

TAS5414A, TAS5424A

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# FOUR-CHANNEL AUTOMOTIVE DIGITAL AMPLIFIERS

Check for Samples: TAS5414A, TAS5424A

#### **FEATURES**

- TAS5414A Single-Ended Input
- TAS5424A Differential Input
- Four-Channel Digital Power Amplifier
- Four Analog Inputs, Four BTL Power Outputs
- Typical Output Power per Channel at 10% THD+N
  - 28 W/Ch Into 4  $\Omega$  at 14.4 Vdc
  - 45 W/Ch Into 2  $\Omega$  at 14.4 Vdc
  - 58 W/Ch Into 4  $\Omega$  at 21 Vdc
  - 116 W/Ch Into 2 Ω at 21 Vdc PBTL
- Channels Can Be Paralleled (PBTL) for 1-Ω Applications
- THD+N < 0.02%, 1 kHz, 1 W Into 4 Ω</li>
- Patented Pop- and Click-Reduction Technology
  - Soft Muting With Gain Ramp Control
  - Common-Mode Ramping
- Patented AM Interference Avoidance
- Patented Cycle-by-Cycle Current Limit
- 75-dB PSRR
- Four-Address I<sup>2</sup>C Serial Interface for Device Configuration and Control
- Channel Gains: 12-dB, 20-dB, 26-dB, 32-dB
- Load Diagnostic Functions:
  - Output Open and Shorted Load
  - Output-to-Power and -to-Ground Shorts
  - Patented Tweeter Detection
- Protection and Monitoring Functions:
  - Short-Circuit Protection
  - Load-Dump Protection to 50 V
  - Fortuitous Open Ground and Power Tolerant
  - Patented Output DC Level Detection While Music Playing
  - Overtemperature Protection
  - Over- and Undervoltage Conditions
  - Clip Detection
- 36-Pin PSOP3 (DKD) Power SOP Package With

- 44-Pin PSOP3 (DKD) Power SOP Package With Heat Slug Up for the TAS5424A
- 64-Pin QFP (PHD) Power Package With Heat Slug Up for TAS5414A
- Designed for Automotive EMC Requirements
- Qualified According to AEC-Q100

Heat Slug Up for the TAS5414A

- ISO9000:2002 TS16949 Certified
- –40°C to 105°C Ambient Temperature Range

#### **APPLICATIONS**

 High-Power OEM/Retail Head Units and Amplifier Modules Where Feature Densities and System Configurations Require Reduction in Heat From the Audio Power Amplifier

### DESCRIPTION

The TAS5414A and TAS5424A are four-channel digital audio amplifiers designed for use in automotive head units and external amplifier modules. The TAS5414A and TAS5424A provide four channels at 23 W continuously into 4 Ω at less than 1% THD+N from a 14.4-V supply. Each channel can also deliver 38 W into 2  $\Omega$  at 1% THD+N. The TAS5414A uses single-ended analog inputs, while the TAS5424A employs differential inputs for increased immunity to common-mode system noise. The digital PWM topology of the TAS5414A and TAS5424A provides dramatic improvements in efficiency over traditional linear amplifier solutions. This reduces the power dissipated by the amplifier by a factor of ten under typical music playback conditions. The TAS5414A and TAS5424A incorporate all the functionality needed to perform in the demanding OEM applications area. They have built-in load diagnostic functions for detecting and diagnosing misconnected outputs to help to reduce test time during the manufacturing process.



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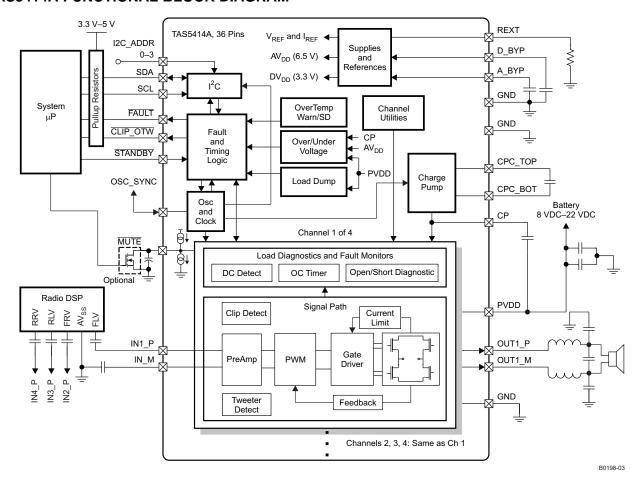


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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

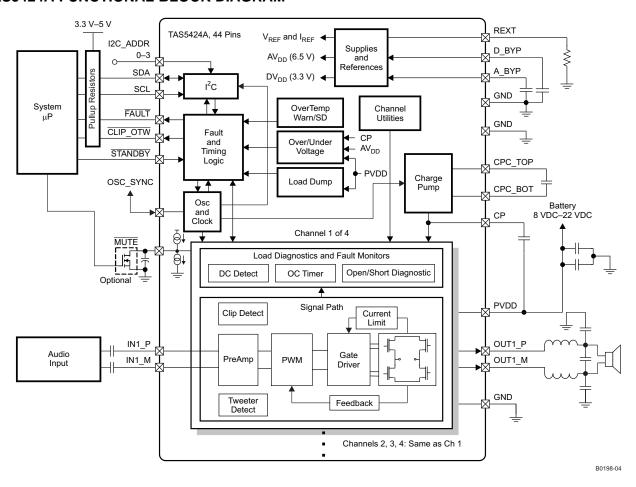
### TAS5414A FUNCTIONAL BLOCK DIAGRAM





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### TAS5424A FUNCTIONAL BLOCK DIAGRAM

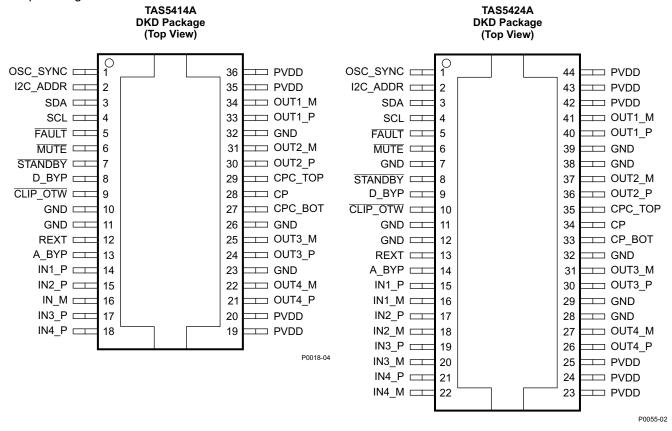




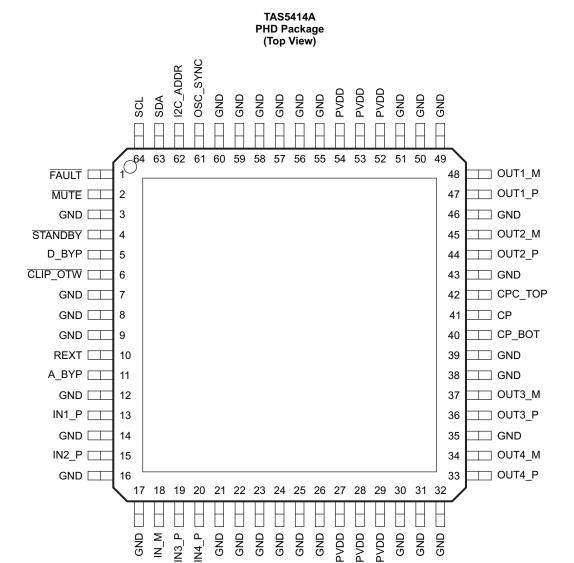
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#### PIN ASSIGNMENTS AND FUNCTIONS

The pin assignments for the TAS5414A and TAS5424A are shown as follows.



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TEXAS INSTRUMENTS

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### **Table 1. TERMINAL FUNCTIONS**

| TERMINAL     |                       |                                     |   |   |   |  |  |
|--------------|-----------------------|-------------------------------------|---|---|---|--|--|
| MANE         | DKD Package           |                                     | PHD<br>Package  | TYPE <sup>(1)</sup>   | DESCRIPTION   |  |  |
| NAME         | TAS5414A<br>NO.       | TAS5424A<br>NO.                     | TAS5414A<br>NO.   |   |   |  |  |
| A_BYP        | 13                    | 14                                  | 11  | PBY   | Bypass pin for the AVDD analog regulator  |  |  |
| CLIP_OT<br>W | 9                     | 10                                  | 6   | DO  | Open-drain CLIP, OTW, or logical OR of the CLIP and OTW outputs. It also reports tweeter detection during tweeter mode. |  |  |
| CP           | 28                    | 34                                  | 41  | CP Top of main storage capacitor for charge pump (bottom go |   |  |  |
| CPC_BOT      | 27                    | 33                                  | 40  | СР  | Bottom of flying capacitor for charge pump  |  |  |
| CPC_TOP      | 29                    | 35                                  | 42  | СР  | Top of flying capacitor for charge pump   |  |  |
| D_BYP        | 8                     | 9                                   | 5   | PBY   | Bypass pin for DVDD regulator output  |  |  |
| FAULT        | 5                     | 5                                   | 1   | DO  | Global fault output (open drain): UV, OV, OTSD, OCSD, DC  |  |  |
| GND          | 10, 11, 23,<br>26, 32 | 7, 11, 12,<br>28, 29, 32,<br>38, 39 | 3, 7, 8, 9, 12,<br>14, 16, 17,<br>21, 22, 23,<br>24, 25, 26,<br>30, 31, 32,<br>35, 38, 39,<br>43, 46, 49,<br>50, 51, 55,<br>56, 57, 58,<br>59, 60 | AG / DG /<br>PGND   | Ground  |  |  |
| I2C_ADDR     | 2                     | 2                                   | 62  | AI  | I <sup>2</sup> C address bit  |  |  |
| IN1_M        | N/A                   | 16                                  | N/A   | Al  | Inverting analog input for channel 1 (TAS5424A only)  |  |  |
| IN1_P        | 14                    | 15                                  | 13  | Al  | Non-inverting analog input for channel 1  |  |  |
| IN2_M        | N/A                   | 18                                  | N/A   | AI  | Inverting analog input for channel 2 (TAS5424A only)  |  |  |
| IN2_P        | 15                    | 17                                  | 15  | Al  | Non-inverting analog input for channel 2  |  |  |
| IN3_M        | N/A                   | 20                                  | N/A   | Al  | Inverting analog input for channel 3 (TAS5424A only)  |  |  |
| IN3_P        | 17                    | 19                                  | 19  | Al  | Non-inverting analog input for channel 3  |  |  |
| IN4_M        | N/A                   | 22                                  | N/A   | Al  | Inverting analog input for channel 4 (TAS5424A only)  |  |  |
| IN4_P        | 18                    | 21                                  | 20  | Al  | Non-inverting analog input for channel 4  |  |  |
| IN_M         | 16                    | N/A                                 | 18  | ARTN  | Signal return for the 4 analog channel inputs (TAS5414A only)   |  |  |
| MUTE         | 6                     | 6                                   | 2   | Al  | Gain ramp control: mute (low), play (high)  |  |  |
| OSC_SYN<br>C | 1                     | 1                                   | 61  | DI/DO   | Oscillator sync input from master or output to slave amplifiers (20 MHz divided by 5, 6, or 7)                          |  |  |
| OUT1_M       | 34                    | 41                                  | 48  | PO  | - polarity output for bridge 1  |  |  |
| OUT1_P       | 33                    | 40                                  | 47  | PO  | + polarity output for bridge 1  |  |  |
| OUT2_M       | 31                    | 37                                  | 45  | PO  | - polarity output for bridge 2  |  |  |
| OUT2_P       | 30                    | 36                                  | 44  | PO  | + polarity output for bridge 2  |  |  |
| OUT3_M       | 25                    | 31                                  | 37  | PO  | - polarity output for bridge 3  |  |  |
| OUT3_P       | 24                    | 30                                  | 36  | PO  | + polarity output for bridge 3  |  |  |
| OUT4_M       | 22                    | 27                                  | 34  | PO  | - polarity output for bridge 4  |  |  |
| OUT4_P       | 21                    | 26                                  | 33  | PO  | + polarity output for bridge 4  |  |  |
| PVDD         | 19, 20, 35,<br>36     | 23, 24, 25,<br>42, 43, 44           | 27, 28, 29,<br>52, 53, 54   | PWR   | PVDD supply   |  |  |
| REXT         | 12                    | 13                                  | 10  | Al  | Precision resistor pin to set analog reference  |  |  |
| SCL          | 4                     | 4                                   | 64  | DI  | I <sup>2</sup> C clock input from system I <sup>2</sup> C master  |  |  |
| SDA          | 3                     | 3                                   | 63  | DI/DO   | I <sup>2</sup> C data I/O for communication with system I <sup>2</sup> C master   |  |  |
| STANDBY      | 7                     | 8                                   | 4   | DI  | Active-low STANDBY pin. Standby (low), power up (high)  |  |  |

<sup>(1)</sup> DI = digital input, DO = digital output, AI = analog input, ARTN = analog signal return, PWR = power supply, PGND = power ground, PBY = power bypass, PO = power output, AG = analog ground, DG = digital ground, CP = charge pump.



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#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)

|                                   |   |  | VALUE       | UNIT |
|-----------------------------------|---|--|-------------|------|
| PVDD                              | DC supply voltage range   | Relative to GND                              | -0.3 to 30  | V    |
| PVDD <sub>MAX</sub>               | Pulsed supply voltage range   | t ≤ 100 ms exposure                          | –1 to 50    | V    |
| PVDD <sub>RAMP</sub>              | Supply voltage ramp rate  |  | 15          | V/ms |
| I <sub>PVDD</sub>                 | Externally imposed dc supply current per PVDD or GND pin  |  | ±12         | Α    |
| I <sub>PVDD_MAX</sub>             | Pulsed supply current per PVDD pin (one shot)   | t < 100 ms                                   | 17          | Α    |
| I <sub>O</sub>                    | Maximum allowed dc current per output pin   |  | ±13.5       | Α    |
| I <sub>O_MAX</sub> <sup>(1)</sup> | Pulsed output current per output pin (single pulse)   | t < 100 ms                                   | ±17         | Α    |
| I <sub>IN_MAX</sub>               | Maximum current, all digital and analog input pins (2)  | DC or pulsed                                 | ±1          | mA   |
| I <sub>MUTE_MAX</sub>             | Maximum current on MUTE pin   | DC or pulsed                                 | ±20         | mA   |
| I <sub>IN_ODMAX</sub>             | Maximum sinking current for open-drain pins   |  | 7           | mA   |
| V <sub>LOGIC</sub>                | Input voltage range for logic pin relative to GND (SCL and SDA pins)                            | Supply voltage range:<br>6.5 V < PVDD < 24 V | -0.3 to 7   | V    |
| V <sub>I2C_ADDR</sub>             | Input voltage range for I2C_ADDR pin relative to GND  Supply voltage range: 6.5 V < PVDD < 24 V |  | -0.3 to 7   | V    |
| V <sub>STANDBY</sub>              | Input voltage range for STANDBY pin   | Supply voltage range:<br>6.5 V < PVDD < 24 V | -0.3 to 5.5 | V    |
| V <sub>OSC_SYNC</sub>             | Input voltage range for OSC_SYNC pin relative to GND  | Supply voltage range:<br>6.5 V < PVDD < 24 V | -0.3 to 3.6 | V    |
| V <sub>AIN_MAX</sub>              | Maximum instantaneous input voltage (per pin), analog input pins                                | Supply voltage range:<br>6.5 V < PVDD < 24 V | 6.5         | V    |
| V <sub>AIN_AC_MAX_5414</sub>      | Maximum ac-coupled input voltage for TAS5414A (2), analog input pins                            | Supply voltage range:<br>6.5 V < PVDD < 24 V | 0 to 6.5    | V    |
| V <sub>AIN_AC_MAX_5424</sub>      | Maximum ac-coupled differential input voltage for TAS5424A <sup>(2)</sup> , analog input pins   | Supply voltage range:<br>6.5 V < PVDD < 24 V | 0 to 6.5    | V    |
| V <sub>AIN_DC</sub>               | Input voltage range for analog pin relative to GND (INx pins)                                   | Supply voltage range:<br>6.5 V < PVDD < 24 V | -0.3 to 6.5 | V    |
| $V_{GND}$                         | Maximum voltage between GND pins  |  | ±0.3        | V    |
| T <sub>J</sub>                    | Maximum operating junction temperature range  |  | -55 to 150  | °C   |
| T <sub>stg</sub>                  | Storage temperature range   |  | -55 to 150  | °C   |
| Power dissipation                 | Continuous power dissipation  | T <sub>case</sub> = 70°C                     | 80          | W    |

<sup>(1)</sup> Pulsed current ratings are maximum survivable currents externally applied to the TAS5414A and TAS5424A. High currents may be encountered during reverse battery, fortuitous open ground, and fortuitous open supply fault conditions.

