







RES11A-Q1

JAJSRL2A - OCTOBER 2023 - REVISED DECEMBER 2023

# RES11A-Q1 車載用、マッチング済み、薄膜分割抵抗、1kΩ 入力

# 1 特長

- 車載アプリケーション向けに AEC-Q200 認定済み:
  - 温度:-40°C~+125°C
- 高比率マッチング精度:±0.05%(最大値)
- 低いドリフト:±2ppm/°C TCR (最大値)

# 2 アプリケーション

- 高精度電圧分割器、高精度レベル変換
- ゲインおよび減衰アンプ
- CMRR の高い差動アンプ
- ゲイン精度の高いディスクリート計測アンプ
- ゲイン精度の高い完全差動アンプ
- ピンポイントのコンパレータ・スレッショルド設定

# 3 概要

RES11A-Q1は、マッチングされた抵抗分割器のペアで、 テキサス・インスツルメンツの最新の高性能アナログ CMOS プロセスで薄膜 SiCr に実装されています。このデ バイスは、熱および電流ノイズを低減するための公称入力 抵抗が 1kΩ であり、幅広いシステムの要求を満たすた め、いくつかの公称比率で供給されます。RES11A-Q1 は、デバイスの配置を 180° 回転させるだけで、ゲインを 反転した構成で使用できます。この機能により、レイアウト の再利用がサポートされ、ディスクリート計測機器や差動 アンプの実装などのアプリケーションで柔軟性が向上しま す。

RES11A-Q1 シリーズは高い比率マッチング精度を特長と しており、各分割器の測定比率は公称値の ±120 ppm (標準値) 以内です。この精度は温度範囲全体にわたって 維持され、最大比ドリフトはわずか ± 2ppm/℃です。さら に、デバイスのバイアスされた長期安定性は、徹底的な特 性評価によって証明されています。

RES11A-Q1 は、AEC-Q200 温度グレード 1 の車載認定 済みです。-40°C~+125°Cの温度範囲で動作が規定さ れています。このデバイスは8ピンのSOT-23-THINパッ ケージで供給され、本体サイズは 2.9mm × 1.6mm です (本体サイズは公称値であり、ピンは含まれていません)。

# パッケージ情報

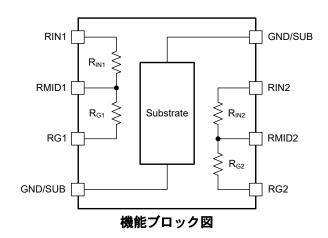
部品番号	パッケージ <sup>(1)</sup>	パッケージ サイズ <sup>(2)</sup>
RES11A-Q1	DDF (SOT-23-THIN, 8)	2.9mm × 2.8mm

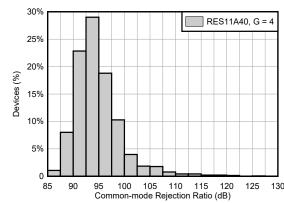
- 詳細については、セクション 11 を参照してください。 (1)
- パッケージ サイズ (長さ×幅) は公称値であり、該当する場合はピ ンも含まれます。

# 制口柱机

部品番号	公称比
RES11A10-Q1	1:1
RES11A15-Q1 (1)	1:1.5
RES11A16-Q1 (1)	1:1.667
RES11A20-Q1 (1)	1:2
RES11A25-Q1 (1)	1:2.5
RES11A30-Q1 (1)	1:3
RES11A40-Q1	1:4
RES11A50-Q1 (1)	1:5
RES11A90-Q1	1:9
RES11A00-Q1	1:10

(1) プレビュー情報 (事前情報ではありません)。





最高の CMRR を実現する優れた比率マッチング



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# **4 Pin Configuration and Functions**

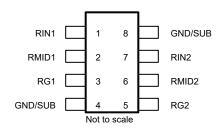


図 4-1. DDF Package, 8-Pin SOT-23-THN (Top View)

表 4-1. Pin Functions

PIN		TYPE	DESCRIPTION			
NAME	NO.	1176	DESCRIPTION			
(GNI)/SUB   4.8   Ground		Substrate bias connection. Only bias one GND/SUB pin. Float the other GND/SUB pin to prevent current return paths from forming through the substrate. See also セクション 7.4.				
RG1 3 Input		Input	Gain resistor connection for divider 1			
RG2	5	Input	Gain resistor connection for divider 2			
RIN1	1	Input	Input resistor connection for divider 1			
RIN2	7	Input	Input resistor connection for divider 2			
RMID1	2	Output	Center tap of divider 1			
RMID2 6 Output		Output	Center tap of divider 2			



# **5 Specifications**

# **5.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)(1)

			MIN	MAX	UNIT
V <sub>CM</sub>	Maximum common mode voltage (any pin to	o GND/SUB)		±135	V
	Maximum instantaneous overload voltage per divider (RINx pin to RGx pin) (2)	RES11A10		±77.0	
		RES11A15		±64.2	
		RES11A16		±63.0	
		RES11A20		±57.8	
437		RES11A25		±89.9	V
$\Delta V_{DMAX}$		RES11A30		±102.7	
		RES11A40		±96.3	
		RES11A50		±94.6	
		RES11A90		±128.4	
		RES11A00		±135	
T <sub>A</sub>	Ambient temperature		-55	150	°C
TJ	Junction temperature		-55	150	°C
T <sub>stg</sub>	Storage temperature		-55	175	°C

<sup>(1)</sup> Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 5.2 ESD Ratings

			VALUE	UNIT
V.===>	Electrostatic discharge	Human body model (HBM), per AEC Q100-002 <sup>(1)</sup>	±1200	V
V <sub>(ESD)</sub>	Liectrostatic discharge	Charged device model (CDM), per AEC Q100-011	±2000	v

(1) AEC Q100-002 indicates that HBM stressing must be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

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Product Folder Links: RES11A-Q1

<sup>(2)</sup> Maximum instantaneous voltage permitted under transient conditions. Avoid sustained operation at these voltage levels because the resulting self-heating causes T<sub>J</sub> to exceed 150°C.



# **5.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Maximum common-mode voltage (any pin to	GND/SUB)			±120	V
	RES11A10		±8.93	±12.2	
	RES11A15		±8.93	±12.2	
	RES11A16		±8.93	±12.5	mA
	RES11A20		±8.93	±12.2	
Maximum sustained current through R <sub>INx</sub> (RIN	RES11A25		±7.44	±10.2	
pin to RMIDx pin, 10 years at $T_A = 25^{\circ}\text{C})^{(1)}$	RES11A30		±8.93	±12.2	
A 7	RES11A40		±8.93	±12.2	
	RES11A50		±8.93	±12.5	
	RES11A90		±8.93	±12.2	
	RES11A00		±7.44	±10.2	
	RES11A10		±8.93	±12.2	
	RES11A15		±5.95	±8.14	
	RES11A16		±5.36	±7.49	
	RES11A20		±4.47	±6.11	
Maximum sustained current through R <sub>Gx</sub> (RG)	RES11A25		±5.95	±8.14	4
pin to RMIDx pin, 10 years at $T_A = 25^{\circ}\text{C})^{(1)}$	RES11A30		±5.95	±8.14	mA
	RES11A40		±4.47	±6.11	
	RES11A50		±3.57	±5.00	
	RES11A90		±2.98	±4.07	
	RES11A00		±2.98	±4.07	
Ambient temperature	1	-40		125	°C

<sup>(1)</sup> Assumes R<sub>0JA</sub> = 156.2 °C/W. Applies whether the specified current is applied across a single divider, or both dividers simultaneously. For long-term use under static dc biases, keep the current less than or equal to the nominal value. For long-term use under dynamic conditions, keep the RMS current less than or equal to the maximum value. Adhere to the limitations in Absolute Maximum Ratings.

# **5.4 Thermal Information**

		RES11A-Q1	
	THERMAL METRIC <sup>(1)</sup>	DDF (SOT-23-THIN)	UNIT
		8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	156.2	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	77.0	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	73.7	°C/W
ΨЈТ	Junction-to-top characterization parameter	4.5	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	73.5	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

English Data Sheet: SLPS755



# 5.5 Electrical Characteristics

at T<sub>A</sub> = 25°C (unless otherwise noted)

at T <sub>A</sub> = 25°C (unless otherwise noted)  PARAMETER  TEST CONDITIONS  MIN		MIN TYP	MAX	UNIT		
INITIAL	RESISTANCE					
		RES11A10		1		
		RES11A15		1.5		
		RES11A16		1.667		
		RES11A20		2		
_	N : 1 :: 45 45 X	RES11A25		2.5		
$G_{nom}$	Nominal ratio (R <sub>Gx</sub> / R <sub>INx</sub> )	RES11A30		3		V/V
		RES11A40		4		
		RES11A50		5		
		RES11A90		9		
		RES11A00		10		
			RES11A10		±500	
			RES11A15		±500	
			RES11A16		±500	
			RES11A20		±500	
t <sub>D1</sub>	Ratio tolerance of divider 1 <sup>(1)</sup>	(R <sub>G1</sub> / R <sub>IN1</sub> ) / G <sub>nom</sub> – 1	RES11A25		±500	ppm
			RES11A30		±500	
			RES11A40	±120	±500	
			RES11A50		±500	
			RES11A90		±500	
			RES11A00		±500	
			RES11A10		±500	
			RES11A15		±500	
			RES11A16		±500	
			RES11A20		±500	
	Voltage-divider circuit tolerance of	(1 + G <sub>nom</sub> ) × (R <sub>IN1</sub> / (R <sub>IN1</sub> + R <sub>G1</sub> )) – 1	RES11A25		±500	
	divider 1		RES11A30		±500	ppm
			RES11A40	±100	±500	
			RES11A50		±500	
			RES11A90		±500	
			RES11A00		±500	
			RES11A10		±500	
			RES11A15		±500	
			RES11A16		±500	
			RES11A20		±500	
	Datio telerance of divider 2 (1)	(D	RES11A25		±500	
D2	Ratio tolerance of divider 2 <sup>(1)</sup>	(R <sub>G2</sub> / R <sub>IN2</sub> ) / G <sub>nom</sub> – 1	RES11A30		±500	ppm
			RES11A40	±120	±500	
			RES11A50		±500	
			RES11A90		±500	
			RES11A00		±500	



