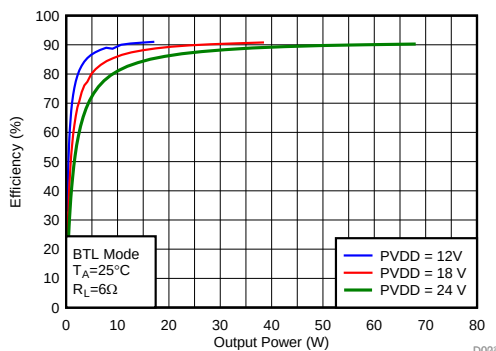


TAS5755M 2×50W (2×19W + 1×50W)、オーディオ・プロセッサ搭載、 2.1モード対応のデジタル入力オーディオ・アンプ

1 特長

- Sol低減
 - シングル・チップで2.1、2.0、モノラルの各モードに対応
 - モノラル(PBTL)モードでのシングル・フィルタ
 - パッド・アップ・パッケージと80mΩのR_{DS(on)}により熱特性を強化
- 大きな出力電力に対応
 - 2.1モードで2×19W + 1×50W (2×4Ω + 1×6Ω, 24V)
 - 2.0モードで2×50W (2×6Ω, 24V)
 - モノラル・モードで1×100W (1×2Ω, 24V)
 - 広い電圧範囲: 8V~26.4V
- オーディオ性能
 - 1kHzでTHD+N ≤ 0.05% (R_{SPK} = 8Ω, P_{OUT} = 1W, PVDD = 18V)
 - ICN ≤ 50μVRMS
 - クロストーク ≤ -67dB
 - SNR ≥ 104dB
 - BD変調を利用してオーディオ性能と効率を向上可能
- 内蔵のオーディオ処理
 - 2×8 + 1×2バイクワッド
 - 2バンド + 1バンドの構成可能なダイナミック・レンジ制御(DRC)
 - ライセンス不要の3Dエフェクト
 - 信号ミキシングおよびDCブロッキング・フィルタ
 - 自動レイト検出
- 内蔵の自己保護機能
 - 過熱保護
 - 過電流制限保護
 - 低電圧保護

効率と合計出力電力との関係



2 アプリケーション

- DTV、UHD、および多用途モニタ
- サウンドバー、PCオーディオ
- 汎用オーディオ機器

3 概要

TAS5755Mはシングル・チップの柔軟なデジタル・オーディオ・ソリューションで、2.1 (2スピーカー+サブウーファー)、2.0またはステレオ(2スピーカー)、モノラル(大電力スピーカー)モードをサポートする処理機能が内蔵されています。

高効率、80mΩの低R_{DS(on)}、パッド・アップ・パッケージにより、このデバイスは最大2×50Wまたは1×100Wを出力できます。

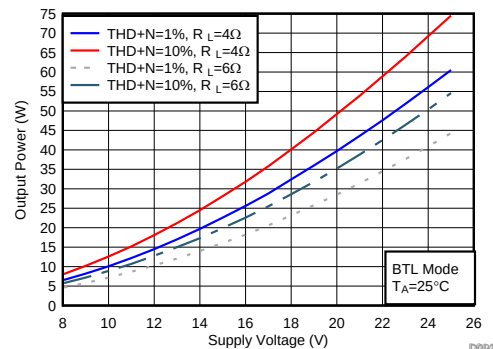
TAS5755Mは、ステレオ・モードでは各チャンネルに2つのフルHブリッジを使用します。2.1モードでは、TAS5755Mは2つのハーフ・ブリッジを使用して2つの独立したスピーカー・チャンネルを駆動しながら、サブウーファーをフル・ブリッジで駆動します。最後にモノラル・モードでは、1つのフィルタ段のみを使用してプリフィルタの平行・ブリッジ接続負荷(PBTL)をサポートし、システム全体のサイズとコストを削減できます。

製品情報⁽¹⁾

型番	パッケージ	本体サイズ(公称)
TAS5755M	DFD	14mm×6.1mm

(1) 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。

出力電力と電源電圧との関係



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4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Revision B (January 2018) to Revision C	Page
Changed "DVSSO" in OSC_RES Pin Description to "DVSS_OSC ground."	7
Added R _{θJA} in Thermal Information Table	9
Changed R _{θJC(top)} in Thermal Information Table	9
Added R _{θJB} in Thermal Information Table	9
Added Ψ _{JT} in Thermal Information Table	9
Added R _{θJC(bot)} in Thermal Information Table	9

Revision A (November 2017) to Revision B	Page
Changed SE Mode, PVDD = 24 V, R _L = 4Ω, 7% THD from 17.1 W to 17.6 W in AC Electrical Characteristics (BTL, PBTL)	10
Changed SE Mode, PVDD = 24 V, R _L = 4Ω, 10% THD from 18.1 W to 19 W in AC Electrical Characteristics (BTL, PBTL)	10
Changed 図 6 and 図 7	14
Changed 図 19, 図 20, and 図 21	17
Changed 図 33, 図 34, and 図 35	20

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- デバイスを量産データとしてリリース [4](#)
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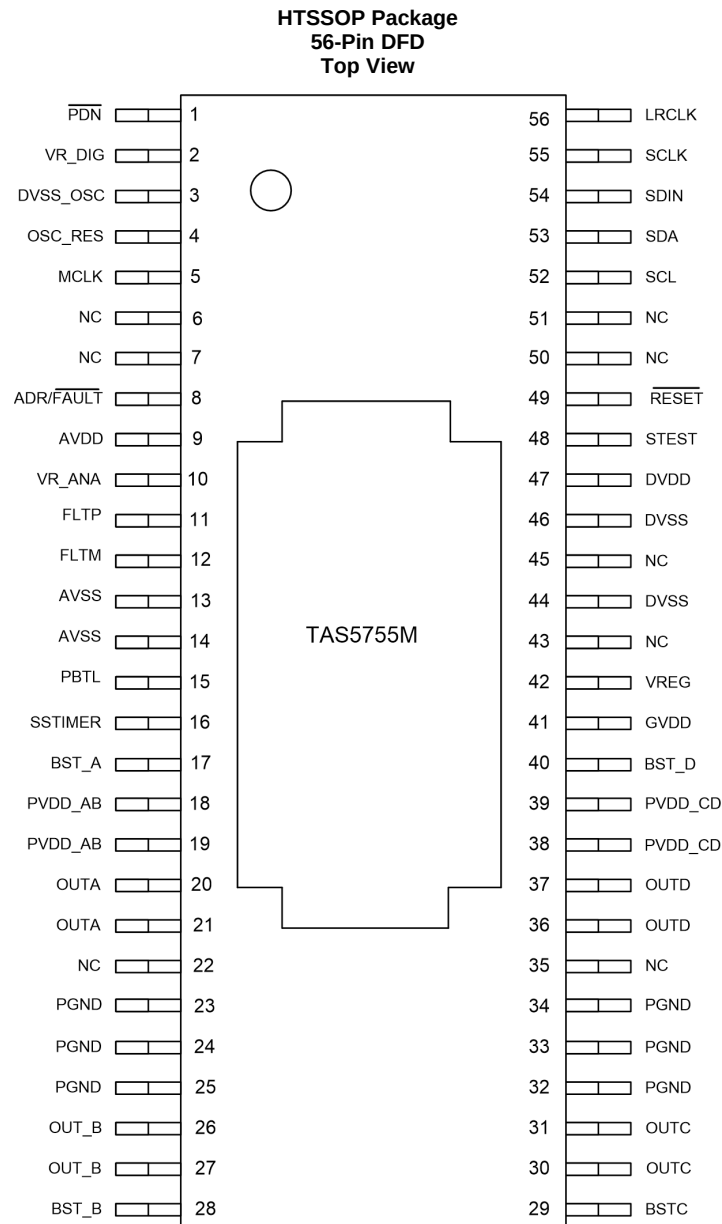
5 概要（続き）

TAS5755Mにはオーディオ処理機能として、信号ミキシング、DCブロッキング・フィルタ、イコライゼーション用の $2 \times 8 + 1 \times 2$ バイクワッドが内蔵されています。2バンドの対数形式DRCと、サブウーファー・チャンネル用に別のシングル・バンドDRCを使用して、電力制限が実装されています。

6 Device Comparison Table

	TAS5755M	TAS5731M	TAS5729MD	TAS5721	TAS5717	TAS5711
Max Power to Single-Ended Load	19	18		10		16
Max Power to Bridge Tied Load	50	37	20	15	10	20
Max Power to Parallel Bridge Tied Load	100	70	40	30		40
Min Supported Single-Ended Load	2	2		4		4
Min Supported Bridge Tied Load	4	4	4	8	4	6
Min Supported Parallel Bridge Tied Load	2	2	4	4		4
Closed/Open Loop	Open	Open	Open	Open	Open	Open
Max Speaker Outputs	3	3	2	3	2	3
Headphone Channels			Yes	Yes	Yes	
Architecture	Class D	Class D	Class D	Class D	Class D	Class D
Dynamic Range Control (DRC)	2-Band	2-Band	2-Band AGL	2-Band	2-Band AGL	Single-Band
Biquads (EQ)	21	21	28	21	28	21

7 Pin Configuration and Functions



Pin Functions

PIN		TYPE ⁽¹⁾	DESCRIPTION
NAME	NO.		
ADR/FAULT	8	DIO	Dual function terminal which sets the LSB of the 7-bit I2C address to "0" if pulled to GND and to "1" if pulled to DVDD. If configured to be a fault output by the methods described in I ² C Address Selection and Fault Output, this terminal is pulled low when an internal fault occurs. A pull-up or pull-down resistor is required, as is shown in the Typical Application Circuit Diagrams. If pulled high (to DVDD), a 15-kΩ resistor must be used to minimize in-rush current at power up and to isolate the net if the pin is used as a fault output, as described above.
AVDD	9	P	3.3-V analog power supply
AVSS	13,14	P	Analog 3.3-V supply ground
BST_A	17	P	High-side bootstrap supply for half-bridge A
BST_B	28	P	High-side bootstrap supply for half-bridge B

(1) TYPE: A = analog; D = 3.3-V digital; P = power/ground/decoupling; I = input; O = output

Pin Functions (continued)

PIN		TYPE ⁽¹⁾	DESCRIPTION
NAME	NO.		
BST_C	29	P	High-side bootstrap supply for half-bridge C
BST_D	40	P	High-side bootstrap supply for half-bridge D
DVDD	47	P	3.3-V digital power supply
DVSS	44,46	P	Digital ground
DVSS_OSC	3	P	Oscillator ground
GVDD	41	P	Gate drive internal regulator output
LRCLK	56	P	Input serial audio data left/right clock (sample-rate clock)
MCLK	5	DI	Master clock input
NC	6,7,22,35, 43,45,50,51	–	No connect
OSC_RES	4	AO	Oscillator trim resistor. Connect an 18.2-k Ω , 1% resistor to DVSS_OSC ground.
OUT_A	20,21	O	Output, half-bridge A
OUT_B	26,27	O	Output, half-bridge B
OUT_C	30,31	O	Output, half-bridge C
OUT_D	36,37	O	Output, half-bridge D
PBTL	15	DI	Low means BTL mode; high means PBTL mode. Information goes directly to power stage.
$\overline{\text{PDN}}$	1	DI	Power down, active-low. $\overline{\text{PDN}}$ prepares the device for loss of power supplies by shutting down the noise shaper and initiating the PWM stop sequence.
PGND	23,24,25, 32,33,34	P	Power ground for half-bridges A and B
FLTM	12	AO	PLL negative loop-filter terminal
FLTP	11	AO	PLL positive loop-filter terminal
PVDD_AB	18,19	P	Power-supply input for half-bridge output A and B
PVDD_CD	38,39	P	Power-supply input for half-bridge output C and D
$\overline{\text{RESET}}$	49	DI	Reset, active-low. A system reset is generated by applying a logic low to this pin. RESET is an asynchronous control signal that restores the DAP to its default conditions and places the PWM in the hard-mute (high-impedance) state.
SCL	52	DI	I ² C serial control clock input
SCLK	55	DI	Serial audio-data clock (shift clock). SCLK is the serial-audio-port input-data bit clock.
SDA	53	DIO	I ² C serial control data interface input/output
SDIN	54	DI	Serial audio data input. SDIN supports three discrete (stereo) data formats.
SSTIMER	16	AI	Controls ramp time of OUT_x to minimize pop. Leave this pin floating for BD mode. Requires capacitor of 2.2 nF to GND in AD mode. The capacitor determines the ramp time.
STEST	48	DI	Factory test pin. Connect directly to DVSS.
VR_ANA	10	P	Internally regulated 1.8-V analog supply voltage. This pin must not be used to power external devices.
VR_DIG	2	P	Internally regulated 1.8-V digital supply voltage. This pin must not be used to power external devices.
VREG	42	P	Digital regulator output. Not to be used for powering external circuitry.
PowerPAD™		P	Connect to GND for best system performance. If not connected to GND, leave floating.

8 Specifications

8.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Supply voltage	DVDD, AVDD	−0.3	4.2	V
	PVDD_x	−0.3	30	V
Input voltage	3.3-V digital input	−0.5	DVDD + 0.5	V
	5-V tolerant ⁽²⁾ digital input (except MCLK)	−0.5	DVDD + 2.5 ⁽³⁾	
	5-V tolerant MCLK input	−0.5	AVDD + 2.5 ⁽³⁾	
OUT_x to PGND_x			32 ⁽⁴⁾	V
BST_x to PGND_x			39 ⁽⁴⁾	V
Input clamp current, I _{IK}		−20	20	mA
Output clamp current, I _{OK}		−20	20	mA
Operating free-air temperature		0	85	°C
Operating junction temperature		0	150	°C
Storage temperature, T _{stg}		−40	125	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) 5-V tolerant inputs are PDN, RESET, SCLK, LRCLK, MCLK, SDIN, SDA, and SCL.
- (3) Maximum pin voltage must not exceed 6 V.
- (4) DC voltage + peak ac waveform measured at the pin must be below the allowed limit for all conditions.

8.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±1000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±250	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

8.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
Digital/analog supply voltage		DVDD, AVDD	3	3.3	3.6	V
Half-bridge supply voltage		PVDD_x	8		26.4 ⁽¹⁾	V
V _{IH}	High-level input voltage	5-V tolerant	2			V
V _{IL}	Low-level input voltage	5-V tolerant			0.8	V
T _A	Operating ambient temperature range		0		85	°C
T _J ⁽²⁾	Operating junction temperature range		0		125	°C
R _L (PBTL)	Load impedance	Output filter: L = 15 μH, C = 680 nF	2			Ω
R _L (BTL)	Load impedance	Output filter: L = 15 μH, C = 680 nF	4			Ω
R _L (SE)	Load impedance	Output filter: L = 15 μH, C = 680 nF	2			Ω
L _O	Output-filter inductance	Minimum output inductance under short-circuit condition	10			μH

- (1) For operation at PVDD_x levels greater than 18 V, the modulation limit must be set to 93.8% through the control port register 0x10.
- (2) Continuous operation above the recommended junction temperature may result in reduced reliability and/or lifetime of the device.

8.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TAS5755M	UNIT
		DFD HTSSOP	
		56-PIN	
R _{θJA}	Junction-to-ambient thermal resistance	50.9	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	1.3	°C/W
R _{θJB}	Junction-to-board thermal resistance	26.9	°C/W
ψ _{JT}	Junction-to-top characterization parameter	3.1	°C/W
ψ _{JB}	Junction-to-board characterization parameter	26.7	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

8.5 PWM Operation at Recommended Operating Conditions

PARAMETER	TEST CONDITIONS	VALUE	UNIT
Output PWM switch frequency	11.025/22.05/44.1-kHz data rate ±2%	352.8	kHz
	48/24/12/8/16/32-kHz data rate ±2%	384	

8.6 DC Electrical Characteristics

T_A = 25°, PVDD_{_X} = 18 V, DVDD = AVDD = 3.3 V, R_L = 8 Ω, BTL AD mode, f_S = 48 kHz (unless otherwise noted)

PARAMETER			TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{OH}	High-level output voltage	ADR/ $\overline{\text{FAULT}}$ and SDA	I _{OH} = −4 mA DVDD = 3 V	2.4			V
V _{OL}	Low-level output voltage	ADR/ $\overline{\text{FAULT}}$ and SDA	I _{OL} = 4 mA DVDD = 3 V			0.5	V
I _{IL}	Low-level input current		V _I < V _{IL} ; DVDD = AVDD = 3.6 V			75	μA
I _{IH}	High-level input current		V _I > V _{IH} ; DVDD = AVDD = 3.6 V			75 ⁽¹⁾	μA
I _{DD}	3.3-V supply current	3.3-V supply voltage (DVDD, AVDD)	Normal mode	49	68	mA	
			Reset ($\overline{\text{RESET}}$ = low, PDN = high)	23	38		
I _{PVDD}	Supply current	No load (PVDD_x)	Normal mode	32	50	mA	
			Reset ($\overline{\text{RESET}}$ = low, PDN = high)	4	8		
r _{DS(on)} ⁽²⁾	Drain-to-source resistance, LS	T _J = 25°C, includes metallization resistance		80		mΩ	
	Drain-to-source resistance, HS	T _J = 25°C, includes metallization resistance		80			
I/O PROTECTION							
V _{uvp}	Undervoltage protection limit	PVDD falling		6.4		V	
V _{uvp,hyst}	Undervoltage protection limit	PVDD rising		7.1		V	
OTE ⁽³⁾	Overtemperature error			150		°C	
OTE _{HYST} ⁽³⁾	Extra temperature drop required to recover from error			30		°C	
I _{OC}	Overcurrent limit protection	Output to output short in BTL mode		6		A	
I _{OCT}	Overcurrent response time			150		ns	

(1) I_{IH} for the PBTL pin has a maximum limit of 200 μA due to an internal pulldown on the pin.

(2) This does not include bond-wire or pin resistance.

(3) Specified by design.

8.7 AC Electrical Characteristics (BTL, PBTL)

PVDD_x = 18 V, BTL AD mode, f_S = 48 kHz, R_L = 8 Ω, C_{BST} = 10 nF, audio frequency = 1 kHz, AES17 filter, f_{PWM} = 384 kHz, T_A = 25°C (unless otherwise noted). All performance is in accordance with recommended operating conditions (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P _O	Power output per channel	BTL mode, PVDD = 8 V, R _L = 8 Ω, 7% THD		3.9		W
		BTL mode, PVDD = 8 V, R _L = 8 Ω, 10% THD		4.2		
		BTL mode, PVDD = 12 V, R _L = 8 Ω, 7% THD		8		
		BTL mode, PVDD = 12 V, R _L = 8 Ω, 10% THD		9.6		
		BTL mode, PVDD = 18 V, R _L = 8 Ω, 7% THD		18.7		
		BTL mode, PVDD = 18 V, R _L = 8 Ω, 10% THD		21.2		
		BTL mode, PVDD = 24 V, R _L = 8 Ω, 7% THD		32.6		
		BTL mode, PVDD = 24 V, R _L = 8 Ω, 10% THD		37.2		
		BTL mode, PVDD = 24 V, R _L = 6 Ω, 10% THD		50		
		PBTL mode, PVDD = 12 V, R _L = 4 Ω, 7% THD		16.5		
		PBTL mode, PVDD = 12 V, R _L = 4 Ω, 10% THD		17.9		
		PBTL mode, PVDD = 18 V, R _L = 4 Ω, 7% THD		37		
		PBTL mode, PVDD = 18 V, R _L = 4 Ω, 10% THD		39.6		
		PBTL mode, PVDD = 24 V, R _L = 4 Ω, 10% THD		66		
		PBTL mode, PVDD = 24 V, R _L = 4 Ω, 10% THD		69.6		
		SE Mode, PVDD = 12 V, R _L = 4 Ω, 7% THD		4.2		
		SE Mode, PVDD = 12 V, R _L = 4 Ω, 10% THD		4.6		
		SE Mode, PVDD = 18 V, R _L = 4 Ω, 7% THD		9.6		
		SE Mode, PVDD = 18 V, R _L = 4 Ω, 10% THD		10.2		
		SE Mode, PVDD = 24 V, R _L = 4 Ω, 7% THD		17.6		
		SE Mode, PVDD = 24 V, R _L = 4 Ω, 10% THD		19		
THD+N	Total harmonic distortion + noise	PVDD = 8 V, P _O = 1 W		0.15%		
		PVDD = 12 V, P _O = 1 W		0.03%		
		PVDD = 18 V, P _O = 1 W		0.04%		
		PVDD = 24 V, P _O = 1 W		0.1%		
V _n	Output integrated noise (rms)	A-weighted		46		μV
	Cross-talk	P _O = 0.25 W, f = 1 kHz (AD Mode)		–67		dB
SNR	Signal-to-noise ratio ⁽¹⁾	A-weighted, f = 1 kHz, maximum power at THD < 1%		104		dB

(1) SNR is calculated relative to 0-dBFS input level.

8.8 Electrical Characteristics - PLL External Filter Components

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
External PLL filter capacitor C1	SMD 0603 X7R		47		nF
External PLL filter capacitor C2	SMD 0603 X7R		4.7		nF
External PLL filter resistor R	SMD 0603, metal film		470		Ω

8.9 Electrical Characteristic - I²C Serial Control Port Operation

for I²C Interface signals over recommended operating conditions (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
C _L	Load capacitance for each bus line			400	pF

8.10 Timing Requirements - PLL Input Parameters

		MIN	NOM	MAX	UNIT
f_{MCLKI}	MCLK frequency	2.8224		24.576	MHz
	MCLK duty cycle	40%	50%	60%	
$t_r/t_f(MCLK)$	Rise/fall time for MCLK			5	ns
	LRCLK allowable drift before LRCLK reset			4	MCLKs

8.11 Timing Requirements - Serial Audio Ports Slave Mode

over recommended operating conditions (unless otherwise noted)

		MIN	NOM	MAX	UNIT
f_{SCLKIN}	Frequency, SCLK $32 \times f_S$, $48 \times f_S$, $64 \times f_S$	1.024		12.288	MHz
t_{su1}	Setup time, LRCLK to SCLK rising edge	10			ns
t_{h1}	Hold time, LRCLK from SCLK rising edge	10			ns
t_{su2}	Setup time, SDIN to SCLK rising edge	10			ns
t_{h2}	Hold time, SDIN from SCLK rising edge	10			ns
	LRCLK frequency	8	48	48	kHz
	SCLK duty cycle	40%	50%	60%	
	LRCLK duty cycle	40%	50%	60%	
	SCLK rising edges between LRCLK rising edges	32		64	SCLK edges
$t_{(edge)}$	LRCLK clock edge with respect to the falling edge of SCLK	-1/4		1/4	SCLK period
t_r/t_f	Rise/fall time for SCLK/LRCLK			8	ns

8.12 Timing Requirements - I²C Serial Control Port Operation

for I²C Interface signals over recommended operating conditions (unless otherwise noted)

		MIN	NOM	MAX	UNIT
f_{SCL}	Frequency, SCL			400	kHz
$t_{w(H)}$	Pulse duration, SCL high	0.6			μs
$t_{w(L)}$	Pulse duration, SCL low	1.3			μs
t_r	Rise time, SCL and SDA			300	ns
t_f	Fall time, SCL and SDA			300	ns
t_{su1}	Setup time, SDA to SCL	100			ns
t_{h1}	Hold time, SCL to SDA	0			ns
$t_{(buf)}$	Bus free time between stop and start conditions	1.3			μs
t_{su2}	Setup time, SCL to start condition	0.6			μs
t_{h2}	Hold time, start condition to SCL	0.6			μs
t_{su3}	Setup time, SCL to stop condition	0.6			μs

8.13 Timing Requirements - Reset ($\overline{RESET}$)

Control signal parameters over recommended operating conditions (unless otherwise noted).

		MIN	NOM	MAX	UNIT
$t_{w(RESET)}$	Pulse duration, $\overline{RESET}$ active	100			μs
$t_{d(I2C_ready)}$	Time to enable I ² C			12	ms

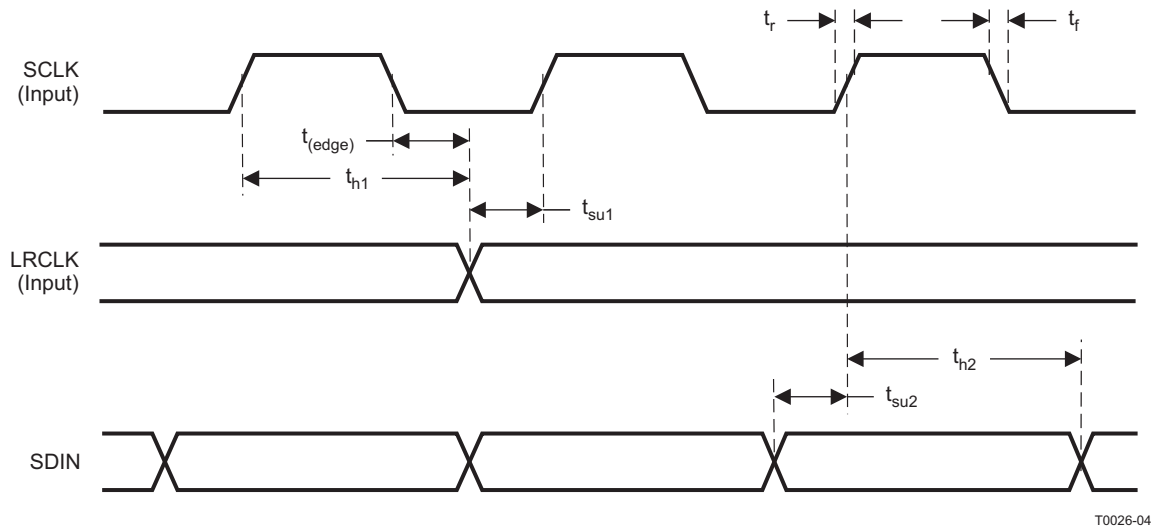


图 1. Slave-Mode Serial Data-Interface Timing

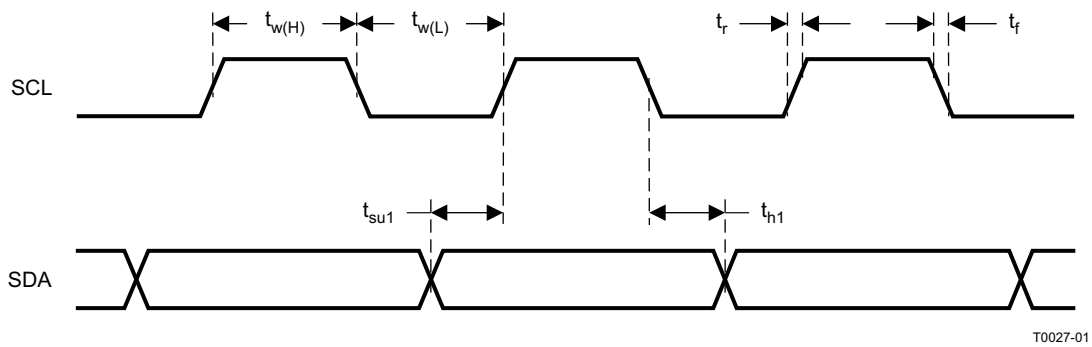


图 2. SCL and SDA Timing

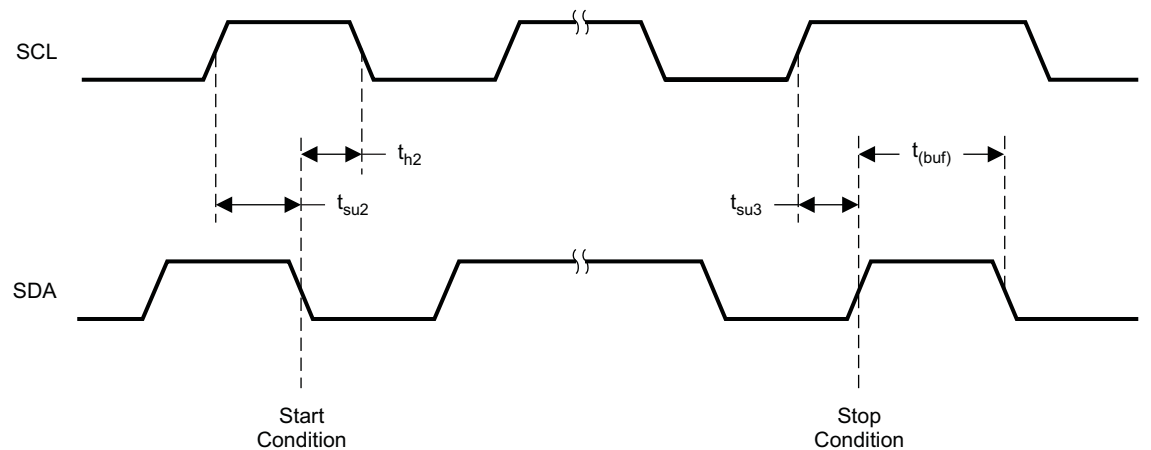
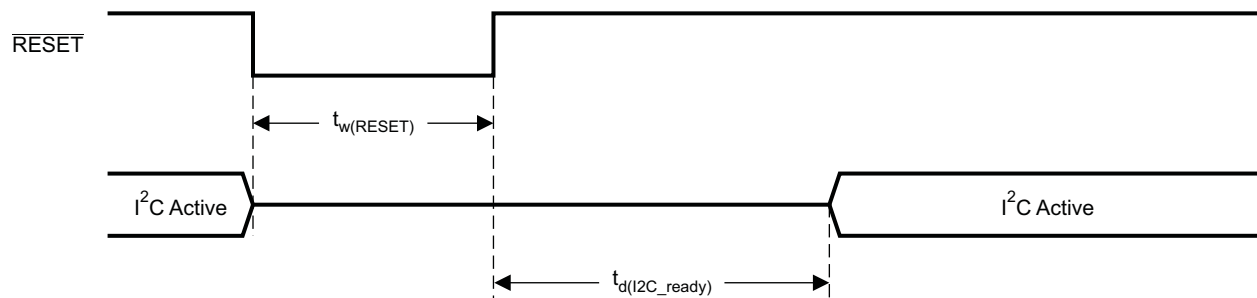


图 3. Start and Stop Conditions Timing



System Initialization.

