

TPA3245 115Wステレオ、230Wモノラル、PurePath™ Ultra HDアナログ入力Class-Dアンプ

1 特長

- 差動アナログ入力
- 10%THD+N時の総出力電力
 - BTL構成で4Ω〜115W (ステレオ)
 - BTL構成で3Ω〜145W (ステレオ)
 - PBTL構成で2Ω〜230W (モノラル)
- 1%THD+N時の総出力電力
 - BTL構成で4Ω〜95W (ステレオ)
 - BTL構成で3Ω〜115W (ステレオ)
 - PBTL構成で2Ω〜185W (モノラル)
- 高度な統合フィードバック設計と、高速なゲート・ドライバ・エラー訂正 (PurePath™ Ultra-HD)
 - 最高100kHzの信号帯域幅によりHDソースからの高周波数のコンテンツに対応
 - 非常に低いTHD+N: 4Ω〜1Wで0.005%、クリッピングへ0.01%未満
 - 65dB PSRR (BTL、入力信号なし)
 - 出力ノイズ50μV未満(Aウェイト)
 - SNR 112dB超(Aウェイト)
- 複数の構成が可能:
 - ステレオ、モノラル、2.1、4xSE
- 開始時と停止時にクリック音やポップ音が発生しない
- 90%効率のClass-D動作(4Ω)
- 12V〜30Vの広い電源電圧範囲での動作
- 自己保護設計(低電圧、過熱、クリッピング、短絡保護を含む)とエラー報告機能
- 推奨システム設計で使用時にEMI準拠

2 アプリケーション

- Blu-ray Disc™/ DVDレシーバ
- ハイエンドTVセット
- ハイエンド・サウンドバー
- ミニ・コンボ・システム
- アクティブ・スピーカーおよびサブウーファー

3 概要

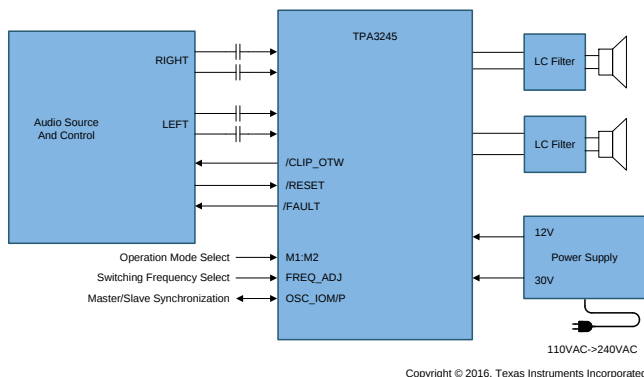
TPA3245は高性能のClass-Dパワー・アンプで、最高のサウンド品質をClass-Dの効率で実現します。高度な統合フィードバック設計と、独自の高速ゲート・ドライバ・エラー訂正機能(PurePath™ Ultra-HD)があります。このテクノロジーにより、音声帯域全体にわたる歪みが非常に低い、優れたオーディオ品質を実現しています。このデバイスはADモードで動作し、4Ω負荷へ最大2×115W、3Ω負荷へ最大2×145Wを駆動でき、2つのVRMSアナログ入力・インターフェイスが搭載されており、TIのPCM5242などの高性能DACとシームレスに動作します。優れたオーディオ性能に加えて、TPA3245は高い出力効率を達成し、電力段でのアイドル損失が0.45W未満と非常に低くなっています。これらは、65mΩ MOSFETの使用と、最適化されたゲート・ドライバ方式で、一般的なディスクリート実装よりも大幅に低いアイドル損失を実現することにより達成されています。

製品情報⁽¹⁾

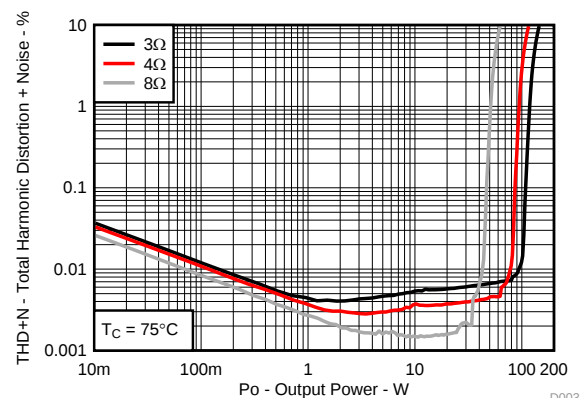
型番	パッケージ	本体サイズ(公称)
TPA3245	HTSSOP (44)	6.10mm×14.00mm

(1) 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。

概略回路図



全高調波歪み



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4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

2016年4月発行のものから更新

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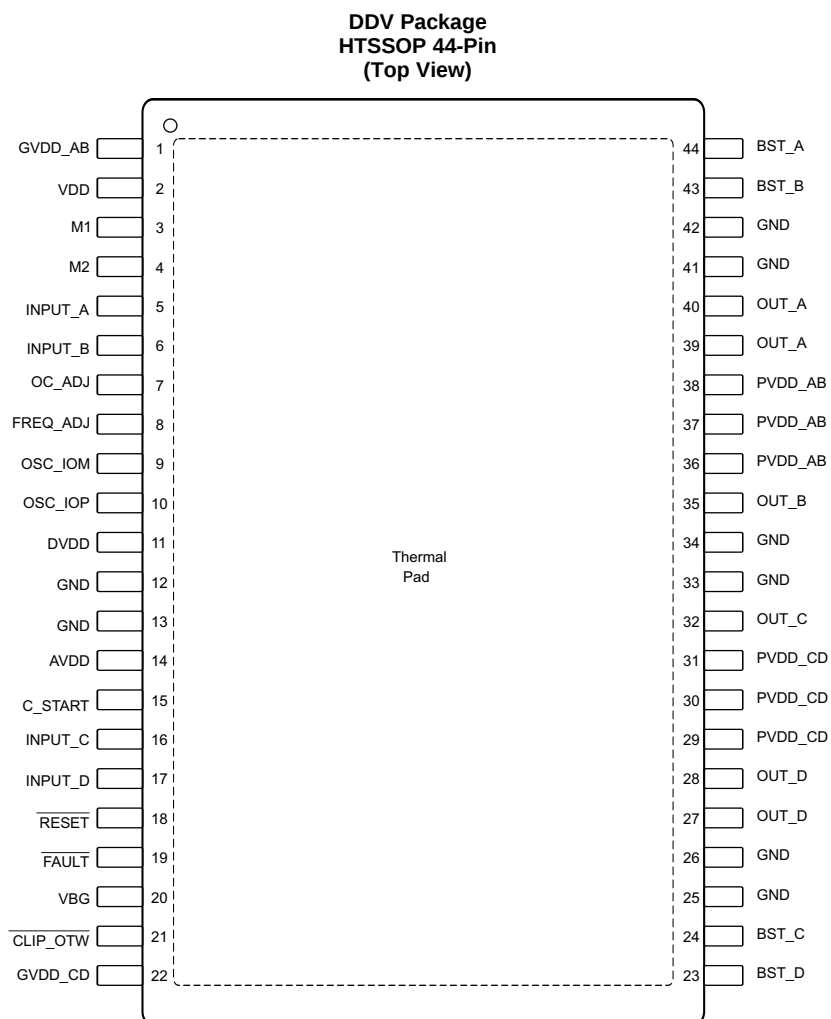
5 Device Comparison Table

DEVICE NAME	DESCRIPTION
TPA3244	40-W Stereo, 100-W peak PurePath™ Ultra-HD Pad Down Class-D Amplifier
TPA3250	70-W Stereo, 130-W peak PurePath™ Ultra-HD Pad Down Class-D Amplifier
TPA3251	175-W Stereo, 350-W Mono PurePath™ Ultra-HD Analog-Input Class-D Amplifier
TPA3255	315-W Stereo, 600-W Mono PurePath™ Ultra-HD Analog-Input Class-D Amplifier

6 Pin Configuration and Functions

The TPA3245 is available in a thermally enhanced TSSOP package.

The package type contains a PowerPAD™ that is located on the top side of the device for convenient thermal coupling to the heat sink.



Pin Functions

NAME	NO.	I/O	DESCRIPTION
AVDD	14	P	Internal voltage regulator, analog section
BST_A	44	P	HS bootstrap supply (BST), external 0.033 μ F capacitor to OUT_A required.
BST_B	43	P	HS bootstrap supply (BST), external 0.033 μ F capacitor to OUT_B required.
BST_C	24	P	HS bootstrap supply (BST), external 0.033 μ F capacitor to OUT_C required.
BST_D	23	P	HS bootstrap supply (BST), external 0.033 μ F capacitor to OUT_D required.
CLIP_OTW	21	O	Clipping warning and Over-temperature warning; open drain; active low. Do not connect if not used.
C_START	15	O	Startup ramp, requires a charging capacitor to GND
DVDD	11	P	Internal voltage regulator, digital section
FAULT	19	O	Shutdown signal, open drain; active low. Do not connect if not used.
FREQ_ADJ	8	O	Oscillator frequency programming pin
GND	12, 13, 25, 26, 33, 34, 41, 42	P	Ground
GVDD_AB	1	P	Gate-drive voltage supply; AB-side, requires 0.1 μ F capacitor to GND
GVDD_CD	22	P	Gate-drive voltage supply; CD-side, requires 0.1 μ F capacitor to GND
INPUT_A	5	I	Input signal for half bridge A
INPUT_B	6	I	Input signal for half bridge B
INPUT_C	16	I	Input signal for half bridge C
INPUT_D	17	I	Input signal for half bridge D
M1	3	I	Mode selection 1 (LSB)
M2	4	I	Mode selection 2 (MSB)
OC_ADJ	7	I/O	Over-Current threshold programming pin
OSC_IOM	9	I/O	Oscillator synchronization interface. Do not connect if not used.
OSC_IOP	10	O	Oscillator synchronization interface. Do not connect if not used.
OUT_A	39, 40	O	Output, half bridge A
OUT_B	35	O	Output, half bridge B
OUT_C	32	O	Output, half bridge C
OUT_D	27, 28	O	Output, half bridge D
PVDD_AB	36, 37, 38	P	PVDD supply for half-bridge A and B
PVDD_CD	29, 30, 31	P	PVDD supply for half-bridge C and D
RESET	18	I	Device reset Input; active low
VDD	2	P	Power supply for internal voltage regulator requires a 10- μ F capacitor with a 0.1- μ F capacitor to GND for decoupling.
VBG	20	P	Internal voltage reference requires a 0.1- μ F capacitor to GND for decoupling.
PowerPad™		P	Ground, connect to grounded heat sink

Table 1. Mode Selection Pins

MODE PINS		INPUT MODE	OUTPUT CONFIGURATION	DESCRIPTION
M2	M1			
0	0	2N + 1	2 $\times$ BTL	Stereo BTL output configuration
0	1	2N/1N + 1	1 $\times$ BTL + 2 $\times$ SE	2.1 BTL + SE mode. Channel AB: BTL, channel C + D: SE
1	0	2N + 1	1 $\times$ PBTL	Paralleled BTL configuration. Connect INPUT_C and INPUT_D to GND.
1	1	1N + 1	4 $\times$ SE	Single ended output configuration

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Supply voltage	BST_X to GVDD_X ⁽²⁾	−0.3	43	V
	VDD to GND	−0.3	13.2	V
	GVDD_X to GND ⁽²⁾	−0.3	13.2	V
	PVDD_X to GND ⁽²⁾	−0.3	43	V
	DVDD to GND	−0.3	4.2	V
	AVDD to GND	−0.3	8.5	V
	VBG to GND	−0.3	4.2	V
Interface pins	OUT_X to GND ⁽²⁾	−0.3	43	V
	BST_X to GND ⁽²⁾	−0.3	55.5	V
	OC_ADJ, M1, M2, OSC_IOP, OSC_IOM, FREQ_ADJ, C_START, to GND	−0.3	4.2	V
	RESET, FAULT, CLIP_OTW to GND	−0.3	4.2	V
	INPUT_X to GND	−0.3	7	V
	Continuous sink current, RESET, FAULT, CLIP_OTW to GND		9	mA
T _J	Operating junction temperature range	0	150	°C
T _{stg}	Storage temperature range	−40	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) These voltages represents the DC voltage + peak AC waveform measured at the terminal of the device in all conditions.

7.2 ESD Ratings

			VALUE	UNIT
V _{ESD}	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±1000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	±250	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	TYP	MAX	UNIT
PVDD_x	Half-bridge supply	DC supply voltage	12	30	31.5	V
GVDD_x	Supply for logic regulators and gate-drive circuitry	DC supply voltage	10.8	12	13.2	V
VDD	Digital regulator supply voltage	DC supply voltage	10.8	12	13.2	V
R _L (BTL)	Load impedance	Output filter inductance within recommended value range	2.7	4		Ω
R _L (SE)			1.5	3		
R _L (PBTL)			1.6	2		
L _{OUT} (BTL)	Output filter inductance	Minimum output inductance at I _{OC}	5			μH
L _{OUT} (SE)			5			
L _{OUT} (PBTL)			5			
F _{PWM}	PWM frame rate selectable for AM interference avoidance; 1% Resistor tolerance	Nominal	575	600	625	kHz
		AM1	475	500	525	
		AM2	430	450	470	
R _(FREQ_ADJ)	PWM frame rate programming resistor	Nominal; Master mode	9.9	10	10.1	kΩ
		AM1; Master mode	19.8	20	20.2	
		AM2; Master mode	29.7	30	30.3	
C _{PVDD}	PVDD close decoupling capacitors		1.0			μF
R _{OC}	Over-current programming resistor	Resistor tolerance = 5%	22		30	kΩ
R _{OC} (LATCHED)	Over-current programming resistor	Resistor tolerance = 5%	47		64	kΩ
V _(FREQ_ADJ)	Voltage on FREQ_ADJ pin for slave mode operation	Slave mode	3.3			V
T _J	Junction temperature		0		125	°C

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPA3251D2	UNIT
		DDV 44-PINS HTSSOP	
		FIXED 85°C HEATSINK TEMPERATURE ⁽²⁾	
R _{θJA}	Junction-to-ambient thermal resistance	2.8 ⁽²⁾	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	0.5	
R _{θJB}	Junction-to-board thermal resistance	n/a	
ψ _{JT}	Junction-to-top characterization parameter	0.9	
ψ _{JB}	Junction-to-board characterization parameter	n/a	
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	n/a	

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
- (2) Thermal data are obtained with 85°C heat sink temperature using thermal compound with 0.7W/mK thermal conductivity and 2mil thickness. In this model heat sink temperature is considered to be the ambient temperature and only path for dissipation is to the heatsink.

7.5 Electrical Characteristics

PVDD_X = 30 V, GVDD_X = 12 V, VDD = 12 V, T_C (Case temperature) = 75°C, f_S = 600 kHz, unless otherwise specified.

