An All-Digital Automatic Gain Control

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An All-Digital Automatic Gain Control

Abstract

This report describes an all-digital implementation of an AGC on a TMS320C17 DSP. The AGC is designed specifically for modem applications.

- ☐ The first section provides an overview of modem receiver structure and implementation.
- ☐ The second section discusses the AGC block diagram and the motivation for using an AGC in a modem receiver.
- ☐ The third section covers the AGC hardware and software implementation aspects on a TMS320C17 DSP.
- □ Appendix A provides QAM Signal Energy data.
- □ Appendix B gives an overview on Fractional Number Representation.



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One of the basic structural blocks of a modem receiver is the Automatic Gain Control (AGC). The AGC is an adaptive system that operates over a wide dynamic range while maintaining the output signal at a constant level. This is necessary for the proper operation of the carrier recovery and clock recovery algorithms of the modem receiver.

This application report describes an all-digital implementation of an AGC on a TMS320C17 Digital Signal Processor (DSP). The AGC is designed specifically for modern applications. The structure of this application report is as follows:

- The first section provides an overview of modern receiver structure and implementation.
- Section two discusses the AGC block diagram and the motivation for using an AGC in a modern receiver.
- The last section covers the AGC hardware and software implementation aspects on a TMS320C17 DSP.

Introduction

A modem (MOdulator/DEModulator) is a device that modulates baseband signals at the transmitter and demodulates the received data at the receiver. To achieve full-duplex operation, frequency division multiplexing is employed, in which both modems simultaneously transmit and receive information over a single channel by dividing the telephone bandwidth into separate frequency bands: one for transmit with a carrier frequency of 1200 Hz and one for receive with a carrier frequency of 2400 Hz. A modem receiver consists of several functional blocks, which include answer/originate bandpass filters, AGC, demodulator, adaptive equalizer, clock recovery, carrier recovery, decision block, decoder, and descrambler.

In this report, we are concerned with the implementation of a DSP-based AGC for a V.22 bis modem product[1]. One of the basic structural blocks of a modem receiver is the AGC. The AGC is an adaptive system that operates over a wide dynamic range while maintaining the output signal at a constant level. The AGC is needed because several modules within the receiver use amplitude thresholds to make their decisions. These threshold levels must remain constant over the entire dynamic range of input signals, typically from –9 dbm to –43 dBm[2]. This is achieved through use of a software AGC, which multiplies the input signal with a gain factor, depending on the actual received signal level.

Modem Transmitter

The CCITT V.22 bis standard is a 2400-bps modern that uses Quadrature Amplitude Modulation (QAM) technique to transmit and receive data through the communications channel. This section presents an overview of QAM systems and the equations governing their operations.

In Quadrature Amplitude Modulation, the information is encoded as phase changes of the transmitted carrier and amplitude variations. With R denoting the amplitude and ϕ the phase change, the transmitted signal s(n) is mathematically represented as

where ω_c is the carrier frequency. Simplifying (1) and substituting $I_n = R \cos(\phi)$ and $Q_n = -R \sin(\phi)$ into it results in (2); this is used to describe QAM modulation systems.

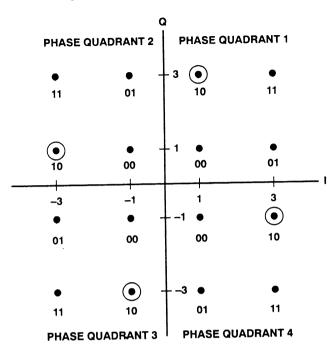
$$s(n) = I_n \cos(\omega_n) + Q_n \sin(\omega_n)$$
 (2)

Transmission of a baseband sequence $\{In,Qn\}$ is called *quadrature* transmission, with two carriers in phase quadrature to one another ($\cos \omega_c t$ and $\sin \omega_c t$) transmitted simultaneously over the same communications channel. Figure 1 shows a two-dimensional diagram of the signals of form (2) with the horizontal axis corresponding to the *in-phase* signal (I_n) and the vertical axis representing the *quadrature* signal (Q_n). These signal points are referred to as a 16-symbol QAM-signal constellation.

Each value of the $\{I_n,Q_n\}$ corresponds to one signaling element transmitted. The number of signaling elements per second is referred to as the baud rate. The *baud rate* is set by the CCITT V.22 bis recommendation to 600. By encoding four incoming bits (*quadbits*) in a single baud, transmission of 2400 bps is accomplished.

The encoding of the incoming data stream $d_s(n)$ into values of the sequence $\{I_n,Q_n\}$ is accomplished by the encoder. The encoder maps the first two bits of a quadbit as a phase quadrant change relative to the quadrant occupied by the preceding signal element. The last two bits of the quadbit define one of four signaling elements associated with the new quadrant[3].

Figure 1. V.22 bis Signal Constellation

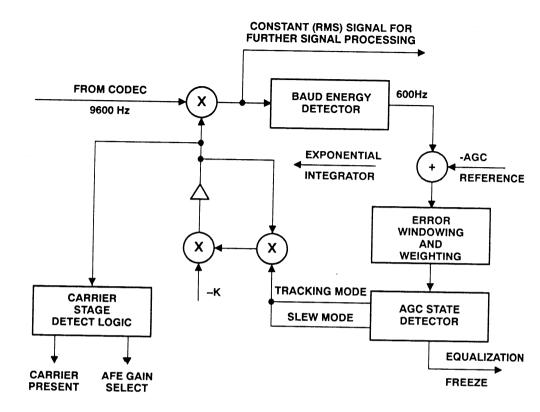


The AGC Algorithm

The AGC circuit is a closed-loop regulating system that maintains the output level of an amplifier at a constant level, even though the input signal may vary substantially. The AGC modeling and design techniques based on linear system design have been studied in detail[4]. The global stability of AGC loops assures the designer that the overall loop will stay stable under considerable weaker conditions if the proper design rules are followed[5].

Figure 2 is a block diagram of the modem automatic gain control. The AGC algorithm is partitioned into tasks performed once per sampling interval, and tasks performed once per baud interval. The sampling rate for the overall system is the designer's choice as long as it satisfies the Nyquist's criterion. A widely used sampling rate for the communications channel is 8 kHz. In the system in Figure 2, the sampling rate is chosen to be an integer multiple of the baud rate. Therefore, a sampling rate of 9.6 kHz is selected. This value is divisible by the master crystal frequency of 18.432 MHz.