Enable via I²C.

T0421-01

NOTES: On power up, it is recommended that the TAS5755M $\overline{\text{RESET}}$ be held LOW for at least 100 μs after DVDD has reached 3 V.

If $\overline{\text{RESET}}$ is asserted LOW while $\overline{\text{PDN}}$ is LOW, then $\overline{\text{RESET}}$ must continue to be held LOW for at least 100 μs after $\overline{\text{PDN}}$ is deasserted (HIGH).

4. Reset Timing

8.14 Typical Characteristics

8.14.1 Typical Characteristics, 2.1 SE Configuration

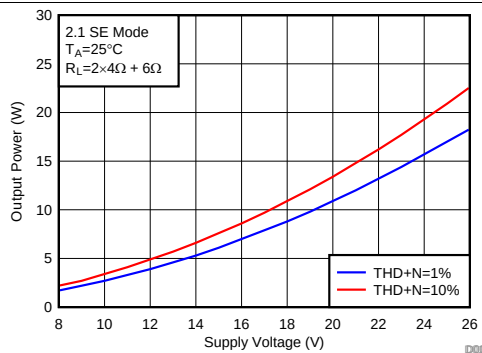


FIG 5. Output Power vs Supply Voltage

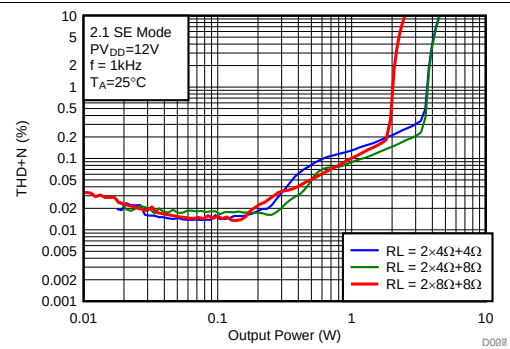


FIG 6. Total Harmonic Distortion + Noise vs Output Power

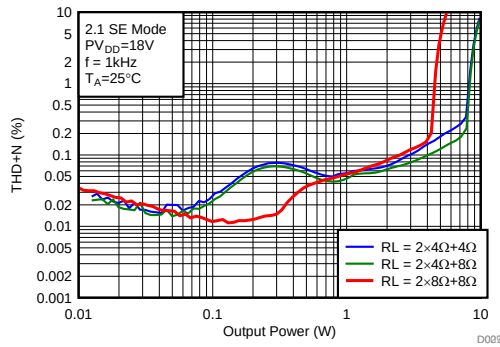


FIG 7. Total Harmonic Distortion + Noise vs Output Power

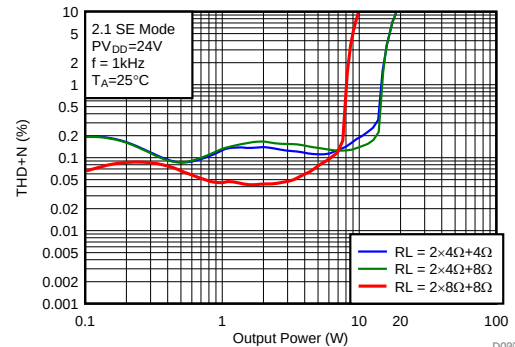


FIG 8. Total Harmonic Distortion + Noise vs Output Power

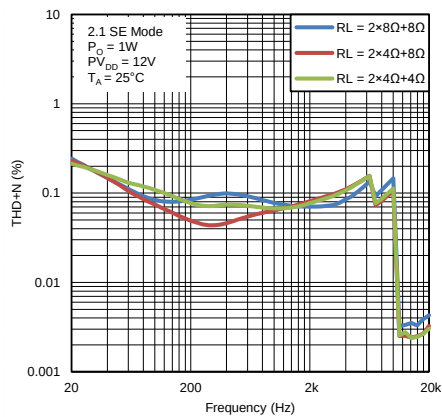


FIG 9. Total Harmonic Distortion + Noise vs Frequency

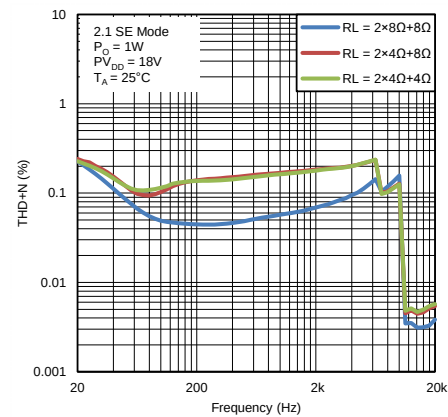
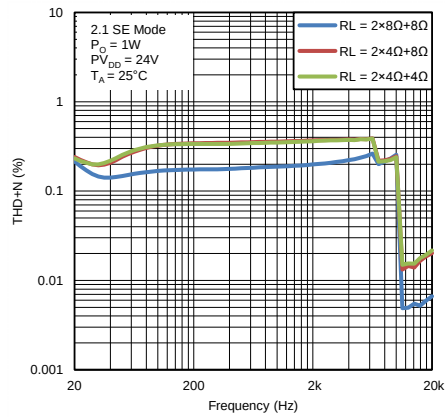
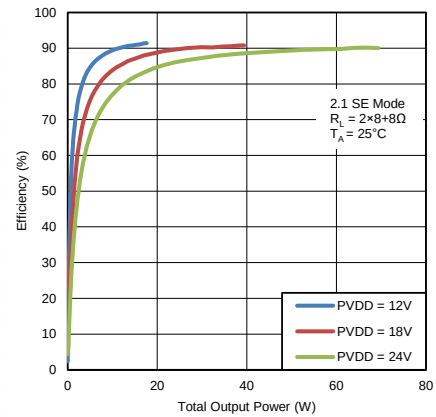


FIG 10. Total Harmonic Distortion + Noise vs Frequency

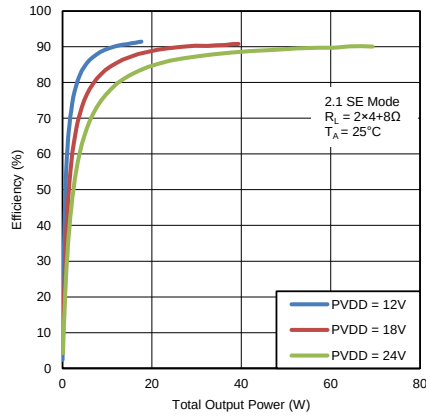
Typical Characteristics, 2.1 SE Configuration (continued)



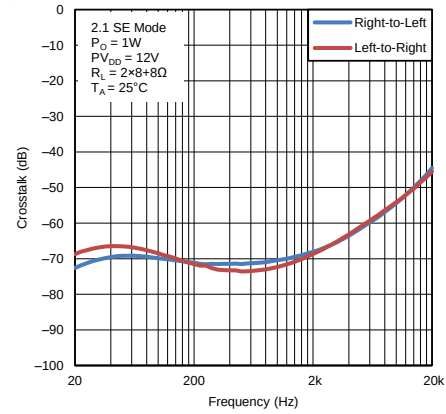
11. Total Harmonic Distortion + Noise vs Frequency



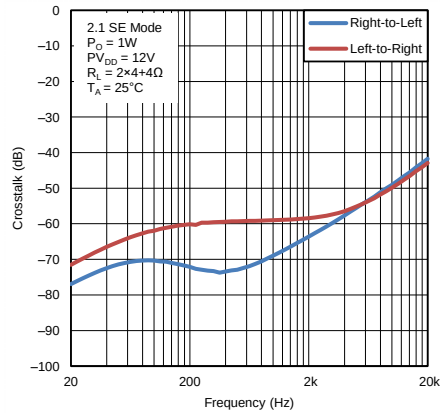
12. Efficiency vs Total Output Power



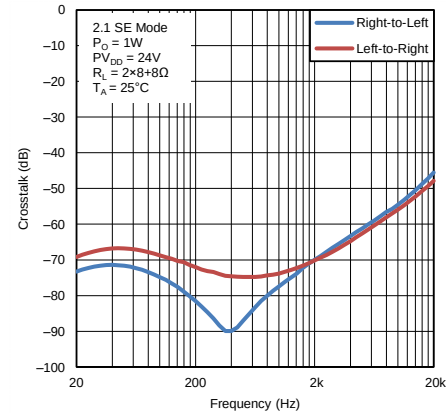
13. Efficiency vs Total Output Power



14. Crosstalk vs Frequency



15. Crosstalk vs Frequency



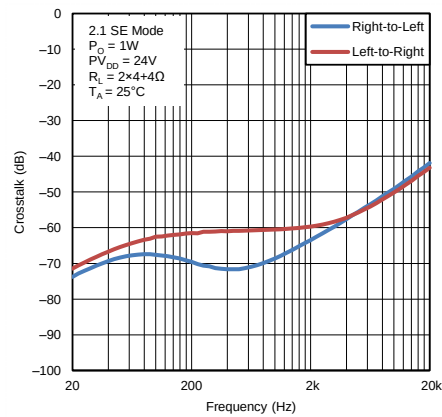
16. Crosstalk vs Frequency

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Typical Characteristics, 2.1 SE Configuration (continued)



17. Crosstalk vs Frequency

8.14.2 Typical Characteristics, 2.0 BTL Configuration

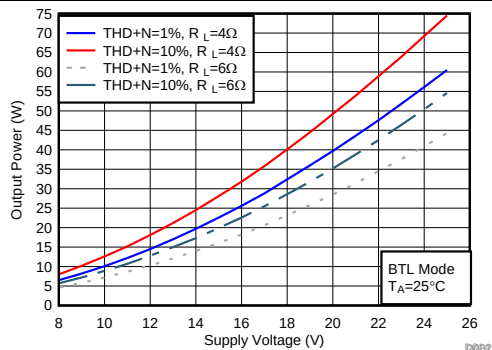


Figure 18. Output Power vs Supply Voltage

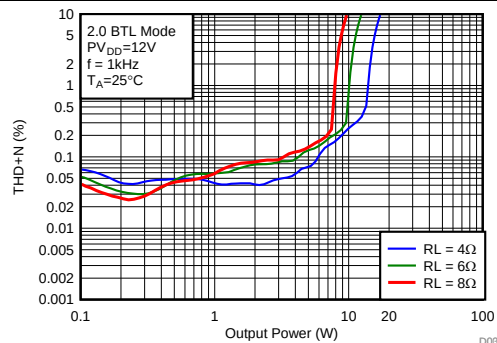


Figure 19. Total Harmonic Distortion + Noise vs Output Power

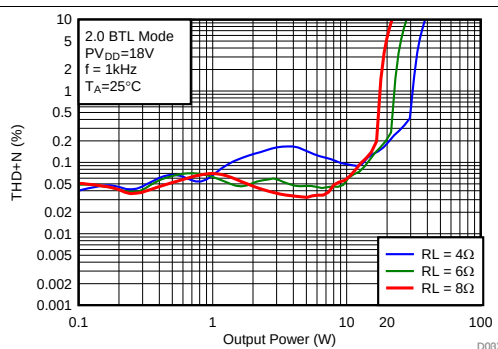


Figure 20. Total Harmonic Distortion + Noise vs Output Power

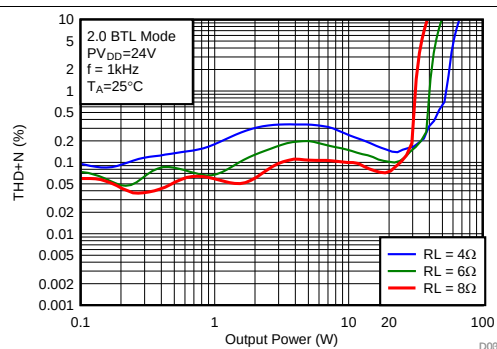


Figure 21. Total Harmonic Distortion + Noise vs Output Power

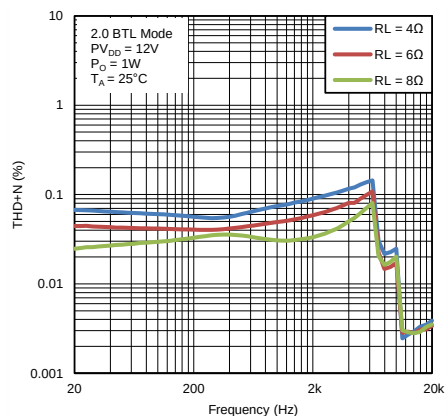


Figure 22. Total Harmonic Distortion vs Frequency

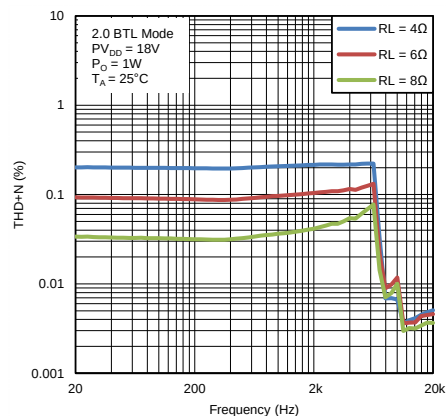


Figure 23. Total Harmonic Distortion vs Frequency

Typical Characteristics, 2.0 BTL Configuration (continued)

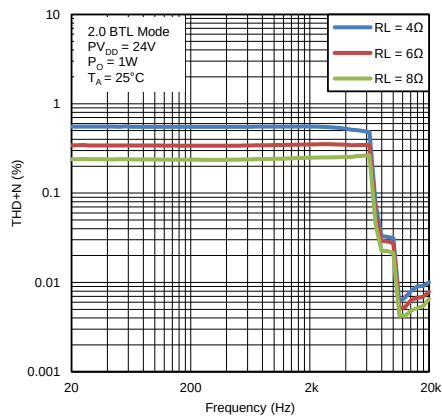


Figure 24. Total Harmonic Distortion vs Frequency

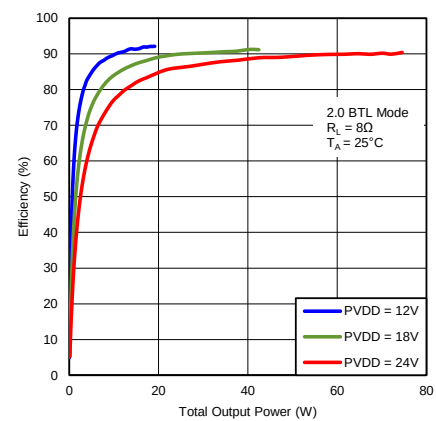


Figure 25. Efficiency vs Output Power

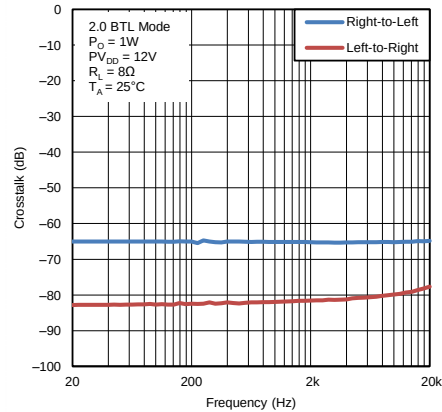


Figure 26. Crosstalk vs Frequency

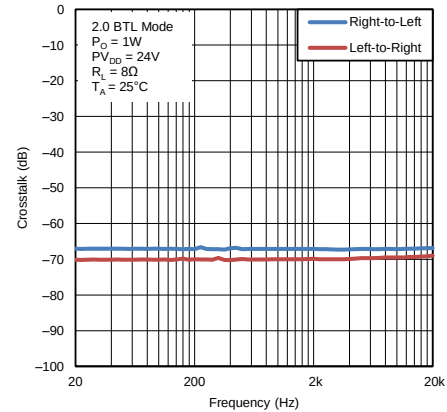


Figure 27. Crosstalk vs Frequency

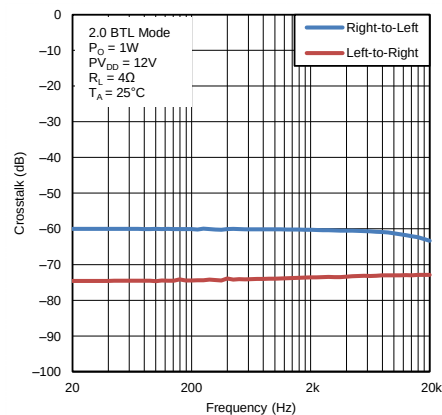


Figure 28. Crosstalk vs Frequency

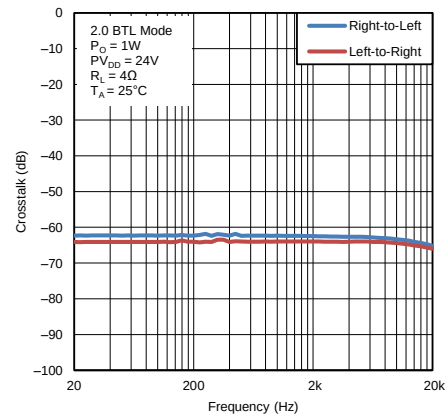


Figure 29. Crosstalk vs Frequency

Typical Characteristics, 2.0 BTL Configuration (continued)

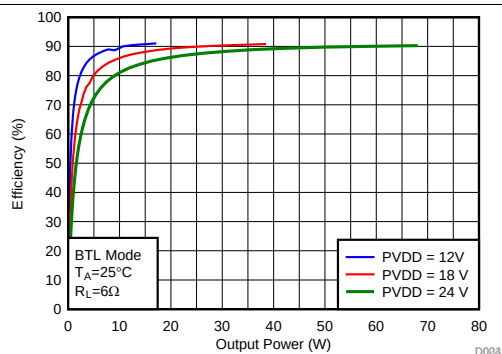


図 30. Power vs Supply Voltage

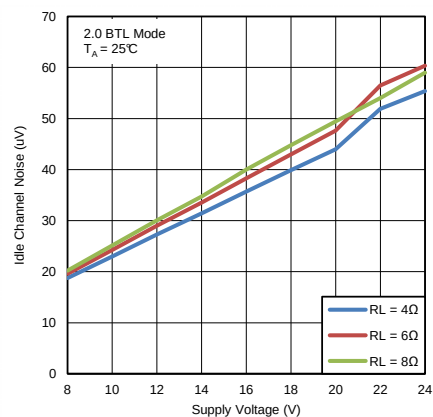


図 31. Idle Channel Noise vs Supply Voltage

8.14.3 Typical Characteristics, PBTL Configuration

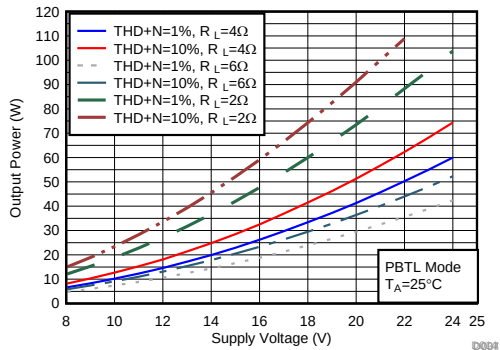


Figure 32. Output Power vs Supply Voltage

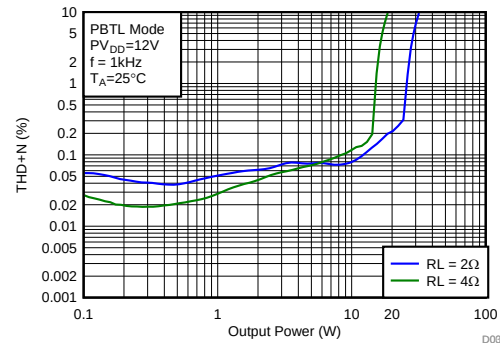


Figure 33. Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)

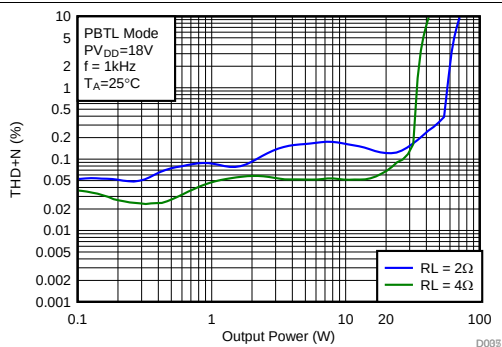


Figure 34. Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)

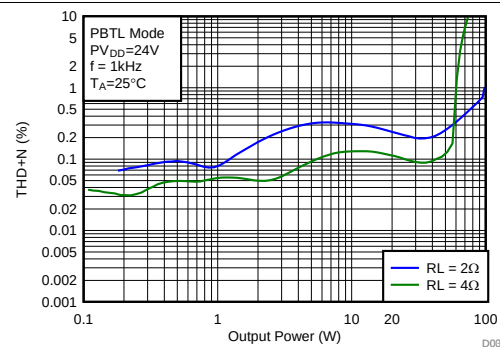


Figure 35. Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)

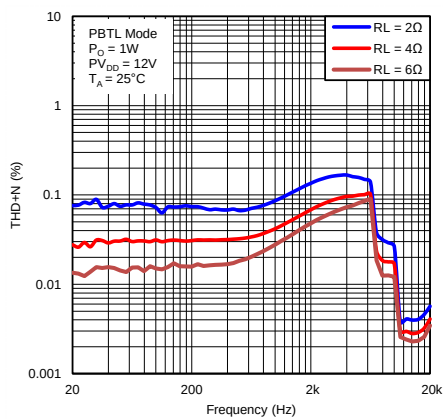


Figure 36. Total Harmonic Distortion vs Frequency (PBTL Mode)

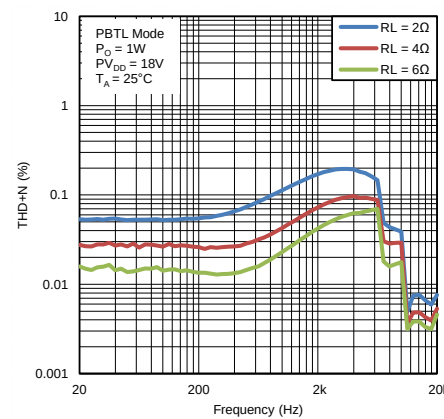


Figure 37. Total Harmonic Distortion vs Frequency (PBTL Mode)

Typical Characteristics, PBTL Configuration (continued)

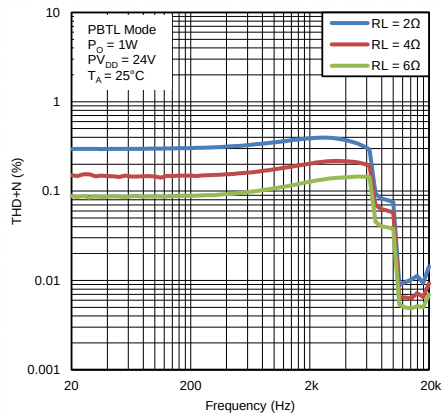


FIG 38. Total Harmonic Distortion vs Frequency (PBTL Mode)

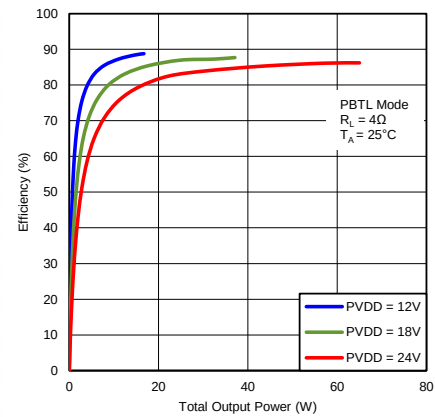


FIG 39. Efficiency vs Output Power (PBTL Mode)

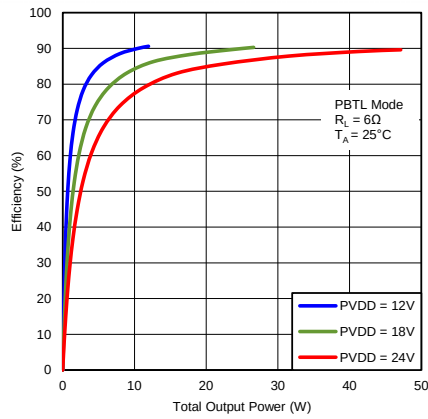


FIG 40. Efficiency vs Output Power (PBTL Mode)

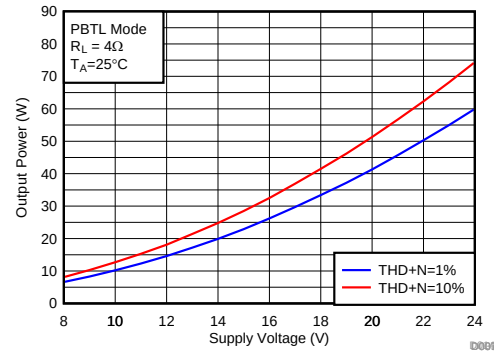


FIG 41. Power vs Supply Voltage (PBTL Mode)

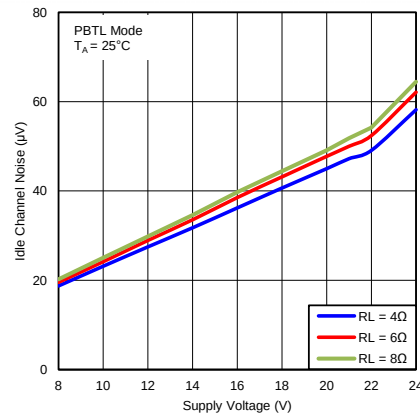


FIG 42. Idle Channel Noise vs Supply Voltage (PBTL Mode)

9 Parameter Measurement Information

All parameters are measured according to the conditions described in the [Specifications](#) section.