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
INTERNAL VOLTAGE REGULATOR AND CURRENT CONSUMPTION							
DVDD	Voltage regulator, only used as reference node	VDD = 12 V		3.3			V
AVDD	Voltage regulator, only used as reference node	VDD = 12 V		7.8			V
I _{VDD}	VDD supply current	Operating, 50% duty cycle		40			mA
		Idle, reset mode		10			
I _{GVDD_X}	Gate-supply current per full-bridge	50% duty cycle		19			mA
		Reset mode		2.5			
I _{PVDD_X}	PVDD idle current per full bridge	50% duty cycle with recommended output filter		15			mA
		Reset mode, No switching		1.1			mA
ANALOG INPUTS							
R _{IN}	Input resistance			24			kΩ
V _{IN}	Maximum input voltage swing					7	V
I _{IN}	Maximum input current					1	mA
G	Inverting voltage Gain	V _{OUT} /V _{IN}		18			dB
OSCILLATOR							
f _{OSC(IO+)} ⁽¹⁾	Nominal, Master Mode	F _{PWM} × 6		3.45	3.6	3.75	MHz
	AM1, Master Mode			2.85	3	3.15	
	AM2, Master Mode			2.58	2.7	2.82	
V _{IH}	High level input voltage			1.86			V
V _{IL}	Low level input voltage					1.45	V
OUTPUT-STAGE MOSFETS							
R _{DS(on)}	Drain-to-source resistance, low side (LS)	T _J = 25°C, Includes metallization resistance, GVDD = 12 V		65			mΩ
	Drain-to-source resistance, high side (HS)			65			mΩ
I/O PROTECTION							
V _{uvp,VDD,GVDD}	Undervoltage protection limit, GVDD_x and VDD			8.6			V
V _{uvp,VDD, GVDD,hyst} ⁽²⁾				0.85			V
V _{uvp,PVDD}	Undervoltage protection limit, PVDD_x			9.7			V
V _{uvp,PVDD,hyst} ⁽²⁾				1.25			V
OTW	Overtemperature warning, $\overline{\text{CLIP_OTW}}$ ⁽²⁾			115	125	135	°C
OTW _{hyst} ⁽²⁾	Temperature drop needed below OTW temperature for $\overline{\text{CLIP_OTW}}$ to be inactive after OTW event.			20			°C
OTE ⁽²⁾	Overtemperature error			145	155	165	°C
OTE _{hyst} ⁽²⁾	A reset needs to occur for $\overline{\text{FAULT}}$ to be released following an OTE event			20			°C
OTE-OTW ₍₂₎ ^(differential)	OTE-OTW differential			30			°C
OLPC	Overload protection counter	f _{PWM} = 600 kHz (1024 PWM cycles)		1.7			ms
I _{OC}	Overcurrent limit protection	Resistor – programmable, nominal peak current in 1Ω load, R _{OCp} = 22 kΩ		13.5			A
I _{OC(LATCHED)}	Overcurrent limit protection	Resistor – programmable, peak current in 1Ω load, R _{OCp} = 47kΩ		13.5			A
I _{DCspkr}	DC Speaker Protection Current Threshold	BTL current imbalance threshold		2			A
I _{OCT}	Overcurrent response time	Time from switching transition to flip-state induced by overcurrent.		150			ns
I _{PD}	Output pulldown current of each half	Connected when $\overline{\text{RESET}}$ is active to provide bootstrap charge. Not used in SE mode.		3			mA

(1) Nominal, AM1 and AM2 use same internal oscillator with fixed ratio 6 : 5 : 4.5

(2) Specified by design.

Electrical Characteristics (continued)

PVDD_X = 30 V, GVDD_X = 12 V, VDD = 12 V, T_C (Case temperature) = 75°C, f_S = 600 kHz, unless otherwise specified.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
STATIC DIGITAL SPECIFICATIONS						
V _{IH}	High level input voltage	M1, M2, OSC_IOP, OSC_IOM, RESET	1.9		0.8	V
V _{IL}	Low level input voltage					V
I _{ikg}	Input leakage current				100	μA
OTW/SHUTDOWN (FAULT)						
R _{INT_PU}	Internal pullup resistance, CLIP_OTW to DVDD, FAULT to DVDD		20	26	32	kΩ
V _{OH}	High level output voltage	Internal pullup resistor	3	3.3	3.6	V
V _{OL}	Low level output voltage	I _O = 4 mA		200	500	mV
Device fanout	CLIP_OTW, FAULT	No external pullup		30		devices

7.6 Audio Characteristics (BTL)

PCB and system configuration are in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, R_L = 4 Ω, f_S = 600 kHz, R_{OC} = 22 kΩ, T_C = 75°C, Output Filter: L_{DEM} = 10 μH, C_{DEM} = 1 μF, mode = 00, AES17 + AUX-0025 measurement filters, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P _O	Power output per channel	R _L = 3 Ω, 10% THD+N		145		W
		R _L = 4 Ω, 10% THD+N		115		
		R _L = 3 Ω, 1% THD+N		115		
		R _L = 4 Ω, 1% THD+N		95		
THD+N	Total harmonic distortion + noise	1 W		0.005%		
V _n	Output integrated noise	A-weighted, AES17 filter, Input Capacitor Grounded		50		μV
V _{OS}	Output offset voltage	Inputs AC coupled to GND		20	60	mV
SNR	Signal-to-noise ratio ⁽¹⁾			112		dB
DNR	Dynamic range			113		dB
P _{idle}	Power dissipation due to Idle losses (I _{PVDD_X})	P _O = 0, 4 channels switching ⁽²⁾		0.45		W

(1) SNR is calculated relative to 1% THD+N output level.

(2) Actual system idle losses also are affected by core losses of output inductors.

7.7 Audio Characteristics (SE)

PCB and system configuration are in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, $R_L = 2\ \Omega$, $f_s = 600\ \text{kHz}$, $R_{OC} = 22\ \text{k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 15\ \mu\text{H}$, $C_{DEM} = 680\ \text{nF}$, MODE = 11, AES17 + AUX-0025 measurement filters, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P_O	Power output per channel	$R_L = 2\ \Omega$, 10% THD+N		55		W
		$R_L = 3\ \Omega$, 10% THD+N		39		
		$R_L = 4\ \Omega$, 10% THD+N		30		
		$R_L = 2\ \Omega$, 1% THD+N		44		
		$R_L = 3\ \Omega$, 1% THD+N		32		
		$R_L = 4\ \Omega$, 1% THD+N		25		
THD+N	Total harmonic distortion + noise	1 W		0.01%		
V_n	Output integrated noise	A-weighted, AES17 filter, Input Capacitor Grounded		100		μV
SNR	Signal to noise ratio ⁽¹⁾	A-weighted		106		dB
DNR	Dynamic range	A-weighted		101		dB
P_{idle}	Power dissipation due to idle losses (IPVDD_X)	$P_O = 0$, 4 channels switching ⁽²⁾		0.45		W

(1) SNR is calculated relative to 1% THD+N output level.

(2) Actual system idle losses are affected by core losses of output inductors.

7.8 Audio Characteristics (PBTl)

PCB and system configuration are in accordance with recommended guidelines. Audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, $R_L = 2\ \Omega$, $f_s = 600\ \text{kHz}$, $R_{OC} = 22\ \text{k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, MODE = 10, outputs paralleled before LC filter, AES17 + AUX-0025 measurement filters, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P_O	Power output per channel	$R_L = 2\ \Omega$, 10% THD+N		230		W
		$R_L = 3\ \Omega$, 10% THD+N		160		
		$R_L = 4\ \Omega$, 10% THD+N		125		
		$R_L = 2\ \Omega$, 1% THD+N		185		
		$R_L = 3\ \Omega$, 1% THD+N		130		
		$R_L = 4\ \Omega$, 1% THD+N		100		
THD+N	Total harmonic distortion + noise	1 W		0.005%		
V_n	Output integrated noise	A-weighted, AES17 filter, Input Capacitor Grounded		45		μV
SNR	Signal to noise ratio ⁽¹⁾	A-weighted		113		dB
DNR	Dynamic range	A-weighted		113		dB
P_{idle}	Power dissipation due to idle losses (IPVDD_X)	$P_O = 0$, 4 channels switching ⁽²⁾		0.45		W

(1) SNR is calculated relative to 1% THD+N output level.

(2) Actual system idle losses are affected by core losses of output inductors.

7.9 Typical Characteristics, BTL Configuration

All Measurements taken at audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 600\text{ kHz}$, $R_{OC} = 22\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, mode = 00, AES17 + AUX-0025 measurement filters, unless otherwise noted.

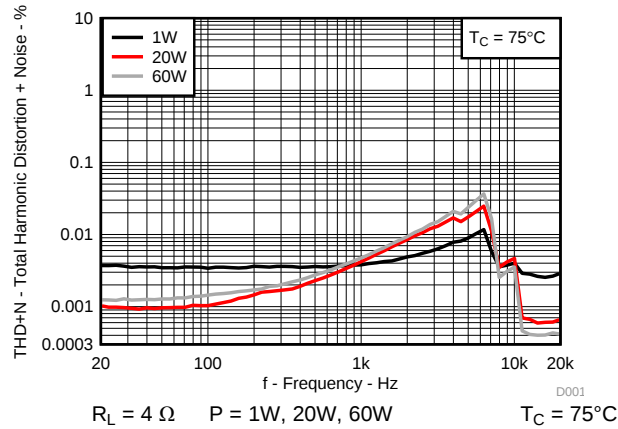
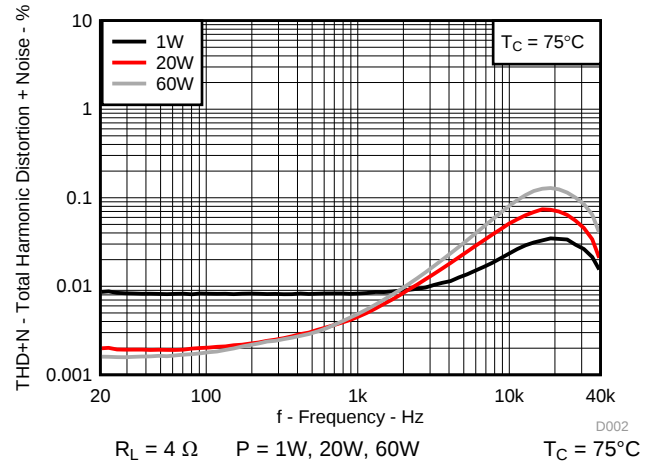


Figure 1. Total Harmonic Distortion+Noise vs Frequency



AUX-0025 filter, 80 kHz analyzer BW

Figure 2. Total Harmonic Distortion+Noise vs Frequency

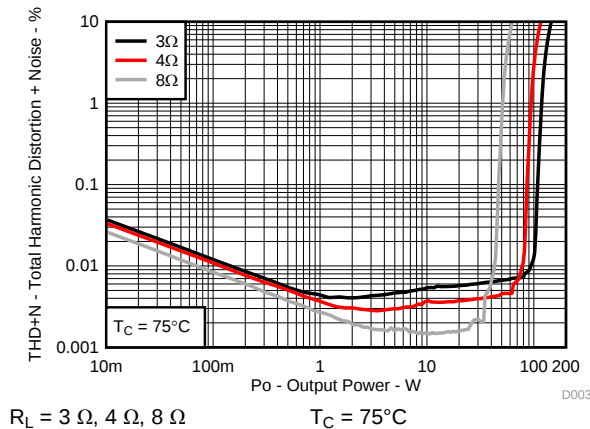


Figure 3. Total Harmonic Distortion + Noise vs Output Power

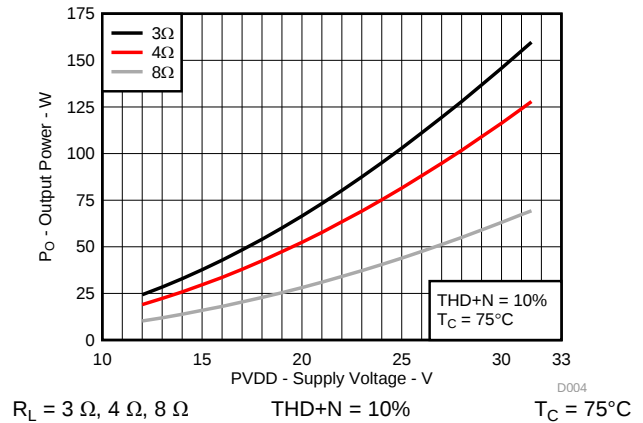


Figure 4. Output Power vs Supply Voltage

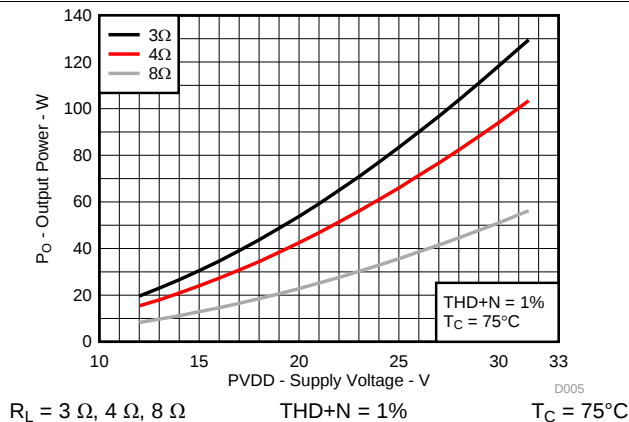


Figure 5. Output Power vs Supply Voltage

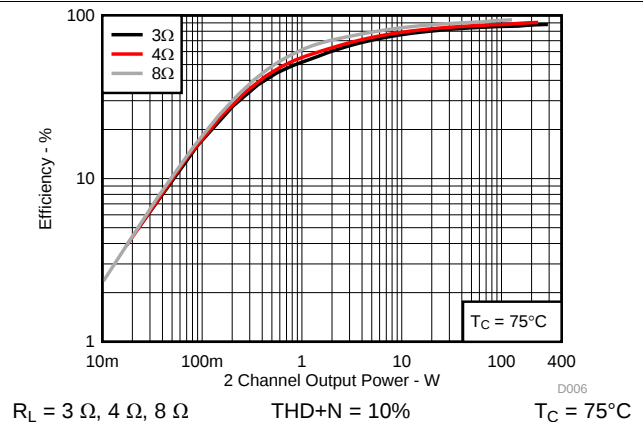


Figure 6. System Efficiency vs Output Power

Typical Characteristics, BTL Configuration (continued)

All Measurements taken at audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, $R_L = 4\ \Omega$, $f_s = 600\text{ kHz}$, $R_{OC} = 22\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\ \mu\text{H}$, $C_{DEM} = 1\ \mu\text{F}$, mode = 00, AES17 + AUX-0025 measurement filters, unless otherwise noted.

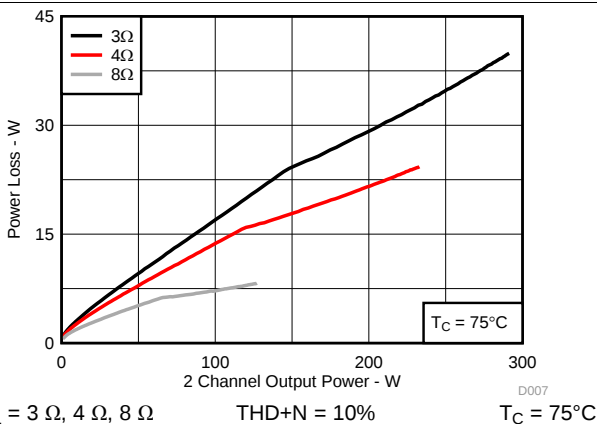


Figure 7. System Power Loss vs Output Power

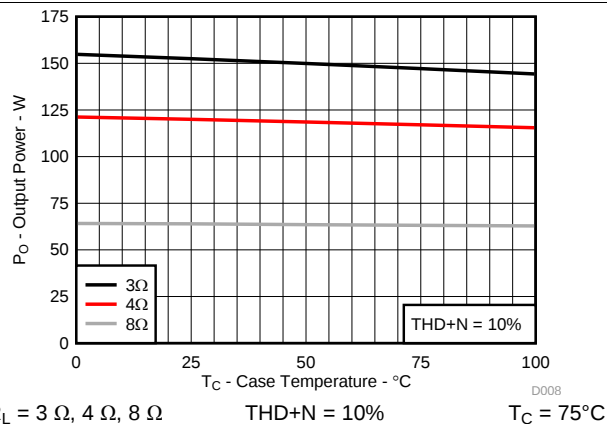
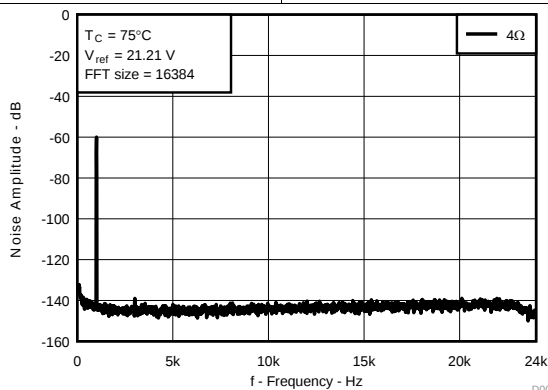


Figure 8. Output Power vs Case Temperature



4 Ω , $V_{REF} = 21.21\text{ V}$ (1% Output power)
AUX-0025 filter, 80 kHz analyzer BW
FFT = 16384
 $T_C = 75^\circ\text{C}$

Figure 9. Noise Amplitude vs Frequency

7.10 Typical Characteristics, SE Configuration

All Measurements taken at audio frequency = 1 kHz, PVDD_X = 30 V, GVDD_X = 12 V, $R_L = 3\ \Omega$, $f_s = 600\ \text{kHz}$, $R_{OC} = 22\ \text{k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 15\ \mu\text{H}$, $C_{DEM} = 680\ \text{nF}$, MODE = 11, AES17 + AUX-0025 measurement filters, unless otherwise noted.