#### THERMAL CHARACTERISTICS

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|--|--|---|------|--|--|--|--|
|  | PARAMETER  | VALUE (Typical)   |      |  |  |  |  |
| $R_{\theta JC}$  | Junction-to-case (heat slug) thermal resistance, DKD package | 1   | °C/W |  |  |  |  |
| $R_{\theta JC}$  | Junction-to-case (heat slug) thermal resistance, PHD package | 1.2   | °C/W |  |  |  |  |
| $R_{\theta JA}$  | Junction-to-ambient thermal resistance                       | This device is not intended to be used without a heatsink. Therefore, $R_{\theta JA}$ is not specified. See the <i>Thermal Information</i> section. | °C/W |  |  |  |  |
|  | Exposed pad dimensions, DKD package                          | 13.8 × 5.8  | mm   |  |  |  |  |
|  | Exposed pad dimensions, PHD package                          | 8 × 8   | mm   |  |  |  |  |

# **RECOMMENDED OPERATING CONDITIONS<sup>(1)</sup>**

|                     |  | MIN | TYP  | MAX  | UNIT |
|---------------------|--|-----|------|------|------|
| PVDD <sub>OP</sub>  | DC supply voltage range relative to GND                | 8   | 14.4 | 22   | V    |
| PVDD <sub>I2C</sub> | DC supply voltage range for I <sup>2</sup> C reporting | 6   | 14.4 | 26.5 | V    |

<sup>(1)</sup> The Recommended Operating Conditions table specifies only that the device is functional in the given range. See the Electrical Characteristics table for specified performance limits.

<sup>(2)</sup> See Application Information section for information on analog input voltage and ac coupling.

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# RECOMMENDED OPERATING CONDITIONS<sup>(1)</sup> (continued)

|                           |   |  | MIN  | TYP      | MAX                   | UNIT |
|---------------------------|---|--|------|----------|-----------------------|------|
| V <sub>AIN_5414</sub> (2) | Analog audio input signal level (TAS5414A)  | AC-coupled input voltage   | 0    |          | 0.25-1 <sup>(3)</sup> | Vrms |
| V <sub>AIN_5424</sub> (2) | Analog audio input signal level (TAS5424A)  | AC-coupled input voltage   | 0    |          | 0.5-2(3)              | Vrms |
| f <sub>AUDIO_TW</sub>     | Audio frequency for tweeter detect  |  | 10   | 20       | 25                    | kHz  |
| T <sub>A</sub>            | Ambient temperature   |  | -40  |          | 105                   | °C   |
| TJ                        | Junction temperature  | An adequate heat sink is required to keep T <sub>J</sub> within specified range. | -40  |          | 115                   | °C   |
| $R_L$                     | Nominal speaker load impedance  |  | 2    | 4        |                       | Ω    |
| V <sub>PU</sub>           | Pullup voltage supply (for open-drain logic outputs)  |  | 3    | 3.3 or 5 | 5.5                   | V    |
| R <sub>PU_EXT</sub>       | External pullup resistor on open-drain logic outputs  | Resistor connected between open-drain logic output and V <sub>PU</sub> supply    | 10   | 47       | 100                   | kΩ   |
| R <sub>PU_I2C</sub>       | I <sup>2</sup> C pullup resistance on SDA and SCL pins  |  | 1    | 4.7      | 10                    | kΩ   |
| R <sub>I2C_ADD</sub>      | Total resistance of voltage divider for I <sup>2</sup> C address slave 1 or slave 2, connected between D_BYP and GND pins |  | 10   |          | 100                   | kΩ   |
| R <sub>REXT</sub>         | External resistance on REXT pin   | 1% tolerance required  | 19.8 | 20       | 20.2                  | kΩ   |
| C <sub>D_BYP</sub>        | External capacitance on D_BYP pin   |  | 10   |          | 120                   | nF   |
| C <sub>A_BYP</sub>        | External capacitance on A_BYP pin   |  | 10   |          | 120                   | nF   |
| C <sub>IN</sub>           | External capacitance to analog input pin in series with input signal  |  |      | 1        |                       | μF   |
| C <sub>FLY</sub>          | Flying capacitor on charge pump   |  | 0.47 | 1        | 1.5                   | μF   |
| C <sub>P</sub>            | Charge pump capacitor   |  | 0.47 | 1        | 1.5                   | μF   |
| C <sub>MUTE</sub>         | Capacitance on MUTE pin   |  | 100  | 330      |                       | nF   |
| C <sub>OSCSYNC_MAX</sub>  | Allowed loading capacitance on OSC_SYNC pin   |  |      | 5        |                       | pF   |

Signal input for full unclipped output with gains of 32 dB, 26 dB, 20 dB, and 12 dB Maximum recommended input voltage is determined by the gain setting.



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# **ELECTRICAL CHARACTERISTICS**

Test conditions (unless otherwise noted):  $T_{Case} = 25^{\circ}C$ , PVDD = 14.4 V,  $R_{L} = 4 \Omega$ ,  $f_{S} = 417$  kHz,  $P_{out} = 1$  W/ch, Rext = 20 k $\Omega$ , AES17 Filter, master mode operation (see application diagram)

|                          | PARAMETER                                       | TEST CONDITIONS  | MIN      | TYP   | MAX  | UNIT   |
|--------------------------|---|--|----------|-------|------|--------|
| OPERATING C              | CURRENT   |  |          |       |      |        |
| I <sub>PVDD_IDLE</sub>   |   | All four channels running in MUTE mode   |          | 240   | 300  |        |
| I <sub>PVDD_Hi-Z</sub>   | PVDD idle current                               | All four channels in Hi-Z mode   |          | 80    |      | mA     |
| I <sub>PVDD_STBY</sub>   | PVDD standby current                            | STANDBY mode, T <sub>.1</sub> ≤ 85°C   |          | 2     | 20   | μA     |
| OUTPUT POW               | ·   | , ,  |          |       |      |        |
|                          |   | $4 \Omega$ , PVDD = 14.4 V, THD+N ≤ 1%, 1 kHz, $T_c = 75$ °C   |          | 23    |      |        |
|                          |   | 4 Ω, PVDD = 14.4 V, THD+N = 10%, 1 kHz, T <sub>c</sub> = 75°C  | 25       | 28    |      |        |
|                          |   | $4 \Omega$ , PVDD = 14.4 V, square wave, 1 kHz, $T_c = 75$ °C  |          | 43    |      |        |
|                          |   | 4 $\Omega$ , PVDD = 21 V, THD+N = 1%, 1 kHz, $T_c$ = 75°C  |          | 47    |      |        |
|                          |   | 4 Ω, PVDD = 21 V, THD+N = 10%, 1 kHz, T <sub>c</sub> = 75°C  | 50       | 58    |      |        |
| D                        | Output newer per channel                        | 2 Ω, PVDD = 14.4 V, THD+N = 1%, 1 kHz, T <sub>G</sub> = 75°C   |          | 38    |      | W      |
| P <sub>OUT</sub>         | Output power per channel                        | $2 \Omega$ , PVDD = 14.4 V, THD+N = 10%, 1 kHz, $T_c = 75$ °C  | 40       | 45    |      | VV     |
|                          |   | $2 Ω$ , PVDD = 14.4 V, square wave 1 kHz, $T_c = 75$ °C  | 40       | 70    |      |        |
|                          |   | PBTL 2- $\Omega$ operation, PVDD = 21 V, THD+N = 10%,  |          |       |      |        |
|                          |   | 1 kHz, T <sub>c</sub> = 75°C   |          | 116   |      |        |
|                          |   | PBTL 1-Ω operation, PVDD = 14.4 V, THD+N = 10%,  |          | 90    |      |        |
|                          |   | 1 kHz, $T_c = 75^{\circ}C$   |          | 30    |      |        |
| EFF <sub>P</sub>         | Power efficiency                                | 4 channels operating, 23-W output power/ch, L = 10 $\mu$ H, T, $\leq$ 85°C   |          | 90%   |      |        |
| AUDIO PERFO              | DRMANCE   | , ,  |          |       |      |        |
| V <sub>NOISE</sub>       | Noise voltage at output                         | G = 26 dB, zero input, and A-weighting   |          | 60    | 100  | μV     |
| Crosstalk                | Channel crosstalk                               | 1 W, G = 26 dB, 1 kHz  | 60       | 75    |      | dB     |
| CMRR <sub>5424</sub>     | Common-mode rejection ratio (TAS5424A)          | 1 kHz, 1 Vrms referenced to GND, G = 26 dB   | 60       | 75    |      | dB     |
| PSRR                     | Power supply rejection ratio                    | G = 26 dB, PVDD = 14.4 Vdc + 1 Vrms, f = 1 kHz   | 60       | 75    |      | dB     |
| THD+N                    | Total harmonic distortion + noise               | P = 1 W, G = 26 dB, f = 1 kHz, 0°C ≤ T <sub>J</sub> ≤ 75°C   |          | 0.02% | 0.1% |        |
|                          |   |  | 336      | 357   | 378  |        |
| $f_S$                    | Switching frequency                             | Switching frequency selectable for AM interference   | 392      | 417   | 442  | kHz    |
| '5                       | ewitering inequency                             | avoidance  | 470      | 500   | 530  | 131 12 |
| R <sub>AIN</sub>         | Analog input resistance                         | Internal shunt resistance on each input pin  | 60       | 80    | 100  | kΩ     |
| V <sub>CM_INT</sub>      | Internal common-mode input bias voltage         | Internal bias applied to IN_M pin  | 00       | 3.25  | 100  | V      |
| V CM_IN I                | internal common mode input blas voltage         | memai bias applied to fiv_wi pin   | 11       | 12    | 13   |        |
|                          |   |  | 19       | 20    | 21   |        |
| G                        | Voltage gain (V <sub>O</sub> /V <sub>IN</sub> ) | Source impedance = $0 \Omega$ , gain measurement taken at 1 W of power per channel   |          | 26    | 27   | dB     |
|                          |   | The second per second s | 25<br>31 | 32    | 33   |        |
| <u> </u>                 | Channel-to-channel variation                    | Any gain commanded   | -1       | 0     | 1    | dB     |
| G <sub>CH</sub>          | Output-voltage common-mode ramping time         | Any gain commanded   | -1       | 35    |      |        |
| t <sub>CM</sub>          | Gain ramping time                               | 111012   |          | 30    |      | ms     |
| t <sub>GAIN</sub>        | 1 0   | External C <sub>MUTE</sub> = 330 nF  |          | 30    |      | ms     |
| PWM OUTPUT               | FET drain-to-source resistance                  | Not including hand wire registence, T = 25°C   |          | 75    | 95   | mΩ     |
| R <sub>DS(on)</sub>      | FET drain-to-source resistance                  | Not including bond wire resistance, T <sub>J</sub> = 25°C  Zero input signal, dc offset reduction enabled, and   |          | 75    | 90   | 11122  |
| $V_{O\_OFFSET}$          | Output offset voltage                           | G = 26 dB  |          | ±10   | ±25  | mV     |
| PVDD OVERVO              | OLTAGE (OV) PROTECTION                          |  |          |       |      |        |
| $V_{OV}$                 | PVDD overvoltage shutdown                       |  | 22.1     | 23.7  | 26.3 | V      |
| LOAD DUMP (              | (LD) PROTECTION                                 |  |          |       |      |        |
| $V_{LD\_SD\_SET}$        | Load-dump shutdown voltage                      |  | 26.6     | 29    | 32   | V      |
| V <sub>LD_SD_CLEAR</sub> | Recovery voltage for load-dump shutdown         |  | 23.5     | 26.4  | 28.4 | V      |
| PVDD UNDER               | VOLTAGE (UV) PROTECTION                         |  |          |       |      |        |
| V <sub>UV_SET</sub>      | PVDD undervoltage shutdown                      |  | 6.5      | 7     | 7.5  | V      |
| V <sub>UV_CLEAR</sub>    | Recovery voltage for PVDD UV                    |  | 7        | 7.5   | 8    | V      |
| AVDD                     |   |  |          |       |      |        |
| V <sub>A_BYP</sub>       | A_BYP pin voltage                               |  |          | 6.5   |      | V      |



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### **ELECTRICAL CHARACTERISTICS (continued)**

Test conditions (unless otherwise noted):  $T_{Case} = 25^{\circ}C$ , PVDD = 14.4 V,  $R_{L} = 4 \Omega$ ,  $f_{S} = 417$  kHz,  $P_{out} = 1$  W/ch, Rext = 20 k $\Omega$ , AES17 Filter, master mode operation (see application diagram)

|  | PARAMETER  | TEST CONDITIONS  | MIN  | TYP  | MAX  | UNIT  |
|--|--|--|------|------|------|-------|
| V <sub>A_BYP_UV_SET</sub>                          | A_BYP UV voltage   |  |      | 4.8  |      | V     |
| V <sub>A_BYP_UV_CLEAR</sub>                        | Recovery voltage A_BYP UV  |  |      | 5.3  |      | V     |
| DVDD   |  |  |      |      | ļ    |       |
| V <sub>D BYP</sub>                                 | D_BYP pin voltage  |  |      | 3.3  |      | V     |
| POWER-ON RES                                       |  | I  |      |      |      |       |
| V <sub>POR</sub>                                   | Maximum PVDD voltage for POR; I <sup>2</sup> C active above this voltage   |  |      |      | 6    | V     |
| V <sub>POR_HY</sub>                                | PVDD recovery hysteresis voltage for POR                                   |  |      | 0.1  |      | V     |
| REXT   |  |  |      |      |      |       |
| V <sub>REXT</sub>                                  | Rext pin voltage   |  |      | 1.24 |      | V     |
| CHARGE PUMP  |  |  |      |      |      |       |
| V <sub>CPUV_SET</sub>                              | CP undervoltage  |  |      | 4.8  |      | V     |
| V <sub>CPUV</sub> CLEAR                            | Recovery voltage for CP UV   |  |      | 5.2  |      | V     |
|  | TURE (OT) PROTECTION   | <u> </u>   |      | 0.2  |      | •     |
| T <sub>OTW1 CLEAR</sub>                            |  |  | 102  | 115  | 128  |       |
| T <sub>OTW1_SET</sub> /                            | -  |  |      |      |      |       |
| TOTW1_SET /<br>TOTW2_CLEAR                         | lunation townsor-turn for our  |  | 112  | 125  | 138  |       |
| T <sub>OTW2_SET</sub> /<br>T <sub>OTW3_CLEAR</sub> | Junction temperature for overtemperature warning                           |  | 122  | 135  | 148  | °C    |
| T <sub>OTW3_SET</sub> /<br>T <sub>OTSD_CLEAR</sub> |  |  | 132  | 145  | 158  |       |
| T <sub>OTSD</sub>                                  | Junction temperature for overtemperature shutdown                          |  | 142  | 155  | 168  |       |
| CURRENT LIMIT                                      | ING PROTECTION   |  |      |      |      |       |
| I <sub>LIM1</sub>                                  | Current limit 1 (load current)   | Load < 4 Ω   | 5.5  | 7.3  | 9    | Α     |
| I <sub>LIM2</sub>                                  | Current limit 2 (load current), through I <sup>2</sup> C setting           | Load < 2 Ω   | 8.5  | 11   | 13.5 | Α     |
| OVERCURRENT  | (OC) SHUTDOWN PROTECTION   | I  |      |      |      |       |
| I <sub>MAX1</sub>                                  | Maximum current 1 (peak output current)                                    |  | 9.5  | 11.3 | 13   | Α     |
| I <sub>MAX2</sub>                                  | Maximum current 2 (peak output current)                                    | Any short to supply, ground, or other channels             | 11.5 | 14.3 | 17   | Α     |
| TWEETER DETE                                       |  |  |      |      |      |       |
| I <sub>TH_TW</sub>                                 | Load current threshold for tweeter detect                                  |  | 325  | 540  | 750  | mA    |
| I <sub>LIM TW</sub>                                | Load current limit for tweeter detect                                      |  |      | 2    |      | Α     |
| STANDBY MODE                                       |  |  |      |      |      |       |
| V <sub>IH_STBY</sub>                               | STANDBY input voltage for logic-level high                                 |  | 2    |      | 5.5  | V     |
| V <sub>IL_STBY</sub>                               | STANDBY input voltage for logic-level low                                  |  | 0    |      | 0.7  | V     |
| I <sub>STBY PIN</sub>                              | STANDBY pin current  |  |      | 0.1  | 0.2  | μA    |
| MULE WODE  |  | 1  |      | J    | U    | ha. , |
| G <sub>MUTE</sub>                                  | Output attenuation   | MUTE pin ≤ 0.9 Vdc, V <sub>IN</sub> = 1 Vrms on all inputs |      | 85   |      | dB    |
| DC DETECT  | 4  |  |      |      |      |       |
| V <sub>TH DCD POS</sub>                            | DC detect positive threshold default value                                 | PVDD = 14.4 Vdc, register 0x0E = 8EH                       |      | 6.5  |      | V     |
| V <sub>TH_DCD_POS</sub>                            | DC detect negative threshold default value                                 | PVDD = 14.4 Vdc, register 0x0F = 3DH                       |      | -6.5 |      | V     |
| t <sub>DCD</sub>                                   | DC detect step response time for four channels                             |  |      | 5.0  | 4.3  | s     |
| CLIP_OTW REPO                                      |  |  |      |      |      |       |
| V <sub>OH_CLIPOTW</sub>                            | CLIP_OTW pin output voltage for logic level high (open-drain logic output) |  | 2.4  |      |      | V     |
| V <sub>OL_CLIPOTW</sub>                            | CLIP_OTW pin output voltage for logic level low (open-drain logic output)  | External 47-kΩ pullup resistor to 3 V–5.5 V                |      |      | 0.5  | V     |
| =- =:::  |  |  |      |      |      |       |
| t <sub>DELAY_CLIPDET</sub>                         | CLIP_OTW signal delay when output clipping detected                        |  |      |      | 20   | μs    |