# 5.5 Electrical Characteristics (続き)

at  $T_A = 25^{\circ}C$  (unless otherwise noted)

	PARAMETER	TEST CON	IDITIONS	MIN TYP	MAX	UNIT	
			RES11A10		±500		
			RES11A15		±500		
			RES11A16		±500		
			RES11A20		±500		
	Voltage-divider circuit tolerance of	(1 + G <sub>nom</sub> ) ×	RES11A25		±500		
	divider 2	(R <sub>IN2</sub> / (R <sub>IN2</sub> + R <sub>G2</sub> )) – 1	RES11A30		±500	ppm	
			RES11A40	±100	±500		
			RES11A50		±500		
			RES11A90		±500		
			RES11A00		±500		
			RES11A10		±1000		
			RES11A15		±1000		
			RES11A16		±1000		
			RES11A20		±1000		
	Matching tolerance of dividers 1		RES11A25		±1000	- ppm -	
t <sub>M</sub>	and 2	$t_{D2}-t_{D1}$	RES11A30		±1000		
			RES11A40	±85	±1000		
			RES11A50		±1000		
			RES11A90		±1000		
			RES11A00		±1000		
t <sub>abs</sub>	Absolute tolerance (per resistor)	$(R_x / R_{xnom}) - 1$ (3)	'	±2	±12	%	
	Absolute tolerance span	MAX (t <sub>absRIN1</sub> , t <sub>absRG1</sub> , t <sub>abs</sub> MIN (t <sub>absRIN1</sub> , t <sub>absRG1</sub> , t <sub>abs</sub>	sRIN2, t <sub>abs</sub> RG2) – RIN2, t <sub>abs</sub> RG2)	±235		ppm	
RESISTA	ANCE DRIFT						
	Absolute temperature coefficient of resistance (per resistor) (4)	(ΔR <sub>x</sub> / R <sub>x(25°C)</sub> ) / ΔT <sub>A</sub>	T <sub>A</sub> = -40C to +125°C	±18		ppm/°C	
	Divider temperature coefficient of resistance (per divider) (4)	Δt <sub>Dx</sub> / ΔT <sub>A</sub>	T <sub>A</sub> = -40C to +125°C	-0.2	±2	ppm/°C	
TCR	Matching temperature coefficient of resistance <sup>(4)</sup>	$\Delta t_{M} / \Delta T_{A}$	T <sub>A</sub> = -40C to +125°C	±0.05		ppm/°C	
	Absolute voltage coefficient of	ΔR <sub>INx</sub> / ΔV <sub>RINx</sub>	V <sub>RINx</sub> = 0 V to V <sub>RINx</sub> = 40 V	±0.02		01/	
	resistance (per resistor) <sup>(2) (4)</sup>	$\Delta R_{Gx} / (\Delta V_{RGx} \times G_{nom})$	V <sub>RGx</sub> = 0 V to V <sub>RGx</sub> = 40 V	±0.02		Ω/V	
	Divider voltage coefficient of resistance (per divider) (4)	$\Delta t_{Dx}$ / $\Delta V_{Dx}$	V <sub>Dx</sub> = 0 V to V <sub>Dx</sub> = 40 V	±2		ppm/V	
VCR	Matching voltage coefficient of resistance (4)	$(\Delta t_{D2} - \Delta t_{D1}) / \Delta V_{Dx}$	V <sub>Dx</sub> = 0 V to V <sub>Dx</sub> = 40 V	±0.5		ppm/V	
IMPEDA	NCE		,				
		RINx to GND/SUB		2.2			
C <sub>IN</sub>	Pin capacitance (4)	RGx to GND/SUB		1.6		pF	
MPEDA		RMIDx to GND/SUB		3.3		۳'	

English Data Sheet: SLPS755



# 5.5 Electrical Characteristics (続き)

at T<sub>A</sub> = 25°C (unless otherwise noted)

	PARAMETER	TEST CON	DITIONS	MIN	TYP	MAX	UNIT
		Substrate biased to GND	f = 10 kHz		-100		
	Crosstalk (RMID1 to RMID2) (4)	Substrate plased to GND	f = 1 MHz		-64		dB
	Clossiaik (INIVIID I to INIVIID2)	Substrate floating	f = 10 kHz		-98		uБ
		f	f = 1 MHz		-56		
	–3-dB bandwidth <sup>(4)</sup>	Substrate biased to GND			35		MHz
	-3-ub bandwidth V	Substrate floating			40		IVII IZ
		RES11A10		66.0			
		RES11A15		68.0			
		RES11A16		68.5			
		RES11A20		69.5			
CMDD	Common-mode rejection ratio (5)	RES11A25		70.9			dB
CMRR	Common-mode rejection ratio (%)	RES11A30		72.0			uБ
		RES11A40		74.0	95.4		
		RES11A50		75.6			
		RES11A90		80.0			
		RES11A00		80.8			

- (1) Relation of  $R_{G1}$  /  $R_{IN1}$  or  $R_{G2}$  /  $R_{IN2}$  to nominal ratio.
- (2) Relation of  $R_{G1}$ ,  $R_{IN1}$ ,  $R_{G2}$ , or  $R_{IN2}$  to nominal resistance.
- (3) The specification is the result of this expression, given as a percentage (multiplied by 100%).
- (4) Specified by characterization.
- The specification is the calculated CMRR when implemented in a difference amplifier configuration with an ideal op-amp, such that the only source of common-mode error is the resistor network. See the Optimizing CMRR in Differential Amplifier Circuits With Precision Matched Resistor Divider Pairs application note for more information. Effects over frequency are not included. If the circuit is configured in an attenuating gain, this result changes accordingly.

# 5.6 AEC-Q200 Qualification Testing

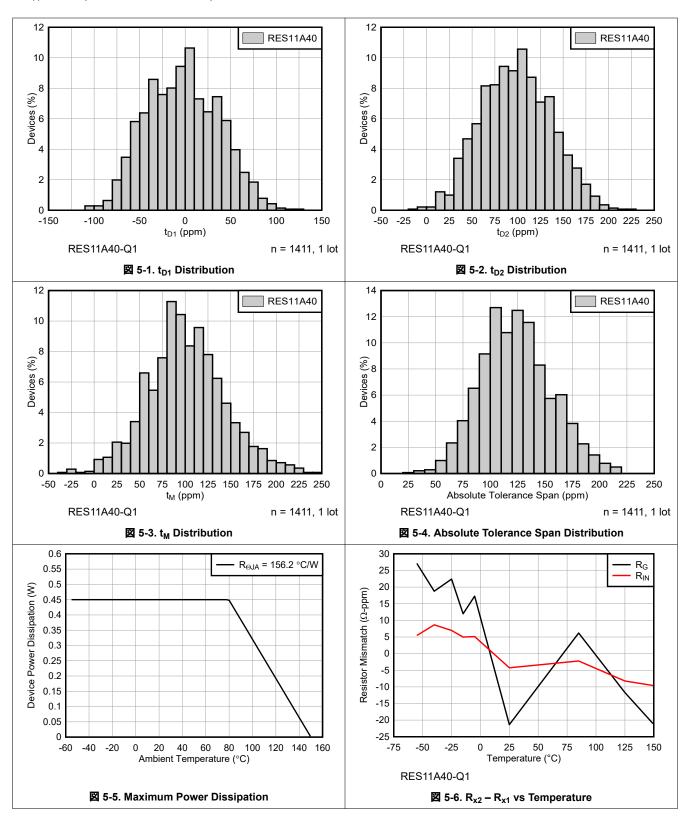
at T<sub>A</sub> = 25°C (unless otherwise noted). Compliance is specified by design and/or characterization.