Figure 2. Modem AGC Block Diagram



Baud Energy Detector

In Figure 2, every incoming linearized PCM sample is multiplied by the AGC gain factor. The result is available to the modem reciever for further signal processing. It is also used to update the baud energy detector. The energy of a baud interval is computed according to

$$E = \sum x_n^2 \tag{3}$$

where x_n represents the incoming samples. The accumulated band energy is then compared against a reference level, which depends on the modulation scheme. This comparison is necessary to compute the AGC loop error signal. It is this error that the AGC is trying to minimize.

The QAM transmitted signal shown in (2) can be rewritten, taking waveform shaping into account as follows

$$s(t) = \sum_{n} I_{n} g(t-nT) \cos \omega_{c} t + \sum_{n} Q_{n} g(t-nT) \sin \omega_{c} t$$
 (4)

where $\omega_c = 2\pi f_c$, where $f_c =$ carrier frequency g(t) = shaping waveform T = sampling interval $I_n, Q_n =$ data symbols

AGC Reference Energy

The signal energy for a particular constellation point (I_n,Q_n) is given by (see Appendix A)

$$E_n = 1/2 (I_n^2 + Q_n^2) ag{5}$$

The energy reference level is chosen to be

$$E_{ref} = E \left\{ E_n \right\} \tag{6}$$

where E{} denotes the expectation operation. The V.22 bis modem standard requires the transmitter to scramble the incoming digital sequence from the DTE and descramble the decoded data in the receiver[2,3]. The use of scrambler in the modem transmitter effectively randomizes the data and avoids data-dependent patterns in the transmitted sequence. This allows the constellation point sequences to be modeled as a random sequence, with each point having an equal probability of occurrence of $E\{(I_n, Q_n)\} = 1/N$. Therefore, (6) can be written as

$$E_{ref} = \sum_{n=1}^{N} 1/N (E_n)$$
 (7)

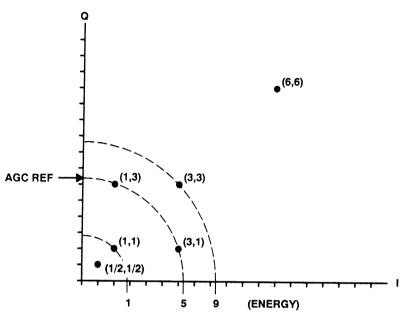
Figure 3 shows a portion of the signal constellation diagram of a V.22 bis modem.

Applying (7) to all 16 constellation points results in

$$E_{ref} = \frac{1}{16} \left\{ 4 \left[\left(1^2 + 3^2 \right) + \frac{1}{2} \left(1^2 + 1^2 \right) + \frac{1}{2} \left(3^2 + 3^2 \right) \right] \right\}$$

= $\frac{1}{16} \left\{ 4 \left[\left(10 \right) + \left(1 \right) + \left(9 \right) \right] \right\}$
= 5

Figure 3. Signal Energy Constellation Diagram



In Figure 3, constellation points (3,3) and (1,1) with respective energy contents of 9 and 1 lie outside the reference level of 5. A window function is then necessary so that the AGC does not treat these energy variations around the nominal energy as distortions induced by the communication channel.

Therefore, the AGC should apply corrections when the incoming signal level is outside the interval (1,9)(see Figure 3). Such implementation, however, neglects the effects of intersymbol interference (ISI). ISI arises in systems whenever pulses are transmitted in a band-limited channel. In such channels, pulses tend not to die out immediately, and the tail from one pulse interferes with the next pulse. ISI-related effects are more easily shown when constant amplitude modulation techniques, such as DPSK, are considered. In a DPSK modem receiver, the received signal exhibits gain variations, that are entirely due to ISI. Since the modem equalizer compensates for ISI, the AGC should not act upon ISI-related signal-level variations, because this would introduce noise into the modem receiver and degrade the overall performance.

The received signal r(t) at the input of the receiver is the convolution of the channel impulse response h(t) with the transmitted symbols x_i in

$$r(t) = \sum_{j} x_{j} h(t-jT) + \mu(t)$$
 (9)

where $\mu(t)$ is the additive white Gaussian noise. For the effects of ISI to be seen, the received signal must be sampled at the instant t_0+kT with t_0 incorporating the sampler phase and delay effects.

$$r(t_0 + kT) = x_k h(t_0) + \sum_{i=1}^{n} x_j h(t_0 + kT - jT) + \mu(t_0 + kt)$$
(10)

The first term of the right-hand side of (10) is the desired signal and is used to determine the transmitted symbol, while the middle term is ISI, which arises from the neighboring symbols [6]. With x_k , a constant amplitude sequence, the middle term in (10) results in received signal amplitude variations. Thus, the AGC design must incorporate an energy window around the energy reference level as defined by x_k 's.

DSP Implementation

Hardware

This section describes the hardware requirements of the modem. The modem hardware consists of the following functional blocks:

- 1) Host Interface
- 2) DSP
- 3) Controller
- 4) Controller-DSP Interface
- 5) Analog Front-End
 - Telephone Line Interface

For the purpose of understanding the operation of the Automatic Gain Control (AGC), the discussion is limited to only the analog front end.

Modem Analog Front End

The function of the analog front end (AFE) in the modem is to convert the analog signals received on the telephone line to digital data that can be processed by a digital signal processing device, in this case the TMS320C17. Depending on the modem standard that is implemented, the modem AFE could further assist the DSP by preventing as many of the unwanted signals as possible from being received by the DSP. This reduces the signal conditioning and preprocessing required by the DSP, which, in turn, reduces the computational requirement.

In the implementation described here, the modem AFE performs the bandpass filtering, a single-step gain stage, and the A/D-D/A conversions. Although the modem hardware also includes the two-to-four wire conversion and the proper telephone line interface and impedance matching, it will not be considered in this discussion.