10 Detailed Description

10.1 Overview

The TAS5755M is an efficient 50-W stereo I²S input Class-D audio power amplifier. The digital auto processor of the device uses noise shaping and customized correction algorithms to achieve a great power efficiency and high audio performance. Also, the device has up to eight Equalizers per channel and two -band configurable Dynamic Range Control (DRC).

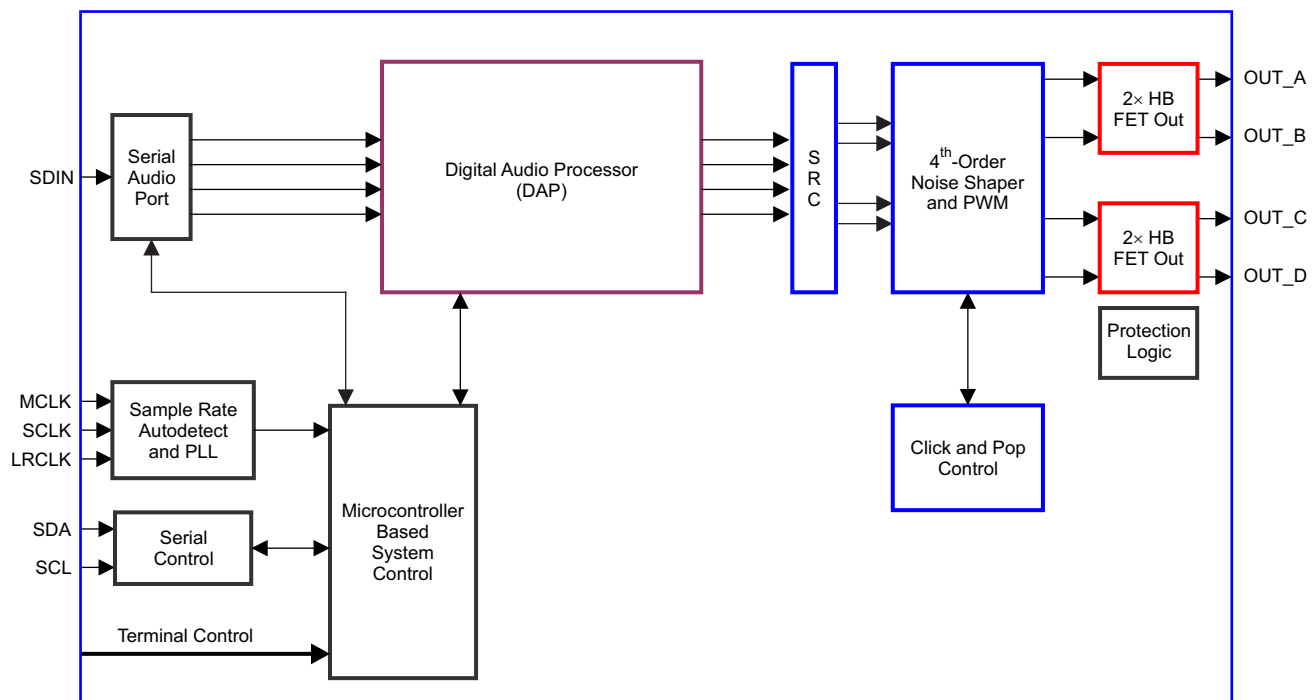
The device needs only a single DVDD supply in addition to the higher-voltage PVDD power supply. An internal voltage regulator provides suitable voltage levels for the gate drive circuit. The wide PVDD power supply range of the device enables its use in a multitude of applications.

The TAS5755M is a slave-only device that is controlled by a bidirectional I²C interface that supports both 100-kHz and 400-kHz data transfer rates for single- and multiple-byte write and read operations. This control interface is used to program the registers of the device and read the device status.

The PWM of this device operates with a carrier frequency between 384 kHz and 354 kHz, depending the sampling rate. This device allows the use of the same clock signal for both MCLK and BCLK (64xFs) when using a sampling frequency of 44.1 kHz or 48 kHz.

This device can be used in three different modes of operation, Stereo BTL mode, Single filter PBTL mono mode, and 2.1 mode.

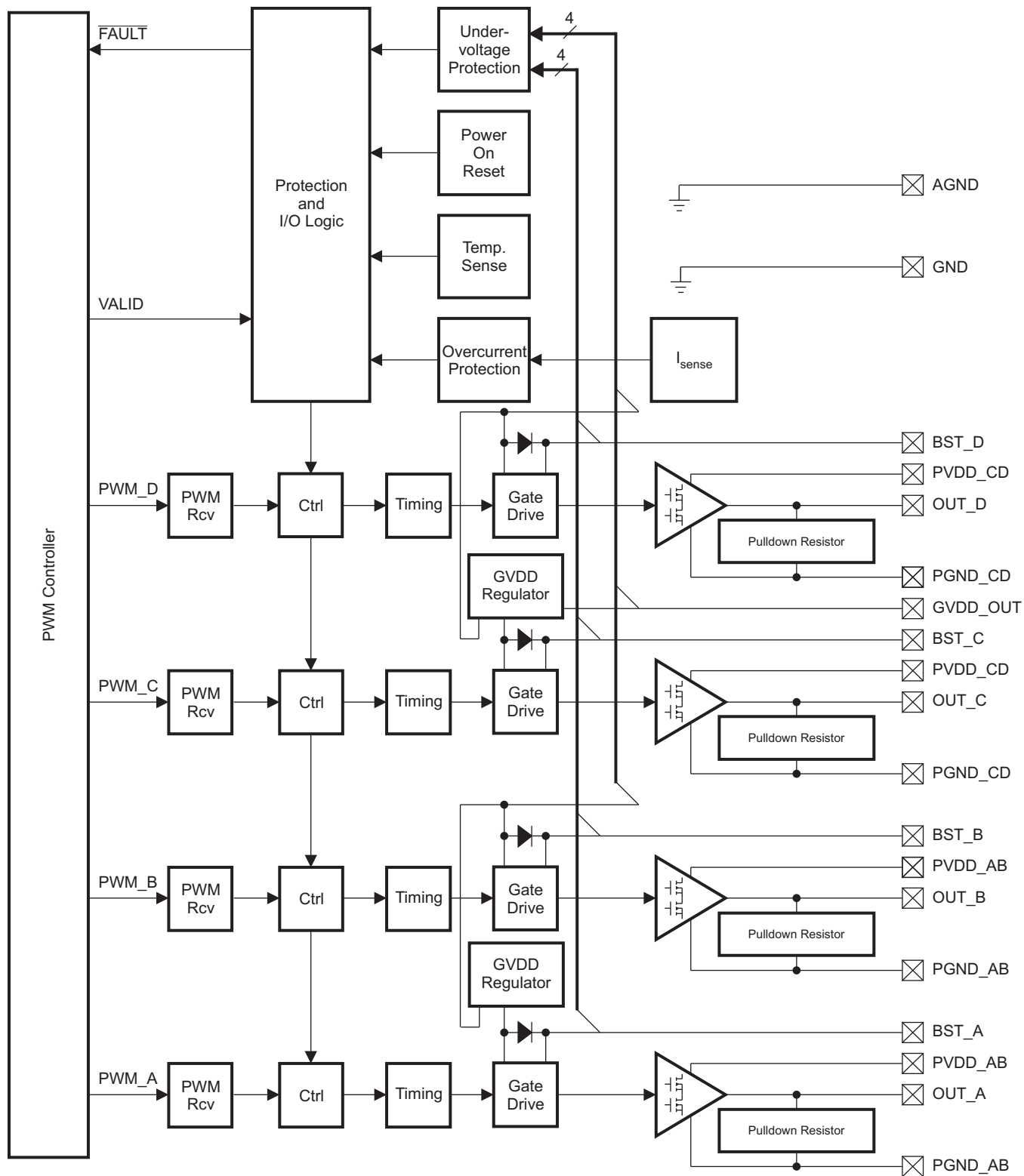
10.2 Functional Block Diagrams



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 **43. Functional Block Diagram**

Functional Block Diagrams (continued)



B0034-08

图 44. Power-Stage Functional Block Diagram

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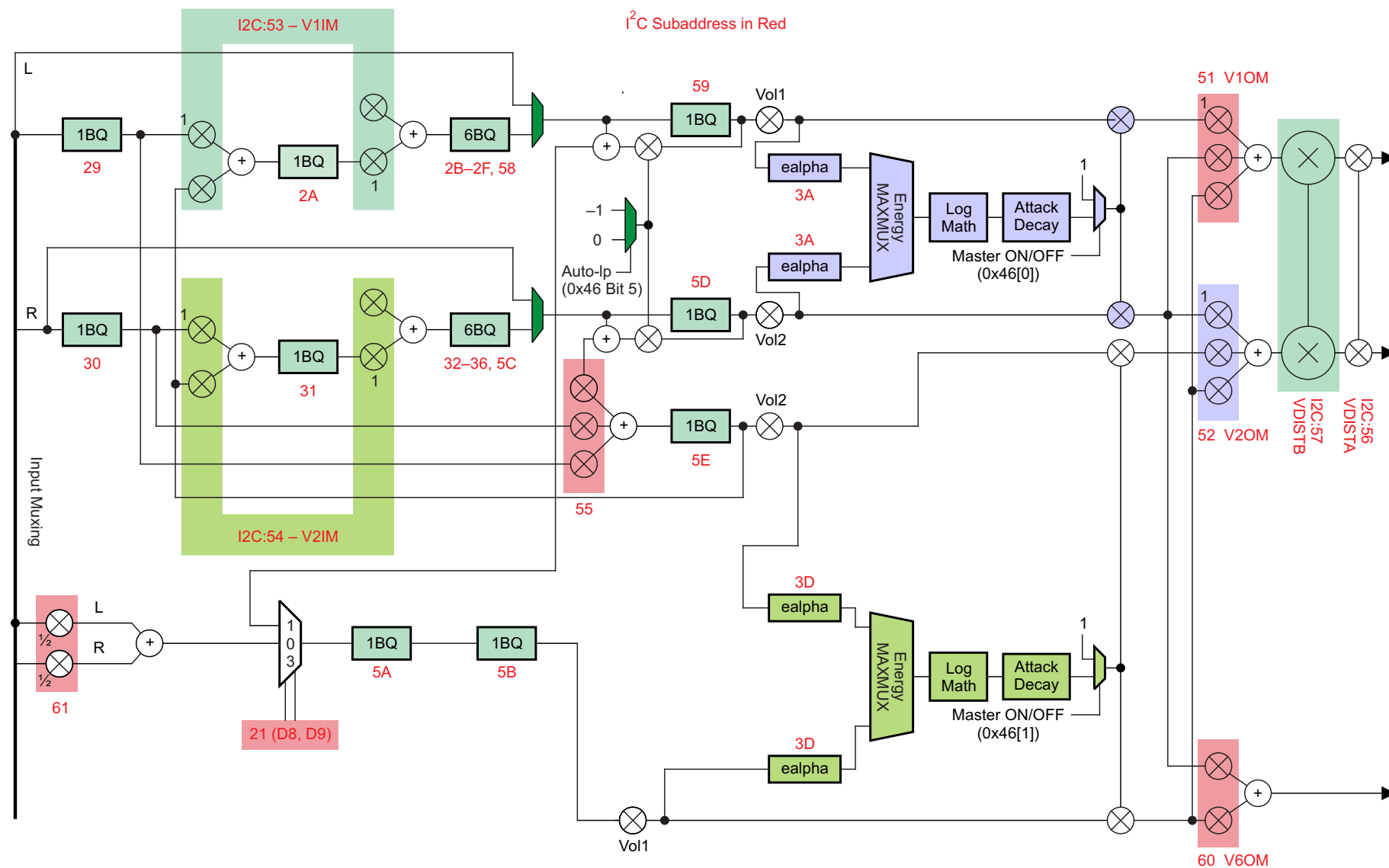


图 45. DAP Process Structure

B0321-14

10.3 Feature Description

10.3.1 Power Supply

To facilitate system design, the TAS5755M needs only a 3.3-V supply in addition to the PVDD power-stage supply. An internal voltage regulator provides suitable voltage levels for the gate drive circuitry. Additionally, all circuitry requiring a floating voltage supply, for example, the high-side gate drive, is accommodated by built-in bootstrap circuitry requiring only a few external capacitors.

In order to provide good electrical and acoustical characteristics, the PWM signal path for the output stage is designed as identical half-bridges with separate bootstrap pins (BST_x). The gate-drive voltage (GVDD_OUT) is derived from the PVDD voltage. Special attention must be paid to placing all decoupling capacitors as close to their associated pins as possible. Inductance between the power-supply pins and decoupling capacitors must be avoided.

For a properly functioning bootstrap circuit, a small ceramic capacitor must be connected from each bootstrap pin (BST_x) to the power-stage output pin (OUT_x). When the power-stage output is low, the bootstrap capacitor is charged through an internal diode connected between the gate-drive regulator output pin (GVDD_OUT) and the bootstrap pin. When the power-stage output is high, the bootstrap capacitor potential is shifted above the output potential and thus provides a suitable voltage supply for the high-side gate driver. In an application with PWM switching frequencies in the range from 288 kHz to 384 kHz, it is recommended to use 10-nF, X7R ceramic capacitors, size 0603 or 0805, for the bootstrap supply. These 10-nF capacitors ensure sufficient energy storage, even during minimal PWM duty cycles, to keep the high-side power-stage FET (LDMOS) fully turned on during the remaining part of the PWM cycle.

Special attention must be paid to the power-stage power supply; this includes component selection, PCB placement, and routing. As indicated, each half-bridge has independent power-stage supply pins (PVDD_x). For optimal electrical performance, EMI compliance, and system reliability, it is important that each PVDD_x pin is decoupled with a 100-nF, X7R ceramic capacitor placed as close as possible to each supply pin.

The TAS5755M is fully protected against erroneous power-stage turnon due to parasitic gate charging.

10.3.2 I²C Address Selection and Fault Output

ADR/FAULT is an input pin during power up. It can be pulled HIGH or LOW through a resistor as shown in the [Typical Applications](#) sections in order to set the I²C address. Pulling this pin HIGH through the resistor results in setting the I²C 7-bit address to 0011011 (0x36), and pulling it LOW through the resistor results in setting the address to 0011010 (0x34).

During power up, the address of the device is latched in, freeing up the ADR/FAULT pin to be used as a fault notification output. When configured as a fault output, the pin will go low when a fault occurs and will return to its default state when register 0x02 is cleared. The behavior of the pin in response to a fault condition is to be pulled low immediately upon an error. The device then waits for a period of time determined by BKND_ERR Register (0x1C) before attempting to resume playback. If the error has been cleared when the device attempts to resume playback, playback will resume, the ADR/FAULT pin will remain high, and normal operation will resume. If the error has not been removed, then the device will immediately re-enter the protected state and wait again for the predetermined period of time to pass. The device will pull the fault pin low for over-current, over-temperature, and under-voltage lock-out.

10.3.3 Single-Filter PBTL Mode

The TAS5755M supports parallel BTL (PBTL) mode with OUT_A/OUT_B (and OUT_C/OUT_D) connected before the LC filter. In addition to connecting OUT_A/OUT_B and OUT_C/OUT_D, BST_A/BST_B and BST_C/BST_D must also be connected before the LC filter, as shown in the [Figure 71](#). In order to put the part in PBTL configuration, drive PBTL (pin 8) HIGH. This synchronizes the turnoff of half-bridges A and B (and similarly C/D) if an overcurrent condition is detected in either half-bridge. There is a pulldown resistor on the PBTL pin that configures the part in BTL mode if the pin is left floating.

PWM output multiplexers register (0x25) and PWM Shutdown Group Register (0x19) must be updated to set the device in PBTL mode. Must follow one of below listed configurations for PBTL mode.

- Register (0x25) be written with a value of 0x0110 3245, Register (0x19) be written with a value of 0x35
- Register (0x25) be written with a value of 0x0101 2345, Register (0x19) be written with a value of 0x3A

Feature Description (continued)

10.3.4 Device Protection System

10.3.4.1 Overcurrent (OC) Protection With Current Limiting

The device has independent, fast-reacting current detectors on all high-side and low-side power-stage FETs. The detector outputs are closely monitored by a protection system. If the high-current condition situation persists, that is, the power stage is being overloaded, a protection system triggers a latching shutdown, resulting in the power stage being set in the high-impedance (Hi-Z) state. The device returns to normal operation once the fault condition (that is, a short circuit on the output) is removed. Current-limiting and overcurrent protection are not independent for half-bridges. That is, if the bridge-tied load between half-bridges A and B causes an overcurrent fault, half-bridges A, B, C, and D are shut down.

10.3.4.2 Overtemperature Protection

The TAS5755M has an overtemperature-protection system. If the device junction temperature exceeds 150°C (nominal), the device is put into thermal shutdown, resulting in all half-bridge outputs being set in the high-impedance (Hi-Z) state. The TAS5755M recovers automatically once the temperature drops approximately 30°C.

10.3.4.3 Undervoltage Protection (UVP) and Power-On Reset (POR)

The UVP and POR circuits of the TAS5755M fully protect the device in any power-up/down and brownout situation. While powering up, the POR circuit resets the overload circuit (OLP) and ensures that all circuits are fully operational when the PVDD and AVDD supply voltages reach 7.6 V and 2.7 V, respectively. Although PVDD and AVDD are independently monitored, a supply-voltage drop below the UVP threshold on AVDD or either PVDD pin results in all half-bridge outputs immediately being set in the high-impedance (Hi-Z) state.

10.3.5 SSTIMER Functionality

The SSTIMER pin uses a capacitor connected between this pin and ground to control the output duty cycle when exiting all-channel shutdown. The capacitor on the SSTIMER pin is slowly charged through an internal current source, and the charge time determines the rate at which the output transitions from a near-zero duty cycle to the desired duty cycle. This allows for a smooth transition that minimizes audible pops and clicks. When the part is shut down, the drivers are placed in the high-impedance state and transition slowly down through a 3-kΩ resistor, similarly minimizing pops and clicks. The shutdown transition time is independent of the SSTIMER pin capacitance. Larger capacitors increase the start-up time, while capacitors smaller than 2.2 nF decrease the start-up time. The SSTIMER pin can be left floating for BD modulation.

10.3.6 Clock, Autodetection, and PLL

The TAS5755M is an I²S slave device. It accepts MCLK, SCLK, and LRCLK. The digital audio processor (DAP) supports all the sample rates and MCLK rates that are defined in the [Clock Control Register \(0x00\)](#).

The TAS5755M checks to verify that SCLK is a specific value of 32 f_S, 48 f_S, or 64 f_S. The DAP only supports a 1 × f_S LRCLK. The timing relationship of these clocks to SDIN is shown in subsequent sections. The clock section uses MCLK or the internal oscillator clock (when MCLK is unstable, out of range, or absent) to produce the internal clock (DCLK) running at 512 times the PWM switching frequency.

The DAP can autodetect and set the internal clock control logic to the appropriate settings for all supported clock rates as defined in the clock-control register.

The TAS5755M has robust clock error handling that uses the built-in trimmed oscillator clock to quickly detect changes/errors. Once the system detects a clock change/error, it mutes the audio (through a single-step mute) and then forces PLL to limp using the internal oscillator as a reference clock. Once the clocks are stable, the system autodetects the new rate and reverts to normal operation. During this process, the default volume is restored in a single step (also called hard unmute). The ramp process can be programmed to ramp back slowly (also called soft unmute) as defined in volume register (0x0E).

Feature Description (continued)

10.3.7 PWM Section

The TAS5755M DAP device uses noise-shaping and customized nonlinear correction algorithms to achieve high power efficiency and high-performance digital audio reproduction. The DAP uses a fourth-order noise shaper to increase dynamic range and SNR in the audio band. The PWM section accepts 24-bit PCM data from the DAP and outputs two BTL PWM audio output channels.

The PWM section has individual-channel dc-blocking filters that can be enabled and disabled. The filter cutoff frequency is less than 1 Hz. Individual-channel de-emphasis filters for 44.1 kHz and 48 kHz are included and can be enabled and disabled.

Finally, the PWM section has an adjustable maximum modulation limit of 93.8% to 99.2%.

For a detailed description of using audio processing features like DRC and EQ, see the *TAS5755EVM User's Guide* ([SLOU481](#)) and *TAS570X GDE Software Setup* development tool documentation ([SLOC124](#)).

10.3.8 2.1-Mode Support

The TAS5755M uses a special mid-Z ramp sequence to reduce click and pop in SE-mode and 2.1-mode operation. To enable the mid-Z ramp, register 0x05 bit D7 must be set to 1. To enable 2.1 mode, register 0x05 bit D2 must be set to 1. The SSTIMER pin must be left floating in this mode.

10.3.9 I²C Compatible Serial Control Interface

The TAS5755M DAP has an I²C serial control slave interface to receive commands from a system controller. The serial control interface supports both normal-speed (100 kHz) and high-speed (400 kHz) operations without wait states. As an added feature, this interface operates even if MCLK is absent. The serial control interface supports both single-byte and multiple-byte read and write operations for status registers and the general control registers associated with the PWM.

10.3.10 Audio Serial Interface

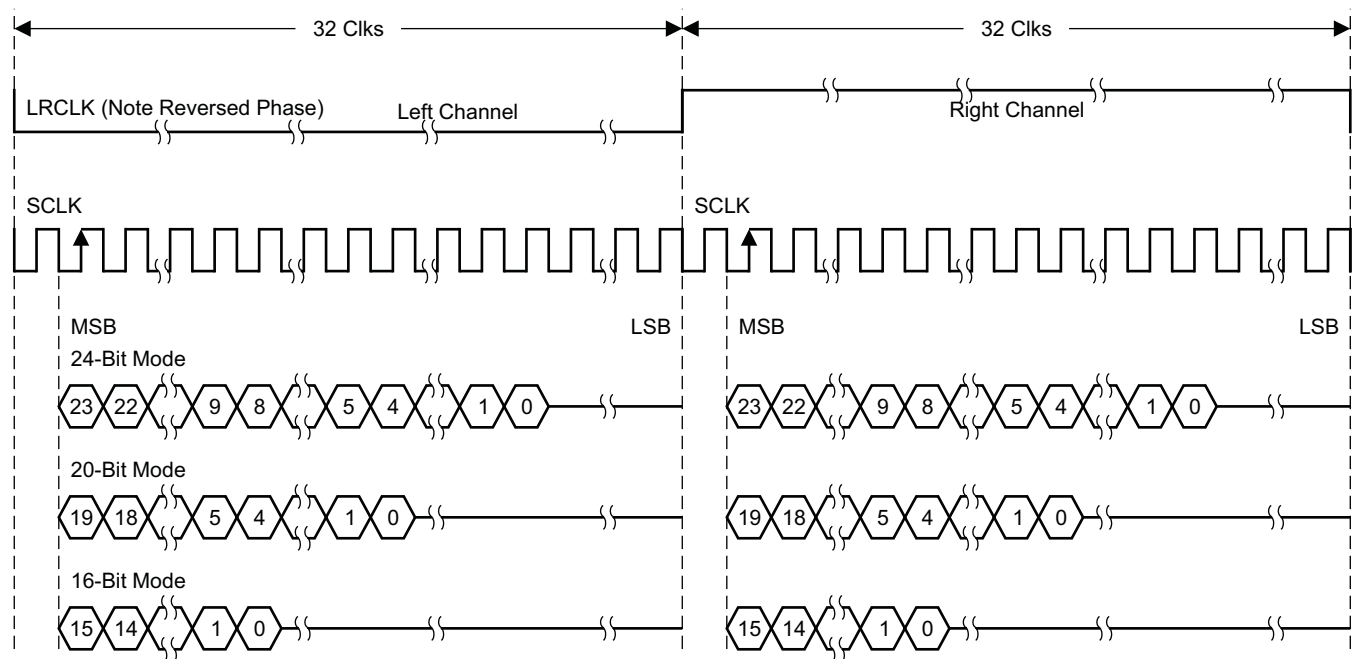
Serial data is input on SDIN. The PWM outputs are derived from SDIN. The TAS5755M DAP accepts serial data in 16-, 20-, or 24-bit left-justified, right-justified, and I²S serial data formats.

10.3.10.1 I²S Timing

I²S timing uses LRCLK to define when the data being transmitted is for the left channel and when it is for the right channel. LRCLK is low for the left channel and high for the right channel. A bit clock running at $32, 48, \text{ or } 64 \times f_s$ is used to clock in the data. There is a delay of one bit clock from the time the LRCLK signal changes state to the first bit of data on the data lines. The data is written MSB-first and is valid on the rising edge of bit clock. The DAP masks unused trailing data bit positions.

