

DRV5033 デジタル・オムニポーラ・スイッチ・ホール効果センサ

1 特長

- デジタル・オムニポーラ・スイッチ・ホール・センサ
- 優れた温度安定性
 - 温度範囲全体にわたって $B_{OP} \pm 10\%$
- 複数の感度オプション (B_{OP} / B_{RP})
 - $\pm 3.5 / \pm 2$ mT (FA、[図 24](#)を参照)
 - $\pm 6.9 / \pm 3.5$ mT (AJ、[図 24](#)を参照)
- N極とS極の磁場を検出
- 広い範囲の電圧をサポート
 - 2.5V~38V
 - 外部レギュレータ不要
- 広い範囲の温度で動作
 - $T_A = -40^\circ\text{C} \sim 125^\circ\text{C}$ (Q、[図 24](#)を参照)
- オープン・ドレイン出力 (30mAシンク)
- 高速な電源オン時間: 35 μ s
- 小さなパッケージと占有面積
 - 表面実装の3ピンSOT-23 (DBZ)
 - 2.92mm \times 2.37mm
 - スルーホールの3ピンTO-92 (LPG)
 - 4.00mm \times 3.15mm
- 保護機能
 - 逆電圧保護 (最大-22V)
 - 40Vまでの負荷ダンピングをサポート
 - 出力短絡保護
 - 出力電流制限

2 アプリケーション

- ドッキング検出
- ドアの開閉検出
- 近接感知
- バルブの位置決め
- パルスのカウント

3 概要

DRV5033 デバイスはチョップ安定化されたホール効果センサで、温度範囲全体にわたって優れた感度の安定性を持つ磁気感知ソリューションを提供し、保護機能が内蔵されています。

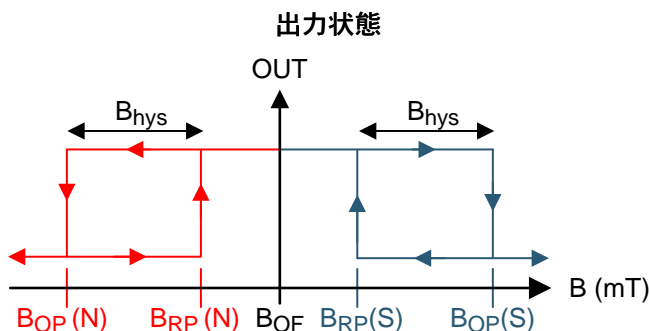
DRV5033 は磁場方向の検出において、両方の極に対して同じように反応します。周囲の磁束密度が B_{OP} スレッショルドを超えると、DRV5033 のオープン・ドレイン出力が LOW に変化します。磁場が B_{RP} 未満に低下するまで出力は LOW に維持され、その後で出力がハイ・インピーダンスになります。出力電流シンクの容量は 30mA です。2.5V~38V までの広い範囲の電圧で動作し、-22V までは逆極性保護されるため、広範な産業用アプリケーションに適したデバイスです。

逆電圧の状態、負荷ダンピング、および出力短絡や過電流に対して、内部的な保護機能が搭載されています。

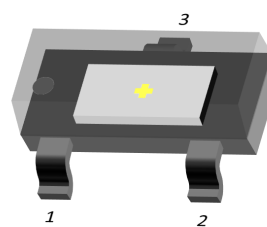
製品情報⁽¹⁾

| 型番 | パッケージ | 本体サイズ(公称) |
|---------|------------|------------------------|
| DRV5033 | SOT-23 (3) | 2.92mm \times 1.30mm |
| | TO-92 (3) | 4.00mm \times 3.15mm |

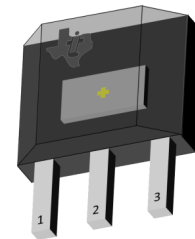
(1) 提供されているすべてのパッケージについては、巻末の注文情報を参照してください。



SOT-23



TO-92



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4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

| Revision F (May 2016) から Revision G に変更 | Page |
|---|------|
| • Changed the power-on time for the FA version in the <i>Electrical Characteristics</i> table | 6 |
| • Added the <i>Layout</i> section | 19 |
| • 追加「ドキュメントの更新通知を受け取る方法」セクション | 21 |

| Revision E (February 2016) から Revision F に変更 | Page |
|---|------|
| • Revised preliminary limits for the FA version | 6 |

| Revision D (December 2015) から Revision E に変更 | Page |
|--|------|
| • FAデバイス・オプション 追加 | 1 |
| • Added the typical bandwidth value to the <i>Magnetic Characteristics</i> table | 6 |

| Revision C (May 2015) から Revision D に変更 | Page |
|--|------|
| • SOT-23パッケージの本体サイズを訂正し、SIPパッケージ名をTO-92に訂正 | 1 |
| • Added B_{MAX} to <i>Absolute Maximum Ratings</i> | 5 |
| • Removed table note from junction temperature | 5 |
| • パッケージのテープ&リールに関するMとブランクのオプションを更新 | 20 |
| • 「コミュニティ・リソース」を追加 | 21 |

| Revision B (September 2014) から Revision C に変更 | Page |
|---|------|
| • デバイスのステータスを量産データへ更新 | 1 |

Revision A (August 2014) から Revision B に変更
Page

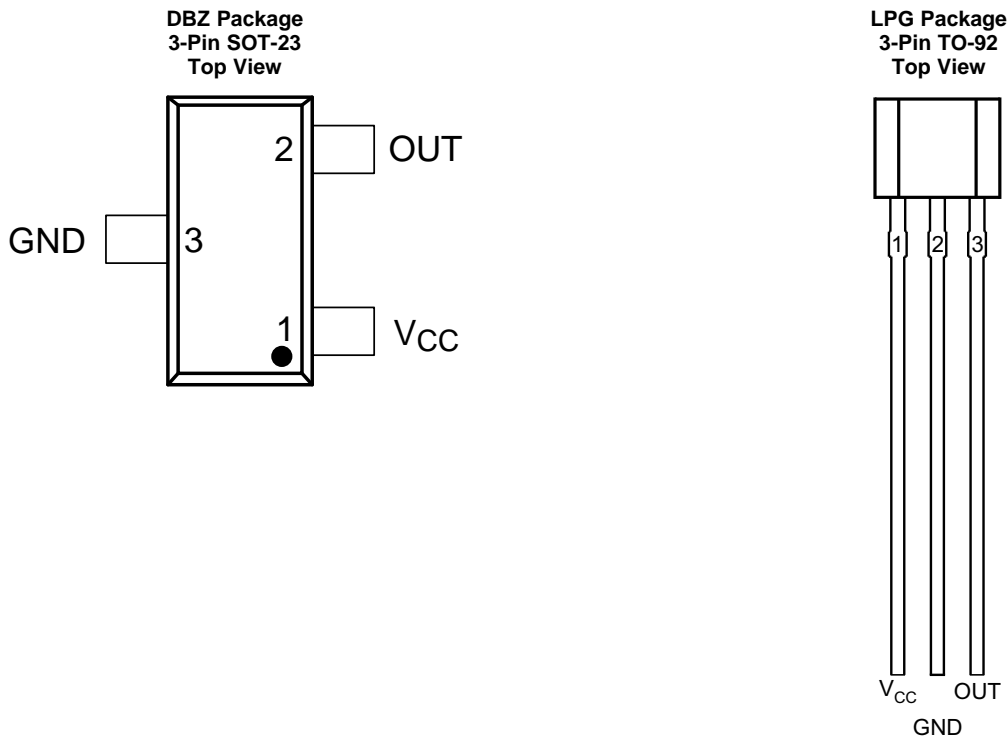
| | |
|---|----|
| • Changed the maximum T_J value to 150°C | 5 |
| • Added typical rise and fall time and removed maximum value in Switching Characteristics | 6 |
| • Updated the <i>Magnetic Characteristics</i> values | 6 |
| • Updated all <i>Typical Characteristics</i> graphs | 7 |
| • Updated Equation 4 | 17 |

2014年5月発行のものから更新
Page

| | |
|--|---|
| • 高感度オプション: +6.9 / +2.3mT (AJ) ~ +6.9 / +3.5mT (AJ) 変更 | 1 |
| • Changed the maximum T_J value from 175°C to 150°C..... | 5 |
| • Changed MIN value for I_{OCP} from 20 to 15 | 6 |
| • Changed Max value for I_{OCP} from 40 to 45 | 6 |
| • Updated <i>Magnetic Characteristics</i> table. | 6 |

5 Pin Configuration and Functions

For additional configuration information, see [デバイスのマーキング](#) and [メカニカル、パッケージ、および注文情報](#).



Pin Functions

| PIN | | | TYPE | DESCRIPTION |
|-----------------|-----|-----|--------|---|
| NAME | DBZ | LPG | | |
| GND | 3 | 2 | GND | Ground pin |
| OUT | 2 | 3 | Output | Hall sensor open-drain output. The open drain requires a resistor pullup. |
| V _{CC} | 1 | 1 | PWR | 2.5 to 38 V power supply. Bypass this pin to the GND pin with a 0.01- μ F (minimum) ceramic capacitor rated for V _{CC} . |

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

| | | MIN | MAX | UNIT |
|--|---|--------------------|-----|------|
| Power supply voltage | V _{CC} | -22 ⁽²⁾ | 40 | V |
| | Voltage ramp rate (V _{CC}), V _{CC} < 5 V | Unlimited | | V/μs |
| | Voltage ramp rate (V _{CC}), V _{CC} > 5 V | 0 | 2 | |
| Output pin voltage | | -0.5 | 40 | V |
| Output pin reverse current during reverse supply condition | | 0 | 100 | mA |
| Magnetic flux density, B _{MAX} | | Unlimited | | |
| Operating junction temperature, T _J | | -40 | 150 | °C |
| Storage temperature, T _{stg} | | -65 | 150 | °C |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Ensured by design. Only tested to -20 V.

