







DAC5311, DAC6311, DAC7311

JAJS498D - AUGUST 2008 - REVISED AUGUST 2023

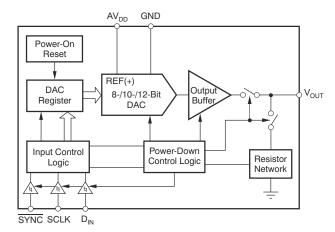
# DACx311 2V~5.5V、80μA、8 ビット、10 ビット、12 ビット、低消費電力、シン グルチャネル、 D/A コンバータ、SC70 パッケージ封止

# 1 特長

- 相対精度:
  - 0.25LSB INL (DAC5311:8 ビット)
  - 0.5LSB INL (DAC6311:10 ビット)
  - 1LSB INL (DAC7311:12 ビット)
- マイクロパワー動作:80µA (2.0V 時)
- パワーダウン:5V で 0.5μA、2.0V で 0.1μA
- 広い電源電圧範囲:2.0V~5.5V
- ゼロ・スケールへのパワーオン・リセット
- ストレート・バイナリ・データ・フォーマット
- シュミット・トリガ入力を持つ低消費電力シリアル・インタ ーフェイス:最高 50MHz
- レール・ツー・レール動作のオンチップ出力バッファ・ア
- SYNC 割り込み機能
- 拡張温度範囲:-40℃~+125℃
- 小型の 6 ピン SC70 パッケージで供給されるピン互換 のファミリ

# 2 アプリケーション

- 携帯型のバッテリ駆動計測機器
- 4mA~20mA のループ電源アプリケーション
- プロセス制御および産業用オートメーション
- プログラム可能な電圧源および電流源



概略回路図

# 3 概要

8 ビット DAC5311、10 ビット DAC6311、12 ビット DAC7311 (DACx311) は、低消費電力、シングル・チャネ ルの電圧出力 D/A コンバータ (DAC) です。通常動作時 の消費電力が低いため (5V で 0.55mW、パワーダウン・ モードでは 2.5µW に低下)、DACx311 は携帯型のバッテ リ駆動アプリケーションに最適です。

これらのデバイスは設計上単調で、優れた直線性を備え ており、不要なコード間過渡電圧が最小限に抑えられてい るうえに、ピン互換のファミリ内で簡単にアップグレードでき ます。すべてのデバイスは、最高 50MHz のクロック・レー トで動作する汎用 3 ワイヤ・シリアル・インターフェイスによ り、SPI、QSPI、Microwire の規格、およびデジタル・シグ ナル・プロセッサ (DSP) との接続に対応しています。

すべてのデバイスは、出力範囲を設定するための基準電 圧として外部電源を使用しています。このデバイスにはパ ワーオン・リセット (POR) 回路が組み込まれており、DAC 出力が OV で起動され、デバイスへの有効な書き込みが 発生するまで OV に維持されます。 DACx311 には、シリア ル・インターフェイスでアクセス可能なパワーダウン機能が 含まれており、パワーダウン・モードではデバイスの消費電 流を 2.0V で 0.1µA にまで低減できます。

これらのデバイスは DAC8311 および DAC8411 とピン互 換であり、8 ビット、10 ビット、12 ビットの分解能から 14 ビ ット、16 ビットの分解能に簡単にアップグレードできます。 すべてのデバイスは小型の 6 ピン SC70 (SOT) パッケー ジで供給されます。このパッケージは、ファミリ内でピン互 換および機能互換の柔軟なドロップイン DAC を提供し、 拡張温度範囲 -40℃~+125℃で動作します

#### 製品情報(1)

部品番号 <sup>(2)</sup>	分解能	パッケージ・サイズ <sup>(3)</sup>
DAC7311	12 ビット	
DAC6311		DCK (SC70、6) 2mm × 1.5mm
DAC5311	8 ビット	

- (1) 利用可能なすべてのパッケージについては、データシートの末尾 にあるパッケージ・オプションについての付録を参照してください。
- 製品比較表を参照してください。
- パッケージ・サイズ (長さ×幅) は公称値であり、該当する場合はピ ンも含まれます。



# **Table of Contents**

2 アプリケーション 1 8.2 Functional Block Diagram. 22 3 数要 1 8.2 Functional Block Diagram. 22 4 Revision History 2 8.4 Device Comparison	1 特長	1 8.1 Overview	<mark>2</mark> 2
8 Pevice Comparison	2 アプリケーション	8.2 Functional Block Diagram	22
8 A Pevice Functional Modes		005 1 5 : 1:	22
5 Device Comparison. 3 9 Application and Functions 3 9 Application and Implementation 27 7 Specifications. 4 9.1 Applications and Implementation 27 7 Specifications. 4 9.1 Application information 27 7 1.1 Absolute Maximum Ratings. 4 9.2 Typical Applications . 28 9.3 Power Supply Recommendations. 28 9.3 Power Supply Recommendations. 31 9.4 Layout. 32 9.3 Power Supply Recommendations. 32 9.3 Power Supply Recommendations. 31 9.4 Layout. 32 9.3 Power Supply Recommendations. 31 9.4 Layout. 32 9.3 Power Supply Recommendations. 33 9.4 Layout. 32 9.3 Power Supply Propose Supply Propose Supply Propose Supply Propose Supply Supply Propose Supply Propose Supply Propose Supply Supply Propose Supply Propos			<mark>2</mark> 4
8 Pin Configuration and Functions. 3 9 Application and Implementation 27 7 Specifications. 4 9.1 Application Information 27 7.1 Absolute Maximum Ratings. 4 9.2 Typical Applications 28 7.2 ESD Ratings. 4 9.3 Power Supply Recommendations. 28 7.3 Recommended Operating Conditions. 4 9.4 Layout. 31 7.3 Recommended Operating Conditions. 4 10 Device and Documentation Support. 32 7.5 Electrical Characteristics. 5 10.1 ドキュメトの更新通知を受け限る方法. 33 7.6 Timing Requirements. 7 10.2 サポート・リソース. 33 7.7 Timing Diagrams. 7 10.3 Trademarks. 33 7.8 Typical Characteristics: AV <sub>DD</sub> = 5 V. 8 10.2 サポート・リソース. 33 7.9 Typical Characteristics: AV <sub>DD</sub> = 2.7 V. 16 8 Detailed Description. 22 11 Mechanical, Packaging, and Orderable Information. 33 10.5 用語集. 35 10.5 Page 10.5 和学工作工作工作工作工作工作工作工作工作工作工作工作工作工作工作工作工作工作工作		3 8.5 Programming	
7. Specifications			27
7.1 Absolute Maximum Ratings. 4 9.2 Typical Applications 28 19.2 Espical Applications 28 19.3 Power Supply Recommendations 31 7.3 Recommended Operating Conditions. 4 17.4 Thermal Information. 4 17.5 Electrical Characteristics. 5 10.1 ドキュメントの更新通知を受け取る方法. 33 7.5 Elypical Characteristics: Wpp = 5 V. 8 10.2 サポートリアース 33 7.8 Typical Characteristics: Wpp = 5 V. 8 10.4 静電気放電に関する注意専項 33 7.9 Typical Characteristics: Wpp = 3.6 V. 15 7.10 Typical Characteristics: Wpp = 2.7 V. 16 8 10 Description. 22 10 Description. 22 10 Description. 33 10.5 用語集 33 1		4 9.1 Application Information	
7.2 ESD Ratings		4 9.2 Typical Applications	
7.3 Recommended Operating Conditions. 4 1 Device and Documentation Support 33 7.5 Electrical Characteristics. 5 10.1 ドネュントの更新通知を受け取る方法. 33 10.1 ドネュントの更新通知を受け取る方法. 33 10.1 ドネュントの更新通知を受け取る方法. 33 10.3 Trademarks. 33 7.8 Typical Characteristics: AV <sub>DD</sub> = 5.V. 8 10.4 静電気放電に関する注音事項. 33 7.9 Typical Characteristics: AV <sub>DD</sub> = 2.7 V. 8 10.3 Trademarks. 33 7.10 Typical Characteristics: AV <sub>DD</sub> = 2.7 V. 16 8 Detailed Description. 22 11 Mechanical, Packaging, and Orderable Information. 33 11 Mechanical, Packaging, and Orderable Information. 34 11 Mechanical, Packaging, and Orderable Information. 35 11 Mechanical, Packaging, and Orderable Information. 36 11 Mechanical, Packaging, and Orderable Information.		4 9.3 Power Supply Recommendations	
7.4 Thermal Information		4 9.4 Layout	
7.6 Timing Requirements			33
7.7 Timing Diagrams	7.5 Electrical Characteristics	5 10.1 ドキュメントの更新通知を受け取る方法	33
7.7 Timing Diagrams 7 10.3 Trademarks 33 7.8 Typical Characteristics: AV <sub>DD</sub> = 5 V. 8 10.4 静電気放電に関する注意事項 33 7.9 Typical Characteristics: AV <sub>DD</sub> = 3.6 V. 16 10.5 用語集 33 10.5 用語集 33 10.5 円記集 33 10.5 円記集 33 10.5 円記集 33 11.5 Piagram 34 Piagram 35 Piagram 36 Piagram 37 Piagram 37 Piagram 36 Piagram 36 Piagram 37 Piagram 38 Piagram	7.6 Timing Requirements	7 10.2 サポート・リソース	33
7.8 Typical Characteristics: AV <sub>DD</sub> = 5 V			33
7.9 Typical Characteristics: AV <sub>DD</sub> = 3.6 V 15 16 8 Detailed Description 22 11 Mechanical, Packaging, and Orderable Information 33			33
7.10 Typical Characteristics: AV <sub>DD</sub> = 2.7 V			33
8 Detailed Description			
4 Revision History 資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。 Changes from Revision C (July 2015) to Revision D (August 2023) Page ・ドキュメント全体にわたって表、図、相互参照の採番方法を更新			33
Changes from Revision B (May 2013) to Revision C (July 2015)  「ESD 定格」表、および「機能説明」、「デバイスの機能モード」、「アプリケーションと実装」、「電源に関する推奨事項」、「レイアウト」、「デバイスおよびドキュメントのサポート」、「メカニカル、パッケージ、および注文情報」の各セクションを追加	<ul> <li>本体サイズではなくパッケージ・サイズを示すよう。</li> <li>Changed power dissipation max value for norr Electrical Characteristics</li> </ul>	うに「製品情報」表を変更し、デバイス間の違いを示す項目 rmal mode at AV <sub>DD</sub> = 3.6 V to 5.5 V from 0.88 mW to	目を追加 1 0.99 mW in 5
・「ESD 定格」表、および「機能説明」、「デバイスの機能モード」、「アプリケーションと実装」、「電源に関する推奨事項」、「レイアウト」、「デバイスおよびドキュメントのサポート」、「メカニカル、パッケージ、および注文情報」の各セクションを追加	Characteristics		5
項」、「レイアウト」、「デバイスおよびドキュメントのサポート」、「メカニカル、パッケージ、および注文情報」の各セクションを追加			
Added Device Comparison section and moved existing tables to this new section	項」、「レイアウト」、「デバイスおよびドキュメントの	)サポート」、「メカニカル、パッケージ、および注文情報」の	り各セクショ
Moved Operating Temperature parameter from Electrical Characteristics table to Recommended Operating Conditions table			
Conditions table			
・ Deleted <i>Parameter Definitions</i> section; definitions moved to new <i>Glossary</i> section			
Changes from Revision A (August 2011) to Revision B (May 2013)Page・ データシート全体にわたってすべての 1.8V を 2.0V に変更1・ Deleted the 1.8-V Typical Characteristics section8・ Changed X-axis for Figure 7-36, Power-Supply Current vs Power-Supply Voltage8・ Changed X-axis for Figure 7-37, Power-Down Current vs Power-Supply Voltage8Changes from Revision * (August, 2008) to Revision A (August, 2011)Page			
<ul> <li>データシート全体にわたってすべての 1.8V を 2.0V に変更</li></ul>	Deleted Parameter Definitions Section; definition	tions moved to new Glossary section	33
<ul> <li>Deleted the 1.8-V Typical Characteristics section.</li> <li>Changed X-axis for Figure 7-36, Power-Supply Current vs Power-Supply Voltage.</li> <li>Changed X-axis for Figure 7-37, Power-Down Current vs Power-Supply Voltage.</li> <li>Changes from Revision * (August, 2008) to Revision A (August, 2011)</li> </ul>			
<ul> <li>Changed X-axis for Figure 7-36, Power-Supply Current vs Power-Supply Voltage</li></ul>	• データシート全体にわたってすべての 1.8V を 2.	2.0V に変更	1
<ul> <li>Changed X-axis for Figure 7-36, Power-Supply Current vs Power-Supply Voltage</li></ul>	• Deleted the 1.8-V Typical Characteristics section	tion	8
<ul> <li>Changed X-axis for Figure 7-37, Power-Down Current vs Power-Supply Voltage</li></ul>			
		, , , ,	
	Changes from Pavision * /August 2009) to Pa	ovicion A (August 2011)	Doco