Split-band Filtering

In Frequency Division Multiplexing (FDM) modems, the originating and answering stations use different carrier frequencies to transmit data[2]. For V.22 bis modems, the originating modem transmits data using a 1200-Hz carrier and receives signals from the remote modem at 2400 Hz. Since these signals are carried over the two-wire Public Switched Telephone Network (PSTN) for a full duplex communication, both signals are present in the telephone line simultaneously. For a modem to prevent its transmitted signal from interfering with its received signal, it must eliminate its own transmit signal at its receiver. Since the two modems use separate carrier frequencies to

transmit, this task becomes relatively easy. It is done by bandpass filtering the received signal with the passband filter being centered at the transmit carrier frequency of the remote modem.

This implementation uses a commercially available modem filter that has special modes to allow call-progress signal monitoring. This filter must provide adequate adjacent channel rejection while maintaining linear phase. The filter must operate over the entire dynamic range required by the modem, typically from 0 dBm to -43 dBm. For better Signal-to-Noise Ratio (SNR) and linear phase, it is desirable not to operate the filter and the Analog-to-Digital converter at very low signal levels. If signals are weak, an external gain stage (turned on/off under software control) in the receive signal path easily accomplishes this goal.

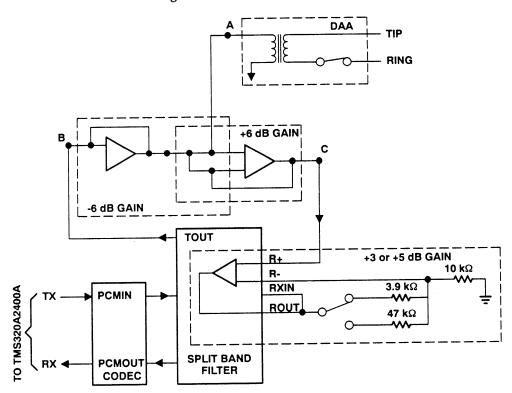
Hardware Gain Control

The hardware gain switch is implemented by changing the gain in the analog input buffer to the filter. When the average signal energy falls below -28 dBm, the DSP sets a status line to the modem controller. The controller, in turn, switches on a different resistor in the feedback circuit of the op-amp, increasing the gain by 12 dB. This switching is normally done only once during call initialization. However, if the connection starts with low-level signals and later the signals become stronger due to change in line impedance, the DSP resets this status line to the controller. The modem controller then turns off the external gain stage.

When the modem received signal is actually at the threshold level, it is possible that the external gain could frequently be turned on and off by slight changes in signal level. To prevent this, a 4-dB hysteresis has been established between external gain On and Off. This means the external gain will be turned On when the average signal level is less than -24 dBm and will be turned Off when the level is more than -28 dBm. Figure 4 shows the AFE schematic of the modem.

	LINE (dBm)	AFE GAIN (dB)	CODEC (dBm)
Rx level	-12	0	- 9
	-24	0	-21
	-25	12	-10
	-43	12	-28

Figure 4. Modem AFE Schematic



Codec Interface

The TMS320A2400A features hardware companding logic to interface directly to a μ -law codec[1]. The SCLK output provides the master clock frequency for the codec, and the FR provides the transmit and receive framing signal to the codec. Since the modem algorithm uses a 9.6-kHz sampling frequency, the codec must complete one A/D,D/A conversion at this rate.

The DSP serial port control register was programmed to provide an SCLK which is generated by dividing the DSP's input clock by ten. Thus, using an 18.432–MHz crystal as the DSP's clock input, a 1.8432-MHz SCLK was generated. The TCM29C19 uses an internal divide ratio of 192 to generate the 9.6-kHz sampling rate.

Software

The previous section provided a brief overview of the hardware design issues associated with the AGC for a V.22 bis modem. DSP implementation issues are the focus throughout the rest of this report. All values are represented in decimal format unless otherwise noted. Data values in a digital system are not integers, but they must be manipulated as such on an integer processor. Appendix B provides an overview of fractional number representation on a two's-complement fixed-point device.

We choose to represent the signal within the AGC loop in S4.11 format. Recall that the $\{I_n,Q_n\}$ sequence can assume any value from the sequence $\{\pm 1,\pm 3\}$. This means that the sequence is bound in the ± 3 range. We use three bits to represent the values in the given range, while the rest of the 12 bits can be treated as the fractional part that accommodates noise. Allocating an extra bit to the $\{I_n,Q_n\}$ sequence fully represents the RMS signal and allows for some gain hit.

For QAM signals, experimentation has shown that the ratio of peak signal to RMS signal is approximately 3 to 1. The maximum peak signal that can be represented using S4.11 notation is 16 (see Appendix B); therefore, 16 represents the peak value a QAM signal can attain using this notation. The RMS_{max} is hence 5.33, which corresponds to approximately 14.5 dB (20 log 5.33). We design the system to work with a 10-dB gain hit. It follows that the AGC should maintain the signal level at approximately 4.5 dB or 1.69 RMS level. The constant level of 1.69 RMS represented in S4.11 format is 3461.12. The AGC loop maintains an average squared level of 2.86, or (1.69)², per sample. Therefore, to determine the average baud energy, the sample energy must be multiplied by 16. The resultant value (45.8) is represented in S10.5 format (corresponding to 1466 (05BAh) in S15.0 format), the actual value used in the implementation (see Appendix E for the code listing).

As shown in the previous section, the reference energy for a V.22 bis modem is 5. This corresponds to the energy level of the constellation points (1,3) and (3,1), shown in Figure 3. Hence it is possible to map the average baud energy of 5 into 45.8. Extending the mapping to the other energy levels results in the following:

Average Baud Energy	S10.5 Format	S15.0 Format
1 maps into 5 maps into 9 maps into	9.16 45.8 82.4	292 1466 2632

Error Windowing and Weighting

In the previous section, the need was established for an energy window around the nominal baud energy level to compensate for the effects of intersymbol interference. The AGC is not designed to, and should not be expected to, compensate for ISI. The equalizer in the modem receiver is designed for this purpose [6]. Experimental window values of 1320 and 950 were chosen for QAM and DPSK modes of operation, respectively.