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# **ELECTRICAL CHARACTERISTICS (continued)**

Test conditions (unless otherwise noted):  $T_{Case} = 25^{\circ}C$ , PVDD = 14.4 V,  $R_L = 4~\Omega$ ,  $f_S = 417$  kHz,  $P_{out} = 1$  W/ch, Rext = 20 k $\Omega$ , AES17 Filter, master mode operation (see application diagram)

|                                     | PARAMETER   | TEST CONDITIONS   | MIN  | TYP  | MAX  | UNIT         |
|-------------------------------------|---|---|------|------|------|--------------|
| $V_{OH\_FAULT}$                     | FAULT pin output voltage for logic-level high (open-drain logic output) | External 47-kΩ pullup resistor to 3 V–5.5 V                                       | 2.4  |      |      | V            |
| V <sub>OL_FAULT</sub>               | FAULT pin output voltage for logic-level low (open-drain logic output)  | External 47-A22 pullup resistor to 5 V=5.5 V                                      |      |      | 0.5  | V            |
| OPEN/SHORT D                        | IAGNOSTICS  |   |      |      |      |              |
| R <sub>S2P</sub> , R <sub>S2G</sub> | Maximum resistance to detect a short from OUT pin(s) to PVDD or ground  |   |      |      | 200  | Ω            |
| R <sub>OPEN_LOAD</sub>              | Minimum load resistance to detect open circuit                          | Including speaker wires   | 300  | 800  | 1300 | Ω            |
| R <sub>SHORTED_LOAD</sub>           | Maximum load resistance to detect short circuit                         | Including speaker wires   | 0.5  | 1    | 1.5  | Ω            |
| I <sup>2</sup> C ADDRESS D          | ECODER  |   |      |      |      |              |
| t <sub>LATCH_I2CADDR</sub>          | Time delay to latch I <sup>2</sup> C address after POR                  |   |      | 300  |      | μs           |
|                                     | Voltage on I2C_ADDR pin for address 0                                   | Connect to GND  | 0%   | 0%   | 15%  |              |
|                                     | Voltage on I2C_ADDR pin for address 1                                   | External resistors in series between D_BYP and GND as                             | 25%  | 35%  | 45%  | 1            |
| V <sub>I2C_ADDR</sub>               | Voltage on I2C_ADDR pin for address 2                                   | a voltage divider   | 55%  | 65%  | 75%  | $V_{D\_BYP}$ |
|                                     | Voltage on I2C_ADDR pin for address 3                                   | Connect to D_BYP  |      | 100% | 100% |              |
| I <sup>2</sup> C                    |   |   |      |      |      |              |
| t <sub>HOLD_I2C</sub>               | Power-on hold time before I <sup>2</sup> C communication                | STANDBY high  |      | 1    |      | ms           |
| f <sub>SCL</sub>                    | SCL clock frequency   |   |      |      | 100  | kHz          |
| V <sub>IH_SCL</sub>                 | SCL pin input voltage for logic-level high                              | 5   |      |      | 5.5  | V            |
| V <sub>IL_SCL</sub>                 | SCL pin input voltage for logic-level low                               | $R_{PU\_I2C} = 5-k\Omega$ pullup, supply voltage = 3.3 V or 5 V                   |      |      | 1.1  | V            |
| $V_{OH\_SDA}$                       | SDA pin output voltage for logic-level high                             | $I^2$ C read, $R_{12C}$ = 5-kΩ pullup,<br>supply voltage = 3.3 V or 5 V           | 2.4  |      |      | V            |
| V <sub>OL_SDA</sub>                 | SDA pin output voltage for logic-level low                              | I <sup>2</sup> C read, 3-mA sink current  | 0    |      | 0.4  | V            |
| $V_{IH\_SDA}$                       | SDA pin input voltage for logic-level high                              | $I^2$ C write, $R_{I2C}$ = 5-kΩ pullup,<br>supply voltage = 3.3 V or 5 V          | 2.1  |      | 5.5  | V            |
| $V_{IL\_SDA}$                       | SDA pin input voltage for logic-level low                               | I <sup>2</sup> C write, $R_{I2C}$ = 5-kΩ pullup,<br>supply voltage = 3.3 V or 5 V | -0.5 |      | 1.1  | V            |
| Cı                                  | Capacitance for SCL and SDA pins  |   |      |      | 10   | pF           |
| OSCILLATOR                          |   |   |      |      |      |              |
| V <sub>OH_OSCSYNC</sub>             | OSC_SYNC pin output voltage for logic-level high                        | IOO ARRE : AA MAOTER :  | 2.4  |      | 3.6  | V            |
| V <sub>OL_OSCSYNC</sub>             | OSC_SYNC pin output voltage for logic-level low                         | I2C_ADDR pin set to MASTER mode   |      |      | 0.5  | V            |
| V <sub>IH_OSCSYNC</sub>             | OSC_SYNC pin input voltage for logic-level high                         | 100 ADDD : 44 OLAVE   | 2    |      | 3.6  | V            |
| V <sub>IL_OSCSYNC</sub>             | OSC_SYNC pin input voltage for logic-level low                          | I2C_ADDR pin set to SLAVE mode  |      |      | 0.8  | V            |
|                                     |   | I2C_ADDR pin set to MASTER mode, f <sub>S</sub> = 500 kHz                         | 3.76 | 4.0  | 4.24 |              |
| f <sub>OSC_SYNC</sub>               | OSC_SYNC pin clock frequency  | I2C_ADDR pin set to MASTER mode, f <sub>S</sub> = 417 kHz                         | 3.13 | 3.33 | 3.63 | MHz          |
|                                     |   | I2C_ADDR pin set to MASTER mode, f <sub>S</sub> = 357 kHz                         | 2.68 | 2.85 | 3.0  |              |

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# TIMING REQUIREMENTS FOR I2C INTERFACE SIGNALS

over recommended operating conditions (unless otherwise noted)

|                   | PARAMETER  | MIN              | TYP | MAX  | UNIT |
|-------------------|--|------------------|-----|------|------|
| t <sub>r</sub>    | Rise time for both SDA and SCL signals                               |                  |     | 1000 | ns   |
| t <sub>f</sub>    | Fall time for both SDA and SCL signals                               |                  |     | 300  | ns   |
| t <sub>w(H)</sub> | SCL pulse duration, high   | 4                |     |      | μs   |
| t <sub>w(L)</sub> | SCL pulse duration, low  | 4.7              |     |      | μs   |
| t <sub>su2</sub>  | Setup time for START condition                                       | 4.7              |     |      | μs   |
| t <sub>h2</sub>   | START condition hold time after which first clock pulse is generated | 4                |     |      | μs   |
| t <sub>su1</sub>  | Data setup time  | 250              |     |      | ns   |
| t <sub>h1</sub>   | Data hold time   | 0 <sup>(1)</sup> |     |      | ns   |
| t <sub>su3</sub>  | Setup time for STOP condition  | 4                |     |      | μs   |
| C <sub>B</sub>    | Load capacitance for each bus line                                   |                  |     | 400  | pF   |

(1) A device must internally provide a hold time of at least 300 ns for the SDA signal to bridge the undefined region of the falling edge of SCL.

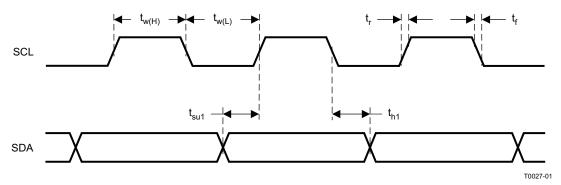


Figure 1. SCL and SDA Timing

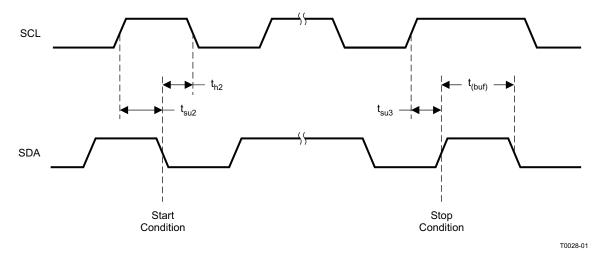
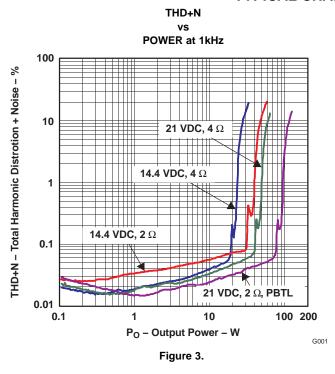
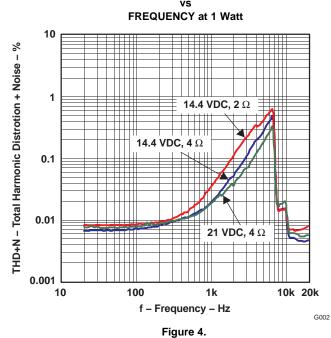


Figure 2. Timing for Start and Stop Conditions



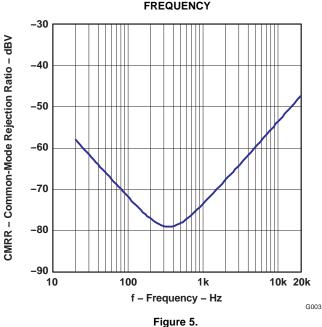
### TYPICAL CHARACTERISTICS

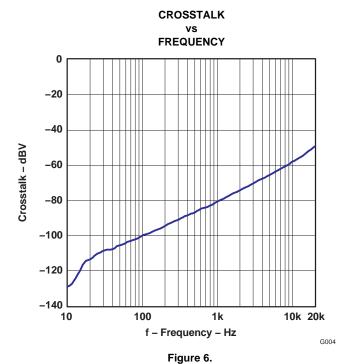




THD+N

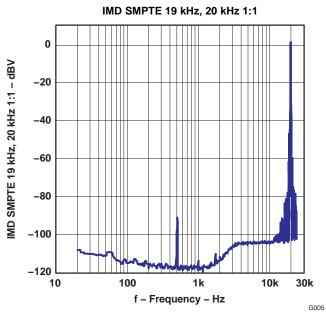
TAS5424A
COMMON-MODE REJECTION RATIO
vs
FREQUENCY





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# TYPICAL CHARACTERISTICS (continued)



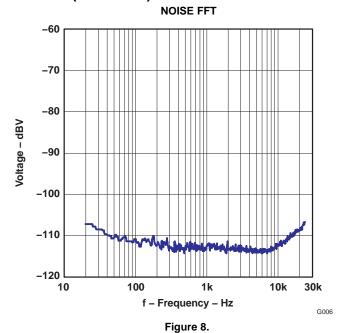


Figure 7.



DEVICE POWER DISSIPATION FOUR CHANNELS AT 4  $\Omega$  EACH

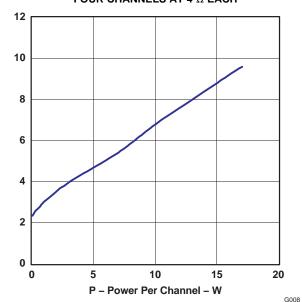


Figure 10.



# **TYPICAL CHARACTERISTICS (continued)**

DC DETECT VOLTAGE vs

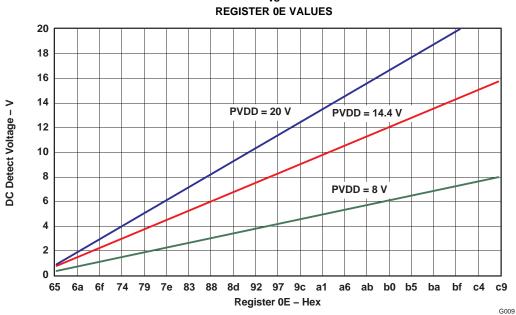


Figure 11.

DC DETECT VOLTAGE

VS

DEGISTED OF VALUES

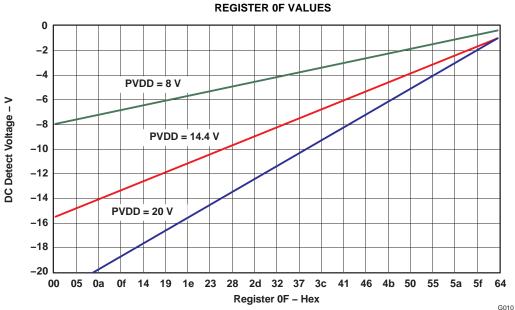


Figure 12.

TEXAS INSTRUMENTS

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#### **DESCRIPTION OF OPERATION**

#### **OVERVIEW**

The TAS5414A and TAS5424A are single-chip, four-channel, analog-input audio amplifiers for use in the automotive environment. The design uses an ultra-efficient class-D technology developed by Texas Instruments, but with changes needed by the automotive industry. This technology allows for reduced power consumption, reduced heat, and reduced peak currents in the electrical system. The TAS5414A and TAS5424A realize an audio sound system design with smaller size and lower weight than traditional class-AB solutions.

The TAS5414A and TAS5424A are composed of eight elements:

- Preamplifier
- PWM
- Gate drive
- Power FETs
- Diagnostics
- Protection
- Power supply
- I<sup>2</sup>C serial communication bus

### **Preamplifier**

The preamplifier of the TAS5414A and TAS5424A is a high-input-impedance, low-noise, low-offset-voltage input stage with adjustable gain. The high input impedance of the TAS5414A and TAS5424A allows the use of low-cost 1-µF input capacitors while still achieving extended low-frequency response. The preamplifier is powered by a dedicated, internally regulated supply, which gives it excellent noise immunity and channel separation. Also included in the preamp are:

- 1. **Mute Pop-and-Click Control**—An audio input signal is reshaped and amplified as a step when a mute is applied at the crest or trough of the signal. Such a step is perceived as a loud click. This is avoided in the TAS5414A and TAS5424A by ramping the gain gradually when a mute or play command is received. Another form of click and pop can be caused by the start or stopping of switching in a class-D amplifier. The TAS5414A and TAS5424A incorporate a patented method to reduce the pop energy during the switching startup and shutdown sequence. Fault conditions require rapid protection response by the TAS5414A and the TAS5424A, which do not have time to ramp the gain down in a pop-free manner. The device transitions into Hi-Z mode when an OV, UV, OC, OT, or DC fault is encountered. Also, activation of the STANDBY pin may not be pop-free.
- 2. **Gain Control**—The four gain settings are set in the preamplifier via I<sup>2</sup>C control registers. The gain is set outside of the global feedback resistors of the TAS5414A and the TAS5424A, thus allowing for stability in the system all gain settings with properly loaded conditions.
- 3. **DC Offset Reduction Circuitry**—Circuitry has been incorporated to reduce the dc offset. DC offset in high-gain amplifiers can produce audible clicks and pops when the amplifier is started or stopped. The offset reduction circuitry can be disabled or enabled via I<sup>2</sup>C.

