

**GC5016 Application Note:**  
**Digital Up Converter Mode Gain Settings**  
March 23, 2004

**Setting the GC5016's gain in the DUC mode**

The objective in the DUC mode is to set the gain variables to prevent overflow in the PFIR and CIC and then to adjust G and *sum\_shift* to achieve the user's desired overall gain. The cmd5016 program calculates the optimal gain settings based on the user's desired overall gain. The desired overall gain is set using the keyword *overall\_gain*.

Note that the gain in the up convert mode is almost always an attenuation. Full scale input data needs to be attenuated in the PFIR to prevent overflow at the PFIR's output. This is because the PFIR filter taps can create peaks in the interpolated data. Attenuation also needs to be added to prevent overflow in the sum of multiple channels. Gain should only be added if the input data is too small. For example, gain may be added if the user mistakenly connected 12 bit input data into the LSBs of the 16 bit GC5016 input ports and sign extended, rather than connecting them into the MSBs.

Gain through the DUC is usually set to optimize the crest factor of the output data. The crest factor is the ratio of the maximum output amplitude to the RMS signal level. For example, a 12 dB crest factor for a 16 bit output word would mean that the maximum "peak" in the data is 32767, and the RMS level is one-fourth that, or 8192.

The user sets the overall gain using the key word *overall\_gain*. The user sets the overall gain to achieve the desired output crest factor. If the input data has a crest factor of 9 dB, and the desired output crest factor is 14 dB, then the overall gain would be set to -5dB (*overall\_gain* = 0.56).

The user must set the overall gain on a per channel basis. If two channels are being added together, then the per-channel gain should be lowered by 3 dB to give the desired output crest factor. If four channels are added together, then the per-channel gain needs to be lowered by 6 dB.

For example, if the input crest factor is 9dB, and the desired output crest factor is 14dB, then overall gain should be -5dB (*overall\_gain*=0.56). If two channels are being added together, then each channel should have an overall gain of -8dB (*overall\_gain* = 0.398). If four channels are being added together, then each channel should have an overall gain of -11dB (*overall\_gain* = 0.28).

**How CMD5016 Calculates the Gain settings**

Definitions:

NOTE: All variables in italics are key words for the cmd5016 program

*overall\_gain*: User's desired overall gain for each channel.

G: 19 bit unsigned front end gain word, manually set using *gain*, *gain\_lsb* or *gain\_msb*

*gain*: Keyword for the front end gain,  $gain = G/4096 = (gain\_msb * 2^{16} + gain\_lsb) / 4096$

*gain\_msb*: 3 MSBs of G

*gain\_lsb*: 16 LSBs of G

*fir\_int*: Interpolation in the PFIR

*fir\_shift*: Gain adjustment at the output of the PFIR.

*cic\_int*: Interpolation in the CIC

*cic\_xmt\_5stg*: Keyword to set the CIC into the 5stage rather than the standard 6 stage mode.

*cic\_shift*: Gain adjustment in the CIC

*sum\_shift*: Gain adjustment in the sum tree

*tout\_nsig*: Keyword to specify the number of outputs the DUCs are summed into

*tout\_sumin*: Keyword to specify if the sumIO mode is being used

*tout\_res*: Keyword to specify the 22 bit output mode

MAX\_P FIR\_MAG\_SUM: Calculated from the PFIR taps to give the peak gain in the PFIR  
 FIR\_PEAK\_GAIN: The peak gain in the PFIR after *fir\_shift* is applied  
 PFIR\_SUM: Calculated from the PFIR taps to give the RMS gain through the PFIR  
 FIR\_GAIN: The RMS gain through the PFIR after *fir\_shift* is applied  
 CIC\_GAIN: The RMS gain through the CIC after *cic\_shift* is applied  
 SUM\_GAIN: The RMS gain through the sum tree after *sum\_shift* is applied  
 OVERALL\_GAIN: The overall gain in the chip (should be equal to *overall\_gain*)

The DUC gain is set by cmd5016 using the following algorithm:

- 1) Set G and *fir\_shift* to prevent clipping in the PFIR.
  - a. Divide the PFIR filter taps into the "*fir\_int*" sets of interpolation phases.
  - b. Sum the magnitude of the taps in each interpolation phase. The largest sum of magnitude is the MAX\_P FIR\_MAG\_SUM.
  - c. Set *fir\_shift* so that  $FIR\_PEAK\_GAIN = (MAX\_PFIR\_MAG\_SUM)/(2^{(21-fir\_shift)})$  is between 1 and 2.
  - d. Set G so that  $1.0 = (G/4096)*FIR\_PEAK\_GAIN$ , i.e.,  $G = 4096/FIR\_PEAK\_GAIN$
  - e. Calculate the sum of the PFIR taps (PFIR\_SUM)
  - f. Calculate  $GAIN=(G/4096)$
  - g. Calculate  $FIR\_GAIN=(PFIR\_SUM)/(fir\_int*2^{(21-fir\_shift)})$

Note: G will be between 2048 and 4096 if these are set properly.
- 2) Set *cic\_shift* to prevent overflow in the CIC.
  - a. Set *cic\_shift* so that  $CIC\_GAIN=(N^{(5-cic\_xmt\_5stg)})(2^{(cic\_shift-41)})$  is between 0.5 and 1.0.
- 3) Set *sum\_shift* to get OVERALL\_GAIN to be between *overall\_gain* and *overall\_gain\*2.0*
  - a. In the 22 bit sumIO mode (*tout\_nsig*=1, *tout\_sumin*=1, *tout\_res*=1), use  $SUM\_GAIN=2^{(sum\_Shift-6)}$
  - b. In all other modes use  $SUM\_GAIN=2^{(sum\_Shift-3)}$
  - c. In the four output mode (*tout\_nsig*=4), use  $SUM\_GAIN=1.0$  and *sum\_shift*=3.
  - d. Calculate  $OVERALL\_GAIN = GAIN*FIR\_GAIN*CIC\_GAIN*SUM\_GAIN$  and adjust *sum\_shift* so OVERALL\_GAIN is between *overall\_gain* and  $2*overall\_gain$ .
- 4) Adjust G to make  $OVERALL\_GAIN = overall\_gain$ 
  - a. Set  $G = G*overall\_gain/OVERALL\_GAIN$
  - b. While ( $G < 2048$ , and *fir\_shift*>0), set  $G=G*2$ , and set *fir\_shift* = *fir\_shift*-1.
  - c. Calculate *gain\_lsb* and *gain\_msb* from G.
- 5) Recalculate GAIN, FIR\_GAIN, FIR\_PEAK\_GAIN, CIC\_GAIN, SUM\_GAIN and OVERALL\_GAIN. Cmd5016 should report them to the analysis file.

## IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

<b>Products</b>		<b>Applications</b>	
Amplifiers	<a href="http://amplifier.ti.com">amplifier.ti.com</a>	Audio	<a href="http://www.ti.com/audio">www.ti.com/audio</a>
Data Converters	<a href="http://dataconverter.ti.com">dataconverter.ti.com</a>	Automotive	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Military	<a href="http://www.ti.com/military">www.ti.com/military</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Optical Networking	<a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
		Telephony	<a href="http://www.ti.com/telephony">www.ti.com/telephony</a>
		Video & Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>
		Wireless	<a href="http://www.ti.com/wireless">www.ti.com/wireless</a>

Mailing Address: Texas Instruments  
Post Office Box 655303 Dallas, Texas 75265