 mA. This limitation is easily accomplished with adding a resistor in series with the input, as shown in 図 37.

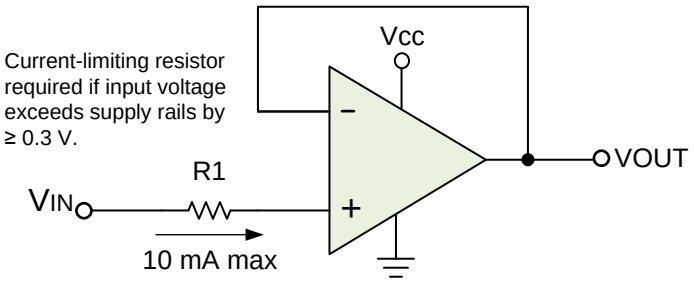


図 37. Input Current Protection

8.3.3 Internal Offset Correction

The LPV821 operational amplifier combines an auto-calibration technique with a time-continuous 8-kHz operational amplifier in the signal path. The amplifier's offset is zero-corrected every 1 ms using a proprietary technique. This design has no aliasing or flicker (1/f) noise.

8.3.4 Input Offset Voltage Drift

The LPV821 operational amplifier's input voltage offset drift is defined over the entire temperature range of –40°C to 125°C. The maximum input voltage drift allows designers to calculate the worst-case input offset change over this temperature range. The maximum input voltage drift over temperature is defined using 式 1:

$$dV_{OS}/dT = \Delta V_{OS} / \Delta T \quad (1)$$

where

- ΔV_{OS} = Change in input offset voltage
- ΔT = Change in temperature (125°C - (-40°C) = 165°C)
- dV_{OS}/dT = Input offset voltage drift

The LPV821 datasheet maximum value for input offset voltage drift is specified for a sample size with a C_{pk} (process capability index) of 2.0.

8.4 Device Functional Modes

The LPV821 has a single functional mode. The device is powered on as long as the power supply voltage is between 1.7 V (±0.85 V) and 3.6 V (±1.8 V).

8.4.1 EMI Performance and Input Filtering

Operational amplifiers vary in susceptibility to EMI. If conducted EMI enters the operational amplifier, the dc offset at the amplifier output can shift from its nominal value when EMI is present. This shift is a result of signal rectification associated with the internal semiconductor junctions. Although all operational amplifier pin functions can be affected by EMI, the input pins are likely to be the most susceptible. The LPV821 operational amplifier incorporates an internal input low-pass filter that reduces the amplifier response to EMI. Both common mode and differential-mode filtering are provided by the input filter.

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Device Functional Modes (continued)

8.4.2 Driving Capacitive Load

The LPV821 is internally compensated for stable unity-gain operation, with a 8-kHz typical gain bandwidth. However, the unity-gain follower is the most sensitive configuration-to-capacitive load. The combination of a capacitive load placed directly on the output of an amplifier along with the output impedance of the amplifier creates a phase lag, which reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response is under-damped, which causes peaking in the transfer and, when there is too much peaking, the op amp might start oscillating.

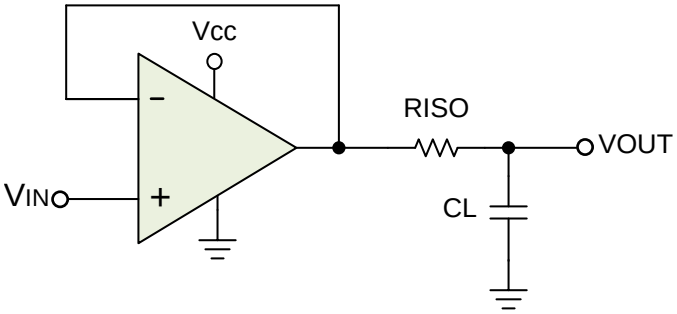


図 38. Resistive Isolation of Capacitive Load

In order to drive heavy (> 50 pF) capacitive loads, use an isolation resistor, R_{ISO}, as shown in 図 38. The value of the R_{ISO} to be used should be decided depending on the size of the $C_L$and the level of performance desired. Recommended minimum values for R_{ISO} are given in the following table, for 3.3V supply. 図 39 shows the typical response obtained with the C_L = 50 pF R_{ISO} = 160 kΩ. By using the isolation resistor, the capacitive load is isolated from the output of the amplifier. The larger the value of R_{ISO}, the more stable the amplifier will be. If the value of R_{ISO} is sufficiently large, the feedback loop is stable, independent of the value of C_L. However, larger values of R_{ISO} (e.g. 50 kΩ) result in reduced output swing and reduced output current drive.