### **Pulse-Width Modulator (PWM)**

The PWM converts the analog signal from the preamplifier into a switched signal of varying duty cycle. This is the critical stage that defines the class-D architecture. In the TAS5414A and TAS5424A, the modulator is an advanced design with high bandwidth, low noise, low distortion, excellent stability, and full 0–100% modulation capability. The patented PWM uses clipping recovery circuitry to eliminate the deep saturation characteristic of PWMs when the input signal exceeds the modulator waveform.

### **Gate Drive**

The gate driver accepts the low-voltage PWM signal and level shifts it to drive a high-current, full-bridge, power FET stage. The TAS5414A and TAS5424A use patent-pending techniques to avoid shoot-through and are optimized for EMI and audio performance.

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#### **Power FETs**

The BTL output for each channel comprises four rugged N-channel 30-V FETs, each of which has an  $R_{DSon}$  of 75 m $\Omega$  for high efficiency and maximum power transfer to the load. These FETs are designed to handle large voltage transients during load dump.

### **Load Diagnostics**

The TAS5414A and TAS5424A incorporate load diagnostic circuitry designed to help pinpoint the nature of output misconnections during installation. The TAS5414A and the TAS5424A include functions for detecting and determining the status of output connections. The following diagnostics are supported:

- Short to GND
- Short to PVDD
- Short across load (R < 1 Ω, typical)</li>
- Open load (R > 800 Ω, typical)
- · Tweeter detection

The presence of any of the short o<u>r open cond</u>itions is reported to the system via I<sup>2</sup>C register read. The tweeter detect status can be read from the CLIP\_OTW pin when properly configured.

1. **Output Short and Open Diagnostics**—The TAS5414A and TAS5424A contain circuitry designed to detect shorts and open conditions on the outputs. The load diagnostic function can only be invoked when the output is in the Hi-Z mode. There are four phases of test during load diagnostics and two levels of test. In the full level, all channels must be in the Hi-Z state. All four phases are tested on each channel, all four channels at the same time. When fewer than four channels are in Hi-Z, the reduced level of test is the only available option. In the reduced level, only short to PVDD and short to GND can be tested. Load diagnostics can occur at power up before the amplifier is moved out of Hi-Z mode. If the amplifier is already in play mode, it must *Mute* and then *Hi-Z* before the load diagnostic can be performed. By performing the mute function, the normal pop- and click-free transitions occur before the diagnostics begin. The diagnostics are performed as shown in Figure 13. Figure 14 shows the impedance ranges for the open-load and shorted-load diagnostics. The results of the diagnostic are read from the diagnostic register for each channel via I<sup>2</sup>C. **Note:** Do not send a command via I<sup>2</sup>C to register 0x0C during the load diagnostic test.

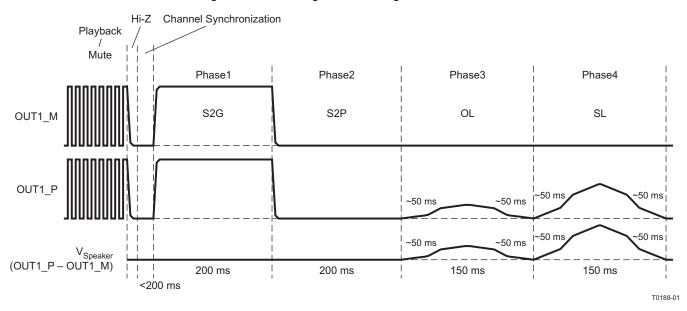


Figure 13. Load Diagnostics Sequence of Events

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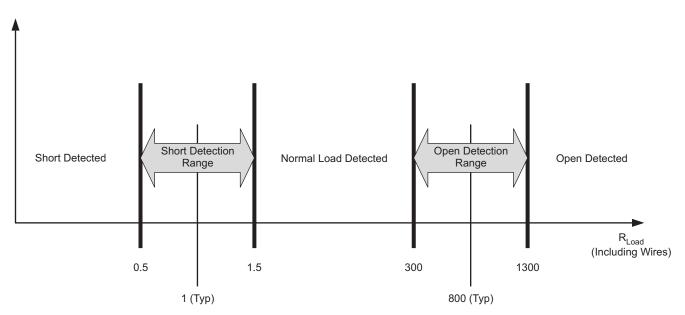


Figure 14. Open and Shorted Load Detection

M0067-01

2. Tweeter Detection— Tweeter detection is an alternate operating mode that is used to determine the proper connection of a frequency dependent load (such as a speaker with a crossover). Tweeter detection is invoked via I<sup>2</sup>C, and all four channels should be tested individually. Tweeter detection uses the average cycle-by-cycle current limit circuit (see CBC section) to measure the current delivered to the load. The proper implementation of this diagnostic function is dependent on the amplitude of a user-supplied test signal and on the impedance versus frequency curve of the acoustic load. The system (external to the TAS5414A and TAS5424A) must generate a signal to which the load will respond. The frequency and amplitude of this signal must be calibrated by the user to result in a current draw that is greater than the tweeter detection threshold when the load under test is present, and less than the detection threshold if the load is not properly connected. The current level for the tweeter detection threshold, as well as the maximum current that can safely be delivered to a load when in tweeter detection mode, can be found in the Electrical Characteristics section of the datasheet. The tweeter detection results are reported on the CLIP\_OTW pin during the application of the test signal. When tweeter detection is activated (indicating that the tested load is present), pulses on the CLIP\_OTW pin begin to toggle. The pulses on the CLIP\_OTW pins will report low whenever the current detection threshold is exceeded, and the pin will remain low until the threshold is no longer exceeded. The minimum low-pulse period that can be expected is equal to one period of the switching frequency. Having an input signal that increases the amount of time that the detector is activated (e. g. increasing the amplitude of the input signal) will increase the amount of time for which the pin reports low. NOTE: Because tweeter detection is an alternate operating mode, the channels to be tested must be placed in Play mode (via register 0x0C) after tweeter detection has been activated in order to commence the detection process. Additionally, the CLIP\_OTW pin must be set up via register 0x0A to report the results of tweeter detection.

#### **Protection and Monitoring**

- 1. Cycle-By-Cycle Current Limit (CBC)—The CBC current-limiting circuit terminates each PWM pulse to limit the output current flow when the average current limit (I<sub>LIM</sub>) threshold is exceeded. The overall effect on the audio in the case of a current overload is quite similar to a voltage-clipping event, where power is temporarily limited at the peaks of the musical signal and normal operation continues without disruption when the overload is removed. The TAS5414A and TAS5424A do not prematurely shut down in this condition. All four channels continue in play mode and pass signal.
- 2. Overcurrent Shutdown (OCSD)—Under severe short-circuit events, such as a short to PVDD or ground, a peak-current detector is used, and the affected channel shuts down in 200 μs to 390 μs if the conditions are severe enough. The shutdown speed depends on a number of factors, such as the impedance of the short circuit, supply voltage, and switching frequency. Only the shorted channels are shut down in such a scenario.



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The user may restart the affected channel via I<sup>2</sup>C. An OCSD event activates the fault pin, and the affected channel(s) are recorded in the I<sup>2</sup>C fault register. If the supply or ground short is strong enough to exceed the peak current threshold but not severe enough to trigger the OCSD, the peak current limiter prevents excess current from damaging the output FETs, and operation returns to normal after the short is removed.

- 3. **DC Detect**—This circuit detects a dc offset continuously during normal operation at the output of the amplifier. If the dc offset reaches the level defined in the I<sup>2</sup>C registers for the specified time period, the circuit triggers. By default a dc detection event does not shut the output down. The shutdown function can be enabled or disabled via I<sup>2</sup>C. If enabled, the triggered channel shuts down, but the others remain playing and the FAULT pin is asserted. The positive dc level and negative dc level are defined in I<sup>2</sup>C registers and can have separate thresholds.
- 4. Clip Detect—The clip detect circuit alerts the user to the presence of a 100% duty-cycle PWM due to a clipped waveform. When this occurs, a signal is passed to the CLIP\_OTW pin and it is asserted until the 100% duty-cycle PWM signal is no longer present. All four channels are connected to the same CLIP\_OTW pin. Through I<sup>2</sup>C, the CLIP\_OTW signal can be changed to clip-only, OTW-only, or both. A fourth mode, used only during diagnostics, is the option to report tweeter detection events on this pin (see the *Tweeter Detection* section). The microcontroller in the system can monitor the signal at the CLIP\_OTW pin and may be configured to reduce the volume to all four channels in an active clipping-prevention circuit.
- 5. Overtemperature Warning (OTW) and Overtemperature Shutdown (OTSD)—By default, the CLIP\_OTW pin is set to indicate an OTW. This can be changed via I<sup>2</sup>C commands. If selected to indicate a temperature warning, the CLIP\_OTW pin is asserted when the die temperature reaches 125°C. The OTW has three temperature thresholds with a 10°C hysteresis. Each threshold is indicated in I<sup>2</sup>C register 0x04 bits 5, 6, and 7. The TAS5414A and TAS5424A still function until the temperature reaches the OTSD threshold, 155°C, at which time the outputs are placed into Hi-Z mode and the FAULT pin is asserted. I<sup>2</sup>C is still active in the event of an OTSD and the registers can be read for faults, but all audio ceases abruptly. The OTSD resets at 145°C, to allow the TAS5414A/5424A to be turned back on through I<sup>2</sup>C. The OTW is still indicated until the temperature drops below 115°C. All temperatures are nominal values.

### **CAUTION**

CAUTIONARY NOTE: The PHD package version of the TAS5414A has a thermal weakness when any channel is outputting high current. The TAS5414A PHD may experience permanent thermal-related damage when high output current causes heating in the output stages of the device. Typical dangerous scenarios include shorted output loads and when delivering high power to low-impedance loads. The DKD versions of the TAS5414A and TAS5424A do not have this thermal weakness and are not at risk for damage due to these conditions. Please contact Texas Instruments directly for further application details.

- 6. Undervoltage (UV) and Power-on-Reset (POR)—The undervoltage (UV) protection detects low voltages on PVDD, AVDD, and CP. In the event of an undervoltage, the FAULT pin is asserted and the I<sup>2</sup>C register is updated, depending on which voltage caused the event. Power-on-reset (POR) occurs when PVDD drops low enough. A POR event causes the I<sup>2</sup>C to go into a high-impedance state. After the device recovers from the POR event, the device must be re-initialized via I<sup>2</sup>C.
- 7. Overvoltage (OV) and Load <u>Dump</u>—The OV protection detects high voltages on PVDD. If PVDD reaches the overvoltage threshold, the FAULT pin is asserted and the I²C register is updated. If the voltage increases beyond the load dump threshold of 29 Vdc, the device shuts down and must be restarted once the voltage returns to a safe value. After the device recovers from the ≉ load dump event, the device must be re-initialized via I²C. The TAS5414A and TAS5424A can withstand 50-V load-dump voltage spikes (see Figure 15). Also depicted in this graph are the voltage thresholds for normal operation region, overvoltage operation region, and load-dump protection region. Figure 13 shows the regions of operating voltage and the profile of the load dump event. Battery charger voltages from 25 V to 35 V can be withstood for up to 1 hour.

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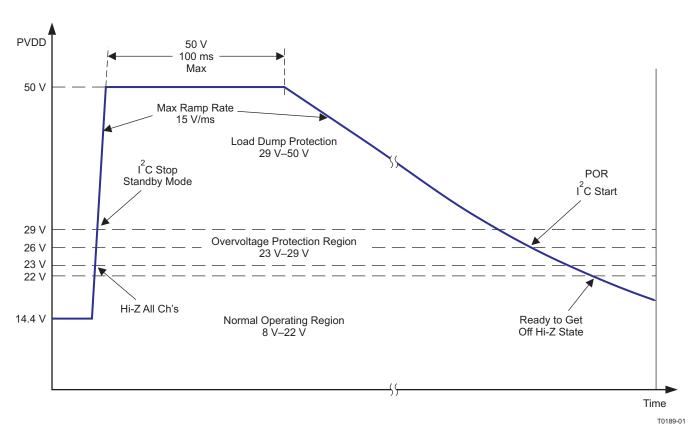


Figure 15. Voltage Operating Regions With Load Dump Transition Defined

### **Power Supply**

The power for the device is most commonly provided by a car battery that can have a large voltage swing, 8 Vdc to 18 Vdc. PVDD is a filtered battery voltage, and it is the supply for the output FETS and the low-side FET gate driver. The high-side FET gate driver is supplied by a charge pump (CP) supply. The charge pump supplies the gate drive voltage for all four channels. The analog circuitry is powered by AVDD, which is a provided by an internal linear regulator. A 0.1µF/10V external bypass capacitor is needed at the A\_BYP pin for this supply. It is recommended that no external components except the bypass capacitor be attached to this pin. The digital circuitry is powered by DVDD, which is provided by an internal linear regulator. A 0.1µF/10V external bypass capacitor is needed at the D\_BYP pin. It is recommended that no external components except the bypass capacitor be attached to this pin.

The TAS5414A and TAS5424A can withstand fortuitous open ground and power conditions. Fortuitous open ground usually occurs when a speaker wire is shorted to ground, allowing for a second ground path through the body diode in the output FETs. The uniqueness of the diagnostic capabilities allows the speakers and speaker wires to be debugged, eliminating the need to remove the amplifier to diagnose the problem.

#### I<sup>2</sup>C Serial Communication Bus

The TAS5414A and TAS5424A communicate with the system processor via the  $I^2C$  serial communication bus. The TAS5414A and TAS5424A are  $I^2C$  slave-only devices. The processor can poll the TAS5414A and the TAS5424A via  $I^2C$  to determine the operating status of the device. All fault conditions and detections are reported via  $I^2C$ . There are also numerous features and operating conditions that can be set via  $I^2C$ .

The I<sup>2</sup>C bus allows control of the following configurations:

- Independent gain control of each channel. The gain can be set to 12 dB, 20 dB, 26 dB, and 32 dB.
- Select current limit (for 2-Ω and for 4-Ω loads). This allows optimal design of the filter inductor, and the use of smaller gauge speaker wires for 4-Ω applications.
- Select AM non-interference switching frequency



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- Select the function of OTW\_CLIP pin
- · Enable or disable dc detect function with selectable threshold
- Place channel in Hi-Z (switching stopped) mode (mute)
- Select tweeter detect, set detect threshold and initiate function
- · Initiate open/short load diagnostic
- Reset faults and return to normal switching operation from Hi-Z mode (unmute)

In addition to the standard SDA and SCL pins for the I<sup>2</sup>C bus, the TAS5414A and the TAS5424A include a single pin that allows up to four devices to work together in a system with no additional hardware required for communication or synchronization. The I2C\_ADDR pin sets the device in master or slave mode and selects the I<sup>2</sup>C address for that device. Tie I2C\_ADDR to GND for master, to 1.2 Vdc for slave 1, to 2.4 Vdc for slave 2, and to D\_BYP for slave 3. The OSC\_SYNC pin is used to synchronize the internal clock oscillators and thereby avoid beat frequencies. An external oscillator can also be applied to this pin for external control of the switching frequency.

Table 2. Table 7. I2C ADDR Pin Connection

| DESCRIPTION                     | I2C_ADDR PIN CONNECTION   | I <sup>2</sup> C ADDRESS |
|---------------------------------|---|--------------------------|
| TAS5414A/5424 0 (OSC<br>MASTER) | To GND pin  | 0xD8/D9                  |
| TAS5414A/5424 1 (OSC SLAVE1)    | 35% DVDD (resistive voltage divider between D_BYP pin and GND pin) <sup>(1)</sup> | 0xDA/DB                  |
| TAS5414A/5424 2 (OSC SLAVE2)    | 65% DVDD (resistive voltage divider between D_BYP pin and GND pin) (1)            | 0xDC/DD                  |
| TAS5414A/5424 3 (OSC SLAVE3)    | To D_BYP pin  | 0xDE/DF                  |

<sup>(1)</sup> R<sub>I2C ADDR</sub> with 5% or better tolerance is recommended.

#### I<sup>2</sup>C Bus Protocol

The TAS5414A and TAS5424A have a bidirectional serial control interface that is compatible with the Inter IC ( $I^2C$ ) bus protocol and supports 100-kbps data transfer rates for random and sequential write and read operations. This is a slave-only device that does not support a multimaster bus environment or wait state insertion. The control interface is used to program the registers of the device and to read device status.