PARAMETER	TEST CONDITIONS	MIN TYP MA	X UNIT
ENVIRONMENTAL TEST RATINGS			
High temperature exposure (storage)	MIL-STD-202 Method 108	PASS	
Temperature cycling	JESD22-A104	PASS	
Humidity bias	MIL-STD-202 Method 103	PASS	
High temperature operating life	MIL-STD-202 Method 108	PASS	
Mechanical shock	MIL-STD-202, Method 213	PASS	
Vibration	MIL-STD-202, Method 204	PASS	
Resistance to soldering heat	MIL-STD-202, Method 210	PASS	
Solderability	J-STD-002	PASS	
Flammability	UL-94	PASS	
Flame retardance	AEC-Q200-01	PASS	

資料に関するフィードバック(ご意見やお問い合わせ) を送信

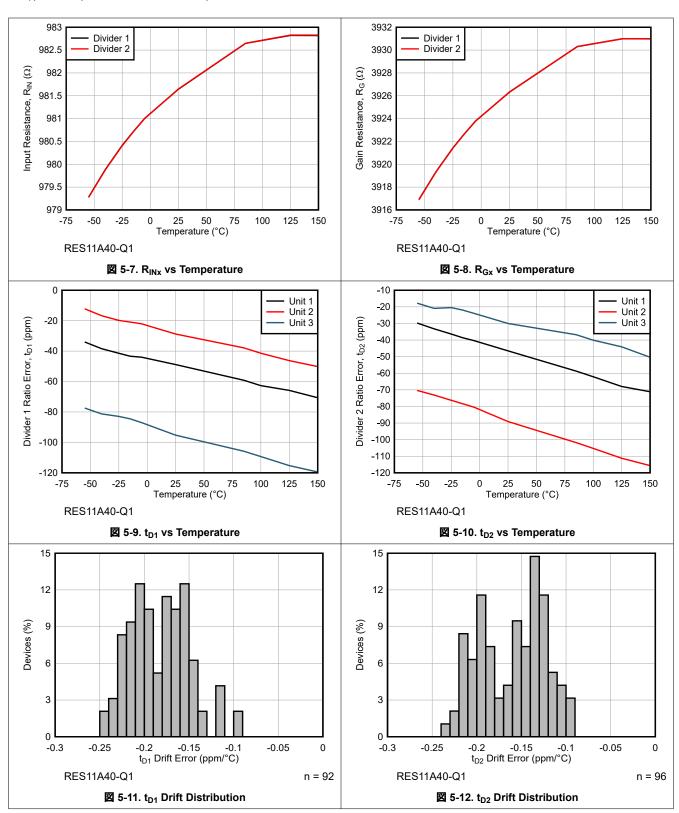


# **5.7 Typical Characteristics**



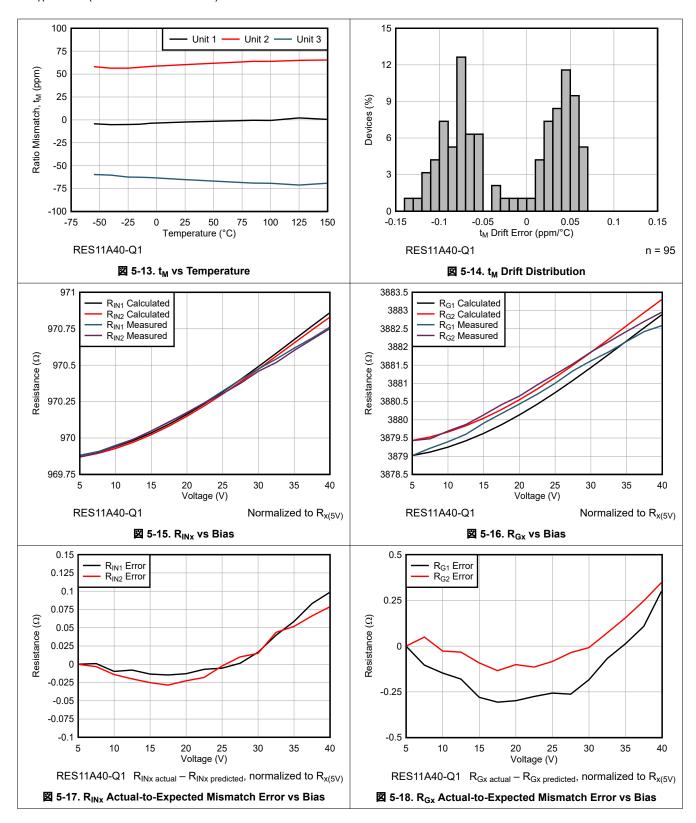


# 5.7 Typical Characteristics (continued)



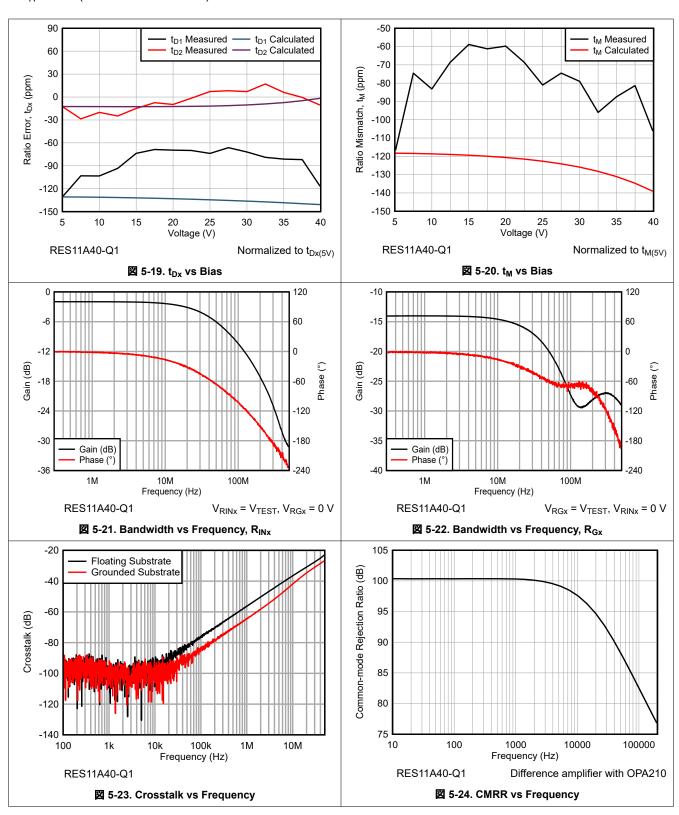


# 5.7 Typical Characteristics (continued)





# 5.7 Typical Characteristics (continued)





### **6 Parameter Measurement Information**

# **6.1 DC Measurement Configurations**

An example of the circuit configuration used for dc measurements is shown in  $\boxtimes$  6-1. Voltage  $V_{Dx}$  refers to the voltage across a given divider, such as  $V_{D1}$  for divider 1. Voltage  $V_{Rx}$  refers to the voltage across a given resistor, such as  $V_{RIN1}$  for  $R_{IN1}$  for

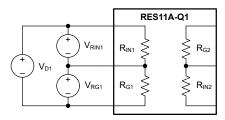


図 6-1. DC Measurement Terminology for Divider 1

When the RES11A-Q1 is used to set the gain of an op amp (shown in  $\boxtimes$  6-2), the ratio of the resistors in a divider sets the amplifier gain according to  $G = R_G / R_{IN}$ . Discrete-difference-amplifier and instrumentation-amplifier circuits are variations on this ratiometric use case. Typical and maximum parameter values for ratio tolerance  $(t_{D1}, t_{D2})$  are expressed in terms of  $R_{Gx} / R_{INx}$  to simplify calculations for these circuits.

However, another valid use case of the RES11A-Q1 is a simple voltage divider, where the midpoint voltage  $V_{MID}$  is equal to the input voltage  $V_D$  multiplied by  $R_G$  / ( $R_{IN}$  +  $R_G$ ), or by  $R_{IN}$  / ( $R_{IN}$  +  $R_G$ ) as shown in  $\boxtimes$  6-3. Typical and maximum parameter values for ratio tolerance of these voltage-divider circuits, expressed in terms of  $R_{INx}$  / ( $R_{INx}$  +  $R_{Gx}$ ), are provided.

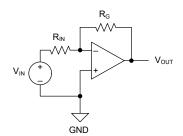


図 6-2. Amplifier Gain Circuit

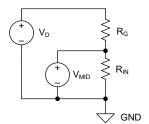


図 6-3. Voltage-divider circuit

図 6-4 shows the circuit configuration used for CMRR calculations. For an ideal amplifier with no offset and infinite CMRR, the effective circuit CMRR is entirely a function of the matching of the resistors. See セクション 8.1.1.1 and the *Optimizing CMRR in Differential Amplifier Circuits With Precision Matched Resistor Divider Pairs* application note for more information.



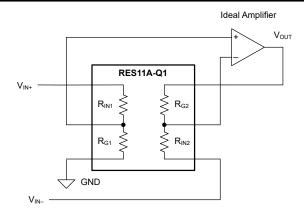


図 6-4. CMRR Calculation Reference Schematic

# **6.2 AC Measurement Configurations**

 $\boxtimes$  6-5 shows the circuit configuration used for capacitance measurements. For the RES11A-Q1, a 1-MΩ R<sub>KNOWN</sub> resistance and 10-pF C<sub>KNOWN</sub> capacitance are used. The circuit creates an impedance divider; the resulting gain-vs-frequency relationship is used to calculate the parasitic capacitance in parallel with the resistor under test (in this case, R<sub>IN1</sub>). Calibration with an empty socket is performed to account for board parasitics. The ac source is swept from 100 Hz to 50 MHz.