表 1. Capacitive Loads vs. Needed Isolation Resistors

C_L	R_{ISO}
0 – 20 pF	not needed
50 pF	160 kΩ
100 pF	140 kΩ
500 pF	54.9 kΩ
1 nF	33 kΩ
5 nF	15 kΩ
10 nF	5.62 kΩ

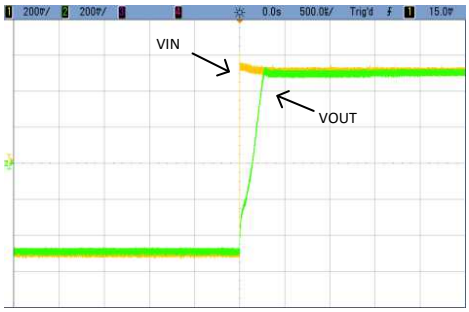


図 39. Typical Step Response

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9 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The LPV821 is a unity-gain stable, precision operational amplifier with very low offset voltage drift; the device is also free from output phase reversal. Applications with noisy or high-impedance power supplies require decoupling capacitors close to the device power-supply pins. In most cases, 0.1-μF capacitors are adequate.

9.2 Typical Applications

9.2.1 Low-Side Current Measurement

This single-supply, low-side, current-sensing solution shown in 図 40 detects load currents up to 1 A. This design uses the LPV821 because of its low offset voltage and rail-to-rail input and output. The LPV821 in the main signal path is configured as a difference amplifier and a second LPV821 provides a buffered bias voltage to allow transition of signal below and above the bias level for bi-direction current sensing. The low offset voltage and offset drift of the LPV821 facilitate excellent dc accuracy for the circuit.

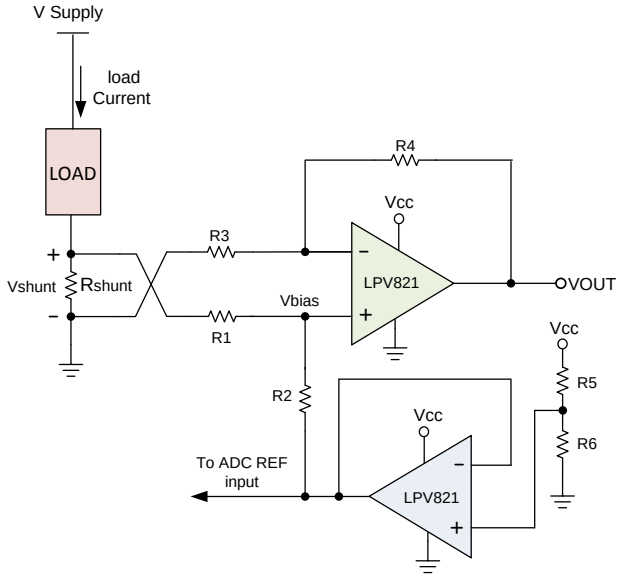


図 40. Low-Side Current Measurement

9.2.1.1 Design Requirements

The design requirements are as follows:

- Supply Voltage: 3.3 V DC
- Input: 1 A (Max)
- Output: 1.65V ± 1.54 V ; (110 mV to 3.19 V)

Typical Applications (continued)

9.2.1.2 Detailed Design Procedure

Referring to 図 40, the load current passing though the shunt resistor (Rshunt) develops the shunt voltage, Vshunt across the resistor. The shunt voltage is then amplified by the LPV821 by the ratio of R4 by R3 . The gain of the difference amplifier is set by the ratio of R4 to R3 . To minimize errors, set R2 = R4 and R1 = R3 . The bias voltage is supplied by buffering a resistor divider using a second LPV821 nanopower op amp. The circuit equations are provided below.

$$V_{out} = V_{shunt} * Gain_{Diff} + V_{bias} \quad (2)$$

$$V_{shunt} = I_{load} * R_{shunt} \quad (3)$$

$$Gain_{Diff} = R_4 / R_3 \quad (4)$$

$$V_{bias} = [R_6 / (R_6 + R_5)] * V_{CC} \quad (5)$$

$$R_{shunt} = [V_{shunt}\ (max)] / [I_{load}\ (max)] \quad (6)$$

Because V_{shunt} is a low-side measurement, a maximum value 100 mV was selected.