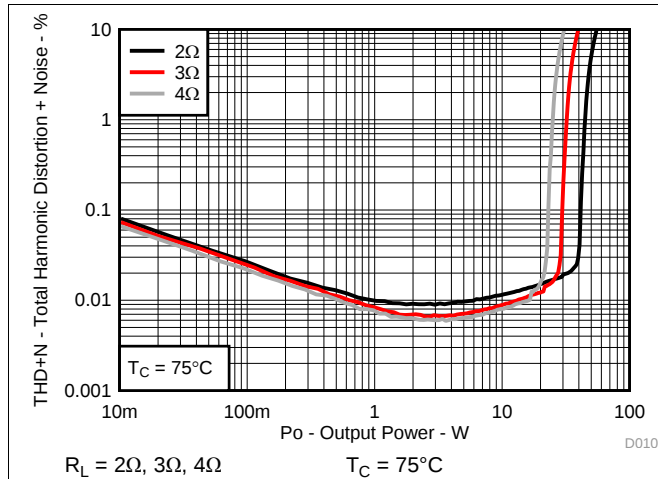


Figure 10. Total Harmonic Distortion+Noise vs Output Power

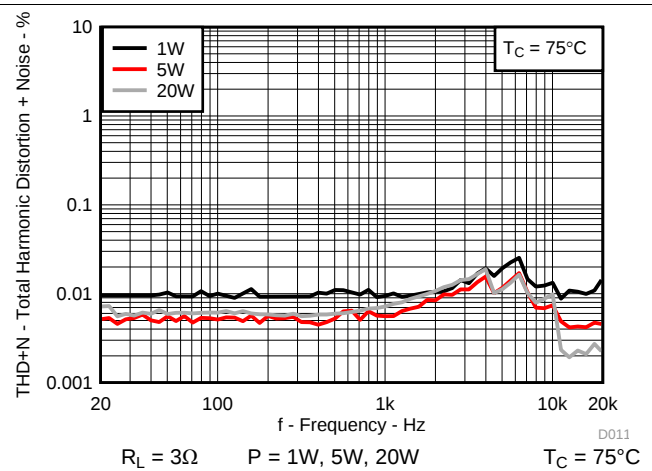


Figure 11. Total Harmonic Distortion+Noise vs Frequency

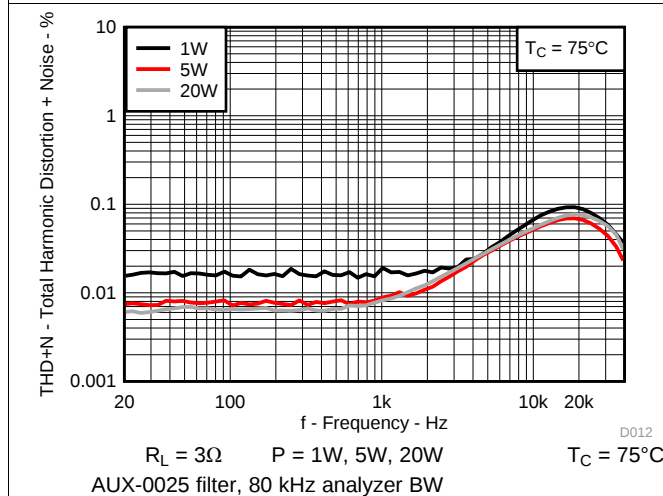


Figure 12. Total Harmonic Distortion+Noise vs Frequency

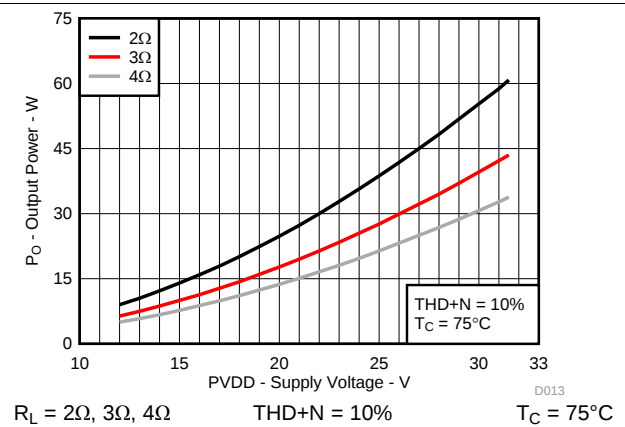


Figure 13. Output Power vs Supply Voltage

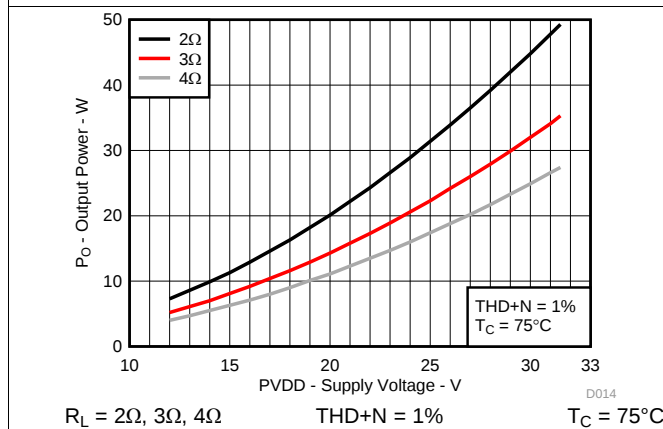


Figure 14. Output Power vs Supply Voltage

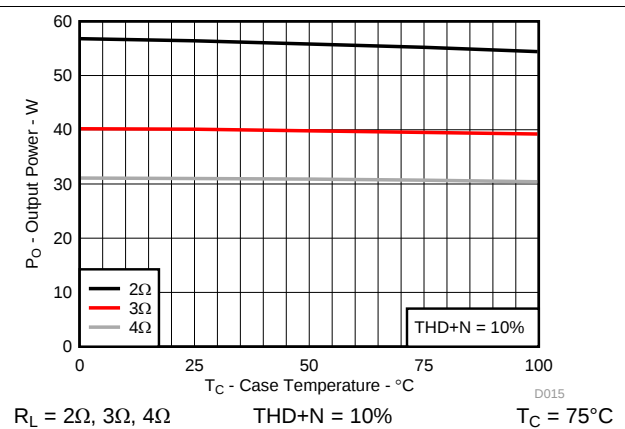


Figure 15. Output Power vs Case Temperature

7.11 Typical Characteristics, PBTL Configuration

All Measurements taken at audio frequency = 1kHz, PVDD_X = 30

V, GVDD_X = 12V, $R_L = 2\Omega$, $f_s = 600\text{ kHz}$, $R_{OC} = 22\text{ k}\Omega$, $T_C = 75^\circ\text{C}$, Output Filter: $L_{DEM} = 10\mu\text{H}$, $C_{DEM} = 1\mu\text{F}$, MODE = 10, outputs paralleled before LC filter, AES17 + AUX-0025 measurement filters, unless otherwise noted.

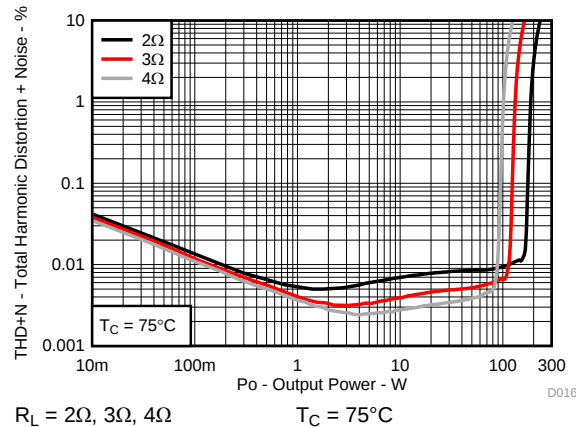


FIG 16. Total Harmonic Distortion+Noise vs Output Power

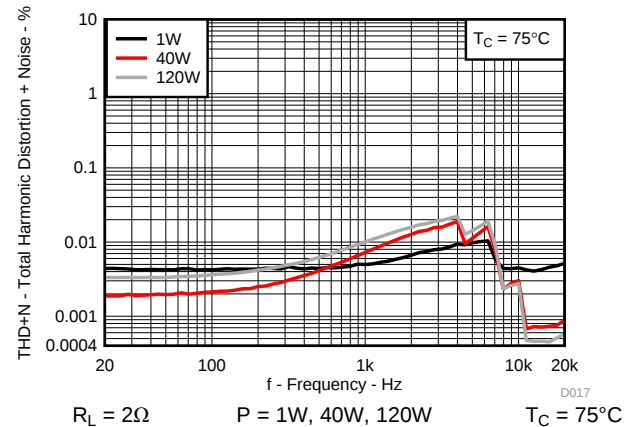


FIG 17. Total Harmonic Distortion+Noise vs Frequency

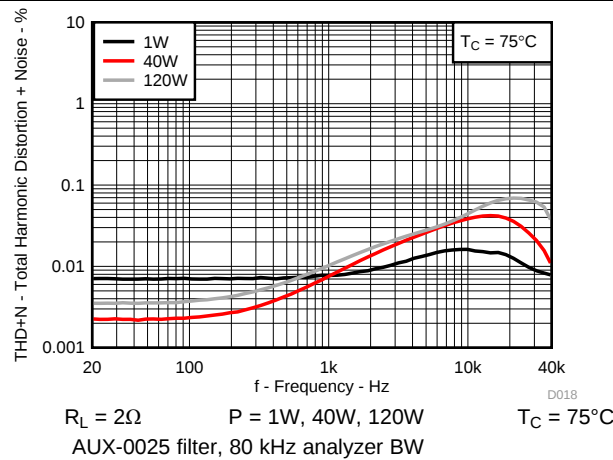


FIG 18. Total Harmonic Distortion+Noise vs Frequency

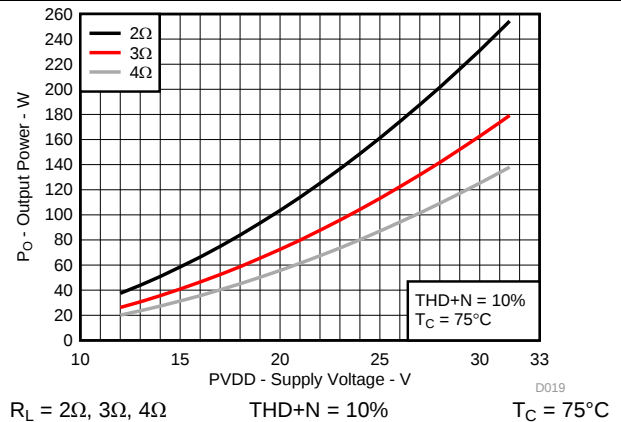


FIG 19. Output Power vs Supply Voltage

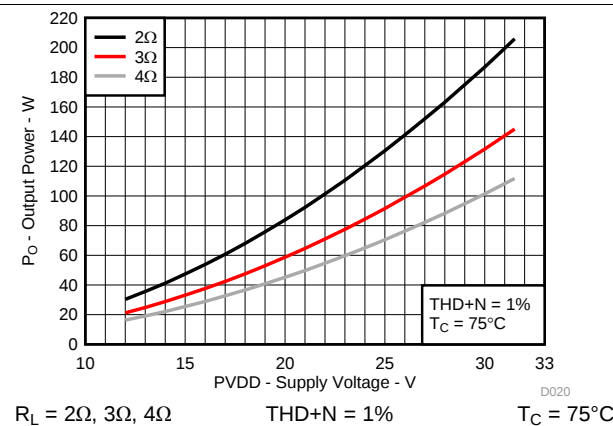


FIG 20. Output Power vs Supply Voltage

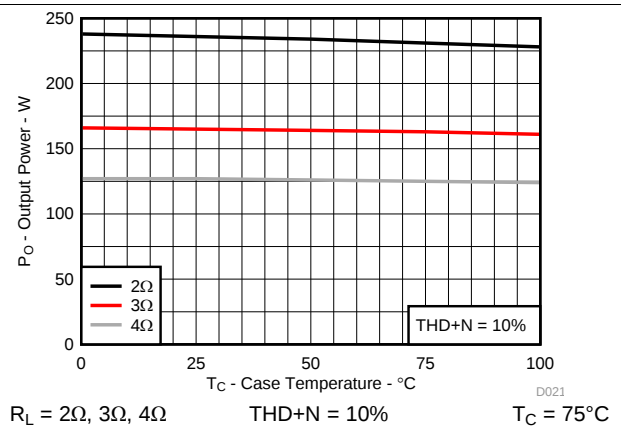


FIG 21. Output Power vs Case Temperature

8 Parameter Measurement Information

All parameters are measured according to the conditions described in the [Recommended Operating Conditions](#) and [Typical Characteristics, BTL Configuration](#) sections.

Most audio analyzers will not give correct readings of Class-D amplifiers' performance due to their sensitivity to out of band noise present at the amplifier output. AES-17 + AUX-0025 pre-analyzer filters are recommended to use for Class-D amplifier measurements. In absence of such filters, a 30-kHz low-pass filter ($10\ \Omega + 47\ \text{nF}$) can be used to reduce the out of band noise remaining on the amplifier outputs.

9 Detailed Description

9.1 Overview

To facilitate system design, the TPA3245 needs only a 12-V supply in addition to the (typical) 30-V power-stage supply. An internal voltage regulator provides suitable voltage levels for the digital and low-voltage analog circuitry, AVDD and DVDD. Additionally, all circuitry requiring a floating voltage supply, that is, the high-side gate drive, is accommodated by built-in bootstrap circuitry requiring only an external capacitor for each half-bridge.

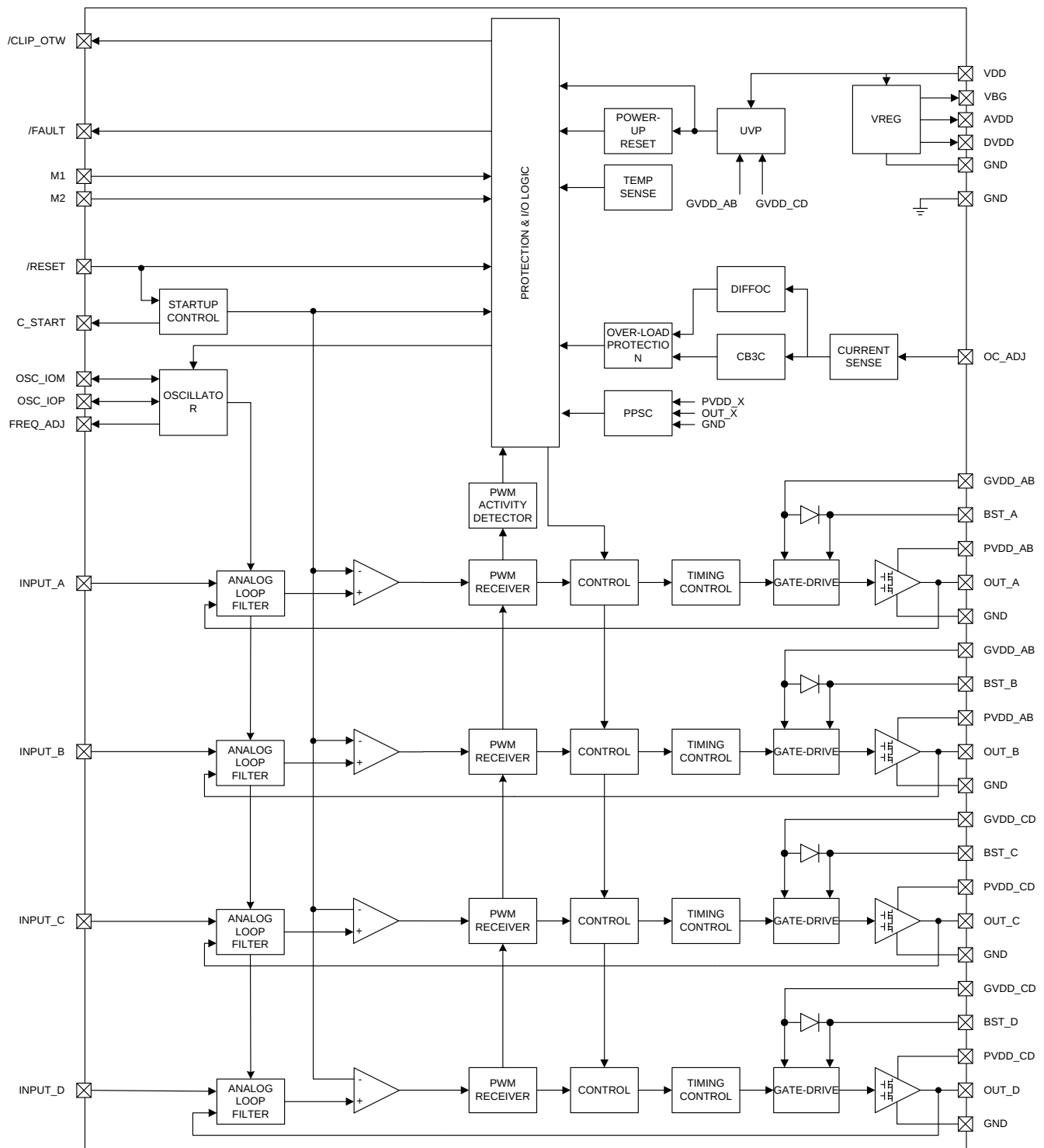
The audio signal path including gate drive and output stage is designed as identical, independent half-bridges. For this reason, each half-bridge has separate bootstrap pins (BST_X). Power-stage supply pins (PVDD_X) and gate drive supply pins (GVDD_X) are separate for each full bridge. Although supplied from the same 12-V source, separating to GVDD_AB, GVDD_CD, and VDD on the printed-circuit board (PCB) by RC filters (see application diagram for details) is recommended. These RC filters provide the recommended high-frequency isolation. Special attention should be paid to placing all decoupling capacitors as close to their associated pins as possible. In general, the physical loop with the power supply pins, decoupling capacitors and GND return path to the device pins must be kept as short as possible and with as little area as possible to minimize induction (see reference board documentation for additional information).