Feature Description (continued)

2-Channel I²S (Philips Format) Stereo Input



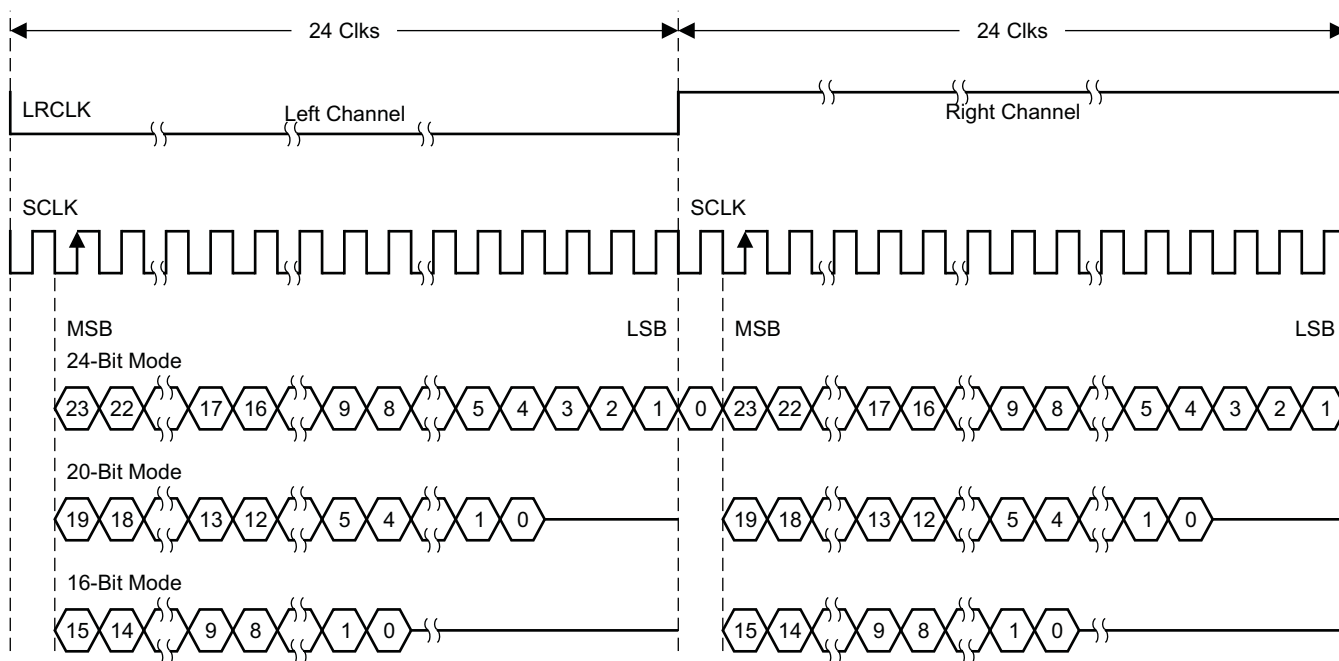
T0034-01

NOTE: All data presented in 2s-complement form with MSB first.

图 46. I²S 64-F_s Format

Feature Description (continued)

2-Channel I²S (Philips Format) Stereo Input/Output (24-Bit Transfer Word Size)

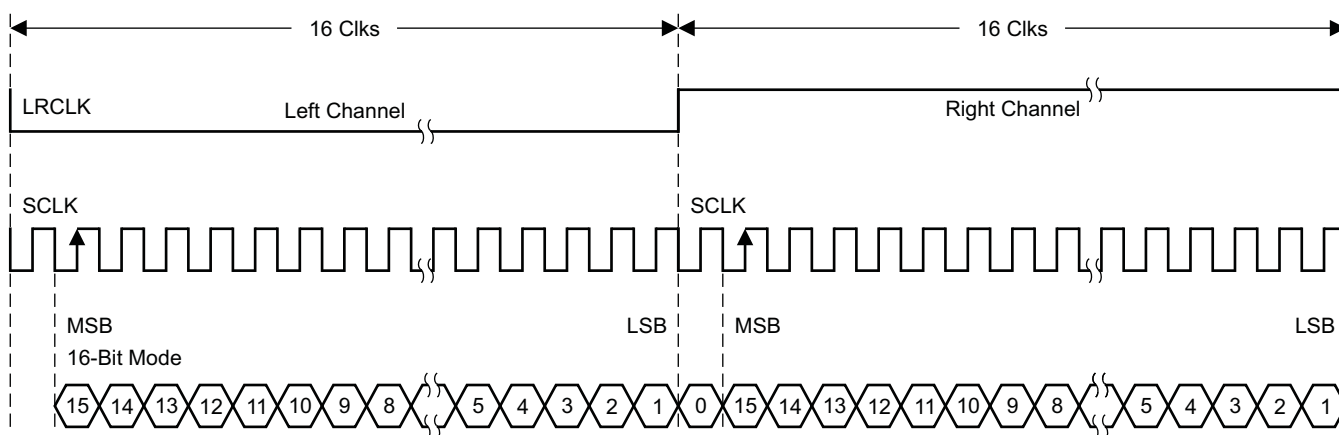


T0092-01

NOTE: All data presented in 2s-complement form with MSB first.

图 47. I²S 48-F_s Format

2-Channel I²S (Philips Format) Stereo Input



T0266-01

NOTE: All data presented in 2s-complement form with MSB first.

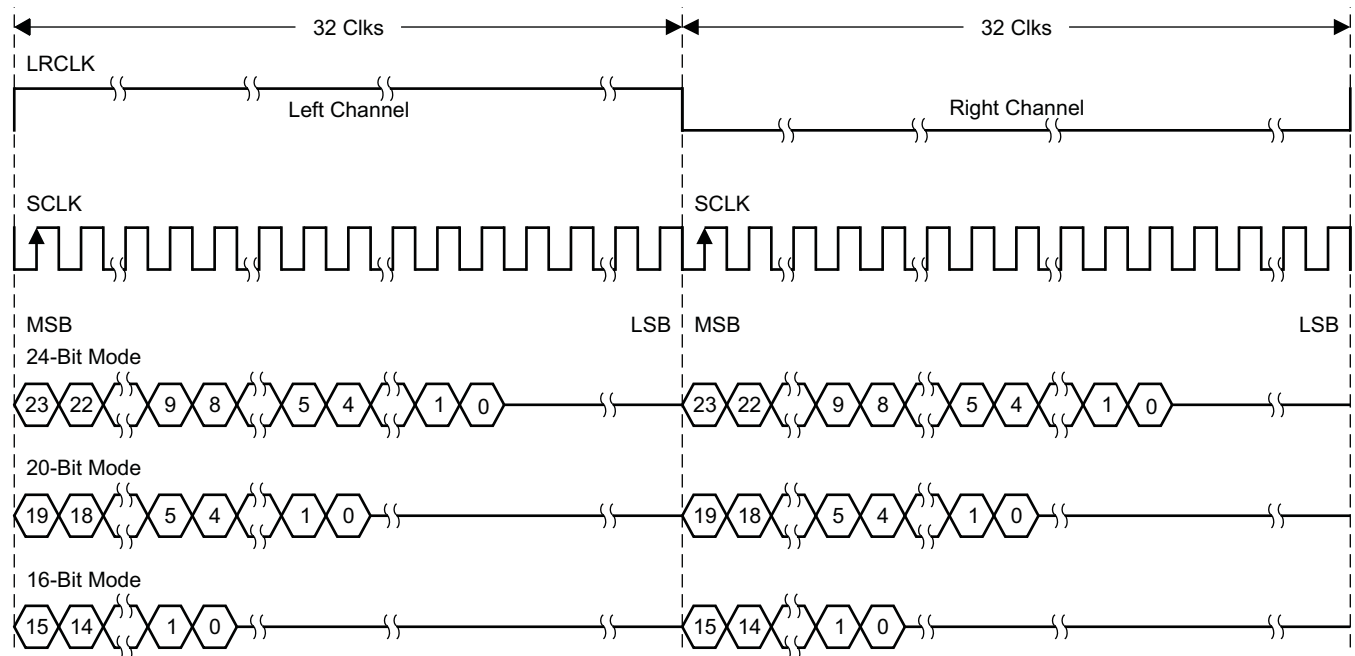
图 48. I²S 32-F_s Format

Feature Description (continued)

10.3.10.2 Left-Justified

Left-justified (LJ) timing uses LRCLK to define when the data being transmitted is for the left channel and when it is for the right channel. LRCLK is high for the left channel and low for the right channel. A bit clock running at 32 , 48 , or $64 \times f_s$ is used to clock in the data. The first bit of data appears on the data lines at the same time LRCLK toggles. The data is written MSB-first and is valid on the rising edge of the bit clock. The DAP masks unused trailing data bit positions.

2-Channel Left-Justified Stereo Input



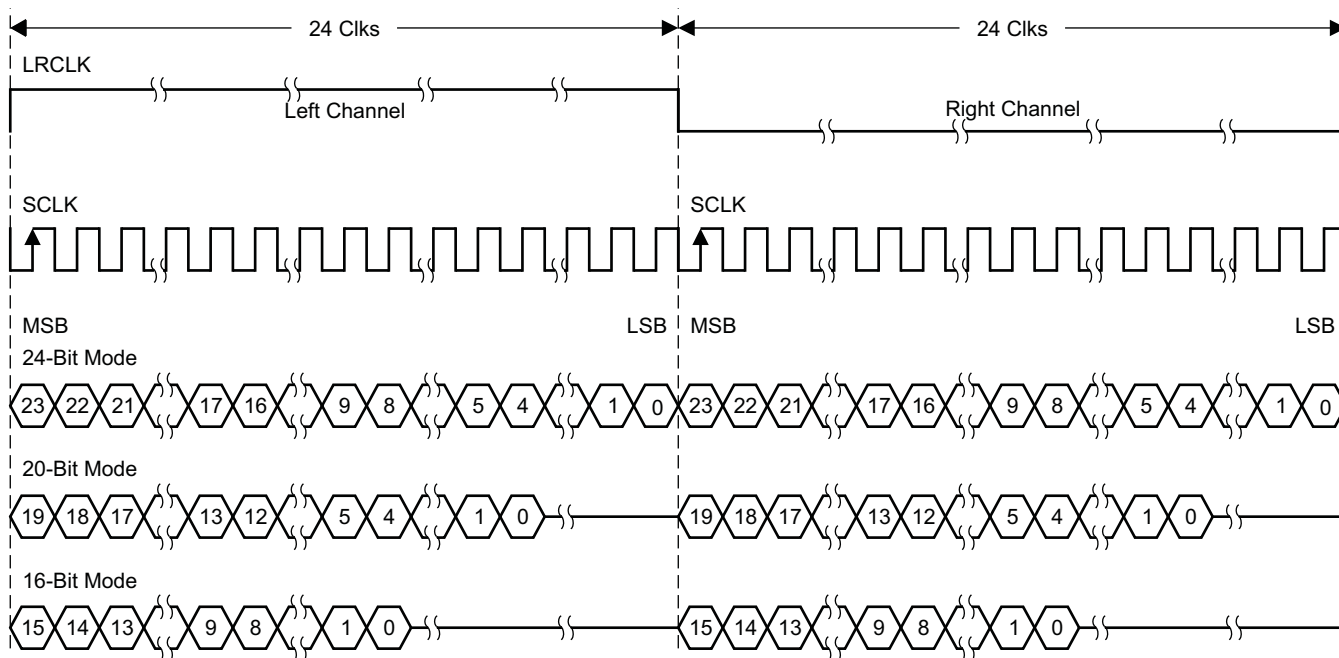
T0034-02

NOTE: All data presented in 2s-complement form with MSB first.

图 49. Left-Justified 64- F_s Format

Feature Description (continued)

2-Channel Left-Justified Stereo Input (24-Bit Transfer Word Size)

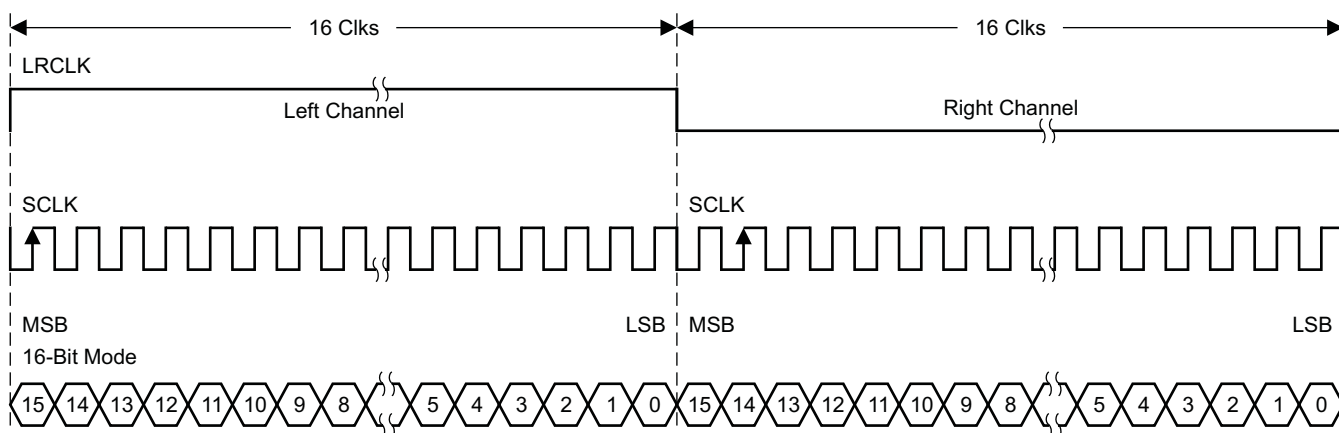


T0092-02

NOTE: All data presented in 2s-complement form with MSB first.

图 50. Left-Justified 48-F_s Format

2-Channel Left-Justified Stereo Input



T0266-02

NOTE: All data presented in 2s-complement form with MSB first.

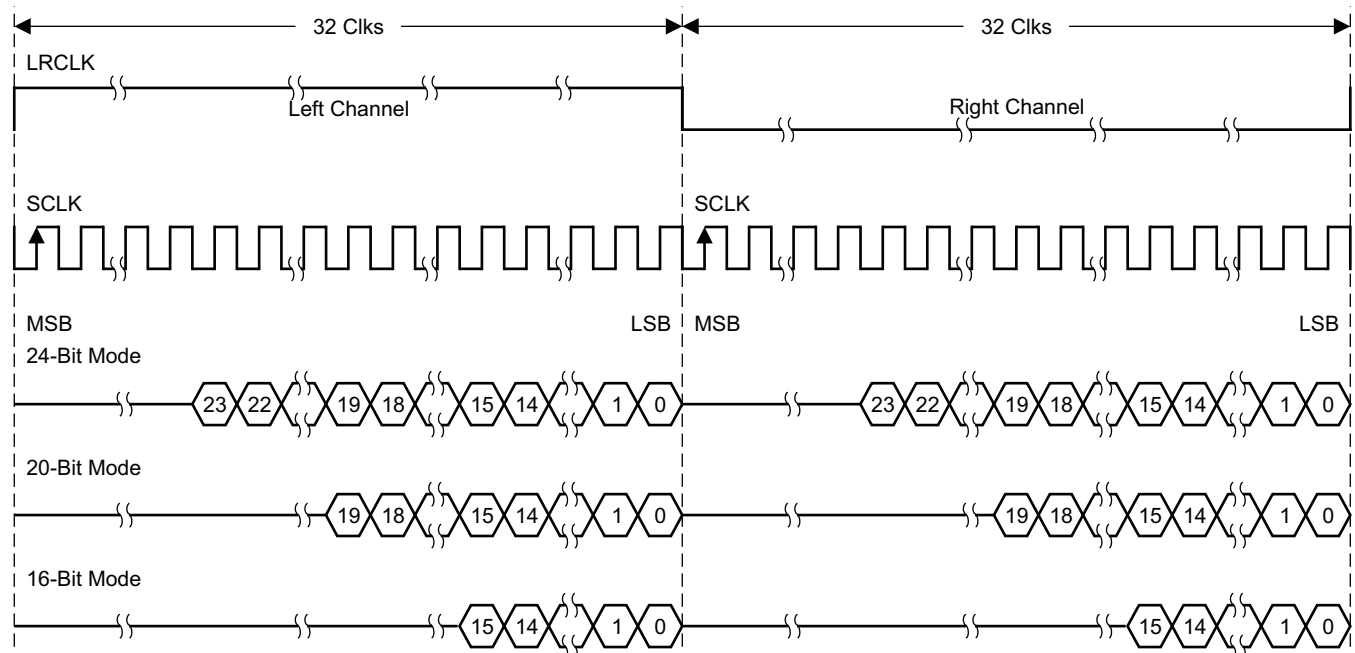
图 51. Left-Justified 32-F_s Format

Feature Description (continued)

10.3.10.3 Right-Justified

Right-justified (RJ) timing uses LRCLK to define when the data being transmitted is for the left channel and when it is for the right channel. LRCLK is high for the left channel and low for the right channel. A bit clock running at $32, 48, \text{ or } 64 \times f_s$ is used to clock in the data. The first bit of data appears on the data 8 bit-clock periods (for 24-bit data) after LRCLK toggles. In RJ mode, the LSB of data is always clocked by the last bit clock before LRCLK transitions. The data is written MSB-first and is valid on the rising edge of bit clock. The DAP masks unused leading data bit positions.

2-Channel Right-Justified (Sony Format) Stereo Input

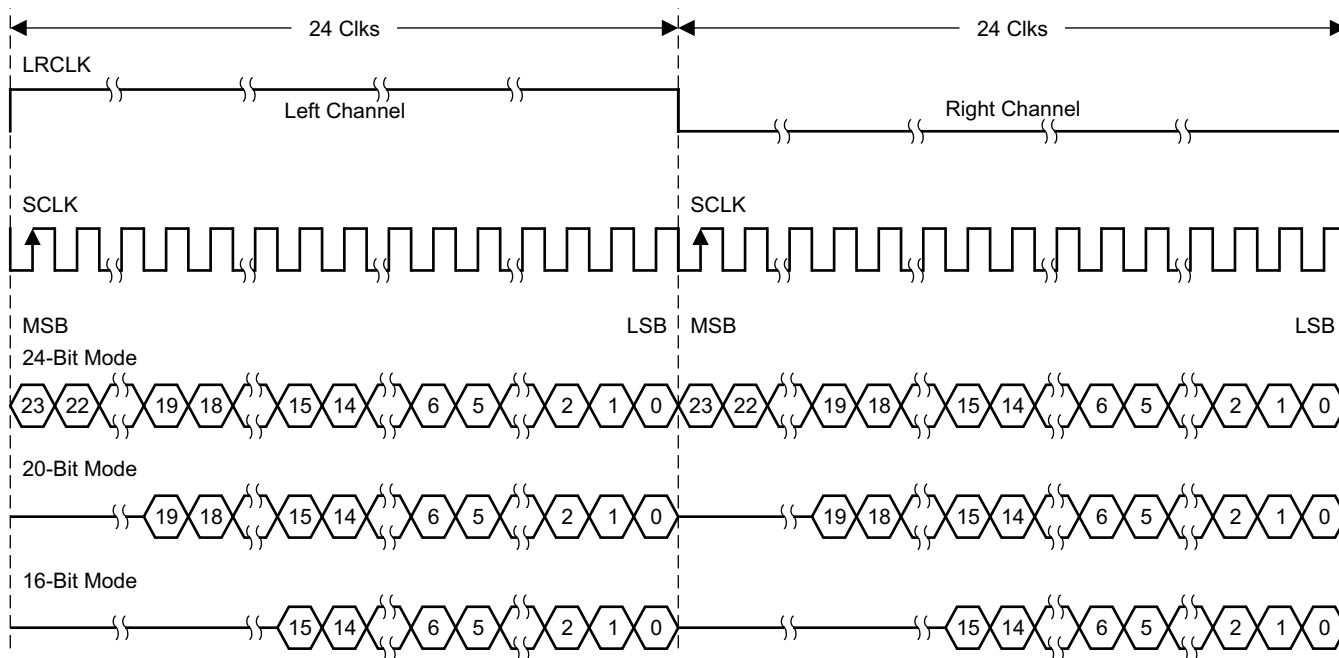


T0034-03

✎ 52. Right-Justified 64- F_s Format

Feature Description (continued)

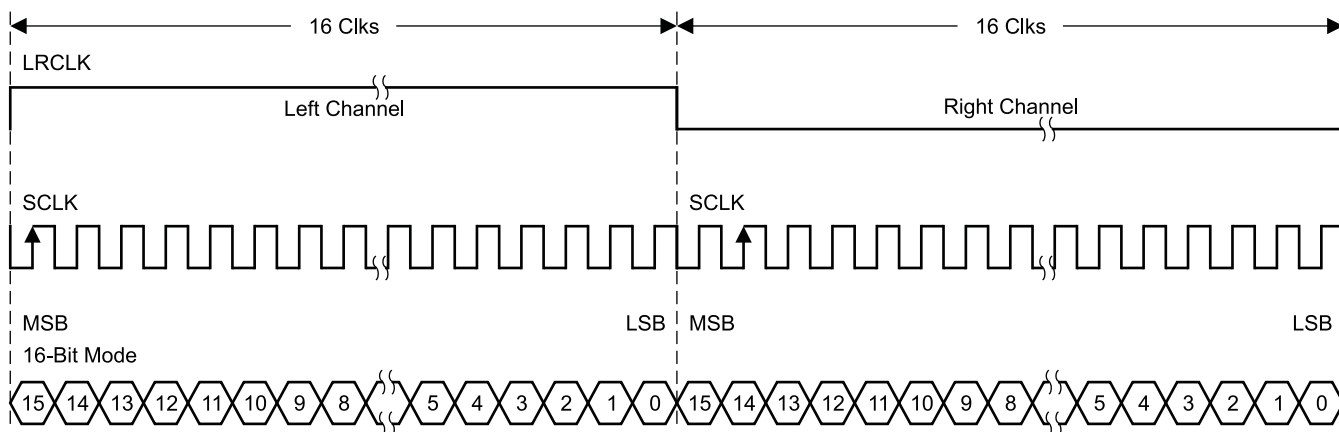
2-Channel Right-Justified Stereo Input (24-Bit Transfer Word Size)



T0092-03

FIG 53. Right-Justified 48-F_S Format

2-Channel Right-Justified (Sony Format) Stereo Input



T0266-03

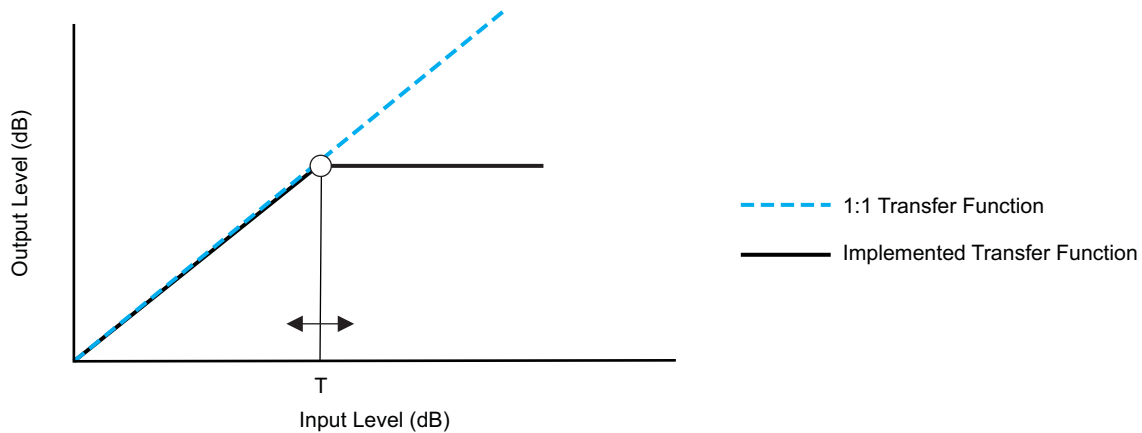
FIG 54. Right-Justified 32-F_S Format

Feature Description (continued)

10.3.11 Dynamic Range Control (DRC)

The DRC scheme has two DRC blocks. There is one ganged DRC for the high-band left/right channels and one DRC for the low-band left/right channels.

The DRC input/output diagram is shown in [Figure 55](#).



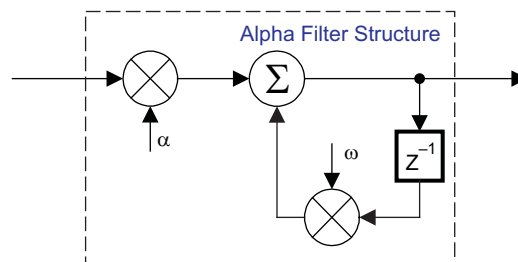
M0091-04

Professional-quality dynamic range compression automatically adjusts volume to flatten volume level.

- Each DRC has adjustable threshold levels.
- Programmable attack and decay time constants
- *Transparent compression*: compressors can attack fast enough to avoid apparent clipping before engaging, and decay times can be set slow enough to avoid pumping.

Figure 55. Dynamic Range Control

	α, ω	T	$\alpha_a, \omega_a / \alpha_d, \omega_d$
DRC1	0x3C	0x3B	0x40
DRC2	0x3F	0x3E	0x43



B0265-04

T = 9.23 format, all other DRC coefficients are 3.23 format

Figure 56. DRC Structure

10.4 Device Functional Modes

10.4.1 Stereo BTL Mode

The classic stereo mode of operation uses the TAS5755M device to amplify two independent signals, which represent the left and right portions of a stereo signal. These amplified left and right audio signals are presented on differential output pairs shown as OUT_A and OUT_B for a channel and OUT_C and OUT_D for the other one. The routing of the audio data which is presented on the OUT_x outputs can be changed according to the PWM Output Mux Register (0x25). By default, the TAS5755M device is configured to output channel 1 to the OUT_A and OUT_B outputs, and channel 2 to the OUT_C and OUT_D outputs. Stereo Mode operation outputs are shown in [Figure 57](#).

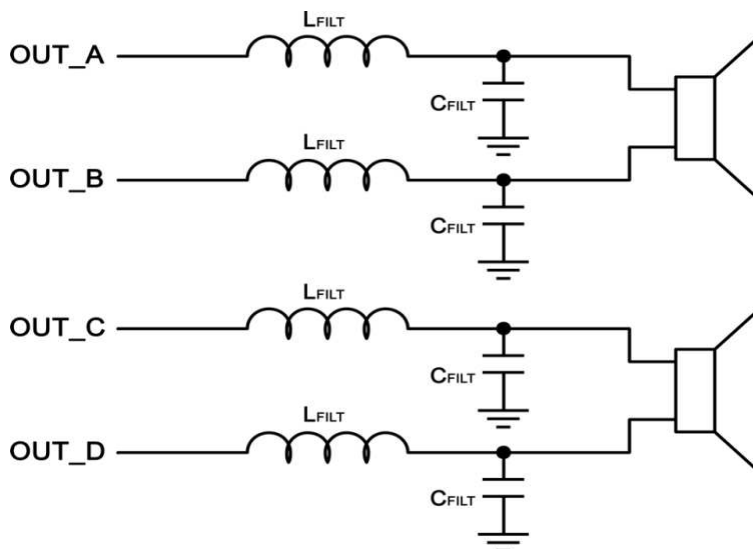


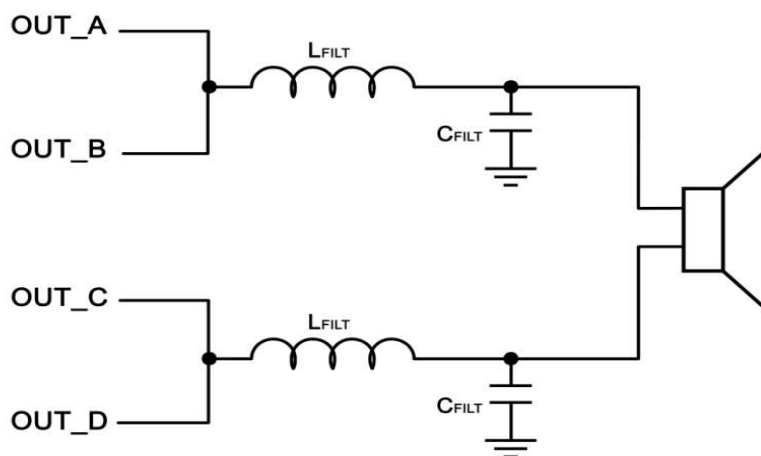
Figure 57. Stereo BTL Mode

10.4.2 Mono PBTL Mode

When this mode of operation is used, the two stereo outputs of the device are placed in parallel one with another to increase the power sourcing capabilities of the device. The TAS5755M supports parallel BTL (PBTL) mode with OUT_A/OUT_B (and OUT_C/OUT_D) connected before the LC filter.