Submit Document Feedback

Copyright © 2023 Texas Instruments Incorporated

Changed specifications and test conditions for input high voltage parameter......5



# **5 Device Comparison**

#### 表 5-1. Related Devices

RELATED DEVICES	16-BIT	14-BIT	12-BIT	10-BIT	8-BIT
Pin and Function Compatible	DAC8411	DAC8311	DAC7311	DAC6311	DAC5311

# 表 5-2. Relative Accuracy and Differential Nonlinearity

2								
DEVICE	MAXIMUM RELATIVE ACCURACY (LSB)	MAXIMUM DIFFERENTIAL NONLINEARITY (LSB)						
DAC5311	±0.25	±0.25						
DAC6311	±0.5	±0.5						
DAC7311	±1	±1						

# **6 Pin Configuration and Functions**

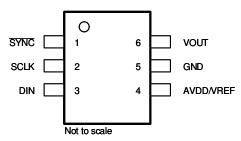


図 6-1. DCK Package, 6-Pin SC70 (Top View)

表 6-1. Pin Functions

PII	N	TYPE	DESCRIPTION
NAME	NO.	1176	DESCRIPTION
AV <sub>DD</sub> /V <sub>REF</sub>	4	Input	Power supply input, 2.0 V to 5.5 V.
D <sub>IN</sub>	3	Input	Serial Data Input. Data are clocked into the 16-bit input shift register on the falling edge of the serial clock input.
GND	5	_	Ground reference point for all circuitry on the part.
SCLK	2	Input	Serial clock input. Data are transferred at rates up to 50 MHz.
SYNC	1	Input	Level-triggered control input (active low). This pin is the frame synchronization signal for the input data. When SYNC goes low, the input shift register is enabled and data are transferred in on the falling edges of the following clocks. The DAC is updated following 16th clock cycle, unless SYNC is taken high before this edge, in which case the rising edge of SYNC acts as an interrupt and the write sequence is ignored by the DACx311. See the SYNC Interrupt section for more details.
V <sub>OUT</sub>	6	Output	Analog output voltage from DAC. The output amplifier has rail-to-rail operation.



# 7 Specifications

# 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) (1)

			MIN	MAX	UNIT
		AV <sub>DD</sub> to GND	-0.3	+6	V
	Voltage	Digital input voltage to GND	-0.3	+AV <sub>DD</sub> + 0.3	V
		V <sub>OUT</sub> to GND	-0.3	+AV <sub>DD</sub> + 0.3	V
TJ	Junction temperature			150	°C
T <sub>stg</sub>	Storage temperatur	е	-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# 7.2 ESD Ratings

			VALUE	UNIT
, Licotrostatio	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	\/	
V(ESD)	V <sub>(ESD)</sub>	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	v

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

# 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
T <sub>A</sub>	Operating temperature	-40	-	125	°C
$AV_{DD}$	Supply voltage	2		5.5	V

#### 7.4 Thermal Information

		DACx311	
	THERMAL METRIC <sup>(1)</sup>	DCK (SC70)	UNIT
		6 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	216.4	°C/W
R <sub>0</sub> JC(top)	Junction-to-case (top) thermal resistance	52.1	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	65.9	°C/W
ΨЈТ	Junction-to-top characterization parameter	1.3	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	65.2	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the application report, Semiconductor and IC Package Thermal Metrics application note.

Submit Document Feedback

Copyright © 2023 Texas Instruments Incorporated

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



# 7.5 Electrical Characteristics

at AV<sub>DD</sub> = 2.0 V to 5.5 V, R<sub>L</sub> = 2 k $\Omega$  to GND, C<sub>L</sub> = 200 pF to GND, and T<sub>A</sub> = -40°C to +125°C (unless otherwise noted)

P	ARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
STATIC PERFO	RMANCE <sup>(1)</sup>					
DAC5311			8			Bits
DAC6311	Resolution		10			Bits
DAC7311			12			Bits
DAC5311		Measured by the line passing through codes 3 and 252		±0.01	±0.25	LSB
DAC6311	Relative accuracy	Measured by the line passing through codes 12 and 1012		±0.06	±0.5	LSB
DAC7311		Measured by the line passing through codes 30 and 4050		±0.3	±1	LSB
DAC5311				±0.01	±0.25	LSB
DAC6311	Differential nonlinearity			±0.03	±0.5	LSB
DAC7311	Tionimeanty			±0.2	±1	LSB
Offset error		Measured by the line passing through two codes <sup>(2)</sup>		±0.05	±4	mV
Offset error drift				3		μV/°C
Zero code error		All zeros loaded to the DAC register		0.2		mV
Full-scale error		All ones loaded to DAC register		0.04	0.2	% of FSR
Gain error				0.05	±0.15	% of FSR
Gain temperature coefficient		AV <sub>DD</sub> = 5 V		±0.5		ppm of
Gain temperatur	e coemcient	AV <sub>DD</sub> = 2.0 V		±1.5		FSR/°C
OUTPUT CHAR	ACTERISTICS					
Output voltage ra	ange		0		$AV_DD$	V
Output voltage s	ettling time <sup>(3)</sup>	$R_L$ = 2 k $\Omega$ , $C_L$ = 200 pF, $AV_{DD}$ = 5 V, 1/4 scale to 3/4 scale		6	10	μs
		$R_L = 2 M\Omega$ , $C_L = 470 pF$		12		μs
Slew rate				0.7		V/µs
Capacitive load s	stability	R <sub>L</sub> = ∞		470		pF
Capacitive load s	Stability	$R_L = 2 k\Omega$		1000		pF
Code change gli	tch impulse	1 LSB change around major carry		0.5		nV-s
Digital feedthrou	gh			0.5		nV-s
Power-on glitch i	impulse	$R_L = 2 k\Omega$ , $C_L = 200 pF$ , $AV_{DD} = 5 V$		17		mV
DC output imped	lance			0.5		Ω
Chart aircuit aur	ant	AV <sub>DD</sub> = 5 V		50		mA
Short circuit current		AV <sub>DD</sub> = 3 V		20		mA
Power-up time		Coming out of power-down mode		50		μs
AC PERFORMA	NCE	-				
SNR				81		dB
THD		T <sub>A</sub> = 25°C, BW = 20 kHz, 12-bit level,		-65		dB
SFDR		AV <sub>DD</sub> = 5 V, f <sub>OUT</sub> = 1 kHz, 1st 19 harmonics removed for SNR calculation		65		dB
SFUR		Terrioved for SINK calculation		•		



# 7.5 Electrical Characteristics (continued)

at AV<sub>DD</sub> = 2.0 V to 5.5 V, R<sub>L</sub> = 2 k $\Omega$  to GND, C<sub>L</sub> = 200 pF to GND, and T<sub>A</sub> = -40°C to +125°C (unless otherwise noted)

PAR	AMETER	TEST (	CONDITIONS	MIN	TYP	MAX	UNIT
DAC output noise d	longity(4)	$T_A = 25$ °C, at zero- $f_{OUT} = 1$ kHz, AV <sub>DD</sub>			17		nV/√ <del>Hz</del>
' '		$T_A = 25$ °C, at mid-or $f_{OUT} = 1$ kHz, $AV_{DD}$			110		nV/√ <del>Hz</del>
DAC output noise <sup>(5</sup>	)	T <sub>A</sub> = +25°C, at mid- 0.1 Hz to 10 Hz, AV			3		μV <sub>PP</sub>
LOGIC INPUTS(3)							
Input current						±1	μA
V <sub>IN</sub> L, Input low voltage		AV <sub>DD</sub> = 2.7 V to 5.5	V			$0.3 \times AV_{DD}$	V
V <sub>IN</sub> L, input low voice	age	AV <sub>DD</sub> = 2.0 V to 2.7	V		0.3 × AV <sub>DD</sub> 0.1 × AV <sub>DD</sub> 0 1.5 3 1.5 3 110 180 95 150 80 140	V	
\/	H, Input high voltage $ \frac{\text{AV}_{\text{DD}} = 2.7 \text{ V to } 5.5 \text{ V}}{\text{AV}_{\text{DD}} = 2.0 \text{ V to } 2.7 \text{ V}}                                 $		V	$0.7 \times AV_{DD}$			V
V <sub>IN</sub> H, input nigh voi				V			
Pin capacitance					1.5	3	pF
POWER REQUIRE	MENTS						
$AV_{DD}$				2.0		5.5	V
		V <sub>IN</sub> H = AV <sub>DD</sub> and	AV <sub>DD</sub> = 3.6 V to 5.5 V		110	180	μA
	Normal mode	$V_{IN}L = GND$ , at	AV <sub>DD</sub> = 2.7 V to 3.6 V		95	17 110 3  ±1 0.3 × AV <sub>DD</sub> 0.1 × AV <sub>DD</sub> 1.5 3  5.5 110 180 95 150	μA
I		midscale code <sup>(6)</sup>	AV <sub>DD</sub> = 2.0 V to 2.7 V		80		μA
'DD		$V_{IN}H = AV_{DD}$ and	AV <sub>DD</sub> = 3.6 V to 5.5 V		0.5	3.5	μΑ
	All power-down mode	$V_{IN}L = GND$ , at	AV <sub>DD</sub> = 2.7 V to 3.6 V		0.4	3	μΑ
	mi		AV <sub>DD</sub> = 2.0 V to 2.7 V		0.1	2	μA
		$V_{IN}H = AV_{DD}$ and	AV <sub>DD</sub> = 3.6 V to 5.5 V		0.55	0.99	mW
$V_{\text{IN}\text{L}, \text{ Input low voltage}} \\ \hline V_{\text{IN}\text{H}, \text{ Input high voltage}} \\ \hline V_{\text{IN}\text{D}} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline AV_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.7 \times \text{AV}_{DD} \\ \hline AV_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} \\ \hline AV_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} \\ \hline AV_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 3.6 \text{ V to } 5.5 \text{ V} \\ \hline AV_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.9 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 \text{ V} \\ \hline 0.1 \times \text{AV}_{DD} = 2.0 \text{ V to } 2.7 $	0.54	mW					
Dower dissination		midscale code <sup>(6)</sup>	AV <sub>DD</sub> = 2.0 V to 2.7 V		0.14	0.38	mW
Pin capacitance POWER REQUIRE AVDD		$V_{IN}H = AV_{DD}$ and	AV <sub>DD</sub> = 3.6 V to 5.5 V		2.50	19.2	μW
	All power-down mode	$V_{IN}L = GND$ , at	AV <sub>DD</sub> = 2.7 V to 3.6 V		1.08	10.8	μW
		midscale code <sup>(6)</sup>	AV <sub>DD</sub> = 2.0 V to 2.7 V		0.72	8.1	μW