6.2 ESD Ratings

| | | | VALUE | UNIT |
|--------------------|-------------------------|--|-------|------|
| V _(ESD) | Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾ | ±2500 | V |
| | | Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾ | ±500 | |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | MIN | MAX | UNIT |
|-------------------|--|-----|-----|------|
| V _{CC} | Power supply voltage | 2.5 | 38 | V |
| V _O | Output pin voltage (OUT) | 0 | 38 | V |
| I _{SINK} | Output pin current sink (OUT) ⁽¹⁾ | 0 | 30 | mA |
| T _A | Operating ambient temperature | -40 | 125 | °C |

- (1) Power dissipation and thermal limits must be observed

6.4 Thermal Information

| THERMAL METRIC ⁽¹⁾ | DRV5033 | | UNIT | |
|-------------------------------|--|-------------|-------|------|
| | DBZ (SOT-23) | LPG (TO-92) | | |
| | 3 PINS | 3 PINS | | |
| R _{θJA} | Junction-to-ambient thermal resistance | 333.2 | 180 | °C/W |
| R _{θJC(top)} | Junction-to-case (top) thermal resistance | 99.9 | 98.6 | °C/W |
| R _{θJB} | Junction-to-board thermal resistance | 66.9 | 154.9 | °C/W |
| ψ _{JT} | Junction-to-top characterization parameter | 4.9 | 40 | °C/W |
| ψ _{JB} | Junction-to-board characterization parameter | 65.2 | 154.9 | °C/W |

- (1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|-----------------------------------|---|-----|-----|-----|------|
| POWER SUPPLIES (V_{CC}) | | | | | | |
| V _{CC} | V _{CC} operating voltage | | 2.5 | | 38 | V |
| I _{CC} | Operating supply current | V _{CC} = 2.5 to 38 V, T _A = 25°C | | 2.7 | | mA |
| | | V _{CC} = 2.5 to 38 V, T _A = 125°C | | 3 | 3.6 | |
| t _{on} | Power-on time | AJ version | | 35 | 50 | μs |
| | | FA version | | 35 | 70 | |
| OPEN DRAIN OUTPUT (OUT) | | | | | | |
| r _{DS(on)} | FET on-resistance | V _{CC} = 3.3 V, I _O = 10 mA, T _A = 25°C | | 22 | | Ω |
| | | V _{CC} = 3.3 V, I _O = 10 mA, T _A = 125°C | | 36 | 50 | |
| I _{lkg(off)} | Off-state leakage current | Output Hi-Z | | | 1 | μA |
| PROTECTION CIRCUITS | | | | | | |
| V _{CCR} | Reverse supply voltage | | -22 | | | V |
| I _{OCp} | Overcurrent protection level | OUT shorted V _{CC} | 15 | 30 | 45 | mA |

6.6 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------------------|-------------------------------|--|-----|-----|-----|------|
| OPEN DRAIN OUTPUT (OUT) | | | | | | |
| t _d | Output delay time | B = B _{RP} – 10 mT to B _{OP} + 10 mT in 1 μs | | 13 | 25 | μs |
| t _r | Output rise time (10% to 90%) | R1 = 1 kΩ, C _O = 50 pF, V _{CC} = 3.3 V | | 200 | | ns |
| t _f | Output fall time (90% to 10%) | R1 = 1 kΩ, C _O = 50 pF, V _{CC} = 3.3 V | | 31 | | ns |

6.7 Magnetic Characteristics

over operating free-air temperature range (unless otherwise noted)

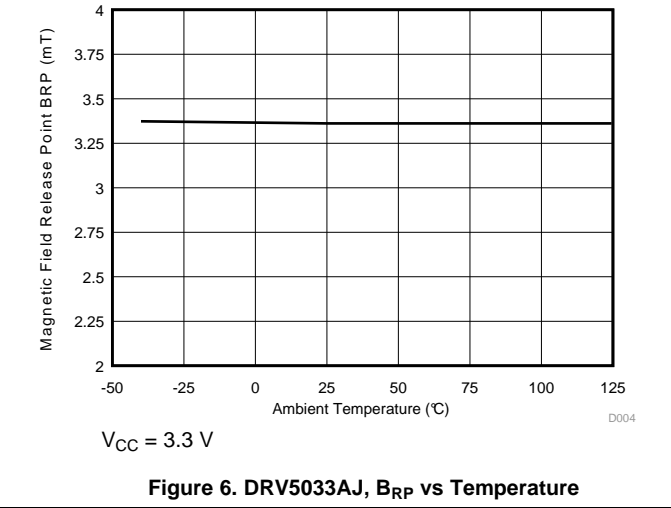
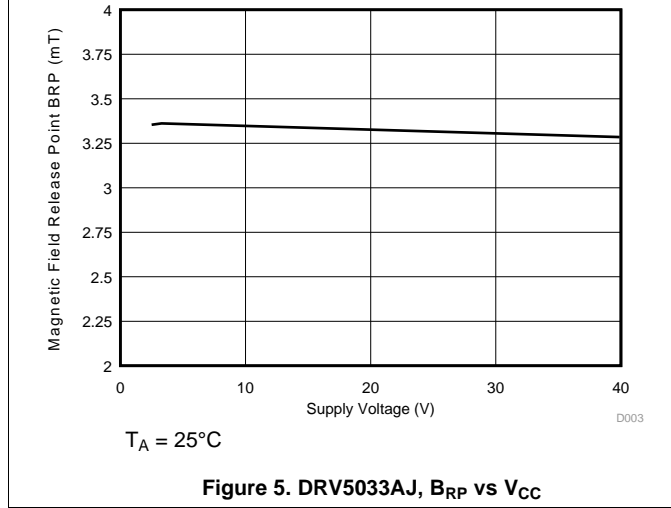
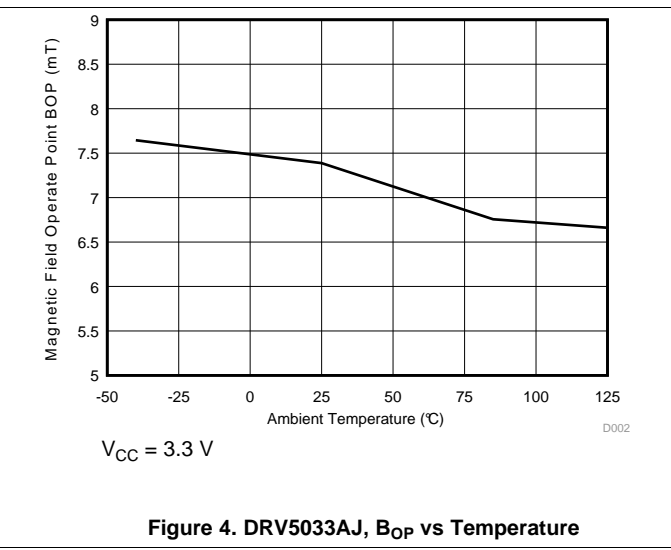
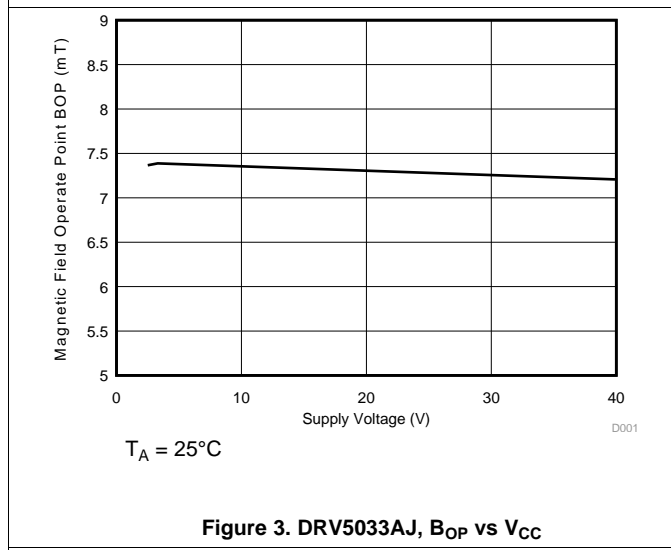
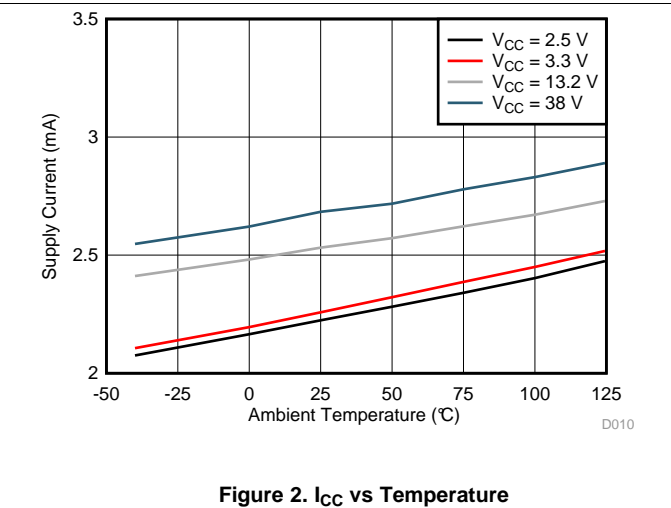
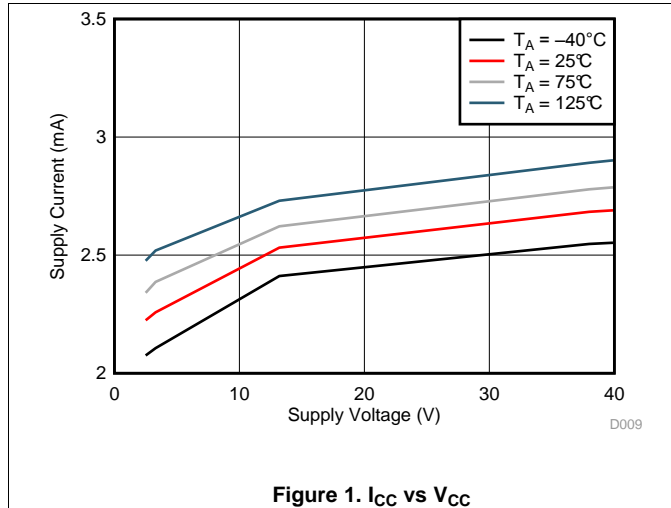
| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT ⁽¹⁾ |
|----------------------------------|--|---------------------------------|------|------|------|---------------------|
| f _{BW} | Bandwidth ⁽²⁾ | | 20 | 30 | | kHz |
| DRV5033FA: ±3.5 / ±2 mT | | | | | | |
| B _{OP} | Operate point; see Figure 12 | T _A = –40°C to 125°C | ±1.8 | ±3.5 | ±6.8 | mT |
| B _{RP} | Release point; see Figure 12 | | ±0.5 | ±2 | ±4.2 | mT |
| B _{hys} | Hysteresis; B _{hys} = (B _{OP} – B _{RP}) ⁽³⁾ | | | ±1.5 | | mT |
| B _O | Magnetic offset; B _O = (B _{OP} + B _{RP}) / 2 | | | ±2.8 | | mT |
| DRV5033AJ: ±6.9 / ±3.5 mT | | | | | | |
| B _{OP} | Operate point; see Figure 12 | T _A = –40°C to 125°C | ±3 | ±6.9 | ±12 | mT |
| B _{RP} | Release point; see Figure 12 | | ±1 | ±3.5 | ±5 | mT |
| B _{hys} | Hysteresis; B _{hys} = (B _{OP} – B _{RP}) ⁽³⁾ | | | 3.4 | | mT |
| B _O | Magnetic offset; B _O = (B _{OP} + B _{RP}) / 2 | | | 5.2 | | mT |

(1) 1 mT = 10 Gauss

(2) Bandwidth describes the fastest changing magnetic field that can be detected and translated to the output.