For a properly functioning bootstrap circuit, a small ceramic capacitor must be connected from each bootstrap pin (BST_X) to the power-stage output pin (OUT_X). When the power-stage output is low, the bootstrap capacitor is charged through an internal diode connected between the gate-drive power-supply pin (GVDD_X) and the bootstrap pins. When the power-stage output is high, the bootstrap capacitor potential is shifted above the output potential and thus provides a suitable voltage supply for the high-side gate driver. It is recommended to use 33-nF ceramic capacitors, size 0603 or 0805, for the bootstrap supply. These 33nF capacitors ensure sufficient energy storage, even during minimal PWM duty cycles, to keep the high-side power stage FET (LDMOS) fully turned on during the remaining part of the PWM cycle.

Special attention should be paid to the power-stage power supply; this includes component selection, PCB placement, and routing. As indicated, each full-bridge has independent power-stage supply pins (PVDD_X). For optimal electrical performance, EMI compliance, and system reliability, it is important that each PVDD_X node is decoupled with 1- μF ceramic capacitor placed as close as possible to the supply pins. It is recommended to follow the PCB layout of the TPA3245 reference design. For additional information on recommended power supply and required components, see the application diagrams in this data sheet.

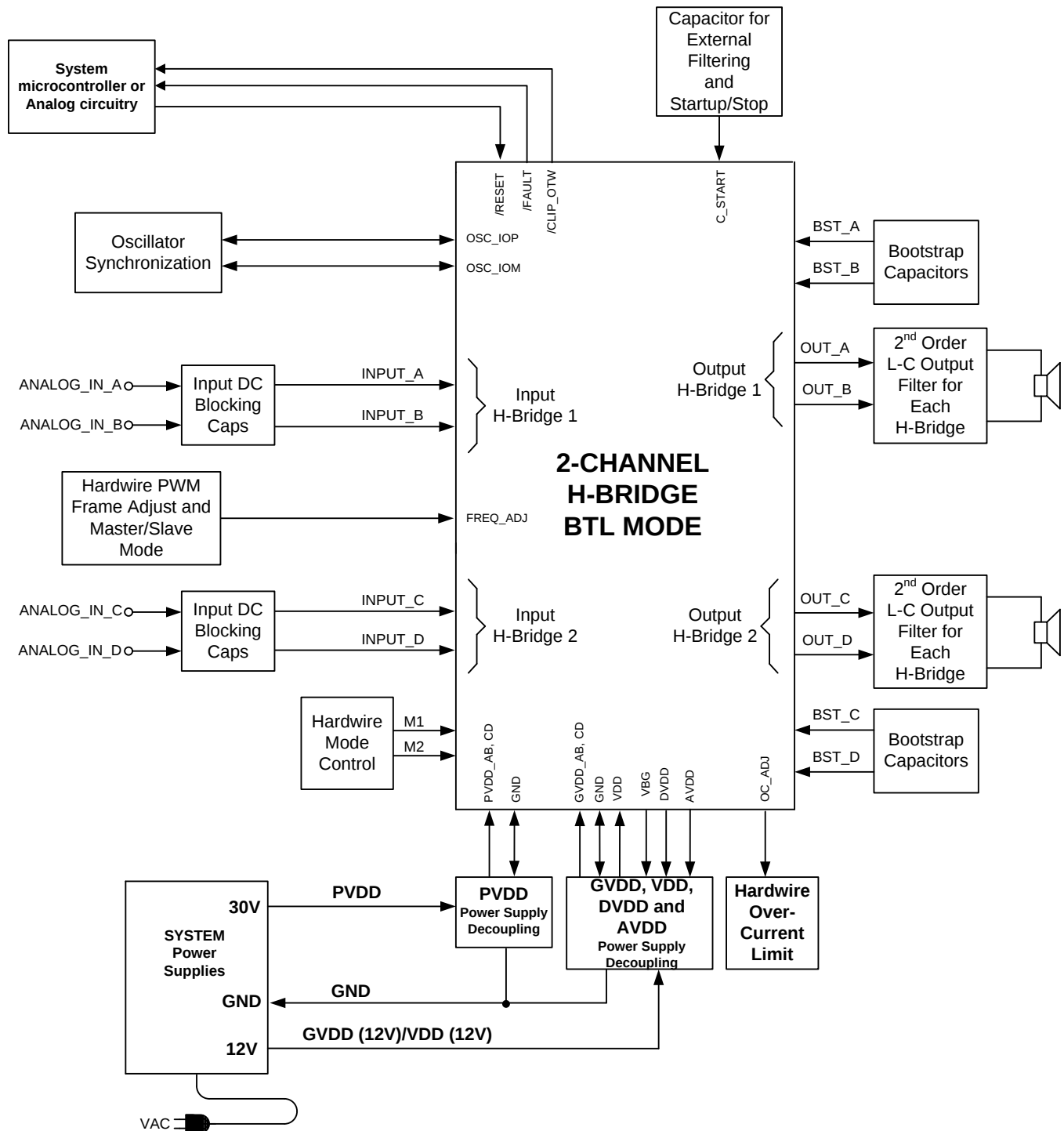
The 12-V supply should be from a low-noise, low-output-impedance voltage regulator. Likewise, the 30-V power-stage supply is assumed to have low output impedance and low noise. The power-supply sequence is not critical as facilitated by the internal power-on-reset circuit, but it is recommended to release RESET after the power supply is settled for minimum turn on audible artefacts. Moreover, the TPA3245 is fully protected against erroneous power-stage turn on due to parasitic gate charging. Thus, voltage-supply ramp rates (dV/dt) are non-critical within the specified range (see the [Recommended Operating Conditions](#) table of this data sheet).

9.2 Functional Block Diagrams



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Functional Block Diagrams (continued)



*NOTE1: Logic AND in or outside microcontroller

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22. System Block Diagram

9.3 Feature Description

9.3.1 Error Reporting

The $\overline{\text{FAULT}}$, and $\overline{\text{CLIP_OTW}}$, pins are active-low, open-drain outputs. The function is for protection-mode signaling to a system-control device.

Any fault resulting in device shutdown is signaled by the $\overline{\text{FAULT}}$ pin going low. Also, $\overline{\text{CLIP_OTW}}$ goes low when the device junction temperature exceeds 125°C (see 表 2).

表 2. Error Reporting

$\overline{\text{FAULT}}$	$\overline{\text{CLIP_OTW}}$	DESCRIPTION
0	0	Overtemperature (OTE) or overload (OLP) or undervoltage (UVP) Junction temperature higher than 125°C (overtemperature warning)
0	0	Overload (OLP) or undervoltage (UVP). Junction temperature higher than 125°C (overtemperature warning)
0	1	Overload (OLP) or undervoltage (UVP). Junction temperature lower than 125°C
1	0	Junction temperature higher than 125°C (overtemperature warning)
1	1	Junction temperature lower than 125°C and no OLP or UVP faults (normal operation)

Note that asserting $\overline{\text{RESET}}$ low forces the $\overline{\text{FAULT}}$ signal high, independent of faults being present. TI recommends monitoring the $\overline{\text{CLIP_OTW}}$ signal using the system microcontroller and responding to an overtemperature warning signal by turning down the volume to prevent further heating of the device resulting in device shutdown (OTE).

To reduce external component count, an internal pullup resistor to 3.3 V is provided on both $\overline{\text{FAULT}}$ and $\overline{\text{CLIP_OTW}}$ outputs.

9.4 Device Protection System

The TPA3245 contains advanced protection circuitry carefully designed to facilitate system integration and ease of use, as well as to safeguard the device from permanent failure due to a wide range of fault conditions such as short circuits, overload, overtemperature, and undervoltage. The TPA3245 responds to a fault by immediately setting the power stage in a high-impedance (Hi-Z) state and asserting the $\overline{\text{FAULT}}$ pin low. In situations other than overload and overtemperature error (OTE), the device automatically recovers when the fault condition has been removed, that is, the supply voltage has increased.

The device will handle errors, as shown in 表 3.

表 3. Device Protection

BTL MODE		PBTL MODE		SE MODE	
LOCAL ERROR IN	TURNS OFF	LOCAL ERROR IN	TURNS OFF	LOCAL ERROR IN	TURNS OFF
A	A+B	A	A+B+C+D	A	A+B
B		B		B	
C	C+D	C		C	C+D
D		D		D	

Bootstrap UVP does not shutdown according to the table, it shuts down the respective halfbridge (non-latching, does not assert $\overline{\text{FAULT}}$).

9.4.1 Overload and Short Circuit Current Protection

TPA3245 has fast reacting current sensors with a programmable trip threshold (OC threshold) on all high-side and low-side FETs. To prevent output current from increasing beyond the programmed threshold, TPA3245 has the option of either limiting the output current for each switching cycle (Cycle By Cycle Current Control, CB3C) or to perform an immediate shutdown of the output in case of excess output current (Latching Shutdown). CB3C prevents premature shutdown due to high output current transients caused by high level music transients and a drop of real speaker's load impedance, and allows the output current to be limited to a maximum programmed

level. If the maximum output current persists, i.e. the power stage being overloaded with too low load impedance, the device will shut down the affected output channel and the affected output is put in a high-impedance (Hi- Z) state until a RESET cycle is initiated. CB3C works individually for each half bridge output. If an over current event is triggered, CB3C performs a state flip of the half bridge output that is cleared upon beginning of next PWM frame.

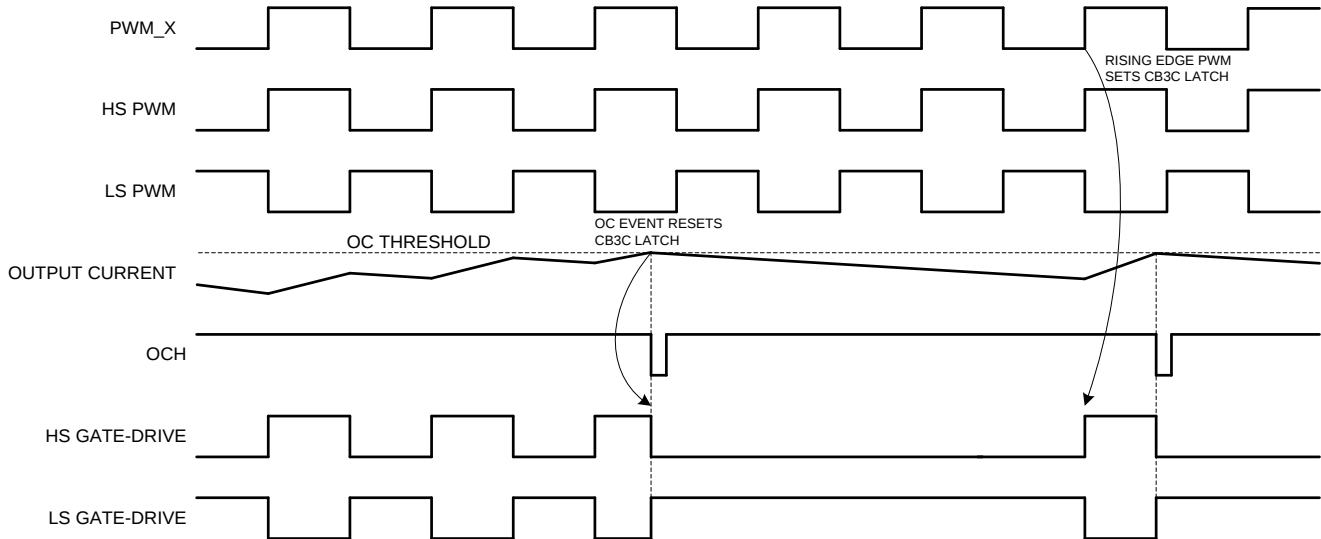


图 23. CB3C Timing Example

During CB3C an over load counter increments for each over current event and decrease for each non-over current PWM cycle. This allows full amplitude transients into a low speaker impedance without a shutdown protection action. In the event of a short circuit condition, the over current protection limits the output current by the CB3C operation and eventually shut down the affected output if the overload counter reaches its maximum value. If a latched OC operation is required such that the device shuts down the affected output immediately upon first detected over current event, this protection mode should be selected. The over current threshold and mode (CB3C or Latched OC) is programmed by the OC_ADJ resistor value. The OC_ADJ resistor needs to be within its intentional value range for either CB3C operation or Latched OC operation.

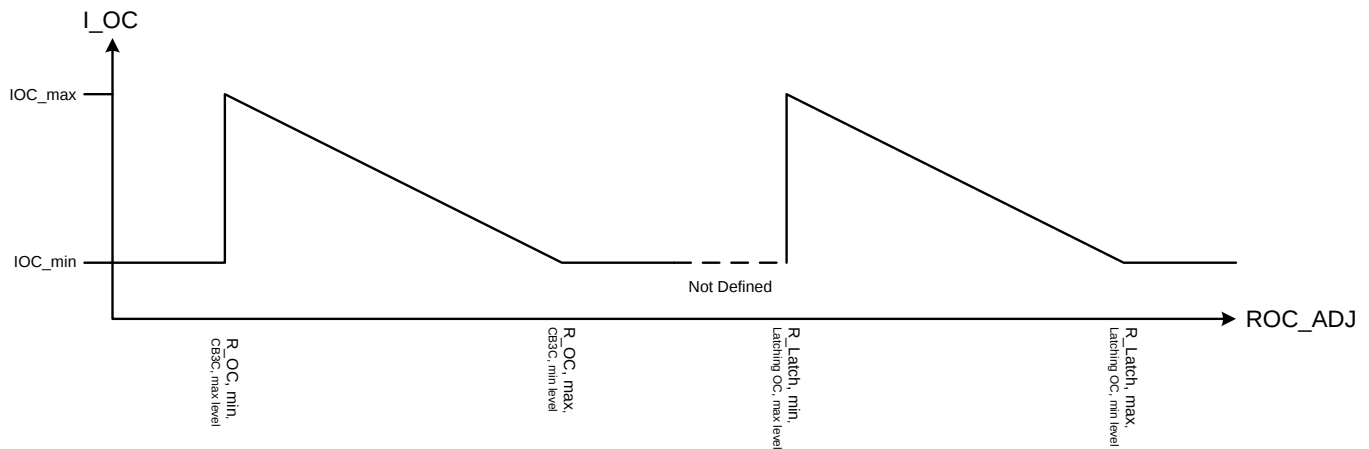


图 24. OC Threshold versus OC ADJ Resistor Value Example

OC_ADJ values outside specified value range for either CB3C or latched OC operation will result in minimum OC threshold.

