

# DLPC6540 高解像度コントローラ

## 1 特長

- DLPC6540 DLP471TP デジタル・マイクロミラー・デバイス (DMD) を使用するコントローラは、以下をサポートします。
  - 60Hz で最大 4K UHD
  - 240Hz (2D) および 120Hz (3D) で最大 1080p
- 1、2、4、または 8 レーンの V-by-One® HS ビデオ入力ポート × 1
  - 最大 600MHz のピクセル・クロックをサポート
  - 最大 3.0Gbps の入力伝送レート
- サポートされている入力形式
  - RGB、YCbCr、および ICtCp
  - 4:4:4、4:2:2、4:2:0
- FPU 搭載の内蔵 Arm® Cortex® R4F プロセッサ
  - 88 本の構成可能な GPIO
  - プログラマブルな PWM ジェネレータ
  - プログラマブルなキャプチャ・タイマおよび遅延タイマ
  - USB 2.0 ハイスピード OTG コントローラ
  - SPI 1 次 / 2 次コントローラ
  - I<sup>2</sup>C 1 次 / 2 次コントローラ
  - UART および割り込みコントローラ
- ワーピング・エンジン
  - 1D、2D、および 3D キーストーン補正の改善
  - 光歪み補正 (たとえば、短い投影の場合、半径方向と横方向の色歪み)
  - ワーピング (マルチポイント・マニュアル・ワープおよびフル・ワープ・マップ・アクセス 62 × 32 ポイント)
  - ブレンディング (手動ブレンディングおよびフル・ブレンディング・マップ・アクセス 63 × 32 ポイント)
- 追加の画像処理
  - DynamicBlack
  - TI の DLP® BrilliantColor™ 技術
  - HDR10 (PQ および HLG) をサポート
  - フレーム・レート変換
  - 色座標調整
  - 白色色温度調整
  - 逆ガンマ補正をプログラム可能
  - 空間分割 / 時分割多重化
  - 3D ディスプレイの統合サポート
- スプラッシュ・スクリーンの表示とキャプチャ
- 2G ビットのフレーム・メモリを内蔵し、外部の高速メモリが不要
- 外部メモリに対応
  - マイクロプロセッサおよび PWM シーケンス用のパラレル・フラッシュ

- スプラッシュ・キャプチャおよびワーピング用の 2 次フラッシュ
- システム制御
  - DMD 電源およびリセット・ドライバ制御
  - DMD 画像の左右 / 上下反転
- JTAG バウンダリ・スキャン・テストをサポート

## 2 アプリケーション

- モバイル・スマート TV
- モバイル・プロジェクタ
- デジタル・サイネージ

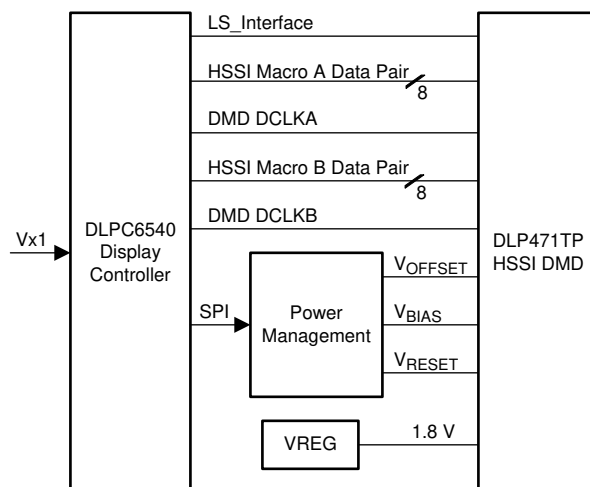
## 3 概要

DLPC6540 は、TI の DLP 製品である 4K UHD ディスプレイ・チップセット用のデジタル・ディスプレイ・コントローラです。DLPC6540 ディスプレイ・コントローラは、DLP471TP デジタル・マイクロミラー・デバイス (DMD) と DLPA3005 パワー・マネージメント IC (PMIC) とともにチップセットを構成します。このソリューションは、小型で高解像度と高輝度を必要とするディスプレイ・システムに最適です。信頼性の高い動作を保証するために、DLPC6540 ディスプレイ・コントローラは、常にアプリケーションごとに DLP471TP DMD と DLPA3005 パワー・マネージメント IC と組み合わせて使用する必要があります。

### 製品情報 (1)(2)

部品番号	パッケージ	本体サイズ (公称)
DLPC6540ZDC	P-HBGA (676)	31.00mm × 31.00mm

- 利用可能なすべてのパッケージについては、注文情報を参照してください。
- ヒート・スラグを内蔵



代表的なスタンドアロン・システム



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## 4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision B (August 2020) to Revision C (November 2022)	Page
• Updated SSP0_CSZ_0, 1, 2 pullup value 表 5-9 .....	3
• Updated 図 6-6 .....	36
• Updated 図 6-7 .....	36
• Updated 図 6-8 .....	36
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• Updated Inter-lane skew 表 9-5 .....	79

Changes from Revision A (June 2020) to Revision B (August 2020)	Page
• 文書全体にわたって表、図、相互参照の採番方法を更新.....	1
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• Added parameter t <sub>RDSD115</sub> to セクション 6.12 .....	36
• Added parameter t <sub>PROJ_ON</sub> to セクション 6.12 .....	36
• Added parameter t <sub>REFCLKA</sub> to セクション 6.12 .....	36

Changes from Revision * (May 2020) to Revision A (June 2020)	Page
• ドキュメントのステータスを「事前情報」から「量産データ」に変更 .....	1

## 5 Pin Configuration and Functions

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	
A	●	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
B	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
C	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
D	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
E	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
F	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
G	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
H	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
J	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
K	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
L	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
M	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
N	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
P	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
R	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
T	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
U	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
V	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
W	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
Y	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AA	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AB	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AC	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AD	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AE	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AF	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AG	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AH	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AJ	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
AK	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○

図 5-1. ZDC Package 676-Pin PBGA Top View

表 5-1. Initialization, Board Level Test, and Debug

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
POSENSE	AE27	I <sub>8</sub>	Power-On Sense: Signal provided from external voltage monitoring circuit ('0' = All controller supply voltages not at valid level, '1' = All controller supply voltages have reached 90% specified minimum voltage) Drive this signal to inactive (low) after the falling edge of PWRGOOD as specified. See <a href="#">セクション 6.12</a> for specific timing requirements as well as the required power up and power down sequence. This pin includes hysteresis.

表 5-1. Initialization, Board Level Test, and Debug (continued)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
PWRGOOD	AG30	I <sub>8</sub>	<p>Power Good: Signal provided from external power supply of voltage monitor. A high value indicates all power is within operating voltage specifications and the system is safe to exit its reset state. A transition from high to low indicates that the controller or DMD supply voltage drops below its rated minimum level. This transition must occur prior to the supply voltage dropping per the timing specified, as this is an early warning of an imminent power loss condition. This warning is required to enhance long term DMD reliability. When PWRGOOD goes low for the specified minimum time, a DMD park and full Controller reset are performed, protecting the DMD. Note that both controller and DMD supply voltages must be within operating voltage levels to successfully execute the DMD park. The minimum PWRGOOD deassertion time is used to protect the system input from glitches. When PWRGOOD is low, the Controller is held in its reset state.</p> <p>See <a href="#">セクション 6.12</a> for specific timing requirements as well as the required power up and power down sequence.</p> <p>This pin includes hysteresis.</p>
EXT_ARSTZ	AF29	O <sub>8</sub>	<p>External Reset: General purpose reset output ('0' = Reset, '1' = Normal Operation)</p> <p>This output is asserted low immediately upon POSENSE being asserted low, and remains low while POSENSE remains low. This signal remains low after POSENSE is set high, until released by software. This signal is also asserted low approximately 5 μs after the detection of PWRGOOD going low, or any internally generated reset. In all cases, this signal remains active low for a minimum of 2 ms.</p> <p>Note: This signal can also be independently driven through the software register.</p>
MTR_ARSTZ	AF27	O <sub>8</sub>	<p>Color Wheel Motor Controller Reset: Color wheel motor controller reset output ('0' = Reset, '1' = Normal Operation)</p> <p>This output is asserted low immediately upon POSENSE being asserted low, and remains low while POSENSE remains low. This signal remains low after POSENSE is set high, until released by software. This signal is also asserted low approximately 5 μs after the detection of PWRGOOD going low, or any internally generated reset. In all cases, this signal remains active low for a minimum of 2 ms.</p> <p>Note: This signal can also be independently driven through the software register.</p>
TCK	AK19	I <sub>8</sub>	<p>JTAG, ARM-ICE, and CPU MBIST Serial Data Clock.</p> <p>This signal is shared between JTAG, ARM-ICE (TI test only), and CPU MBIST (Manufacturing test only) operation.</p> <p>Includes a weak internal pulldown.</p>
TMS1	AH20	I <sub>8</sub>	<p>JTAG Test Mode Select</p> <p>Includes a weak internal pullup.</p>
TMS2	AJ20	I <sub>8</sub>	<p>ARM-ICE Test Mode Select</p> <p>For normal operation, this pin must be left open or unconnected. Includes a weak internal pullup.</p>
TMS3	AK20	I <sub>8</sub>	<p>CPU MBIST Test Mode Select</p> <p>For normal operation this pin must be left open or unconnected. Includes a weak internal pullup.</p>
TRSTZ	AG21	I <sub>8</sub>	<p>JTAG, ARM-ICE, and CPU MBIST Reset.</p> <p>This signal is shared between JTAG, ARM-ICE (TI test only), and CPU MBIST (Manufacturing test only) operation.</p> <p><i>For normal operation, this pin must be pulled to ground through an external resistor with value 8 kΩ or less. Failure to pull this pin low during normal operation causes start-up and initialization problems.</i></p> <p>For JTAG Boundary Scan, ARM-ICE Debug operation, or CPU MBIST, this pin must be pulled-up or left disconnected. Includes a weak internal pullup and hysteresis.</p>
TDI	AG20	I <sub>8</sub>	<p>JTAG, ARM-ICE, and CPU MBIST: Serial Data In</p> <p>Includes a weak internal pullup.</p>
TDO1	AG19	O <sub>8</sub>	JTAG Serial Data Out
TDO2	AH19	O <sub>8</sub>	<p>ARM-ICE Serial Data Out</p> <p>For normal operation, this pin must be left open or unconnected.</p>

**表 5-1. Initialization, Board Level Test, and Debug (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
TDO3	AJ19	O <sub>8</sub>	CPU MBIST Serial Data Out For normal operation, this pin must be left open or unconnected.
ETM_TRACECLK	C30	O <sub>8</sub>	TI internal use. Must be left unconnected (clock for trace debug)
ETM_TRACECTL	D30	O <sub>8</sub>	TI internal use. Must be left unconnected (control for trace debug)
ICTSEN	K26	I <sub>8</sub>	IC Tristate Enable (Active high) Asserting this signal transitions all outputs into tristate (except for the JTAG interface). Includes a weak internal pulldown, however, an external pulldown is recommended for added protection. Also includes hysteresis
ICTSE	M26	I <sub>8</sub>	TI internal use. Includes a weak internal pulldown, however, an external pulldown is recommended for added protection. Also includes hysteresis
TSTPT_0	E29	B <sub>8</sub>	Test pin 0 This pin requires an external pulldown or pullup resistor (depending on the desired debug output as noted below) with a value of ≤ 10 kΩ. Tristated while PWRGOOD is asserted low. It may be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_1	E30	B <sub>8</sub>	Test pin 1 This pin requires an external pulldown or pullup resistor (depending on the desired debug output as noted below) with a value of ≤ 10 kΩ. Tristated while PWRGOOD is asserted low. It may be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_2	F26	B <sub>8</sub>	Test pin 2 This pin requires an external pulldown or pullup resistor (depending on the desired debug output as noted below) with a value of ≤ 10 kΩ. Tristated while PWRGOOD is asserted low. It can be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_3	F27	B <sub>8</sub>	Test pin 3 This pin requires an external pulldown or pullup resistor (depending on the desired debug output as noted below) with a value of ≤ 10 kΩ. Tristated while PWRGOOD is asserted low. It may be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_4	F28	B <sub>8</sub>	Test pin 4 This pin requires an external pulldown resistor (≤ 10 kΩ). Tri-stated while PWRGOOD is asserted low. It can be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_5	F29	B <sub>8</sub>	Test pin 5 This pin requires an external pulldown resistor (≤ 10 kΩ). Tristated while PWRGOOD is asserted low. It can be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_6	G26	B <sub>8</sub>	Test pin 6 This pin requires an external pulldown resistor (≤ 10 kΩ). Tristated while PWRGOOD is asserted low. It can be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
TSTPT_7	G28	B <sub>8</sub>	Test pin 7 This pin requires an external pulldown resistor (≤ 10 kΩ). Tristated while PWRGOOD is asserted low. It can be driven as an output for debug use as described in <a href="#">セクション 7.3.7</a> .
HWTEST_EN	L26	I <sub>8</sub>	Manufacturing test enable signal. This signal must be connected directly to ground on the PCB for normal operation. Includes a weak internal pulldown and hysteresis

(1) See [表 5-13](#) for more information on I/O definitions.

**表 5-2. Analog Front End (Not Supported in DLPC6540)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
AFE_ARSTZ	K2	O <sub>8</sub>	Reserved
AFE_CLK	K3	O <sub>8</sub>	Reserved
AFE_IRQ	K4	I <sub>8</sub>	Reserved
ALF_VSYNC	K5	I <sub>8</sub>	Reserved
ALF_HSYNC	J1	I <sub>8</sub>	Reserved
ALF_CS SYNC	J2	I <sub>8</sub>	Reserved

(1) See 表 5-13 for more information on I/O definitions.

**表 5-3. V-by-One Interface Input Data and Control**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3)</sup>
NAME	NO.		
VX1_DATA0_P	C18	I <sub>1</sub>	V-by-One interface data lanes
VX1_DATA0_N	D18		
VX1_DATA1_P	A19		
VX1_DATA1_N	B19		
VX1_DATA2_P	C20		
VX1_DATA2_N	D20		
VX1_DATA3_P	A21		
VX1_DATA3_N	B21		
VX1_DATA4_P	C22		
VX1_DATA4_N	D22		
VX1_DATA5_P	A23		
VX1_DATA5_N	B23		
VX1_DATA6_P	C24		
VX1_DATA6_N	D24		
VX1_DATA7_P	A25		
VX1_DATA7_N	B25		
VX1_HTPDN	E17	O <sub>4</sub>	V-by-One interface hot plug detect (controller receiver pulls this signal low to indicate its presence to the transmitter) This signal is open drain at the controller output. A pullup resistor is required at the transmitter.
VX1_LOCKN	E19	O <sub>4</sub>	V-by-One interface clock detect lock (controller receiver pulls this signal low to indicate clock extraction lock to the transmitter) This signal is open drain at the controller output. A pullup resistor is required at the transmitter.
VX1_CM_CKREF0	E20	I <sub>1</sub>	V-by-One reserved: Tie these reserved pins to ground.
VX1_CM_CKREF1	E21		
VX1_CM_CKREF2	E23		
VX1_CM_CKREF3	E24		
VX1_CM_AMOUT0	F19	O <sub>1</sub>	V-by-One reserved: These pins are reserved and must remain unconnected.
VX1_CM_AMOUT1	F21		
VX1_CM_AMOUT2	F22		
VX1_CM_AMOUT3	F23		

(1) See 表 5-13 for more information on I/O definitions.

(2) The system supports 1-lane, 2-lane, 4-lane, or 8-lane operation, based on the bandwidth requirement of the input source. The inputs for any unused data lanes must be left open.

(3) The V-by-One port supports limited lane remapping to help optimize board layout. The details are described in [セクション 7.3.3](#).

**表 5-4. OpenLDI (FPD-Link I) (Not Supported in DLPC6540) Ports Input Data and Control**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3)</sup>
NAME	NO.		
FPDA_CLK_P	H3	I <sub>5</sub>	Reserved
FPDA_CLK_N	H4		

**表 5-4. OpenLDI (FPD-Link I) (Not Supported in DLPC6540) Ports Input Data and Control (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3)</sup>
NAME	NO.		
FPDA_DATAA_P	G1	I <sub>5</sub>	Reserved
FPDA_DATAA_N	G2		
FPDA_DATAAB_P	F3		
FPDA_DATAAB_N	F4		
FPDA_DATAAC_P	E1		
FPDA_DATAAC_N	E2		
FPDA_DATAD_P	D3		
FPDA_DATAD_N	D4		
FPDA_DATAE_P	C1		
FPDA_DATAE_N	C2		
FPDB_CLK_P	A4	I <sub>5</sub>	Reserved
FPDB_CLK_N	B4		
FPDB_DATAA_P	C5	I <sub>5</sub>	Reserved
FPDB_DATAA_N	D5		
FPDB_DATAAB_P	A6		
FPDB_DATAAB_N	B6		
FPDB_DATAAC_P	C7		
FPDB_DATAAC_N	D7		
FPDB_DATAD_P	A8		
FPDB_DATAD_N	B8		
FPDB_DATAE_P	C9		
FPDB_DATAE_N	D9		
FPDC_CLK_P	A10	I <sub>5</sub>	Reserved
FPDC_CLK_N	B10		
FPDC_DATAA_P	C11	I <sub>5</sub>	Reserved.
FPDC_DATAA_N	D11		
FPDC_DATAAB_P	A12		
FPDC_DATAAB_N	B12		
FPDC_DATAAC_P	C13		
FPDC_DATAAC_N	D13		
FPDC_DATAD_P	A14		
FPDC_DATAD_N	B14		
FPDC_DATAE_P	C15		
FPDC_DATAE_N	D15		

- (1) See 表 5-13 for more information on I/O definitions.
- (2) Throughout this document the terms FPD and FPD-Link refer to OpenLDI (FPD-Link I).
- (3) Tie the inputs for any unused port(s) to ground, or pull to ground through an external resistor.

**表 5-5. Parallel Port Input Data and Control (Not Supported in DLPC6540)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION PARALLEL RGB MODE
NAME	NO.		
PCLK (FPDB_DATAAB_N)	B6	I <sub>6</sub>	Reserved
VSYNC (FPDA_DATAE_P)	C1	I <sub>6</sub>	Reserved
HSYNC (FPDA_DATAE_N)	C2	I <sub>6</sub>	Reserved
DATEN (FPDB_DATAE_N)	D9	I <sub>6</sub>	Reserved <sup>(2)</sup>
FIELD (FPDC_DATAE_P)	C15	I <sub>6</sub>	Reserved
3D_REF (FPDC_DATAE_N)	D15	I <sub>6</sub>	Reserved
PDATA_A0 (FPDA_CLK_P)	H3	I <sub>6</sub>	Reserved
PDATA_A1 (FPDA_CLK_N)	H4		
PDATA_A2 (FPDA_DATAA_P)	G1		
PDATA_A3 (FPDA_DATAA_N)	G2		
PDATA_A4 (FPDA_DATAAB_P)	F3		
PDATA_A5 (FPDA_DATAAB_N)	F4		
PDATA_A6 (FPDA_DATAAC_P)	E1		
PDATA_A7 (FPDA_DATAAC_N)	E2		
PDATA_A8 (FPDA_DATAD_P)	D3		
PDATA_A9 (FPDA_DATAD_N)	D4		

**表 5-5. Parallel Port Input Data and Control (Not Supported in DLPC6540) (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION PARALLEL RGB MODE
NAME	NO.		
PDATA_B0 (FPDB_CLK_P)	A4	I <sub>6</sub>	Reserved
PDATA_B1 (FPDB_CLK_N)	B4		
PDATA_B2 (FPDB_DATAA_P)	C5		
PDATA_B3 (FPDB_DATAA_N)	D5		
PDATA_B4 (FPDB_DATAB_P)	A6		
PDATA_B5 (FPDB_DATA_C_P)	C7		
PDATA_B6 (FPDB_DATA_C_N)	D7		
PDATA_B7 (FPDB_DATA_D_P)	A8		
PDATA_B8 (FPDB_DATA_D_N)	B8		
PDATA_B9 (FPDB_DATAE_P)	C9		
PDATA_C0 (FPDC_CLK_P)	A10	I <sub>6</sub>	Reserved
PDATA_C1 (FPDC_CLK_N)	B10		
PDATA_C2 (FPDC_DATAA_P)	C11		
PDATA_C3 (FPDC_DATAA_N)	D11		
PDATA_C4 (FPDC_DATAB_P)	A12		
PDATA_C5 (FPDC_DATAB_N)	B12		
PDATA_C6 (FPDC_DATA_C_P)	C13		
PDATA_C7 (FPDC_DATA_C_N)	D13		
PDATA_C8 (FPDC_DATA_D_P)	A14		
PDATA_C9 (FPDC_DATA_D_N)	B14		

(1) See 表 5-13 for more information on I/O definitions.

(2) If the DATEN is not actively driven, then it must be pulled up to 3.3 V with a weak pullup resistor (50-kΩ max).

**表 5-6. DMD Reset and Low Speed Interfaces**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
DMD_LS0_CLK_P DMD_LS0_CLK_N	AH17 AG17	O <sub>2</sub>	DMD low speed differential interface, Port 0 Clock
DMD_LS0_WDATA_P DMD_LS0_WDATA_N	AK16 AJ16	O <sub>2</sub>	DMD low speed differential interface, Port 0 Write Data
DMD_LS1_CLK_P DMD_LS1_CLK_N	AH15 AG15	O <sub>2</sub>	DMD low speed differential interface, Port 1 Clock <sup>(2)</sup>
DMD_LS1_WDATA_P DMD_LS1_WDATA_N	AK14 AJ14	O <sub>2</sub>	DMD low speed differential interface, Port 1 Write Data <sup>(2)</sup>
DMD_LS0_RDATA	AH13	I <sub>3</sub>	DMD, low speed single ended serial interface, Port 0 Read Data <sup>(3)</sup>
DMD_LS1_RDATA	AG13	I <sub>3</sub>	DMD, low speed single ended serial interface, Port 1 Read Data <sup>(2) (3)</sup> . If this port is not used, this signal requires an external pullup or pulldown to keep this input from floating.
DMD_DEN_ARSTZ	AK12	O <sub>3</sub>	DMD driver enable signal / Active Low Asynchronous Reset ('1' = Enabled, '0' = Reset) This signal is driven low after the DMD is parked and before power is removed from the DMD. If the 1.8-V power to the DLPC6540 is independent of the 1.8-V power to the DMD, then an external pulldown resistor must be used to hold the signal low in the event the DLPC6540 power is inactive while DMD power is applied.

(1) See 表 5-13 for more information on I/O definitions.

(2) DMD LS1 port is reserved for single controller, two DMD applications.

(3) All control interface reads make use of the single ended low speed signals. The read data is clocked by the low speed differential write clock.

**表 5-7. DMD HSSI (High Speed Serial Interface)**

PIN <sup>(1)</sup>		TYPE <sup>(2)</sup>	DESCRIPTION
NAME	NO.		
DMD_HSSI0_CLK_P DMD_HSSI0_CLK_N	AK25 AJ25	O <sub>7</sub>	DMD high speed serial interface, Port 0 Clock Lane



**表 5-7. DMD HSSI (High Speed Serial Interface) (continued)**

PIN <sup>(1)</sup>		TYPE <sup>(2)</sup>	DESCRIPTION
NAME	NO.		
DMD_HSSI0_D0_P	AK29	O <sub>7</sub>	DMD high speed serial interface, Port 0 Data Lanes
DMD_HSSI0_D0_N	AJ29		
DMD_HSSI0_D1_P	AH28		
DMD_HSSI0_D1_N	AG28		
DMD_HSSI0_D2_P	AK27		
DMD_HSSI0_D2_N	AJ27		
DMD_HSSI0_D3_P	AH26		
DMD_HSSI0_D3_N	AG26		
DMD_HSSI0_D4_P	AH24		
DMD_HSSI0_D4_N	AG24		
DMD_HSSI0_D5_P	AK23		
DMD_HSSI0_D5_N	AJ23		
DMD_HSSI0_D6_P	AH22		
DMD_HSSI0_D6_N	AG22		
DMD_HSSI0_D7_P	AK21		
DMD_HSSI0_D7_N	AJ21		
DMD_HSSI1_CLK_P	AH7	O <sub>7</sub>	DMD high speed serial interface, Port 1 Clock Lane
DMD_HSSI1_CLK_N	AG7		
DMD_HSSI1_D0_P	AH11	O <sub>7</sub>	DMD high speed serial interface, Port 1 Data Lanes
DMD_HSSI1_D0_N	AG11		
DMD_HSSI1_D1_P	AK10		
DMD_HSSI1_D1_N	AJ10		
DMD_HSSI1_D2_P	AH9		
DMD_HSSI1_D2_N	AG9		
DMD_HSSI1_D3_P	AK8		
DMD_HSSI1_D3_N	AJ8		
DMD_HSSI1_D4_P	AK6		
DMD_HSSI1_D4_N	AJ6		
DMD_HSSI1_D5_P	AH5		
DMD_HSSI1_D5_N	AG5		
DMD_HSSI1_D6_P	AK4		
DMD_HSSI1_D6_N	AJ4		
DMD_HSSI1_D7_P	AK2		
DMD_HSSI1_D7_N	AJ2		
HSSI_ATETEST	AJ12	O <sub>7</sub>	Manufacturing Test use only—Must be left open (that is, unconnected)

- (1) A number of pin remapping options are available for the HSSI high speed channels to aid with optimizing board signal routing. See [セクション 7.3.4](#) for information on these pin remapping options.
- (2) See [表 5-13](#) for more information on I/O definitions.

**表 5-8. Program Memory (FLASH) Interface**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
PM_CSZ_0	T27	O <sub>8</sub>	Chip select: boot FLASH only (Boot FLASH must use this chip select.)
PM_CSZ_1	T28	O <sub>8</sub>	Chip select: additional peripheral device
PM_CSZ_2	T29	O <sub>8</sub>	Chip select: additional peripheral device
PM_ADDR_0	T30	O <sub>8</sub>	Address bit (LSB)
PM_ADDR_1	U26	O <sub>8</sub>	Address bit
PM_ADDR_2	U27	O <sub>8</sub>	Address bit
PM_ADDR_3	U29	O <sub>8</sub>	Address bit
PM_ADDR_4	U30	O <sub>8</sub>	Address bit
PM_ADDR_5	V29	O <sub>8</sub>	Address bit
PM_ADDR_6	V28	O <sub>8</sub>	Address bit
PM_ADDR_7	V27	O <sub>8</sub>	Address bit
PM_ADDR_8	V26	O <sub>8</sub>	Address bit
PM_ADDR_9	W30	O <sub>8</sub>	Address bit

**表 5-8. Program Memory (FLASH) Interface (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
PM_ADDR_10	W29	O <sub>8</sub>	Address bit
PM_ADDR_11	W28	O <sub>8</sub>	Address bit
PM_ADDR_12	W26	O <sub>8</sub>	Address bit
PM_ADDR_13	Y30	O <sub>8</sub>	Address bit
PM_ADDR_14	Y29	O <sub>8</sub>	Address bit
PM_ADDR_15	Y28	O <sub>8</sub>	Address bit
PM_ADDR_16	Y27	O <sub>8</sub>	Address bit
PM_ADDR_17	Y26	O <sub>8</sub>	Address bit
PM_ADDR_18	AA30	O <sub>8</sub>	Address bit
PM_ADDR_19	AA29	O <sub>8</sub>	Address bit
PM_ADDR_20	AA27	O <sub>8</sub>	Address bit
PM_ADDR_21	AA26	O <sub>8</sub>	Address bit
PM_ADDR_22	AB29	O <sub>8</sub>	Address bit
PM_ADDR_23 (GPIO_47)	AB28	B <sub>8</sub>	Address bit (MSB) <sup>(2)</sup>
PM_WEZ	R28	O <sub>8</sub>	Write enable (active low)
PM_OEZ	R29	O <sub>8</sub>	Output enable (active low)
PM_BLSZ_0	R30	O <sub>8</sub>	Lower Byte (7:0) Enable (active low)—only applicable to devices using PM_CSZ_1 or PM_CSZ_2
PM_BLSZ_1	T26	O <sub>8</sub>	Upper Byte (15:8) Enable (active low)—only applicable to devices using PM_CSZ_1 or PM_CSZ_2
PM_Data_0	L29	B <sub>8</sub>	Data bit
PM_Data_1	L30	B <sub>8</sub>	Data bit
PM_Data_2	L28	B <sub>8</sub>	Data bit
PM_Data_3	M27	B <sub>8</sub>	Data bit
PM_Data_4	M28	B <sub>8</sub>	Data bit
PM_Data_5	M29	B <sub>8</sub>	Data bit
PM_Data_6	M30	B <sub>8</sub>	Data bit
PM_Data_7	N26	B <sub>8</sub>	Data bit
PM_Data_8	N27	B <sub>8</sub>	Data bit
PM_Data_9	N29	B <sub>8</sub>	Data bit
PM_Data_10	N30	B <sub>8</sub>	Data bit
PM_Data_11	P26	B <sub>8</sub>	Data bit
PM_Data_12	P27	B <sub>8</sub>	Data bit
PM_Data_13	P28	B <sub>8</sub>	Data bit
PM_Data_14	P29	B <sub>8</sub>	Data bit
PM_Data_15	R26	B <sub>8</sub>	Data bit

(1) See 表 5-13 for more information on I/O definitions.

(2) The Program Memory address bus can be extended by one bit to 24 bits by making use of GPIO\_47. Add an external pulldown resistor when this GPIO is configured for this purpose.

**表 5-9. Peripheral Interfaces**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
IIC0_SCL	E27	B <sub>13</sub>	I <sup>2</sup> C Port 0 (master-slave), Typically slave for Host Command and Control to Controller, SCL (bidirectional, open-drain): An external pullup is required. The minimum acceptable value for this pullup is 1 K $\Omega$ .

**表 5-9. Peripheral Interfaces (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
IIC0_SDA	D29	B <sub>13</sub>	I <sup>2</sup> C Port 0 (master-slave), Typically slave for Host Command and Control to Controller, SDA. (bidirectional, open-drain): An external pullup is required. The minimum acceptable value for this pullup is 1 kΩ.
SSP0_TXD	AD27	O <sub>8</sub>	SSP/SPI Port 0 Data Out (master): transmit data pin
SSP0_RXD	AD29	I <sub>8</sub>	SSP/SPI Port 0 Data In (master): Receive data pin
SSP0_CLK	AD28	O <sub>8</sub>	SSP/SPI Port 0 clock (master): clock pin
SSP0_CSZ_2	AC28	O <sub>8</sub>	SPI Port 0 chip select 2 (master): chip select (active low) An external pullup resistor (≤ 100 kΩ) is suggested to avoid a floating chip select input to the external device.
SSP0_CSZ_1	AC26	O <sub>8</sub>	SPI Port 0 chip select 1 (master): chip select (active low) An external pullup resistor (≤ 100 kΩ) is suggested to avoid a floating chip select input to the external device.
SSP0_CSZ_0	AB27	O <sub>8</sub>	SPI Port 0 chip select 0 (master): chip select (active low) An external pullup resistor (≤ 100 kΩ) is suggested to avoid a floating chip select input to the external device.
UART0_TXD	P4	O <sub>8</sub>	UART Port 0 (slave): serial data transmit This UART port is reserved for TI debug. An external pullup resistor (≤ 10 kΩ) is required.
UART0_RXD	P5	I <sub>8</sub>	UART Port 0 (slave): serial data receive This UART port is reserved for TI debug. An external pullup resistor (≤ 10 kΩ) is required.
UART0_RTSZ	N2	O <sub>8</sub>	UART Port 0 (slave): ready to send (hardware flow control signal [active low]) This UART port is reserved for TI debug. An external pullup resistor (≤ 10 kΩ) is required.
UART0_CTSZ	N3	I <sub>8</sub>	UART Port 0 (slave): clear to send (hardware flow control signal [active low]) This UART port is reserved for TI debug. An external pullup resistor (≤ 10 kΩ) is required.
USB_DAT_P USB_DAT_N	B27 A27	B <sub>11</sub>	USB OTG Data Lane (master-slave)
USB_VBUS	D26	B <sub>11</sub>	USB OTG 5V Power Supply Detection (master-slave)
USB_ID	C27	I <sub>Other</sub>	USB OTG Mini Receptacle Identification (master-slave)
USB_TXRTUNE	C26	B <sub>GND</sub>	USB OTG Reference Resistor An external reference resistor must be connected as shown in <a href="#">セクション 9.1.6</a> .
USB_XI	A29	I <sub>GND</sub>	USB OTG External Oscillator XI—Not used (clock provided internally) For normal operation this pin must be connected to GND.
USB_XO	B29	B <sub>GND</sub>	USB OTG External Oscillator XO—Not used (clock provided internally) For normal operation this pin must be left open (unconnected).
USB_ANALOGTEST	C28	B <sub>Other</sub>	USB OTG Manufacturing Test This pin must be left open (unconnected).
PMD_INTZ	AD26	I <sub>8</sub>	Reserved function. This signal requires an external pullup.
CW_PWM	AE30	O <sub>8</sub>	Reserved function
CW_INDEX	AE29	I <sub>8</sub>	Reserved function

(1) See [表 5-13](#) for more information on I/O definitions.