 (3) |B_{OP}| is always greater than |B_{RP}|.

6.8 Typical Characteristics



Typical Characteristics (continued)

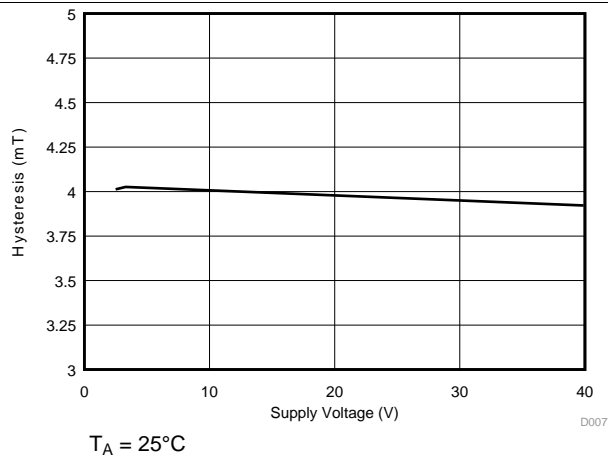


Figure 7. DRV5033AJ, Hysteresis vs V_{CC}

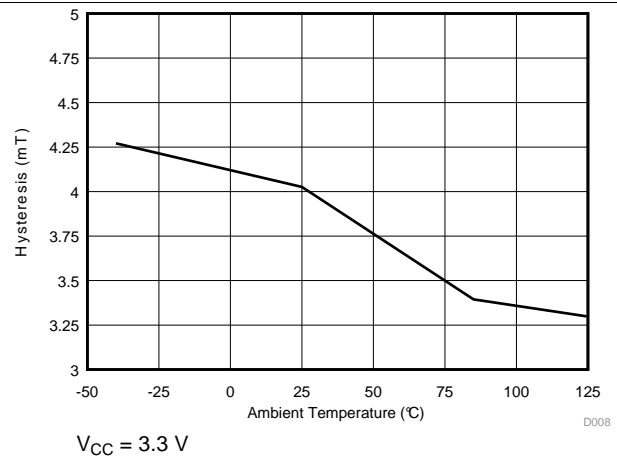


Figure 8. DRV5033AJ, Hysteresis vs Temperature

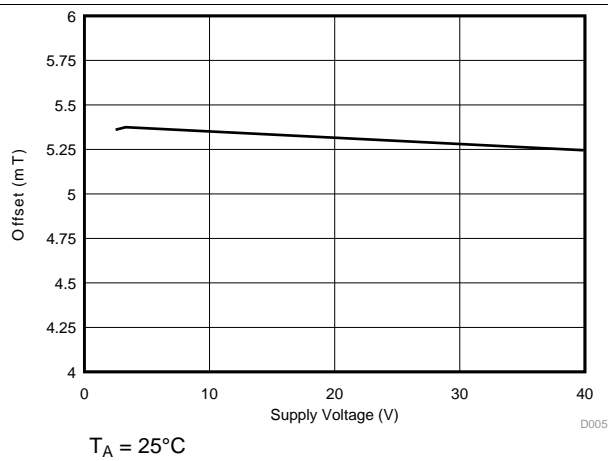


Figure 9. DRV5033AJ, Offset vs V_{CC}

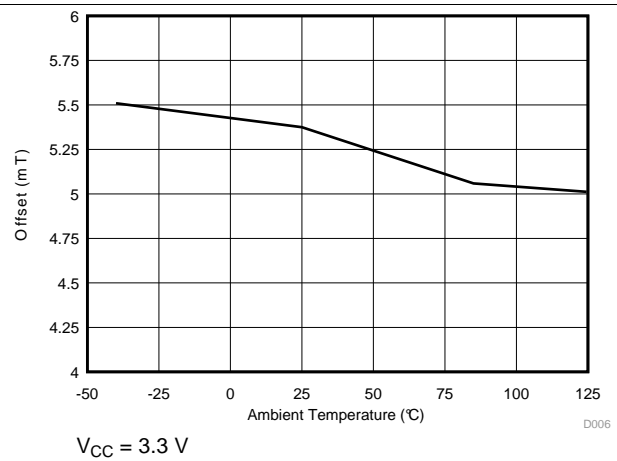


Figure 10. DRV5033AJ, Offset vs Temperature

7 Detailed Description

7.1 Overview

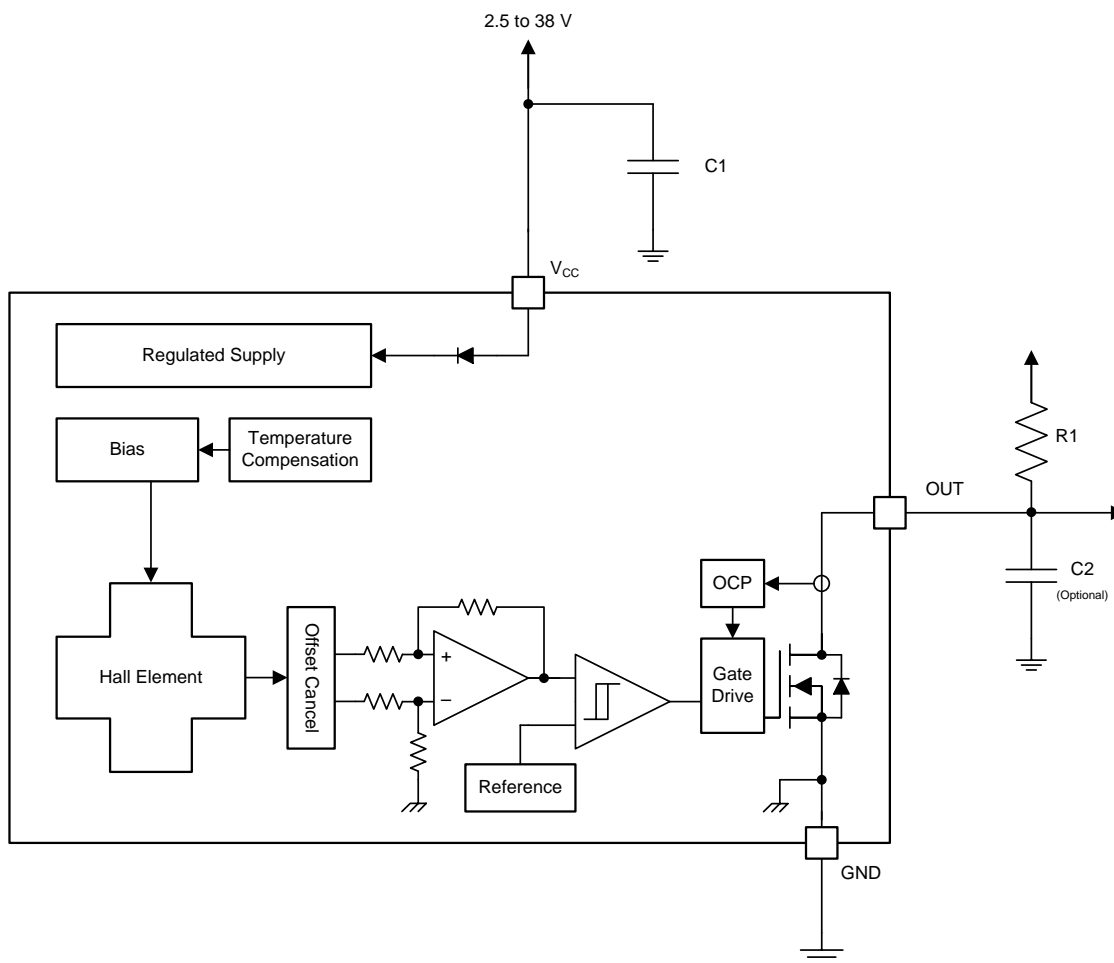
The DRV5033 device is a chopper-stabilized hall sensor with a digital omnipolar switch output for magnetic sensing applications. The DRV5033 device can be powered with a supply voltage between 2.5 and 38 V, and will survive -22 V reverse battery conditions continuously. Note that the DRV5033 device will not be operating when about -22 to 2.4 V is applied to V_{CC} (with respect to GND). In addition, the device can withstand voltages up to 40 V for transient durations.

The field polarity is defined as follows: a **south pole** near the marked side of the package is a **positive magnetic field**. A **north pole** near the marked side of the package is a **negative magnetic field**.

The omnipolar configuration allows the hall sensor to respond to either a south or north pole. A strong magnetic field of either polarity will cause the output to pull low (operate point, B_{OP}), and a weaker magnetic field will cause the output to release (release point, B_{RP}). Hysteresis is included in between the operate and release points, so magnetic field noise will not trip the output accidentally.

An external pullup resistor is required on the OUT pin. The OUT pin can be pulled up to V_{CC} , or to a different voltage supply. This allows for easier interfacing with controller circuits.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Field Direction Definition

A positive magnetic field is defined as a south pole near the marked side of the package as shown in Figure 11.