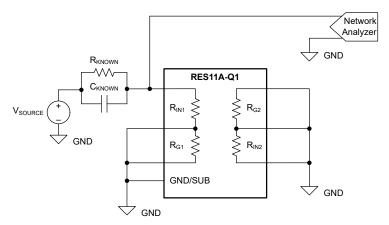


図 6-5. Capacitance Measurement Reference Schematic

☑ 6-6 shows the circuit configuration that is used for bandwidth measurements. The ac source is swept from 100 kHz to 500 MHz.

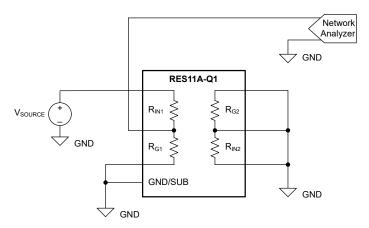


図 6-6. Bandwidth Measurement Reference Schematic



⊠ 6-7 shows the circuit configuration used for crosstalk measurements. The ac source is swept from 100 Hz to 100 MHz.

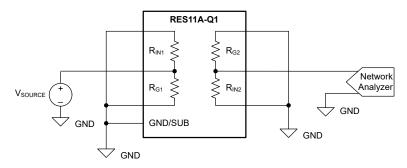


図 6-7. Crosstalk Measurement Reference Schematic

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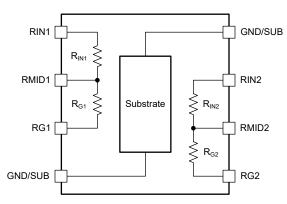


# 7 Detailed Description

### 7.1 Overview

The RES11A-Q1 consists of four precision thin-film SiCr resistors, arranged to form two matched dividers. The device has two input resistors,  $R_{IN1}$  and  $R_{IN2}$ , both nominally 1 k $\Omega$ . The device also has two gain resistors,  $R_{G1}$ and  $R_{G2}$ , with values that depend on the nominal ratio ( $R_{Gx}$  /  $R_{INx}$ ) of the RES11A-Q1 device in question. The resistors are arranged with R<sub>IN1</sub> and R<sub>G1</sub> in series to form the first divider, and R<sub>IN2</sub> and R<sub>G2</sub> in series to form the second divider. Two GND pins are also provided to bias the device substrate.

# 7.2 Functional Block Diagram



# 7.3 Feature Description

#### 7.3.1 Ratiometric Matching

The resistors of the RES11A-Q1 are described by the following equations:

$$R_{\text{IN1}} = R_{\text{INnom}} \times (1 + t_{\text{abs}}) = R_{\text{INnom}} \times (1 + t_{\text{RIN1}}) \times (1 + t_{\text{SiCr}})$$
(1)

$$R_{IN2} = R_{INnom} \times (1 + t_{RIN2}) \times (1 + t_{SiCr}) \tag{2}$$

$$R_{G1} = R_{Gnom} \times (1 + t_{RG1}) \times (1 + t_{SiCr})$$
(3)

$$R_{G2} = R_{Gnom} \times (1 + t_{RG2}) \times (1 + t_{SiCr})$$
(4)

 $R_{INnom}$  and  $R_{Gnom}$  are the nominal values of each resistor. The parameter  $t_{abs}$  is an error term that describes the absolute tolerance of the RES11A-Q1 device in question, such that  $|t_{abs}| \le 12\%$ . The absolute tolerance is dominated by the variation in the SiCr resistivity,  $t_{SiCr}$ . The four resistors of a given RES11A-Q1 are interdigitated and come from the same area of the wafer; therefore,  $t_{S/Cr}$  is effectively the same for each of the four resistors, although  $t_{SiCr}$  varies on a part-to-part basis. The following examples show that when each divider is considered in ratiometric terms, these error terms drop out. Parameter  $t_{Rx}$  is an error term that describes the remaining effective tolerance of each resistor of the given RES11A-Q1 device after accounting for the universal  $t_{SiCr}$ .

$$\frac{R_{Gx}}{R_{INx}} = \frac{R_{Gnom} \times (1 + t_{RGx}) \times (1 + t_{SiCr})}{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr})} = \frac{R_{Gnom} \times (1 + t_{RGx})}{R_{INnom} \times (1 + t_{RINx})} = G_{nom} \times \frac{(1 + t_{RGx})}{(1 + t_{RINx})} = G_x$$
 (5)

$$\frac{R_{INx}}{R_{INx} + R_{Gx}} = \frac{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr})}{R_{INnom} \times (1 + t_{RINx}) \times (1 + t_{SiCr}) + R_{Gnom} \times (1 + t_{RGx}) \times (1 + t_{SiCr})} = \frac{R_{INnom} \times (1 + t_{RINx})}{R_{INnom} \times (1 + t_{RINx}) + R_{Gnom} \times (1 + t_{RGx})}$$
(6)

The RES11A-Q1 is specified with a maximum divider ratio tolerance of 0.05%, meaning that the relationship between the actual divider ratio  $G_x$  and nominal ratio  $G_{nom}$  of a given divider x is described by the following:

$$G_{x} = G_{\text{nom}} \times (1 + t_{\text{D}x}) \tag{7}$$

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such that  $t_{Dx} \le 0.05\%$ . Because any devices that do not meet these criteria are screened out at final test, these equations can be used with  $\not \equiv 5$  to prove the effective bounds of  $t_{Rx}$ . Therefore, despite the device absolute end-to-end tolerance bounds of  $\pm 12\%$ , the effective error tolerances of each resistor (for ratiometric applications) are within approximately  $\pm 0.025\%$ , for the worst-case  $t_{Rx}$ .

The RES11A-Q1 is specified with a maximum divider matching tolerance of 0.1%, meaning that the relationship between the ratio of divider 1 ( $G_1$ ) and ratio of divider 2 ( $G_2$ ) is described by the following:

$$t_{M} = t_{D2} - t_{D1} = \frac{G_2 - G_1}{G_{nom}}$$
 (8)

By definition,  $|t_M| \le 0.1\%$ . Again, the previous equations relate  $t_M$  to the parameters  $t_{DX}$  and  $t_{RX}$ . As a result of the interdigitation of the two dividers, the actual typical magnitude of  $t_M$  is significantly lower than this maximum value, depending on the specific RES11A-Q1 device. This value is used to calculate the common-mode rejection ratio (CMRR) when implementing a difference amplifier circuit. For example, typical  $t_M$  for the RES11A40-Q1 is approximately 85 ppm, and the typical CMRR is 95.4 dB.

#### 7.3.2 Ratiometric Drift

The ratiometric matching of the RES11A-Q1 provides a benefit not just for initial conditions, but also when considering parametric drift. The resistors must be considered individually, in absolute terms, and ratiometrically to each other, in matched terms. The absolute temperature coefficients of each resistor show strong correlation, with the coefficient of  $R_{IN1}$  comparable to that of  $R_{IN2}$  and the coefficient of  $R_{G1}$  comparable to that of  $R_{G2}$ . The absolute temperature coefficient (in  $\Omega$ /°C) of each  $R_{G}$  is approximately  $G_{nom}$  times greater than that of the comparable  $R_{IN}$ ; hence, the normalized absolute temperature coefficient (in ppm/°C) of every resistor is about the same.

Because the resistors of the RES11A-Q1 are interdigitated, and occupy a small footprint, the die temperature of the device is effectively common to each of the four resistors. As the temperature changes, each resistor experiences a similar temperature rise. Because the resistors have very similar temperature coefficients, the ratio of  $R_G$  to  $R_{IN}$  is well preserved. For example, the RES11A40-Q1 has a typical absolute temperature coefficient of approximately 18 ppm/°C for  $R_{IN}$  or  $R_G$ . When considered in ratiometric terms, the typical temperature coefficient of  $t_{D1}$  or  $t_{D2}$  is -0.2 ppm/°C, and the temperature coefficient of  $t_M$  is 0.05 ppm/°C.

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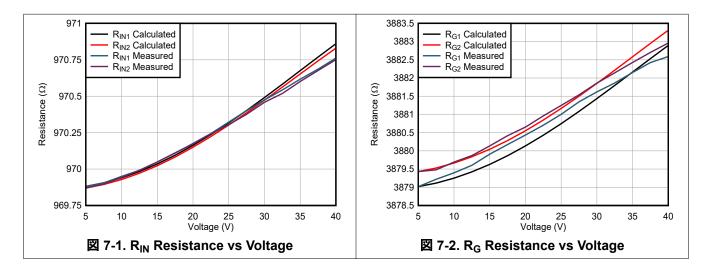


#### 7.3.3 Predictable Voltage Coefficient

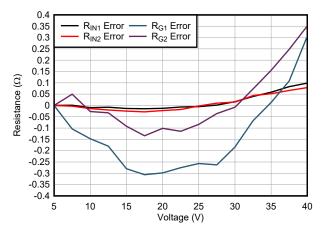
The voltage coefficients of the RES11A-Q1 are almost entirely related to self-heating, where the power dissipated in the device raises the die temperature. As previously mentioned, the commonality of this temperature rise leads to a comparable shift in each resistor, such that the divider ratio is well preserved.