The merging of the two output channels in this device can be done before the inductor portion of the output filter. This is called Single-Filter PBTL, and this mono operation is shown in [Figure 58](#). More information about this can be found in [Single-Filter PBTL Mode](#) section.

Device Functional Modes (continued)



✎ 58. Pre-Filter PBTL

On the input side of the TAS5755M device, the input signal to the mono amplifier can be selected from a mix, left or right frame from an I²S, LJ, or RJ signal. The routing of the audio data which is presented on the SPK_OUTx outputs must be configured with the PWM Output Mux Register (0x25) and PWM Shutdown Group Register (0x19).

Refer to the [Mono Parallel Bridge Tied Load Application](#) section for more details of the correct PBTL output connection of the TAS5755M.

10.4.3 2.1 Mode

2.1 Mode is defined as the application of two Single ended channels and one BTL channel used in systems where a third sub channel is required. Generally, both single-ended inputs drive the Left and Right channels, while the BTL channel drives a low-frequency content channel called often Subwoofer. More information about this can be found in the [2.1-Mode Support](#) section.

Device Functional Modes (continued)

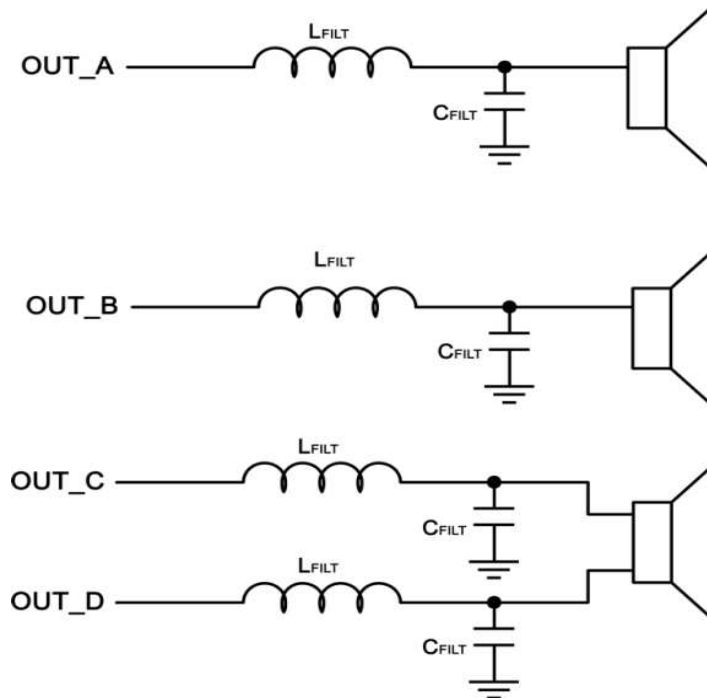


FIG 59. 2.1 Mode

Refer to [2.1 Application](#) section for more details of the correct 2.1 output connection of the TAS5755M.

10.5 Programming

10.5.1 I²C Serial Control Interface

The TAS5755M DAP has a bidirectional I²C interface that is compatible with the Inter IC (I²C) bus protocol and supports both 100-kHz and 400-kHz data transfer rates for single- and multiple-byte write and read operations. This is a slave-only device that does not support a multimaster bus environment or wait-state insertion. The control interface is used to program the registers of the device and to read device status.

The DAP supports the standard-mode I²C bus operation (100 kHz maximum) and the fast I²C bus operation (400 kHz maximum). The DAP performs all I²C operations without I²C wait cycles.

10.5.1.1 General I²C Operation

The I²C bus employs two signals, SDA (data) and SCL (clock), to communicate between integrated circuits in a system. Data is transferred on the bus serially, one bit at a time. The address and data can be transferred in byte (8-bit) format, with the most-significant bit (MSB) transferred first. In addition, each byte transferred on the bus is acknowledged by the receiving device with an acknowledge bit. Each transfer operation begins with the master device driving a start condition on the bus and ends with the master device driving a stop condition on the bus. The bus uses transitions on the data pin (SDA) while the clock is high to indicate start and stop conditions. A high-to-low transition on SDA indicates a start and a low-to-high transition indicates a stop. Normal data-bit transitions must occur within the low time of the clock period. These conditions are shown in [FIG 60](#). The master generates the 7-bit slave address and the read/write (R/W) bit to open communication with another device and then waits for an acknowledge condition. The TAS5755M holds SDA low during the acknowledge clock period to indicate an acknowledgment. When this occurs, the master transmits the next byte of the sequence. Each device is addressed by a unique 7-bit slave address plus R/W bit (1 byte). All compatible devices share the same signals via a bidirectional bus using a wired-AND connection. An external pullup resistor must be used for the SDA and SCL signals to set the high level for the bus.

Programming (continued)

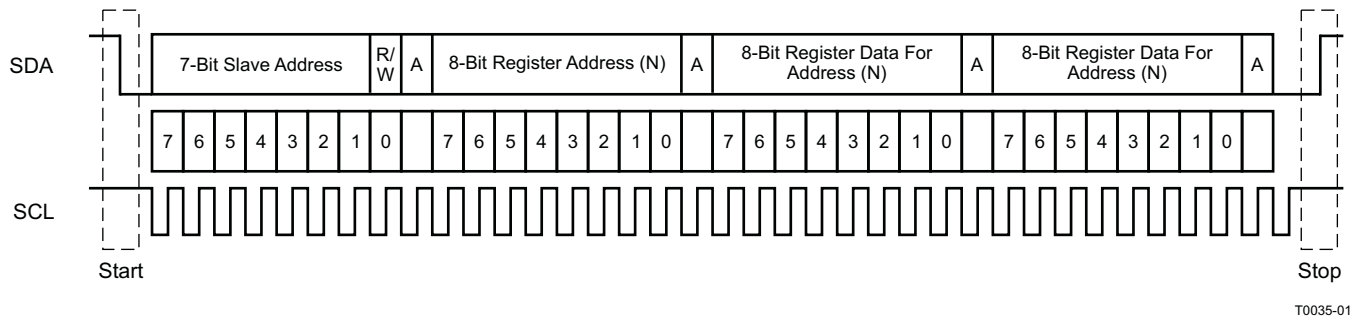


FIG 60. Typical I²C Sequence

There is no limit on the number of bytes that can be transmitted between start and stop conditions. When the last word transfers, the master generates a stop condition to release the bus. A generic data transfer sequence is shown in [FIG 60](#).

The 7-bit address for TAS5755M is 0011 011 (0x36).

10.5.1.2 Single- and Multiple-Byte Transfers

The serial control interface supports both single-byte and multiple-byte read/write operations for subaddresses 0x00 to 0x1F. However, for the subaddresses 0x20 to 0xFF, the serial control interface supports only multiple-byte read/write operations (in multiples of 4 bytes).

During multiple-byte read operations, the DAP responds with data, a byte at a time, starting at the subaddress assigned, as long as the master device continues to respond with acknowledges. If a particular subaddress does not contain 32 bits, the unused bits are read as logic 0.

During multiple-byte write operations, the DAP compares the number of bytes transmitted to the number of bytes that are required for each specific subaddress. For example, if a write command is received for a biquad subaddress, the DAP must receive five 32-bit words. If fewer than five 32-bit data words have been received when a stop command (or another start command) is received, the received data is discarded.

Supplying a subaddress for each subaddress transaction is referred to as random I²C addressing. The TAS5755M also supports sequential I²C addressing. For write transactions, if a subaddress is issued followed by data for that subaddress and the 15 subaddresses that follow, a sequential I²C write transaction has taken place, and the data for all 16 subaddresses is successfully received by the TAS5755M. For I²C sequential-write transactions, the subaddress then serves as the start address, and the amount of data subsequently transmitted, before a stop or start is transmitted, determines how many subaddresses are written. As was true for random addressing, sequential addressing requires that a complete set of data be transmitted. If only a partial set of data is written to the last subaddress, the data for the last subaddress is discarded. However, all other data written is accepted; only the incomplete data is discarded.

10.5.1.3 Single-Byte Write

As shown in [FIG 61](#), a single-byte data-write transfer begins with the master device transmitting a start condition followed by the I²C device address and the read/write bit. The read/write bit determines the direction of the data transfer. For a data-write transfer, the read/write bit is a 0. After receiving the correct I²C device address and the read/write bit, the DAP responds with an acknowledge bit. Next, the master transmits the address byte or bytes corresponding to the TAS5755M internal memory address being accessed. After receiving the address byte, the TAS5755M again responds with an acknowledge bit. Next, the master device transmits the data byte to be written to the memory address being accessed. After receiving the data byte, the TAS5755M again responds with an acknowledge bit. Finally, the master device transmits a stop condition to complete the single-byte data-write transfer.

Programming (continued)

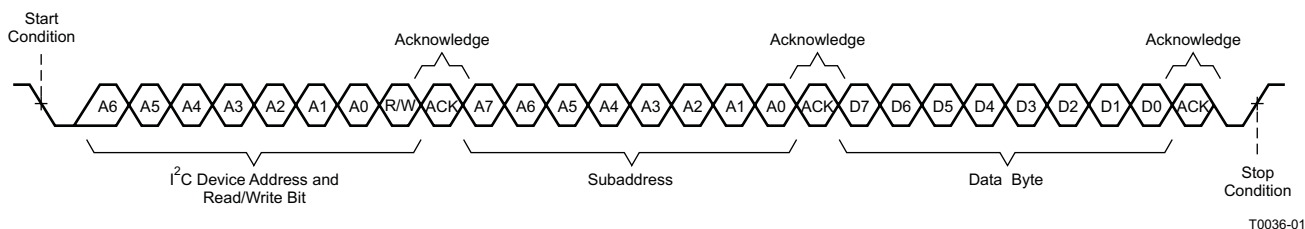


Figure 61. Single-Byte Write Transfer

10.5.1.4 Multiple-Byte Write

A multiple-byte data-write transfer is identical to a single-byte data-write transfer except that multiple data bytes are transmitted by the master device to the DAP as shown in Figure 62. After receiving each data byte, the TAS5755M responds with an acknowledge bit.

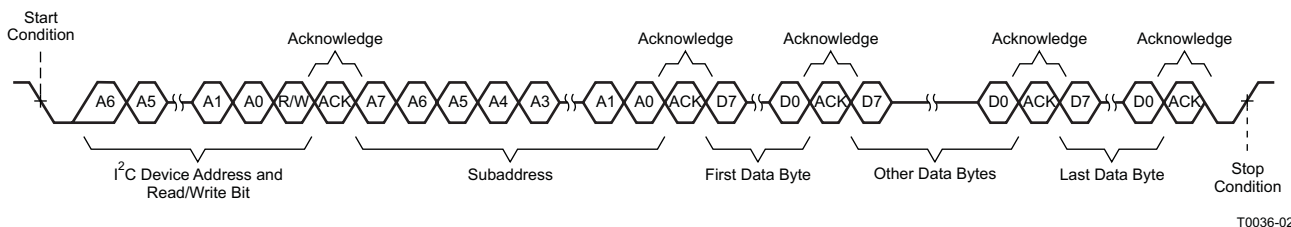


Figure 62. Multiple-Byte Write Transfer

10.5.1.5 Single-Byte Read

As shown in Figure 63, a single-byte data-read transfer begins with the master device transmitting a start condition, followed by the I²C device address and the read/write bit. For the data read transfer, both a write followed by a read are actually done. Initially, a write is done to transfer the address byte or bytes of the internal memory address to be read. As a result, the read/write bit becomes a 0. After receiving the TAS5755M address and the read/write bit, TAS5755M responds with an acknowledge bit. In addition, after sending the internal memory address byte or bytes, the master device transmits another start condition followed by the TAS5755M address and the read/write bit again. This time, the read/write bit becomes a 1, indicating a read transfer. After receiving the address and the read/write bit, the TAS5755M again responds with an acknowledge bit. Next, the TAS5755M transmits the data byte from the memory address being read. After receiving the data byte, the master device transmits a not-acknowledge followed by a stop condition to complete the single-byte data-read transfer.

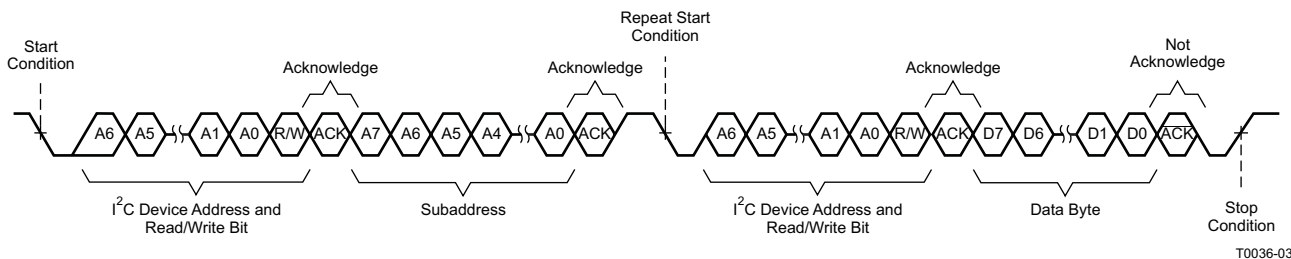


Figure 63. Single-Byte Read Transfer

10.5.1.6 Multiple-Byte Read

A multiple-byte data-read transfer is identical to a single-byte data-read transfer except that multiple data bytes are transmitted by the TAS5755M to the master device as shown in Figure 64. Except for the last data byte, the master device responds with an acknowledge bit after receiving each data byte.

Programming (continued)

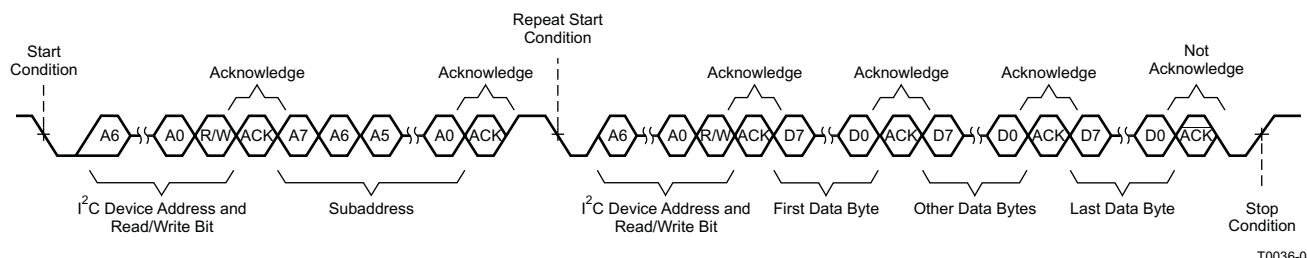


FIG 64. Multiple-Byte Read Transfer

10.5.2 26-Bit 3.23 Number Format

All mixer gain coefficients are 26-bit coefficients using a 3.23 number format. Numbers formatted as 3.23 numbers means that there are 3 bits to the left of the binary point and 23 bits to the right of the binary point. This is shown in FIG 65.

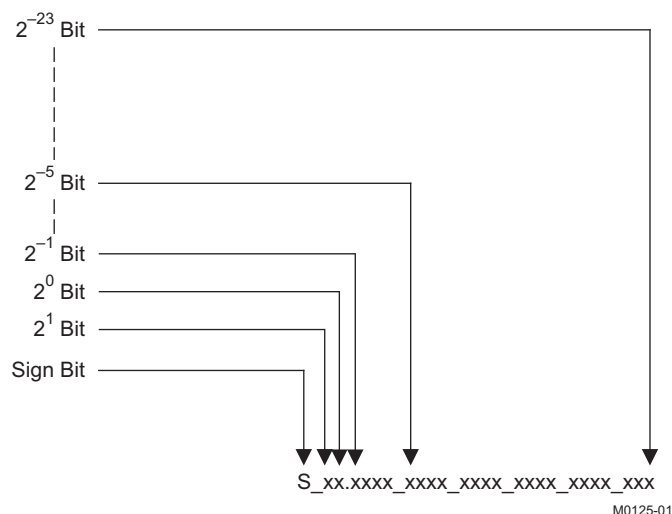


FIG 65. 3.23 Format

The decimal value of a 3.23 format number can be found by following the weighting shown in FIG 65. If the most significant bit is logic 0, the number is a positive number, and the weighting shown yields the correct number. If the most significant bit is a logic 1, then the number is a negative number. In this case every bit must be inverted, a 1 added to the result, and then the weighting shown in FIG 66 applied to obtain the magnitude of the negative number.

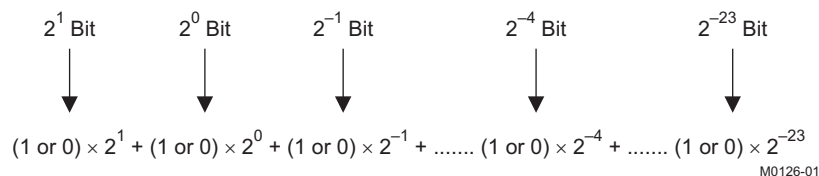
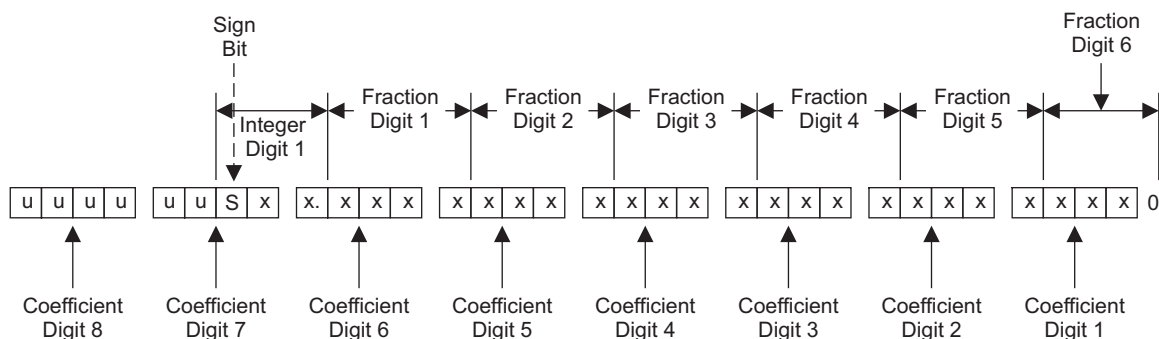


FIG 66. Conversion Weighting Factors — 3.23 Format To Floating Point

Gain coefficients, entered via the I²C bus, must be entered as 32-bit binary numbers. The format of the 32-bit number (4-byte or 8-digit hexadecimal number) is shown in FIG 67.

Programming (continued)



u = unused or don't care bits
Digit = hexadecimal digit

M0127-01

图 67. Alignment of 3.23 Coefficient in 32-Bit I²C Word

表 1. Sample Calculation for 3.23 Format

db	LINEAR	DECIMAL	HEX (3.23 Format)
0	1	8,388,608	80 0000
5	1.77	14,917,288	00E3 9EA8
-5	0.56	4,717,260	0047 FACC
X	$L = 10^{(X/20)}$	$D = 8,388,608 \times L$	$H = \text{dec2hex}(D, 8)$

表 2. Sample Calculation for 9.17 Format

db	LINEAR	DECIMAL	HEX (9.17 Format)
0	1	131,072	2 0000
5	1.77	231,997	3 8A3D
-5	0.56	73,400	1 1EB8
X	$L = 10^{(X/20)}$	$D = 131,072 \times L$	$H = \text{dec2hex}(D, 8)$

10.6 Register Maps

10.6.1 Register Map Summary

表 3. Serial Control Interface Register Summary

SUBADDRESS	REGISTER NAME	NO. OF BYTES	CONTENTS ⁽¹⁾	INITIALIZATION VALUE
0x00	Clock control register	1	Description shown in subsequent section	0x6C
0x01	Device ID register	1	Description shown in subsequent section	0x00
0x02	Error status register	1	Description shown in subsequent section	0x00
0x03	System control register 1	1	Description shown in subsequent section	0xA0
0x04	Serial data interface register	1	Description shown in subsequent section	0x05
0x05	System control register 2	1	Description shown in subsequent section	0x40
0x06	Soft mute register	1	Description shown in subsequent section	0x00
0x07	Master volume	1	Description shown in subsequent section	0xFF (mute)
0x08	Channel 1 vol	1	Description shown in subsequent section	0x30 (0 dB)
0x09	Channel 2 vol	1	Description shown in subsequent section	0x30 (0 dB)
0x0A	Channel 3 vol	1	Description shown in subsequent section	0x30 (0 dB)
0x0B–0x0D		1	Reserved ⁽²⁾	
0x0E	Volume configuration register	1	Description shown in subsequent section	0x91
0x0F		1	Reserved ⁽²⁾	
0x10	Modulation limit register	1	Description shown in subsequent section	0x02
0x11	IC delay channel 1	1	Description shown in subsequent section	0xAC
0x12	IC delay channel 2	1	Description shown in subsequent section	0x54
0x13	IC delay channel 3	1	Description shown in subsequent section	0xAC
0x14	IC delay channel 4	1	Description shown in subsequent section	0x54
0x15–0x18		1	Reserved ⁽²⁾	
0x19	PWM channel shutdown group register	1	Description shown in subsequent section	0x30
0x1A	Start/stop period register	1		0x0F
0x1B	Oscillator trim register	1		0x82
0x1C	BKND_ERR register	1		0x02
0x1D–0x1F		1	Reserved ⁽²⁾	
0x20	Input MUX register	4	Description shown in subsequent section	0x0001 7772
0x21	Ch 4 source select register	4	Description shown in subsequent section	0x0000 4303
0x22–0x24		4	Reserved ⁽²⁾	
0x25	PWM MUX register	4	Description shown in subsequent section	0x0102 1345
0x26–0x28		4	Reserved ⁽²⁾	
0x29	ch1_bq[0]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x2A	ch1_bq[1]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000

(1) A u indicates unused bits.

(2) Reserved registers must not be accessed.

Register Maps (continued)
表 3. Serial Control Interface Register Summary (continued)

SUBADDRESS	REGISTER NAME	NO. OF BYTES	CONTENTS ⁽¹⁾	INITIALIZATION VALUE
0x2B	ch1_bq[2]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x2C	ch1_bq[3]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x2D	ch1_bq[4]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x2E	ch1_bq[5]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x2F	ch1_bq[6]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x30	ch2_bq[0]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x31	ch2_bq[1]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x32	ch2_bq[2]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x33	ch2_bq[3]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000

Register Maps (continued)
表 3. Serial Control Interface Register Summary (continued)

SUBADDRESS	REGISTER NAME	NO. OF BYTES	CONTENTS ⁽¹⁾	INITIALIZATION VALUE
0x34	ch2_bq[4]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x35	ch2_bq[5]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x36	ch2_bq[6]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x37 - 0x39		4	Reserved ⁽²⁾	
0x3A	DRC1 ae ⁽³⁾	8	u[31:26], ae[25:0]	0x0080 0000
	DRC1 (1 – ae)		u[31:26], (1 – ae)[25:0]	0x0000 0000
0x3B	DRC1 aa	8	u[31:26], aa[25:0]	0x0080 0000
	DRC1 (1 – aa)		u[31:26], (1 – aa)[25:0]	0x0000 0000
0x3C	DRC1 ad	8	u[31:26], ad[25:0]	0x0080 0000
	DRC1 (1 – ad)		u[31:26], (1 – ad)[25:0]	0x0000 0000
0x3D	DRC2 ae	8	u[31:26], ae[25:0]	0x0080 0000
	DRC 2 (1 – ae)		u[31:26], (1 – ae)[25:0]	0x0000 0000
0x3E	DRC2 aa	8	u[31:26], aa[25:0]	0x0080 0000
	DRC2 (1 – aa)		u[31:26], (1 – aa)[25:0]	0x0000 0000
0x3F	DRC2 ad	8	u[31:26], ad[25:0]	0x0080 0000
	DRC2 (1 – ad)		u[31:26], (1 – ad)[25:0]	0x0000 0000
0x40	DRC1-T	4	T1[31:0] (9.23 format)	0xFDA2 1490
0x41	DRC1-K	4	u[31:26], K1[25:0]	0x0384 2109
0x42	DRC1-O	4	u[31:26], O1[25:0]	0x0008 4210
0x43	DRC2-T	4	T2[31:0] (9.23 format)	0xFDA2 1490
0x44	DRC2-K	4	u[31:26], K2[25:0]	0x0384 2109
0x45	DRC2-O	4	u[31:26], O2[25:0]	0x0008 4210
0x46	DRC control	4	Description shown in subsequent section	0x0000 0000
0x47–0x4F		4	Reserved ⁽²⁾	
0x50	Bank switch control	4	Description shown in subsequent section	0x0F70 8000
0x51	Ch 1 output mixer	12	Ch 1 output mix1[2]	0x0080 0000
			Ch 1 output mix1[1]	0x0000 0000
			Ch 1 output mix1[0]	0x0000 0000
0x52	Ch 2 output mixer	12	Ch 2 output mix2[2]	0x0080 0000
			Ch 2 output mix2[1]	0x0000 0000
			Ch 2 output mix2[0]	0x0000 0000

(3) "ae" stands for α of energy filter, "aa" stands for α of attack filter and "ad" stands for α of decay filter and $1 - \alpha = \omega$.