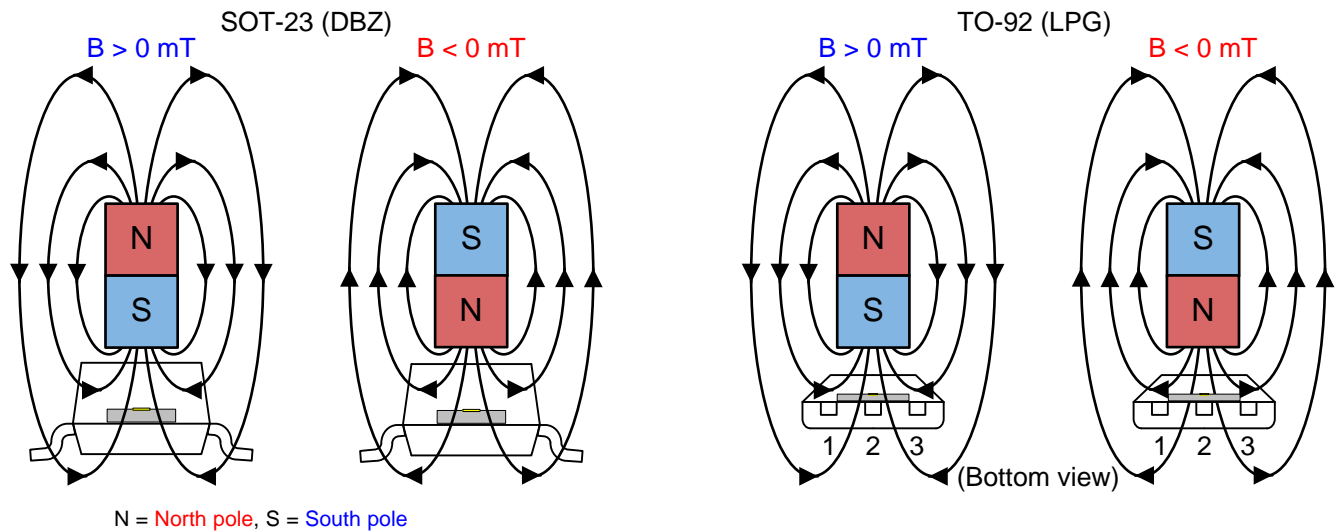


Figure 11. Field Direction Definition

7.3.2 Device Output

If the device is powered on with a magnetic field strength between B_{RP} and B_{OP} , then the device output is indeterminate and can either be Hi-Z or Low. If the field strength is greater than B_{OP} , then the output is pulled low. If the field strength is less than B_{RP} , then the output is released.

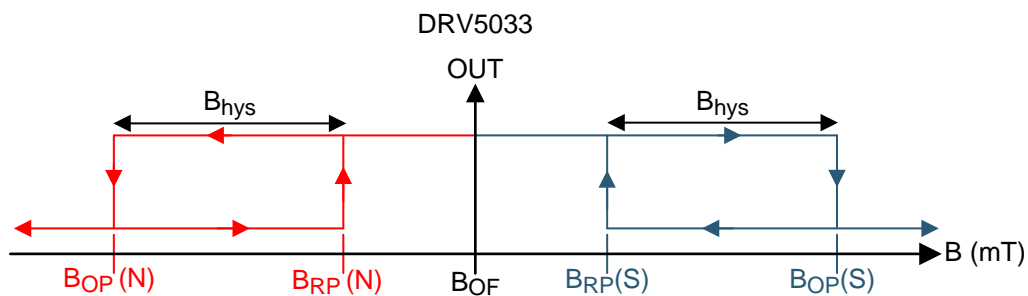


Figure 12. DRV5033— $B_{OP} > 0$

Feature Description (continued)

7.3.3 Power-On Time

After applying V_{CC} to the DRV5033 device, t_{on} must elapse before the OUT pin is valid. During the power-up sequence, the output is Hi-Z. A pulse as shown in Figure 13 and Figure 14 occurs at the end of t_{on} . This pulse can allow the host processor to determine when the DRV5033 output is valid after startup. In Case 1 (Figure 13) and Case 2 (Figure 14), the output is defined assuming a constant magnetic field $B > B_{OP}$ and $B < B_{RP}$.

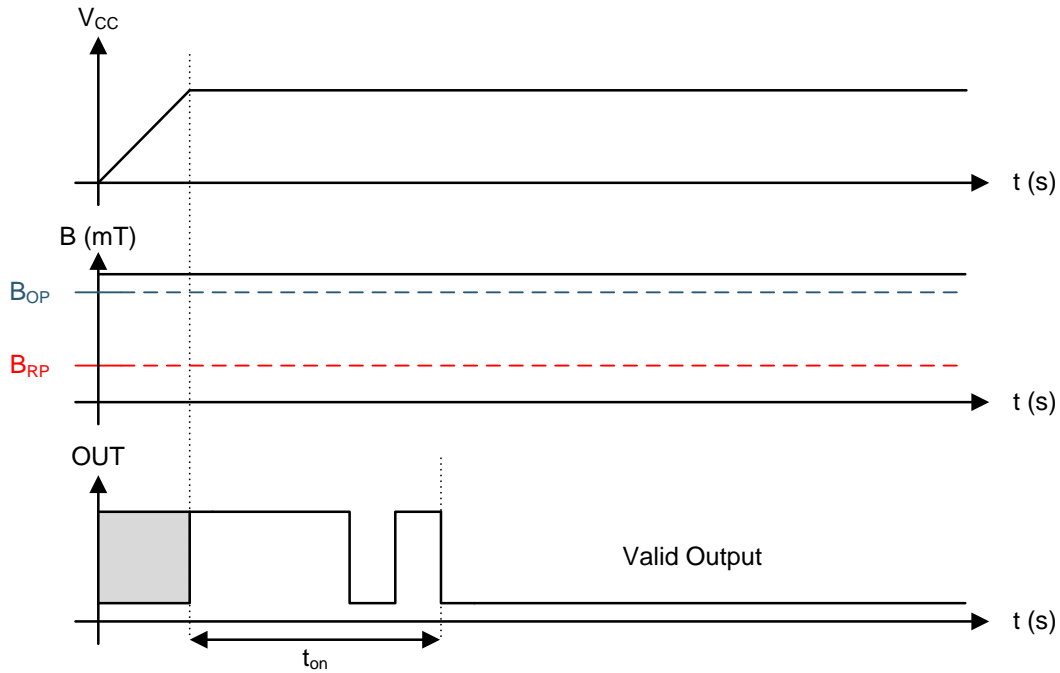


Figure 13. Case 1: Power On When $B > B_{OP}$

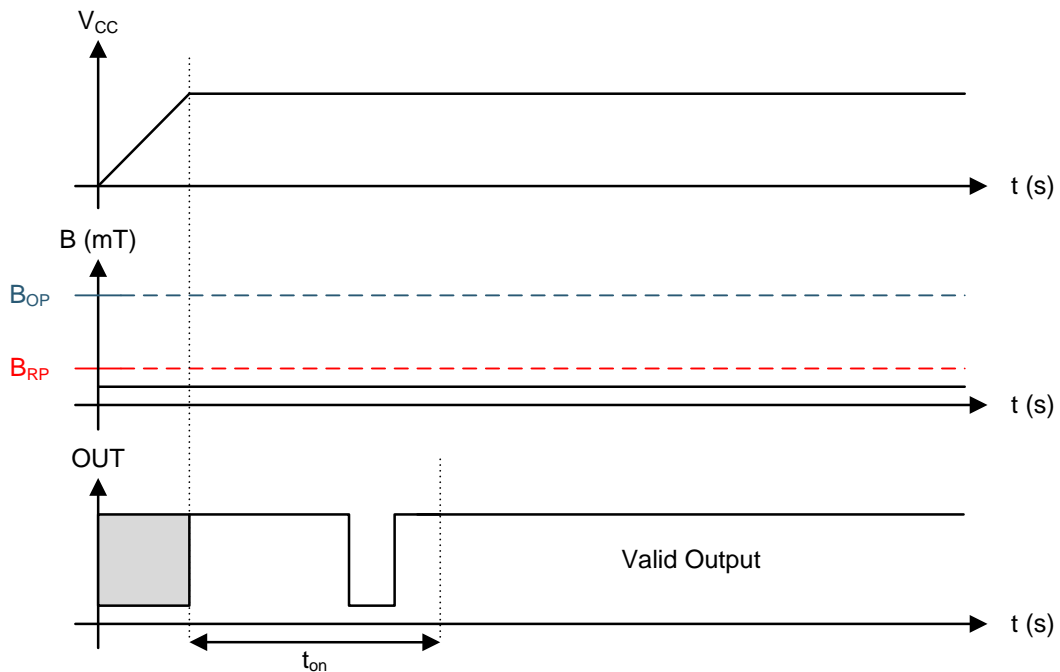


Figure 14. Case 2: Power On When $B < B_{RP}$

Feature Description (continued)

If the device is powered on with the magnetic field strength $B_{RP} < B < B_{OP}$, then the device output is indeterminate and can either be Hi-Z or pulled low. During the power-up sequence, the output is held Hi-Z until t_{on} has elapsed. At the end of t_{on} , a pulse is given on the OUT pin to indicate that t_{on} has elapsed. After t_{on} , if the magnetic field changes such that $B_{OP} < B$, the output is released. Case 3 (Figure 15) and Case 4 (Figure 16) show examples of this behavior.