The windowed error signal must be weighted appropriately to provide an approximate one-to-one relationship between the positive and negative energy errors. In Figure 3, the disparity between the positive and negative errors can be observed. Assume that the received points are (6,6) and (0.5,0.5). The QAM signal energy can be calculated as

$$E_{OAM} = 1/2 \left(I_n^2 + Q_n^2 \right) \tag{11}$$

Therefore, the energy values of the received points are 36 and 0.25, respectively. When these energy values are represented in S10.5 (10552 and 73, respectively) and the deviation from the nominal energy level of 1466 is calculated, full scale error values of 9086 and –1393, respectively, are obtained. This indicates a nonlinear relationship between the received constellation points signal energy with respect to the nominal band energy level. It is important to determine the weighting

factor to provide a parity between positive and negative errors while the AGC operates in the steady state or tracking mode. Appendix D provides a Fortran program to determine the best value for the expansion ratio of negative and positive energy values.

AGC State Detector

The AGC always operates in one of two modes:

- Slew (fast tracking mode) AGC uses a large step size to track the signal.
- Tracking AGC adjusts the signal level by adjusting the gain factor via an exponential integrator loop.

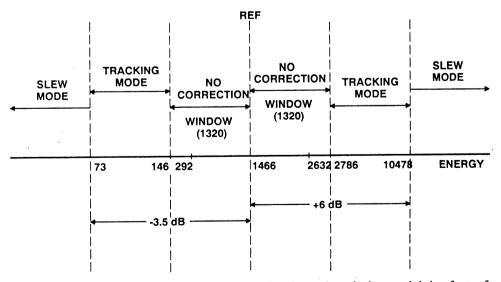
It is important to design the AGC to ignore relatively small gain changes on the telephone line. Otherwise, the AGC loop responds to the smallest variation in the signal level by switching to the slew mode. In this application, the AGC is designed to simply track the incoming signal when the received signal level varies by not more than \pm 6 dB from the window values. These levels are calculated as follows:

$$10\log(x/2632) = +6 \ dB \to x = 10478 \tag{12}$$

$$10\log(x/292) = -6 \ dB \to x = 73 \tag{13}$$

As long as the incoming signal stays within these boundaries, the AGC simply adjusts the gain factor; otherwise, it will switch to the slew mode. Once the AGC determines that the error signal is within the tracking mode boundary, it switches back to the slow tracking mode as shown in 5.

Figure 5. AGC Operating Modes



Appendix C provides a FORTRAN program that determines the best weighting factor for a given QAM signal range. A weighting factor of 2 provided the approximate one-to-one relation-

ship. Since DPSK signals do not have amplitude variations, a value of 1 was chosen for the weighting factor when the modem operates in the V.22/Bell 212A mode.

An upper and lower boundary for the AGC gain value must be determined. The V.22bis standard[3] requires the modem to operate at a signal level of -43 dBm. Therefore, the AGC is designed to work from the 0-dBm signal level to -50 dBm.

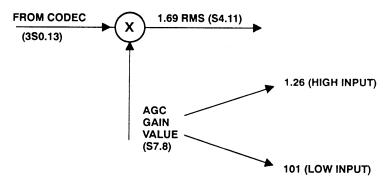
The DSP2400 contains a DSP-activated 12-dB gain switch. Therefore, our design should really have to cover only the range of 0 dBm to –38 dBm levels. The maximum codec output value is 1FFEh (8190 decimal) because the codec output is converted from 8-bit log value to 13-bit two's-complement value. When this value is saved in a data memory location of the TMS320C17 DSP, the number is sign-extended and is represented in 3S0.13 format. The RMS_{max} is therefore 2730, which corresponds to a signal level of 0 dBm in our system. The minimum acceptable signal level from the codec corresponding to the –38-dBm level is computed as follows:

$$-38 = 20 \log (RMS_{\min} / 2730)$$

$$RMS_{\min} = 34.4$$
(14)

Given the maximum and minimum codec output values and the constant RMS output, it follows that $\alpha_{min} = 1.26$ and $\alpha_{max} = 101$ as shown in Figure 6.

Figure 6. AGC Gain Value Computation



The gain value requires 7 bits to represent; therefore, the S7.8 format is used to represent the α values.

Exponential Integrator Loop

When the total baud energy stays within the window limits, the AGC is in the tracking mode and simply compensates for the changes in the signal levels by adjusting the gain factor appropriately. The gain factor is computed and updated via an exponential integrator loop. The exponential integrator loop implements the following function:

$$\alpha_{n+1} = \alpha_n \times (1 - Ke) \tag{15}$$

where the constant K determines the speed of convergence of the AGC closed loop. In our implementation, K is set to 1/2. This value corresponds to step sizes of \pm 6 dB when the AGC is in the

slew mode. The error signal is in S0.15 format while α_n is in S7.8 format with the multiplication result in 2S7.23 format. When the upper half of the accumulator (ACCH) is saved with a left shift, the result is in S7.8 format. A further multiplication by 0.5 is necessary before carrying out the subtraction operation. Note that a divide by 2 is equivalent to a right shift, which cancels out the effect of the previous left shift. Therefore, saving ACCH with no shift accomplishes multiplication by K as shown in Appendix E.

The AGC is designed to declare carrier present when signal levels greater than -43 dBm appear at the input of the receiver. The response time for tone detection depends on the AGC design. The AGC uses a constant that is subtracted from a hysteresis counter, and presence of energy is declared when the counter underflows. It takes 9 bauds for the energy to be detected, corresponding to a response time of 15 ms.

Conclusion

This application report has presented design and implementation techniques for an all-digital automatic gain control. The AGC has been implemented on a TMS320C17 digital signal processor as part of a commercial modem product (DSP2400). The approach of using a programmable processor resulted in minimal hardware configuration with excellent performance. The DSP implementation allows you to fine tune the AGC for your particular modem design, regardless of the modulation technique used.

Acknowledgements

The author wishes to acknowledge the contribution of Technekron Communications Systems and George Troullinos of Texas Instruments. This report is based on their work.