表 4. Device Protection

OC_ADJ Resistor Value	Protection Mode	OC Threshold
22k Ω	CB3C	13.5A
24k Ω	CB3C	12.5A
27k Ω	CB3C	11.3A
30k Ω	CB3C	10.3A
47k Ω	Latched OC	13.5A
51k Ω	Latched OC	12.5A
56k Ω	Latched OC	11.3A
64k Ω	Latched OC	10.3A

9.4.2 Signal Clipping and Pulse Injector

A built in activity detector monitors the PWM activity of the OUT_X pins. TPA3245 is designed to drive unclipped output signals all the way to PVDD and GND rails. In case of audio signal clipping when applying excessive input signal voltage, or in case of CB3C current protection being active, the amplifier feedback loop of the audio channel will respond to this condition with a saturated state, and the output PWM signals will stop unless special circuitry is implemented to handle this situation. To prevent the output PWM signals from stopping in a clipping or CB3C situation, narrow pulses are injected to the gate drive to maintain output activity. The injected narrow pulses are injected at every 4th PWM frame, and thus the effective switching frequency during this state is reduced to 1/4 of the normal switching frequency.

Signal clipping is signalled on the CLIP_OTW pin and is self clearing when signal level reduces and the device reverts to normal operation. The CLIP_OTW pulses starts at the onset to output clipping, typically at a THD level around 0.01%, resulting in narrow CLIP_OTW pulses starting with a pulse width of ~500ns.

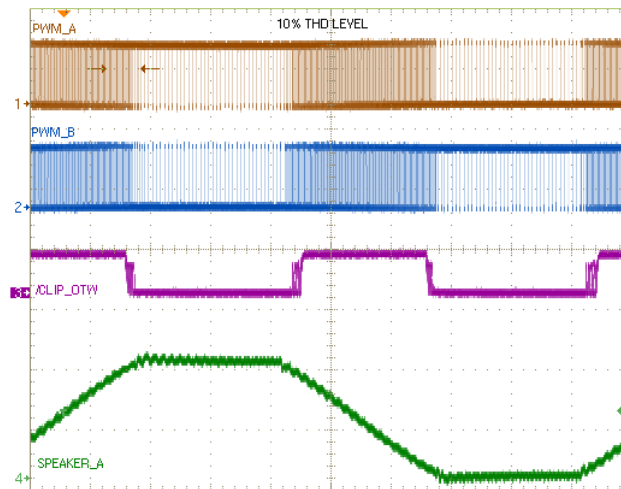


图 25. Signal Clipping PWM and Speaker Output Signals

9.4.3 DC Speaker Protection

The output DC protection scheme protects a speaker from excess DC current in case one terminal of the speaker is connected to the amplifier while the other is accidentally shorted to the chassis ground. Such a short circuit results in a DC voltage of PVDD/2 across the speaker, which potentially can result in destructive current levels. The output DC protection detects any unbalance of the output and input current of a BTL output, and in the event of the unbalance exceeding a programmed threshold, the overload counter increments until its maximum value and the affected output channel is shut down. DC Speaker Protection is disabled in PBTL and SE mode operation.

9.4.4 Pin-to-Pin Short Circuit Protection (PPSC)

The PPSC detection system protects the device from permanent damage in the case that a power output pin (OUT_X) is shorted to GND_X or PVDD_X. For comparison, the OC protection system detects an overcurrent after the demodulation filter where PPSC detects shorts directly at the pin before the filter. PPSC detection is performed at startup i.e. when VDD is supplied, consequently a short to either GND_X or PVDD_X after system startup does not activate the PPSC detection system. When PPSC detection is activated by a short on the output, all half bridges are kept in a Hi-Z state until the short is removed; the device then continues the startup sequence and starts switching. The detection is controlled globally by a two step sequence. The first step ensures that there are no shorts from OUT_X to GND_X, the second step tests that there are no shorts from OUT_X to PVDD_X. The total duration of this process is roughly proportional to the capacitance of the output LC filter. The typical duration is $< 15 \text{ ms}/\mu\text{F}$. While the PPSC detection is in progress, $\overline{\text{FAULT}}$ is kept low, and the device will not react to changes applied to the $\overline{\text{RESET}}$ pin. If no shorts are present the PPSC detection passes, and $\overline{\text{FAULT}}$ is released. A device reset will not start a new PPSC detection. PPSC detection is enabled in BTL and PBTl output configurations, the detection is not performed in SE mode. To make sure not to trip the PPSC detection system it is recommended not to insert a resistive load to GND_X or PVDD_X.

9.4.5 Overtemperature Protection OTW and OTE

TPA3245 has a two-level temperature-protection system that asserts an active-low warning signal ($\overline{\text{CLIP_OTW}}$) when the device junction temperature exceeds 125°C (typical) and, if the device junction temperature exceeds 155°C (typical), the device is put into thermal shutdown, resulting in all half-bridge outputs being set in the high-impedance (Hi-Z) state and $\overline{\text{FAULT}}$ being asserted low. OTE is latched in this case. To clear the OTE latch, $\overline{\text{RESET}}$ must be asserted. Thereafter, the device resumes normal operation.

9.4.6 Undervoltage Protection (UVP) and Power-on Reset (POR)

The UVP and POR circuits of the TPA3255 fully protect the device in any power-up/down and brownout situation. While powering up, the POR circuit ensures that all circuits are fully operational when the GVDD_X and VDD supply voltages reach values stated in the [Electrical Characteristics](#) table. Although GVDD_X and VDD are independently monitored, a supply voltage drop below the UVP threshold on any VDD or GVDD_X pin results in all half-bridge outputs immediately being set in the high-impedance (Hi-Z) state and $\overline{\text{FAULT}}$ being asserted low. The device automatically resumes operation when all supply voltages have increased above the UVP threshold.

9.4.7 Fault Handling

If a fault situation occurs while in operation, the device acts accordingly to the fault being a global or a channel fault. A global fault is a chip-wide fault situation and causes all PWM activity of the device to be shut down, and will assert $\overline{\text{FAULT}}$ low. A global fault is a latching fault and clearing $\overline{\text{FAULT}}$ and restarting operation requires resetting the device by toggling $\overline{\text{RESET}}$. Deasserting $\overline{\text{RESET}}$ should never be allowed with excessive system temperature, so it is advised to monitor $\overline{\text{RESET}}$ by a system microcontroller and only allow releasing $\overline{\text{RESET}}$ ($\overline{\text{RESET}}$ high) if the $\overline{\text{CLIP_OTW}}$ signal is cleared (high). A channel fault results in shutdown of the PWM activity of the affected channel(s). Note that asserting $\overline{\text{RESET}}$ low forces the $\overline{\text{FAULT}}$ signal high, independent of faults being present.

表 5. Error Reporting

Fault/Event	Fault/Event Description	Global or Channel	Reporting Method	Latched/Self Clearing	Action needed to Clear	Output FETs
PVDD_X UVP	Voltage Fault	Global	$\overline{\text{FAULT}}$ pin	Self Clearing	Increase affected supply voltage	HI-Z
VDD UVP						
AVDD UVP						
POR (DVDD UVP)	Power On Reset	Global	$\overline{\text{FAULT}}$ pin	Self Clearing	Allow DVDD to rise	HI-Z
BST_X UVP	Voltage Fault	Channel (Half Bridge)	None	Self Clearing	Allow BST cap to recharge (lowside ON, VDD 12V)	HighSide off
OTW	Thermal Warning	Global	$\overline{\text{OTW}}$ pin	Self Clearing	Cool below OTW threshold	Normal operation
OTE	Thermal Shutdown	Global	$\overline{\text{FAULT}}$ pin	Latched	Toggle $\overline{\text{RESET}}$	HI-Z
OLP (CB3C>1.7ms)	OC Shutdown	Channel	$\overline{\text{FAULT}}$ pin	Latched	Toggle $\overline{\text{RESET}}$	HI-Z
Latched OC (47k Ω <ROC_ADJ<68 k Ω)	OC Shutdown	Channel	$\overline{\text{FAULT}}$ pin	Latched	Toggle $\overline{\text{RESET}}$	HI-Z
CB3C (22k Ω <ROC_ADJ<30 k Ω)	OC Limiting	Channel	None	Self Clearing	Reduce signal level or remove short	Flip state, cycle by cycle at fs/3
Stuck at Fault ⁽¹⁾	No OSC_IO activity in Slave Mode	Global	None	Self Clearing	Resume OSC_IO activity	HI-Z

(1) Stuck at Fault occurs when input OSC_IO input signal frequency drops below minimum frequency given in the [Electrical Characteristics](#) table of this data sheet.

9.4.8 Device Reset

Asserting $\overline{\text{RESET}}$ low initiates the device ramp down. The output FETs go into a HI-Z state after the ramp down is complete. Output pull downs are active both in SE mode and BTL mode with $\overline{\text{RESET}}$ low.

In BTL modes, to accommodate bootstrap charging prior to switching start, asserting the reset input low enables weak pulldown of the half-bridge outputs.

Asserting reset input low removes any fault information to be signaled on the $\overline{\text{FAULT}}$ output, that is, $\overline{\text{FAULT}}$ is forced high. A rising-edge transition on reset input allows the device to resume operation after a fault. To ensure thermal reliability, the rising edge of reset must occur no sooner than 4 ms after the falling edge of $\overline{\text{FAULT}}$.

Typical Applications (continued)

10.2.1.1 Design Requirements

For this design example, use the parameters in 表 6.

表 6. Design Requirements, BTL Application

DESIGN PARAMETER	EXAMPLE
Low Power (Pull-up) Supply	3.3 V
Mid Power Supply 12 V	12 V
High Power Supply	12 - 30 V
Mode Selection	M2 = L
	M1 = L
Analog Inputs	INPUT_A = ± 3.9 V (peak, max)
	INPUT_B = ± 3.9 V (peak, max)
	INPUT_C = ± 3.9 V (peak, max)
	INPUT_D = ± 3.9 V (peak, max)
Output Filters	Inductor-Capacitor Low Pass Filter (10 μ H + 1 μ F)
Speaker Impedance	3-8 Ω

10.2.1.2 Detailed Design Procedures

A rising-edge transition on reset input allows the device to execute the startup sequence and starts switching.

The CLIP signal is indicating that the output is approaching clipping. The signal can be used either to decrease audio volume or to control an intelligent power supply nominally operating at a low rail adjusting to a higher supply rail.

The device is inverting the audio signal from input to output.

The DVDD and AVDD pins are not recommended to be used as a voltage sources for external circuitry.

10.2.1.2.1 Decoupling Capacitor Recommendations

In order to design an amplifier that has robust performance, passes regulatory requirements, and exhibits good audio performance, good quality decoupling capacitors should be used. In practice, X7R should be used in this application.

10.2.1.2.2 PVDD Capacitor Recommendation

The PVDD decoupling capacitors must be placed as close to the device pins as possible to insure short trace length and low inductance path. Likewise the ground path for these capacitors must provide a good reference and should be substantial. This will keep voltage ringing on PVDD to a minimum.

The voltage of the decoupling capacitors should be selected in accordance with good design practices. Temperature, ripple current, and voltage overshoot must be considered. This fact is particularly true in the selection of the 1 μ F that is placed on the power supply to each full-bridge. It must withstand the voltage overshoot of the PWM switching, the heat generated by the amplifier during high power output, and the ripple current created by high power output. A minimum voltage rating of 50 V is required for use with a 30V power supply.

The large capacitors used in conjunction with each full-bridge, are referred to as the PVDD Capacitors. These capacitors should be selected for proper voltage margin and adequate capacitance to support the power requirements. In practice, with a well designed system power supply, 1000 μ F, 50 V supports most applications. The PVDD capacitors should be low ESR type because they are used in a circuit associated with high-speed switching.

10.2.1.2.3 PCB Material Recommendation

FR-4 Glass Epoxy material with 2 oz. (70 μ m) copper is recommended for use with the TPA3245. The use of this material can provide for higher power output, improved thermal performance, and better EMI margin (due to lower PCB trace inductance).

10.2.1.2.4 Oscillator

The built in oscillator frequency can be trimmed by an external resistor from the `FREQ_ADJ` pin to GND. Changes in the oscillator frequency should be made with resistor values specified in [Recommended Operating Conditions](#) while `RESET` is low.

To reduce interference problems while using a radio receiver tuned within the AM band, the switching frequency can be changed from nominal to lower or higher values. These values should be chosen such that the nominal and the alternate switching frequencies together result in the fewest cases of interference throughout the AM band. The oscillator frequency can be selected by the value of the `FREQ_ADJ` resistor connected to GND in master mode.

For slave mode operation, turn off the oscillator by pulling the `FREQ_ADJ` pin to DVDD. This configures the `OSC_I/O` pins as inputs to be slaved from an external differential clock. In a master/slave system inter-channel delay is automatically set up between the switching of the audio channels, which can be illustrated by no idle channels switching at the same time. This will not influence the audio output, but only the switch timing to minimize noise coupling between audio channels through the power supply. Inter-channel delay is needed to optimize audio performance and to get better operating conditions for the power supply. The inter-channel delay will be set up for a slave device depending on the polarity of the `OSC_I/O` connection as follows:

- Slave 1 mode has normal polarity (master + to slave + and master - to slave -)
- Slave 2 mode has reverse polarity (master + to slave - and master - to slave +)

The interchannel delay for interleaved channel idle switching is given in the table below for the master/slave and output configuration modes in degrees relative to the PWM frame.

表 7. Master/Slave Inter Channel Delay Settings

Master	M1 = 0, M2 = 0, 2 x BTL mode	M1 = 1, M2 = 0, 1 x BTL + 2 x SE mode	M1 = 0, M2 = 1, 1 x PBTL mode	M1 = 1, M2 = 1, 4 x SE mode
OUT_A	0°	0°	0°	0°
OUT_B	180°	180°	180°	60°
OUT_C	60°	60°	0°	0°
OUT_D	240°	120°	180°	60°
Slave 1				
OUT_A	60°	60°	60°	60°
OUT_B	240°	240°	240°	120°
OUT_C	120°	120°	60°	60°
OUT_D	300°	180°	240°	120°
Slave 2				
OUT_A	30°	30°	30°	30°
OUT_B	210°	210°	210°	90°
OUT_C	90°	90°	30°	30°
OUT_D	270°	150°	210°	90°

10.2.2 Application Curves

Relevant performance plots for TPA3245 in BTL configuration are shown in [Typical Characteristics, BTL Configuration](#)

表 8. Relevant Performance Plots, BTL Configuration

PLOT TITLE	FIGURE NUMBER
Total Harmonic Distortion+Noise vs Frequency	Figure 1
Total Harmonic Distortion+Noise vs Frequency, 80kHz analyzer BW	Figure 2
Total Harmonic Distortion + Noise vs Output Power	Figure 3
Output Power vs Supply Voltage, 10% THD+N	Figure 4
Output Power vs Supply Voltage, 10% THD+N	Figure 6
System Efficiency vs Output Power	Figure 6
System Power Loss vs Output Power	Figure 7
Output Power vs Case Temperature	Figure 8
Noise Amplitude vs Frequency	Figure 9

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10.2.3 Typical Application, Single Ended (1N) SE

This section provides an example for configuring the TPA3245 in single-ended output (SE) mode.