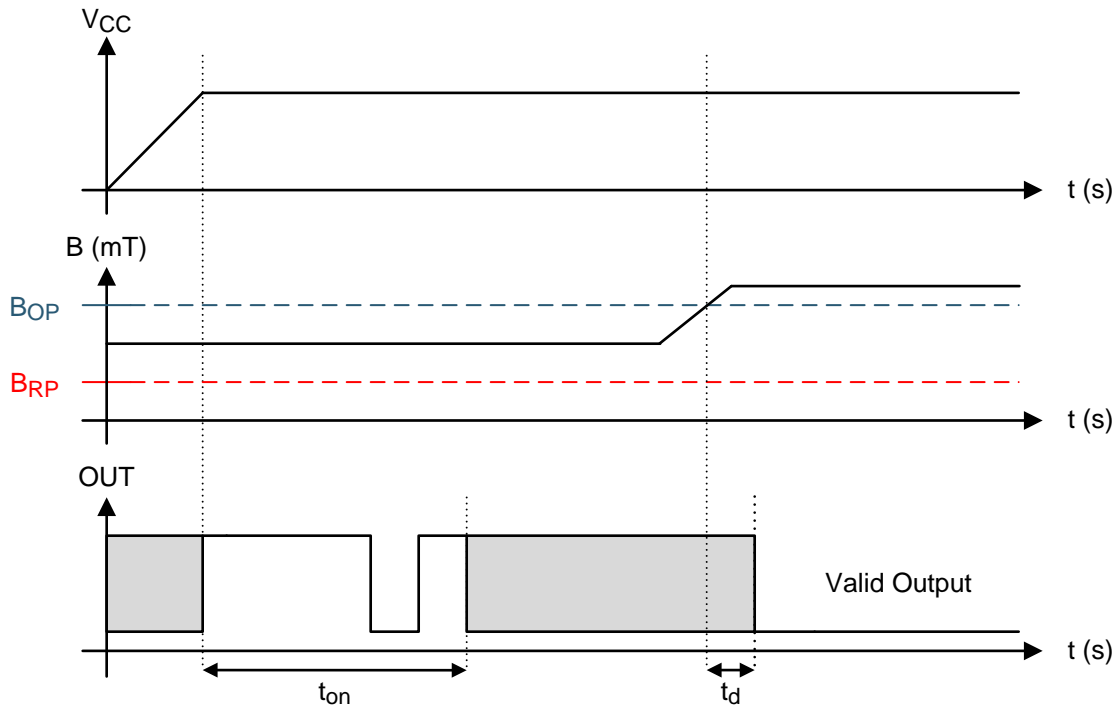


Figure 15. Case 3: Power On When $B_{RP} < B < B_{OP}$, Followed by $B > B_{OP}$

Feature Description (continued)

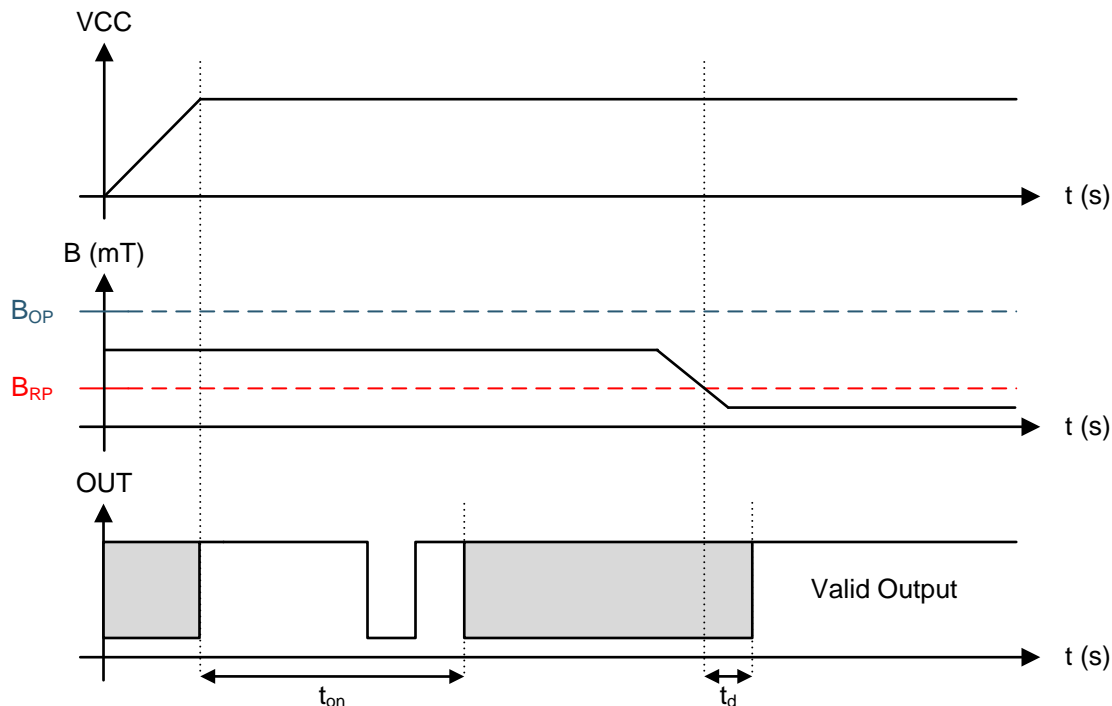


Figure 16. Case 4: Power On When B_{RP} < B < B_{OP}, Followed by B < B_{RP}

7.3.4 Output Stage

The DRV5033 output stage uses an open-drain NMOS, and it is rated to sink up to 30 mA of current. For proper operation, calculate the value of the pullup resistor R1 using Equation 1.

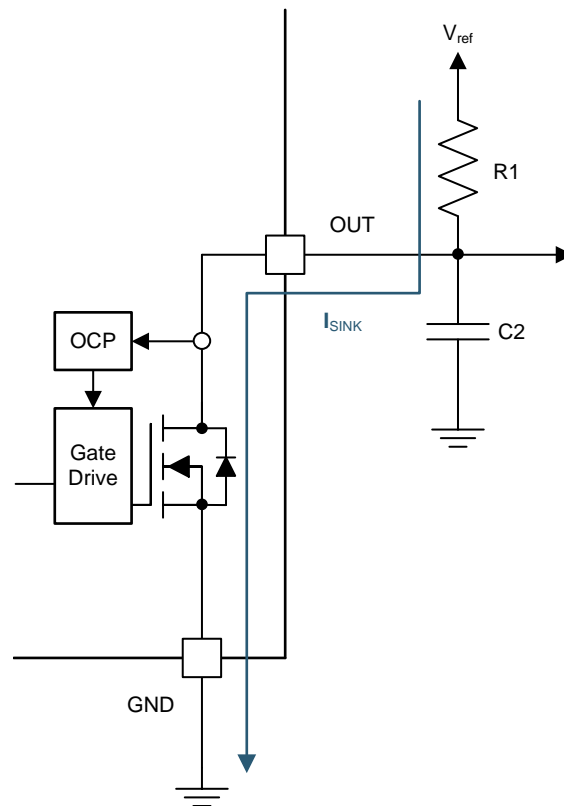
$$\frac{V_{ref \max}}{30 \text{ mA}} \leq R1 \leq \frac{V_{ref \min}}{100 \mu\text{A}} \tag{1}$$

The size of R1 is a tradeoff between the OUT rise time and the current when OUT is pulled low. A lower current is generally better, however faster transitions and bandwidth require a smaller resistor for faster switching.

In addition, ensure that the value of R1 > 500 Ω to ensure the output driver can pull the OUT pin close to GND.

NOTE

V_{ref} is not restricted to V_{CC}. The allowable voltage range of this pin is specified in the [Absolute Maximum Ratings](#).

Feature Description (continued)

Figure 17.

Select a value for C2 based on the system bandwidth specifications as shown in [Equation 2](#).

$$2 \times f_{BW} \text{ (Hz)} < \frac{1}{2\pi \times R1 \times C2} \quad (2)$$

Most applications do not require this C2 filtering capacitor.

Feature Description (continued)

7.3.5 Protection Circuits

The DRV5033 device is fully protected against overcurrent and reverse-supply conditions.

7.3.5.1 Overcurrent Protection (OCP)

An analog current-limit circuit limits the current through the FET. The driver current is clamped to I_{OCP} . During this clamping, the $r_{DS(on)}$ of the output FET is increased from the nominal value.

7.3.5.2 Load Dump Protection

The DRV5033 device operates at DC V_{CC} conditions up to 38 V nominally, and can additionally withstand $V_{CC} = 40$ V. No current-limiting series resistor is required for this protection.

7.3.5.3 Reverse Supply Protection

The DRV5033 device is protected in the event that the V_{CC} pin and the GND pin are reversed (up to -22 V).

NOTE

In a reverse supply condition, the OUT pin reverse-current must not exceed the ratings specified in the [Absolute Maximum Ratings](#).

Table 1.

| FAULT | CONDITION | DEVICE | DESCRIPTION | RECOVERY |
|--------------------|--------------------------------------|-----------|--|----------------------------|
| FET overload (OCP) | $I_{SINK} \geq I_{OCP}$ | Operating | Output current is clamped to I_{OCP} | $I_O < I_{OCP}$ |
| Load dump | $38\text{ V} < V_{CC} < 40\text{ V}$ | Operating | Device will operate for a transient duration | $V_{CC} \leq 38\text{ V}$ |
| Reverse supply | $-22\text{ V} < V_{CC} < 0\text{ V}$ | Disabled | Device will survive this condition | $V_{CC} \geq 2.5\text{ V}$ |

7.4 Device Functional Modes

The DRV5033 device is active only when V_{CC} is between 2.5 and 38 V.

When a reverse supply condition exists, the device is inactive.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The DRV5033 device is used in magnetic-field sensing applications.

8.2 Typical Applications

8.2.1 Standard Circuit

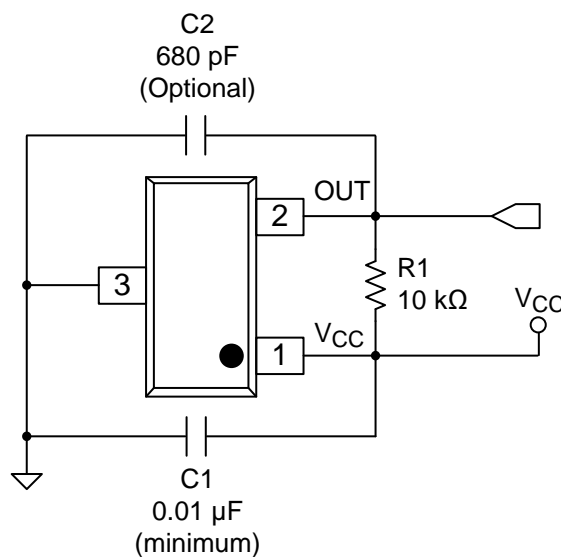


Figure 18. Typical Application Circuit

8.2.1.1 Design Requirements

For this design example, use the parameters listed in [Table 2](#) as the input parameters.