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Appendix A

QAM Signal Energy

The general form of a QAM signal is written as

$$s(t) = R(t) \cos \left[\omega_c t + \phi(t)\right]$$

$$= I_n \cos \omega_c t + Q_n \sin \omega_c t$$
(16)

The energy in a signal s(t) is defined as

$$E_{QAM} = \int_{-\infty}^{\infty} s^2 \left(t \right) dt \tag{17}$$

Substituting (16) into (17) results in

$$E_{QAM} = \int_{0}^{T} s^{2} (t) dt$$

$$= \frac{1}{2\pi} \int_{0}^{2\pi} (I_{n}^{2} \cos^{2}\omega_{c} t + Q_{n}^{2} \omega_{c} t + 2I_{n} Q_{n} \sin \omega_{c} t \cos \omega_{c} t) dt$$

$$= \frac{1}{2\pi} \int_{0}^{2\pi} 1/2 [I_{n}^{2} (1 + \cos 2\omega_{c} t)] dt + \frac{1}{2\pi} \int_{0}^{2\pi} 1/2 [Q_{n} 2^{2} (1 - \cos 2\omega_{c} t)]$$

$$+ \frac{1}{2\pi} \int_{0}^{2\pi} I_{n} Q_{n} \sin 2\omega_{c} t dt$$
(18)

When the three terms in (18) are integrated, the sine and cosine terms drop out since the average energy of sinusoidal signals is zero. Therefore, (18) simplifies to

$$E_{OAM} = 1/2 \left(I_n^2 + Q_n^2 \right) \tag{19}$$

Appendix B

Fractional Number Representation Overview

A typical digital communication system is shown in Figure 7. Two blocks (marked as waveform coder and waveform decoder) are of interest. These blocks are collectively referred to as a codec, especially when both coder and decoder are implemented on a single device. An example is the TCM29C13 PCM codec, which consists of an amplitude quantizer and binary codeword generator.

WAVEFORM x(t) **ANALOG** SAMPLER SOURCE CODER MODULATOR ANALOG CHANNEL DEMODULATOR $\hat{\mathbf{x}}(\mathbf{t})$ WAVEFORM **ANALOG** RECONSTRUCT **DECODER** OUTPUT

Figure 7. A Typical Communication Channel

The quantized data represent instantaneous values of a continuous-time signal in digital form. On the TMS320C17, these data values are represented in two's-complement arithmetic[7]. The binary representation of a two's-complement value is as follows:

$$A = a_0 + \sum_{i=1}^{15} a_i \ 2^{-i} \tag{20}$$

Consider that the incoming samples are coming from a 16-bit linear ADC. The data coming out of the ADC consist of a sign bit at the most significant location, followed by the binary point. This information can be represented in Q15 format or, alternately, S0.15 format. This translates into the following upperbound and lowerbound limits with increments of 2^{-15} (0.00003051):

$$(2^{15} - 1) / 2^{15} = 0.99996948$$

 $-2^{15} / 2^{15} = -1$ (21)

If two Q15 (S0.15) numbers are multiplied, the result is a number in Q30 (SS0.30) format. When the Q30 number resides in the 32-bit accumulator of the TMS320C17, the binary point fol-

lows the second most-significant bit. Assuming that the output of the encoder section is also Q15 format, the Q30 number must be adjusted by left-shifting by one while maintaining the most-significant 16 bits of the result. This is accomplished with a sach y,1. This instruction shifts the Q30 (SS0.30) number to the left by one and, following the shift, stores the upper 16 bits of the accumulator. The y value is in Q15 (S0.15) format.

The S notation is used consistently throughout this application report. The following table should assist you with the conversion between Q notations, S notations, and equivalent decimal representations.

Table 1. S Notation, Q Notation, and Decimal Conversion Information

Q Notation	S Notation	Decimal Equivalent
Q15	S0.15	-1 N≤ 0.9999695
Q14	S1.14	-2 N≤ 1.9999390
Q13	S2.13	-4 N≤ 3.9998779
Q12	S3.12	–8 N≤ 7.9997559
Q11	S4.11	-16 N≤ 15.9995117
Q10	S5.10	-32 N≤ 31.9990234
Q9	S6.9	-64 N≤ 63.9980469
Q8	S7.8	-128 N≤ 127.9960938
Q7	S8.7	-256 N≤ 255.9921875
Q6	S9.6	-512 N≤ 511.9804375
Q5	S10.5	-1024 N≤ 1023.96875
Q4	S11.4	-2048 N≤ 2047.9375
Q3	S12.3	-4096 N≤ 4096.875
Q2	S13.2	-8192 N≤ 8191.75
Q1	S14.1	-16384 N≤ 16383.5
Q0	S15.0	-32768 N≤ 32767

Appendix C

The following is a Fortran program listing that creates a table of AGC gain values and its relation to the input signal strength. The table also includes the corresponding peak input signal level and its RMS equivalent.

٠.	
ż	
Ξ	

```
Peak
4
                                                                                                                                                                                                                                                                                                                                                                                                         In this AGC design, the max coded input is actually +2.2 dBm (equivalent to 8190 peak.
                                                                                                                                                                                                                     - AMS is the AMS signal input to the receiver, where in a GAM system is edual to on third of the peak value.
                                        This crooram obsermances the Valves of obm Signal Tereis in a ONY system:
Double Precision Feat, FMS, Albha, com.
                                                                                                                                                - Peak is the beak signal input to the receiver side.
                                                                                                                                                                                                                                                                                                                                 - Alona is the gain value.
```

	open	(i.file = 'dom.dat', status = 'new')
	Write	(1,8)
00	for mat	(5x, dbm(,15x, seak',16x, rms',17x, alpha')
	wr 1 te	(1.9)
٥	100.00	(5x,' ===',15x,'====',16x,'===',17x,'====')
		dbm = -27.1
		199× = 5
8	, ,,	(dbm .gt. max) goto 1000
		dbm = dbm + 0.1
		Deak = 8190. * (10 ** ((dbm - max) / 20.))
		rms = peak / 3.
		alpha = 3461.12 / rms
	Wr 1 te	(1,10) dbm, peak, rms, alpha
9.	format	(f10,1,10x,f10,4,10x,f10,4,10x,f10,2)
	gote	566
1000	stop	
	end	