$$R_{shunt} = V_{shunt} / I_{load} = 100mV / 1A = 100m\Omega \quad (7)$$

The tolerance of the shunt resistor, the ratio of R4 to R3 and the ratio of R2 to R1 are the main sources of gain error in the signal path. To optimize the cost, a shut resistor with a tolerance of 0.5% was chosen. The main sources of offset errors in the circuit are the voltage divider network comprise of R5, R6 and how closely the ratio of R4 / R3 matches the ration of R2 / R1. The latter value affects the CMRR of the difference amplifier, ultimately translating to an offset error.

The shunt voltage is scaled down by a divider network made of R1 and R2 before reaching the LPV821 amplifier stage. The voltage present at the non-inverting node of the LPV821 should not exceed the common-mode range of the device. The extremely low offset voltage and drift of the LPV821 ensures minimized offset error in the measurement.

In case a bi-direction current sensing is required, for symmetric load current of –1 A to 1 A, the voltage divider resistors R5 and R6 must be equal. To minimize power consumption, 100-kΩ resistors with a tolerance of 0.5% were selected.

To set the gain of the difference amplifier, the common-mode range and output swing of the LPV821 must be considered. The gain of the difference amplifier can now be calculated as shown below

$$Gain = [Vout\ (max) - Vout\ (min)] / [R_{shunt} * (I_{max} – I_{min})] = [3.2\ V - 100\ mV] / [100\ m\Omega] * [1A – (–1A)] = 15.5\ V / V \quad (8)$$

10 Power Supply Recommendations

The LPV821 is specified for operation from 1.7 V to 3.6 (±0.85 V to ±1.8 V); many specifications apply from –40°C to 125°C. The *Typical Characteristics* presents parameters that can exhibit significant variance with regard to operating voltage or temperature.

注意

Supply voltages larger than 4 V can permanently damage the device (see the *Absolute Maximum Ratings*).

TI recommends placing 0.1-µF bypass capacitors close to the power-supply pins to reduce errors coupling in from noisy or high-impedance power supplies. For more detailed information on bypass capacitor placement, refer to the *Layout* section.

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11 Layout

11.1 Layout Guidelines

11.1.1 General Layout Guidelines

Pay attention to good layout practices. Keep traces short and when possible, use a printed-circuit-board (PCB) ground plane with surface-mount components placed as close to the device pins as possible. Place a 0.1-µF capacitor closely across the supply pins. Apply these guidelines throughout the analog circuit to improve performance and provide benefits, such as reducing the electromagnetic interference (EMI) susceptibility.

Operational amplifiers vary in susceptibility to radio frequency interference (RFI). RFI can generally be identified as a variation in offset voltage or DC signal levels with changes in the interfering RF signal. The LPV821 is specifically designed to minimize susceptibility to RFI and demonstrates remarkably low sensitivity compared to previous generation devices. Strong RF fields may still cause varying offset levels.

11.2 Layout Example

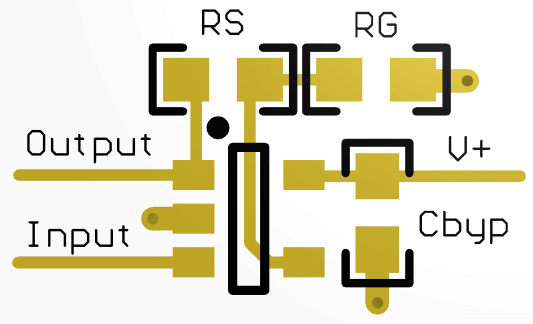


図 41. SOT-23 Layout Example

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12 デバイスおよびドキュメントのサポート

12.1 デバイス・サポート

12.1.1 開発サポート

TINA-TI SPICEベースのアナログ・シミュレーション・プログラム

DIP アダプタ評価モジュール

TIユニバーサル・オペアンプ評価モジュール

TI FilterProフィルタ設計ソフトウェア

12.2 関連リンク

次の表に、クイック・アクセス・リンクを示します。カテゴリには、技術資料、サポートおよびコミュニティ・リソース、ツールとソフトウェア、およびサンプル注文またはご購入へのクイック・アクセスが含まれます。