<sup>(1)</sup> Linearity calculated using a reduced code range of 3 to 252 for 8-bit, 12 to 1012 for 10bit, and 30 to 4050 for 12-bit, output unloaded.

Submit Document Feedback

Copyright © 2023 Texas Instruments Incorporated

<sup>(2)</sup> Straight line passing through codes 3 and 252 for 8-bit, 12 and 1012 for 10-bit, and 30 and 4050 for 12-bit, output unloaded.

<sup>(3)</sup> Specified by design and characterization, not production tested.

<sup>(4)</sup> For more details, see 🗵 7-23.

<sup>(5)</sup> For more details, see ℤ 7-24.

<sup>(6)</sup> For more details, see 🗵 7-16 and 🗵 7-58.



# 7.6 Timing Requirements

at –40°C to 125°C, and AV<sub>DD</sub> = 2 V to 5.5 V (unless otherwise noted) $^{(1)}$ 

			MIN	NOM MAX	UNIT
f	Serial clock frequency	AV <sub>DD</sub> = 2.0 V to 3.6 V		20	MHz
f <sub>(SCLK)</sub>	Senai clock frequency	AV <sub>DD</sub> = 3.6 V to 5.5 V		50	IVITIZ
	SCI K avalatima	AV <sub>DD</sub> = 2.0 V to 3.6 V	50		200
t <sub>1</sub>	SCLK cycle time	AV <sub>DD</sub> = 3.6 V to 5.5 V	20		ns
	SCI K high time	AV <sub>DD</sub> = 2.0 V to 3.6 V	25		no
t <sub>2</sub>	SCLK high time	AV <sub>DD</sub> = 3.6 V to 5.5 V	$AV_{DD} = 2.0 \text{ V to } 3.6 \text{ V}$ $AV_{DD} = 3.6 \text{ V to } 5.5 \text{ V}$ $AV_{DD} = 2.0 \text{ V to } 3.6 \text{ V}$ $AV_{DD} = 3.6 \text{ V to } 5.5 \text{ V}$ $AV_{DD} = 3.6 \text{ V to } 5.5 \text{ V}$ $AV_{DD} = 2.0 \text{ V to } 3.6 \text{ V}$ $20$		ns
	SCLK low time	AV <sub>DD</sub> = 2.0 V to 3.6 V	25	20 50 50 20 25 10 25 10 0 0 5 4.5 4.5 4.5 0 0 0 50 20 100 100	no
t <sub>3</sub>	SCLN low little	AV <sub>DD</sub> = 3.6 V to 5.5 V	20 50 20 25 10 25 10 0 0 5 5 4.5 4.5 4.5 0 0 0 50 20 100 100 15		ns
	CVNC to CCL // vising adap actual time	AV <sub>DD</sub> = 2.0 V to 3.6 V	0		no
t <sub>4</sub>	SYNC to SCLK rising edge setup time	AV <sub>DD</sub> = 3.6 V to 5.5 V	0		ns
+_	Data actus tima	AV <sub>DD</sub> = 2.0 V to 3.6 V	5		
t <sub>5</sub>	Data setup time	AV <sub>DD</sub> = 3.6 V to 5.5 V	5		ns
	Data hald time	AV <sub>DD</sub> = 2.0 V to 3.6 V	4.5		200
t <sub>6</sub>	Data hold time	AV <sub>DD</sub> = 3.6 V to 5.5 V	0 0 5 5 4.5 4.5 0	ns	
	COLV falling adds to CVNC vising adds	AV <sub>DD</sub> = 2.0 V to 3.6 V	0		no
t <sub>7</sub>	SCLK falling edge to SYNC rising edge	AV <sub>DD</sub> = 3.6 V to 5.5 V	0	50 50 20 25 10 25 10 0 0 5 5 4.5 4.5 4.5 0 0 0 100 100 15	ns
	Minimum SYNC high time	AV <sub>DD</sub> = 2.0 V to 3.6 V	50		no
t <sub>8</sub>	Millimum Stric night time	AV <sub>DD</sub> = 3.6 V to 5.5 V	20		ns
	404b 000 K falling and an to OVALO falling address	AV <sub>DD</sub> = 2.0 V to 3.6 V	100		
t <sub>9</sub>	16th SCLK falling edge to SYNC falling edge	AV <sub>DD</sub> = 3.6 V to 5.5 V	100		ns
	SYNC rising edge to 16th SCLK falling edge	AV <sub>DD</sub> = 2.0 V to 3.6 V	15		
t <sub>10</sub>	(for successful SYNC interrupt)	AV <sub>DD</sub> = 3.6 V to 5.5 V	15		ns

<sup>(1)</sup> All input signals are specified with  $t_R = t_F = 3$  ns (10% to 90% of AV<sub>DD</sub>) and timed from a voltage level of (V<sub>IL</sub> + V<sub>IH</sub>) / 2.

# 7.7 Timing Diagrams

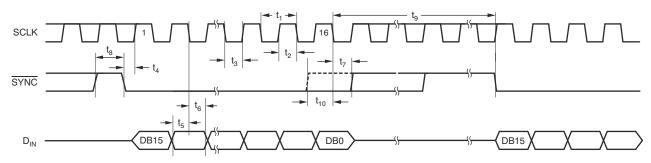
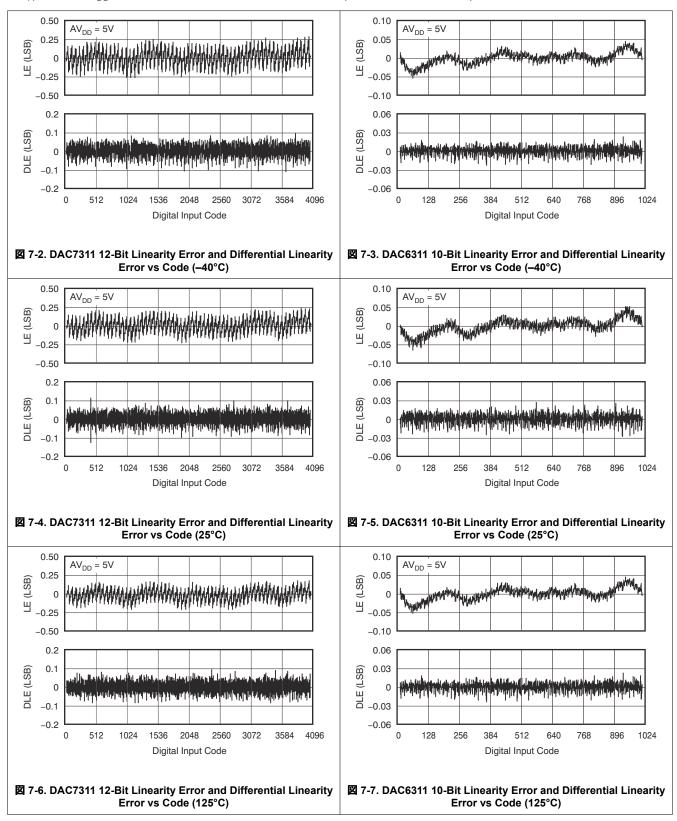


図 7-1. Serial Write Operation



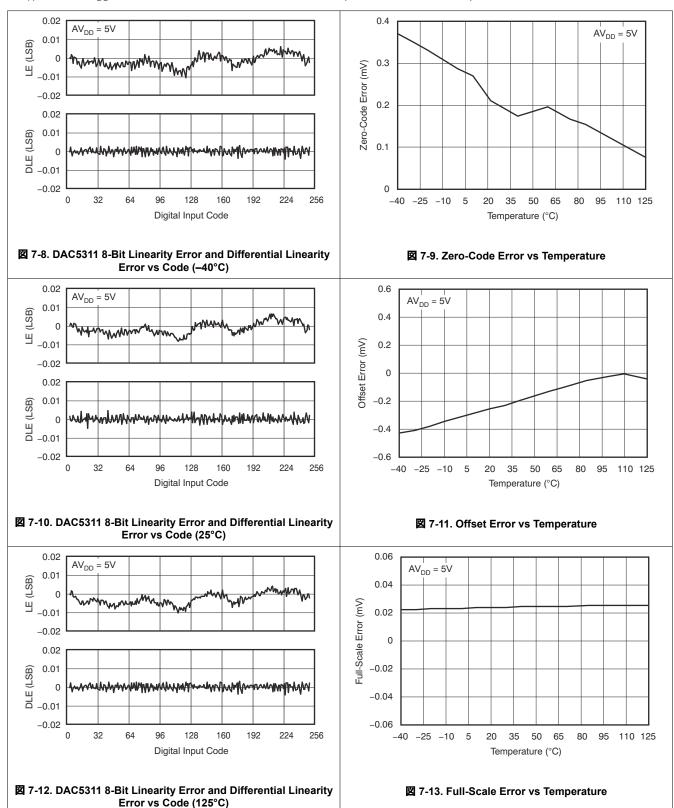
# 7.8 Typical Characteristics: $AV_{DD} = 5 \text{ V}$

at T<sub>A</sub> = 25°C, AV<sub>DD</sub> = 5 V, and DAC loaded with midscale code (unless otherwise noted)