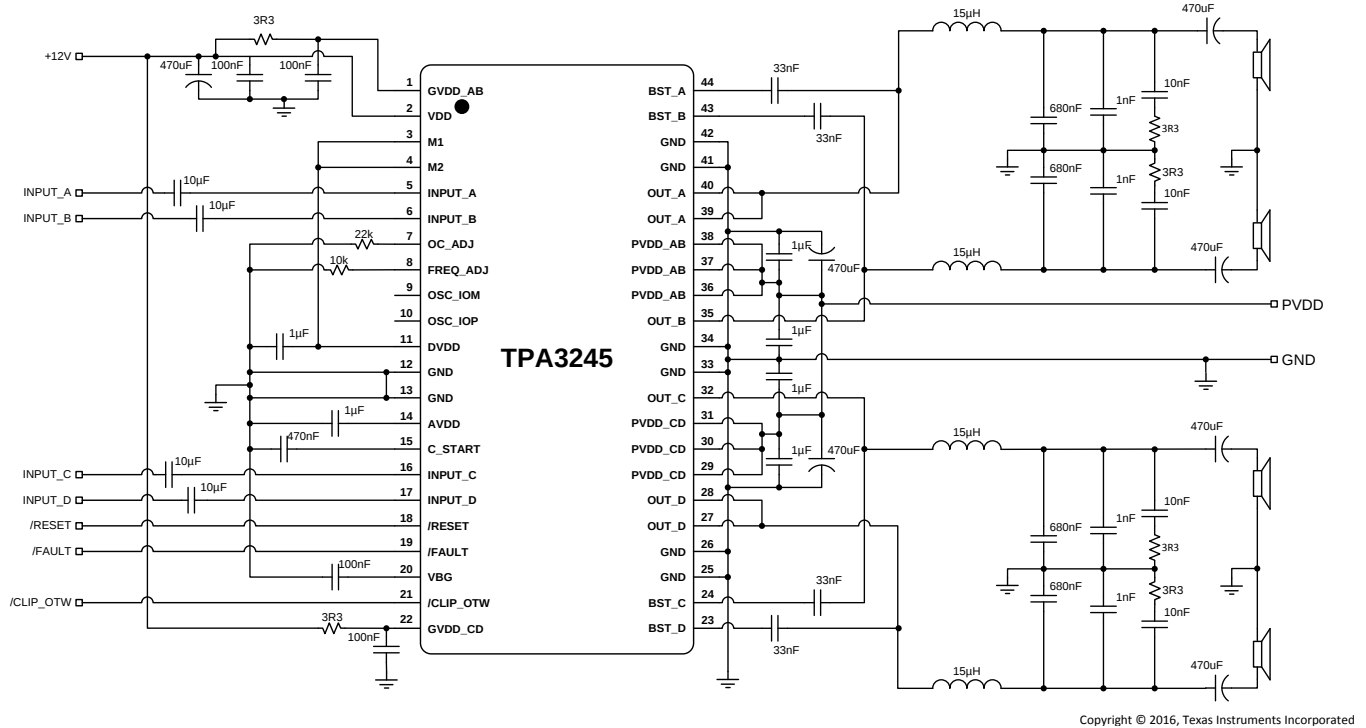


图 27. Typical Single Ended (1N) SE Application

10.2.3.1 Design Requirements

Refer to [Stereo BTL Application](#) for the Design Requirements.

表 9. Design Requirements, SE Application

DESIGN PARAMETER	EXAMPLE
Low Power (Pull-up) Supply	3.3 V
Mid Power Supply 1 2V	12 V
High Power Supply	12 - 30 V
Mode Selection	M2 = H
	M1 = H
Analog Inputs	INPUT_A = ± 3.9 V (peak, max)
	INPUT_B = ± 3.9 V (peak, max)
	INPUT_C = ± 3.9 V (peak, max)
	INPUT_D = ± 3.9 V (peak, max)
Output Filters	Inductor-Capacitor Low Pass Filter (15 μ H + 680 nF)
Speaker Impedance	2 - 8 Ω

10.2.3.2 Detailed Design Procedures

Refer to [Stereo BTL Application](#) for the Detailed Design Procedures.

10.2.3.3 Application Curves

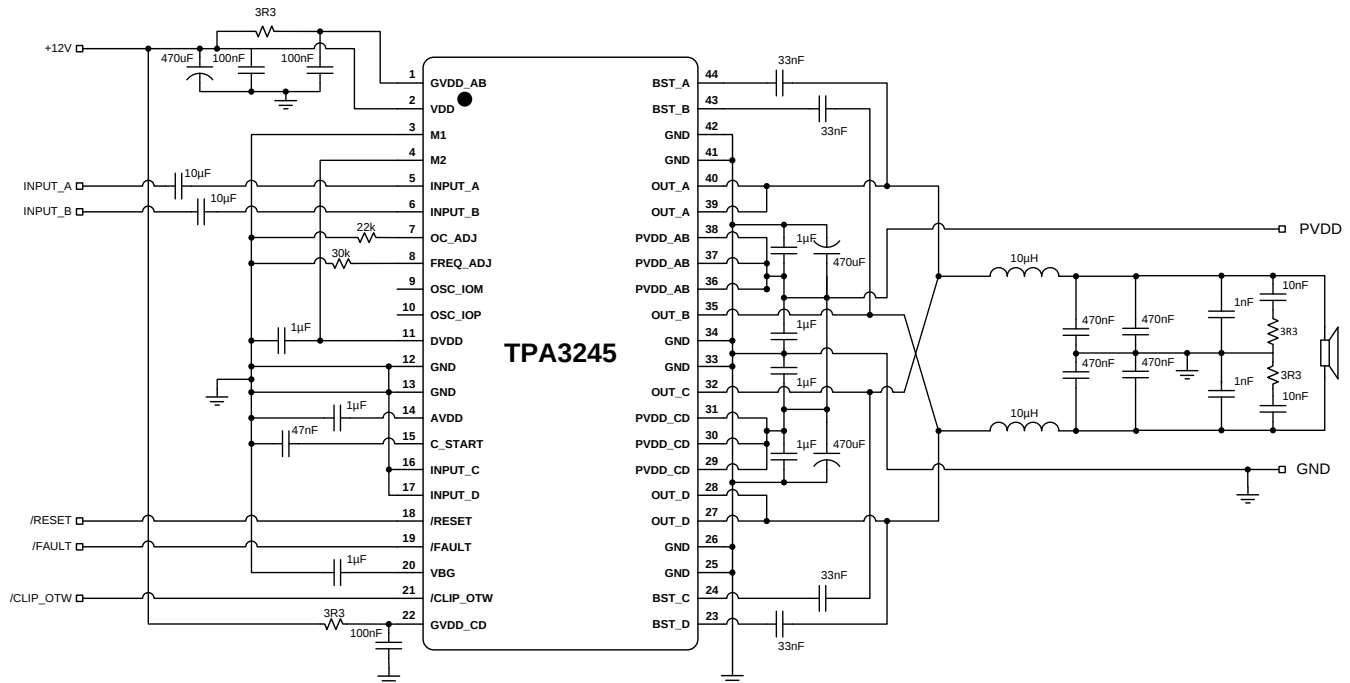
Relevant performance plots for TPA3245 in SE configuration are shown in [Typical Characteristics, SE Configuration](#)

表 10. Relevant Performance Plots, SE Configuration

PLOT TITLE	FIGURE NUMBER
Total Harmonic Distortion+Noise vs Output Power	图 10
Total Harmonic Distortion+Noise vs Frequency	图 11
Total Harmonic Distortion+Noise vs Frequency, 80kHz analyzer BW	图 12
Output Power vs Supply Voltage, 10% THD+N	图 13
Output Power vs Supply Voltage, 1% THD+N	图 14
Output Power vs Case Temperature	图 15

10.2.4 Typical Application, Differential (2N), PBTL (Outputs Paralleled before LC filter)

TPA3245 can be configured in mono PBTL mode by paralleling the outputs before the LC filter or after the LC filter (see [Typical Application, Differential \(2N\), PBTL \(Outputs Paralleled after LC filter\)](#)). Paralleled outputs before the LC filter is recommended for better performance and limiting the number of output LC filter inductors, only two inductors required. This sections shows an example of paralleled outputs before the LC filter.



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图 28. Typical Differential (2N) PBTL (Outputs Paralleled before LC filter) Application

10.2.4.1 Design Requirements

Refer to [Stereo BTL Application](#) for the Design Requirements.

表 11. Design Requirements, PBTL (Outputs Paralleled before LC filter) Application

DESIGN PARAMETER	EXAMPLE
Low Power (Pull-up) Supply	3.3 V
Mid Power Supply 12 V	12 V
High Power Supply	12 - 30 V
Mode Selection	M2 = H
	M1 = L
Analog Inputs	INPUT_A = ± 3.9 V (peak, max)
	INPUT_B = ± 3.9 V (peak, max)
	INPUT_C = Grounded
	INPUT_D = Grounded
Output Filters	Inductor-Capacitor Low Pass Filter (10 μ H + 1 μ F)
Speaker Impedance	2 - 4 Ω

10.2.4.2 Detailed Design Procedures

Refer to [Stereo BTL Application](#) for the Detailed Design Procedures.

10.2.4.3 Application Curves

Relevant performance plots for TPA3245 in PBTL configuration are shown in [Typical Characteristics, PBTL Configuration](#)

表 12. Relevant Performance Plots, PBTL (Outputs Paralleled before LC filter) Configuration

PLOT TITLE	FIGURE NUMBER
Total Harmonic Distortion+Noise vs Output Power	Figure 16
Total Harmonic Distortion+Noise vs Frequency	Figure 17
Total Harmonic Distortion+Noise vs Frequency, 80kHz analyzer BW	Figure 18
Output Power vs Supply Voltage, 10% THD+N	Figure 19
Output Power vs Supply Voltage, 1% THD+N	Figure 20
Output Power vs Case Temperature	Figure 21

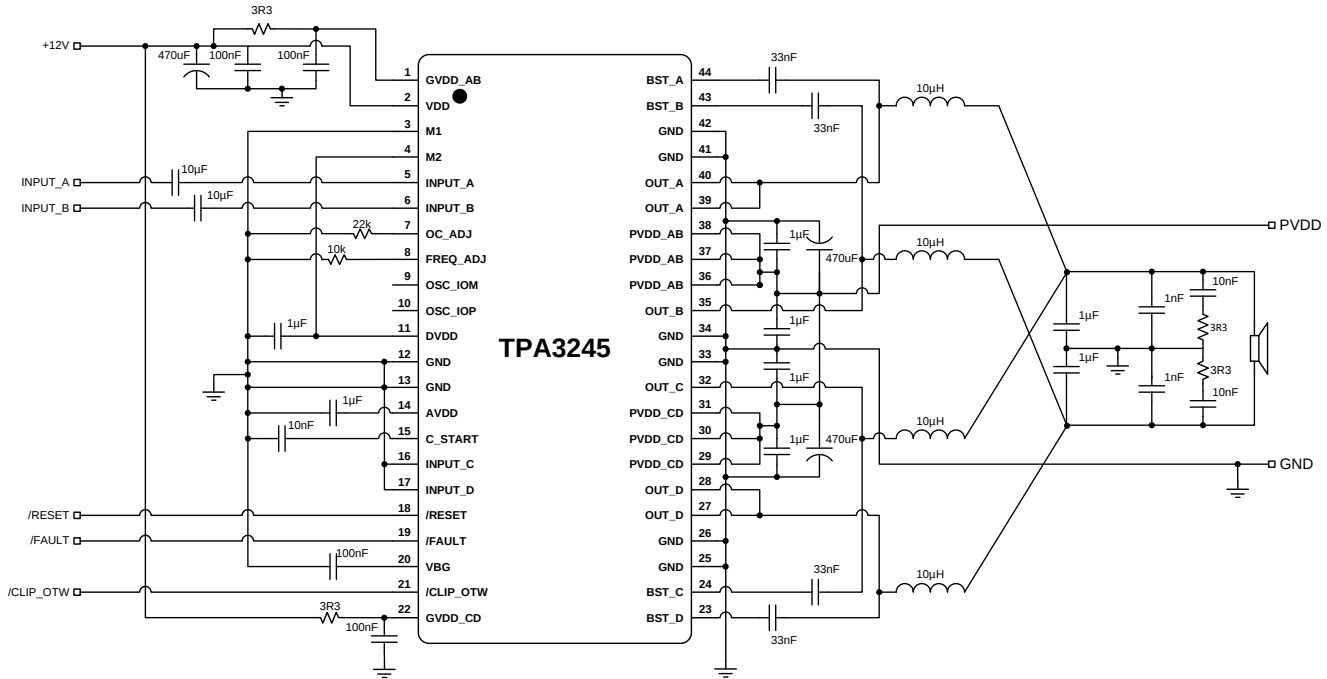
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10.2.5 Typical Application, Differential (2N), PBTL (Outputs Paralleled after LC filter)

TPA3245 can be configured in mono PBTL mode by paralleling the outputs before the LC filter (see [Typical Application, Differential \(2N\), PBTL \(Outputs Paralleled before LC filter\)](#)) or after the LC filter. Paralleled outputs after the LC filter may be preferred if: a single board design must support both PBTL and BTL, or in the case multiple, smaller paralleled inductors are preferred due to size or cost. Paralleling after the LC filter requires four inductors, one for each OUT_x. This section shows an example of paralleled outputs after the LC filter.



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图 29. Typical Differential (2N) PBTL (Outputs Paralleled after LC filter) Application

10.2.5.1 Design Requirements

Refer to [Stereo BTL Application](#) for the Design Requirements.

表 13. Design Requirements, PBTL (Outputs Paralleled after LC filter) Application

DESIGN PARAMETER	EXAMPLE
Low Power (Pull-up) Supply	3.3 V
Mid Power Supply 12 V	12 V
High Power Supply	12 - 30 V
Mode Selection	M2 = H
	M1 = L
Analog Inputs	INPUT_A = ± 3.9 V (peak, max)
	INPUT_B = ± 3.9 V (peak, max)
	INPUT_C = Grounded
	INPUT_D = Grounded
Output Filters	Inductor-Capacitor Low Pass Filter (10 μ H + 1 μ F)
Speaker Impedance	2 - 4 Ω

10.2.5.2 Detailed Design Procedures

Refer to [Stereo BTL Application](#) for the Detailed Design Procedures.

11 Power Supply Recommendations

11.1 Power Supplies

The TPA3245 device requires two external power supplies for proper operation. A high-voltage supply called PVDD is required to power the output stage of the speaker amplifier and its associated circuitry. Additionally, one mid-voltage power supply for GVDD_X and VDD is required to power the gate-drive and other internal digital and analog portions of the device. The allowable voltage range for both the PVDD and the GVDD_X/VDD supplies are listed in the [Recommended Operating Conditions](#) table. Ensure both the PVDD and the GVDD_X/VDD supplies can deliver more current than listed in the [Electrical Characteristics](#) table.

11.1.1 VDD Supply

The VDD supply required from the system is used to power several portions of the device. It provides power to internal regulators DVDD and AVDD that are used to power digital and analog sections of the device, respectively. Proper connection, routing, and decoupling techniques are highlighted in the TPA3245 device EVM User's Guide [SLVUAG8](#) (as well as the [Application Information](#) section and [Layout Examples](#) section) and must be followed as closely as possible for proper operation and performance. Deviation from the guidance offered in the TPA3245 device EVM User's Guide, which followed the same techniques as those shown in the [Application Information](#) section, may result in reduced performance, errant functionality, or even damage to the TPA3245 device. Some portions of the device also require a separate power supply which is a lower voltage than the VDD supply. To simplify the power supply requirements for the system, the TPA3245 device includes integrated low-dropout (LDO) linear regulators to create these supplies. These linear regulators are internally connected to the VDD supply and their outputs are presented on AVDD and DVDD pins, providing a connection point for an external bypass capacitors. It is important to note that the linear regulators integrated in the device have only been designed to support the current requirements of the internal circuitry, and should not be used to power any additional external circuitry. Additional loading on these pins could cause the voltage to sag and increase noise injection, which negatively affects the performance and operation of the device.

11.1.2 GVDD_X Supply

The GVDD_X supply required from the system is used to power the gate-drives for the output H-bridges. Proper connection, routing, and decoupling techniques are highlighted in the TPA3245 device EVM User's Guide [SLVUAG8](#) (as well as the [Application Information](#) section and [Layout Examples](#) section) and must be followed as closely as possible for proper operation and performance. Deviation from the guidance offered in the TPA3245 device EVM User's Guide, which followed the same techniques as those shown in the [Application Information](#) section, may result in reduced performance, errant functionality, or even damage to the TPA3245 device.