Register Maps (continued)

表 3. Serial Control Interface Register Summary (continued)

SUBADDRESS	REGISTER NAME	NO. OF BYTES	CONTENTS ⁽¹⁾	INITIALIZATION VALUE
0x53	Ch 1 input mixer	16	Ch 1 input mixer[3]	0x0080 0000
			Ch 1 input mixer[2]	0x0000 0000
			Ch 1 input mixer[1]	0x0000 0000
			Ch 1 input mixer[0]	0x0080 0000
0x54	Ch 2 input mixer	16	Ch 2 input mixer[3]	0x0080 0000
			Ch 2 input mixer[2]	0x0000 0000
			Ch 2 input mixer[1]	0x0000 0000
			Ch 2 input mixer[0]	0x0080 0000
0x55	Channel 3 input mixer	12	Channel 3 input mixer [2]	0x0080 0000
			Channel 3 input mixer [1]	0x0000 0000
			Channel 3 input mixer [0]	0x0000 0000
0x56	Output post-scale	4	u[31:26], post[25:0]	0x0080 0000
0x57	Output pre-scale	4	u[31:26], pre[25:0] (9.17 format)	0x0002 0000
0x58	ch1 BQ[7]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x59	ch1 BQ[8]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x5A	Subchannel BQ[0]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x5B	Subchannel BQ[1]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x5C	ch2 BQ[7]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x5D	ch2 BQ[8]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000

Register Maps (continued)
表 3. Serial Control Interface Register Summary (continued)

SUBADDRESS	REGISTER NAME	NO. OF BYTES	CONTENTS ⁽¹⁾	INITIALIZATION VALUE
0x5E	pseudo_ch2 BQ[0]	20	u[31:26], b0[25:0]	0x0080 0000
			u[31:26], b1[25:0]	0x0000 0000
			u[31:26], b2[25:0]	0x0000 0000
			u[31:26], a1[25:0]	0x0000 0000
			u[31:26], a2[25:0]	0x0000 0000
0x5F		4	Reserved ⁽²⁾	
0x60	Channel 4 (subchannel) output mixer	8	Ch 4 output mixer[1]	0x0000 0000
			Ch 4 output mixer[0]	0x0080 0000
0x61	Channel 4 (subchannel) input mixer	8	Ch 4 input mixer[1]	0x0040 0000
			Ch 4 input mixer[0]	0x0040 0000
0x62	IDF post scale	4	Post-IDF attenuation register	0x0000 0080
0x63–0xF7			Reserved ⁽²⁾	0x0000 0000
0xF8	Device address enable register	4	Write F9 A5 A5 A5 in this register to enable write to device address update (0xF9)	0x0000 0000
0xF9	Device address Update Register	4	u[31:8], New Dev Id[7:1] , ZERO[0] (New Dev Id (7:1) defines the new device address	0X0000 0036
0xFA–0xFF		4	Reserved ⁽²⁾	0x0000 0000

All DAP coefficients are 3.23 format unless specified otherwise.

10.6.2 Register Maps

10.6.2.1 Clock Control Register (0x00)

The clocks and data rates are automatically determined by the TAS5755M. The clock control register contains the auto-detected clock status. Bits D7–D5 reflect the sample rate. Bits D4–D2 reflect the MCLK frequency. The device accepts a $64 f_S$ or $32 f_S$ SCLK rate for all MCLK ratios, but accepts a $48 f_S$ SCLK rate for MCLK ratios of $192 f_S$ and $384 f_S$ only.

表 4. Clock Control Register (0x00)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	–	–	–	–	–	$f_S = 32\text{-kHz}$ sample rate
0	0	1	–	–	–	–	–	Reserved ⁽¹⁾
0	1	0	–	–	–	–	–	Reserved ⁽¹⁾
0	1	1	–	–	–	–	–	$f_S = 44.1/48\text{-kHz}$ sample rate⁽²⁾
1	0	0	–	–	–	–	–	$f_S = 16\text{-kHz}$ sample rate
1	0	1	–	–	–	–	–	$f_S = 22.05/24\text{-kHz}$ sample rate
1	1	0	–	–	–	–	–	$f_S = 8\text{-kHz}$ sample rate
1	1	1	–	–	–	–	–	$f_S = 11.025/12\text{-kHz}$ sample rate
–	–	–	0	0	0	–	–	MCLK frequency = $64 \times f_S$ ⁽³⁾
–	–	–	0	0	1	–	–	MCLK frequency = $128 \times f_S$ ⁽³⁾
–	–	–	0	1	0	–	–	MCLK frequency = $192 \times f_S$ ⁽⁴⁾
–	–	–	0	1	1	–	–	MCLK frequency = $256 \times f_S$⁽²⁾⁽⁵⁾
–	–	–	1	0	0	–	–	MCLK frequency = $384 \times f_S$
–	–	–	1	0	1	–	–	MCLK frequency = $512 \times f_S$
–	–	–	1	1	0	–	–	Reserved ⁽¹⁾
–	–	–	1	1	1	–	–	Reserved ⁽¹⁾
–	–	–	–	–	–	0	–	Reserved⁽¹⁾⁽²⁾
–	–	–	–	–	–	–	0	Reserved⁽¹⁾⁽²⁾

(1) Reserved registers must not be accessed.

(2) Default values are in **bold**.

(3) Only available for 44.1-kHz and 48-kHz rates

(4) Rate only available for 32/44.1/48-kHz sample rates

(5) Not available at 8 kHz

10.6.2.2 Device ID Register (0x01)

The device ID register contains the ID code for the firmware revision.

表 5. General Status Register (0x01)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	0	0	0	0	0	Identification code

10.6.2.3 Error Status Register (0x02)

The error bits are sticky and are not cleared by the hardware. This means that the software must clear the register (write zeroes) and then read them to determine if they are persistent errors.

Error Definitions:

- MCLK Error : MCLK frequency is changing. The number of MCLKs per LRCLK is changing.
- SCLK Error: The number of SCLKs per LRCLK is changing.
- LRCLK Error: LRCLK frequency is changing.
- Frame Slip: LRCLK phase is drifting with respect to internal Frame Sync.

表 6. Error Status Register (0x02)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
1	-	-	-	-	-	-	-	MCLK error
-	1	-	-	-	-	-	-	PLL autolock error
-	-	1	-	-	-	-	-	SCLK error
-	-	-	1	-	-	-	-	LRCLK error
-	-	-	-	1	-	-	-	Frame slip
-	-	-	-	-	1	-	-	Clip indicator
-	-	-	-	-	-	1	-	Overcurrent, overtemperature, or undervoltage errors
-	-	-	-	-	-	-	0	Reserved
0	0	0	0	0	0	0	-	No errors⁽¹⁾

(1) Default values are in **bold**.

10.6.2.4 System Control Register 1 (0x03)

The system control register 1 has several functions:

Bit D7: If 0, the dc-blocking filter for each channel is disabled.

If 1, the dc-blocking filter (–3 dB cutoff <1 Hz) for each channel is enabled (default).

Bit D5: If 0, use soft unmute on recovery from clock error. This is a slow recovery. Unmute takes the same time as the volume ramp defined in register 0x0E.

If 1, use hard unmute on recovery from clock error (default). This is a fast recovery, a single step volume ramp

Bits D1–D0: Select de-emphasis

表 7. System Control Register 1 (0x03)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	-	-	-	-	-	-	-	PWM high-pass (dc blocking) disabled
1	-	-	-	-	-	-	-	PWM high-pass (dc blocking) enabled⁽¹⁾
-	0	-	-	-	-	-	-	Reserved⁽¹⁾
-	-	0	-	-	-	-	-	Soft unmute on recovery from clock error
-	-	1	-	-	-	-	-	Hard unmute on recovery from clock error⁽¹⁾
-	-	-	0	-	-	-	-	Reserved⁽¹⁾
-	-	-	-	0	-	-	-	Reserved⁽¹⁾
-	-	-	-	-	0	-	-	Reserved⁽¹⁾
-	-	-	-	-	-	0	0	No de-emphasis⁽¹⁾
-	-	-	-	-	-	0	1	De-emphasis for $f_S = 32$ kHz
-	-	-	-	-	-	1	0	De-emphasis for $f_S = 44.1$ kHz
-	-	-	-	-	-	1	1	De-emphasis for $f_S = 48$ kHz

(1) Default values are in **bold**.

10.6.2.5 Serial Data Interface Register (0x04)

As shown in 表 8, the TAS5755M supports 9 serial data modes. The default is 24-bit, I²S mode,

表 8. Serial Data Interface Control Register (0x04)

RECEIVE SERIAL DATA INTERFACE FORMAT	WORD LENGTH	D7–D4	D3	D2	D1	D0
Right-justified	16	0000	0	0	0	0
Right-justified	20	0000	0	0	0	1
Right-justified	24	0000	0	0	1	0
I ² S	16	000	0	0	1	1
I ² S	20	0000	0	1	0	0
I²S ⁽¹⁾	24	0000	0	1	0	1
Left-justified	16	0000	0	1	1	0
Left-justified	20	0000	0	1	1	1
Left-justified	24	0000	1	0	0	0
Reserved		0000	1	0	0	1
Reserved		0000	1	0	1	0
Reserved		0000	1	0	1	1
Reserved		0000	1	1	0	0
Reserved		0000	1	1	0	1
Reserved		0000	1	1	1	0
Reserved		0000	1	1	1	1

(1) Default values are in **bold**.

10.6.2.6 System Control Register 2 (0x05)

When bit D6 is set low, the system exits all channel shutdown and starts playing audio; otherwise, the outputs are shut down (hard mute).

表 9. System Control Register 2 (0x05)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	–	–	–	–	–	–	–	Mid-Z ramp disabled ⁽¹⁾
1	–	–	–	–	–	–	–	Mid-Z ramp enabled
–	0	–	–	–	–	–	–	Exit all-channel shutdown (normal operation)
–	1	–	–	–	–	–	–	Enter all-channel shutdown (hard mute) ⁽¹⁾
				0				Sub-channel in AD Mode
				1				Sub-channel in BD Mode
–	–	–	–	–	0	–	–	2.0 mode [2.0 BTL] ⁽¹⁾
–	–	–	–	–	1	–	–	2.1 mode [2 SE + 1 BTL]
–	–	–	–	–	–	0	–	ADR/ $\overline{\text{FAULT}}$ pin is configured as to serve as an address input only ⁽¹⁾
–	–	–	–	–	–	1	–	ADR/ $\overline{\text{FAULT}}$ pin is configured as fault output
–	–	0	0	–	–	–	0	Reserved ⁽¹⁾

(1) Default values are in **bold**.

10.6.2.7 Soft Mute Register (0x06)

Writing a 1 to any of the following bits sets the output of the respective channel to 50% duty cycle (soft mute).

表 10. Soft Mute Register (0x06)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	0	0	–	–	–	Reserved ⁽¹⁾
–	–	–	–	–	0	–	–	Soft unmute channel 3 ⁽¹⁾
–	–	–	–	–	1	–	–	Soft mute channel 3
–	–	–	–	–	–	0	–	Soft unmute channel 2 ⁽¹⁾
–	–	–	–	–	–	1	–	Soft mute channel 2
–	–	–	–	–	–	–	0	Soft unmute channel 1 ⁽¹⁾
–	–	–	–	–	–	–	1	Soft mute channel 1

(1) Default values are in **bold**.

10.6.2.8 Volume Registers (0x07, 0x08, 0x09, 0x0A)

Step size is 0.5 dB.

Master volume	– 0x07 (default is mute)
Channel-1 volume	– 0x08 (default is 0 dB)
Channel-2 volume	– 0x09 (default is 0 dB)
Channel-3 volume	– 0x0A (default is 0 dB)

表 11. Volume Registers (0x07, 0x08, 0x09, 0x0A)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	0	0	0	0	0	24 dB
0	0	1	1	0	0	0	0	0 dB (default for individual channel volume) ⁽¹⁾
1	1	1	1	1	1	1	0	–103 dB
1	1	1	1	1	1	1	1	Soft mute (default for master volume) ⁽¹⁾

(1) Default values are in **bold**.

10.6.2.9 Volume Configuration Register (0x0E)

Bits D2–D0: Volume slew rate (Used to control volume change and MUTE ramp rates). These bits control the number of steps in a volume ramp. Volume steps occur at a rate that depends on the sample rate of the I²S data as follows

Sample Rate (KHz)	Approximate Ramp Rate
8/16/32	125 µs/step
11.025/22.05/44.1	90.7 µs/step
12/24/48	83.3 µs/step

表 12. Volume Control Register (0x0E)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
1	–	–	1	0	–	–	–	Reserved ⁽¹⁾
–	0	–	–	–	–	–	–	Subchannel (ch4) volume = ch1 volume ^{(2) (1)}
–	1	–	–	–	–	–	–	Subchannel volume = register 0x0A ⁽²⁾
–	–	0	–	–	–	–	–	Ch3 volume = ch2 volume ⁽¹⁾
–	–	1	–	–	–	–	–	Ch3 volume = register 0x0A
–	–	–	–	–	0	0	0	Volume slew 512 steps (43-ms volume ramp time at 48 kHz)
–	–	–	–	–	0	0	1	Volume slew 1024 steps (85-ms volume ramp time at 48 kHz) ⁽¹⁾
–	–	–	–	–	0	1	0	Volume slew 2048 steps (171- ms volume ramp time at 48 kHz)
–	–	–	–	–	0	1	1	Volume slew 256 steps (21-ms volume ramp time at 48 kHz)
–	–	–	–	–	1	X	X	Reserved

(1) Default values are in **bold**.

(2) Bits 6:5 can be changed only when volume is in MUTE [master volume = MUTE (register 0x07 = 0xFF)].

10.6.2.10 Modulation Limit Register (0x10)

The modulation limit is the maximum duty cycle of the PWM output waveform.

表 13. Modulation Limit Register (0x10)

D7	D6	D5	D4	D3	D2	D1	D0	MODULATION LIMIT
–	–	–	–	–	0	0	0	99.2%
–	–	–	–	–	0	0	1	98.4%
–	–	–	–	–	0	1	0	97.7% ⁽¹⁾
–	–	–	–	–	0	1	1	96.9%
–	–	–	–	–	1	0	0	96.1%
–	–	–	–	–	1	0	1	95.3%
–	–	–	–	–	1	1	0	94.5%
–	–	–	–	–	1	1	1	93.8%
0	0	0	0	0	–	–	–	Reserved

(1) Default values are in **bold**.

10.6.2.11 Interchannel Delay Registers (0x11, 0x12, 0x13, and 0x14)

Internal PWM Channels 1, 2, $\bar{1}$, and $\bar{2}$ are mapped into registers 0x11, 0x12, 0x13, and 0x14.

表 14. Channel Interchannel Delay Registers (0x11, 0x12, 0x13, and 0x14)

BITS DEFINITION	D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
	0	0	0	0	0	0	–	–	Minimum absolute delay, 0 DCLK cycles
	0	1	1	1	1	1	–	–	Maximum positive delay, 31×4 DCLK cycles
	1	0	0	0	0	0	–	–	Maximum negative delay, -32×4 DCLK cycles
							0	0	Reserved
SUBADDRESS	D7	D6	D5	D4	D3	D2	D1	D0	DELAY = (VALUE) $\times$ 4 DCLKs
0x11	1	0	1	0	1	1	–	–	Default value for channel 1 ⁽¹⁾
0x12	0	1	0	1	0	1	–	–	Default value for channel 2 ⁽¹⁾
0x13	1	0	1	0	1	1	–	–	Default value for channel $\bar{1}$ ⁽¹⁾
0x14	0	1	0	1	0	1	–	–	Default value for channel $\bar{2}$ ⁽¹⁾

(1) Default values are in **bold**.

ICD settings have high impact on audio performance (e.g., dynamic range, THD, crosstalk etc.). Therefore, appropriate ICD settings must be used. By default, the device has ICD settings for AD mode. If used in BD mode, then update these registers before coming out of all-channel shutdown.

REGISTER	AD MODE	BD MODE
0x11	AC	B8
0x12	54	60
0x13	AC	A0
0x14	54	48

10.6.2.12 PWM Shutdown Group Register (0x19)

Settings of this register determine which PWM channels are active. The value must be 0x30 for BTL mode and 0x3A for PBT mode. The default value of this register is 0x30. The functionality of this register is tied to the state of bit D5 in the system control register.

This register defines which channels belong to the shutdown group (SDG). If a 1 is set in the shutdown group register, that particular channel is **not** started following an exit out of all-channel shutdown command (if bit D5 is set to 0 in system control register 2, 0x05).

表 15. Shutdown Group Register (0x19)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	–	–	–	–	–	–	–	Reserved ⁽¹⁾
–	0	–	–	–	–	–	–	Reserved ⁽¹⁾
–	–	1	–	–	–	–	–	Reserved ⁽¹⁾
–	–	–	1	–	–	–	–	Reserved ⁽¹⁾
–	–	–	–	0	–	–	–	PWM channel 4 does not belong to shutdown group. ⁽¹⁾
–	–	–	–	1	–	–	–	PWM channel 4 belongs to shutdown group.
–	–	–	–	–	0	–	–	PWM channel 3 does not belong to shutdown group. ⁽¹⁾
–	–	–	–	–	1	–	–	PWM channel 3 belongs to shutdown group.
–	–	–	–	–	–	0	–	PWM channel 2 does not belong to shutdown group. ⁽¹⁾
–	–	–	–	–	–	1	–	PWM channel 2 belongs to shutdown group.
–	–	–	–	–	–	–	0	PWM channel 1 does not belong to shutdown group. ⁽¹⁾
–	–	–	–	–	–	–	1	PWM channel 1 belongs to shutdown group.

(1) Default values are in **bold**.

10.6.2.13 Start/Stop Period Register (0x1A)

This register is used to control the soft-start and soft-stop period following an enter/exit all channel shut down command or change in the PDN state. This helps reduce pops and clicks at start-up and shutdown. The times are only approximate and vary depending on device activity level and I²S clock stability.

表 16. Start/Stop Period Register (0x1A)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	–	–	–	–	–	–	–	SSTIMER enabled ⁽¹⁾
1	–	–	–	–	–	–	–	SSTIMER disabled
–	0	0	–	–	–	–	–	Reserved⁽¹⁾
–	–	–	0	0	–	–	–	No 50% duty cycle start/stop period
–	–	–	0	1	0	0	0	16.5-ms 50% duty cycle start/stop period
–	–	–	0	1	0	0	1	23.9-ms 50% duty cycle start/stop period
–	–	–	0	1	0	1	0	31.4-ms 50% duty cycle start/stop period
–	–	–	0	1	0	1	1	40.4-ms 50% duty cycle start/stop period
–	–	–	0	1	1	0	0	53.9-ms 50% duty cycle start/stop period
–	–	–	0	1	1	0	1	70.3-ms 50% duty cycle start/stop period
–	–	–	0	1	1	1	0	94.2-ms 50% duty cycle start/stop period
–	–	–	0	1	1	1	1	125.7-ms 50% duty cycle start/stop period⁽¹⁾
–	–	–	1	0	0	0	0	164.6-ms 50% duty cycle start/stop period
–	–	–	1	0	0	0	1	239.4-ms 50% duty cycle start/stop period
–	–	–	1	0	0	1	0	314.2-ms 50% duty cycle start/stop period
–	–	–	1	0	0	1	1	403.9-ms 50% duty cycle start/stop period
–	–	–	1	0	1	0	0	538.6-ms 50% duty cycle start/stop period
–	–	–	1	0	1	0	1	703.1-ms 50% duty cycle start/stop period
–	–	–	1	0	1	1	0	942.5-ms 50% duty cycle start/stop period
–	–	–	1	0	1	1	1	1256.6-ms 50% duty cycle start/stop period
–	–	–	1	1	0	0	0	1728.1-ms 50% duty cycle start/stop period
–	–	–	1	1	0	0	1	2513.6-ms 50% duty cycle start/stop period
–	–	–	1	1	0	1	0	3299.1-ms 50% duty cycle start/stop period
–	–	–	1	1	0	1	1	4241.7-ms 50% duty cycle start/stop period
–	–	–	1	1	1	0	0	5655.6-ms 50% duty cycle start/stop period
–	–	–	1	1	1	0	1	7383.7-ms 50% duty cycle start/stop period
–	–	–	1	1	1	1	0	9897.3-ms 50% duty cycle start/stop period
–	–	–	1	1	1	1	1	13,196.4-ms 50% duty cycle start/stop period

(1) Default values are in **bold**.

10.6.2.14 Oscillator Trim Register (0x1B)

The TAS5755M PWM processor contains an internal oscillator to support autodetect of I²S clock rates. This reduces system cost because an external reference is not required. Currently, TI recommends a reference resistor value of 18.2 kΩ (1%). This must be connected between OSC_RES and DVSSO.

Writing 0x00 to register 0x1B enables the trim that was programmed at the factory.

注

Trim must always be run following reset of the device.

表 17. Oscillator Trim Register (0x1B)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	–	–	–	–	–	–	–	Reserved ⁽¹⁾
–	0	–	–	–	–	–	–	Oscillator trim not done (read-only) ⁽¹⁾
–	1	–	–	–	–	–	–	Oscillator trim done (read only)
–	–	0	0	0	0	–	–	Reserved ⁽¹⁾
–	–	–	–	–	–	0	–	Select factory trim (Write a 0 to select factory trim; default is 1.)
–	–	–	–	–	–	1	–	Factory trim disabled ⁽¹⁾
–	–	–	–	–	–	–	0	Reserved ⁽¹⁾

(1) Default values are in **bold**.

10.6.2.15 BKND_ERR Register (0x1C)

When a back-end error signal is received from the internal power stage, the power stage is reset stopping all PWM activity. Subsequently, the modulator waits approximately for the time listed in 表 18 before attempting to re-start the power stage.

表 18. BKND_ERR Register (0x1C)⁽¹⁾

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	0	0	0	0	X	Reserved
–	–	–	–	0	0	1	0	Set back-end reset period to 299 ms ⁽²⁾
–	–	–	–	0	0	1	1	Set back-end reset period to 449 ms
–	–	–	–	0	1	0	0	Set back-end reset period to 598 ms
–	–	–	–	0	1	0	1	Set back-end reset period to 748 ms
–	–	–	–	0	1	1	0	Set back-end reset period to 898 ms
–	–	–	–	0	1	1	1	Set back-end reset period to 1047 ms
–	–	–	–	1	0	0	0	Set back-end reset period to 1197 ms
–	–	–	–	1	0	0	1	Set back-end reset period to 1346 ms
–	–	–	–	1	0	1	X	Set back-end reset period to 1496 ms
–	–	–	–	1	1	X	X	Set back-end reset period to 1496 ms

(1) This register can be written only with a "non-Reserved" value. Also this register can be written once after the reset.

(2) Default values are in **bold**.

10.6.2.16 Input Multiplexer Register (0x20)

This register controls the modulation scheme (AD or BD mode) as well as the routing of I²S audio to the internal channels.

表 19. Input Multiplexer Register (0x20)

D31	D30	D29	D28	D27	D26	D25	D24	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D23	D22	D21	D20	D19	D18	D17	D16	FUNCTION
0	–	–	–	–	–	–	–	Channel-1 AD mode⁽¹⁾
1	–	–	–	–	–	–	–	Channel-1 BD mode
–	0	0	0	–	–	–	–	SDIN-L to channel 1⁽¹⁾
–	0	0	1	–	–	–	–	SDIN-R to channel 1
–	0	1	0	–	–	–	–	Reserved
–	0	1	1	–	–	–	–	Reserved
–	1	0	0	–	–	–	–	Reserved
–	1	0	1	–	–	–	–	Reserved
–	1	1	0	–	–	–	–	Ground (0) to channel 1
–	1	1	1	–	–	–	–	Reserved
–	–	–	–	0	–	–	–	Channel 2 AD mode⁽¹⁾
–	–	–	–	1	–	–	–	Channel 2 BD mode
–	–	–	–	–	0	0	0	SDIN-L to channel 2
–	–	–	–	–	0	0	1	SDIN-R to channel 2⁽¹⁾
–	–	–	–	–	0	1	0	Reserved
–	–	–	–	–	0	1	1	Reserved
–	–	–	–	–	1	0	0	Reserved
–	–	–	–	–	1	0	1	Reserved
–	–	–	–	–	1	1	0	Ground (0) to channel 2
–	–	–	–	–	1	1	1	Reserved
D15	D14	D13	D12	D11	D10	D9	D8	FUNCTION
0	1	1	1	0	1	1	1	Reserved ⁽¹⁾
D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	1	1	1	0	0	1	0	Reserved ⁽¹⁾

(1) Default values are in **bold**.

10.6.2.17 Channel 4 Source Select Register (0x21)

This register selects the channel 4 source.

表 20. Subchannel Control Register (0x21)

D31	D30	D29	D28	D27	D26	D25	D24	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D23	D22	D21	D20	D19	D18	D17	D16	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D15	D14	D13	D12	D11	D10	D9	D8	FUNCTION
0	1	0	0	0	0	1	1	Select SDIN path (third path), not available in TAS5755M ⁽¹⁾
–	–	–	–	–	–	–	0	(L + R)/2
–	–	–	–	–	–	0	1	Left-channel post-BQ ⁽¹⁾
D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	0	0	0	0	1	1	Reserved ⁽¹⁾

(1) Default values are in **bold**.

10.6.2.18 PWM Output Mux Register (0x25)

This DAP output mux selects which internal PWM channel is output to the external pins. Any channel can be output to any external output pin.

Bits D21–D20: Selects which PWM channel is output to OUT_A

Bits D17–D16: Selects which PWM channel is output to OUT_B

Bits D13–D12: Selects which PWM channel is output to OUT_C

Bits D09–D08: Selects which PWM channel is output to OUT_D

注

Channels are encoded so that channel 1 = 0x00, channel 2 = 0x01, ..., channel 4 = 0x03.

表 21. PWM Output Mux Register (0x25)

D31	D30	D29	D28	D27	D26	D25	D24	FUNCTION
0	0	0	0	0	0	0	1	Reserved ⁽¹⁾
D23	D22	D21	D20	D19	D18	D17	D16	FUNCTION
0	0	–	–	–	–	–	–	Reserved ⁽¹⁾
–	–	0	0	–	–	–	–	Multiplex PWM 1 to OUT_A ⁽¹⁾
–	–	0	1	–	–	–	–	Multiplex PWM 2 to OUT_A
–	–	1	0	–	–	–	–	Multiplex PWM 3 to OUT_A
–	–	1	1	–	–	–	–	Multiplex PWM 4 to OUT_A
–	–	–	–	0	0	–	–	Reserved ⁽¹⁾
–	–	–	–	–	–	0	0	Multiplex PWM 1 to OUT_B
–	–	–	–	–	–	0	1	Multiplex PWM 2 to OUT_B
–	–	–	–	–	–	1	0	Multiplex PWM 3 to OUT_B ⁽¹⁾
–	–	–	–	–	–	1	1	Multiplex PWM 4 to OUT_B

(1) Default values are in **bold**.

表 21. PWM Output Mux Register (0x25) (continued)

D15	D14	D13	D12	D11	D10	D9	D8	FUNCTION
0	0	–	–	–	–	–	–	Reserved ⁽¹⁾
–	–	0	0	–	–	–	–	Multiplex PWM 1 to OUT_C
–	–	0	1	–	–	–	–	Multiplex PWM 2 to OUT_C⁽¹⁾
–	–	1	0	–	–	–	–	Multiplex PWM 3 to OUT_C
–	–	1	1	–	–	–	–	Multiplex PWM 4 to OUT_C
–	–	–	–	0	0	–	–	Reserved ⁽¹⁾
–	–	–	–	–	–	0	0	Multiplex PWM 1 to OUT_D
–	–	–	–	–	–	0	1	Multiplex PWM 2 to OUT_D
–	–	–	–	–	–	1	0	Multiplex PWM 3 to OUT_D
–	–	–	–	–	–	1	1	Multiplex PWM 4 to OUT_D⁽¹⁾
D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	1	0	0	0	1	0	1	Reserved ⁽¹⁾

10.6.2.19 DRC Control Register (0x46)

Each DRC can be enabled independently using the DRC control register. The DRCs are disabled by default.