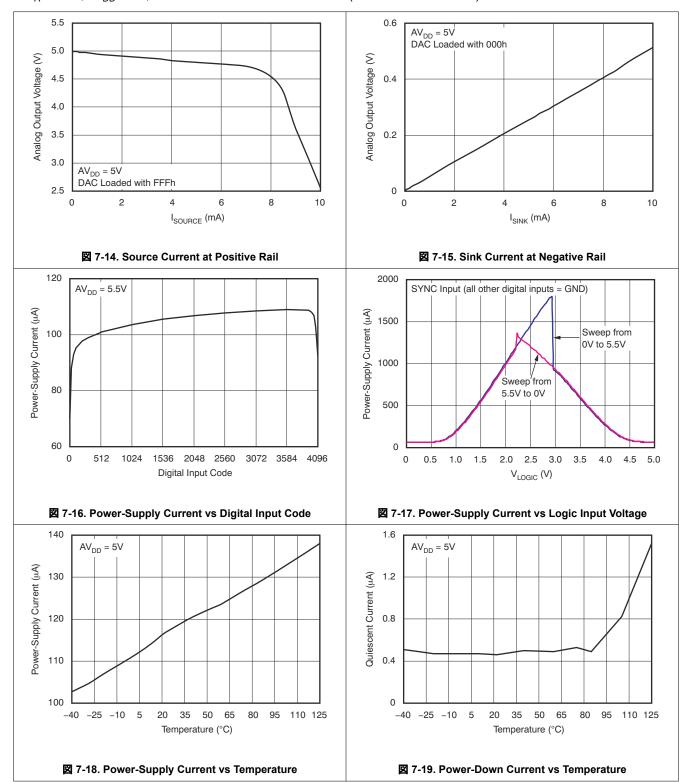


at  $T_A = 25$ °C,  $AV_{DD} = 5$  V, and DAC loaded with midscale code (unless otherwise noted)



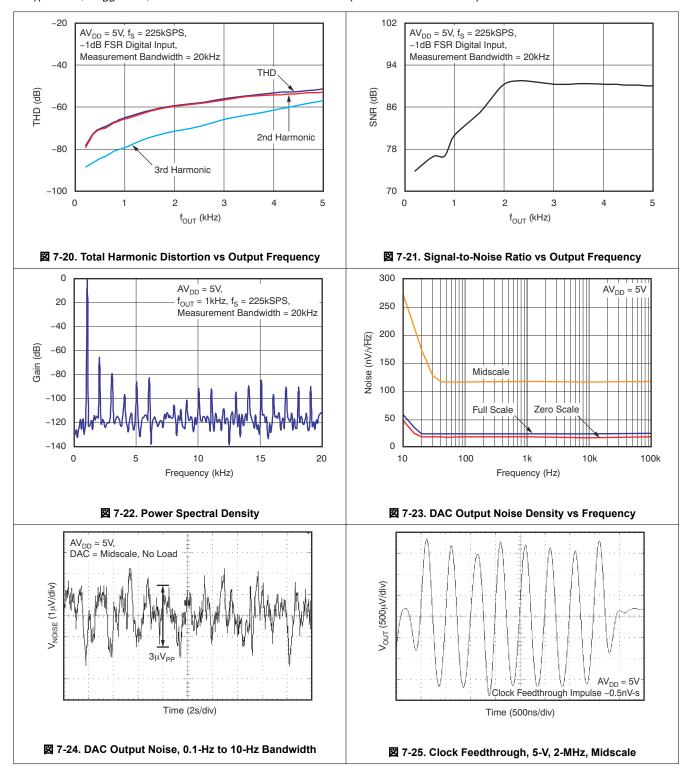


at  $T_A$  = 25°C, AV<sub>DD</sub> = 5 V, and DAC loaded with midscale code (unless otherwise noted)





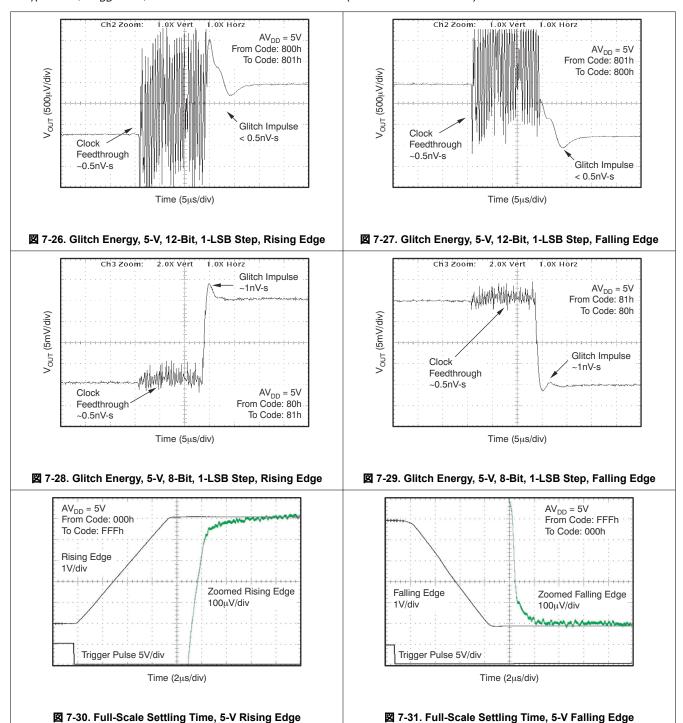
at  $T_A = 25$ °C,  $AV_{DD} = 5$  V, and DAC loaded with midscale code (unless otherwise noted)





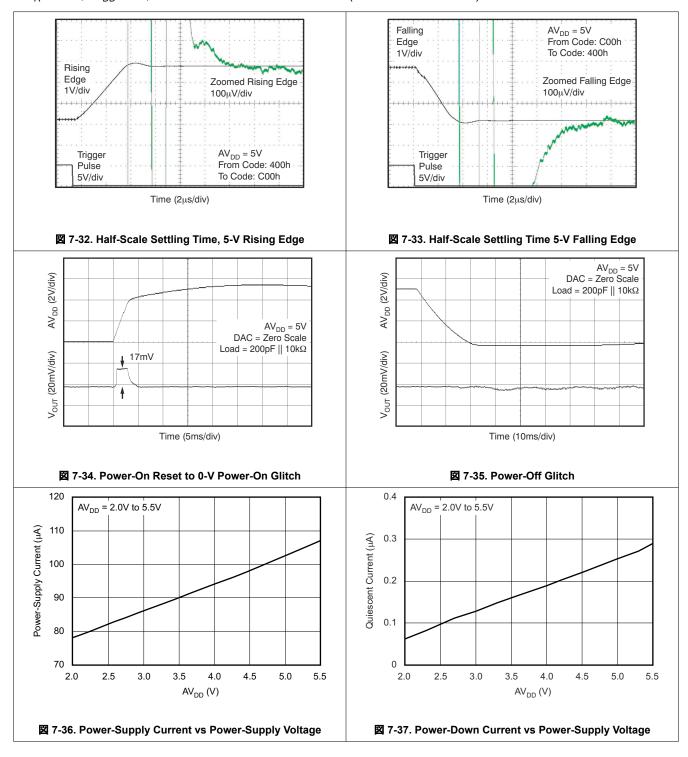
# 7.8 Typical Characteristics: $AV_{DD} = 5 \text{ V}$ (continued)

at  $T_A = 25$ °C,  $AV_{DD} = 5$  V, and DAC loaded with midscale code (unless otherwise noted)





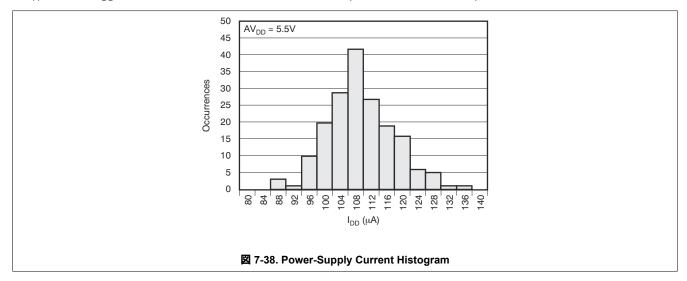
at  $T_A = 25$ °C,  $AV_{DD} = 5$  V, and DAC loaded with midscale code (unless otherwise noted)





# 7.8 Typical Characteristics: $AV_{DD} = 5 V$ (continued)

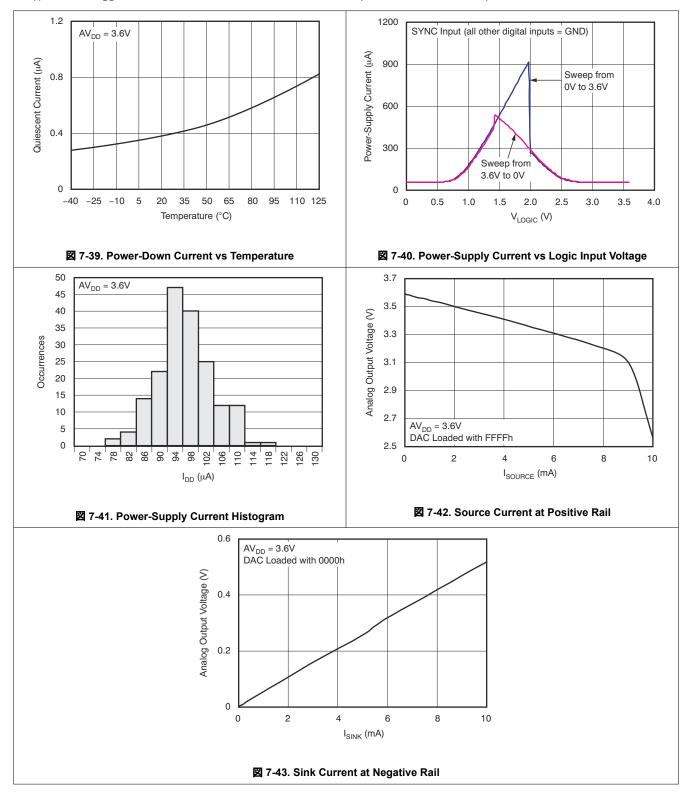
at  $T_A$  = 25°C, AV<sub>DD</sub> = 5 V, and DAC loaded with midscale code (unless otherwise noted)





