

TPS2521xx、2.7V~5.7V、4A、31mΩ、真の逆電流ブロッキング eFuse、入力逆極性保護機能付き

1 特長

- 広い動作時入力電圧範囲: 2.7V~5.7V
- 絶対最大定格: 28V
- -15V までの負の電圧に対応
- 低オン抵抗のバック・ツー・バック FET を内蔵: $R_{ON} = 31m\Omega$ (標準値)
- 真の逆電流ブロッキングを実現する理想ダイオード動作
- ピン選択可能なスレッシュホールド (3.8V、5.7V) と 5μs (標準値) の応答時間を持つ高速過電圧クランプ (OVC)
- 負荷電流監視出力 (ILM) を備えた過電流保護
 - アクティブな電流制限応答
 - 調整可能なスレッシュホールド (I_{LIM}) 0.5A~4.44A
 - 精度: $\pm 10\%$ ($I_{LIM} > 1A$)
 - 可変の過渡ブランキング・タイマ (ITIMER)、最大 $2 \times I_{LIM}$ のピーク電流を許容
 - 出力負荷電流監視精度: $\pm 6\%$ ($I_{OUT} \geq 1A$)
- 高速トリップ応答による短絡保護
 - 応答時間 500ns (標準値)
 - 可変 ($2 \times I_{LIM}$) および固定のスレッシュホールド
- アクティブ HIGH のイネーブル入力、低電圧誤動作防止 (UVLO) スレッシュホールドを設定可能
- 可変の出力スルーレート (dVdt) 制御
- 過熱保護
- 可変スレッシュホールド (PGTH) 付きのパワー・グッド表示 (PG)
- UL 2367 認定
 - ファイル番号 E169910
 - $R_{ILM} \geq 750\Omega$
- IEC 62368-1 CB 認証
- 小型サイズ: QFN 2mm × 2mm (0.45mm ピッチ)

2 アプリケーション

- アダプタの入力保護
- エンタープライズ・ストレージ: RAID/HBA/SAN/eSSD
- USB PD ポート保護回路
- サーバー、PC マザーボード、アドオン・カード
- モニタ、ドッキング・ステーション

3 概要

TPS2521x ファミリの eFuse は、小さなパッケージに搭載され、高度に統合された回路保護および電源管理ソリューションです。このデバイスは、非常に少ない数の外付け部品で複数の保護モードを提供し、過負荷、短絡、電圧サージ、逆極性、過剰な突入電流に対して堅牢な保護を行います。内蔵バック・ツー・バック FET によって出力から入

力への逆電流が常に阻止されるため、入力電源障害に備えた負荷側エネルギー保持ストレージを必要とするシステムに最適です。

出力電流制限レベルは、1 つの外付け抵抗により設定できます。また、電流制限抵抗の両端で電圧降下を測定することにより、出力負荷電流を正確に検出可能です。

特定の突入電流要件を持つアプリケーションでは、1 つの外付けコンデンサにより出力スルーレートを設定できます。出力を安全な固定最大電圧 (ピンで選択可能) にクランプすることで、入力過電圧状態から負荷を保護できます。

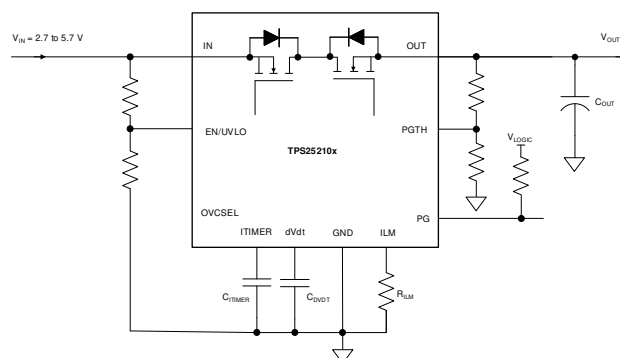
これらのデバイスは、2mm × 2mm、10 ピンの HotRod QFN パッケージで供給され、放熱性能の向上とシステムのフットプリントの削減に役立ちます。

これらのデバイスは、-40°C~+125°Cの接合部温度範囲で動作が規定されています。

製品情報

部品番号	パッケージ(1)	本体サイズ (公称)
TPS2521xxRPW	QFN (10)	2mm × 2mm

- (1) 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。



概略回路図



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4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision * (March 2021) to Revision A (March 2022)	Page
• UIL/IEC 認証ステータスを更新.....	1
• Corrected the ESD Ratings to show CDM testing was per JS-002.....	5
• Updated 表 8-4	27

5 Device Comparison Table

Part Number	Overvoltage Response	Overcurrent Response	Response to Fault
TPS25210A	Pin Selectable OVC (3.8 V/5.7 V)	Active Current Limit	Auto-Retry
TPS25210L			Latch-Off

6 Pin Configuration and Functions

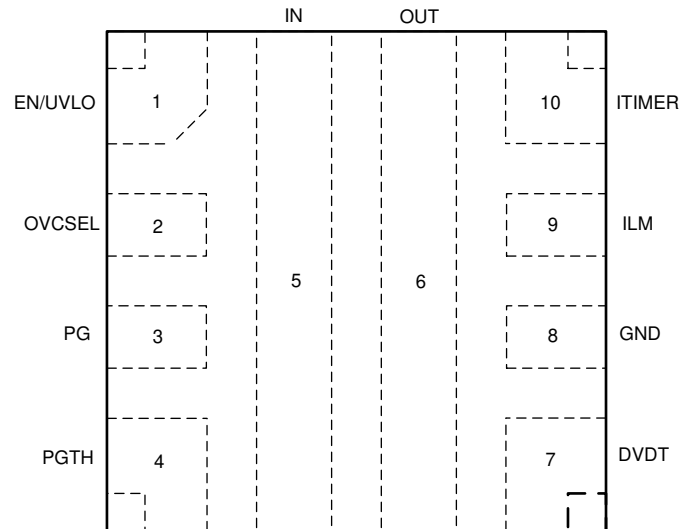


図 6-1. TPS2521x RPW Package 10-Pin QFN Top View

表 6-1. Pin Functions

PIN		TYPE	DESCRIPTION
NAME	NO.		
EN/UVLO	1	Analog Input	Active High Enable for the device. A Resistor Divider on this pin from input supply to GND can be used to adjust the undervoltage lockout threshold. <i>Do not leave floating.</i> Refer to セクション 8.3.2 for details.
OVCSEL	2	Analog Input	Overvoltage clamp threshold select pin. Refer to セクション 8.3.3 for details.
PG	3	Digital Output	Power Good indication. This pin is an Open Drain signal which is asserted High when the internal power path is fully turned ON and PGTH input exceeds a certain threshold. Refer to セクション 8.3.9 for more details.
PGTH	4	Analog Input	Power Good Threshold. Refer to セクション 8.3.9 for more details.
IN	5	Power	Power input
OUT	6	Power	Power output
DVDT	7	Analog Output	A capacitor from this pin to GND sets the output turn on slew rate. Leave this pin floating for the fastest turn on slew rate. Refer to セクション 8.3.4.1 for details.
GND	8	Ground	This pin is the ground reference for all internal circuits and must be connected to system GND.
ILM	9	Analog Output	This pin is a dual function pin used to limit and monitor the output current. An external resistor from this pin to GND sets the output current limit threshold during start-up as well as steady state. The pin voltage can also be used as analog output load current monitor signal. <i>Do not leave floating.</i> Refer to セクション 8.3.4.2 for more details.
ITIMER	10	Analog Output	A capacitor from this pin to GND sets the overcurrent blanking interval during which the output current can temporarily exceed set current limit (but lower than fast-trip threshold) before the device overcurrent response takes action. Leave this pin open for fastest response to overcurrent events. Refer to セクション 8.3.4.2 for more details.

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

Parameter		Pin	MIN	MAX	UNIT
V _{IN}	Maximum Input Voltage Range, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	IN	$\max(-15, V_{\text{OUT}} - 21)$	28	V
	Maximum Input Voltage Range, $-10^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$		$\max(-15, V_{\text{OUT}} - 22)$	28	V
V _{OUT}	Maximum Output Voltage Range, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$	OUT	-0.3	$\min(28, V_{\text{IN}} + 21)$	
	Maximum Output Voltage Range, $-10^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$		-0.3	$\min(28, V_{\text{IN}} + 22)$	
V _{OUT,PLS}	Minimum Output Voltage Pulse ($< 1 \mu\text{s}$)	OUT	-0.8		
V _{EN/UVLO}	Maximum Enable Pin Voltage Range ⁽²⁾	EN/UVLO	-0.3	6.5	V
V _{OVCSEL}	Maximum OVCSEL Pin Voltage Range	OVCSEL	Internally Limited		V
V _{dVdT}	Maximum dVdT Pin Voltage Range	dVdT	Internally Limited		V
V _{ITIMER}	Maximum ITIMER Pin Voltage Range	ITIMER	Internally Limited		V
V _{PGTH}	Maximum PGTH Pin Voltage Range ⁽²⁾	PGTH	-0.3	6.5	V
V _{PG}	Maximum PG Pin Voltage Range	PG	-0.3	6.5	V
V _{ILM}	Maximum ILM Pin Voltage Range	ILM	Internally Limited		V
I _{MAX}	Maximum Continuous Switch Current	IN to OUT	Internally Limited		A
T _J	Junction temperature		Internally Limited		°C
T _{LEAD}	Maximum Lead Temperature			300	°C
T _{STG}	Storage temperature		-65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) If this pin has a pull-up up to V_{IN}, it is recommended to use a resistance of 350 kΩ or higher to limit the current under conditions where IN can be exposed to reverse polarity.

7.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
		Charged device model (CDM), ANSI/ESDA/JEDEC JS-002 ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

Parameter		Pin	MIN	MAX	UNIT
V _{IN}	Input Voltage Range	IN	2.7	5.7 ⁽¹⁾	V
V _{OUT}	Output Voltage Range	OUT	min (23, V _{IN} + 20)		V
V _{EN/UVLO}	Enable Pin Voltage Range	EN/UVLO		5 ⁽²⁾	V
V _{dVdT}	dVdT Capacitor Voltage Rating	dVdT	V _{IN} + 5 V		V
V _{PGTH}	PGTH Pin Voltage Range	PGTH		5 ⁽³⁾	V
V _{PG}	PG Pin Voltage Range	PG		5 ⁽³⁾	V
V _{ITIMER}	ITIMER Pin Capacitor Voltage Rating	ITIMER	4		V
R _{ILM}	ILM Pin Resistance	ILM	750	6650	Ω
I _{MAX}	Continuous Switch Current, T _J ≤ 125°C	IN to OUT		4	A
T _J	Junction temperature		–40	125	°C

- (1) The input operating voltage should be limited to the selected Output Voltage Clamp threshold as listed in the Electrical Characteristics section
- (2) For supply voltages below 5V, it is okay to pull up the EN pin to IN directly. For supply voltages greater than 5V or systems which can be exposed to reverse polarity on input supply, it is recommended to use a pull-up resistor with a minimum value of 350 kΩ.
- (3) For systems which can be exposed to reverse polarity on input supply, if this pin is referred to input supply, it is recommended to use a pull-up resistor with a minimum value of 350 kΩ to limit the current through the pin.

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS2521xx	UNIT
		RPW (QFN)	
		10 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	41.7 ⁽²⁾	°C/W
		74.5 ⁽³⁾	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	1	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	20 ⁽²⁾	°C/W
		27.6 ⁽³⁾	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
- (2) Based on simulations conducted with the device mounted on a custom 4-layer PCB (2s2p) with 8 thermal vias under device
- (3) Based on simulations conducted with the device mounted on a JEDEC 4-layer PCB (2s2p) with no thermal vias under device

7.5 Electrical Characteristics

(Test conditions unless otherwise noted) $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$, $V_{\text{IN}} = 5\text{ V}$, $\text{OUT} = \text{Open}$, $V_{\text{EN/UVLO}} = 2\text{ V}$, $\text{OVCSEL} = \text{Open}$, $R_{\text{ILM}} = 750\ \Omega$, $dV/dT = \text{Open}$, $\text{ITIMER} = \text{Open}$, $\text{PGTH} = \text{Open}$, $\text{PG} = \text{Open}$. All voltages referenced to GND.

Test Parameter	Description	MIN	TYP	MAX	UNITS
INPUT SUPPLY (IN)					
$V_{\text{UVP(R)}}$	IN Supply UVP Rising Threshold	2.44	2.53	2.64	V
$V_{\text{UVP(F)}}$	IN Supply UVP Falling Threshold	2.35	2.42	2.55	V
$I_{\text{Q(ON)}}$	IN Supply Quiescent Current		411	593	μA
$I_{\text{Q(ON)}}$	IN Supply Current during OVC		426	620	μA
$I_{\text{Q(ON)}}$	IN Supply Quiescent Current during RCB, $V_{\text{OUT}} = V_{\text{IN}} + 1\text{ V}$		186		μA
$I_{\text{Q(OFF)}}$	IN Supply OFF State Current ($V_{\text{SD(F)}} < V_{\text{EN}} < V_{\text{UVLO(F)}}$)		67	130	μA
I_{SD}	IN Supply Shutdown Current ($V_{\text{EN}} < V_{\text{SD(F)}}$)		1.62	28.7	μA
$I_{\text{INLKG(IRPP)}}$	IN Supply Leakage Current ($V_{\text{IN}} = -14\text{ V}$, $V_{\text{OUT}} = 0\text{ V}$)		-3.7		μA
ON RESISTANCE (IN - OUT)					
R_{ON}	$V_{\text{IN}} = 5\text{ V}$, $I_{\text{OUT}} = 3\text{ A}$, $T_J = 25^{\circ}\text{C}$		31		m Ω
	$2.7 \leq V_{\text{IN}} \leq 5.7\text{ V}$, $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$			50.2	m Ω
ENABLE/UNDERVOLTAGE LOCKOUT (EN/UVLO)					
$V_{\text{UVLO(R)}}$	EN/UVLO Rising Threshold	1.183	1.2	1.223	V
$V_{\text{UVLO(F)}}$	EN/UVLO Falling Threshold	1.076	1.1	1.116	V
$V_{\text{SD(F)}}$	EN/UVLO Falling Threshold for lowest shutdown current	0.45	0.73		V
I_{ENLKG}	EN/UVLO Leakage Current	-0.1		0.1	μA
OUTPUT VOLTAGE CLAMP (OUT)					
V_{OVC}	Overvoltage Clamp Threshold, $\text{OVCSEL} = \text{Shorted to GND}$	3.65	3.88	4.1	V
	Overvoltage Clamp Threshold, $\text{OVCSEL} = \text{Open}$	5.25	5.74	6.2	V
V_{CLAMP}	Output Voltage During Clamping, $\text{OVCSEL} = \text{Shorted to GND}$, $I_{\text{OUT}} = 10\text{ mA}$	3.2	3.82	4.2	V
	Output Voltage During Clamping, $\text{OVCSEL} = \text{Open}$, $I_{\text{OUT}} = 10\text{ mA}$	5	5.58	6.1	V
OVERCURRENT PROTECTION (OUT)					
I_{LIM}	Current Limit Threshold, $R_{\text{ILM}} = 6.65\text{ k}\Omega$	0.425	0.5	0.575	A
	Current Limit Threshold, $R_{\text{ILM}} = 3.32\text{ k}\Omega$	0.85	1.0	1.15	A
	Current Limit Threshold, $R_{\text{ILM}} = 1.65\text{ k}\Omega$	1.8	2.02	2.2	A
	Current Limit Threshold, $R_{\text{ILM}} = 750\ \Omega$	3.96	4.44	4.84	A
I_{FLT}	Circuit Breaker Threshold, ILM Pin Open (Single point failure)		0.1		A
	Circuit Breaker Threshold, ILM Pin Short to GND (Single point failure)		1.1	2.1	A
I_{SCGain}	Scalable Fast Trip Threshold (I_{SC}) : I_{LIM} Ratio		201		%
I_{FT}	Fixed Fast-trip Current Threshold		22		A
V_{FB}	V_{OUT} threshold to exit Current Limit Foldback		1.9		V
V_{INT}	ITIMER pin internal pull-up voltage	2.3	2.52	2.72	V
OVERCURRENT FAULT TIMER (ITIMER)					
I_{ITIMER}	ITIMER pin internal discharge current, $I_{\text{OUT}} > I_{\text{LIM}}$	1.2	1.81	2.5	μA
R_{ITIMER}	ITIMER pin internal pull-up resistance		15		k Ω
ΔV_{ITIMER}	ITIMER discharge voltage	1.28	1.51	1.74	V
OUTPUT LOAD CURRENT MONITOR (ILM)					

7.5 Electrical Characteristics (continued)

(Test conditions unless otherwise noted) $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$, $V_{\text{IN}} = 5\text{ V}$, $\text{OUT} = \text{Open}$, $V_{\text{EN/UVLO}} = 2\text{ V}$, $\text{OVCSEL} = \text{Open}$, $R_{\text{ILM}} = 750\ \Omega$, $\text{dVdT} = \text{Open}$, $\text{ITIMER} = \text{Open}$, $\text{PGTH} = \text{Open}$, $\text{PG} = \text{Open}$. All voltages referenced to GND.