表 2. 関連リンク

製品	プロダクト・フォルダ	サンプルとご購入	技術資料	ツールとソフトウェア	サポートとコミュニティ
LPV821	ここをクリック	ここをクリック	ここをクリック	ここをクリック	ここをクリック

12.3 ドキュメントの更新通知を受け取る方法

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12.4 コミュニティ・リソース

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設計サポート ***TIの設計サポート*** 役に立つE2Eフォーラムや、設計サポート・ ツールをすばやく見つけることができます。技術サポート用の連絡先情報も参照できます。

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12.6 静電気放電に関する注意事項

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静電気放電はわずかな性能の低下から完全なデバイスの故障に至るまで、様々な損傷を与えます。高精度の集積回路は、損傷に対して敏感であり、極めてわずかなパラメータの変化により、デバイスに規定された仕様に適合しなくなる場合があります。

12.7 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LPV821DBVR	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1CHF
LPV821DBVR.A	Active	Production	SOT-23 (DBV) | 5	3000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1CHF

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

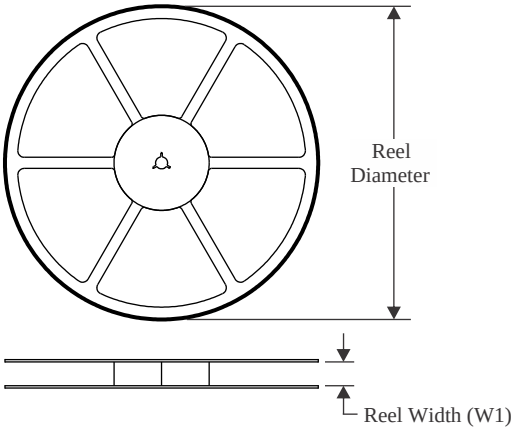
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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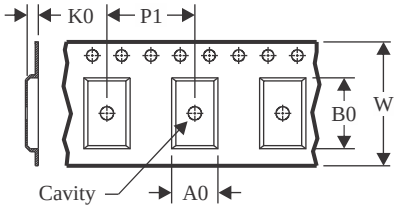
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

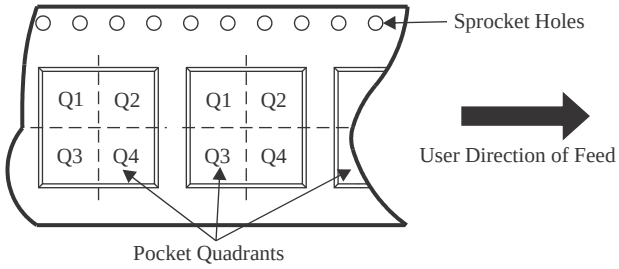


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

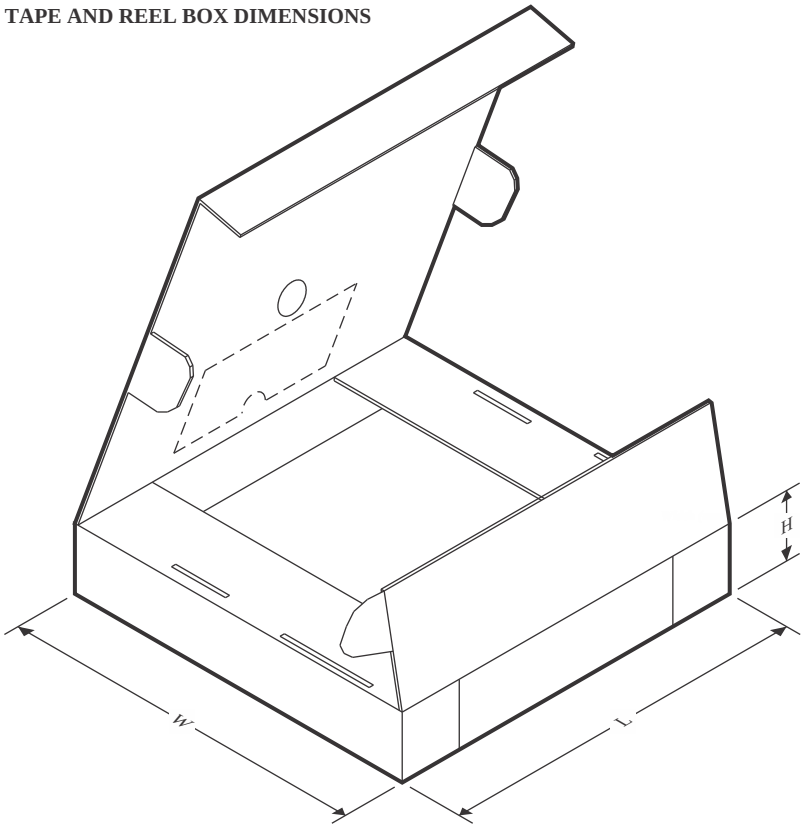
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LPV821DBVR	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