The I<sup>2</sup>C bus employs two signals, SDA (data) and SCL (clock), to communicate between integrated circuits in a system. Data is transferred on the bus serially, one bit at a time. The address and data are transferred in byte (8-bit) format with the most-significant bit (MSB) transferred first. In addition, each byte transferred on the bus is acknowledged by the receiving device with an acknowledge bit. Each transfer operation begins with the master device driving a start condition on the bus and ends with the master device driving a stop condition on the bus. The bus uses transitions on the data terminal (SDA) while the clock is HIGH to indicate a start and stop conditions. A HIGH-to-LOW transition on SDA indicates a start, and a LOW-to-HIGH transition indicates a stop. Normal data bit transitions must occur within the low time of the clock period. These conditions are shown in Figure 16. The master generates the 7-bit slave address and the read/write (R/W) bit to open communication with another device and then wait for an acknowledge condition. The TAS5414A and TAS5424A hold SDA LOW during the acknowledge-clock period to indicate an acknowledgment. When this occurs, the master transmits the next byte of the sequence. Each device is addressed by a unique 7-bit slave address plus R/W bit (1 byte). All compatible devices share the same signals via a bidirectional bus using a wired-AND connection. An external pullup resistor must be used for the SDA and SCL signals to set the HIGH level for the bus. There is no limit on the number of bytes that can be transmitted between start and stop conditions. When the last word transfers, the master generates a stop condition to release the bus.

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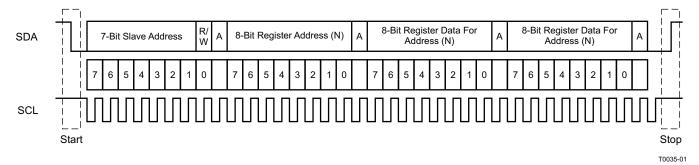


Figure 16. Typical I<sup>2</sup>C Sequence

Use the I2C\_ADDR pin (pin 2) to program the device for one of four addresses. These four addresses are licensed I<sup>2</sup>C addresses and do not conflict with other licensed I<sup>2</sup>C audio devices. To communicate with the TAS5414A and the TAS5424A, the I<sup>2</sup>C master uses addresses shown in Figure 16. Read and write data can be transmitted using single-byte or multiple-byte data transfers.

#### Random Write

As shown in Figure 17, a single-byte data-write transfer begins with the master device transmitting a start condition followed by the I<sup>2</sup>C device address and the read/write bit. The read/write bit determines the direction of the data transfer. For a write data transfer, the read/write bit is a 0. After receiving the correct I<sup>2</sup>C device address and the read/write bit, the TAS5414A or TAS5424A device responds with an acknowledge bit. Next, the master transmits the address byte or bytes corresponding to the internal memory address being accessed. After receiving the address byte, the TAS5414A or TAS5424A again responds with an acknowledge bit. Next, the master device transmits the data byte to be written to the memory address being accessed. After receiving the data byte, the TAS5414A or TAS5424A again responds with an acknowledge bit. Finally, the master device transmits a stop condition to complete the single-byte data-write transfer.

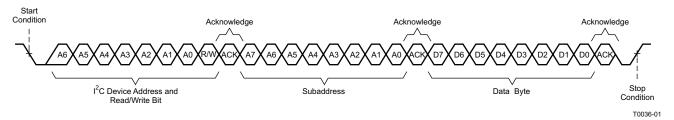


Figure 17. Random Write Transfer

#### **Sequential Write**

A sequential data-write transfer is identical to a single-byte data-write transfer except that multiple data bytes are transmitted by the master device to TAS5414A or TAS5424A as shown in Figure 17. After receiving each data byte, the TAS5414A or TAS5424A responds with an acknowledge bit and the I<sup>2</sup>C subaddress is automatically incremented by one.

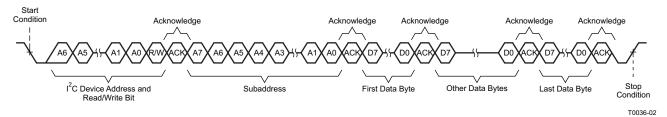


Figure 18. Sequential Write Transfer

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#### Random Read

As shown in Figure 19, a single-byte data-read transfer begins with the master device transmitting a start condition followed by the I<sup>2</sup>C device address and the read/write bit. For the data-read transfer, both a write followed by a read are actually done. Initially, a write is done to transfer the address byte or bytes of the internal memory address to be read. As a result, the read/write bit is a 0. After receiving the address and the read/write bit, the TAS5414A or TAS5424A responds with an acknowledge bit. In addition, after sending the internal memory address byte or bytes, the master device transmits another start condition followed by the TAS5414A or TAS5424A address and the read/write bit again. This time the read/write bit is a 1, indicating a read transfer. After receiving the address and the read/write bit, the TAS5414A or TAS5424A again responds with an acknowledge bit. Next, the TAS5414A or TAS5424A transmits the data byte from the memory address being read. After receiving the data byte, the master device transmits a not-acknowledge followed by a stop condition to complete the single-byte data-read transfer.

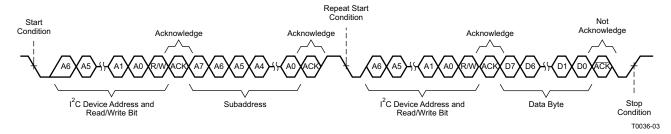


Figure 19. Random Read Transfer

#### **Sequential Read**

A sequential data-read transfer is identical to a single-byte data-read transfer except that multiple data bytes are transmitted by the TAS5414A or TAS5424A to the master device as shown in Figure 20. Except for the last data byte, the master device responds with an acknowledge bit after receiving each data byte and automatically increments the I<sup>2</sup>C subaddress by one. **Note:** The fault registers do not have sequential read capabilities.

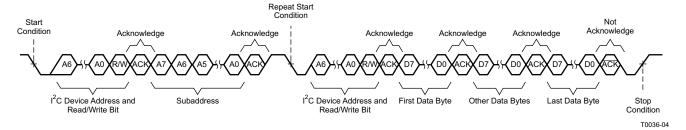


Figure 20. Sequential Read Transfer

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### Table 3. TAS5414A/5424 I<sup>2</sup>C Addresses

| DESCRIPTION     |                        | FIXED ADDRESS |   |   |   |   | SELECTABLE WITH ADDRESS PIN |   | READ/WRITE<br>BIT | I <sup>2</sup> C<br>ADDRESS |
|-----------------|------------------------|---------------|---|---|---|---|-----------------------------|---|-------------------|-----------------------------|
|                 |                        | MSB           | 6 | 5 | 4 | 3 | 2                           | 1 | LSB               | ADDRESS                     |
| TAS5414A/5424 0 | I <sup>2</sup> C WRITE | 1             | 1 | 0 | 1 | 1 | 0                           | 0 | 0                 | 0xD8                        |
| (OSC MASTER)    | I <sup>2</sup> C READ  | 1             | 1 | 0 | 1 | 1 | 0                           | 0 | 1                 | 0xD9                        |
| TAS5414A/5424 1 | I <sup>2</sup> C WRITE | 1             | 1 | 0 | 1 | 1 | 0                           | 1 | 0                 | 0xDA                        |
| (OSC SLAVE1)    | I <sup>2</sup> C READ  | 1             | 1 | 0 | 1 | 1 | 0                           | 1 | 1                 | 0xDB                        |
| TAS5414A/5424 2 | I <sup>2</sup> C WRITE | 1             | 1 | 0 | 1 | 1 | 1                           | 0 | 0                 | 0xDC                        |
| (OSC SLAVE2)    | I <sup>2</sup> C READ  | 1             | 1 | 0 | 1 | 1 | 1                           | 0 | 1                 | 0xDD                        |
| TAS5414A/5424 3 | I <sup>2</sup> C WRITE | 1             | 1 | 0 | 1 | 1 | 1                           | 1 | 0                 | 0xDE                        |
| (OSC SLAVE3)    | I <sup>2</sup> C READ  | 1             | 1 | 0 | 1 | 1 | 1                           | 1 | 1                 | 0xDF                        |

# Table 4. I<sup>2</sup>C Address Register Definitions

| ADDRESS | R/W | REGISTER DESCRIPTION  |
|---------|-----|---|
| 0x00    | R   | Latched fault register 1, global and channel fault                        |
| 0x01    | R   | Latched fault register 2, dc offset and overcurrent detect                |
| 0x02    | R   | Latched diagnostic register 1, load diagnostics                           |
| 0x03    | R   | Latched diagnostic register 2, load diagnostics                           |
| 0x04    | R   | External status register 1, temperature and voltage detect                |
| 0x05    | R   | External status register 2, Hi-Z and low-low state                        |
| 0x06    | R   | External status register 3, mute and play modes                           |
| 0x07    | R   | External status register 4, load diagnostics                              |
| 80x0    | R/W | External control register 1, channel gain select                          |
| 0x09    | R/W | External control register 2, dc offset reduction and current-limit select |
| 0x0A    | R/W | External control register 3, switching frequency and clip pin select      |
| 0x0B    | R/W | External control register 4, load diagnostic, master mode select          |
| 0x0C    | R/W | External control register 5, output state control                         |
| 0x0D    | R/W | External control register 6, output state control                         |
| 0x0E    | R/W | External control register 7, dc detect level select                       |
| 0x0F    | R/W | External control register 8, dc detect level select                       |

# Table 5. Fault Register 1 (0x00) Protection

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No protection-created faults, default value      |
| _  | _  | -  | -  | _  | -  | -  | 1  | Overtemperature warning has occurred             |
| _  | _  | _  | _  | _  | _  | 1  | _  | DC offset has occurred in any channel            |
| _  | _  | -  | -  | _  | 1  | -  | _  | Overcurrent shutdown has occurred in any channel |
| _  | _  | -  | -  | 1  | -  | -  | _  | Overtemperature shutdown has occurred            |
| _  | _  | -  | 1  | _  | -  | -  | -  | Charge pump undervoltage has occurred            |
| _  | -  | 1  | -  | -  | -  | _  | -  | AVDD, analog voltage, undervoltage has occurred  |
| _  | 1  | _  | -  | _  | _  | _  | _  | PVDD undervoltage has occurred                   |
| 1  | _  | _  | _  | _  | _  | _  | _  | PVDD overvoltage has occurred                    |

# Table 6. Fault Register 2 (0x01) Protection

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION                                    |
|----|----|----|----|----|----|----|----|---|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No protection-created faults, default value |
| _  | _  | -  | _  | _  | ı  | -  | 1  | Ovecurrent shutdown channel 1 has occurred  |
| _  | _  | -  | _  | _  | -  | 1  | -  | Overcurrent shutdown channel 2 has occurred |



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# Table 6. Fault Register 2 (0x01) Protection (continued)

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION                                    |
|----|----|----|----|----|----|----|----|---|
| _  | _  | ı  | 1  | _  | 1  | _  | _  | Overcurrent shutdown channel 3 has occurred |
| _  | _  | ı  | 1  | 1  | -  | _  | _  | Overcurrent shutdown channel 4 has occurred |
| _  | _  | 1  | 1  | _  | _  | _  | _  | DC offset channel 1 has occurred            |
| _  | _  | 1  | -  | _  | _  | _  | _  | DC offset channel 2 has occurred            |
| _  | 1  | -  | -  | _  | _  | _  | _  | DC offset channel 3 has occurred            |
| 1  | _  | -  | -  | _  | _  | _  | _  | DC offset channel 4 has occurred            |

# Table 7. Diagnostic Register 1 (0x02) Load Diagnostics

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No load-diagnostic-created faults, default value |
| _  | _  | ı  | 1  | _  | _  | -  | 1  | Output short to ground channel 1 has occurred    |
| _  | _  | ١  | 1  | _  | _  | 1  | _  | Output short to PVDD channel 1 has occurred      |
| _  | _  | ١  | 1  | _  | 1  | -  | _  | Shorted load channel 1 has occurred              |
| _  | _  | 1  | -  | 1  | _  | -  | -  | Open load channel 1 has occurred                 |
| _  | _  | ı  | 1  | _  | _  | -  | _  | Output short to ground channel 2 has occurred    |
| _  | -  | 1  | 1  | -  | -  | -  | -  | Output short to PVDD channel 2 has occurred      |
| _  | 1  | _  | _  | _  | _  | _  | -  | Shorted load channel 2 has occurred              |
| 1  | _  | ı  | ı  | _  | _  | _  | _  | Open load channel 2 has occurred                 |

# Table 8. Diagnostic Register 2 (0x03) Load Diagnostics

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No load-diagnostic-created faults, default value |
| -  | _  | _  | -  | _  | -  | _  | 1  | Output short to ground channel 3 has occurred    |
| -  | _  | _  | -  | _  | -  | 1  | -  | Output short to PVDD channel 3 has occurred      |
| 1  | _  | _  | -  | _  | 1  | _  | -  | Shorted load channel 3 has occurred              |
| -  | _  | _  | -  | 1  | _  | _  | _  | Open load channel 3 has occurred                 |
| -  | _  | _  | 1  | _  | _  | _  | -  | Output short to ground channel 4 has occurred    |
| 1  | _  | 1  | -  | _  | -  | _  | -  | Output short to PVDD channel 4 has occurred      |
| -  | 1  | _  | -  | _  | _  | _  | _  | Shorted load channel 4 has occurred              |
| 1  | _  | _  | _  | _  | _  | _  | _  | Open load channel 4 has occurred                 |

# Table 9. External Status Register 1 (0x04) Fault Detection

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION  |
|----|----|----|----|----|----|----|----|---|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No protection-created faults are present, default value |
| _  | _  | -  | _  | _  | _  | -  | 1  | PVDD overvoltage fault is present                       |
| _  | _  | _  | _  | _  | _  | 1  | _  | PVDD undervoltage fault is present                      |
| _  | _  | _  | _  | _  | 1  | _  | _  | AVDD, analog voltage fault is present                   |
| _  | _  | _  | _  | 1  | _  | _  | _  | Charge-pump voltage fault is present                    |
| _  | -  | _  | 1  | _  | _  | _  | _  | Overtemperature shutdown is present                     |
| _  | _  | 1  | _  | _  | _  | _  | _  | Overtemperature warning                                 |
| _  | 1  | 1  | _  | _  | _  | _  | _  | Overtemperature warning level 1                         |
| 1  | 0  | 1  | _  | _  | _  | -  | -  | Overtemperature warning level 2                         |
| 1  | 1  | 1  | _  | _  | _  | -  | -  | Overtemperature warning level 3                         |

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# Table 10. External Status Register 2 (0x05) Output State of Individual Channels

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 1  | 1  | 1  | 1  | Output is in Hi-Z mode, not in low-low mode <sup>(1)</sup> , default value |
| _  | _  | _  | 1  | _  | _  | -  | 0  | Channel 1 Hi-Z mode (0 = not Hi-Z, 1 = Hi-Z)                               |
| _  | -  | -  | 1  | -  | -  | 0  | -  | Channel 2 Hi-Z mode (0 = not Hi-Z, 1 = Hi-Z)                               |
| _  | _  | _  | 1  | _  | 0  | -  | -  | Channel 3 Hi-Z mode (0 = not Hi-Z, 1 = Hi-Z)                               |
| _  | _  | _  | -  | 0  | _  | -  | -  | Channel 4 Hi-Z mode (0 = not Hi-Z, 1 = Hi-Z)                               |
| _  | -  | -  | 1  | -  | -  | -  | -  | Channel 1 low-low mode (0 = not low-low, 1 = low-low) <sup>(1)</sup>       |
| _  | _  | 1  | 1  | _  | _  | -  | _  | Channel 2 low-low mode (0 = not low-low, 1 = low-low) <sup>(1)</sup>       |
| _  | 1  | -  | _  | _  | _  | _  | -  | Channel 3 low-low mode (0 = not low-low, 1 = low-low) <sup>(1)</sup>       |
| 1  | _  | _  | _  | _  | _  | _  | _  | Channel 4 low-low mode (0 = not low-low, 1 = low-low) <sup>(1)</sup>       |

<sup>(1)</sup> Low-low is defined as both outputs actively pulled to ground.