Test Parameter	Description	MIN	TYP	MAX	UNITS
G_{IMON}	Analog Load Current Monitor Gain ($I_{\text{MON}} : I_{\text{OUT}}$), $I_{\text{OUT}} = 0.5\text{ A}$ to 1 A , $I_{\text{OUT}} < I_{\text{LIM}}$	165	182	200	$\mu\text{A/A}$
	Analog Load Current Monitor Gain ($I_{\text{MON}} : I_{\text{OUT}}$), $I_{\text{OUT}} = 1\text{ A}$ to 4 A , $I_{\text{OUT}} < I_{\text{LIM}}$	165	182	200	$\mu\text{A/A}$
REVERSE CURRENT BLOCKING (IN - OUT)					
V_{FWD}	$V_{\text{IN}} - V_{\text{OUT}}$ Forward regulation voltage, $I_{\text{OUT}} = 10\text{ mA}$	5	17.4		mV
V_{REVTH}	$V_{\text{IN}} - V_{\text{OUT}}$ threshold for fast BFET turn off (enter reverse current blocking)	-36.5	-29.1	-22.3	mV
V_{FWDTH}	$V_{\text{IN}} - V_{\text{OUT}}$ threshold for fast BFET turn on (exit reverse current blocking)	83	102.2	125	mV
$I_{\text{OUTLKG(RCB)}}$	OUT Leakage Current during ON state with RCB, $V_{\text{OUT}} = V_{\text{IN}} + 1\text{ V}$		270		μA
$I_{\text{REVLKG(OFF)}}$	Reverse Leakage Current during unpowered condition, $V_{\text{OUT}} = 12\text{ V}$, $V_{\text{IN}} = 0\text{ V}$		4.8		μA
POWER GOOD INDICATION (PG)					
V_{PGD}	PG pin voltage while de-asserted, $V_{\text{IN}} < V_{\text{UVP(F)}}$, $V_{\text{EN}} < V_{\text{SD(F)}}$, Weak pull-up ($I_{\text{PG}} = 26\ \mu\text{A}$)		0.67	1	V
	PG pin voltage while de-asserted, $V_{\text{IN}} < V_{\text{UVP(F)}}$, $V_{\text{EN}} < V_{\text{SD(F)}}$, Strong pull-up ($I_{\text{PG}} = 242\ \mu\text{A}$)		0.78	1	V
	PG pin voltage while de-asserted, $V_{\text{IN}} > V_{\text{UVP(R)}}$		0		V
I_{PGLKG}	PG Pin Leakage Current, PG asserted		0.9	3	μA
POWERGOOD THRESHOLD (PGTH)					
$V_{\text{PGTH(R)}}$	PGTH Rising Threshold	1.183	1.2	1.223	V
$V_{\text{PGTH(F)}}$	PGTH Falling Threshold	1.076	1.09	1.116	V
I_{PGTHLKG}	PGTH Leakage Current	-0.1		0.3	μA
OVERTEMPERATURE PROTECTION (OTP)					
TSD	Thermal Shutdown Rising Threshold, $T_J \uparrow$		154		$^{\circ}\text{C}$
TSD _{HYS}	Thermal Shutdown Hysteresis, $T_J \downarrow$		10		$^{\circ}\text{C}$
DVDT					
I_{dVdt}	dVdt Pin Charging Current	0.78	1.97	3.3	μA

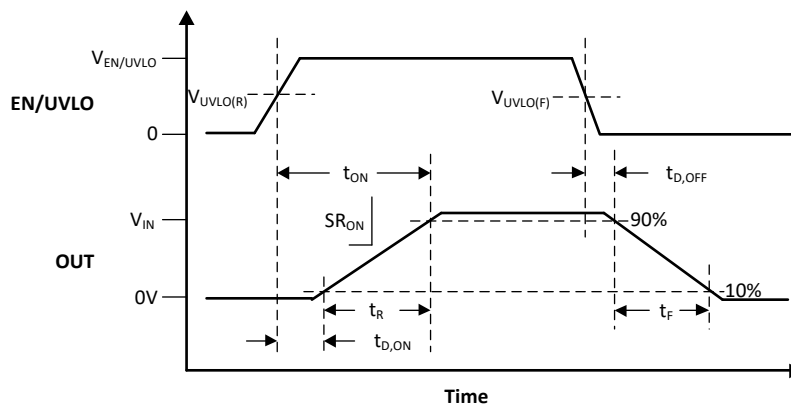
7.6 Timing Requirements

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_{OVC}	Overvoltage clamp response time		5		μs
t_{LIM}	Current limit response time		400		μs
t_{SC}	Scalable fast-trip response time		500		ns
t_{FT}	Fixed fast-trip response time		500		ns
t_{RST}	Auto-Retry Interval after fault (TPS25210A)		110		ms
t_{SWRCB}	Reverse Current Blocking recovery time		50		μs
t_{RCB}	Reverse Current Blocking comparator response time		1		μs
t_{PGA}	PG Assertion de-glitch		12		μs
t_{PGD}	PG De-assertion de-glitch		12		μs

7.7 Switching Characteristics

The output rising slew rate is internally controlled and constant across the entire operating voltage range to ensure the turn on timing is not affected by the load conditions. The rising slew rate can be adjusted by adding capacitance from the dVdt pin to ground. As C_{dVdt} is increased it will slow the rising slew rate (SR). See Slew Rate and Inrush Current Control (dVdt) section for more details. The Turn-Off Delay and Fall Time, however, are dependent on the RC time constant of the load capacitance (C_{OUT}) and Load Resistance (R_L). The Switching Characteristics are only valid for the power-up sequence where the supply is available in steady state condition and the load voltage is completely discharged before the device is enabled. Typical Values are taken at $T_J = 25^\circ C$ unless specifically noted otherwise. $V_{IN} = 2.7 V$, $R_L = 100 \Omega$, $C_{OUT} = 1 \mu F$

PARAMETER		$C_{dVdt} = \text{Open}$	$C_{dVdt} = 1800 \text{ pF}$	$C_{dVdt} = 3300 \text{ pF}$	UNIT
SR_{ON}	Output Rising slew rate	12.14	0.87	0.5	V/ms
$t_{D,ON}$	Turn on delay	0.09	0.6	0.97	ms
t_R	Rise time	0.17	2.51	4.33	ms
t_{ON}	Turn on time	0.27	3.11	5.31	ms
$t_{D,OFF}$	Turn off delay	64.44	64.44	64.44	μs



7-1. TPS2521xx Switching Times

7.8 Typical Characteristics

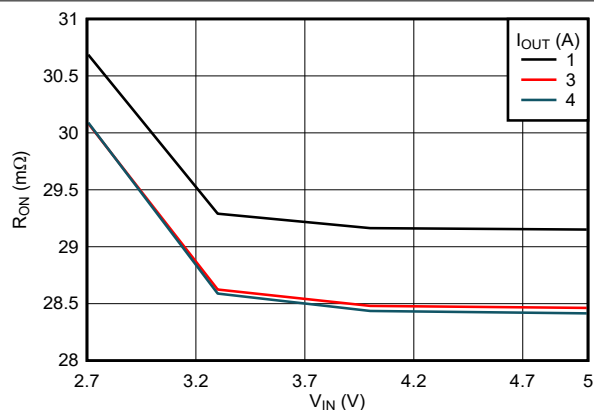


Figure 7-2. ON-Resistance vs Supply Voltage

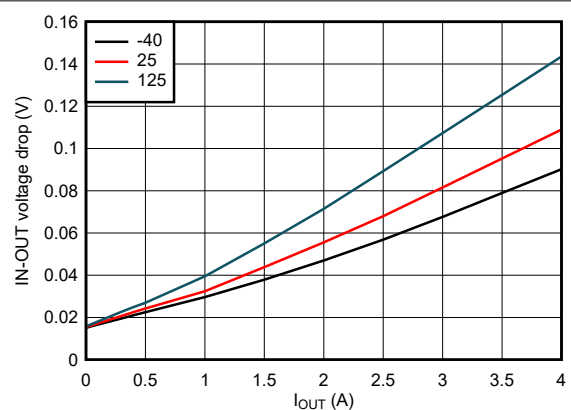


Figure 7-3. Forward Voltage Drop vs Load Current

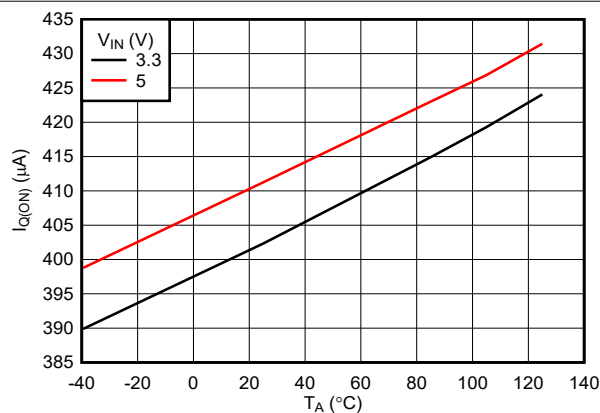


Figure 7-4. IN Quiescent Current vs Temperature

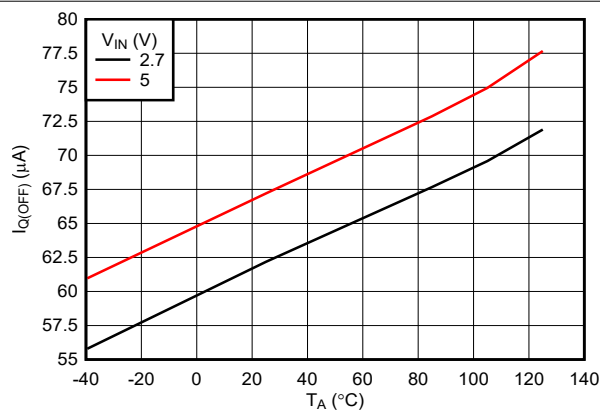


Figure 7-5. IN OFF State (UVLO) Current vs Temperature

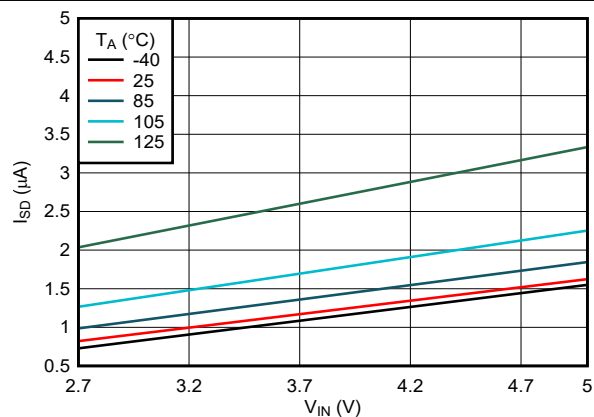


Figure 7-6. IN Shutdown Current vs Supply Voltage

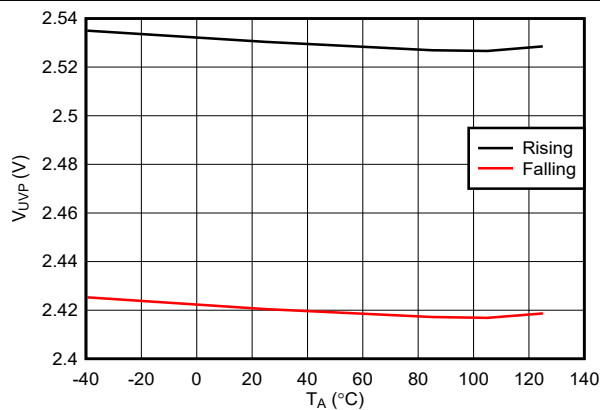


Figure 7-7. IN Undervoltage Threshold vs Temperature

7.8 Typical Characteristics (continued)

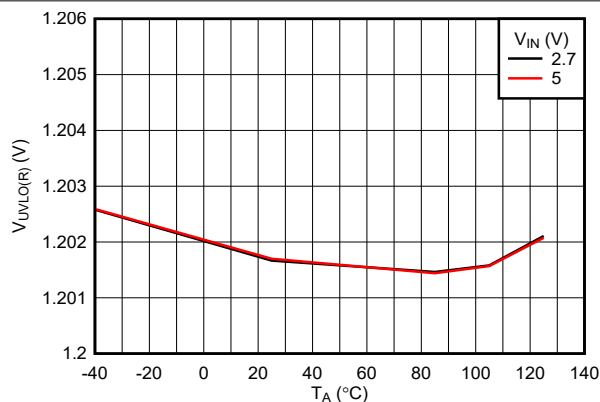


FIG 7-8. EN/UVLO Rising Threshold vs Temperature

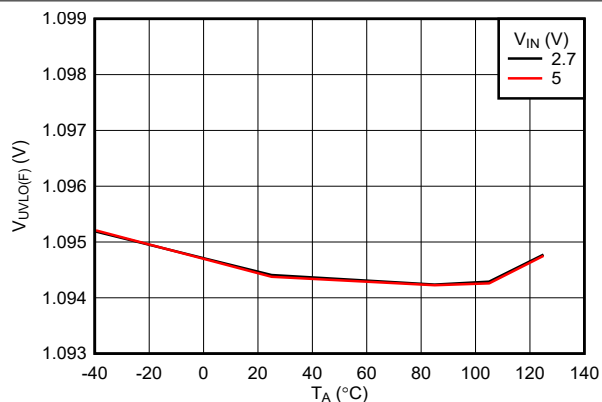


FIG 7-9. EN/UVLO Falling Threshold vs Temperature

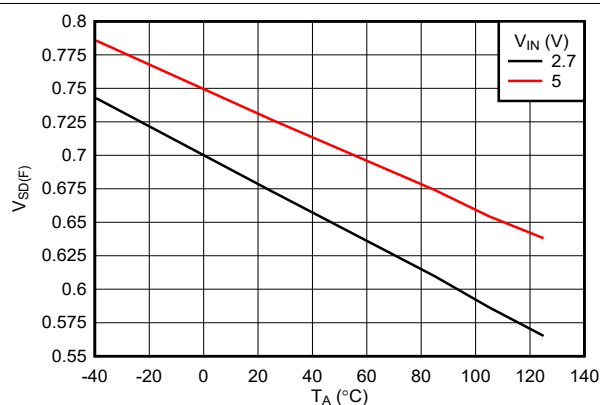


FIG 7-10. EN/UVLO Shutdown Falling Threshold vs Temperature

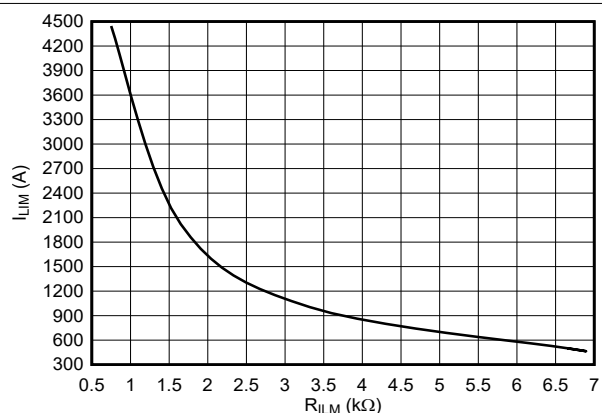


FIG 7-11. Overcurrent Protection Threshold vs ILM Resistor

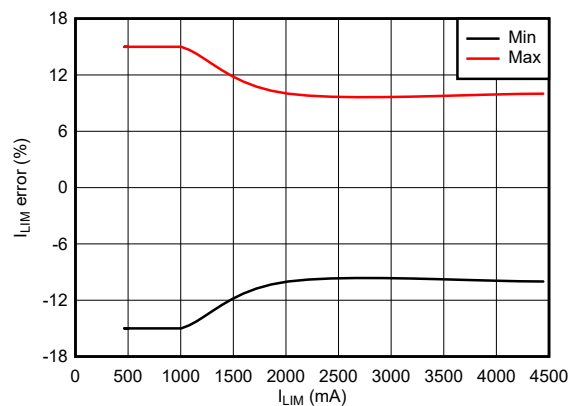


FIG 7-12. Overcurrent Protection Threshold Accuracy (Across Process, Voltage, and Temperature)

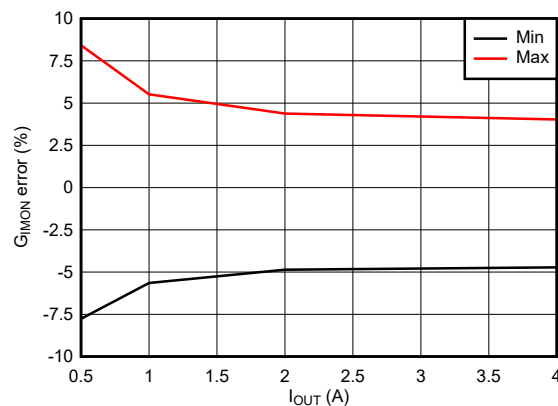


FIG 7-13. Analog Current Monitor Gain Accuracy

7.8 Typical Characteristics (continued)

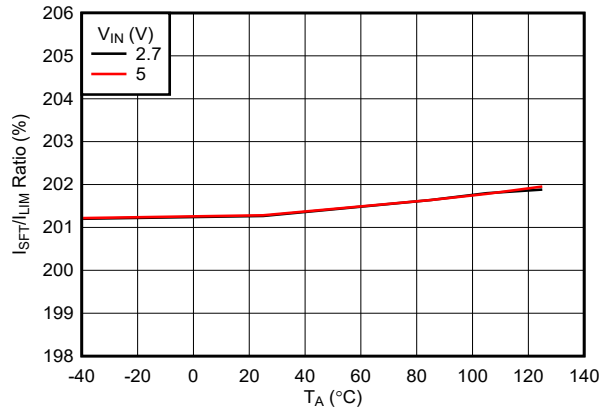


FIG 7-14. Scalable Fast-Trip Threshold: Current Limit Threshold (I_{LIM}) Ratio vs Temperature