Applying voltage V across resistor or divider R results in the loss of a corresponding power dissipation of  $P = V^2 / R$ , in the form of heat in the device die. This heat leads to a localized increase in the junction temperature, which in turn causes the same parametric shifts previously discussed in the context of temperature coefficients. TCR is specified as a function of ambient temperature; therefore, use the effective junction-to-ambient thermal resistance to determine the effective temperature rise and calculate the nominal or expected shift.

$$R_{\text{expected}} = \frac{{v_R}^2}{R} \times R_{\theta JA \text{ effective}} \times TCR_{abs} \times R$$
 (9)



The difference of the expected value of R from the actual value of R describes the actual-to-expected mismatch error of R, due to non-temperature-related effects on the voltage coefficient. Similar to the logarithmic conformity error of a logarithmic amplifier or the integrated nonlinearity error of an ADC, this error describes the deviations of the actual device behavior from the predictable behavior. While the absolute magnitude of the shift varies, the slope or trend is predictable.



☑ 7-3. Resistor Actual-to-expected Mismatch vs Voltage

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The measured value of R for low bias (measured by sourcing a very small current) is used with the actual value of R to calculate the effective voltage coefficient of resistance.

Voltage coefficient 
$$(\Omega/V) = \frac{R_{biased} - R_{initial}}{V_{bias}}$$
 (10)

This exercise is repeated for each  $R_x$ ,  $t_{D1}$ ,  $t_{D2}$ , and  $t_M$ , to calculate the voltage coefficients associated with each parameter. For example, the RES11A40-Q1 has a typical absolute voltage coefficient of approximately 0.02  $\Omega$ /V for  $R_{IN}$  or  $R_{G}$ . When considered in ratiometric terms, the typical voltage coefficient of  $t_{D1}$  or  $t_{D2}$  is 2 ppm/V, and the voltage coefficient of  $t_M$  is 0.5 ppm/V.

# 7.3.4 Ultra-Low Noise

Noise in resistors can be evaluated in two separate regions: low-frequency flicker noise and wideband thermal noise. Flicker, or 1/f noise, is extremely important for systems that require signal gain at frequencies less than 100 Hz. Thermal noise typically dominates in the region greater than 1 kHz, and increases as resistor magnitude increases. Noise is modeled as a voltage source in series with the resistor.

For a resistive divider such as the RES11A-Q1, the thermal noise as measured at the center tap of two resistors,  $R_{IN}$  and  $R_{G}$ , is equivalent to the thermal noise of a resistor with value  $R_{IN} \parallel R_{G}$ :

$$e_N = \sqrt{(4k_BTR)} \tag{11}$$

where:

- e<sub>N</sub> is the thermal noise density in nV/√Hz
- T is the absolute temperature in kelvins (K)
- $k_B$  is the Boltzmann constant, 1.381 × 10-23 J/K
- R = R<sub>IN</sub> || R<sub>G</sub>

As an example, for the RES11A40-Q1 at 25°C:

$$e_N = \sqrt{(4k_BTR)} = \sqrt{4 \times 1.38E^{-23} \frac{J}{K} \times 278 K \times (1 k\Omega \parallel 4 k\Omega)} = 3.5 \text{ nV} / \sqrt{\text{Hz}}$$
 (12)

#### 7.4 Device Functional Modes

The RES11A-Q1 is typically used with the two independently biased resistor dividers.  $R_{IN1}$  and  $R_{G1}$  in series form a resistive divider, with  $R_{IN2}$  and  $R_{G2}$  in series forming another divider. However, the two dividers do not have to be used independently. The resistors can be connected in series or in parallel like any other resistor.

Use one of the two GND pins to bias the part substrate. Connect the substrate to signal ground or a similar low-impedance bias point or plane for best noise rejection. While two GND/SUB connection pins are available on the device, connect only *one* of these to the ground plane. The two GND pins are internally connected through the substrate, which is not intended to conduct significant currents. Connect only *one* GND pin at a time and leave the other pin floating to prevent current return paths from developing through the substrate.

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# 8 Application and Implementation

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Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 8.1 Application Information

# 8.1.1 Discrete Difference Amplifier

The RES11A-Q1 is commonly used to implement a simple difference amplifier. The ratiometric matching between the two resistor dividers improves CMRR performance and gain drift for the circuit, when compared to a similar implementation using unmatched discrete resistors. The basic circuit is shown in  $\boxtimes$  8-1.



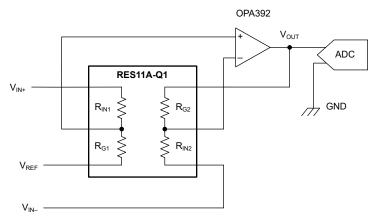


図 8-1. Discrete Difference Amplifier Using RES11A-Q1

#### 8.1.1.1 Difference-Amplifier Common-Mode Rejection Analysis

In this simple difference amplifier configuration, the nominal CMRR is calculated as:

$$CMRR = 20 \times \log_{10} \left( \left| \frac{A_{D}}{A_{CM}} \right| \right)$$
 (14)

The term  $A_D$  is the differential gain of the circuit, and the term  $A_{CM}$  is the common-mode gain of the circuit. These are defined as the following:

$$A_{D} \times = \frac{V_{OUT}}{V_{D}} = 0.5 \times \frac{\left(\frac{R_{G1}}{R_{G1} + R_{IN1}}\right) + \left(\frac{R_{G2}}{R_{G2} + R_{IN2}}\right)}{\left(\frac{R_{IN2}}{R_{G2} + R_{IN2}}\right)}$$
(15)

$$A_{CM} = \frac{V_{OUT}}{V_{CM}} = \frac{\left(\frac{R_{G1}}{R_{G1} + R_{IN1}}\right) - \left(\frac{R_{G2}}{R_{G2} + R_{IN2}}\right)}{\left(\frac{R_{IN2}}{R_{G2} + R_{IN2}}\right)}$$
(16)

Therefore,



$$CMRR = 20 \times \log_{10} \left( \left| 2 \times \frac{R_{G1} \times (R_{IN2} + R_{G2}) - R_{G2} \times (R_{IN1} + R_{G1})}{R_{G1} \times (R_{IN2} + R_{G2}) + R_{G2} \times (R_{IN1} + R_{G1})} \right| \right)$$
(17)

When this expression is evaluated with the definitions given in セクション 7.3.1, assuming the worst-case scenario of the most unbalanced divider matching possible,

$$CMRR = 20 \times \log_{10} \left( \left| \frac{G_{\text{nom}} + 1 + t_{\text{Rx}}^2 (1 - G_{\text{nom}})}{4 \times t_{\text{Rx}}} \right| \right)$$
 (18)

Because  $t_{Rx}^2 \ll 1$ , the worst-case CMRR is approximated as

$$CMRR = 20 \times \log_{10} \left( \left| \frac{G_{\text{nom}} + 1}{4 \times t_{\text{Rx}}} \right| \right)$$
 (19)

By definition, the parameter  $t_M$  describes the effective error that is otherwise equivalent to  $4 \times t_X$  for an unmatched divider network, and so the maximum value of  $t_M$  can be used to calculate the same worst-case result. Likewise, the typical value of  $t_M$  can be used to approximate the typical CMRR.

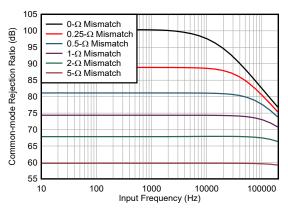
$$CMRR = 20 \times \log_{10} \left( \left| \frac{G_{\text{nom}} + 1}{t_{\text{M}}} \right| \right)$$
 (20)

For example, the worst-case CMRR for a RES11A40-Q1 device with G = 4 is approximately 74.0 dB, with a typical CMRR of approximately 95.4 dB. In comparison, implementation of a comparable G = 4 difference amplifier with unmatched 0.1%-tolerance resistors results in a worst-case CMRR of approximately 62 dB.

In a difference amplifier configuration, the CMRR of the op amp contributes error as well. The op-amp CMRR is considered in parallel with the CMRR of the resistor network, as per the following equation:

$$\frac{1}{\text{CMRR}_{\text{TOTAL}}} = \frac{1}{\text{CMRR}_{\text{AMP}}} + \frac{1}{\text{CMRR}_{\text{RESISTORS}}} \tag{21}$$

Additional mismatches in the divider end-to-end resistances reduce the effective CMRR of a difference amplifier. While the low absolute tolerance span of the RES11A-Q1 (235 ppm typical) helps reduce these concerns, parasitic trace resistances can lead to additional mismatches that impact the CMRR specs. Bench results from a difference amplifier implementation of the RES11A40-Q1 and the OPA210 are presented for various deliberate input-impedance mismatches.



☑ 8-2. Effect of Input Impedance Mismatch on Common-mode Rejection Ratio

#### 8.1.2 Discrete Instrumentation Amplifiers

The RES11A-Q1 can be used to in conjunction with a dual-channel operational amplifier to implement a discrete instrumentation amplifier (INA). The ratiometric matching between the two resistor dividers improves CMRR

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performance for the circuit when compared to a similar implementation using unmatched discrete resistors, and results in better overtemperature and overaging gain drift characteristics. INAs are often used instead of difference amplifiers when high input impedance and low bias currents are needed, such as when measuring bridge sensors.