Table 2. Design Parameters

| DESIGN PARAMETER | REFERENCE | EXAMPLE VALUE |
|------------------|-----------|---------------|
| Supply voltage | V_{CC} | 3.2 to 3.4 V |
| System bandwidth | f_{BW} | 10 kHz |

8.2.1.2 Detailed Design Procedure

Table 3. External Components

| COMPONENT | PIN 1 | PIN 2 | RECOMMENDED |
|-----------|----------|--------------------|--|
| C1 | V_{CC} | GND | A 0.01- μ F (minimum) ceramic capacitor rated for V_{CC} |
| C2 | OUT | GND | Optional: Place a ceramic capacitor to GND |
| R1 | OUT | REF ⁽¹⁾ | Requires a resistor pullup |

(1) REF is not a pin on the DRV5033 device, but a REF supply-voltage pullup is required for the OUT pin; the OUT pin may be pulled up to V_{CC} .

8.2.1.2.1 Configuration Example

In a 3.3-V system, $3.2\text{ V} \leq V_{\text{ref}} \leq 3.4\text{ V}$. Use Equation 3 to calculate the allowable range for R1.

$$\frac{V_{\text{ref max}}}{30\text{ mA}} \leq R1 \leq \frac{V_{\text{ref min}}}{100\text{ }\mu\text{A}} \tag{3}$$

For this design example, use Equation 4 to calculate the allowable range of R1.

$$\frac{3.4\text{ V}}{30\text{ mA}} \leq R1 \leq \frac{3.2\text{ V}}{100\text{ }\mu\text{A}} \tag{4}$$

Therefore:

$$113\text{ }\Omega \leq R1 \leq 32\text{ k}\Omega \tag{5}$$

After finding the allowable range of R1 (Equation 5), select a value between 500 Ω and 32 k Ω for R1.

Assuming a system bandwidth of 10 kHz, use Equation 6 to calculate the value of C2.

$$2 \times f_{\text{BW}}\text{ (Hz)} < \frac{1}{2\pi \times R1 \times C2} \tag{6}$$

For this design example, use Equation 7 to calculate the value of C2.

$$2 \times 10\text{ kHz} < \frac{1}{2\pi \times R1 \times C2} \tag{7}$$

An R1 value of 10 k Ω and a C2 value less than 820 pF satisfy the requirement for a 10-kHz system bandwidth.

A selection of R1 = 10 k Ω and C2 = 680 pF would cause a low-pass filter with a corner frequency of 23.4 kHz.

8.2.1.3 Application Curves

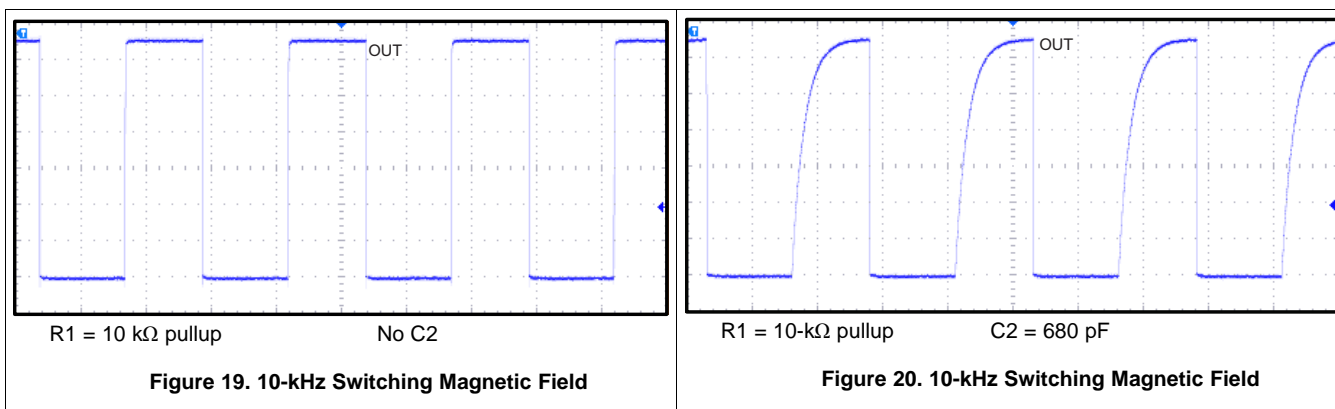


Figure 19. 10-kHz Switching Magnetic Field

Figure 20. 10-kHz Switching Magnetic Field

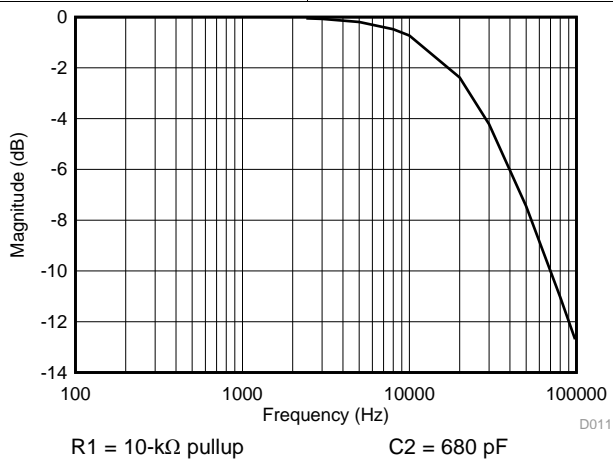


Figure 21. Low-Pass Filtering

8.2.2 Alternative Two-Wire Application

For systems that require minimal wire count, the device output can be connected to V_{CC} through a resistor, and the total supplied current can be sensed near the controller.

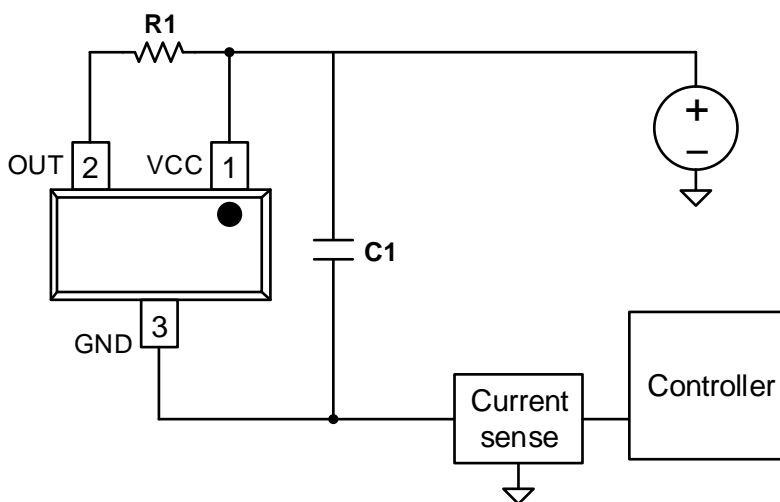


Figure 22. 2-Wire Application

Current can be sensed using a shunt resistor or other circuitry.

8.2.2.1 Design Requirements

Table 4 lists the related design parameters.

Table 4. Design Parameters

| DESIGN PARAMETER | REFERENCE | EXAMPLE VALUE |
|---------------------------|---------------|---------------|
| Supply voltage | V_{CC} | 12 V |
| OUT resistor | R1 | 1 k Ω |
| Bypass capacitor | C1 | 0.1 μ F |
| Current when $B < B_{RP}$ | $I_{RELEASE}$ | About 3 mA |
| Current when $B > B_{OP}$ | $I_{OPERATE}$ | About 15 mA |

8.2.2.2 Detailed Design Procedure

When the open-drain output of the device is high-impedance, current through the path equals the I_{CC} of the device (approximately 3 mA).

When the output pulls low, a parallel current path is added, equal to $V_{CC} / (R1 + r_{DS(on)})$. Using 12 V and 1 k Ω , the parallel current is approximately 12 mA, making the total current approximately 15 mA.

The local bypass capacitor C1 should be at least 0.1 μ F, and a larger value if there is high inductance in the power line interconnect.

9 Power Supply Recommendations

The DRV5033 device is designed to operate from an input voltage supply (V_M) range between 2.5 and 38 V. A 0.01- μ F (minimum) ceramic capacitor rated for V_{CC} must be placed as close to the DRV5033 device as possible.

10 Layout

10.1 Layout Guidelines

The bypass capacitor should be placed near the DRV5033 device for efficient power delivery with minimal inductance. The external pullup resistor should be placed near the microcontroller input to provide the most stable voltage at the input; alternatively, an integrated pullup resistor within the GPIO of the microcontroller can be used.

Generally, using PCB copper planes underneath the DRV5033 device has no effect on magnetic flux, and does not interfere with device performance. This is because copper is not a ferromagnetic material. However, if nearby system components contain iron or nickel, they may redirect magnetic flux in unpredictable ways.