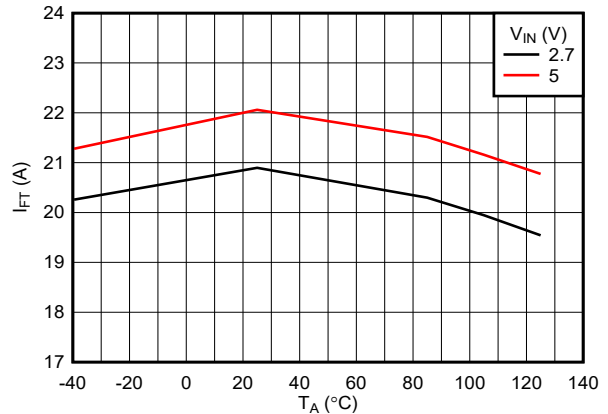


FIG 7-15. Steady State Fixed Fast-Trip Current Threshold vs Temperature

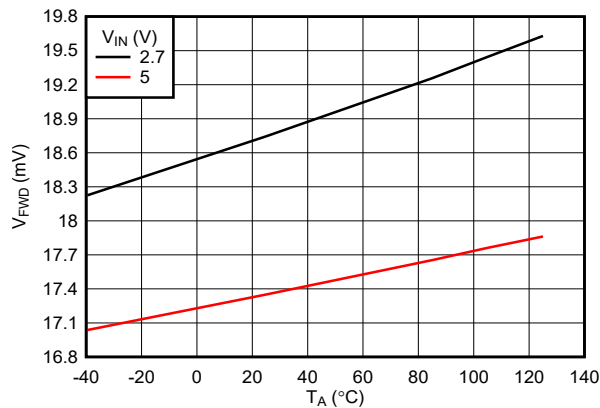


FIG 7-16. RCB - Forward Regulation Voltage vs Temperature

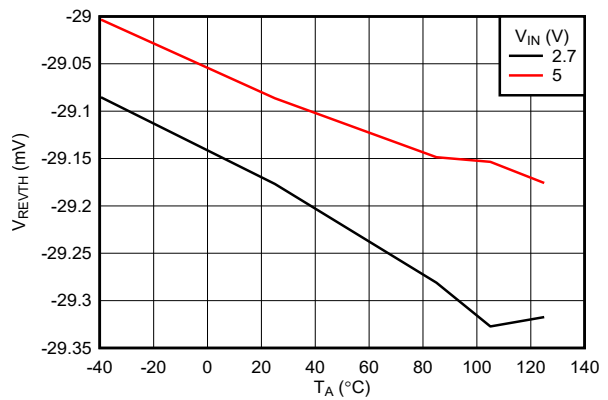


FIG 7-17. RCB - Reverse Comparator Threshold vs Temperature

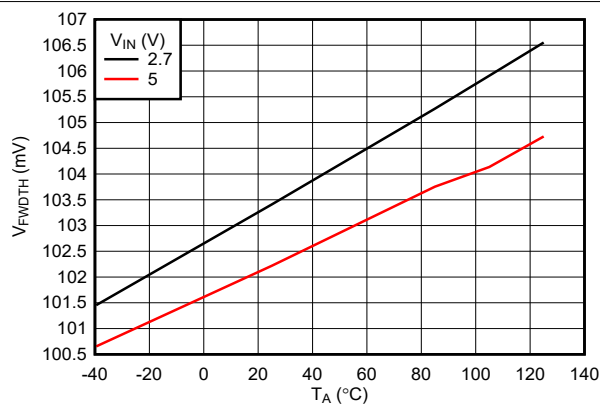


FIG 7-18. RCB - Forward Comparator Threshold vs Temperature

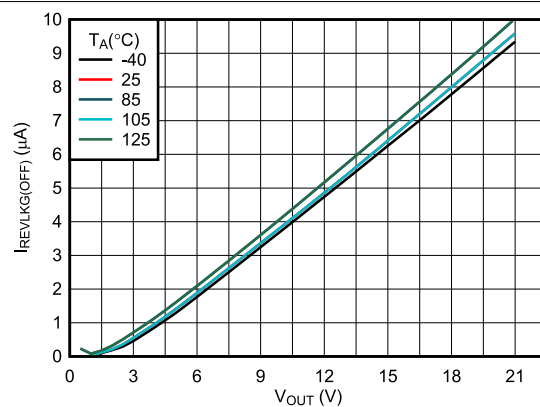


FIG 7-19. Reverse Leakage Current During OFF State

7.8 Typical Characteristics (continued)

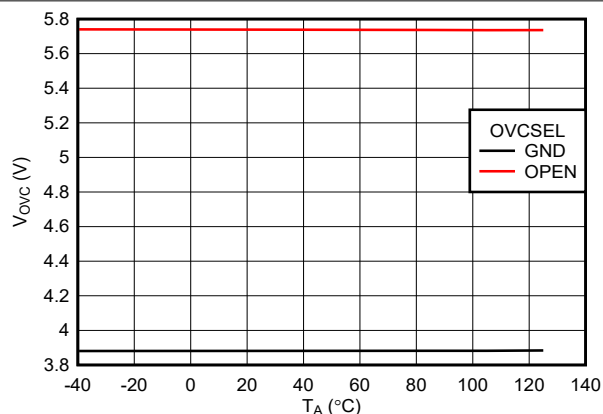


FIG 7-20. OVC Threshold vs Temperature

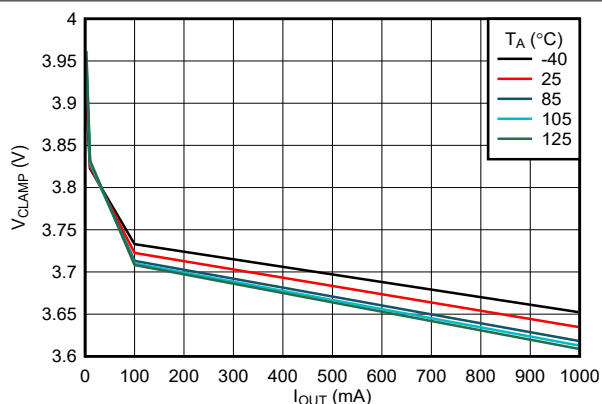


FIG 7-21. OVC Clamping Voltage (OVCSEL = GND) vs Load Current

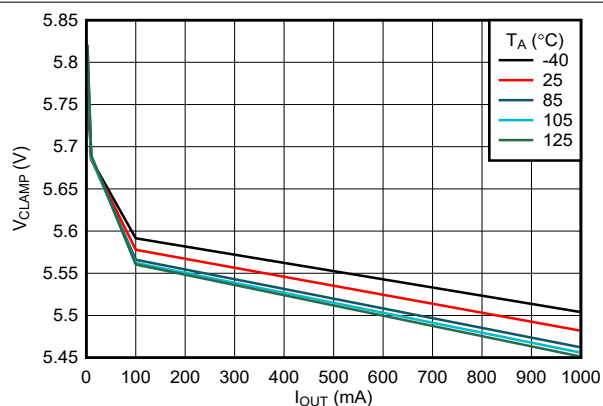


FIG 7-22. OVC Clamping Voltage (OVCSEL = Open) vs Load Current

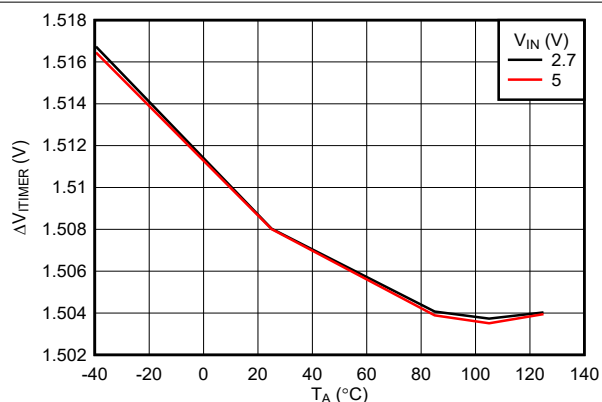


FIG 7-23. ITIMER Discharge Differential Voltage Threshold vs Temperature

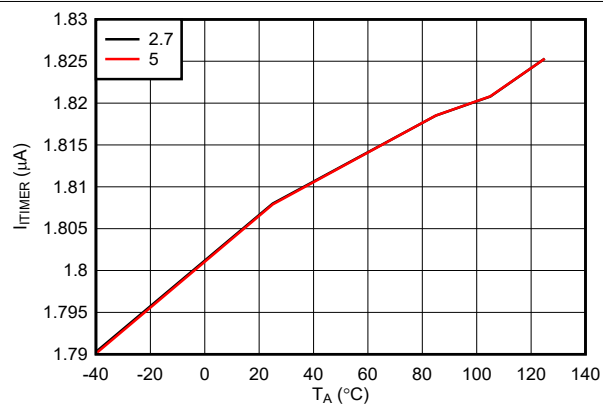


FIG 7-24. ITIMER Discharge Current vs Temperature

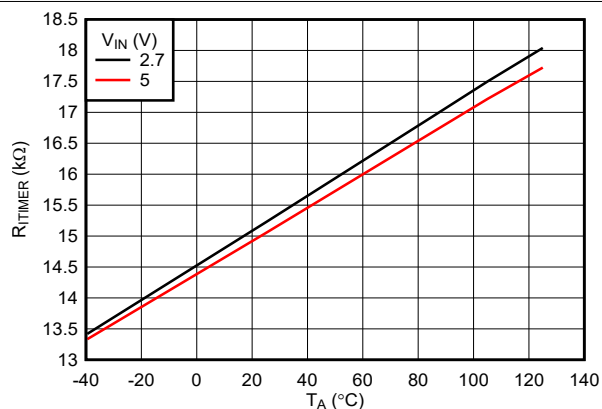


FIG 7-25. ITIMER Internal Pullup Resistance vs Temperature

7.8 Typical Characteristics (continued)

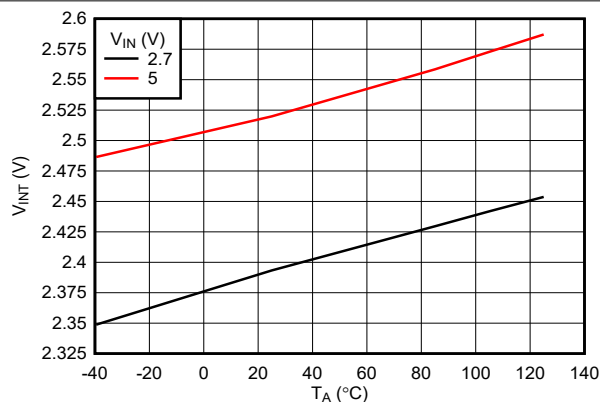


Figure 7-26. ITIMER Internal Pullup Voltage vs Temperature

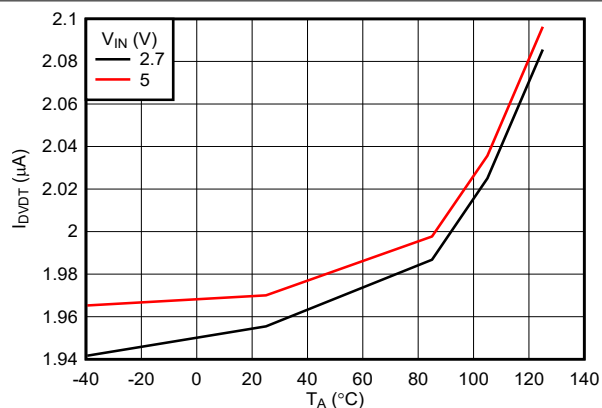


Figure 7-27. DVDVT Charging Current vs Temperature

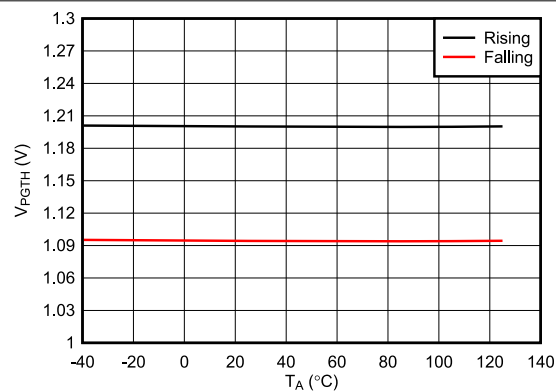


Figure 7-28. PGTH Threshold vs Temperature

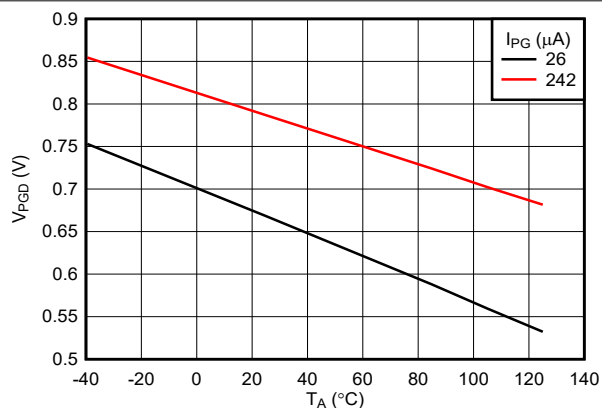


Figure 7-29. PG Low Voltage Without Input Supply vs Temperature

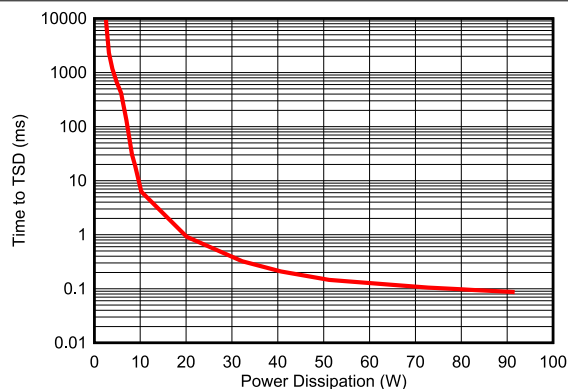


Figure 7-30. Time to Thermal Shut-Down During Inrush State

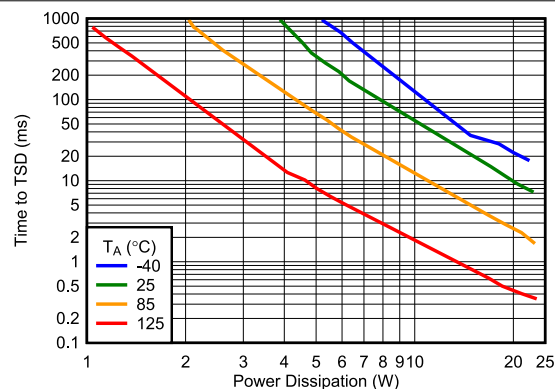
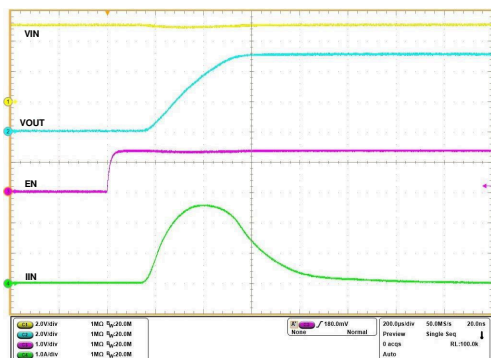


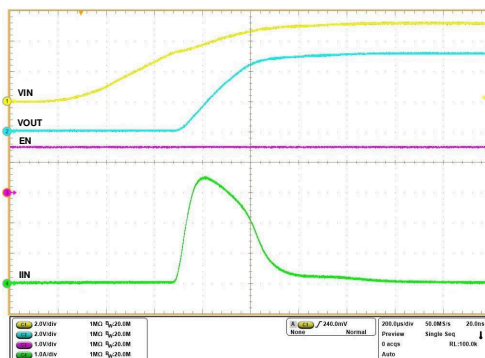
Figure 7-31. Time to Thermal Shut-Down During Steady State

7.8 Typical Characteristics (continued)



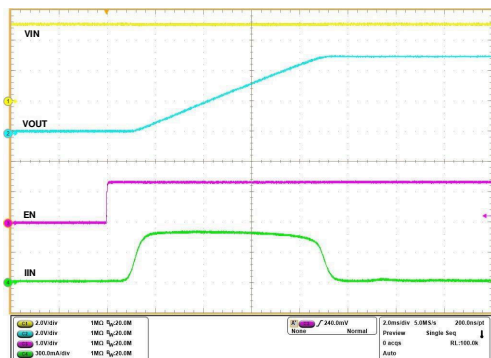
$V_{IN} = 5\text{ V}$, $C_{OUT} = 220\text{ }\mu\text{F}$, $C_{dVdt} = \text{Open}$, $V_{EN/UVLO}$ stepped up to 1.4 V

7-32. Start-Up with Enable



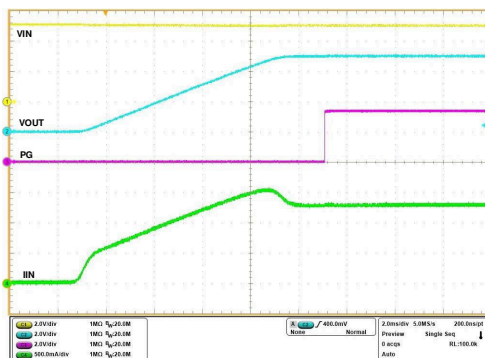
$V_{EN/UVLO} = 1.5\text{ V}$, $C_{OUT} = 220\text{ }\mu\text{F}$, $C_{dVdt} = \text{Open}$, V_{IN} ramped up to 5 V

7-33. Start-Up with Supply



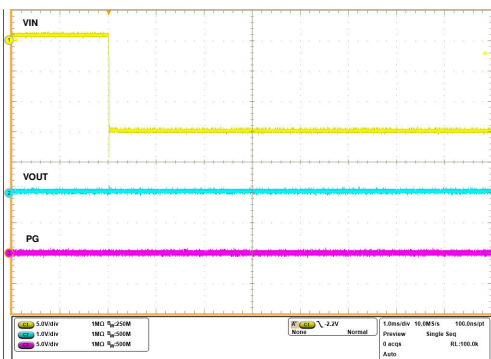
$V_{IN} = 5\text{ V}$, $C_{OUT} = 690\text{ }\mu\text{F}$, $C_{dVdt} = 3300\text{ pF}$, $V_{EN/UVLO}$ stepped up to 1.4 V