**表 5-10. GPIO Peripheral Interface**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_87	K1	B <sub>8</sub>	General purpose I/O 87: Options: 1. Alt 0: Reserved 2. Alt 1: DAO_CLKIN (I) 3. Optional GPIO

表 5-10. GPIO Peripheral Interface (continued)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_86	L5	B <sub>8</sub>	General purpose I/O 86: Options: 1. Alt 0: Reserved 2. Alt 1: DAO_DI_1 (I) 3. Optional GPIO
GPIO_85	L4	B <sub>8</sub>	General purpose I/O 85: Options: 1. Alt 0: Reserved 2. Alt 1: DAO_DI_0 (I) 3. Optional GPIO
GPIO_84	L3	B <sub>8</sub>	General purpose I/O 84: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_CLKIN_2 (I) 3. Optional GPIO
GPIO_83	L2	B <sub>8</sub>	General purpose I/O 83: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_DI_2 (I) 3. Optional GPIO
GPIO_82	M5	B <sub>8</sub>	General purpose I/O 82: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_CLKIN_1 (I) 3. Optional GPIO
GPIO_81	M4	B <sub>8</sub>	General purpose I/O 81: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_DI_1 (I) 3. Optional GPIO
GPIO_80	M2	B <sub>8</sub>	General purpose I/O 80: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_CLKIN_0 (I) 3. Optional GPIO
GPIO_79	M1	B <sub>8</sub>	General purpose I/O 79: Options: 1. Alt 0: Reserved 2. Alt 1: HBT_DI_0 (I) 3. Optional GPIO
GPIO_78	N5	B <sub>8</sub>	General purpose I/O 78: Options: 1. Alt 0: Reserved 2. Alt 1: SEQ_SYNC (B/ open drain) 3. Optional GPIO
GPIO_77	N4	B <sub>8</sub>	General purpose I/O 77: Options: 1. Alt 0: Reserved 2. Alt 1: EFSYNC (O)/ DASYNC (I) 3. Optional GPIO
GPIO_76	AD5	B <sub>8</sub>	General purpose I/O 76: Options: 1. Alt 0: AWC1_DACD_PWMB_1 (O) 2. Alt 1: N/A 3. Optional GPIO

**表 5-10. GPIO Peripheral Interface (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_75	AC1	B <sub>8</sub>	General purpose I/O 75: Options: 1. Alt 0: AWC1_DACS_PWMA_1 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_74	AC2	B <sub>8</sub>	General purpose I/O 74: Options: 1. Alt 0: AWC1_DACD_PWMB_0 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_73	AC4	B <sub>8</sub>	General purpose I/O 73: Options: 1. Alt 0: AWC1_DACS_PWMA_0 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_72	AC5	B <sub>8</sub>	General purpose I/O 72: Options: 1. Alt 0: AWC1_DACCLK_0_1 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_71	AD1	B <sub>8</sub>	General purpose I/O 71: Options: 1. Alt 0: AWC1_OUT_ENZ (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_70	AD2	B <sub>8</sub>	General purpose I/O 70: Options: 1. Alt 0: AWC0_DACD_PWMB_1 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_69	AD3	B <sub>8</sub>	General purpose I/O 69: Options: 1. Alt 0: AWC0_DACS_PWMA_1 (O) 2. Alt 1: MEMAUX_1 (O) (#2) 3. Optional GPIO
GPIO_68	AD4	B <sub>8</sub>	General purpose I/O 68: Options: 1. Alt 0: AWC0_DACD_PWMB_0 (O) 2. Alt 1: IIC2_SDA (B) (#3) 3. Optional GPIO
GPIO_67	AF4	B <sub>8</sub>	General purpose I/O 67: Options: 1. Alt 0: AWC0_DACS_PWMA_0 (O) 2. Alt 1: IIC2_SCL (B) (#3) 3. Optional GPIO
GPIO_66	AE2	B <sub>8</sub>	General purpose I/O 66: Options: 1. Alt 0: AWC0_DACCLK_0_1 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_65	AE3	B <sub>8</sub>	General purpose I/O 65: Options: 1. Alt 0: AWC0_OUT_ENZ (O) 2. Alt 1: N/A 3. Optional GPIO

表 5-10. GPIO Peripheral Interface (continued)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_64	AE4	B <sub>8</sub>	General purpose I/O 64: Options: 1. Alt 0: OCLKB (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_63	AG2	B <sub>8</sub>	General purpose I/O 63: Options: 1. Alt 0: Reserved 2. Alt 1: OCLKD (O) (#2) 3. Optional GPIO
GPIO_62	AG3	B <sub>8</sub>	General purpose I/O 62: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO
GPIO_61	AF1	B <sub>8</sub>	General purpose I/O 61: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO
GPIO_60	AF2	B <sub>8</sub>	General purpose I/O 60: Options: 1. Alt 0: Reserved 2. Alt 1: UART2_RXD (I) (#2) 3. Optional GPIO
GPIO_59	AG1	B <sub>8</sub>	General purpose I/O 59: Options: 1. Alt 0: Reserved 2. Alt 1: UART2_TXD (O) (#2) 3. Optional GPIO
GPIO_58	V1	B <sub>8</sub>	General purpose I/O 58: Options: 1. Alt 0: Reserved 2. Alt 1: Reserved 3. Optional GPIO
GPIO_57	V2	B <sub>8</sub>	General purpose I/O 57: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO
GPIO_56	W2	B <sub>8</sub>	General purpose I/O 56: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO
GPIO_55	K29	B <sub>8</sub>	General purpose I/O 55: Options: 1. Alt 0: Reserved 2. Alt 1: Reserved 3. Optional GPIO
GPIO_54	K28	B <sub>8</sub>	General purpose I/O 54: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO

**表 5-10. GPIO Peripheral Interface (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_53	W3	B <sub>8</sub>	General purpose I/O 53: Options: 1. Alt 0: Reserved 2. Alt 1: LED_DRIVER_ON (O) 3. Optional GPIO
GPIO_52	W4	B <sub>8</sub>	General purpose I/O 52: Options: 1. Alt 0: Reserved 2. Alt 1: N/A 3. Optional GPIO
GPIO_51	V5	B <sub>8</sub>	General purpose I/O 51: Options: 1. Alt 0: Reserved 2. Alt 1: DMD_PWR_EN (O) 3. Optional GPIO
GPIO_50	AC29	B <sub>8</sub>	General purpose I/O 50: Options: 1. Alt 0: SSP0_CSZ_3 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_49	AC30	B <sub>8</sub>	General purpose I/O 49: Options: 1. Alt 0: SSP0_CSZ_4 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_48	AB26	B <sub>8</sub>	General purpose I/O 48: Options: 1. Alt 0: USB OTG External USB Switch Control (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_47	AB28	B <sub>8</sub>	General purpose I/O 47: Options: 1. Alt 0: PM_ADDR_23 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_46	K27	B <sub>8</sub>	General purpose I/O 46: Options: 1. Alt 0: Reserved 2. Alt 1: SSP2_BC_CSZ (O-MST/I-SLV) 3. Optional GPIO
GPIO_45	J30	B <sub>8</sub>	General purpose I/O 45: Options: 1. Alt 0: Reserved 2. Alt 1: SSP2_CSZ_2 (O-MST/I-SLV) 3. Optional GPIO
GPIO_44	J29	B <sub>8</sub>	General purpose I/O 44: Options: 1. Alt 0: OCLKC (O) (#1) 2. Alt 1: SSP2_CSZ_1 (O-MST/I-SLV) 3. Optional GPIO
GPIO_43	J27	B <sub>8</sub>	General purpose I/O 43: Options: 1. Alt 0: OCLKD (O) (#1) 2. Alt 1: SSP2_CSZ_0 (O-MST/I-SLV) 3. Optional GPIO

表 5-10. GPIO Peripheral Interface (continued)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_42	J26	B <sub>8</sub>	General purpose I/O 42: Options: 1. Alt 0: IIC2_SDA (B) (#1) 2. Alt 1: SSP2_DO (O) 3. Optional GPIO
GPIO_41	H30	B <sub>8</sub>	General purpose I/O 41: Options: 1. Alt 0: IIC2_SCL (B) (#1) 2. Alt 1: SSP2_DI (I) 3. Optional GPIO
GPIO_40	H29	B <sub>8</sub>	General purpose I/O 40: Options: 1. Alt 0: MEMAUX_1 (O) (#1) 2. Alt 1: SSP2_SCLK (O-MST/I-SLV) 3. Optional GPIO
GPIO_39	H28	B <sub>8</sub>	General purpose I/O 39: Options: 1. Alt 0: UART2_RXD (I) (#1) 2. Alt 1: HBT_CLKOUT (O) 3. Optional GPIO
GPIO_38	H27	B <sub>8</sub>	General purpose I/O 38: Options: 1. Alt 0: UART2_TXD (O) (#1) 2. Alt 1: HBT_DO (O) 3. Optional GPIO
GPIO_37	H26	B <sub>8</sub>	General purpose I/O 37: Options: 1. Alt 0: Reserved 2. Alt 1: DAO_CLKOUT (O) 3. Optional GPIO
GPIO_36	G30	B <sub>8</sub>	General purpose I/O 36: Options: 1. Alt 0: Reserved 2. Alt 1: DAO_DO_1 (O) 3. Optional GPIO
GPIO_35	G29	B <sub>8</sub>	General purpose I/O 35: Options: 1. Alt 0: OCLKC (O) (#2) 2. Alt 1: DAO_DO_0 (O) 3. Optional GPIO
GPIO_34	Y1	B <sub>8</sub>	General purpose I/O 34: Options: 1. Alt 0: WRP_CAMERA_TRIG (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_33	Y2	B <sub>8</sub>	General purpose I/O 33: Options: 1. Alt 0: PAUX11 (O) 2. Alt 1: IIC2_SDA (B) (#2) 3. Optional GPIO
GPIO_32	Y4	B <sub>8</sub>	General purpose I/O 32: Options: 1. Alt 0: PAUX10 (O) 2. Alt 1: IIC2_SCL (B) (#2) 3. Optional GPIO



**表 5-10. GPIO Peripheral Interface (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_31	Y5	B <sub>8</sub>	General purpose I/O 31: Options: 1. Alt 0: PAUX9 (O) 2. Alt 1: PAUX_INT3 (O) 3. Optional GPIO
GPIO_30	AA1	B <sub>8</sub>	General purpose I/O 30: Options: 1. Alt 0: PAUX8 (O) 2. Alt 1: PAUX_INT2 (O) 3. Optional GPIO
GPIO_29	AA2	B <sub>8</sub>	General purpose I/O 29: Options: 1. Alt 0: PAUX7 (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_28	AA3	B <sub>8</sub>	General purpose I/O 28: Options: 1. Alt 0: PAUX6 (O) 2. Alt 1: LEDSEL_4 (O) 3. Optional GPIO
GPIO_27	AA4	B <sub>8</sub>	General purpose I/O 27: Options: 1. Alt 0: PAUX5 (O) 2. Alt 1: LEDSEL_3 (O) 3. Optional GPIO
GPIO_26	AA5	B <sub>8</sub>	General purpose I/O 26: Options: 1. Alt 0: PAUX4 (O) 2. Alt 1: LEDSEL_2 (O) 3. Optional GPIO
GPIO_25	AB2	B <sub>8</sub>	General purpose I/O 25: Options: 1. Alt 0: PAUX3 (O) 2. Alt 1: LEDSEL_1 (O) 3. Optional GPIO
GPIO_24	AB3	B <sub>8</sub>	General purpose I/O 24: Options: 1. Alt 0: PAUX2 (O) 2. Alt 1: LEDSEL_0 (O) 3. Optional GPIO
GPIO_23	AB4	B <sub>8</sub>	General purpose I/O 23: Options: 1. Alt 0: PAUX1 (O) {SEQ Index} 2. Alt 1: PAUX_INT1 (O) 3. Optional GPIO
GPIO_22	AB5	B <sub>8</sub>	General purpose I/O 22: Options: 1. Alt 0: PAUX0 (O) 2. Alt 1: PAUX_INT0 (O) 3. Optional GPIO
GPIO_21	P3	B <sub>8</sub>	General purpose I/O 21: Options: 1. Alt 0: PWM-IN1 (I) 2. Alt 1: N/A 3. Optional GPIO

表 5-10. GPIO Peripheral Interface (continued)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_20	P2	B <sub>8</sub>	General purpose I/O 20: Options: 1. Alt 0: PWM-IN0 (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_19	P1	B <sub>8</sub>	General purpose I/O 19: Options: 1. Alt 0: IR1 (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_18	R5	B <sub>8</sub>	General purpose I/O 18: Options: 1. Alt 0: IR0 (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_17	R4	B <sub>8</sub>	General purpose I/O 17: Options: 1. Alt 0: N/A 2. Alt 1: N/A 3. Optional GPIO
GPIO_16	R2	B <sub>8</sub>	General purpose I/O 16: Options: 1. Alt 0: UART1_RTSZ (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_15	R1	B <sub>8</sub>	General purpose I/O 15: Options: 1. Alt 0: UART1_CTSZ (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_14	T3	B <sub>8</sub>	General purpose I/O 14: Options: 1. Alt 0: UART1_RXD (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_13	T4	B <sub>8</sub>	General purpose I/O 13: Options: 1. Alt 0: UART1_TXD (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_12	T5	B <sub>8</sub>	General purpose I/O 12: Options: 1. Alt 0: IIC1_SDA (B) 2. Alt 1: N/A 3. Optional GPIO
GPIO_11	T2	B <sub>8</sub>	General purpose I/O 11: Options: 1. Alt 0: IIC1_SCL (B) 2. Alt 1: N/A 3. Optional GPIO
GPIO_10	V3	B <sub>8</sub>	General purpose I/O 10: Options: 1. Alt 0: SAS_INTGTR_EN (O) 2. Alt 1: N/A 3. Optional GPIO

**表 5-10. GPIO Peripheral Interface (continued)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION <sup>(2) (3) (4)</sup>
NAME	NO.		
GPIO_09	U1	B <sub>8</sub>	General purpose I/O 09: Options: 1. Alt 0: SAS_CSZ (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_08	U2	B <sub>8</sub>	General purpose I/O 08: Options: 1. Alt 0: SAS_DO (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_07	U4	B <sub>8</sub>	General purpose I/O 07: Options: 1. Alt 0: SAS_DI (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_06	V4	B <sub>8</sub>	General purpose I/O 06: Options: 1. Alt 0: SAS_CLK (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_05	A17	B <sub>8</sub>	General purpose I/O 05: Options: 1. Alt 0: SSP1_CSZ_2 (O-MST/I-SLV) 2. Alt 1: N/A 3. Optional GPIO
GPIO_04	B17	B <sub>8</sub>	General purpose I/O 04: Options: 1. Alt 0: SSP1_CSZ_1 (O-MST/I-SLV) 2. Alt 1: N/A 3. Optional GPIO
GPIO_03	B15	B <sub>8</sub>	General purpose I/O 03: Options: 1. Alt 0: SSP1_CSZ_0 (O-MST/I-SLV) 2. Alt 1: N/A 3. Optional GPIO
GPIO_02	C16	B <sub>8</sub>	General purpose I/O 02: Options: 1. Alt 0: SSP1_DO (O) 2. Alt 1: N/A 3. Optional GPIO
GPIO_01	D16	B <sub>8</sub>	General purpose I/O 01: Options: 1. Alt 0: SSP1_DI (I) 2. Alt 1: N/A 3. Optional GPIO
GPIO_00	E16	B <sub>8</sub>	General purpose I/O 00: Options: 1. Alt 0: SSP1_SCLK (O-MST/I-SLV) 2. Alt 1: N/A 3. Optional GPIO

(1) See 表 5-13 for more information on I/O definitions.

(2) This table defines the GPIO capabilities of the DLPC6540. Please see セクション 7.3.6 for specific product configuration allocations of these GPIO.

(3) Most GPIO have at least one alternate hardware functional use in addition to being available as a general purpose I/O. Depending on the product configuration, GPIO may be reserved specifically for use as an alternate hardware function (and would therefore not be

available as a general purpose I/O). More information on GPIO allocations for specific product configurations can be found in [セクション 7.3.6](#).

- (4) All GPIO that are available as a general purpose I/O must be configured as an input, a standard output, or an open-drain output. This is set in the flash configuration. Configure unused GPIO as a logic zero output and leave unconnected, otherwise an external pullup or pulldown resistor is required to avoid a floating input. The reset default for all GPIO is as an input signal. An external pullup resistor ( $\leq 10\text{ k}\Omega$ ) is required for each signal configured as open-drain output.

**表 5-11. Clock and Support**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
REFCLKA_I	AJ18	I <sub>9</sub>	Crystal A Input: Reference clock crystal input <sup>(2) (3)</sup>
REFCLKA_O	AK18	O <sub>10</sub>	Crystal A Output: Reference clock crystal output <sup>(2)</sup>
REFCLKB_I	B16	I <sub>14</sub>	Crystal B Input: Reference clock crystal input <sup>(2) (3)</sup>
REFCLKB_O	A16	O <sub>15</sub>	Crystal B Output: Reference clock crystal output <sup>(2)</sup>
OCLKA	AD30	O <sub>8</sub>	General Purpose Output Clock A <sup>(4)</sup> Targeted for driving Color Wheel motor controller. Frequency is software programmable, with a power-up default frequency of 0.77 MHz. Note: The output frequency is not affected by non-power-up reset operations (that is, the system holds the last programmed value until system is power cycled).

- (1) See [表 5-13](#) for more information on I/O definitions.  
(2) For more information on this signal see [セクション 6.11](#).  
(3) For applications where an external oscillator is used in place of a crystal, use an oscillator to drive this pin.  
(4) For more information on this signal see [セクション 6.19](#).

**表 5-12. Power and Ground**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
VDD115_PLLMA	AE18	PWR	1.15-V digital power for MCG (Master Clock Generator A) PLL
VDD115_PLLMB	F15	PWR	1.15-V digital power for MCG (Master Clock Generator B) PLL
VAD115_PLLS	F16	PWR	1.15-V analog power for SCG doubler PLL
VAD18_PLLMA	AE19	PWR	1.8-V analog power for MCG (Master Clock Generator A) PLL
VAD18_PLLMB	F14	PWR	1.8-V analog power for MCG (Master Clock Generator B) PLL
VAD33_OSCA	Y18	PWR	3.3-V analog power for Crystal-OSC
VAD33_OSCB	L17	PWR	3.3-V analog power for Crystal-OSC
VAD115_FPD	F7,F9,F11,J6,L12	PWR	1.15-V analog power for FPD
VDD33_FPD	E6,E8,E10,E12,E14,G6,L11,L13	PWR	3.3-V digital power for FPD
VAD115_VX1	F24,L18	PWR	1.15-V analog power for VX1
VAD18_VX1	E18,L19	PWR	1.8-V analog power for VX1
VAD33_USB	D27,E26,F25	PWR	3.3-V analog power for USB
VDD18_SCS	L16,R6,T25,AE16	PWR	1.8-V digital power for SCS DRAM
VDD121_SCS	L15,N11,P20,U11,V20,Y16	PWR	1.21-V digital power for SCS SRAM
VAD115_HSSI	Y14,Y19,AF7,AF9,AF11,AF13AF21,A F23,AF25	PWR	1.15-V analog power for HSSI interface
VAD115_HSSI0_PLL	AE22	PWR	1.15-V analog power for HSSI-0 PLL
VAD115_HSSI1_PLL	AE10	PWR	1.15-V analog power for HSSI-1 PLL
VDD33_HSSI	Y12,Y20,AE8,AE12,AE20,AE24	PWR	3.3-V digital power for HSSI interface
VAD18_LSIF	Y15,AE13,AE14	PWR	1.8-V analog power for DMD low-speed interface
LVDS_VREFTEST	AF16		Manufacturing test use only; must be left open-unconnected
VDD115	L14,L20,M11,N20,P11,R20,T11,U20, V11,W20,Y11,Y13,Y17	PWR	1.15-V core power

**表 5-12. Power and Ground (continued)**

NAME	PIN		TYPE <sup>(1)</sup>	DESCRIPTION
		NO.		
VDD33		H25,K25,L6,M20,M25,N6,P25,R11,T20,U6,V25,W6,W11,Y25,AA6,AB25,AC6,AD25,AE6	PWR	3.3-V digital power
VSS		A1,A2,A3,A5,A7,A9,A11,A13,A15,A18,A20,A22,A24,A26,A28,A30,B1,B2,B3,B5,B7,B9,B11,B13,B18,B20,B22,B24,B26,B28,B30,C3,C4,C6,C8,C10,C12,C14,C17,C19,C21,C23,C25,C29,D1,D2,D6,D8,D10,D12,D14,D17,D19,D21,D23,D25,D28,E3,E4,E5,E7,E9,E11,E13,E15,E22,E25,E28,F1,F2,F5,F6,F8,F10,F12,F13,F17,F18,F20,F30,G3,G4,G5,G27,H1,H2,H5,H6,J3,J4,J5,J25,J28,K6,K30,L1,L25,L27,M3,M6,(M12),(M13),(M14),(M15),(M16),(M17),(M18),(M19),N1,(N12),(N13),(N14),(N15),(N16),(N17),(N18),(N19),N25,N28,P6,(P12),(P13),(P14),(P15),(P16),(P17),(P18),(P19),P30,R3,(R12),(R13),(R14),(R15),(R16),(R17),(R18),(R19),R25,R27,T1,T6,(T12),(T13),(T14),(T15),(T16),(T17),(T18),(T19),U3,U5,(U12),(U13),(U14),(U15),(U16),(U17),(U18),(U19),U25,U28,V6,(V12),(V13),(V14),(V15),(V16),(V17),(V18),(V19),V30,W1,W5,(W12),(W13),(W14),(W15),(W16),(W17),(W18),(W19),W25,W27,Y3,Y6,AA25,AA28,AB1,AB6,AB30,AC3,AC25,AC27,AD6,AE1,AE5,AE7,AE9,AE11,AE15,AE17,AE21,AE23,AE25,AE26,AE28,AF3,AF5,AF6,AF8,AF10,AF12,AF14,AF15,AF17,AF18,AF19,AF20,AF22,AF24,AF26,AF28,AF30,AG4,AG6,AG8,AG10,AG12,AG14,AG16,AG18,AG23,AG25,AG27,AG29,AH1,AH2,AH3,AH4,AH6,AH8,AH10,AH12,AH14,AH16,AH18,AH21,AH23,AH25,AH27,AH29,AH30,AJ1,AJ3,AJ5,AJ7,AJ9,AJ11,AJ13,AJ15,AJ17,AJ22,AJ24,AJ26,AJ28,AJ30,AK1,AK3,AK5,AK7,AK9,AK11,AK13,AK15,AK17,AK22,AK24,AK26,AK28,AK30	RTN	GND for all power supplies. Ball numbers in parenthesis are also used as thermal balls and are located within the package center region.
VPGM		G25		Manufacturing use only (efuse); must be tied to ground

(1) See 表 5-13 for more information on I/O definitions.

表 5-13. I/O Type Subscript Definition

TYPE		SUPPLY REFERENCE	ESD STRUCTURE
SUBSCRIPT	DESCRIPTION		
1	1.8 V SERDES (VX1)	VAD18_VX1	ESD diode to supply rail and GND
2	1.8-V LVDS (LS DMD)	VAD18_LSIF	ESD diode to supply rail and GND
3	1.8-V LMCOS (LS DMD)	VAD18_LSIF	ESD diode to supply rail and GND
4	3.3-V OpenDrain (VX1)	VDD33	ESD diode to supply rail and GND
5	3.3-V LVDS (FPD)	VDD33_FPD	ESD diode to supply rail and GND
6	3.3-V LVCMOS (PP)	VDD33_FPD	ESD diode to supply rail and GND
7	1.15-V HSSI (HS DMD)	VAD115_HSSI	ESD diode to supply rail and GND
8	3.3-V LVCMOS I/O (8ma output drive - GPIO, etc. )	VDD33	ESD diode to supply rail and GND
9	3.3-V LVCMOS I/O (OSC)	VAD33_OSCA	ESD diode to GND
10	3.3-V LVCMOS I/O (OSC)	VAD33_OSCA	ESD diode to supply rail and GND
11	3.3-V USB (USB)	VAD33_USB	ESD diode and LBJT to GND
12	3.3-V LVCMOS (USB)	VAD33_USB	ESD diode to supply rail and GND
13	3.3-V OpenDrain (I2C)	VDD33	ESD diode to supply rail and GND
14	3.3-V LVCMOS I/O (OSC)	VAD33_OSCB	ESD diode to GND
15	3.3-V LVCMOS I/O (OSC)	VAD33_OSCB	ESD diode to supply rail and GND
<b>TYPE</b>			
I	Input		N/A
O	Output		
B	Bidirectional		
PWR	Power		
RTN	Ground return		

表 5-14. Internal Pullup and Pulldown Characteristics<sup>(1)</sup>

INTERNAL PULLUP AND PULLDOWN RESISTOR CHARACTERISTICS	CONDITIONS	MIN	MAX	UNIT
		Weak pullup resistance	$V_{IN} = 0.8 \text{ V}, VDD33 = 3.3 \text{ V}$	19
	$V_{IN} = 2.0 \text{ V}, VDD33 = 3.3 \text{ V}$	12	39	k $\Omega$

- (1) An external 5.7-k $\Omega$  or less pullup or pulldown resistor (if needed) is sufficient for any voltage condition to correctly override any associated internal pullup or pulldown resistance.

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over operating free-air temperature (unless otherwise noted)<sup>(1)</sup>

SUPPLY VOLTAGE <sup>(2)</sup>		MIN	MAX	UNIT
V <sub>(VDD115)</sub> (Core)		-0.3	1.6	V
V <sub>(VDD115_PLLMA)</sub> (Core)		-0.3	1.6	V
V <sub>(VDD115_PLLMB)</sub> (Core)		-0.3	1.6	V
V <sub>(VDD115_PLLS)</sub> (Core)		-0.3	1.6	V
V <sub>(VAD115_FPD)</sub> (Core)		-0.3	1.6	V
V <sub>(VAD115_VX1)</sub> (Core)		-0.5	1.5	V
V <sub>(VAD115_HSSI)</sub> (Core)		-0.3	1.6	V
V <sub>(VAD115_HSSI0_PLL)</sub> (Core)		-0.3	1.6	V
V <sub>(VAD115_HSSI1_PLL)</sub> (Core)		-0.3	1.6	V
V <sub>(VDD121_SCS)</sub> (Core)		-0.4	1.6	V
V <sub>(VAD18_PLLMA)</sub> (Core)		-0.3	2.5	V
V <sub>(VAD18_PLLMB)</sub> (Core)		-0.3	2.5	V
V <sub>(VAD18_VX1)</sub> (I/O)		-0.5	2.5	V
V <sub>(VDD18_SCS)</sub> (Core)		-0.4	2.3	V
V <sub>(VDD18_LVDS)</sub> (I/O)		-0.3	2.5	V
V <sub>(VDD33)</sub> (I/O)		-0.3	3.9	V
V <sub>(VAD33_OSCA)</sub> (I/O)		-0.3	3.9	V
V <sub>(VAD33_OSCB)</sub> (I/O)		-0.3	3.9	V
V <sub>(VDD33_FPD)</sub> (I/O)		-0.3	3.9	V
V <sub>(VAD33_USB)</sub> (I/O)		-0.3	3.9	V
V <sub>(VDD33_HSSI)</sub> (I/O)		-0.3	3.9	V
<b>GENERAL</b>				
T <sub>J</sub>	Operating junction temperature	0	115	°C
T <sub>C</sub>	Operating case temperature	0	108 <sup>(3)</sup>	°C
I <sub>lat</sub>	Latch-up	-100	100	mA
T <sub>stg</sub>	Storage temperature range	-40	125	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) All voltage values are with respect to GND.

(3) Value calculated using package parameters defined in [セクション 6.4](#).

### 6.2 ESD Ratings

PARAMETER			VALUE	UNIT	
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI-ESDA-JEDEC JS-001 <sup>(1)</sup>	All pins (except Vx1_CM_CKREF0, 1, 2, 3)	±1000	V
			Vx1_CM_CKREF0, 1, 2, 3	±750	
		Charged device model (CDM), per ANSI-ESDA-JEDEC JS-002 <sup>(2)</sup>	All pins (except Vx1_CM_CKREF0, 1, 2, 3)	±500	
			Vx1_CM_CKREF0, 1, 2, 3	+500 -200	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		TOLERANCE	MIN	NOM	MAX	UNIT
V <sub>(VDD115)</sub> (Core)	1.15-V Power	± 4.35% tolerance	1.10	1.15	1.20	V
V <sub>(VDD115_PLLMA)</sub> (Core)	1.15-V Digital Power - MCG-A PLL (Master Clock Generator)	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
V <sub>(VDD115_PLLMB)</sub> (Core)	1.15-V Digital Power - MCG-B PLL (Master Clock Generator)	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
V <sub>(VDD115_PLLS)</sub> (Core)	1.15-V Analog Power - SCG Doubler PLL	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
V <sub>(VAD115_FPD)</sub> (Core)	1.15-V Analog Power - FPD	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
V <sub>(VAD115_VX1)</sub> (Core)	1.15-V Analog Power - VX1	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
V <sub>(VAD115_HSSI)</sub> (Core)	1.15-V Analog Power - HSSI	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
ΔV <sub>(VAD115_HSSI)</sub> (Core)	pk-pkVAD115_HSSI supply noise @ 10 MHz (sine)				20	mV
V <sub>(VAD115_HSSI0_PLL)</sub> (Core)	1.15-V Analog Power - HSSI0 PLL	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
ΔV <sub>(VAD115_HSSI0_PLL)</sub> (Core)	pk-pkVAD115_HSSI0_PLL supply noise @ 10 MHz (sine)				20	mV
V <sub>(VAD115_HSSI1_PLL)</sub> (Core)	1.15-V Analog Power - HSSI1 PLL	+4.35/-9.13% tolerance	1.045	1.15	1.20	V
ΔV <sub>(VAD115_HSSI1_PLL)</sub> (Core)	pk-pkVAD115_HSSI1_PLL supply noise @ 10 MHz (sine)				20	mV
V <sub>(VDD121_SCS)</sub> (Core)	1.21V Digital Power - SCS DRAM	+7.43/-4.95% tolerance	1.15	1.21	1.30	V
V <sub>(VAD18_PLLMA)</sub> (Core)	1.8-V Analog Power - MCG-A PLL (Master Clock Generator)	±5.0% tolerance	1.71	1.80	1.89	V
V <sub>(VAD18_PLLMB)</sub> (Core)	1.8-V Analog Power - MCG-B PLL (Master Clock Generator)	±5.0% tolerance	1.71	1.80	1.89	V
V <sub>(VAD18_VX1)</sub> (I/O)	1.8-V Analog Power - VX1 Interface	±5.0% tolerance	1.71	1.80	1.89	V
V <sub>(VDD18_SCS)</sub> (Core)	1.8-V Digital Power - SCS DRAM	±5.0% tolerance	1.71	1.80	1.89	V
V <sub>(VDD18_LVDS)</sub> (I/O)	1.8-V Analog Power - DMD LS Interface	±5.0% tolerance	1.71	1.80	1.89	V
V <sub>(VDD33)</sub> (I/O)	3.3-V Digital Power - (All 3.3-V I/O without dedicated 3.3-V supply - e.g. GPIO)	±5.0% tolerance	3.135	3.3	3.465	V
V <sub>(VAD33_OSCA)</sub> (I/O)	3.3-V Analog Power - Crystal-OSCA Interface	±5.0% tolerance	3.135	3.3	3.465	V



### 6.3 Recommended Operating Conditions (continued)

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		TOLERANCE	MIN	NOM	MAX	UNIT
V <sub>(VAD33_OSCB)</sub> (I/O)	3.3-V Analog Power - Crystal-OSCB Interface	±5.0% tolerance	3.135	3.3	3.465	V
V <sub>(VDD33_FPD)</sub> (I/O)	3.3-V Digital Power - FPD interface	±5.0% tolerance	3.135	3.3	3.465	V
V <sub>(VAD33_USB)</sub> (I/O)	3.3-V Analog Power - USB Interface	±5.0% tolerance	3.135	3.3	3.465	V
V <sub>(VDD33_HSSI)</sub> (I/O)	3.3-V Digital Power - DMD HSSI Interface	±5.0% tolerance	3.135	3.3	3.465	V
ΔV <sub>(VDD33_HSSI)</sub> (I/O)	pk-pkVDD33_HSSI supply noise @ 10 MHz (sine)				60	mV
<b>GENERAL</b>						
T <sub>J</sub>	Operating junction temperature		0		115	°C
T <sub>C</sub>	Operating case temperature		0		108	°C
T <sub>A</sub>	Operating ambient temperature <sup>(1)</sup> <sup>(2)</sup>		0		55	°C

(1) The operating ambient temperature range values were determined based on the board design parameters described in [セクション 9.1.1](#), rather than using a JEDEC JESD51 standard test card and environment, along with min and max estimated power dissipation across process, voltage, and temperature. Ambient thermal conditions, which impact R<sub>θJA</sub>, vary by application. Thus, maximum operating ambient temperature varies by application.

a.  $T_{a\_min} = T_{j\_min} - (P_{d\_min} \times R_{\theta JA}) = 0^{\circ}\text{C} - (\text{host\_min\_valueW} \times \text{host\_value}^{\circ}\text{C/W}) = -\text{host\_calculated\_value}^{\circ}\text{C}$

b.  $T_{a\_max} = T_{j\_max} - (P_{d\_max} \times R_{\theta JA}) = +115^{\circ}\text{C} - (\text{host\_max\_valueW} \times \text{host\_value}^{\circ}\text{C/W}) = +\text{host\_calculated\_value}^{\circ}\text{C}$

(2) Operating ambient temperature is dependent on system thermal design. Operating case temperature cannot exceed its specified range across ambient temperature conditions.