10.2 Layout Example

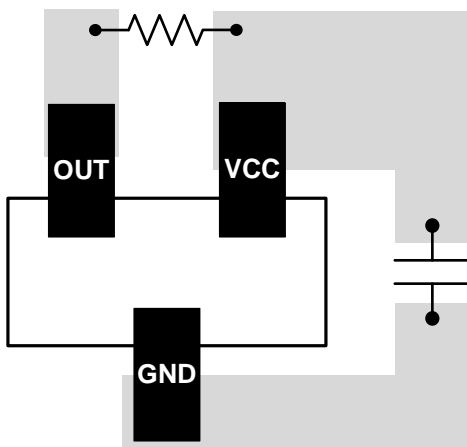


Figure 23. DRV5033 Layout Example

11 デバイスおよびドキュメントのサポート

11.1 デバイス・サポート

11.1.1 デバイスの項目表記

DRV5033のデバイス名の各部の読み方を図 24に示します。

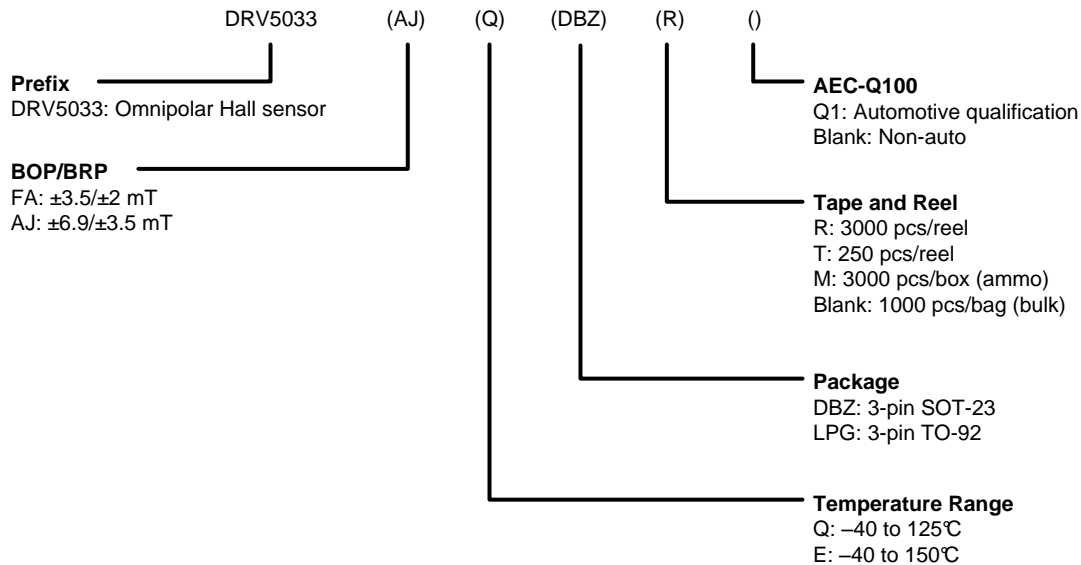


図 24. デバイスの項目表記

11.1.2 デバイスのマーキング

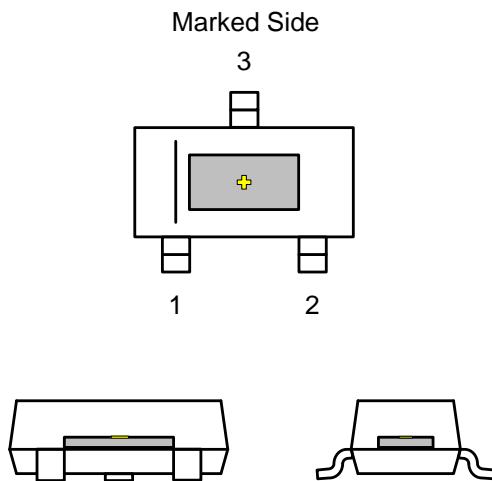


図 25. SOT-23 (DBZ)パッケージ

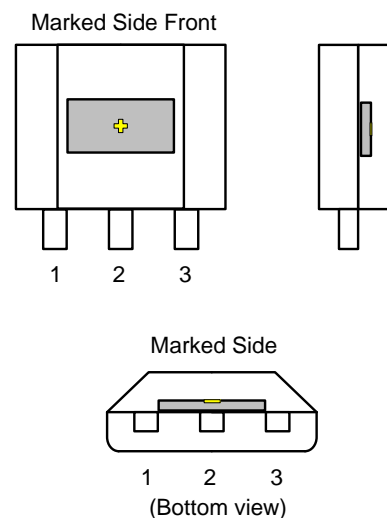


図 26. TO-92 (LPG)パッケージ

✦はホール効果センサを示します(実際の大きさに比例してはなりません)。ホール素子はパッケージの中心に、許容誤差 $\pm 100\mu\text{m}$ で配置されています。ホール素子の高さは、パッケージの底面から計測して、DBZパッケージでは $0.7\text{mm}\pm 50\mu\text{m}$ 、LPGパッケージでは $0.987\text{mm}\pm 50\mu\text{m}$ です。

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11.6 用語集

SLYZ022 — *TI用語集*.

この用語集には、用語や略語の一覧および定義が記載されています。

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PACKAGING INFORMATION

| Orderable part number | Status (1) | Material type (2) | Package Pins | Package qty Carrier | RoHS (3) | Lead finish/ Ball material (4) | MSL rating/ Peak reflow (5) | Op temp (°C) | Part marking (6) |
|--------------------------------|---------------|----------------------|------------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| DRV5033AJQDBZR | Active | Production | SOT-23 (DBZ) 3 | 3000 LARGE T&R | Yes | NIPDAUAG SN | Level-1-260C-UNLIM | -40 to 125 | (+QLAJ, 1J72) |
| DRV5033AJQDBZR.A | Active | Production | SOT-23 (DBZ) 3 | 3000 LARGE T&R | Yes | SN | Level-1-260C-UNLIM | -40 to 125 | (+QLAJ, 1J72) |
| DRV5033AJQLPG | Active | Production | TO-92 (LPG) 3 | 1000 BULK | Yes | SN | N/A for Pkg Type | -40 to 125 | +QLAJ |
| DRV5033AJQLPG.A | Active | Production | TO-92 (LPG) 3 | 1000 BULK | Yes | SN | N/A for Pkg Type | -40 to 125 | +QLAJ |
| DRV5033AJQLPGM | Active | Production | TO-92 (LPG) 3 | 3000 AMMO | Yes | SN | N/A for Pkg Type | -40 to 125 | +QLAJ |
| DRV5033AJQLPGM.A | Active | Production | TO-92 (LPG) 3 | 3000 AMMO | Yes | SN | N/A for Pkg Type | -40 to 125 | +QLAJ |
| DRV5033FAQDBZR | Active | Production | SOT-23 (DBZ) 3 | 3000 LARGE T&R | Yes | SN | Level-1-260C-UNLIM | -40 to 125 | (+QLFA, 1J8W) |
| DRV5033FAQDBZR.A | Active | Production | SOT-23 (DBZ) 3 | 3000 LARGE T&R | Yes | SN | Level-1-260C-UNLIM | -40 to 125 | (+QLFA, 1J8W) |

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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OTHER QUALIFIED VERSIONS OF DRV5033 :

- Automotive : [DRV5033-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|----------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| DRV5033AJQDBZR | SOT-23 | DBZ | 3 | 3000 | 178.0 | 9.0 | 3.15 | 2.77 | 1.22 | 4.0 | 8.0 | Q3 |
| DRV5033AJQDBZR | SOT-23 | DBZ | 3 | 3000 | 180.0 | 8.4 | 3.2 | 2.85 | 1.3 | 4.0 | 8.0 | Q3 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 180.0 | 8.4 | 3.15 | 2.77 | 1.22 | 4.0 | 8.0 | Q3 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 178.0 | 9.0 | 3.15 | 2.77 | 1.22 | 4.0 | 8.0 | Q3 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 180.0 | 8.4 | 3.2 | 2.85 | 1.3 | 4.0 | 8.0 | Q3 |

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

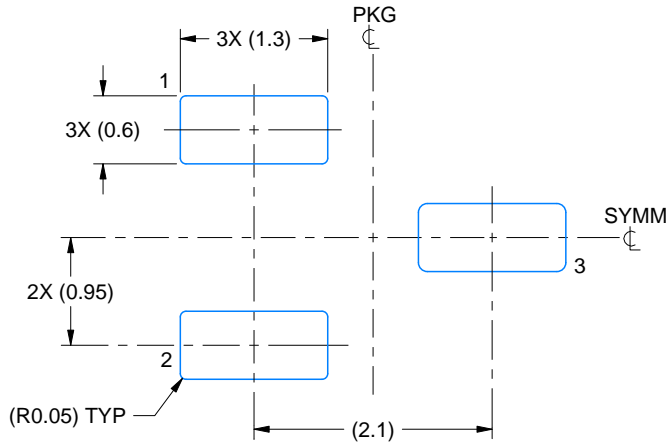
| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| DRV5033AJQDBZR | SOT-23 | DBZ | 3 | 3000 | 180.0 | 180.0 | 18.0 |
| DRV5033AJQDBZR | SOT-23 | DBZ | 3 | 3000 | 210.0 | 185.0 | 35.0 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 202.0 | 201.0 | 28.0 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 180.0 | 180.0 | 18.0 |
| DRV5033FAQDBZR | SOT-23 | DBZ | 3 | 3000 | 210.0 | 185.0 | 35.0 |

EXAMPLE BOARD LAYOUT

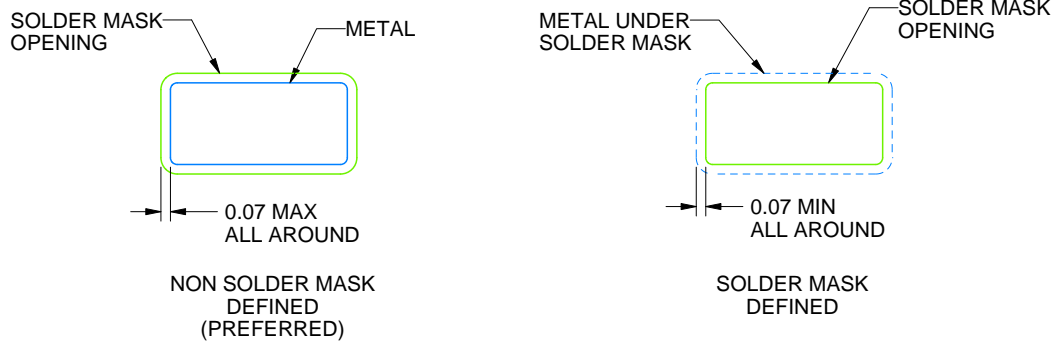
DBZ0003A

SOT-23 - 1.12 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE
SCALE:15X



SOLDER MASK DETAILS

4214838/F 08/2024

NOTES: (continued)

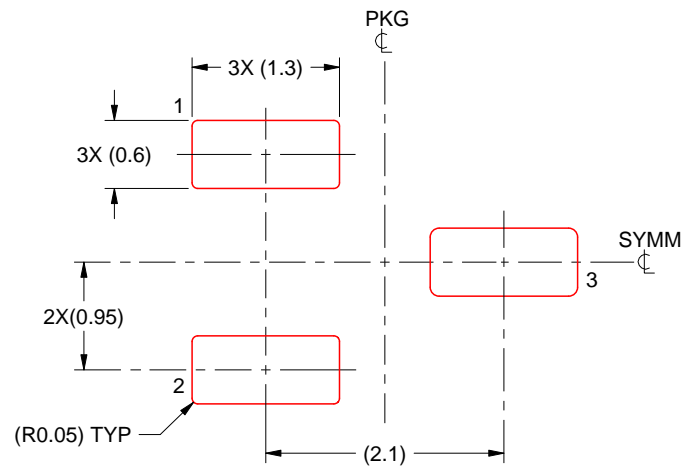
5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DBZ0003A

SOT-23 - 1.12 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE
BASED ON 0.125 THICK STENCIL
SCALE:15X

4214838/F 08/2024

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
8. Board assembly site may have different recommendations for stencil design.