### Table 11. External Status Register 3 (0x06) Play and Mute Modes

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION  |
|----|----|----|----|----|----|----|----|---|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | Mute mode is disabled, play mode disabled, default value, (Hi-Z mode) |
| _  | _  | _  | _  | _  | _  | _  | 1  | Channel 1 play mode is enabled  |
| _  | _  | 1  | -  | -  | -  | 1  | _  | Channel 2 play mode is enabled  |
| _  | _  | 1  | -  | -  | 1  | -  | _  | Channel 3 play mode is enabled  |
| _  | _  | -  | -  | 1  | _  | _  | _  | Channel 4 play mode is enabled  |
| _  | _  | ١  | 1  | -  | -  | -  | _  | Channel 1 mute mode is enabled  |
| _  | _  | 1  | 1  | -  | -  | -  | _  | Channel 2 mute mode is enabled  |
| _  | 1  | -  | -  | _  | _  | _  | _  | Channel 3 mute mode is enabled  |
| 1  | -  | -  | -  | _  | _  | _  | _  | Channel 4 mute mode is enabled  |

# Table 12. External Status Register 4 (0x07) Load Diagnostics

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION  |
|----|----|----|----|----|----|----|----|---|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | No channels are set in load diagnostics mode, default value |
| _  | _  | _  | -  | ı  | -  | _  | 1  | Channel 1 is in load diagnostics mode                       |
| _  | _  | _  | -  | ı  | -  | 1  | -  | Channel 2 is in load diagnostics mode                       |
| _  | _  | _  | -  | 1  | 1  | _  | -  | Channel 3 is in load diagnostics mode                       |
| _  | _  | _  | -  | 1  | -  | _  | -  | Channel 4 is in load diagnostics mode                       |
| Х  | Х  | Х  | Х  | _  | _  | _  | _  | Reserved  |

# Table 13. External Control Register 1 (0x08) Gain Select

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION  |
|----|----|----|----|----|----|----|----|---|
| 1  | 0  | 1  | 0  | 1  | 0  | 1  | 0  | Set gain for all channels to 26 dB, default value |
| _  | _  | ı  | ı  | _  | _  | 0  | 0  | Set channel 1 gain to 12 dB                       |
| _  | _  | -  | -  | _  | _  | 0  | 1  | Set channel 1 gain to 20 dB                       |
| _  | _  | ı  | ı  | _  | _  | 1  | 1  | Set channel 1 gain to 32 dB                       |
| _  | _  | ı  | ı  | 0  | 0  | -  | -  | Set channel 2 gain to 12 dB                       |
| _  | _  | -  | -  | 0  | 1  | -  | -  | Set channel 2 gain to 20 dB                       |
| _  | _  | -  | -  | 1  | 1  | _  | _  | Set channel 2 gain to 32 dB                       |
| _  | _  | 0  | 0  | _  | _  | -  | _  | Set channel 3 gain to 12 dB                       |
| _  | _  | 0  | 1  | _  | _  | -  | -  | Set channel 3 gain to 20 dB                       |
| _  | _  | 1  | 1  | _  | _  | -  | -  | Set channel 3 gain to 32 dB                       |
| 0  | 0  | -  | -  | _  | _  | -  | -  | Set channel 4 gain to 12 dB                       |
| 0  | 1  | _  | -  | _  | _  | _  | _  | Set channel 4 gain to 20 dB                       |
| 1  | 1  | -  | -  | _  | _  | _  | _  | Set channel 4 gain to 32 dB                       |



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# Table 14. External Control Register 2 (0x09) DC Offset Reduction and Current Limit

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | Enable dc offset reduction, set current limit to level 1 |
| _  | ı  | ı  | ı  | ı  | ı  | ı  | 1  | Disable channel 1 dc offset reduction                    |
| _  | _  | -  | -  | _  | _  | 1  | _  | Disable channel 2 dc offset reduction                    |
| _  | 1  | ı  | ı  | _  | 1  | -  | _  | Disable channel 3 dc offset reduction                    |
| _  | 1  | ı  | ı  | 1  | _  | -  | _  | Disable channel 4 dc offset reduction                    |
| _  | ı  | ı  | 1  | -  | -  | -  | -  | Set channel 1 current limit (0 = level 1, 1 = level 2)   |
| _  | ı  | 1  | ı  | ı  | ı  | ı  | 1  | Set channel 2 current limit (0 = level 1, 1 = level 2)   |
| _  | 1  | -  | -  | _  | _  | -  | -  | Set channel 3 current limit (0 = level 1, 1 = level 2)   |
| 1  | ı  | ı  | ı  | _  | _  | _  | _  | Set channel 4 current limit (0 = level 1, 1 = level 2)   |

# Table 15. External Control Register 3 (0x0A) Switching Frequency Select and Clip\_OTW Configuration

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION   |
|----|----|----|----|----|----|----|----|--|
| 0  | 0  | 0  | 0  | 1  | 1  | 0  | 1  | Set f <sub>S</sub> = 417 kHz, configure clip and OTW, 45° phase, disable hard stop |
| -  | -  | _  | _  | _  | _  | 0  | 0  | Set $f_S = 500 \text{ kHz}$  |
| -  | _  | _  | _  | _  | _  | 1  | 0  | Set $f_S = 357 \text{ kHz}$  |
| -  | _  | _  | _  | _  | _  | 1  | 1  | Invalid frequency selection (do not set)   |
| -  | _  | _  | _  | 0  | 0  | -  | _  | Configure CLIP_OTW pin for tweeter detect only                                     |
| -  | _  | _  | _  | 0  | 1  | _  | _  | Configure CLIP_OTW pin for clip detect only  |
| -  | _  | _  | _  | 1  | 0  | _  | _  | Configure CLIP_OTW pin for overtemperature warning only                            |
| _  | _  | _  | 1  | _  | _  | _  | _  | Enable hard-stop mode  |
| _  | _  | 1  | _  | _  | -  | _  | _  | Set f <sub>S</sub> to a 180° phase difference between adjacent channels            |
| Х  | Х  | _  | _  | _  | _  | _  | _  | Reserved   |

### Table 16. External Control Register 4 (0x0B) Load Diagnostics and Master/Slave Control

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0   | FUNCTION   |  |  |  |
|----|----|----|----|----|----|----|--|--|--|--|--|
| 0  | 1  | 0  | 0  | 0  | 0  | 0  | Disable load diagnostics and dc detect SD, master mode |  |  |  |  |
| _  | _  | _  | -  | _  | -  | -  | 1 Enable channel 1, load diagnostics                   |  |  |  |  |
| _  | _  | _  | -  | _  | -  | 1  | Enable channel 2, load diagnostics                     |  |  |  |  |
| _  | _  | _  | -  | _  | 1  | _  | Enable channel 3, load diagnostics                     |  |  |  |  |
| _  | _  | _  | -  | 1  | -  | -  | -  | Enable channel 4, load diagnostics                       |  |  |  |
| _  | _  | _  | 1  | _  | -  | -  | -  | Enable dc detect shutdown on all channels                |  |  |  |
| _  | _  | 1  | -  | _  | -  | -  | -  | Enable tweeter-detect mode                               |  |  |  |
| _  | 0  | _  | -  | _  | -  | -  | -  | Enable slave mode (external oscillator must be provided) |  |  |  |
| Х  | _  | _  | _  | _  | _  | _  | _  | Reserved   |  |  |  |

# Table 17. External Control Register 5 (0x0C) Output Control

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0                                     | FUNCTION   |
|----|----|----|----|----|----|----|--|--|
| 0  | 0  | 0  | 1  | 1  | 1  | 1  | 1                                      | All channels, Hi-Z, mute, reset disabled                     |
| _  | 1  | ١  | 1  | _  | -  | -  | 0 Set channel 1 to mute mode, non-Hi-Z |  |
| _  | _  | 1  | -  | _  | -  | 0  | Set channel 2 to mute mode, non-Hi-Z   |  |
| _  | 1  | 1  | 1  | -  | 0  | _  | Set channel 3 to mute mode, non-Hi-Z   |  |
| _  | 1  | ı  | 1  | 0  | _  | _  | _                                      | Set channel 4 to mute mode, non-Hi-Z                         |
| _  | 1  | ١  | 0  | _  | -  | -  | -                                      | Set non-Hi-Z channels to play mode, (unmute)                 |
| _  | 1  | 1  | _  | _  | _  | _  | -                                      | Reserved   |
| 1  | _  | _  | _  | _  | _  | _  | _                                      | Reset device (I <sup>2</sup> C does not respond with an ACK) |

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### Table 18. External Control Register 6 (0x0D) Output Control

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0                                      | FUNCTION                       |  |  |
|----|----|----|----|----|----|----|---|--------------------------------|--|--|
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0 0 Low-low state disabled all channels |                                |  |  |
| _  | _  | ı  | 1  | -  | -  | _  | - 1 Set channel 1 to low-low state      |                                |  |  |
| _  | _  | ı  | 1  | -  | -  | 1  | 1 – Set channel 2 to low-low state      |                                |  |  |
| _  | _  | 1  | -  | -  | 1  | _  | -                                       | Set channel 3 to low-low state |  |  |
| _  | _  | 1  | -  | 1  | -  | _  | -                                       | Set channel 4 to low-low state |  |  |
| Х  | Х  | Х  | Х  | _  | _  | _  | _                                       | Reserved                       |  |  |

### Table 19. External Control Register 7 (0x0E) Positive DC Detect Threshold Selection

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION                                      |  |  |  |
|----|----|----|----|----|----|----|----|---|--|--|--|
| 1  | 0  | 0  | 0  | 1  | 1  | 1  | 0  | Default positive dc detect value              |  |  |  |
| 0  | 1  | 1  | 0  | 0  | 1  | 0  | 1  | Minimum positive dc detect value              |  |  |  |
| Х  | X  | Χ  | X  | X  | X  | Χ  | Х  | See Figure 11 to set positive dc detect value |  |  |  |
| 1  | 1  | 0  | 0  | 1  | 0  | 1  | 1  | Maximum positive dc detect value              |  |  |  |

### Table 20. External Control Register 8 (0x0F) Negative DC Detect Threshold Selection

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | FUNCTION                                      |  |  |  |
|----|----|----|----|----|----|----|----|---|--|--|--|
| 0  | 0  | 1  | 1  | 1  | 1  | 0  | 1  | Default negative dc detect value              |  |  |  |
| 0  | 1  | 1  | 0  | 0  | 1  | 0  | 1  | Minimum negative dc detect value              |  |  |  |
| X  | X  | Χ  | Χ  | Χ  | Χ  | Χ  | Х  | See Figure 12 to set negative dc detect value |  |  |  |
| 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | Maximum negative dc detect value              |  |  |  |

#### **Hardware Control Pins**

The TAS5414A and TAS5424A incorporate four discrete hardware pins for real-time control and indication of device status.

FAULT pin: This active-low, open-drain output pin indicates the presence of a fault condition that requires the TAS5414A and TAS5424A to go automatically into the Hi-Z mode or standby mode. When this pin is asserted high, the device has acted to protect itself and the system from potential damage. The exact nature of the fault can be read via I<sup>2</sup>C with the exception of faults that are the result of PVDD voltage excursions above 25 Vdc or below 6 Vdc. In these instances, the device goes into standby mode and the I<sup>2</sup>C bus is no longer operational. However, the fault is still indicated due to the fact that the FAULT pin is open-drain and active-high.

CLIP\_OTW pin: The function of this active-low pin is configured by the user to indicate one of the following conditions: overtemperature warning, the detection of clipping, or the logical OR of both of these conditions. The configuration is selected via I<sup>2</sup>C. During tweeter detect diagnostics, this pin also is asserted when a tweeter is present.

 $\overline{\text{MUTE}}$  pin: This active-low pin is used for hardware control of the mute/unmute function for all four channels. Capacitor  $C_{\text{MUTE}}$  is used to control the time constant for the gain ramp needed to produce a pop- and click-free mute function. For pop- and click-free operation, the mute function should be implemented through  $I^2C$  commands. The use of a hard mute with an external transistor does not ensure pop- and click-free operation, and is not recommended unless an *emergency hard mute* function is required in case of a loss of  $I^2C$  control. For proper pop- and click-free operation the minimum recommended value of  $C_{\text{MUTE}}$  is 330 nF.

 $\overline{\text{STANDBY}}$  pin: When this active-low pin is asserted, the device goes into a complete shutdown, and current draw is limited to 2  $\mu$ A, typical. This is pin typically asserted when the car ignition is in the off position. It can also be used to shut down the device rapidly when certain operating conditions are violated. All I²C register content is lost when this pin is asserted. The I²C bus goes into the high-impedance state when the  $\overline{\text{STANDBY}}$  pin is asserted.

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#### **EMI Considerations**

Automotive level EMI performance depends on both careful integrated circuit design and good system level design. Controlling sources of electromagnetic interference (EMI) was a major consideration in all aspects of the TAS5414A and TAS5424A design.

The TAS5414A and TAS5424A have minimal parasitic inductances due to the short leads on the PSOP3 package. This dramatically reduces the EMI that results from current passing from the die to the system PCB. Each channel of the TAS5414A and TAS5424A also operates at a different phase. The phase between channels is I<sup>2</sup>C selectable to either 45° or 180°, to reduce EMI caused by high-current switching. The TAS5414A and TAS5424A incorporate patent-pending circuitry that optimizes output transitions that cause EMI.

#### **AM Radio EMI Reduction**

To reduce interference in the AM radio band, the TAS5414A and TAS5424A have the ability to change the switching frequency via  $I^2C$  commands. The recommended frequencies are listed in Table 21. The fundamental frequency and its second harmonic straddle the AM radio band listed. This eliminates the tones that can be present due to the switching frequency being demodulated by the AM radio. To function properly, AM avoidance requires the use of a 20- $k\Omega$ , 1% tolerance Rext resistor.

Table 21. Recommended Switching Frequencies for AM Mode Operation

| U                     | IS                              | EUROPEAN              |                                 |  |  |
|-----------------------|---------------------------------|-----------------------|---------------------------------|--|--|
| AM FREQUENCY<br>(kHz) | SWITCHING<br>FREQUENCY<br>(kHz) | AM FREQUENCY<br>(kHz) | SWITCHING<br>FREQUENCY<br>(kHz) |  |  |
|                       |                                 | 522-540               | 417                             |  |  |
| 540–917               | 500                             | 540–914               | 500                             |  |  |
| 917–1125              | 417                             | 914–1122              | 417                             |  |  |
| 1125–1375             | 500                             | 1122–1373             | 500                             |  |  |
| 1375–1547             | 417                             | 1373–1548             | 417                             |  |  |
| 1547–1700             | 357                             | 1548–1701             | 357                             |  |  |

### **Operating States**

The operating regions, or states, of the TAS5414A and TAS5424A are depicted in the following tables.

**Table 22. Operating States and Supplies** 

| STATE NAME       | OUTPUT FETS          | CHARGE PUMP | OSCILLATOR | I <sup>2</sup> C | AVDD and DVDD |
|------------------|----------------------|-------------|------------|------------------|---------------|
| STANDBY          | Hi-Z, floating       | Stopped     | Stopped    | Stopped          | OFF           |
| Hi-Z             | Hi-Z, weak pulldown  | Active      | Active     | Active           | ON            |
| Mute             | Switching at 50%     | Active      | Active     | Active           | ON            |
| Normal operation | Switching with audio | Active      | Active     | Active           | ON            |

#### Table 23. Global Faults and Actions

| FAULT/<br>EVENT | FAULT/EVENT<br>CATEGORY | MONITORING<br>MODES | REPORTING<br>METHOD             | ACTION<br>TYPE      | ACTION<br>RESULT | LATCHED/<br>SELF-<br>CLEARING |
|-----------------|-------------------------|---------------------|---------------------------------|---------------------|------------------|-------------------------------|
| POR             | Voltage fault           | All                 | FAULT pin                       | Hard mute (no ramp) | Standby          | Self-clearing                 |
| UV              |                         | Hi-Z, mute, normal  | $I^2C + \overline{FAULT}$ pin   |                     | Hi-Z             | Latched                       |
| CP UV           |                         |                     |                                 |                     | Hi-Z             |                               |
| OV              |                         |                     |                                 |                     | Hi-Z             |                               |
| Load dump       |                         | All                 | FAULT pin                       |                     | Standby          | Self-clearing                 |
| OTW             | Thermal warning         | Hi-Z, mute, normal  | I <sup>2</sup> C + CLIP_OTW pin | None                | None             | Self-clearing                 |
| OTSD            | Thermal fault           | Hi-Z, mute, normal  | I <sup>2</sup> C + FAULT pin    | Hard mute           | Standby          | Latched                       |



### **Table 24. Channel Faults and Actions**

| FAULT/<br>EVENT        | FAULT/EVENT<br>CATEGORY | MONITORING<br>MODES               | REPORTING<br>METHOD           | ACTION<br>TYPE | ACTION<br>RESULT | LATCHED/<br>SELF-<br>CLEARING |
|------------------------|-------------------------|-----------------------------------|-------------------------------|----------------|------------------|-------------------------------|
| Open/short diagnostic  | Diagnostic              | Hi-Z (I <sup>2</sup> C activated) | I <sup>2</sup> C              | None           | None             | Latched                       |
| Clipping online        | Warning                 | Normal                            | CLIP_OTW pin                  | None           | None             | Self-clearing                 |
| CBC load current limit | Online protection       | Mute, normal                      | CLIP_OTW pin                  | Current limit  | Start OC timer   | Self-clearing                 |
| OC fault               | Output channel fault    | Mute, normal                      | I <sup>2</sup> C + FAULT pin  | Hard mute      | Hi-Z             | Latched                       |
| DC detect              |                         | Normal                            | $I^2C + \overline{FAULT}$ pin | Hard mute      | Hi-Z             | Latched                       |