## 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		TEST CONDITIONS <sup>(2)</sup>	ZDC	UNIT
			P-HBGA676	
			676 PINS (576 Populated)	
R <sub>θJA</sub>	Junction-to-air thermal resistance <sup>(3)</sup>	0 m/s of forced airflow, without heat-sink	7.4	°C/W
		1 m/s of forced airflow, without heat-sink	6.3	
		2 m/s of forced airflow, without heat-sink	6.0	
		1 m/s of forced airflow, with heat-sink, 7 W	5.3	
		2 m/s of forced airflow, with heat-sink, 7 W	4.8	
		1 m/s of forced airflow, with heat-sink, 15 W	4.0	
		2 m/s of forced airflow, with heat-sink, 15 W	3.5	
R <sub>JC</sub>	Junction-to-case thermal resistance <sup>(4)</sup>		2.7	°C/W
R <sub>JB</sub>	Junction-to-board thermal resistance <sup>(4)</sup>		3.5	°C/W
ψ <sub>JT</sub> <sup>(5)</sup>	Temperature variance from junction to package top center temperature, per unit power dissipation.	0 m/s of forced airflow, without heat-sink	0.6	°C/W
		1 m/s of forced airflow, without heat-sink	0.6	
		2 m/s of forced airflow, without heat-sink	0.6	
P <sub>MAX</sub>	Package - Maximum Power <sup>(3) (6)</sup>	0 m/s of forced airflow, without heat-sink	8.10	W
		1 m/s of forced airflow, without heat-sink	9.52	
		2 m/s of forced airflow, without heat-sink	10.00	

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).
- (2) These test conditions also included a PCB sized at 101.3mm x 152.4mm incorporating the recommended PCB thermal enhancements specified in [セクション 9.1.1](#). In addition, airflow is parallel to the board surface directed at the device.
- (3) See [表 6-1](#) for thermal parameters based on the example heat-sinks listed below
- Heatsink-7 W: S1525-7W, Size = 25 mm x 25 mm x 7 mm, Pins = 7 x 7 = 49 (Vendor: Alpha, Type S Series)
  - Heatsink-15 W: S1530-15W, Size = 30 mm x 30 mm x 15 mm, Pins = 8 x 8 = 64 (Vendor: Alpha, Type S Series)
- (4) Due to the complex internal construction of the DLPC6540 controller, the R<sub>JC</sub> and R<sub>JB</sub> thermal coefficients do not always produce an accurate junction temperature estimate. A limited set of comparison scenario data shows that the R<sub>JC</sub> and R<sub>JB</sub> modeled junction temperature can have a +9% to -2% error vs the actual temperature. The amount of this error varies with the use and size of an external heat sink as well as the amount of external air flow. Validate all thermal estimates based on R<sub>JC</sub> and R<sub>JB</sub> with an actual temperature measurement at the top-center of the package plus the delta-temp defined by ψ<sub>JT</sub>.
- (5) Example: Using the power we expect of 11.31 W  
 $11.31 \text{ W} * 0.6 \text{ °C/W} = 6.786 \text{ °C} \Rightarrow T_{C-max} = 115 \text{ °C} - \sim 7 \text{ °C} = 108 \text{ °C}$
- (6)  $P_{MAX} = (T_{J-max} - T_{A-max}) / R_{\theta JA}$

**表 6-1. Thermal Examples using Two Different Heat-sinks**

THERMAL METRIC <sup>(1)</sup>		TEST CONDITIONS	ZDC	UNIT
			P-HBGA676	
			676 PINS (576 Populated)	
R <sub>θJA</sub>	Junction-to-air thermal resistance	1 m/s of forced airflow, with heat-sink, 7 W	5.3	°C/W
		2 m/s of forced airflow, with heat-sink, 7 W	4.8	
		1 m/s of forced airflow, with heat-sink, 15 W	4.0	
		2 m/s of forced airflow, with heat-sink, 15 W	3.5	
P <sub>MAX</sub>	Package - Maximum Power	1 m/s of forced airflow, with heat-sink, 7 W	11.32	W
		2 m/s of forced airflow, with heat-sink, 7 W	12.50	
		1 m/s of forced airflow, with heat-sink, 15 W	15.00	
		2 m/s of forced airflow, with heat-sink, 15 W	17.14	

- (1) This table show examples of what is achievable based on the two example heat-sinks.

## 6.5 Power Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX <sup>(1)</sup>	UNIT
V <sub>(VDD115)</sub>	1.15-V Power	Maximum current at VDD115 = 1.2 V			5640	mA
V <sub>(VDD115_PLLMA)</sub> (Core)	1.15-V Digital Power MCG-A PLL (Master Clock Generator)	Maximum current at VDD115_PLLMA = 1.2 V			6	mA
V <sub>(VDD115_PLLMB)</sub> (Core)	1.15-V Digital Power MCG-B PLL (Master Clock Generator)	Maximum current at VDD115_PLLMB = 1.2 V			6	mA
V <sub>(VDD115_PLLS)</sub> (Core)	1.15-V Analog Power SCG Doubler PLL	Maximum current at VDD115_PLLS = 1.2 V			3	mA
V <sub>(VAD115_FPD)</sub> (Core) <sup>(2)</sup>	1.15-V Analog Power FPD	Maximum current at VAD115_FPD = 1.2 V Ports A and B Active, Port C inactive			99	mA
V <sub>(VAD115_VX1)</sub> (Core) <sup>(2)</sup>	1.15-V Analog Power VX1	Maximum current at VAD115_VX1 = 1.2 V 8 Lanes, with total BW = 3.0Gbps)			400	mA
V <sub>(VAD115_HSSI)</sub> (Core)	1.15-V Digital Power HSSI	Maximum current at VDD115_HSSI = 1.2 V Both ports active			462	mA
V <sub>(VAD115_HSSI0_PLL)</sub> (Core)	1.15-V Digital Power HSSI0 PLL	Maximum current at VDD115_HSSI0_PLL = 1.2 V Both ports active			1	mA
V <sub>(VAD115_HSSI1_PLL)</sub> (Core)	1.15-V Digital Power HSSI1 PLL	Maximum current at VDD115_HSSI1_PLL = 1.2 V Both ports active			1	mA
V <sub>(VDD121_SCS)</sub> (Core)	1.21V Digital Power SCS DRAM	Maximum current at VDD121_SCS = 1.30 V			334	mA
V <sub>(VAD18_PLLMA)</sub> (Core)	1.8-V Analog Power MCG-A PLL (Master Clock Generator)	Maximum current at VAD18_PLLMA = 1.89 V			10	mA
V <sub>(VAD18_PLLMB)</sub> (Core)	1.8-V Analog Power MCG-B PLL (Master Clock Generator)	Maximum current at VAD18_PLLMB = 1.89 V			10	mA
V <sub>(VAD18_VX1)</sub> (I/O) <sup>(2)</sup>	1.8-V Analog Power VX1 Interface	Maximum current at VAD18_VX1 = 1.89 V 8 Lanes, with total BW = 3.0Gbps			41	mA
V <sub>(VDD18_SCS)</sub> (Core)	1.8-V Digital Power SCS DRAM	Maximum current at VDD18_SCS = 1.89 V			327	mA
V <sub>(VDD18_LVDS)</sub> (I/O)	1.8-V Analog Power DMD LS Interface	Maximum current at VDD18_LVDS = 1.89 V			31	mA
V <sub>(VDD33)</sub> (I/O)	3.3-V Digital Power - (All 3.3-V I/O without dedicated 3.3-V supply - e.g. GPIO)	Maximum current at VDD33 = 3.3456 V			28	mA
V <sub>(VAD33_OSCA)</sub> (I/O)	3.3-V Analog Power Crystal/OSCA Interface	Maximum current at VDD33_OSCA = 3.3456 V			5	mA
V <sub>(VAD33_OSCB)</sub> (I/O)	3.3-V Analog Power Crystal-OSCB Interface	Maximum current at VDD33_OSCB = 3.3456 V			5	mA
V <sub>(VDD33_FPD)</sub> (I/O) <sup>(2)</sup>	3.3-V Digital Power FPD interface	Maximum current at VDD33_FPD = 3.3456 V Ports A and B Active, Port C inactive			102	mA
V <sub>(VAD33_USB)</sub> (I/O)	3.3-V Analog Power USB Interface	Maximum current at VDD33_USB = 3.3456 V			78	mA

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX <sup>(1)</sup>	UNIT
$V_{(VDD33\_HSSI)}$ (I/O)	3.3-V Digital Power DMD HSSI Interface	Maximum current at VDD33_HSSI = 3.3456 V Both ports active, with total BW = 3.0Gbps			194	mA

- (1) Vendor estimate for worst case power PVT condition = corner process, high voltage, high temperature (115°C junction).  
(2) The V-by-One interface and FPD-Link receivers are never intended to be simultaneously enabled. Always disable one of these interfaces.

## 6.6 Pin Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH}$	High-level input threshold voltage	1.8 V LVCMOS (I/O type 3 - LS DMD)	1.05			V
		3.3 V OpenDrain (I/O type 4 - VX1)	N/A			
		3.3 V LVCMOS (I/O type 6 - FPD)	$0.8 \times$ VDD33_FPD			
		3.3 V LVCMOS (I/O type 6 - PP)	2.0			
		3.3 V LVCMOS (I/O type 8 - GPIO)	2.0			
		3.3 V LVCMOS (I/O type 9 - OSCA)	2.0			
		3.3 V LVCMOS (I/O type 10 - OSCB)	2.0			
		3.3 V OpenDrain (I/O type 13 - I2C)	$0.7 \times VDD33$			
$V_{IL}$	Low-level input threshold voltage	1.8 V LVCMOS (I/O type 3 - LS DMD)			0.6	V
		3.3 V OpenDrain (I/O type 4 - VX1)			N/A	
		3.3 V LVCMOS (I/O type 6 - FPD)			$0.2 \times VDD33\_FPD$	
		3.3 V LVCMOS (I/O type 6 - PP)			0.8	
		3.3 V LVCMOS (I/O type 8 - GPIO)			0.8	
		3.3 V LVCMOS (I/O type 9 - OSCA)			0.8	
		3.3 V LVCMOS (I/O type 10 - OSCB)			0.8	
		3.3 V OpenDrain (I/O type 13 - I2C)			$0.3 \times VDD33$	

## 6.6 Pin Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
I <sub>IH</sub>	High-level input current	1.8 V LVCMOS (I/O type 3 - LS DMD)	V <sub>IN</sub> = VAD18_LSIF	-10		10	μA
		3.3 V OpenDrain (I/O type 4 - VX1)		N/A		N/A	
		3.3 V LVCMOS (I/O type 6 - PP)		-10		10	
		3.3 V LVCMOS (I/O type 8 - GPIO)	V <sub>IN</sub> = VDD33	-10		10	
		3.3 V LVCMOS (I/O type 9 - OSCA)	V <sub>IN</sub> = VDD33	-10		10	
		3.3 V LVCMOS (I/O type 10 - OSCB)	V <sub>IN</sub> = VDD33	-10		10	
		3.3 V OpenDrain (I/O type 13 - I2C)		-10		10	
I <sub>IL</sub>	Low-level input current	1.8 V LVCMOS (I/O type 3 - LS DMD)	V <sub>IN</sub> = VSS	-10		10	μA
		3.3 V OpenDrain (I/O type 4 - VX1)		N/A		N/A	
		3.3 V LVCMOS (I/O type 6 - PP)		-10		10	
		3.3 V LVCMOS (I/O type 8 - GPIO)	V <sub>IN</sub> = VSS	-10		10	
		3.3 V LVCMOS (I/O type 9 - OSCA)	V <sub>IN</sub> = VSS	-10		10	
		3.3 V LVCMOS (I/O type 10 - OSCB)	V <sub>IN</sub> = VSS	-10		10	
		3.3 V OpenDrain (I/O type 13 - I2C)		-10		10	
V <sub>OH</sub>	High-level output voltage	1.8 V LVCMOS (I/O type 3 - LS DMD)			VDD18 - 0.6	V	
		3.3 V OpenDrain (I/O type 4 - VX1)			N/A		
		3.3 V LVCMOS (I/O type 6 - PP)			N/A		
		3.3 V LVCMOS (I/O type 8 - GPIO)	I <sub>OH</sub> = 8 mA		VDD33 - 0.6		
		3.3 V LVCMOS (I/O type 9 - OSCA)			N/A		
		3.3 V LVCMOS (I/O type 10 - OSCB)			N/A		
		3.3 V OpenDrain (I/O type 13 - I2C)			N/A		

## 6.6 Pin Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OL</sub>	Low-level output voltage	1.8 V LVCMOS (I/O type 3 - LS DMD)			0.4	V
		3.3 V OpenDrain (I/O type 4 - VX1)	I <sub>OL</sub> = 8 mA		0.4	
		3.3 V LVCMOS (I/O type 6 - PP)			N/A	
		3.3 V LVCMOS (I/O type 8 - GPIO)	I <sub>OL</sub> = 8 mA		0.4	
		3.3 V LVCMOS (I/O type 9 - OSCA)			N/A	
		3.3 V LVCMOS (I/O type 10 - OSCB)			N/A	
		3.3 V OpenDrain (I/O type 13 - I2C)	3-mA sink		0.4	
I <sub>OH</sub>	High-level output current	1.8 V LVCMOS (I/O type 3 - LS DMD)		N/A		mA
		3.3 V OpenDrain (I/O type 4 - VX1)		N/A		
		3.3 V LVCMOS (I/O type 6 - PP)		N/A		
		3.3 V LVCMOS (I/O type 8 - GPIO)	V <sub>OH</sub> = VDD33 - 0.6 V	8		
		3.3 V LVCMOS (I/O type 9 - OSCA)		N/A	N/A	
		3.3 V LVCMOS (I/O type 10 - OSCB)		N/A	N/A	
		3.3 V OpenDrain (I/O type 13 - I2C)		N/A		
I <sub>OL</sub>	Low-level output current	1.8 V LVCMOS (I/O type 3 - LS DMD)		N/A		mA
		3.3 V OpenDrain (I/O type 4 - VX1)	V <sub>OL</sub> = 0.4 V	8		
		3.3 V LVCMOS (I/O type 6 - PP)			N/A	
		3.3 V LVCMOS (I/O type 8 - GPIO)	V <sub>OL</sub> = 0.4 V	8		
		3.3 V LVCMOS (I/O type 9 - OSCA)		N/A	N/A	
		3.3 V LVCMOS (I/O type 10 - OSCB)		N/A	N/A	
		3.3 V OpenDrain (I/O type 13 - I2C)	V <sub>OL</sub> = 0.6 V	6	-	

## 6.6 Pin Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARAMETER			TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{oz}$	High-impedance leakage current	1.8 V LVCMOS (I/O type 3 - LS DMD)		N/A			$\mu\text{A}$
		3.3 V OpenDrain (I/O type 4 - VX1)		-10		10	
		3.3 V LVCMOS (I/O type 6 - PP)		-10		10	
		3.3 V LVCMOS (I/O type 8 - GPIO)	VOUT = VDD33	-10		10	
		3.3 V LVCMOS (I/O type 9 - OSCA)		N/A		N/A	
		3.3 V LVCMOS (I/O type 10 - OSCB)		N/A		N/A	
		3.3 V OpenDrain (I/O type 13 - I2C)		N/A		N/A	

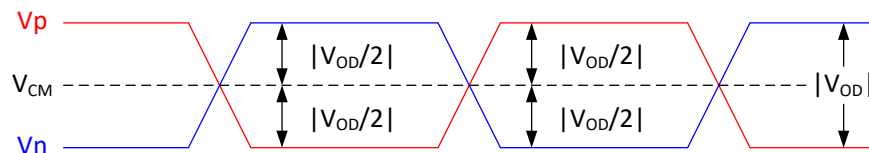
(1) The number inside each parenthesis for the I/O refers to the type defined in 表 5-13.

## 6.7 DMD HSSI Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	NOM	MAX	UNIT
V <sub>DIFF</sub>	Output Peak-to-Peak Differential <sup>(1)</sup> (into floating load R <sub>LOAD</sub> = 100 Ω)	Data	400	1000	mVppd
		Clock	590	1000	mVppd
V <sub>CM</sub>	Output common mode (into floating load R <sub>LOAD</sub> = 100 Ω)	200		700	mV
V <sub>OD</sub>	Output differential voltage <sup>(1)</sup> (into floating load R <sub>LOAD</sub> = 100 Ω)	Data	200	500	mV
		Clock	295	500	mV
R <sub>DIFF</sub>	Differential termination resistance	80	100	120	Ω
R <sub>TERM</sub>	Single-ended termination resistance	40	50	60	Ω
SDD22	Differential output return loss (100 MHz to 0.75 × Baud)			-8	dB
SCC22	Common mode return loss (100 MHz to 0.75 × Baud)			-6	dB
N <sub>CM</sub>	Transmitter common mode noise			(7.5% × V <sub>DIFF</sub> ) + 25 mV	mVppd
DJ <sub>DATA</sub>	Deterministic jitter data (non-DCD)			0.20	UI pp
DJ <sub>CLOCK</sub>	Deterministic jitter clock (non-DCD)			0.16	UI pp
DCD	Duty cycle distortion			0.05	UI pp
TJ	Total jitter (random + DJ)			0.30	UI pp

- (1)  $V_{DIFF-pp} = (V_p - V_n)_{cycle\_N} - (V_p - V_n)_{cycle\_N+1} = 2 \times |V_{OD}|$   
See [6-1](#).



**6-1. HSSI Differential Voltage Parameters**

## 6.8 DMD Low-Speed LVDS Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	NOM	MAX	UNIT	
V <sub>DIFF</sub>	Output peak-to-peak differential (into R <sub>LOAD</sub> = 100 Ω)	VAD18_LSIF (I/O type 2)	340	600	mVppd	
V <sub>CM</sub>	Steady-state common mode voltage	VAD18_LSIF (I/O type 2)	1100	1200	1300	mV
V <sub>OD</sub>   <sup>(1)</sup>	Differential output voltage (into R <sub>LOAD</sub> = 100 Ω)	VAD18_LSIF (I/O type 2)	170	300	mV	
V <sub>OD</sub> (Δ)  <sup>(2)</sup>	V <sub>OD</sub> change (between logic states)	VAD18_LSIF (I/O type 2)		25	mV	
V <sub>CM</sub> (Δ)	V <sub>CM</sub> change (between logic states)	VAD18_LSIF (I/O type 2)		25	mV	
V <sub>OH</sub>	Single-ended output voltage high <sup>(3)</sup>	VAD18_LSIF (I/O type 2)		1450	mV	
V <sub>OL</sub>	Single-ended output voltage low <sup>(3)</sup>	VAD18_LSIF (I/O type 2)	950		mV	
T <sub>Xterm</sub>	Internal differential termination		85	100	115	Ω

- (1)  $V_{DIFF-pp} = (V_p - V_n)_{cycle\_N} - (V_p - V_n)_{cycle\_N+1} = 2 \times |V_{OD}|$   
See [6-2](#)
- (2)  $|V_{OD}(\Delta)| = ||V_{OD}|_{cycle\_N} - |V_{OD}|_{cycle\_N+1}|$
- (3)  $V_{OH} = 1300 + 300/2 = 1450$ ;  $V_{OL} = 1100 - 300/2 = 950$



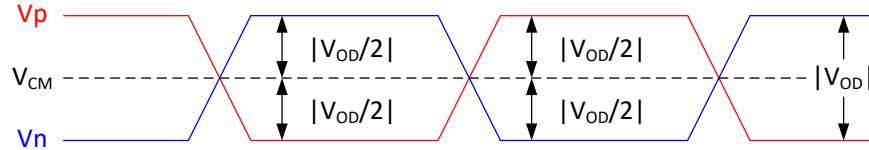


图 6-2. DMD Low-Speed Differential Voltage Parameters

## 6.9 V-by-One Interface Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)

PARAMETER <sup>(1)</sup>			MIN	NOM	MAX	UNIT
$V_{DIFF}$	Input peak-to-peak differential	VAD18_VX1 (I/O type 1)	100			mVppd
$ V_{ID} $	Differential input voltage	VAD18_VX1 (I/O type 1)	50			mV
$R_{Xterm}$	Internal differential termination	VAD18_VX1 (I/O type 1)	80	100	120	$\Omega$

(1) See the [V-by-One interface standard](#) for more information

## 6.10 USB Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)

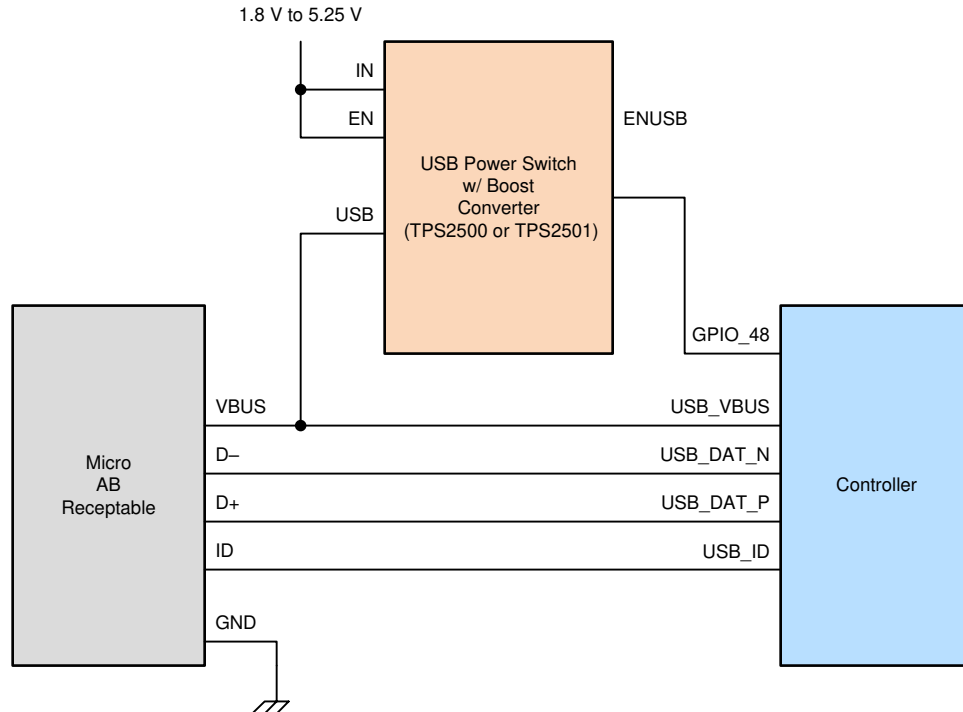
PARAMETER <sup>(1) (2)</sup>			MIN	NOM	MAX	UNIT
Low-Speed and Full Speed (Input Level)						
$V_{IH}$	Single-ended input voltage high (driven)		2.0			V
$V_{IHZ}$	Single-ended input voltage high (floating)		2.7		3.6	V
$V_{IL}$	Single-ended input voltage low				0.8	V
$V_{DI}$	Differential input sensitivity	$ (DP) - (DM) $	0.2			V
$V_{CM}$	Differential common mode voltage	Includes $V_{DI}$ range	0.8		2.5	V
Low-Speed and Full Speed (Output Level)						
$V_{OL}$	Low-level output voltage	with 1.425 K $\Omega$ pullup to 3.6 V	0.0		0.3	V
$V_{OH}$	High-level output voltage	with 14.25 K $\Omega$ pulldown	2.8		3.6	V
$V_{CRS}$	Output signal crossover voltage		1.3		2.0	V
High-Speed (Input Level)						
$V_{HSSQ}$	High-speed squelch detection threshold (differential signal amplitude)		100		150	mV
$V_{HSDSC}$	High-speed disconnect detection threshold (differential signal amplitude)		525		626	mV
$V_{HSCM}$	High-speed data signal common mode voltage		-50		500	mV
High-Speed (Output Level)						
$V_{HSOI}$	High-speed idle level		-10.0		10.0	mV
$V_{HSOH}$	High-speed data signal - high		360		440	mV
$V_{HSOL}$	High-speed data signal - low		-10.0		10.0	mV
$V_{CHIRPJ}$	High-speed chirp J level (differential voltage)		700		1100	mV
$V_{CHIRPK}$	High-speed chirp K level (differential voltage)		-900		-500	mV
<b>Termination</b>						
$R_{PU}$	Bus pullup resistor		1.425		1.575	K $\Omega$
$R_{PD}$	Bus pulldown resistor		14.25		15.75	K $\Omega$

## 6.10 USB Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted)

PARAMETER <sup>(1) (2)</sup>		MIN	NOM	MAX	UNIT
Z <sub>HSDRV</sub>	High-speed driver output impedance	40.5		49.5	Ω

- (1) Referenced to VAD33\_USB (I/O type 11)
- (2) When used as a master as part of USB OTG, the DLPC6540 requires an external USB switch to provide the USB 5-V power. The example shown in [Figure 6-3](#) uses a TI TPS2500/2501 device. The example figure does not describe the required ancillary components (such as resistors and capacitors). For this information, refer to the USB switch logic data sheet for the selected device. The external USB switch is not required for product configurations that support USB slave mode only.

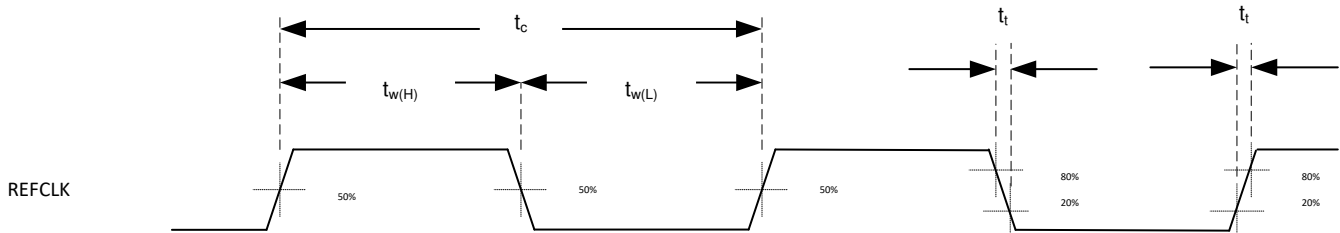


**Figure 6-3. External USB Switch Example for DLPC6540 Controller as USB OTG Master**

## 6.11 System Oscillator Timing Requirements

PARAMETER			MIN	NOM	MAX	UNIT
$f_{\text{clock}}$	Clock frequency, REFCLKA <sup>(1) (2)</sup>	PLLA: 40 MHz	39.9960	40.000	40.0040	MHz
$t_c$	Cycle time, REFCLKA <sup>(1)</sup>	PLLA: 40 MHz	24.9975	25.000	25.0025	ns
$t_{w(H)}$	Pulse duration <sup>(3)</sup> , REFCLKA, high	PLLA: 40 MHz 50% to 50% reference points (signal)	11.25			ns
$t_{w(L)}$	Pulse duration <sup>(3)</sup> , REFCLKA, low	PLLA: 40 MHz 50% to 50% reference points (signal)	11.25			ns
$t_t$	Transition time <sup>(3)</sup> , REFCLKA, $t_t = t_f / t_r$	PLLA: 40 MHz 20% to 80% reference points (signal)			2.5	ns
$t_{jp}$	Long term periodic jitter <sup>(3)</sup> , REFCLKA (that is the deviation in period from ideal period due solely to high frequency jitter)	PLLA: 40 MHz			18	ps
$f_{\text{clock}}$	Clock frequency, REFCLKB <sup>(1)</sup>	PLLB: 38 MHz	37.9962	38.000	38.0038	MHz
$t_c$	Cycle time, REFCLKB <sup>(1)</sup>	PLLB: 38 MHz	26.3132	26.3157	26.3184	ns
$t_{w(H)}$	Pulse duration <sup>(3)</sup> , REFCLKB, high	PLLB: 38 MHz 50% to 50% reference points (signal)	11.84			ns
$t_{w(L)}$	Pulse duration <sup>(3)</sup> , REFCLKB, low	PLLB: 38 MHz 50% to 50% reference points (signal)	11.84			ns
$t_t$	Transition time <sup>(3)</sup> , REFCLKB, $t_t = t_f / t_r$	PLLB: 38 MHz 20% to 80% reference points (signal)			2.63	ns
$t_{jp}$	Long term periodic jitter <sup>(3)</sup> , REFCLKB (that is the deviation in period from ideal period due solely to high frequency jitter)	PLLB: 38 MHz			18	ps

- (1) The REFCLK inputs do not support spread spectrum clock spreading.  
(2) Multi-controller systems require that a single oscillator be used to drive the REFCLKA input for all controllers in the system.  
(3) Applies only when driven through an external digital oscillator. This is a 1-sigma RMS value.



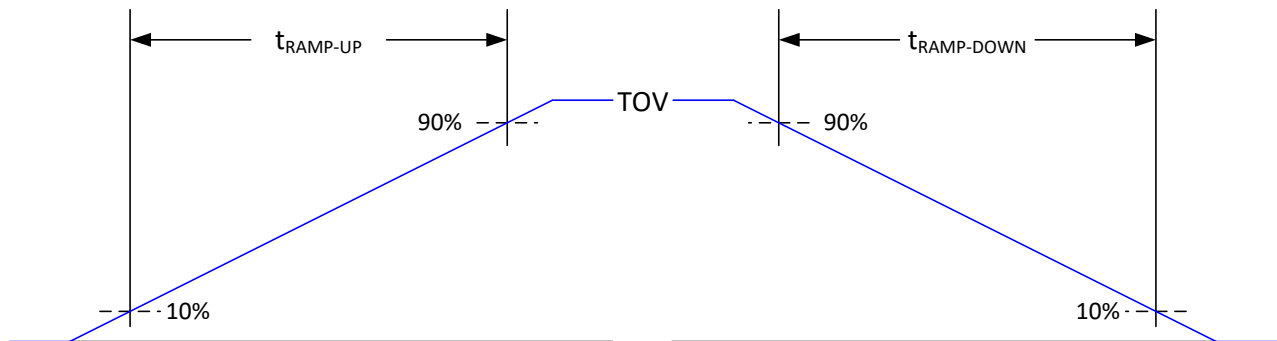
6-4. System Oscillators

## 6.12 Power Supply and Reset Timing Requirements

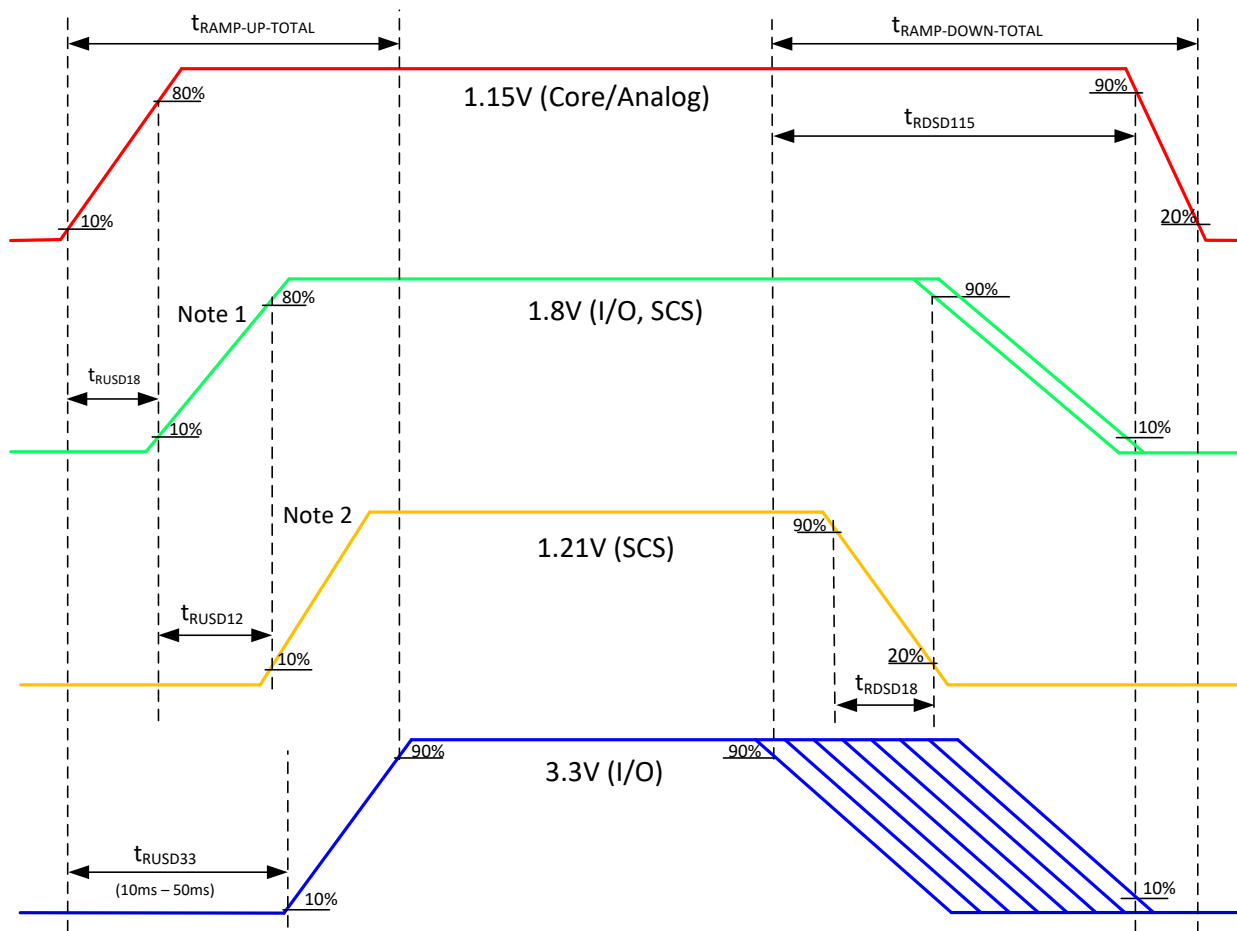
PARAMETER		MIN	MAX	UNIT
$t_{\text{RAMP-UP}}$	Power supply ramp-up time. (1) <a href="#">6-5</a>	0.01	10	ms
$t_{\text{RAMP-UP-TOTAL}}$	Total power supply ramp-up time. <sup>(1)</sup>		100	ms
$t_{\text{RAMP-DOWN}}$	Power supply ramp-down time. (1) <a href="#">6-5</a> <a href="#">6-6</a>	0	100	ms
$t_{\text{RAMP-DOWN-TOTAL}}$	Total power supply ramp-down time. <sup>(1)</sup>		100	ms
$t_{\text{RUSD18}}$	1.8-V Supply Ramp-up Start Delay (2) <a href="#">6-6</a>	See (3)		ms
$t_{\text{RUSD33}}$	3.3-V Supply Ramp-up Start Delay (2) <a href="#">6-6</a>	10	50	ms
$t_{\text{RUSD12}}$	1.21-V Supply Ramp-up Start Delay (2) <a href="#">6-6</a>	See (4)		ms
$t_{\text{RDSD18}}$	1.8-V Supply Ramp-down Start Delay (2) <a href="#">6-6</a>	See (5)		ms
$t_{\text{RDSD115}}$	1.15-V Supply Ramp-down Start Delay (2) <a href="#">6-6</a>	See(8)		
$t_{\text{EW}}$	Early Warning Time <a href="#">6-8</a>	500		$\mu\text{s}$
$t_{\text{PH}}$	Power Hold Time <a href="#">6-8</a>	500 <sup>(9)</sup>		$\mu\text{s}$
$t_{\text{w1}}$	Pulse duration, in-active low, PWRGOOD <a href="#">6-7</a>	4	1000 <sup>(6)</sup>	$\mu\text{s}$
$t_{\text{t1}}$	Transition time, PWRGOOD $t_{\text{t1}} = t_{\text{f1}}$ and $t_{\text{r1}}$ <a href="#">6-7</a>		625	$\mu\text{s}$
$t_{\text{w2}}$	Pulse duration, in-active low, POSENCE <a href="#">6-8</a>	100		ms
$t_{\text{t2}}$	Transition time, POSENCE $t_{\text{t1}} = t_{\text{f1}}$ and $t_{\text{r1}}$ <a href="#">6-8</a>		25	$\mu\text{s}$
$t_{\text{PSD}}$	PWRGOOD Start Delay <a href="#">6-7</a>	51.5	60	ms
$t_{\text{PROJ\_ON}}$	PROJ_ON fall time delay to PWRGOOD <a href="#">6-8</a>	10		ms
$t_{\text{REFCLKA}}$	Time to stable REFCLKA <a href="#">6-7</a>	See (10)		

- (1) It is assumed that all 1.15-V supplies come from the same source, although some can have additional filtering before entering the DLPC6540. As such, it is expected these supplies to ramp together (aside from differences caused by filtering). This same expectation is true for the 1.21-V, 1.8-V, and 3.3-V supplies.
- (2) The DLPC6540 has specific power supply sequencing requirements, listed below, that include the timings specified in this table.
- a. Power Up Order:

- i. 1.15-V (Core, Analog) » 1.8-V (I/O, SCS) » 1.21-V (SCS)
- ii. 1.15-V (Core, Analog) » 3.3-V (I/O)
- b. Power Down Order:
  - i. 3.3-V (I/O) » 1.15-V (Core, Analog)
  - ii. 1.21-V (SCS) » 1.8-V (I/O, SCS) » 1.15-V (Core, Analog)
- (3) This delay requirement parameter is defined as the time between two events. The first event is the point where the 1.15-V power supply ramp-up is started, and the second event is when the 1.15-V supply ramp-up reaches 80% of TOV (at which point the 1.8-V supply can start its ramp-up). Because the occurrence of the second event depends on the specific design of the 1.15-V power supply, the designer must determine the specific delay time.
- (4) This delay requirement parameter is defined as the time between two events. The first event is the point where the 1.8-V power supply ramp-up is started, and the second event is when the 1.8-V supply ramp-up reaches 80% of TOV (at which point the 1.21-V supply can start its ramp-up). Because the occurrence of the second event depends on the specific design of the 1.8-V power supply, the designer must determine the specific delay time.
- (5) This delay requirement parameter is defined as the time between two events. The first event is the point where the 1.21-V power supply ramp-down is started, and the second event is when the 1.21-V supply ramp-down reaches 20% of TOV (at which point the 1.8-V supply can start its ramp-down). Because the occurrence of the second event depends on the specific design of the 1.21-V power supply, the designer must determine the specific delay time. The intent of this delay time is to guarantee that the voltage level of the 1.8-V supply never falls lower than the voltage level of the 1.21-V supply during the ramp-down until the 1.2-V supply is below 300 mV.
- (6) This max value is only applicable if the 1.8-V power remains ON while PWRGOOD is inactive. Otherwise, there is no maximum limit.
- (7) As long as noise on this signal is below the hysteresis threshold
- (8) This delay requirement parameter is defined as the time between two events. The first event is the point where the 3.3-V power supply ramp-down is started, and the second event is when the 3.3-V supply ramp-down and 1.8-V supply ramp down reaches 10% of TOV (at which point the 1.15-V supply can start its ramp-down). Because the occurrence of the second event depends on the specific design of the 3.3-V and 1.8-V power supply, the designer must determine the specific delay time.
- (9) If PROJ\_ON is used for power down then Power Hold Time ( $t_{PH}$ ) is not required.
- (10) This delay requirement parameter is defined by design of RECLKA oscillator. Stable clock must be provided before releasing POSENSE.