Discrete INAs are often configured as a differential-input differential-output circuit as shown in 🗵 8-3. While not shown, if needed, use an additional discrete difference amplifier stage (requiring a second RES11A-Q1 and another op-amp channel) to convert the differential output voltage to a single-ended voltage (for example, when driving a single-ended ADC). This extra stage can also add an additional offset and provide additional gain, effectively mimicking the common three-amplifier INA architecture.

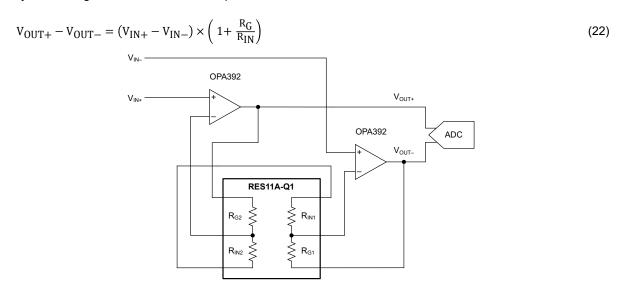


図 8-3. Differential-Input, Differential-Output Instrumentation Amplifier Using the RES11A-Q1

Less commonly, a discrete INA can be implemented as a differential-input, single-ended output circuit as shown in  $\boxtimes$  8-4. This topology maintains high input impedances, allows an offset to be applied, and gives a single-ended output without requiring a third amplifier channel. The offset must be driven by a low-impedance source, such as a reference buffer. When designing a discrete INA, carefully consider the output swing and input common-mode range limitations of the amplifiers used in the circuit design process.

$$V_{OUT} = (V_{IN+} - V_{IN-}) \times (1 + \frac{R_G}{R_{IN}}) + V_{REF}$$
 (23)

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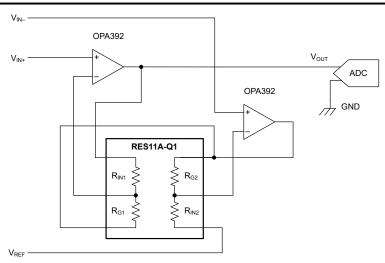


図 8-4. Differential-Input, Single-Ended Output Instrumentation Amplifier Using the RES11A-Q1

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#### 8.1.2.1 Instrumentation Amplifier Common-Mode Rejection Analysis

The differential-input, differential-output instrumentation amplifier shown in  $\boxtimes$  8-3 has a common-mode gain of  $A_{CM} = 1 \text{ V/V}$ . The differential gain is described by the following (assuming an ideal amplifier):

$$A_{D} = \frac{R_{G1} + R_{G2}}{R_{IN1} + R_{IN2}} + 1 = G_{nom} \times \frac{(1 \pm t_{RG1}) + (1 \pm t_{RG2})}{(1 \pm t_{RIN1}) + (1 \pm t_{RIN2})} + 1$$
(24)

Because the worst-case-stage CMRR occurs when the differential gain is lowest, and the common-mode gain is unity, the minimum CMRR is evaluated as:

$$\frac{A_{D}}{A_{CM}} = G_{nom} \times \frac{(1 - t_{RG1}) + (1 - t_{RG2})}{(1 + t_{RIN1}) + (1 + t_{RIN2})} + 1 = G_{nom} \times \frac{1.9995}{2.0005} + 1$$
 (25)

For example, for an instrumentation amplifier with RES11A90-Q1, the worst-case CMRR is:

$$\frac{A_{D}}{A_{CM}} = G_{nom} \times \frac{(1 - t_{RG1}) + (1 - t_{RG2})}{(1 + t_{RIN1}) + (1 + t_{RIN2})} + 1 = 9 \text{ V/V} \times \frac{1.9995}{2.0005} + 1 = 9.9955 \text{ V/V}$$
(26)

#### 8.1.3 Fully Differential Amplifier

The RES11A-Q1 can be used to set the gain of a fully differential amplifier, such as the THP210. The ratiometric matching between the two resistor dividers leads to improved gain matching and CMRR performance for the circuit, when compared to a similar implementation using unmatched discrete resistors.

☑ 8-5 shows a generic schematic representation of a fully differential amplifier driving a differential ADC, with a RES11A-Q1 used to set the amplifier gain.

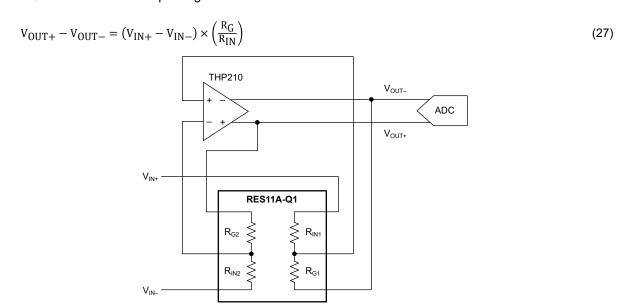


図 8-5. Fully-differential Amplifier Gain Setting Using RES11A-Q1

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# 8.2 Typical Application

#### 8.2.1 Common-Mode Shifting Input Stage

The RES11A-Q1 can be used to implement a common-mode attenuator at the high-impedance inputs of an instrumentation amplifier (INA). This configuration extends the usable signal range, so long as the maximum differential voltage limitation of each resistor divider is respected.

 $\boxtimes$  8-6 shows an example of a high-side current-sense circuit where a differential voltage,  $V_{SHUNT}$ , develops across a sense resistor with an undesirably high common-mode voltage  $V_{CM}$ .  $V_{REF}$  is used to shift input common-mode voltages  $V_{MID1}$  and  $V_{MID2}$  to levels within the specified input common-mode range of the INA. The amplifier output,  $V_{OUT}$ , is a scaled function of  $V_{SHUNT}$ , such that nominally:

$$V_{OUT} = V_{SHUNT} \times \left(\frac{R_{IN}}{R_G + R_{IN} + R_{EQUIV}}\right)$$
 (28)

 $V_{OUT}$  can be gained up further by the INA stage, to make maximal use of the effective resolution of a downstream ADC. In practice  $R_{EQUIV}$  is optional; however, if  $R_{EQUIV} = R_{SHUNT}$ , this resistance equalizes the nominal impedance between  $V_{CM}$  and each of the INA high-impedance inputs, thus improving CMRR performance. Select an INA with input bias currents  $I_{B1}$  and  $I_{B2} << I_{STATIC1}$  and  $I_{STATIC2}$ , such as the INA333 or INA823. Select a RES11A-Q1 device with a sufficiently high divider series resistance so that  $I_{STATIC1}$  and  $I_{STATIC2} << I_{I_{CAD}}$ .

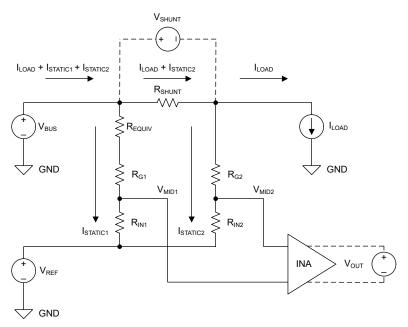


図 8-6. RES11A-Q1 Common-Mode Shifting Circuit

To achieve a desired nominal input common-mode voltage, V<sub>MID1TARGET</sub>, set V<sub>REF</sub> as follows:

$$V_{REF} = V_{MID1TARGET} \times \left(\frac{R_{G} + R_{IN} + R_{EQUIV}}{R_{G} + R_{EQUIV}}\right) - V_{CM} \times \left(\frac{R_{G} + R_{IN} + R_{EQUIV}}{R_{G} + R_{EQUIV}} - 1\right)$$
(29)



#### 8.2.1.1 Design Requirements

Consider a level-shifting application where a high-side current shunt measurement from an 18-V supply rail must be measured by a 3.3-V amplifier and ADC.

PARAMETER	DESIGN GOAL
Input V <sub>BUS</sub>	18 V
I <sub>LOAD</sub>	300 mA (maximum)
R <sub>SHUNT</sub>	1 Ω
ADC full-scale range (target V <sub>OUT</sub> )	3.3 V
Possible V <sub>REF</sub> voltages	3.3 V, 0 V

#### 8.2.1.2 Detailed Design Procedure

The design parameters are used with the aforementioned equations to select a nominal target G. When the possible  $V_{REF}$  voltages available in the system are considered,  $V_{REF}$  = 0 V with G = 9 is found to result in a  $V_{MID1}$  value of 1.8 V, well within the input common-mode range of a 3.3-V rail-to-rail amplifier such as the OPA392. When the corresponding RES11A90-Q1 is employed, the loss terms  $I_{STATIC1}$  and  $I_{STATIC2}$  are nominally 1.80 mA and 1.77 mA for  $I_{LOAD}$  = 300 mA, resulting in an effective floor of 1.77 mA for  $I_{LOAD}$ . For simplicity, the error contributions of the INA stage  $V_{OS}$  and  $I_{B}$  are ignored.