Al pha	成果乳头头或说话可以可以的现在分词 化二氯甲基甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲甲	2 8 8 8 8 8 8 8 8 8 8 8 8 8
Æ	95, 8841 97, 8857 97, 1203 100, 2881 101, 4291 102, 6036 103, 6036 104, 6735 106, 6833 109, 9417 111, 2047 111, 2047 111, 2047 111, 2047 111, 2047 111, 2047 112, 2047 113, 2047 113, 2047 113, 2047 113, 2047 114, 627 114, 627 114, 628 114, 628 115, 628 116, 639 117, 697 118, 628 118, 628 118	166.4036 168.304 170.2796 174.2439
Peak	200, 3922 300, 3842 300, 3842 301, 3013 314, 3073 314, 3073 318, 4239 318, 4	504.9913 504.9913 510.8388 516.7540 522.7378
4	2, 2, 2, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3,	2

994, 6545 328, 2182 996, 6563 322, 0188 1007, 5901 365, 8634 1019, 2574 399, 7225 1011, 0599 343, 6846 1042, 9990 347, 6463 1055, 0944 355, 7445	109., 278. 855.,745. 109., 278. 109., 278. 109., 279. 841. 109., 150. 349. 249. 110., 800. 349. 249. 110., 800. 349. 249. 110., 800. 349. 249. 110., 800. 349. 249. 110., 800. 349. 249. 110., 800. 349. 249. 110., 800. 349. 402. 349. 349. 349. 349. 349. 349. 349. 349	1288, 4996 427, 7230 1283, 1691 427, 7230 1283, 1691 427, 7230 1283, 2621 42, 7541 133, 6579 47, 68810 139, 2016 43, 6870 140, 2687 441, 4196 140, 7394 479, 9131 145, 4108 45, 4703	-12.9 1473.273 491.0918 7.05 -12.8 1490.3782 495.7783 6.59 -12.8 1575.0493 508.3498 6.51 -12.5 1575.0493 508.3498 6.51 -12.5 1575.0493 508.3498 6.51 -12.5 1595.708 5.45 -12.4 1505.723 500.1908 6.55 -12.2 1596.8723 500.1908 6.55 -12.2 1596.8723 500.1908 6.59 -12.2 1596.8723 500.1908 6.59 -12.2 1596.8723 500.3734 6.59 -12.2 1596.8723 500.3734 6.73 -11.9 1652.9423 535.3944 6.73 -11.1 1671.5463 535.3948 6.14 -11.1 1671.5463 535.3948 6.14 -11.1 1705.9909 583.6438 5.59 -11.4 1705.9909 583.6438 5.73 -11.1 1812.5248 6.4748 5.73
238,7908 176,2836 334,9139 178,3046 341,1079 180,3873 347,3736 182,4579 550,1236 186,7079 556,6079 188,869 373,770 191,685	193,0869 193,0869 195,5071 200,0811 201,7710 201,0917 201,4977 201,4873 211,9155 211,9155 211,9155 211,9155 211,925 214,727	681.2145 277.0715 687.1065 222.3007 687.0805 222.3007 705.1399 237.7731 721.579 20.5263 728.3807 248.7790 725.380 21.880 765.382 264.7784 775.1828 777.1828 767.1839 260.7130	771.176 800.2573 800.2573 800.2573 800.2573 800.2573 800.2578 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588 800.7588

-0.1 6431,0779 2143,4873 1.64 0.1 6260,8770 2143,4873 1.16 0.2 6457,0617 2219,0273 1.15 0.3 6457,1673 2249,7234 1.15 0.4 6412,1453 2270,7734 1.15 0.5 6412,1453 2270,7734 1.15 0.5 6412,1453 2270,7734 1.45 0.7 7051,3389 2250,5130 1.47 1.0 7279,3482 2250,5130 1.47 1.1 7279,3482 2452,2483,115 1.2 749,3482 2452,7882 1.33 1.4 744,3268 2277,7842 1.33 1.4 744,3268 2277,7842 1.33 1.5 7731,894 2267,7842 1.33 1.6 7731,894 2267,7842 1.33 1.7 7731,894 2267,7842 1.33 1.8 8003,3779 2267,7842 1.33 1.9 8003,3779 2267,7842 1.33 1.1 7831,894 2267,7842 1.33 1.2 7831,894 2267,7842 1.33 1.3 7831,894 2267,7842 1.33 1.4 741,854 2267,7842 1.33 1.5 7731,894 2267,7842 1.33 1.6 7731,894 2267,7842 1.33 1.7 7731,894 2267,7842 1.33 1.8 8003,779 2267,7867 1.33 2.0 8196,0000 2730,0000 1.27

Appendix D

Appendix D provides a Fortran program that calculates an optimal value for the expansion ratio of negative and positive energy values, subject to some constraints (maximum signal levels). The program searches expansion ratios with their corresponding error values up to a maximum value defined by the user. The value that produces the least error is chosen as the optimal value. In this implementation, the tracking mode window is 6 dB for positive errors and at least 3.5 dBs wide for negative errors. The program, however, calculates the expansion window in 6-dB range. Error values are calculated using no-worse windows data. The index value for positive and negative errors correspond to the actual signal level in tenths of dBs.