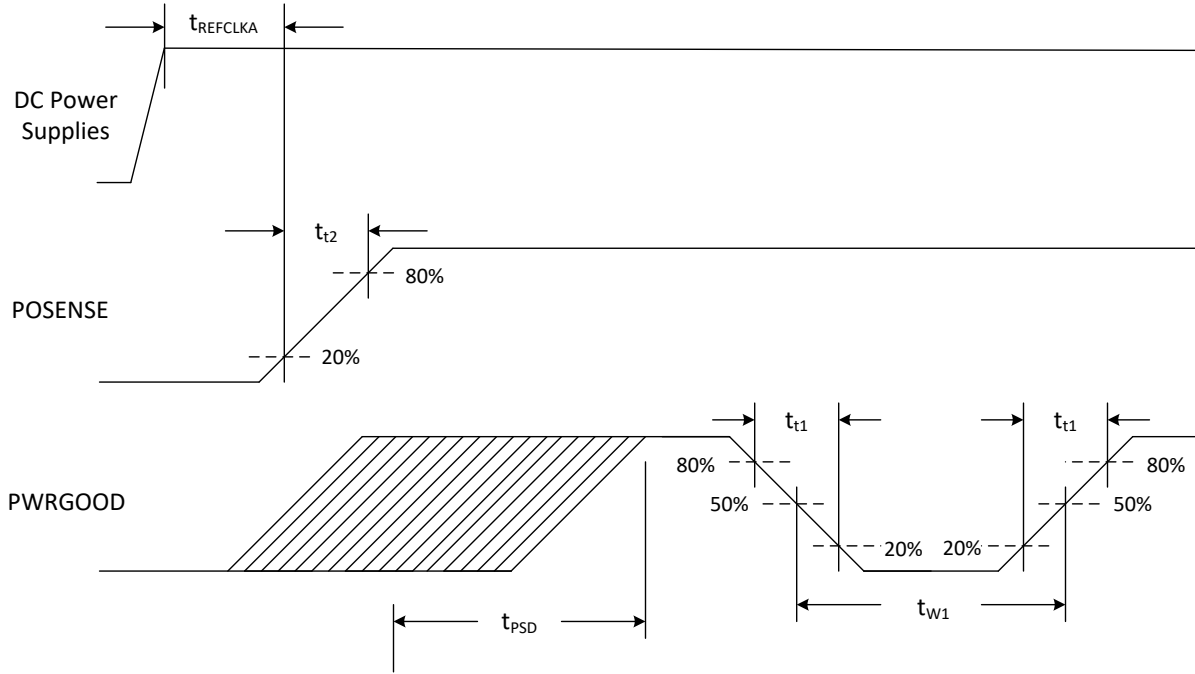


**6-5. Power Supply Ramp Time**

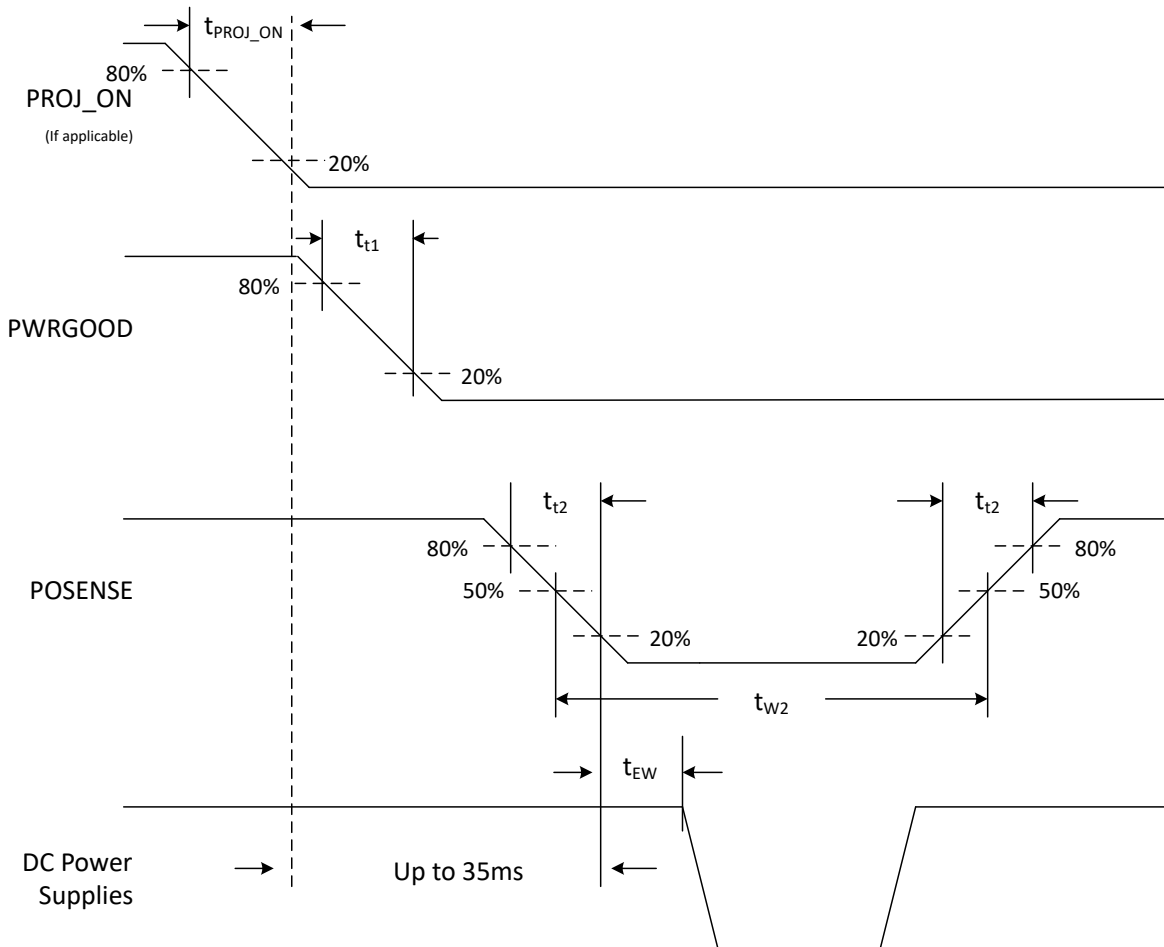


Note 1: No power up or power down timing dependency between 1.8V and 3.3V  
 Note 2: No power up or power down timing dependency between 1.21V and 3.3V

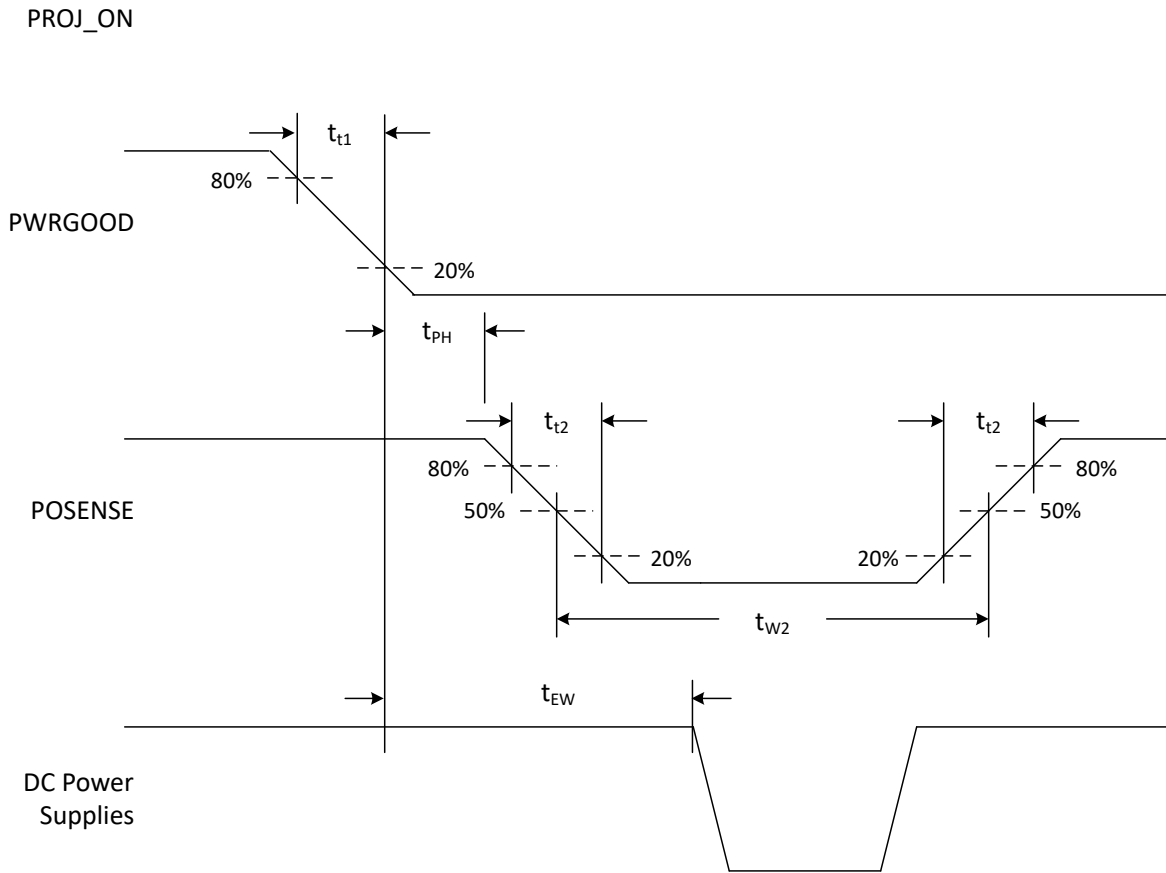
**6-6. Power Supply Ramp Sequencing Profiles**



**Figure 6-7. Power Up Timing**



**Figure 6-8. Power Down Timing—Normal**



6-9. Power Down Timing—Fault

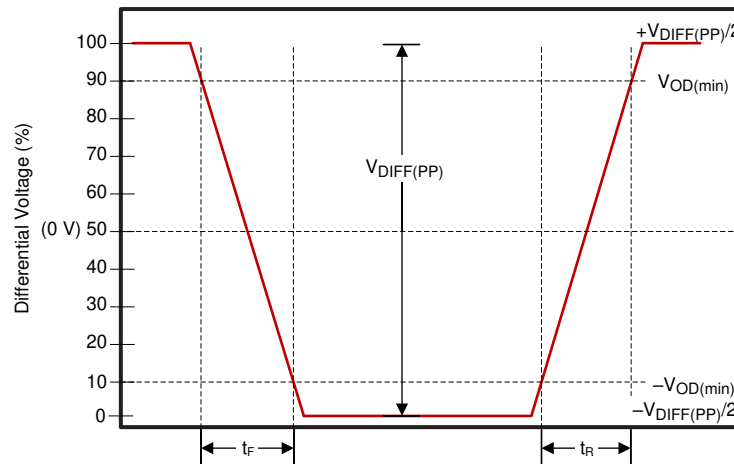


### 6.13 DMD HSSI Timing Requirements

over operating free-air temperature range (unless otherwise noted)

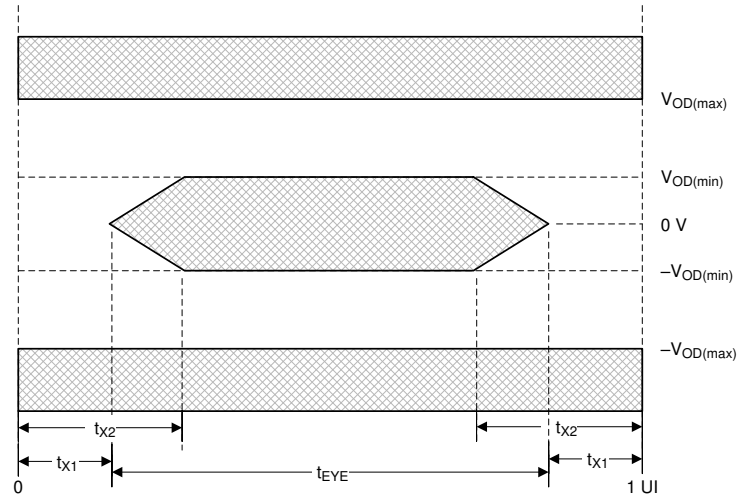
PARAMETER		MIN	NOM	MAX	UNIT
Baud	Baud Rate	2.4		3.2	Gbps
UI	Unit Interval, 1/Baud	312.5		416.7	ps
$t_R$	Differential output rise time <sup>(1) (2)</sup> (0% to 100% of minimum eye mask height)	Data		115	ps
		Clock	50	135	ps
$t_F$	Differential output fall time <sup>(1) (2)</sup> (0% to 100% of minimum eye mask height)	Data		115	ps
		Clock	50	135	ps
$t_{X1}$	Maximum eye closure <sup>(3)</sup>	at zero crossing		0.15	UI
$t_{X2}$	Maximum eye closure <sup>(3)</sup>	at minimum eye height		0.375	UI
$t_{EYE}$	Differential Data Eye <sup>(3)</sup>	0.7			UI
$t_{skIn2In}$	Lane to lane skew within a macro <sup>(2)</sup>			200	ps
$t_{skM2M}$	Lane to lane skew macro to macro <sup>(2)</sup>			4UI+200	ps
$f_{SSCD}$	Spread Spectrum (down spreading only) <sup>(4)</sup>	When SSCD Enabled		1	%
$f_{MOD}$	Modulation Frequency <sup>(4)</sup>	When SSCD Enabled		78.125	KHz

- (1) Rise and fall times are associated with  $V_{DIFF-pp}$  as shown in [6-10](#).
- (2) Measured with an interconnect with an insertion loss of 3dB at 1.6 GHz
- (3) See [6-11](#)
- (4) When SSCD is enabled, the available modulation waveform is: Triangular



$V_{CM}$  is removed when signals are viewed differentially.

**6-10. HSSI Differential Timing Parameters**



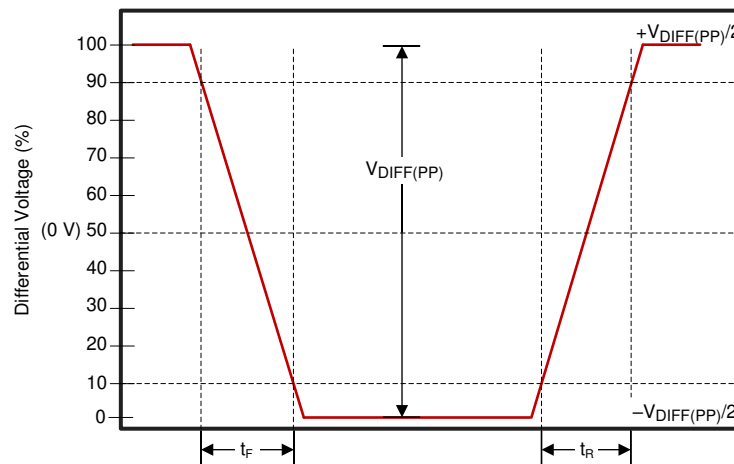
**6-11. HSSI Eye Characteristics**

## 6.14 DMD Low-Speed LVDS Timing Requirements

over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	NOM	MAX	UNIT
f <sub>clock</sub>		119.966	120	120.034	MHz
t <sub>R</sub> <sup>(1)</sup>	Differential output rise time (10% to 90%)			250	ps
t <sub>F</sub> <sup>(1)</sup>	Differential output fall time (10% to 90%)			250	ps
DCD	Duty Cycle Distortion	45		55	%

(1) Rise and Fall times are associated with V<sub>DIFF-pp</sub> as shown in [6-12](#)



V<sub>CM</sub> is removed when signals are viewed differentially

**6-12. DMD Low-Speed Differential Timing Parameters**

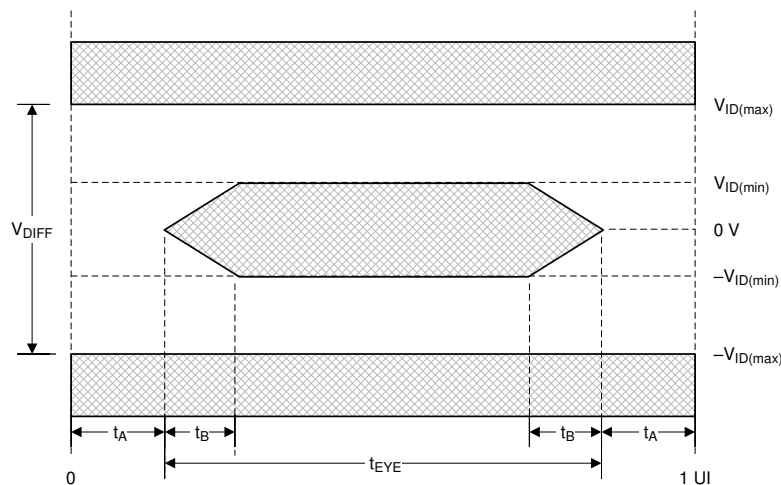
## 6.15 V-by-One Interface General Timing Requirements

PARAMETER <sup>(1)</sup>		MIN	MAX	UNIT
f <sub>clock</sub>	Source clock frequency	40 (1 lane) 20 (1 lane with Pixel Repeat) <sup>(2)</sup>	600 (8 lanes)	MHz

### 6.15 V-by-One Interface General Timing Requirements (continued)

PARAMETER <sup>(1)</sup>			MIN	MAX	UNIT
$f_{\text{link-ck}}$	Link clock frequency per lane <sup>(3)</sup>	8 lanes	43	75	MHz
		4 lanes	43	85	
		2 lanes	43	85	
		1 lane	43 (21.5 with Pixel Repeat)	85	
$f_{\text{link}}$	Link transfer rate <sup>(3)</sup>	3-Byte Mode	2	2.55	Gbps
		4-Byte Mode	2	3.0	
		5-Byte Mode	2.15	3.0	
$t_{\text{RBIT}}$	Unit interval	3-Byte Mode	392	500	ps
		4-Byte Mode	294	500	ps
		5-Byte Mode	294	500	ps
$t_{\text{A}}$	Jitter Margin	0.25		UI	
$t_{\text{B}}$	Rise / Fall Time	0.05		UI	
$t_{\text{EYE}}$	Differential Data Eye	0.5		UI	
$t_{\text{skew\_intra}}$	Allowable intra-pair skew			0.3	UI
$t_{\text{skew\_inter}}$	Allowable Inter-pair Skew			5	UI
$f_{\text{oskew\_inter}}$	Allowable inter-pair frequency offset	-300		300	ppm
$T_{\text{J}}$	Total jitter	—		0.5	UI
$R_{\text{J}}$	Random jitter	10 <sup>^</sup> 12 UI	-	0.2	UI
$D_{\text{J\_ISI}}$	Deterministic jitter (ISI)			0.2	UI
$S_{\text{J}}$	Sinusoidal jitter			0.1	UI

- (1) V-by-One high-speed technology supports 1, 2, 4, or 8 lane operation, in addition to 3-byte, 4-byte, and 5-byte transfer modes.
- (2) Pixel repeat is a method used to support slower clock rate sources, whereby, the source come at twice the original clock rate, with each data pixel being repeated once, and blanking being doubled as well. This method must operate external to DLPC6540. Once received, the DLPC6540 discards each duplicate data pixel and blanking clock. Pixel repeat is supported only during 1- lane operation.
- (3) For V-by-One high-speed technology, both link clock rate and link transfer rate limits must be met for any source.



6-13. V-by-One Timing

## 6.16 Source Frame Timing Requirements

See [Figure 6-14](#)

PARAMETER <sup>(1)</sup>			MIN	MAX	UNIT
$t_{p\_vsw}$	VSYNC Active Pulse Width	50% reference points	1	127	lines
$t_{p\_vbp}$	Vertical back porch (VBP) <sup>(2)</sup>	50% reference points	2 <sup>(3)</sup>		lines
$t_{p\_vfp}$	Vertical front porch (VFP) <sup>(2)</sup>	50% reference points	MAX[ (TVB <sub>MIN</sub> - 65), 1] <sup>(3)</sup>		lines
$t_{p\_tvb}$	Total vertical blanking (TVB) <sup>(2)</sup>	50% reference points	See <sup>(4)</sup>		lines
$t_{p\_hsw}$	HSYNC Active Pulse Width	50% reference points	16		PCLKs
$t_{p\_hbp}$	Horizontal back porch (HBP) <sup>(5)</sup>	50% reference points	5 (Digital Video Sources) 65 (Analog Video Sources)		PCLKs
$t_{p\_hfp}$	Horizontal front porch (HFP) <sup>(5)</sup>	50% reference points	2		PCLKs
$t_{p\_thb}$	Total horizontal blanking (THB) <sup>(5)</sup>	50% reference points	20 (Digital Video Sources) 80 (Analog Video Sources) <sup>(6)</sup>		PCLKs
$f_{line}$	Horizontal line rate		37.354		K Hz
APPL	Active Pixels per Line		640	4096	Pixels
ALPF	Active Lines per Frame		480	2160 (Normal)	Lines

(1) The requirements in the table apply to all external sources

(2) Vertical Blanking Parameter Definitions:

- Vertical Back Porch: Time from the leading edge of VSYNC to the leading edge of HSYNC for the first active line, and includes the VSYNC pulse width  $t_{p\_vsw}$ .
- Vertical Front Porch: Time from the leading edge of HSYNC following the last active line in a frame to the leading edge of VSYNC
- Total Vertical Blanking: The sum of VBP + VFP = TVB.

(3) The vertical blanking required (per TVB) can be allocated as desired as long as the VFP and VBP minimum values are met.

(4) The minimum TVB can be calculated using the following:

$TVB_{min} = 11 + \text{ROUNDUP}(LLS\_VFP\_MIN \times (\text{Source\_ALPF}/VPS\_ALPF))$ , where:

- LLS\_VFP\_MIN (Normal Mode) = 22
- Source\_ALPF = Active Lines Per Frame of the incoming source
- VPS\_ALPF = 1080 (for 1920x1080 Native products and 3840x2160 4-way XPR products)
- Less TVBmin blanking can be required depending on the video processing being done. The configurations that drive the worst case minimum value are those configurations that combine the maximum (or near maximum) capabilities of functions such as scaling, warping, and keystone correction.
- This is applicable to all sources ([Section 7.4](#)). Other sources require directed testing in the end application.
- The minimum recommended TVB with CVT 1.2 sources is 23.

(5) Horizontal Blanking Parameter Definitions:

- Horizontal Back Porch: Time from the leading edge of HSYNC to the rising edge of DATEN, and includes the HSYNC pulse width  $t_{p\_hsw}$ .
- Horizontal Front Porch: Time from the falling edge of DATEN to the leading edge of HSYNC.
- Total Horizontal Blanking: The sum of HBP + HFP = THB.

(6) The horizontal blanking required (per THB) can be allocated as desired as long as the HFP and HBP minimum values are met.

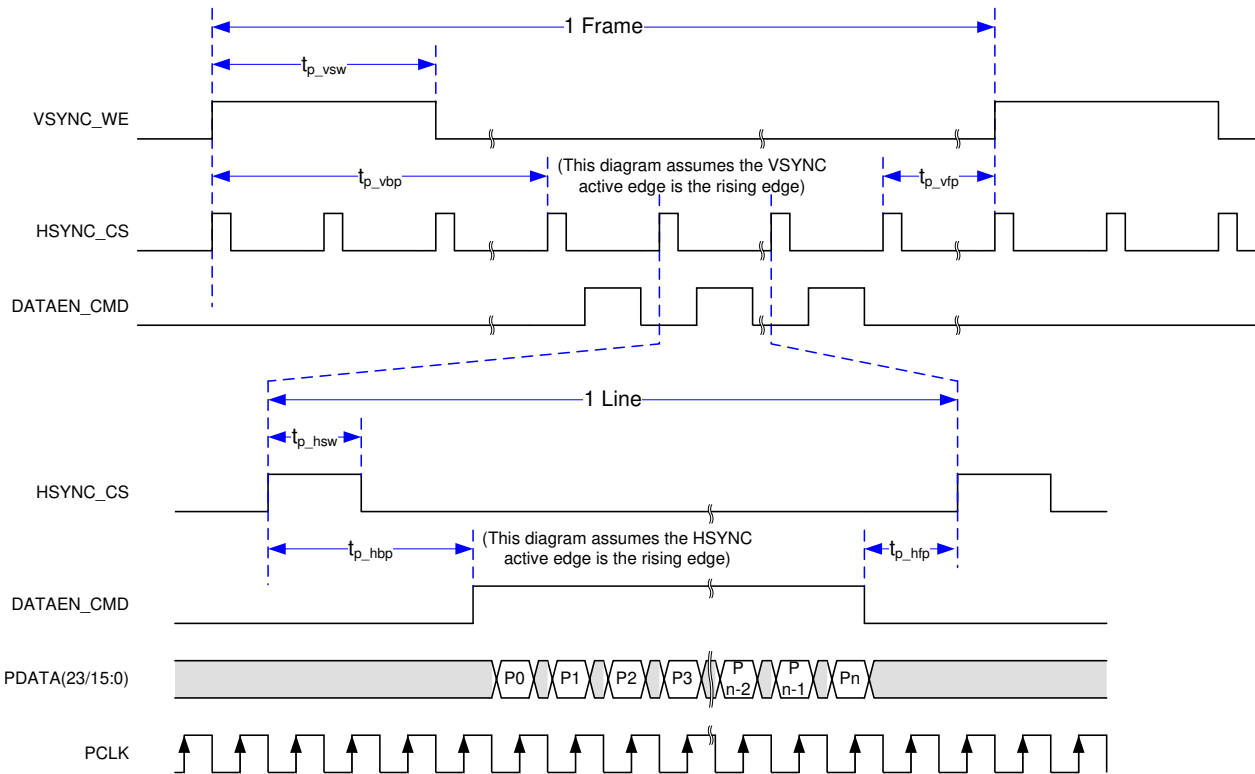


图 6-14. Source Frame Timing

## 6.17 Synchronous Serial Port Interface Timing Requirements

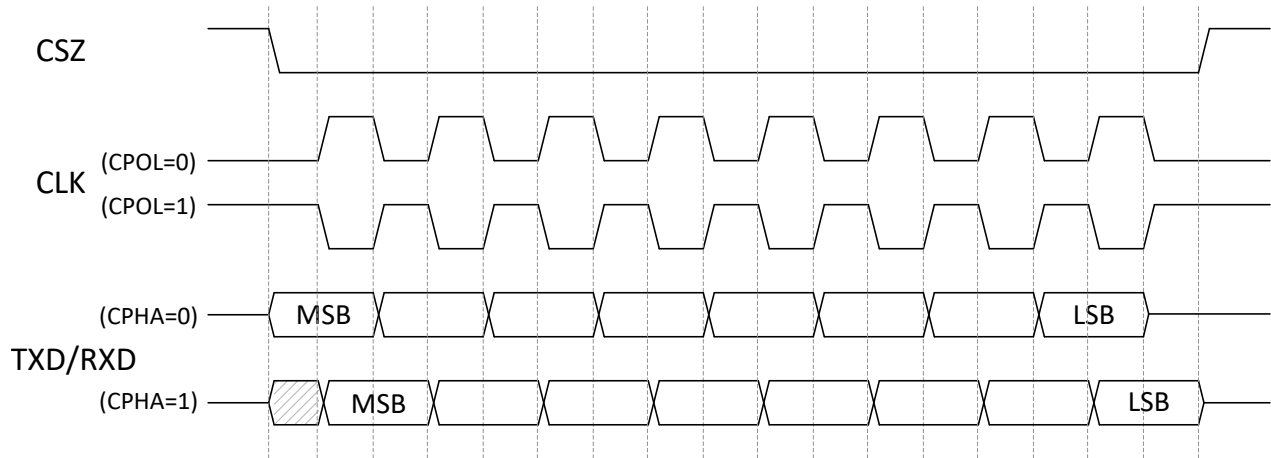
For SSP0, SSP1 and SSP2<sup>(1)(2)</sup>

PARAMETER		MIN	MAX	UNIT
<b>SSP Master</b>				
$f_{clock}$	Clock frequency, SSPx_CLK	50% to 50% reference points		MHz
$t_{clock}$	Clock Period, SSPx_CLK	50% to 50% reference points		ns
$t_{w(L)}$	Pulse duration low, SSPx_CLK	50% to 50% reference points		ns
$t_{w(H)}$	Pulse duration high, SSPx_CLK	50% to 50% reference points		ns
$t_{delay}$	Output Delay – SSPx_TXD (MOSI)	-2.5	2.5	ns
$t_{su}$	Setup time – SSPx_RXD (MISO)	50% to 50% reference points		ns
$t_h$	hold time – SSPx_RXD (MISO)	50% to 50% reference points		ns
$t_t$	Transition time ( $t_r$ and $t_f$ SSPx_RXD)	20% to 80% reference points		ns
$t_{clkjit}$	Clock Jitter, SSPx_CLK		300	ps
$t_{delay\Delta}$	Clock output delay $\Delta \{  t_{w(H)} - t_{w(L)}  \}$		500	ps
<b>SSP Slave</b>				
$t_{delay}$	Output Delay – SSPx_TXD (MOSI)	0	15	ns
$t_{su}$	Setup time – SSPx_RXD (MISO)	50% to 50% reference points		ns
$t_h$	hold time – SSPx_RXD (MISO)	50% to 50% reference points		ns

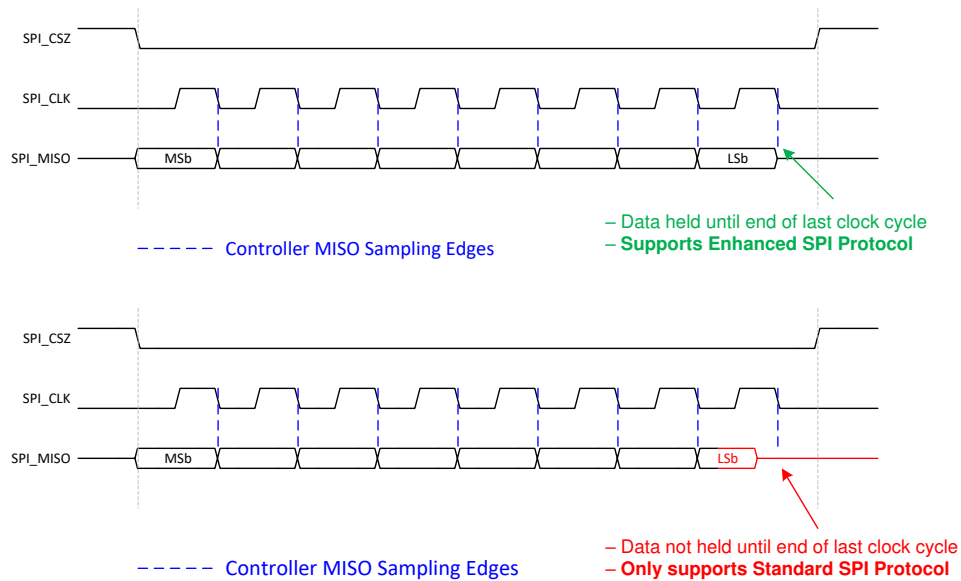
- (1) The DLPC6540 SPI interfaces support SPI Modes 0, 1, 2, and 3 (that is, both clock polarities and both clock phases) as shown in 表 6-2 and 图 6-15. As such, each SPI interface configuration must be setup to match the SPI mode being used.
- (2) In most SPI applications, one clock edge is used by both master and slave devices for transmitting data while the other edge is use by both for sampling received data. This is referred to as *Standard SPI Protocol*. To maximize the SPI\_CLK frequency potential, SPI masters can alternatively be designed to sample the data in (MISO) bit on the same clock edge used to transmit the next data out (MOSI) bit. This is referred to as *Enhanced SPI Protocol*. The DLPC6540 SPI master implementation supports both protocols (part of SPI interface configuration), however, to be able to use the "Enhanced SPI Protocol", the slave device must meet the requirement shown in 图 6-16.