# 7.9 Typical Characteristics: $AV_{DD} = 3.6 V$

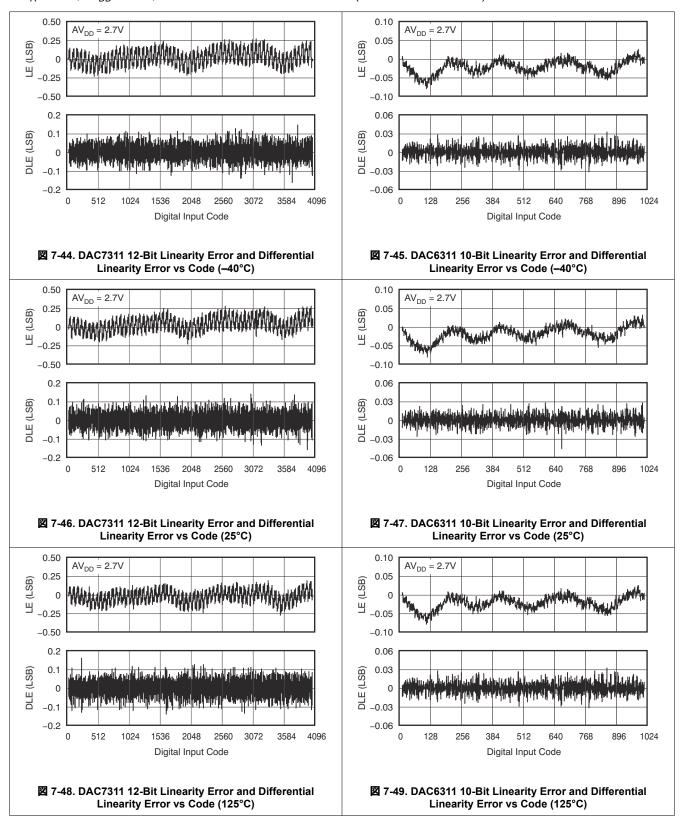
at  $T_A = 25$ °C,  $AV_{DD} = 3.6$  V, and DAC loaded with midscale code (unless otherwise noted)





### 7.10 Typical Characteristics: $AV_{DD} = 2.7 \text{ V}$

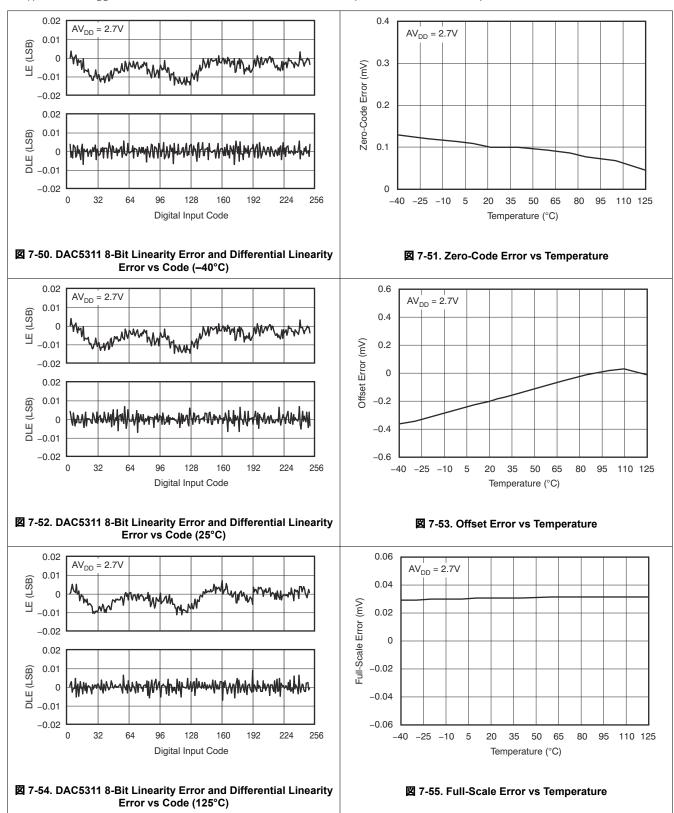
at T<sub>A</sub> = 25°C, AV<sub>DD</sub> = 2.7 V, and DAC loaded with midscale code (unless otherwise noted)





# 7.10 Typical Characteristics: $AV_{DD} = 2.7 \text{ V (continued)}$

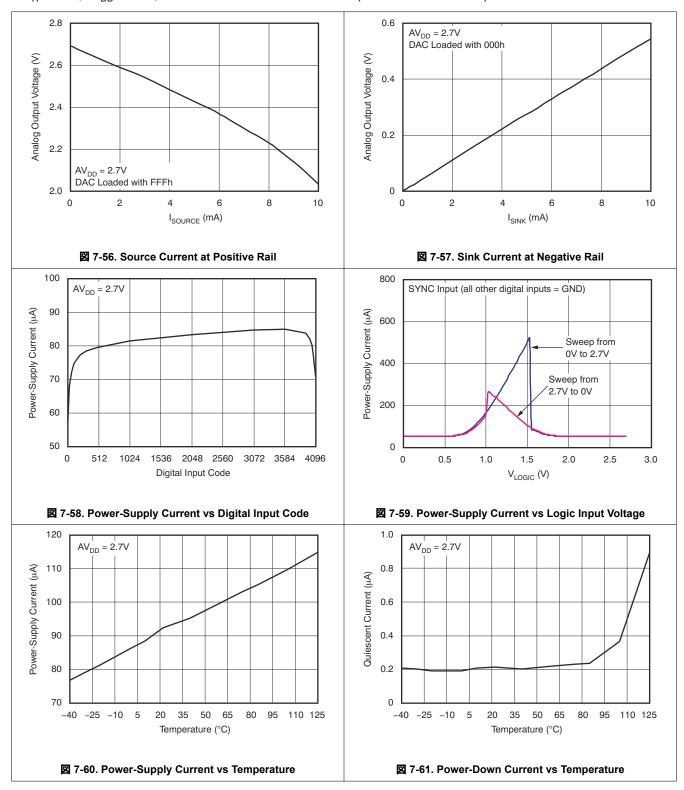
at  $T_A = 25$ °C,  $AV_{DD} = 2.7$  V, and DAC loaded with midscale code (unless otherwise noted)





# 7.10 Typical Characteristics: $AV_{DD} = 2.7 \text{ V (continued)}$

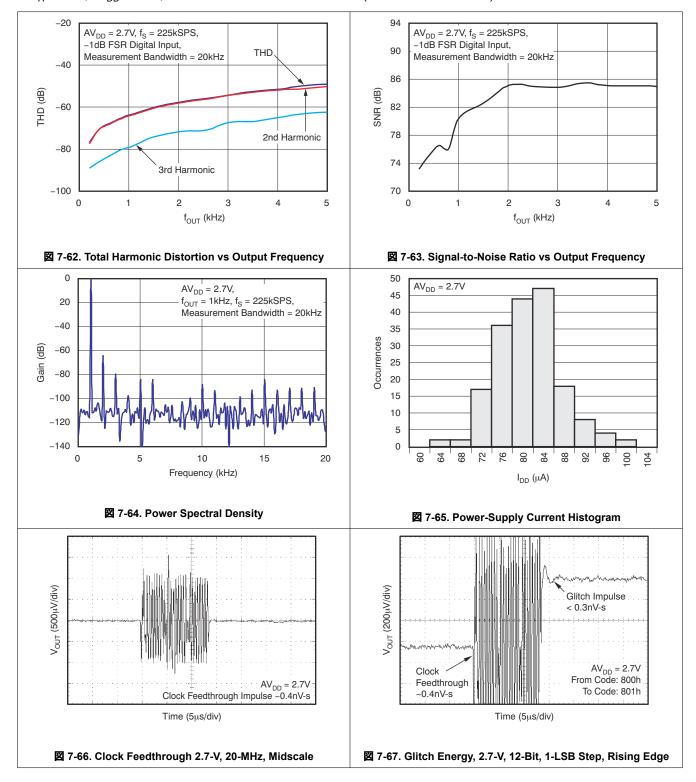
at  $T_A$  = 25°C, AV<sub>DD</sub> = 2.7 V, and DAC loaded with midscale code (unless otherwise noted)





# 7.10 Typical Characteristics: $AV_{DD} = 2.7 \text{ V}$ (continued)

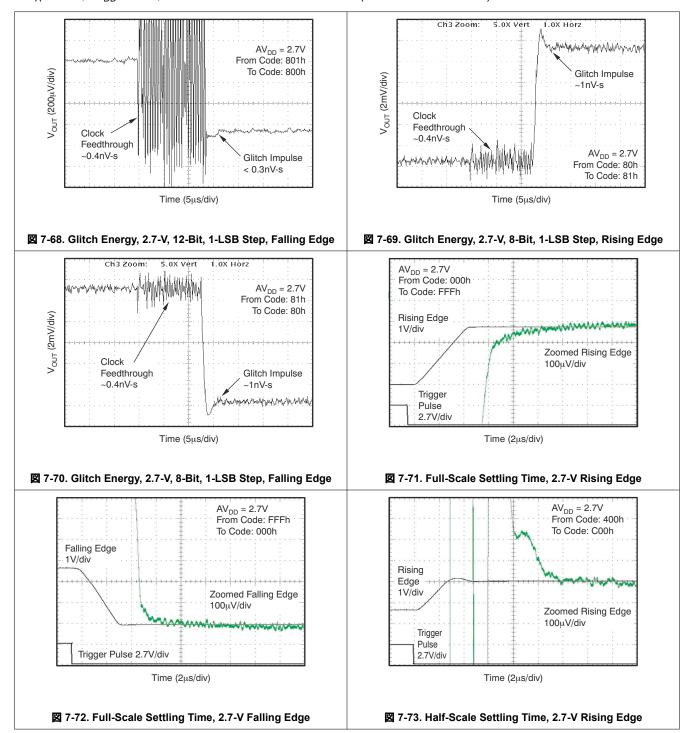
at  $T_A = 25$ °C,  $AV_{DD} = 2.7$  V, and DAC loaded with midscale code (unless otherwise noted)





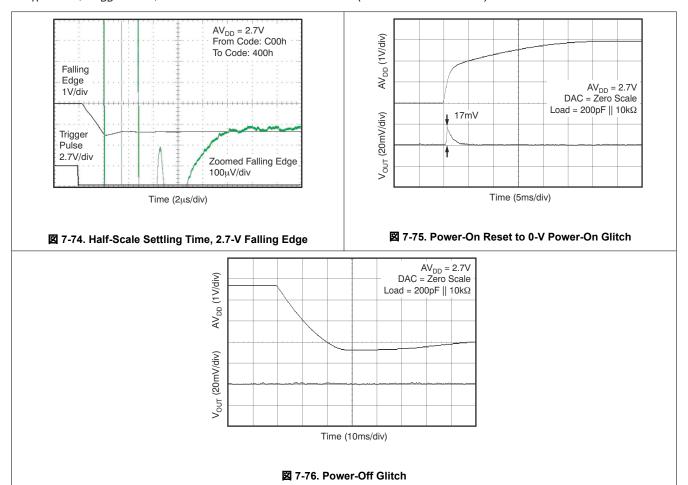
# 7.10 Typical Characteristics: $AV_{DD} = 2.7 \text{ V}$ (continued)

at  $T_A = 25$ °C,  $AV_{DD} = 2.7$  V, and DAC loaded with midscale code (unless otherwise noted)





at  $T_A = 25$ °C,  $AV_{DD} = 2.7$  V, and DAC loaded with midscale code (unless otherwise noted)

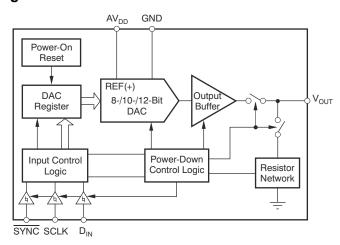


# 8 Detailed Description

#### 8.1 Overview

The 8-bit DAC5311, 10-bit DAC6311, and 12-bit DAC7311 devices (DACx311) are low-power, single-channel, voltage output DACs. These devices are monotonic by design, provide excellent linearity, and minimize undesired code-to-code transient voltages while offering an easy upgrade path within a pin-compatible family. All devices use a versatile, three-wire serial interface that operates at clock rates of up to 50 MHz and is compatible with standard SPI, QSPI, Microwire, and digital signal processor (DSP) interfaces.