表 22. DRC Control Register (0x46)

D31	D30	D29	D28	D27	D26	D25	D24	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D23	D22	D21	D20	D19	D18	D17	D16	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D15	D14	D13	D12	D11	D10	D9	D8	FUNCTION
0	0	0	0	0	0	0	0	Reserved ⁽¹⁾
D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0	0	–	–	–	–	–	–	Reserved ⁽¹⁾
–	–	0	–	–	–	–	–	Disable complementary (1 - H) low-pass filter generation
–	–	1	–	–	–	–	–	Enable complementary (1 - H) low-pass filter generation
–	–	–	0	–	–	–	–	
–	–	–	1	–	–	–	–	
				0	0			Reserved ⁽¹⁾
–	–	–	–	–	–	0	–	DRC2 turned OFF⁽¹⁾
–	–	–	–	–	–	1	–	DRC2 turned ON
–	–	–	–	–	–	–	0	DRC1 turned OFF⁽¹⁾
–	–	–	–	–	–	–	1	DRC1 turned ON

(1) Default values are in **bold**.

10.6.2.20 Bank Switch and EQ Control Register (0x50)
表 23. Bank Switching Command Register (0x50)

D31	D30	D29	D28	D27	D26	D25	D24	FUNCTION
0	–	–	–	–	–	–	–	32 kHz, does not use bank 3⁽¹⁾
1	–	–	–	–	–	–	–	32 kHz, uses bank 3
–	0	–	–	–	–	–	–	Reserved⁽¹⁾
–	–	0	–	–	–	–	–	Reserved⁽¹⁾
–	–	–	0	–	–	–	–	44.1/48 kHz, does not use bank 3⁽¹⁾
–	–	–	1	–	–	–	–	44.1/48 kHz, uses bank 3
–	–	–	–	0	–	–	–	16 kHz, does not use bank 3
–	–	–	–	1	–	–	–	16 kHz, uses bank 3⁽¹⁾
–	–	–	–	–	0	–	–	22.025/24 kHz, does not use bank 3
–	–	–	–	–	1	–	–	22.025/24 kHz, uses bank 3⁽¹⁾
–	–	–	–	–	–	0	–	8 kHz, does not use bank 3
–	–	–	–	–	–	1	–	8 kHz, uses bank 3⁽¹⁾
–	–	–	–	–	–	–	0	11.025 kHz/12, does not use bank 3
–	–	–	–	–	–	–	1	11.025/12 kHz, uses bank 3⁽¹⁾
D23	D22	D21	D20	D19	D18	D17	D16	FUNCTION
0	–	–	–	–	–	–	–	32 kHz, does not use bank 2⁽¹⁾
1	–	–	–	–	–	–	–	32 kHz, uses bank 2
–	1	–	–	–	–	–	–	Reserved⁽¹⁾
–	–	1	–	–	–	–	–	Reserved⁽¹⁾
–	–	–	0	–	–	–	–	44.1/48 kHz, does not use bank 2
–	–	–	1	–	–	–	–	44.1/48 kHz, uses bank 2⁽¹⁾
–	–	–	–	0	–	–	–	16 kHz, does not use bank 2⁽¹⁾
–	–	–	–	1	–	–	–	16 kHz, uses bank 2
–	–	–	–	–	0	–	–	22.025/24 kHz, does not use bank 2⁽¹⁾
–	–	–	–	–	1	–	–	22.025/24 kHz, uses bank 2
–	–	–	–	–	–	0	–	8 kHz, does not use bank 2⁽¹⁾
–	–	–	–	–	–	1	–	8 kHz, uses bank 2
–	–	–	–	–	–	–	0	11.025/12 kHz, does not use bank 2⁽¹⁾
–	–	–	–	–	–	–	1	11.025/12 kHz, uses bank 2
D15	D14	D13	D12	D11	D10	D9	D8	FUNCTION
0	–	–	–	–	–	–	–	32 kHz, does not use bank 1
1	–	–	–	–	–	–	–	32 kHz, uses bank 1⁽¹⁾
–	0	–	–	–	–	–	–	Reserved⁽¹⁾
–	–	0	–	–	–	–	–	Reserved⁽¹⁾
–	–	–	0	–	–	–	–	44.1/48 kHz, does not use bank 1⁽¹⁾
–	–	–	1	–	–	–	–	44.1/48 kHz, uses bank 1
–	–	–	–	0	–	–	–	16 kHz, does not use bank 1⁽¹⁾
–	–	–	–	1	–	–	–	16 kHz, uses bank 1
–	–	–	–	–	0	–	–	22.025/24 kHz, does not use bank 1⁽¹⁾
–	–	–	–	–	1	–	–	22.025/24 kHz, uses bank 1
–	–	–	–	–	–	0	–	8 kHz, does not use bank 1⁽¹⁾
–	–	–	–	–	–	1	–	8 kHz, uses bank 1
–	–	–	–	–	–	–	0	11.025/12 kHz, does not use bank 1⁽¹⁾
–	–	–	–	–	–	–	1	11.025/12 kHz, uses bank 1

 (1) Default values are in **bold**.

表 23. Bank Switching Command Register (0x50) (continued)

D7	D6	D5	D4	D3	D2	D1	D0	FUNCTION
0								EQ ON
1	–	–	–	–	–	–	–	EQ OFF (bypass BQ 0-7 of channels 1 and 2)
–	0	–	–	–	–	–	–	Reserved ⁽¹⁾
–	–	0	–	–	–	–	–	Ignore bank-mapping in bits D31–D8. Use default mapping. ⁽¹⁾
		1						Use bank-mapping in bits D31–D8.
–	–	–	0	–	–	–	–	L and R can be written independently. ⁽¹⁾
–	–	–	1	–	–	–	–	L and R are ganged for EQ biquads; a write to left-channel BQ is also written to right-channel BQ. (0x29–0x2F is ganged to 0x30–0x36. Also 0x58–0x59 is ganged to 0x5C–0x5D)
–	–	–	–	0	–	–	–	Reserved ⁽¹⁾
–	–	–	–	–	0	0	0	No bank switching. All updates to DAP ⁽¹⁾
–	–	–	–	–	0	0	1	Configure bank 1 (32 kHz by default)
–	–	–	–	–	0	1	0	Configure bank 2 (44.1/48 kHz by default)
–	–	–	–	–	0	1	1	Configure bank 3 (other sample rates by default)
–	–	–	–	–	1	0	0	Automatic bank selection
–	–	–	–	–	1	0	1	Reserved
–	–	–	–	–	1	1	X	Reserved

11 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

11.1 Application Information

Figure 68, Figure 71, and Figure 72 highlight the required external components and system level connections for proper operation of the device in several popular use cases.

Each of these configurations can be realized using the Evaluation Modules (EVMS) for the device. These flexible modules allow full evaluation of the device in the most common modes of operation. Any design variation can be supported by TI through schematic and layout reviews. Visit <http://e2e.ti.com> for design assistance and join the audio amplifier discussion forum for additional information.

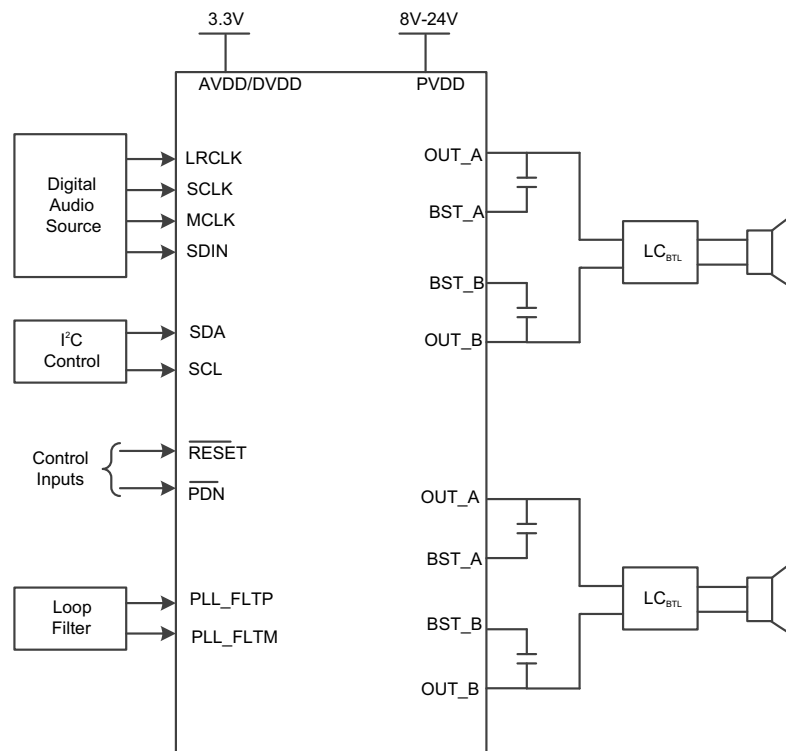
11.2 Typical Applications

11.2.1 Stereo Bridge Tied Load Application

A stereo system generally refers to a system in which there are two full range speakers without a separate amplifier path for the speakers that reproduce the low-frequency content. In this system, two channels are presented to the amplifier via the digital input signal. These two channels are amplified and then sent to two separate speakers.

Most commonly, the two channels are a pair of signals called a stereo pair, with one channel containing the audio for the left channel and the other channel containing the audio for the right channel.

The Stereo BTL Configuration with Headphone and Line Driver Amplifier application is shown in Figure 68.



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Figure 68. Stereo Bridge Tied Load Application

Typical Applications (continued)

11.2.1.1 Design Requirements

表 24. Design Requirements

PARAMETER	EXAMPLE
Low Power Supply	3.3 V
High Power Supply	8 V to 24 V
Host Processor	I ² S Compliant Master
	I ² C Compliant Master
	GPIO Control
Output Filters	Inductor-Capacitor Low Pass Filter
Speaker	4 Ω minimum

11.2.1.2 Detailed Design Procedure

11.2.1.2.1 Component Selection and Hardware Connections

The typical connections required for proper operation of the device can be found in the *TAS5755EVM User's Guide* ([SLOU481A](#)). The device was tested with this list of components; deviation from this list of typical application components, unless recommended by this document, may produce unwanted results, which could range from degradation of audio performance to destructive failure of the device.

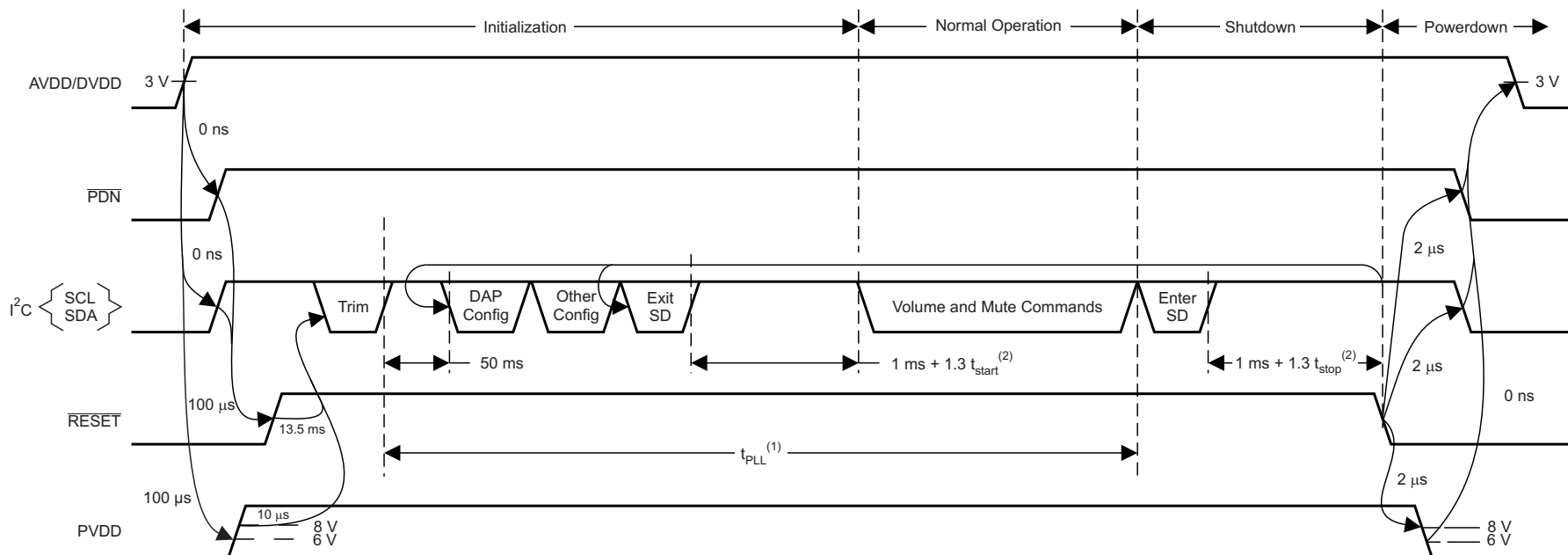
11.2.1.2.2 I²C Pullup Resistors

Customary pullup resistors are required on the SCL and SDA signal lines. They are not shown in the Typical Application Circuits, because they are shared by all of the devices on the I²C bus and are considered to be part of the associated passive components for the System Processor. These resistor values must be chosen per the guidance provided in the I²C Specification.

11.2.1.2.3 Digital I/O Connectivity

The digital I/O lines of the TAS5755M are described in previous sections. As discussed, whenever a static digital pin (that is a pin that is hardwired to be HIGH or LOW) is required to be pulled HIGH, it must be connected to DVDD through a pullup resistor to control the slew rate of the voltage presented to the digital I/O pins. It is not, however, necessary to have a separate pullup resistor for each static digital I/O line. Instead, a single resistor can be used to tie all static I/O lines HIGH to reduce BOM count.

11.2.1.2.4 Recommended Start-Up and Shutdown Procedures



(1) t_{PLL} has to be greater than $240 \text{ ms} + 1.3 t_{\text{start}}$.

This constraint only applies to the first trim command following AVDD/DVDD power-up.

It does not apply to trim commands following subsequent resets.

(2) $t_{\text{start}}/t_{\text{stop}}$ = PWM start/stop time as defined in register 0X1A

T0419-06

图 69. Recommended Command Sequence

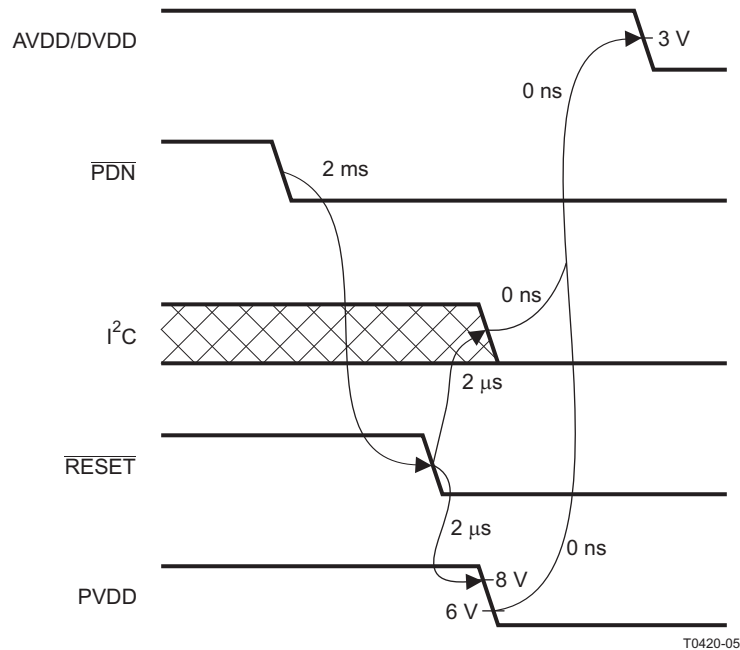


图 70. Power-Loss Sequence

11.2.1.2.4.1 Initialization Sequence

Use the following sequence to power up and initialize the device:

1. Hold all digital inputs low and ramp up AVDD/DVDD to at least 3 V.
2. Initialize digital inputs and PVDD supply as follows:
 - Drive $\overline{\text{RESET}} = 0$, $\overline{\text{PDN}} = 1$, and other digital inputs to their desired state while ensuring that all are never more than 2.5 V above AVDD/DVDD. Wait at least 100 μs , drive $\overline{\text{RESET}} = 1$, and wait at least another 13.5 ms.
 - Ramp up PVDD to at least 8 V while ensuring that it remains below 6 V for at least 100 μs after AVDD/DVDD reaches 3 V. Then wait at least another 10 μs .
3. Trim oscillator (write 0x00 to register 0x1B) and wait at least 50 ms.
4. Configure the DAP via I²C, see *TAS5755EVM Evaluation Module User's Guide* ([SLOU481A](#)) for typical values.
5. Configure remaining registers.
6. Exit shutdown (sequence defined in [Shutdown Sequence](#)).

11.2.1.2.4.2 Normal Operation

The following are the only events supported during normal operation:

1. Writes to master/channel volume registers
2. Writes to soft-mute register
3. Enter and exit shutdown (sequence defined in [Shutdown Sequence](#))

注

Event 3 is not supported for $240 \text{ ms} + 1.3 \times t_{\text{start}}$ after trim following AVDD/DVDD power-up ramp (where t_{start} is specified by register 0x1A).

11.2.1.2.4.3 Shutdown Sequence

Enter:

1. Write 0x40 to register 0x05.
2. Wait at least $1\text{ ms} + 1.3 \times t_{\text{stop}}$ (where t_{stop} is specified by register 0x1A).
3. If desired, reconfigure by returning to step 4 of initialization sequence.

Exit:

1. Write 0x00 to register 0x05 (exit shutdown command may not be serviced for as much as 240 ms after trim following AVDD/DVDD power-up ramp).
2. Wait at least $1\text{ ms} + 1.3 \times t_{\text{start}}$ (where t_{start} is specified by register 0x1A).
3. Proceed with normal operation.

11.2.1.2.4.4 Power-Down Sequence

Use the following sequence to power down the device and its supplies:

1. If time permits, enter shutdown (sequence defined in [Shutdown Sequence](#)); else, in case of sudden power loss, assert $\overline{\text{PDN}} = 0$ and wait at least 2 ms.
2. Assert $\overline{\text{RESET}} = 0$.
3. Drive digital inputs low and ramp down PVDD supply as follows:
 - Drive all digital inputs low after $\overline{\text{RESET}}$ has been low for at least 2 μs .
 - Ramp down PVDD while ensuring that it remains above 8 V until $\overline{\text{RESET}}$ has been low for at least 2 μs .
4. Ramp down AVDD/DVDD while ensuring that it remains above 3 V until PVDD is below 6 V and that it is never more than 2.5 V below the digital inputs.

11.2.1.3 Application Curves

表 25. Relevant Performance Curves

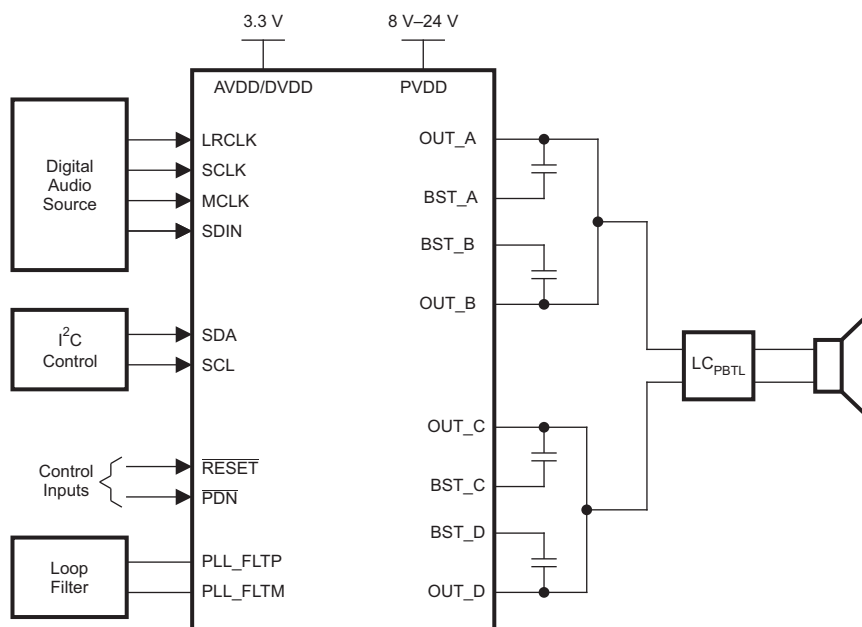
CURVE TITLE	FIGURE
Output Power vs Supply Voltage (2.0 BTL Mode) With 4 Ω Load on Typical 2 Layer PCB Device May Be Thermally Limited Above 20 V	图 18
Total Harmonic Distortion + Noise vs Output Power (2.0 BTL Mode)	图 19
Total Harmonic Distortion + Noise vs Output Power (2.0 BTL Mode)	图 20
Total Harmonic Distortion + Noise vs Output Power (2.0 BTL Mode)	图 21
Total Harmonic Distortion vs Frequency (2.0 BTL Mode)	图 22
Total Harmonic Distortion vs Frequency (2.0 BTL Mode)	图 23
Total Harmonic Distortion vs Frequency (2.0 BTL Mode)	图 24
Efficiency vs Output Power (2.0 BTL Mode)	图 25
Crosstalk vs Frequency (2.0 BTL Mode)	图 26
Crosstalk vs Frequency (2.0 BTL Mode)	图 27
Crosstalk vs Frequency (2.0 BTL Mode)	图 28
Crosstalk vs Frequency (2.0 BTL Mode)	图 29
Power vs Supply Voltage (2.0 BTL Mode)	图 30
Idle Channel Noise vs Supply Voltage (2.0 BTL Mode)	图 31

11.2.2 Mono Parallel Bridge Tied Load Application

A mono system refers to a system in which the amplifier is used to drive a single loudspeaker. Parallel Bridge Tied Load (PBTTL) indicates that the two full-bridge channels of the device are placed in parallel and drive the loudspeaker simultaneously using an identical audio signal. The primary benefit of operating the TAS5755M device in PBTTL operation is to reduce the power dissipation and increase the current sourcing capabilities of the amplifier output. In this mode of operation, the current limit of the audio amplifier is approximately doubled while the on-resistance is approximately halved.

The loudspeaker can be a full-range transducer or one that only reproduces the low-frequency content of an audio signal, as in the case of a powered subwoofer. Often in this use case, two stereo signals are mixed together and sent through a low-pass filter in order to create a single audio signal which contains the low frequency information of the two channels.

The Mono Parallel Bridge Tied Load application is shown in [Figure 71](#).



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Figure 71. Mono Parallel Bridge Tied Load Application

11.2.2.1 Design Requirements

表 26. Design Requirements

PARAMETER	EXAMPLE
Low Power Supply	3.3 V
High Power Supply	8 V to 24 V
Host Processor	I ² S Compliant Master
	I ² C Compliant Master
	GPIO Control
Output Filters	Inductor-Capacitor Low Pass Filter
Speaker	4 Ω minimum

11.2.2.2 Detailed Design Procedure

Refer to [Detailed Design Procedure](#) for information.

11.2.2.3 Application Curves

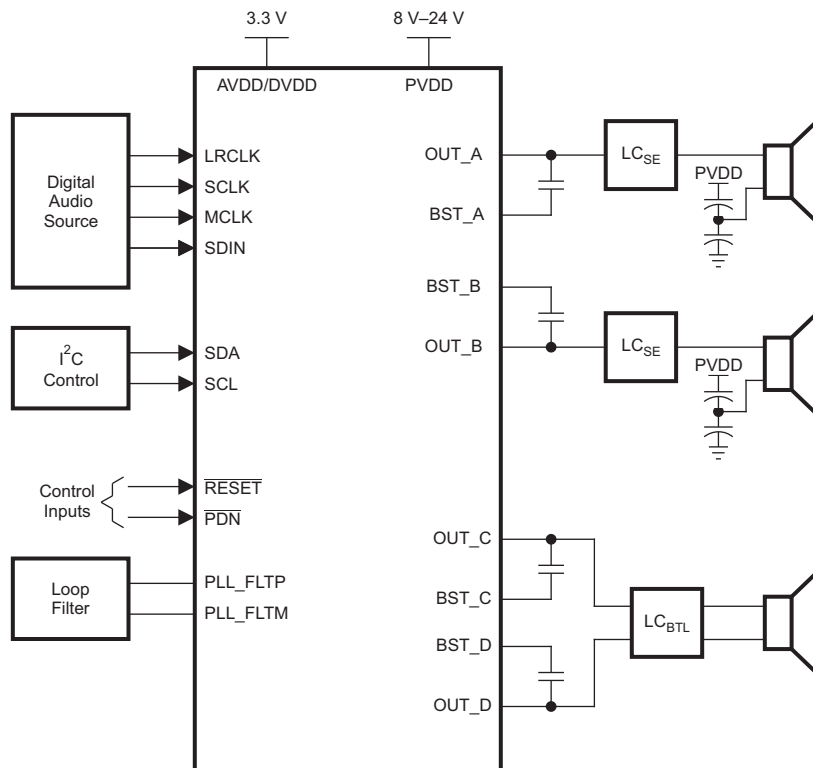
表 27. Relevant Performance Curves

CURVE TITLE	FIGURE
Output Power vs Supply Voltage (PBTL Mode) With 2Ω Load on Typical 2 Layer PCB, Device May Be Thermally Limited Above 20 V	Figure 32
Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)	Figure 33
Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)	Figure 34
Total Harmonic Distortion + Noise vs Output Power (PBTL Mode)	Figure 35
Total Harmonic Distortion vs Frequency (PBTL Mode)	Figure 36
Total Harmonic Distortion vs Frequency (PBTL Mode)	Figure 37
Total Harmonic Distortion vs Frequency (PBTL Mode)	Figure 38
Efficiency vs Output Power (PBTL Mode)	Figure 39
Efficiency vs Output Power (PBTL Mode)	Figure 40
Power vs Supply Voltage (PBTL Mode)	Figure 41
Idle Channel Noise vs Supply Voltage (PBTL Mode)	Figure 42

11.2.3 2.1 Application

A 2.1 system generally refers to a system in which there are two full range speakers with a separate amplifier path for the speakers which reproduce the low-frequency content. In this system, two channels are presented to the amplifier via the digital input signal, these are driven into two single-ended speakers and are mixed into a third channel, conditioned to stream low-frequency content into a differentially connected speaker.

The 2.1 application is shown in [Figure 72](#).



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Figure 72. Simplified 2.1 Application Diagram

11.2.3.1 Design Requirements

Table 28. Design Requirements

PARAMETER	EXAMPLE
Low Power Supply	3.3 V
High Power Supply	8 V to 24 V
Host Processor	I²S Compliant Master
	I²C Compliant Master
	GPIO Control
Output Filters	Inductor-Capacitor Low Pass Filter
Speaker	4 Ω (BTL), 2 Ω (SE) minimum

11.2.3.2 Detailed Design Procedure

Refer to [Detailed Design Procedure](#) for information.