**表 6-2. SPI Clocking Modes**

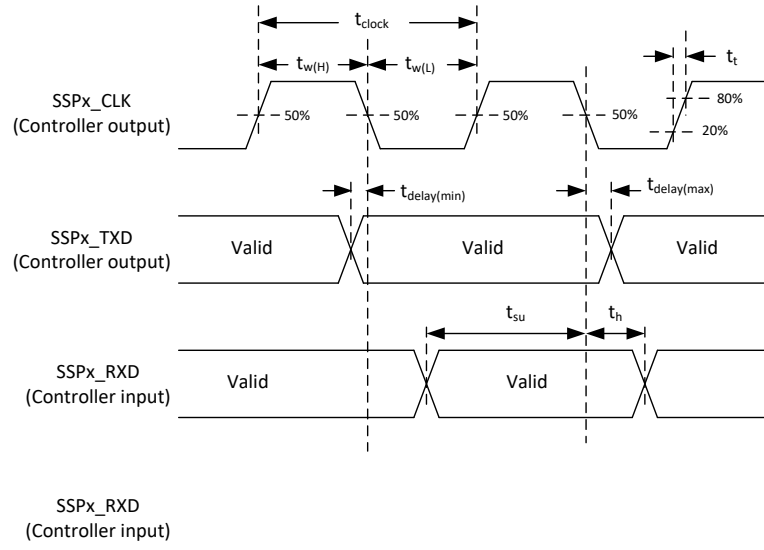
SPI Clocking Mode	SPI Clock Polarity	SPI Clock Phase
0	0	0
1	0	1
2	1	0
3	1	1



**图 6-15. Timing Diagram for SPI Clocking Modes**



**图 6-16. Requirement for Enhanced SPI Protocol**



❏ 6-17. Timing Diagram for SSP Master (Modes 0/3)

## 6.18 Master and Slave I<sup>2</sup>C Interface Timing Requirements

For IIC0, IIC1 and IIC2

PARAMETER <sup>(1)</sup>		MIN	MAX	UNIT
f <sub>clock</sub>	Clock frequency, IICx_SCL <sup>(2)</sup> (50% reference points)	Full speed	400	kHz
		Standard mode	100	kHz
C <sub>L</sub>	Capacitive Load (for each bus line)		200	pF

- (1) Meets all I<sup>2</sup>C timing per the I<sup>2</sup>C Bus Specification (except for capacitive loading as specified). For reference, see Version 2.1 of the Phillips-NXP specification.
- (2) By definition, I<sup>2</sup>C transactions operate at the speed of the slowest device on the bus. Full speed operation requires all other I<sup>2</sup>C devices on the bus support full-speed operation. The length of the line (due to its capacitance), as well as the value of the I<sup>2</sup>C pullup resistors, can reduce the obtainable clock rate.

## 6.19 Programmable Output Clock Timing Requirements

PARAMETER		MIN	MAX	UNIT
f <sub>clock</sub>	Clock frequency, OCLKA <sup>(1)</sup>	0.19	48.75	MHz
t <sub>clock</sub>	Clock period, OCLKA	20.52	5263.15	ns
t <sub>w(H)</sub>	Pulse duration high, OCLKA (50% reference points)	(t <sub>clock</sub> /2) - 2		ns
t <sub>w(L)</sub>	Pulse duration low, OCLKA (50% reference points)	(t <sub>clock</sub> /2) - 2		ns
t <sub>cclkjit</sub>	Jitter, OCLKA		200	ps
f <sub>clock</sub>	Clock frequency, OCLKB <sup>(1)</sup>	0.19	48.75	MHz
t <sub>clock</sub>	Clock period, OCLKB	20.52	5263.15	ns
t <sub>w(H)</sub>	Pulse duration high, OCLKB (50% reference points)	(t <sub>clock</sub> /2) - 2		ns
t <sub>w(L)</sub>	Pulse duration low, OCLKB (50% reference points)	(t <sub>clock</sub> /2) - 2		ns
t <sub>cclkjit</sub>	Jitter, OCLKB		200	ps
f <sub>clock</sub>	Clock frequency, OCLKC <sup>(1)</sup>	0.19	48.75	MHz
t <sub>clock</sub>	Clock period, OCLKC	20.52	5263.15	ns
t <sub>w(H)</sub>	Pulse duration high, OCLKC (50% reference points)	(t <sub>clock</sub> /2) - 2		ns

PARAMETER		MIN	MAX	UNIT
$t_{w(L)}$	Pulse duration low, OCLKC (50% reference points)	$(t_{clock}/2) - 2$		ns
$t_{cclkjit}$	Jitter, OCLKC	200		ps
$f_{clock}$	Clock frequency, OCLKD <sup>(1)</sup>	0.19	48.75	MHz
$t_{clock}$	Clock period, OCLKD	20.52	5263.15	ns
$t_{w(H)}$	Pulse duration high, OCLKD (50% reference points)	$(t_{clock}/2) - 2$		ns
$t_{w(L)}$	Pulse duration low, OCLKD (50% reference points)	$(t_{clock}/2) - 2$		ns
$t_{cclkjit}$	Jitter, OCLKD	200		ps

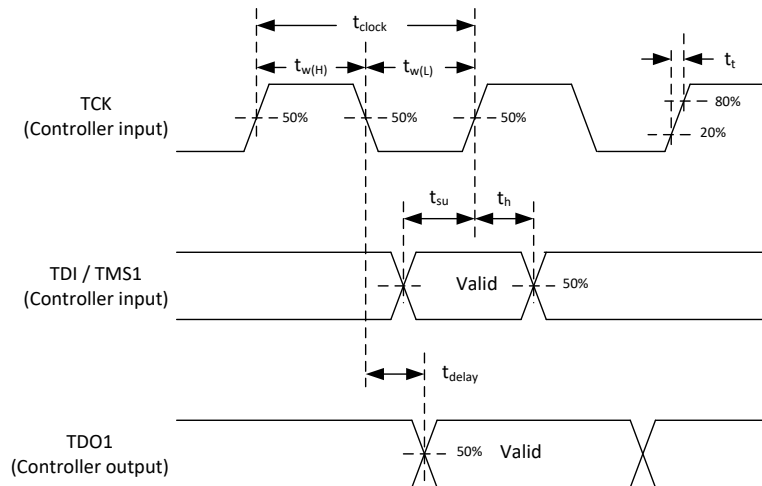
- (1) a. OCLKA is a dedicated pin, while OCLKB thru OCLKD are available via GPIO as alternate functions.
- b. The frequency of OCLKA thru OCLKD is programmable, with each having a power-up default frequency of 0.77 MHz. This default frequency is not that meaningful for OCLKB thru OCLKD since they must be configured to their alternate GPIO function before they can be used as a clock output.



## 6.20 JTAG Boundary Scan Interface Timing Requirements (Debug Only)

See [6-18](#)

PARAMETER		MIN	MAX	UNIT	
$f_{\text{clock}}$	Clock frequency, TCK		20	MHz	
$t_{\text{clock}}$	Clock period, TCK	50		ns	
$t_{w(H)}$	Pulse duration low, TCK	50% reference points	23	ns	
$t_{w(L)}$	Pulse duration high, TCK	50% reference points	27	ns	
$t_s$	Setup time – TDI valid before TCK $\uparrow$	50% reference points	10	ns	
$t_h$	Hold time – TDI valid after TCK $\uparrow$	50% reference points	10	ns	
$t_s$	Setup time – TMS1 valid before TCK $\uparrow$	50% reference points	10	ns	
$t_h$	Hold time – TMS1 valid after TCK $\uparrow$	50% reference points	10	ns	
$t_t$	Transition time ( $t_r$ and $t_f$ )	20% to 80% reference points	3	ns	
$t_{\text{delay}}$	Output delay, TCK $\downarrow$ to TDO1	60pF load	0	15	ns

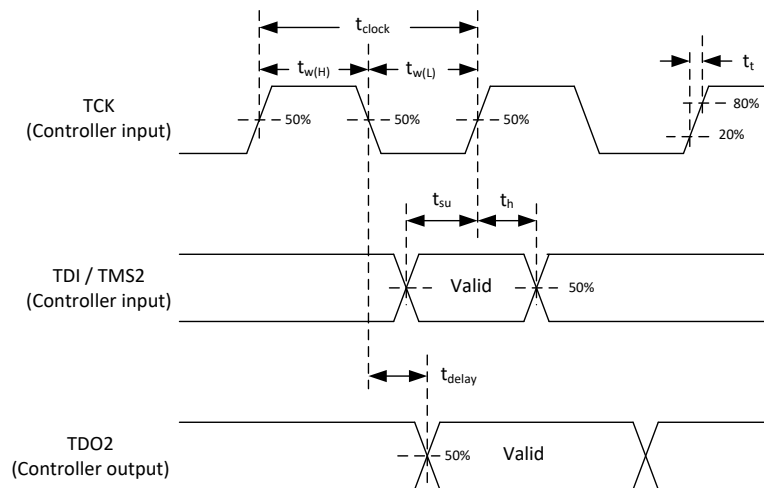


**6-18. Timing Diagram for JTAG Boundary Scan**

## 6.21 JTAG ARM Multi-Ice Interface Timing Requirements (Debug Only)

See [Figure 6-19](#).

PARAMETER		MIN	MAX	UNIT
$f_{\text{clock}}$	Clock frequency, TCK		8.33	MHz
$t_{\text{clock}}$	Clock period, TCK	120		ns
$t_{w(H)}$	Pulse duration low, TCK	50% reference points		ns
$t_{w(L)}$	Pulse duration high, TCK	50% reference points		ns
$t_s$	Setup time – TDI valid before TCK $\uparrow$	50% reference points		ns
$t_h$	Hold time – TDI valid after TCK $\uparrow$	50% reference points		ns
$t_s$	Setup time – TMS2 valid before TCK $\uparrow$	50% reference points		ns
$t_h$	Hold time – TMS2 valid after TCK $\uparrow$	50% reference points		ns
$t_t$	Transition time ( $t_r$ and $t_f$ )		5	ns
$t_{\text{delay}}$	Output delay, TCK $\downarrow$ to TDO2	0	15	ps



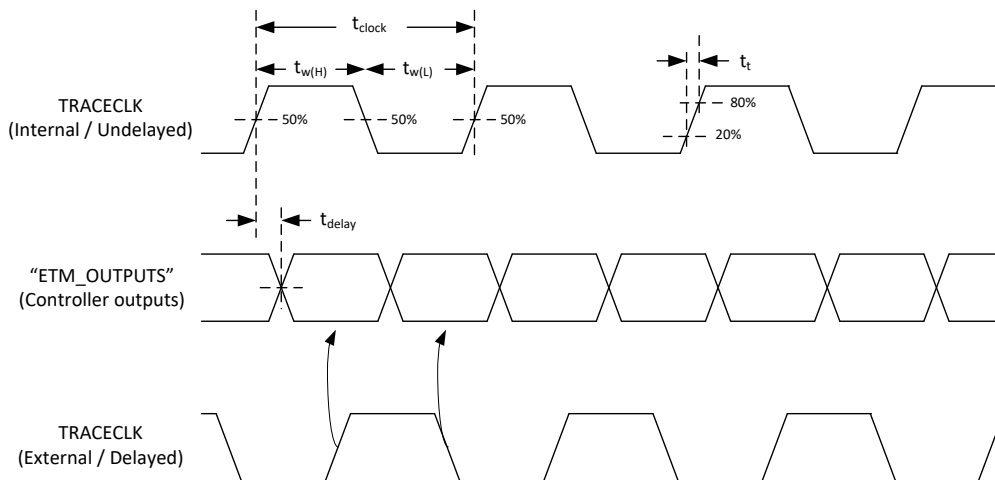
**Figure 6-19. Timing Diagram for JTAG ARM Multi-Ice**

## 6.22 Multi-Trace ETM Interface Timing Requirements

See [Figure 6-20](#).

PARAMETER <sup>(1)</sup>		MIN	MAX	UNIT
$f_{\text{clock}}$	Clock frequency, ETM_TRACECLK		41.56	MHz
$t_{\text{clock}}$	Clock period, ETM_TRACECLK	24.1		ns
$t_{w(H)}$	Pulse duration low, ETM_TRACECLK	50% reference points	11.2	ns
$t_{w(L)}$	Pulse duration high, ETM_TRACECLK	50% reference points	11.2	ns
$t_{\text{delay}}$	Output delay, ETM_TRACECLK $\uparrow$ to "ETM_OUTPUTS" <sup>(2)</sup>	3.0	9.0	ps
$t_{\text{delay}}$	Output delay, ETM_TRACECLK $\downarrow$ to "ETM_OUTPUTS" <sup>(2)</sup>	3.0	9.0	ps

- (1) The trace interface is a source synchronous DDR interface. TRACE\_CLK has a programmable delay to provide for centering its edges in the center of the trace data to optimize performance.
- (2) "ETM\_OUTPUTS" are: TSTPT\_(7:0) and ETM\_TRACECTL



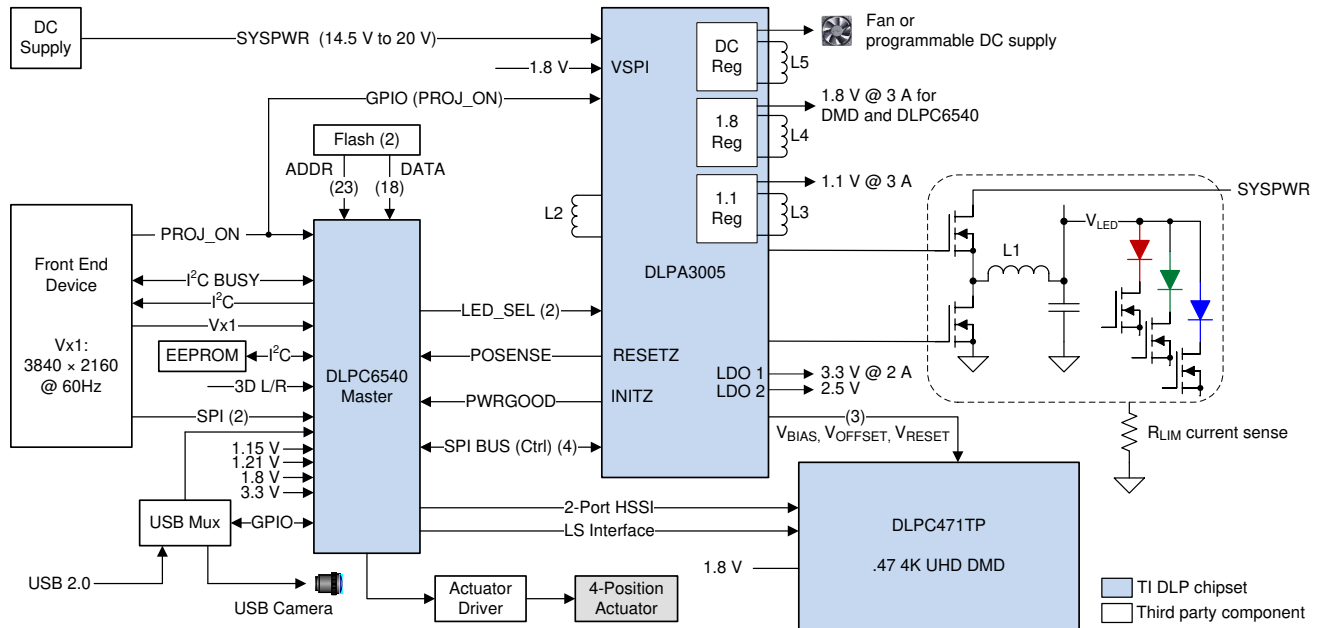
**Figure 6-20. Timing Diagram for Multi-Trace ETM**

## 7 Detailed Description

### 7.1 Overview

The DLP Products chipset consists of three components: the DLPC471TP digital micromirror device (DMD), the DLPC6540 digital display controller, and the DLPA3005. The DLPC6540 is the display controller for the DMD that formats incoming video and controls the timing of the DMD. It also controls DLPA3005 light source signal timing to coordinate with DMD timing in order to synchronize light output with DMD mirror movement. The DLPC6540 provides interfaces such as V-by-One and HSSI (DMD interface) to minimize power consumption and EMI. Applications include mobile smart TV, digital signage, and mobile home cinema.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Input Sources

**表 7-1. Supported Input Source Parameters**

INTERFACE	BITS/PIXEL ACCEPTED (MAX)	BITS/PIXEL PROCESSED (MAX)	SOURCE RESOLUTION: 2D		SOURCE RESOLUTION: 3D (PER EYE) <sup>(1)</sup>
			MIN	MAX	MAX
V-by-One	12	10	640 × 480 <sup>(2)</sup>	4096 × 2160	1920 × 1080 (FS)

(1) FS = Frame Sequential (full resolution).

(2) The minimum clock rate and link rate for the V-by-One interface, as well as Byte Mode, limits the smallest resolution that can be supported by this interface. This interface supports 3-byte, 4-byte, and 5-byte modes.

### 7.3.2 Processing Delays

The DLPC6540 introduces a variable number of field/frame delays dependent on the source type and selected processing steps performed on the source. For optimum audio/video synchronization, this delay must be matched in the audio path. The following tables define the various video delay scenarios to aid in audio matching.

Because the input and output rates are different when frame rate conversion (FRC) is employed, the delay through the FRC is variable.

**表 7-2. Normal Mode Video-Graphics Processing Delay (2-D Sources) <sup>(1)(2)</sup>**

FRC TYPE <sup>(3) (4)</sup>	SOURCE EXAMPLE	DE-INTERLACING	FRAME RATE CONVERSION (INCLUDES WARPING)	FORMATTER BUFFER	TOTAL DELAY
ASYNCR (↑)	10-47 Hz Progressive Graphics	Disabled (0 Frame)	1 to (1 + N) Frames	N Frames	(1 + N) to (1 + 2N) Frames
SYNCR (1:1)	47-120 Hz Progressive Graphics	Disabled (0 Frame)	1 Frame	1 Frame	2 Frames
ASYNCR (↓)	63-120 Hz Progressive Graphics	Disabled (0 Frame)	0 to N Frames	N Frames	N to 2N Frames
SYNCR (↑)	24-30 Hz Progressive Video	Enabled <sup>(5)</sup> (1 Frame)	1 Frame	N Frame	2 + N Frames
SYNCR (1:1)	60 Hz Progressive Video	Enabled <sup>(5)</sup> (1 Frame)	1 Frame	1 Frame	3 Frames

(1) "N" is defined to be the ratio of the source frame rate (or field rate for interlaced video) to the display frame/field rate.

(2) This table assumes that the resolution limits for input sources specified elsewhere in this document are adhered to.

(3) "ASYNCR" is defined as an asynchronous source

(4) "SYNCR" is defined as a synchronous source

(5) DEI noise reduction enabled

**表 7-3. Normal Mode Video-Graphics Processing Delay (3-D Sources) <sup>(1)(2)</sup>**

FRC TYPE	SOURCE EXAMPLE	DE-INTERLACING	FRAME RATE CONVERSION (INCLUDES WARPING)	FORMATTER BUFFER	TOTAL DELAY
SYNCR(1:4)	30 Hz Frame Sequential (30 Hz both eyes)	Disabled (0 Frame)	1 Frame	M Frames	1 + M Frames
SYNCR(1:2)	60 Hz Frame Sequential (60 Hz both eyes)	Disabled (0 Frame)	1 Frame	M Frames	1 + M Frames

(1) "M" is defined to be the ratio of the source frame rate (or field rate for interlaced video) *required to obtain both the left and right image of an eye pair*, to the display frame/field rate (the rate at which each eye is displayed).

(2) This table assumes that the resolution limits for input sources specified elsewhere in this document are adhered to.

### 7.3.3 V-by-One Interface

The DLPC6540 controller supports a single 8 lane V-by-One port that can be configured for 1, 2, 4, or 8 lane use. This interface supports limited lane remapping, which is shown in [表 7-4](#) . Intra-lane remapping (that is, swapping P with N) is not supported.

**表 7-4. V-by-One Interface Lane Remapping Options**

CONFIGURATION N <sup>(1)</sup>	# OF LANES	V-BY-ONE PORT PHYSICAL LANES <sup>(1)</sup>							
		LANE 7	LANE 6	LANE 5	LANE 4	LANE 3	LANE 2	LANE 1	LANE 0
1	8	7	6	5	4	3	2	1	0
2	8	1	0	2	3	4	5	6	7

(1) There are two controller lane mapping options, with the option to use fewer than the full eight lanes for each of these.

Independent from the remapping of the physical V-by-One interface, the DLPC6540 supports a number of data mappings onto the actual physical interface as specified by the standard. V-by-One sources must match at least one of these mappings. These are shown in [表 7-5](#), [表 7-6](#), [表 7-7](#), [表 7-8](#), [表 7-9](#), [表 7-10](#), [表 7-11](#), [表 7-12](#), [表 7-13](#), and [表 7-14](#).

**表 7-5. V-by-One Data Mapping for 36bpp/30bpp RGB/YCbCr 4:4:4**

V-by-One DATA MAP MODE 0			
V-by-One INPUT DATA BIT	36bpp RGB/YCbCr 4:4:4 <sup>(1)</sup>	30bpp RGB/YCbCr 4:4:4	MAPPER OUTPUT
D[0]	R/Cr[4]	R/Cr[2]	B(2)
D[1]	R/Cr[5]	R/Cr[3]	B(3)
D[2]	R/Cr[6]	R/Cr[4]	B(4)
D[3]	R/Cr[7]	R/Cr[5]	B(5)
D[4]	R/Cr[8]	R/Cr[6]	B(6)
D[5]	R/Cr[9]	R/Cr[7]	B(7)
D[6]	R/Cr[10]	R/Cr[8]	B(8)
D[7]	R/Cr[11]	R/Cr[9]	B(9)
D[8]	G/Y[4]	G/Y[2]	A(2)
D[9]	G/Y[5]	G/Y[3]	A(3)
D[10]	G/Y[6]	G/Y[4]	A(4)
D[11]	G/Y[7]	G/Y[5]	A(5)
D[12]	G/Y[8]	G/Y[6]	A(6)
D[13]	G/Y[9]	G/Y[7]	A(7)
D[14]	G/Y[10]	G/Y[8]	A(8)
D[15]	G/Y[11]	G/Y[9]	A(9)
D[16]	B/Cb[4]	B/Cb[2]	C(2)
D[17]	B/Cb[5]	B/Cb[3]	C(3)
D[18]	B/Cb[6]	B/Cb[4]	C(4)
D[19]	B/Cb[7]	B/Cb[5]	C(5)
D[20]	B/Cb[8]	B/Cb[6]	C(6)
D[21]	B/Cb[9]	B/Cb[7]	C(7)
D[22]	B/Cb[10]	B/Cb[8]	C(8)
D[23]	B/Cb[11]	B/Cb[9]	C(9)
D[24]	-	-	-
D[25]	-	-	-
D[26]	B/Cb[2]	B/Cb[1]	C[0]
D[27]	B/Cb[3]	B/Cb[0]	C[1]
D[28]	G/Y[2]	G/Y[1]	A[0]
D[29]	G/Y[3]	G/Y[0]	A[1]
D[30]	R/Cr[2]	R/Cr[1]	B[0]
D[31]	R/Cr[3]	R/Cr[0]	B[1]

(1) For 36-bit inputs, the 12 bits per color truncate to 10-bits per color with the two least significant bits per color being discarded.

表 7-6. V-by-One Data Mapping for 27bpp RGB/YCbCr 4:4:4

V-by-One DATA MAP MODE 1		
V-by-One INPUT DATA BIT	27bpp RGB/YCbCr 4:4:4 <sup>(1)</sup>	MAPPER OUTPUT
D[0]	R/Cr[1]	B(2)
D[1]	R/Cr[2]	B(3)
D[2]	R/Cr[3]	B(4)
D[3]	R/Cr[4]	B(5)
D[4]	R/Cr[5]	B(6)
D[5]	R/Cr[6]	B(7)
D[6]	R/Cr[7]	B(8)
D[7]	R/Cr[8]	B(9)
D[8]	G/Y[1]	A(2)
D[9]	G/Y[2]	A(3)
D[10]	G/Y[3]	A(4)
D[11]	G/Y[4]	A(5)
D[12]	G/Y[5]	A(6)
D[13]	G/Y[6]	A(7)
D[14]	G/Y[7]	A(8)
D[15]	G/Y[8]	A(9)
D[16]	B/Cb[1]	C(2)
D[17]	B/Cb[2]	C(3)
D[18]	B/Cb[3]	C(4)
D[19]	B/Cb[4]	C(5)
D[20]	B/Cb[5]	C(6)
D[21]	B/Cb[6]	C(7)
D[22]	B/Cb[7]	C(8)
D[23]	B/Cb[8]	C(9)
D[24]	-	-
D[25]	-	-
'0'	—	C[0]
D[27]	B/Cb[0]	C[1]
'0'	—	A[0]
D[29]	G/Y[0]	A[1]
'0'	—	B[0]
D[31]	R/Cr[0]	B[1]

(1) For 27-bit inputs, the 9 bits for each color shifts up one bit, and the least significant bit of each color is set to '0'.



**表 7-7. V-by-One Data Mapping for 24bpp RGB/YCbCr 4:4:4**

V-by-One DATA MAP MODE 2		
V-by-One INPUT DATA BIT	24bpp RGB/YCbCr 4:4:4 <sup>(1)</sup>	MAPPER OUTPUT
D[0]	R/Cr[0]	B(2)
D[1]	R/Cr[1]	B(3)
D[2]	R/Cr[2]	B(4)
D[3]	R/Cr[3]	B(5)
D[4]	R/Cr[4]	B(6)
D[5]	R/Cr[5]	B(7)
D[6]	R/Cr[6]	B(8)
D[7]	R/Cr[7]	B(9)
D[8]	G/Y[0]	A(2)
D[9]	G/Y[1]	A(3)
D[10]	G/Y[2]	A(4)
D[11]	G/Y[3]	A(5)
D[12]	G/Y[4]	A(6)
D[13]	G/Y[5]	A(7)
D[14]	G/Y[6]	A(8)
D[15]	G/Y[7]	A(9)
D[16]	B/Cb[0]	C(2)
D[17]	B/Cb[1]	C(3)
D[18]	B/Cb[2]	C(4)
D[19]	B/Cb[3]	C(5)
D[20]	B/Cb[4]	C(6)
D[21]	B/Cb[5]	C(7)
D[22]	B/Cb[6]	C(8)
D[23]	B/Cb[7]	C(9)
D[24]	-	-
D[25]	-	-
'0'	—	C[0]
'0'	—	C[1]
'0'	—	A[0]
'0'	—	A[1]
'0'	—	B[0]
'0'	—	B[1]

(1) For 24-bit inputs, the 8 bits for each color shift up two bits, and the two least significant bits of each color are set to '0'.

表 7-8. V-by-One Data Mapping for 32bpp/24bpp/20bpp YCbCr 4:2:2 <sup>(1)</sup>

V-by-One DATA MAP MODE 3				
V-by-One INPUT DATA BIT	32bpp YCbCr 4:2:2 <sup>(2)</sup>	24bpp YCbCr 4:2:2 <sup>(3)</sup>	20bpp YCbCr 4:2:2	MAPPER OUTPUT
D[0]	CbCr[8]	CbCr[4]	CbCr[2]	B(2)
D[1]	CbCr[9]	CbCr[5]	CbCr[3]	B(3)
D[2]	CbCr[10]	CbCr[6]	CbCr[4]	B(4)
D[3]	CbCr[11]	CbCr[7]	CbCr[5]	B(5)
D[4]	CbCr[12]	CbCr[8]	CbCr[6]	B(6)
D[5]	CbCr[13]	CbCr[8]	CbCr[7]	B(7)
D[6]	CbCr[14]	CbCr[10]	CbCr[8]	B(8)
D[7]	CbCr[15]	CbCr[11]	CbCr[9]	B(9)
D[8]	Y[8]	Y[4]	Y[2]	A(2)
D[9]	Y[9]	Y[5]	Y[3]	A(3)
D[10]	Y[10]	Y[6]	Y[4]	A(4)
D[11]	Y[11]	Y[7]	Y[5]	A(5)
D[12]	Y[12]	Y[8]	Y[6]	A(6)
D[13]	Y[13]	Y[9]	Y[7]	A(7)
D[14]	Y[14]	Y[10]	Y[8]	A(8)
D[15]	Y[15]	Y[11]	Y[9]	A(9)
'0'	—	—	—	C(2)
'0'	—	—	—	C(3)
'0'	—	—	—	C(4)
'0'	—	—	—	C(5)
'0'	—	—	—	C(6)
'0'	—	—	—	C(7)
'0'	—	—	—	C(8)
'0'	—	—	—	C(9)
D[24]	-	-	-	-
D[25]	-	-	-	-
'0'	—	—	—	C[0]
'0'	—	—	—	C[1]
D[28]	Y[6]	Y[2]	Y[2]	A[0]
D[29]	Y[7]	Y[3]	Y[3]	A[1]
D[30]	CbCr[6]	CbCr[2]	CbCr[2]	B[0]
D[31]	CbCr[7]	CbCr[3]	CbCr[3]	B[1]

(1) For all YCbCr 4:2:2 formats, data channel C is forced to "0".

(2) For 32-bit inputs, the 16 bits per color truncate to 10-bit per color, with the six least significant bits per color discarded.

(3) For 24-bit inputs, the 12 bits per color truncate to 10-bit per color, with the two least significant bits per color discarded.

**表 7-9. V-by-One Data Mapping for 18bpp YCbCr 4:2:2<sup>(1)</sup>**

V-by-One DATA MAP MODE 4		
V-by-One INPUT DATA BIT	18bpp YCbCr 4:2:2 <sup>(2)</sup>	MAPPER OUTPUT
D[0]	CbCr[1]	B(2)
D[1]	CbCr[2]	B(3)
D[2]	CbCr[3]	B(4)
D[3]	CbCr[4]	B(5)
D[4]	CbCr[5]	B(6)
D[5]	CbCr[6]	B(7)
D[6]	CbCr[7]	B(8)
D[7]	CbCr[8]	B(9)
D[8]	Y[1]	A(2)
D[9]	Y[2]	A(3)
D[10]	Y[3]	A(4)
D[11]	Y[4]	A(5)
D[12]	Y[5]	A(6)
D[13]	Y[6]	A(7)
D[14]	Y[7]	A(8)
D[15]	Y[8]	A(9)
'0'	—	C(2)
'0'	—	C(3)
'0'	—	C(4)
'0'	—	C(5)
'0'	—	C(6)
'0'	—	C(7)
'0'	—	C(8)
'0'	—	C(9)
D[24]	-	-
D[25]	-	-
'0'	—	C[0]
'0'	—	C[1]
'0'	—	A[0]
D[29]	Y[0]	A[1]
'0'	—	B[0]
D[31]	CbCr[0]	B[1]

- (1) For all YCbCr 4:2:2 formats, data channel C is forced to "0".  
 (2) For 18-bit inputs, the 9 bits for each color shift up one bit, and the least significant bits of each color is set to '0'.

表 7-10. V-by-One Data Mapping for 16bpp YCbCr 4:2:2<sup>(1)</sup>

V-by-One DATA MAP MODE 5		
V-by-One INPUT DATA BIT	16bpp YCbCr 4:2:2 <sup>(2)</sup>	MAPPER OUTPUT
D[0]	CbCr[0]	B(2)
D[1]	CbCr[1]	B(3)
D[2]	CbCr[2]	B(4)
D[3]	CbCr[3]	B(5)
D[4]	CbCr[4]	B(6)
D[5]	CbCr[5]	B(7)
D[6]	CbCr[6]	B(8)
D[7]	CbCr[7]	B(9)
D[8]	Y[0]	A(2)
D[9]	Y[1]	A(3)
D[10]	Y[2]	A(4)
D[11]	Y[3]	A(5)
D[12]	Y[4]	A(6)
D[13]	Y[5]	A(7)
D[14]	Y[6]	A(8)
D[15]	Y[7]	A(9)
'0'	—	C(2)
'0'	—	C(3)
'0'	—	C(4)
'0'	—	C(5)
'0'	—	C(6)
'0'	—	C(7)
'0'	—	C(8)
'0'	—	C(9)
D[24]	-	-
D[25]	-	-
'0'	—	C[0]
'0'	—	C[1]
'0'	—	A[0]
'0'	—	A[1]
'0'	—	B[0]
'0'	—	B[1]

(1) For all YCbCr 4:2:2 formats, data channel C is forced to "0".

(2) For 16-bit inputs, the 8 bits for each color shift up one bit, and the least significant bit of each color is set to '0'.