#### 8.2 Functional Block Diagram



# 8.3 Feature Description

#### 8.3.1 DAC Section

The DACx311 are fabricated using Texas Instruments' proprietary HPA07 process technology. The architecture consists of a string DAC followed by an output buffer amplifier. Because there is no reference input pin, the power supply  $(AV_{DD})$  acts as the reference.  $\boxtimes$  8-1 shows a block diagram of the DAC architecture.

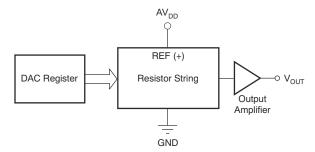


図 8-1. DACx311 Architecture

The input coding to the DACx311 is straight binary, so the ideal output voltage is given by:

$$V_{OUT} = AV_{DD} \times \frac{D}{2^n}$$
 (1)

#### where

- n = resolution in bits; either 8 (DAC5311), 10 (DAC6311), or 12 (DAC7311).
- D = decimal equivalent of the binary code that is loaded to the DAC register. D ranges from 0 to 255 for 8-bit DAC5311, 0 to 1023 for the 10-bit DAC6311, and 0 to 4095 for the 12-bit DAC7311.

Submit Document Feedback

Copyright © 2023 Texas Instruments Incorporated

#### 8.3.2 Resistor String

⊠ 8-2 shows the resistor string section, which is a string of resistors, each of value R. The code loaded into the DAC register determines at which node on the string the voltage is tapped off to be fed into the output amplifier by closing one of the switches connecting the string to the amplifier. The resistor string architecture is inherently monotonic.

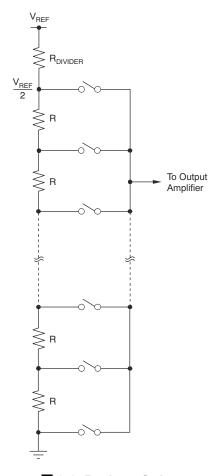


図 8-2. Resistor String

#### 8.3.3 Output Amplifier

The output buffer amplifier is capable of generating rail-to-rail voltages on the output, which gives an output range of 0 V to  $AV_{DD}$ . The output amplifier is capable of driving a load of 2 k $\Omega$  in parallel with 1000 pF to GND. The source and sink capabilities of the output amplifier can be seen in the *Typical Characteristics* section for the given voltage input. The slew rate is 0.7 V/ $\mu$ s with a half-scale settling time of typically 6  $\mu$ s with the output unloaded.

#### 8.3.4 Power-On Reset

The DACx311 contain a power-on reset circuit that controls the output voltage during power up. On power up, the DAC register is filled with zeros and the output voltage is 0 V. The DAC register remains that way until a valid write sequence is made to the DAC. This design is useful in applications where knowing the state of the DAC output while powering up is important.

The occurring power-on glitch impulse is only a few millivolts (typically, 17 mV; see 🗵 7-34).

#### 8.4 Device Functional Modes

#### 8.4.1 Power-Down Modes

The DACx311 contain four separate modes of operation. These modes are programmable by setting two bits (PD1 and PD0) in the control register. 表 8-1 shows how the state of the bits corresponds to the mode of operation of the device.

表 8-1. Modes of Operation for the DACx311

PD1	PD0	OPERATING MODE								
NORMA	NORMAL MODE									
0	0 0 Normal Operation									
POWER	POWER-DOWN MODES									
0	1	Output 1 kΩ to GND								
1	0	Output 100 kΩ to GND								
1	1	High-Z								

When both bits are set to 0, the device works normally with a standard power consumption of typically 80  $\mu$ A at 2 V. However, for the three power-down modes, the typical supply current falls to 0.5  $\mu$ A at 5 V, 0.4  $\mu$ A at 3 V, and 0.1  $\mu$ A at 2 V. Not only does the supply current fall, but the output stage is also internally switched from the output of the amplifier to a resistor network of known values. The advantage of this architecture is that the output impedance of the part is known while the part is in power-down mode. There are three different options: the output is connected internally to GND either through a 1-k $\Omega$  resistor or a 100-k $\Omega$  resistor, or is left open-circuited (High-Z).  $\boxtimes$  8-3 illustrates the output stage.

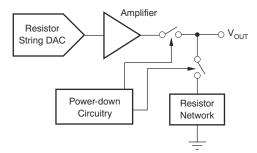


図 8-3. Output Stage During Power-Down

All linear circuitry is shut down when the power-down mode is activated. However, the contents of the DAC register are unaffected when in power-down. The time to exit power-down is typically 50  $\mu$ s for AV<sub>DD</sub> = 5 V and AV<sub>DD</sub> = 3 V.

Submit Document Feedback

Copyright © 2023 Texas Instruments Incorporated

# 8.5 Programming

#### 8.5.1 Serial Interface

The DACx311 has a 3-wire serial interface (SYNC, SCLK, and DIN) compatible with SPI, QSPI, and Microwire interface standards, as well as most DSPs. For an example of a typical write sequence, see  $\boxtimes$  7-1.

#### 8.5.1.1 Input Shift Register

The input shift register is 16 bits wide, as shown in  $\frac{1}{8}$  8-2. The first two bits (PD0 and PD1) are reserved control bits that set the desired mode of operation (normal mode or any one of three power-down modes) as indicated in  $\frac{1}{8}$  8-1.

The remaining data bits are either 12 (DAC7311), 10 (DAC6311), or 8 (DAC5311) data bits, followed by *don't care* bits, as shown in 表 8-2, 表 8-3, and 表 8-4, respectively.

#### 表 8-2. DAC5311 8-Bit Data Input Register

DB15	DB14								DB6	DB5					DB0
PD1	PD0	D7	D6	D5	D4	D3	D2	D1	D0	Х	Х	Х	Х	Х	Х

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

### 表 8-3. DAC6311 10-Bit Data Input Register

DB15	DB14										DB4	DB3			DB0
PD1	PD0	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Χ	Χ	Х	Х

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# 表 8-4. DAC7311 12-Bit Data Input Register

DE	315	DB14												DB2	DB1	DB0
PI	D1	PD0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Х	X

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

The write sequence begins by bringing the SYNC line low. Data from the DIN line are clocked into the 16-bit shift register on each falling edge of SCLK. The serial clock frequency can be as high as 50 MHz, making

the DACx311 compatible with high-speed DSPs. On the 16th falling edge of the serial clock, the last data bit is clocked in and the programmed function is executed.

At this point, the SYNC line can be kept low or brought high. In either case, SYNC must be brought high for a minimum of 20 ns before the next write sequence so that a falling edge of SYNC can initiate the next write sequence.

### 8.5.1.2 SYNC Interrupt

In a normal write sequence, the  $\overline{\text{SYNC}}$  line is kept low for at least 16 falling edges of SCLK and the DAC is updated on the 16th falling edge. However, bringing  $\overline{\text{SYNC}}$  high before the 16th falling edge acts as an interrupt to the write sequence. The shift register is reset and the write sequence is seen as invalid. Neither an update of the DAC register contents nor a change in the operating mode occurs, as shown in  $\boxtimes$  8-4.



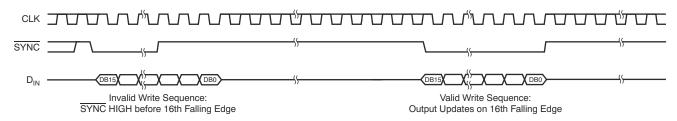


図 8-4. DACx311 SYNC Interrupt Facility

# 9 Application and Implementation

注

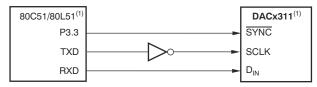
以下のアプリケーション情報は、TIの製品仕様に含まれるものではなく、TIではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

#### 9.1 Application Information

#### 9.1.1 Microprocessor Interfacing

#### 9.1.1.1 DACx311 to 8051 Interface

№ 9-1 shows a serial interface between the DACx311 and a typical 8051-type microcontroller. The setup for the interface is as follows: TXD of the 8051 drives SCLK of the DACx311, while RXD drives the serial data line of the device. The SYNC signal is derived from a bit programmable pin on the port. In this case, port line P3.3 is used. When data are to be transmitted to the DACx311, P3.3 is taken low. The 8051 transmits data only in 8-bit bytes; thus, only eight falling clock edges occur in the transmit cycle. To load data to the DAC, P3.3 remains low after the first eight bits are transmitted, and a second write cycle is initiated to transmit the second byte of data. P3.3 is taken high following the completion of this cycle. The 8051 outputs the serial data in a format that has the LSB first. The DACx311 requires data with the MSB as the first bit received. Therefore, the 8051 transmit routine must take this requirement into account, and *mirror* the data as needed.

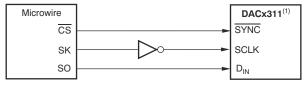


NOTE: (1) Additional pins omitted for clarity.

図 9-1. DACx311 to 80C51/80I51 Interfaces

#### 9.1.1.2 DACx311 to Microwire Interface

☑ 9-2 shows an interface between the DACx311 and any Microwire-compatible device. Serial data (SO) are shifted out on the falling edge of the serial clock (SK) and are clocked into the DACx311 on the rising edge of the SK signal.

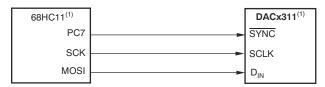


NOTE: (1) Additional pins omitted for clarity.

図 9-2. DACx311 to Microwire Interface

#### 9.1.1.3 DACx311 to 68HC11 Interface

☑ 9-3 shows a serial interface between the DACx311 and the 68HC11 microcontroller. SCK of the 68HC11 drives the SCLK of the DACx311, while the MOSI output drives the serial data line of the DAC. The SYNC signal is derived from a port line (PC7), similar to what was done for the 8051.



NOTE: (1) Additional pins omitted for clarity.