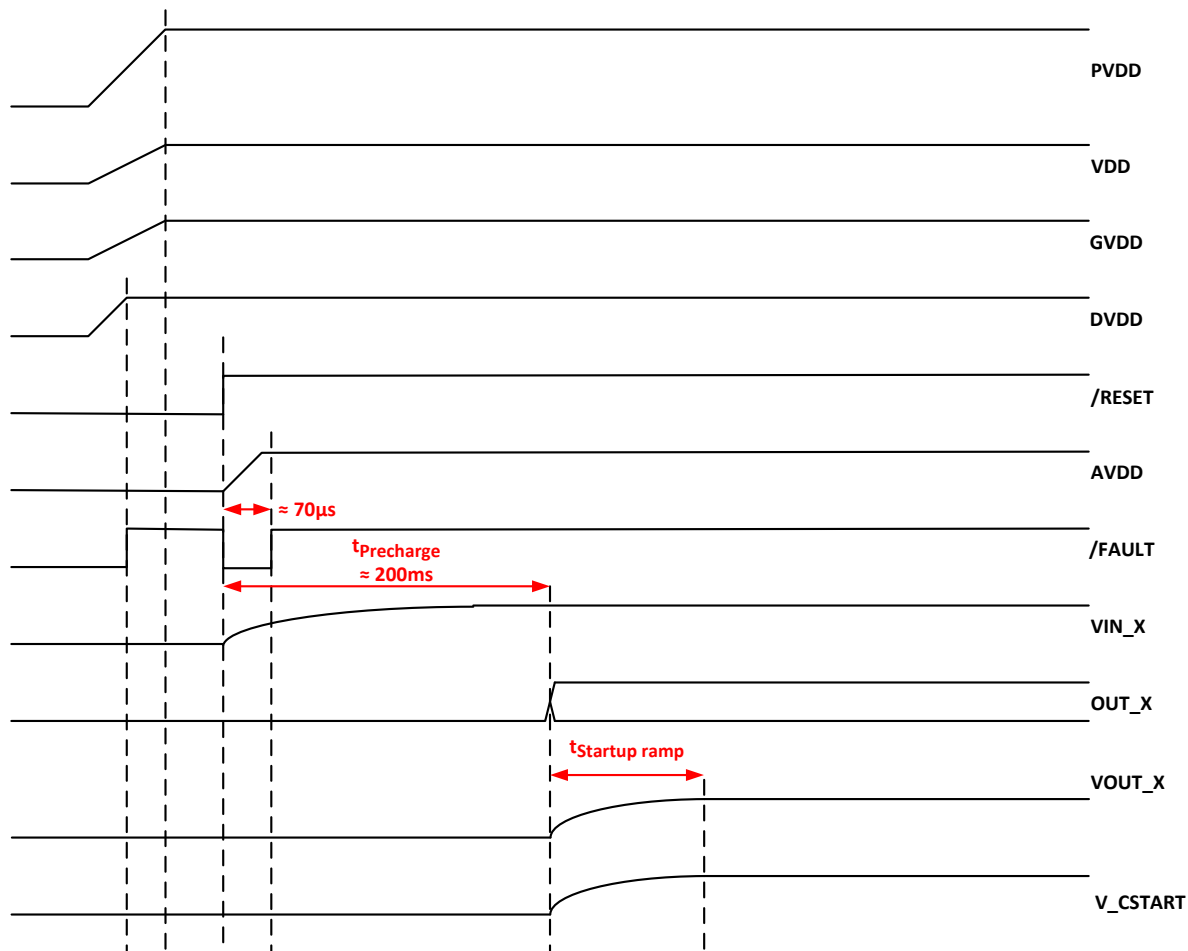
11.1.3 PVDD Supply

The output stage of the amplifier drives the load using the PVDD supply. This is the power supply which provides the drive current to the load during playback. Proper connection, routing, and decoupling techniques are highlighted in the TPA3245 device EVM User's Guide [SLVUAG8](#) (as well as the [Application Information](#) section and [Layout Examples](#) section) and must be followed as closely as possible for proper operation and performance. Due the high-voltage switching of the output stage, it is particularly important to properly decouple the output power stages in the manner described in the TPA3245 device EVM User's Guide [SLVUAG8](#). The lack of proper decoupling, like that shown in the EVM User's Guide, can results in voltage spikes which can damage the device, or cause poor audio performance and device shutdown faults.

11.2 Powering Up

The TPA3245 does not require a power-up sequence, but it is recommended to hold $\overline{\text{RESET}}$ low for at least 250 ms after PVDD supply voltage is turned ON. The outputs of the H-bridges remain in a high-impedance state until the gate-drive supply voltage (GVDD_X) and VDD voltages are above the undervoltage protection (UVP) voltage threshold (see the [Electrical Characteristics](#) table of this data sheet). This allows an internal circuit to charge the external bootstrap capacitors by enabling a weak pulldown of the half-bridge output as well as initiating a controlled ramp up sequence of the output voltage.

Powering Up (continued)



✕ 30. Startup Timing

When $\overline{RESET}$ is released to turn on TPA3245, $\overline{FAULT}$ signal will turn low and AVDD voltage regulator will be enabled. $\overline{FAULT}$ will stay low until AVDD reaches the undervoltage protection (UVP) voltage threshold (see the Electrical Characteristics table of this data sheet). After a precharge time to stabilize the DC voltage across the input AC coupling capacitors, the ramp up sequence starts.

11.3 Powering Down

The TPA3245 does not require a power-down sequence. The device remains fully operational as long as the gate-drive supply (GVDD_X) voltage and VDD voltage are above the undervoltage protection (UVP) voltage threshold (see the [Electrical Characteristics](#) table of this data sheet). Although not specifically required, it is a good practice to hold $\overline{RESET}$ low during power down, thus preventing audible artifacts including pops or clicks by initiating a controlled ramp down sequence of the output voltage.

12 Layout

12.1 Layout Guidelines

- Use an unbroken ground plane to have good low impedance and inductance return path to the power supply for power and audio signals.
- Maintain a contiguous ground plane from the ground pins to the PCB area surrounding the device for as many of the ground pins as possible, since the ground pins are the best conductors of heat in the package.

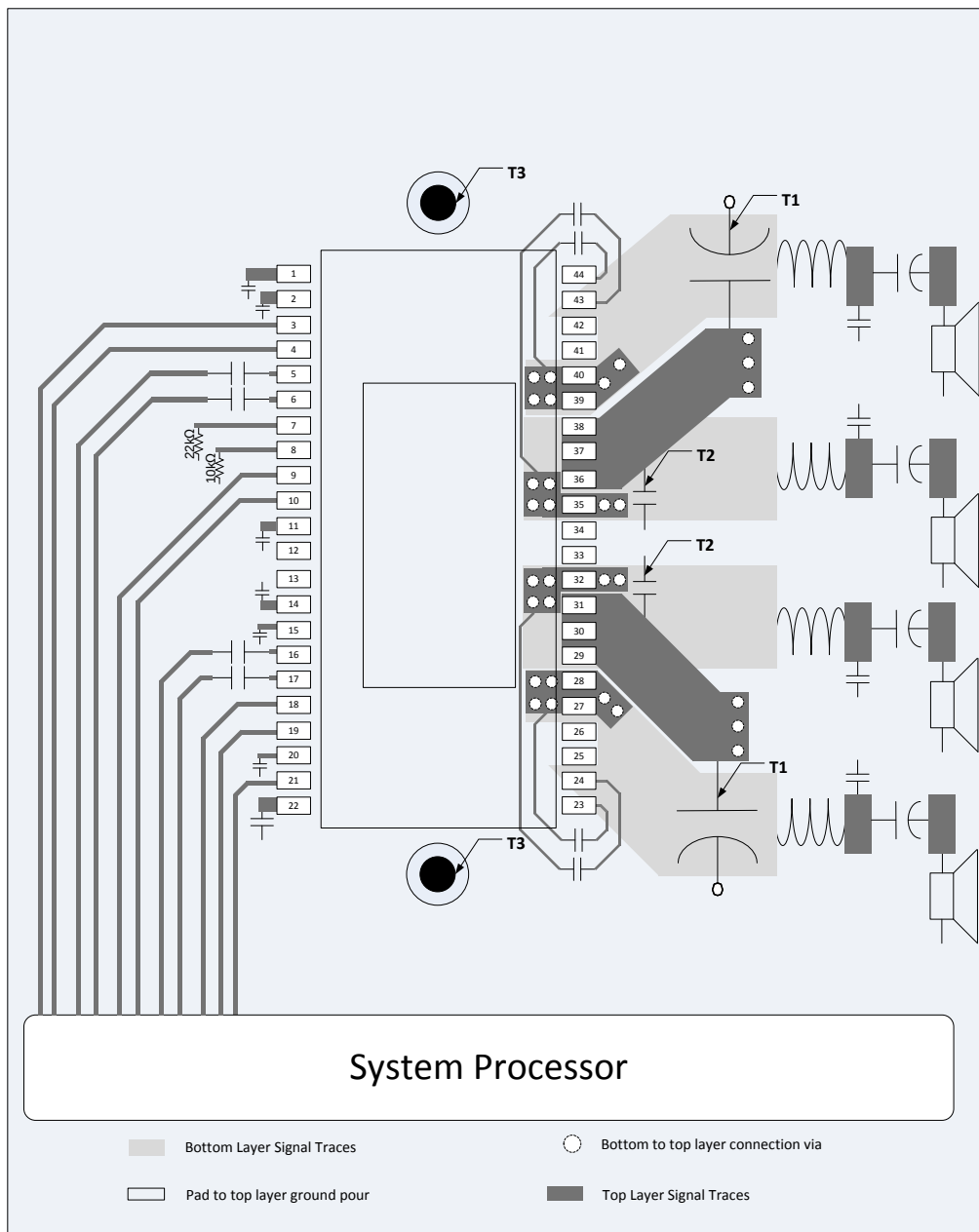
Layout Guidelines (continued)

- PCB layout, audio performance and EMI are linked closely together.
- Routing the audio input should be kept short and together with the accompanied audio source ground.
- The small bypass capacitors on the PVDD lines of the DUT be placed as close the PVDD pins as possible.
- A local ground area underneath the device is important to keep solid to minimize ground bounce.
- Orient the passive component so that the narrow end of the passive component is facing the TPA3245 device, unless the area between two pads of a passive component is large enough to allow copper to flow in between the two pads.
- Avoid placing other heat producing components or structures near the TPA3245 device.
- Avoid cutting off the flow of heat from the TPA3245 device to the surrounding ground areas with traces or via strings, especially on output side of device.

Netlist for this printed circuit board is generated from the schematic in [Figure 31](#).

Layout Examples (continued)

12.2.2 SE Application Printed Circuit Board Layout Example

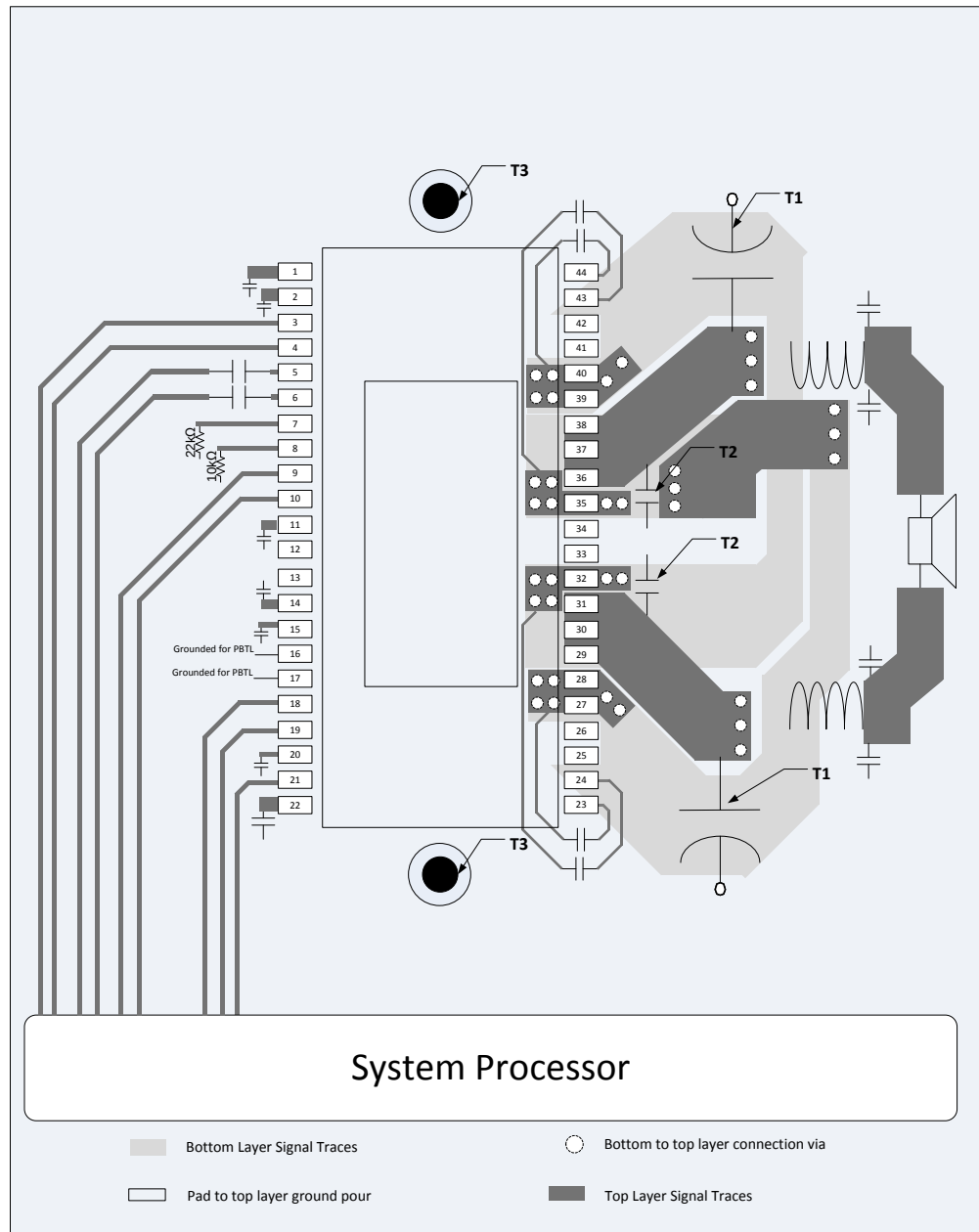


- A. Note: PCB layout example shows composite layout. Dark grey: Top layer copper traces, light gray: Bottom layer copper traces. All PCB area not used for traces should be GND copper pour (transparent on example image)
- B. **Note T1:** PVDD decoupling bulk capacitors should be as close as possible to the PVDD and GND_X pins, the heat sink sets the distance. Wide traces should be routed on the top layer with direct connection to the pins and without going through vias. No vias or traces should be blocking the current path.
- C. **Note T2:** Close decoupling of PVDD with low impedance X7R ceramic capacitors is placed under the heat sink and close to the pins.
- D. **Note T3:** Heat sink needs to have a good connection to PCB ground.