**表 7-11. V-by-One Data Mapping Example for 12bpp/10bpp YCbCr 4:2:0<sup>(1)</sup>**

V-by-One DATA MAP MODE 6					
V-by-One INPUT DATA BIT	12bpp YCbCr 4:2:0 EVEN LINE <sup>(2)</sup>	12bpp YCbCr 4:2:0 Odd Line <sup>(2)</sup>	10bpp YCbCr 4:2:0 EVEN LINE	10bpp YCbCr 4:2:0 ODD LINE	MAPPER OUTPUT
D[0]	Y01[4]	Y01[4]	Y01[2]	Y11[2]	C(2)
D[1]	Y01[5]	Y01[5]	Y01[3]	Y11[3]	C(3)
D[2]	Y01[6]	Y01[6]	Y01[4]	Y11[4]	C(4)
D[3]	Y01[7]	Y01[7]	Y01[5]	Y11[5]	C(5)
D[4]	Y01[8]	Y01[8]	Y01[6]	Y11[6]	C(6)
D[5]	Y01[9]	Y01[9]	Y01[7]	Y11[7]	C(7)
D[6]	Y01[10]	Y01[10]	Y01[8]	Y11[8]	C(8)
D[7]	Y01[11]	Y01[11]	Y01[9]	Y11[9]	C(9)
D[8]	Y00[4]	Y00[4]	Y00[2]	Y10[2]	A(2)
D[9]	Y00[5]	Y00[5]	Y00[3]	Y10[3]	A(3)
D[10]	Y00[6]	Y00[6]	Y00[4]	Y10[4]	A(4)
D[11]	Y00[7]	Y00[7]	Y00[5]	Y10[5]	A(5)
D[12]	Y00[8]	Y00[8]	Y00[6]	Y10[6]	A(6)
D[13]	Y00[9]	Y00[9]	Y00[7]	Y10[7]	A(7)
D[14]	Y00[10]	Y00[10]	Y00[8]	Y10[8]	A(8)
D[15]	Y00[11]	Y00[11]	Y00[9]	Y10[9]	A(9)
D[16]	Cb00[4]	Cr00[4]	Cb00[2]	Cr00[2]	B(2)
D[17]	Cb00[5]	Cr00[5]	Cb00[3]	Cr00[3]	B(3)
D[18]	Cb00[6]	Cr00[6]	Cb00[4]	Cr00[4]	B(4)
D[19]	Cb00[7]	Cr00[7]	Cb00[5]	Cr00[5]	B(5)
D[20]	Cb00[8]	Cr00[8]	Cb00[6]	Cr00[6]	B(6)
D[21]	Cb00[9]	Cr00[9]	Cb00[7]	Cr00[7]	B(7)
D[22]	Cb00[10]	Cr00[10]	Cb00[8]	Cr00[8]	B(8)
D[23]	Cb00[11]	Cr00[11]	Cb00[9]	Cr00[9]	B(9)
D[24]	-	-	-	-	-
D[25]	-	-	-	-	-
D[26]	Cb00[2]	Cr00[2]	Cb00[0]	Cr00[0]	B[0]
D[27]	Cb00[3]	Cr00[3]	Cb00[1]	Cr00[1]	B[1]
D[28]	Y00[2]	Y10[2]	Y00[0]	Y10[0]	A[0]
D[29]	Y00[3]	Y10[3]	Y00[1]	Y10[1]	A[1]
D[30]	Y01[2]	Y11[2]	Y01[0]	Y11[0]	C[0]
D[31]	Y01[3]	Y11[3]	Y01[1]	Y11[1]	C[1]

- (1) For all YCbCr 4:2:0 inputs, two consecutive pixel luma values are brought in on each clock. Even lines carry the Cb values, and odd lines carry the Cr values.
- (2) For 12bpp YCbCr 4:2:0 inputs, the 12 bits per color truncate to 10 bits per color with the two least significant bits per color discarded.

表 7-12. V-by-One Data Mapping Example for 8bpp YCbCr 4:2:0<sup>(1)</sup>

V-by-One DATA MAP MODE 7			
V-by-One INPUT DATA BIT	8bpp YCbCr 4:2:0 EVEN LINE <sup>(2)</sup>	8bpp YCbCr 4:2:0 ODD LINE <sup>(2)</sup>	MAPPER OUTPUT
D[0]	Y01[0]	Y11[0]	C(2)
D[1]	Y01[1]	Y11[1]	C(3)
D[2]	Y01[2]	Y11[2]	C(4)
D[3]	Y01[3]	Y11[3]	C(5)
D[4]	Y01[4]	Y11[4]	C(6)
D[5]	Y01[5]	Y11[5]	C(7)
D[6]	Y01[6]	Y11[6]	C(8)
D[7]	Y01[7]	Y11[7]	C(9)
D[8]	Y00[0]	Y10[0]	A(2)
D[9]	Y00[1]	Y10[1]	A(3)
D[10]	Y00[2]	Y10[2]	A(4)
D[11]	Y00[3]	Y10[3]	A(5)
D[12]	Y00[4]	Y10[4]	A(6)
D[13]	Y00[5]	Y10[5]	A(7)
D[14]	Y00[6]	Y10[6]	A(8)
D[15]	Y00[7]	Y10[7]	A(9)
D[16]	Cb00[0]	Cr00[0]	B(2)
D[17]	Cb00[1]	Cr00[1]	B(3)
D[18]	Cb00[2]	Cr00[2]	B(4)
D[19]	Cb00[3]	Cr00[3]	B(5)
D[20]	Cb00[4]	Cr00[4]	B(6)
D[21]	Cb00[5]	Cr00[5]	B(7)
D[22]	Cb00[6]	Cr00[6]	B(8)
D[23]	Cb00[7]	Cr00[7]	B(9)
D[24]	-	-	-
D[25]	-	-	-
'0'	—	—	B[0]
'0'	—	—	B[1]
'0'	—	—	A[0]
'0'	—	—	A[1]
'0'	—	—	C[0]
'0'	—	—	C[1]

- (1) For all YCbCr 4:2:0 inputs, two consecutive pixel luma values are brought in on each clock. Even lines carry the Cb values, and odd lines carry the Cr values.
- (2) For 8bpp YCbCr 4:2:0 inputs, the 8 bits for each color shift up two bits, and the two least significant bits of each color are set to '0'.

**表 7-13. V-by-One Data Mapping Example for 10bpp YCbCr 4:2:0 <sup>(1)</sup>**

V-by-One DATA MAP MODE 8			
V-by-One INPUT DATA BIT	10bpp YCbCr 4:2:0 EVEN LINE	10bpp YCbCr 4:2:0 ODD LINE	MAPPER OUTPUT
D[0]	Y00[2]	Y10[2]	A(2)
D[1]	Y00[3]	Y10[3]	A(3)
D[2]	Y00[4]	Y10[4]	A(4)
D[3]	Y00[5]	Y10[5]	A(5)
D[4]	Y00[6]	Y10[6]	A(6)
D[5]	Y00[7]	Y10[7]	A(7)
D[6]	Y00[8]	Y10[8]	A(8)
D[7]	Y00[9]	Y10[9]	A(9)
D[8]	Cb00[2]	Cr00[2]	B(2)
D[9]	Cb00[3]	Cr00[3]	B(3)
D[10]	Cb00[4]	Cr00[4]	B(4)
D[11]	Cb00[5]	Cr00[5]	B(5)
D[12]	Cb00[6]	Cr00[6]	B(6)
D[13]	Cb00[7]	Cr00[7]	B(7)
D[14]	Cb00[8]	Cr00[8]	B(8)
D[15]	Cb00[9]	Cr00[9]	B(9)
D[16]	Y01[2]	Y11[2]	C(2)
D[17]	Y01[3]	Y11[3]	C(3)
D[18]	Y01[4]	Y11[4]	C(4)
D[19]	Y01[5]	Y11[5]	C(5)
D[20]	Y01[6]	Y11[6]	C(6)
D[21]	Y01[7]	Y11[7]	C(7)
D[22]	Y01[8]	Y11[8]	C(8)
D[23]	Y01[9]	Y11[9]	C(9)
D[24]	-	-	-
D[25]	-	-	-
D[26]	Y01[0]	Y11[0]	C[0]
D[27]	Y01[1]	Y11[1]	C[1]
D[28]	Cb00[0]	Cr00[0]	B[0]
D[29]	Cb00[1]	Cr00[1]	B[1]
D[30]	Y00[0]	Y10[0]	A[0]
D[31]	Y00[1]	Y10[1]	A[1]

(1) For all YCbCr 4:2:0 inputs, two consecutive pixel luma values are brought in on each clock. Even lines carry Cb values, and odd lines carry the Cr values.

表 7-14. V-by-One Data Mapping Example for 8bpp YCbCr 4:2:0 <sup>(1)</sup>

V-by-One DATA MAP MODE 9			
V-by-One INPUT DATA BIT	8bpp YCbCr 4:2:0 EVEN LINE <sup>(2)</sup>	8bpp YCbCr 4:2:0 ODD LINE <sup>(2)</sup>	MAPPER OUTPUT
D[0]	Y00[0]	Y10[0]	A(2)
D[1]	Y00[1]	Y10[1]	A(3)
D[2]	Y00[2]	Y10[2]	A(4)
D[3]	Y00[3]	Y10[3]	A(5)
D[4]	Y00[4]	Y10[4]	A(6)
D[5]	Y00[5]	Y10[5]	A(7)
D[6]	Y00[6]	Y10[6]	A(8)
D[7]	Y00[7]	Y10[7]	A(9)
D[8]	Cb00[0]	Cr00[0]	B(2)
D[9]	Cb00[1]	Cr00[1]	B(3)
D[10]	Cb00[2]	Cr00[2]	B(4)
D[11]	Cb00[3]	Cr00[3]	B(5)
D[12]	Cb00[4]	Cr00[4]	B(6)
D[13]	Cb00[5]	Cr00[5]	B(7)
D[14]	Cb00[6]	Cr00[6]	B(8)
D[15]	Cb00[7]	Cr00[7]	B(9)
D[16]	Y01[0]	Y11[0]	C(2)
D[17]	Y01[1]	Y11[1]	C(3)
D[18]	Y01[2]	Y11[2]	C(4)
D[19]	Y01[3]	Y11[3]	C(5)
D[20]	Y01[4]	Y11[4]	C(6)
D[21]	Y01[5]	Y11[5]	C(7)
D[22]	Y01[6]	Y11[6]	C(8)
D[23]	Y01[7]	Y11[7]	C(9)
D[24]	-	-	-
D[25]	-	-	-
'0'	—	—	C[0]
'0'	—	—	C[1]
'0'	—	—	B[0]
'0'	—	—	B[1]
'0'	—	—	A[0]
'0'	—	—	A[1]

- (1) For all YCbCr 4:2:0 inputs, two consecutive pixel luma values are brought in on each clock. Even lines carry the Cb values, and odd lines carry the Cr values.
- (2) For 8bpp YCbCr 4:2:0 inputs, the 8 bits for each color shift up two bits, and the two least significant bits of each color are set to '0'.



### 7.3.4 DMD (HSSI) Interface

The DLPC6540 Controller DMD interface supports two High Speed Serial Interface (HSSI) output-only interfaces for data transmission, a single low speed LVDS output-only interface for command write transactions, as well as a low speed single-ended input interface used for command read transactions. Each HSSI port supports full data-only inter-lane remapping within the port, but not between ports. When utilizing this feature, each unique data lane pair can only be mapped to one unique destination data lane pair, and Intra-lane remapping (i.e. swapping P with N) is not supported. In addition, the two HSSI ports can also be swapped. Lane and port remapping (specified in flash) can help with board layout as needed. The number of HSSI ports and number of HSSI lanes/per HSSI port required are based on DMD type and DMD display resolution. 表 7-15 shows some remapping examples. When both ports are used, they do not need to have the same pin mapping.

**表 7-15. Controller to DMD Pin Mapping Examples**

DLPC6540 Controller PINS - REMAPPING EXAMPLES TO DMD PINS				
BASELINE	FLIP HSSI0 180 No FLIP HSSI1	SWAP HSSI0 PORT WITH HSSI1 PORT	SWAP HSSI0 PORT WITH HSSI1 PORT AND MIXED REMAPPING	DMD PINS
DMD_HSSI0_D0_P DMD_HSSI0_D0_N	DMD_HSSI0_D7_P DMD_HSSI0_D7_N	DMD_HSSI1_D0_P DMD_HSSI1_D0_N	DMD_HSSI1_D2_P DMD_HSSI1_D2_N	DMD_HSSI0_D0_P DMD_HSSI0_D0_N
DMD_HSSI0_D1_P DMD_HSSI0_D1_N	DMD_HSSI0_D6_P DMD_HSSI0_D6_N	DMD_HSSI1_D1_P DMD_HSSI1_D1_N	DMD_HSSI1_D3_P DMD_HSSI1_D3_N	DMD_HSSI0_D1_P DMD_HSSI0_D1_N
DMD_HSSI0_D2_P DMD_HSSI0_D2_N	DMD_HSSI0_D5_P DMD_HSSI0_D5_N	DMD_HSSI1_D2_P DMD_HSSI1_D2_N	DMD_HSSI1_D0_P DMD_HSSI1_D0_N	DMD_HSSI0_D2_P DMD_HSSI0_D2_N
DMD_HSSI0_D3_P DMD_HSSI0_D3_N	DMD_HSSI0_D4_P DMD_HSSI0_D4_N	DMD_HSSI1_D3_P DMD_HSSI1_D3_N	DMD_HSSI1_D1_P DMD_HSSI1_D1_N	DMD_HSSI0_D3_P DMD_HSSI0_D3_N
DMD_HSSI0_D4_P DMD_HSSI0_D4_N	DMD_HSSI0_D3_P DMD_HSSI0_D3_N	DMD_HSSI1_D4_P DMD_HSSI1_D4_N	DMD_HSSI1_D6_P DMD_HSSI1_D6_N	DMD_HSSI0_D4_P DMD_HSSI0_D4_N
DMD_HSSI0_D5_P DMD_HSSI0_D5_N	DMD_HSSI0_D2_P DMD_HSSI0_D2_N	DMD_HSSI1_D5_P DMD_HSSI1_D5_N	DMD_HSSI1_D7_P DMD_HSSI1_D7_N	DMD_HSSI0_D5_P DMD_HSSI0_D5_N
DMD_HSSI0_D6_P DMD_HSSI0_D6_N	DMD_HSSI0_D1_P DMD_HSSI0_D1_N	DMD_HSSI1_D6_P DMD_HSSI1_D6_N	DMD_HSSI1_D4_P DMD_HSSI1_D4_N	DMD_HSSI0_D6_P DMD_HSSI0_D6_N
DMD_HSSI0_D7_P DMD_HSSI0_D7_N	DMD_HSSI0_D0_P DMD_HSSI0_D0_N	DMD_HSSI1_D7_P DMD_HSSI1_D7_N	DMD_HSSI1_D5_P DMD_HSSI1_D5_N	DMD_HSSI0_D7_P DMD_HSSI0_D7_N
DMD_HSSI1_D0_P DMD_HSSI1_D0_N	DMD_HSSI1_D0_P DMD_HSSI1_D0_N	DMD_HSSI0_D0_P DMD_HSSI0_D0_N	DMD_HSSI0_D6_P DMD_HSSI0_D6_N	DMD_HSSI1_D0_P DMD_HSSI1_D0_N
DMD_HSSI1_D1_P DMD_HSSI1_D1_N	DMD_HSSI1_D1_P DMD_HSSI1_D1_N	DMD_HSSI0_D1_P DMD_HSSI0_D1_N	DMD_HSSI0_D7_P DMD_HSSI0_D7_N	DMD_HSSI1_D1_P DMD_HSSI1_D1_N
DMD_HSSI1_D2_P DMD_HSSI1_D2_N	DMD_HSSI1_D2_P DMD_HSSI1_D2_N	DMD_HSSI0_D2_P DMD_HSSI0_D2_N	DMD_HSSI0_D4_P DMD_HSSI0_D4_N	DMD_HSSI1_D2_P DMD_HSSI1_D2_N
DMD_HSSI1_D3_P DMD_HSSI1_D3_N	DMD_HSSI1_D3_P DMD_HSSI1_D3_N	DMD_HSSI0_D3_P DMD_HSSI0_D3_N	DMD_HSSI0_D5_P DMD_HSSI0_D5_N	DMD_HSSI1_D3_P DMD_HSSI1_D3_N
DMD_HSSI1_D4_P DMD_HSSI1_D4_N	DMD_HSSI1_D4_P DMD_HSSI1_D4_N	DMD_HSSI0_D4_P DMD_HSSI0_D4_N	DMD_HSSI0_D2_P DMD_HSSI0_D2_N	DMD_HSSI1_D4_P DMD_HSSI1_D4_N
DMD_HSSI1_D5_P DMD_HSSI1_D5_N	DMD_HSSI1_D5_P DMD_HSSI1_D5_N	DMD_HSSI0_D5_P DMD_HSSI0_D5_N	DMD_HSSI0_D3_P DMD_HSSI0_D3_N	DMD_HSSI1_D5_P DMD_HSSI1_D5_N
DMD_HSSI1_D6_P DMD_HSSI1_D6_N	DMD_HSSI1_D6_P DMD_HSSI1_D6_N	DMD_HSSI0_D6_P DMD_HSSI0_D6_N	DMD_HSSI0_D0_P DMD_HSSI0_D0_N	DMD_HSSI1_D6_P DMD_HSSI1_D6_N
DMD_HSSI1_D7_P DMD_HSSI1_D7_N	DMD_HSSI1_D7_P DMD_HSSI1_D7_N	DMD_HSSI0_D7_P DMD_HSSI0_D7_N	DMD_HSSI0_D1_P DMD_HSSI0_D1_N	DMD_HSSI1_D7_P DMD_HSSI1_D7_N

### 7.3.5 Program Memory Flash Interface

The DLPC6540 provides three external program memory chip selects for devices to access the program memory interface. These are detailed in [表 7-16](#).

**表 7-16. Program Memory Interface Chip Selects**

CHIP SELECT NAME	CHIP SELECT USE	DATA BUS WIDTH	ACCESS TIME	MAXIMUM SIZE SUPPORTED <sup>(1)</sup>
PM_CSZ_0	Boot FLASH only - Required <sup>(2)</sup>	16 bits	< = 120ns	256Mb
PM_CSZ_1	Additional Peripheral Device (or additional FLASH) - Optional	16 bits	< = 120ns	256Mb
PM_CSZ_2	Additional Peripheral Device - Optional	16 bits	< = 120ns	256Mb

(1) Using GPIO\_47 as additional address bit

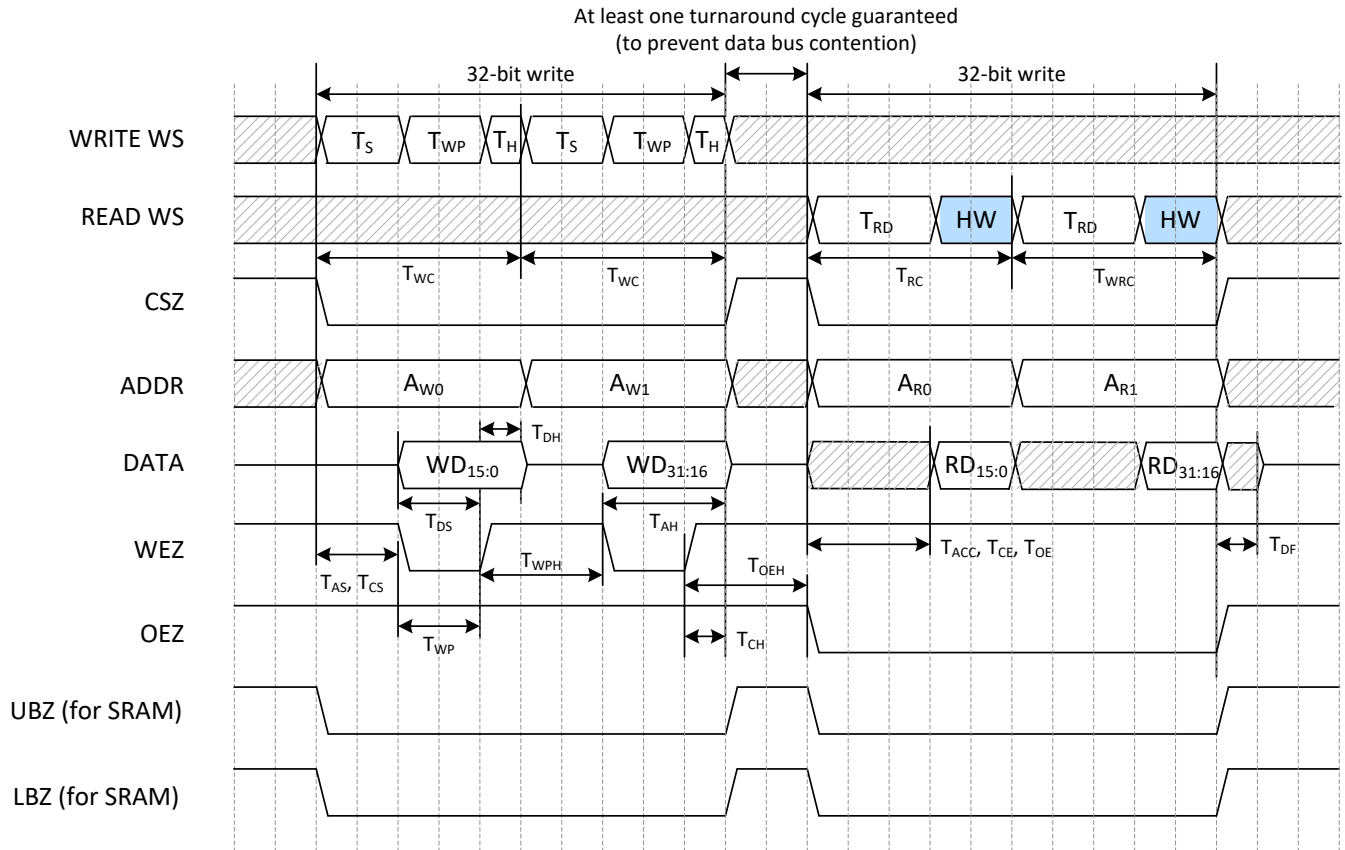
(2) Boot FLASH type supported is *Standard NOR parallel FLASH*, single or multi-bank.

FLASH access timing is software programmable with up to 31 wait states. Additional information about read and write wait state timing is provided in [表 7-17](#) and [图 7-1](#).

**表 7-17. Program Memory Wait State Timing**

PARAMETER	EQUATION <sup>(1)</sup>
$T_{WSR}$ : Wait State Resolution	6ns
Read Wait States (Number of Read Wait States for each CSz read access)	$\text{ROUNDUP}(\text{MAX}(T_{ACC}, T_{CE}, T_{OE})/T_{WSR-N})$ <sup>(2) (3)</sup>
Write Wait States for $T_{CS}$ and $T_{AS}$ (Time from CS/Address activation to WRZ assertion)	$\text{ROUNDUP}(\text{MAX}(T_{CS}+5\text{ns}, T_{AS}+5\text{ns})/T_{WSR-N})$ <sup>(2)</sup>
Write Wait States for $T_{WP}$ and $T_{DS}$ (Time from WRZ assertion to WEZ de-assertion)	$\text{ROUNDUP}(\text{MAX}(T_{WP}+5\text{ns}, T_{DS}+5\text{ns})/T_{WSR-N})$ <sup>(2)</sup>
Write Wait States for $T_{CH}$ and $T_{DH}$ (Time from CS/Address activation to WRZ assertion)	$\text{ROUNDUP}(\text{MAX}(T_{CH}+5\text{ns}, T_{DH}+5\text{ns})/T_{WSR-N})$ <sup>(2)</sup>

- (1) a.  $T_{ACC}$ : Read Access Time (ADDR to DATA valid) – (address valid to DATA valid)  
 b.  $T_{CE}$ : Read Access Time (CSZ to DATA valid) – (chip select active to DATA valid)  
 c.  $T_{OE}$ : Read Access Time (OEZ to DATA valid) – (output enable active to DATA valid)  
 d.  $T_{CS}$ : CSZ Setup Time (Writes) – (chip select active before negedge(WEZ))  
 e.  $T_{CS}$ : Address Setup Time (Writes) – (address valid before negedge(WEZ))  
 f.  $T_{AS}$ : Address Setup Time (Writes) – (address valid before negedge(WEZ))  
 g.  $T_{WP}$ : Write Pulse Width (Writes) – (WEZ active low time)  
 h.  $T_{DS}$ : Data Setup Time (Writes) – (DATA valid before posedge(WEZ))  
 i.  $T_{CH}$ : CSZ Hold Time (Writes) – (CSZ held active after posedge(WEZ))  
 j.  $T_{DH}$ : Data Hold Time (Writes) – (DATA held valid after posedge(WEZ))
- (2) Requires a minimum of at least 1 wait state
- (3) Assumes a maximum single direction trace length of 90 mm (3.5 inches)



7-1. Program Memory Interface Timing Diagram

### 7.3.6 GPIO Supported Functionality

The DLPC6540 provides 88 general purpose I/O that are available to support a variety of functions for many different product configurations. In general, most of these I/O pins support only one specific function based on a specific product configuration, although that function can be different for a different product configuration. Most of these I/O can also be made available for TI test and debug use. Each of the following GPIO tables provide product specific details on the allocated use of each of the GPIO for a specific supported product configuration.

表 7-18. GPIO Supported Functionality - LED with DLPA3005 <sup>(1)</sup>

GPIO	SIGNAL NAME	DESCRIPTION
GPIO_00	SSP1_SCLK (I)	SSP Master or Slave
GPIO_01	SSP1_DI (I)	SSP Master or Slave
GPIO_02	SSP1_DO (O)	SSP Master or Slave
GPIO_03	SSP1_CSZ0 (I)	SSP Master or Slave
GPIO_04	SSP1_CSZ1 (I)	SSP Master or Slave
GPIO_05	SSP1_CSZ2 (I)	SSP Master or Slave
GPIO_06	SAS_CLK (O)	
GPIO_07	SAS_DI (I)	
GPIO_08	SAS_DO (O)	
GPIO_09	SAS_CSZ (O)	
GPIO_10	SAS_INTGTR_EN (O)	
GPIO_11	IIC1_SCL (B)	
GPIO_12	IIC1_SDA (B)	
GPIO_13	UART1_TXD (O)	
GPIO_14	UART1_RXD (I)	
GPIO_15	UART1_CTSZ (I)	
GPIO_16	UART1_RTSZ (O)	
GPIO_17	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_18	IR0 (I)	
GPIO_19	IR1 (I)	
GPIO_20	PWM-IN0 (I)	
GPIO_21	PWM-IN1 (I)	
GPIO_22	3D LR (I)	For 3D applications: Left or right 3D reference (left = 1, right = 0). To be provided by the host when a 3D command is not provided. Must transition in the middle of each frame (no closer than 1 ms to the active edge of VSYNC)
GPIO_23	LL_FAULT (O)	
GPIO_24	LEDSEL_0 (O)	
GPIO_25	LEDSEL_1 (O)	
GPIO_26	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_27	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_28	Heartbeat (O)	
GPIO_29	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_30	VBIAS_MON (I)	
GPIO_31	HDMI_CEC (B)	
GPIO_32	IIC2_SCL (B)	
GPIO_33	IIC2_SDA (B)	
GPIO_34	WRP_TRIG_OUT (O)	
GPIO_35	DAO_DO_0 (O)	

**表 7-18. GPIO Supported Functionality - LED with DLPA3005 <sup>(1)</sup> (continued)**

GPIO	SIGNAL NAME	DESCRIPTION
GPIO_36	DAO_DO_1 (O)	
GPIO_37	DAO_CLKOUT (O)	
GPIO_38	HBT_DO (O)	
GPIO_39	HBT_CLKOUT (O)	
GPIO_40	SSP2_SCLK (I)	SSP Master
GPIO_41	SSP2_DI (I)	SSP Master
GPIO_42	SSP2_DO (O)	SSP Master
GPIO_43	SSP2_CSZ0 (I)	SSP Master
GPIO_44	SSP2_CSZ1 (I)	SSP Master
GPIO_45	SSP2_CSZ2 (I)	SSP Master
GPIO_46	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_47	PM_ADDR_23 (O)	
GPIO_48	USB OTG Charge Pump Enable (O)	
GPIO_49	SSP0_CSZ4 (O)	DLPA3005
GPIO_50	SSP0_CSZ3 (O)	
GPIO_51	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_52	LED_Enable (O)	
GPIO_53	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_54	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_55	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_56	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_57	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_58	I2C_BUSY (O)	
GPIO_59	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_60	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_61	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_62	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_63	PROJ_ON (I)	
GPIO_64	HOLD_BOOTZ (I)	
GPIO_65	4 way XPR (O)	
GPIO_66	4 way XPR (O)	
GPIO_67	4 way XPR (O)	
GPIO_68	4 way XPR (O)	
GPIO_69	4 way XPR (O)	
GPIO_70	4 way XPR (O)	
GPIO_71	4 way XPR (O)	
GPIO_72	4 way XPR (O)	
GPIO_73	4 way XPR (O)	

**表 7-18. GPIO Supported Functionality - LED with DLPA3005 <sup>(1)</sup> (continued)**

GPIO	SIGNAL NAME	DESCRIPTION
GPIO_74	4 way XPR (O)	
GPIO_75	4 way XPR (O)	
GPIO_76	4 way XPR (O)	
GPIO_77	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_78	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_79	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_80	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_81	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_82	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_83	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_84	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_85	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_86	General Purpose Input/Output	Available for general host use via Host Commands
GPIO_87	General Purpose Input/Output	Available for general host use via Host Commands

- (1) All GPIO that are listed as General Purpose Input/Output must be configured as an input, a standard output, or an open-drain output. This is set in the flash configuration. It is suggested that all unused General Purpose Input/Output GPIO should be configured as a logic zero output and be left unconnected, otherwise an external pull-up or pull-down will be required to avoid a floating input. It should be noted that the reset default for all GPIO is as an input signal. It should also be noted that an external pull-up ( $\leq 10k\Omega$ ) is required for each signal configured as open-drain output.

### 7.3.7 Debug Support

The DLPC6540 contains a test point output port, TSTPT\_(7:0), which provides the Host with the ability to provide for Controller debug support. For initial debug operation, the four signals (TSTPT(3:0)) are sampled as inputs approximately 1.5  $\mu$ s after PWRGOOD goes high (or after a system reset). Once their input state has been sampled and captured, this information is used to setup the initial test mode output state of the TSTPT\_(7:0) bus. 表 7-19 defines the test mode selection for a few programmable output states for TSTPT\_(7:0). Use the default state of 0000 (defined by the required external pulldown resistors) for normal operation (that is, no debug required).

To allow TI to make use of this debug capability, providing for the option of a jumper to an external pullup is recommended for TSTPT(3:0), as well as providing access to allow observation of the TSTPT bus outputs.

**表 7-19. Examples of Test Mode Selection Outputs Defined by TSTPT(3:0) <sup>(1)</sup>**

TSTPT_(7:0) OUTPUT	TSTPT(3:0) CAPTURED VALUES		
	0000 (DEFAULT) (NO SWITCHING ACTIVITY)	0101 CLOCK DEBUG	1000 SYSTEM CALIBRATION
TSTPT(0)	0	HIGH	Vertical Sync
TSTPT(1)	0	166.25 MHz	Delayed CW Index
TSTPT(2)	0	83.13 MHz	Sequence Index
TSTPT(3)	0	41.56 MHz	CW Spoke Test Point
TSTPT(4)	0	10.39 MHz	CW Revolution Test Point
TSTPT(5)	0	25.16 MHz	Reset Sequence Aux Bit 0
TSTPT(6)	0	133.00 MHz	Reset Sequence Aux Bit 1
TSTPT(7)	0	HIGH	Reset Sequence Aux Bit 2

- (1) These are only the default output selections. Software can reprogram the selection at any time.

## **7.4 Device Operational Modes**

The DLPC6540 has two operational modes which are enabled via software command via the Host control interface. These modes are Standby and Active.

### **7.4.1 Standby Mode**

The system is powered up and active, however, most blocks within the Controller have been shut down to conserve power. Only the  $\mu$ Processor and its peripherals are active (supporting a dormant projector waiting to be woken up). In this mode the DMD is parked and no image can be displayed.

### **7.4.2 Active Mode**

The system is powered up and fully operational, capable of projecting internal or external source images.

#### **7.4.2.1 Normal Configuration**

This configuration enables the full functionality of the DLPC6540.

## 8 Power Supply Recommendations

### 8.1 Power Supply Management

The DLPA3005 manages power for the DLPC6540 and DMD. See [セクション 6.12](#) for all power sequencing and timing requirements.

### 8.2 Hot Plug Usage

While the V-by-One, FPD-Link, and USB interfaces support hot plug usage (i.e. these interfaces can be connected and disconnected while the DLPC6540 is powered), the controller itself (and any DMD connected to the system) do not support Hot Plug use. As such, power down the system prior to removing the controller or DMD from any system.

### 8.3 Power Supplies for Unused Input Source Interfaces

While certain product configurations cannot offer or make use of all of the available input source interfaces (e.g. V-by-One, FPD-Link), *the power supplies that are associated with these unused input source interfaces must still be provided as if the interface was actually being used.* The only concession is that the ferrite based isolation filters for these supplies can be simplified down to simple de-coupling caps.

### 8.4 Power Supplies

#### 8.4.1 1.15-V Power Supplies

The DLPC6540 can support a low cost power delivery system with a single 1.15-V power source derived from a switching regulator. To enable this approach, provide typical bulk (e.g. 10  $\mu$ F, 22  $\mu$ F) and high frequency (e.g. 0.1  $\mu$ F) filtering for the core 1.15-V power rail (VDD115). Ensure that the the high-frequency capacitors are evenly distributed amongst the power balls and that they are placed as close to the power balls as possible. Additional filtering must be provided for each of the uniquely defined 1.15-V power pins (e.g. VDD115\_PLLMA, VAD115VX1). Filtering for the unique power pins is discussed further in [セクション 9.1](#) of this document.

#### 8.4.2 1.21V Power Supply

The DLPC6540 can support a low cost power delivery system with a single 1.21V power source derived from a switching regulator. To enable this approach, provide typical bulk (e.g. 10  $\mu$ F, 22  $\mu$ F) and high frequency (e.g. 0.1  $\mu$ F) filtering for the 1.21-V power rail (VDD121\_SCS). Place the high-frequency filtering capacitors as close as possible to the VDD121\_SCS power balls.

#### 8.4.3 1.8-V Power Supplies

The DLPC6540 can support a low cost power delivery system with a single 1.8-V power source derived from a switching regulator. To enable this approach, appropriate filtering must be provided for each of the uniquely defined 1.8-V power pins (e.g. VDD18\_PLLMA, VAD18\_VX1). See [セクション 9.1](#) for more information.

#### 8.4.4 3.3-V Power Supplies

The DLPC6540 can support a low cost power delivery system with a single 3.3-V power source derived from a switching regulator. To enable this approach, provide typical bulk (e.g. 10  $\mu$ F, 22  $\mu$ F) and high frequency (e.g. 0.1  $\mu$ F) filtering for the main 3.3-V I/O power rail (VDD33). Ensure that the the high-frequency capacitors are evenly distributed amongst the power balls and that they are placed as close to the power balls as possible. Additional filtering must be provided for each of the uniquely defined 3.3-V power pins (e.g. VAD33\_USB, VDD33\_FPD). This is discussed further in [セクション 9.1](#) of the document.