7-34. Inrush Current with Capacitive Load



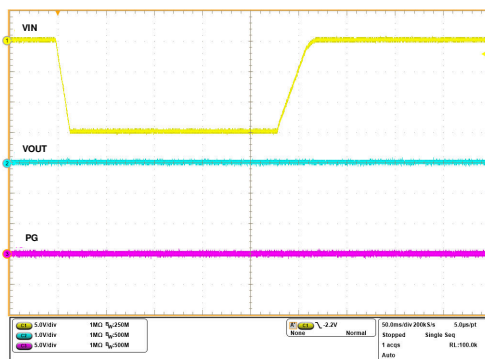
$V_{IN} = 5\text{ V}$, $C_{OUT} = 690\text{ }\mu\text{F}$, $R_{OUT} = 4\text{ }\Omega$, $C_{dVdt} = 3300\text{ pF}$, $V_{EN/UVLO}$ stepped up to 1.4 V

7-35. Inrush Current with Resistive and Capacitive Load



$C_{OUT} = 220\text{ }\mu\text{F}$, PG pulled up to 3 V, -15 V hot-plugged to IN

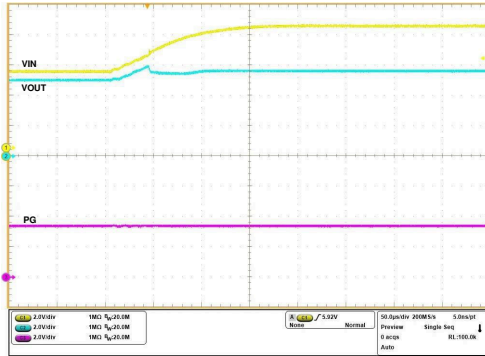
7-36. Input Reverse Polarity Protection - Fast Ramp



$C_{OUT} = 220\text{ }\mu\text{F}$, PG pulled up to 3 V, V_{IN} ramped down from 0 V to -15 V and then ramped up to 0 V

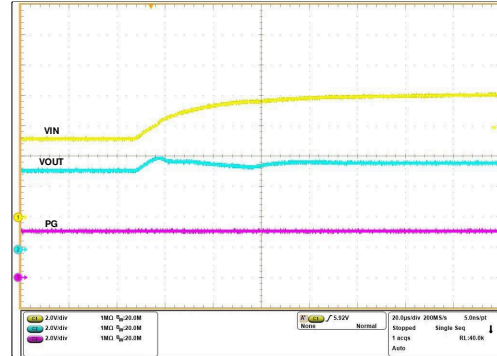
7-37. Input Reverse Polarity Protection - Slow Ramp

7.8 Typical Characteristics (continued)



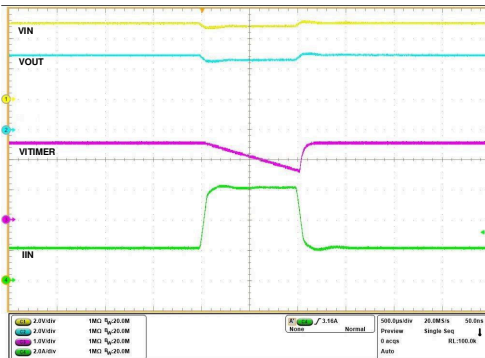
$R_{OVCSSEL} = GND$, $C_{OUT} = 220 \mu F$, $I_{OUT} = 120 \text{ mA}$, V_{IN} ramped up from 3.3 V to 6 V

7-38. Overvoltage Clamp Response



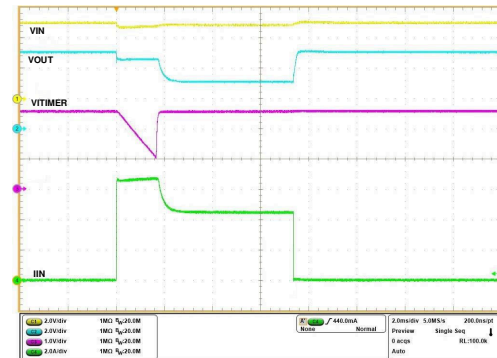
$R_{OVCSSEL} = \text{Open}$, $C_{OUT} = 220 \mu F$, $I_{OUT} = 150 \text{ mA}$, V_{IN} ramped up from 5 V to 8 V

7-39. Overvoltage Clamp Response



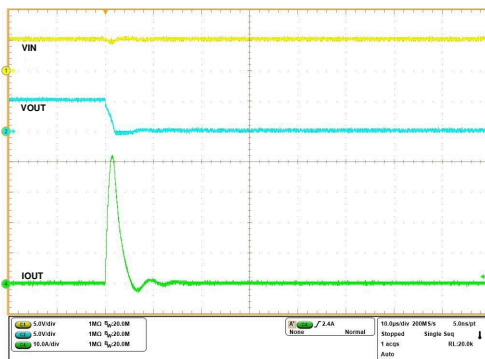
A. $V_{IN} = 5 \text{ V}$, $C_{TIMER} = 2.2 \text{ nF}$, $C_{OUT} = 220 \mu F$, $R_{ILM} = 750 \Omega$, I_{OUT} stepped from 2 A \rightarrow 6 A \rightarrow 2 A within 1 ms

7-40. Transient Overcurrent Blanking Timer Response



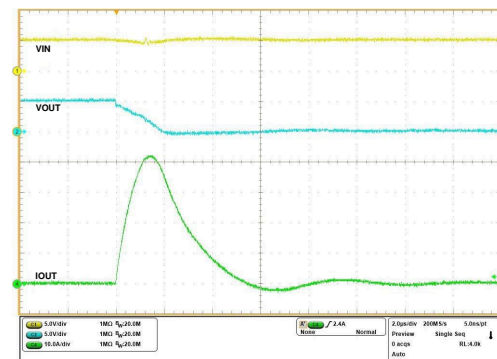
$V_{IN} = 5 \text{ V}$, $C_{TIMER} = 2.2 \text{ nF}$, $C_{OUT} = 220 \mu F$, $R_{ILM} = 750 \Omega$, I_{OUT} stepped from 0 A \rightarrow 6.7 A

7-41. Active Current Limit Response



$V_{IN} = 5 \text{ V}$, $R_{ILM} = 750 \Omega$, $V_{EN/UVLO} = 1.4 \text{ V}$, OUT stepped from Open \rightarrow Short-circuit to GND

7-42. Output Short-Circuit During Steady State



$V_{IN} = 5 \text{ V}$, $R_{ILM} = 750 \Omega$, $V_{EN/UVLO} = 1.4 \text{ V}$, OUT stepped from Open \rightarrow Short-circuit to GND

7-43. Output Short-Circuit During Steady State (Zoomed In)

8 Detailed Description

8.1 Overview

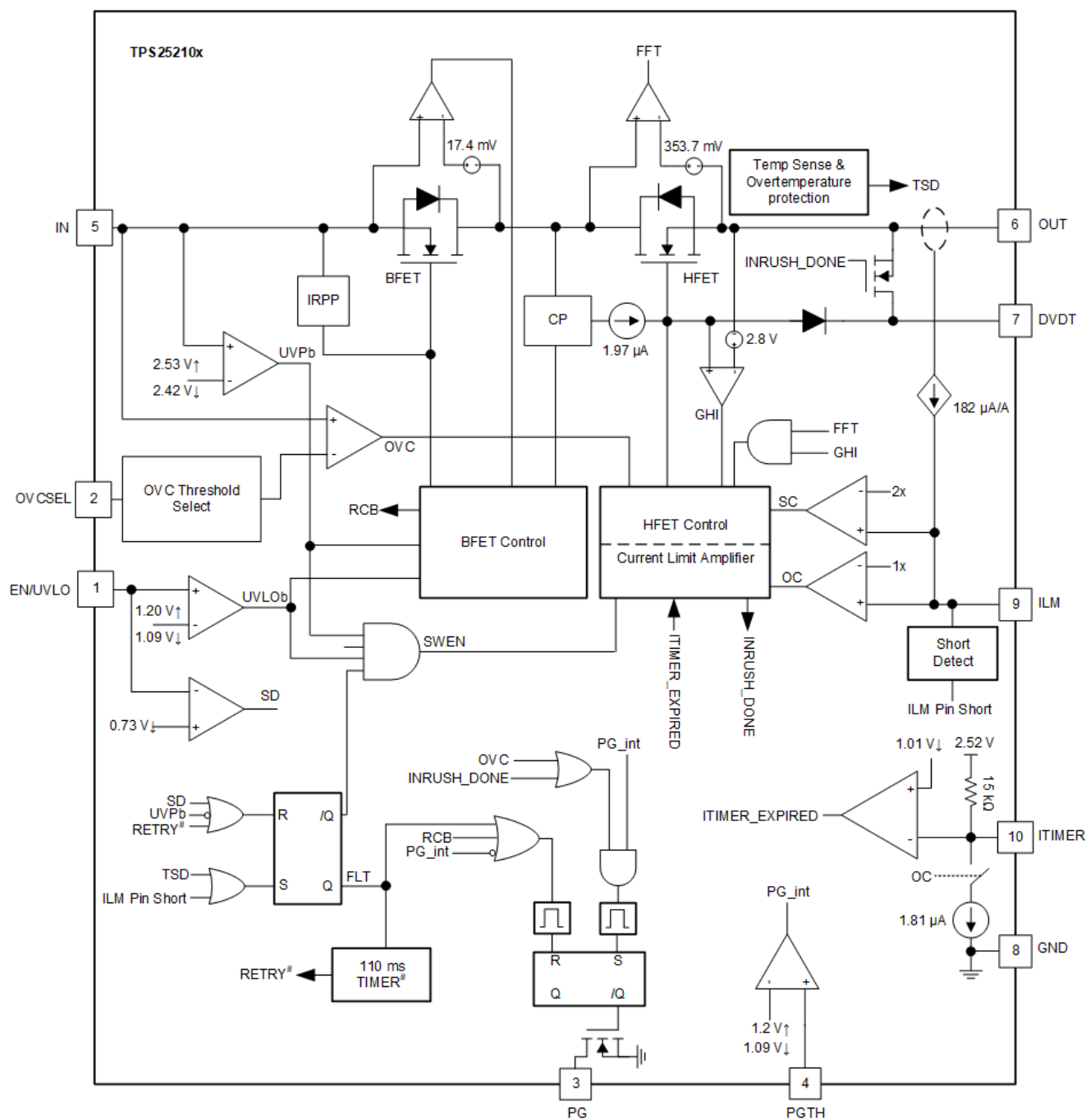
The TPS2521xx is an eFuse with integrated power path that is used to ensure safe power delivery in a system. The device starts its operation by monitoring the IN bus. When the input supply voltage (V_{IN}) exceeds the Undervoltage Protection threshold (V_{UVP}), the device samples the EN/UVLO pin. A high level ($> V_{UVLO}$) on this pin enables the internal power path (BFET + HFET) to start conducting and allow current to flow from IN to OUT. When EN/UVLO is held low ($< V_{UVLO}$), the internal power path is turned off. In case of reverse voltages appearing at the input, the power path remains OFF thereby protecting the output load.

After a successful start-up sequence, the device now actively monitors its load current and input voltage, and controls the internal HFET to ensure that the user adjustable overcurrent limit threshold (I_{LIM}) is not exceeded and overvoltage spikes are either safely clamped to the selected threshold voltage (V_{OVC}). The device also provides fast protection against severe overcurrent during short-circuit events. This keeps the system safe from harmful levels of voltage and current. At the same time, a user adjustable overcurrent blanking timer allows the system to pass moderate transient peaks in the load current profile without tripping the eFuse. This ensures a robust protection solution against real faults which is also immune to transients, thereby ensuring maximum system uptime.

The device has integrated reverse current blocking FET (BFET) which operates like an ideal diode. The BFET is linearly regulated to maintain a small constant forward drop (V_{FWD}) in forward conduction mode and turned off completely to block reverse current if output voltage exceeds the input voltage.

The device also has a built-in thermal sensor based shutdown mechanism to protect itself in case the device temperature (T_J) exceeds the recommended operating conditions.

8.2 Functional Block Diagram



8.3 Feature Description

The TPS2521xx eFuse is a compact, feature rich power management device that provides detection, protection and indication in the event of system faults.

8.3.1 Input Reverse Polarity Protection

The TPS2521xx device is internally protected against steady state negative voltages applied at the input supply pin. The device blocks the negative voltage from appearing at the output, thereby protecting the load circuits. There's no reverse current flowing from output to the input in this condition. The lowest negative voltage the device can handle at the input is limited to -15 V or $V_{\text{OUT}} - 21\text{ V}$, whichever is higher. TI also recommends that all signal pins (for example, EN/UVLO, PGTH) which are connected to input supply should have a sufficiently large pullup resistor to limit the current flowing out of these pins during reverse polarity conditions.

8.3.2 Undervoltage Lockout (UVLO and UVP)

The TPS2521x implements Undervoltage Protection on IN in case the applied voltage becomes too low for the system or device to properly operate. The Undervoltage Protection has a default lockout threshold of V_{UVP} which is fixed internally. Also, the UVLO comparator on the EN/UVLO pin allows the Undervoltage Protection threshold to be externally adjusted to a user defined value. The [Figure 8-1](#) and [Equation 1](#) show how a resistor divider can be used to set the UVLO set point for a given voltage supply.

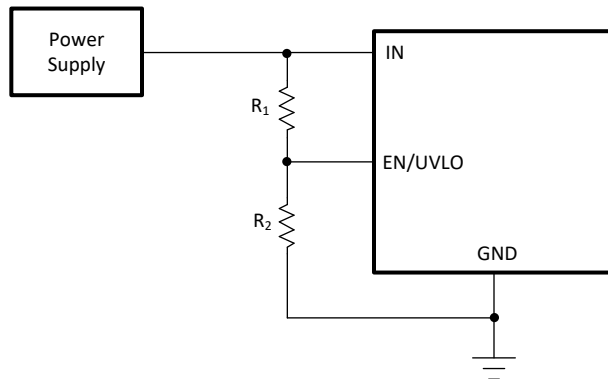


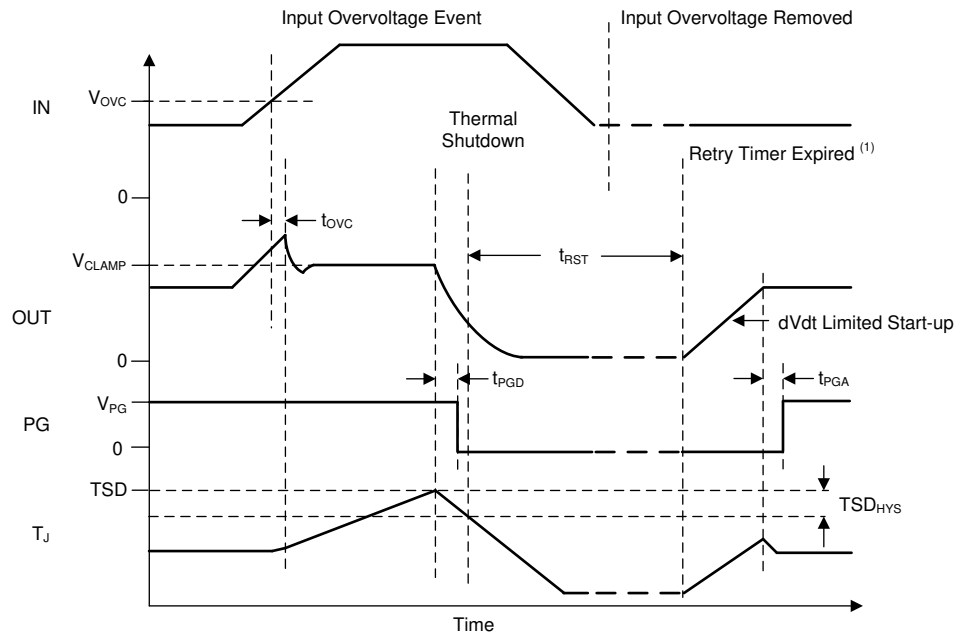
Figure 8-1. Adjustable Undervoltage Protection

$$V_{\text{IN(UV)}} = \frac{V_{\text{UVLO(R)}} \times (R1 + R2)}{R2} \quad (1)$$

8.3.3 Overvoltage Clamp (OVC)

The TPS2521xx implements a voltage clamp on the output to protect the system in the event of input overvoltage. When the device detects the input has exceeded the Overvoltage Clamp Threshold (V_{OVC}), it quickly responds within t_{OVC} and stops the output from rising further and then regulates the HFET linearly to clamp the output voltage below V_{CLAMP} as long as an overvoltage condition is present on the input.

If the part stays in clamping state for an extended period of time, there is higher power dissipation inside the part which can eventually lead to thermal shut-down (TSD). After the part shuts down due to TSD fault, it either stays latched off (TPS2521xL variant) or restarts automatically after a fixed delay (TPS2521xA variant). See [Overtemperature Protection \(OTP\)](#) for more details on device response to overtemperature.



(1) Applicable only for TPS25210A (Auto-retry variant)

图 8-2. TPS2521xA Overvoltage Response (Auto-Retry)

There are two available overvoltage clamp threshold options which can be configured using the OVCSEL pin.

表 8-1. TPS2521xx Overvoltage Clamp Threshold Selection

OVCSEL Pin Connection	Overvoltage Clamp Threshold
Shorted to GND	3.8 V
Open	5.7 V

8.3.4 Inrush Current, Overcurrent, and Short Circuit Protection

TPS2521xx incorporates four levels of protection against overcurrent:

1. Adjustable slew rate (dVdt) for inrush current control
2. Adjustable threshold (I_{LIM}) for overcurrent protection during start-up or steady-state
3. Adjustable threshold (I_{SC}) for fast-trip response to severe overcurrent during start-up or steady-state
4. Fixed threshold (I_{FT}) for fast-trip response to quickly protect against hard output short-circuits during steady-state

8.3.4.1 Slew Rate (dVdt) and Inrush Current Control

During hot-plug events or while trying to charge a large output capacitance at start-up, there can be a large inrush current. If the inrush current is not managed properly, it can damage the input connectors and/or cause the system power supply to droop leading to unexpected restarts elsewhere in the system. The inrush current during turn on is directly proportional to the load capacitance and rising slew rate. 式 2 can be used to find the slew rate (SR) required to limit the inrush current (I_{INRUSH}) for a given load capacitance (C_{OUT}):

$$SR (V/ms) = \frac{I_{INRUSH} (mA)}{C_{OUT} (\mu F)} \quad (2)$$

A capacitor can be connected to the dVdt pin to control the rising slew rate and lower the inrush current during turn on. The required C_{dVdt} capacitance to produce a given slew rate can be calculated using 式 3.

$$C_{dVdt} (pF) = \frac{2000}{SR (V/ms)} \quad (3)$$

The fastest output slew rate is achieved by leaving the dVdt pin open.