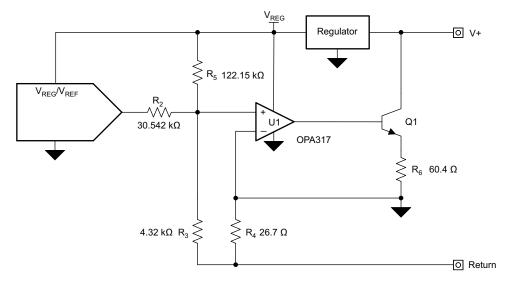
#### 図 9-3. DACx311 to 68HC11 Interface

Configure the 68HC11 so that the CPOL bit is 0 and the CPHA bit is 1. This configuration causes data appearing on the MOSI output to be valid on the falling edge of SCK. When data are being transmitted to the DAC, the SYNC line is taken low (PC7). Serial data from the 68HC11 are transmitted in 8-bit bytes with only eight falling clock edges occurring in the transmit cycle. Data are transmitted MSB first. To load data to the DACx311, PC7 is held low after the first eight bits are transferred, and a second serial write operation is performed to the DAC; PC7 is taken high at the end of this procedure.

### 9.2 Typical Applications

#### 9.2.1 Loop Powered Transmitter

The described loop powered transmitter can accurately source currents from 4 mA to 20 mA.



**図 9-4. Loop Powered Transmitter Schematic** 

#### 9.2.1.1 Design Requirements

The transmitter has only two external input pins; a supply connection and a ground (or return) connection. The transmitter communicates back to the host, typically a PLC analog input module, by precisely controlling the magnitude of the return current. To conform to the 4-mA to 20-mA communication standards, the complete transmitter must consume less than 4 mA of current.

The complete design of this circuit is outlined in TIPD158, Low Cost Loop-Powered 4-20mA Transmitter EMC/EMI Tested Reference Design. The design is expected to be low-cost and deliver immunity to the IEC61000-4 suite of tests with minimum impact on the accuracy of the system. Reference design TIPD158 includes the design goals, simulated results, and measured performance.

Copyright © 2023 Texas Instruments Incorporated

#### 9.2.1.2 Detailed Design Procedure

Amplifier U1 uses negative feedback to make sure that the potentials at the inverting (V–) and noninverting (V+) input terminals are equal. In this configuration, V– is directly tied to the local GND; therefore, the potential at the noninverting input terminal is driven to local ground. Thus, the voltage difference across  $R_2$  is the DAC output voltage (VOUT), and the voltage difference across  $R_5$  is the regulator voltage (VREG). These voltage differences cause currents to flow through  $R_2$  and  $R_5$ , as illustrated in  $\boxtimes$  9-5.

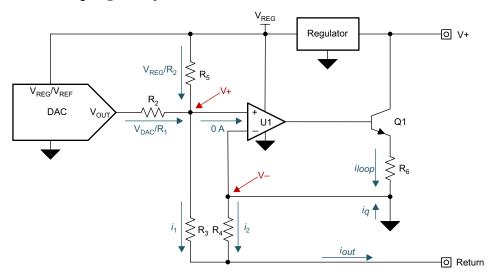


図 9-5. Voltage to Current Conversion

The currents from  $R_2$  and  $R_5$  sum into  $i_1$  (defined in  $\gtrsim 2$ ), and  $i_1$  flows through  $R_3$ .

$$i_1 = \frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} \tag{2}$$

Amplifier U2 drives the base of Q1, the NPN bipolar junction transistor (BJT), to allow current to flow through  $R_4$  so that the voltage drops across  $R_3$  and  $R_4$  remain equal. This design keeps the inverting and noninverting terminals at the same potential. A small part of the current through  $R_4$  is sourced by the quiescent current of all of the components used in the transmitter design (regulator, amplifier, and DAC). The voltage drops across  $R_3$  and  $R_4$  are equal; therefore, different-sized resistors cause different current flow through each resistor. Use these different-sized resistors to apply gain to the current flow through  $R_4$  by controlling the ratio of resistor  $R_3$  to  $R_4$ , as shown in  $R_4$  3:

$$V+=i_1\cdot R_3 \\ V-=i_2\cdot R_4 \Rightarrow i_2=\frac{i_1\cdot R_3}{R_4} \\ V+=V-$$
 (3)

The current gain in the circuit helps allow a majority of the output current to come directly from the loop through Q1 instead of from the voltage-to-current converter. This current gain, in addition to the low-power components, keeps the current consumption of the voltage-to-current converter low. Currents  $i_1$  and  $i_2$  sum to form output current  $i_{out}$ , as shown in  $\pm 3$ :

$$i_{out} = i_1 + i_2 = \frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5} + \frac{R_3}{R_4} \cdot \left(\frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5}\right) = \left(\frac{V_{DAC}}{R_2} + \frac{V_{REG}}{R_5}\right) \cdot \left(1 + \frac{R_3}{R_4}\right)$$
(4)

The complete transfer function, arranged as a function of input code, is shown in  $\pm$  5. The remaining sections divide this circuit into blocks for simplified discussion.

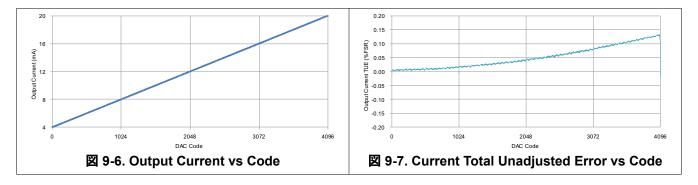


$$i_{out}\left(Code\right) = \left(\frac{V_{REG} \cdot Code}{2^{Resolution} \cdot R_2} + \frac{V_{REG}}{R_5}\right) \cdot \left(1 + \frac{R_3}{R_4}\right) \tag{5}$$

Resistor  $R_6$  is included to reduce the gain of transistor Q1, and therefore, reduce the closed-loop gain of the voltage-to-current converter for a stable design. Size resistors  $R_2$ ,  $R_3$ ,  $R_4$ , and  $R_5$  based on the full-scale range of the DAC, regulator voltage, and the desired current output range of the design.

#### 9.2.1.3 Application Curves

☑ 9-6 shows the measured transfer function of the circuit. ☑ 9-7 shows the total unadjusted error (TUE) of the circuit, staying below 0.15 %FSR.



#### 9.2.2 Using the REF5050 as a Power Supply for the DACx311

As a result of the extremely low supply current required by the DACx311, an alternative option is to use a REF5050 5-V precision voltage reference to supply the required voltage to the part, as shown in  $\boxtimes$  9-8. This option is especially useful if the power supply is too noisy or if the system supply voltages are at some value other than 5 V. The REF5050 outputs a steady supply voltage for the DACx311. If the REF5050 is used, the current needed to supply DACx311 is typically 110  $\mu$ A at 5 V, with no load on the output of the DAC. When the DAC output is loaded, the REF5050 also needs to supply the current to the load. The total current required (with a 5 k $\Omega$  load on the DAC output) is:

110 
$$\mu$$
A + (5 V / 5 k $\Omega$ ) = 1.11 mA (6)

The load regulation of the REF5050 is typically 0.002%/mA, which results in an error of 90  $\mu$ V for the 1.1 mA current drawn from the device. This value corresponds to a 0.07 LSB error at 12 bits (DAC7311).

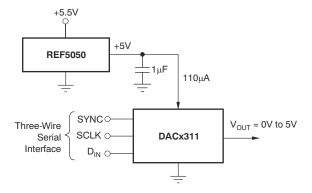


図 9-8. REF5050 as Power Supply to DACx311

For other power-supply voltages, alternative references such as the REF3030 (3 V), REF3033 (3.3 V), or REF3220 (2.048 V) are recommended. For a full list of available voltage references from TI, see the TI web site at www.ti.com.

# 9.2.3 Bipolar Operation Using the DACx311

The DACx311 has been designed for single-supply operation but a bipolar output range is also possible using the circuit in № 9-9. The circuit shown gives an output voltage range of ±5 V. Rail-to-rail operation at the amplifier output is achievable using an OPA211, OPA340, or OPA703 as the output amplifier. For a full list of available operational amplifiers from TI, see the TI web site at www.ti.com

The output voltage for any input code can be calculated as follows:

$$V_{O} = \left[ AV_{DD} \times \left( \frac{D}{2^{n}} \right) \times \left( \frac{R_{1} + R_{2}}{R_{1}} \right) - AV_{DD} \times \left( \frac{R_{2}}{R_{1}} \right) \right]$$
(7)

where

- n = resolution in bits; either 8 (DAC5311), 10 (DAC6311), or 12 (DAC7311).
- D = decimal equivalent of the binary code that is loaded to the DAC register. D ranges from 0 to 255 for 8-bit DAC5311, 0 to 1023 for the 10-bit DAC6311 and 0 to 4095 for the 12-bit DAC7311.

With  $AV_{DD} = 5 \text{ V}$ ,  $R_1 = R_2 = 10 \text{ k}\Omega$ :

$$V_{O} = \left(\frac{10 \times D}{2^{n}}\right) - 5V \tag{8}$$

The resulting output voltage range is  $\pm 5$  V. Code 000h corresponds to a -5-V output and FFFh (12-bit level) corresponding to a  $\pm 5$ -V output.

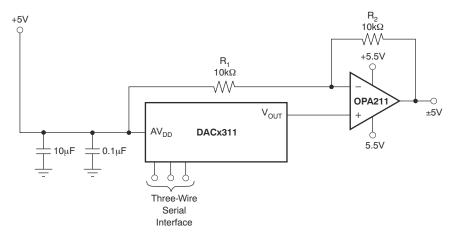


図 9-9. Bipolar Operation With the DACx311

#### 9.3 Power Supply Recommendations

The DACx311 is designed to operate with a unipolar analog power supply ranging from 2.0 V to 5.5 V on the AV<sub>DD</sub> pin. The AV<sub>DD</sub> pin supplies power to the digital and analog circuits (including the resistor string) inside the DAC. The current consumption of this pin is specified in the *Electrical Characteristics* table. Use a 1  $\mu$ F to 10  $\mu$ F capacitor in parallel with a 0.1  $\mu$ F bypass capacitor on this pin to remove high-frequency noise.

#### 9.4 Layout

#### 9.4.1 Layout Guidelines

A precision analog component requires careful layout, adequate bypassing, and clean, well-regulated power supplies.

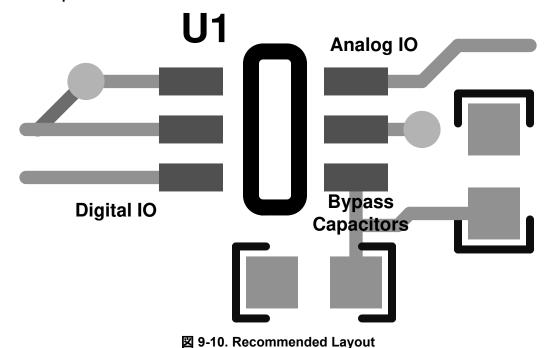
The DACx311 offers single-supply operation, and is often used in close proximity to digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult the task is to achieve good performance from the converter.