## 9 Layout

### 9.1 Layout Guidelines

#### 9.1.1 General Layout Guidelines

In order to meet the thermal loads associated with the DLPC6540, TI recommends the following enhanced PCB design parameters.

- A minimum of 4 power and ground planes
  - Power layers: 1-oz. copper; Ground layers: 2-oz. copper
    - Copper coverage: 90%
  - Top and bottom signal layers: minimum 0.5-oz copper
  - Internal signal layers: 1-oz copper
- Thermal copper ground planes beneath the thermal ball array of package containing a via farm with the following attributes
  - Thermal via quantity to ground plane = 64 (as 8x8 array)
  - Thermal via size = 0.229mm - 0.25 mm (9mils - 10 mils)
  - Thermal via plating thickness = 0.025 mm (1 mil) wall thickness

For signal integrity reasons, FR370HR or equivalent high performance epoxy laminate and prepreg is also recommended.

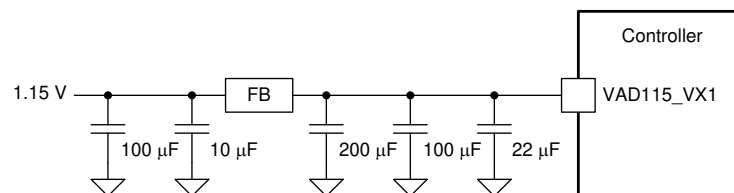
#### 9.1.2 Power Supply Layout Guidelines

The following filtering circuits are recommended for the power supply inputs listed below.

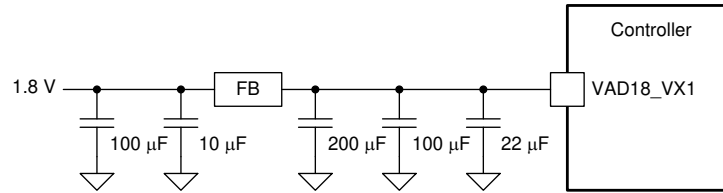
- VAD115\_VX1
- VAD18\_VX1
- VAD115\_FPD
- VDD33\_FPD
- VAD33\_USB
- VDD18\_SCS

Because the PBC layout is critical to the performance of the interfaces associated with these power supplies, it is vital that these power supplies be treated like an analog signal. Specifically:

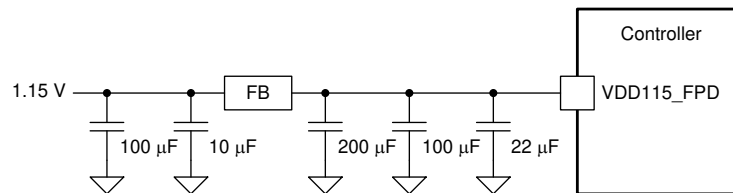
- Place high-frequency components (such as ferrites and capacitors) as close to the power ball(s) as possible.
- Choose high-frequency ceramic capacitors (such as those with a value of 0.1  $\mu\text{F}$ , 0.01  $\mu\text{F}$ , and 100 nF) that have low ESR and ESL values. Design the leads as short as possible, and as such, place these capacitors under the package on the opposite side of the board.
- For each power pin, a single trace (as wide as possible) must be used from the controller to the capacitor and then through the series ferrite to the power source.
- For each power pin, add a 100-nF decoupling capacitor placed near the escape via. Add this decoupling capacitance to the capacitance recommended for filters. These are minimum recommendations, so different layouts could require additional capacitance.
- See [表 9-1](#) for the recommended series ferrite component for these supplies.



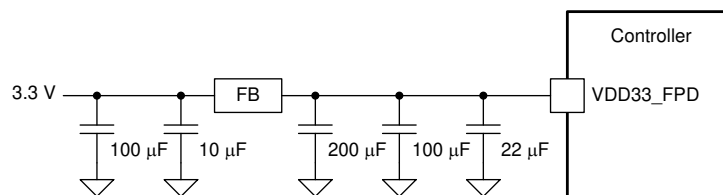
**图 9-1. VAD115\_VX1 (V-by-One) Recommended Filter**



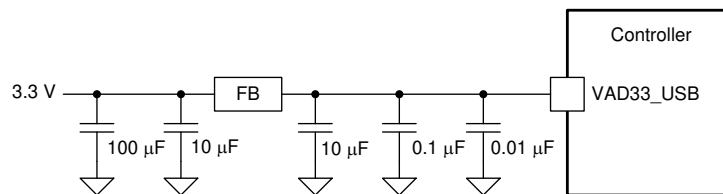
☒ 9-2. VAD18\_VX1 (V-by-One) Recommended Filter



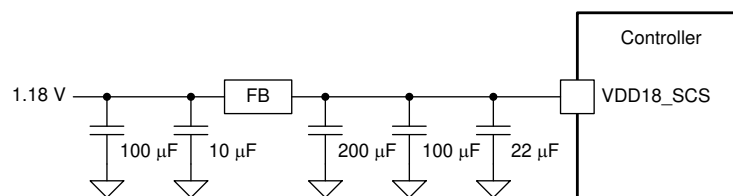
☒ 9-3. VAD115\_FPD (FPD-Link) Recommended Filter



☒ 9-4. VDD33\_FPD (FPD-Link) Recommended Filter



☒ 9-5. VAD33\_USB (USB) Recommended Filter



☒ 9-6. VDD18\_SCS (SCS DRAM) Recommended Filter

### 9.1.3 Layout Guidelines for Internal Controller PLL Power

The following guidelines are recommended to achieve the desired Controller performance relative to the internal PLLs. The DLPC6540 contains multiple internal PLLs which have dedicated 1.15-V supply pins and 1.8-V supply pins which are listed below:

- VDD115\_PLLMA
- VDD115\_PLLMB
- VAD115\_PLLS

- VAD115\_HSSI0\_PLL
- VAD115\_HSSI1\_PLL

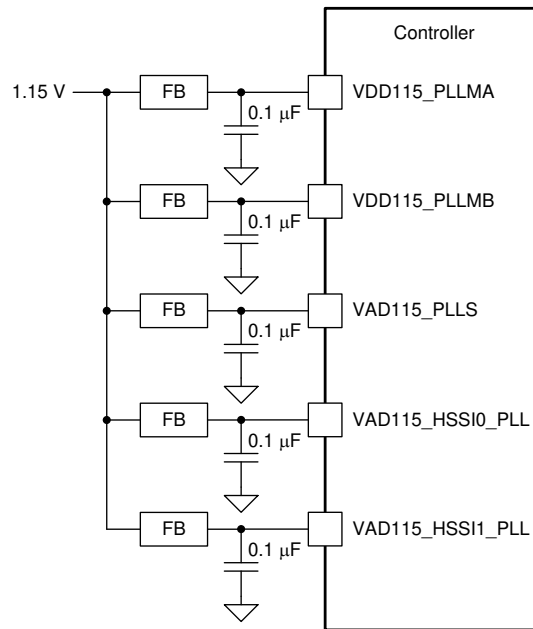
and

- VAD18\_PLLMA
- VAD18\_PLLMB

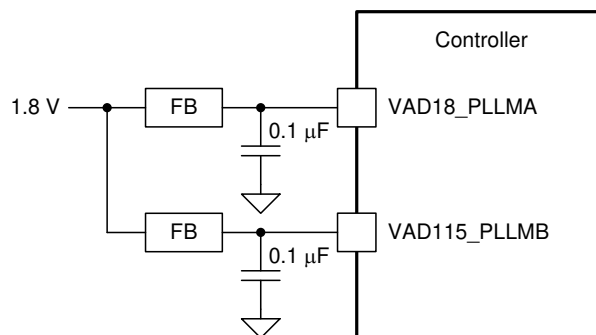
It is important that each of these 1.15-V and 1.8-V supply pins have individual high frequency filtering in the form of a ferrite bead and a 0.1- $\mu$ F ceramic capacitor. Ensure that the impedance of the ferrite bead is much greater than that of the capacitor at frequencies above 10 MHz. Locate these components very close to the individual PLL power supply balls. Recommended values, topology, and layout examples are shown in 表 9-1, 图 9-7 and 图 9-8, and 图 9-9 respectively.

**表 9-1. Recommended PLL and Crystal Power Supply Filter Components**

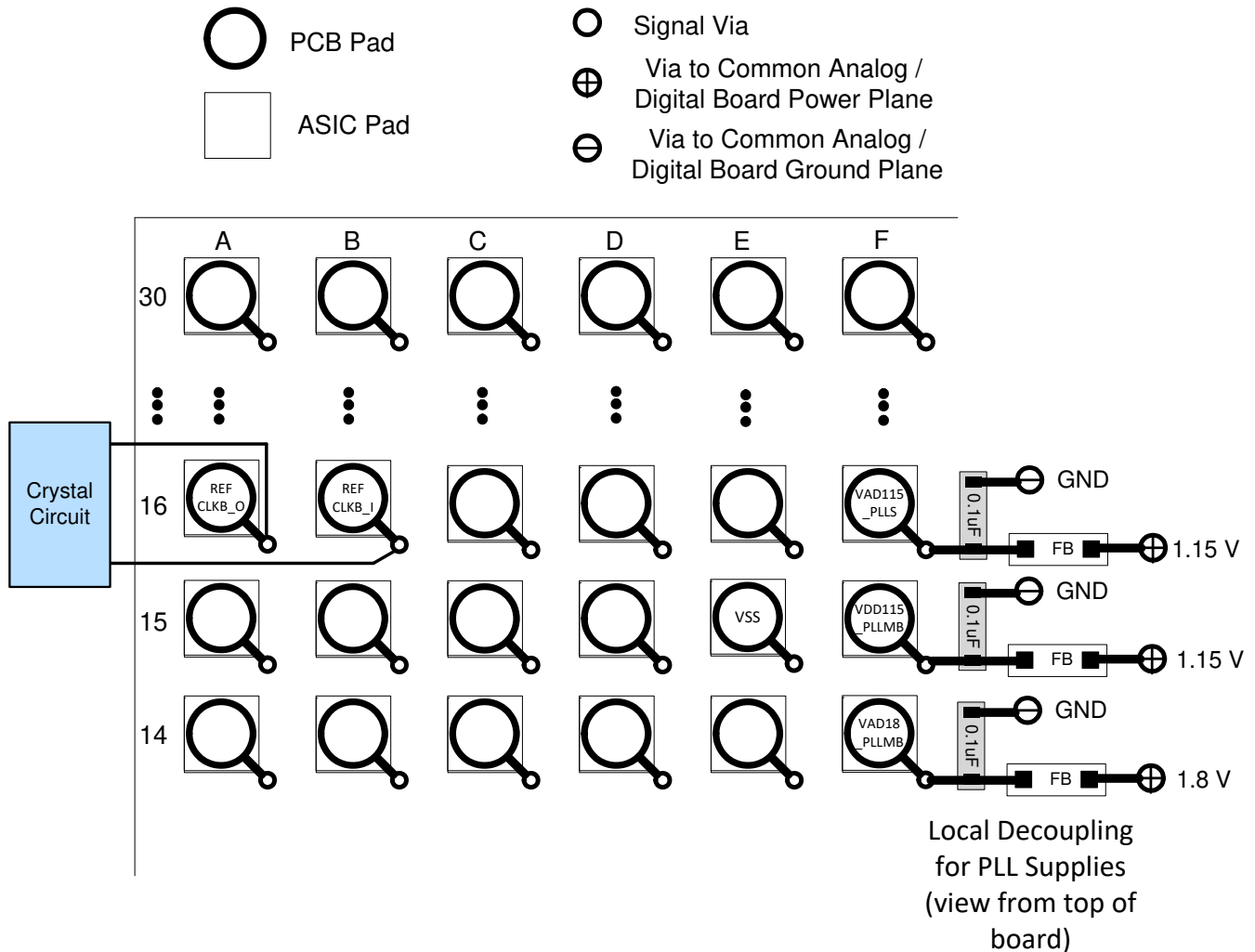
COMPONENT	PARAMETER	RECOMMENDED VALUE	UNIT
Shunt capacitor	Capacitance	0.1	$\mu$ F
Series ferrite	Impedance at 100 MHz	> 100	$\Omega$
	DC Resistance	< 0.40	$\Omega$



**图 9-7. 1.15-V PLL Power Supply Filter Topology**



**图 9-8. 1.8-V PLL Power Supply Filter Topology**



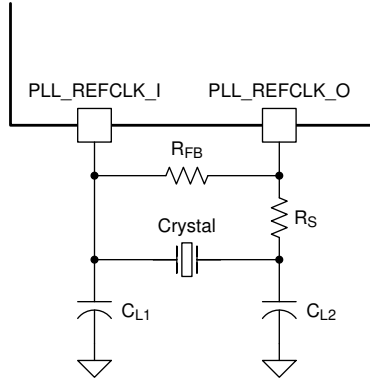
**9-9. PLL Power Supply Filter Layout Examples**

Since the PCB layout is critical to PLL performance, it is vital that the PLL power is treated like an analog signal. Additional design guidelines are as follows:

- Place all filter components as close to possible to each of the PLL supply package pins.
- Keep the leads of the high-frequency capacitors as short as possible, and as such, it is recommended that these capacitors be placed under the package on the opposite side of the board.
- Use a surface mount capacitor that is of high quality, low ESR, and monolithic.
- For each PLL power pin, a single trace (as wide as possible) must be used from the DLPC6540 to the capacitor and then through the series ferrite to the power source.

#### 9.1.4 Layout Guideline for DLPC6540 Reference Clock

The DLPC6540 requires two external reference clocks to feed its internal PLLs. A crystal or oscillator can supply these references. The recommended crystal configurations and reference clock frequencies are listed in [表 9-2](#), with additional required discrete components shown in [图 9-10](#) and defined in [表 9-2](#).



$C_L$  = Crystal load capacitance

$R_{FB}$  = Feedback Resistor

图 9-10. Discrete Components Required for Crystal

### 9.1.4.1 Recommended Crystal Oscillator Configuration

表 9-2. Recommended Crystal Configurations

PARAMETER	CRYSTAL A	CRYSTAL B	UNIT
Crystal circuit configuration	Parallel resonant	Parallel resonant	
Crystal type	Fundamental (first harmonic)	Fundamental (first harmonic)	
Crystal nominal frequency	40	38	MHz
Crystal frequency tolerance <sup>(1)</sup>	±100 (200 p-p max)	±100 (200 p-p max)	PPM
Crystal equivalent series resistance (ESR)	60 (Max)	60 (Max)	Ω
Crystal load capacitance	20 (Max)	20 (Max)	pF
Crystal Shunt Load capacitance	7 (Max)	7 (Max)	pF
Temperature range	–40°C to +85°C	–40°C to +85°C	°C
Drive level	100 (Nominal)	100 (Nominal)	μW
$R_{FB}$ feedback resistor (nominal)	1 Meg (Nominal)	1 Meg (Nominal)	Ω
$C_{L1}$ external crystal load capacitor	See equation in <sup>(2)</sup> .	See equation in <sup>(2)</sup> .	pF
$C_{L2}$ external crystal load capacitor	See equation in <sup>(3)</sup> .	See equation in <sup>(3)</sup> .	pF
PCB layout	A ground isolation ring around the crystal is recommended.	A ground isolation ring around the crystal is recommended.	

- (1) Crystal frequency tolerance to include accuracy, temperature, aging, and trim sensitivity. These are typically specified separately and the sum of all required to meet this requirement.
- (2)  $CL1 = 2 \times (CL - C_{stray\_pll\_refclk\_i})$ , where:  $C_{stray\_pll\_refclk\_i}$  = Sum of package and PCB stray capacitance at the crystal pin associated with the Controller pin REFCLKx\_I. See 表 9-3.
- (3)  $CL2 = 2 \times (CL - C_{stray\_pll\_refclk\_o})$ , where:  $C_{stray\_pll\_refclk\_o}$  = Sum of package and PCB stray capacitance at the crystal pin associated with the Controller pin REFCLKx\_O. See 表 9-3.

表 9-3. Crystal Pin Capacitance

PARAMETER		MIN	NOM	MAX	UNITS
Cstray_pll_refclkA_i	Sum of package and PCB stray capacitance at REFCLKA_I		4.5		pF
Cstray_pll_refclkA_o	Sum of package and PCB stray capacitance at REFCLKA_O		4.5		pF
Cstray_pll_refclkB_i	Sum of package and PCB stray capacitance at REFCLKB_I		4.5		pF
Cstray_pll_refclkB_o	Sum of package and PCB stray capacitance at REFCLKB_O		4.5		pF

The crystal circuits in the DLPC6540 have dedicated power (VAD33\_OSCA and VAD33\_OSCB) pins, with the recommended filtering for each shown in 图 9-11, and recommended values shown in 表 9-1.

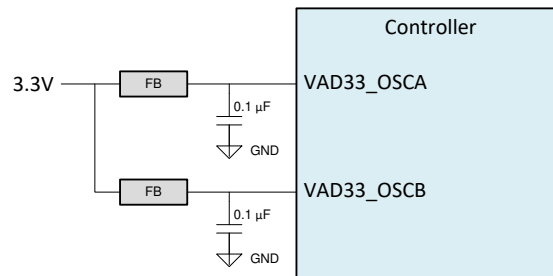


图 9-11. Crystal Power Supply Filtering

表 9-4. DLPC6540 Recommended Crystal Parts

MANUFACTURER	PART NUMBER	NOMINAL FREQUENCY	FREQUENCY TOLERANCE, FREQUENCY STABILITY, AGING/YEAR	ESR	LOAD CAPACITANCE	OPERATING TEMPERATURE	DRIVE LEVEL
TXC	7M38070001 (1)	38 MHz	Freq Tolerance: ±20 ppm	30-Ω max	12 pF	-40°C to +85°C	100 μW
			Freq Stability: ±20 ppm				
			Aging/Year: ±3 ppm				
TXC	7M40070041 (2)	40 MHz	Freq Tolerance: ±20 ppm	30-Ω max	12 pF	-40°C to +85°C	100 μW
			Freq Stability: ±20 ppm				
			Aging/Year: ±3 ppm				

(1) This device requires an  $R_S$  resistor with value = 0.

(2) This device requires an  $R_S$  resistor with value = 0.

### 9.1.5 V-by-One Interface Layout Considerations

The DLPC6540 V-by-One SERDES differential interface waveform quality and timing is dependent on the total length of the interconnect system, the spacing between traces, the characteristic impedance, etch losses, and how well matched the lengths are across the interface. Thus, ensuring positive timing margin requires attention to many factors.

DLPC6540 I/O timing parameters, V-by-One transmitter timing parameters, as well as Thine specific timing requirements can be found in their corresponding data sheets. PCB routing mismatch can be budgeted and met through controlled PCB routing. PCB related requirements for V-by-One are provided in [表 9-5](#) as a starting point for the customer.

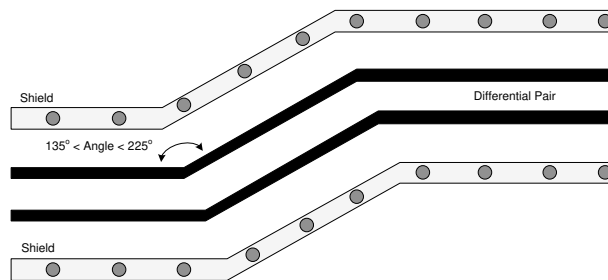
**表 9-5. V-by-One Interface PBC Related Requirements (1)**

PARAMETER	MIN	TYP	MAX	UNIT
Intra-lane cross-talk (between VX1_DATAx_P and VX1_DATAx_N)			< 1.5	mVpp
Inter-lane cross-talk (between data lane pairs)			< 1.5	mVpp
Cross-talk between data lanes and other signals			< 1.5	mVpp
Intra-lane skew			< 40	ps
Inter-lane skew			< 5	UI
Differential Impedance	90	100	110	$\Omega$

(1) If using the minimum trace width and spacing to escape the Controller ball field, widening these out after escape is desirable if practical to achieve the target 100  $\Omega$  impedance (e.g. to reduce transmission line losses).

Additional V-by-One layout guidelines:

- Route the differential signal pairs on the top layer of the PBC to minimize the number of vias. Limit the number of necessary vias to two.
- Route differential signal pairs over a single ground or power plane using a Micro-strip line configuration. Ground guard traces are also recommended.
- Do not route the differential signal pairs over the slit of power or ground planes.
- Minimize the trace length mismatch for each pair, and between each pair, in order to meet the skew requirements.
- Ensure that the bend angles associated with the differential signal pairs are between 135° and 225°(See [图 9-12](#)).



**图 9-12. V-by-One Routing Example**

### 9.1.6 USB Interface Layout Considerations

The DLPC6540 USB differential interface waveform quality and timing is dependent on the total length of the interconnect system, the spacing between traces, the characteristic impedance, etch losses, and how well matched the lengths are across the interface. Thus, ensuring positive timing margin requires attention to many factors.

DLPC6540 I/O timing parameters, USB transmitter and receiver timing parameters, as well as USB specific timing requirements can be found in their corresponding data sheets. PCB routing mismatch can be budgeted and met through controlled PCB routing. PCB related requirements for USB are provided in 表 9-6 as a starting point for the customer.

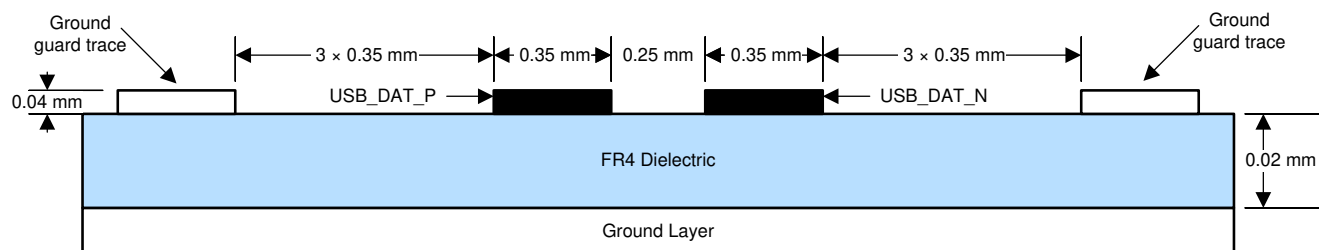
**表 9-6. USB Interface PBC Related Requirements (1)(2)**

PARAMETER	MIN	TYP	MAX	UNIT
Cross-talk between data lane (USB_DAT_P, USB_DAT_N) and other signals			< 1.5	mVpp
Intra-lane skew (USB_DAT_P, USB_DAT_N)			< 20	ps
Differential Impedance (USB_DAT_P, USB_DAT_N)	76.5	90	103.5	$\Omega$
Single Mode impedance (USB_DAT_P, USB_DAT_N)		45		$\Omega$
Common Mode Impedance (USB_DAT_P, USB_DAT_N)	21	30	39	$\Omega$
Parasitic resistance (USB_DAT_P, USB_DAT_N)			$\leq 0.5$	$\Omega$
Total capacitance (USB_DAT_P, USB_DAT_N)			< 4	pF
Differences of trace capacitance between USB_DAT_P, USB_DAT_N			< 1	pF
TXRTUNE resistor	172.26	174	175.74	$\Omega$

- (1) If using the minimum trace width and spacing to escape the Controller ball field, widening these out after escape is desirable if practical to achieve the target 100  $\Omega$  impedance (e.g. to reduce transmission line losses).
- (2) One pcb layout example for the differential pair is shown in 图 9-13

Additional layout guidelines for USB\_DAT\_P/USB\_DAT\_N:

- Route the differential signal pairs on the top layer of the PBC to minimize the number of vias. Limit the number of necessary vias to two.
- Route differential signal pairs over a single ground or power plane using a Micro-strip line configuration. Ground guard traces are also recommended.
- Do not route the differential signal pairs over the slit of power or ground planes.
- Minimize the trace length mismatch for each pair, and between each pair, in order to meet the skew requirements.
- Ensure that the bend angles associated with the differential signal pair are between 135° and 225°. (See 图 9-14).
- Minimize the length where the differential signal pair are parallel to clocks or digital signals.
- Do not route the differential signal pair under an IC that uses a quartz crystal, oscillator, clock synchronization circuit, magnetic device, or clock.



**图 9-13. USB Layout Example**



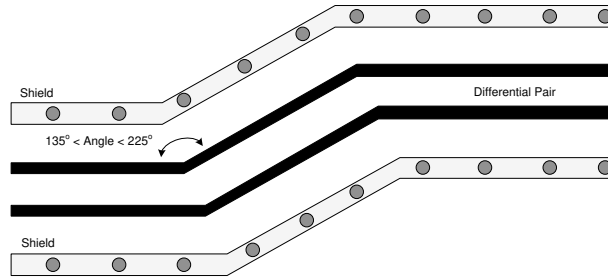


図 9-14. USB Routing Example

Additional USB layout guidelines for TXRTUNE

- Use the shortest possible connection lengths for the resistor between TXRTUNE and ground.
- Use ground layer and ground guard traces to shield the wires and resistor.

### 9.1.7 DMD Interface Layout Considerations

The DLPC6540 controller HSSI differential interface waveform quality and timing is dependent on the total length of the interconnect system, the spacing between traces, the characteristic impedance, etch losses, and how well matched the lengths are across the interface. Thus, ensuring positive timing margin requires attention to many factors.

DLPC6540 I/O timing parameters as well as DMD I/O timing parameters can be found in their corresponding data sheets. Similarly, PCB routing mismatch can be budgeted and met through controlled PCB routing. PCB design recommendations are provided in 表 9-7, 図 9-15, and the paragraph below as a starting point for the customer.

表 9-7. PCB Recommendations for DMD Interface <sup>(1)(2)</sup>

PARAMETER	MIN	MAX	UNIT
$T_W$ Trace Width	5.7		mils
$T_S$ Intra-lane Trace Spacing	5.3		mils
$T_{SPP}$ Inter-lane trace spacing <sup>(3)</sup>	48.3		mils

- (1) Recommendations to achieve the desired nominal differential impedance as specified by  $R_{DIFF}$  in セクション 6.7.
- (2) These parameters show recommendations based on the micro-strip design shown in 図 9-15. This design minimizes signal loss to support longer trace lengths at the expense of electromagnetic interference (EMI). The designer has the option to use of a stripline design for shorter trace lengths and to target minimizing EMI at the expense of signal loss.
- (3) A reduced inter-lane spacing can be used to escape the Controller ball field, however, widen this spacing to at least the stated minimum after escape.

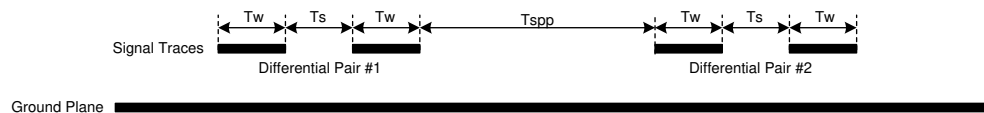


図 9-15. DMD Differential Layout Recommendations

Additional DMD interface layout guidelines:

- Route the differential signal pairs on the top layer of the PBC to minimize the number of vias. Limit the number of necessary vias to two. If two are required, place one at each end of the line (one at the controller and one at the DMD).
- Route the differential signal pairs over a single ground or power plane using a Micro-strip line configuration.
- Do not route the differential signal pairs over the slit of power or ground planes.
- Ensure the bend angles associated with the differential signal pairs are between 135° and 225°.
- Route the single-ended signal in a way that to minimizes the number of vias required. Limit the number of necessary vias to two. If two are required, place one at each end of the line (one at the controller and one at the DMD).
- Avoid stubs.
- No external termination resistors are required on the DMD\_HSSI or DMD\_LS differential signals.

- Include a series termination resistor (with a value of 30.1  $\Omega$ , for example) to the DMD\_LS0\_RDATA and DMD\_LS1\_RDATA single-ended signal paths. Place the resistor as close as possible to the corresponding DMD pin.
- The DMD\_DEN\_ARSTZ does not typically require a series resistor, however, for a long trace, one might be needed to reduce undershoot or overshoot.

### 9.1.8 General Handling Guidelines for Unused CMOS-Type Pins

To avoid potential damage to unused video source inputs and unused GPIO, the instructions specifically noted in the associated [セクション 5](#) must be followed. For those unused inputs without specific instructions, TI recommends that these input pins be tied through a pullup resistor to its associated power supply or a pulldown to ground. Unused output-only pins can remain open. Never tie unused output-only pins directly to power or ground. For controller inputs with an internal pullup or pulldown resistor, it is unnecessary to add an external pullup or pulldown unless specifically recommended. Internal pullup and pulldown resistors are weak and cannot be expected to drive the external line. When external pullup or pulldown resistors are needed for pins that have built-in weak pullups or pulldowns, use the value specified in [表 5-14](#).

There are also power supply considerations that must be followed for any unused video sources. These are detailed in [セクション 8.3](#).

### 9.1.9 Maximum Pin-to-Pin, PCB Interconnects Etch Lengths

**表 9-8. Max Pin-to-Pin PCB Interconnect Recommendations - DMD**

Controller INTERFACE	SIGNAL INTERCONNECT TOPOLOGY <sup>(1)</sup> <sup>(2)</sup> <sup>(3)</sup>		UNIT
	SINGLE BOARD SIGNAL ROUTING LENGTH	MULTI-BOARD SIGNAL ROUTING LENGTH	
DMD_HSSI0_CLK_P DMD_HSSI0_CLK_N	10 (254)	Controller PCB: 2 (50.8) DMD PCB: 4 (101.6) Flex: 10 (254)	inch (mm)
DMD_HSSI0_D0_P DMD_HSSI0_D0_N	10 (254)	Controller PCB: 2 (50.8) DMD PCB: 4 (101.6) Flex: 10 (254)	inch (mm)
DMD_HSSI0_D1_P DMD_HSSI0_D1_N			
DMD_HSSI0_D2_P DMD_HSSI0_D2_N			
DMD_HSSI0_D3_P DMD_HSSI0_D3_N			
DMD_HSSI0_D4_P DMD_HSSI0_D4_N			
DMD_HSSI0_D5_P DMD_HSSI0_D5_N			
DMD_HSSI0_D6_P DMD_HSSI0_D6_N			
DMD_HSSI0_D7_P DMD_HSSI0_D7_N			
DMD_HSSI1_CLK_P DMD_HSSI1_CLK_N	10 (254)	Controller PCB: 2 (50.8) DMD PCB: 4 (101.6) Flex: 10 (254)	inch (mm)
DMD_HSSI1_D0_P DMD_HSSI1_D0_N	10 (254)	Controller PCB: 2 (50.8) DMD PCB: 4 (101.6) Flex: 10 (254)	inch (mm)
DMD_HSSI1_D1_P DMD_HSSI1_D1_N			
DMD_HSSI1_D2_P DMD_HSSI1_D2_N			
DMD_HSSI1_D3_P DMD_HSSI1_D3_N			
DMD_HSSI1_D4_P DMD_HSSI1_D4_N			
DMD_HSSI1_D5_P DMD_HSSI1_D5_N			
DMD_HSSI1_D6_P DMD_HSSI1_D6_N			
DMD_HSSI1_D7_P DMD_HSSI1_D7_N			
DMD_LS0_CLK_P DMD_LS0_CLK_N	18 (457.2)	18 (457.2)	inch (mm)
DMD_LS0_WDATA_P DMD_LS0_WDATA_N	18 (457.2)	18 (457.2)	inch (mm)
DMD_LS1_CLK_P DMD_LS1_CLK_N	18 (457.2)	18 (457.2)	inch (mm)
DMD_LS1_WDATA_P DMD_LS1_WDATA_N	18 (457.2)	18 (457.2)	inch (mm)
DMD_LS0_RDATA	18 (457.2)	18 (457.2)	inch (mm)
DMD_LS1_RDATA	18 (457.2)	18 (457.2)	inch (mm)

**表 9-8. Max Pin-to-Pin PCB Interconnect Recommendations - DMD (continued)**

Controller INTERFACE	SIGNAL INTERCONNECT TOPOLOGY <sup>(1) (2) (3)</sup>		UNIT
	SINGLE BOARD SIGNAL ROUTING LENGTH	MULTI-BOARD SIGNAL ROUTING LENGTH	
DMD_DEN_ARSTZ	N/A	N/A	inch (mm)

- (1) Max signal routing length includes escape routing.  
(2) Multi-board DMD routing lengths shown are the combination that was analyzed by TI.  
(3) Due to board variations, create a SPICE simulation for all board designs with the Controller IBIS models to ensure signal routing lengths do not exceed signal requirements.