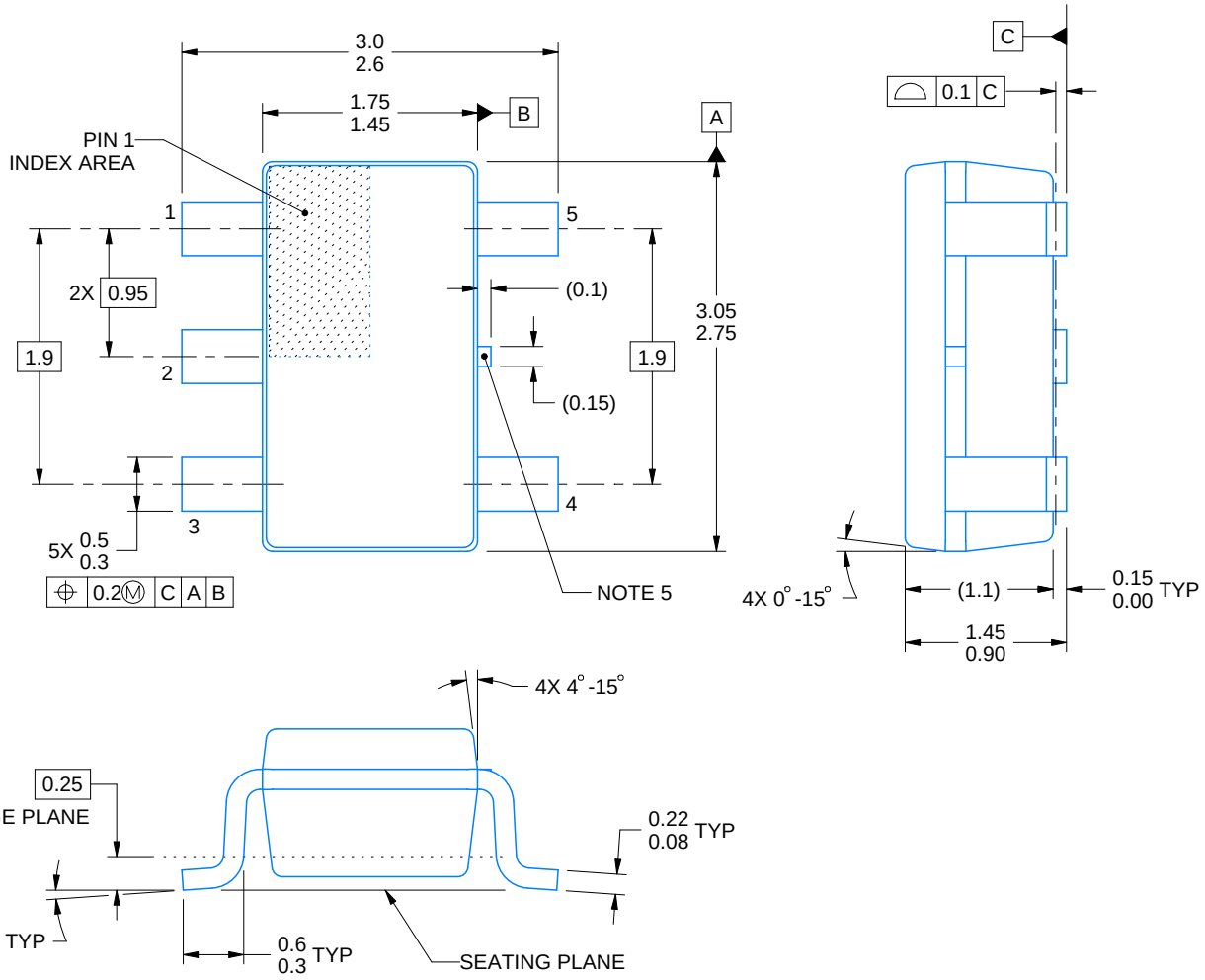
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LPV821DBVR	SOT-23	DBV	5	3000	208.0	191.0	35.0