For the INA stage, an integrated TI instrumentation amplifier (IA) can be used. Alternatively, a discrete approach can be implemented using another RES11A-Q1 device or devices, and one or more op amps. For this example, an IA stage is constructed with two channels of a OPA4392 and a second RES11A90-Q1 ( $R_{IN3}$ ,  $R_{G3}$ ,  $R_{IN4}$ , and  $R_{G4}$ ). This stage is in turn cascaded with a difference amplifier stage, constructed with the third amplifier channel and a RES11A00-Q1 ( $R_{IN5}$ ,  $R_{G5}$ ,  $R_{IN6}$ , and  $R_{G6}$ ). The level-shifting stage gain of  $10^{-1}$ , multiplied by the instrumentation amplifier stage gain of 10, results in an effective unity-gain transfer function for  $V_{SHUNT}$ . Therefore, the differential output voltage for this stage is approximately 0.3 V, with amplifier outputs of 1.936 V and 1.634 V. After the final difference amplifier stage gain of G = 10, the common-mode voltage drops out and the maximum value of the resulting  $V_{OUT}$  is nominally 3.0 V, compatible with a single-ended 3.3-V ADC such as the ADS7046. If desired, the fourth channel of the OPA4392 can be used to buffer this output signal and serve as a dedicated ADC driver.

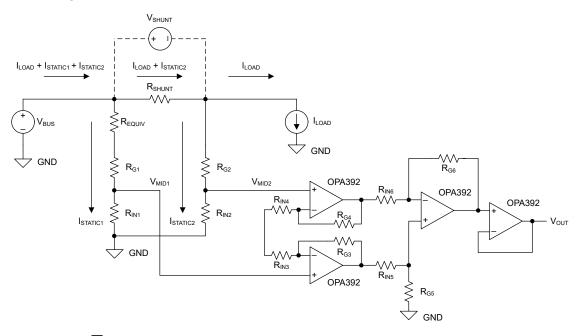


図 8-7. High-Side Current Shunt Common-Mode Shifting Circuit



### 8.2.1.3 Application Curves

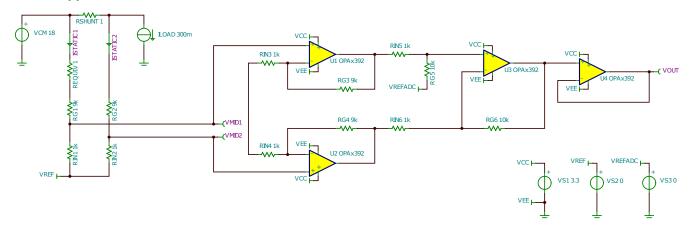
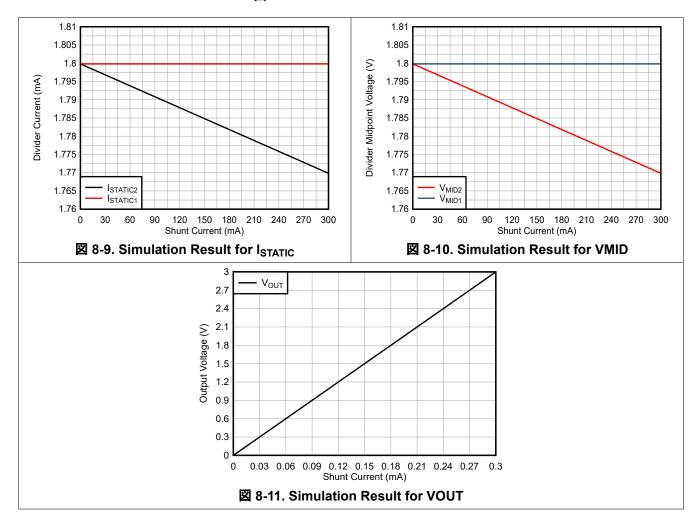


図 8-8. Circuit Model in TINA-TI





# 8.3 Power Supply Recommendations

The ratio of a given RES11A-Q1 device dictates the maximum differential voltage rating for the resistor dividers of the device. See the *Absolute Maximum Ratings* and *Recommended Operating Conditions* for device-specific values under transient and sustained bias conditions, respectively. See  $\boxtimes$  8-12 for approximate values, assuming R<sub> $\theta$ JA</sub> = 156.2°C/W and that both dividers are biased to the same dc voltage at the same time. Keep T<sub>J</sub> less than the absolute maximum rating of 150°C.

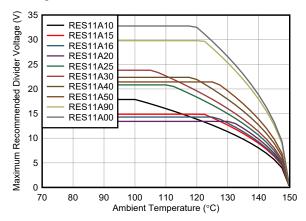


図 8-12. Maximum Recommended Divider Voltage vs Ambient Temperature

# 8.4 Layout

### 8.4.1 Layout Guidelines

For best operational performance of the device, use good printed-circuit board (PCB) layout practices, including:

- Reduce parasitic coupling by running input traces as far away from supply or output traces as possible. If
  these traces cannot be kept separate, crossing the sensitive trace perpendicular is much better as opposed
  to in parallel with the noisy trace.
- Place the external components as close to the device as possible.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit. For differential circuits, match the length of the input traces as best possible.
- Keep high impedance input signals away from noisy traces.
- Make sure system supply voltages are adequately filtered.
- Clean the PCB following board assembly for best performance.
- Any precision integrated circuit can experience performance shifts resulting from moisture ingress into the
  plastic package. Following any aqueous PCB cleaning process, bake the PCB assembly to remove moisture
  introduced into the device packaging during the cleaning process. A low temperature, post-cleaning bake at
  85°C for 30 minutes is sufficient for most circumstances.
- Only connect one of the two GND/SUB pins to the ground plane, to prevent the formation of current return paths through the device substrate. Float the other GND/SUB pin.

資料に関するフィードバック(ご意見やお問い合わせ) を送信



# 8.4.2 Layout Examples

In the following examples, the RES11A-Q1 is shown with a VSSOP amplifier and 0402-size decoupling capacitors.

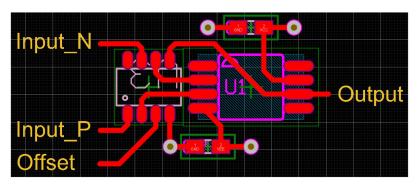


図 8-13. Single-Layer Difference Amplifier Implementation

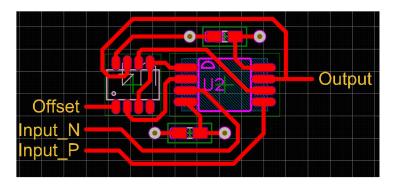


図 8-14. Single-Layer Instrumentation Amplifier Implementation

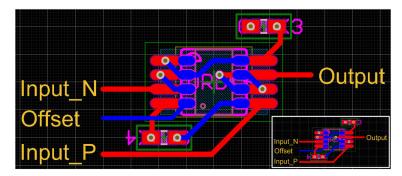


図 8-15. Front-and-Back Instrumentation Amplifier Implementation



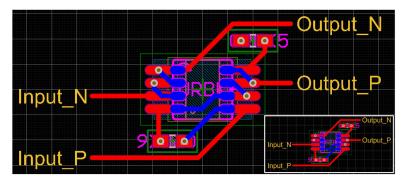


図 8-16. Front-and-Back, Differential-Output Instrumentation Amplifier Implementation

For 🗵 8-17, two RES11A-Q1 devices (bottom side) and one dual-channel op-amp (top side) are used.

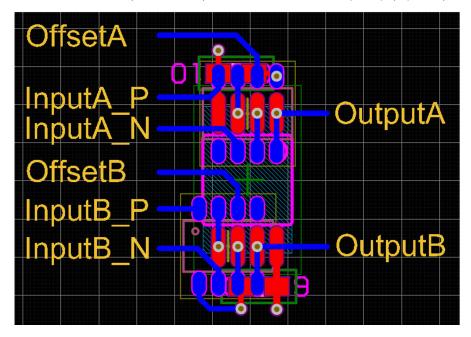


図 8-17. Front-and-Back Dual Difference Amplifiers Implementation



# 9 Device and Documentation Support

# 9.1 Device Support

## 9.1.1 Development Support

# 9.1.1.1 PSpice® for TI

PSpice® for TI は、アナログ回路の性能評価に役立つ設計およびシミュレーション環境です。レイアウトと製造に移る前に、サブシステムの設計とプロトタイプ・ソリューションを作成することで、開発コストを削減し、市場投入までの期間を短縮できます。

# 9.1.1.2 TINA-TI™ シミュレーション・ソフトウェア (無償ダウンロード)

TINA-TI™ シミュレーション・ソフトウェアは、SPICE エンジンをベースにした単純かつ強力な、使いやすい回路シミュレーション・プログラムです。 TINA-TI シミュレーション・ソフトウェアは、TINA™ ソフトウェアのすべての機能を持つ無償バージョンで、パッシブ・モデルとアクティブ・モデルに加えて、マクロモデルのライブラリがプリロードされています。 TINA-TI シミュレーション・ソフトウェアには、SPICE の標準的な DC 解析、過渡解析、周波数ドメイン解析などの全機能に加え、追加の設計機能が搭載されています。

TINA-TI シミュレーション・ソフトウェアは設計ツールとシミュレーション Web ページから無料でダウンロードでき、ユーザーが結果をさまざまな方法でフォーマットできる、広範な後処理機能を備えています。 仮想計測器により、入力波形を選択し、回路ノード、電圧、および波形をプローブして、動的なクイック・スタート・ツールを作成できます。

泔

これらのファイルを使用するには、TINA ソフトウェアまたは TINA-TI ソフトウェアがインストールされている必要があります。 TINA-TI™ ソフトウェア・フォルダから、無償の TINA-TI シミュレーション・ソフトウェアをダウンロードしてください。