Note

For $C_{dVdt} > 10 \text{ nF}$, Ti recommends to add a 100-Ω resistor in series with the capacitor on the dVdt pin.

8.3.4.2 Active Current Limiting

The TPS2521xx responds to output overcurrent conditions by actively limiting the current after a user adjustable transient fault blanking interval. When the load current exceeds the set overcurrent threshold (I_{LIM}) set by the ILM pin resistor (R_{ILM}), but stays lower than the short-circuit threshold ($2 \times I_{LIM}$), the device starts discharging the ITIMER pin capacitor using an internal 1.8-μA pulldown current. If the load current drops below the overcurrent threshold before the ITIMER capacitor (C_{ITIMER}) discharges by ΔV_{ITIMER} , the ITIMER is reset by pulling it up to V_{INT} internally and the current limit action is not engaged. This allows short load transient pulses to pass through the device without getting current limited. If the overcurrent condition persists, the C_{ITIMER} continues to discharge and after it discharges by ΔV_{ITIMER} , the current limit starts regulating the HFET to actively limit the current to the set overcurrent threshold (I_{LIM}). At the same time, the C_{ITIMER} is charged up to V_{INT} again so that it is at its default state before the next overcurrent event. This ensures the full blanking timer interval is provided for every overcurrent event. 式 4 can be used to calculate the R_{ILM} value for a desired overcurrent threshold.

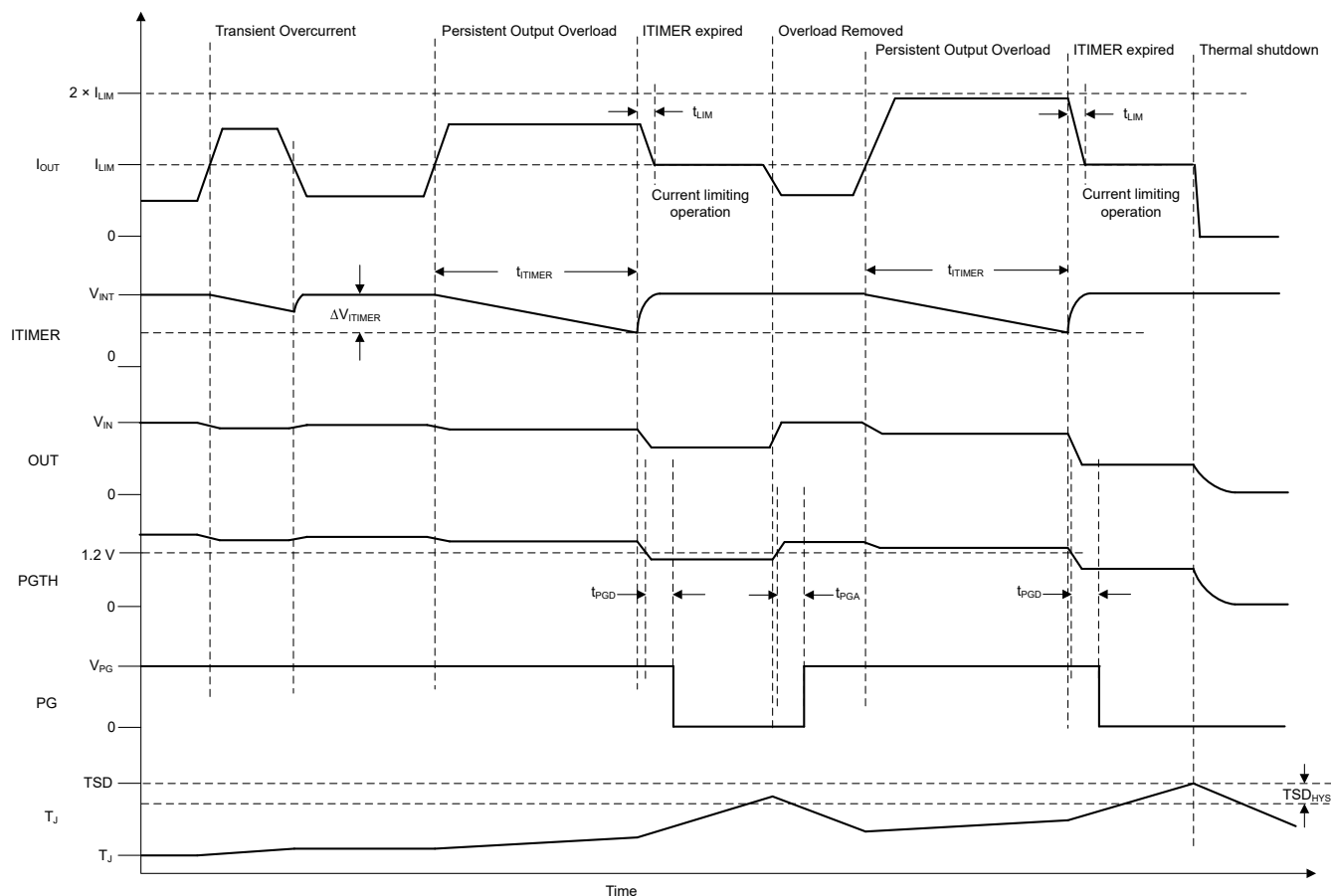
$$R_{ILM} (\Omega) = \frac{3334}{I_{LIM} (A)} \quad (4)$$

Note

1. Leaving the ILM pin open sets the current limit to nearly zero and results in the part entering current limit with the slightest amount of loading at the output.
 2. The current limit circuit employs a foldback mechanism. The current limit threshold in the foldback region ($0 \text{ V} < V_{OUT} < V_{FB}$) is lower than the steady state current limit threshold (I_{LIM}).
 3. Shorting the ILM pin to ground at any point during normal operation is detected as a fault and the part shuts down. There is a minimum current (I_{FLT}) which the part allows in this condition before the pin short condition is detected.
-

The duration for which transients are allowed can be adjusted using an appropriate capacitor value from ITIMER pin to ground. The C_{ITIMER} value needed to set the desired transient overcurrent blanking interval can be calculated using 式 5 below.

$$t_{ITIMER} (\text{ms}) = \frac{\Delta V_{ITIMER} (V) \times C_{ITIMER} (\text{nF})}{I_{ITIMER} (\mu A)} \quad (5)$$



8-3. TPS2521xx Active Current Limit Response

Note

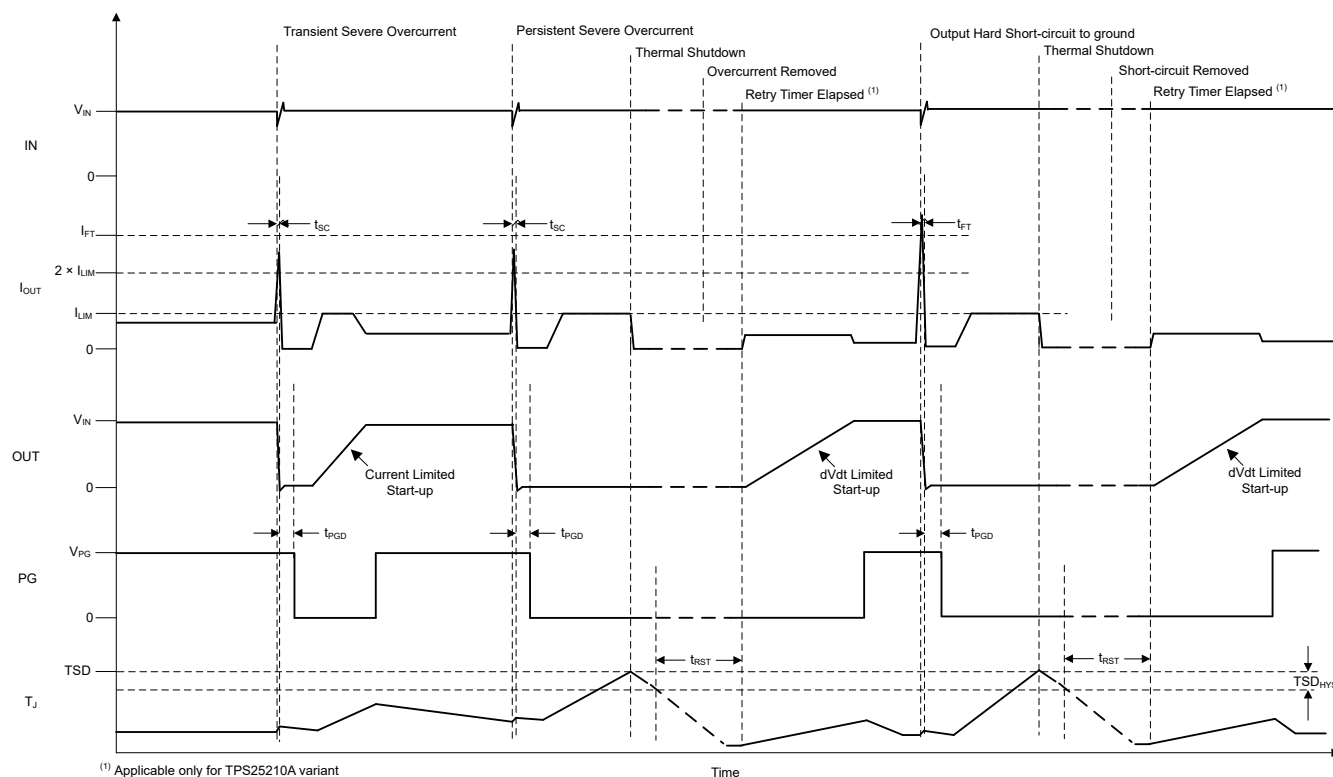
1. Leave the ITIMER pin open to allow the part to limit the current with the minimum possible delay.
2. Shorting the ITIMER pin to ground results in minimum overcurrent response delay (similar to ITIMER pin open condition), but increases the device current consumption. This is not a recommended mode of operation.
3. Active current limiting based on R_{ILIM} is active during start-up. In case the start-up current exceeds I_{LIM} , the device regulates the current to the set limit. However, during start-up the current limit is engaged without waiting for the ITIMER delay.
4. During overvoltage clamp condition, if an overcurrent event occurs, the current limit is engaged without waiting for the ITIMER delay.
5. Increasing the C_{ITIMER} value extends the overcurrent blanking interval, but it also extends the time needed for the C_{ITIMER} to recharge up to V_{INT} . If the next overcurrent event occurs before the C_{ITIMER} is recharged fully, it takes lesser time to discharge to the ITIMER expiry threshold, thereby providing a shorter blanking interval than intended.

During active current limit, the output voltage drops resulting in increased device power dissipation across the HFET. If the device internal temperature (T_J) exceeds the thermal shutdown threshold (TSD), the HFET is turned off. After the part shuts down due to TSD fault, it either stays latched off (TPS2521x1L variant) or restarts automatically after a fixed delay (TPS2521xA variant). See [Overtemperature Protection \(OTP\)](#) for more details on device response to overtemperature.

8.3.4.3 Short-Circuit Protection

During an output short-circuit event, the current through the device increases very rapidly. When a severe overcurrent condition is detected, the device triggers a fast-trip response to limit the current to a safe level. The

internal fast-trip comparator employs a scalable threshold (I_{SC}) which is equal to $2 \times I_{LIM}$. This enables the user to adjust the fast-trip threshold rather than using a fixed threshold which can be too high for some low current systems. The device also employs a fixed fast-trip threshold (I_{FT}) to protect fast protection against hard short-circuits during steady state. The fixed fast-trip threshold is higher than the maximum recommended user adjustable scalable fast-trip threshold. After the current exceeds I_{SC} or I_{FT} , the HFET is turned off completely within t_{FT} . Thereafter, the device tries to turn the HFET back ON after a short de-glitch interval (30 μ s) in a current limited manner instead of a dVdt limited manner. This ensures that the HFET has a faster recovery after a transient overcurrent event and minimizes the output voltage droop. However, if the fault is persistent, the device stays in current limit causing the junction temperature to rise and eventually enter thermal shutdown. See [Overtemperature Protection \(OTP\)](#) section for details on the device response to overtemperature.



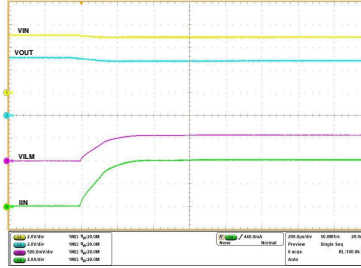
8-4. TPS2521xx Short-Circuit Response

8.3.5 Analog Load Current Monitor

The device allows the system to accurately monitor the output load current by providing an analog current sense output on the ILM pin which is proportional to the current through the FET. The user can sense the voltage (V_{ILM}) across the R_{ILM} to get a measure of the output load current.

$$I_{OUT} (A) = \frac{V_{ILM} (\mu V)}{R_{ILM} (\Omega) \times G_{IMON} (\mu A/A)} \quad (6)$$

The waveform below shows the ILM signal response to a load step at the output.



$V_{IN} = 5\text{ V}$, $C_{OUT} = 220\text{ }\mu\text{F}$, $R_{ILM} = 750\text{ }\Omega$, I_{OUT} stepped up from 0 A to 4 A

8-5. Analog Load Current Monitor Response

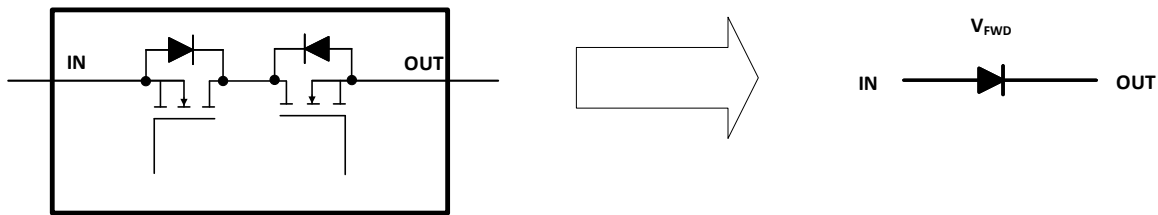
Note

The ILM pin is sensitive to capacitive loading. Careful design and layout is needed to ensure the parasitic capacitive loading on the ILM pin is $< 50\text{ pF}$ for stable operation.

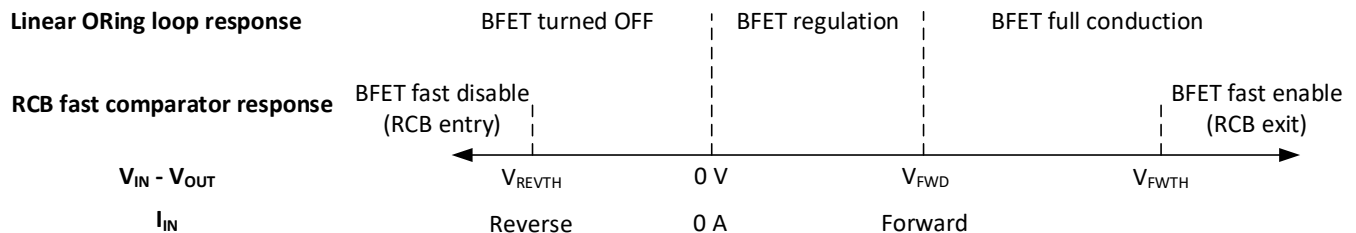
8.3.6 Reverse Current Protection

The device functions like an ideal diode and blocks reverse current flow from OUT to IN under all conditions. The device has integrated back-to-back MOSFETs connected in a common drain configuration. The voltage drop between the IN and OUT pins is constantly monitored and the gate drive of the blocking FET (BFET) is adjusted as needed to regulate the forward voltage drop at V_{FWD} . This closed loop regulation scheme (linear ORing control) enables graceful turn off of the MOSFET during a reverse current event and ensures there is no DC reverse current flow.

The device also uses a conventional comparator (V_{REVTH}) based reverse blocking mechanism to provide fast response (t_{RCB}) to transient reverse currents. After the device enters reverse current blocking condition, it waits for the ($V_{IN} - V_{OUT}$) forward drop to exceed the V_{FWDTH} before it performs a fast recovery to reach full forward conduction state. This provides sufficient hysteresis to prevent supply noise or ripple from affecting the reverse current blocking response. The recovery from reverse current blocking is very fast (t_{SWRCB}). This ensures minimum supply droop which is helpful in applications such as supply MUXing/ORing and USB Fast Role Swap (FRS).



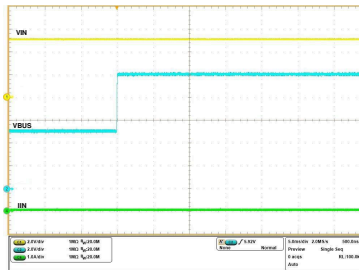
BFET operating state



8-6. Reverse Current Blocking Response

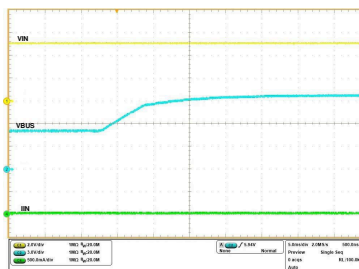
The waveforms below illustrate the reverse current blocking performance in various scenarios.

During fast voltage step at output (for example, hot-plug), the fast comparator based reverse blocking mechanism ensures minimum jump/glitch on the input rail.