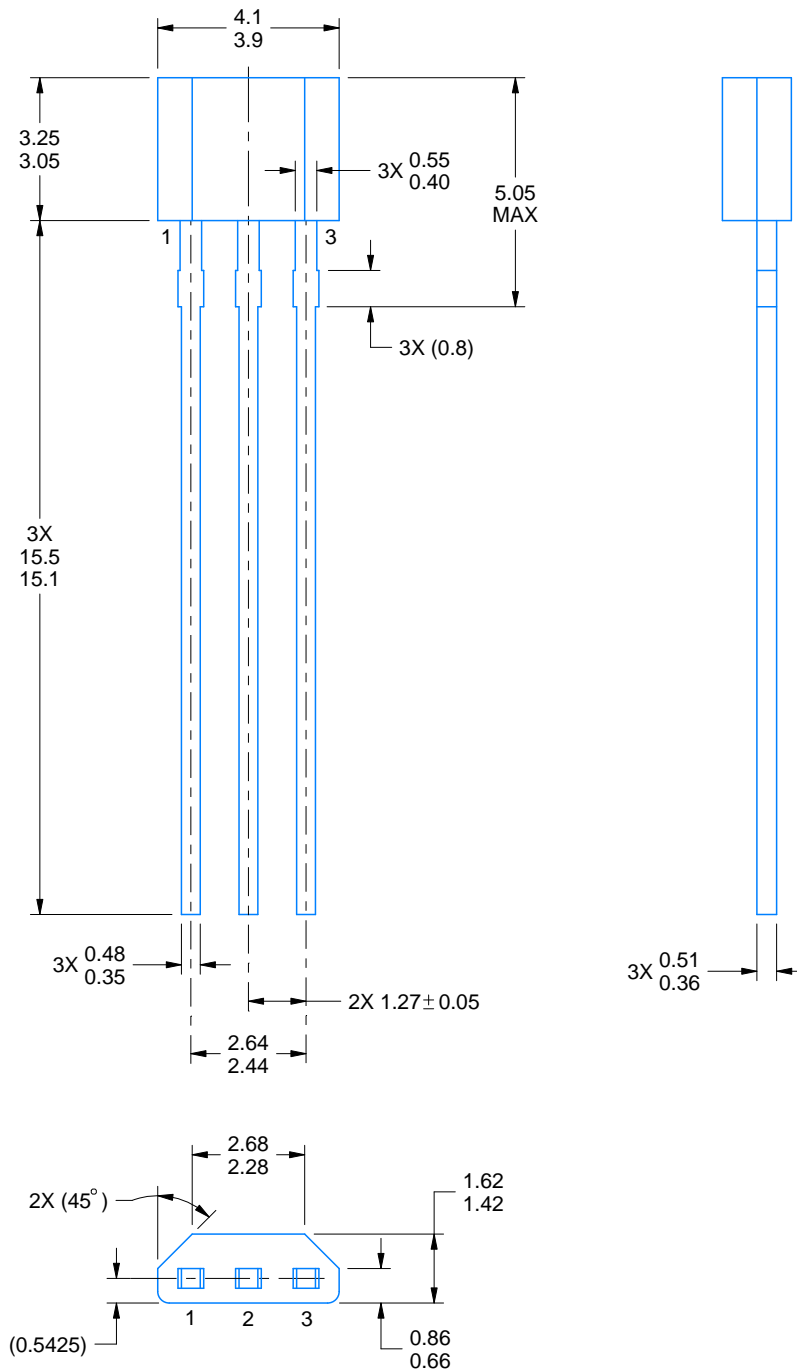
LPG0003A



PACKAGE OUTLINE

TO-92 - 5.05 mm max height

TRANSISTOR OUTLINE



4221343/C 01/2018

NOTES:

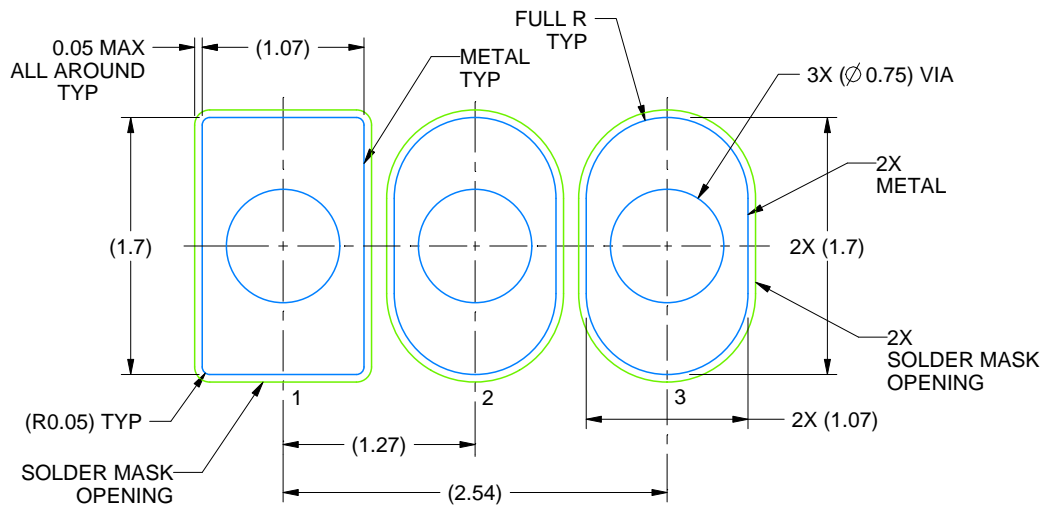
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

LPG0003A

TO-92 - 5.05 mm max height

TRANSISTOR OUTLINE



LAND PATTERN EXAMPLE
NON-SOLDER MASK DEFINED
SCALE:20X

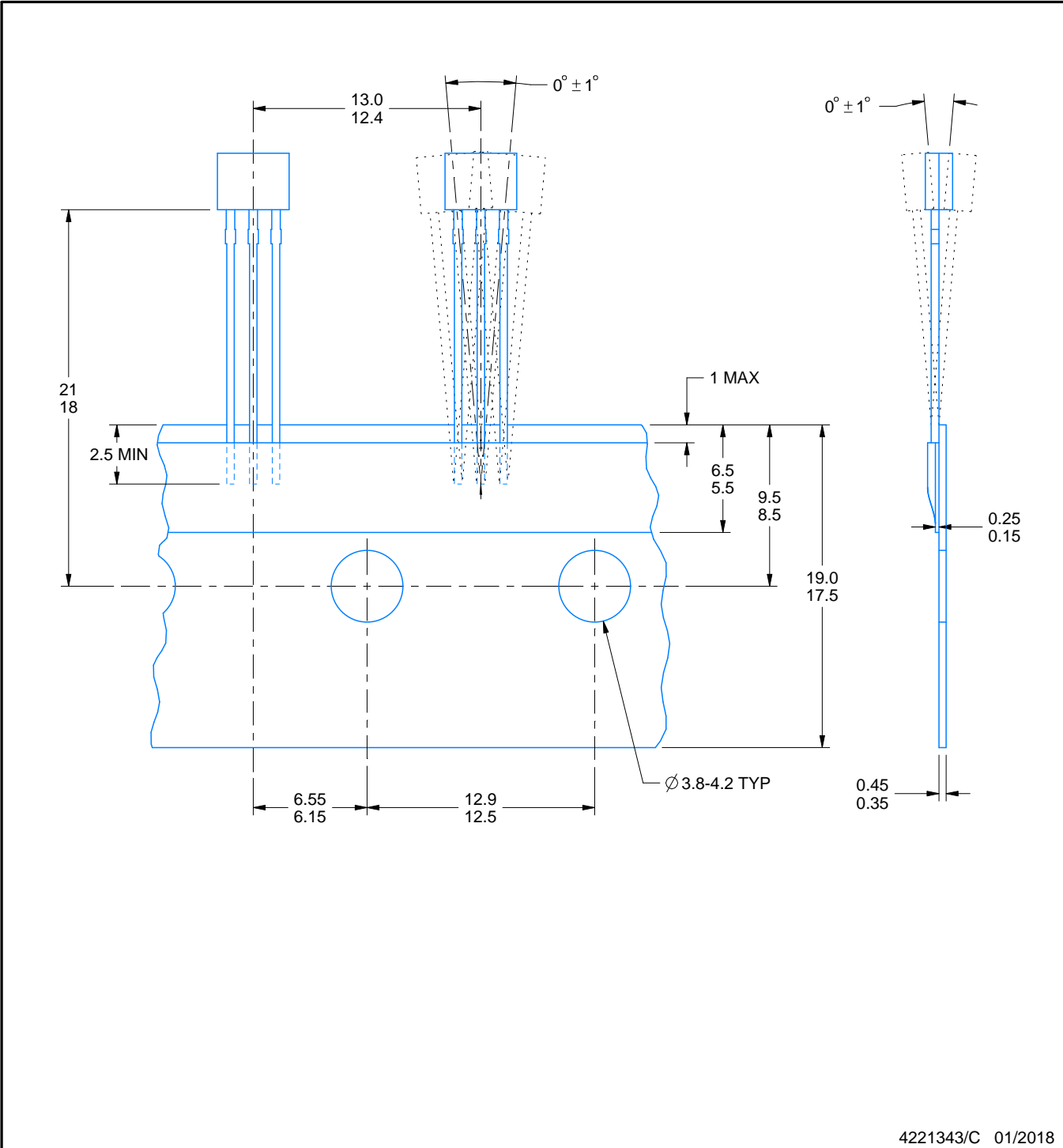
4221343/C 01/2018

TAPE SPECIFICATIONS

LPG0003A

TO-92 - 5.05 mm max height

TRANSISTOR OUTLINE



4221343/C 01/2018

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最終更新日 : 2025 年 10 月