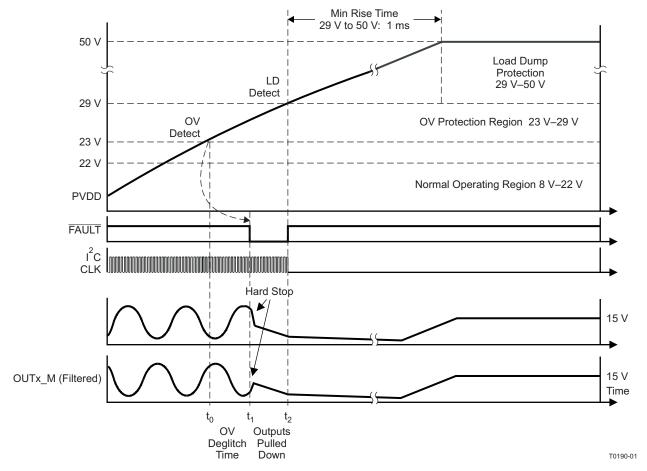


Figure 21. Sequence of Events for Supply Transition Out of Normal Operating Region

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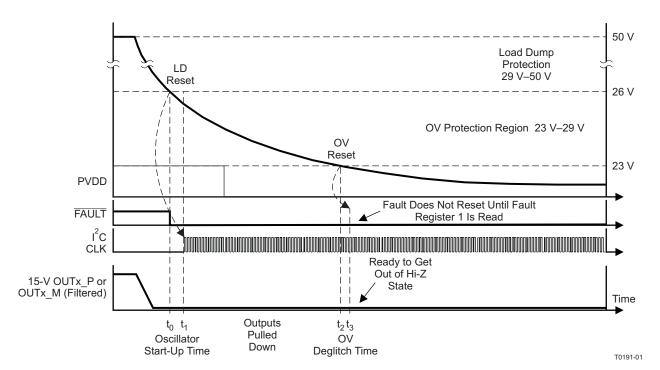


Figure 22. Sequence of Events for Supply Transition Back Into Normal Operating Region

### **Power Shutdown and Restart Sequence Control**

The gain ramp of the filtered output signal and the updating of the I<sup>2</sup>C registers correspond to the MUTE pin voltage during the ramping process. For the decreasing gain ramp (when transitioning from Play to Mute mode), the actual decrease in output gain begins when the MUTE pin voltage is approximately 2/3 of the A\_BYP voltage, and the ramp itself completes when the MUTE pin voltage is approximately 1/3 of A\_BYP. However, the I<sup>2</sup>C register indicating that Mute mode has been entered does not update externally until the MUTE pin voltage is approximately 1/10 of the A\_BYP voltage. Conversely, for the increasing ramp process (when transitioning from Mute to Play), the actual increase in output gain begins when the MUTE pin voltage is approximately 1/3 of the A\_BYP voltage and the gain increase completes when the MUTE pin voltage is approximately 2/3 of A\_BYP. The I<sup>2</sup>C register indicating Play mode has been entered updates when the MUTE pin voltage is approximately 9/10 of the A\_BYP voltage. For both gain ramps, the change in MUTE pin voltage begins when the I<sup>2</sup>C command to change operating modes is received by the device. The length of time that the MUTE pin takes to complete its ramp is dictated by the value of the external capacitor on the MUTE pin.

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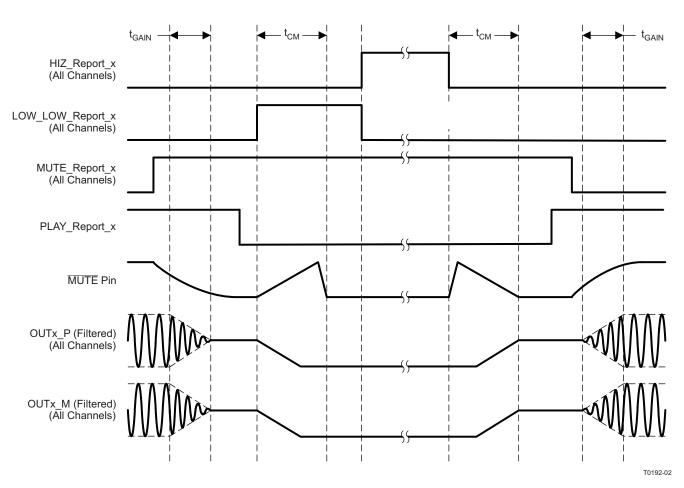


Figure 23. Click- and Pop-Free Shutdown and Restart Sequence Timing Diagram With Four Channels Sharing the Mute Pin

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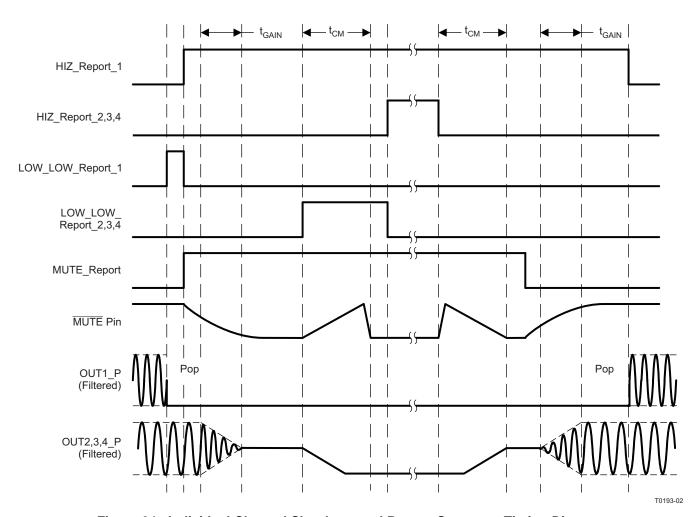


Figure 24. Individual Channel Shutdown and Restart Sequence Timing Diagram



# **Latched Fault Shutdown and Restart Sequence Control**

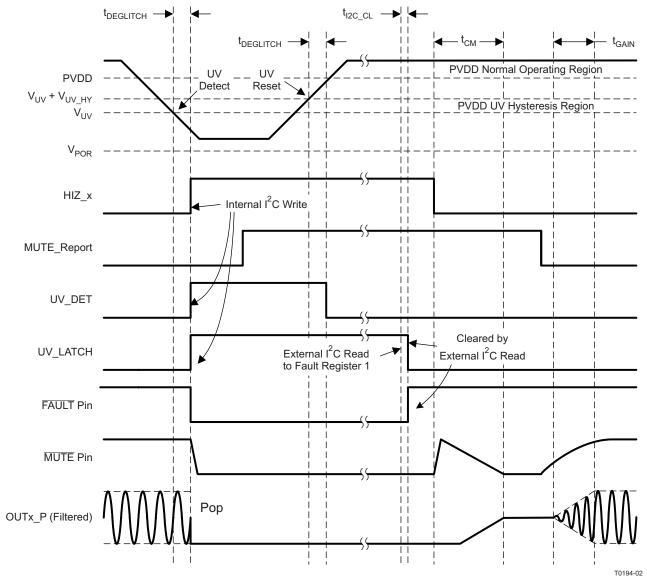


Figure 25. Latched Global Fault Shutdown and Restart Timing Diagram (UV Shutdown and Recovery)

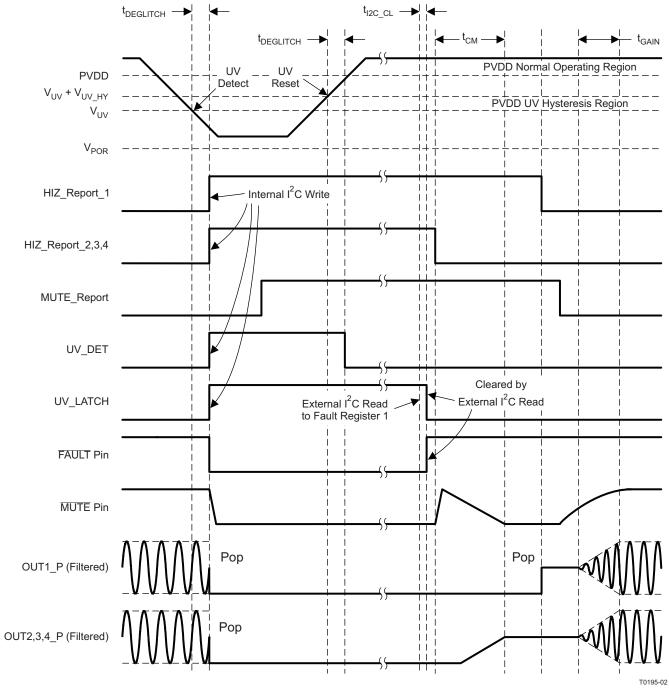


Figure 26. Latched Global Fault Shutdown and Individual Channel Restart Timing Diagram (UV Shutdown and Recovery)

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### **APPLICATION INFORMATION**

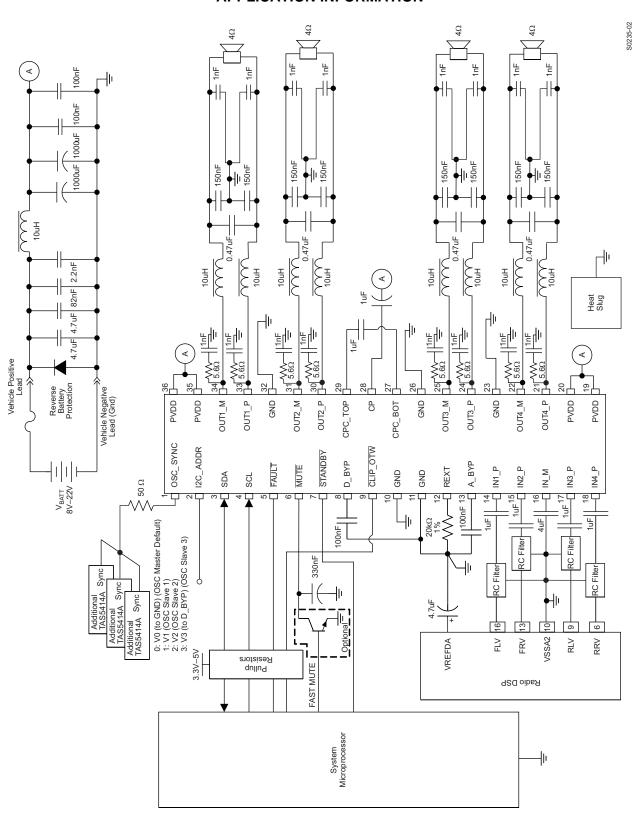


Figure 27. TAS5414A Typical Application Schematic

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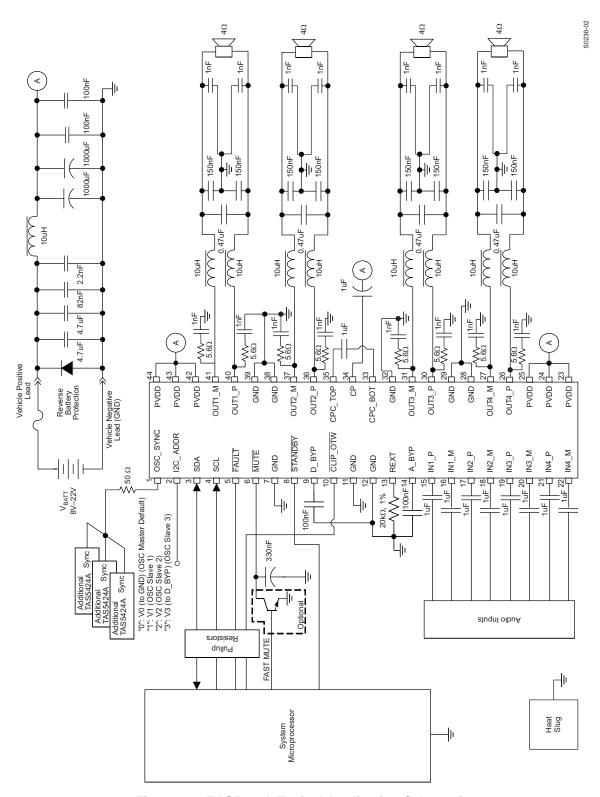


Figure 28. TAS5424A Typical Application Schematic

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### Parallel Operation (PBTL)

The TAS5414A and TAS5424A can be used to drive four 4- $\Omega$  loads, two 2- $\Omega$  loads, or even one 1- $\Omega$  load by paralleling BTL channels on the load side of the LC output filter. For parallel operation, identical I<sup>2</sup>C settings are required for any two paralleled channels (especially gain and current-limit settings) in order to have reliable system performance and evenly dissipated power on multiple channels. Having identical gain and current-limit settings can also prevent energy feeding back from one channel to the other. For smooth power up, power down, and mute operation, the same control commands (such as mute, play, Hi-Z, etc.) should be sent to the paralleled channels at the same time. Load diagnostic is also supported for parallel connection. Paralleling on the TAS5414A and TAS5424A side of the LC output filter is not supported, and can result in device failure.

## **Input Filter Design**

For the TAS5424A device, the input filter for a single channel's P and M inputs should be identical. For the TAS5414A the IN\_M pin should have an impedance to GND that is equivalent to the parallel combination of the input impedances of all IN\_P channels combined, including any source impedance from the previous stage in the system design. For example, if each of the 4 IN\_P channels have a 1uF DC blocking capacitor,  $1k\Omega$  of series resistance due to an input RC filter, and  $1k\Omega$  of source resistance from the DAC supplying the audio signal, the IN\_M channel should have a 4uF capacitor in series with a  $500\Omega$  resistor to GND (4 x 1uF in parallel = 4uF; 4 x  $2k\Omega$  in parallel =  $500\Omega$ ).

# **Demodulation Filter Design**

The TAS5414A and TAS5424A amplifier outputs are driven by high-current LDMOS transistors in an H-bridge configuration. These transistors are either off or fully on. The result is a square-wave output signal with a duty cycle that is proportional to the amplitude of the audio signal. It is recommended that a second-order LC filter be used to recover the audio signal. The main purpose of the demodulation filter is to attenuate the high-frequency components of the output signals that are out of the audio band. Design of the demodulation filter significantly affects the audio performance of the power amplifier. Therefore, to meet the device THD+N specification, the selection of the inductors used in the output filter should be carefully considered. The rule is that the inductance should remain stable within the range of peak current seen at maximum output power and deliver approximately 5 µH of inductance at 16 A. If this rule is observed, the TAS5414A and TAS5424A should not have distortion issues due to the output inductors. Another parameter to be considered is the idle-current loss in the inductor. This can be measured or specified as inductor dissipation (D). The target specification for dissipation is less than 0.05. If the dissipation factor is above this value, idle current increases. In general, 10-µH inductors suffice for most applications. The frequency response of the amplifier is slightly altered by the change in output load resistance; however, unless tight control of frequency response is necessary (better than 0.5 dB), it is not necessary to deviate from 10 µH.

### **Line Driver Applications**

In many automotive audio applications the end user would like to use the same head unit to drive either a speaker (with several Ohms of impedance) or an external amplifier (with several  $k\Omega$  of impedance). The TAS5414A and the TAS5424A are capable of supporting both applications. However, the output filter must be sized appropriately to handle the expected output load in either case (i.e. different output filter values need to be populated to handle the two different cases). If the user would like to use the same output filter for both applications additional hardware measures such as a Zobel filter are needed to ensure output stability for both loading conditions. Please refer to the TAS54x4A hardware application note for additional details.

### **Thermal Information**

The thermally augmented package provided with the TAS5414A and TAS5424A is designed to interface directly to heat sinks using a thermal interface compound (for example, Arctic Silver, Ceramique thermal compound.) The heat sink then absorbs heat from the ICs and couples it to the local air. If louvers or fans are supplied, this process can reach equilibrium and heat can be continually removed from the ICs. Because of the efficiency of the TAS5414A and TAS5424A, heat sinks can be smaller than those required for linear amplifiers of equivalent performance.