As a result of the single ground pin of the DACx311, all return currents, including digital and analog return currents, must flow through the GND pin. Ideally, GND is connected directly to an analog ground plane. Separate this plane from the ground connection for the digital components until connected at the power entry point of the system.

The power applied to  $AV_{DD}$  must be well-regulated and low-noise. Switching power supplies and dc/dc converters often have high-frequency glitches or spikes riding on the output voltage. In addition, digital components can create similar high-frequency spikes as the internal logic switches state. This noise can easily couple into the DAC output voltage through various paths between the power connections and analog output. This condition is particularly true for the DACx311, as the power supply is also the reference voltage for the DAC.

As with the GND connection, connect  $AV_{DD}$  to a 5-V power supply plane or trace that is separate from the connection for digital logic until connected at the power entry point. In addition, 1- $\mu$ F to 10- $\mu$ F and 0.1- $\mu$ F bypass capacitors are strongly recommended. In some situations, additional bypassing can be required, such as a 100  $\mu$ F electrolytic capacitor or even a *Pi* filter made up of inductors and capacitors—all designed to essentially low-pass filter the 5-V supply and remove high-frequency noise.

#### 9.4.2 Layout Example



Submit Document Feedback



# 10 Device and Documentation Support

# 10.1 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.com のデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

#### 10.2 サポート・リソース

TI E2E<sup>™</sup> サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計で必要な支援を迅速に得ることができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の使用条件を参照してください。

#### 10.3 Trademarks

TI E2E™ is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

# 10.4 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

#### 10.5 用語集

テキサス・インスツルメンツ用語集 この用語集には、用語や略語の一覧および定義が記載されています。

# 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Copyright © 2023 Texas Instruments Incorporated

Submit Document Feedback

www.ti.com

9-Nov-2025

#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
						(4)	(5)		
DAC5311IDCKR	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC5311IDCKR.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC5311IDCKRG4	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC5311IDCKRG4.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC5311IDCKT	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC5311IDCKT.A	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D53
DAC6311IDCKR	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKR.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKRG4	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKRG4.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKT	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKT.A	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC6311IDCKTG4	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D63
DAC7311IDCKR	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKR.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKRG4	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKRG4.A	Active	Production	SC70 (DCK)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKT	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKT.A	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73
DAC7311IDCKTG4	Active	Production	SC70 (DCK)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	D73

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

# PACKAGE OPTION ADDENDUM

www.ti.com 9-Nov-2025

(4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF DAC5311:

Automotive : DAC5311-Q1

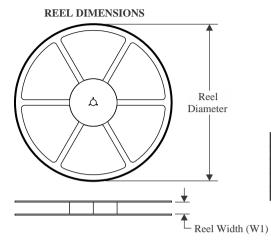
NOTE: Qualified Version Definitions:

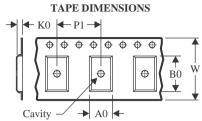
Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects



www.ti.com 18-Jun-2025

# TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

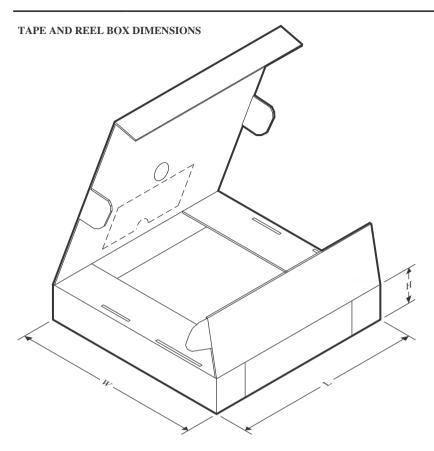


#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC5311IDCKR	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC5311IDCKRG4	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC5311IDCKT	SC70	DCK	6	250	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC6311IDCKR	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC6311IDCKRG4	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC6311IDCKT	SC70	DCK	6	250	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC7311IDCKR	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC7311IDCKRG4	SC70	DCK	6	3000	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3
DAC7311IDCKT	SC70	DCK	6	250	178.0	9.0	2.4	2.5	1.2	4.0	8.0	Q3



www.ti.com 18-Jun-2025

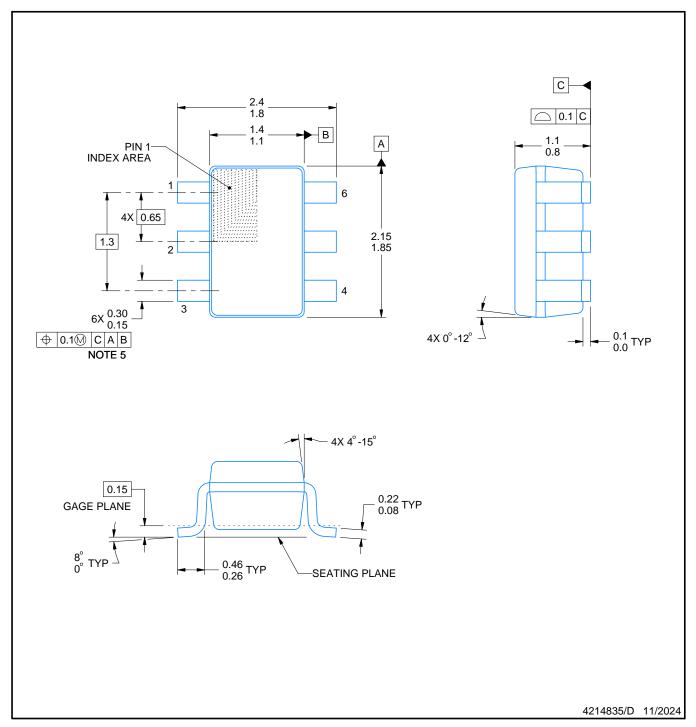


\*All dimensions are nominal

til dilliciololio die fiorilitai							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DAC5311IDCKR	SC70	DCK	6	3000	180.0	180.0	18.0
DAC5311IDCKRG4	SC70	DCK	6	3000	180.0	180.0	18.0
DAC5311IDCKT	SC70	DCK	6	250	180.0	180.0	18.0
DAC6311IDCKR	SC70	DCK	6	3000	180.0	180.0	18.0
DAC6311IDCKRG4	SC70	DCK	6	3000	180.0	180.0	18.0
DAC6311IDCKT	SC70	DCK	6	250	180.0	180.0	18.0
DAC7311IDCKR	SC70	DCK	6	3000	180.0	180.0	18.0
DAC7311IDCKRG4	SC70	DCK	6	3000	180.0	180.0	18.0
DAC7311IDCKT	SC70	DCK	6	250	180.0	180.0	18.0



SMALL OUTLINE TRANSISTOR



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

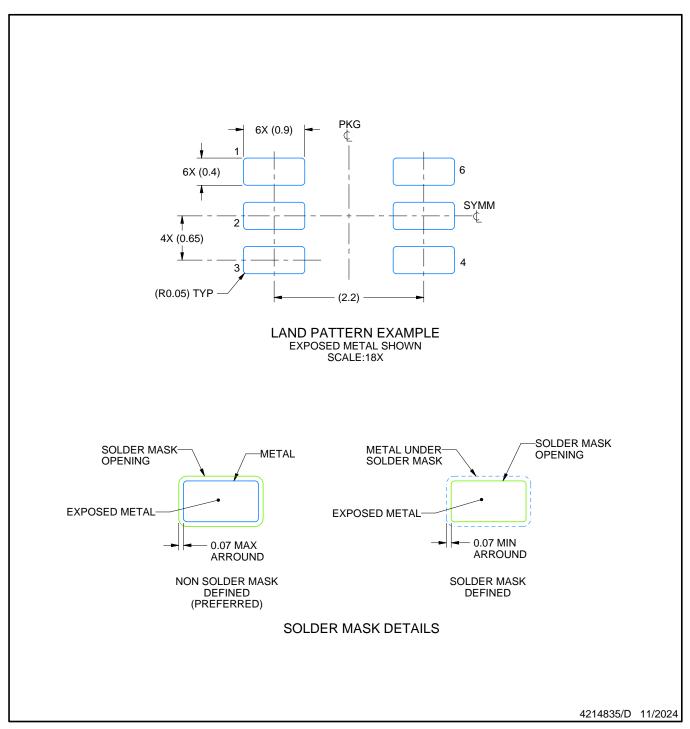
  2. This drawing is subject to change without notice.

  3. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.

  4. Falls within JEDEC MO-203 variation AB.



SMALL OUTLINE TRANSISTOR



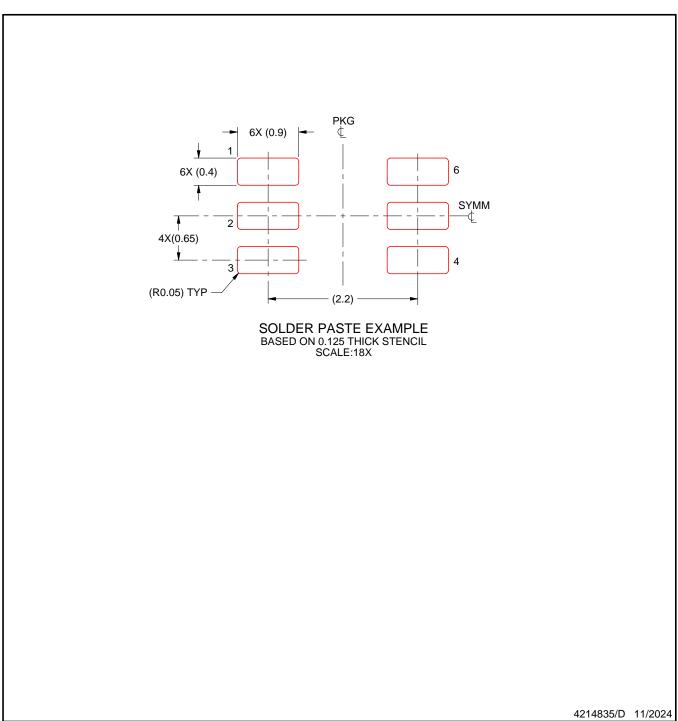
NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.

6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE TRANSISTOR



NOTES: (continued)

- 7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 8. Board assembly site may have different recommendations for stencil design.



# 重要なお知らせと免責事項

TI は、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプリケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TIの製品は、TIの販売条件、TIの総合的な品質ガイドライン、 ti.com または TI 製品などに関連して提供される他の適用条件に従い提供されます。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありません。 TI がカスタム、またはカスタマー仕様として明示的に指定していない限り、TI の製品は標準的なカタログに掲載される汎用機器です。

お客様がいかなる追加条項または代替条項を提案する場合も、TIはそれらに異議を唱え、拒否します。

Copyright © 2025, Texas Instruments Incorporated

最終更新日: 2025 年 10 月