PACKAGE OUTLINE

DBV0005A

SOT-23 - 1.45 mm max height

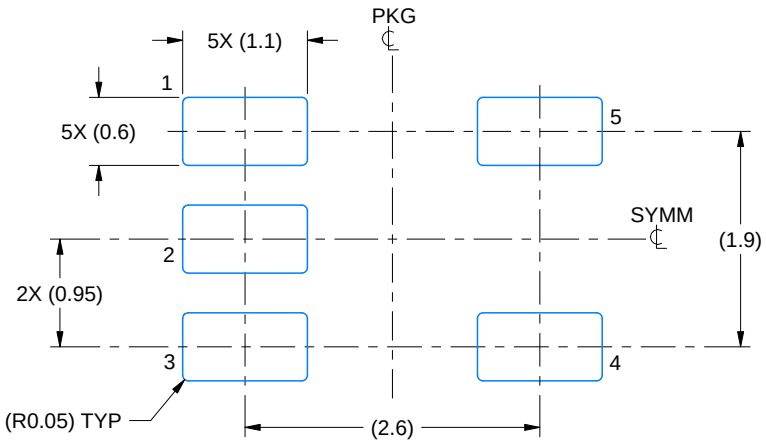
SMALL OUTLINE TRANSISTOR



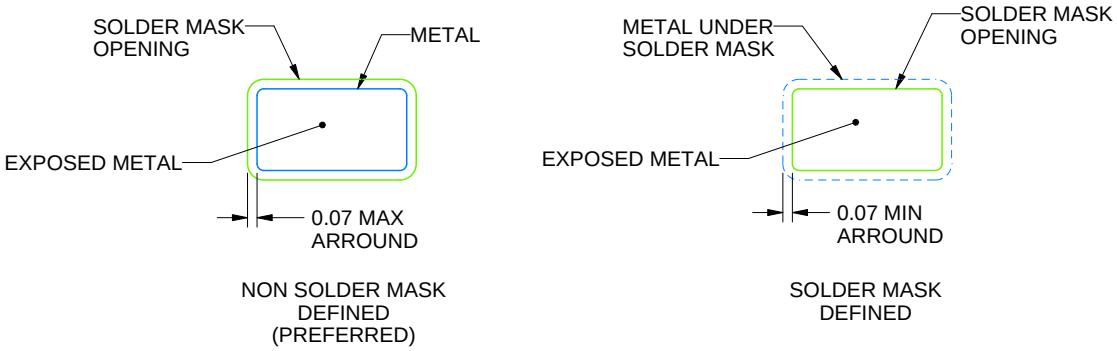
4214839/K 08/2024

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Refernce JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X

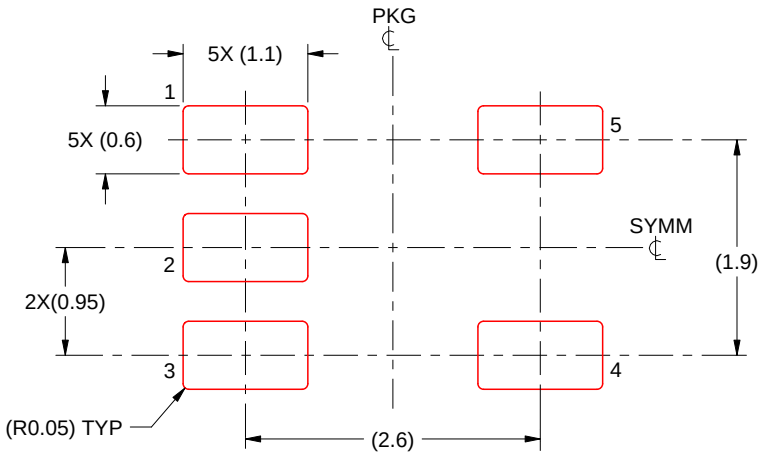


SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:15X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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