FIG 32. SE Application Printed Circuit Board - Composite

Layout Examples (continued)

12.2.3 PBTL (Outputs Paralleled before LC filter) Application Printed Circuit Board Layout Example

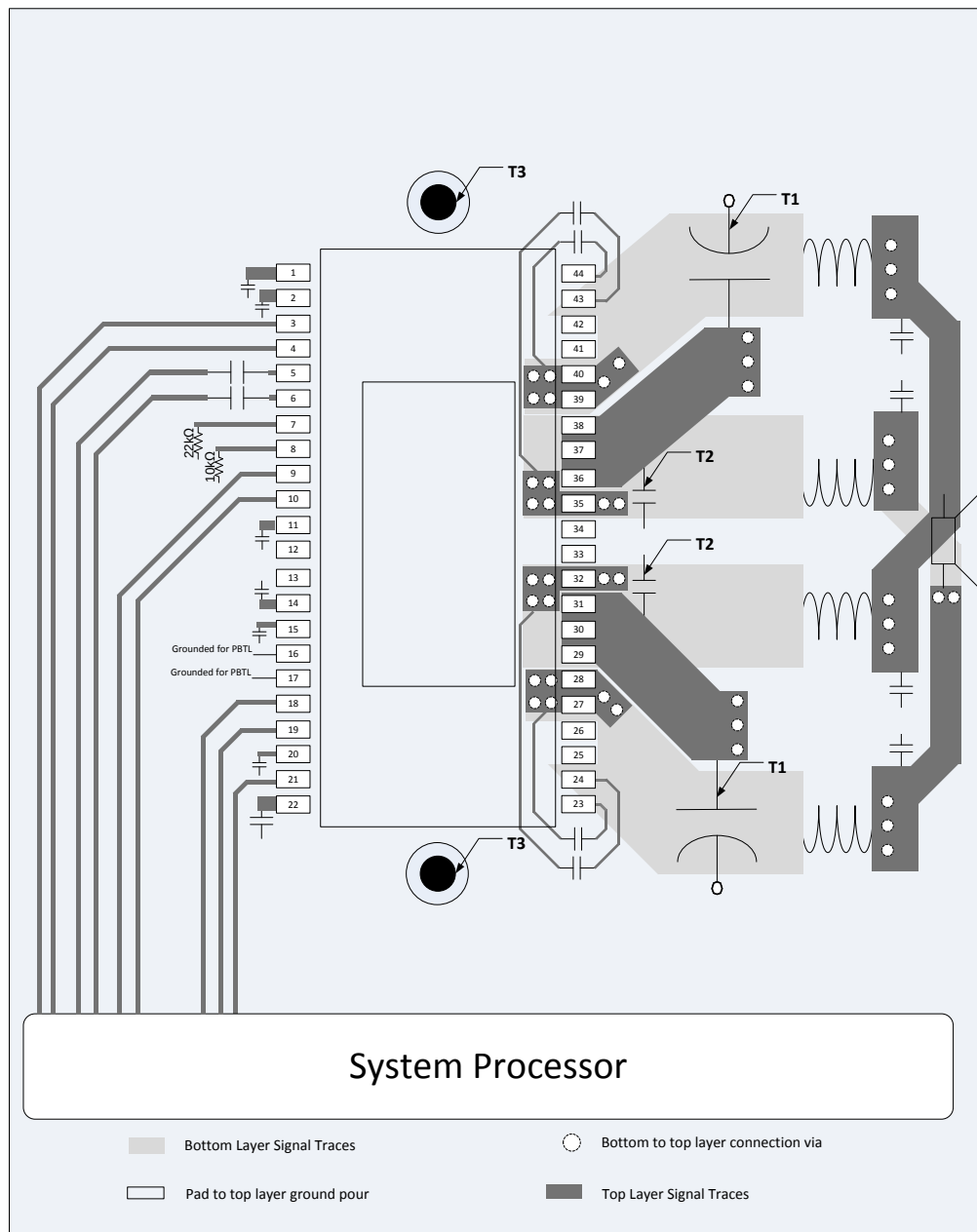


- Note: PCB layout example shows composite layout. Dark grey: Top layer copper traces, light gray: Bottom layer copper traces. All PCB area not used for traces should be GND copper pour (transparent on example image)
- Note T1:** PVDD decoupling bulk capacitors should be as close as possible to the PVDD and GND_X pins, the heat sink sets the distance. Wide traces should be routed on the top layer with direct connection to the pins and without going through vias. No vias or traces should be blocking the current path.
- Note T2:** Close decoupling of PVDD with low impedance X7R ceramic capacitors is placed under the heat sink and close to the pins.
- Note T3:** Heat sink needs to have a good connection to PCB ground.

33. PBTL (Outputs Paralleled before LC filter) Application Printed Circuit Board - Composite

Layout Examples (continued)

12.2.4 PBTL (Outputs Paralleled after LC filter) Application Printed Circuit Board Layout Example



- A. Note: PCB layout example shows composite layout. Dark grey: Top layer copper traces, light gray: Bottom layer copper traces. All PCB area not used for traces should be GND copper pour (transparent on example image)
- B. **Note T1:** PVDD decoupling bulk capacitors should be as close as possible to the PVDD and GND_X pins, the heat sink sets the distance. Wide traces should be routed on the top layer with direct connection to the pins and without going through vias. No vias or traces should be blocking the current path.
- C. **Note T2:** Close decoupling of PVDD with low impedance X7R ceramic capacitors is placed under the heat sink and close to the pins.
- D. **Note T3:** Heat sink needs to have a good connection to PCB ground.

34. PBTL (Outputs Paralleled after LC filter) Application Printed Circuit Board - Composite

13 デバイスおよびドキュメントのサポート

13.1 ドキュメントのサポート

『TPA3245EVMユーザー・ガイド』、[SLVUAG8](#)

13.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。右上の隅にある「通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

13.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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設計サポート *TIの設計サポート* 役に立つE2Eフォーラムや、設計サポート・ツールをすばやく見つけることができます。技術サポート用の連絡先情報も参照できます。

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13.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

14 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPA3245DDV	Active	Production	HTSSOP (DDV) 44	35 TUBE	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	3245
TPA3245DDV.B	Active	Production	HTSSOP (DDV) 44	35 TUBE	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	3245
TPA3245DDVR	Active	Production	HTSSOP (DDV) 44	2000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	3245
TPA3245DDVR.B	Active	Production	HTSSOP (DDV) 44	2000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	0 to 70	3245

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPA3245DDVR	HTSSOP	DDV	44	2000	330.0	24.4	8.6	15.6	1.8	12.0	24.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

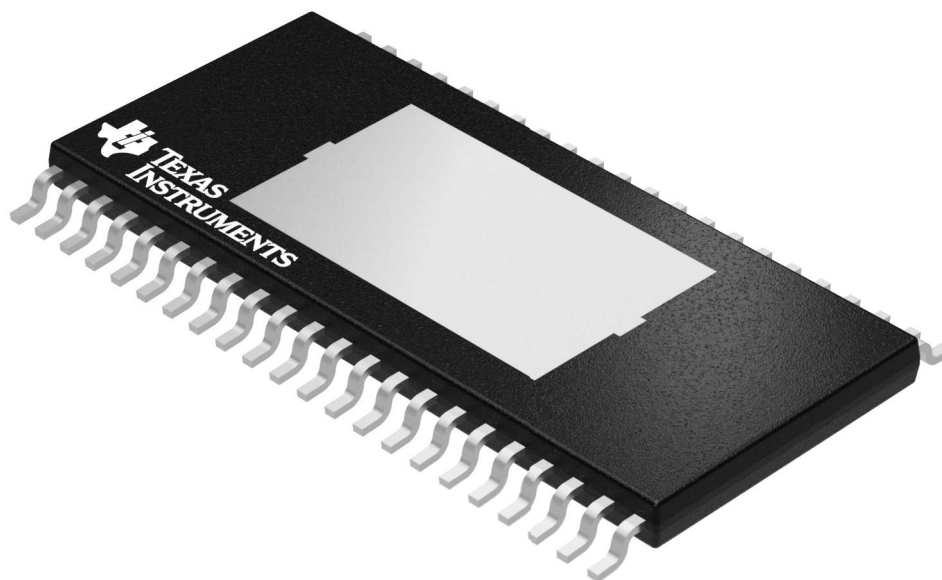
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPA3245DDVR	HTSSOP	DDV	44	2000	350.0	350.0	43.0

TUBE

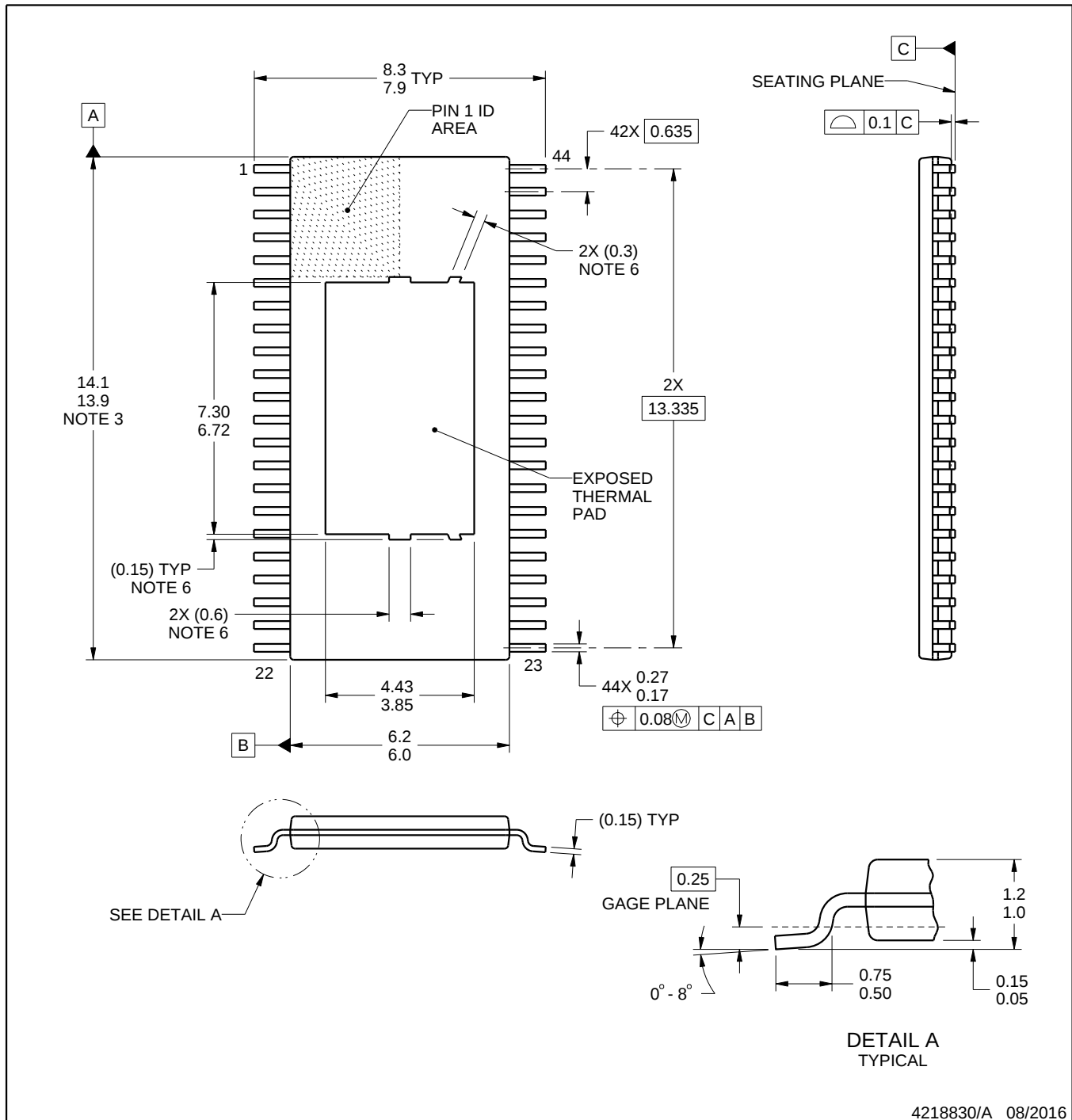
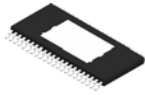


*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TPA3245DDV	DDV	HTSSOP	44	35	530	11.89	3600	4.9
TPA3245DDV.B	DDV	HTSSOP	44	35	530	11.89	3600	4.9



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



NOTES:

PowerPAD is a trademark of Texas Instruments.

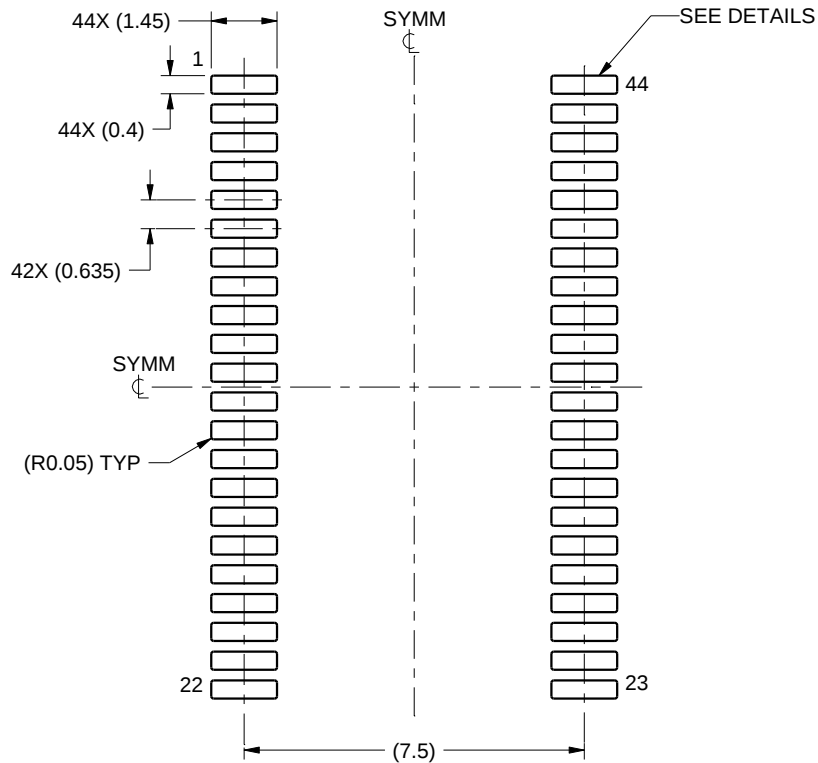
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-153.
5. The exposed thermal pad is designed to be attached to an external heatsink.
6. Features may differ or may not be present.

EXAMPLE BOARD LAYOUT

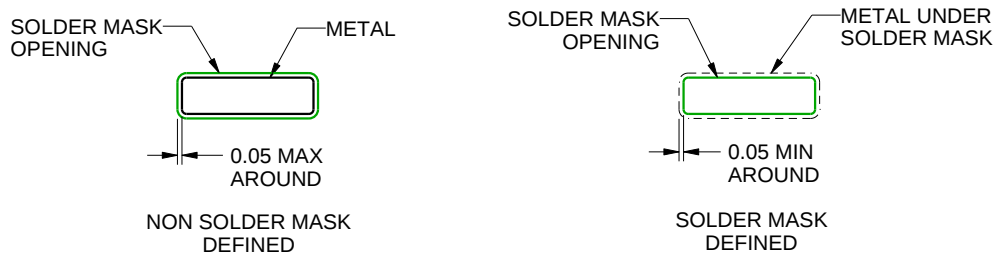
DDV0044D

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE
SCALE:6X



SOLDER MASK DETAILS
NOT TO SCALE

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NOTES: (continued)

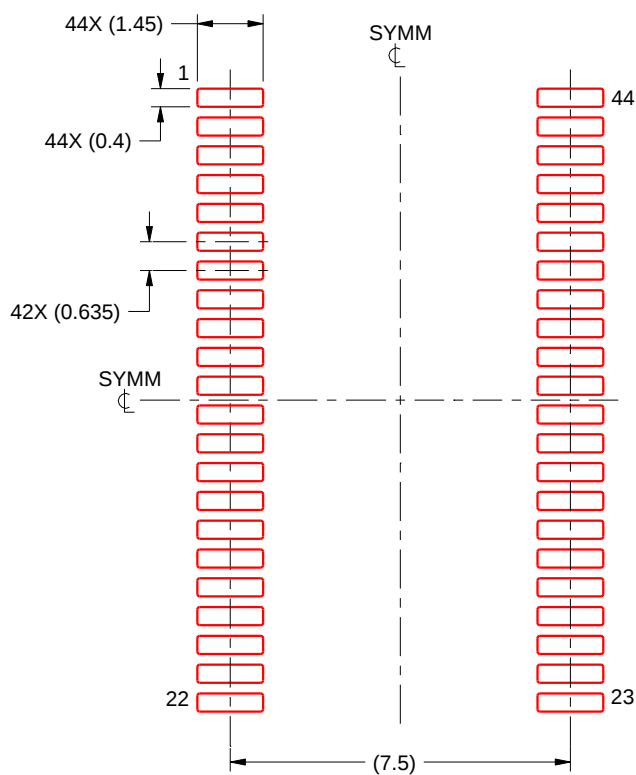
7. Publication IPC-7351 may have alternate designs.
8. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DDV0044D

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE
BASED ON 0.125 MM THICK STENCIL
SCALE :6X

4218830/A 08/2016

NOTES: (continued)

9. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
10. Board assembly site may have different recommendations for stencil design.

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