 $R_{\theta JA}$  is a system thermal resistance from junction to ambient air. As such, it is a system parameter with the following components:

R<sub>A IC</sub> (the thermal resistance from junction to case, or in this case the heat slug)



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- Thermal grease thermal resistance
- · Heat sink thermal resistance

The thermal grease thermal resistance can be calculated from the exposed heat slug area and the thermal grease manufacturer's area thermal resistance (expressed in °C-in²/W or °C-mm²/W). The area thermal resistance of the example thermal grease with a 0.001-inch (0.0254-mm) thick layer is about 0.007°C-in²/W (4.52°C-mm²/W). The approximate exposed heat slug size is as follows:

| TAS5424A, 44-pin PSOP3         | 0.124 in <sup>2</sup> (80 mm <sup>2</sup> ) |
|--------------------------------|---|
| TAS5414A, 36-pin PSOP3         | 0.124 in <sup>2</sup> (80 mm <sup>2</sup> ) |
| TAS5414A, TAS5424A, 64-pin QFP | 0.099 in <sup>2</sup> (64 mm <sup>2</sup> ) |

Dividing the example thermal grease area resistance by the area of the heat slug gives the actual resistance through the thermal grease for both parts:

| TAS5424A, 44-pin PSOP3         | 0.06°C/W |
|--------------------------------|----------|
| TAS5414A, 36-pin PSOP3         | 0.06°C/W |
| TAS5414A, TAS5424A, 64-pin QFP | 0.07°C/W |

The thermal resistance of thermal pads is generally considerably higher than a thin thermal grease layer. Thermal tape has an even higher thermal resistance and should not be used at all. Heat sink thermal resistance generally is predicted by the heat sink vendor, modeled using a continuous flow dynamics (CFD) model, or measured.

Thus, for a single monaural channel in the IC, the system  $R_{\theta JA} = R_{\theta JC}$  + thermal grease resistance + heat sink resistance.

The following table indicates modeled parameters for one TAS5414A or TAS5424A IC on a heat sink. The junction temperature is set at  $115^{\circ}$ C in both cases while delivering 20 Wrms per channel into  $4-\Omega$  loads with no clipping. It is assumed that the thermal grease is about 0.001 inches (0.0254 mm) thick.

| Device                               | TAS5414A, 36-Pin PSOP3 |
|--------------------------------------|------------------------|
| Ambient temperature                  | 25°C                   |
| Power to load                        | 20 W × 4               |
| Power dissipation                    | 1.90 W × 4             |
| ΔT inside package                    | 7.6°C                  |
| ΔT through thermal grease            | 0.46°C                 |
| Required heatsink thermal resistance | 10.78°C/W              |
| Junction temperature                 | 115°C                  |
| System R <sub>θJA</sub>              | 11.85°C/W              |
| R <sub>0JA</sub> × power dissipation | 90°C                   |

## **Electrical Connection of Heat Slug and Heat Sink**

Any heat sink that is connected to the heat slug of the TAS5414A or TAS5424A should be connected to GND or left floating. The heat slug should never be connected to any electrical node other than GND.



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# **REVISION HISTORY**

| Cł | nanges from Revision A (February 2008) to Revision B  | Page     |
|----|---|----------|
| •  | Changed all instances of SGND and PGND to GND on all pinout diagrams  | 4        |
| •  | Deleted TAS5424A from PHD package in the Terminal Functions table   | 6        |
| •  | Changed all PGND and SGND pins to GND   | 6        |
| •  | Changed upper end of V <sub>STANDBY</sub> voltage range to 5.5 V in absolute Maximum Ratings  | <b>7</b> |
| •  | Changed value for V <sub>AIN_AC_MAX_5414</sub> and V <sub>AIN_AC_MAX_5424</sub> in Absolute Maximum Ratings   | <b>7</b> |
| •  | Deleted V <sub>PGND</sub> , V <sub>SGND</sub> , and T <sub>SOLDER</sub> rows from Absolute Maximum Ratings. Changed all occurrences in document of PGND and SGND to GND |          |
| •  | Deleted V <sub>IN_CM</sub> row from Electrical Characteristics table  | 9        |
| •  | Added power level to Test Condition of gain measurement in Electrical Characteristics   | 9        |
| •  | Changed text of Tweeter Detection paragraph and added a note  | 18       |
| •  | Added caution regarding PHD package thermal weakness  | 19       |
| •  | Changed maximum ramp rate to 15 V/ms in Figure 15   | 20       |
| •  | Unified ground names and symbols, and added 50-Ω series resistor for OSC_SYNC line, on TAS5414A application schematic   |          |
| •  | Unified ground names and symbols, and added 50-Ω resistor series resistor on OSC_SYNC line, on TAS5424A application schematic   | 37       |
| •  | Added subsection on input filter design. New recommendation for IN_M impedance on TAS5414A  | 38       |
| •  | Added Line Driver application subsection  | 38       |
| •  | Added a new section for electrical connection of the heat slug  | 39       |
| Cł | nanges from Revision B (January 2010) to Revision C   | Page     |
| •  | Changed AGND to GND for the V <sub>AIN_DC</sub> description in the Abs Max Table  | 7        |
| •  | Added V <sub>GND</sub> to the Abs Max Table   | 7        |
| •  | Changed DGND to GND in I <sup>2</sup> C Serial Communication Bus Section  |          |
| •  | Changed SGND to GND in Figure 27  | 36       |
| •  | Changed SGND to GND in Figure 28  | 37       |

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### PACKAGING INFORMATION

| Orderable part number | Status | Material type | Package   Pins   | Package qty   Carrier | RoHS | Lead finish/  | MSL rating/         | Op temp (°C) | Part marking |
|-----------------------|--------|---------------|------------------|-----------------------|------|---------------|---------------------|--------------|--------------|
|                       | (1)    | (2)           |                  |                       | (3)  | Ball material | Peak reflow         |              | (6)          |
|                       |        |               |                  |                       |      | (4)           | (5)                 |              |              |
| HPA01140ATPHDRMQ1     | NRND   | Production    | HTQFP (PHD)   64 | -                     | -    | Call TI       | Call TI             | -40 to 105   |              |
| TAS5414ATPHDMQ1       | NRND   | Production    | HTQFP (PHD)   64 | 90   JEDEC            | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 105   | TAS5414ATMQ1 |
|                       |        |               |                  | TRAY (5+1)            |      |               |                     |              |              |
| TAS5414ATPHDMQ1.A     | NRND   | Production    | HTQFP (PHD)   64 | 90   JEDEC            | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 105   | TAS5414ATMQ1 |
|                       |        |               |                  | TRAY (5+1)            |      |               |                     |              |              |
| TAS5414ATPHDMQ1.B     | NRND   | Production    | HTQFP (PHD)   64 | 90   JEDEC            | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 105   | TAS5414ATMQ1 |
|                       |        |               |                  | TRAY (5+1)            |      |               |                     |              |              |
| TAS5414ATPHDRMQ1      | NRND   | Production    | HTQFP (PHD)   64 | 1000   LARGE T&R      | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 105   | TAS5414ATMQ1 |
| TAS5414ATPHDRMQ1.B    | NRND   | Production    | HTQFP (PHD)   64 | 1000   LARGE T&R      | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 105   | TAS5414ATMQ1 |

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE OPTION ADDENDUM**

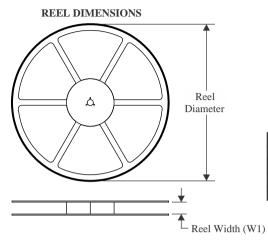
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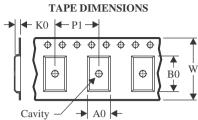
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# **PACKAGE MATERIALS INFORMATION**

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# TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width     |
|----|---|
| В0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

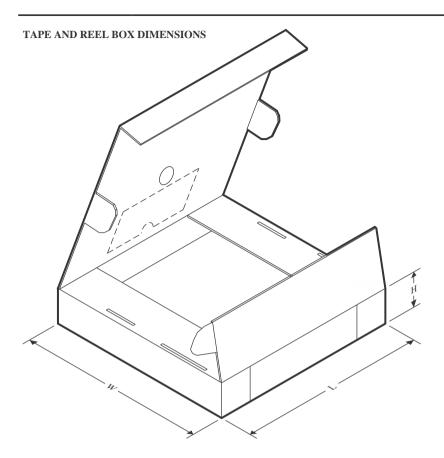


#### \*All dimensions are nominal

| Device           | Package<br>Type | Package<br>Drawing |    | SPQ  | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|------------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| TAS5414ATPHDRMQ1 | HTQFP           | PHD                | 64 | 1000 | 330.0                    | 24.4                     | 17.0       | 17.0       | 1.5        | 20.0       | 24.0      | Q2               |

**PACKAGE MATERIALS INFORMATION** 

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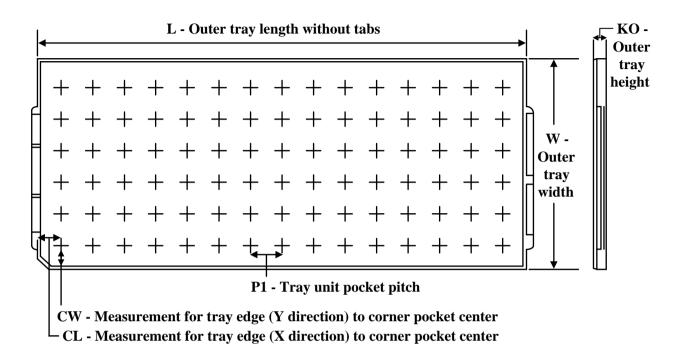
### \*All dimensions are nominal

| Device           | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |  |
|------------------|--------------|-----------------|------|------|-------------|------------|-------------|--|
| TAS5414ATPHDRMQ1 | HTQFP        | PHD             | 64   | 1000 | 350.0       | 350.0      | 43.0        |  |



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# **TRAY**



Chamfer on Tray corner indicates Pin 1 orientation of packed units.

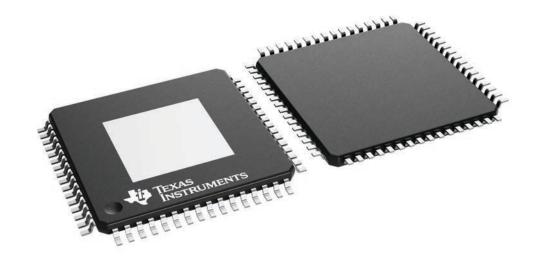
#### \*All dimensions are nominal

| Device            | Package<br>Name | Package<br>Type | Pins | SPQ | Unit array<br>matrix | Max<br>temperature<br>(°C) | L (mm) | W<br>(mm) | Κ0<br>(μm) | P1<br>(mm) | CL<br>(mm) | CW<br>(mm) |
|-------------------|-----------------|-----------------|------|-----|----------------------|----------------------------|--------|-----------|------------|------------|------------|------------|
| TAS5414ATPHDMQ1   | PHD             | HTQFP           | 64   | 90  | 6 X 15               | 150                        | 315    | 135.9     | 7620       | 20.3       | 15.4       | 15.45      |
| TAS5414ATPHDMQ1.A | PHD             | HTQFP           | 64   | 90  | 6 X 15               | 150                        | 315    | 135.9     | 7620       | 20.3       | 15.4       | 15.45      |
| TAS5414ATPHDMQ1.B | PHD             | HTQFP           | 64   | 90  | 6 X 15               | 150                        | 315    | 135.9     | 7620       | 20.3       | 15.4       | 15.45      |

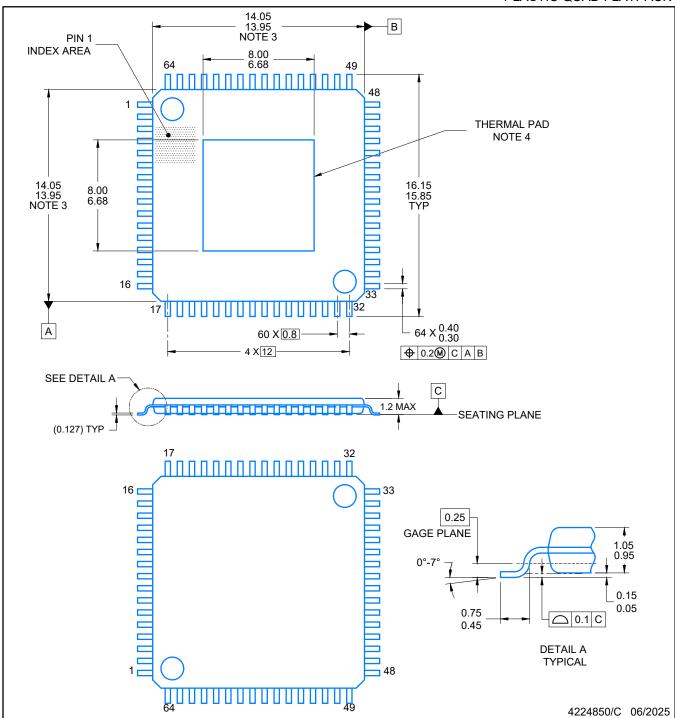
14 x 14, 0.8 mm pitch

PLASTIC QUAD FLATPACK

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



PLASTIC QUAD FLATPACK

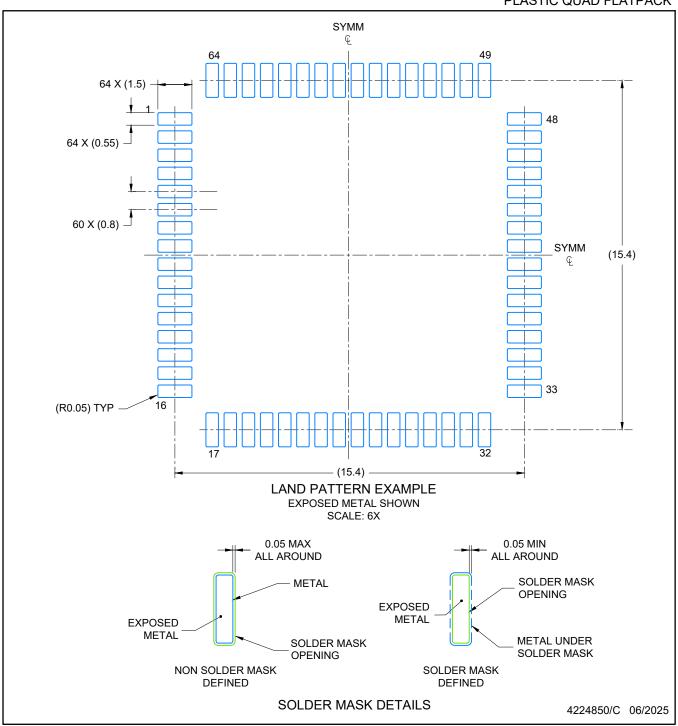


### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per side
- See technical brief. PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 (www.ti.com/lit/slma002) and SLMA004 (www.ti.com/lit/slma004) for information regarding recommended board layout.



PLASTIC QUAD FLATPACK

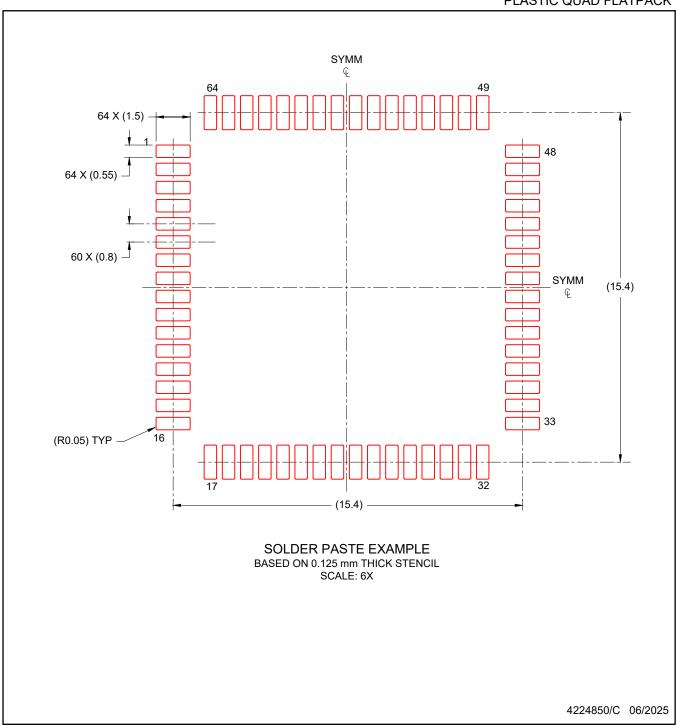


NOTES: (continued)

- 5. Publication IPC-7351 may have alternate designs.
- 6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- Vias are optional depending on application, refer to device data sheet. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUAD FLATPACK



NOTES: (continued)

- 7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 8. Board assembly site may have different recommendations for stencil design.



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