**表 9-9. High Speed PCB Signal Routing Matching Requirements**

SIGNAL GROUP LENGTH MATCHING <sup>(1) (2)</sup>				
INTERFACE	SIGNAL GROUP	REFERENCE SIGNAL	MAX MISMATCH <sup>(3)</sup>	UNIT
DMD <sup>(4)</sup>	DMD_HSSI0_D0_P DMD_HSSI0_D0_N	DMD_HSSI0_CLK_P DMD_HSSI0_CLK_N	±1.0 (±25.4)	inch (mm)
	DMD_HSSI0_D1_P DMD_HSSI0_D1_N			
	DMD_HSSI0_D2_P DMD_HSSI0_D2_N			
	DMD_HSSI0_D3_P DMD_HSSI0_D3_N			
	DMD_HSSI0_D4_P DMD_HSSI0_D4_N			
	DMD_HSSI0_D5_P DMD_HSSI0_D5_N			
	DMD_HSSI0_D6_P DMD_HSSI0_D6_N			
	DMD_HSSI0_D7_P DMD_HSSI0_D7_N			
DMD <sup>(5)</sup>	DMD_HSSI0_x_P	DMD_HSSI0_x_N	±0.01 (±0.254)	inch (mm)
DMD <sup>(4)</sup>	DMD_HSSI1_D0_P DMD_HSSI1_D0_N	DMD_HSSI1_CLK_P DMD_HSSI1_CLK_N	±1.0 (±25.4)	inch (mm)
	DMD_HSSI1_D1_P DMD_HSSI1_D1_N			
	DMD_HSSI1_D2_P DMD_HSSI1_D2_N			
	DMD_HSSI1_D3_P DMD_HSSI1_D3_N			
	DMD_HSSI1_D4_P DMD_HSSI1_D4_N			
	DMD_HSSI1_D5_P DMD_HSSI1_D5_N			
	DMD_HSSI1_D6_P DMD_HSSI1_D6_N			
	DMD_HSSI1_D7_P DMD_HSSI1_D7_N			
DMD <sup>(5)</sup>	DMD_HSSI1_x_P	DMD_HSSI1_x_N	±0.01 (±0.254)	inch (mm)
DMD <sup>(6)</sup>	DMD_HSSI0_CLK_P	DMD_HSSI1_CLK_P	±0.05 (±1.27)	inch (mm)
DMD <sup>(6)</sup>	DMD_HSSI0_CLK_N	DMD_HSSI1_CLK_N	±0.05 (±1.27)	inch (mm)
DMD <sup>(4)</sup>	DMD_LS0_WDATA_P DMD_LS0_WDATA_N	DMD_LS0_CLK_P DMD_LS0_CLK_N	±1.0 (±25.4)	inch (mm)

**表 9-9. High Speed PCB Signal Routing Matching Requirements (continued)**

SIGNAL GROUP LENGTH MATCHING <sup>(1) (2)</sup>				
INTERFACE	SIGNAL GROUP	REFERENCE SIGNAL	MAX MISMATCH <sup>(3)</sup>	UNIT
DMD <sup>(5)</sup>	DMD_LS0_x_P	DMD_LS0_x_N	±0.025 (±0.635)	inch (mm)
DMD <sup>(4)</sup>	DMD_LS1_WDATA_P DMD_LS1_WDATA_N	DMD_LS1_CLK_P DMD_LS1_CLK_N	±1.0 (±25.4)	inch (mm)
DMD <sup>(5)</sup>	DMD_LS1_x_P	DMD_LS1_x_N	±0.025 (±0.635)	inch (mm)
DMD	DMD_LS0_RDATA DMD_LS1_RDATA	N/A	N/A <sup>(7)</sup>	inch (mm)
DMD	DMD_DEN_ARSTZ	N/A	N/A	inch (mm)

- (1) These routing requirements are specific to the PCB routing. Internal package routing mismatches in the DLPC6540 and DLP471TP have already been accounted for in these requirements.
- (2) Training is applied to DMD HS data lines, so defined matching requirements are slightly relaxed.
- (3) This requirement must be maintained from the Controller to the DMD, even if the signals traverse multiple boards.
- (4) This is an inter-pair specification (that is, differential pair to differential pair within the group).
- (5) This is an intra-pair specification (that is, length mismatch between P and N for the same pair). This is applicable to both clock and data.
- (6) This is a channel to channel skew specification.
- (7) The low speed read control interface from the DMD is single ended, and makes use of the differential write clock. As such, a routing mismatch between these is not applicable.

## 9.2 Thermal Considerations

The underlying thermal requirement for the DLPC6540 is that the maximum operating junction temperature ( $T_J$ ) not be exceeded (defined in the [セクション 6.3](#)). This temperature is dependent on operating ambient temperature, heatsink, airflow, PCB design (including the component layout density and the amount of copper used), power dissipation of the DLPC6540, and power dissipation of surrounding components. The DLPC6540's package is designed to extract heat via the package heat slug to the heatsink, via the thermal balls, and through the power and ground planes of the PCB. Thus, heatsink, copper content, and airflow over the PCB are important factors.

The recommended maximum operating ambient temperature ( $T_A$ ) is provided primarily as a design target and is based on maximum DLPC6540 power dissipation and  $R_{\theta JA}$  at 0 m/s, 1 m/s, and 2 m/s of forced airflow, where  $R_{\theta JA}$  is the thermal resistance of the package as measured using the test board described in [セクション 9.1.1](#). This test PCB is not necessarily representative of the customer's PCB and thus the reported thermal resistance can differ from the actual product application. Although the actual thermal resistance can be different, it is the best information available during the design phase to estimate thermal performance. TI highly recommends that once the host PCB is designed and built that the thermal performance be measured and validated.

To do this, measure the top center case temperature under the worst case product scenario (max power dissipation, max voltage, max ambient temperature) and validate that the maximum recommended case temperature ( $T_C$ ) is not exceeded. This specification is based on the measured  $\phi_{JT}$  for the DLPC6540 package and provides a relatively accurate correlation to junction temperature. Take care when measuring this case temperature to prevent accidental cooling of the package surface. TI recommends a small (approximately 40 gauge) thermocouple. Ensure that the bead and thermocouple wire contact the top of the package. Cover the bead and thermocouple wire with a minimal amount of thermally conductive epoxy. Route the wires closely along the package and the board surface to avoid cooling the bead through the wires.

## 10 Device and Documentation Support

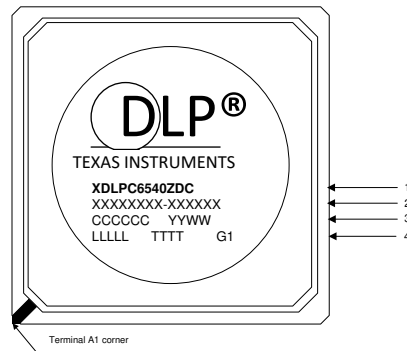
### 10.1 Device Support

#### 10.1.1 Third-Party Products Disclaimer

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#### 10.1.2 Device Nomenclature

##### 10.1.2.1 Device Markings



#### Marking Definitions:

Line 1:	TI Part Number: Engineering Samples	X = Engineering Samples DLPC6540 = Device ID blank or A, B, C ... = Part Revision ZDC = Package designator
	TI Part Number: Production	DLPC6540 = Device ID blank or A, B, C ... = Part Revision ZDC = Package designator
Line 2:	Vendor Information	XXXXXXXX-XXXXXX
Line 3:	Vendor Country Year and Week code	CCCCCC = Country YY = Year WW = Week
Line 4:	Vendor Lot and Trace Code	LLLLL = Lot code TTTT = Trace code

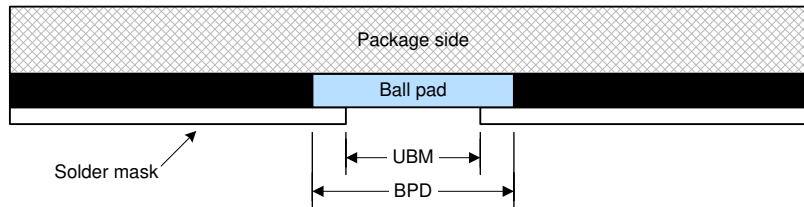
##### 10.1.2.2 Package Data

表 10-1. Package Information

PARAMETER	VALUE	UNITS
Number of balls (signal/thermal)	612 / 64	
Ball pitch	1.00	mm
UBM (under bump metallurgy)	0.48 (See <a href="#">10-1</a> )	mm
BPD (ball pad diameter)	0.58 (See <a href="#">10-1</a> )	mm
Body dimension	See Mechanical Drawing	mm
Mold compound dimensions	See Mechanical Drawing	mm
Package volume class	350 - 2000 (J-STD-20D)	mm <sup>3</sup>
Approximate weight	5.64	g
Substrate circuit	Pb-free	
Package balls	Pb-free	
Solder paste	Pb-free	

**表 10-1. Package Information (continued)**

PARAMETER	VALUE	UNITS
Solder profile	$T_C = 250^\circ\text{C}$ , $T_P = 253^\circ\text{C}$ (J-STD-20D)	
Moisture sensitivity level	MSL Level 3 (J-STD-20D)	
Solder ball composition	SAC305	
Wirebond	Cu	
Mounting technique	a) Hot air reflow (including the combination of long and/or medium infrared ray reflow) b) Long or medium infrared ray reflow	



**図 10-1. Package Ball Parameters**

## 10.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](http://ti.com). Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## 10.3 サポート・リソース

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## 10.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 10.6 Glossary

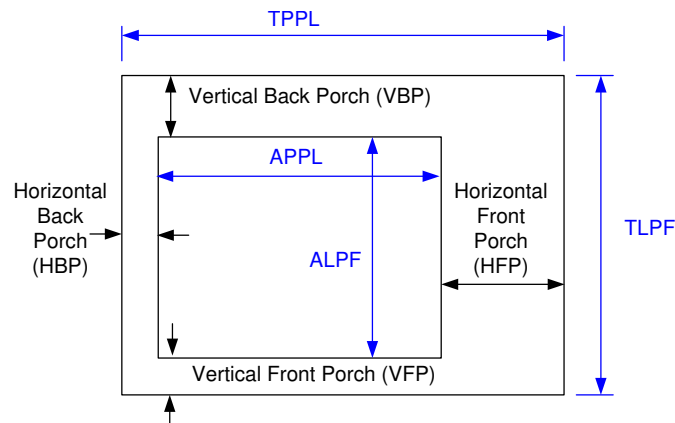
**TI Glossary** This glossary lists and explains terms, acronyms, and definitions.

### 10.6.1 Video Timing Parameter Definitions

**Active Lines Per Frame (ALPF)** Defines the number of lines in a frame containing displayable data: ALPF is a subset of the TLPF.

**Active Pixels Per Line (APPL)** Defines the number of pixel clocks in a line containing displayable data: APPL is a subset of the TPPL.

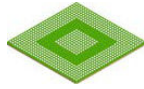
<b>Horizontal Back Porch (HBP) Blanking</b>	Number of blank pixel clocks after horizontal sync but before the first active pixel. Note: HBP times are reference to the leading (active) edge of the respective sync signal.
<b>Horizontal Front Porch (HFP) Blanking</b>	Number of blank pixel clocks after the last active pixel but before Horizontal Sync.
<b>Horizontal Sync (HS)</b>	Timing reference point that defines the start of each horizontal interval (line). The absolute reference point is defined by the active edge of the HS signal. The active edge (either rising or falling edge as defined by the source) is the reference from which all horizontal blanking parameters are measured.
<b>Total Lines Per Frame (TLPF)</b>	Defines the vertical period (or frame time) in lines: TLPF = Total number of lines per frame (active and inactive).
<b>Total Pixel Per Line (TPPL)</b>	Defines the horizontal line period in pixel clocks: TPPL = Total number of pixel clocks per line (active and inactive).
<b>Vertical Sync (VS)</b>	Timing reference point that defines the start of the vertical interval (frame). The absolute reference point is defined by the active edge of the VS signal. The active edge (either rising or falling edge as defined by the source) is the reference from which all vertical blanking parameters are measured.
<b>Vertical Back Porch (VBP) Blanking</b>	Number of blank lines after vertical sync but before the first active line.
<b>Vertical Front Porch (VFP) Blanking</b>	Number of blank lines after the last active line but before vertical sync.





## 11 Mechanical, Packaging, and Orderable Information

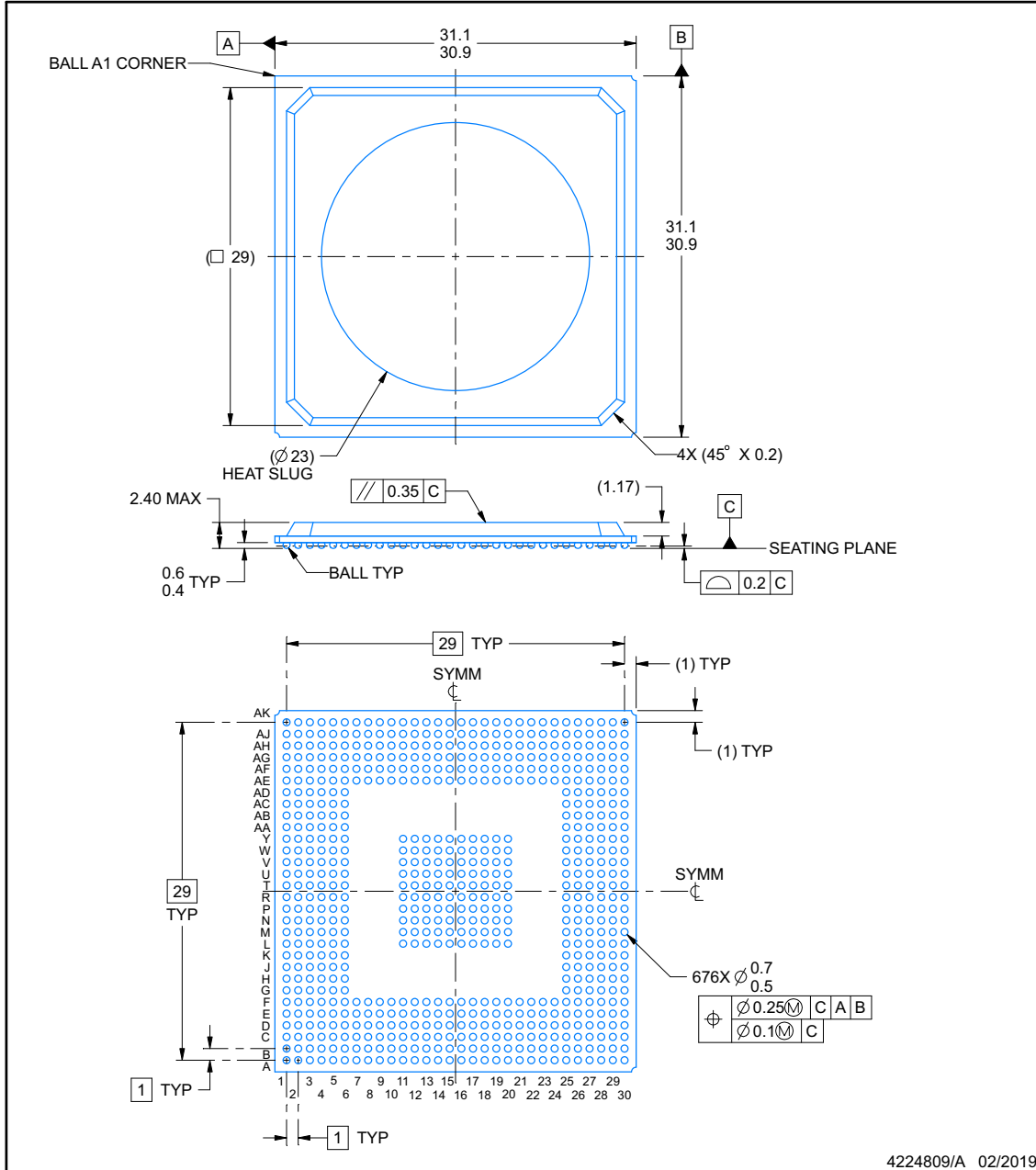
The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



**ZDC0676A**

**PACKAGE OUTLINE**  
**PBGA - 2.4 mm max height**

PLASTIC BALL GRID ARRAY



4224809/A 02/2019

NOTES:

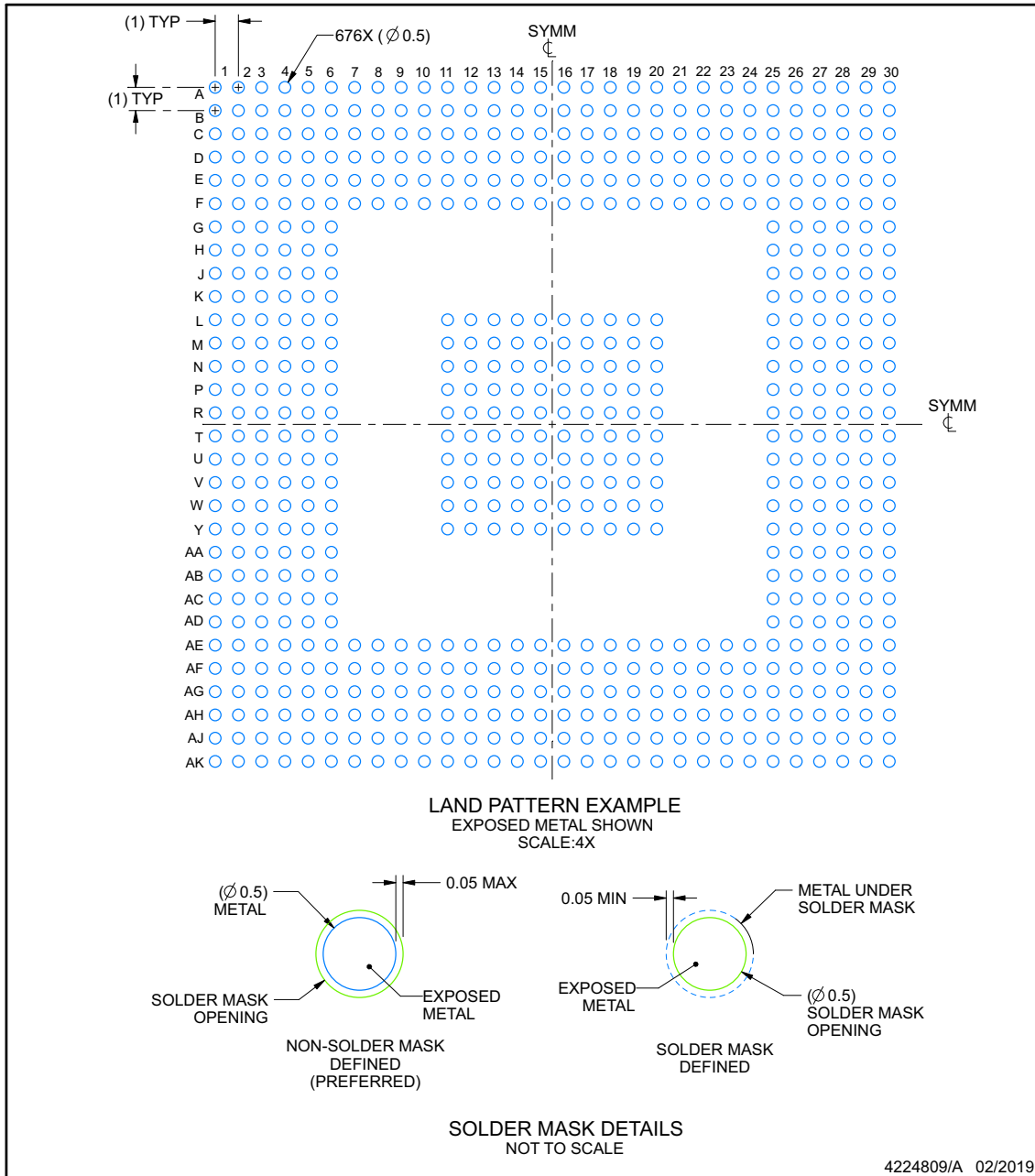
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

## EXAMPLE BOARD LAYOUT

**ZDC0676A**

**PBGA - 2.4 mm max height**

PLASTIC BALL GRID ARRAY



NOTES: (continued)

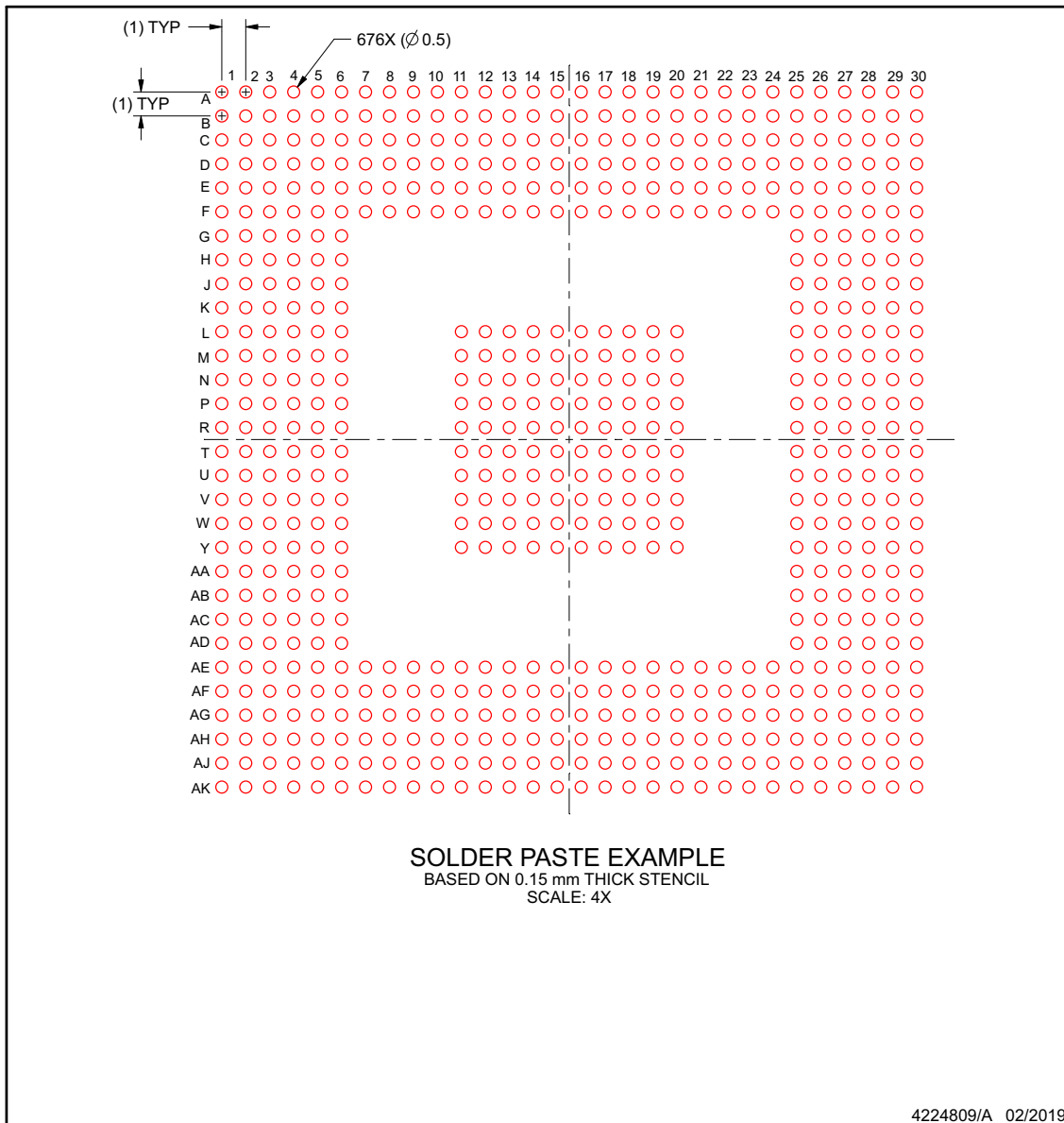
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For information, see Texas Instruments literature number SSZA002 ([www.ti.com/lit/ssza002](http://www.ti.com/lit/ssza002)).

### EXAMPLE STENCIL DESIGN

ZDC0676A

PBGA - 2.4 mm max height

PLASTIC BALL GRID ARRAY



NOTES: (continued)

- 5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
DLPC6540ZDC	Active	Production	BGA (ZDC)   676	27   JEDEC TRAY (10+1)	Yes	Call TI	Call TI	0 to 70	

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

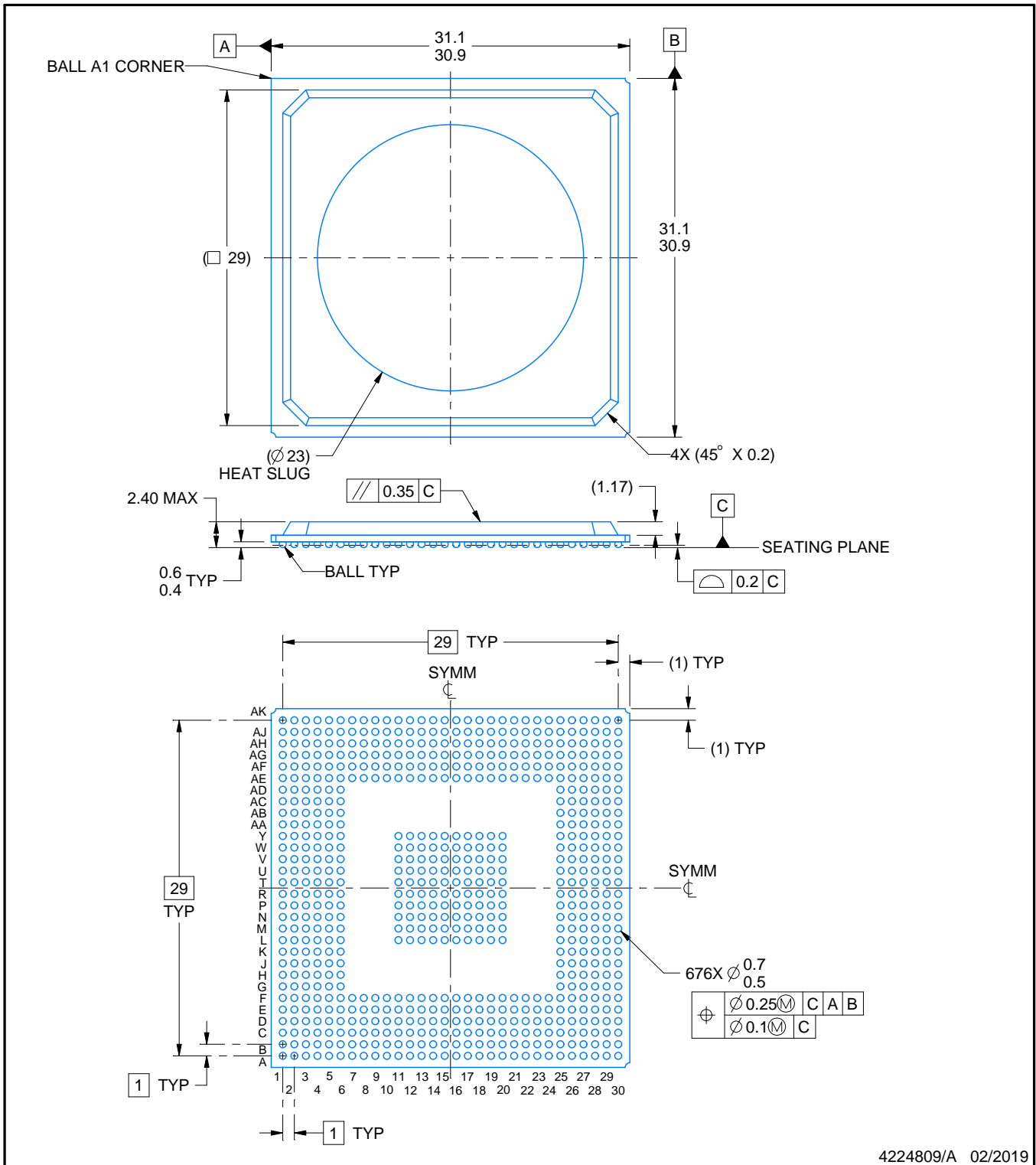
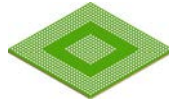
(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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NOTES:

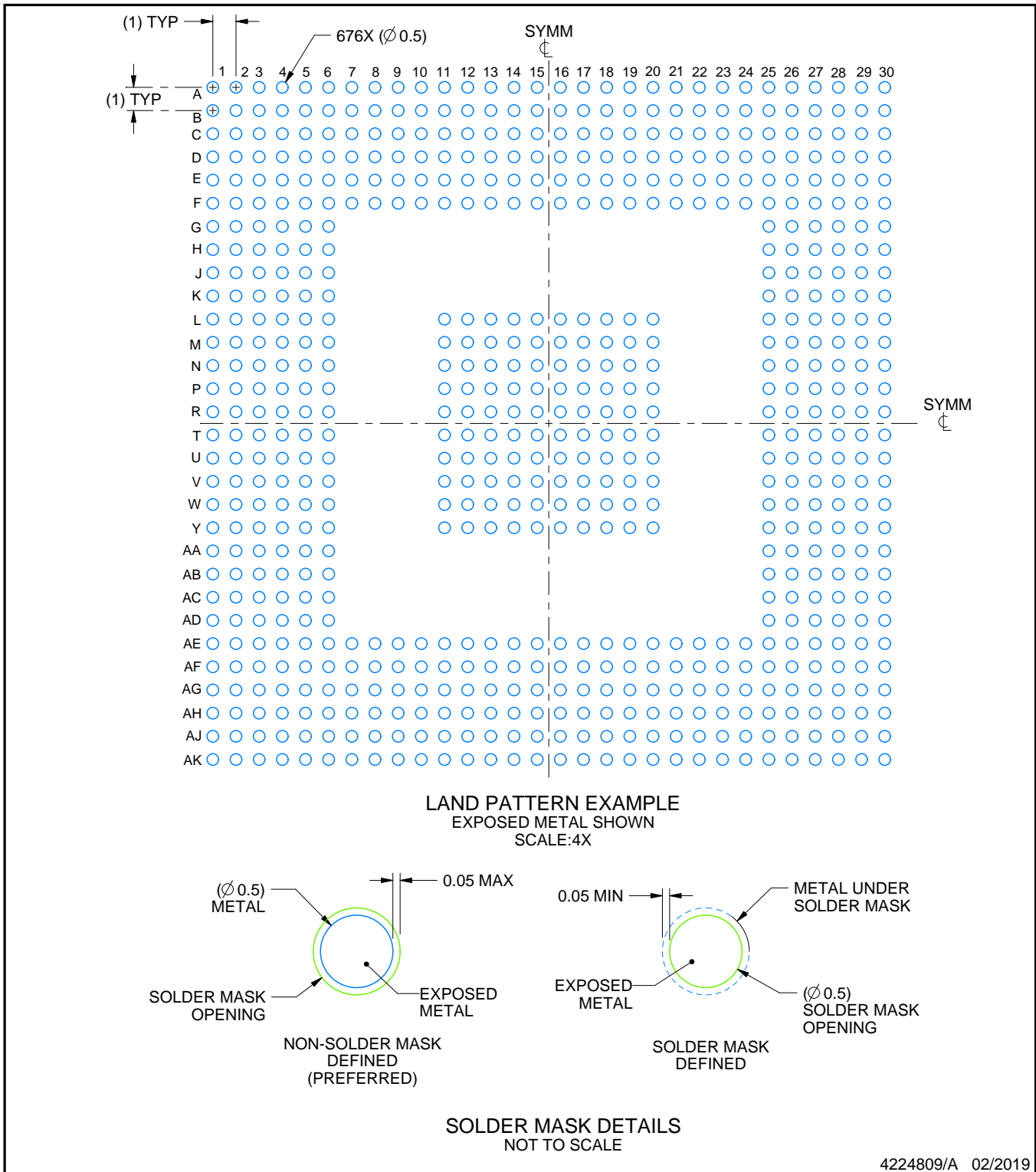
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

# EXAMPLE BOARD LAYOUT

ZDC0676A

PBGA - 2.4 mm max height

PLASTIC BALL GRID ARRAY



4224809/A 02/2019

NOTES: (continued)

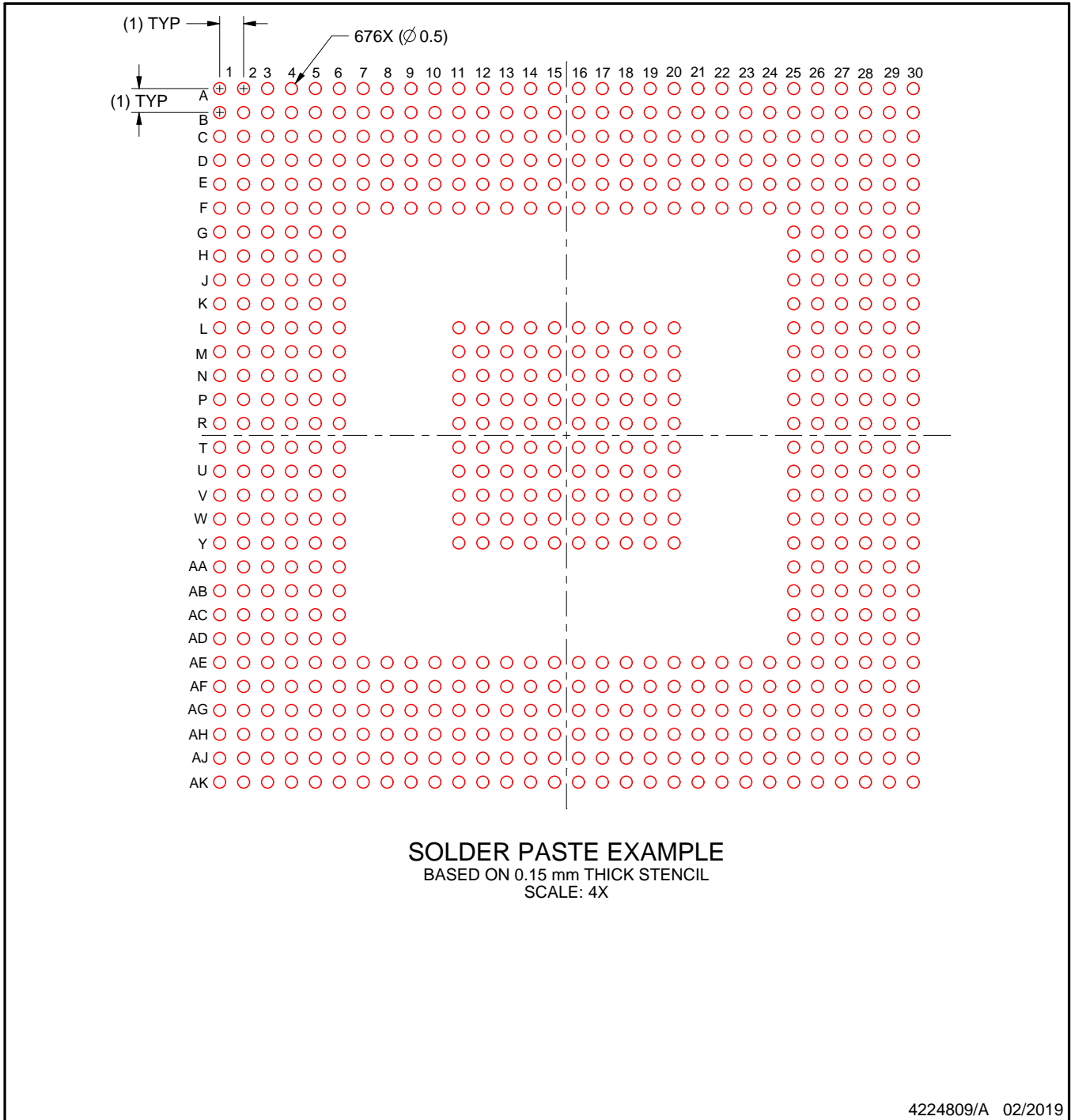
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For information, see Texas Instruments literature number SSZA002 ([www.ti.com/lit/ssza002](http://www.ti.com/lit/ssza002)).

# EXAMPLE STENCIL DESIGN

ZDC0676A

PBGA - 2.4 mm max height

PLASTIC BALL GRID ARRAY



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



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