negicity, essert(GD), aspert(GD) 201 signat(GD), assert(GD), aspert(GD) 202 signat(GD), assert(SD), aspert(GD) 202 signation actor, ainer, binge er asxista value for N') er engative dhe level') er existive dhe level') er axxista value for N') er		88	negerr (k) = 292.#(1, - (10, ++ (float(-k) /100.))) write(1,9) k.negerr(k)
of positive ones. ingic(60), pascer(60) and ingic(60), pascer(60) and indic(1), pascer(60) and	ne the best value for the expansion ratio of negative	*	format (1x, 'negative error(',i2,') = ', 1x, £20.4)
injunction, paserrichol, insperrichol injunction, auxerr, ainerr, binge injunction, auxerr, ainerr, binge inition(', status = 'new') on on on on on on on on on o	that of positive ones.	U	
1.0 1.0	ion neg(60), poserr(60), negerr(60)	108	60 301 $K = 22,30,2$ 10 10 10 10 10 10 10 10 10 10 10 10 10 10
	tion signa (60), maxer, miner, bingo	100	write(1,9) k, negerr(k)
	ion total(400)	u	•
Uses C 100	e = 'ni.dat',status = 'new')	ş	do 302 k = 40,60,10
se to the boundary, more 501 503 503 503 504 504 504 505 506 507 508 508 509 509 509 509 509 509 509 509 509 509	clear all the total values	2305 C 305	meger (x) = 222.vt; = (10, vs (r)04(1-x) /100.))) write(1,9) k,neger(k)
er positive due level') er engative due level') er anximum value fer N') er anximum value fer	1,400	S S S	uming that the magning is actually linear, then the following criteria
er positive dum level') er anximum value fer N') er anximum value fer N') er aximum value fer N') ers is the tracting mode close to the boundary, more these regions. pps pps pps pps pps pps pps	٠٥.	c is	used to determine the optimum value for M.
er positive due level') er engative due level') er aximama value fer N') er aximama value fer N') er si the tracting mode close to the boundary, more these regions. 22. e ((10, ee (float(i) / 100.)) - 1.) 500 502 503 504 505 506 506 507 508 508 509 509 509 509 509 509		. .	
er negative dam level') eg er auximam value for N') ers ers ers ers ers ers ers er	'enter positive dbm level')	C tet	al(n) = Signa [e - e + n]
es en existes value for N') es en existes value for N') er existes value for N') ers in the tracting mode close to the boundary, more others regions. pts pts pts pts pts pts pts p	dbapos	J	* * *
for inspative one level 400 er auximum value for N'		u	**************************************
er axxista value for N') er axxista value for N') for axxista value for N') in the tracking mode close to the boundary, more these regions. 22. e ((10. ee (float(i) / 100.)) - 1.) 50. 50. 50. 50. 6(10. ee (float(i) / 100.)) - 1.) 50. 50. 50. 6(10. ee (float(i) / 100.)) - 1.) 50. 50. 6(10. ee (float(i) / 100.)) - 1.) 60. 60. 60. 60. 60. 60. 60. 60. 60. 60.	enter negative one level')		46 AM to 1 AM
ers axisma value for N() ers is the tracting mode close to the boundary, more these regions. \$25, + ((10, ee (float(i) / 100.)) - 1.) \$26, + ((10, ee (float(i) / 100.)) - 1.) \$37, + ((10, ee (float(i) / 100.)) - 1.) \$38, + ((10, ee (float(i) / 100.)) - 1.) \$39, + ((10,	Commen		ciona(k) = paserr(k) - flast(n) + nemerr(k)
these regions. pts pts pts pts pts pts pts p	'enter maximum value for N')	004	total(n) = total(n) + signa(k)
in the tracking mode close to the boundary, more to these regions. pts pts pts 22. * ((10. ** (float(i) / 100.)) - 1.) 0,2 22. * ((10. ** (float(i) / 100.)) - 1.) 500 502 502. * ((10. ** (float(i) / 100.)) - 1.) 500 503 603 600 ith the magative errors. 600		U	
pts	31414	∄	it is time to determine the minimum value of the error.
is the tracting mode close to the boundary, more o these regions. \$15 \$2. * ((10, ** (float(i) / 100.)) - 1.) \$2. * ((10, ** (float(i) / 100.)) - 1.) \$30 \$30 \$30 \$30 \$30 \$30 \$30 \$30 \$30 \$30			do 500 n = 1,nn
pts	wates in the tracking mode close to the boundary, more		<pre>if (bingo .lt. 0.) goto 504 if (tetal(a) .le. tetal(a+1) oute 50i</pre>
pts pts 22. + ((10. +* (float(i) / 100.)) - 1.) 1,poserr(i) 622. + ((10. +* (float(i) / 100.)) - 1.) 504 505 507 508 509 508 509 509 509 509 509	to these regions.		bingo = total(n+1)
501 502 503 503 504 505 505 506 507 507 508 508 508 508 508 508 508 508 508 508	10 pts		itr = n+1
22, + ((10, ee (float(i) / 100.)) - 1.) 29, + ((10, ee (float(i) / 100.)) - 1.) 504 505 507 508 508 509 509 50 + ((10, ee (float(i) / 100.)) - 1.) 509 509 509 509 509 509 600 600	10 pts	i	gete 502
502 503 509 509 509 509 509 509 509 509 509 509	ts	ŝ	binge # tetal(a)
22. * ((10, ** (float(i) / 100.)) - 1.) 503 503 503 503 503 503 503 503 503 503	3	S	If a H
22. + ((10. ee (float(i) / 100.)) - 1.) 504 1, paserr(i) 5.2 22. + ((10. ee (float(i) / 100.)) - 1.) 504 23. + ((10. ee (float(i) / 100.)) - 1.) 600 24. + ((10. ee (float(i) / 100.)) - 1.) 600 25. + ((10. ee (float(i) / 100.)) - 1.) 600 26. + ((10. ee (float(i) / 100.)) - 1.) 600 27. + ((10. ee (float(i) / 100.)) - 1.) 600 28. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) - 1.) 600 29. + ((10. ee (float(i) / 100.)) 600 20. + ((10. ee (float(i) / 100.))		7 6	Antimas of any geto DAS
(i) / 100.)) - 1.) 504 (i) / 100.)) - 1.) c Calcular 600 1) / 100.)) - 1.) 5 61 661	2	8	it = n
1) / 100.)) - 1,) 304 (i) / 100.)) - 1,) C Calcula 1) / 100.)) - 1,) C S	1,30		binge = total(n)
(i) / 100,)) - 1,) c Calcula 600 1) / 100,)) - 1,) 5	= 2632, + ((10, ++ (float(i) / 100,)) - 1,)	3	gete 510
(i) / 100,)) - 1,) c Calculai 600 (i) / 100,)) - 1,) 5	[1,3] 1,poserr(1)	ş	ist = n-1 bingo = total(n-1)
(i) / 100, i) - 1, ·)	2,39,2		
600 (1) / 100.)) - 1.) 5 601) = 2632, 4 ((10, 44 (fleat(i) / 100.)) - 1.)) i,poser(i)	<u>.</u>	CHIEFE BEXIDES AND BIRIDES CHEFS I CHEIS
198 9	22,30,2 = 26.22, + (f 10, ++ (fleat(i) / 100,)) - 1,)	99 s	<pre>de 600 i = 1,60 urite (1,5) i, paser(i) format(lx, 'positive errer(',i2,') = ',lx,f20.4)</pre>
199	i,poserr(i)	u	
56 →	-	3	neg(k) = ifr = neger(k)
	We do the same thing with the megative errors.	8 3	formatity, 'magative error(',i2,') = ',ix,f20.4,
	8:		* equivalent (0', 720.4) maxerr = 2632, * ((10, 4* (dampes / 10,)) - 1.)

```
miner = 222. e float(itr) = (10. ee (donney / 10. ))
urite (1.3) ancor
3. format (1x, Maxima energy level is ', £20.4)
urite (1.4) miner
4. format (1x, Minima energy level is ', £20.4)
c. Output the N value
510 urite(1,7) itr, bings
7. format(1x, N = ', 13,' with the corresponding error of ', £20.4)
end
```