# 9.1.1.3 TI のリファレンス・デザイン

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#### 9.1.1.4 フィルタ設計ツール

フィルタ設計ツールは単純で強力な、使いやすいアクティブ・フィルタ設計プログラムです。フィルタ設計ツールを使用すると、TI のベンダ・パートナーからの TI 製オペアンプやパッシブ・コンポーネントを使用して、最適なフィルタ設計を作成できます。

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# 9.2 Documentation Support

#### 9.2.1 Related Documentation

For related documentation see the following:

- Texas Instruments, Optimizing CMRR in Differential Amplifier Circuits With Precision Matched Resistor Divider Pairs application note
- Texas Instruments, THP210 Ultra-Low Offset, High-Voltage, Low-Noise, Precision, Fully-Differential Amplifier data sheet
- Texas Instruments, OPAx392 Precision, Low-Offset-Voltage, Low-Noise, Low-Input-Bias-Current, Rail-to-Rail
   I/O, e-trim™ Operational Amplifiers data sheet

# 9.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、www.tij.co.jp のデバイス製品フォルダを開いてください。[通知] をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取ることができます。 変更の詳細については、改訂されたドキュメントに含まれている改訂履歴をご覧ください。

# 9.4 サポート・リソース

テキサス・インスツルメンツ E2E<sup>™</sup> サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計で必要な支援を迅速に得ることができます。

リンクされているコンテンツは、各寄稿者により「現状のまま」提供されるものです。これらはテキサス・インスツルメンツの仕様を構成するものではなく、必ずしもテキサス・インスツルメンツの見解を反映したものではありません。テキサス・インスツルメンツの使用条件を参照してください。

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TINA™ is a trademark of DesignSoft. Inc.

PSpice® is a registered trademark of Cadence Design Systems, Inc.

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ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

#### 9.7 用語集

テキサス・インスツルメンツ用語集 この用語集には、用語や略語の一覧および定義が記載されています。

#### 10 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

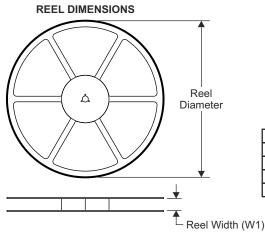
C	hanges from Revision * (October 2023) to Revision A (December 2023)	Page
•	ドキュメント全体を通して「t <sub>M</sub> 」の定義を更新し、それに応じて仕様値を更新	1
•	より大きなサンプル サイズのデータに基づき、ドキュメント全体を通して標準的なパラメータ値を更新	1
•	デバイスの使用可能範囲を拡張するため、ドキュメント全体を通して絶対最大定格および推奨最大電圧/電流定	格を
	更新	1
•	Added histograms and characteristic curves to Typical Characteristics	9
•	Added Parameter Measurement Information section	
•	Added Predictable Voltage Coefficient section	18
	Added input impedance mismatch text to Difference-Amplifier Common-Mode Rejection Analysis	

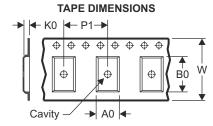
- Changed V<sub>RAIL</sub> to V<sub>BUS</sub> in Common-Mode Shifting Input Stage ......25
- Changed guidance in Power Supply Recommendations to reflect updated absolute and recommended

# 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

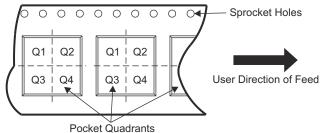
# 11.1 Tape and Reel Information





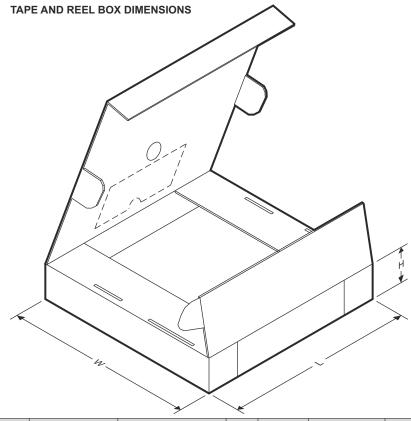
	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**



Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PRES11A00QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A10QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A150QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A16QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A20QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A25QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A30QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A40QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A50QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
PRES11A90QDDFRQ1	SOT-23- THIN	DDF	8	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3





Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
PRES11A00QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A10QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A15QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A16QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A20QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A25QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A30QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A40QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A50QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0
PRES11A90QDDFRQ1	SOT-23-THIN	DFF	8	3000	201.0	185.0	35.0



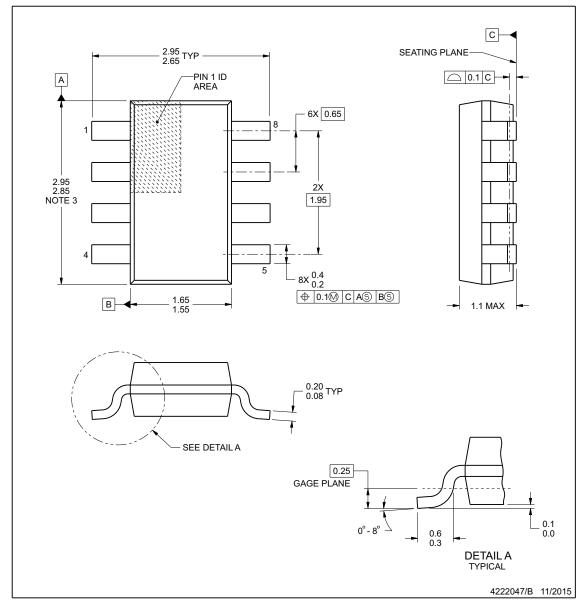
# 11.2 Mechanical Data

**DDF0008A** 

# **PACKAGE OUTLINE**

# SOT-23 - 1.1 mm max height

PLASTIC SMALL OUTLINE



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.



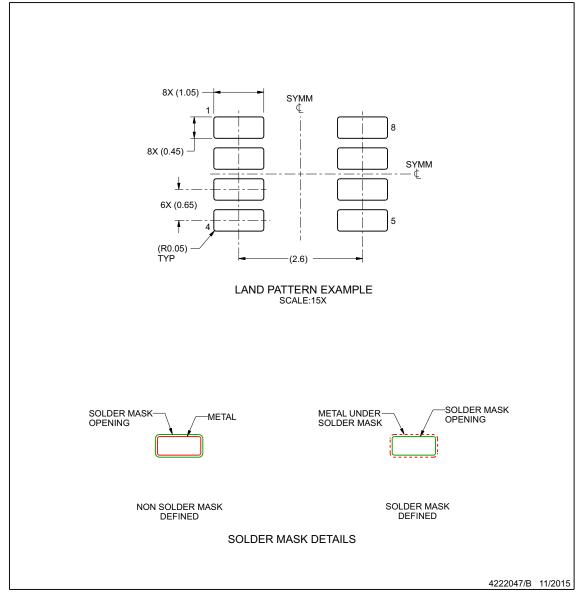


# **EXAMPLE BOARD LAYOUT**

# **DDF0008A**

SOT-23 - 1.1 mm max height

PLASTIC SMALL OUTLINE



NOTES: (continued)

- 4. Publication IPC-7351 may have alternate designs.
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



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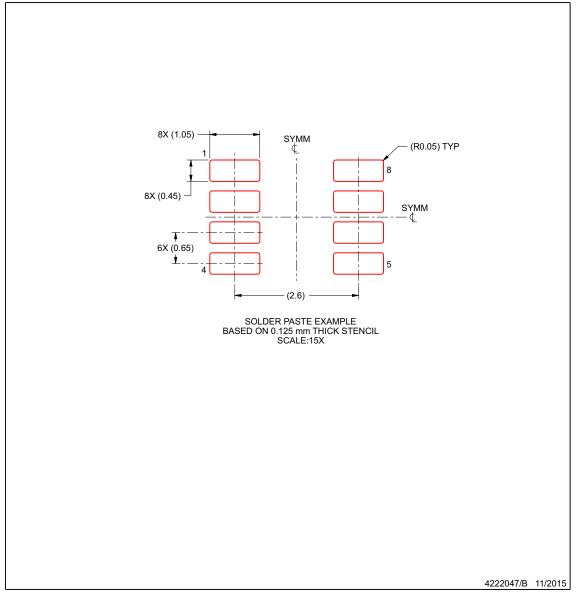


### **EXAMPLE STENCIL DESIGN**

# **DDF0008A**

SOT-23 - 1.1 mm max height

PLASTIC SMALL OUTLINE



NOTES: (continued)

- 6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

  7. Board assembly site may have different recommendations for stencil design.



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#### PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
PRES11A00QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples
PRES11A10QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples
PRES11A16QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples
PRES11A40QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples
PRES11A50QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples
PRES11A90QDDFRQ1	ACTIVE	SOT-23-THIN	DDF	8	3000	TBD	Call TI	Call TI	-40 to 125		Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

# **PACKAGE OPTION ADDENDUM**

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF RES11A-Q1:

Catalog: RES11A

NOTE: Qualified Version Definitions:

Catalog - TI's standard catalog product

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