8-7. Reverse Current Blocking Performance During Fast Voltage Step at Output

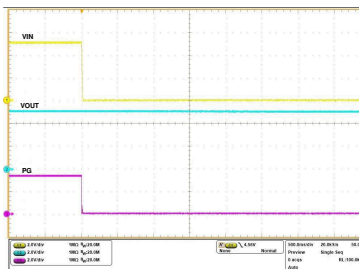
During slow voltage ramp at output, the linear ORing based reverse blocking mechanism ensures there is no DC current flow from OUT to IN, thereby avoiding input rail from getting slowly charged up to output voltage.



8-8. Reverse Current Blocking Performance During Slow Voltage Ramp at Output

When the input supply droops or gets disconnected while the output storage element (capacitor bank or super capacitor) is charged to the full voltage, the linear ORing scheme minimizes the self-discharge from OUT to IN. This ensures maximum hold-up time for the output storage element in critical power back-up applications.

It also prevents incorrect supply presence indication in applications which sense the input voltage to detect if the supply is connected.



8-9. Reverse Current Blocking Performance During Input Supply Failure

8.3.7 Overtemperature Protection (OTP)

The device monitors the internal die temperature (T_J) at all times and shuts down the part as soon as the temperature exceeds a safe operating level (TSD) thereby protecting the device from damage. The device does not turn back on until the junction cools down sufficiently, that is the die temperature falls below $(TSD - TSD_{HYS})$.

When the TPS2521xL (latch-off variant) detects thermal overload, it shuts down and remains latched-off until the device is power cycled or re-enabled. When the TPS2521xA (auto-retry variant) detects thermal overload, it remains off until it has cooled down by TSD_{HYS} . Thereafter, the device remains off for an additional delay of t_{RST} after which it automatically retries to turn on if it is still enabled.

表 8-2. Thermal Shutdown

Device	Enter TSD	Exit TSD
TPS2521xL (Latch-Off)	$T_J \geq TSD$	$T_J < TSD - TSD_{HYS}$ V_{IN} cycled to 0 V and then above $V_{UVP(R)}$ OR EN/UVLO toggled below $V_{SD(F)}$
TPS2521xA (Auto-Retry)	$T_J \geq TSD$	$T_J < TSD - TSD_{HYS}$ V_{IN} cycled to 0 V and then above $V_{UVP(R)}$ OR EN/UVLO toggled below $V_{SD(F)}$ OR t_{RST} timer expired

8.3.8 Fault Response

The following table summarizes the device response to various fault conditions.

表 8-3. Fault Summary

Event	Protection Response	Fault Latched Internally
Overtemperature	Shutdown	Y
Undervoltage (UVP or UVLO)	Shutdown	N
Input Reverse Polarity	Shutdown	N
Input Overvoltage	Voltage Clamp	N
Transient Overcurrent ($I_{LIM} < I_{OUT} < 2 \times I_{LIM}$)	None	N
Persistent Overcurrent	Current Limit	N
Output Short-Circuit to GND	Fast-trip followed by Current Limit	N
ILM Pin Open (During Steady State)	Shutdown	N
ILM Pin Shorted to GND	Shutdown	Y
Reverse Current ($(V_{OUT} - V_{IN}) > V_{REVTH}$)	Reverse Current Blocking	N

Faults which are latched internally can be cleared either by power cycling the part (pulling V_{IN} to 0 V) or by pulling the EN/UVLO pin voltage below V_{SD} . This also resets the t_{RST} timer for the TPS2521xA (auto-retry) variants.

During a latched fault, pulling the EN/UVLO just below the UVLO threshold has no impact on the device. This is true for both TPS2521xL (latch-off) and TPS2521xA (auto-retry) variants.

For TPS2521xA (auto-retry) variant, on expiry of the t_{RST} timer after a fault, the device restarts automatically.

8.3.9 Power Good Indication (PG)

The TPS2521xx provides an active high digital output (PG) which serves as a power good indication signal and is asserted high depending on the voltage at the PGTH pin along with the device state information. The PG is an open-drain pin and needs to be pulled up to an external supply.

After power up, PG is pulled low initially. The device initiates a inrush sequence in which the HFET is turned on in a controlled manner. When the HFET gate voltage reaches the full overdrive indicating that the inrush sequence is complete and the voltage at PGTH is above $V_{PGTH(R)}$, the PG is asserted after a de-glitch time (t_{PGA}).

PG is de-asserted if at any time during normal operation, the voltage at PGTH falls below $V_{PGTH(F)}$, or the device detects a fault (except overcurrent). The PG de-assertion de-glitch time is t_{PGD} .

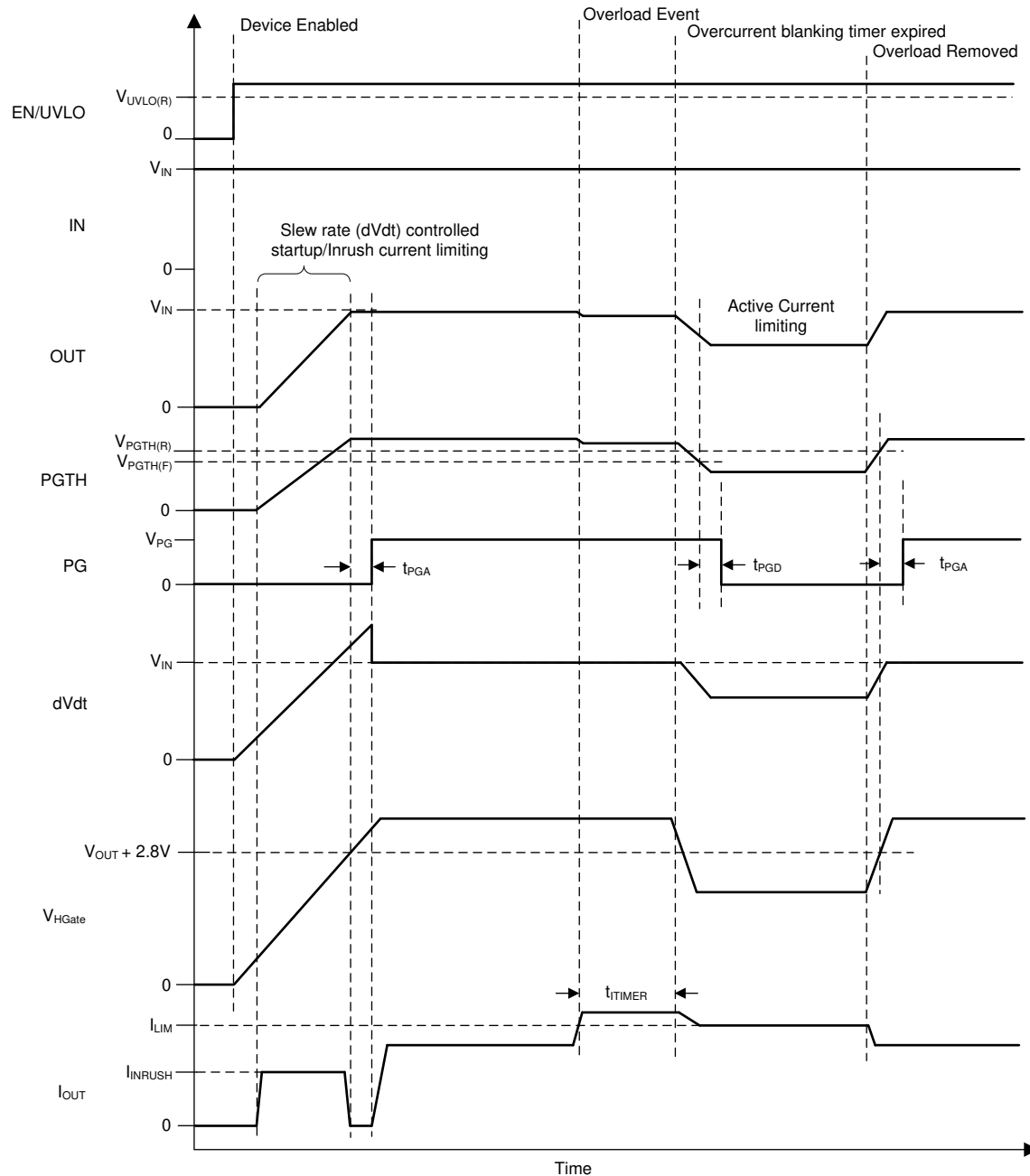


图 8-10. TPS2521xx PG Timing Diagram

表 8-4. TPS2521xx PG Indication Summary

Event	Protection Response	PG Pin	PG Delay
Undervoltage (UVP or UVLO)	Shutdown	L	
Input Reverse Polarity	Shutdown	L	
Overshoot (OVC)	Clamp	H (If PGTH pin voltage > $V_{PGTH(R)}$) L (If PGTH pin voltage < $V_{PGTH(F)}$)	t_{PGA} t_{PGD}

表 8-4. TPS2521xx PG Indication Summary (continued)

Event	Protection Response	PG Pin	PG Delay
Steady State	NA	H (If PGTH pin voltage > $V_{PGTH(R)}$) L (If PGTH pin voltage < $V_{PGTH(F)}$)	t_{PGA} t_{PGD}
Transient Overcurrent	NA	H (If PGTH pin voltage > $V_{PGTH(R)}$) L (If PGTH pin voltage < $V_{PGTH(F)}$)	t_{PGA} t_{PGD}
Persistent Overload	Current Limiting	H (If PGTH pin voltage > $V_{PGTH(R)}$) L (If PGTH pin voltage < $V_{PGTH(F)}$)	t_{PGA} t_{PGD}
Output Short-Circuit to GND	Fast trip followed by Current Limit	H (If PGTH pin voltage > $V_{PGTH(R)}$) L (If PGTH < $V_{PGTH(F)}$)	t_{PGA} t_{PGD}
ILM Pin Open	Shutdown	L (If PGTH pin voltage < $V_{PGTH(F)}$)	t_{PGD}
ILM Pin Shorted to GND	Shutdown	L (If PGTH < $V_{PGTH(F)}$)	t_{PGD}
Reverse Current ($(V_{OUT} - V_{IN}) > V_{REVTH}$)	Reverse Current Blocking	L	t_{PGD}
Overtemperature	Shutdown	L	

When there is no supply to the device, the PG pin is expected to stay low. However, there is no active pulldown in this condition to drive this pin all the way down to 0 V. If the PG pin is pulled up to an independent supply which is present even if the device is unpowered, there can be a small voltage seen on this pin depending on the pin sink current, which is a function of the pullup supply voltage and resistor. Minimize the sink current to keep this pin voltage low enough not to be detected as a logic HIGH by associated external circuits in this condition.

8.4 Device Functional Modes

表 8-5. TPS2521xx Overvoltage Clamp Threshold Selection

OVCSEL Pin Connection	Overvoltage Clamp Threshold
Shorted to GND	3.8 V
Open	5.7 V

9 Application and Implementation

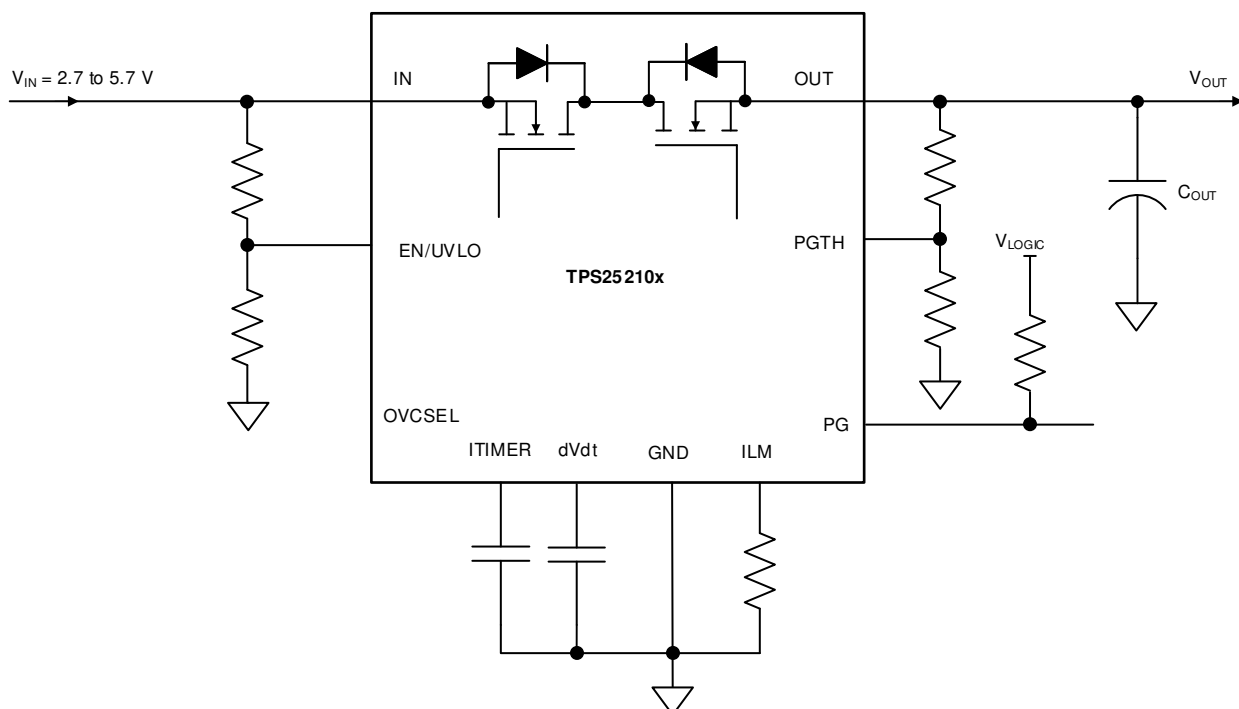
Note

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9.1 Application Information

The TPS2521xx is a 2.7-V to 5.7-V, 4-A eFuse that is typically used for power rail protection applications. The device can withstand maximum input voltage of 28 V with adjustable undervoltage lockout and fast overvoltage clamp protection. The device provides ability to control inrush current and protection against input reverse polarity as well as reverse current conditions. The device can be used in a variety of systems such as adapter input protection, storage – eSSD/cSSD, e-meters, smart speakers, headphones, USB power accessories. The design procedure explained in the subsequent sections can be used to select the supporting component values based on the application requirement. Additionally, a spreadsheet design tool, [TPS2521x Design Calculator](#), is available in the web product folder.

9.2 Single Device, Self-Controlled



9-1. Single Device, Self-Controlled

Other variations:

In a Host MCU controlled system, EN/UVLO or OVCSEL can also be driven from the host GPIO to control/configure the device operation.

ILM pin can be connected to the MCU ADC input for current monitoring purpose.

Note

TI recommends to keep parasitic capacitance on ILM pin below 50 pF to ensure stable operation.

Either V_{IN} or V_{OUT} can be used to drive the PGTH resistor divider depending on which supply needs to be monitored for power good indication.

9.3 Typical Application

End equipments like PC, notebooks, docking stations, monitors, and so on have USB PD ports which can be configured as DFP (Source), UFP (Sink) or DRP (Source + Sink). TPS2521xx can be used independently or in conjunction with LM73100 to handle the power path protection requirements of USB PD ports as shown in [Figure 9-2](#) below.

TPS2521xx provides overcurrent and short-circuit protection in the source path, while blocking any reverse current from the port to the internal source power rail. The fast recovery (t_{SWRCB}) from reverse current blocking ensures minimum supply droop during Fast Role Swap (FRS) events.

The LM73100 provides overvoltage protection on the sink path, while blocking reverse current from internal sink rail to the port.

The linear ORing mechanism in TPS2521xx and LM73100 ensures that there is no reverse current flowing from one power source to the other during fast or slow ramp of either supply.