Appendix E

***************************************	***********	***************************************		new subtrac in s10.5 fo	treference from AGC o	now subtract reference from baud energy to get error, the baud energy is in $$10.5$ format, the AGC maintains that level at $2.86 {\rm Mpc} = 46.7$ (in 5ho
84C. 858				in \$10.5).	the agoref 15 1	in si0.5), the aggref is therefore h 500
			:tohe			
***************************************	************			ž	avesor	
				Diez	cont1	: for negative energy
front and a	front and and function) e	one, 15	: Set to max positive
				ĝ,s	30 e	: energy level - forced
				sie	Bode	
************	***************************************		out:			
		***************************************		#	oue	
the average	crops cons			₽0 y ×	agenef	: agonef = h/5b6
avecor mb	pone public .	average which is classed to the fear program and stored in		Spac		:avesur - agonef - acc
a window wh	OSe Width dep	districtly, which is created by this routine after using it, the routine uses a mindow whose winth depends on the model that is seen asset.	-			•
weighting	Mahich also de	enes on the modulation (1200, 2400) and a error		ompare the	compare the error to window (impl),	w (tmp1).
,	A 06 1 10 110 110	The state of the s	•	ferror w	ndow = error -	if error window = error - window - error
900:			•	F -WIRGON	1f -Window error window = 0 - error	= 0 - error
				f error	Indow = tmp0	If error _window = twoO × (error + window) - error
MAOS .			•-	f the avera	De baud energy	If the average band enemy is a the neat band enemy for one and
Jac	5	: Check for afe switching		Sa and th	i.8 a and the minimis is 0.2 a	2 a, the press back energy for that signals is
DNZ	SWITCH			i monutan at	t bacadaca c	the mindow is therefore thoses to be 0 0 a a category
				Octob = 1,5	andref = h'Sh4 the window or h'400	osen to be die all either direction, with
check 1f 240	check if 2400 and change those values	those values		or deek erd	10 the 11100	724 61
				te distorti	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	and distortion and therefore the
iack	ო			TOTAL CHACK	first check of energy mander	the district opens to send the time window is much smaller (h/a).
and	status	: if status bits 0 and 1		1131 (1140)	10 La	•
2 = 2400				9	-	
gns	one, 1			3 3		
blez	9000	: if 2, do not modify tmp0 and tmp1		paez	200	terror - window - tep3
				ļ	į	
10 Z400 , 1	for 2400 , 2 - tmp0 and 1320 - tmp1	.320 - tmp1		rop windor	ı = check ıf er	error window = check if error -window, in which case zero the error.
100	·	:		Irst zero ti	He error (1.e.	first zero the error (1.e. assume error -window) and modify if wrong
(565	, ,	; 17 15 Z4(X)		assumption.		
	0					
= ;	900			lark	ar1,0	
XÁ :	1320			Ser	arl, tmp3	assume error anibadom
9			•-			
580	tmp]			Check asumption	ge g	
۵	agc i		•••			
				900	tmo1.1	1000011
,				2062	aoc2	a angular in the same
ACK.	_	; it is 1200	••			11161 51 110114-1-1-1
	tapo	; weighting factor - tmp0		ror -windo	and views	CTOC INIDGOM = temp()x(aprocedurates) - temp()
±	one					
₽ DÀ	ģ			540	tan3	
Dig				<u>+</u>	2 4	
() 75	tmp i	; window - tmp1		.	tano	
				1	•	
				UPO		

; agc3;

; ; ; ; ; ; ; ; ;

swtch1!			die Cadanan .		the state of the s
10 %	5 .4	; reset the gm value to zero .) and the sea sinks called	: requiring so	requiring some manipulations	•
# # #	alpha	reset alpha to 5.05	≠	Įį Į	; multiply by age word
ž			de de	al pha	
. ,,,,,,			ž.		
<u> </u>	ŧ		shift accumu	lator eight fo	shift accumulator eight four times before storing
í	. 8	decrement the counter			
2	set ch2		Sec	# 9	
:			sach	tae I	
725	ŧ). - -	tmp0,8	
2			sach	tmp0	
•			¥	9 e e	; mask off any sign extension
entrh2:			qns	ope o	: 00ff - acc
75	8			tae0	
, i	5. 4	and an adula was been .	3	9	
¥ .	rates.	of the property of the propert		•	
Ė	70	theset alpha to 8.78 in 57.5	7	,	
į			998	2	
			1286	Ē	
-	***************************************	***************************************	••		:
			; update the sign	al power estim	; update the signal power estimate avesgr. avesgr = avesgr + (tmp1)2
			s avesqr is zeron	d by the ago r	; avesqr is zeroed by the agc routine once per baud.
DEIVER PER	RECEIVER PER SAMPLE PROCEDURE	₩		•	
			¥.	tep1,13	•
rstskfi			Sech	2	time in soluti
<u>=</u>	ria	; input 2's complement sample	*	9	
			Ì	ige Ide	
ah pass fi	ilter the income	high pass filter the incoming signal to remove the dc component.	75.		
			uppe e	avesar	; avesqr in s10.5
- \$	-		sach avesqr	'esqr	
280	×		•		
24 5	stlsb		•		
*			•		
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