11.2.3.3 Application Curves

表 29. Relevant Performance Curves

CURVE TITLE	FIGURE
Output Power vs Supply Voltage (2.1 SE Mode) With $2 \times 4\Omega + 4\Omega$ Load on Typical 2 Layer PCB Device May Be Thermally Limited Above 20 V	Figure 5
Total Harmonic Distortion + Noise vs Output Power (2.1 SE Mode)	Figure 6
Total Harmonic Distortion + Noise vs Output Power (2.1 SE Mode)	Figure 7
Total Harmonic Distortion + Noise vs Output Power (2.1 SE Mode)	Figure 8
Total Harmonic Distortion + Noise vs Frequency (2.1 SE Mode)	Figure 9
Total Harmonic Distortion + Noise vs Frequency (2.1 SE Mode)	Figure 10
Total Harmonic Distortion + Noise vs Frequency (2.1 SE Mode)	Figure 11
Efficiency vs Total Output Power (2.1 SE Mode)	Figure 12
Efficiency vs Total Output Power (2.1 SE Mode)	Figure 13
Crosstalk vs Frequency (2.1 SE Mode)	Figure 14
Crosstalk vs Frequency (2.1 SE Mode)	Figure 15
Crosstalk vs Frequency (2.1 SE Mode)	Figure 16
Crosstalk vs Frequency (2.1 SE Mode)	Figure 17

12 Power Supply Recommendations

The TAS5755M requires two power supplies; a low voltage 3.3 V nominal for the pins DVDD and AVDD and a high power supply, 8 V to 24 V for the pin PVDD. There is no requirement for power up sequencing of low and high power supplies, however is recommended to put the PDN pin to low before removing the low voltage power supplies in order to protect the outputs.

12.1 DVDD and AVDD Supplies

The AVDD Supply is used to power the analog internal circuit of the device, and needs a well regulated and filtered 3.3-V supply voltage. The DVDD Supply is used to power the digital circuitry. DVDD needs a well regulated and filtered 3.3-V supply voltage.

12.2 PVDD Power Supply

The TAS5755M class-D audio amplifier requires adequate power supply decoupling to ensure the output total harmonic distortion (THD) and noise is as low as possible. A good low equivalent-series-resistance (ESR) ceramic capacitor, typically 1 μ F, placed as close as possible to the device PVDD leads works best. For filtering lower frequency noise signals, a 10 μ F or greater capacitor placed near the audio power amplifier is recommended.

13 Layout

13.1 Layout Guidelines

Class-D switching edges are fast and switched currents are high so it is necessary to take care when planning the layout of the printed circuit board. The following suggestions will help to meet audio, thermal and EMC requirements.

- Decoupling capacitors: the high-frequency decoupling capacitors must be placed as close to the supply pins as possible; on the TAS5755M a 1- μ F high-quality ceramic capacitor is used. Large (10 μ F or greater) bulk power supply decoupling capacitors must be placed near the TAS5755M on the PVDD supplies.
- Keep the current loop from each of the outputs through the output inductor and the small filter cap and back to GND as small and tight as possible. The size of this current loop determines its effectiveness as an antenna.
- Grounding: A big common GND plane is recommended. The PVDD decoupling capacitors must connect to GND. The TAS5755M PowerPAD must be connected to GND.
- Output filter: remember to select inductors that can handle the high short circuit current of the device. The LC filter must be placed close to the outputs.

The EVM product folder ([TAS5755EVM](#)) and User's Guide ([SLOU481A](#)) available on www.ti.com show schematic, bill of material, gerber files, and more detailed layout plots.

13.2 Layout Examples

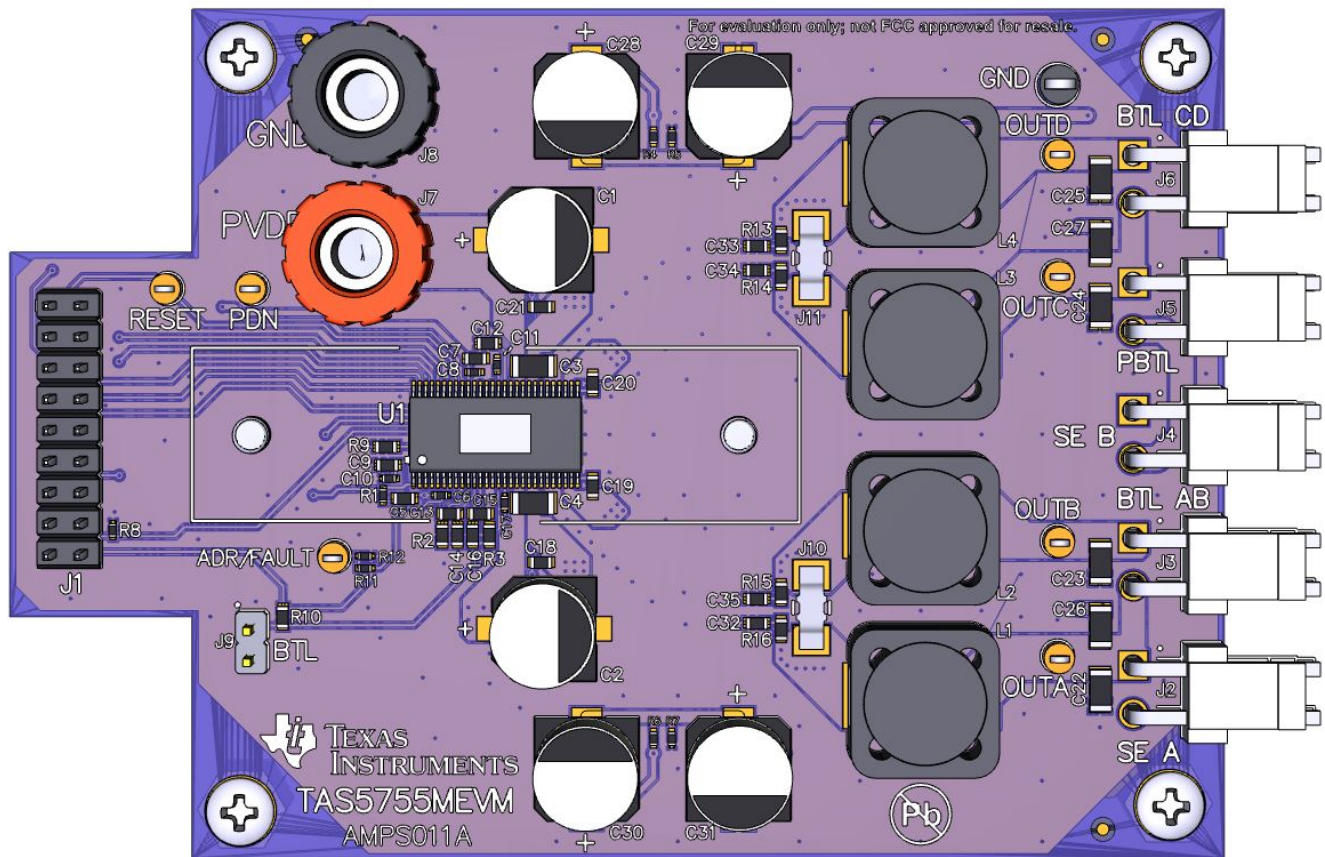


FIG 73. Top Layer Layout with Stereo BTL Mode

Layout Examples (continued)

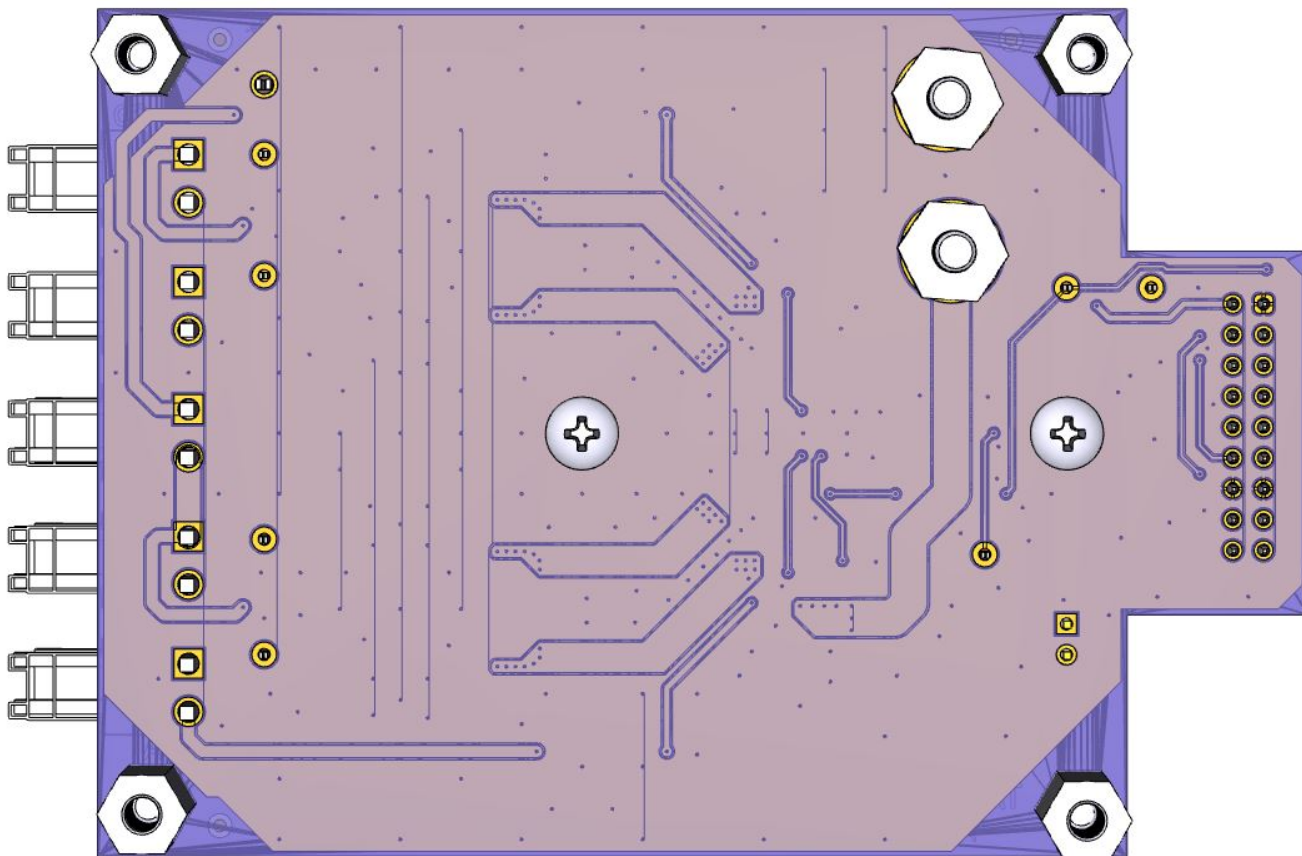


図 74. Bottom Layer Layout with Stereo BTL Mode

14 デバイスおよびドキュメントのサポート

14.1 デバイス・サポート

14.1.1 開発サポート

TAS570X GDEソフトウェア・セットアップ開発ツール・ドキュメント([SLOC124](#))

14.2 ドキュメントのサポート

EVM製品フォルダ([TAS5755MEVM](#))

14.2.1 関連資料

『TAS5755MEVMユーザー・ガイド』([SLOU481A](#))

14.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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14.5 Electrostatic Discharge Caution



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14.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TAS5755MDFD	Active	Production	HTSSOP (DFD) 56	35 TUBE	Yes	NIPDAU	Level-4-260C-72 HR	0 to 125	5755M
TAS5755MDFD.A	Active	Production	HTSSOP (DFD) 56	35 TUBE	Yes	NIPDAU	Level-4-260C-72 HR	0 to 125	5755M
TAS5755MDFDR	Active	Production	HTSSOP (DFD) 56	2000 LARGE T&R	Yes	NIPDAU	Level-4-260C-72 HR	0 to 125	5755M
TAS5755MDFDR.A	Active	Production	HTSSOP (DFD) 56	2000 LARGE T&R	Yes	NIPDAU	Level-4-260C-72 HR	0 to 125	5755M

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

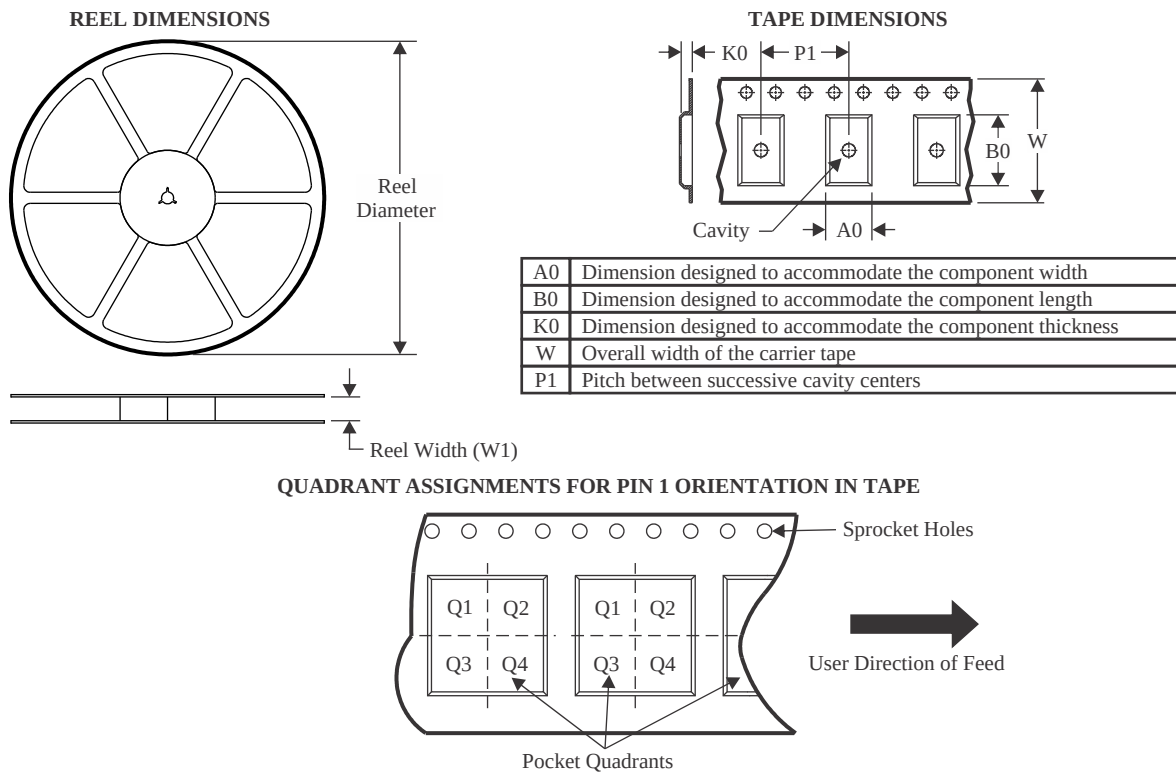
⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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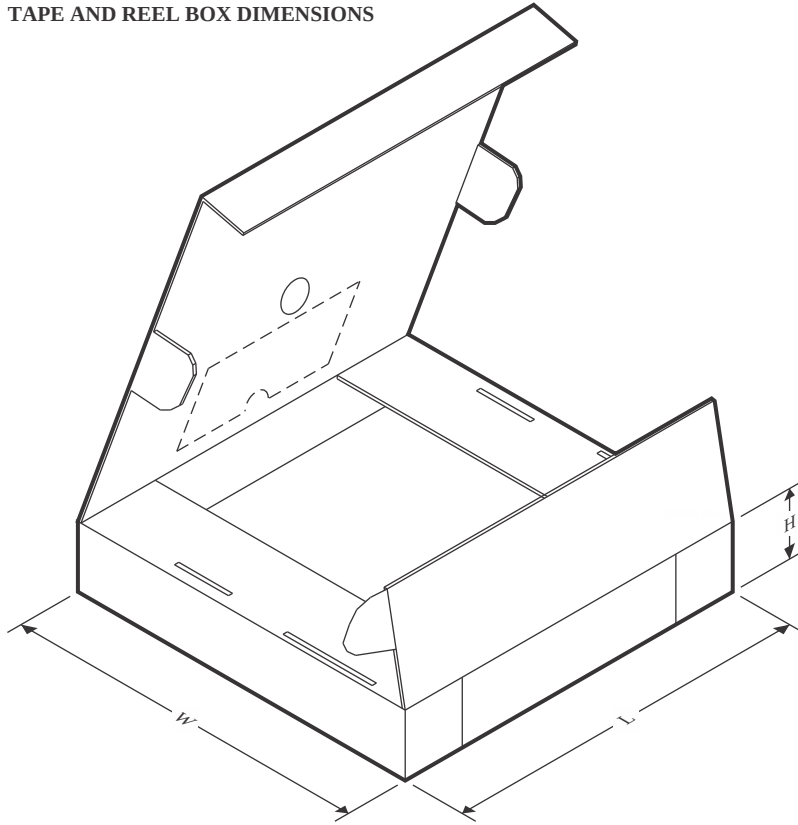
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TAS5755MDFDR	HTSSOP	DFD	56	2000	330.0	24.4	8.6	15.6	1.8	12.0	24.0	Q1

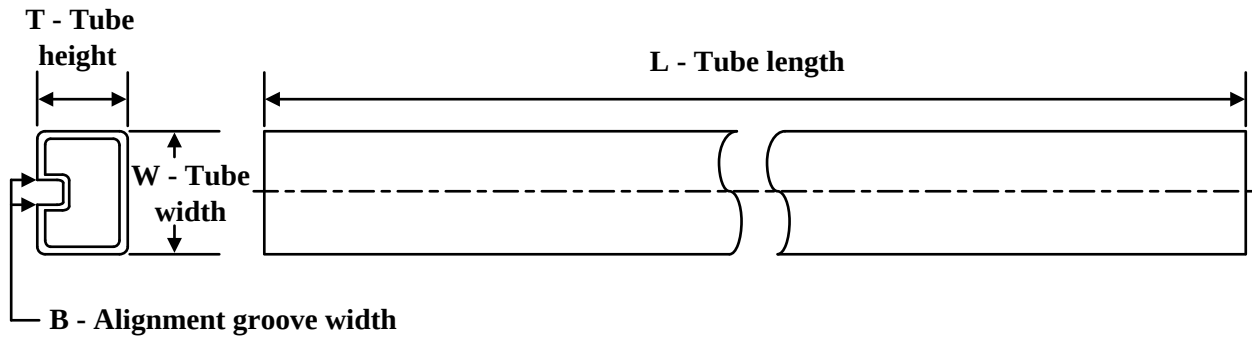
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TAS5755MDFDR	HTSSOP	DFD	56	2000	350.0	350.0	43.0

TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TAS5755MDFD	DFD	HTSSOP	56	35	530	11.89	3600	4.9
TAS5755MDFD.A	DFD	HTSSOP	56	35	530	11.89	3600	4.9

GENERIC PACKAGE VIEW

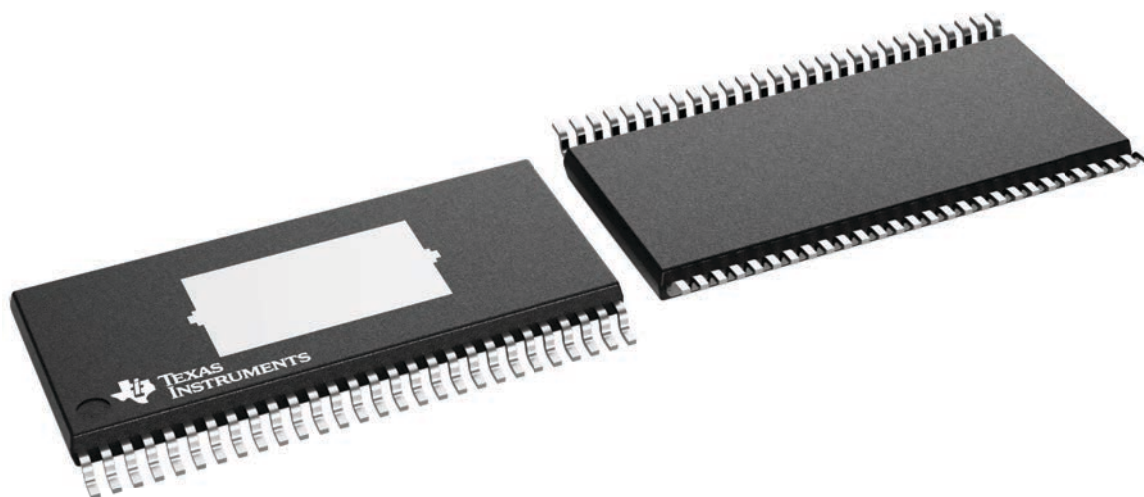
DFD 56

PowerPAD TSSOP - 1.2 mm max height

6.1 x 14, 0.5 mm pitch

PLASTIC SMALL OUTLINE

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

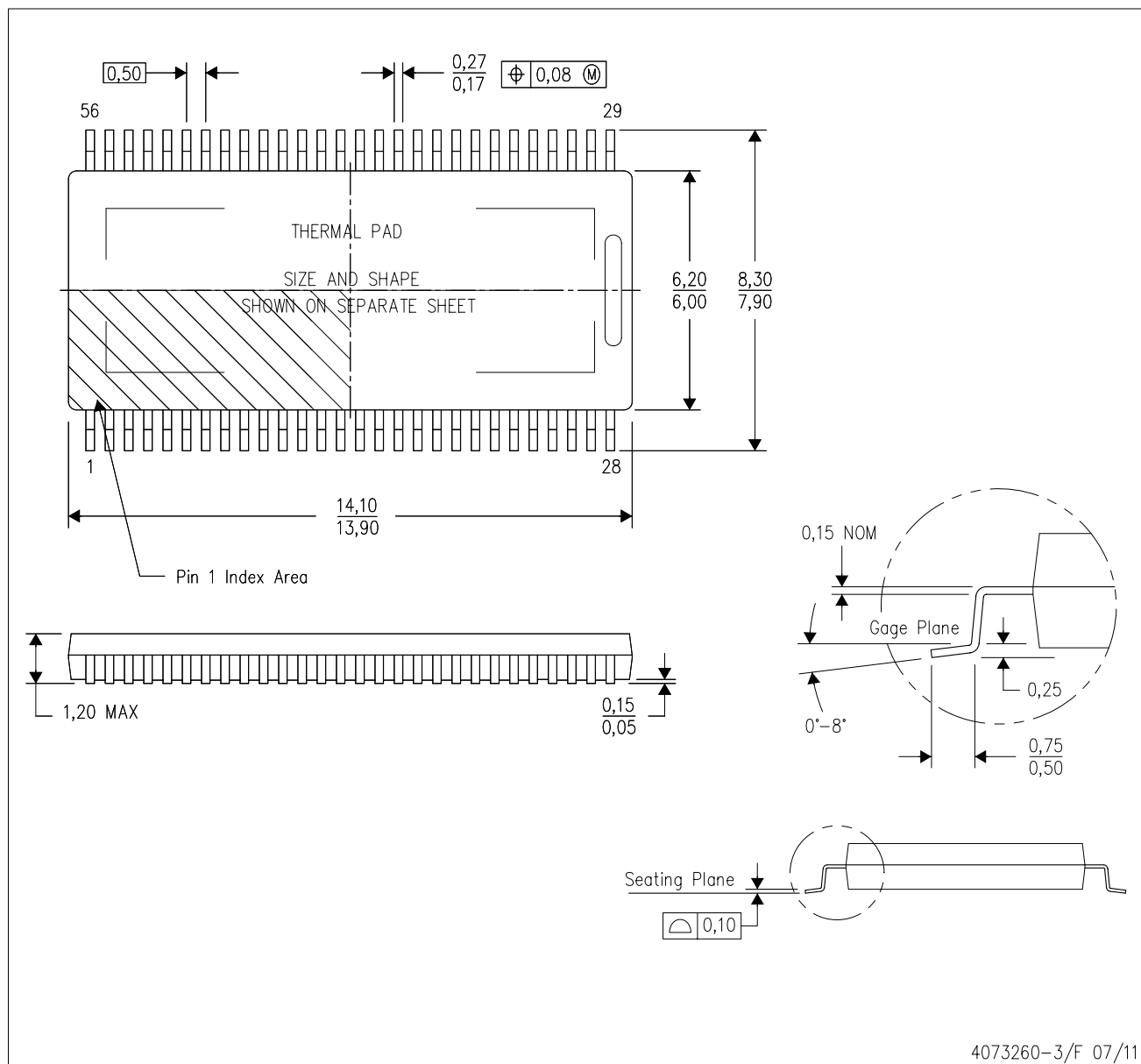


4230655/A

MECHANICAL DATA

DFD (R-PDSO-G56)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE (DIE DOWN)



- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - This drawing is subject to change without notice.
 - Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <<http://www.ti.com>>.
 - See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
 - Falls within JEDEC MO-153

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THERMAL PAD MECHANICAL DATA

DFD (R-PDSO-G56)

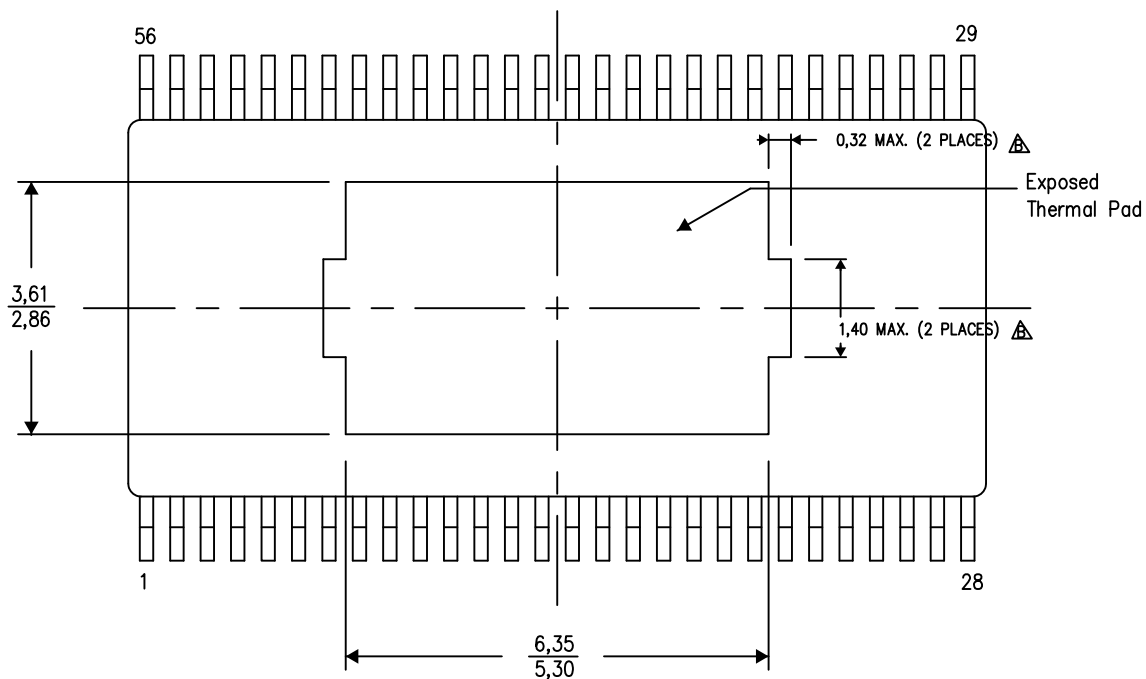
PowerPAD™ PLASTIC SMALL OUTLINE

THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



4210501-4/G 07/12

NOTES: A. All linear dimensions are in millimeters



Keep-out features are identified to prevent board routing interference.

These exposed metal features may vary within the identified area or completely absent on some devices.

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