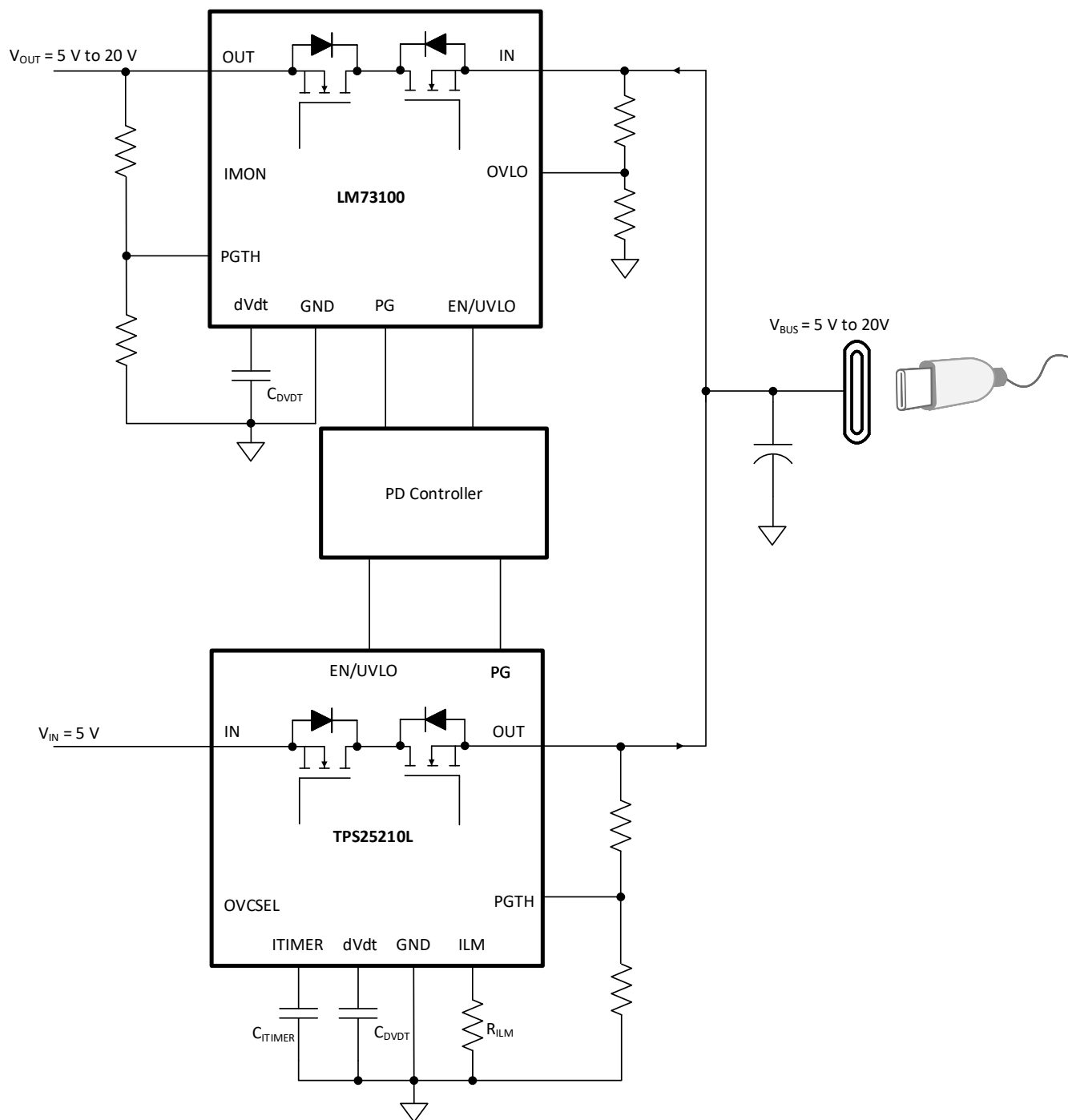


图 9-2. USB PD Port Protection

9.3.1 Application

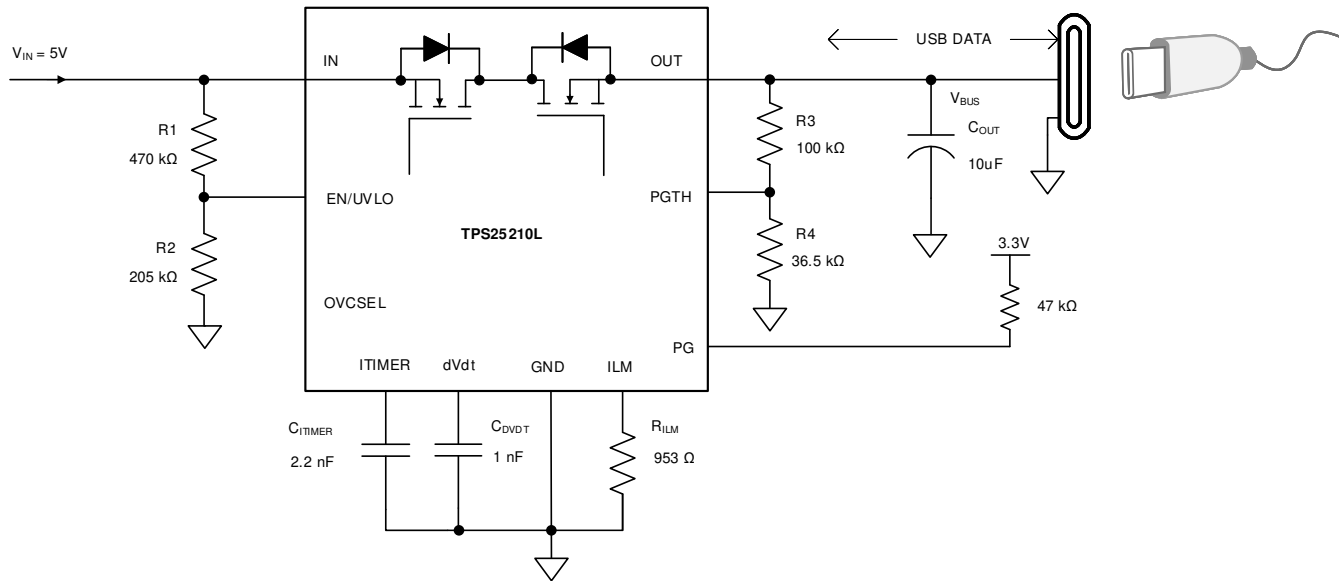


图 9-3. TPS2521xx Application Circuit for USB PD Source Path Protection

9.3.2 Design Requirements

表 9-1. Design Parameters

PARAMETER	VALUE
Input supply voltage (V_{IN})	5 V
Undervoltage threshold ($V_{IN(UV)}$)	4 V
Overvoltage clamp ($V_{IN(OVC)}$)	5.7 V
Output Power Good threshold (V_{PG})	4.5 V
Output capacitance (C_{OUT})	10 μ F
Output Slew Rate (SR)	2 V/ms
Max continuous current	3 A
Overcurrent response	Current limit
Current limit threshold (I_{LIM})	3.5 A
Load transient blanking interval (t_{ITIMER})	2 ms
Fault response	Latch-off

9.3.3 Detailed Design Procedure

9.3.3.1 Device Selection

Because the application requires current limit response to overcurrent with latch-off response after a fault, the TPS25210L variant is selected after referring to the [Device Comparison Table](#).

9.3.3.2 Setting Undervoltage and Overvoltage Thresholds

The supply undervoltage threshold is set using the resistors R1, R2 and can be calculated using 式 7:

$$V_{IN(UV)} = \frac{V_{UVLO(R)} \times (R1 + R2)}{R2} \quad (7)$$

$V_{UVLO(R)}$ is the UVLO rising threshold. Because R1 and R2 leak the current from input supply V_{IN} , these resistors must be selected based on the acceptable leakage current from input power supply V_{IN} . The current drawn by R1 and R2 from the power supply is $I_{R12} = V_{IN} / (R1 + R2)$. However, leakage currents due to external active

components connected to the resistor string can add error to these calculations. So, the resistor string current, IR12 must be chosen to be 20 times greater than the leakage current expected on the EN/UVLO pin.

From the device electrical specifications, the EN/UVLO leakage current is 0.1 μA (maximum), and $V_{\text{UVLO(R)}} = 1.2\text{ V}$. From design requirements, $V_{\text{IN(UV)}} = 4\text{ V}$. To solve the equation, first choose the value of $R_1 = 470\text{ k}\Omega$ and use the above equation to solve for $R_2 = 201.4\text{ k}\Omega$.

Using the closest standard 1% resistor values, we get $R_1 = 470\text{ k}\Omega$ and $R_2 = 205\text{ k}\Omega$.

Refer to 表 8-5 to set overvoltage clamp. OVCSEL pin is left open to select overvoltage clamp as 5.7 V.

9.3.3.3 Setting Output Voltage Rise Time (t_R)

The slew rate (SR) needed to meet the target specification is:

$$\text{SR (V/ms)} = 2\text{ V/ms} \quad (8)$$

The C_{dVdt} needed to achieve this slew rate can be calculated as:

$$C_{\text{dVdt}} (\text{pF}) = \frac{2000}{\text{SR (V/ms)}} = \frac{2000}{2} = 1000\text{ pF} \quad (9)$$

Choose the nearest standard capacitor value as 1 nF.

For this slew rate, the inrush current can be calculated as:

$$I_{\text{INRUSH}} (\text{mA}) = \text{SR (V/ms)} \times C_{\text{OUT}} (\mu\text{F}) = 2 \times 10 = 20\text{ mA} \quad (10)$$

The average power dissipation inside the part during inrush can be calculated as:

$$PD_{\text{INRUSH}} (\text{W}) = \frac{I_{\text{INRUSH}} (\text{A}) \times V_{\text{IN}} (\text{V})}{2} = \frac{0.02 \times 5}{2} = 0.05\text{ W} \quad (11)$$

The power dissipation is below the allowed limit for a successful start-up without hitting thermal shut-down within the target rise time as shown in 图 9-4.

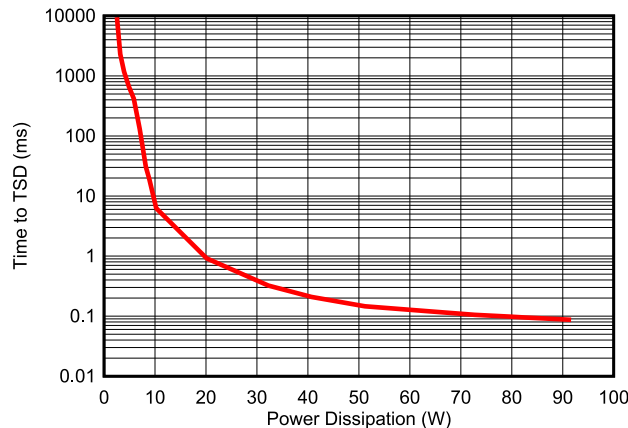


图 9-4. Thermal Shut-Down Plot During Inrush

9.3.3.4 Setting Power Good Assertion Threshold

The Power Good assertion threshold can be set using the resistors R3 and R4 connected to the PGTH pin whose values can be calculated as:

$$V_{PG} = \frac{V_{PGTH(R)} \times (R3 + R4)}{R4} \quad (12)$$

Because R3 and R4 leak the current from the output rail V_{OUT} , these resistors must be selected to minimize the leakage current. The current drawn by R3 and R4 from the power supply is $I_{R34} = V_{OUT} / (R3 + R4)$. However, leakage currents due to external active components connected to the resistor string can add error to these calculations. So, the resistor string current, I_{R34} must be chosen to be 20 times greater than the PGTH leakage current expected.

From the device electrical specifications, PGTH leakage current is 1 μ A (maximum), $V_{PGTH(R)} = 1.2$ V and from design requirements, $V_{PG} = 4.5$ V. To solve the equation, first choose the value of $R3 = 100$ k Ω and calculate $R4 = 36.4$ k Ω . Choose nearest 1% standard resistor value as $R4 = 36.5$ k Ω .

9.3.3.5 Setting Overcurrent Threshold (I_{LIM})

The overcurrent protection (Current limit) threshold can be set using the R_{ILM} resistor whose value can be calculated as:

$$R_{ILM} (\Omega) = \frac{3334}{I_{LIM} (A)} = \frac{3334}{3.5 A} = 952.57 \Omega \quad (13)$$

Choose nearest 1% standard resistor value as 953 Ω .

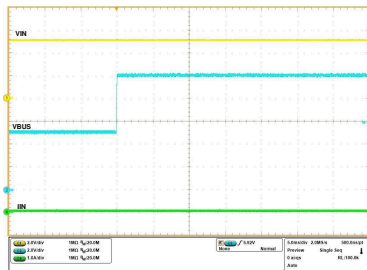
9.3.3.6 Setting Overcurrent Blanking Interval (t_{TIMER})

The overcurrent blanking timer interval can be set using the C_{TIMER} capacitor whose value can be calculated as:

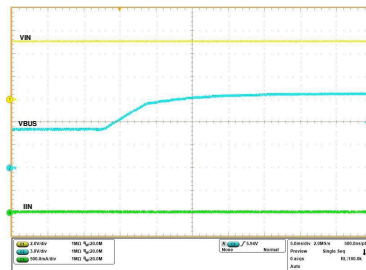
$$C_{TIMER} (nF) = \frac{t_{TIMER} (ms) \times I_{TIMER} (\mu A)}{\Delta V_{TIMER} (V)} = \frac{2 \times 1.8}{1.5} = 2.4 nF \quad (14)$$

Choose nearest standard capacitor value as 2.2 nF.

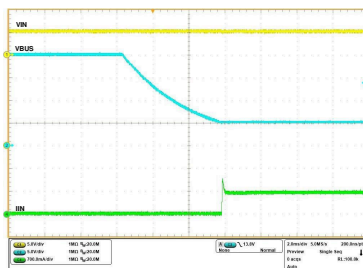
9.3.4 Application Curves



9-5. VBUS 20-V Hot-Plug



9-6. VBUS 20-V Slow Ramp Up



$V_{IN} = 5\text{ V}$, $C_{OUT} = 10\text{ }\mu\text{F}$, $R_{OUT} = 8\text{ }\Omega$, $V_{BUS} = 20\text{ V}$ initially and then disconnected

9-7. Fast Role Swap

10 Power Supply Recommendations

The TPS2521xx devices are designed for a supply voltage range of $2.7\text{ V} \leq V_{\text{IN}} \leq 5.7\text{ V}$. TI recommends an input ceramic bypass capacitor higher than $0.1\text{ }\mu\text{F}$ if the input supply is located more than a few inches from the device. The power supply must be rated higher than the set current limit to avoid voltage droops during overcurrent and short-circuit conditions.

The lowest negative voltage the device can handle at the input is limited to -15 V or $V_{\text{OUT}} - 21\text{ V}$, whichever is higher. Any low voltage signals (for example, EN/UVLO, PGTH) derived from the input supply must have a sufficiently large pullup resistor to limit the current through those pins to $< 10\text{ }\mu\text{A}$ during reverse polarity conditions. Please refer to [Absolute Maximum Ratings](#) table for more details.

10.1 Transient Protection

In the case of a short-circuit and overload current limit when the device interrupts current flow, the input inductance generates a positive voltage spike on the input, and the output inductance generates a negative voltage spike on the output. The peak amplitude of voltage spikes (transients) is dependent on the value of inductance in series to the input or output of the device. Such transients can exceed the absolute maximum ratings of the device if steps are not taken to address the issue. Typical methods for addressing transients include:

- Minimize lead length and inductance into and out of the device.
- Use a large PCB GND plane.
- Use a Schottky diode across the output to absorb negative spikes.
- Connect a low ESR capacitor of value greater than $1\text{ }\mu\text{F}$ at the OUT pin very close to the device.
- Use a low-value ceramic capacitor $C_{\text{IN}} = 1\text{ }\mu\text{F}$ to absorb the energy and dampen the transients. The capacitor voltage rating must be at least twice the input supply voltage to be able to withstand the positive voltage excursion during inductive ringing.

The approximate value of input capacitance can be estimated with 式 15:

$$V_{\text{SPIKE (Absolute)}} = V_{\text{IN}} + I_{\text{LOAD}} \times \sqrt{\frac{L_{\text{IN}}}{C_{\text{IN}}}} \quad (15)$$

where

- V_{IN} is the nominal supply voltage.
- I_{LOAD} is the load current.
- L_{IN} equals the effective inductance seen looking into the source.
- C_{IN} is the capacitance present at the input.

Some applications can require the addition of a Transient Voltage Suppressor (TVS) to prevent transients from exceeding the absolute maximum ratings of the device. In some cases, even if the maximum amplitude of the transients is below the absolute maximum rating of the device, a TVS can help to absorb the excessive energy dump and prevent it from creating very fast transient voltages on the input supply pin of the IC, which can couple to the internal control circuits and cause unexpected behavior.

Note

If there is a likelihood of input reverse polarity in the system, TI recommends to use a bi-directional TVS, or a reverse blocking diode in series with the TVS.

For applications such as USB-C ports where a powered cable can be plugged to the output of the device, there can be excess voltage stress from OUT to IN which exceeds the absolute maximum rating of the device. TI recommends to add a TVS diode from OUT to IN to clamp the voltage to a safe level.

The circuit implementation with optional protection components is shown in [Figure 10-1](#).

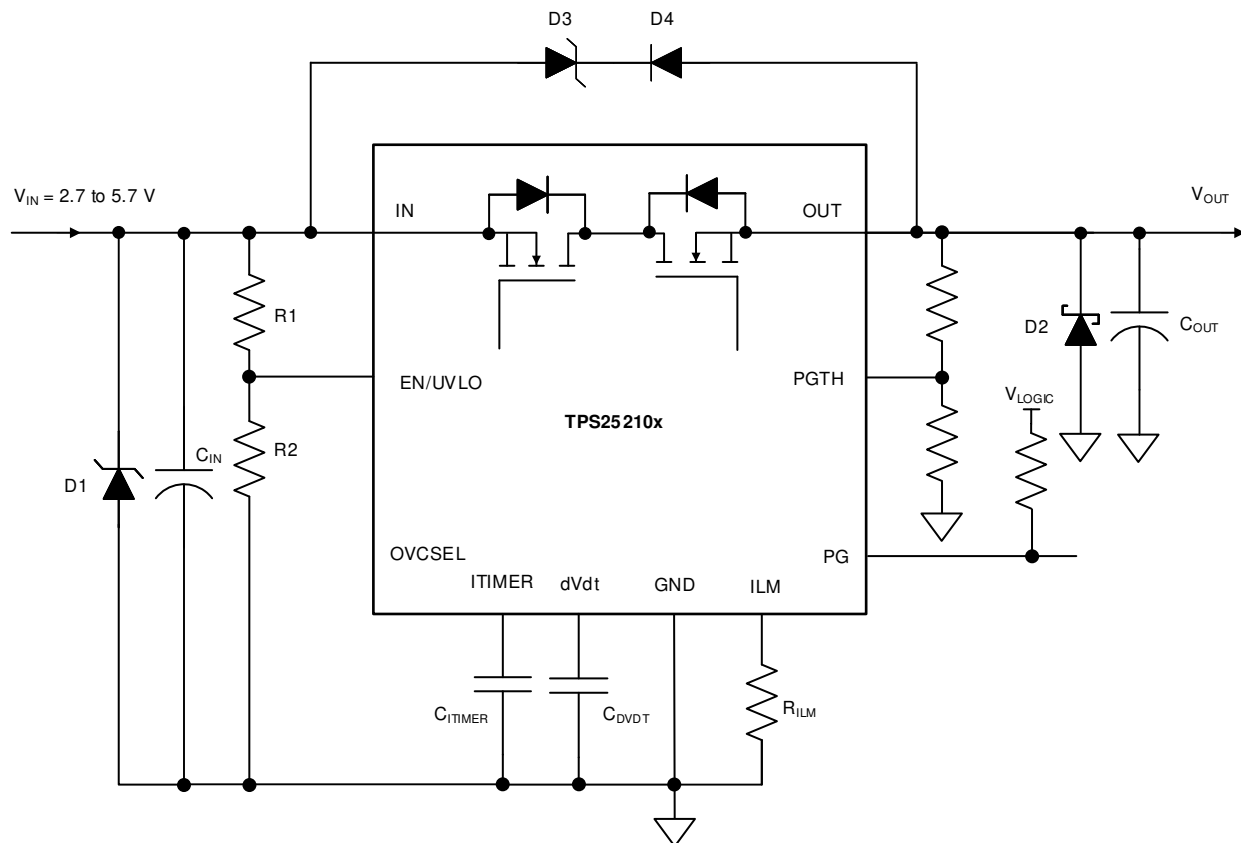


FIG 10-1. Circuit Implementation with Optional Protection Components

10.2 Output Short-Circuit Measurements

Obtain repeatable and similar short-circuit testing results is difficult. The following contribute to variation in results:

- Source bypassing
- Input leads
- Circuit layout
- Component selection
- Output shorting method
- Relative location of the short
- Instrumentation

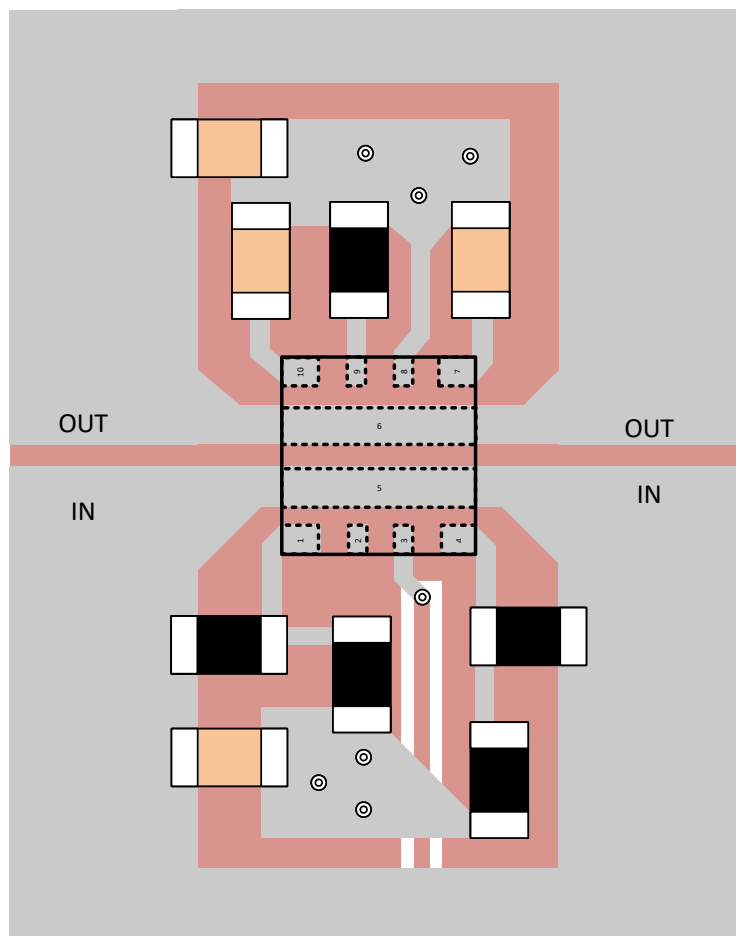
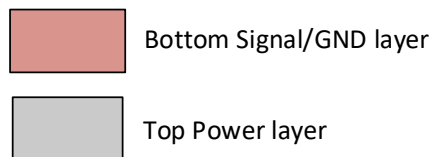
The actual short exhibits a certain degree of randomness because it microscopically bounces and arcs. Ensure that configuration and methods are used to obtain realistic results. Do not expect to see waveforms exactly like those in this data sheet because every setup is different.

11 Layout

11.1 Layout Guidelines

- For all applications, TI recommends a ceramic decoupling capacitor of 0.1 μF or greater between the IN terminal and GND terminal.
- The optimal placement of the decoupling capacitor is closest to the IN and GND terminals of the device. Care must be taken to minimize the loop area formed by the bypass-capacitor connection, the IN terminal, and the GND terminal of the IC.
- High current-carrying power-path connections must be as short as possible and must be sized to carry at least twice the full-load current.
- The GND terminal must be tied to the PCB ground plane at the terminal of the IC with the shortest possible trace. The PCB ground must be a copper plane or island on the board. It's recommended to have a separate ground plane island for the eFuse. This plane doesn't carry any high currents and serves as a quiet ground reference for all the critical analog signals of the eFuse. The device ground plane should be connected to the system power ground plane using a star connection.
- The IN and OUT pins are used for heat dissipation. Connect to as much copper area on top and bottom PCB layers using as possible. Adding thermal vias on the under the device further helps to minimize the voltage gradient across the IN and OUT pads and distribute current uniformly through the device, which improves the on-resistance and current sense accuracy.
- Locate the following support components close to their connection pins:
 - R_{ILM}
 - C_{dVdT}
 - C_{ITIMER}
 - Resistors for the EN/UVLO, OVCSEL and PGTH pins
- Connect the other end of the component to the GND pin of the device with shortest trace length. The trace routing for the R_{ILM} , C_{ITIMER} and C_{dVdT} components to the device must be as short as possible to reduce parasitic effects on the current limit, overcurrent blanking interval and soft start timing. TI recommends to keep parasitic capacitance on ILM pin below 50 pF to ensure stable operation. These traces must not have any coupling to switching signals on the board.
- Because the bias current on ILM pin directly controls the overcurrent protection behavior of the device, the PCB routing of this node must be kept away from any noisy (switching) signals.
- Protection devices such as TVS, snubbers, capacitors, or diodes must be placed physically close to the device they are intended to protect. These protection devices must be routed with short traces to reduce inductance. For example, a protection Schottky diode is recommended to address negative transients due to switching of inductive loads. TI also recommends to add a ceramic decoupling capacitor of 1 μF or greater between OUT and GND. These components must be physically close to the OUT pins. Care must be taken to minimize the loop area formed by the Schottky diode/bypass-capacitor connection, the OUT pin and the GND terminal of the IC.

11.2 Layout Example



11-1. Layout Example

12 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

12.1 Documentation Support

12.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [TPS25210EVM eFuse Evaluation Board user's guide](#)
- Texas Instruments, [TPS2521x Design Calculator](#)
- Texas Instruments, [Fast Role Swap, Linear ORing with TPS25947 and LM73100 in USB Type-C systems application brief](#)
- Texas Instruments, [eFuses in Smart Electricity Meters application brief](#)

12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.3 サポート・リソース

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12.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

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12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.6 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS25210ARPWR	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AJH
TPS25210ARPWR.A	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AJH
TPS25210ARPWR.B	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AJH
TPS25210LRPWR	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AIH
TPS25210LRPWR.A	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AIH
TPS25210LRPWR.B	Active	Production	VQFN-HR (RPW) 10	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 125	2AIH

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

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TAPE AND REEL INFORMATION



*All dimensions are nominal

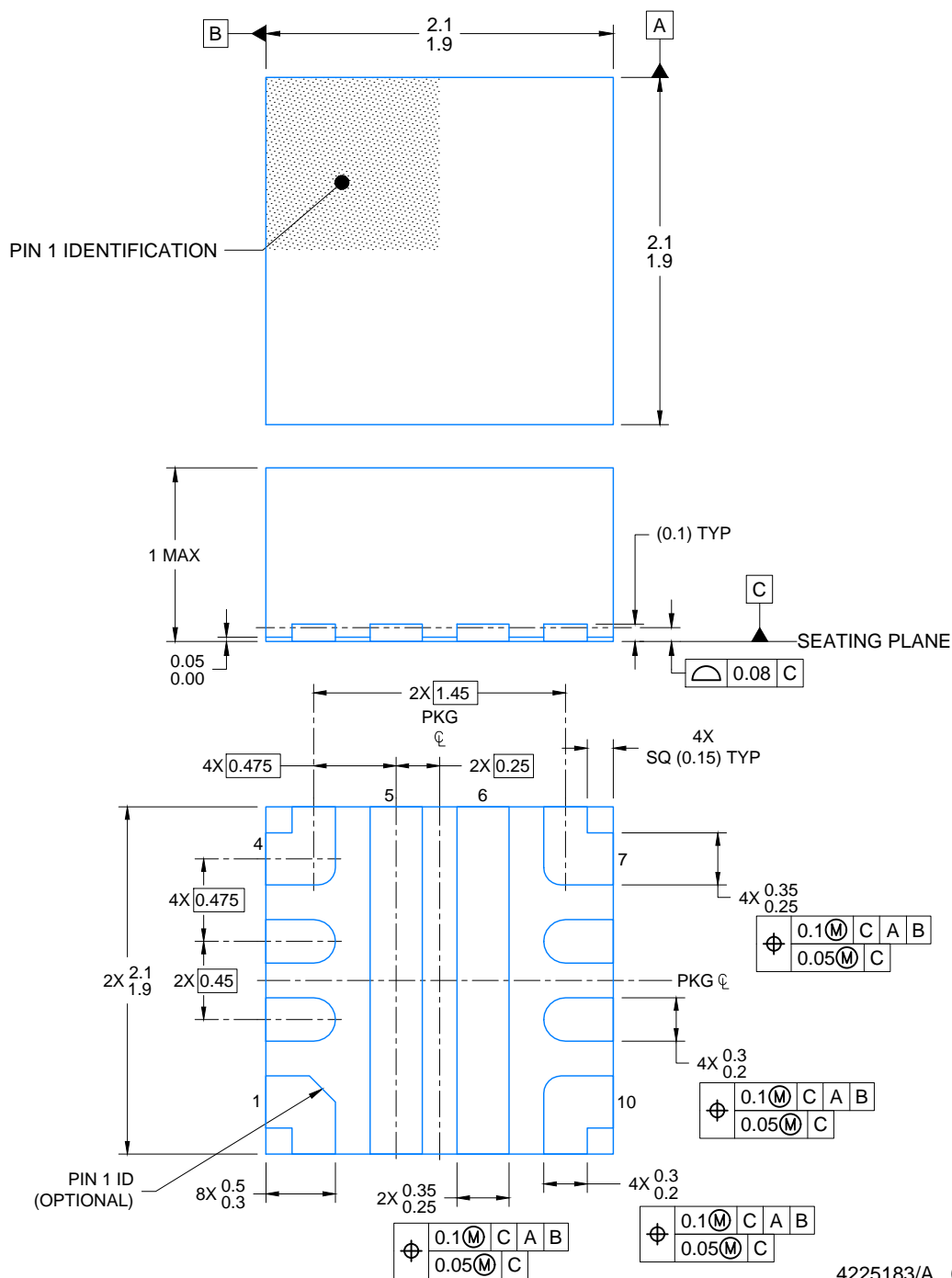
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS25210ARPWR	VQFN-HR	RPW	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
TPS25210LRPWR	VQFN-HR	RPW	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

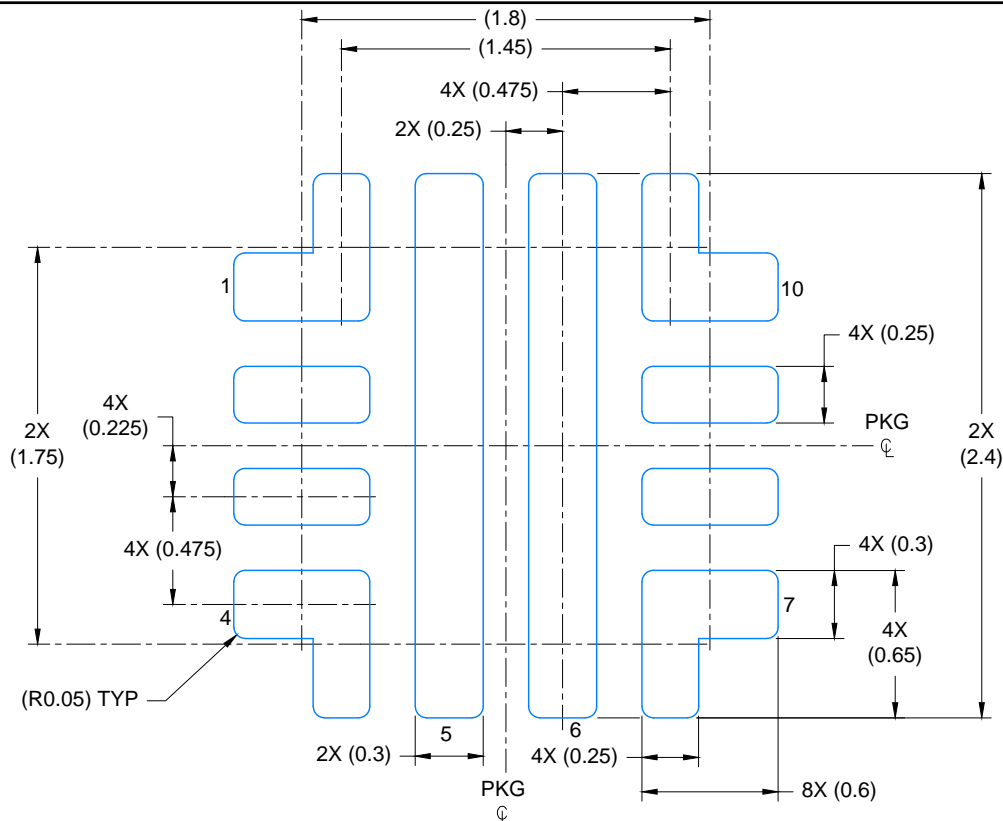
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS25210ARPWR	VQFN-HR	RPW	10	3000	210.0	185.0	35.0
TPS25210LRPWR	VQFN-HR	RPW	10	3000	210.0	185.0	35.0



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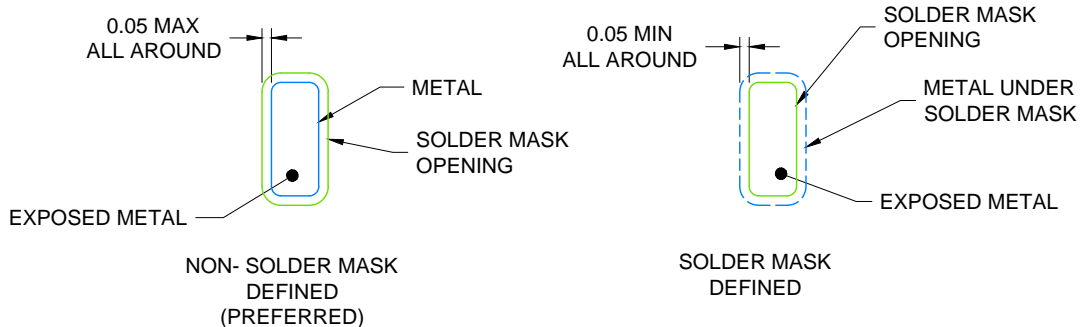
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.



LAND PATTERN EXAMPLE

SCALE: 30X



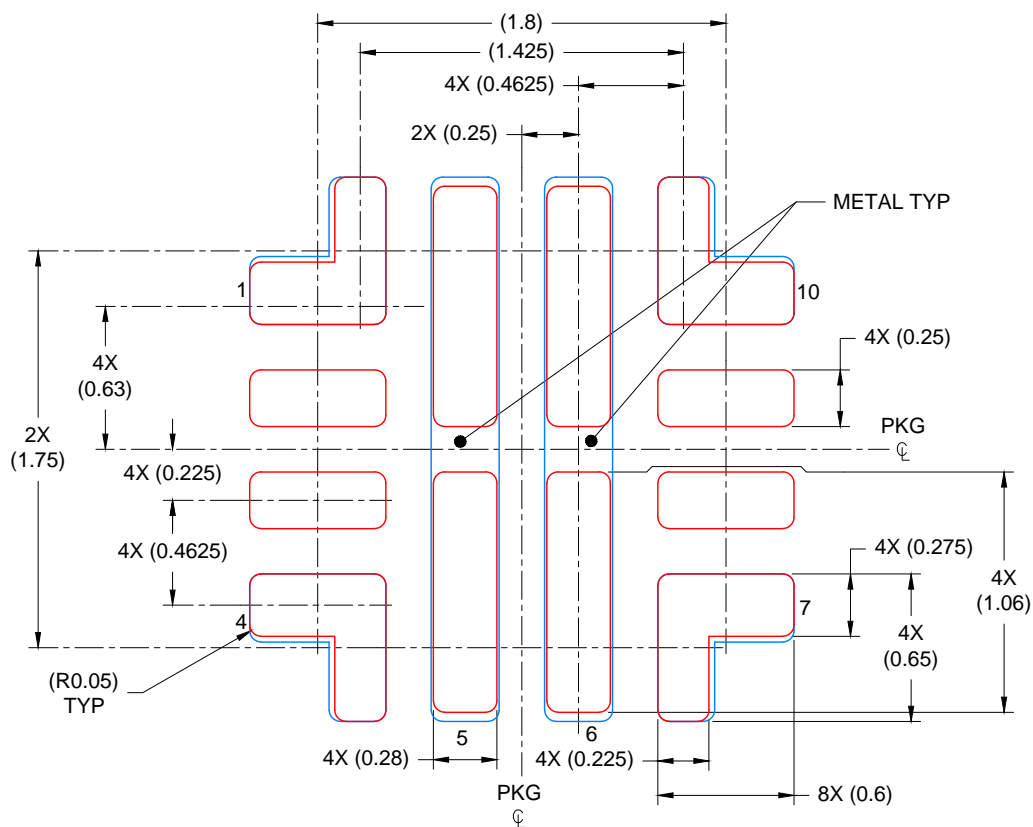
SOLDER MASK DETAILS

NOT TO SCALE

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NOTES: (continued)

- For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
- Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.100 mm THICK STENCIL

PADS 1, 4, 7 & 10: 93%; PADS 5 & 6: 82%
SCALE: 30X

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NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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最終更新日：2025 年 10 月